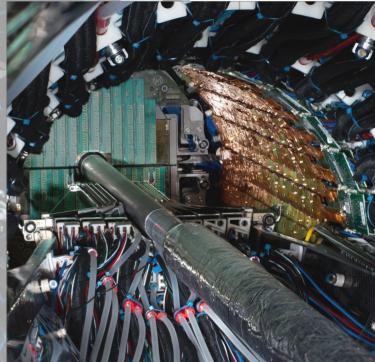
Results of the new MAPS-based ALICE inner tracker operation in the LHC Run 3

### Ivan Ravasenga<sup>1</sup> for the ALICE Collaboration

### <sup>1</sup>CERN (Geneva, CH)

PSD13

St. Catherine's College September 3-8, 2023 OXFORD

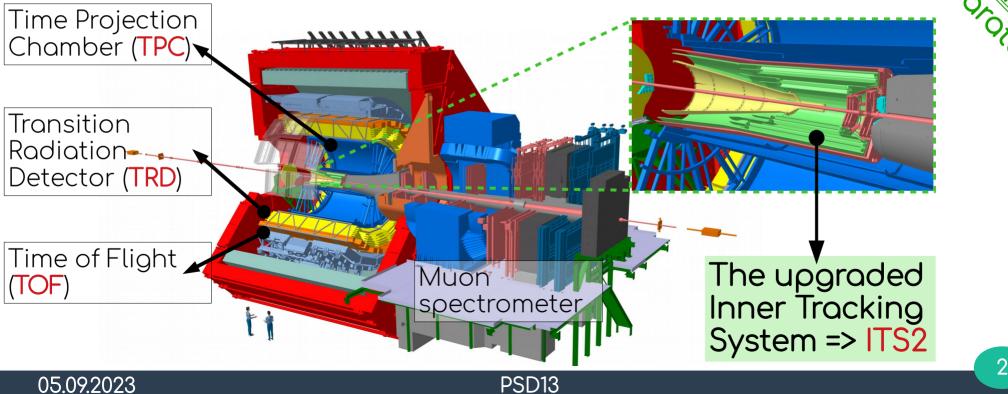




## Introduction – ALICE experiment

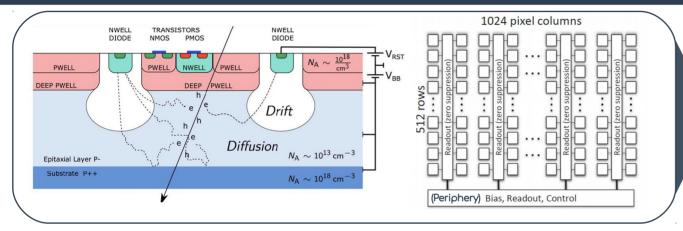


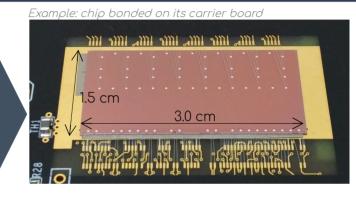
- Run 2 of LHC completed in 2018 with Pb-Pb collisions at  $\sqrt{s_{_{\rm NN}}}$  = 5.02 TeV
- Long-shutdown 2 started in 2018 to allow detector & computing system upgrades



# ALPIDE chip – the detector core → ALice Plxel DEtector







#### Key numbers

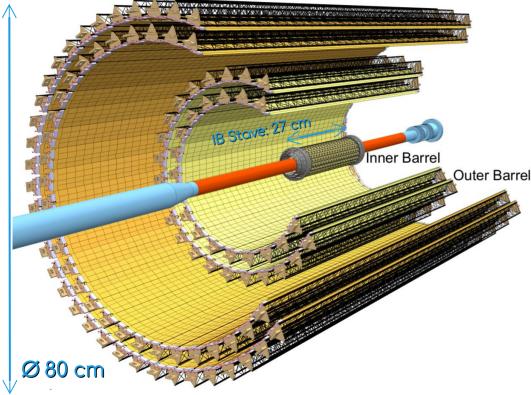
Resistivity	1÷6 kΩcm
Epitaxial layer thickness	25 µm
N-well diode diameter	2 µm
Power consumption	≤ 47 mW/cm <sup>2</sup>
Pixel size	27x29 µm²
Spatial resolution (rø,xz)	5x5 μm²

- TowerJazz 0.18 µm CMOS imaging process a Monolithic Active Pixel Sensor (MAPS)
  - High resistivity p-type epitaxial layer on p-type substrate
  - Small n-well diode  $\rightarrow$  small capacitance ~fF
  - In-matrix sparsification using priority encoder
  - Pixel signal amplified and digitized at a pixel level
  - Low power consumption
  - Pixel data sent towards periphery to the Data Transmission Unit (Serializer + PLL + LVDS driver)



