# Accelerators Part I 

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## References and accessible Reading Material

available on the internet:
P. Schmüser \& J. Rossbach, Basic course on accelerator optics:
https://cds.cern.ch/record/247501/files/p17.pdf
F. Tecker, Longitudinal Dynamics material:
https://arxiv.org/pdf/1601.04901.pdf

Book, H.Wiedemann, Particle Accelerators, download pdf !:
https://link.springer.com/book/10.1007\%2F978-3-319-18317-6

CERN Accelerator School (CAS) proceedings homepage (huge!)
http://cas.web.cern.ch/cas/CAS Proceedings.html

## books, papers:

S.Peggs, T.Satogata, Introduction to Accelerator Dynamics, Cambridge University Press, 2017
A. Wolski, Beam Dynamics in high energy particle accelerators, Imperial College Press, 2014
A. W. Chao, M. Tigner, Handbook of Accelerator Physics and Engineering, World Scientific 1999
E. D. Courant and H. S. Snyder, Annals of Physics: 3, 1-48 (1958)

## Contents:

- Particle types and relativity for accelerators
- Accelerator components: Dipole, quadrupoles magnets, accelerating RF cavities...
- Transverse plane ( $\mathrm{x}, \mathrm{y}$ ) $\rightarrow$ Guiding and focusing beams
- Particle motion in linear approximation
- Invariant of motion and Emittance
- Beam Optics: beta functions, beams sizes, Beam Tunes
- Longitudinal plane ( $\mathrm{s}, \mathrm{t}$ ) $\rightarrow$ Acceleration
- Synchronous motion
- Synchrotrons and LHC injection complex
- Hadron Accelerators: Synchrotrons
- Beam production
- Magnets
- Luminosity
- Collective effects


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## Introduction to accelerators and particle Dynamics

## Accelerator = series of elements for beam guiding (bending, focusing) and acceleration of particles

- guiding fields must ensure stability of circulating particles on designed trajectory
- often arranged in a closed loop (ring) $\rightarrow$ acceleration occurs at every turn
- or in a periodic "straight" sequence (linacs) $\rightarrow$ acceleration all along the length



## Accelerating particles $\rightarrow$ Towards Relativity



## Particles to Accelerate

Wide range of rest masses from electron to heavy ions

The accelerators differ vastly, e.g.

- particle speed in cavities
- synchrotron radiation power
- activation by losses
- requirements for vacuum

Accelerator design depends on particle type and properties Energy

## Speed of different particles vs energy

## relativistic energy-

 momentum relation:$$
\begin{aligned}
E & =\sqrt{m_{0}^{2} c^{4}+c^{2} p^{2}} \\
& =m_{0} c^{2}+E_{k}
\end{aligned}
$$

$$
\gamma=\frac{E}{m_{0} c^{2}}=1+\frac{E_{k}}{m_{0} c^{2}}
$$

$$
\beta=\sqrt{1-1 / \gamma^{2}}
$$


numerical example for protons LHC injection energy 450 GeV ultra relativistic beam $\beta^{\sim} 1$

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## Guiding charged particles: Lorentz Force

$$
\vec{F}=e \vec{E}+e \vec{v} \times \vec{B} \quad \text { (charge = e) }
$$

electric field energy gain: $\Delta E_{k}=e U$

Longitudinal Motion Parallel to the direction of motion. Used to accelerate charged particles.

## magnetic field

$$
\text { bending: } B \rho=p / e, \Delta E_{k}=0
$$


H.A.Lorentz 1853-1928


## Lorentz Force - getting it right



## Lorentz Force - getting it right



Tevatron p-pbar collider $\rightarrow$ same B field $\rightarrow$ difficult to have pbar beams LHC p-p collider $\rightarrow$ opposite B field $\rightarrow$ complex magnet design so called 2 in 1

## Comparison E and B field

Bending radius for protons in B and E :
example: electric and magnetic force on protons
$\overrightarrow{F_{E}}=e \cdot \vec{E}, \quad \overrightarrow{F_{B}}=e \cdot \vec{v} \times \vec{B}$ table: bending radius, varying $\mathrm{E}_{\mathrm{k}}$

| $E_{k}$ | $B=1 T$ | $E=10 \mathrm{MV} / \mathrm{m}$ |
| :---: | :---: | :---: |
| 60 keV | 35 mm | 12 mm |
| 1 MeV | 140 mm | 200 mm |
| 1 GeV | 5.6 m | 150 m |

Magnetic fields are used exclusively to bend and focus ultra-relativistic particles

Accelerators in fundamental Particle Physics Research

- High Energy $\rightarrow$ Acceleration
- High Luminosity $\rightarrow$ Guiding and focusing high intensity beams

LEIR
Low Energy Ion Ring


## Accelerate Particles

$$
\Delta E_{k}=e U
$$



## Make Particles Circulate



## Bending Magnet and magnetic rigidity



Field defined by the geometry of poles
$\rightarrow 2$ flat poles


Superconducting
Field defined by the geometry of coils
$\rightarrow$ Current distribution Cos $\phi$

$F_{c}$

- accelerate beams $\rightarrow$ increase B
- at fixed B : higher $\mathrm{p} \rightarrow$ increase bending angle...

$$
B \rho=\frac{p}{e}
$$

Magnetic rigidity:

## Focusing the Particles



## Quadrupole Magnet - Focusing Element

Quadrupole magnets:


Iron dominated:
field determined by geometry of poles
$\rightarrow 4$ hyperbolic poles

## Superconducting:

field determined by
geometry of coils
$\rightarrow j(\phi) \sim \cos 2 \phi$

## Quadrupole magnets

- Focusing in one plane
- Defocusing in the other plane


$$
\nabla \times \boldsymbol{B}=0 \rightarrow \frac{\partial B_{y}}{\partial x}=\frac{\partial B_{x}}{\partial y}
$$

Gradient g

## HiLumi LHC magnet zoo



Triplet QXF (LARP and CERN)


Orbit corrector (CIEMAT)


Separation dipole D1 (KEK)


11 T dipole (CERN)


Recombination dipole D2 (INFN design)


Overall, about 150 magnets are needed

## Accelerator elements



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## Curvelinear Coordinate System

aim: derive a set of equations that describe the motion of a single particle wrt. a curved coordinate system around the reference orbit of a beam, $(x, y)$

see also: Frenet-Serret coordinates, e.g. Wiedemann chap 4.3

## Deriving the Equation of Motion in x-plane (see Appendix)



Frenet-Serret coordinate system
the effect of the curved coordinate system, i.e. the moving unit vectors $e_{x}, e_{s}$ must be included in the calculation

## starting with general equation of motion: <br> $$
\frac{d \vec{p}}{d t}=\gamma m_{0} \ddot{\vec{R}}=\vec{F}
$$

dipole and
quadrupole field
orbit curvature

Quadrupole field gradient sign convention!
$k$-value

$$
x^{\prime \prime}+\left(\frac{1}{\rho^{2}}+k\right) x=0
$$

off momentum term
derivative w.r.t. path-length $s$, not time $t$

Equation of Motion in $x$ and $y$ planes for designed momentum:

$$
\begin{gathered}
x^{\prime \prime}+\left(\frac{1}{\rho^{2}}+k\right) x=0 \\
y^{\prime \prime}-k y=0
\end{gathered}
$$



