

Physical thresholds and cluster decomposition

Zeno Capatti ETH Zürich

Amplitudes 2023 07/06/2023, CERN, Switzerland



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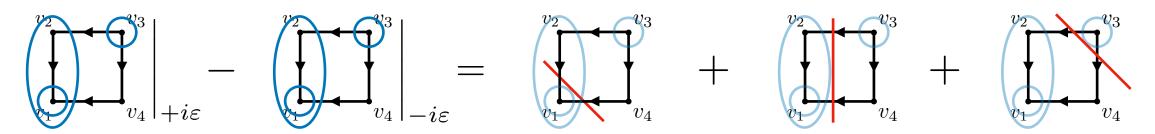
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First part: Cross-Free Families

- Sketch the derivation of the representation

$$f_{G_u}^{3d} = \int \left[\prod_{i=1}^{L} \frac{dk_i^0}{2\pi} \right] \frac{\mathcal{N}(\{q_e^0\}_{e \in \mathcal{E}})}{\prod_{e \in \mathcal{E}} (q_e^0)^2 - E_e^2}$$

- Highlight role of connectedness by comparison with Time-Ordered Perturbation Theory



(spurious singularities in TOPT)

Notation

Energy conservation

Acyclic graphs

We start with an arbitrary diagram integrated over loop energies only

Energy conservation

$$f_{G_u}^{3\mathrm{d}} = \int \left[\prod_{i=1}^L \frac{\mathrm{d}k_i^0}{2\pi} \right] \frac{\mathcal{N}(\{q_e^0\}_{e \in \mathcal{E}})}{\prod_{e \in \mathcal{E}} (q_e^0)^2 - E_e^2} \qquad \qquad \begin{aligned} q_e^0 &= p_e^0 + \sum_{i=1}^L s_{ei}k_i^0 & G_u \text{ undirected graph} \\ E_e &= \sqrt{|\vec{q}_e|^2 + m_e^2} & \mathcal{E} \text{ set of edges of graph} \end{aligned}$$

$$q_e^0 = p_e^0 + \sum_{i=1}^L s_{ei} k_i^0$$

$$G_u$$
 undirected graph

$${\mathcal E}$$
 set of edges of graph

Acyclic graphs

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Acyclic graphs and edge contraction

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Performing the integrals using residue theorem is a matter of correctly addressing energy conservation (depending on how, get TOPT, LTD, CFF). For CFF (zc [arXiv:2211.09653]):

$$\frac{1}{(q_e^0)^2 - E_e^2} = \int dx_e d\tau_e \frac{e^{i\tau_e(x_e - q_e^0)}}{x_e^2 - E_e^2}$$

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Acyclic graphs

After insertion of this identity, loop energy integrations are trivial (dependence is only in exponents)

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$$f_{G_u}^{3d} = \sum_{\substack{\text{directed graph } G}} \frac{\mathcal{N}_G}{\prod_{e \in \mathcal{E}} 2E_e} \int_{\mathcal{K}_G} \left[\prod_{e \in \mathcal{E}} d\tau_e e^{i\tau_e (E_e - p_e^G)} \right]$$

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$$f_{G_u}^{3d} = \sum_{\substack{\text{directed} \\ G \text{ or } G \text{ or } G}} \frac{\mathcal{N}_G}{\prod_{e \in \mathcal{E}} 2E_e} \int_{\mathcal{K}_G} \left[\prod_{e \in \mathcal{E}} \mathrm{d}\tau_e e^{i\tau_e(E_e - p_e^G)} \right] \quad \text{with} \quad \mathcal{K}_G = \left\{ (\tau_e)_{e \in \mathcal{E}} \in \mathbb{R}_+^{|\mathcal{E}|} \middle| \sum_{e \in \mathcal{E}} s_{ei}^G \tau_e = 0, \ i = 1, ..., L \right\}$$

Notation

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$$f_{G_u}^{3\mathrm{d}} = \int \left[\prod_{i=1}^L \frac{\mathrm{d}k_i^0}{2\pi} \right] \frac{\mathcal{N}(\{q_e^0\}_{e \in \mathcal{E}})}{\prod_{e \in \mathcal{E}} (q_e^0)^2 - E_e^2} \qquad \qquad \begin{aligned} q_e^0 &= p_e^0 + \sum_{i=1}^L s_{ei}k_i^0 & G_u \text{ undirected graph} \\ E_e &= \sqrt{|\vec{q}_e|^2 + m_e^2} & \mathcal{E} \text{ set of edges of graph} \end{aligned}$$

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Acyclic graphs

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 (\mathcal{K}_G) is empty if graph not acyclic)

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Acyclic graphs

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with
$$\mathcal{K}_G = \left\{ (\tau_e)_{e \in \mathcal{E}} \in \mathbb{R}_+^{|\mathcal{E}|} \middle| \sum_{e \in \mathcal{E}} s_{ei}^G \tau_e = 0, i = 1, ..., L \right\}$$

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$$f_{G_u}^{3d} = \sum_{\substack{\text{acyclic} \\ \text{graph } C}} \frac{\mathcal{N}_G}{\prod_{e \in \mathcal{E}} 2E_e} \int_{\mathcal{K}_G} \left[\prod_{e \in \mathcal{E}} d\tau_e e^{i\tau_e(E_e - p_e^G)} \right] \text{ with } \mathcal{K}_G = \left\{ (\tau_e)_{e \in \mathcal{E}} \in \mathbb{R}_+^{|\mathcal{E}|} \middle| \sum_{e \in \mathcal{E}} s_{ei}^G \tau_e = 0, i = 1, ..., L \right\}$$

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(\mathcal{K}_G is empty if graph not acyclic)

$$\underbrace{e_1 \left(e_4 + e_5\right)}_{e_3} e_2 \quad \tau_i > 0, \ i = 1, ..., 6 \quad \tau_2 + \tau_6 + \tau_5 = 0 \quad \tau_1 + \tau_2 + \tau_3 = 0 \quad \tau_3 + \tau_4 - \tau_6 = 0$$

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Diagrammatically
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Acyclic graphs

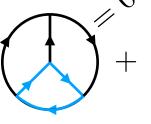
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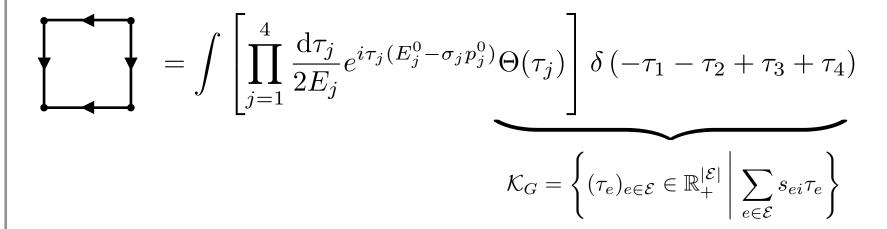
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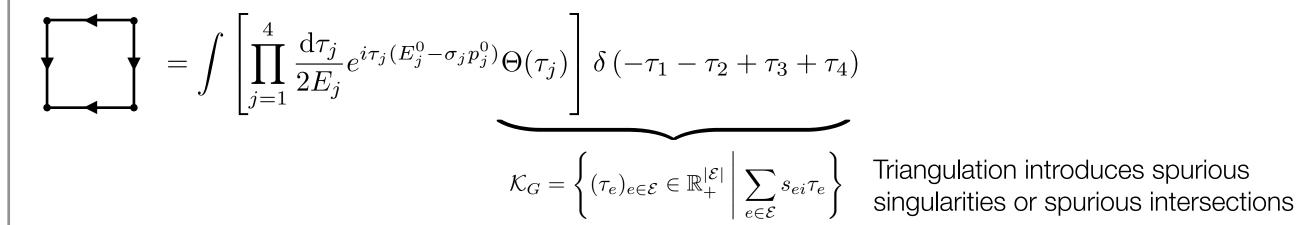
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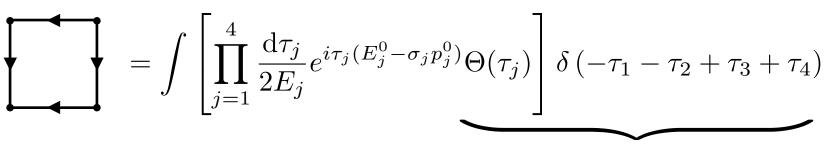


Position space: Fourier duality maps acyclic graphs to strongly-connected graphs

$$= \int \left[\prod_{j=1}^{4} \frac{d\tau_{j}}{2E_{j}} e^{i\tau_{j}(E_{j}^{0} - \sigma_{j}p_{j}^{0})} \Theta(\tau_{j}) \right] \delta(-\tau_{1} - \tau_{2} + \tau_{3} + \tau_{4})$$

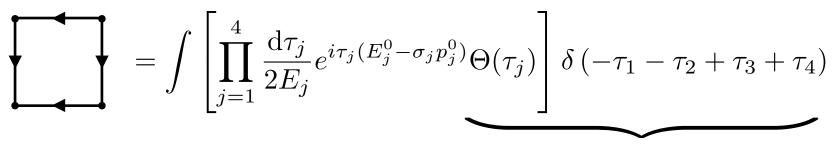






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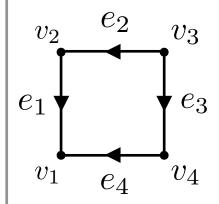
Edge contraction

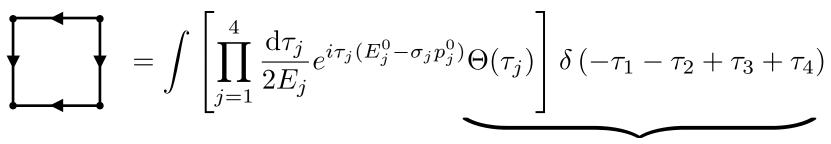
$$= \int \left[\prod_{j=1}^{4} \frac{\mathrm{d}\tau_j}{2E_j} e^{i\tau_j (E_j^0 - \sigma_j p_j^0)} \Theta(\tau_j) \right] \delta(-\tau_1 - \tau_2 + \tau_3 + \tau_4)$$

$$\mathcal{K}_G = \left\{ (\tau_e)_{e \in \mathcal{E}} \in \mathbb{R}_+^{|\mathcal{E}|} \middle| \sum_{e \in \mathcal{E}} s_{ei} \tau_e \right\}$$

 $\mathcal{K}_G = \left\{ (\tau_e)_{e \in \mathcal{E}} \in \mathbb{R}_+^{|\mathcal{E}|} \, \middle| \, \sum_{e \in \mathcal{E}} s_{ei} \tau_e \right\} \quad \text{Triangulation introduces spurious singularities or spurious intersections}$

Edge contraction



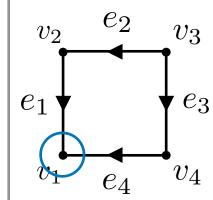


$$\mathcal{K}_G = \left\{ (\tau_e)_{e \in \mathcal{E}} \in \mathbb{R}_+^{|\mathcal{E}|} \, \middle| \, \sum_{e \in \mathcal{E}} s_{ei} \tau_e \right\}$$

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Edge contraction

How do we perform the remaining integrations (one for each edge)? Edge-contraction



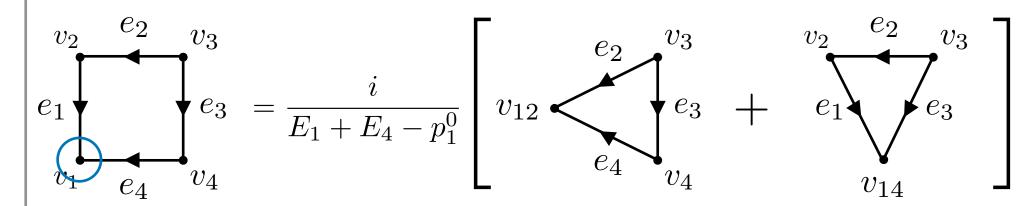
1. Choose sink/source with connected complement

$$= \int \left[\prod_{j=1}^{4} \frac{\mathrm{d}\tau_j}{2E_j} e^{i\tau_j (E_j^0 - \sigma_j p_j^0)} \Theta(\tau_j) \right] \delta(-\tau_1 - \tau_2 + \tau_3 + \tau_4)$$

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Edge contraction



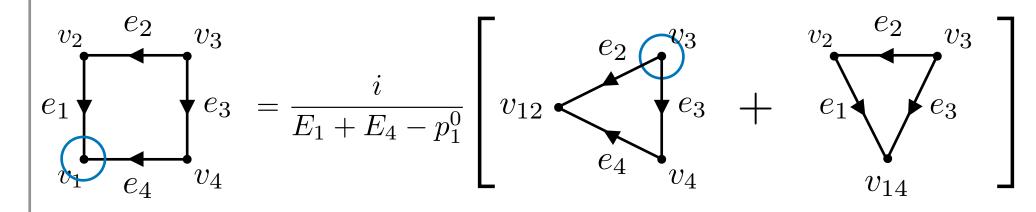
- 1. Choose sink/source with connected complement
- 2. Contract one-by-one adjacent edges
- 3. Multiply by inverse sum of energies of adjacent edges

$$= \int \left[\prod_{j=1}^{4} \frac{\mathrm{d}\tau_j}{2E_j} e^{i\tau_j (E_j^0 - \sigma_j p_j^0)} \Theta(\tau_j) \right] \delta(-\tau_1 - \tau_2 + \tau_3 + \tau_4)$$

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Edge contraction



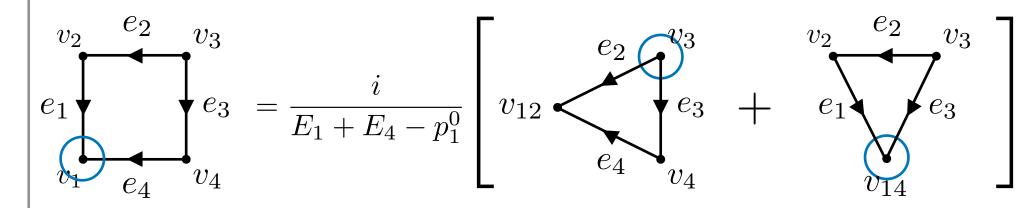
- 1. Choose sink/source with connected complement
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Edge contraction