### Introduction – The Upgraded Tracker (ITS2) → 10 m<sup>2</sup> of monolithic active pixel sensors (12.5 GPixels)





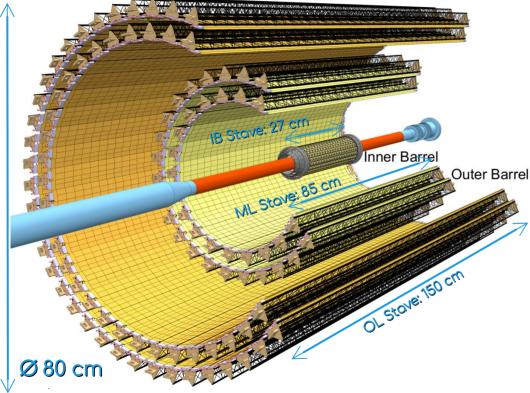
#### Inner Barrel (IB)

- 3 layers (L0  $\rightarrow$  L2)
- 48 Staves made of 9 ALPIDE chips each
- Material budget: 0.36% X<sub>0</sub>
- Readout at 1200 Mb/s per chip

### Inner Tracking System (ITS)

# → 10 m<sup>2</sup> of monolithic active pixel sensors (12.5 GPixels)





#### Inner Barrel (IB)

- 3 layers (**L0 → L2**)
- 48 Staves made of 9 ALPIDE chips each
- Material budget: 0.36%  $X_0$
- Readout at 1200 Mb/s per chip

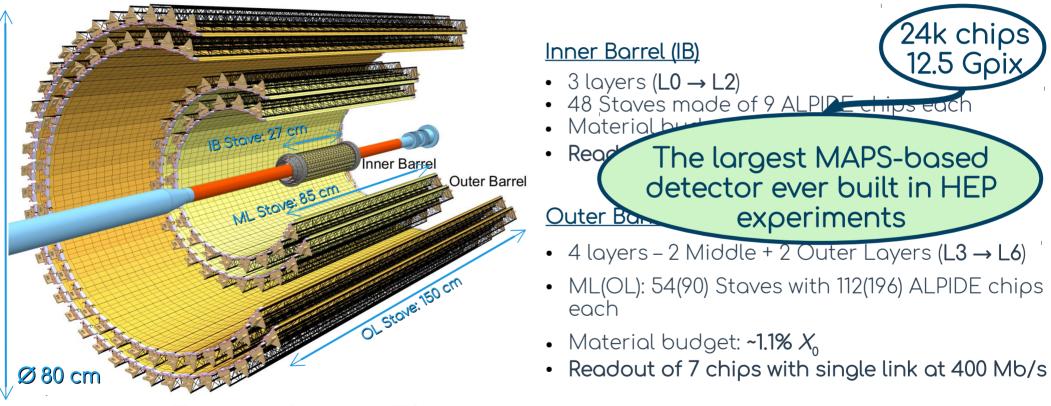
#### <u>Outer Barrel (OB)</u>

- 4 layers 2 Middle + 2 Outer Layers ( $L3 \rightarrow L6$ )
- ML(OL): 54(90) Staves with 112(196) ALPIDE chips each
- Material budget: ~1.1% X<sub>0</sub>
- Readout of 7 chips with single link at 400 Mb/s

### Inner Tracking System (ITS)

# → 10 m<sup>2</sup> of monolithic active pixel sensors (12.5 GPixels)



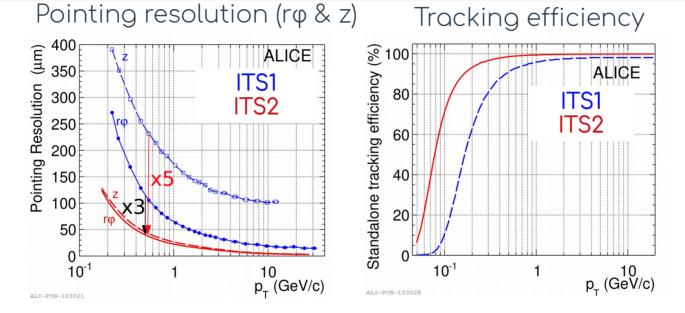


#### Inner Tracking System (ITS)



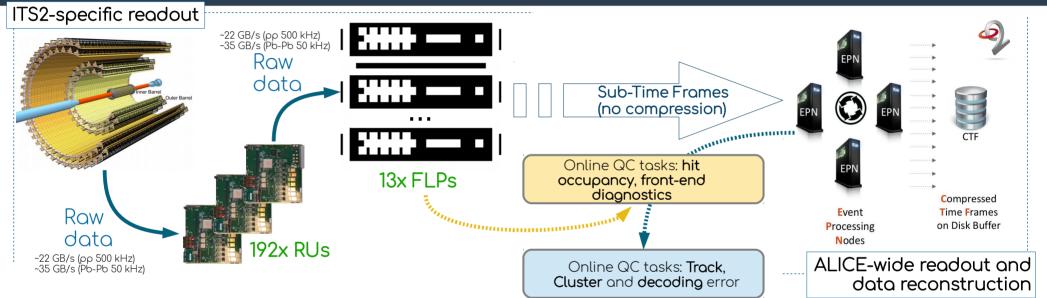
### Expected improvements with ITS2





- Improved impact parameter resolution: factor ~5 (z), factor ~3 ( $r\varphi$ ) at  $\rho_T$  = 500 MeV/c
- Improved standalone tracking efficiency: 60%  $\rightarrow$  90% at  $\rho_T$  = 200 MeV/c

