

Hadron Identification at the dRICH Detector Using Deep Learning

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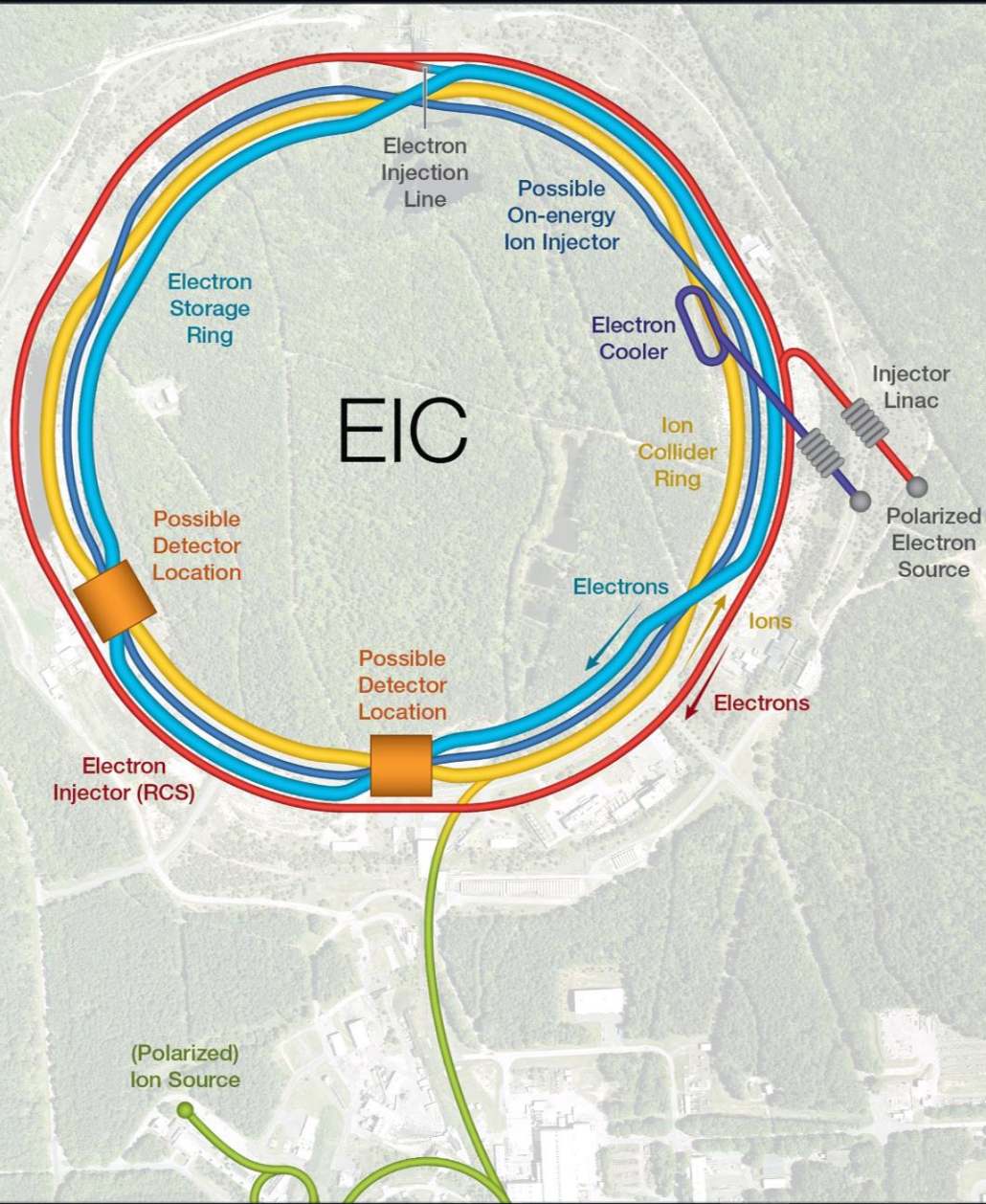
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Dr. Zhiyang Zhou (UManitoba)

27/07/2023

Outline

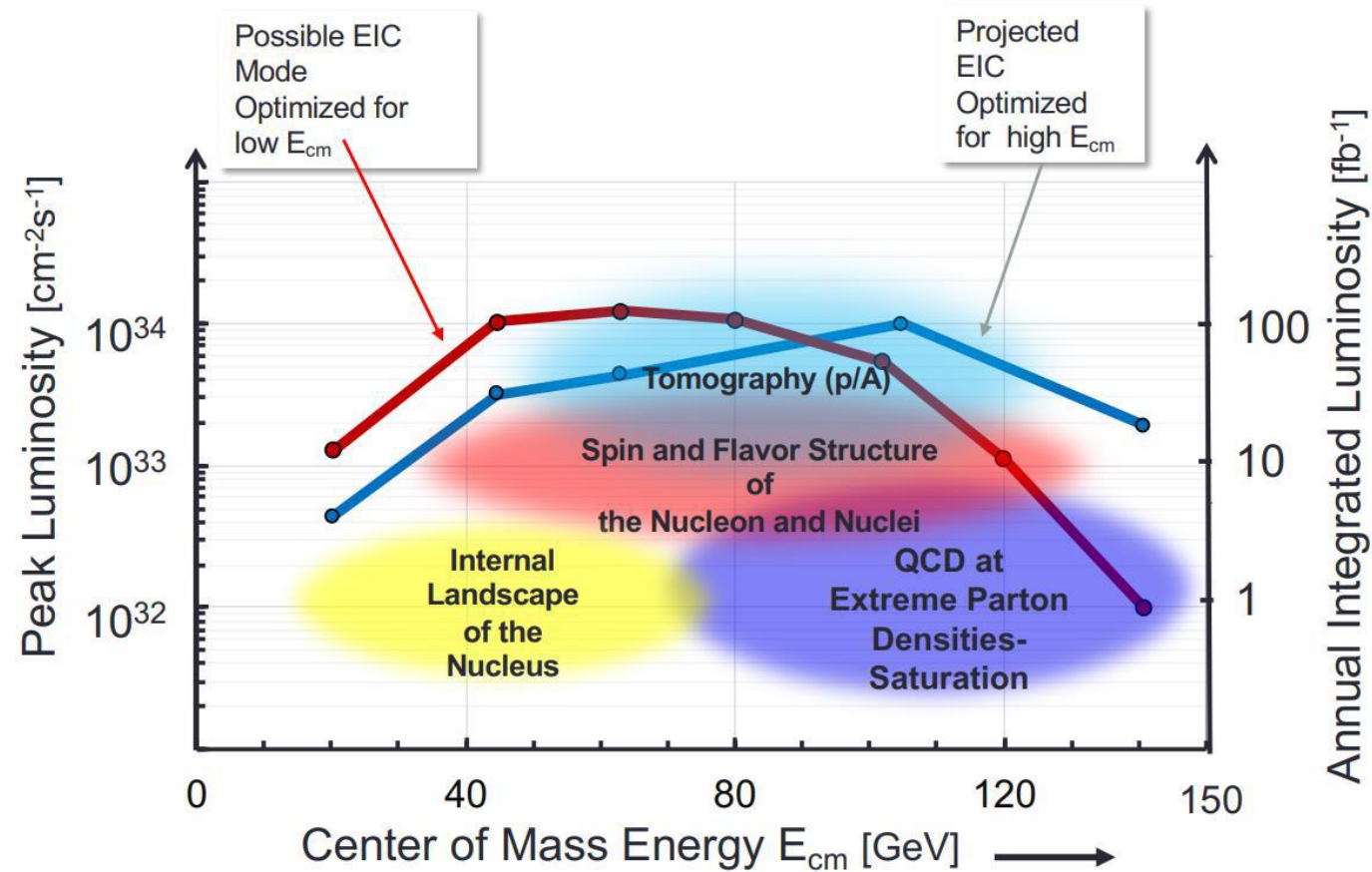
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1. Review:
 - a) Background
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 - d) Convolutional Neural Networks
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 - c) Hyperparameter Optimization
 - d) New model
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 - b) Limitations
 - c) Future work
 - d) Q&A

