

Three-point energy correlator in N=4 and QCD

$$\delta\left(x_1 - \frac{1 - \cos\theta_{jk}}{2}\right)\delta\left(x_2 - \frac{1 - \cos\theta_{ik}}{2}\right)\delta\left(x_3 - \frac{1 - \cos\theta_{ij}}{2}\right)$$

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Based on:

- [Kai Yan and XYZ, Phys.Rev.Lett. 129 (2022) 2, 021602, arXiv: 2203.04349]
- [Tong-Zhi Yang and XYZ, JHEP 09 (2022) 006, <u>arXiv: 2208.01051</u> and in progress work]
 Also on:
- [Aurélien Dersy, Matthew Schwartz and XYZ, arXiv: 2206.04115]

Energy correlators

Energy correlator is defined as the Wightman correlation function of the energy flow operators

$$\mathcal{E}(\vec{n}) = \int_{-\infty}^{\infty} d\tau \lim_{r \to \infty} r^2 n^i T_{0i}(t = \tau + r, r\vec{n})$$

N-point energy correlator \Rightarrow (N+2)-point correlation function

[Hofman, Maldacena, 0803.1467]



$$\int \left[d\Omega_{\vec{n}_i} \delta(\vec{n}_i \cdot \vec{n}_{i+1} - \cos \chi_i) \right] \times \int d^4 x e^{iqx} \left\langle \Omega | J^{\mu}(x) \mathcal{E}(\vec{n}_1) \cdots \mathcal{E}(\vec{n}_N) J_{\mu}(0) | \Omega \right\rangle$$

Perturbative: as a energy-weighted differential cross section,

e.g. EEC (N=2)

$$\operatorname{EEC}(\chi) = \sum_{i,j} \int d\sigma \frac{E_i E_j}{Q^2} \delta(\vec{n}_i \cdot \vec{n}_j - \cos \chi)$$

[Basham, Brown, Ellis, Love, 1978]



Motivation

- Energy correlator is almost the simplest jet observables:
 - No jet algorithm needed;
 - Soft divergence suppressed;

Analytic measurement function;



Multi-point energy correlators



- N-point (multi-point) energy correlator is a perfect candidate for understand the internal structure of a jet, allowing approaches both from analytic fixed-order calculation and EFT factorization
- Compared to EEC, N-point gives rise to more interesting jet substructure (involving energy flows)
- How do we study a multi-dimensional distribution?

Jet substructure aspect

- Projected N-point energy correlator [Chen, Moult, XYZ, Zhu, 2004.11381] $\frac{d\sigma^{[N]}}{dx_L} = \sum_{n} \sum_{1 \le i_1, \dots i_N \le n} \int d\sigma \frac{\prod_{a=1}^N E_{i_a}}{Q^N} \delta(x_L - \max\{x_{i_1,i_2}, x_{i_1,i_3}, \dots x_{i_{N-1},i_N}\}))$ $x_{i,j} \equiv (1 - \cos \theta_{ij})/2$
- N can also be extended to a complex number ν with $\operatorname{Re}[\nu] > 0$

• One of the main measurement at collider physics is the α_s determination

simple power correction compared to other event shapes (heavy jet mass, C parameter...)



Jet substructure aspect

[Chen, Luo, Moult, Yang, XYZ, Zhu, EEEC in the triple collinear limit $x_1, x_2, x_3 \sim \lambda^2$ • 1912.11050]

$$\frac{d^{3}\sigma}{dx_{1}dx_{2}dx_{3}} = \int dPS |\mathcal{M}|^{2} \delta \left(x_{3} - \frac{1 - \cos\theta_{12}}{2}\right) \delta \left(x_{2} - \frac{1 - \cos\theta_{13}}{2}\right) \delta \left(x_{1} - \frac{1 - \cos\theta_{23}}{2}\right)$$
$$\stackrel{\text{coll}}{\approx} \frac{1}{x_{L}^{3}} \times G(z, \bar{z}) \implies \text{scaling} \times \text{shape function} \qquad \text{factorized to 2D}$$

with $x_1 = x_L z \overline{z}, x_2 = x_L (1-z)(1-\overline{z}), x_3 = x_L$



Figures from Chen & Zhu









EFT aspect: collinear limit

Collinear factorization for projected N-point correlator: (N=2 is the EEC)

 \sum Cumulant:

ant:
$$\Sigma^{[N]} \left(x_L, \ln \frac{Q^2}{\mu^2} \right) = \frac{1}{\sigma_{\text{tot}}} \int_0^{x_L} dx'_L \frac{d\sigma^{[N]}}{dx'_L} \left(x'_L, \ln \frac{Q^2}{\mu^2} \right)$$
$$\Rightarrow \Sigma^{[N]} \left(x_L, \ln \frac{Q^2}{\mu^2} \right) = \int_0^1 dx \, x^N \, \vec{J}^{[N]} \left(\ln \frac{x_L x^2 Q^2}{\mu^2} \right).$$

$$\vec{H}\left(x,\ln\frac{Q^2}{\mu^2}\right)$$

 $\frac{Q^2}{\mu^2}$

jet function

hard function

- N=2 EEC for N = 4 and e^+e^- : NNLL [Dixon, Moult, Zhu, 1905.01310] ${\color{black}\bullet}$
- Projected N-/(ν -)point for e^+e^- : NLL [Chen, Moult, XYZ, Zhu, 2004.11381]
- Projected N=3-6-point for *pp*: NLL [Lee, Meçaj, Moult, 2205.03414] •
- Projected 3-point for both e^+e^- and pp: NNLL [Chen, Gao, Li, Xu, XYZ, Zhu, to appear]
- It is conjectured that this functional form works for triple-collinear EEEC with a fixed • shape (fixed z)
- The collinear squeezed factorization (collinear+ $z \rightarrow 0$) is also understood with light-• ray OPE