# Data readout architecture and quality control (QC) → a simplified view



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• 13 ITS First Level Processors (FLPs)

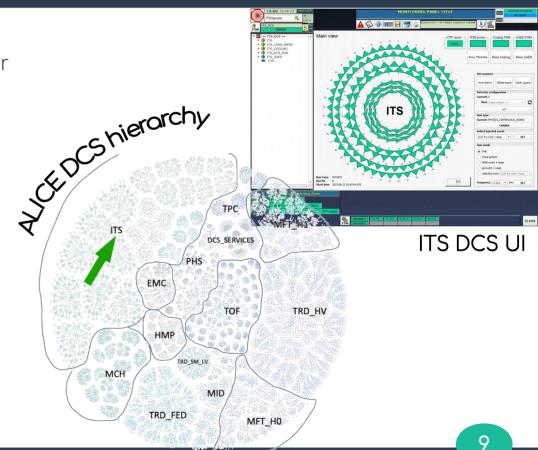
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- Online data quality control tasks: hit occupancy and front-end electronics diagnostics.
- 340 Event Processing Nodes (total EPN from ALICE farm)
  - Online quality control tasks: reconstructed ITS2 tracks, clusters and decoding errors.
- Synchronous reconstruction, calibration and data compression ( $\rightarrow$  GPUs)
- Asynchronous stage: reconstruction with final calibration  $\rightarrow$  final Analysis Object Data (AOD)

## Detector Control System (DCS) - a quick view



- User Interface developed in WinCC detector logic implemented in a Finite State Machine
- Detector operation, monitoring and archiving of detector data.
- Deal with ~110000 data points (ITS only)  $\rightarrow$  typical monitoring frequency of 1 Hz.
- Built as a hierarchical system (partitioned with system of locks)  $\rightarrow$  ITS occupies a big slice of the ALICE hierarchy
- An **independent safety system** interlocks power channels based on stave temperatures and cooling status



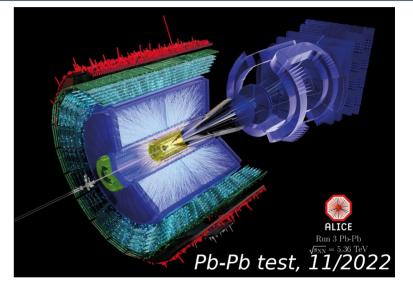


- Started on 2022, July 5<sup>th</sup> with first pp collisions at √s = 13.6 TeV (*stable beams*)
- Pb-Pb ion test in November 2022: record energy 5.36 TeV
- <u>Integrated</u> luminosity so far (pp collisions): ~28 pb<sup>-1</sup>
- ALICE & ITS2 numbers in data taking
  - Nominal ITS framing rate: 202 kHz

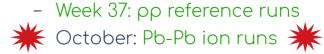
05.09.2023

- ALICE standard luminosity: 500 kHz (instantaneous luminosity ~10<sup>31</sup> cm<sup>-2</sup> s<sup>-1</sup>)
- ITS2 successfully tested up to 4 MHz interaction rate (~ 50 GB/s data rate).
- Loss of acceptance during runs auto-recovered by DCS
- At every beam dump: fast ITS threshold scan on 2% of the pixels to evaluate the quality of the detector calibration

### Run 3 overview



• Main events till next technical stop





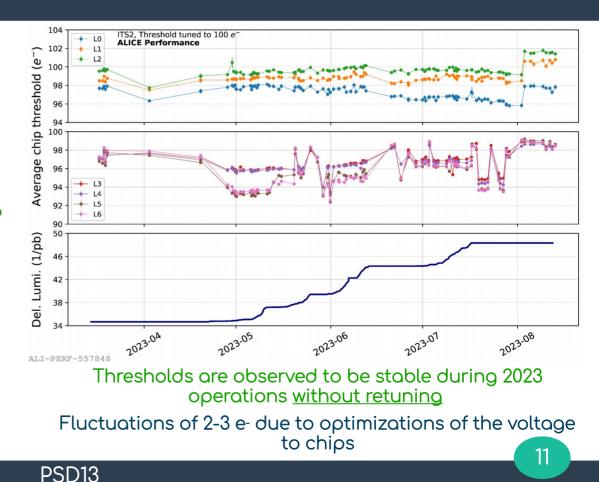
#### PSD13

#### Performance results in Run 3 → ITS2 full calibration (1)



- Main ITS calibration parameters:
  - Masking of noisy pixels
  - Tuning of in-pixel discriminating thresholds
  - Power supply voltage
  - On-chip temperatures
- Percentage of non-working pixels: ~0.2 %
- Threshold calibration of 24120 chips is challenging:
  - Online calibration workflow runs on 40 EPNs with parallel processing
  - Pulsing of ~1% of the pixels: ~252Ghits
  - Thresholds: tuned to 100e-(in-layer RMS < 5-6 e-)