## Equation of Motion in x and y planes for designed momentum: generalized form

$$
\begin{gathered}
x^{\prime \prime}+\left(\frac{1}{\rho^{2}}+k\right) x=0 \\
y^{\prime \prime}-k y=0
\end{gathered}
$$

generalised form:


$$
\begin{array}{r}
x^{\prime \prime}+K_{x}(s) x=0 \\
y^{\prime \prime}-K_{y}(s) y=0
\end{array}
$$


*see also Wiedemann sec. 1.5.8

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$$

generalised form:

$$
\begin{aligned}
x^{\prime \prime}+K_{x}(s) x & =0 \\
y^{\prime \prime}-K_{y}(s) y & =0
\end{aligned}
$$

## Differential Equation valid for:

- drift spaces
- Quadrupoles ( $k \neq 0$ )
- combined function magnets ( $k \neq 0$, $1 / \rho \neq 0$ )
- on-momentum particles ( $\Delta \mathrm{p}=0$ )
we discuss solutions of different cases of this equations in single accelerator magnets, depending on $K(s)$ and $\rho(\mathrm{s})$


## Equation of Motion in $x$ and $y$ planes for designed momentum: off momentum particles

$$
\begin{aligned}
x^{\prime \prime}+\left(\frac{1}{\rho^{2}}+k\right) x & =\frac{1}{\rho} \frac{\Delta p}{p_{0}} \\
y^{\prime \prime}-k y & =0
\end{aligned}
$$



Differential Equation valid for:

- drift spaces
- Quadrupoles ( $k \neq 0$ )
- combined function magnets ( $k \neq 0$, $1 / \rho \neq 0$ )
- on-momentum particles ( $\Delta p \neq 0$, first order)
we discuss solutions of different cases of this equations in single accelerator magnets, depending on $K(s), \rho(s)$ and $\Delta p$
*see also Wiedemann sec. 1.5.8


## Summary on Approximations used

- small displacements $x \ll \rho, y \ll \rho, \ddot{s} \approx 0$ (paraxial optics)
- only dipole and quadrupole magnets (linear field changes)
- design orbit lies in a plane, horizontal (flat accelerator)
- no coupling between motion in hor. and vert. plane (upright magnets)
- small momentum deviations $\Delta \mathrm{p} / \mathrm{p}_{0} \sim 10^{-4}$ (quasi monochromatic beam)
- in general: no quadratic or higher order terms (linear beam optics)

Next Step: Solving the Equation of Motion

$$
\begin{aligned}
x^{\prime \prime}+K_{x}(s) x & =0 \\
y^{\prime \prime}-K_{y}(s) y & =0
\end{aligned}
$$

## Piecewise Solution of Equation

$$
x^{\prime \prime}+K(s) x=0
$$

For ON MOMENTA particles $\rightarrow$ general form of equation similar to harmonic oscillator with three cases: $K=0, K<0, K>0$

$m \ddot{x}+k x=0, \omega=\sqrt{\frac{k}{m}}$


## Drift Space

On momentum particles $(\Delta p=0)$ moves straight

$$
x^{\prime \prime}+K(s) x=0
$$

1) $\mathrm{K}=0 \rightarrow$ Drift Space

$$
\binom{x}{x^{\prime}}_{\text {out }}=\left(\begin{array}{ll}
1 & L \\
0 & 1
\end{array}\right)\binom{x}{x^{\prime}}_{\mathrm{in}}
$$



## Focusing Quadrupole

On momentum particles ( $\Delta \mathrm{p}=0$ )

$$
x^{\prime \prime}+K(s) x=0
$$

2) K $>0$ : Focusing Quadrupole

$$
\begin{aligned}
& \binom{x}{x^{\prime}}_{\text {out }}=\left(\begin{array}{cc}
\cos (\sqrt{K} L) \\
-\sin (\sqrt{K} L) \sqrt{K} & \sin (\sqrt{K} L) / \sqrt{K} \\
\cos (\sqrt{K} L)
\end{array}\right)\binom{x}{x^{\prime}}_{\text {in }} \\
& \text { lens approximation: } \quad K=\frac{1}{L f}, \quad \lim _{L \rightarrow 0}\left(\sin (\sqrt{L / f}) \frac{1}{\sqrt{L f}}\right)=\frac{1}{f}
\end{aligned}
$$

$$
\binom{x}{x^{\prime}}_{\text {out }}=\left(\begin{array}{cc}
1 & 0 \\
-1 / f & 1
\end{array}\right)\binom{x}{x^{\prime}}_{\mathrm{in}}
$$



## Defocusing Quadrupole

3) K<0: Defocusing Quadrupole

$$
\binom{x}{x^{\prime}}_{\text {out }}=\left(\begin{array}{cc}
\cosh (\sqrt{|K|} L) & \sinh (\sqrt{|K|} L) / \sqrt{|K|} \\
\sinh (\sqrt{|K|} L) \sqrt{|K|} & \cosh (\sqrt{|K|} L)
\end{array}\right)\binom{x}{x^{\prime}}_{\mathrm{in}}
$$

thin lens approximation: $\quad K=\frac{1}{L f}, \lim _{L \rightarrow 0}\left(\sin (\sqrt{L / f}) \frac{1}{\sqrt{L f}}\right)=\frac{1}{f}$
thin lens approximation for defocusing quad:

$$
\binom{x}{x^{\prime}}_{\text {out }}=\left(\begin{array}{cc}
1 & 0 \\
1 / f & 1
\end{array}\right)\binom{x}{x^{\prime}}_{\text {in }}
$$



## Alternating gradient sequence $\rightarrow$ net focusing effect!

concatenation of particle transport through a series of elements:

$$
\boldsymbol{M}=\boldsymbol{M}_{n} \ldots \boldsymbol{M}_{2} \cdot \boldsymbol{M}_{1} \quad(\boldsymbol{M}=\text { transport matrix } 2 \times 2)
$$




$$
\begin{aligned}
M_{\text {doublet }}=\left(\begin{array}{cc}
1 & 0 \\
-\frac{1}{f} & 1
\end{array}\right) & \cdot\left(\begin{array}{cc}
1 & l \\
0 & 1
\end{array}\right) \cdot\left(\begin{array}{cc}
1 & 0 \\
\frac{1}{f} & 1
\end{array}\right) \\
& =\left(\begin{array}{cc}
1+\frac{l}{f} & l \\
-\frac{1}{f^{*}} & 1-\frac{l}{f}
\end{array}\right)
\end{aligned}
$$

$$
f^{*}=\frac{f^{2}}{l}>0 \quad \rightarrow \mathrm{M}_{\text {doublet }} \text { is always focusing }
$$

## FODO Cell

$$
\boldsymbol{M}_{\mathrm{FODO}}=\left(\begin{array}{cc}
C & S \\
C^{\prime} & S^{\prime}
\end{array}\right)=\left(\begin{array}{cc}
1-\frac{L^{2}}{8 f^{2}} & L\left(1+\frac{L}{4 f}\right) \\
-\frac{1}{f^{*}} & 1-\frac{L^{2}}{8 f^{2}}
\end{array}\right), \quad \frac{1}{f^{*}}=\frac{L}{4 f^{2}}\left(1-\frac{L}{4 f}\right)
$$



Unit sequence of magnets used to build an accelerator Alternating gradients $\rightarrow$ net focusing!