EFT aspect: back-to-back limit

• Back-to-back factorization for EEC to all orders: [Moult, Zhu, 1801.02627]

$$\begin{aligned} \frac{d\sigma^{[2]}}{dz} &= \frac{\hat{\sigma}_0}{2} H_{q\bar{q}}(Q,\mu) \int \frac{d^2 \vec{b}_T d^2 \vec{q}_T}{(2\pi)^2} e^{i\vec{q}_T \cdot \vec{b}_T} \delta\left(1 - z - \frac{q_T^2}{Q^2}\right) \\ & \times J_q\left(b_T,\mu,\frac{\nu}{Q}\right) J_{\bar{q}}\left(b_T,\mu,\frac{\nu}{Q}\right) \tilde{S}_q(b_T,\mu,\nu) \end{aligned}$$
TMD soft function

- NNLL: [Collins, Soper, 1981], [Ellis, Richards, Stirling, 1984], [Florian, Grazzini, 0407241]
- N^3LL' and N^4LL : [Ebert, Mistlberger, Vita, 2012.07859], [Duhr, Mistlberger, Vita, 2205.02242]
- For three-point correlator (EEEC) and beyond, there is no unique back-to-back limit Instead, we have three back-to-back limits: $x_i \rightarrow 1$, i = 1,2,3 and a coplanar limit
- The fact that EEEC has multiple overlapping kinematic limits requires the factorization from multi-scale EFTs and the joint resummation in a 3D distribution
- How about the fixed-order side:

This talk: first look at the fixed-order result (LO EEEC in N=4 and QCD)



EEEC in N = 4 SYM theory M

[Yan, **XYZ**, 2203.04349]

• The leading order EEEC with arbitrary angle dependence:

$$\frac{1}{\sigma_0} \frac{d^3 \sigma}{dx_1 dx_2 dx_3} = \sum_{i,j,k} \int dPS_4 |\mathcal{M}_{\mathcal{N}=4}|^2 \frac{E_i E_j E_k}{Q^3} \qquad \text{No soft divergence} \Rightarrow d = 4 \text{ finite}$$
$$\times \delta \left(x_3 - \frac{1 - \cos \theta_{12}}{2} \right) \delta \left(x_2 - \frac{1 - \cos \theta_{13}}{2} \right) \delta \left(x_1 - \frac{1 - \cos \theta_{23}}{2} \right)$$

• The four-particle phase space:

$$dPS_4 = (2\pi)^{4-3d} (Q^2)^{3-\frac{d}{2}} 2^{1-2d} \prod_{i < j} ds_{ij} \, d\Omega_{d-1} \, d\Omega_{d-2} \, d\Omega_{d-3}$$
$$\times \delta \left(Q^2 - \sum_{i < j} s_{ij} \right) \, (-\Delta_4)^{\frac{d-5}{2}} \, \Theta \left(-\Delta_4 \right)$$

Gram determinant:

 $\Delta_4 = \lambda(s_{12}s_{34}, s_{13}s_{24}, s_{14}s_{23}),$ $\lambda(x, y, z) = x^2 + y^2 + z^2 - 2(xy + xz + yz)$

3 detectors separated by angle $heta_{ii}$



• Matrix elements: tree-level $1 \rightarrow 4$ squared form factor $|\langle p_1 p_2 p_3 p_4 | tr[\phi^2] | \rangle|^2$

$$|\mathcal{M}_{\mathcal{N}=4}|^2 \sim \frac{1}{24} \left[\frac{1}{s_{13}s_{14}s_{23}s_{24}} + \frac{4}{s_{123}s_{124}s_{13}s_{14}} + \frac{4}{s_{123}s_{124}s_{14}s_{23}} + \text{perm} \right]$$



Calculation setup

• Attempt using traditional IBP+DE method: for each δ measurement function

Reverse unitarity:
$$\delta\left(\mathcal{M}_{jk}(x_i)\right) = \frac{1}{2\pi i} \left(\frac{1}{\mathcal{M}_{jk}(x_i) - i\epsilon} - \frac{1}{\mathcal{M}_{jk}(x_i) + i\epsilon}\right)$$

 $\mathcal{M}_{jk}(x_i) \equiv (p_j \cdot Q)(p_k \cdot Q)(\vec{n}_j \cdot \vec{n}_k - (1 - 2x_i)) = (p_j \cdot Q)(p_k \cdot Q)(2x_i) - p_j \cdot p_k$

