

Forum on Tracking Detector Mechanics 2023

Estimation of Interfacial Strain Response for a Bi-material Strip in Tensile and Shear Loading Using THz-TDS

Sushrut Karmarkar, Vikas Tomar, Andy Jung

2 June 2023



School of Aeronautics
and Astronautics

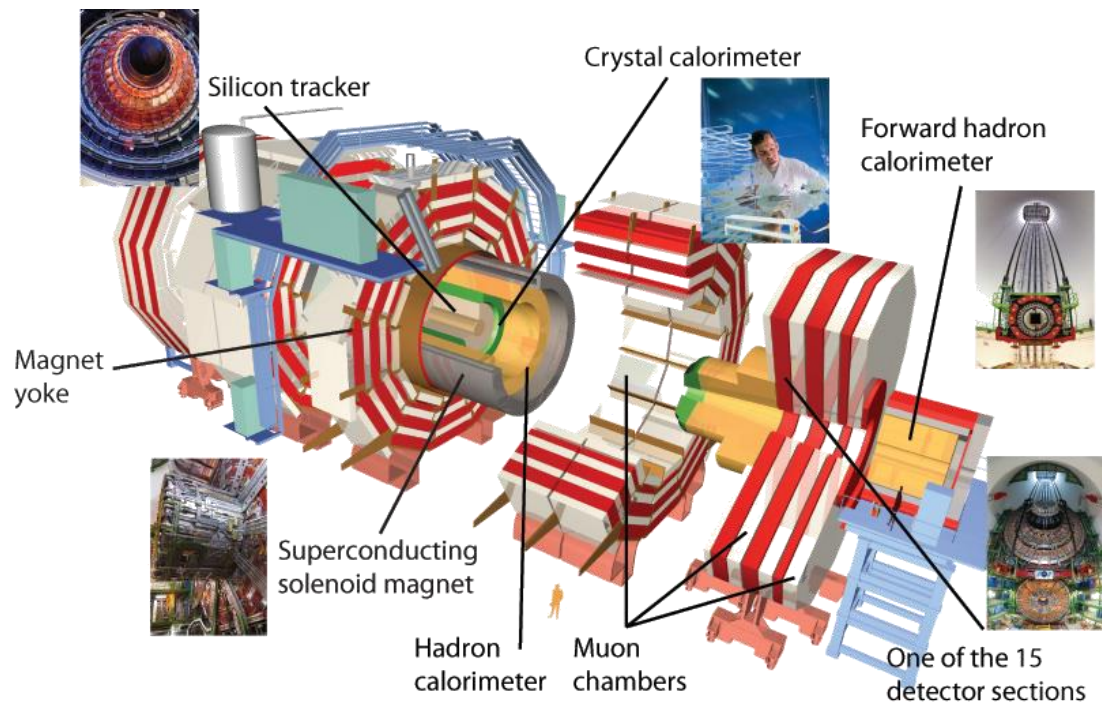
Presentation flow

- 1 Introduction
- 2 Experimental and theoretical approach
- 3 Experimental measurements
- 4 Results and discussion
- 5 Derivation for correlating ΔT_{oA} to volumetric strain for a tension test (back up slides)

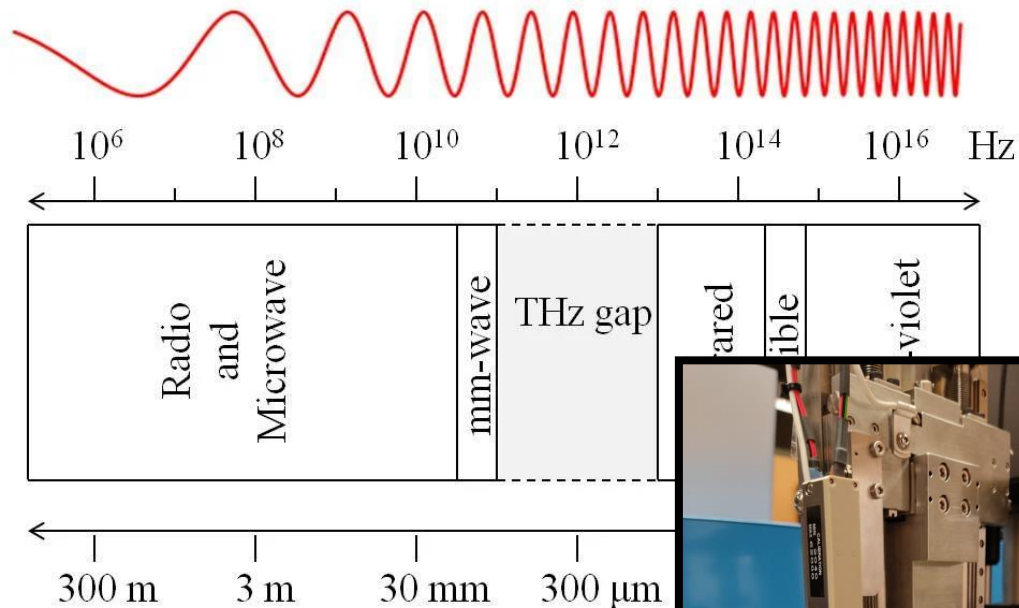
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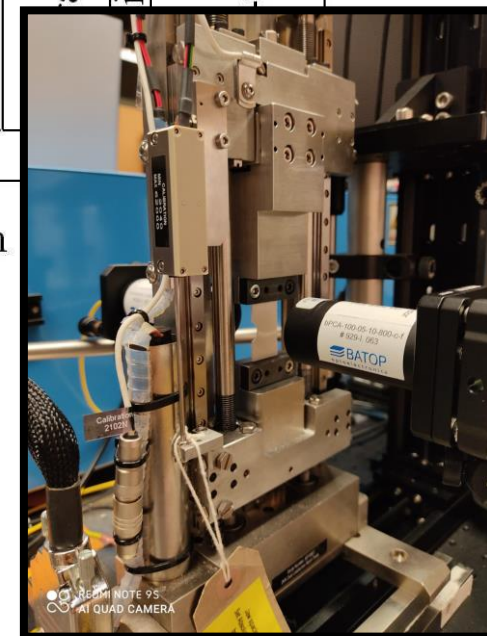
1. Introduction