## Summary Matrix Treatment

- equation of motion is piecewise solved for constant $K(s)$
- coordinates $x, x^{\prime}$ are transported by multiplication with a $2 \times 2$ matrix
- matrixes can be concatenated $\rightarrow$ particle transport over many turns
- defocusing and focusing quadrupoles are combined in overall focusing doublets
- linear motion in a ring is stable over $n$ turns if stability conditions are fulfilled ( $|\operatorname{Tr} \mathbf{M}|<2$ )



## The two dialects of

Accelerator Physics

EPFL

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- defocusing and focusing quadrupoles are combined in overall focusing doublets
- linear motion in a ring is stable over $n$ turns if stability conditions are fulfilled ( $|\operatorname{Tr} \mathbf{M}|<2$ )
- The motion can be parametrized (Courant-Schneider Parametrization) $\rightarrow$ introduce optical function $\beta$ function



## Hill equation

- First used by an astronomer G. Hill in his studies of the motion of the moon, a motion under the influence of periodically changing forces

$$
x^{\prime \prime}+K(s) \cdot x=0
$$




1838-- 1914

$$
K(s)=K(s+C)
$$

Periodic over one full revolution C = 29 days

## Hill equation

- First used by an astronomer G. Hill in his studies of the motion of the moon, a motion under the influence of periodically changing forces


## Solution is of the type:

$u(s)=A \sqrt{\beta(s)} \cos [\phi(s)]$
Pseudo-harmonic oscillator



$$
\begin{array}{r}
x^{\prime \prime}+K(s) \cdot x=0 \\
K(s)=K(s+C)
\end{array}
$$

## Hill: Solution for periodic $K$

$$
x(s)=A \sqrt{\beta(s)} \cos \left(\varphi(s)-\varphi_{0}\right), \varphi(s)=\int_{t=s_{0}}^{s} \frac{d t}{\beta(t)}
$$

$\rightarrow$ the beta function is a scaling factor for the amplitude of orbit oscillations and their local wavelength
$A, \varphi_{0}$ are constants of motion


strong quads

## Comparison to Classical Harmonic Oscillator

$$
\begin{gathered}
\ddot{u}+\omega^{2} u=0 \\
u(t)=A \cos \omega t, \omega=\sqrt{\frac{k}{m}}
\end{gathered}
$$


amplitude is fixed:

$$
A=\mathrm{const}
$$

phase grows linear with time: $\quad \sqrt{\frac{k}{m}} t$
conserved (energy):

$$
\frac{k}{2} u^{2}+\frac{m}{2} \dot{u}^{2}=\frac{k}{2} A^{2}
$$

## Hill Equation (pseudo harmonic equation)

$$
\begin{aligned}
x(s) & =\sqrt{2 J \beta} \cos (\varphi) \\
x^{\prime}(s) & =-\sqrt{\frac{2 J}{\beta}}(\alpha \cos (\varphi)+\sin (\varphi))
\end{aligned}
$$

amplitude varies:

$$
x(s) \propto \sqrt{\beta(s)}
$$

phase increases monotonically
but growth rate varies as $1 / \beta$ :

$$
d \varphi=\frac{d s}{\beta(s)}
$$

conserved (action):

$$
\gamma x^{2}+2 \alpha x x^{\prime}+\beta x^{\prime 2}=2 J=\mathrm{const}
$$

## Conserved action : invariant on motion for single Particle



## Closer look to Equation of Motion

Initial conditions for the amplitude and phase.


## Beta Function (1)

The Beta-function is a periodic function entirely defined by the lattice (the magnets).
This function is calculated by means of accelerator design software codes. An examples of this is the Methodical Accelerator Design (MAD-X) that describes particle accelerators, simulate beam dynamics and optimise the optics. In case you want to play http://cern.ch/madx

Beta-function $\rightarrow$ beam envelope


Trajectory of a single particle

Turn, after turn, after turn...betatron


Trajectory of a many particles defining the beam envelope

LHC beams contain about $3 \times 10^{14}$ protons/beam

## Beta Function at LHC

Examples of real optics used in the LHC at the very small beta-star of 0.25 m in ATLAS and CMS.
LHC 6.5TeV Collisions at 0.25 m beta-star ATLAS and CMS


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## Beam Emittance



- single particles are associated with a particular ellipse
- In a bunch we have many particles $10^{11}$
- emittance $\varepsilon$ is the average value of particle action J
- Beam Emittance is a property of the beam.

$$
\varepsilon=<>
$$

## Beam Emittance


beam emittance as statistical property:

$$
\varepsilon_{x}=\sqrt{<x^{2}><x^{\prime 2}>-<x x^{\prime}>^{2}}
$$

projected Gaussian distribution:
$f(x)=\frac{1}{\sqrt{2 \pi} \sqrt{\beta_{x} \varepsilon_{x}}} \exp \left(-\frac{x^{2}}{2 \beta_{x} \varepsilon_{x}}\right)$

Beam size is known all along the ring:

$$
\sigma_{x, y}(s)=\sqrt{\epsilon_{x, y} \beta_{x, y}(s)}
$$


$\xrightarrow[s]{ }$

## Conservation of Emittance

Beams subject to conservative forces as in our accelerator (without dissipative forces
i.e. synchrotron radiation) $\rightarrow$ preserve the phase space density over time

The phase space density behaves like an incompressible liquid.


with a given emittance a beam can be made small with large angular spread, or can have small angular spread with a large size

## Phase Space Ellipse in Drift Space



## Phase Space Ellipse after focusing



## Beam transverse size

Beam Emittance is a property of the beam.
Together with the beta-function gives the complete definition of the beam size (standard deviation).

$$
\sigma_{x}(s)=\sqrt{\epsilon \beta_{x}(s)}
$$



Emittance cannot be changed by focusing/defocusing but it shrinks with beam energy.

Normalized Emittance is constant with energy

$$
\epsilon_{n}=\beta_{\mathrm{rel}} \gamma_{\mathrm{rel}} \epsilon
$$

## Beam size and Emittance measurements

Different mechanisms are used to measure the transverse beam size (and de-convolute it to global emittance).

Some interact with the beam, they can only be used at low intensities or low energies, like fast rotations wire scanners.

Other measure the induced ionisation in the rest gas, like ionisation profile monitors or synchrotron radiation, like LHC BSRT.


## Betatron Tune <br> $Q x=64.31$ <br> $Q y=59.32$

Number of complete oscillations per turn:

$$
Q_{x}=\frac{1}{2 \pi} \oint \frac{\mathrm{~d} s}{\beta_{x}(s)} \quad \begin{aligned}
& x: \text { horizontal tune } \\
& y: \text { vertical tune }
\end{aligned}
$$

## Integer tune:

Seen in orbit response by ~550 dual plane Beam Position Monitors (BPM Electrodes)


## Fractional Tune:

Turn-by-turn signal on single electrode after a small beam excitation (kick)

Fast Fourier transform (FFT) of oscillation data gives resonant frequency

## Off momentum particles

What happens to a particle with energy deviation $\delta$ travelling in the accelerator magnetic elements?