Background

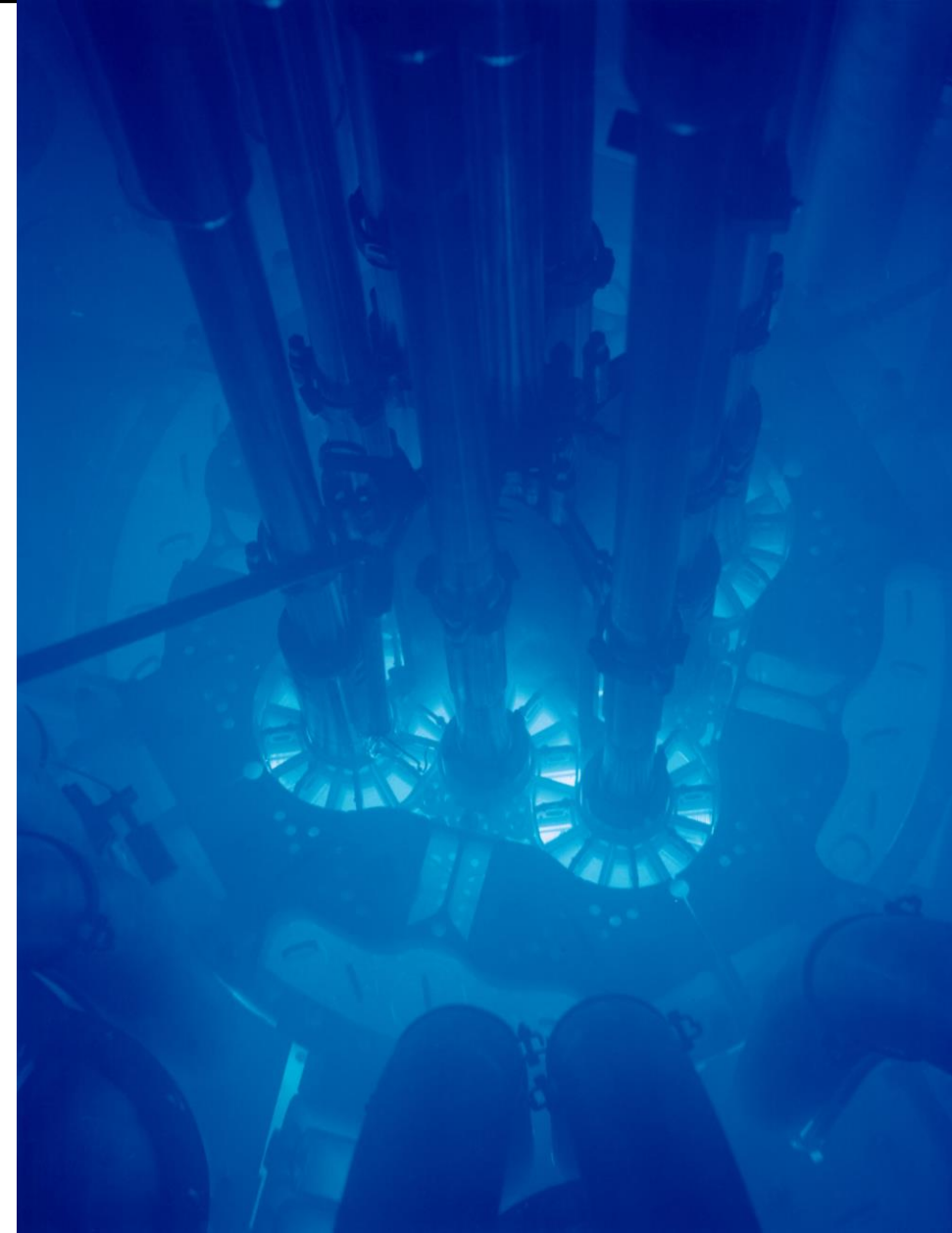
- Brookhaven National Laboratory proposed the Electron-Ion Collider which is scheduled to be built in the 2020s.
- The EIC facility is a high polarization and high luminosity collider.
- Home to the dRICH detector, the focus of our studies.