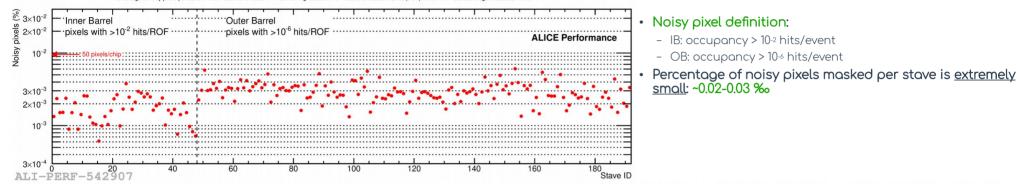
05.09.2023



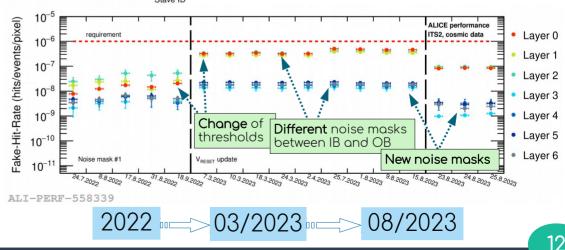
### Performance results in Run 3 $\rightarrow$ ITS2 full calibration (2)

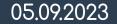
Percentage of noisy pixels per stave in ITS2 - Cosmic run 525947 - ITS2 framing rate 202 kHz - Recorded readout frames (ROF); 27.5 × 10<sup>6</sup> - Stave average thresholds; 100 et





- Fake-hit rate trend during cosmic runs (tuned thresholds + noise masks)
- Stable and < 10-6 hits/event/pixel (design requirement) by masking only ~0.03‰ of the pixels





 $\rightarrow$  Cluster size and simulation

Layer 6

Layer 5

Laver 4

Layer 3

Layer 2

Laver

Laver 0

Laver 0 Layer 1

Layer 2

Laver 3

Layer 4

Layer 5

Laver 6

-60 ALI-PERF-528421

Ton

Rottor

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-40

-20

0



- Cluster size averaged for half barrels
  - Between 3 and 8 pixels depending on n
  - RMS ranging on the same interval
  - Observed to be stable over time
  - Independent of the interaction rate

ALICE Performance

Framing rate: 202 kH

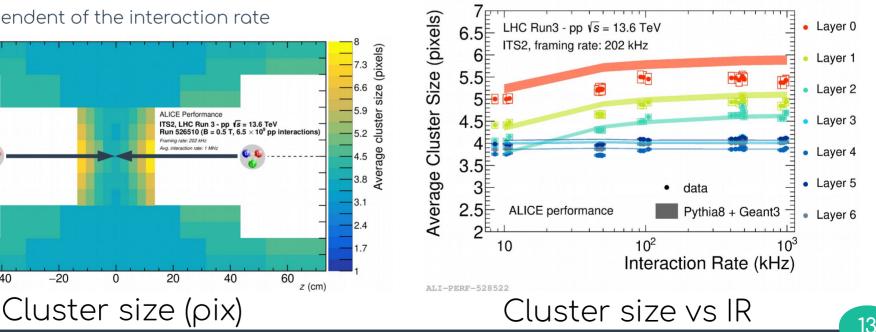
20

40

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Ava, interaction rate: 1 M

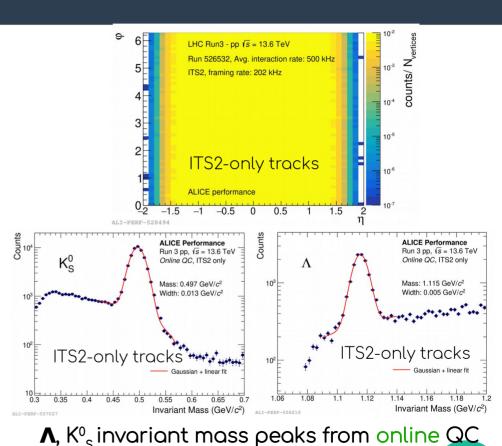
- Simulation with Pythia 8 + Geant 3
  - Simulated noise: 2x10-8 hits/event/pix (IB), 3x10-9 hits/event/pix (OB)
  - Good agreement with data considering approximations: \_
    - Average noise per barrel and not per stave/chip.



Limited statistics in MC: ~20k events.