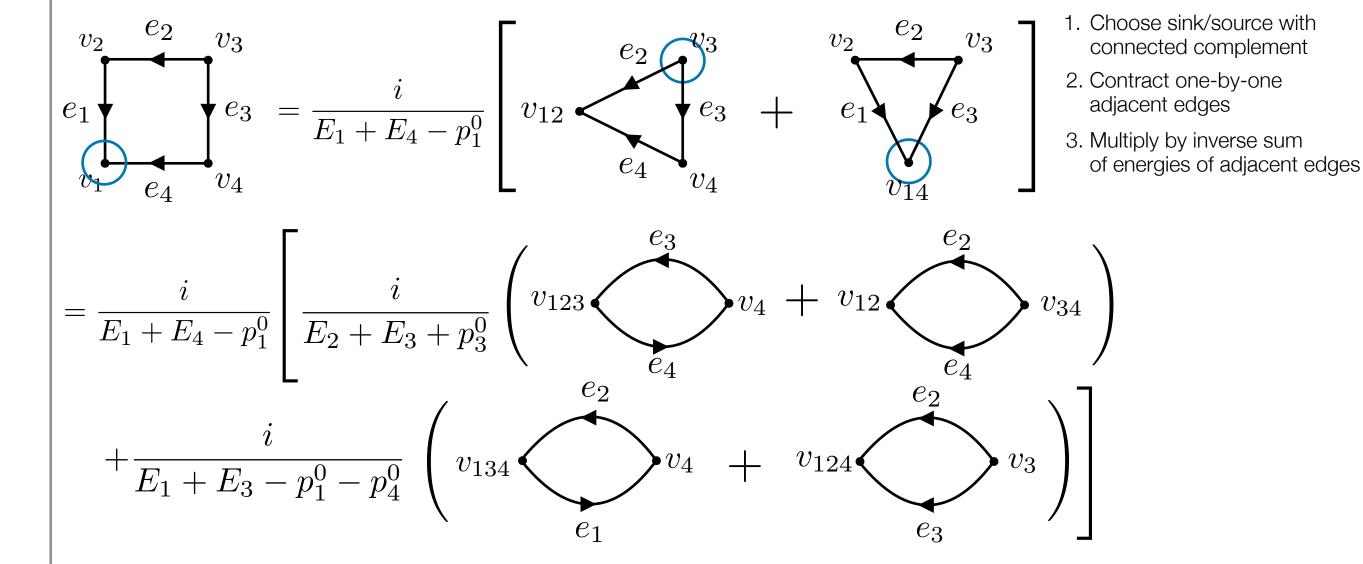
- 1. Choose sink/source with connected complement
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$$= \int \left[\prod_{j=1}^{4} \frac{\mathrm{d}\tau_j}{2E_j} e^{i\tau_j (E_j^0 - \sigma_j p_j^0)} \Theta(\tau_j) \right] \delta(-\tau_1 - \tau_2 + \tau_3 + \tau_4)$$

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Edge contraction

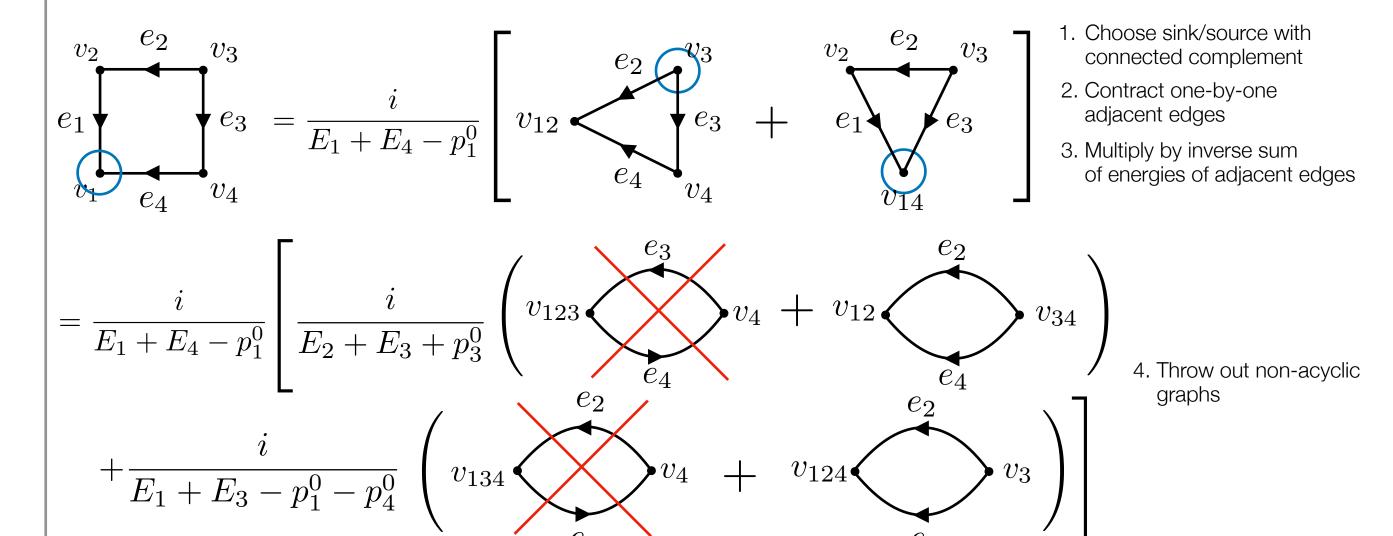


$$= \int \left[\prod_{j=1}^{4} \frac{\mathrm{d}\tau_j}{2E_j} e^{i\tau_j (E_j^0 - \sigma_j p_j^0)} \Theta(\tau_j) \right] \delta(-\tau_1 - \tau_2 + \tau_3 + \tau_4)$$

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Edge contraction

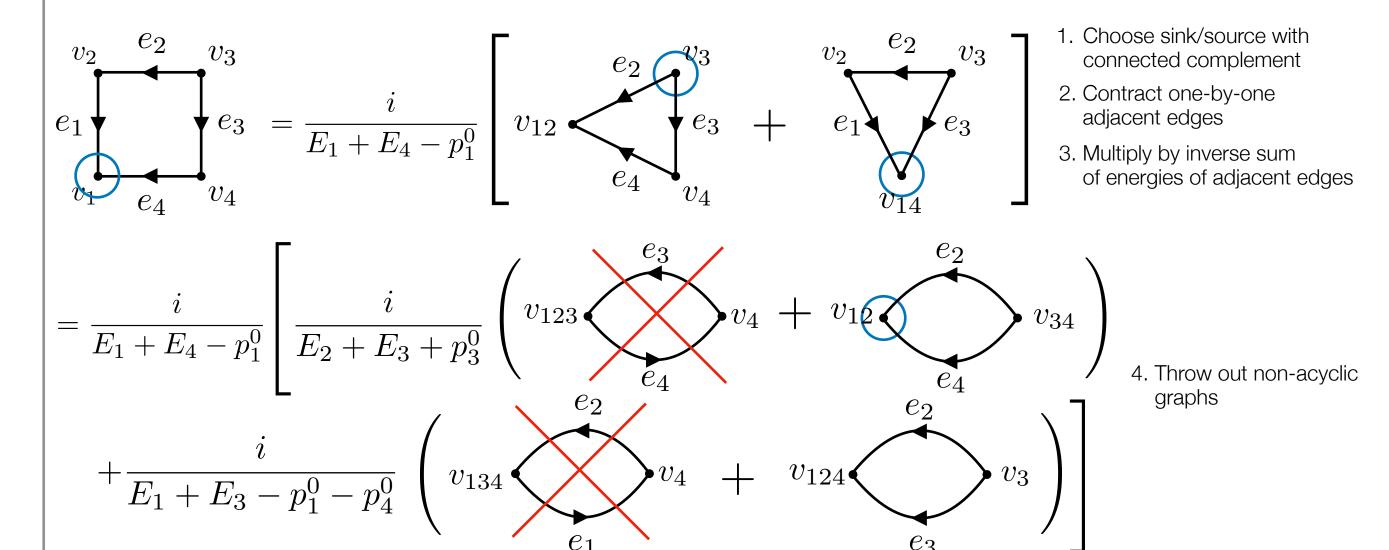


$$= \int \left[\prod_{j=1}^{4} \frac{\mathrm{d}\tau_j}{2E_j} e^{i\tau_j (E_j^0 - \sigma_j p_j^0)} \Theta(\tau_j) \right] \delta(-\tau_1 - \tau_2 + \tau_3 + \tau_4)$$

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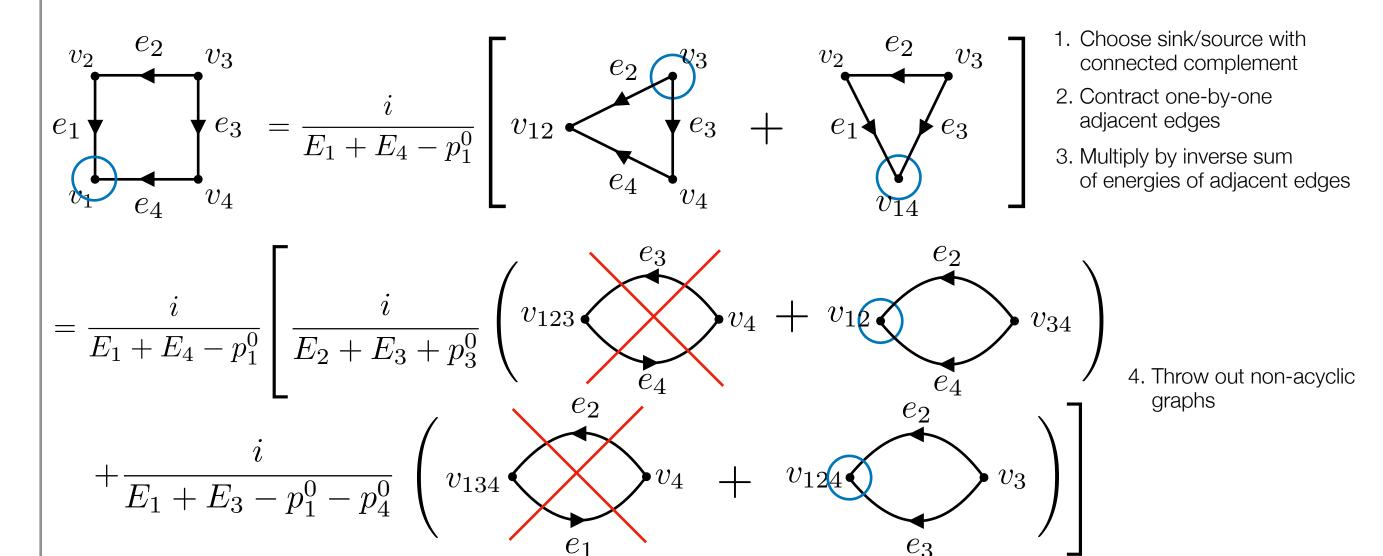


$$= \int \left[\prod_{j=1}^{4} \frac{\mathrm{d}\tau_j}{2E_j} e^{i\tau_j (E_j^0 - \sigma_j p_j^0)} \Theta(\tau_j) \right] \delta(-\tau_1 - \tau_2 + \tau_3 + \tau_4)$$

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Edge contraction

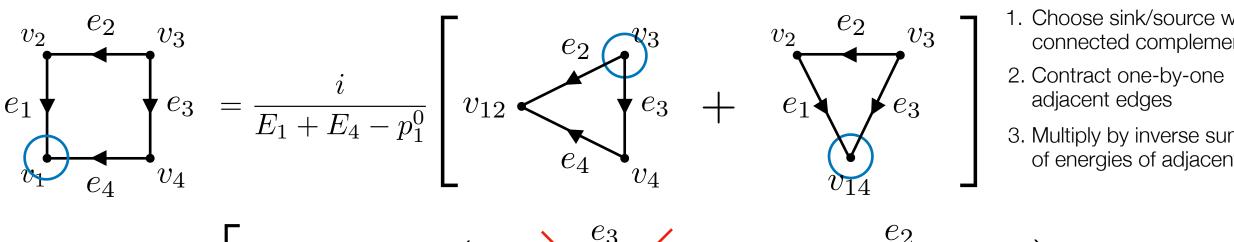


$$= \int \left[\prod_{j=1}^{4} \frac{\mathrm{d}\tau_j}{2E_j} e^{i\tau_j (E_j^0 - \sigma_j p_j^0)} \Theta(\tau_j) \right] \delta\left(-\tau_1 - \tau_2 + \tau_3 + \tau_4\right)$$

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 $\mathcal{K}_G = \left\{ (\tau_e)_{e \in \mathcal{E}} \in \mathbb{R}_+^{|\mathcal{E}|} \middle| \sum_{e \in \mathcal{E}} s_{ei} \tau_e \right\}$ Triangulation introduces spurious singularities or spurious intersections

Edge contraction



- 1. Choose sink/source with connected complement
- 3. Multiply by inverse sum

$$=\frac{i}{E_1+E_4-p_1^0}\left[\frac{i}{E_2+E_3+p_3^0}\underbrace{v_{123}}_{e_4}v_4+v_{12}\underbrace{v_{24}}_{e_4}v_4\right] \qquad \text{of energies of adjacent edges}$$

$$+\frac{i}{E_1+E_3-p_1^0-p_4^0}\underbrace{v_{134}}_{e_1}\underbrace{v_{24}}_{e_4}v_4+v_{124}\underbrace{v_{24}}_{e_3}v_3\right] \qquad \text{4. Throw out non-acyclic graphs}$$

$$=\frac{i}{E_1+E_4-p_1^0}\left[\frac{i}{E_2+E_3+p_3^0}\underbrace{v_{134}}_{E_2+E_3+p_3^0}\underbrace{v_{134}}_{E_2+E_4-p_1^0-p_2^0}+\frac{i}{E_1+E_3-p_1^0-p_3^0}\underbrace{v_{124}}_{E_2+E_3+p_3^0}\right]$$

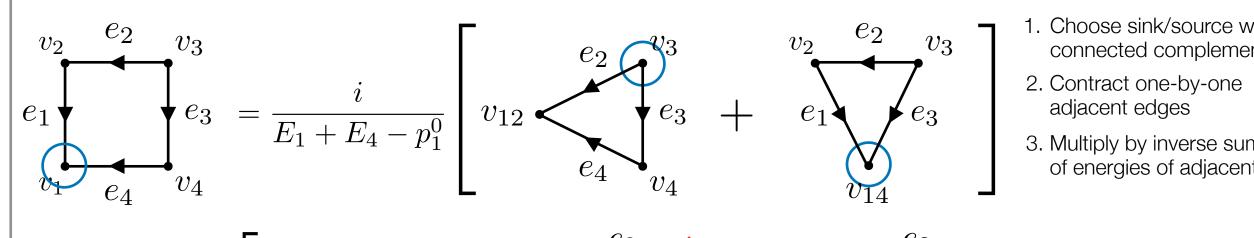
$$= \int \left[\prod_{j=1}^{4} \frac{\mathrm{d}\tau_j}{2E_j} e^{i\tau_j (E_j^0 - \sigma_j p_j^0)} \Theta(\tau_j) \right] \delta(-\tau_1 - \tau_2 + \tau_3 + \tau_4)$$