Additional IBP equation: $[(p_j \cdot Q)(p_k \cdot Q)(2x_i) - p_j \cdot p_k] [\delta(\mathcal{M}_{jk}(x_i))]^k = [\delta(\mathcal{M}_{jk}(x_i))]^{k-1}$ [Dixon, Luo, Shtabovenko, Yang, Zhu, 1801.03219]

- It turns out IBP reduction is NOT efficient (e.g. FIRE6) with three nonlinear propagators
- Instead, we expand the phase space in $d = 4 2\epsilon$ and do the integration directly
- Introduce a nice parameterization for all Mandelstam variables:

$$z_{1} = \frac{2p_{1} \cdot q}{Q^{2}}, \quad z_{2} = \frac{2p_{2} \cdot q}{Q^{2}}, \quad z_{3} = \frac{2p_{3} \cdot q}{Q^{2}}, \qquad \Rightarrow \begin{cases} s_{12} = z_{1}z_{2}x_{3}, \\ s_{13} = z_{1}z_{3}x_{2}, \\ s_{23} = z_{2}z_{3}x_{1}, \\ s_{24} = z_{2}(1 - z_{2}x_{3} - z_{3}x_{2}), \\ s_{24} = z_{2}(1 - z_{1}x_{3} - z_{3}x_{1}), \\ s_{34} = z_{3}(1 - z_{1}x_{2} - z_{2}x_{1}) \end{cases}$$



Phase space integration

• The main difficulty of integrating the four-particle phase space comes from the Gram determinant $\Theta(-\Delta_4)$. However, with our parameterization:

$$\int ds_{12} ds_{13} ds_{14} ds_{23} ds_{24} ds_{34} \Theta(-\Delta_4) \delta(\sum_{i < j} s_{ij} - 1) \prod_{l=1,2,3} \delta\left(x_l - \frac{1 - \cos \theta_{mn}}{2}\right)$$

$$= \int dz_1 dz_2 dz_3 (z_1^2 z_2^2 z_3^2) \Theta(-\Delta_4) \frac{1}{1 - x_2 z_1 - x_1 z_2} \delta\left(z_3 - \frac{z_1 + z_2 - x_3 z_1 z_2 - 1}{z_1 x_2 + z_2 x_1 - 1}\right)$$

$$= \Theta(-\widetilde{\Delta}_4) \int dz_1 dz_2 dz_3 (z_1^2 z_2^2 z_3^2) \frac{1}{1 - x_2 z_1 - x_1 z_2} \delta\left(z_3 - \frac{z_1 + z_2 - x_3 z_1 z_2 - 1}{z_1 x_2 + z_2 x_1 - 1}\right) ,$$

with factorized Θ function:

$$\frac{\Delta_4}{z_1^2 z_2^2 z_3^2} = x_1^2 + x_2^2 + x_3^2 - 2x_1 x_2 - 2x_1 x_3 - 2x_2 x_3 + 4x_1 x_2 x_3 \equiv \widetilde{\Delta}_4.$$

• In the triple collinear limit, $x_1, x_2, x_3 \sim \lambda^2$, the kinematic space is reduced to a triangle

('Zongzi'-shaped) kinematic space:

$$\widetilde{\Delta}_4 \approx \widetilde{\Delta}_4^{\text{coll}} = x_1^2 + x_2^2 + x_3^2 - 2x_1x_2 - 2x_1x_3 - 2x_2x_3$$

where $\sqrt{x_1}, \sqrt{x_2}, \sqrt{x_3}$ form a triangle by Helen's area formula



Phase space integration

• Eventually the EEEC integration takes the form

$$\int dz_1 dz_2 dz_3 \delta \left(z_3 - \frac{z_1 + z_2 - x_3 z_1 z_2 - 1}{z_1 x_2 + z_2 x_1 - 1} \right) f(x_1, x_2, x_3, z_1, z_2, z_3)$$
$$= \int_0^1 dz_1 \int_0^{\frac{1 - z_1}{1 - x_3 z_1}} dz_2 f \left(x_1, x_2, x_3, z_1, z_2, \frac{z_1 + z_2 - x_3 z_1 z_2 - 1}{z_1 x_2 + z_2 x_1 - 1} \right)$$

with two square roots

$$z_1 x_2 + z_2 x_1 - 1 \qquad)$$

$$\sqrt{x_1^2 + x_2^2 + x_3^2 - 2x_1 x_2 - 2x_1 x_3 - 2x_2 x_3} = \sqrt{\widetilde{\Delta}_4^{\text{coll}}},$$

$$\sqrt{x_1^2 + x_2^2 + x_3^2 - 2x_1 x_2 - 2x_1 x_3 - 2x_2 x_3 + 4x_1 x_2 x_3} = \sqrt{\widetilde{\Delta}_4}$$