Cherenkov Radiation

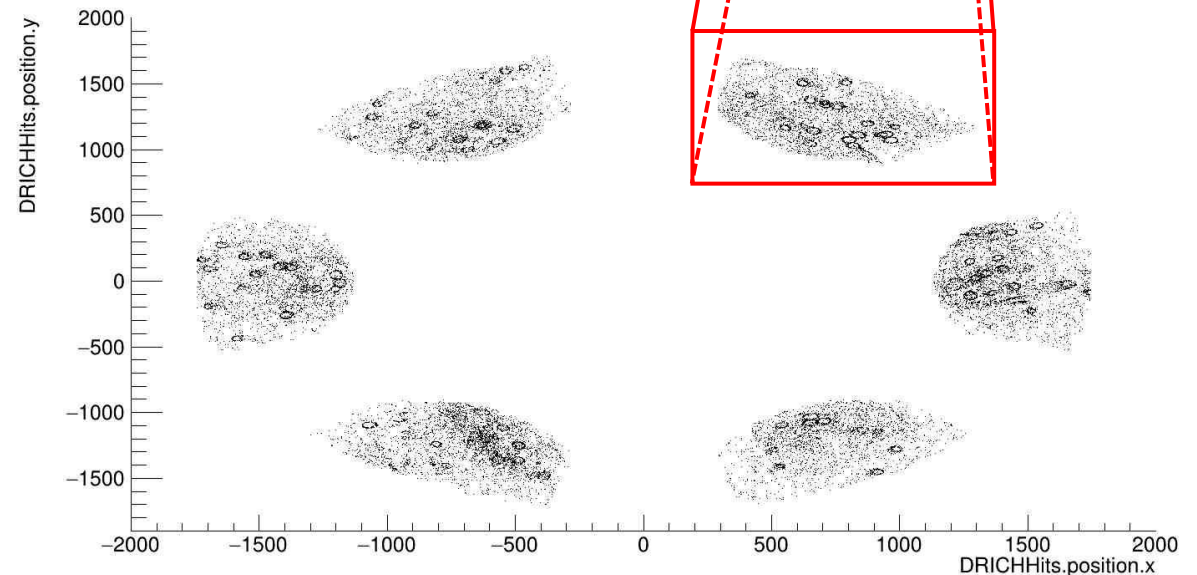
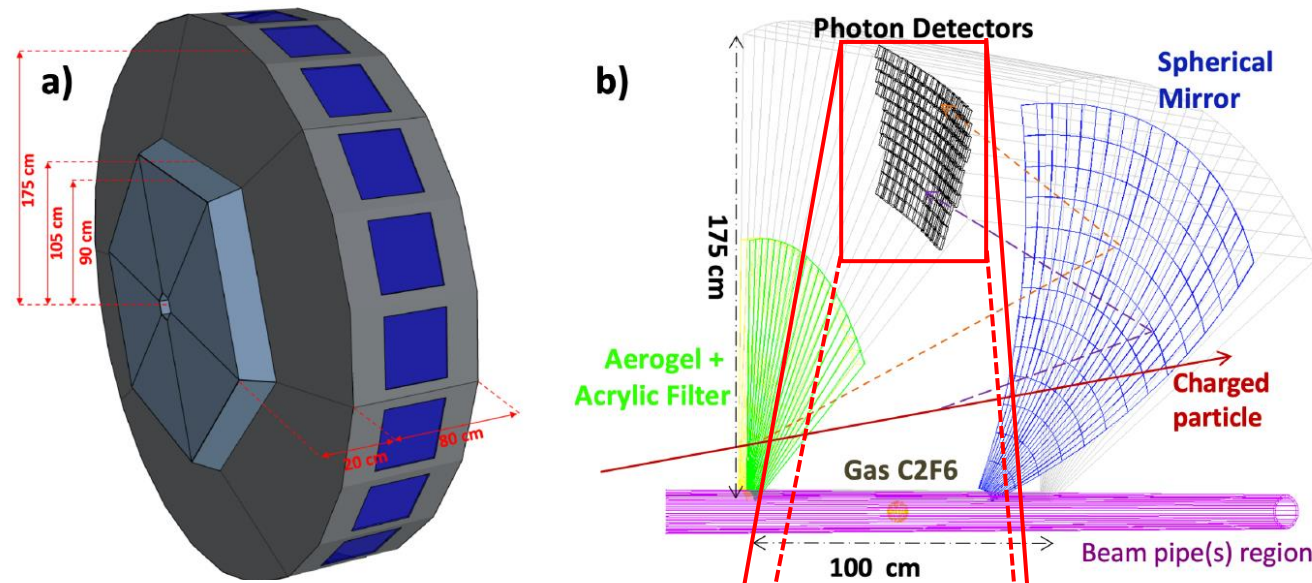
Review (2/9)

- Speed of light is slower in a medium (phase velocity of light)
- Particles can move at higher speed than the phase velocity of light
- When this happens, a characteristic glow is produced. i.e., nuclear reactors
- Analogous to the sonic boom produced at supersonic speeds.



EIC dRICH Detector

- The dual-radiator Ring Imaging Cherenkov detector is a photoionization (PID) detector with powerful hadron identification properties (pions, kaons, & protons).
- Composed of 6 sectors, each sector containing aerogel and gaseous layer.
- The principle behind RICH detectors is to use Cherenkov radiation to produce rings of different sizes (depending on particle type).



Khalek, R. et al. (2021, October 27). *Science requirements and detector concepts for the electron-ion collider: EIC yellow report.* <https://arxiv.org/abs/2103.05419>

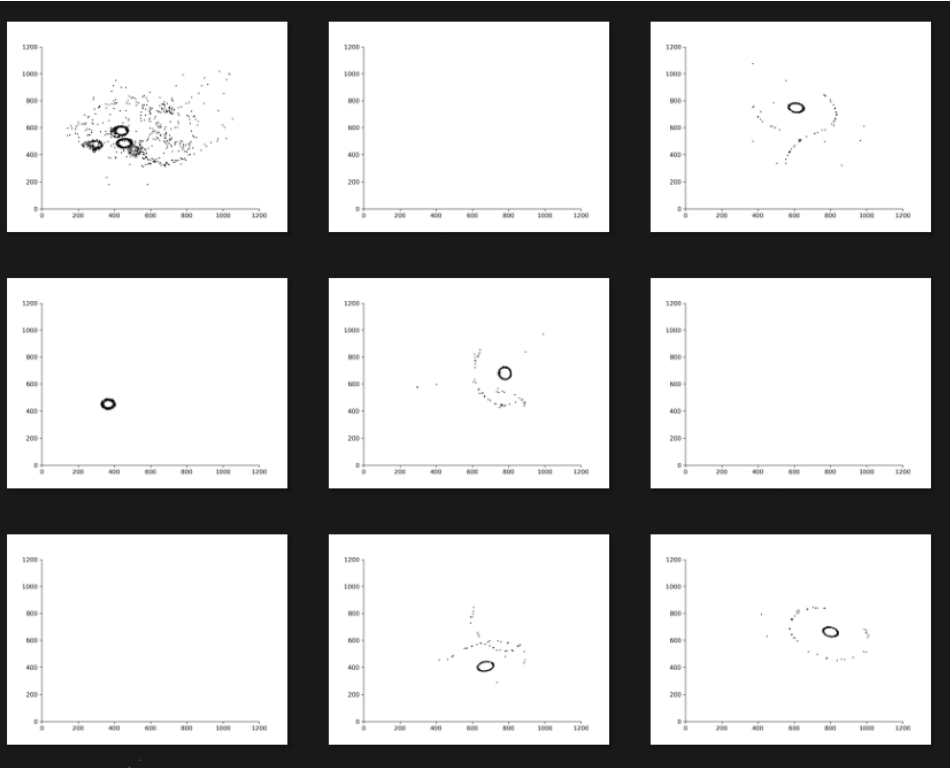
Bock, Friederike. et al. (2021, December 1) *ECCE Particle Identification.* ecce-note-det-2021-04v1.0

Motivation

- Our primary motivation is to provide a continuous method of particle identification with high accuracy.
- Data generated using DD4hep by CERN. ROOT file created containing the specified number of events.
- Sparsification of our model.
- 80/10/10 split for training/validation/test datasets.