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Edge contraction

How do we perform the remaining integrations (one for each edge)? Edge-contraction



- 1. Choose sink/source with connected complement
- 3. Multiply by inverse sum of energies of adjacent edges

$$= \frac{i}{E_1 + E_4 - p_1^0} \left[\frac{i}{E_2 + E_3 + p_3^0} \left(v_{123} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \left(v_{134} \right) + \frac{i}{E_1 + E_2 - E_3 - E_3} \right) + \frac{i}{E_1 + E_3 - E_3 - E_3} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - E_3} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - E_3} \left(v_{134} \right) + \frac{i}{E_1 + E_3 - E_3} \left(v_{134} \right) + \frac{i}{E_1 + E_3} \left(v_{134} \right) + \frac{i}{E_1$$

4. Throw out non-acyclic graphs

5. Contract parallel

edges

$$=\frac{i}{E_1+E_4-p_1^0}\left[\frac{i}{E_2+E_3+p_3^0}\frac{i}{E_2+E_4-p_1^0-p_2^0}+\frac{i}{E_1+E_3-p_1^0-p_4^0}\frac{i}{E_2+E_3+p_3^0}\right]$$

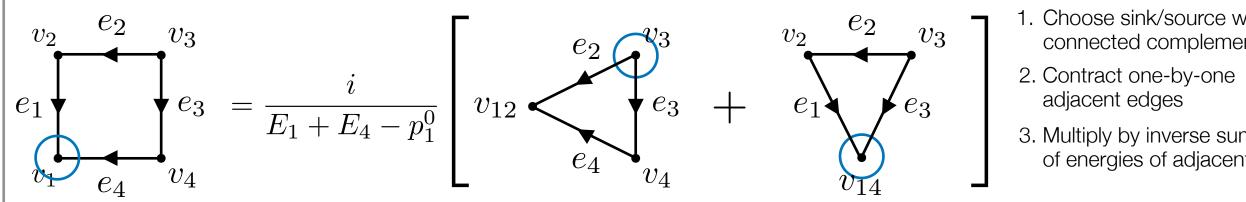
$$= \int \left[\prod_{j=1}^{4} \frac{\mathrm{d}\tau_j}{2E_j} e^{i\tau_j (E_j^0 - \sigma_j p_j^0)} \Theta(\tau_j) \right] \delta\left(-\tau_1 - \tau_2 + \tau_3 + \tau_4\right)$$

$$\mathcal{K}_G = \left\{ (\tau_e)_{e \in \mathcal{E}} \in \mathbb{R}_+^{|\mathcal{E}|} \middle| \sum_{e \in \mathcal{E}} s_{ei} \tau_e \right\}$$

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Edge contraction

How do we perform the remaining integrations (one for each edge)? Edge-contraction



- 1. Choose sink/source with connected complement
- 3. Multiply by inverse sum of energies of adjacent edges

$$= \frac{i}{E_1 + E_4 - p_1^0} \left[\frac{i}{E_2 + E_3 + p_3^0} \left(v_{123} + v_{123} + v_{123} + v_{123} \right) \right]$$

$$+\frac{i}{E_1+E_3-p_1^0-p_4^0}\left(v_{134}+v_{124}+v_{124}+v_{124}+v_{124}\right)$$

graphs

5. Contract parallel

$$= \frac{i}{E_1 + E_4 - p_1^0} \left[\frac{i}{E_2 + E_3 + p_3^0} \frac{i}{E_2 + E_4 - p_1^0 - p_2^0} + \frac{i}{E_1 + E_3 - p_1^0 - p_4^0} \frac{i}{E_2 + E_3 + p_3^0} \right]$$

All time integrations are performed diagrammatically!

Cross-Free Families

Boundary operator

Cross-Free Families

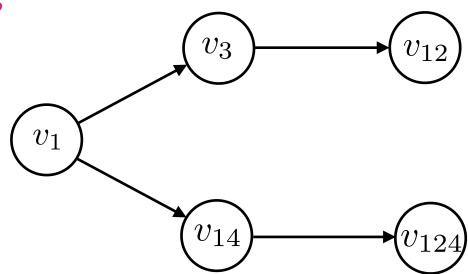
Cross-Free Families

Collecting the chosen vertices and collecting them according to order of choice, we get a decision tree, whose root is the first chosen vertex

Boundary operator

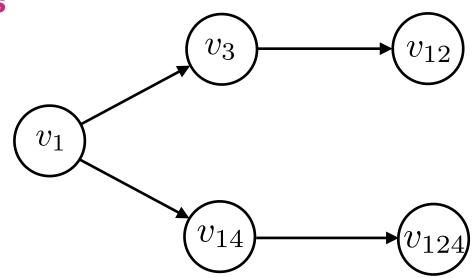
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Boundary operator

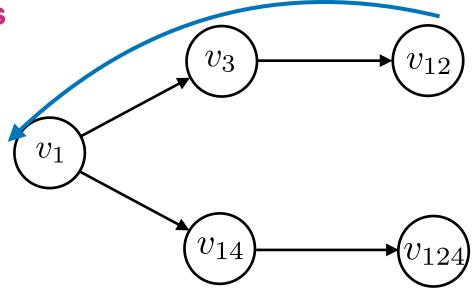
Collecting the chosen vertices and collecting them according to order of choice, we get a decision tree, whose root is the first chosen vertex



Tracing the route from the leaves to the root gives sets of vertices

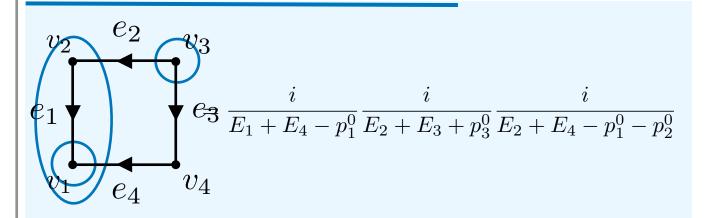
Boundary operator

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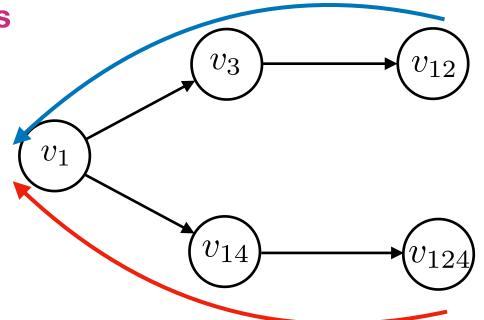
Tracing the route from the leaves to the root gives sets of vertices

$$F_1 = \{\{v_1\}, \{v_3\}, \{v_1, v_2\}\}$$



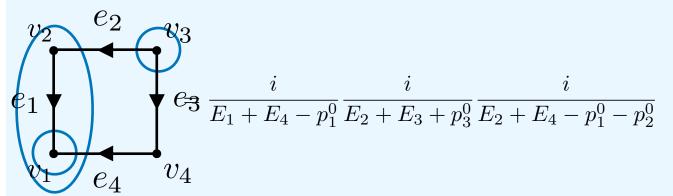
Boundary operator

Collecting the chosen vertices and collecting them according to order of choice, we get a decision tree, whose root is the first chosen vertex

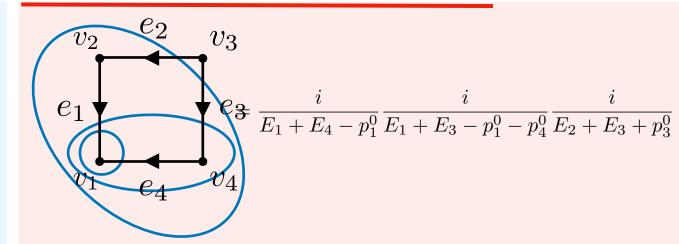


Tracing the route from the leaves to the root gives sets of vertices

$$F_1 = \{\{v_1\}, \{v_3\}, \{v_1, v_2\}\}$$

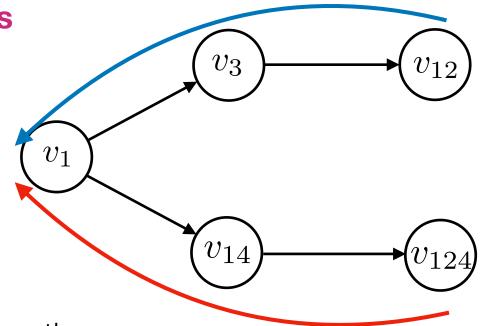


$$F_2 = \{\{v_1\}, \{v_1, v_4\}, \{v_1, v_2, v_4\}\}$$



Boundary operator

Collecting the chosen vertices and collecting them according to order of choice, we get a decision tree, whose root is the first chosen vertex

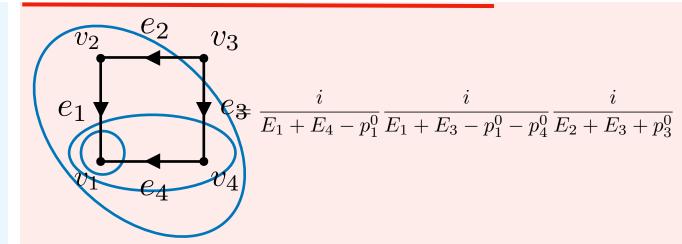


Tracing the route from the leaves to the root gives sets of vertices

$$F_1 = \{\{v_1\}, \{v_3\}, \{v_1, v_2\}\}$$

$$e_{1} = e_{2} + e_{3} = \frac{i}{E_{1} + E_{4} - p_{1}^{0}} \frac{i}{E_{2} + E_{3} + p_{3}^{0}} \frac{i}{E_{2} + E_{4} - p_{1}^{0} - p_{2}^{0}}$$

$$F_2 = \{\{v_1\}, \{v_1, v_4\}, \{v_1, v_2, v_4\}\}$$



Boundary operator

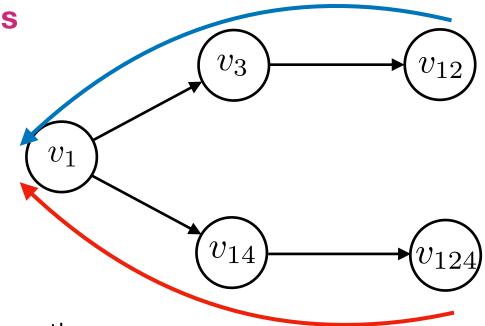
Boundary operator provides nexus

e.g.
$$\partial(\{v_1, v_2\}) = \{e_2, e_4\}$$

$$\Rightarrow$$

$$rac{\imath}{E_2 + E_4 - p_1^0 - p_2^0}$$

Collecting the chosen vertices and collecting them according to order of choice, we get a decision tree, whose root is the first chosen vertex



Tracing the route from the leaves to the root gives sets of vertices

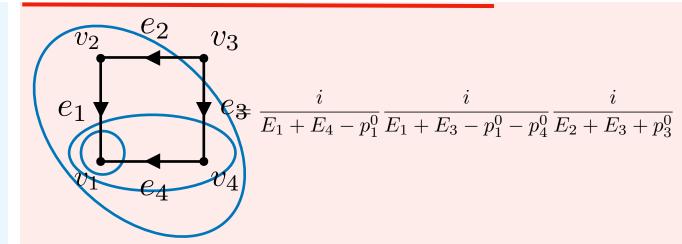
$$F_1 = \{\{v_1\}, \{v_3\}, \{v_1, v_2\}\}$$

$$e_{1} = e_{2}$$

$$e_{3} = \frac{i}{E_{1} + E_{4} - p_{1}^{0}} \frac{i}{E_{2} + E_{3} + p_{3}^{0}} \frac{i}{E_{2} + E_{4} - p_{1}^{0} - p_{2}^{0}}$$

$$v_{4}$$

$$F_2 = \{\{v_1\}, \{v_1, v_4\}, \{v_1, v_2, v_4\}\}$$



Boundary operator

Boundary operator provides nexus

e.g.
$$\partial(\{v_1, v_2\}) = \{e_2, e_4\}$$

$$\Rightarrow$$

$$rac{\imath}{E_2+E_4-p_1^0-p_2^0}$$

Cross-Free Families

We notice some regularities... these families of cuts satisfy

$$S \in F \implies S, V \setminus S$$
 are connected

$$S_1, S_2 \in F \implies S_1 \subset S_2 \text{ or } S_2 \subset S_1 \text{ or } S_1 \cap S_2 = \emptyset$$

$$S \in F \implies S$$
 cannot be written as union of other sets in F

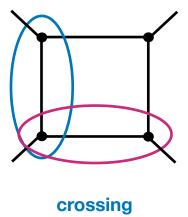
Abreu, Britto, Duhr, Gardi Bloch, Kreimer arXiv:2010.01068 (2014) arXiv:1512.01705 (2015) Arkani-Hamed, Benincasa, Postnikov

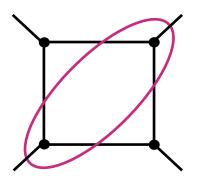
arXiv:1709.02813 (2017) Benincasa, McLeod, Vergu

arXiv:2009.03047 (2020) Capatti, Hirschi, Pelloni, Ruijl,

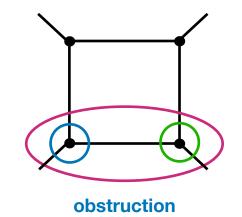
arXiv:2010.01068 (2020)

