Introduction

PostDoc at Hamburg University (UHH) working with CMS

Physics projects and interests

- Observation of $t\bar{t}H$ production and $H \rightarrow bb$ decays (PhD @ RWTH)
- Search for $HH \rightarrow b\bar{b}\tau^+\tau^-$ production, HH combination (research fellow @ CERN)
- HH + H combination in CMS, HH combination CMS + ATLAS (PostDoc @ UHH)
- HH BSM interpretations, BSM, heavy resonances, DM, 2HDM (ongoing)
- Differentiable limit extraction & assumption-free ML optimization (ongoing)

CMS projects and roles

- 2020-2023: CMS ML group, coordinator for production deployment
 - Integration of TensorFlow into core software \triangleright
 - Ahead-of-time compilation of ML graphs \triangleright
 - Automated performance measurement (time & memory) of models \triangleright
- Since 2023: CMS CAT (Common Analysis Tools), coordinator for workflow orchestration & preservation
 - Definition of common meta data format for all CMS analyses \triangleright
 - Development of tools & support for automating analyses end-to-end \triangleright
 - Automation of NanoAOD production for users \triangleright

PyHEP.dev 2023 Marcel Rieger





riga

marcel.rieger@cern.ch



Personal projects (1)

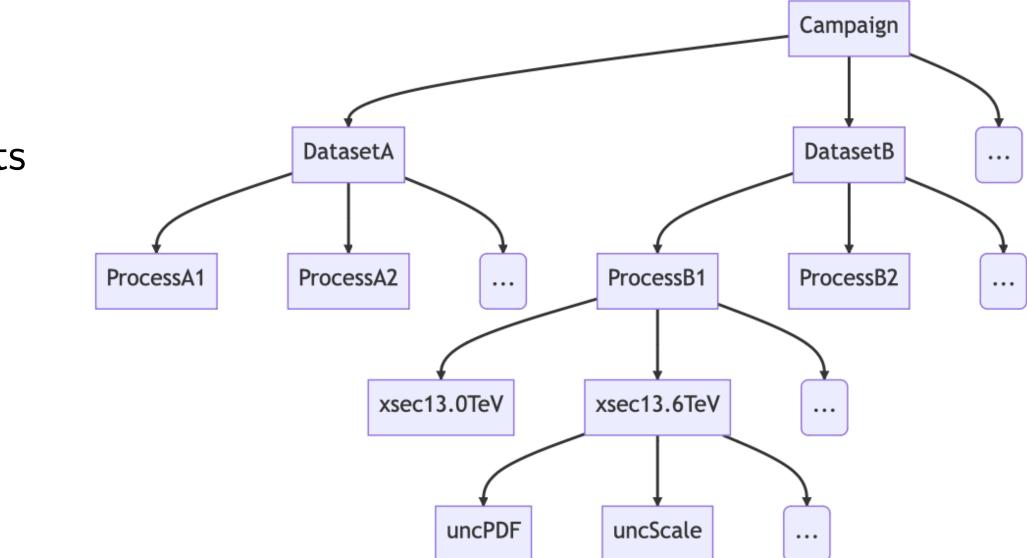
• SCINUM () CO Open in Colab

- Python package for defining numbers, subject to one or multiple uncertainties (single file, no dependencies, all Python versions)
- Automatic gaussian error propagation (\approx eager autograd)
- Support for arrays, rounding according to PDG rules, neat formatting, export to HEPData format, ...



CO Open in Colab Order

- Pythonic class collection to structure meta data for LHC experiments
- Relational structure covering
 - Production campaigns, datasets \triangleright
 - Physics processes, cross sections, uncertainties \triangleright
 - Variables, categories, channels, ... \triangleright
- Seed project for CMS-wide meta data format