→ Detector alignment and reconstructed tracks

- ITS tracking: excellent performance with current detector alignment
  - Cellular automaton algorithm
  - Online tracking for quick QA of the data
  - Angular distribution of tracks of good quality  $\rightarrow$  good detector acceptance
- Online physics performance from QC through ▲ and K<sup>0</sup><sub>S</sub> invariant mass peaks



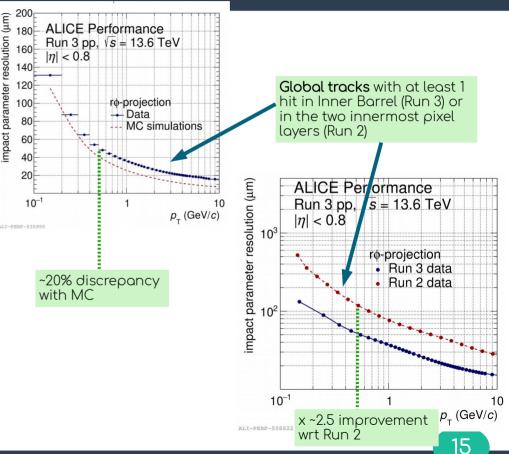


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 $\rightarrow$  Detector alignment and reconstructed tracks

ALICE

- ITS tracking: excellent performance with current detector alignment
  - Cellular automaton algorithm
  - Online tracking for quick QA of the data
  - Angular distribution of tracks of good quality  $\rightarrow$  good detector acceptance
- Online physics performance from QC through ∧ and K<sup>0</sup><sub>S</sub> invariant mass peaks
- Impact parameter resolution measured with Run 3 pp data  $\rightarrow$  <u>excellent performance</u>
  - About 2.5x improvement at p<sub>T</sub> = 500 MeV/c →
    Detector alignment, space charge corrections and calibrations still continuously improving
  - ~20% discrepancy with MC could be related to a mismatch of sensor response in simulation and residual misalignments in data



#### 05.09.2023

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05.09.2023

### Conclusions

- Run 3 started on July 5th 2022
  - pp collisions at √s = 13.6 TeV, nominal interaction rate at 500 kHz.
- Pb-Pb collisions in October 2023 before the year-end closure
  - Major event of the year for ALICE
- Excellent performance of ITS2 in Run 3
  - ITS2 performance is within expectations → no showstoppers for upcoming Pb-Pb.
- Detector Control System and Quality Control system
  - Ready to monitor the detector hardware and data in Run 3

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#### The ITS2 Collaboration



CERN (Switzerland), CCNU (China), Řež u Prahy (Czech Republic), Strasbourg (France), LIPI (Indonesia), Alessandria (Italy), Bari (Italy), Cagliari (Italy), Catania (Italy), LNF (Italy), Messina (Italy), Padova (Italy), Pavia (Italy), Torino (Italy), Trieste (Italy), Nikhef (The Netherlands), UoB/ BUC (Bergen, Norway), Oslo (Norway), COMSATS (Pakistan), Inha (Republic of Korea), Yonsei (Republic of Korea), PNU (Republic of Korea), St. Petersburg (Russia), Kosice TU (Slovakia), Kosice Slovak Academy (Slovakia), SUT (Thailand), Kiev BITP (Ukraine), Liverpool (United Kingdom), Daresbury (United Kingdom), Austin (United States), LBNL (United states), ORNL (United States)



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## Ready to monitor the detector hardware and data in Run 3

(Slovakia), **SUT** (Thailand), **Kiev BITP** (Ukraine), **Liverpool** (United Kingdom), **Daresbury** (United Kingdom), **Austin** (United States), **LBNL** (United states), **ORNL** (United States)