## Off momentum particles

What happens to a particle with energy deviation $\delta$ travelling in the accelerator magnetic elements?

Particle with an energy deviation $\delta$

- Will be bent and focused differently

- The equation of motion: non-homogeneous Hill equation


## Off momentum particles: Dispersion

$$
\delta=\frac{\Delta p}{p_{0}}
$$

$$
x^{\prime \prime}+K_{x}(s) x=\frac{1}{\rho(s)} \frac{\Delta p}{p_{0}}
$$

Bending in a dipole changes with the particle energy...

Particles will move on different orbit!

$$
B \rho=p / e
$$



Particle deviation from ideal orbit

$$
x=x_{\beta}+x_{\varepsilon}=x_{\beta}+D(s) \cdot \delta
$$

$D(s)$ - dispersion function

## Beam size

- When the beam energy spread is $\delta$


$$
\sigma^{2}=\sigma_{\beta}^{2}+\sigma_{\varepsilon}^{2}=\varepsilon \cdot \beta+D^{2} \delta^{2}
$$

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## Acceleration

Why we would like to accelerate particles?
*Reach of higher energetic collisions (ions, protons and leptons)

* Compensate for energy loss due to emission of synchrotron radiation (leptons)

$$
\vec{F}=\frac{\mathrm{d} \vec{p}}{\mathrm{~d} t}=e(\vec{E}+\vec{v} \times \vec{B})
$$

Longitudinal Motion
Parallel to the direction of motion.
Used to accelerate charged particles.

Transverse Motion Perpendicular to the direction of motion. Used to keep circulating orbit and beam steering.

Acceleration has to be done by an electric field in the direction of the motion

## Electrostatic acceleration

Simplest way to generate an electric field in the motion direction: voltage difference


Gain on kinetic energy is proportional to V (the potential)

## Curiosity:

The energy unit (electron Volt): 1 eV is the energy that 1 elementary charge e gains when it is accelerated in a voltage of 1 Volt.


Electrostatic machines are still used at lower energy, as a 1st stage of acceleration, radiotherapy, particle source, etc.

## Limitations:

Max. Voltage ~ 10MV due to insulation problems.

## Radio-frequency acceleration



Apply an E-field which is reversed while the particle travels inside the tube $\rightarrow$ it gets accelerated at each passage.

Build the acceleration with one or more series of drift tubes with gaps in between them.

Could accelerate in linear and circular machines

Only particles synchronized with RF will be accelerated $\rightarrow$ particles are bunched in packages

## LINAC: linear accelerator

## Acceleration gaps (electrical field) Drift-tubes (field free)



For non-relativistic particles $\rightarrow$ Distance (L) between the acceleration gaps needs to fulfil the synchronism condition with T the period of the RF oscillator.

Bunched Beam
$\uparrow v \Longrightarrow \uparrow L$

Energy gain:
$E=n e V_{\mathrm{RF}} \sin \phi_{\mathrm{s}}$
$n$ : number of gaps
$e$ : charge
$V_{\mathrm{RF}}$ : applied voltage
$\phi_{\mathrm{s}}$ : synchronous phase

## RF field break down

High gradient limits : field levels of 10-100 MV/m.

Electrons in surface are emitted (field emission), vacuum arcs may form and the field breaks down. Eventually the break down processes may damage the structure.



Figure 4.3.: Power flows around a field emitter tip in an RF cavity.

## From LINAC to Circular Machines

LINACs are today the first stage in many accelerator complexes

Limited by the particle energy reach due to length and single pass


## Circular Accelerators

Use of circular structures in order to apply over and over the accelerating fields. Particles are bend onto circular trajectories $\rightarrow$ Many passages through RF structure

## The Synchrotron: acceleration

The synchrotron is a synchronous accelerator since there is a synchronous RF phase for which the energy gain fits the increase of the magnetic field at each turn. That implies the following operating conditions:


If $\mathrm{v} \approx \mathrm{c}, \omega$ hence $\omega_{\mathrm{RF}}$ remain constant (ultra-relativistic)
LHC case $\mathrm{fRF}=400 \mathrm{MHz}$ and $\mathrm{frev}=11 \mathrm{kHz}=\mathrm{c} / 27 \mathrm{Km} \mathrm{h} \sim 35640$

## Synchrotron oscillations (with acceleration)

Case with acceleration B increasing $\quad \gamma>\gamma_{t}$



- Bucket area = longitudinal Acceptance [eVs]
- Bunch area $=$ longitudinal beam emittance $=4 \pi \sigma_{E} \sigma_{\dagger}[\mathrm{eVs}]$


## Synchrotron motion in phase space

The restoring force is nonlinear.
$\Rightarrow$ speed of motion depends on position in phase-space
(here shown for a stationary bucket)


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- Hadron Accelerators: Synchrotrons
- Beam production
- Magnets
- Luminosity
- Collective effects


## Synchrotrons

- First Synchrotron the Cosmotron at Brookhaven Laboratory 19523 GeV protons (288 magnets)
- In 1947 General Electric's Research Lab observed for the first time Synchrotron radiation $\rightarrow$ electromagnetic radiation emitted by charged particles travelling at relativistic speeds, forced to take a curved path by a magnetic field ( Synchrotron light sources for spectroscopy and crystallography)

Large scale accelerators since components can be divided in different sections


## Synchrotrons

## 1959 construction of the first "larger" synchrotron machines

> CERN-PS (Proton Synchrotron): 60 year still in operation, still in use for the injection to the LHC.
> BNL-AGS (Alternating Gradient Synchrotron)


## The CERN Accelerator Complex

The CERN accelerator complex Complexe des accélérateurs du CERN


## LINAC 4

## 160 MeV (90 meter linac)



## PS Booster

$1^{\text {st }}$ Synchrotron in the chain with 4 superposed rings
Circumference of 157 m
Increases proton energy from $\mathbf{1 6 0} \mathbf{~ M e V}$ to $\mathbf{2 ~ G e V ~ i n ~} \mathbf{1 . 2 s}$

LINAC 4 pulse is distributed vertically in the 4 rings. Bunches are built as multi-turn PSB injection. Keeping charge density constant every injection in a different phase-space defining the transverse emittance.

- ISOLDE: High-Intensity 10-13 turns are injected = large transverse emittance
- LHC: 2-3 injected turns = small transverse emittance After acceleration they will be combined and transferred to the PS.