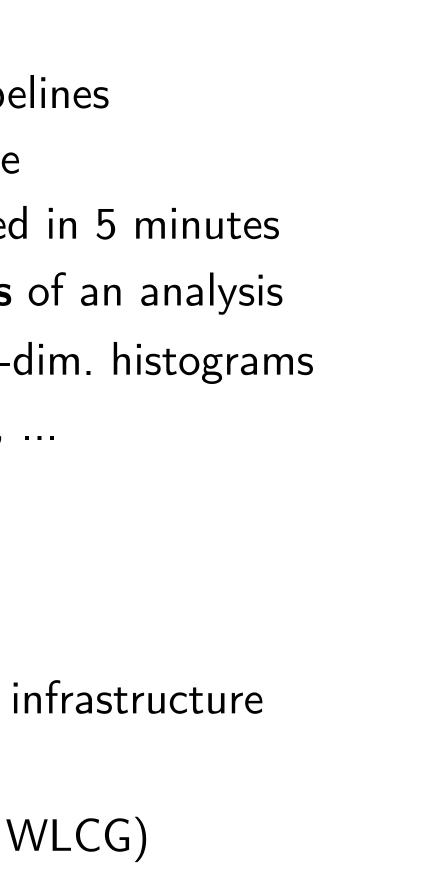


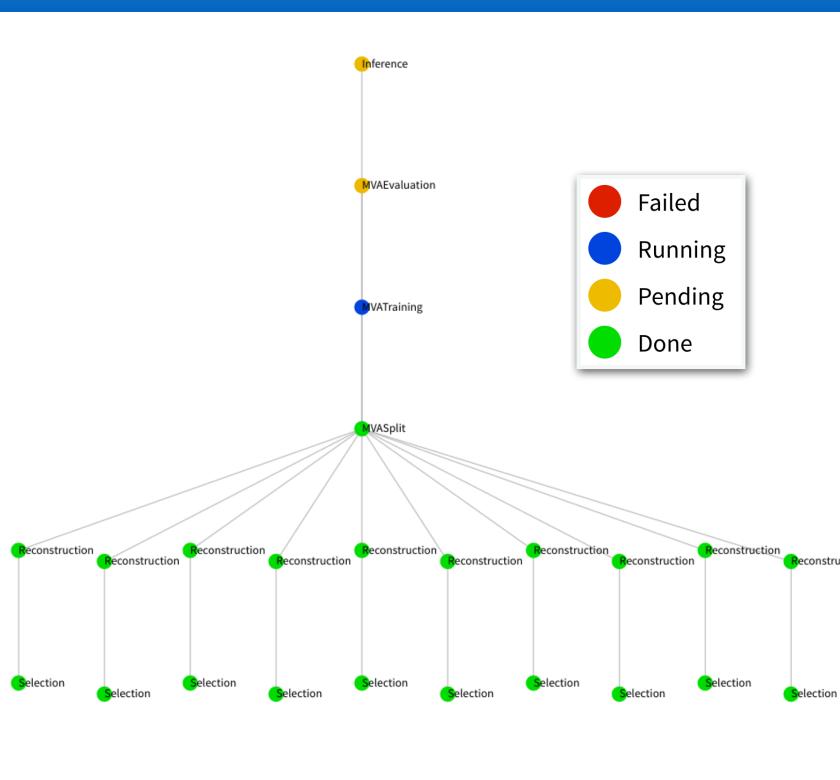
Personal projects (2) 3

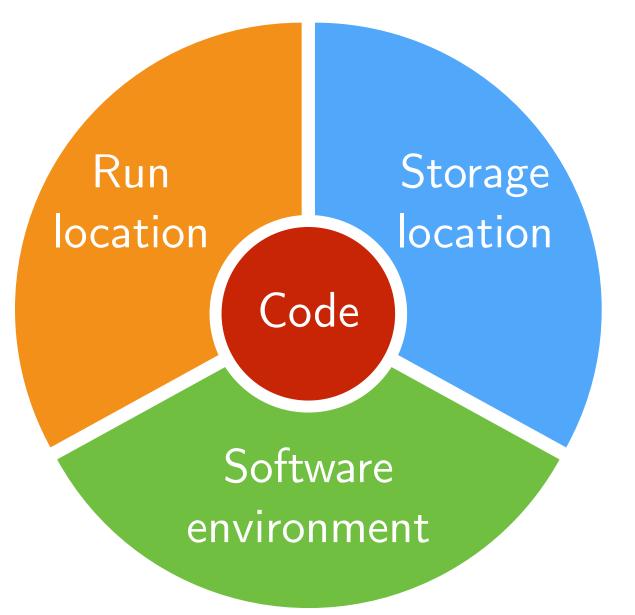
- - Python package for creating large & scalable task pipelines
 - Development started at Spotify, now fully open source
 - Extremely lightweight & flexible core, can be explained in 5 minutes
 - Enables macroscopic workflows, connecting all parts of an analysis
 - Not *just* heavy lifting from (nano) input files to n-dim. histograms \triangleright
 - No constraint on language (popen), data formats, ... \triangleright

- Extension on-top of luigi, providing scale-out of HEP infrastructure
- **Full decoupling** of
 - ▷ run locations (local, various batch systems, WLCG)
 - **storage locations** (local, all WLCG protocols, cloud) \triangleright
 - **environments** (subshells, docker/singularity, venv, conda)
- Everything executable by a **single command**
- Experiment-agnostic, O(120-150) users, most used analysis workflow system at CMS
- Provides a **daily working environment**, not just a tool to automate an analysis after the fact