#### Run 3 started on July 5<sup>th</sup> 2022 The ITS2 Collaboration



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## Conclusions



### Backup slides

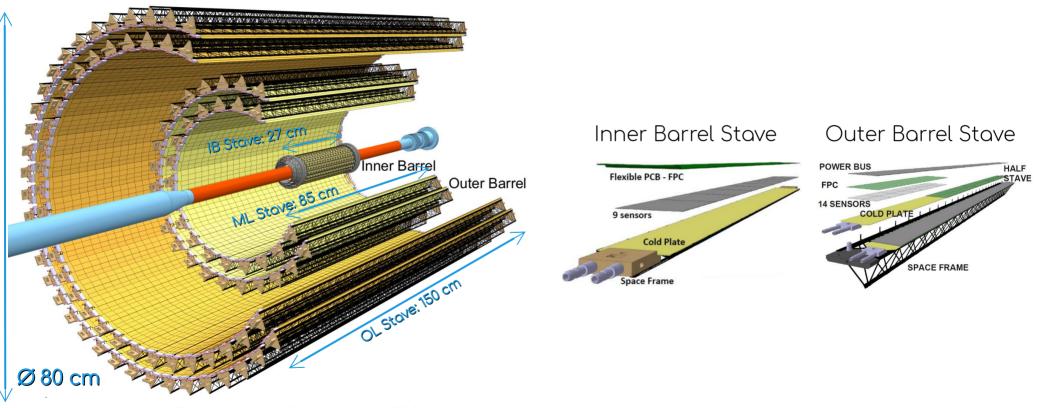






### ITS2 – details on components





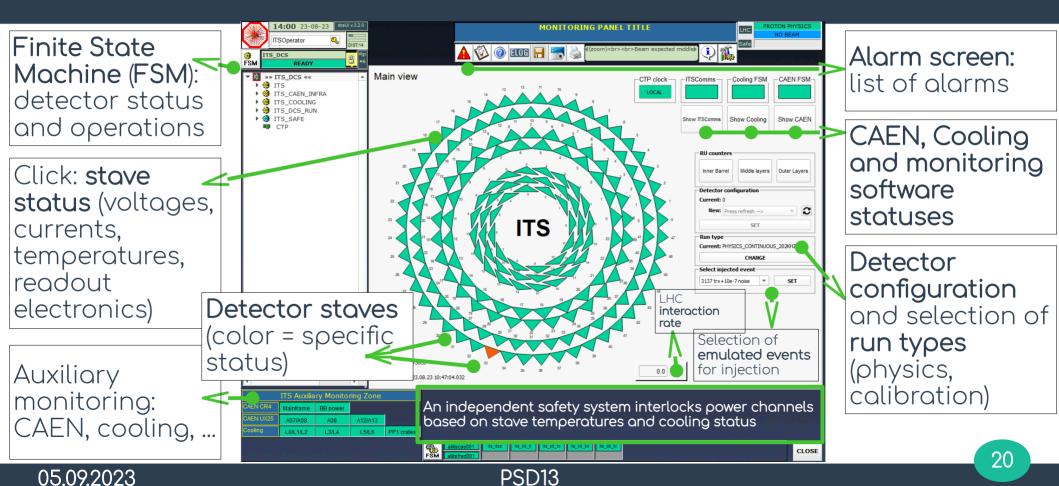
#### Inner Tracking System (ITS)

#### 05.09.2023

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## Detector Control System (DCS) - a quick view





#### 21

# (Data) Quality Control (QC)

#### <u>7 QC online tasks</u> (online monitoring on data subsets)

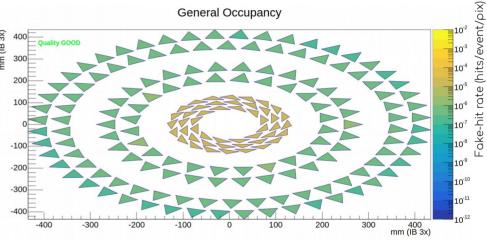
05.09.2023

- Fake-hit rate: monitoring of detector FHR and noisy pixels
- Noisy pixels: for detector noise calibration
- **Calibration**: monitoring of pixel threshold and dead pixels.
- Cluster: monitoring cluster size, topology, etc.
- **Tracks**: monitoring of track multiplicity, angular track distribution, clusters, etc.
- Front-end Electronics: chips in error, trigger flags
- **Decoding errors:** summary of decoding errors per chip

### ... and

<u>5 online post-processing tasks</u> + <u>offline post-</u> <u>processing framework/macros</u> → trending vs run

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Example: detector average occupancy per stave in  $\rho \rho \sqrt{s} = 13.6$  TeV (500kHz IR, 202 kHz framing rate)





## On-surface commissioning overview - 2019/2020

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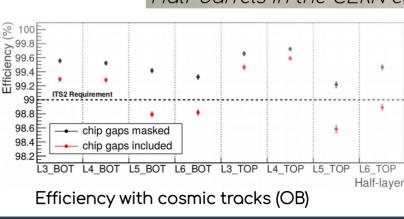
22

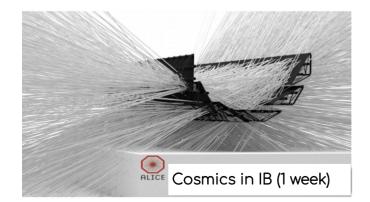
- Commissioning of the full detector in the laboratory before installation in the ALICE cavern
  - Sept 2019  $\rightarrow$  Dec 2020

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- Continuous data taking: cosmic + calibration runs
  - 24/7 shifts + operations by detector experts





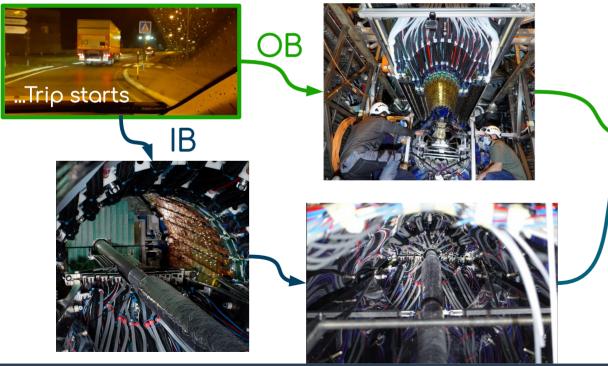


#### ITS installation inside ALICE cavern - 2021 → a trip from lab to ALICE cavern



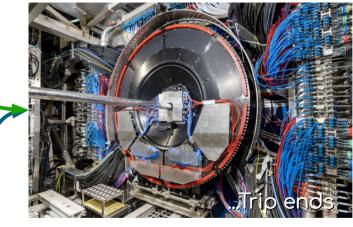
- ITS installation in ALICE cavern started in 2021 after a **successful on surface commissioning from Sept/2019 to Dec/2020**
- OB installation completed in March 2021  $\rightarrow$  IB installation completed in May 2021