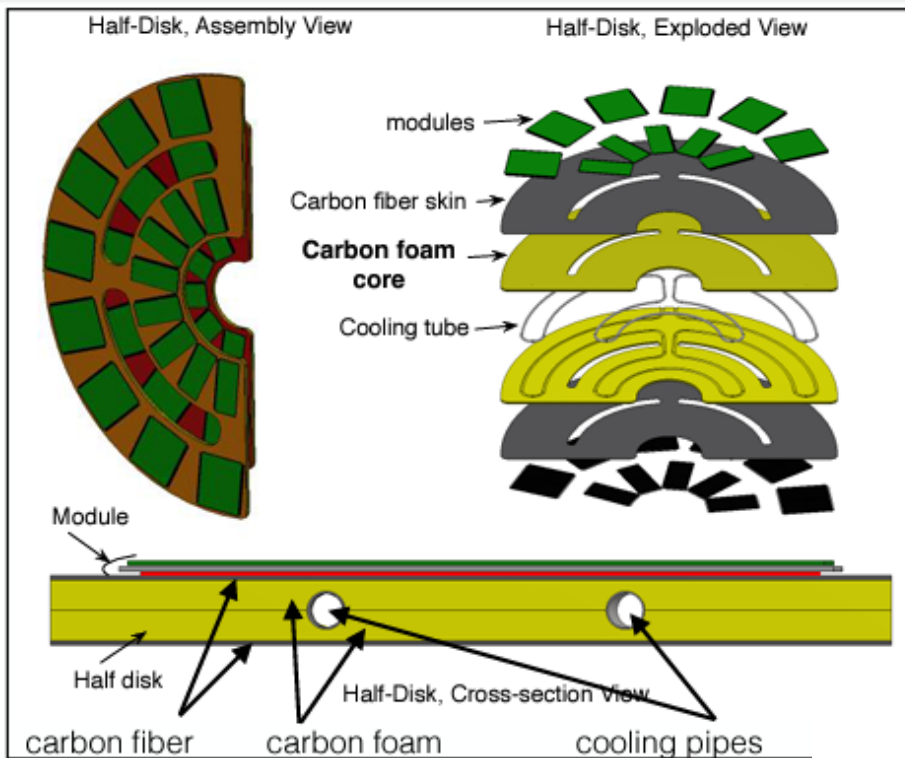
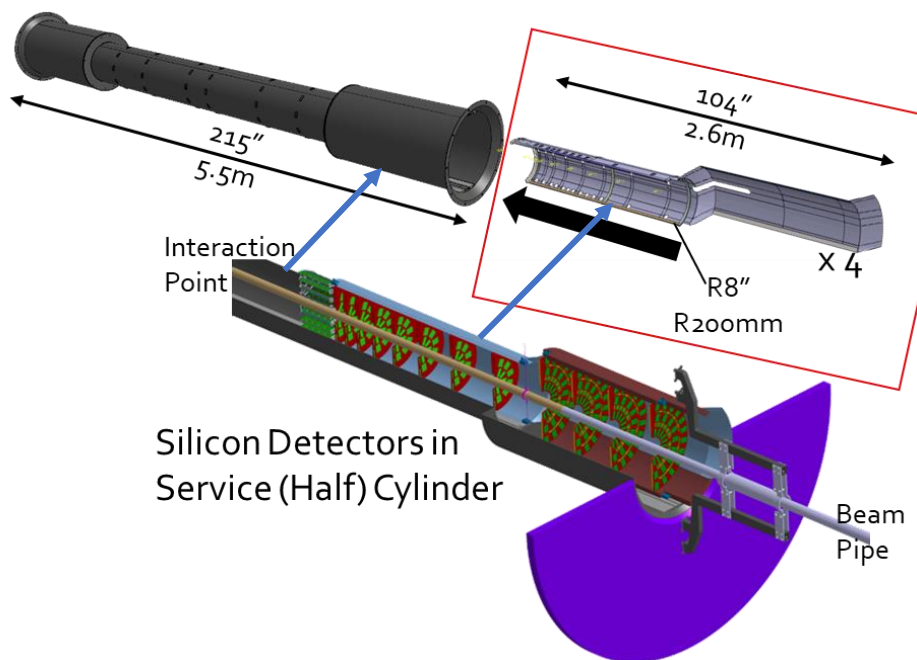
Compact Muon Solenoid detector at LHC-CERN



Terahertz Time Domain Spectroscopy – strain mapping

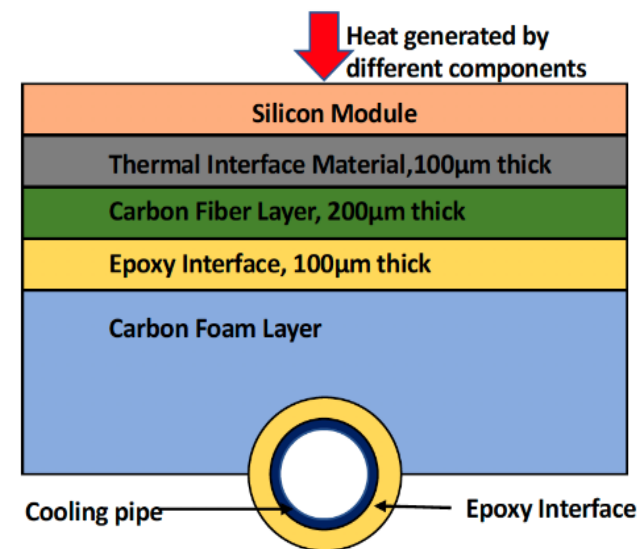


Measurement of thermal and mechanical strains non-destructively in a composite Dee detector



Schematic of Dee cross section

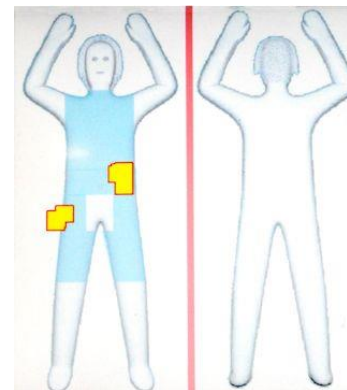
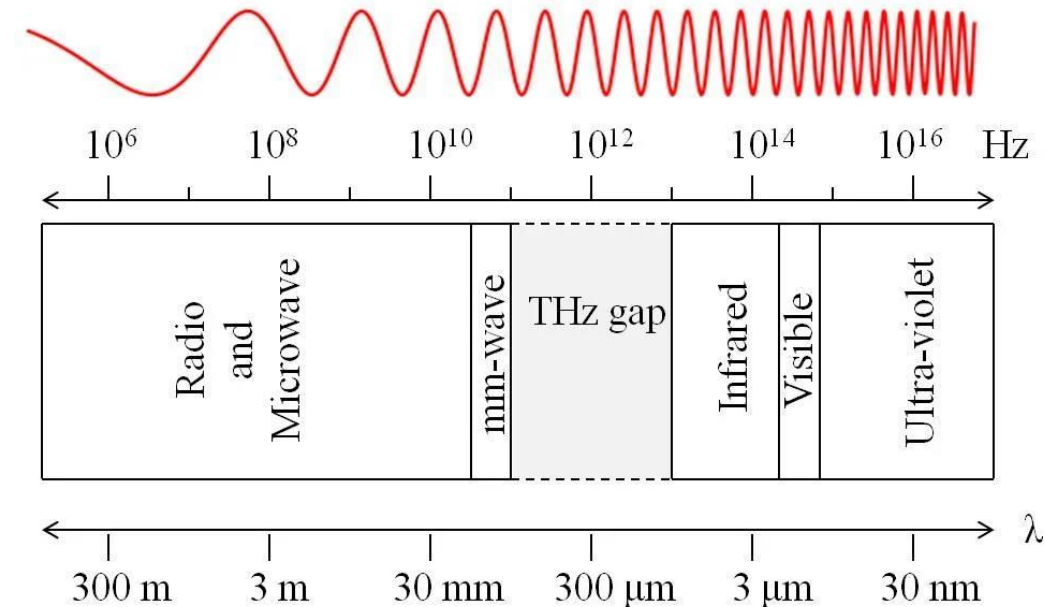
- Mechanical loads due to module weights
- Thermal loads due to CTE mismatch when Dee cooled to -35°C using CO_2 cooling



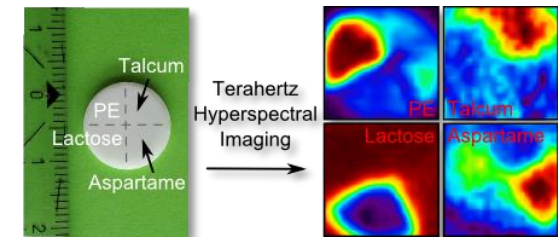
1. Introduction

- ⬢ Tera Hertz Time Domain Spectroscopy allows
 - ⬢ High transmission through visibly opaque materials
 - ⬢ High resolution while avoiding scattering
 - ⬢ High dynamic range, magnitude and phase recording with broad bandwidth
 - ⬢ Quantifying small changes in dielectric properties of media
- ⬢ Applications in security, chemistry, electronics, and now mechanics!

Ref: <https://www.allaboutcircuits.com/technical-articles/introduction-to-terahertz/>