PyHEP.dev 2023 Marcel Rieger

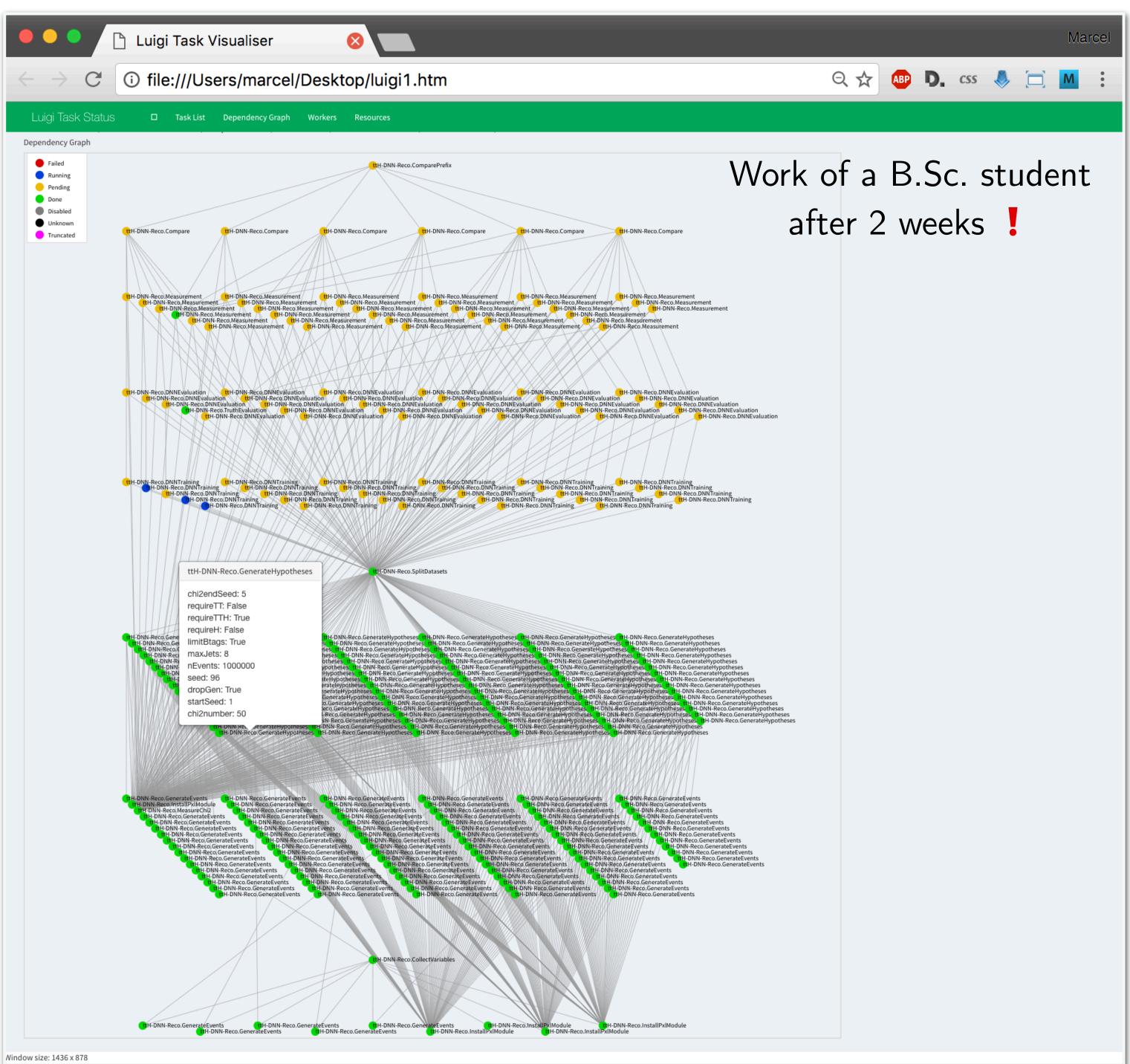








Macroscopic task graph (1) 4







Triggers: CLI, scripting and notebooks 5

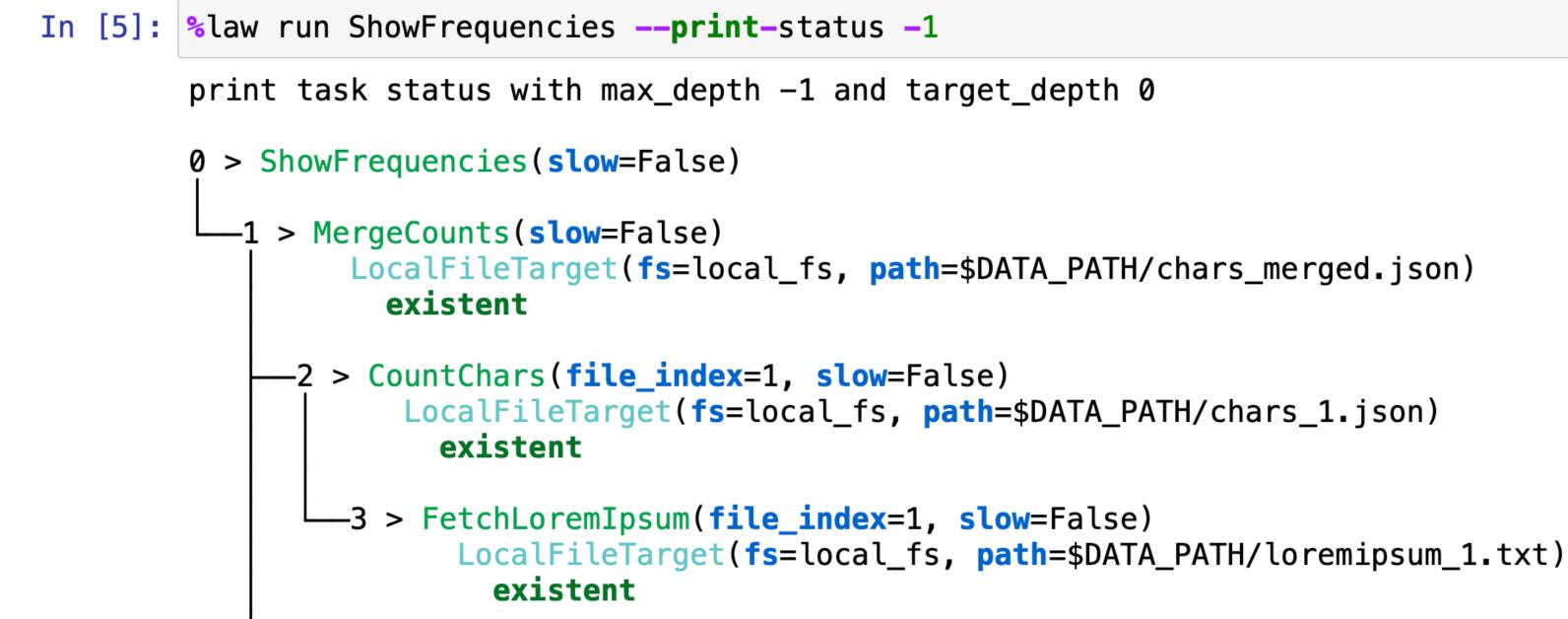
• CLI

- > law run Reconstruction --dataset ttbar --workflow htcondor
- Full auto-completion of tasks and parameters

Scripting

- Mix task completeness checks, job execution & input/output retrieval with custom scripts
- Easy interface to existing tasks for prototyping

Notebooks









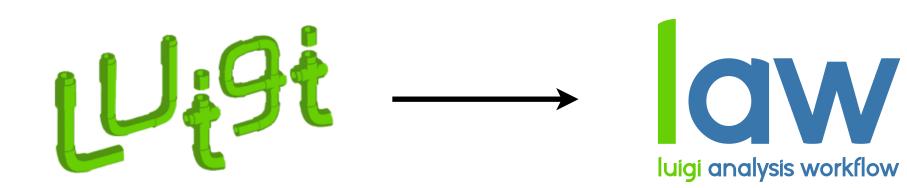
My goals for today 6

Making the Analysis Grand Challenge (AGC) even more realistic

- Machine learning training
- k-fold cross validation, creates realistic points in the analysis where per-event information is needed
- More complex statistical model
- Plotting with systematic shifts, pre-fit and post-fit
- . . .



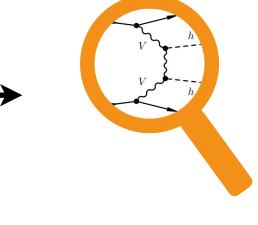




workflow engine (originally by Spotify) layer for HEP & scale-out (experiment independent)



"framework" (experiment independent*)