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Fast Interaction Trigger (FIT) in front of ITS2

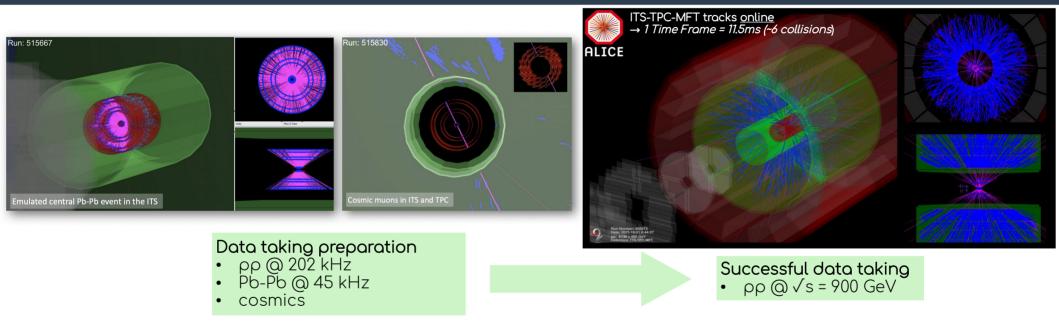


#### The challenge:

- Clearance around beam pipe: ~2 mm
- Clearance between adjacent staves: ~1.2 mm
- Manipulation from **4m distance**

# Verification of barrels after installation and preparation for data taking - 2021 / 2022





<u>19/07/2021</u>: start of ALICE global commissioning with central shifts <u>End October 2021</u>: first pilot collisions ( $pp \sqrt{s} = 900 \text{ GeV}$ ) <u>January 2022 – June 2022</u>: pilot collisions, cosmics, software validation with emulated data

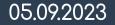




# Verification of barrels after installation and preparation for data taking - 2021

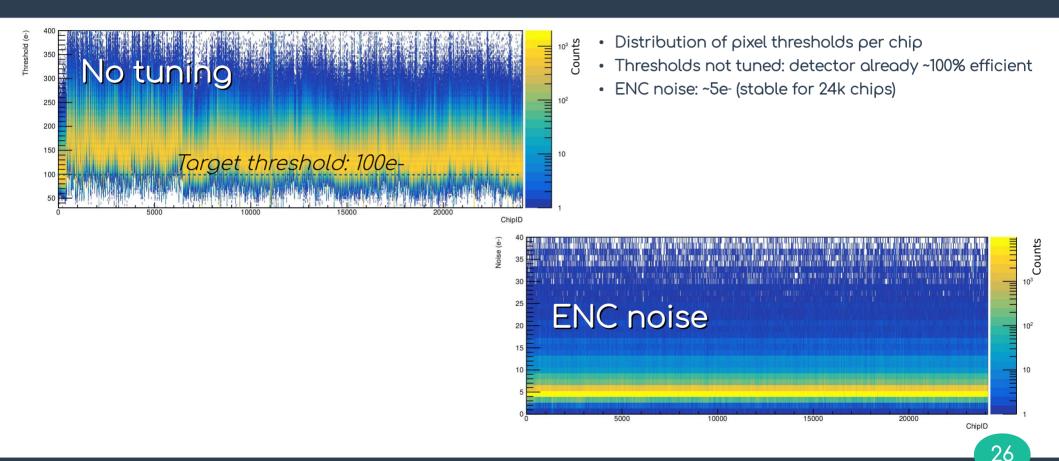


- OB installation (March 2021)
  - Full detector powered and monitored till mid-April
  - Various issues spotted and solved:
    - Problematic cables giving loose contacts or with wrong wire configuration (replaced)
    - Unstable power supplies (replaced)
    - Optimization of cooling for staves and electronics
    - Resolution of bugs into control-system user interface and code.
- IB installation (May 2021)
  - Basic verification of IB: readout tests + resistance measurement to check connections.
  - Basic verification of OB after IB installation: power and communication tests
- ITS standalone commissioning in the cavern (till July 2021)
  - Full verification of the detector: cosmic runs, data taking with emulated data patterns (pp, Pb-Pb), calibration runs.