• There are two different parameterizations to rationalize both of them

$$\begin{array}{ll} \text{cross-ratio variables:} & \frac{x_1}{x_3} = z\bar{z}, & \frac{x_2}{x_3} = (1-z)(1-\bar{z}), & x_3 = \frac{t^2 - (z-\bar{z})^2}{4z\bar{z}(1-z)(1-\bar{z})} \\ \Rightarrow & \sqrt{x_1^2 + x_2^2 + x_3^2 - 2x_1x_2 - 2x_1x_3 - 2x_2x_3} = x_3(z-\bar{z}) = \frac{t^2 - (z-\bar{z})^2}{4z\bar{z}(1-z)(1-\bar{z})}(z-\bar{z}), \\ & \sqrt{x_1^2 + x_2^2 + x_3^2 - 2x_1x_2 - 2x_1x_3 - 2x_2x_3 + 4x_1x_2x_3} = x_3t = \frac{t^2 - (z-\bar{z})^2}{4z\bar{z}(1-z)(1-\bar{z})}t \end{array}$$

The $\{t, z, \overline{z}\}$ variable set manifests the symmetry and geometry in the triple-collinear limit



Phase space integration

The angles are mapped onto the the distances between three points on celestial lacksquaresphere

celestial variables:

$$\begin{aligned} x_1 &= \frac{|y_2 - y_3|^2}{(1 + |y_2|^2)(1 + |y_3|^2)}, x_2 = \frac{|y_1 - y_3|^2}{(1 + |y_1|^2)(1 + |y_3|^2)}, x_3 = \frac{|y_1 - y_2|^2}{(1 + |y_1|^2)(1 + |y_2|^2)} \end{aligned}$$
further map to
$$y_1 &= \sqrt{s} \underbrace{e^{i\phi_1}}_{\equiv \tau_1}, y_2 = \sqrt{s} \underbrace{e^{i(\phi_1 + \phi_2)}}_{\equiv \tau_1 \tau_2}, y_3 = \sqrt{s} \\ \begin{cases} \sqrt{\tilde{\Delta}_4^{\text{coll}}} &= \frac{s(1 - \tau_1)(1 - \tau_2)(1 - \tau_1 \tau_2)}{(1 + s)^2 \tau_1 \tau_2} \\ \sqrt{\tilde{\Delta}_4} &= \frac{s(1 - s)(1 - \tau_1)(1 - \tau_2)(1 - \tau_1 \tau_2)}{(1 + s)^3 \tau_1 \tau_2} \end{cases}$$
The {*s*, τ_1, τ_2 } variable set is easier for understanding the alphabet and simplifying the result

the alphabet and simplifying the result

With either variable set, we can directly perform the integration over z_1, z_2 in lacksquareHyperInt, and express the result in terms of GPLs (up to weight-2)

$$G(a_1, \cdots a_n; x) \equiv \int_0^x \frac{dt}{t - a_1} G(a_2, \cdots a_n; t); \quad G(x) \equiv 1, \ G(\vec{0}_n; x) \equiv \frac{1}{n!} \ln^n(x)$$

[Panzer, 1403.3385]

Embedding

The EEEC kinematic space can be embedded into a hexagon on a unit circle. From lacksquarethe definition of three angles:

$$x_k = \frac{q^2(p_i \cdot p_j)}{2(q \cdot p_i)(q \cdot p_j)} = \frac{\langle p_i p_j \rangle \langle \xi_i \xi_j \rangle}{\langle p_i \xi_j \rangle \langle p_i \xi_j \rangle}, \quad |\xi_j\rangle \equiv q|j]$$

We can embed: $|p_i\rangle \equiv |2i-1\rangle, |\xi_i\rangle \equiv |2i+2\rangle$



Symmetry: D_6 dihedral group $Z_i = \{1, -s\tau_1\tau_2, \tau_1, -s, \tau_1\tau_2, -s\tau_1\}, I = \infty$

- Cyclic permutation (σ): Z(a + 2) = Z(a)ullet
- Parity (*P*) : Z(a + 3) = Z(a) \bullet
- Flip (τ) : Z(8 a) = Z(a)



Symbol alphabet

• From the output of HyperInt, we found 17 symbols:

 $\{s - 1, s, s + 1, \tau_1 - 1, \tau_1, \tau_2 - 1, \tau_2, s + \tau_1, 1 + s\tau_1, s + \tau_2, 1 + s\tau_2, s + \tau_1\tau_2, 1 + s\tau_1\tau_2, \tau_1\tau_2 - 1, \tau_1 - \tau_2, \tau_1^2\tau_2 - 1, \tau_1\tau_2^2 - 1\}$

- However it turns out that only 16 symbols are independent
- This can be written as a close set under D_6 using three conformal invariant ratios:

$$\begin{aligned} u_1 &\equiv -\frac{\langle 51 \rangle \langle 62 \rangle \langle 43 \rangle}{\langle 35 \rangle \langle 16 \rangle \langle 24 \rangle} = -\frac{s+\tau_1}{1+s\tau_1}, \\ u_2 &\equiv -\frac{\langle 31 \rangle \langle 51 \rangle}{\langle 15 \rangle \langle I3 \rangle} = \frac{\tau_1 - 1}{1-\tau_1\tau_2}, \\ u_3 &\equiv -\frac{\langle 13 \rangle \langle 56 \rangle}{\langle 35 \rangle \langle 61 \rangle} = \frac{(1-\tau_1)(s+\tau_2)}{(1-\tau_2)(1+s\tau_1)}, \end{aligned} \qquad \begin{cases} u_1, 1+u_1, u_2, 1+u_2, u_3, 1+u_3, u_1+u_3, \\ 1+u_1+u_3, u_2+u_3+u_2u_3, u_1+u_2+u_3+u_2u_3, \\ 1+u_1+u_2+u_3+u_2u_3, 1+u_1+u_2+u_3+u_2u_3, \\ 1+u_1+u_2+u_3+u_2u_3, 1+u_1+u_2+u_2u_3+u_2u_3, \\ 1+u_1+u_2+u_1u_2+u_2^2+u_3+2u_2u_3+u_2^2u_3, \\ 1+u_1+u_2+u_1u_2+u_2+u_2+u_2+u_3+u_2u_3+u_2u_3, \\ 1+u_1+u_2+u_2+u_2+u_3+u_2+u_3+u_2u_3+u_2u_3+u_2^2u_3, \\ 1+u_1+u_2+u_2$$