analysis



* soon

law & luigi



10

Development started at Spotify, now open-source and community-driven

Building blocks

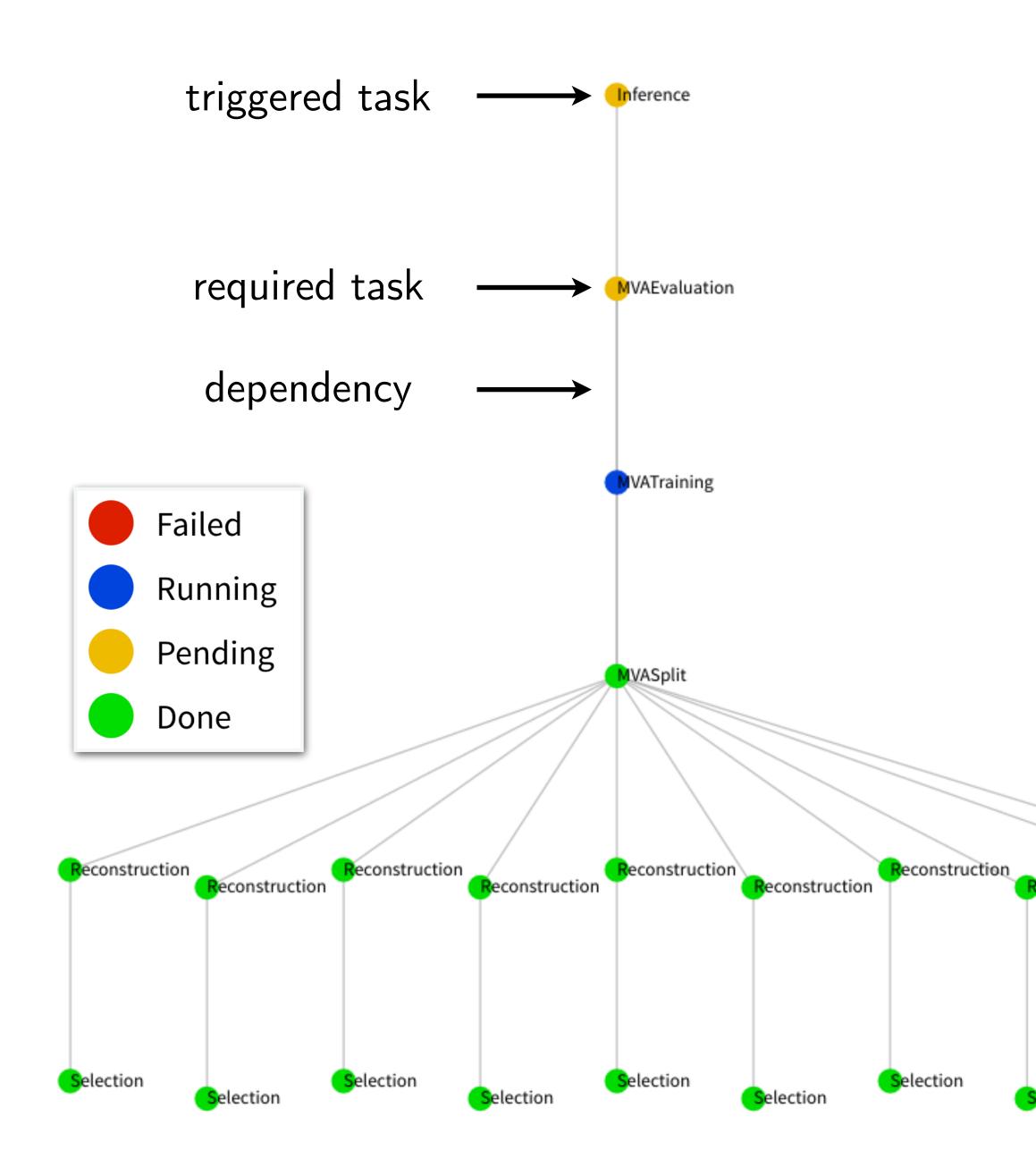
- Workloads defined as **Task** classes that 1. can **require** other **Tasks**
- Tasks produce output **Targets** 2.
- **Parameters** customize tasks & control 3. runtime behavior
- Web UI with two-way messaging (task \rightarrow UI, UI \rightarrow task), automatic error handling, task history browser, collaborative features, command line interface, ...

github.com/spotify/lu	uigi			
⊙ Watch → 493 🔶 🖈 U	Unstar 15.2k 😵	Fork 2.3k		
Luigi Task Visualiser	×			Ma
	aachen.de:8082/static/visualiser		. 🛧 💵 📭 css 🥾 🧮	Μ
Luigi Task Status 🗧 Task List	Dependency Graph Workers Res	sources		
PENDING TASKS 99	RUNNING TASKS 6	DONE TASKS 176	FAILED TASK O	S
UPSTREAM FAIL 0	DISABLED TASKS	UPSTREAM DISA O		
Displaying RUNNING , tasks .				
Show 10 💠 entries		Filter table:	Filter on Serv	
Name	Details	Priority		Actio
RUNNING ttH-bb-semi.SyncCSVs	noDeps=False, taskName=EMPTY_STRING, paramFile=EMPTY_STRING, log=-, setup=RunIISpring16MiniAODv2_13TeV_25 notify=False, printStatus=-1, sandbox=local_ttH_80X, version=test2, dCache=mriegerDESY, dataSource=tth, printDeps=-1, printStore=EMPTY_STRING, purgeOutput=-1, printLog=False	5bx_80X,	04/12/2016, 22:43:24 68 minutes	*
RUNNING ttH-DNN-Reco.DNNTraining	endSeed=100, limitBtags=True, maxJets=8 keep_prob=0.7, num_epochs=20, l2_factor shuffleSeed=123, num_layers=5, dropGen= startSeed=1, report_interval=10.0, normalize=False, testingPortion=0.5, trainingPortion=0.8, label=tth, trainSeed=1 requireTTH=True, requireH=False, batch_size=10000, nEvents=1000000,	r=0.0, =True, 123,	04/12/2016, 23:22:06 29 minutes	
	chi2endSeed=5, requireTT=False, gpu_ind num_units=500, chi2number=50 {"lx3agpu01_gpu0":1500}	ex=0,		



- Luigi's execution model is make-like
 - 1. Create dependency tree for triggered task
 - 2. Determine tasks to actually run:
 - Walk through tree (top-down)
 - For each path, stop if all output targets of a task exist*
- Only processes what is really necessary
- Scalable through simple structure
- Error handling & automatic re-scheduling

* in this case, the task is considered complete





12 Luigi in a nutshell

.

reco.py

import luigi

from my_analysis.tasks import Selection

class Reconstruction(luigi.Task):

dataset = luigi.Parameter(default="ttH")

def requires(self): return Selection(dataset=self.dataset)

def output(self): return luigi.LocalTarget(f"reco_{self.dataset}.root")

def run(self): inp = self.input() # output() of requirements outp = self.output()

. . .