General formula

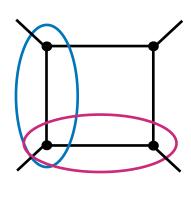


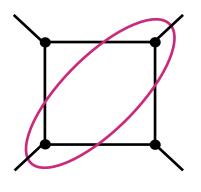


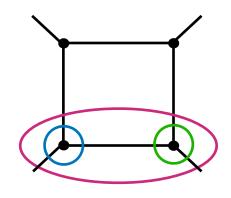
connectedness



General formula







crossing

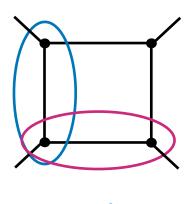
connectedness

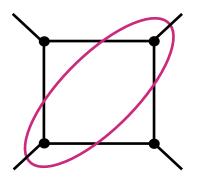
obstruction

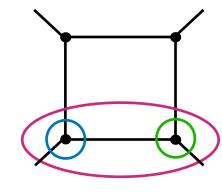
General formula

Repeating the same edge-contraction procedure for all acyclic graphs

$$f_{G_u}^{3d} = \sum_{\substack{\text{acyclic} \\ \text{graph } G}} \frac{\mathcal{N}_G}{\prod_e 2E_e} \sum_{F \in \mathcal{F}_G} \frac{1}{\prod_{S \in F} \left[\mathbf{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 \right]}$$







crossing

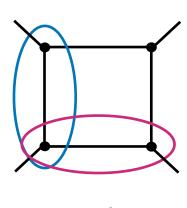
connectedness

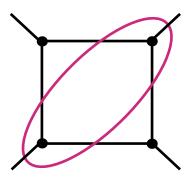
obstruction

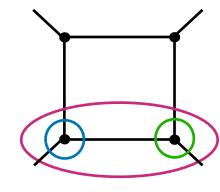
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crossing

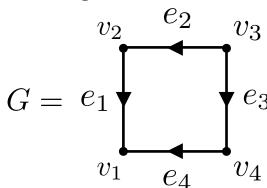
connectedness

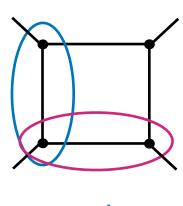
obstruction

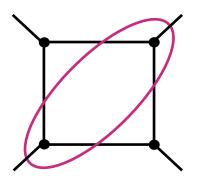
General formula

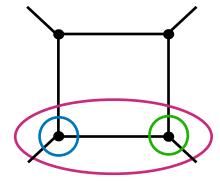
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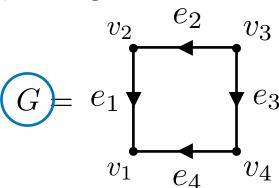
connectedness

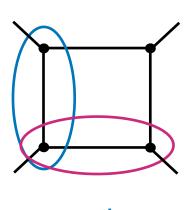
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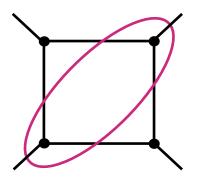
General formula

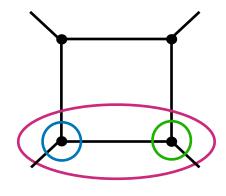
Repeating the same edge-contraction procedure for all acyclic graphs

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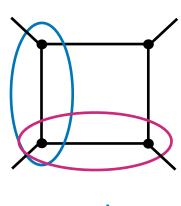
connectedness

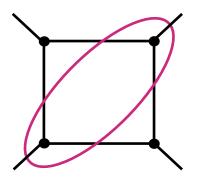
obstruction

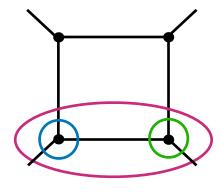
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connectedness

obstruction

General formula

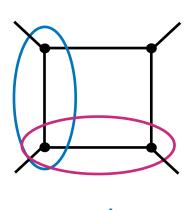
Repeating the same edge-contraction procedure for all acyclic graphs

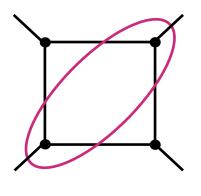
$$f_{G_u}^{3\text{d}} = \sum_{\substack{\text{acyclic} \\ \text{graph } G}} \frac{\mathcal{N}_G}{\prod_e 2E_e} \sum_{F \in \mathcal{F}_G} \frac{1}{\prod_{S \in F} \left[\boldsymbol{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 \right]}$$

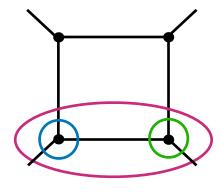
$$G = e_1 \qquad e_2 \qquad v_3 \qquad e_3 \qquad e_4 \qquad v_4$$

$$\mathcal{F}_G = \{F_1, F_2\}$$

$$F_2 = \underbrace{\begin{array}{c} v_2 \\ v_3 \\ v_4 \end{array}}$$







connectedness

obstruction

General formula

Repeating the same edge-contraction procedure for all acyclic graphs

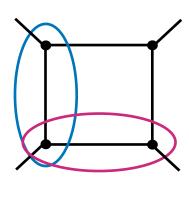
$$f_{G_u}^{3\text{d}} = \sum_{\substack{\text{acyclic} \\ \text{graph } G}} \frac{\mathcal{N}_G}{\prod_e 2E_e} \sum_{F \notin \mathcal{F}_G} \frac{1}{\prod_{S \in F} \left[\boldsymbol{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 \right]}$$

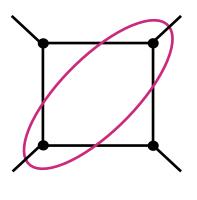
$$G = e_1 \qquad e_2 \qquad v_3 \qquad e_3 \qquad e_3 \qquad e_4 \qquad v_4$$

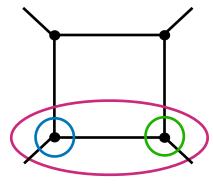
$$\mathcal{F}_G = \{F_1, F_2\}$$

$$F_1 = \bigcup_{v_4}^{v_2}$$

$$F_2 = \underbrace{\begin{array}{c} v_2 \\ v_3 \\ v_4 \end{array}}$$







crossing

connectedness

obstruction

General formula

Repeating the same edge-contraction procedure for all acyclic graphs

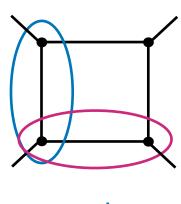
$$f_{G_u}^{3d} = \sum_{\substack{\text{acyclic} \\ \text{graph } G}} \frac{\mathcal{N}_G}{\prod_e 2E_e} \sum_{F \notin \mathcal{F}_G} \frac{1}{\prod_{S \in F} \left[\boldsymbol{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 \right]}$$

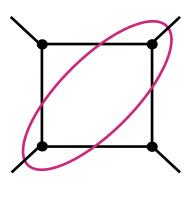
Repeating the same edge-contraction procedure for all acyclic graphs. For our example, we had

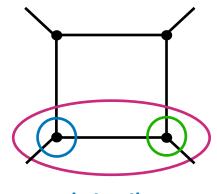
$$G = e_1 \underbrace{\begin{array}{c} e_2 & v_3 \\ e_3 & \\ v_1 & e_4 & v_4 \end{array}} \qquad F_G = \{F_1, F_2\} \qquad F_1 = \underbrace{\begin{array}{c} v_2 \\ v_4 \\ v_4 \end{array}} \qquad F_2 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_2 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_2 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_3 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_3 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_3 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_3 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_4 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_4 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \\ v_4 \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \\ v_4 \\ v_4 \\ v_4 \\ \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \\ v_4 \\ v_4 \\ v_4 \\ \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \\ v_4 \\ v_4 \\ \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \\ v_4 \\ v_4 \\ v_4 \\ \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\ v_4 \\ v_4 \\ v_4 \\ v_4 \\ \end{array}} \qquad F_5 = \underbrace{\begin{array}{c} v_4 \\ v_4 \\$$

Each element of a cross-free family corresponds to a threshold

$$F_1 = \{\{v_1\}, \{v_3\}, \{v_1, v_2\}\}$$







crossing

connectedness

obstruction

General formula

Repeating the same edge-contraction procedure for all acyclic graphs

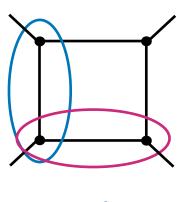
$$f_{G_u}^{3d} = \sum_{\substack{\text{acyclic} \\ \text{graph } G}} \frac{\mathcal{N}_G}{\prod_e 2E_e} \sum_{F \notin \mathcal{F}_G} \frac{1}{\left[\mathbf{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0\right]}$$

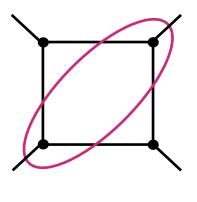
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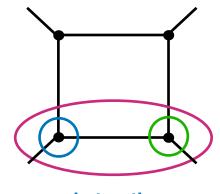
$$G = e_1 \underbrace{\begin{array}{c} v_2 & e_2 \\ v_3 \\ v_1 & e_4 \end{array}}_{v_4} v_4 \qquad F_2 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}}_{v_4} \qquad F_2 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}}_{v_4} \qquad F_2 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}}_{v_4}$$

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crossing

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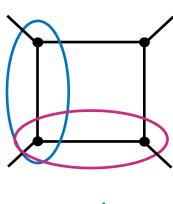
$$G = e_1 \underbrace{\begin{array}{c} v_2 & e_2 \\ v_3 \\ v_1 & e_4 \end{array}}_{v_4} v_4$$

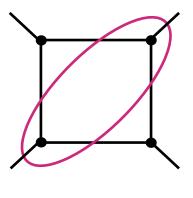
$$F_G = \{F_1, F_2\}$$

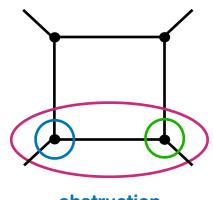
$$F_1 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}}_{v_4} F_2 = \underbrace{\begin{array}{c} v_3 \\ v_4 \\ v_4 \end{array}}_{v_4}$$

Each element of a cross-free family corresponds to a threshold

$$F_1 = \{\{v_1\}, \{v_3\}, \{v_1, v_2\}\} \quad \partial(\{v_1, v_2\}) = \{e_2, e_4\} \quad \mathbf{E} \cdot \mathbf{1}^{\partial(\{v_1, v_2\})} - \sum_{v \in \{v_1, v_2\}} p_v^0 = E_2 + E_4 - p_1^0 - p_2^0 = E_1 + E_2 - E_2 -$$







connectedness

obstruction

General formula

Repeating the same edge-contraction procedure for all acyclic graphs

$$f_{G_u}^{3d} = \sum_{\substack{\text{acyclic} \\ \text{graph } G}} \frac{\mathcal{N}_G}{\prod_e 2E_e} \sum_{F \notin \mathcal{F}_G} \frac{1}{\left[\mathbf{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0\right]}$$

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$$G = e_1 \underbrace{v_2}_{v_1} \underbrace{e_2}_{e_3} \underbrace{v_3}_{e_4}$$

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And the cross-free family corresponds to a product of thresholds

$$= \frac{i}{E_1 + E_4 - p_1^0} \frac{i}{E_2 + E_3 + p_3^0} \frac{i}{E_2 + E_4 - p_1^0 - p_2^0}$$

Local discontinuities

Spurious singularities in TOPT

Local discontinuities | We can compute discontinuities (Bourjaily, Hannesdottir, McLeod, Schwartz, Vergu [arXiv:2007.13747])

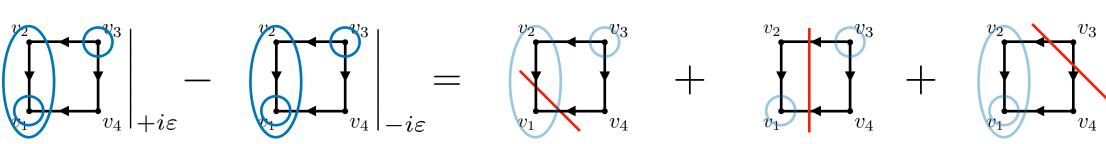
$$\frac{1}{\prod_{S \in F} \left[\mathbf{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 + i\varepsilon \right]} - \frac{1}{\prod_{S \in F} \left[\mathbf{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 - i\varepsilon \right]} = \sum_{S \in F} \frac{\delta \left(\mathbf{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 \right)}{\prod_{S' \in F \setminus \{S\}} \left[\mathbf{E} \cdot \mathbf{1}^{\partial(S')} - \sum_{v \in S'} p_v^0 \right]}$$

Spurious singularities in TOPT

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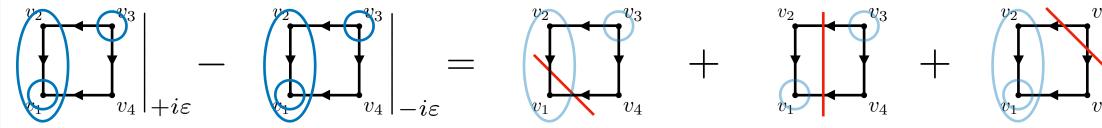
$$\frac{1}{\prod_{S \in F} \left[\mathbf{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 + i\varepsilon \right]} - \frac{1}{\prod_{S \in F} \left[\mathbf{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 - i\varepsilon \right]} = \sum_{S \in F} \frac{\delta \left(\mathbf{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 \right)}{\prod_{S' \in F \setminus \{S\}} \left[\mathbf{E} \cdot \mathbf{1}^{\partial(S')} - \sum_{v \in S'} p_v^0 \right]}$$





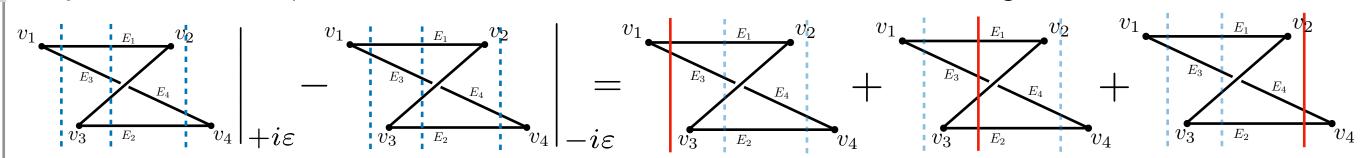
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 $\frac{1}{\prod_{S \in F} \left[\mathbf{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 + i\varepsilon \right]} - \frac{1}{\prod_{S \in F} \left[\mathbf{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 - i\varepsilon \right]} = \sum_{S \in F} \frac{\delta \left(\mathbf{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 \right)}{\prod_{S' \in F \setminus \{S\}} \left[\mathbf{E} \cdot \mathbf{1}^{\partial(S')} - \sum_{v \in S'} p_v^0 \right]}$



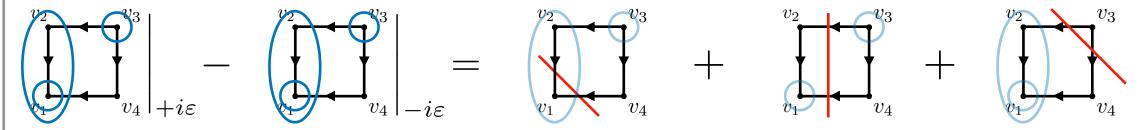
Spurious singularities in TOPT

Why use the CFF rep. and not TOPT? Focus on the TOPT term ordering $\{v_1, v_3, v_2, v_4\}$