• Finally we are able to reconstruct the minimal EEEC function space (up to weight-2)

Function space

• Arguments: 15 conformal invariant ratios that cover the χ - coordinate in [Golden, Paulos, Spradlin, Volovich, 1401.6446]; additional variable $r_1 \equiv -\frac{\langle 14 \rangle \langle 3I \rangle}{\langle 13 \rangle \langle 4I \rangle}$ and the images under D_6

• First entry conditions: (1). Single-value requirement in the physical region; (2). Free of logarithmic divergence in the triple collinear limit $s \rightarrow 0$

• Eventually, we find 3 weight-1 basis and 11 weight-2 basis

$$\frac{d^3\sigma}{dx_1dx_2dx_3} = \sum_{i=1}^3 b_i^{(1)}f_i + \sum_{i=1}^{11} b_i^{(2)}g_i + \text{perm of } x_1, x_2, x_3$$

• Weight-1 is simple

$$\frac{\tilde{\Delta}_{4}^{\text{coll}} + 4x_{3}^{2}x_{2} - 4x_{3}x_{2}^{2}}{x_{1}^{2}x_{2}^{2}x_{3}^{2}} \underbrace{\ln(1-x_{3})}_{f_{1}} + \frac{2(x_{3}-x_{1})}{x_{3}x_{2}^{2}x_{1}} \underbrace{\ln\frac{x_{1}}{x_{3}}}_{f_{2}} - \frac{\sqrt{\tilde{\Delta}_{4}}}{x_{3}x_{2}^{2}x_{1}^{2}} \underbrace{\ln\frac{2-x_{1}-x_{2}-x_{3}-\sqrt{\tilde{\Delta}_{4}}}{2-x_{1}-x_{2}-x_{3}+\sqrt{\tilde{\Delta}_{4}}}}_{f_{3}}$$

with



Function space

• For weight-2 functions, we need to introduce a few variables from the embedding

$$\begin{aligned} z_{1} &= \frac{\langle 56 \rangle \langle 13 \rangle}{\langle 35 \rangle \langle 16 \rangle} = \frac{(\tau_{1} - 1)(s + \tau_{2})}{(1 - \tau_{2})(1 + s\tau_{1})}, \quad \bar{z}_{1} \equiv P(z_{1}) = \frac{\langle 23 \rangle \langle 46 \rangle}{\langle 26 \rangle \langle 34 \rangle} = \frac{(1 + s\tau_{2})(1 - \tau_{1})}{(s + \tau_{1})(1 - \tau_{2})} \\ w_{1} &= \frac{\langle 16 \rangle \langle 25 \rangle}{\langle 56 \rangle \langle 12 \rangle} = -\frac{(1 + s)(1 + s\tau_{1})\tau_{2}}{(s + \tau_{2})(1 + s\tau_{1}\tau_{2})}, \quad \bar{w}_{1} \equiv P(w_{1}) = \frac{\langle 34 \rangle \langle 25 \rangle}{\langle 23 \rangle \langle 45 \rangle} = -\frac{(1 + s)(s + \tau_{1})\tau_{2}}{(1 + s\tau_{2})(s + \tau_{1}\tau_{2})} \\ v_{1} &\equiv \frac{\langle 26 \rangle \langle 35 \rangle}{\langle 56 \rangle \langle 23 \rangle} = -\frac{s(1 - \tau_{2})^{2}}{(s + \tau_{2})(1 + s\tau_{2})} \quad \{z_{2}, z_{3}, \cdots\} \text{ is obtained by cyclic permutations} \end{aligned}$$