## PS: Protons Synchrotron

The oldest operating synchrotron at CERN (since 1959)
Circumference of 628 m
$4 \times$ PSB ring
Accelerates from 2 GeV to a range of energies up to 26 GeV depending on the user

- East area: 24 GeV
- SPS: 14 GeV or 26 GeV
- AD: 26 GeV
- n-TOF: 20 GeV

Cycle length goes from 1.2 s to 3.6 s


## CERN PS

Various types of extractions: fast, slow and multi-turn (MTE) Many different RF cavities: $10 \mathrm{MHz}, 13 / 20 \mathrm{MHz}, 40 \mathrm{MHz}, 80$ MHz,200 MHz

## LHC filling and Bunch Splitting in PS

Changing RF frequency we change the harmonic number $h$

$$
\omega_{R F}=h \omega
$$



Standard: 72
bunches @ 25
ns

BCMS: 48
bunches @ 25
ns

Smaller
Emittance

[^0]
## The LHC25 (ns) cycle in the PS




$\rightarrow$ Each bunch from the Booster divided by $12 \rightarrow 6 \times 3 \times 2 \times 2=72$

## Triple splitting in the PS




## Two times double splitting in the PS

Two times double splitting and bunch rotation:



- Bunch is divided twice using RF systems at
$h=21 / 42(10 / 20 \mathrm{MHz})$ and $h=42 / 84(20 / 40 \mathrm{MHz})$
- Bunch rotation: first part h84 only $+h 168(80 \mathrm{MHz})$ for final part


## SPS

The first synchrotron in the LHC chain at $\mathbf{3 0 m}$ underground.
Circumference of 6.9 km
$11 \times$ PS ring
Accelerates from 26 GeV to up 450 GeV
Store intensity up to 5 e13 protons per cycle.
> Slow extraction to North Area
> Fast extraction to LHC, AWAKE and HiRadMat



## The Synchrotron - LHC Operation Cycle

The magnetic field (dipole current) is increased during the acceleration.


SPPbarS collider 6 bunches


## Synchrotrons Colliders



Tevatron: 36 bunches

RHIC: 110 bunches


1. Superconducting magnets
2. Cleaning and protection
3. Luminosity and Interaction Regions design
4. Collective effects


## Superconducting magnets $\rightarrow$ LHC dipole field for 7 TeV protons

What is the needed dipole field to keep the protons circulating in the 27 km ring?

$$
\text { Magnetic rigidity } \rightarrow 0.3 B[\mathrm{~T}] \approx \frac{p[\mathrm{GeV} / c]}{\rho[\mathrm{m}]}
$$

The radius of the circumference cannot be just $27 \mathrm{~km} / 2 \pi$ as we need space for the detectors, RF, injection and extraction regions and collimation (so-called straight sections).
Approx. 2/3 of LHC ring are dedicated to the bending

$$
\begin{aligned}
& \rho \approx 2.8 \mathrm{~m} \approx \frac{0.65 \times 26.7 \mathrm{~km}}{2 \pi} \\
& \quad B[\mathrm{~T}] \approx \frac{7000 \mathrm{GeV} / \mathrm{c}}{0.3 \times 2.8 \mathrm{~m}}=8.33 \mathrm{~T}
\end{aligned}
$$

LHC Nominal dipole field 8.33 T

## LHC super-conducting dipoles

Previous machines use super-conducting magnets:

- Tevatron at FNAL 1987-2011: proton-antiproton collider
- HERA at Desy 1992 -2007: hadron-electron collider
- RHIC at BNL 2000 - present : relativistic heavy-ion collider

All used NbTi cooled with He at 4.2 K with a maximum B-field $\sim 5$ Tesla
LHC also uses Nb-Ti (Cu clap) used but to push the performance they are cooled to 1.9K using super-fluid He.

With the drawback that a very small energy deposition (by beam interaction in the surroundings) or the slightest microscopic movement of the conductor could create a magnet quench (loosing super-conductivity). unless the fault was detected quickly and the current turned off.


## Niobium-Titanium Rutherford cable



Total superconducting cable required 1200 tonnes which translates to around 7600 km of cable.

The cable is made up of strands which is made of filaments, total length of filaments would go 5 times to the sun and back with enough left over for a few trips to the moon.

## LHC dipole



## LHC cross-section

## LHC DIPOLE : STANDARD CROSS-SECTION

## Re-use the LEP tunnel

 constrained the size of the magnet using the two-inone design.Two beam channels in a common cold mass cryostat and magnetic flux in opposite sense.

Complex design.

Dimensions of the dipole beam screen are:

22 mm horizontal
17 mm vertical




## 1. Superconducting magnets

2. Cleaning and protection
3. Luminosity and Interaction Regions design
4. Collective effects

## Comparison of the 3 LHC Running Periods

Energy depositions at $\mathbf{6 . 5 T e V} \sim \mathbf{1 0 0} \mathbf{m J} / \mathrm{cm}^{\mathbf{3}}$ risk to initiate a quench.


A quench without damage will require $\sim 10$ hours of cool down time to recover the cryogenic conditions. With damage > 3 months.

At 6.8 TeV with about 3 e 14 proton beams, a tiny fraction of beam, $0.00002 \%$, could quench a magnet ( $\sim 6 \mathrm{e} 7$ protons)

## Beam Losses at LHC

- A tiny fraction of the full beam is enough to damage equipment
- Therefore, a very control of beam losses is mandatory to ensure safe LHC operation


## Normal Losses

They can be minimised but cannot be avoided completely
Due to beam dynamics: particle diffusion,
scattering processes, instabilities.
Due to Operational variations: orbit, tune, chromaticity changes during ramp, squeeze, collision.

Collimation system (smallest aperture) is designed to catch increased beam losses up to 500 kW over 10sec.

Beam Loss Measurements that extract the beam if exceed the specified max. loss rates.

## Abnormal losses

Due to failure or irregular behaviour of accelerator components.

## LHC Collimation System

LHC Collimation system guarantees that losses will not reach the cold region.


Like a diaphragm in a camera, collimators are the closest elements to the circulating beam concentrating the losses in the collimation regions.

## Collimator Design

Two parallel jaws in a vacuum tank at different orientations.
Jaw material depends on its functionality:

- Carbon (primary and secondary collimators)
- Copper and Tungsten (absorbers and tertiary collimators)
Movable jaws, controlling gap and jaw angle with precision of 5 microns



## LHC Collimation System

108 Movable Collimators

Momentum cleaning: particles with different momentum are absorbed in this area


## LHC Beam Loss Monitoring

Approximately 4000 Beam Loss Detectors (ionization chambers) distributed along the LHC covering critical locations:

- Losses in the cold area: dipoles, quadrupoles, etc.
- Losses at injection and extraction: transfer lines
- Losses down stream each collimator.

Losses are concentrated in warm regions



## 1. Superconducting magnets <br> 2. Cleaning and protection

## 3. Luminosity and Interaction Regions design

4. Collective effects

## Luminosity

For accelerator people this IS the quantity used to optimise the machine.
The higher the luminosity the better.

Number of particles per bunch


## LHC nominal parameters

Table 2.1: LHC beam parameters relevant for the peak luminosity

|  |  | Injection | Collision |
| :---: | :---: | :---: | :---: |
| Beam Data |  |  |  |
| Proton energy | [GeV] | 450 | 7000 |
| Relativistic gamma |  | 479.6 | 7461 |
| Number of particles per bunch |  | $1.15 \times 10^{11}$ |  |
| Number of bunches |  | 2808 |  |
| Longitudinal emittance (4 $\sigma$ ) | [ eVs ] | 1.0 | $2.5{ }^{a}$ |
| Transverse normalized emittance | [ $\mu \mathrm{m} \mathrm{rad}$ ] | $3.5{ }^{\text {b }}$ | 3.75 |
| Circulating beam current | [A] | 0.582 |  |
| Stored energy per beam | [MJ] | 23.3 | 362 |
| Peak Luminosity Related Data |  |  |  |
| RMS bunch length ${ }^{c}$ | cm | 11.24 | 7.55 |
| RMS beam size at the IP1 and IP5 ${ }^{d}$ | $\mu \mathrm{m}$ | 375.2 | 16.7 |
| RMS beam size at the IP2 and IP8 ${ }^{e}$ | $\mu \mathrm{m}$ | 279.6 | 70.9 |
| Geometric luminosity reduction factor $\mathrm{F}^{f}$ |  | - | 0.836 |
| Peak luminosity in IP1 and IP5 | $\left[\mathrm{cm}^{-2} \mathrm{sec}^{-1}\right]$ | - | $1.0 \times 10^{34}$ |
| Peak luminosity per bunch crossing in IP1 and IP5 | $\left[\mathrm{cm}^{-2} \mathrm{sec}^{-1}\right]$ | - | $3.56 \times 10^{30}$ |

## Peak luminosity



How the increase of peak luminosity was achieved?