Data Cleaning

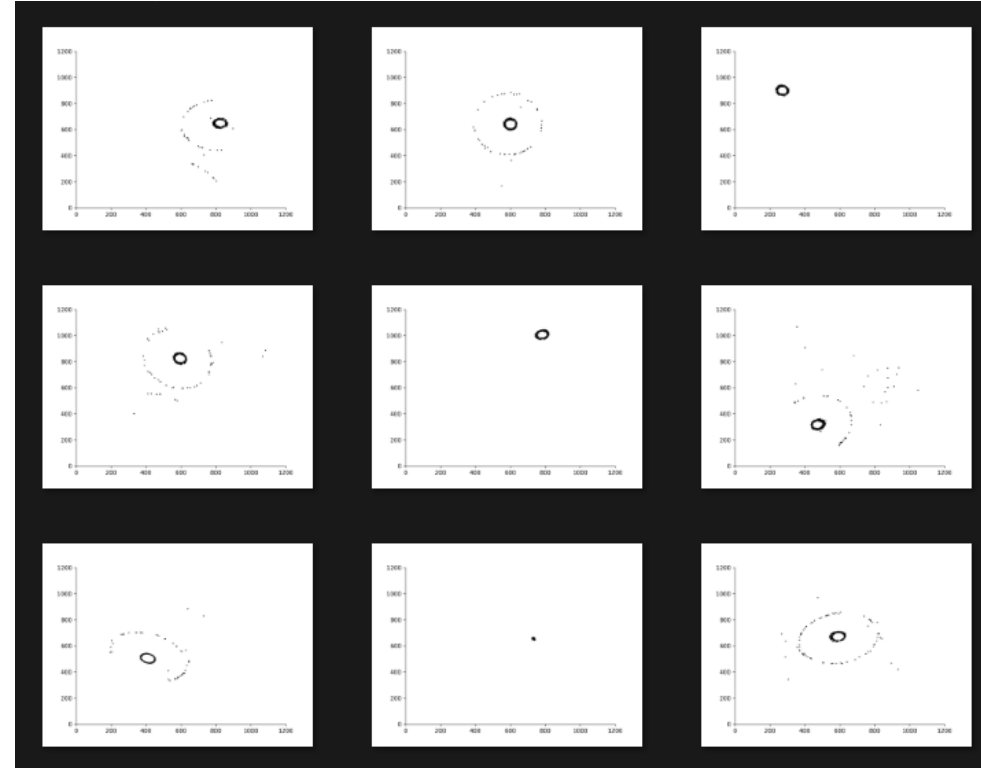
Unfiltered Electron Data



Removing Empty Events
& events with too many
or too little points



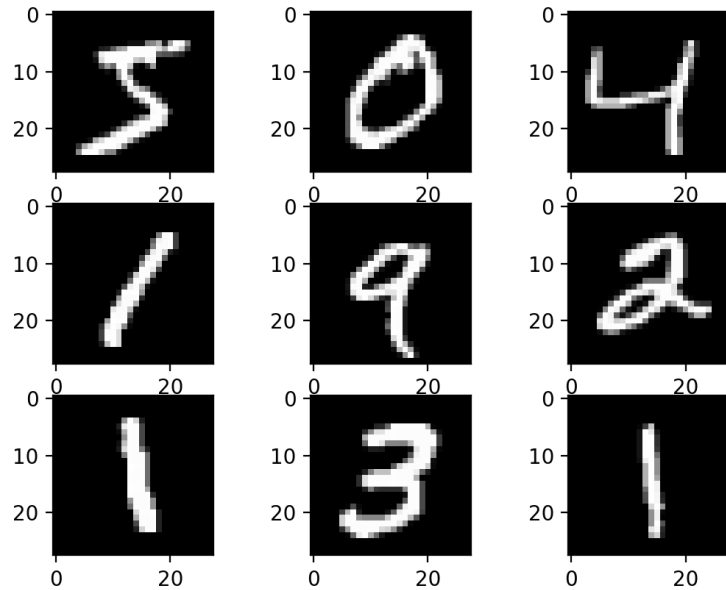
Filtered Electron Data



- Lots of data lost (~ 60% of events are empty)
- Filtered data is not perfect but good enough.

Convolutional Neural Networks (1/3)

- CNNs have remarkable image recognition properties, which make them very suitable for this problem.
- MNIST is an example of a dataset where CNNs perform very well, with an error rate of 0.09%



Convolution Layer

For:

n = input image size

f = filter size

p = padding size

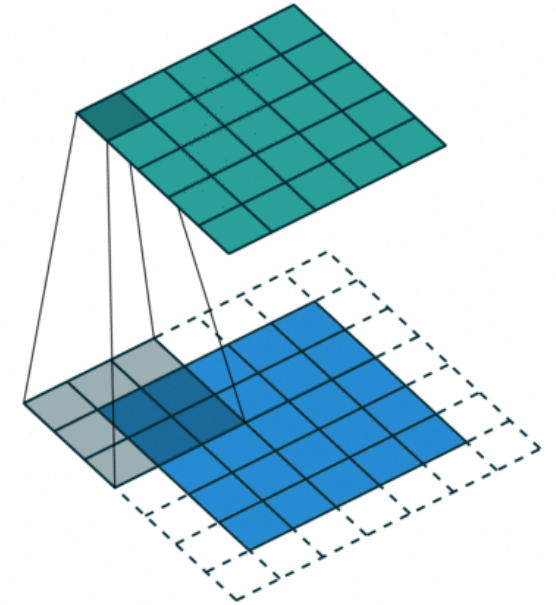
s = stride size

We get:

$$n_{out} = \left\lfloor \frac{n + 2p - f}{s} \right\rfloor + 1$$

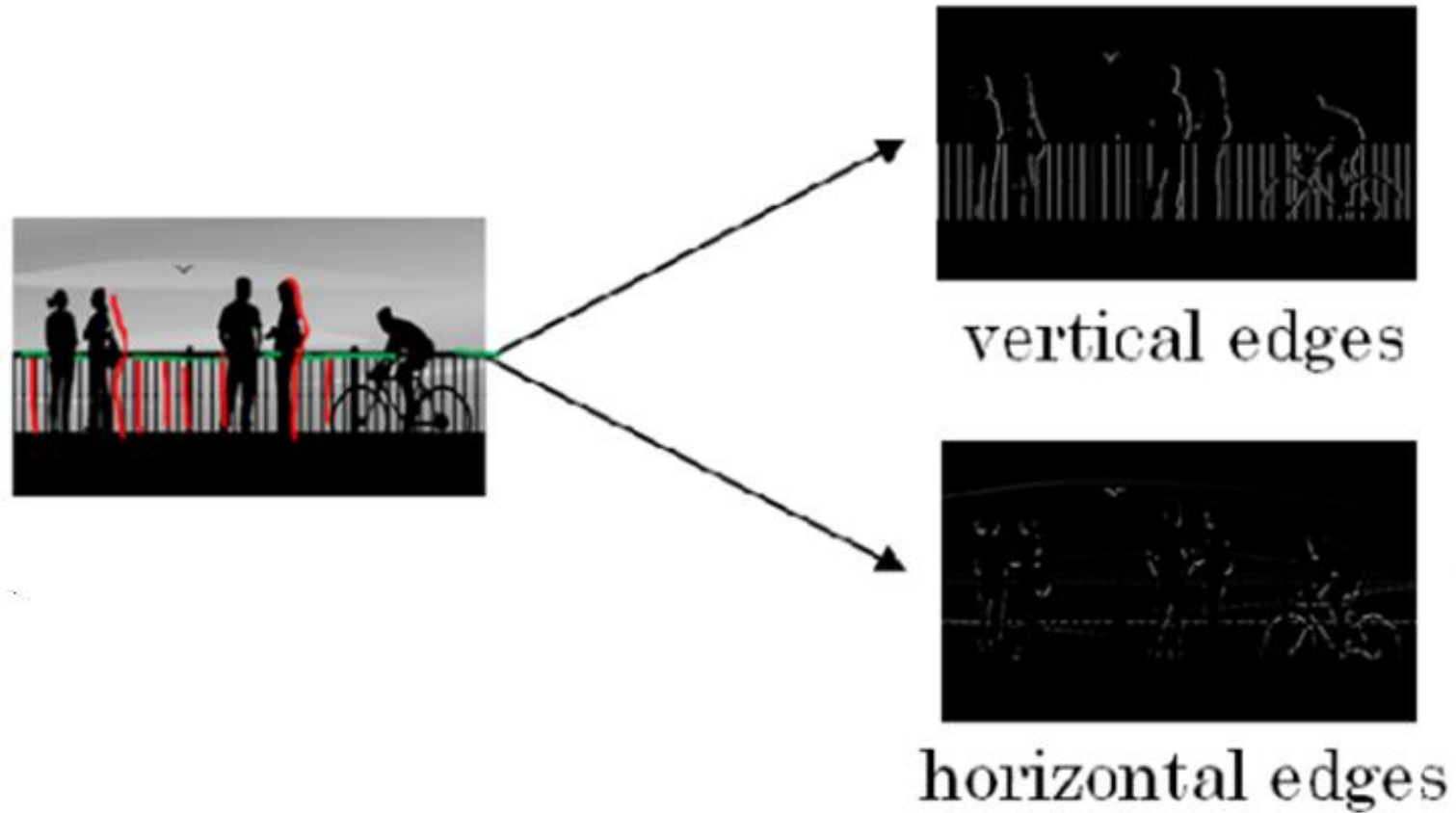
As an example:

$$n_{out} = \left\lfloor \frac{5 + 2(1) - 3}{1} \right\rfloor + 1 = 5$$



Convolutional Neural Networks (2/3)

Review (7/9)



Convolutional Neural Networks (Pooling)

- Pooling layers are used for dimension reduction: retain features of the image while decreasing image size.
- Multiple types of pooling, such as max pooling and average pooling.

Pooling Layer

2	2	7	3
9	4	6	1
8	5	2	4
3	1	2	6

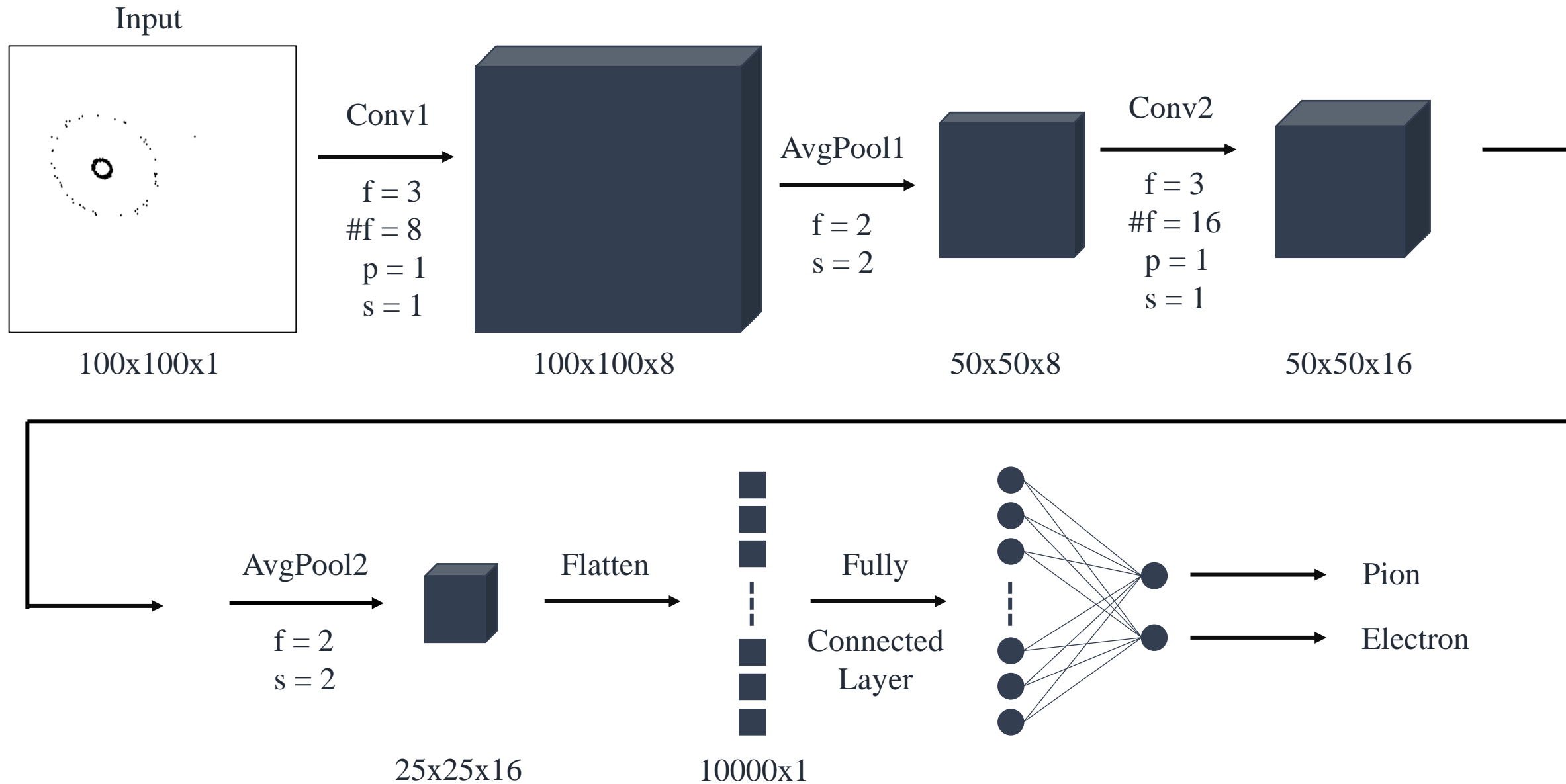
Average Pool



Filter - (2 x 2)
Stride - (2, 2)