$$\begin{aligned} g_{1} &= \text{Li}_{2}(-v_{2}) \\ g_{2} &= \text{Li}_{2}(1 + w_{3}) + \text{Li}_{2}(1 + \bar{w}_{3}) + 2 \text{Li}_{2}(-v_{3}) \\ &- \text{Li}_{2}(1 + w_{1}) - \text{Li}_{2}(1 + \bar{w}_{3}) + 2 \text{Li}_{2}(-v_{1}) \\ g_{3} &= \text{Li}_{2}(-z_{2}) - \text{Li}_{2}(-\bar{z}_{2}) + \frac{1}{2} \ln |z_{2}|^{2} \ln \frac{1 + z_{2}}{1 + \bar{z}_{2}} \\ g_{4} &= \text{Li}_{2}(1 + w_{1}) - \text{Li}_{2}(1 + \bar{w}_{3}) + \text{Li}_{2}(1 + \bar{w}_{3}) \\ &- \text{Li}_{2}(1 + \bar{w}_{3}) + \text{Li}_{2}(1 + w_{3}) - \text{Li}_{2}(1 + \bar{w}_{3}) + \text{Li}_{2}(1 + \bar{w}_{3}) \\ g_{5} &= \pi^{2} \\ g_{6} &= \ln^{2} \frac{\bar{w}_{1}}{w_{1}} \\ g_{6} &= \ln^{2} \frac{\bar{w}_{1}}{w_{1}} \\ g_{6} &= \ln^{2} \frac{\bar{w}_{1}}{w_{1}} \\ &= \frac{\bar{w}_{1}}{w_{1}} \\ g_{9} &= \frac{1}{2} \text{Li}_{2}(1 - \frac{\bar{w}_{1}}{w_{1}}) - \frac{1}{2} \text{Li}_{2}(1 - \frac{\bar{w}_{1}}{w_{1}}) \\ g_{10} &= \text{Li}_{2}(1 - |z_{2}|^{2}) + \frac{1}{2} \ln |z_{2}|^{2} \ln |z_{2}|^{2} \ln |z_{2}|^{2} \end{aligned}$$

 $g_7 = \ln \frac{\bar{w}_1}{w_1} \, \ln |z_2|^2$

 $g_8 = \ln (1 + v_3) \ln |z_1|^2 - \ln (1 + v_1) \ln |z_3|^2$

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N = 4 result

• Visualize the 3D distribution:



Xiaoyuan Zhang

[Chen, Luo, Moult, Yang, XYZ, Zhu, 1912.11050]

EEEC in QCD

[Yang, XYZ, 2208.01051 and in progress work]

For LO EEEC in QCD, we consider both two processes: lacksquare



 $\gamma^{\star} \to q\bar{q}q'\bar{q}', \, q\bar{q}q\bar{q}, \, q\bar{q}gg \qquad \qquad H \to gggg, \, q\bar{q}gg, \, q\bar{q}q'\bar{q}', \, q\bar{q}q\bar{q}$

For Higgs-EEEC, we use the HEFT and work in the massless quark limit

$$\mathcal{L}_{\text{int}} = -\frac{1}{4}\lambda H \text{Tr}(G^{\mu\nu}G_{\mu\nu}) + \sum_{q} \frac{y_q}{\sqrt{2}} H \bar{\psi}_q \psi_q$$

All matrix elements are calculated in QFRAF and FORM, with axial gauge

$$\sum_{\lambda=1}^{2} \epsilon^{\mu}(p_{i},\lambda) \epsilon^{*\nu}(p_{i},\lambda) = -g^{\mu\nu} + \frac{\bar{n}^{\mu}p_{i}^{\nu} + \bar{n}^{\nu}p_{i}^{\mu}}{\bar{n} \cdot p_{i}} - \frac{\bar{n}^{2}p_{i}^{\mu}p_{i}^{\nu}}{(p_{i} \cdot \bar{n})^{2}}$$



 $H \to q\bar{q}gg, \, q\bar{q}q'\bar{q}', \, q\bar{q}q\bar{q}$

EEEC in QCD

• For QCD calculation, we need the topology identification

$$\sum_{i \neq j \neq k \in \{1,2,3,4\}} \int \frac{E_i E_j E_k}{Q^3} dPS_4 \Pi_{ijk} |\mathcal{M}(p_1, p_2, p_3, p_4)|^2$$

$$= \sum_{a \neq b \neq c \in \{1,2,3\}} \int \frac{E_a E_b E_c}{Q^3} dPS_4 \Pi_{abc} \left(|\mathcal{M}(p_a, p_b, p_c, p_4)|^2 + |\mathcal{M}(p_a, p_b, p_4, p_c)|^2 + |\mathcal{M}(p_a, p_4, p_c, p_b)|^2 + |\mathcal{M}(p_4, p_a, p_b, p_c)|^2 \right)$$

$$= \left[\int \frac{E_1 E_2 E_3}{Q^3} dPS_4 \Pi_{123} \left(|\mathcal{M}(p_1, p_2, p_3, p_4)|^2 + |\mathcal{M}(p_1, p_2, p_4, p_3)|^2 + |\mathcal{M}(p_1, p_4, p_3, p_2)|^2 + |\mathcal{M}(p_4, p_1, p_2, p_3)|^2 \right) \right] + \text{permutations of } x_1, x_2, x_3, \quad (2.3)$$

$$\Pi_{abc} = \left\{ \left(\pi - \frac{1 - \cos \theta_{jk}}{Q} \right) \right\} \left(\pi - \frac{1 - \cos \theta_{ik}}{Q} \right) \left\{ \left(\pi - \frac{1 - \cos \theta_{ik}}{Q} \right) \right\} \left(\pi - \frac{1 - \cos \theta_{ik}}{Q} \right) \right\}$$

where

$$\Pi_{ijk} = \delta\left(x_1 - \frac{1 - \cos\theta_{jk}}{2}\right)\delta\left(x_2 - \frac{1 - \cos\theta_{ik}}{2}\right)\delta\left(x_3 - \frac{1 - \cos\theta_{ij}}{2}\right)$$

- The phase space parameterization and integration are the same as N = 4, and we still express the result in terms of GPLs.
- It has been observed that N = 4 and QCD shares a lot of common properties, in both amplitude level and cross-section level. For LO EEEC, N = 4 and QCD turns out to have exactly the same function space.