## LHC Runs Challenges

## Energy

- Lower quench margins
- Lower tolerance to beam loss
- Hardware closer to maximum (beam dumps, power converters etc.)


## 25 ns

- Electron-cloud
- UFOs
- More long range collisions
- Larger crossing angle, higher beta*
- Higher total beam current
- Higher intensity per injection

Smaller Beta-star

- Smaller machine aperture
- Tighter collimator settings
- Higher beam losses



## Increase of beam current

## Number of bunches

Early 2015 went from 50 ns bunch spacing to 25ns.

## Example 2017

144 bunches SPS batch (max 2556b) Based on 48 PS batch x 3



## Number of protons/bunch

With past LINAC 2 ( 50 MeV max energy)
Average 1.1e11p/b in 2018
Peak~1.5e11p/b
With LINAC 4 ( 160 MeV )
Average 1.6 e11p/b in RUN III


Peak ~ 2.2e11p/b $\rightarrow$ ready for HL-LHC era

## Reduction of beam emittance

Different bunch splitting and merging in PS gives a push on beam brightness (reduction of emittance)


Higher peak luminosity at the cost of higher pile-up due to reduced number of bunches

## Beta-star

Reduction of beta-star in ATLAS/CMS over Run 2:

- 2015: 80 cm
- 2016: $\mathbf{4 0}$ cm

First time below Nominal values

- 2017: 40 cm $\boldsymbol{\rightarrow} \mathbf{3 0} \mathbf{c m}$
- 2018-2023: Dynamic squeeze in Stable Beams: $\mathbf{3 0} \mathrm{cm} \rightarrow \mathbf{2 7} \mathbf{~ c m ~} \boldsymbol{\rightarrow} \mathbf{2 5}$ cm
- 202915 cm
concept sketch: using a quadrupole doublet it is possible to focus particles in the horizontal and vertical planes simultaneously through the interaction point




## Low Beta Insertion

the most simple IR configuration

- doublet focusing
- large beta function in doublet
$\rightarrow$ aperture limitation for ring




## Low Beta Insertion - Example of LHC

LHC interaction region with Low-Beta + D.S.


## Beam Waist (e.g. interaction point collider)




$$
\begin{aligned}
& \beta(s)=\beta^{*}+\frac{s^{2}}{\beta^{*}} \\
& \sigma_{\mathrm{rms}}=\sqrt{\varepsilon \beta^{*}}, \sigma_{\mathrm{rms}}^{\prime}=\sqrt{\frac{\varepsilon}{\beta^{*}}} \quad \beta^{*}=\text { Beta function at waist }
\end{aligned}
$$

## Beam Waist (e.g. interaction point in collider)



## Crossing angle operation

$$
\mathcal{L}=\frac{N_{1} N_{2} f n_{b}}{4 \pi \sigma_{x} \sigma_{y}}
$$

Multi Bunch operations brings un-wanted interactions left and right of the 4 Experiments


A finite crossing angle has to be applied to avoid multiple collision points

## Luminosity Geometric reduction factor

Due to the crossing angle the overlap integral between the two colliding bunches is reduced!

$$
\mathcal{L}=\frac{N_{1} N_{2} f n_{b}}{4 \pi \sigma_{x} \sigma_{y}} \cdot \mathcal{S}
$$

## $S$ is the geometric reduction factor

Always valid for LHC and HL-LHC
$\sigma_{s} \gg \sigma_{x, y}$
$\sigma_{\mathrm{x}}=17-7 \mu \mathrm{~m}, \sigma_{\mathrm{s}}=7.5 \mathrm{~cm}$


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## S is the geometric reduction factor

$\sigma_{s} \gg \sigma_{x, y}$
Always valid for LHC and HL-LHC $\sigma_{\mathrm{x}}=17-7 \mu \mathrm{~m}, \sigma_{\mathrm{s}}=7.5 \mathrm{~cm}$



LHC design: $\phi=285 \mu \mathrm{rad}, \sigma_{\mathrm{x}}=17 \mu \mathrm{~m}, \sigma_{\mathrm{s}}=7.5 \mathrm{~cm}, \mathrm{~S}=0.84$
LHC 2018: $\phi=320 \mu \mathrm{rad}, \sigma_{\mathrm{x}}=9.3 \mu \mathrm{~m}, \sigma_{\mathrm{s}}=7.5 \mathrm{~cm}, \mathrm{~S}=0.61$

## Luminosity Levelling at LHC


a) Crossing angle levelling

Modification of large local orbit bump
b) Separation Levelling

Adding a small transverse offset (local orbit bump) to the beams.
It is the simplest way of implementing the levelling
c) Beta* levelling

Requires modification of the beta function at IP
Complex but very effective also in reducing beam-beam long range effects

## Collective effects:

## But ... these particles are electrically charged, and hence are sources of additional EM fields themselves.

- They 'speak' to each other via these EM fields.
- They are not independent, but influence each other motion



## Contents:

- Particle types and relativity for accelerators
- Accelerator components: Dipole, quadrupoles magnets, accelerating RF cavities...
- Transverse plane ( $\mathrm{x}, \mathrm{y}$ ) $\rightarrow$ Guiding and focusing beams
- Particle motion in linear approximation
- Invariant of motion and Emittance
- Beam Optics: beta functions, beams sizes, Beam Tunes
- Longitudinal plane (s,t) $\rightarrow$ Acceleration
- Synchronous motion
- Synchrotrons and LHC injection complex
- Hadron Accelerators: Synchrotrons
- Beam production
- Magnets
- Luminosity
- Collective effects

Future Accelerators

## The near and far future accelerators:



## HEP Landscape - Colliders

HL-LHC (CERN)
Installation 2026
Commissioning 2029


In construction
CD4 June 2030

## HL-LHC

The main goal is to increase luminosity by a factor of 5 to 10 in order to observe rare physics processes.
$250 \mathbf{~ f b}^{-1}$ per year $\leftarrow 2 \times$ LHC 4 years of Run II 3000 fb $^{-1}$ in 12 years

This will be accomplished with a series of upgrades

Injectors Upgrade (LIU)

Higher brightness beams
More intensity less emittance

LHC Upgrade

Increase of luminosity

HL-LHC established as project in summer 2010
Described in HL-LHC book and the HL-LHC design report

HI-LHC Upgrade

- LHC Upgrade of IR ATLAS/CMS inner triplets (quadrupoles)
- Upgrade of Collimation System
- Crab cavities for beam rotation
- 11 Tesla magnet + connection cryostat
- Cold powering
- Machine protection


## IR ATLAS/CMS

## HL-LHC baseline smaller beta-star 15 cm

Replace 1.2 km of the 27 km LHC ring

Super conductive large aperture triplet quadrupoles with use of novel Nb3Sn magnet technology


Triplet [G. Ambrosio, P. Ferracin et al.]