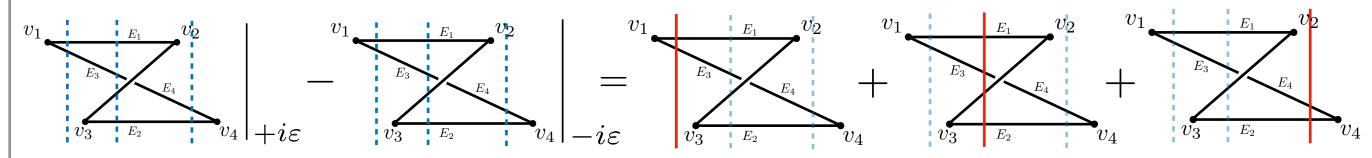
Local discontinuities | We can compute discontinuities (Bourjaily, Hannesdottir, McLeod, Schwartz, Vergu [arXiv:2007.13747])

$$\frac{1}{\prod_{S \in F} \left[\boldsymbol{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 + i\varepsilon \right]} - \frac{1}{\prod_{S \in F} \left[\boldsymbol{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 - i\varepsilon \right]} = \sum_{S \in F} \frac{\delta \left(\boldsymbol{E} \cdot \mathbf{1}^{\partial(S)} - \sum_{v \in S} p_v^0 \right)}{\prod_{S' \in F \setminus \{S\}} \left[\boldsymbol{E} \cdot \mathbf{1}^{\partial(S')} - \sum_{v \in S'} p_v^0 \right]}$$

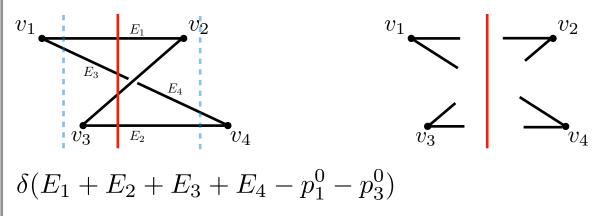


Spurious singularities in TOPT

Why use the CFF rep. and not TOPT? Focus on the TOPT term ordering $\{v_1, v_3, v_2, v_4\}$



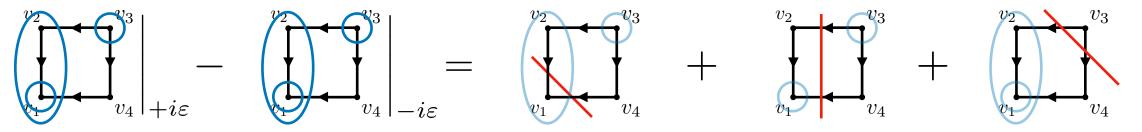
Looking at the second cut



Divides the graph in four connected components, but the CFF representation tells us this is not possible! It is a spurious threshold

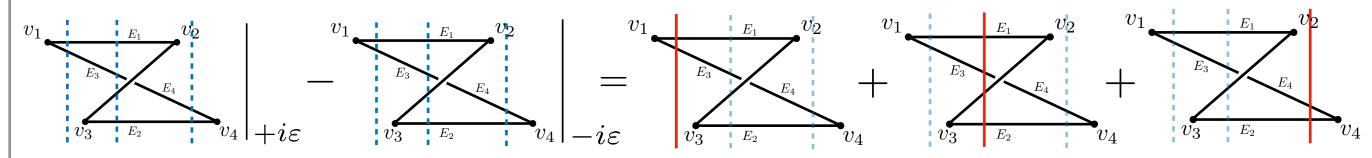
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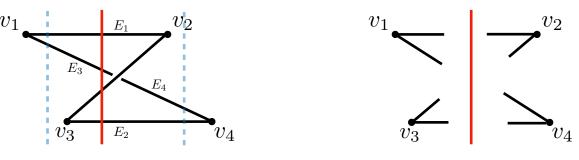


Spurious singularities in TOPT

Why use the CFF rep. and not TOPT? Focus on the TOPT term ordering $\{v_1, v_3, v_2, v_4\}$



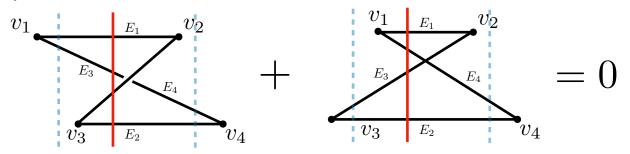
Looking at the second cut

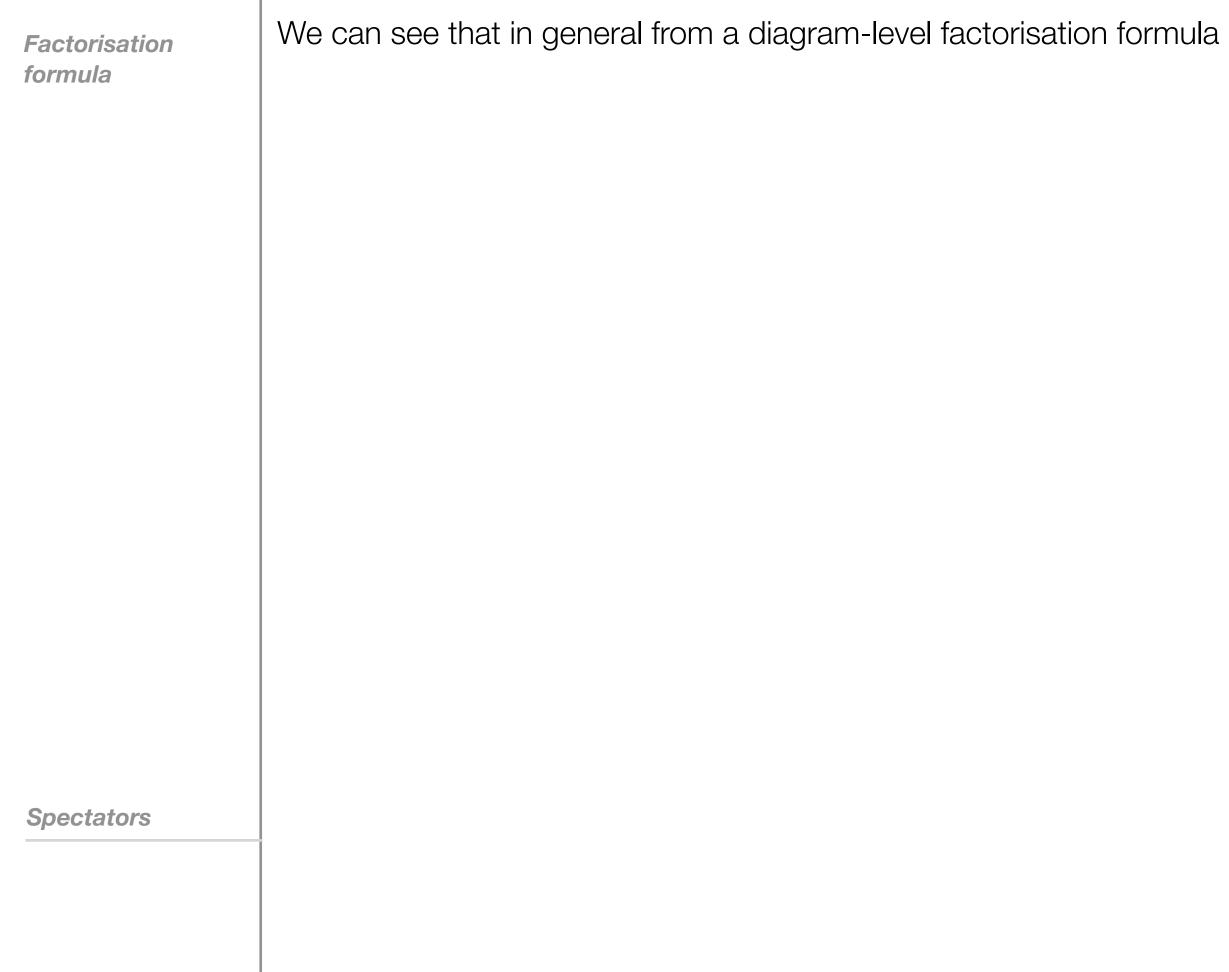


Divides the graph in four connected components, but the CFF representation tells us this is not possible! It is a spurious threshold

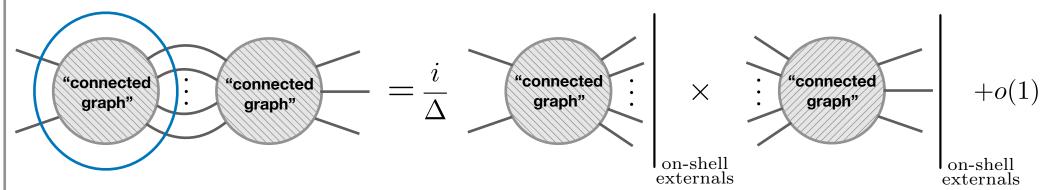
$$\delta(E_1 + E_2 + E_3 + E_4 - p_1^0 - p_3^0)$$

How do we see that it is spurious?

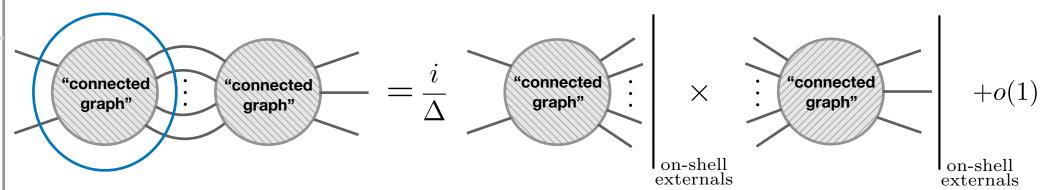




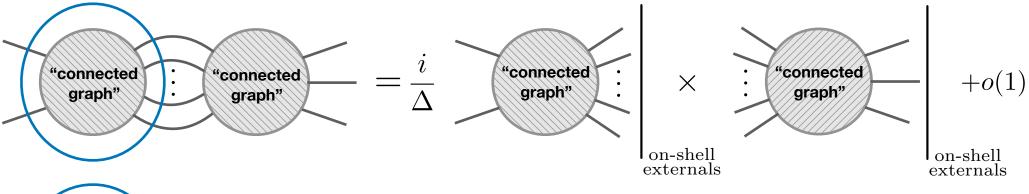
We can see that in general from a diagram-level factorisation formula

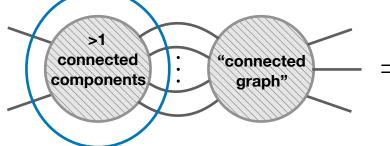


We can see that in general from a diagram-level factorisation formula



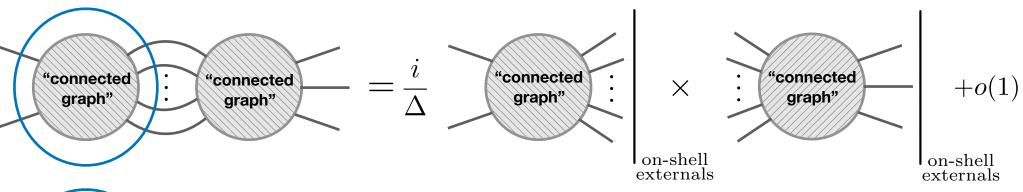
We can see that in general from a diagram-level factorisation formula

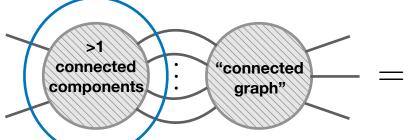




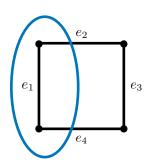
If more than two disconnected components, it is of order one

We can see that in general from a diagram-level factorisation formula





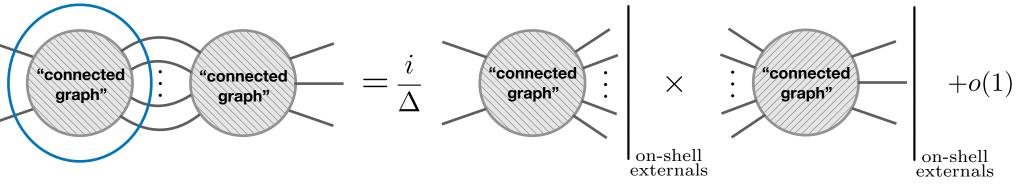
If more than two disconnected components, it is of order one

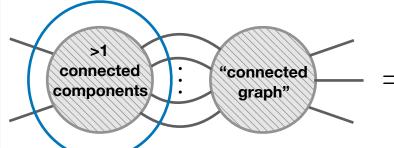


$$\Delta = E_2 + E_4 - p_1^0 - p_4^0 \to 0$$

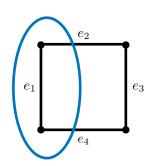
$$e_1$$
 e_3 e_4 e_4 e_4 e_4 e_4 e_4 e_4 e_4 e_4

We can see that in general from a diagram-level factorisation formula

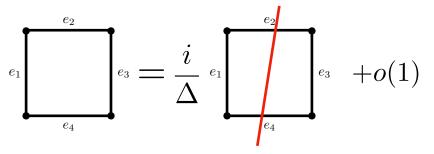




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$$\Delta = E_2 + E_4 - p_1^0 - p_4^0 \to 0$$