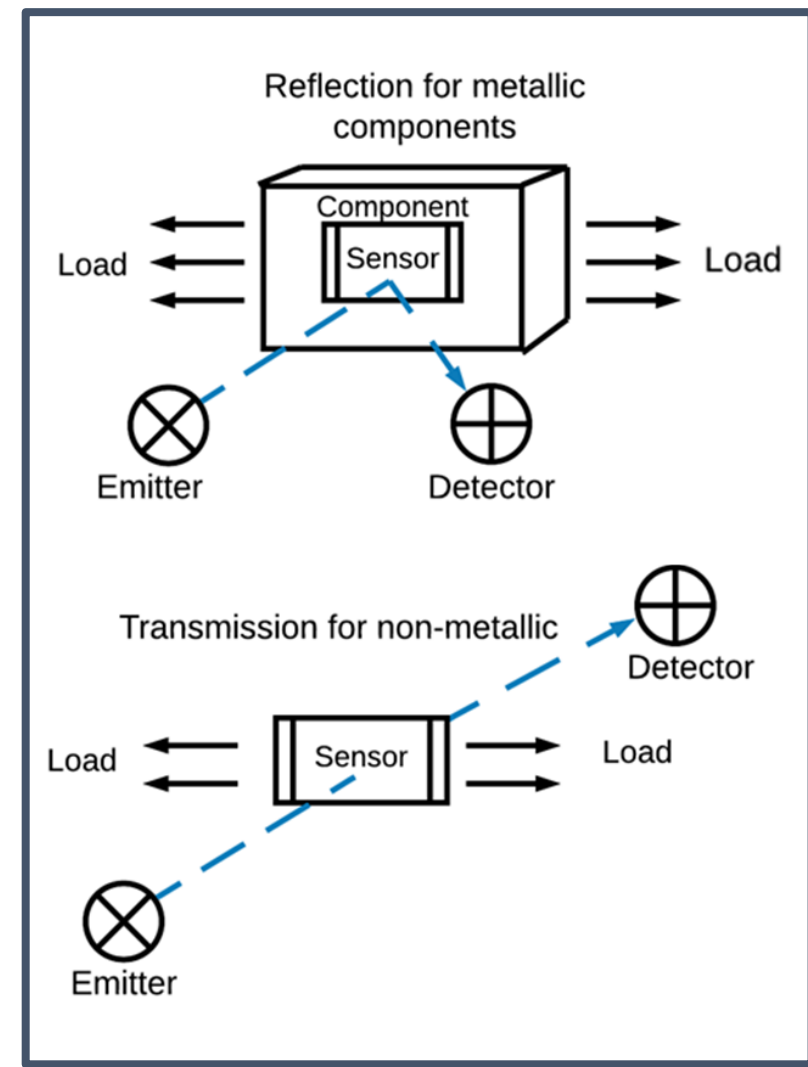
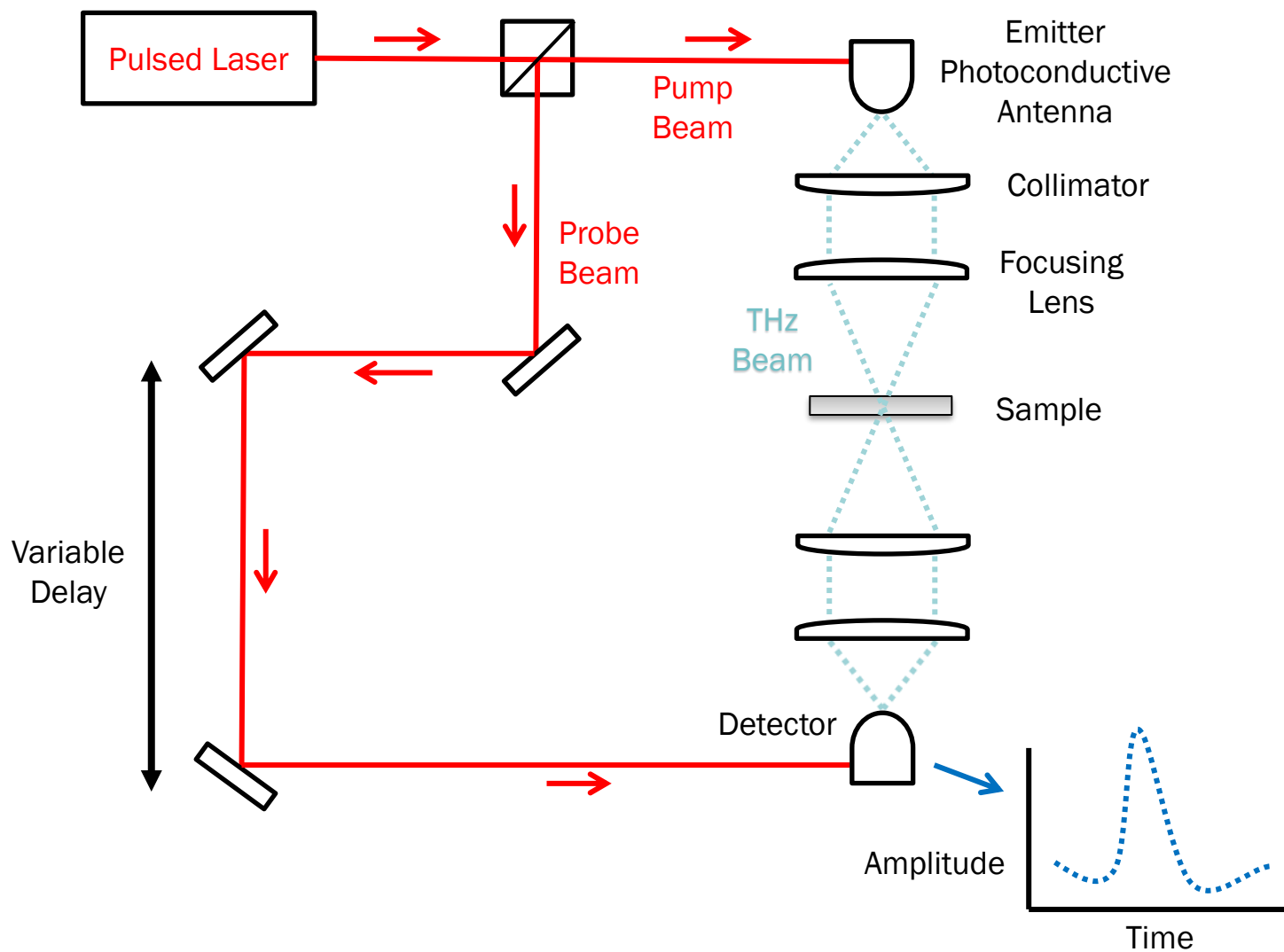