Super conductive separation/recombination dipoles D2 with $B$ field same direction.


D2 [P. Fabbricatore, S. Farinon, et al.]

## HL-LHC Collimators

Study of more robust materials for collimation and reduce impedance.

## During LS2

Replacement of existing primary collimators and 8 secondary collimators with higher-electrically-conductive material MoGr.
Addition of 4 collimators in the dispersion suppression region
$\rightarrow$ shorter magnets 11T Dipole 11-m ( $\mathrm{Nb}_{3} \mathrm{Sn}$ technology)

Impact of 288
proton bunches on copper-allow (left) and MoGr (right)


## HL-LHC Crab-cavities



Crab cavities will reduce the effect of the geometrical factor on the luminosity

## HL-LHC timeline

HL-LHC


## HL-LHC parameter table

| Parameters | Nominal LHC (Design report'. | LHC 2018 max value - | HL-LHC <br> (standard) | $\begin{aligned} & \mathrm{HL}-\mathrm{LHC} \\ & 8 \mathrm{~b}+4 \mathrm{e}^{12} \end{aligned}$ | $\begin{gathered} \text { HL-LHC } \\ \text { (Ultimat } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Beam energy in collision [ TeV ] | 7 | 6.5 | 7 | 7 | 7 |
| $\mathrm{N}_{\mathrm{b}}$ | $1.15 \mathrm{E}+11$ | $1.15 \mathrm{E}+11$ | $2.2 \mathrm{E}+11$ | $2.2 \mathrm{E}+11$ | $2.2 \mathrm{E}+11$ |
| $\mathrm{n}_{\mathrm{b}}$ | 2808 | 2556 | 2760 | 1972 | 2760 |
| Number of collisions in IP1 and IP5 ${ }^{1}$ | 2808 | $\underline{2544}$ | $\underline{2748}$ | 1967 | $\underline{2748}$ |
| $\mathrm{N}_{\text {tot }}$ | $3.2 \mathrm{E}+14$ | $2.9 \mathrm{E}+14$ | $6.1 \mathrm{E}+14$ | $4.3 \mathrm{E}+14$ | $6.1 \mathrm{E}+14$ |
| beam current [A] | 0.58 | 0.52 | 1.1 | 0.79 | 1.1 |
| $x$-ing angle [ $\mu \mathrm{rad}$ ] | 285 | $320=->260$ | 500 | $470{ }^{10}$ | 500 |
| beam separation $[\sigma]^{11}$ | 9.4 | $10.3==>6.8$ | 10.5 | $10.5^{10}$ | 10.5 |
| $\beta^{*}$ [m] | 0.55 | $0.30==>0.25$ | 0.15 | 0.15 | 0.15 |
| $\varepsilon_{\mathrm{n}}[\mu \mathrm{m}]$ | 3.75 | $2=$ => 2.5 | 2.50 | 2.20 | 2.50 |
| r.m.s. bunch length [ m ] | $7.55 \mathrm{E}-02$ | $8.25 \mathrm{E}-02$ | $7.61 \mathrm{E}-02$ | 7.61E-02 | $7.61 \mathrm{E}-02$ |
| Total loss factor RO without crab-cavity |  |  | 0.342 | 0.342 | 0.342 |
| Total loss factor R1 with crab-cavity ${ }^{13}$ |  |  | 0.716 | 0.749 | 0.716 |
| Virtual Luminosity with crab-cavity: Lpeak*R1/RO $\left[\mathrm{cm}^{-2} \mathrm{~s}^{-1}\right]^{13}$ |  |  | $1.70 \mathrm{E}+35$ | $1.44 \mathrm{E}+35$ | $1.70 \mathrm{E}+35$ |
| Luminosity $\left[\mathrm{cm}^{-2} \mathrm{~s}^{-1}\right.$ ] or Leveling luminosity for HL-LHC | $1.00 \mathrm{E}+34$ | $2.00 \mathrm{E}+34$ | $5.0 \mathrm{E}+34^{5}$ | $3.82 \mathrm{E}+34$ | $7.5 \mathrm{E}+34^{5}$ |
| Events / crossing (with leveling and crab-cavities for HL-LHC) ${ }^{8}$ | 27 | 55 | 131 | 140 | 197 |
| Peak line density of events [event/mm] (max over stable beams) | 0.21 | 0.38 | 1.3 | 1.3 | 1.9 |
| Leveling time [h] (assuming no emittance growth) ${ }^{8,13}$ | - |  | 7.2 | 7.2 | 3.5 |

## Proj. leader L. Rossi talk 8th annual collaboration meeting October 2018

## Future Circular Collider (FCC)



FCC-Condeptual Design Reports

Study of a hadron collider with a centre-of-mass energy of the order of 100 TeV in a new tunnel of $\mathbf{8 0 - 1 0 0} \mathbf{~ k m}$ circumference

Start as $e+e$ - collider FCC-ee $\rightarrow$ Higgs Factory Ecom of 90-365 GeV
Luminosity ~ $17 \times 10^{34} \mathrm{~cm}-2 \mathrm{~s}-1$
Beta-star $\sim 1$ mm
Second stage pp collider FCC-hh $\rightarrow$ Energy frontier Ecom of 50-100 TeV $16 \mathrm{~T} \Rightarrow 100 \mathrm{TeV}$ pp in 100 km Luminosity ~ $3 \times 10^{34} \mathrm{~cm}-2 \mathrm{~s}-1$


## Linear Colliders ILC/CLIC

## Two linear accelerators facing each other



Both propose a staged implementation of e+e-collider

$$
\begin{array}{rc}
\text { Ecom }=0.25-1 \mathrm{TeV} & \text { Ecom }=0.5 \mathrm{TeV}-3 \mathrm{TeV} \\
\text { Luminosity } 1.35 \times 10^{34} \mathrm{~cm}^{-2} \mathrm{~s}^{-1} & \text { Luminosity } 1.3-5.9 \times 10^{34} \mathrm{~cm}^{-2} \mathrm{~s}^{-1} \\
& \text { More about ILC: https://ilchome.web.cern.ch } \\
& \text { More about CLIC: } \underline{\text { https://clic.cern }}
\end{array}
$$

## Muon Collider Study




20 T, 150 mm, 100 kW

30... $50 \mathrm{~T}, 50 \mathrm{~mm}$


## Appendix: Magnetic Rigidity (proton)

Lorentz force $\quad \vec{F}_{B}=e \cdot \vec{v} \times \vec{B}$
$B, v$ perpendicular $\quad F_{B}=e v B$
centrifugal force $\quad F_{c}=-m \frac{v^{2}}{\rho}$

$$
\begin{aligned}
F_{B}+F_{c}=0 \longrightarrow e v B & =m \frac{v^{2}}{\rho} \\
B \rho & =\frac{m v}{e}
\end{aligned}
$$


$B=$ magnetic field
$\rho=$ local bending radius
$p=$ momentum
$e=$ elementary charge