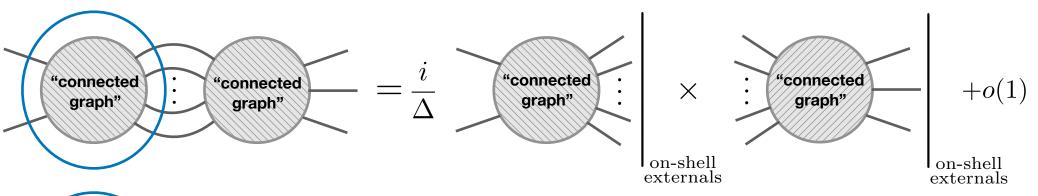


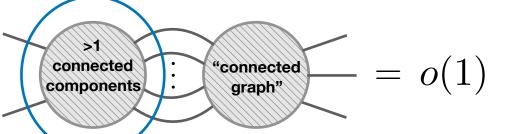
$$e_1$$
 e_2
 e_3

$$\Delta = E_1 + E_2 + E_3 + E_4 - p_1^0 - p_4^0 \to 0$$

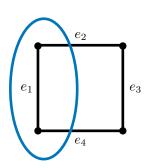
$$e_1$$
 e_2 $e_3 = o(1)$

We can see that in general from a diagram-level factorisation formula





If more than two disconnected components, it is of order one



$$\Delta = E_2 + E_4 - p_1^0 - p_4^0 \to 0$$

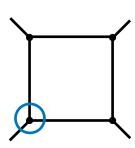
$$e_1$$
 e_2 e_3 e_4 e_4 e_4 e_4 e_4 e_4 e_4

$$e_1$$
 e_2 e_3

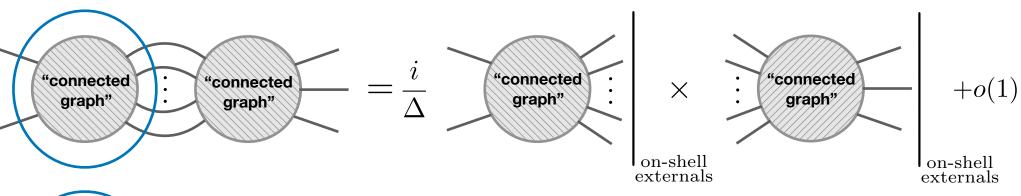
$$\Delta = E_1 + E_2 + E_3 + E_4 - p_1^0 - p_4^0 \to 0$$

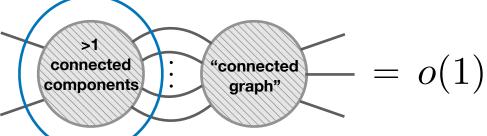
$$e_1$$
 e_2 $e_3 = o(1)$

Spectators

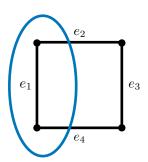


We can see that in general from a diagram-level factorisation formula





If more than two disconnected components, it is of order one



$$\Delta = E_2 + E_4 - p_1^0 - p_4^0 \to 0$$

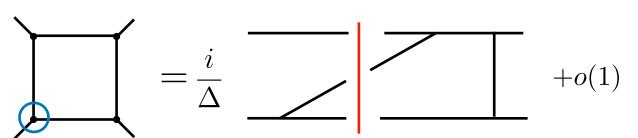
$$e_1$$
 e_2
 e_3
 e_4
 e_4
 e_4
 e_4
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 e_4
 e_4
 e_4
 e_4

$$e_1$$
 e_2
 e_3

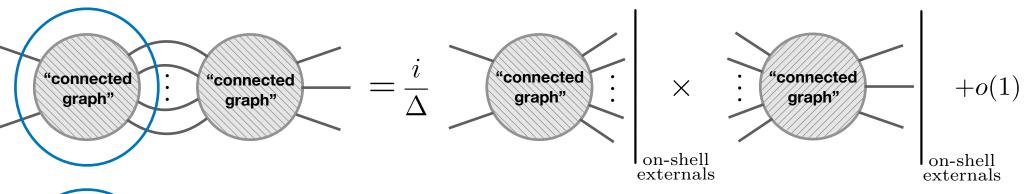
$$\Delta = E_1 + E_2 + E_3 + E_4 - p_1^0 - p_4^0 \to 0$$

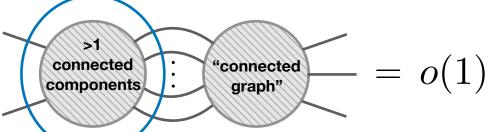
$$e_1$$
 $e_3 = o(1)$

Spectators

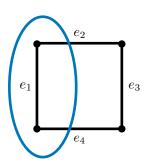


We can see that in general from a diagram-level factorisation formula





If more than two disconnected components, it is of order one



$$\Delta = E_2 + E_4 - p_1^0 - p_4^0 \to 0$$

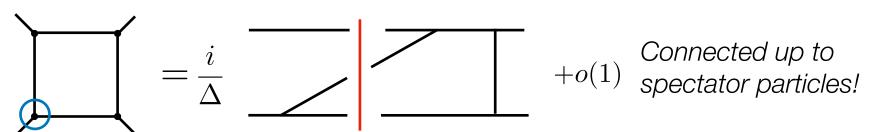
$$e_1$$
 e_2
 e_3
 e_4
 e_4
 e_4
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 e_4
 e_4
 e_4
 e_4
 e_4

$$e_1$$
 e_2 e_3

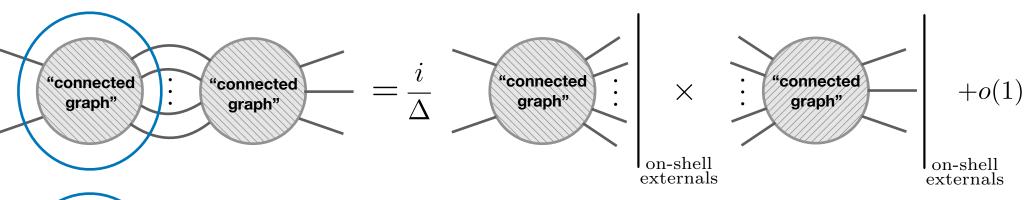
$$\Delta = E_1 + E_2 + E_3 + E_4 - p_1^0 - p_4^0 \to 0$$

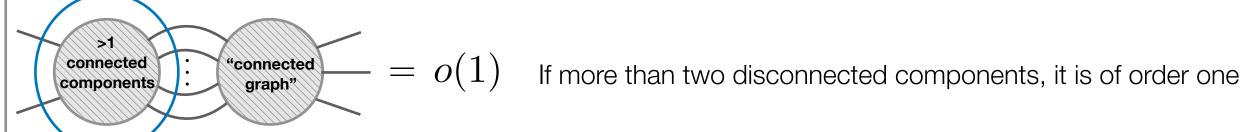
$$e_1$$
 $e_3 = o(1)$

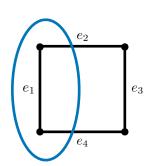
Spectators



We can see that in general from a diagram-level factorisation formula







$$\Delta = E_2 + E_4 - p_1^0 - p_4^0 \to 0$$

$$e_1 \underbrace{ \begin{bmatrix} e_2 \\ e_3 \end{bmatrix}}_{e_4} e_3 = \frac{i}{\Delta} e_1 \underbrace{ \begin{bmatrix} e_2 \\ e_4 \end{bmatrix}}_{e_4} e_3 + o(1)$$

connected

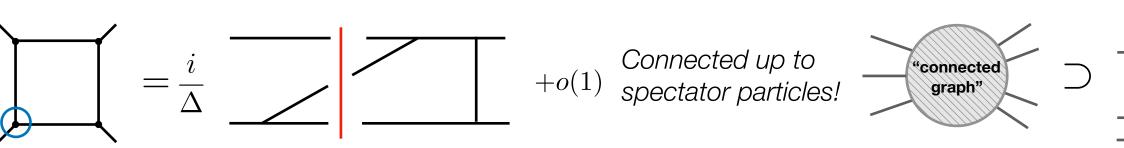
graph

$$e_1$$
 e_2
 e_3

$$\Delta = E_1 + E_2 + E_3 + E_4 - p_1^0 - p_4^0 \to 0$$

$$e_1$$
 e_2 $e_3 = o(1)$

Spectators



Second part: cluster decomposition and infrared finiteness

- Highlight role of connectedness at the operator level

$$ra{lpha|\mathbf{T}_{\mathrm{c}}|eta} \supset lpha \left\{egin{array}{c} \mathsf{connected} \ \mathsf{graph} \end{array}
ight\}eta$$

Reconstruct unitarity, cluster decomposition principle and infrared finiteness from the diagrammatic analysis

- Use Local Unitarity methods to take advantage of this analysis to numerically evaluate cross-sections

Connected transition matrix

S-matrix

"Unitarity"

Cluster Decomposition



Cluster Decomposition

Can we express the role of connectedness at the operator level? Define the connected

transition matrix

 $ra{lpha|\mathbf{T}_{\mathrm{c}}|eta} \supset lpha \left\{egin{array}{c} \mathsf{connected} \ \mathsf{graph} \end{array}
ight\}eta$

S-matrix



Cluster Decomposition

Can we express the role of connectedness at the operator level? Define the connected transition matrix

$$ra{lpha|\mathbf{T}_{\mathrm{c}}|eta} \supset lpha \left\{egin{array}{c} \mathsf{connected} \ \mathsf{graph} \end{array}
ight\}eta$$

S-matrix

The connected transition matrix is not unitary (expected). What is the relationship with S-matrix?



Cluster Decomposition

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$$ra{lpha}{\mathbf{T}_{\mathrm{c}}\ket{oldsymbol{eta}}} lpha \left\{egin{array}{c} \mathsf{connected} \ \mathsf{graph} \end{array}
ight\}oldsymbol{eta}$$

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Cluster Decomposition

Can we express the role of connectedness at the operator level? Define the connected transition matrix

$$ra{lpha|\mathbf{T}_{\mathrm{c}}|eta} \geq lpha \left\{egin{array}{c} \mathsf{connected} \ \mathsf{graph} \end{array}
ight\}eta$$

S-matrix

The connected transition matrix is not unitary (expected). What is the relationship with S-matrix?

$$\mathbf{S} = + \underbrace{\text{"connected graph"}}_{\text{graph"}} + \underbrace{\frac{1}{2!} \left(\underbrace{\text{"connected graph"}}_{\text{graph"}} + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"co$$

$$\mathbf{S} = 1 + i\mathbf{T}_{c} + \frac{i^{2}}{2!}\mathbf{T}_{c}^{2} + \frac{i^{3}}{3!}\mathbf{T}_{c}^{3} + \dots = e^{i\mathbf{T}_{c}}$$

Cluster Decomposition

Can we express the role of connectedness at the operator level? Define the connected

transition matrix $\left<\alpha\right|\mathbf{T}_{\mathrm{c}}\left|\boldsymbol{\beta}\right>\supset\alpha\left\{\begin{array}{c}\mathsf{connected}\\\mathsf{graph}\end{array}\right\}\boldsymbol{\beta}$

S-matrix

The connected transition matrix is not unitary (expected). What is the relationship with S-matrix?

$$S = + = \text{"connected graph"} + \text{"connected graph"} + \text{"connected graph"} + \text{"connected graph"} + \cdots$$

$$\mathbf{S} = \mathbf{I} + \mathbf{I} +$$

$$\mathbf{S} = 1 + i\mathbf{T}_{c} + \frac{i^{2}}{2!}\mathbf{T}_{c}^{2} + \frac{i^{3}}{3!}\mathbf{T}_{c}^{3} + ... = e^{i\mathbf{T}_{c}}$$
 (evokes $Z[J] = e^{iW[J]}$)

Cluster Decomposition

Can we express the role of connectedness at the operator level? Define the connected transition matrix

$$ra{lpha|\mathbf{T}_{\mathrm{c}}|eta} \supset lpha \left\{egin{array}{c} \mathsf{connected} \ \mathsf{graph} \end{array}
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$$S = + \text{"connected graph"} + \text{"connected graph"} + \text{"connected graph"} + \text{"connected graph"} + \cdot \cdot \cdot$$

$$\mathbf{S} = + \underbrace{\text{"connected graph"}}_{\text{graph"}} + \underbrace{\frac{1}{2!} \left(\underbrace{\text{"connected graph"}}_{\text{graph"}} + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}$$

$$\mathbf{S} = 1 + i\mathbf{T}_{\rm c} + \frac{i^2}{2!}\mathbf{T}_{\rm c}^2 + \frac{i^3}{3!}\mathbf{T}_{\rm c}^3 + ... = e^{i\mathbf{T}_{\rm c}} \quad \text{(evokes } Z[J] = e^{iW[J]} \text{)}$$
 (See also holomorphic cutting rules: Hannesdottir, Mizera [arXiv:2204.02988])

Cluster Decomposition

Can we express the role of connectedness at the operator level? Define the connected transition matrix

 $ra{lpha|\mathbf{T}_{\mathrm{c}}|eta} \supset lpha \left\{egin{array}{c} \mathsf{connected} \ \mathsf{graph} \end{array}
ight\}eta$

S-matrix

The connected transition matrix is not unitary (expected). What is the relationship with S-matrix?

$$\mathbf{S} = + \underbrace{\text{"connected graph"}}_{\text{graph"}} + \underbrace{\frac{1}{2!} \left(\underbrace{\text{"connected graph"}}_{\text{graph"}} + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{graph"}} + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{graph"}} + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{graph"}} + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{graph"}} + \underbrace{\frac{1}{3!} \left(\underbrace{\text{$$

$$\mathbf{S} = 1 + i\mathbf{T}_{c} + \frac{i^{2}}{2!}\mathbf{T}_{c}^{2} + \frac{i^{3}}{3!}\mathbf{T}_{c}^{3} + \dots = e^{i\mathbf{T}_{c}}$$
 (evokes $Z[J] = e^{iW[J]}$)

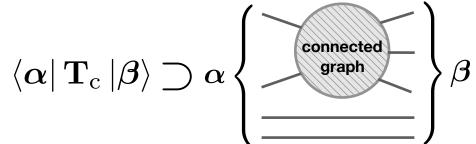
(See also holomorphic cutting rules: Hannesdottir, Mizera [arXiv:2204.02988])

"Unitarity"

In order to establish this relation, we need the following formula

Cluster Decomposition

Can we express the role of connectedness at the operator level? Define the connected transition matrix



S-matrix

The connected transition matrix is not unitary (expected). What is the relationship with S-matrix?

$$\mathbf{S} = + \underbrace{\text{"connected graph"}}_{\text{graph"}} + \underbrace{\frac{1}{2!} \left(\underbrace{\text{"connected graph"}}_{\text{graph"}} + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}} + \dots \right) + \underbrace{\frac{1}{3!} \left(\underbrace{\text{"connected graph"}}_{\text{"connected graph"}$$

$$\mathbf{S} = 1 + i\mathbf{T}_{c} + \frac{i^{2}}{2!}\mathbf{T}_{c}^{2} + \frac{i^{3}}{3!}\mathbf{T}_{c}^{3} + \dots = e^{i\mathbf{T}_{c}}$$
 (evokes $Z[J] = e^{iW[J]}$)

(See also holomorphic cutting rules: Hannesdottir, Mizera [arXiv:2204.02988])

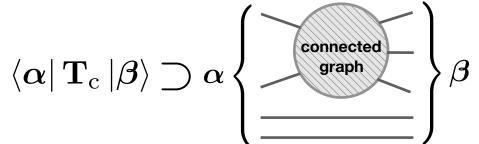
"Unitarity"

In order to establish this relation, we need the following formula

$$\underbrace{i\left\langle\boldsymbol{\alpha}\right|\mathbf{T}_{c}\left|\boldsymbol{\beta}\right\rangle-i\left\langle\boldsymbol{\alpha}\right|\mathbf{T}_{c}^{\dagger}\left|\boldsymbol{\beta}\right\rangle=\left\langle\boldsymbol{\alpha}\right|\mathbf{T}_{c}\mathbf{T}_{c}^{\dagger}\left|\boldsymbol{\beta}\right\rangle}_{\text{usual unitarity}}-\sum_{\substack{\boldsymbol{\alpha}'\subset\boldsymbol{\alpha}\\\boldsymbol{\beta}'\subset\boldsymbol{\beta}}}\left\langle\boldsymbol{\alpha}'\right|\mathbf{T}_{c}\left|\boldsymbol{\beta}'\right\rangle\left\langle\boldsymbol{\alpha}\setminus\boldsymbol{\alpha}'\right|\mathbf{T}_{c}^{\dagger}\left|\boldsymbol{\beta}\setminus\boldsymbol{\beta}'\right\rangle}_{\text{usual unitarity}}$$

Cluster Decomposition

Can we express the role of connectedness at the operator level? Define the connected transition matrix



S-matrix

The connected transition matrix is not unitary (expected). What is the relationship with S-matrix?