<https://physics.aps.org/articles/v13/15>

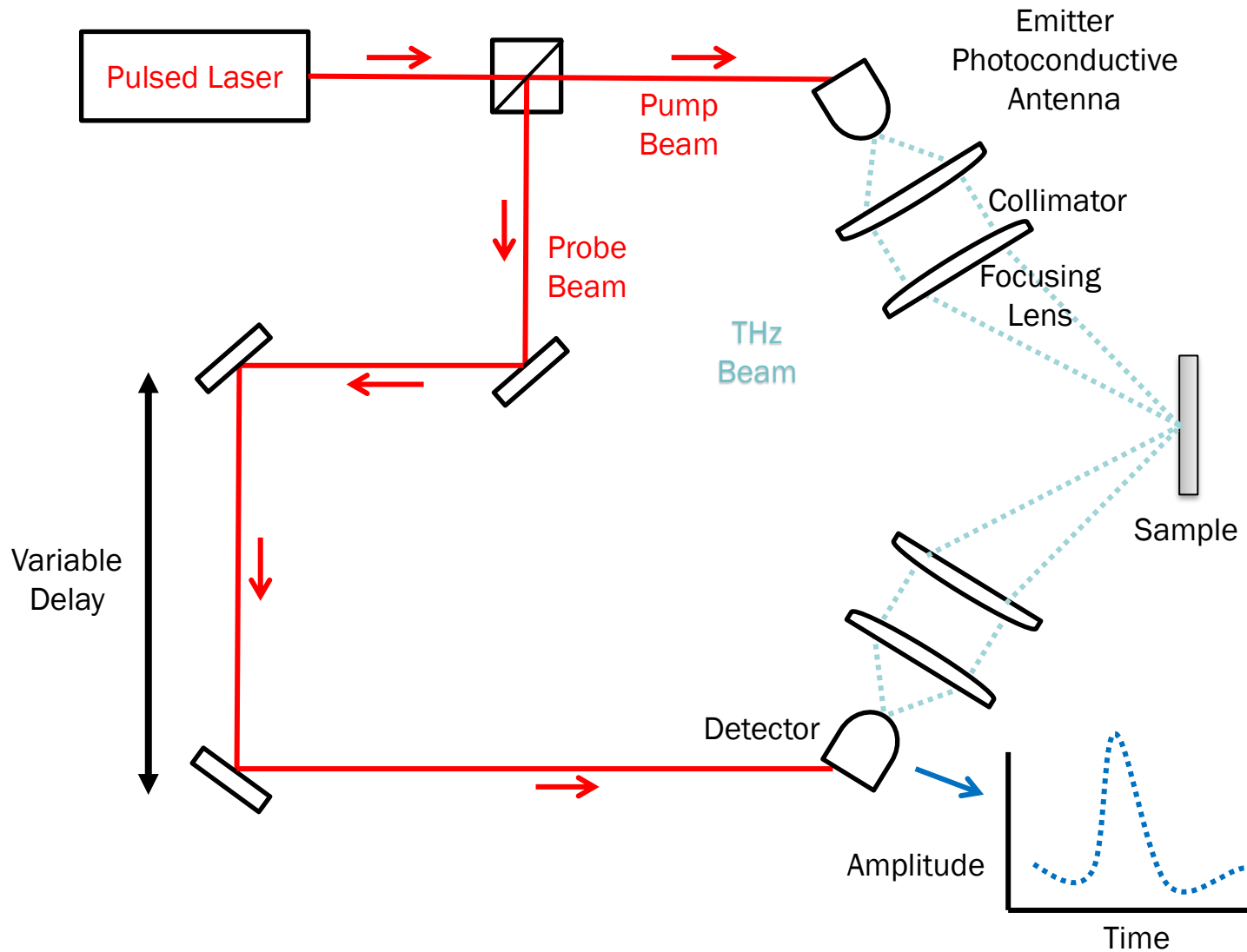


<https://www.recendt.at/en/THz.html>

Schematics for THz Spectroscopy set up



1. Introduction – Schematics for THz Spectroscopy set up



- ⬢ A THz TDS set-up samples the amplitude of the wave as it reaches the detector antenna
- ⬢ It works by splitting a pulsed laser for THz radiation generation into pump and probe beams and making a time domain measurements for the reflected/transmitted beam.
- ⬢ Our set-up produces a resolution of 0.4mm through focusing lenses – measured using the knife edge method

1. Introduction

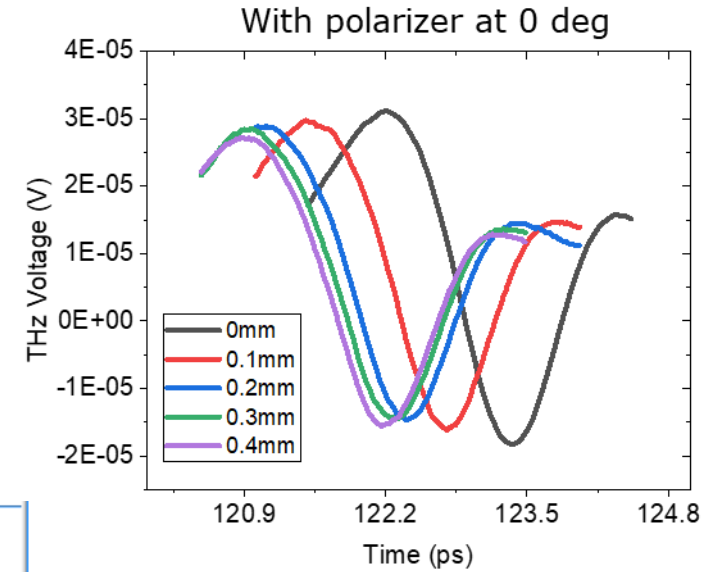
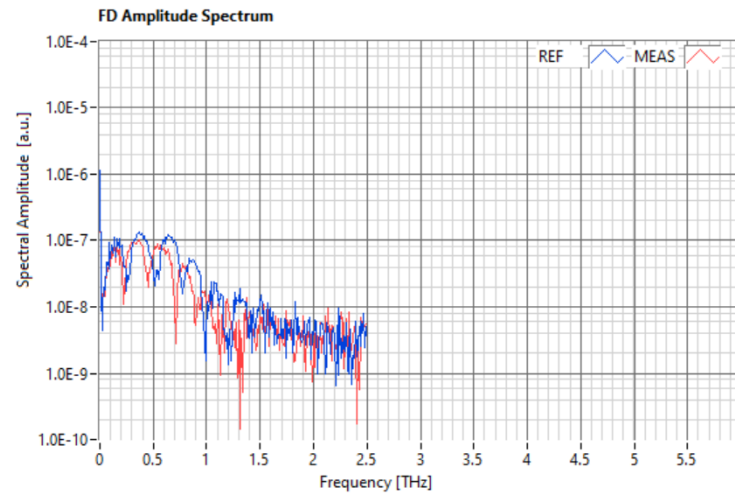
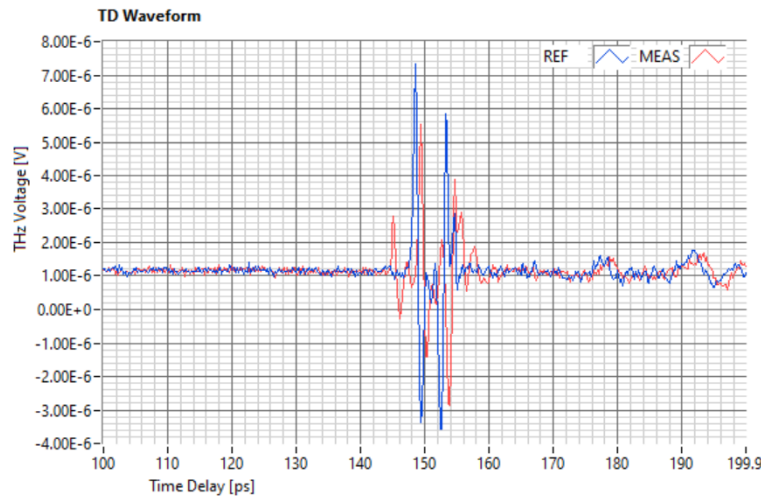
THz temporal wave form data measured at each loading step



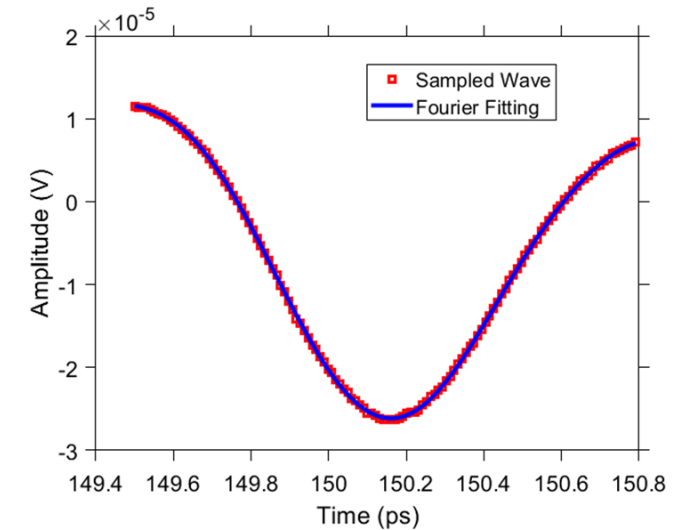
Curve smoothing and Fourier curve fitting to obtain peak positions



Computing ΔT_oA and correlation to strain response



THz wave form shift for deformation in a tensile test for dog bone specimen



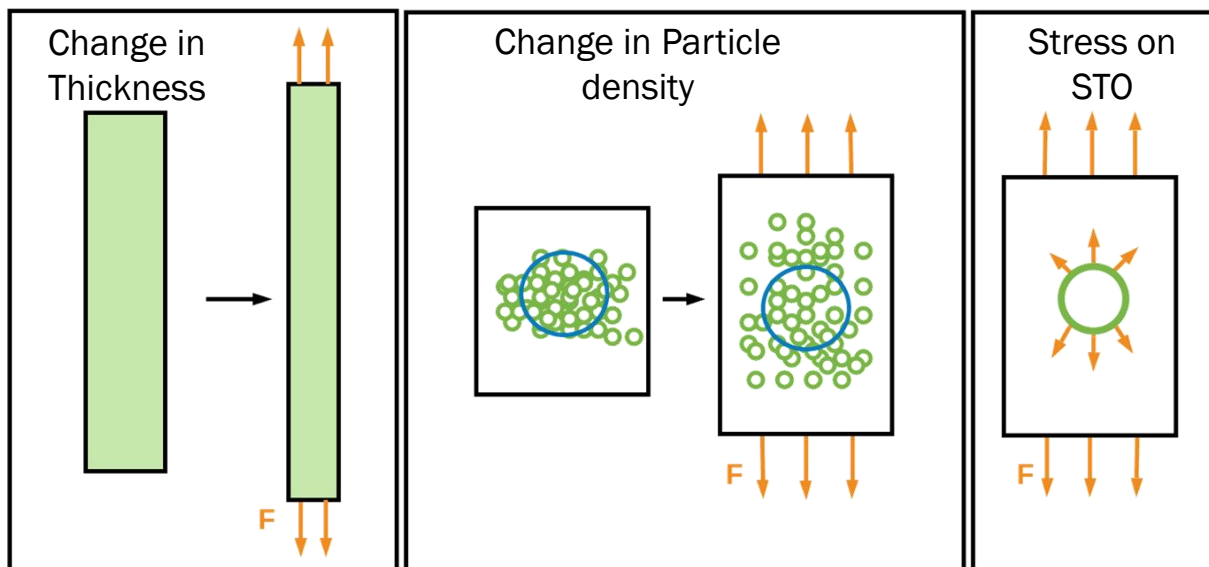
Literature Review: Other Remote Strain Sensing Methods