4.25	4.25
4.25	3.5

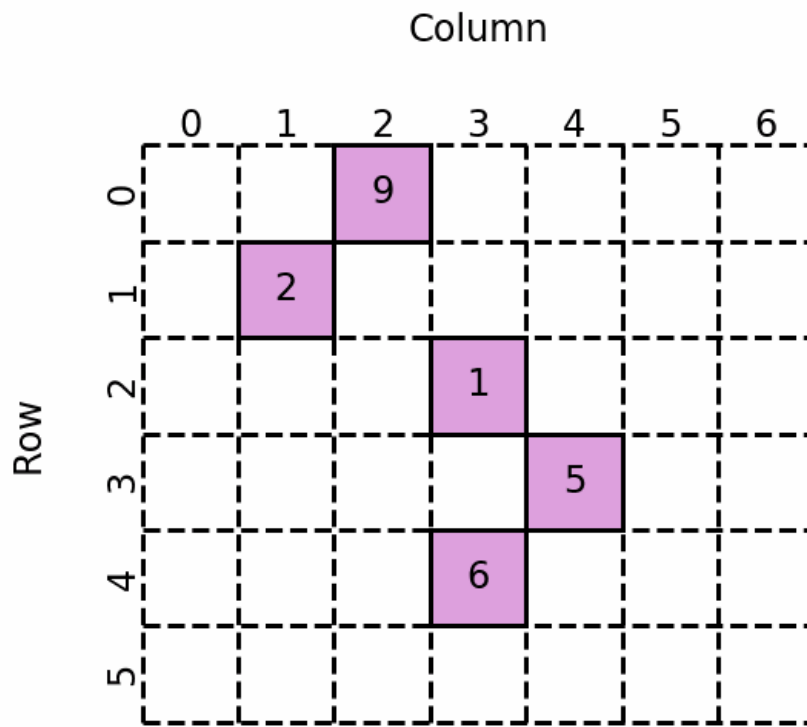
Original Working Model



- Dense tensors become too computationally intensive for a larger number of events.
- A more memory efficient and faster way to store our data is needed.
- Sparsifying our data allows us to do this without a loss in data.
- The amount of memory saved relies on how sparse the data is, but there is at least a 200-fold memory efficiency in sparsification [1].

The Sparse COO Format

- There are a number of formats to store sparse data, for example the coordinate format (COO) and the CSR/CSC format.
- The COO format is used by Minkowski Engine so we will focus on it.
- The COO format stores both the row and column coordinates, alongside the value at that coordinate.



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COO

Row

1	3	0	2	4
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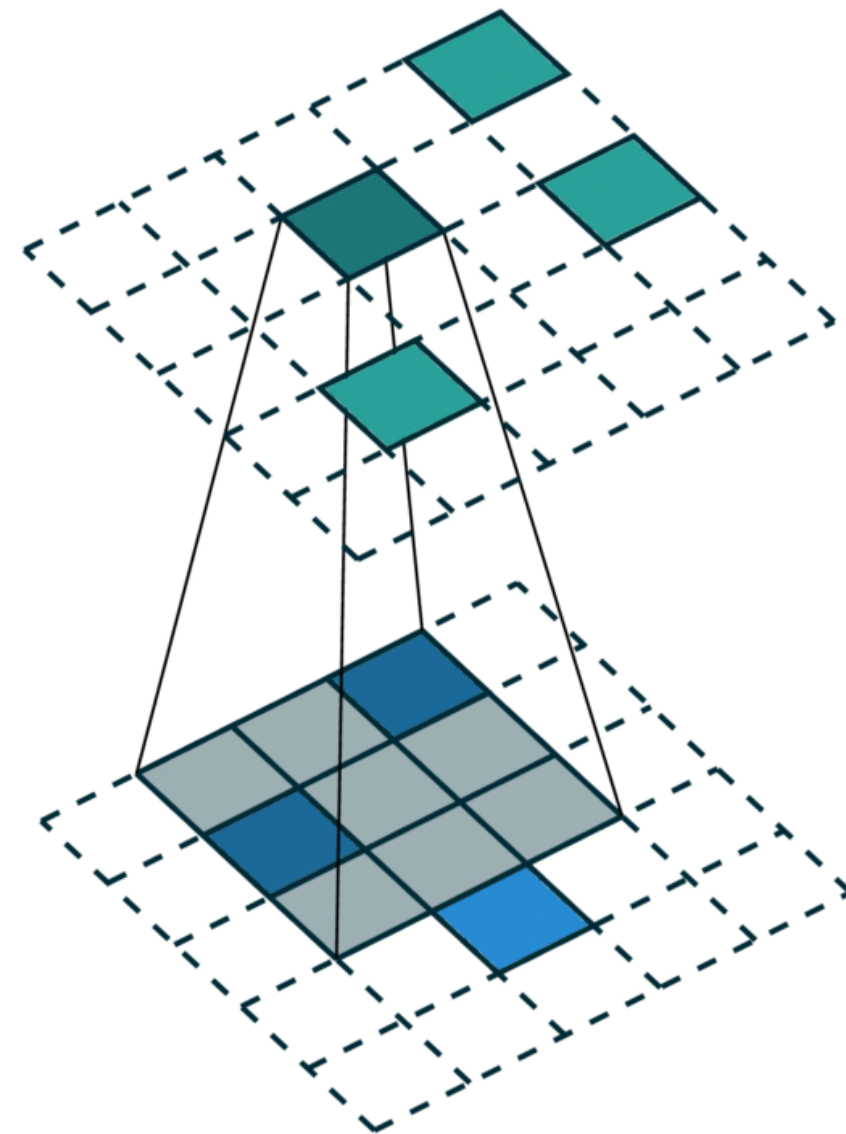
Column

1	4	2	3	3
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Data

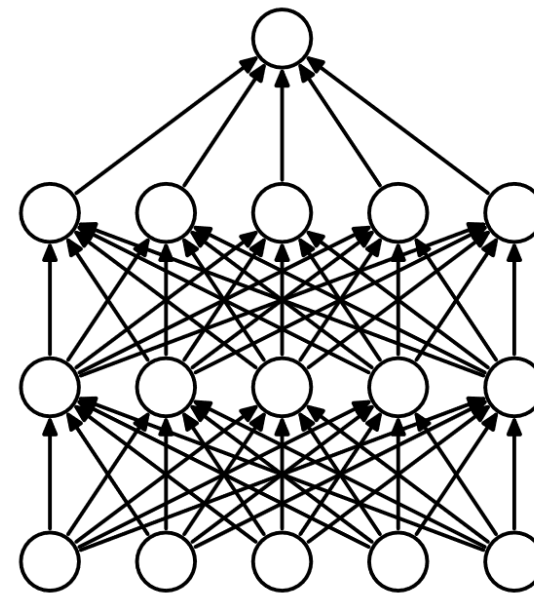
2	5	9	1	6
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- The major frameworks for machine learning lack native support for convolutions with sparse data.
- This leads to using an external library, we opted for Nvidia's Minkowski Engine.
- Data is quantized.