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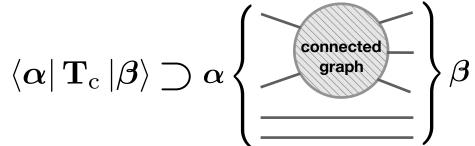
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cluster decomposition term

$$\underbrace{i\left\langle \alpha\right|\mathbf{T}_{c}\left|\beta\right\rangle - i\left\langle \alpha\right|\mathbf{T}_{c}^{\dagger}\left|\beta\right\rangle = \left\langle \alpha\right|\mathbf{T}_{c}\mathbf{T}_{c}^{\dagger}\left|\beta\right\rangle}_{\text{usual unitarity}} - \underbrace{\sum_{\substack{\alpha'\subset\alpha\\\beta'\subset\beta}}\left\langle \alpha'\right|\mathbf{T}_{c}\left|\beta'\right\rangle\left\langle \alpha\setminus\alpha'\right|\mathbf{T}_{c}^{\dagger}\left|\beta\setminus\beta'\right\rangle}_{\text{usual unitarity}} \underbrace{\alpha'\left\{\begin{array}{c}\text{connected}\\\text{graph}\end{array}\right\}\beta'}_{\alpha\setminus\alpha'}$$

Cluster Decomposition

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S-matrix

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$$\mathbf{S} = \mathbf{I} + \mathbf{I} +$$

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(See also holomorphic cutting rules: Hannesdottir, Mizera [arXiv:2204.02988])

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Factorisation formula expressed at the operator level!

Transition probabilities

Clusters and infrared finiteness

Cluster
decomposition
principle

This S-matrix also trivially satisfies the cluster-decomposition principle. Indeed

$$\mathbf{T}_{\mathrm{c}}(\ket{oldsymbol{lpha}}\otimes\ket{oldsymbol{eta}}) = (\mathbf{T}_{\mathrm{c}}\ket{oldsymbol{lpha}})\otimes\ket{oldsymbol{eta}}+\ket{oldsymbol{lpha}}\otimes(\mathbf{T}_{\mathrm{c}}\ket{oldsymbol{eta}})$$

 $P = P_A P_B$

for states with large space-like separations.

Transition probabilities

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Using it, we can compute transition probabilities

$$P = \text{Tr}[\boldsymbol{\rho} \mathbf{S} \boldsymbol{P} \mathbf{S}^{\dagger}]$$

Transition probabilities

infrared finiteness

Clusters and

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$$\mathbf{T}_{\mathrm{c}}(|oldsymbol{lpha}
angle\otimes|oldsymbol{eta}
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angle)\otimes|oldsymbol{eta}
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Sum over massless particles requires decoherence

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Clusters and infrared finiteness

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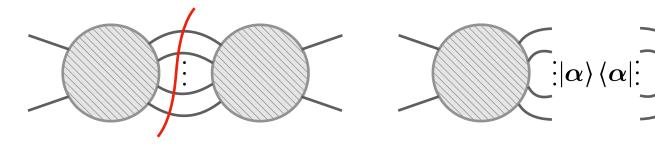
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$$P = \sum_{m} \int d\Pi_{m} |\mathcal{A}(pp \to EW + mp)|^{2}$$



Clusters and infrared finiteness

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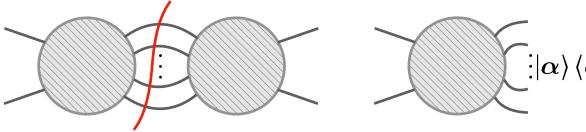
$$P = \text{Tr}[\boldsymbol{\rho} \mathbf{S} \boldsymbol{P} \mathbf{S}^{\dagger}]$$

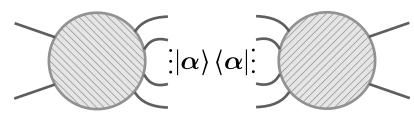
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And also the reason why we can write interference diagrams in the first place!

Clusters and infrared finiteness

Transition probabilities

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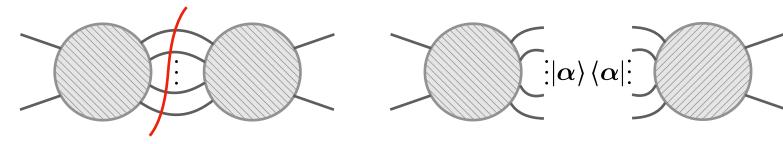
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And also the reason why we can write interference diagrams in the first place!

$$P = \text{Tr}[\boldsymbol{\rho} \mathbf{S} \boldsymbol{P} \mathbf{S}] = \sum_{n,m} \frac{i^{n+m}}{n!m!} \text{Tr}[\boldsymbol{\rho} \mathbf{T}_{c}^{n} \boldsymbol{P} (\mathbf{T}_{c}^{\dagger})^{m}]$$

Transition probabilities

Clusters and infrared finiteness

This S-matrix also trivially satisfies the cluster-decomposition principle. Indeed

$$\mathbf{T}_{\mathrm{c}}(|\boldsymbol{\alpha}\rangle\otimes|\boldsymbol{\beta}\rangle) = (\mathbf{T}_{\mathrm{c}}|\boldsymbol{\alpha}\rangle)\otimes|\boldsymbol{\beta}\rangle + |\boldsymbol{\alpha}\rangle\otimes(\mathbf{T}_{\mathrm{c}}|\boldsymbol{\beta}\rangle) \qquad \Rightarrow \qquad P = P_{A}P_{B}$$

for states with large space-like separations.

Using it, we can compute transition probabilities

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And also the reason why we can write interference diagrams in the first place!

Finally:
$$P = \text{Tr}[\boldsymbol{\rho} \mathbf{S} \boldsymbol{P} \mathbf{S}] = \sum_{n,m} \frac{i^{n+m}}{n!m!} \text{Tr}[\boldsymbol{\rho} \mathbf{T}_{\mathrm{c}}^{n} \boldsymbol{P} (\mathbf{T}_{\mathrm{c}}^{\dagger})^{m}]$$

Infrared finite if density matrix and projector sum over degenerate massless radiation

Transition probabilities

Clusters and infrared finiteness

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Using it, we can compute transition probabilities

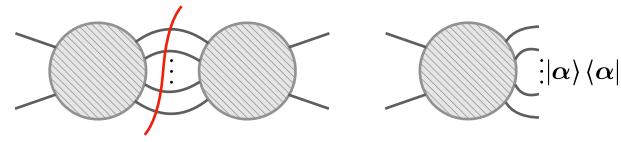
$$P = \text{Tr}[\boldsymbol{\rho} \mathbf{S} \boldsymbol{P} \mathbf{S}^{\dagger}]$$

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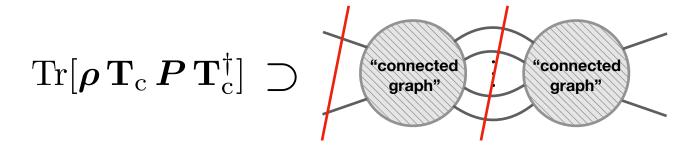
$$P = \text{Tr}[\boldsymbol{\rho} \mathbf{S} \boldsymbol{P} \mathbf{S}] = \sum_{n,m} \frac{i^{n+m}}{n!m!} \text{Tr}[\boldsymbol{\rho} \mathbf{T}_{c}^{n} \boldsymbol{P} (\mathbf{T}_{c}^{\dagger})^{m}]$$

Infrared finite if density matrix and projector sum over degenerate massless radiation

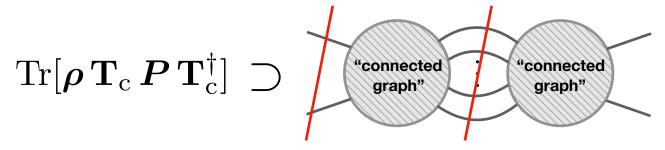
Infrared-finiteness follows from the unitarity relation we showed in the previous slide. But we can also look at it at a diagrammatic level.

Final-state sum example

Final-state sum example

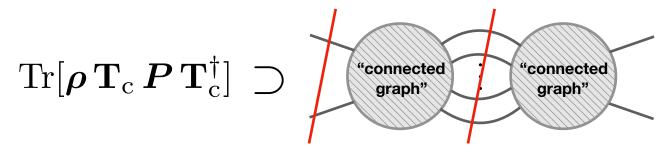


Final-state sum example



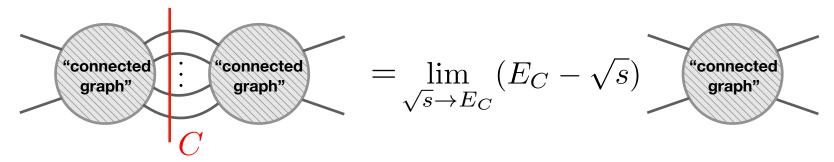
Final-state sum example

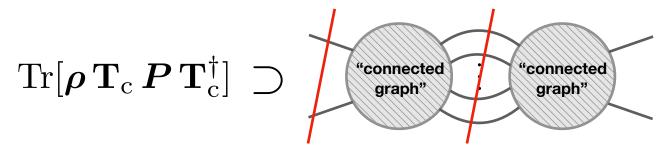
Using the CFF representation we can show that



Final-state sum example

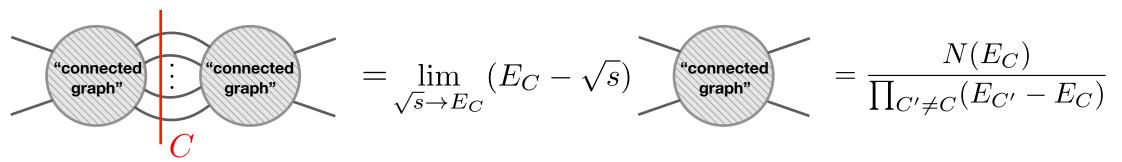
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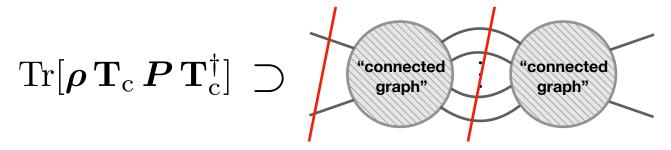




Final-state sum example

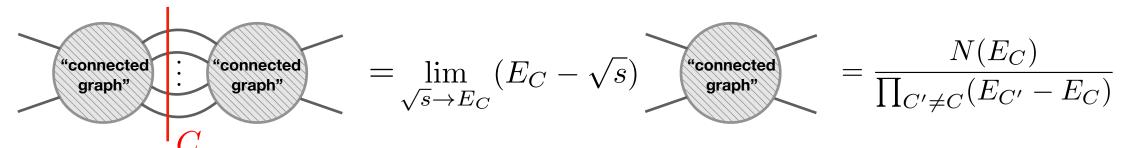
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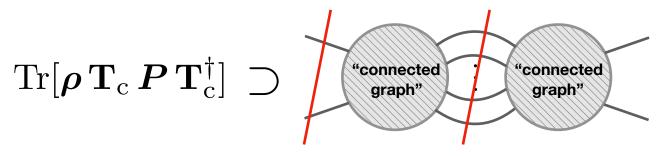


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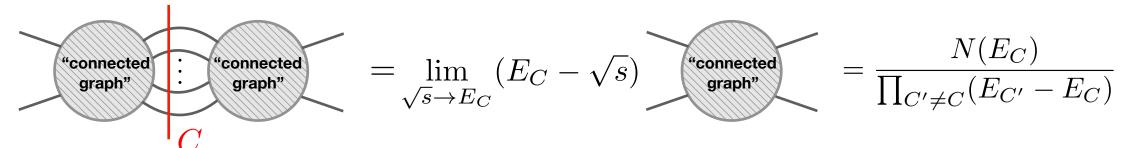


This relation allows to collect locally interference diagrams

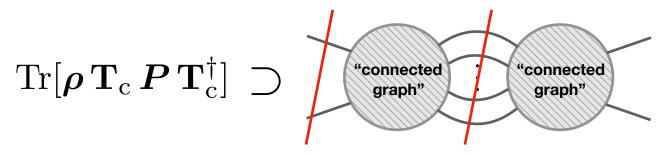


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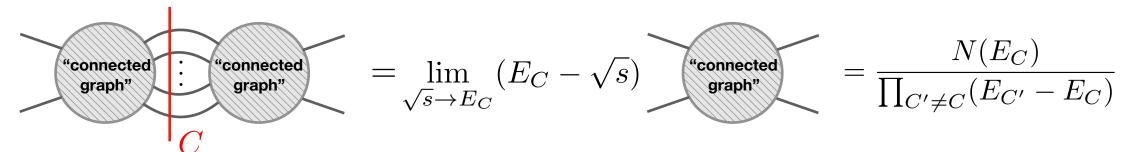