> python reco.py Reconstruction --dataset ttbar

perform reco on file described by "inp" and produce "outp"

pyhep.dev 2023 Marcel Rieger



12 Luigi in a nutshell

reco.py

import luigi

from my_analysis.tasks import Selection

class Reconstruction(luigi.Task):

dataset = luigi.Parameter(default="ttH")

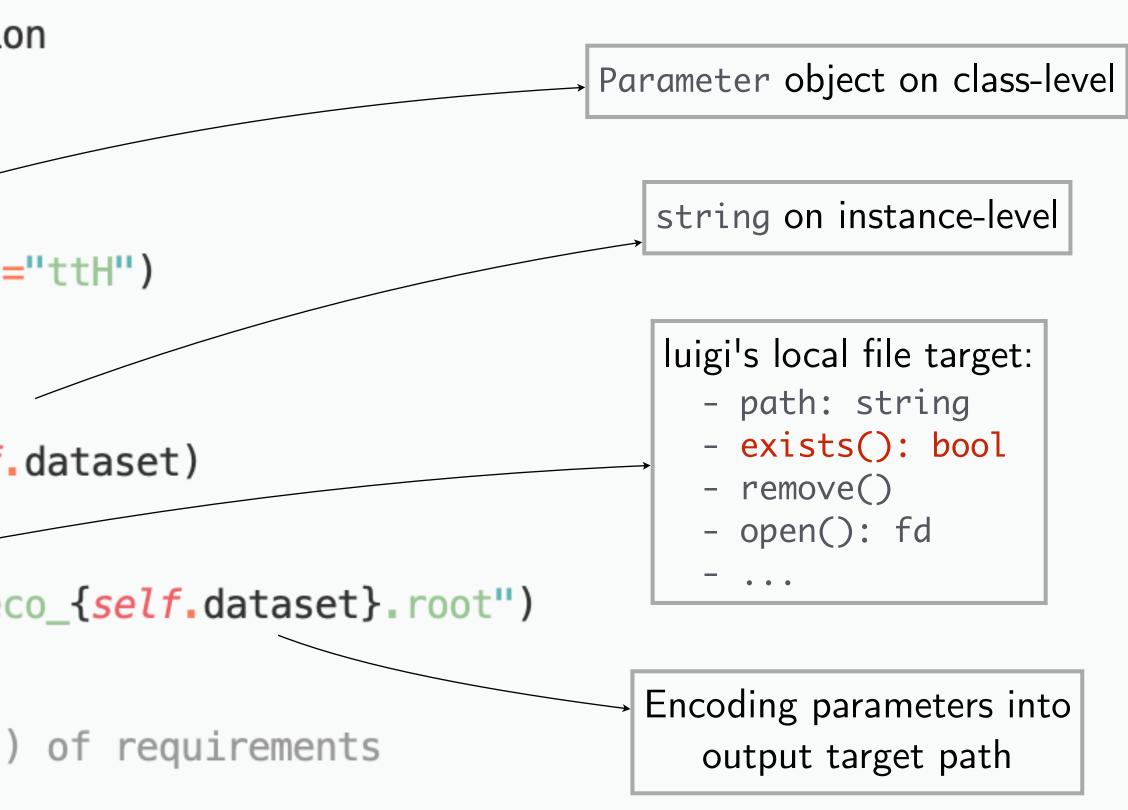
def requires(self): return Selection(dataset=self.dataset)

def output(self): return luigi.LocalTarget(f"reco_{self.dataset}.root")

def run(self): inp = self.input() # output() of requirements outp = self.output()

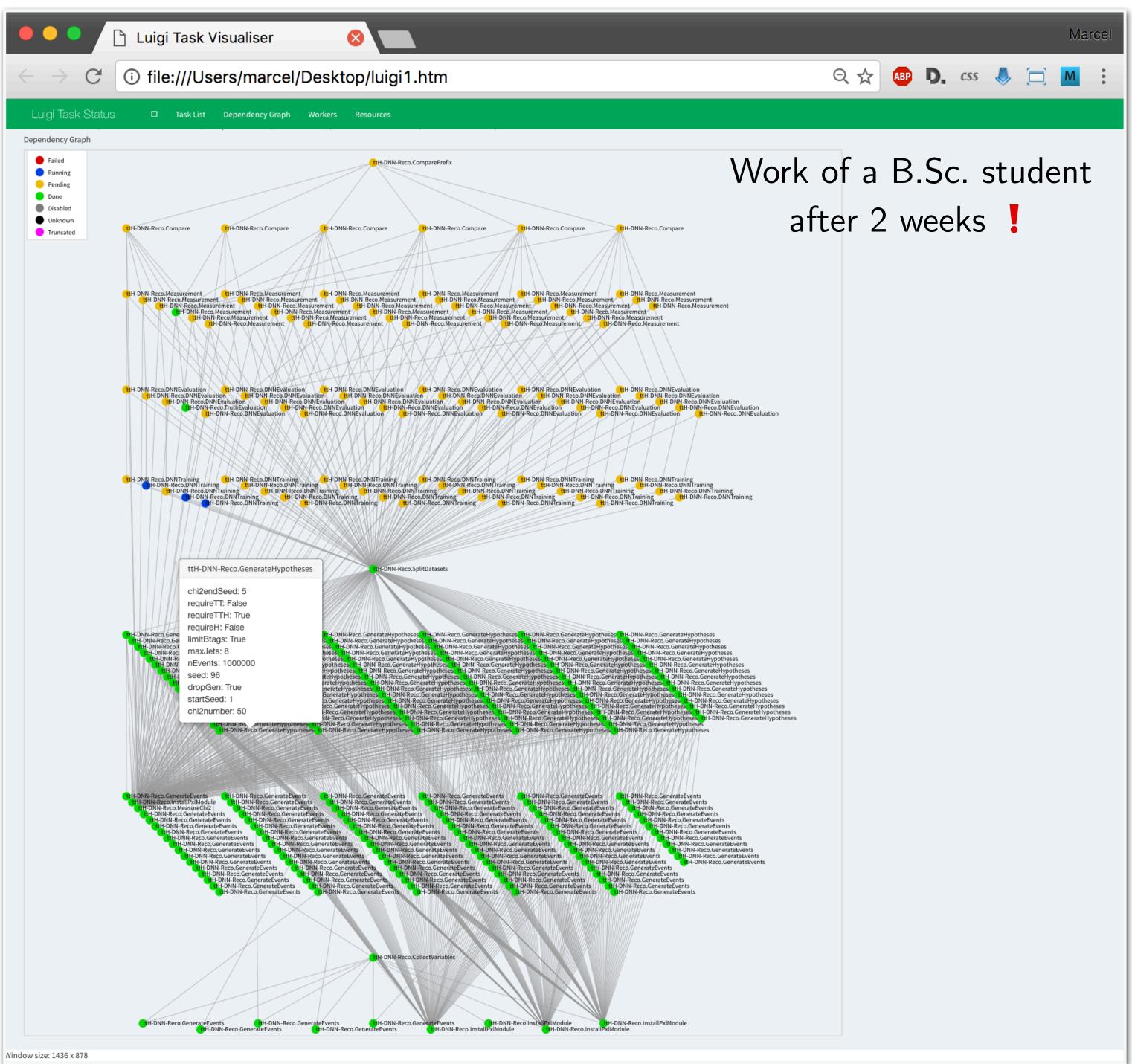
perform reco on file described by "inp" and produce "outp" . . .