### Preliminary performance results in Run 3 → ITS2 full calibration (2)



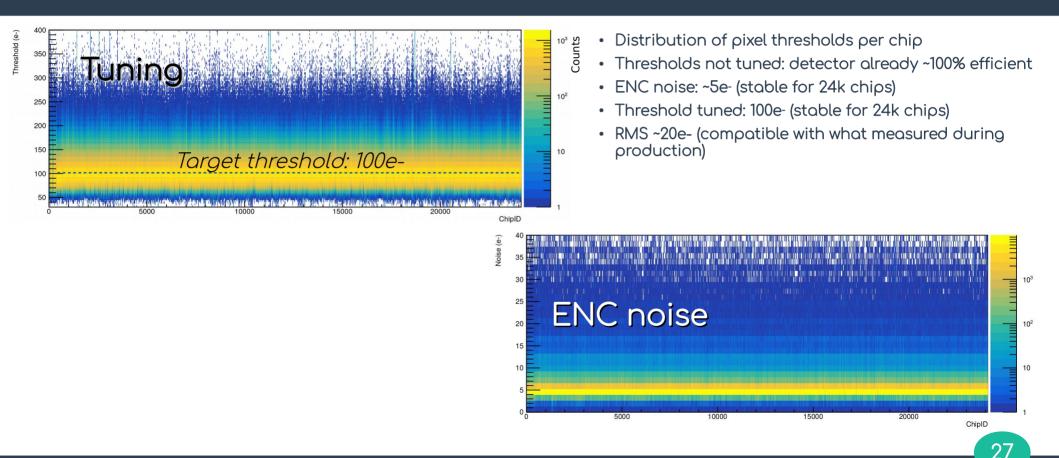






### Preliminary performance results in Run 3 → ITS2 full calibration (3)









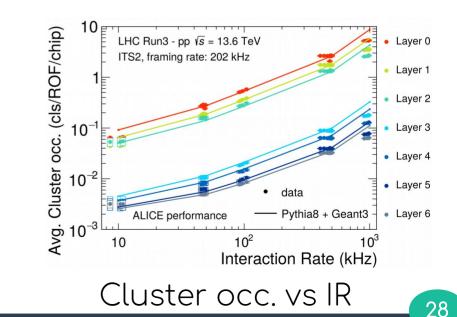
 $\rightarrow$  Cluster occupancy and simulation

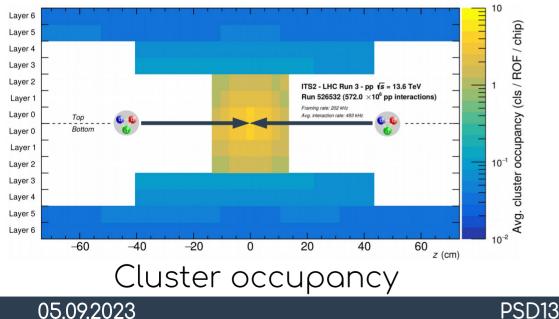


- Cluster occupancy per readout frame (ROF) and per chip
  - Between 0.1 and 10 clusters/ROF/chip @ 1 MHz (202 kHz framing rate)
  - Observed to be stable over time (at the same IR)
  - Dependent on the interaction rate



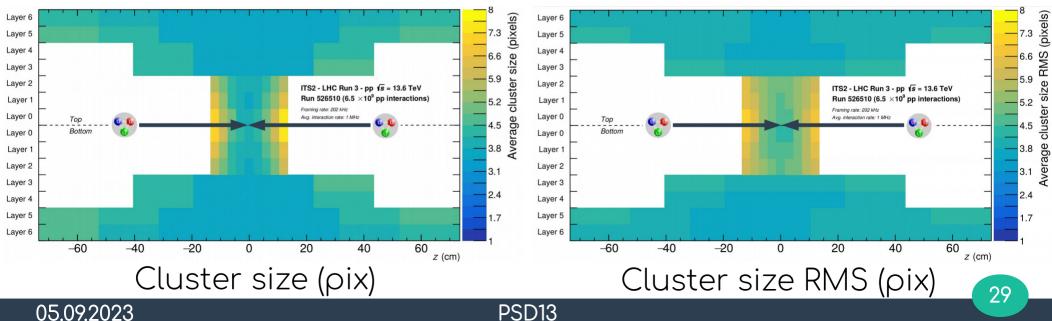
- Simulated noise: 2x10-8 hits/event/pix (IB), 3x10-9 hits/event/pix (OB)
- Good agreement with data considering approximations:
  - Average noise per barrel and not per stave/chip.
  - Limited statistics in MC: ~20k events.





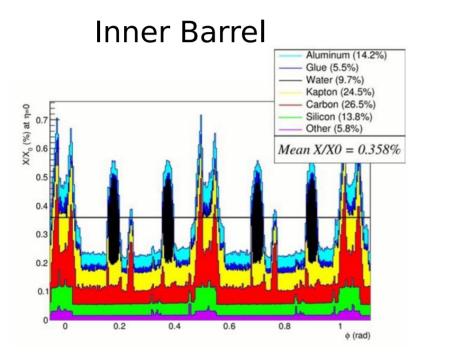
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- Cluster size averaged for half barrels
  - Between 3 and 8 pixels depending on  $\eta$
  - RMS ranging on the same interval
  - Observed to be stable over time
  - Independent of the interaction rate
  - PID studies with machine learning techniques are ongoing



### ITS2 material budget





#### **Outer Barrel**