Strain Mapping Method	Comparison with THz TDS
Strain Gauges: <ul style="list-style-type: none"> • Optical Fiber Strain Sensors • Radio Wave Strain Sensors 	<ul style="list-style-type: none"> -Sensors are highly reliable and widely available -Low spatial resolution
Optical Whole-Field Techniques: <ul style="list-style-type: none"> • Holography • Laser Speckle • DIC • Moiré • CT Scanning 	<ul style="list-style-type: none"> -THz TDS will have lower resolution -THz TDS is not able to measure a whole-field at once -THz TDS could measure through opaque media
X-Ray Diffraction	<ul style="list-style-type: none"> -X-ray has high transmittivity and resolution -X-ray measures axial strain in a crystal -X-ray produces ionizing radiation
Raman Spectroscopy	<ul style="list-style-type: none"> -Raman has high resolution -Measures stresses -Does not penetrate opaque media

Presentation flow

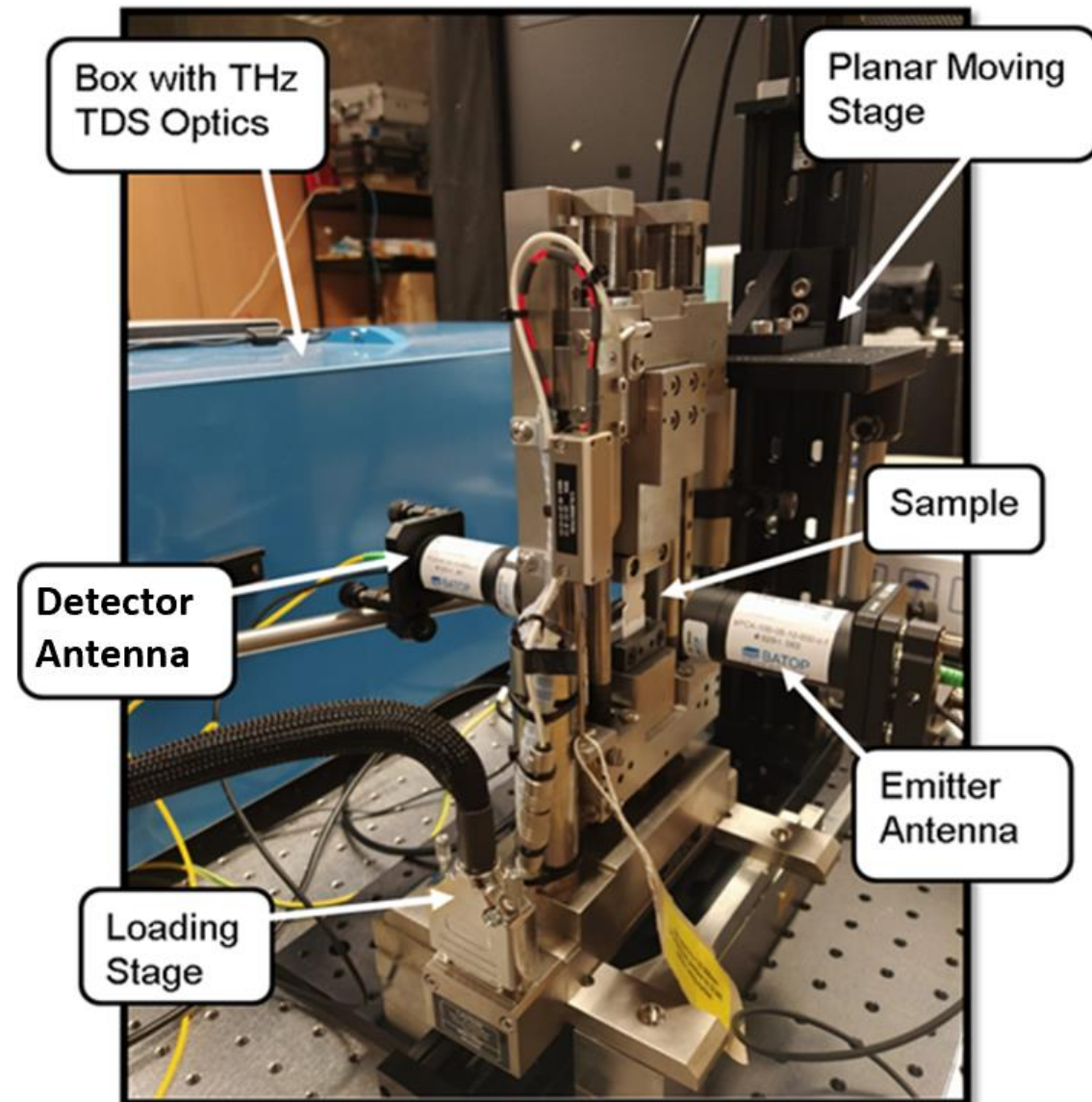
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THz Strain Measurement through STO Dielectrostrictive Composite



- ⬠ Our sensor consists of high dielectric strontium titanate (STO) particles dispersed in an elastomer matrix (8% by wt)
- ⬠ Strain will produce changes in the THz TDS response by:
 1. Change in thickness by Poisson's effect
 2. Dielectrostriction by change in high dielectric particles density.
 3. Dielectrostriction by stress on STO

Measuring the THz wave response in time domain at different strain levels - Transmission set up