> python reco.py Reconstruction --dataset ttbar





13 Example dependency trees



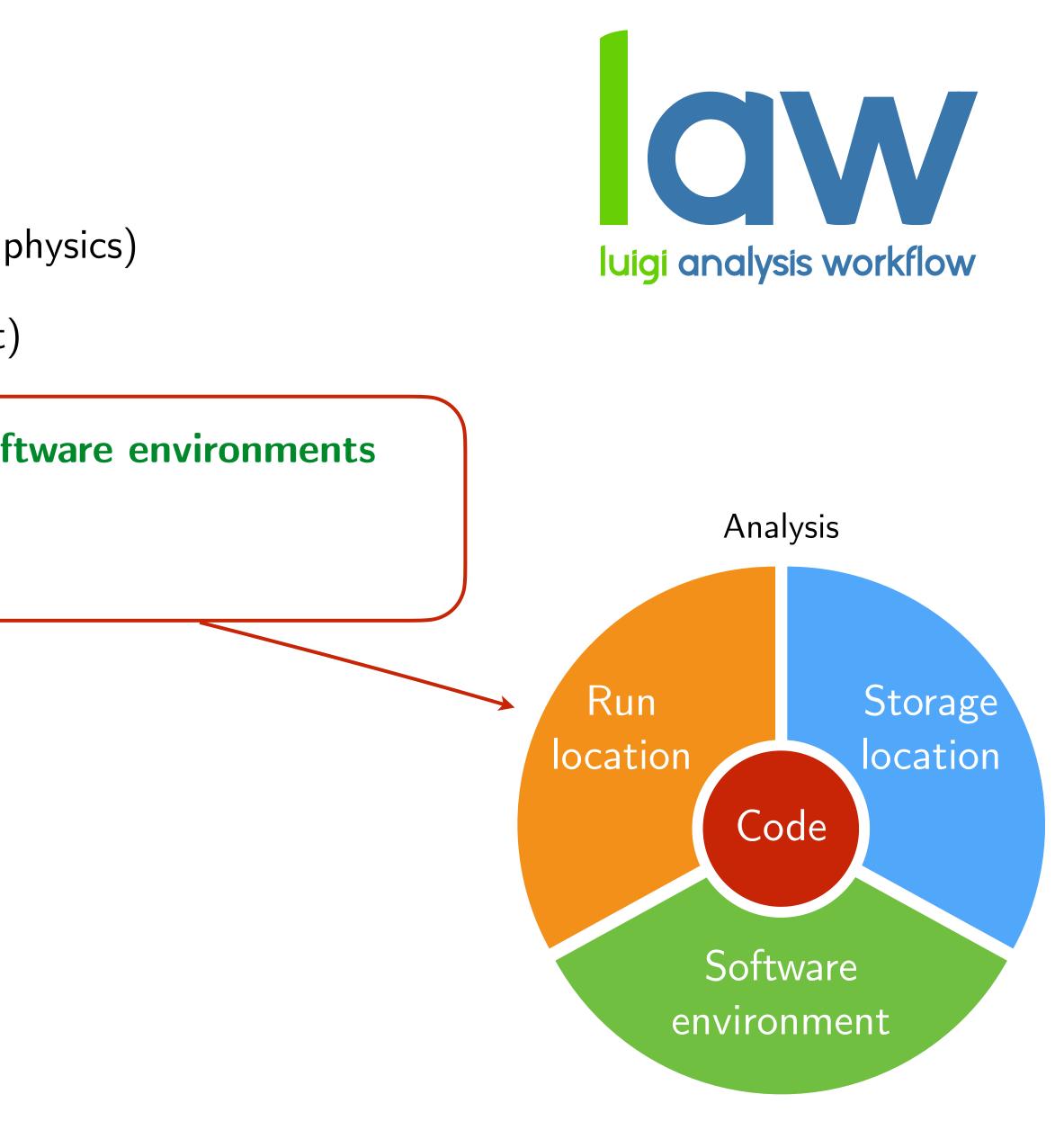
pyhep.dev 2023 Marcel Rieger



14 Law

- law: extension **on top** of *luigi* (i.e. it does not replace *luigi*)
- Software design follows 3 primary goals:
 - 1. Experiment-agnostic core (in fact, not even related to physics)
 - 2. Scalability on HEP infrastructure (but not limited to it)
 - 3. Decoupling of run locations, storage locations & software environments
 - ▷ Not constrained to specific resources
 - ▷ All components interchangeable
- Toolbox to follow an **analysis design pattern**
 - No constraint on language or data structures
 - → Not a *framework*
- Most used workflow system for analyses in CMS
 - O(20) analyses, O(60-80) people
 - Used at all german CMS sites
 - Central CMS groups, e.g. HIG, TAU, BTV

pyhep.dev 2023 Marcel Rieger





1. Job submission

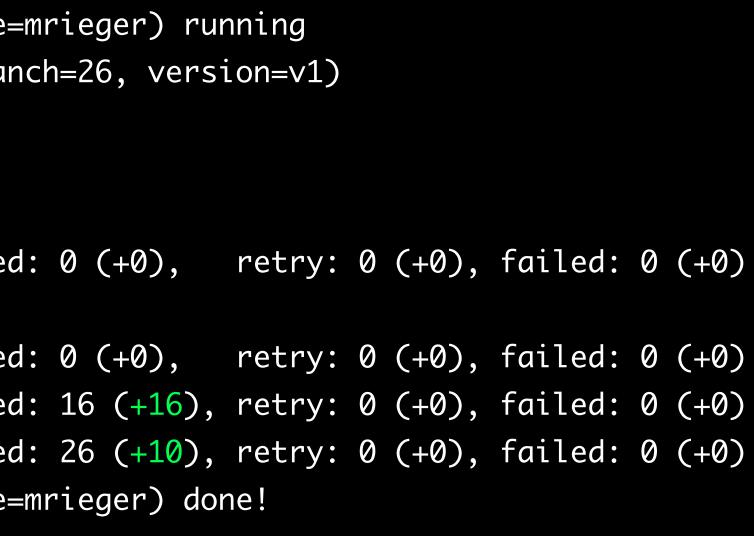


- Idea: submission built into tasks, **no need to write extra code**
- Currently supported job systems: HTCondor, LSF, gLite, ARC, Slurm (+ CRAB ~next month)
- Mandatory features such as automatic resubmission, flexible task \leftrightarrow job matching, job files fully configurable at submission time, internal job staging when queues are saturated, ...
- From the htcondor at cern example:

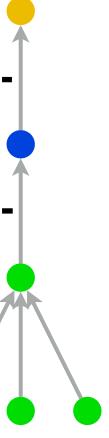
```
lxplus129:law_test > law run CreateChars --workflow htcondor
INFO: [pid 30564] Worker Worker(host=lxplus129.cern.ch, username=mrieger) running
                 CreateChars(branch=-1, start_branch=0, end_branch=26, version=v1)
going to submit 26 htcondor job(s)
submitted 1/26 job(s)
submitted 26/26 job(s)
14:35:40: all: 26, pending: 26 (+26), running: 0 (+0), finished: 0 (+0), retry: 0 (+0), failed: 0 (+0)
14:37:10: all: 26, pending: 0 (+0), running: 26 (+26), finished: 0 (+0), retry: 0 (+0), failed: 0 (+0)
14:37:40: all: 26, pending: 0 (+0), running: 10 (-16), finished: 16 (+16), retry: 0 (+0), failed: 0 (+0)
14:38:10: all: 26, pending: 0 (+0), running: 0 (+0), finished: 26 (+10), retry: 0 (+0), failed: 0 (+0)
INF0: [pid 30564] Worker Worker(host=lxplus129.cern.ch, username=mrieger) done!
```

lxplus129:law_test >





local htcondor local



2. Remote targets



- Idea: work with remote files as if they were local
- Remote targets built on top of GFAL2 Python bindings
 - ▷ Supports all WLCG protocols (XRootD, WebDAV, GridFTP, dCache, SRM, ...) + DropBox
 - API **identical** to local targets \triangleright
 - Actual remote interface **interchangeable** (GFAL2 is just a good default, fsspec integration easily possible)
- Mandatory features: automatic retries, **local caching** (backup), configurable protocols, round-robin, ...

```
"FileSystem" configuration
```

```
# law.cfg
[wlcg_fs]
base: root://eosuser.cern.ch/eos/user/m/mrieger
. . .
```



- Base path prefixed to all paths using this "fs"
- Configurable per file operation (stat, listdir, ...)
- Protected against removal of parent directories

2. Remote targets



- Idea: work with remote files as if they were local
- Remote targets built on top of GFAL2 Python bindings
 - ▷ Supports all WLCG protocols (XRootD, WebDAV, GridFTP, dCache, SRM, ...) + DropBox
 - API **identical** to local targets \triangleright
 - Actual remote interface **interchangeable** (GFAL2 is just a good default, fsspec integration easily possible)
- Mandatory features: automatic retries, local caching (backup), configurable protocols, round-robin, ...

read a remote json file with target.open("r") as f: data = json.load(f)



```
Conveniently reading remote files
```

```
target = law.WLCGFileTarget("/file.json", fs="wlcg_fs")
```

2. Remote targets



- Idea: work with remote files as if they were local
- Remote targets built on top of GFAL2 Python bindings
 - ▷ Supports all WLCG protocols (XRootD, WebDAV, GridFTP, dCache, SRM, ...) + DropBox
 - API **identical** to local targets \triangleright
 - Actual remote interface **interchangeable** (GFAL2 is just a good default, fsspec integration easily possible)
- Mandatory features: automatic retries, **local caching** (backup), configurable protocols, round-robin, ...

read a remote json file

data = target.load(formatter="json")



```
Conveniently reading remote files
```

```
target = law.WLCGFileTarget("/file.json", fs="wlcg_fs")
# use convenience methods for common operations
```

2. Remote targets



- Idea: work with remote files as if they were local
- Remote targets built on top of GFAL2 Python bindings
 - ▷ Supports all WLCG protocols (XRootD, WebDAV, GridFTP, dCache, SRM, ...) + DropBox
 - API **identical** to local targets \triangleright
 - Actual remote interface **interchangeable** (GFAL2 is just a good default, fsspec integration easily possible)
- Mandatory features: automatic retries, local caching (backup), configurable protocols, round-robin, ...

same for root files with context guard

with target.load(formatter="root") as tfile: tfile.ls()



```
Conveniently reading remote files
```

```
target = law.WLCGFileTarget("/file.root", fs="wlcg_fs")
```

2. Remote targets



- Idea: work with remote files as if they were local
- Remote targets built on top of GFAL2 Python bindings
 - Supports all WLCG protocols (XRootD, WebDAV, GridFTP, dCache, SRM, ...) + DropBox
 - API **identical** to local targets \triangleright
 - Actual remote interface **interchangeable** (GFAL2 is just a good default, fsspec integration easily possible)
- Mandatory features: automatic retries, **local caching** (backup), configurable protocols, round-robin, ...

multiple other "formatters" available

graph = target.load(formatter="tensorflow") session = tf.Session(graph=graph)



```
Conveniently reading remote files
```

```
target = law.WLCGFileTarget("/model.pb", fs="wlcg_fs")
```