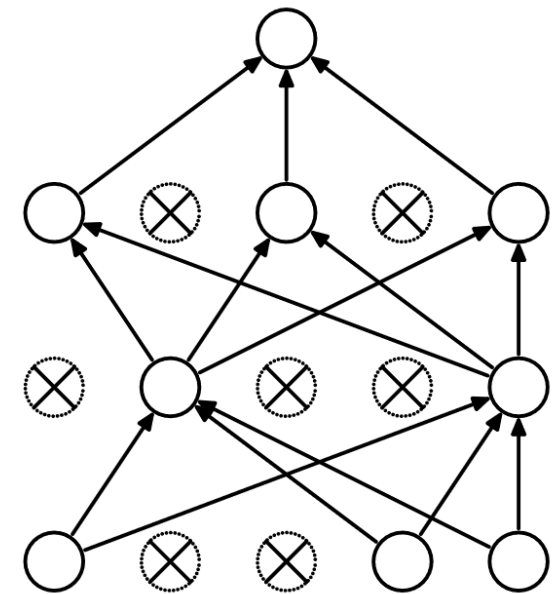


Overfitting & Dropout

- Overfitting is a common issue where the model learns the training data too well. This causes the model to fail with new data.
- Validation dataset allows us to test the model on new data during the training process.
- Dropout layers address this issue by deactivating some neurons during the training process.



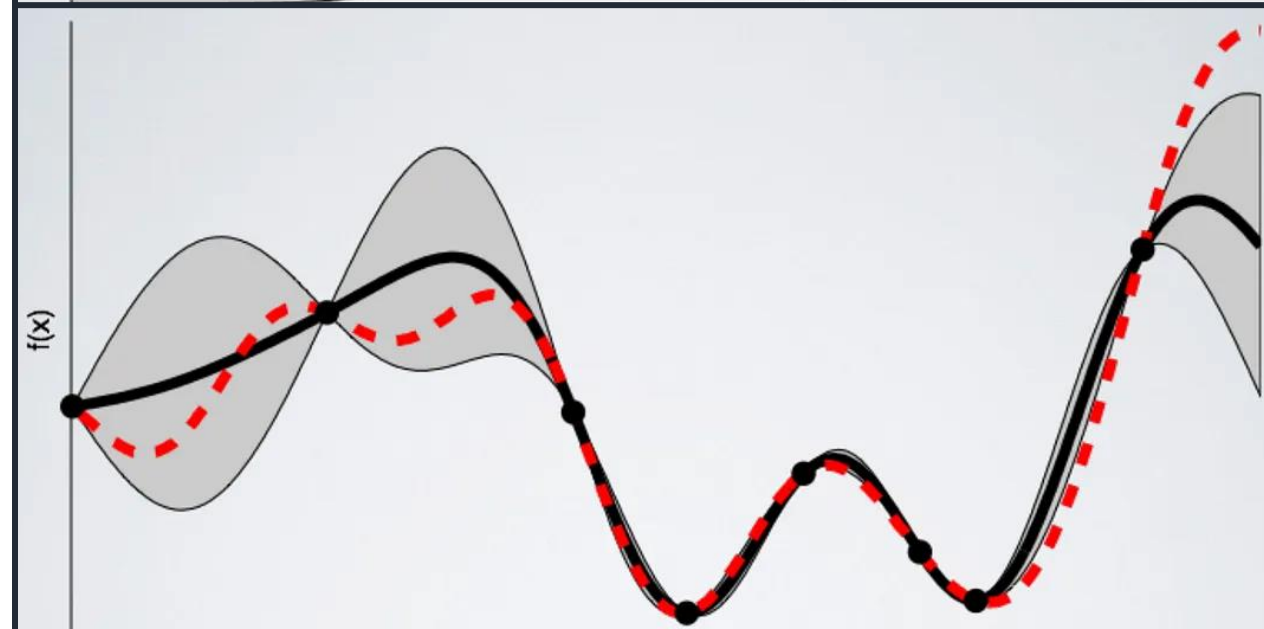
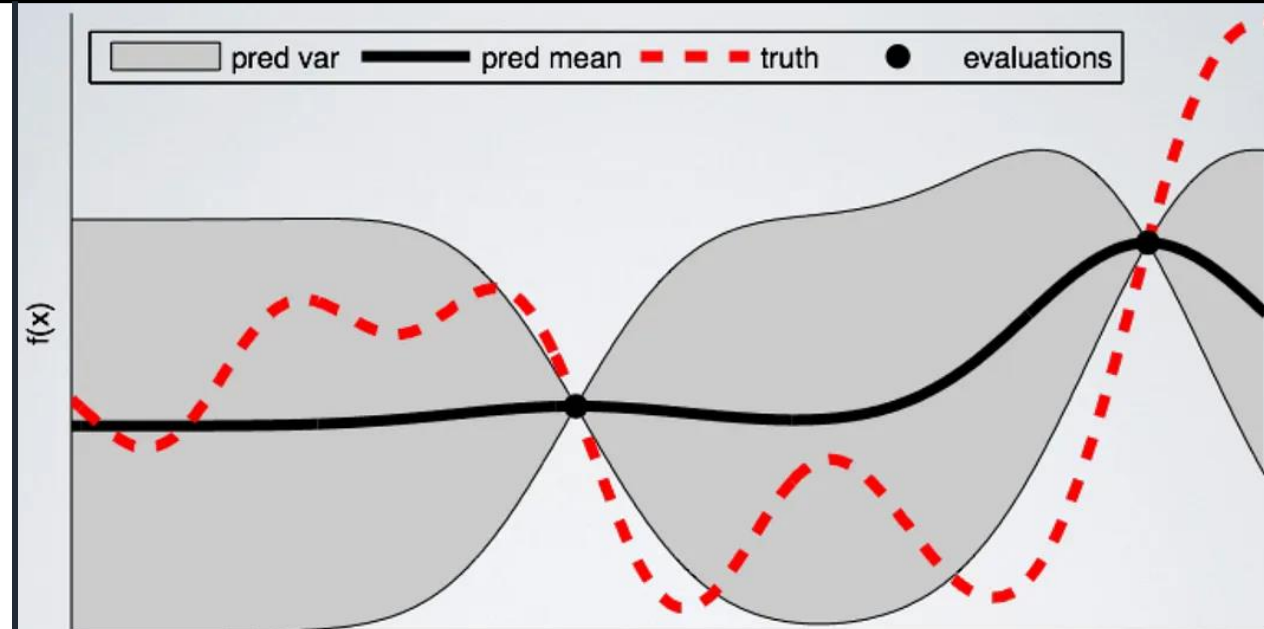
(a) Standard Neural Net