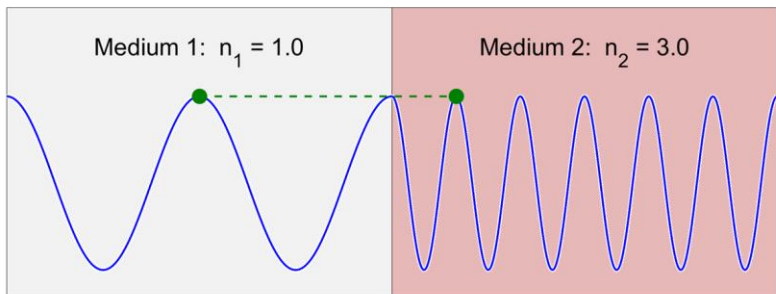


Mathematical modelling and data reduction

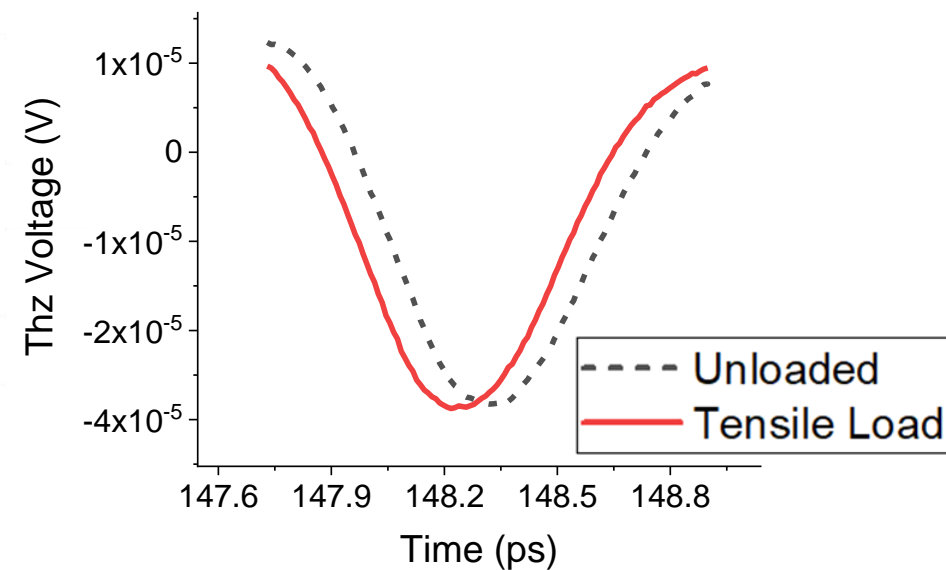
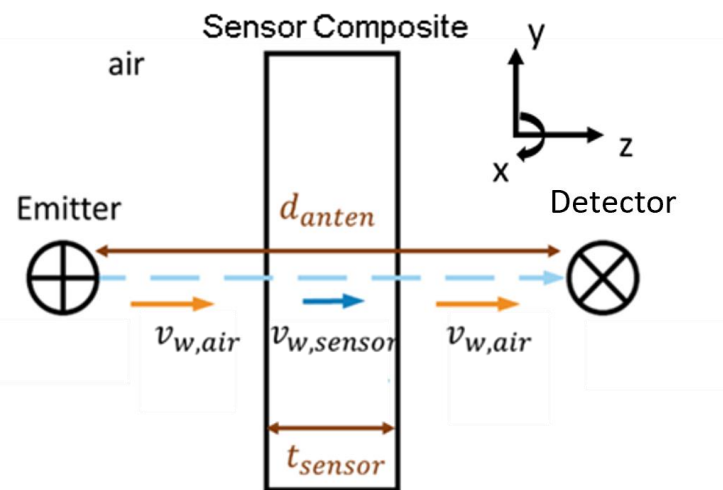
Velocity of wave in a media

$$v_w = \frac{c}{n} = \frac{c}{\sqrt{\epsilon_r \mu_r}} \approx \frac{c}{\sqrt{\epsilon_r}}$$

Time of arrival $ToA = \frac{d_{anten} - t_{sensor}}{v_{w,air}} + \frac{t_{sensor}}{v_{w,sensor}}$



<https://empossible.net/academics/emp4303/>



So, we measure $ToA_{xx}^{deformed}$ and $ToA_{xx}^{undeformed}$

Note that all the dielectric permittivities ϵ^0, a_1, a_2 (since $a_1, a_2 \rightarrow f(\epsilon^0, \epsilon^m)$) are directionally dependent. Using correlation equations, we compute the $\Delta ToA = ToA_{xx}^{deformed} - ToA_{xx}^{undeformed}$ simplified follows

$$\Delta ToA_{xx} \cdot \left(\frac{c}{t_0}\right) = \left(1 - \frac{v \cdot e_{vol}}{1 - 2\nu}\right) \cdot \left(\left(\epsilon^0 + a_1 \cdot \frac{-v \cdot e_{vol}}{1 - 2\nu} + a_2 \cdot (e_{vol}) \right)^{\frac{1}{2}} - 1 \right) + \sqrt{\epsilon^0} - 1$$

$$\Delta ToA_{yy} \cdot \left(\frac{c}{t_0}\right) = \left(1 - \frac{v \cdot e_{vol}}{1 - 2\nu}\right) \cdot \left(\left(\epsilon^0 + a_1 \cdot \frac{e_{vol}}{1 - 2\nu} + a_2 \cdot (e_{vol}) \right)^{\frac{1}{2}} - 1 \right) + \sqrt{\epsilon^0} - 1$$

Presentation flow

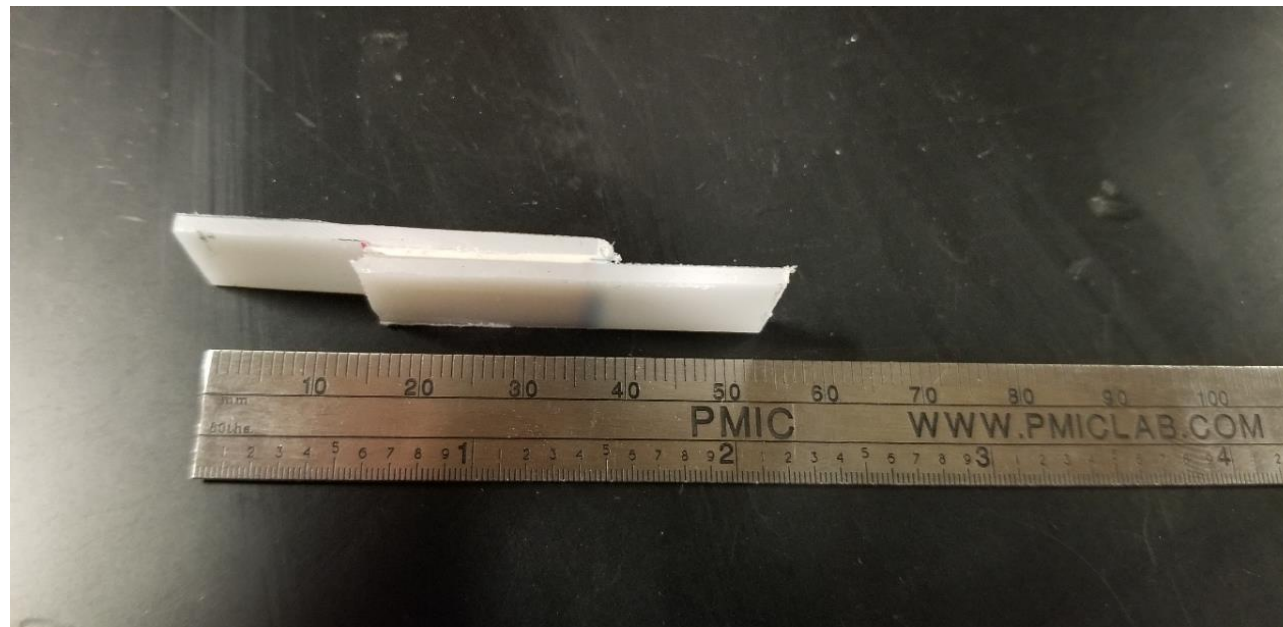
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Measurement of volumetric strain for a simple open hole tensile and lap shear specimens

Circular Hole Tensile Testing



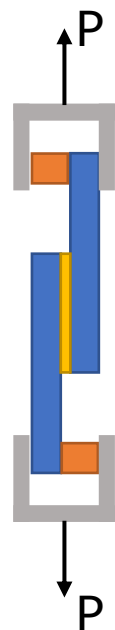
Lap Shear specimen



Experimental set up – STO (8% wt) + PDMS composite ‘adhesive’ on a HDPE base plate – transmission mode

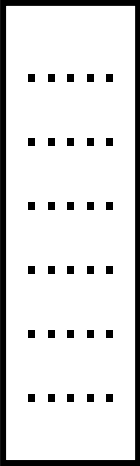
- HDPE strips
- STO + PDMS
- Spacer blocks for gripping