QCD result

- To simplify the QCD result, we build the linear relation between the GPL function space and the N = 4 classical polylogarithmic space via PSLQ, and project the QCD result onto it.
- Example: $e^+e^- \rightarrow$ hadrons 6.3 MB \rightarrow 1.2 MB
- Comparison with Monte Carlo programs:



Event2: fifty billion points are sampling; NLOJet++: ten billion points

200 digits precision within

4 sec for a regular point



21

Kinematic limits

• Different ways to visualize the kinematic limits:





Its boundary corresponds to the coplanar limit

- For triple-collinear limit:
 - The LP is understood.
 - Our result also provides perturbative data for NLP and beyond
 - The NLP triple-collinear function space is the same as LP:

$$\left\{\ln x_1; \, \pi^2, \, 2iD_2^-(z), \, \mathrm{Li}_2\left(1 - \frac{x_2}{x_1}\right) + \frac{1}{2}\ln\frac{x_1}{x_3}\ln\frac{x_1}{x_2}\right\} + \text{permutations}$$



 $x_{1} = -\frac{s}{(s+1)^{2}} \frac{(1-\tau_{1})^{2}}{\tau_{1}}, x_{2} = -\frac{s}{(s+1)^{2}} \frac{(1-\tau_{2})^{2}}{\tau_{2}},$ $x_{3} = -\frac{s}{(s+1)^{2}} \frac{(1-\tau_{1}\tau_{2})^{2}}{\tau_{1}\tau_{2}}$

Kinematic limits

• Squeezed limit:

$$x_1 \to 0, x_2 \sim x_3 \to \eta$$

$$\frac{1}{\sigma_{\text{tot}}} \frac{d^3 \sigma}{dx_1 dx_2 dx_3} \overset{x_1 \to 0, x_{2,3} \sim \eta}{\approx} \left(\frac{\alpha_s}{4\pi}\right)^2 \frac{1}{4\pi\sqrt{-s_2^2}} \left(\frac{B(\eta)}{x_1} + \mathcal{O}(x_1^0)\right)$$
$$B(\eta) = C_F n_f T_F \left(\frac{4\left(28\eta^2 - 82\eta + 63\right)\log(1-\eta)}{15\eta^6} - \frac{67\eta^3 - 702\eta^2 + 1362\eta - 756}{45(1-\eta)\eta^5}\right)$$
$$+ C_F^2 \left(-\frac{6\left(12\eta^3 - 41\eta^2 + 40\eta - 9\right)\log(1-\eta)}{(1-\eta)\eta^6} - \frac{31\eta^3 - 288\eta^2 + 426\eta - 108}{2(1-\eta)\eta^5}\right)$$
$$+ C_A C_F \left(\frac{4\left(166\eta^2 - 544\eta + 441\right)\log(1-\eta)}{15\eta^6} - \frac{349\eta^3 - 4374\eta^2 + 9174\eta - 5292}{45(1-\eta)\eta^5}\right)$$

- However, the squeeze limit itself is ambiguous since it is path-dependent
- If we take the double limit: triple-collinear +squeezed $x_1 \sim x_2 \sim x_3 \rightarrow 0, z \rightarrow 0$

$$\begin{aligned} \frac{1}{\sigma_{\text{tot}}} \frac{d^3 \sigma}{dx_1 dx_2 dx_3} &\approx \left(\frac{\alpha_s}{4\pi}\right)^2 \frac{1}{4\pi \sqrt{-s_2^2}} \left[\frac{C_F^2}{x_3} \left(\frac{16}{5r^2} + \frac{8(1+t^2)}{5rt} \right) \right. \\ &+ \frac{C_F C_A}{x_3} \left(\frac{5+273t^2+5t^4}{225r^2t^2} + \frac{10+273t^2+273t^4+10t^6}{450rt^3} \right) \\ &+ \frac{C_F T_F n_f}{x_3} \left(-\frac{10-39t^2+10t^4}{225r^2t^2} + \frac{-20+39t^2+39t^4-20t^6}{450rt^3} \right) \\ &+ C_F n_f T_F \left(-\frac{24t^4-31t^2+24}{225r^2t^2} - \frac{4(t-1)^2\left(t^2+1\right)\left(t+1\right)^2}{75rt^3} \right) \\ &+ C_A C_F \left(\frac{12t^4+367t^2+12}{225r^2t^2} + \frac{2(t-1)^2\left(t^2+1\right)\left(t+1\right)^2}{75rt^3} \right) + \frac{47C_F^2}{10r^2} \right] \end{aligned}$$
t-dependence disappears for $N = 1$ SYM [Chen, Moult, Zhu, 2104.00009]



Kinematic limits

• There are also various possibilities on slicing the EEEC kinematic space. The simplest one is the equilateral limit $x_1 = x_2 = x_3 \equiv x$



- It will be interesting to study factorization and the joint resummation of different kinematic limits/slicing
- It might be also possible to develop a ENC bootstrap program using all these kinematic limits



Simplification game: necessary but challenging

- The most difficult part of EEEC calculation is how to simplify the result. It is important because:
 - Fast and accurate numerical evaluation \Rightarrow essential for collider physics
 - Mathematical structure understanding \Rightarrow physical singularities

e.g. [Hannesdottir, McLeod, Schwartz, Vergu, 2109.09744]

- Observables involving various cuts (θ/δ functions) usually lead to complicate symbol and alphabet. It is hard to lift the symbol into simplified polylogarithms.
- Even for standard loop integrals and phase space integrals, the raw expressions could involve spurious singularities.