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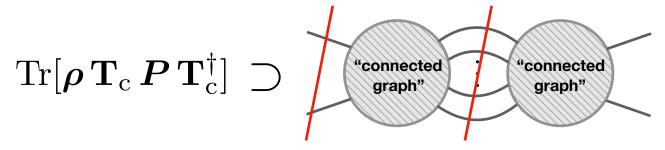
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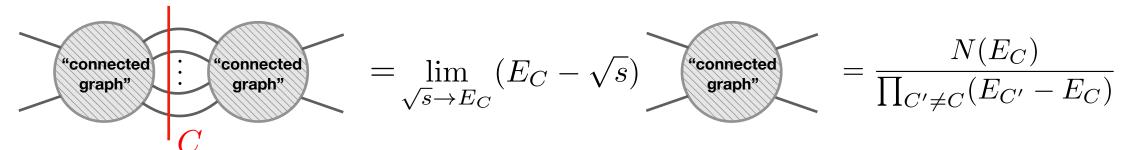
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$$\sigma(\phi^* \to n \, \text{jets}_{\phi}) =$$

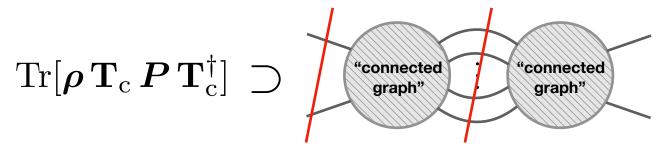


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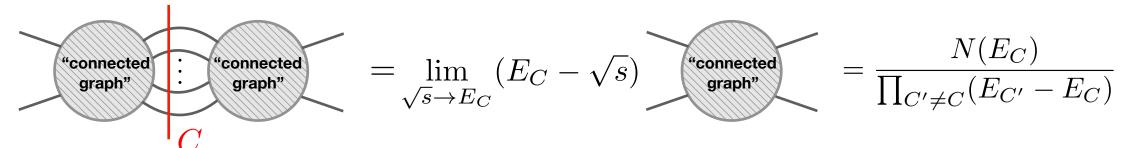


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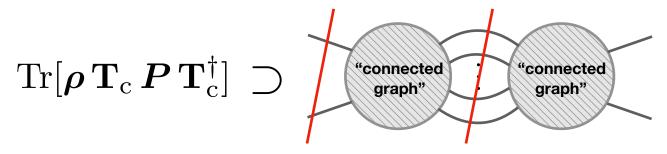
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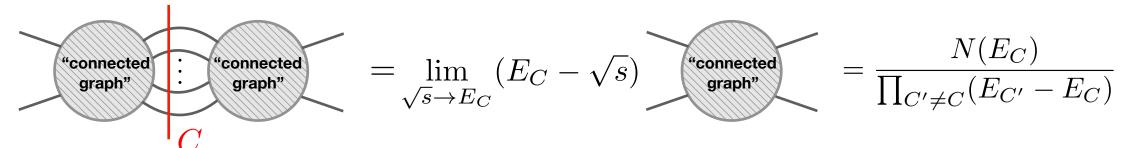
This relation allows to collect locally interference diagrams

$$\sigma(\phi^{\star} \to n \, \mathrm{jets}_{\phi}) = - \begin{array}{c} & & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ &$$



Final-state sum example

Using the CFF representation we can show that



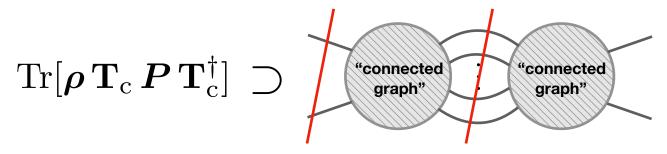
This relation allows to collect locally interference diagrams

Example: consider massless scalar corrections to the decay of a massive scalar $\rho = |\phi^*\rangle \langle \phi^*|$

$$= \int d\Pi \sum_{i=1}^{4} g_i$$

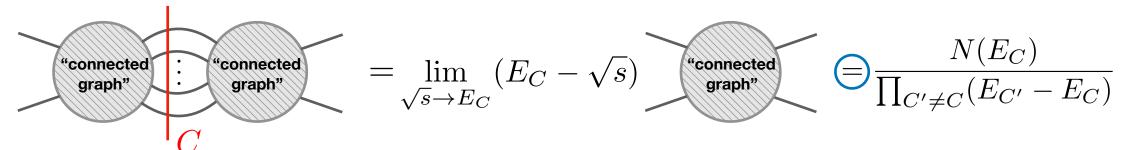
(Capatti, Hirschi, Ruijl, Pelloni [arXiv:2010.01068])

How do we show it?



Final-state sum example

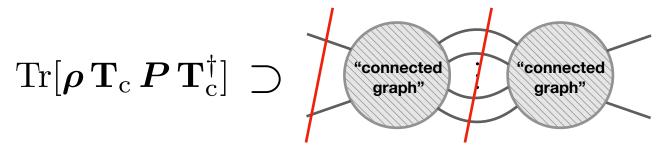
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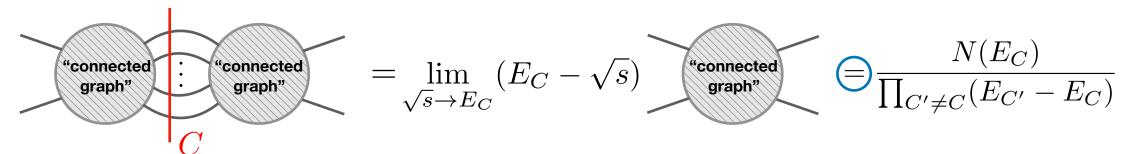
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Final-state sum example

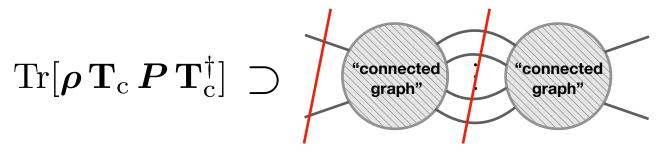
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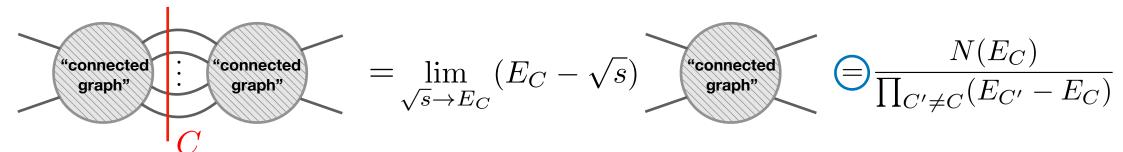
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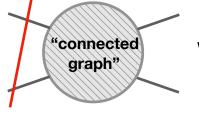
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Extension to initialstate sums



Extension to initialstate sums In the preceding example, we fixed a massive initial-state. What if we want to have massless initial states?



We need to write forward-scattering diagrams as residues of something!

"connected graph"

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How do we extend to initial-state sums? In other words what are forward-scattering diagrams residues of

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Embedding vacuum graph in $\mathbb{C}\setminus\{0\}$ $\operatorname{Re}[z]$

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Embedding vacuum graph in $\mathbb{C}\setminus\{0\}$ $\mathbb{Re}[z]$ $x^0\to z$

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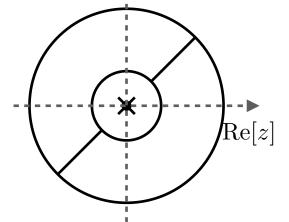
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Embedding vacuum graph in $\mathbb{C} \setminus \{0\}$

$$x^0 \rightarrow z$$



states?

"connected

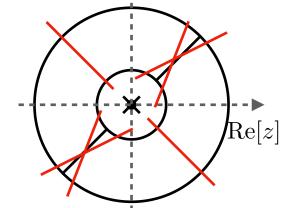
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residues of

Embedding vacuum graph in $\mathbb{C}\setminus\{0\}$ $x^0 \to z$



A Cutkosky cut is a minimal set of edges whose deletion makes the graph contractible

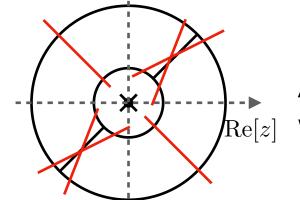
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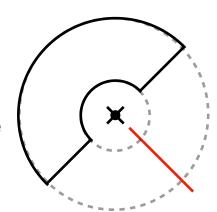
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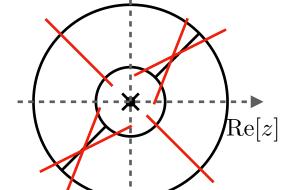
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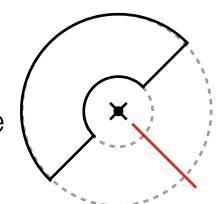
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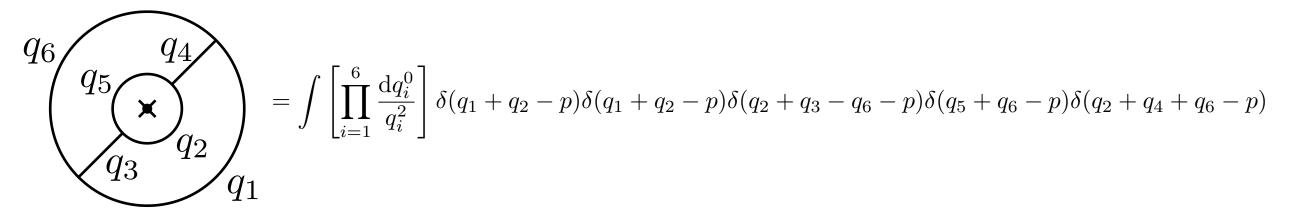
Embedding vacuum graph in $\mathbb{C}\setminus\{0\}$ $x^0 \to z$



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We can construct a three-dimensional representation for embeddings



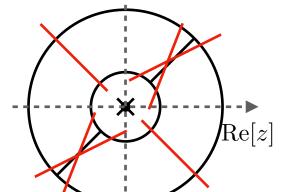
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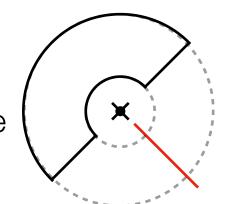
How do we extend to initial-state sums? In other words what are forward-scattering diagrams residues of $\mathbf{Im}[z]$

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Embedding vacuum graph in $\mathbb{C}\setminus\{0\}$ $x^0\to z$



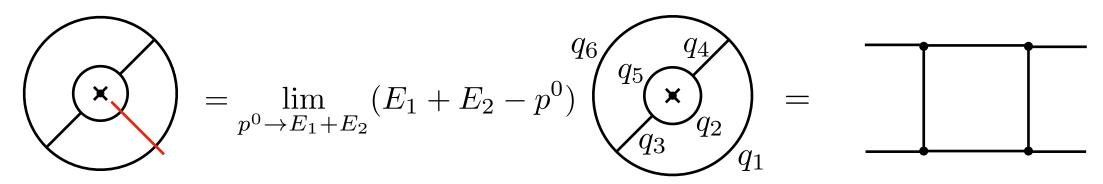
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We can construct a three-dimensional representation for embeddings

$$q_{6} \underbrace{q_{5}}_{q_{3}} \underbrace{q_{4}}_{q_{2}} = \int \left[\prod_{i=1}^{6} \frac{\mathrm{d}q_{i}^{0}}{q_{i}^{2}} \right] \delta(q_{1} + q_{2} - p) \delta(q_{1} + q_{2} - p) \delta(q_{2} + q_{3} - q_{6} - p) \delta(q_{5} + q_{6} - p) \delta(q_{2} + q_{4} + q_{6} - p)$$

Embeddings have thresholds associated with their Cutkosky cuts



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How do we extend to initial-state sums? In other words what are forward-scattering diagrams residues of $\operatorname{Im}[z]$

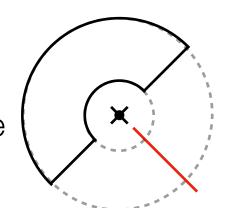
residues of

 $x^0 \to z$

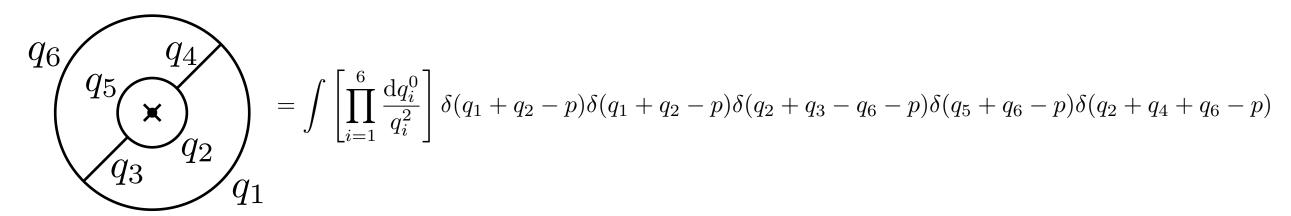
Embedding vacuum graph in $\mathbb{C} \setminus \{0\}$

 $\operatorname{Re}[z]$

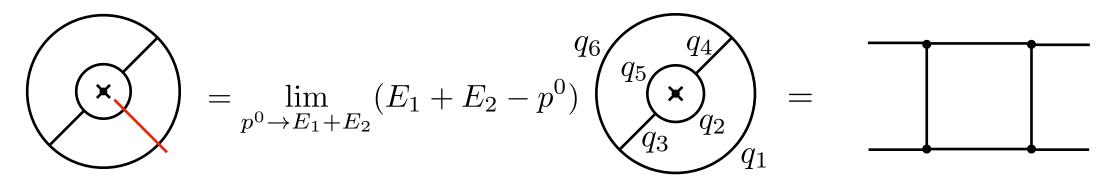
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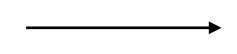


This observation allows to extend the Local Unitarity representation to initial states!

Conclusion

- Energy conservation implies a rigid diagrammatic structure for threshold singularities
 - Connectedness
 - Absence of crossing
 - Obstruction-freedom
- These principles are manifest in a novel 3D-representation that holds for any theory (independent of numerator) and at any loop

Implemented in Mathematica package



https://github.com/apelloni/cLTD

- The presence of connectedness suggests that, in order to understand IR-finiteness, one should decompose cross-sections according to the degree of connectedness
- 3D representations can be used to express interference diagrams as local residues of forward-scattering diagrams, and forward-scattering diagrams as local residues of vacuum embeddings
- In turn, these local residues can be used to write cross-sections in a way that manifests the KLN cancellation mechanism at the local level (Local Unitarity)
- Local Unitarity can be used to numerically evaluate cross-sections