Single Lap Shear Testing

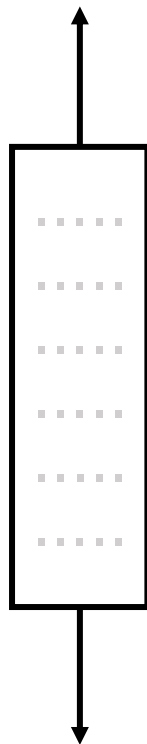


Measurement methodology

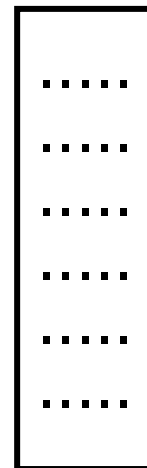
Initial Measurement – no strain



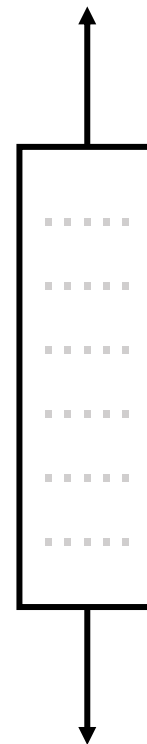
Strain step 1



THz wave Measurement

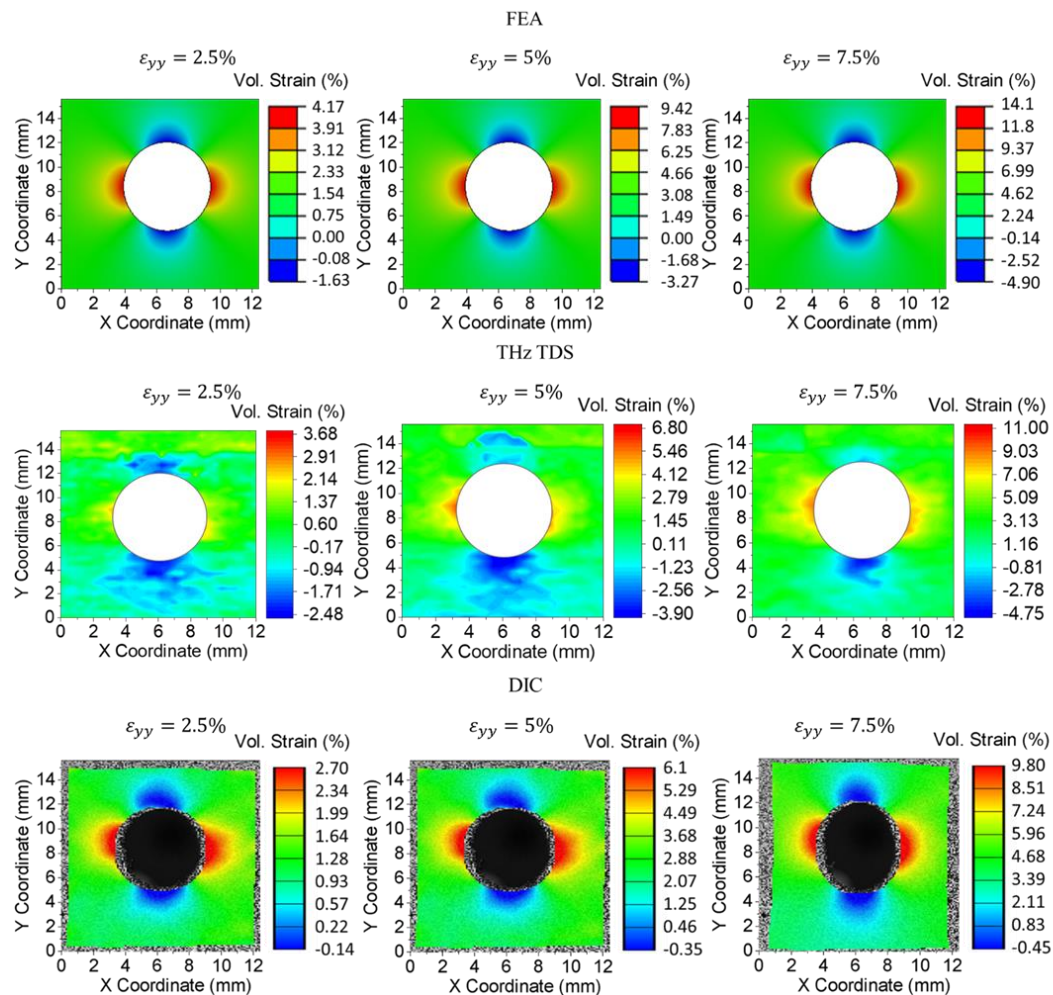


Strain step 2



..... and repeat

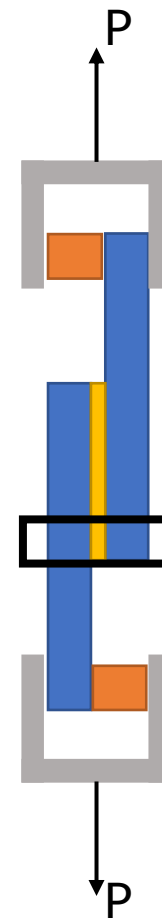
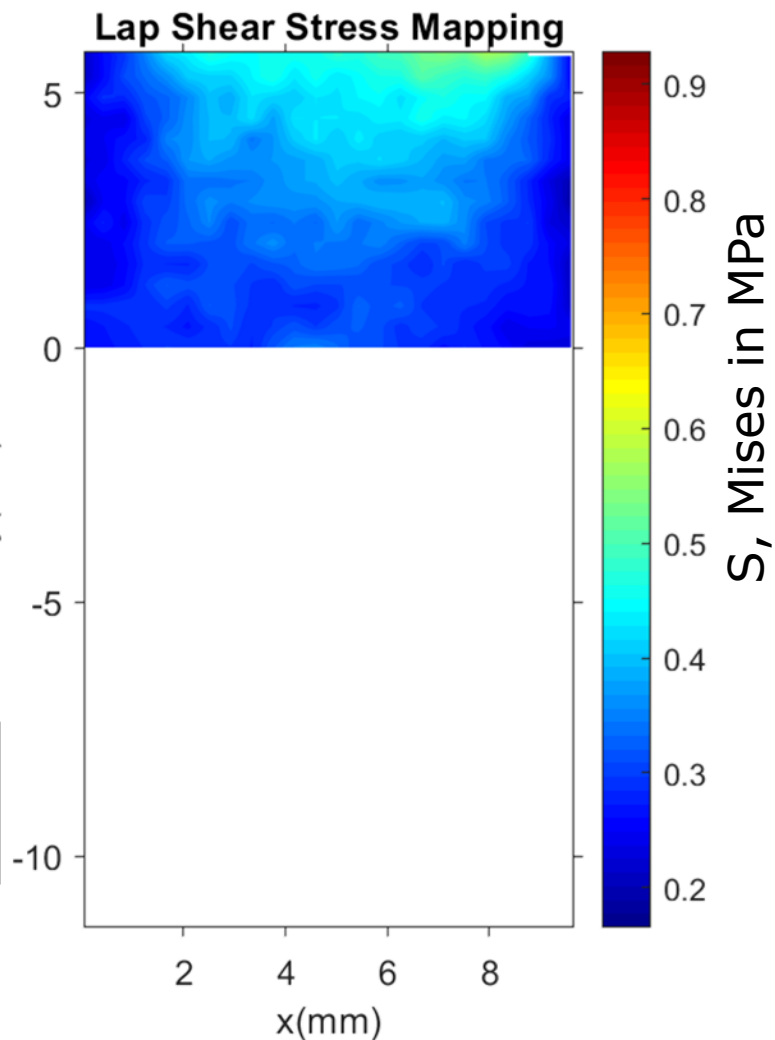
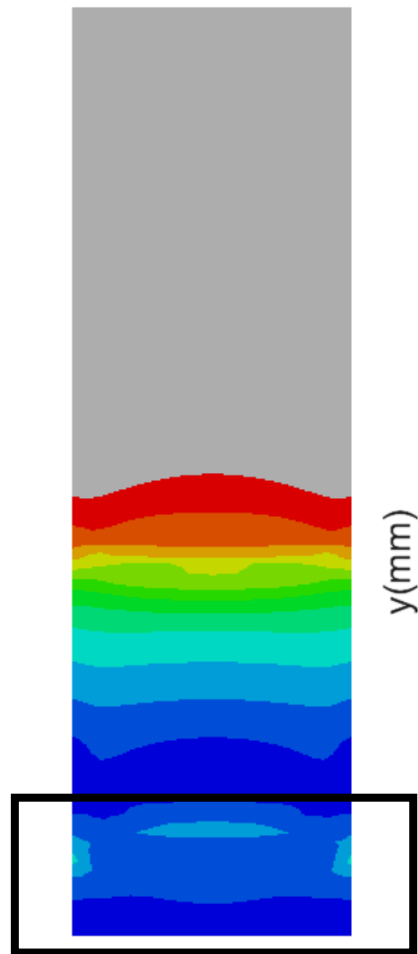
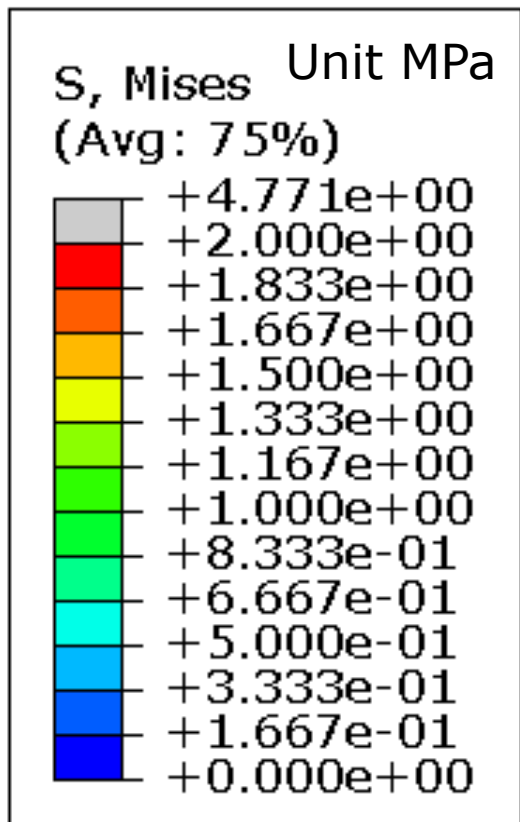
Open hole tensile test