## Appendix: Magnetic Rigidity in Practical Units

$$
\begin{aligned}
B \rho & =\frac{p}{e}=\frac{m v}{e}=\beta \gamma \frac{m_{0} c}{e} \\
& =\beta \gamma \frac{m_{0} c^{2}}{c e} \\
& =\beta \frac{E_{\mathrm{tot}}}{c e} \\
& =\beta \frac{10^{9}}{c} E_{\mathrm{tot}}[\mathrm{GeV}] \\
& \downarrow
\end{aligned}
$$

$B=$ magnetic field
$\rho=$ local bending radius
$p$ = momentum
$e=$ elementary charge
$E_{k}=$ kinetic energy
total energy:
$E_{\mathrm{tot}}=E_{k}+m_{0} c^{2}$
approximations:

$$
\begin{aligned}
& B \rho[\mathrm{Tm}] \approx 3.3356 \cdot E_{k}[\mathrm{GeV} / \mathrm{c}] \\
& B \rho[\mathrm{Tm}]=3.3356 \cdot p[\mathrm{GeV} / \mathrm{c}]
\end{aligned}
$$

for $E_{k} \gg m_{0} c^{2}$
see also Wiedemann, p.101, eq.5.6

## Appendix, Derivation: Equation of Motion I

$$
\begin{aligned}
& \text { starting with general } \\
& \text { equation of motion: }
\end{aligned} \quad \frac{d \vec{p}}{d t}=\gamma m_{0} \ddot{\vec{R}}=\vec{F}
$$



$$
\vec{R}=r \boldsymbol{e}_{x}+y \boldsymbol{e}_{y}, r \equiv \rho+x
$$

$\dot{\vec{R}}=\dot{r} \boldsymbol{e}_{x}+r \dot{\boldsymbol{e}}_{x}+\dot{y} \boldsymbol{e}_{y}$
$\dot{\vec{R}}=\dot{r} \boldsymbol{e}_{x}+r \dot{\theta} \boldsymbol{e}_{s}+\dot{y} \boldsymbol{e}_{y}$
$\ddot{\vec{R}}=\ddot{r} \boldsymbol{e}_{x}+(2 \dot{\boldsymbol{r}} \dot{\theta}+r \ddot{\theta}) \boldsymbol{e}_{s}+r \dot{\theta} \dot{\boldsymbol{e}}_{s}+\ddot{y} \boldsymbol{e}_{y}$
$\ddot{\vec{R}}=\left(\ddot{r}-r \dot{\theta}^{2}\right) \boldsymbol{e}_{x}+(2 \dot{r} \dot{\theta}+r \ddot{\theta}) \boldsymbol{e}_{s}+\ddot{y} \boldsymbol{e}_{y}$
used here: $\quad \dot{\boldsymbol{e}}_{x}=\dot{\theta} \boldsymbol{e}_{s}, \dot{\boldsymbol{e}}_{s}=-\dot{\theta} \boldsymbol{e}_{x}$
comment: the main purpose here is to correctly treat the effect of the curved coordinate system, i.e. the moving unit vectors $e_{x}, e_{s}$

## Derivation: Equation of Motion II

right side of equation, the force:

$$
\begin{aligned}
& \vec{F}=e \vec{v} \times \vec{B} \\
& \vec{v} \times \vec{B}=\left|\begin{array}{ccc}
\boldsymbol{e}_{x} & \boldsymbol{e}_{y} & \boldsymbol{e}_{s} \\
v_{x} & v_{y} & v_{s} \\
B_{x} & B_{y} & 0
\end{array}\right| \\
&=-v_{s} B_{y} \boldsymbol{e}_{x}+v_{s} B_{x} \boldsymbol{e}_{y}+\left(v_{x} B_{y}-v_{y} B_{x}\right) \boldsymbol{e}_{s} \\
& \begin{array}{l}
\text { assumptions: } \\
\bullet \\
\bullet B_{x}(y=0)=0
\end{array} \\
& g \equiv \frac{\partial B_{y}}{\partial x}=\frac{\partial B_{x}}{\partial y}
\end{aligned}
$$

result: two equations hor/vert from $x, y$ components:

$$
\begin{aligned}
\gamma m_{0}\left(\ddot{r}-r \dot{\theta}^{2}\right) & =-e v_{s}\left(B_{0}+g x\right) \\
\gamma m_{0} \ddot{y} & =e v_{s} g y
\end{aligned}
$$

in literature $g$ has varying sign conventions Wiedemann, Table 6.2: $\quad g=+d B_{\gamma} / d x$ Schmüser/Hillert: $\mathrm{g}=-\mathrm{dB}_{\mathrm{y}} / \mathrm{dx}$

## Derivation: Equation of Motion III

introduce path length $s$ as independent variable:

$$
\begin{aligned}
\gamma m_{0}\left(\ddot{r}-r \dot{\theta}^{2}\right) & =-e v_{s}\left(B_{0}+g x\right) \\
\gamma m_{0} \ddot{y} & =e v_{s} g y
\end{aligned}
$$

$$
\begin{aligned}
x^{\prime \prime} & =\frac{1}{r}-\frac{e}{\gamma m_{0} v}\left(B_{0}+g x\right) \\
y^{\prime \prime} & =\frac{e}{\gamma m_{0} v} g y
\end{aligned}
$$

use:

$$
\begin{aligned}
& v_{s}=r \dot{\theta} \approx v \\
& \ddot{r}=\ddot{x} \\
& \ddot{x}=v^{2} x^{\prime \prime}, x^{\prime \prime} \equiv \frac{\partial^{2} x}{\partial s^{2}} \\
& \ddot{y}=v^{2} y^{\prime \prime}, y^{\prime \prime} \equiv \frac{\partial^{2} y}{\partial s^{2}}
\end{aligned}
$$

## Derivation: Equation of Motion IV

$$
\begin{aligned}
& \text { use: } \\
& x^{\prime \prime}=\frac{1}{r}-\frac{e}{\gamma m_{0} v}\left(B_{0}+g x\right) \\
& y^{\prime \prime}=\frac{e}{\gamma m_{0} v} g y \\
& x^{\prime \prime}=\frac{1}{\rho}\left(1-\frac{x}{\rho}\right)-k x-\frac{1}{\rho\left(1+\frac{\Delta p}{p_{0}}\right)} \\
& =-\left(\frac{1}{\rho^{2}}+k\right) x+\frac{1}{\rho} \frac{\Delta p}{p_{0}} \\
& y^{\prime \prime}=k y \\
& \text { use: } \\
& \frac{1}{r}=\frac{1}{\rho+x} \approx \frac{1}{\rho}\left(1-\frac{x}{\rho}\right) \\
& \frac{e B_{0}}{\gamma m_{0} v}=\frac{e B_{0}}{p}=\frac{1}{\rho} \\
& p=p_{0}\left(1+\frac{\Delta p}{p_{0}}\right) \\
& k=\frac{e g}{\gamma m_{0} v}
\end{aligned}
$$

## The Cyclotron as seen by the inventor



## as seen by the LBL booklet 1967

ELECTBOMAGNET


## as seen by the theoretical physicist



## by the electrical engineer



## as seen by the visitor



## by the government funding agency



## as seen by the laboratory director



## by the experimental physicist



## The cyclotron as seen by the student




[^0]:    Image credit R.Garoby