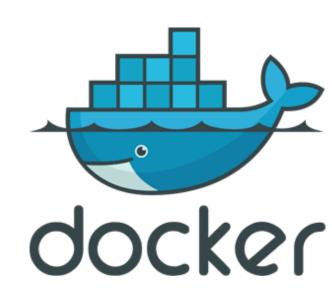
3. Environment sandboxing



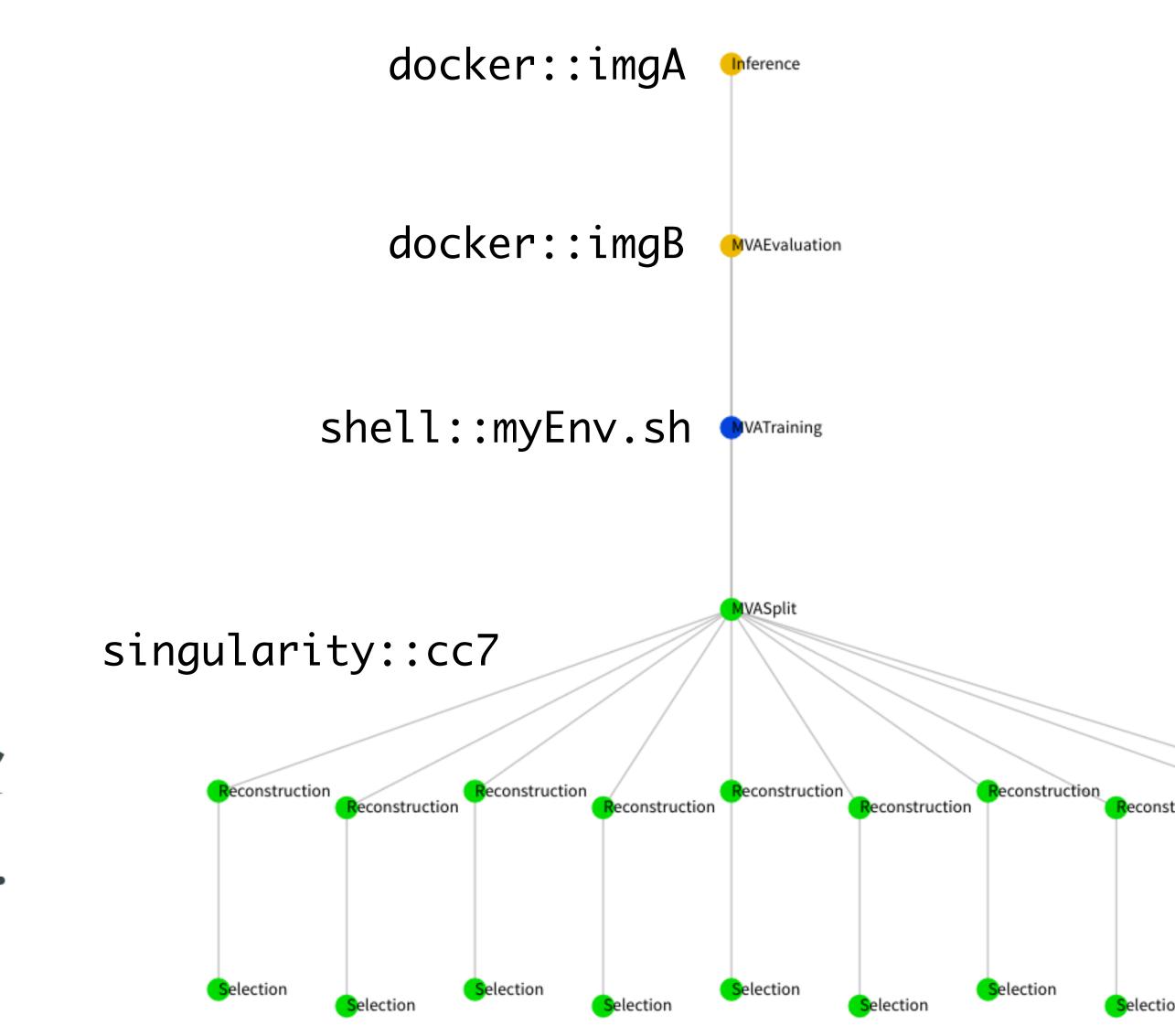
- Diverging software requirements between typical workloads is a great feature / challenge / problem
- Introduce sandboxing:
 - ▶ Run entire task in **different environment**
- Existing sandbox implementations:
 - ▷ Sub-shell with init file
 - Virtual envs \triangleright
 - Docker images \triangleright
 - ▷ Singularity images











.

reco.py

import luigi

from my_analysis.tasks import Selection

class Reconstruction(luigi.Task):

dataset = luigi.Parameter(default="ttH")

def requires(self): return Selection(dataset=self.dataset)

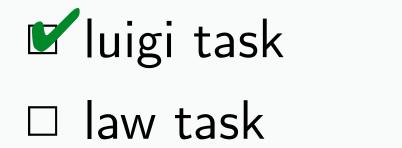
def output(self): return luigi.LocalTarget(f"reco_{self.dataset}.root")

def run(self): inp = self.input() # output() of requirements outp = self.output()

perform reco on file described by "inp" and produce "outp" . . .

> python reco.py Reconstruction --dataset ttbar

pyhep.dev 2023 Marcel Rieger



- □ Run on HTCondor
- \Box Store on EOS
- □ Run in docker









reco.py

import luigi import law from my_analysis.tasks import Selection

class Reconstruction(law_Task):

dataset = luigi.Parameter(default="ttH")

def requires(self): return Selection(dataset=self.dataset)

def output(self): return law.LocalFileTarget(f"reco_{self.dataset}.root")

def run(self): inp = self.input() # output() of requirements outp = self.output()

perform reco on file described by "inp" and produce "outp" . . .

> law run Reconstruction --dataset ttbar

pyhep.dev 2023 Marcel Rieger

✓ luigi task Value law task □ Run on HTCondor \Box Store on EOS

□ Run in docker









reco.py

import luigi import law from my_analysis.tasks import Selection

class Reconstruction(law.Task, law.HTCondorWorkflow):

dataset = luigi.Parameter(default="ttH")

def requires(self): return Selection(dataset=self.dataset)

def output(self): return law.LocalFileTarget(f"reco_{self.dataset}.root")

def run(self): inp = self.input() # output() of requirements outp = self.output()

perform reco on file described by "inp" and produce "outp" . . .

> law run Reconstruction --dataset ttbar --workflow htcondor

pyhep.dev 2023 Marcel Rieger

✓ luigi task Value law task **Run on HTCondor** \Box Store on EOS □ Run in docker









reco.py

import luigi import law from my_analysis.tasks import Selection

class Reconstruction(law.Task, law.HTCondorWorkflow):

dataset = luigi.Parameter(default="ttH")

def requires(self): return Selection(dataset=self.dataset)

def output(self): return law.WLCGFileTarget(f"reco_{self.dataset}.root")

def run(self): inp = self.input() # output() of requirements outp = self.output()

perform reco on file described by "inp" and produce "outp" . . .

> law run Reconstruction --dataset ttbar --workflow htcondor

pyhep.dev 2023 Marcel Rieger

✓ luigi task V law task Run on HTCondor Store on EOS □ Run in docker









```
# reco.py
```

import luigi import law from my_analysis.tasks import Selection

class Reconstruction(law.SandboxTask, law.HTCondorWorkflow):

dataset = luigi.Parameter(default="ttH") sandbox = "docker::cern/cc7-base"

def requires(self): return Selection(dataset=self.dataset)

def output(self): return law.WLCGFileTarget(f"reco_{self.dataset}.root")

def run(self): inp = self.input() # output() of requirements outp = self.output()

perform reco on file described by "inp" and produce "outp" . . .

> law run Reconstruction --dataset ttbar --workflow htcondor

pyhep.dev 2023 Marcel Rieger

✓ luigi task Value law task Run on HTCondor Store on EOS **Run in docker**