Test results for a TRANSMISSION mode measurement with sample made from STO + PDMS

We can capture good results for tensile load cases. Good correlation seen between the THz-TDS measurements, FEA and DIC measurements

Lap Shear Test – FEA analysis – Cohesive surface model – comparison to THz- TDS scan



PRELIMINARY
RESULTS

Conclusions and summary

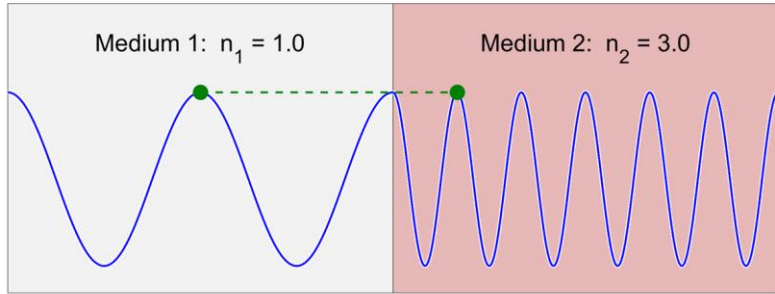
1. Tera-hertz time domain spectroscopy shows promise for interface strain and stress measurements by using passive sensor media, a baseline approach for the same has been established in this study.
2. The correlation of time or arrival and the strain/stress state in a loaded state (either thermal or mechanical or combined loading) is the novelty of this research.
3. Future research will enable in-situ measurement of interface strain in bi-material and multi-material interfaces.

Thank you

Questions ?

Back up slides

Mathematical modelling and data reduction



<https://empossible.net/academics/emp4303/>

v_w – velocity of wave

n – refractive index

ϵ_r – dielectric permittivity

$e_{vol}, e_{xx}, e_{yy}, e_{zz}$ – strains in local coordinate system

t_f, t_o – final thickness and initial thickness of sample

$\epsilon^0 = \epsilon^i$ – dielectric permittivity of undeformed composite (here PDMS + 8% STO)

ϵ_{eff} – effective dielectric permittivity of deformed composite as a function of strain

c – speed of light

μ_r – magnetic permeability

ToA – time of arrival of a wave

e_{11}, e_{22}, e_{33} – principal strains

ν – Poisson's ratio

ϵ^m – dielectric permittivity of matrix material (here PDMS)

d_{anten} – distance between the antennae

v_w – velocity of wave

n – refractive index

ϵ_r – dielectric permittivity

$e_{vol}, e_{xx}, e_{yy}, e_{zz}$ – strains in local coordinate system

t_f, t_o – final thickness and initial thickness of sample

$\epsilon^0 = \epsilon^i$ – dielectric permittivity of undeformed composite (here PDMS + 8% STO)

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e_{11}, e_{22}, e_{33} – principal strains

ν – Poisson's ratio

ϵ^m – dielectric permittivity of matrix material (here PDMS)

d_{anten} – distance between the antennae

The velocity of a wave in a media is given by

$$v_w = \frac{c}{n} = \frac{c}{\sqrt{\epsilon_r \mu_r}} \approx \frac{c}{\sqrt{\epsilon_r}} \quad (\text{i.})$$

The volumetric strain in a thin plate can be approximated to

$$e_{vol} = e_{xx} + e_{yy} + e_{zz} \quad (\text{ii.})$$

$$e_{xx} = \frac{-\nu \cdot e_{vol}}{1 - 2\nu}$$

$$e_{yy} = \frac{e_{vol}}{1 - 2\nu}$$

$$e_{zz} = \frac{-\nu \cdot e_{vol}}{1 - 2\nu}$$

On tensile loading of the sample there is a thickness change in the sample that is given by

$$t_f = t_0 \left(1 - \frac{\nu \cdot e_{vol}}{1 - 2\nu} \right) \quad (\text{iii.})$$

The effective dielectric permittivity will be dependent on the volumetric strain at each step and is given by Shkel Y.M. and Klingenberg D.J. (1998) as follows

$$\varepsilon_{ij} = \varepsilon^0 \cdot \delta_{ij} + a_1 \cdot e_{ij} + a_2 \cdot e_{kk} \cdot \delta_{ij} \rightarrow \begin{cases} \varepsilon_{11} = \varepsilon^0 + a_1 \cdot e_{11} + a_2 \cdot (e_{vol}) \\ \varepsilon_{22} = \varepsilon^0 + a_1 \cdot e_{22} + a_2 \cdot (e_{vol}) \\ \varepsilon_{33} = \varepsilon^0 + a_1 \cdot e_{33} + a_2 \cdot (e_{vol}) \end{cases} \quad (iv.)$$

$$a_1 = -\frac{2}{5} \frac{(\varepsilon^0 - \varepsilon^m)^2}{\varepsilon^m}$$

$$a_2 = -\frac{1}{3} \frac{(\varepsilon^i - \varepsilon^m)(\varepsilon^i + 2\varepsilon^m)}{\varepsilon^m} + \frac{2}{15} \frac{(\varepsilon^i - \varepsilon^m)^2}{\varepsilon^m}$$

The time of arrival of a wave is given by

$$ToA = \frac{d_{anten} - t_{sensor}}{v_{w,air}} + \frac{t_{sensor}}{v_{w,sensor}} \quad (v.)$$

Hence for undeformed sample with no strain, which is the initial case we have

$$ToA^{undeformed} = \frac{d_{anten}}{c} - \frac{t_o}{c} + \frac{t_o}{c} \sqrt{\varepsilon^0} \quad (vi.)$$

for the deformed sample we use the final thickness given by equation iii.

$$T_{oA}_{xx}^{deformed} = \frac{d_{anten}}{c} - \frac{t_f}{c} + \frac{t_f}{c} \sqrt{\varepsilon_{11}} \quad (\text{vii.})$$

$$T_{oA}_{xx}^{deformed} = \frac{d_{anten}}{c} - \frac{t_0 \left(1 - \frac{\nu \cdot e_{vol}}{1 - 2\nu}\right)}{c} + \frac{t_0 \left(1 - \frac{\nu \cdot e_{vol}}{1 - 2\nu}\right)}{c} \sqrt{\varepsilon^0 + a_1 \cdot \frac{-\nu \cdot e_{vol}}{1 - 2\nu} + a_2 \cdot (e_{vol})}$$

Note that all the dielectric permittivities ε^0, a_1, a_2 (since $a_1, a_2 \rightarrow f(\varepsilon^0, \varepsilon^m)$) are directionally dependent. Using these equations, we compute the $\Delta T_{oA} = T_{oA}_{xx}^{deformed} - T_{oA}_{xx}^{undeformed}$ simplified follows

$$\Delta T_{oA}_{xx} \cdot \left(\frac{c}{t_0}\right) = \left(1 - \frac{\nu \cdot e_{vol}}{1 - 2\nu}\right) \cdot \left(\left(\varepsilon^0 + a_1 \cdot \frac{-\nu \cdot e_{vol}}{1 - 2\nu} + a_2 \cdot (e_{vol}) \right)^{\frac{1}{2}} - 1 \right) + \sqrt{\varepsilon^0} - 1$$

$$\Delta T_{oA}_{yy} \cdot \left(\frac{c}{t_0}\right) = \left(1 - \frac{\nu \cdot e_{vol}}{1 - 2\nu}\right) \cdot \left(\left(\varepsilon^0 + a_1 \cdot \frac{e_{vol}}{1 - 2\nu} + a_2 \cdot (e_{vol}) \right)^{\frac{1}{2}} - 1 \right) + \sqrt{\varepsilon^0} - 1$$

(viii.)

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