Can Symbolic ML help with any step?

Xiaoyuan Zhang

Polylogarithm meets symbolic ML

[Dersy, Schwartz and XYZ, 2206.04115]



- Approach 1: Reinforcement learning
- Approach 2: transformer networks



[Vaswani et al, 2017]

[Facebook: Deep learning for integration and solving ODEs, Lample, Charton, 1912.01412]

Simplifying polylogarithms with transformer

- A baby step: consider single-variable expressions without any square root
- Procedure:
 - Compute the symbol expressions with PolyLogTools [Duhr, Dulat, 1904.07279]
 - Translation task in ML: find the simplest result corresponding a given symbol
 - Transformer could give a wrong result, but it is easy to verify



- We do weight-2,3,4, and only calculate the leading transcendental term.
- Training: Generate simple expressions (\sim 1-2M) and compute their symbol

Weight 2	Weight 3	Weight 4
$\operatorname{Li}_2(x)$	${ m Li}_3(x)$	${ m Li}_4(x)$
$\ln(x)\ln(y)$	$\operatorname{Li}_2(x)\ln(y)$	${ m Li}_3(x)\ln(y)$
	$\ln(x)\ln(y)\ln(z)$	$\operatorname{Li}_2(x)\operatorname{Li}_2(y)$
		$\operatorname{Li}_2(x)\ln(y)\ln(z)$
		$\ln(w)\ln(x)\ln(y)\ln(z)$



Simplifying polylogarithms with transformer

• Evaluation: We ask the transformer for N guess (Beam evaluation)

Result: we can integrate ~90% symbols

Sample problems

Bear	m Size 1 Beam Size 5			
Weight 2 Transformer Classical Algorithm	82% 91% 59% 59%	Input symbol \mathcal{S}_i	Simple expression F_i	
Weight 3TransformerWeight 4Transformer	88% 80%	$-(-x^{2}-x+1) \otimes (1-x) + (-x^{2}-x+1) \otimes x$ $-(-x^{2}-x+1) \otimes (x+1) + x \otimes (1-x) - x \otimes x + x \otimes (x+1)$	$\operatorname{Li}_2\left(rac{(1-x)(x+1)}{x} ight)$	
100		$-\tfrac{23}{4}(1-x)\otimes x - 6\left(x^2 + x + 1\right)\otimes x$	$2\operatorname{Li}_2(x^3) - rac{1}{4}\operatorname{Li}_2(x)$	
80 L		$-40(6-x^2)\otimes(6-x^2)-3(1-x)\otimes(-x^6-x^2+3)$	$3 \text{Li}_2 \left(-x^6 - x^2 + 3\right)$	
00 Ctio		$-3(x+1)\otimes(-x^6-x^2+3)-3(x^4+x^2+2)\otimes(-x^6-x^2+3)$	$-rac{1}{4}\operatorname{Li}_2(2x-4)$	
redi		$+rac{1}{4}(5-2x)\otimes(2-x)$	$-20\ln^2{(x^2-6)}$	
d d d d d d d d d d	Beam 1 - Weight 4 Beam 1 - Weight 3 Beam 1 - Weight 2	$8\frac{x^2 - x - 1}{x - 1} \otimes x - 8((x + 1)(x^2 - x - 1)) \otimes x$ $+8(1 - x) \otimes (-x^3 + x^2 - x - 1) - 8\frac{1}{x - 1} \otimes x$ $-8(1 - x) \otimes (x(x^3 - x^2 + x + 1))$	$4 \operatorname{Li}_2(x^2)$	
Number of distinct symbols in input				

• Unlike humans, transformer does NOT care about transcendentally weights!



Conclusions

- Multi-point energy correlator lives in the intersection of studies involving jet substructure, fixed-order calculation and effective field theories.
- We present the analytic calculation of leading order EEEC in both N = 4 super Yang-Mills theory and QCD (e^+e^- annihilation and Higgs decays).
 - Instead of IBP+DE, we preform direct phase space integration with proper parameterization.
 - The result is converted to polylogarithms (up to t.w.2) and simplified using symbol and symmetries.
- Our analytic result provides perturbative data for various kinematic limits at leading power and beyond: triple-collinear, squeezed, back-to-back, coplanar etc. It will be useful once we initialize the study on factorization and joint resummation.
- We also initialize the symbolic ML project (mainly transformer) on simplifying polylogarithms in Feynman integral calculations.

Thank you for your attention!