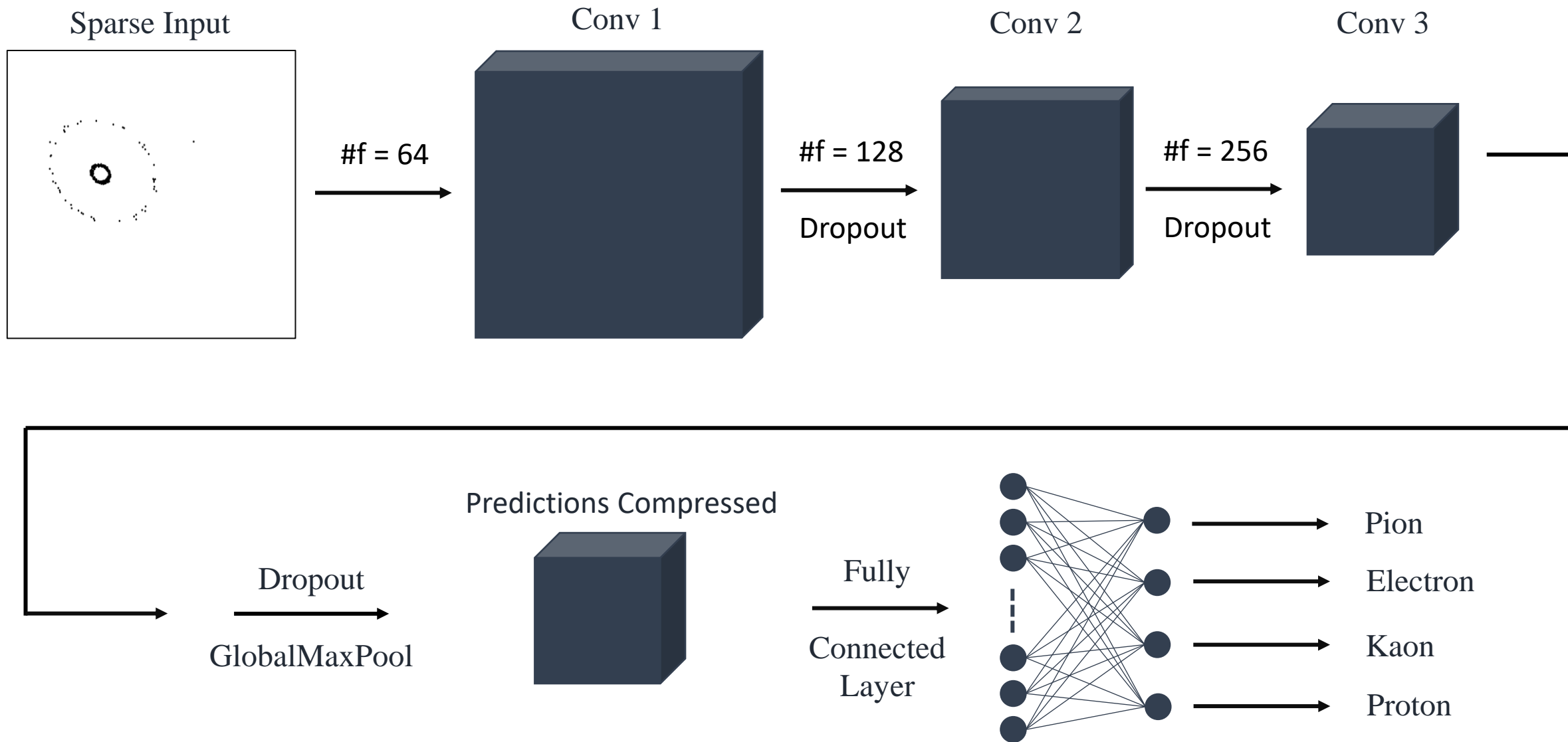
(b) After applying dropout.

Hyperparameter Optimization

- Manually adjusting hyperparameters is a tedious process and unlikely to give the best hyperparameters to train our model.
- Hyperparameter optimization methods offer an automated and methodical way by which we can find the best hyperparameters to minimize our loss.
- We use Bayesian hyperparameter optimization, a method which uses prior results to better predict the parameters.

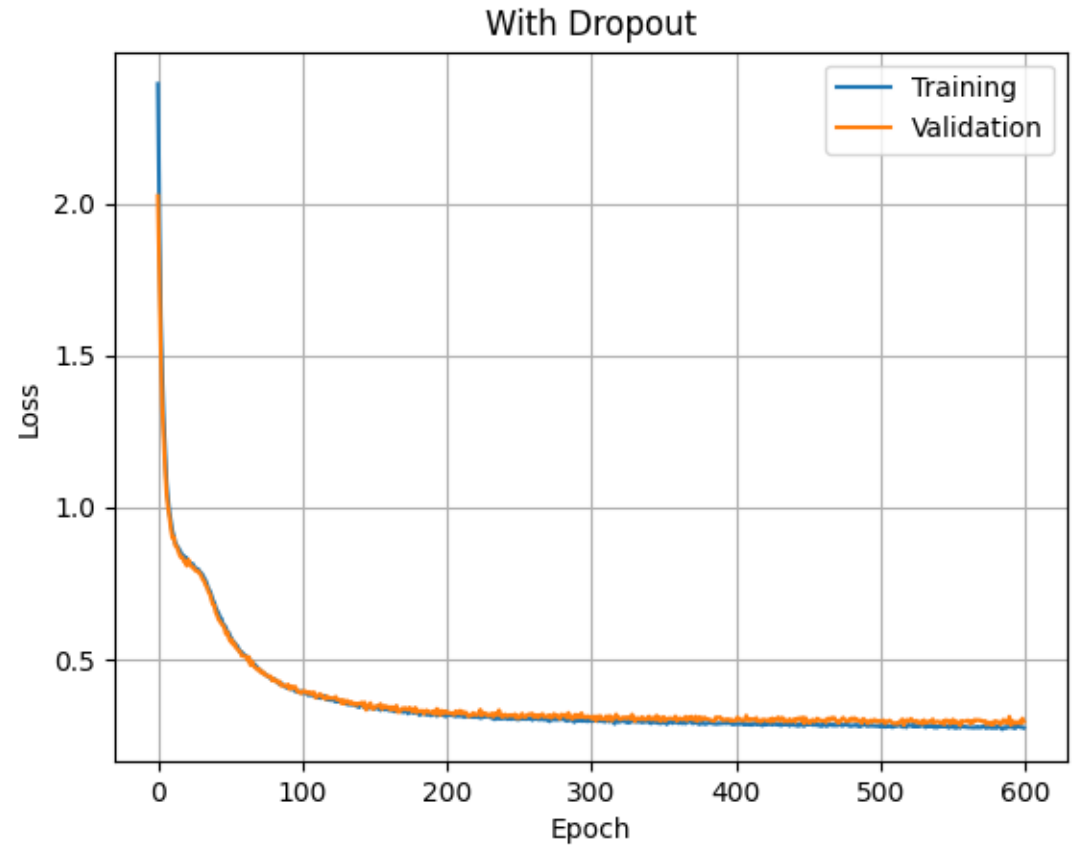
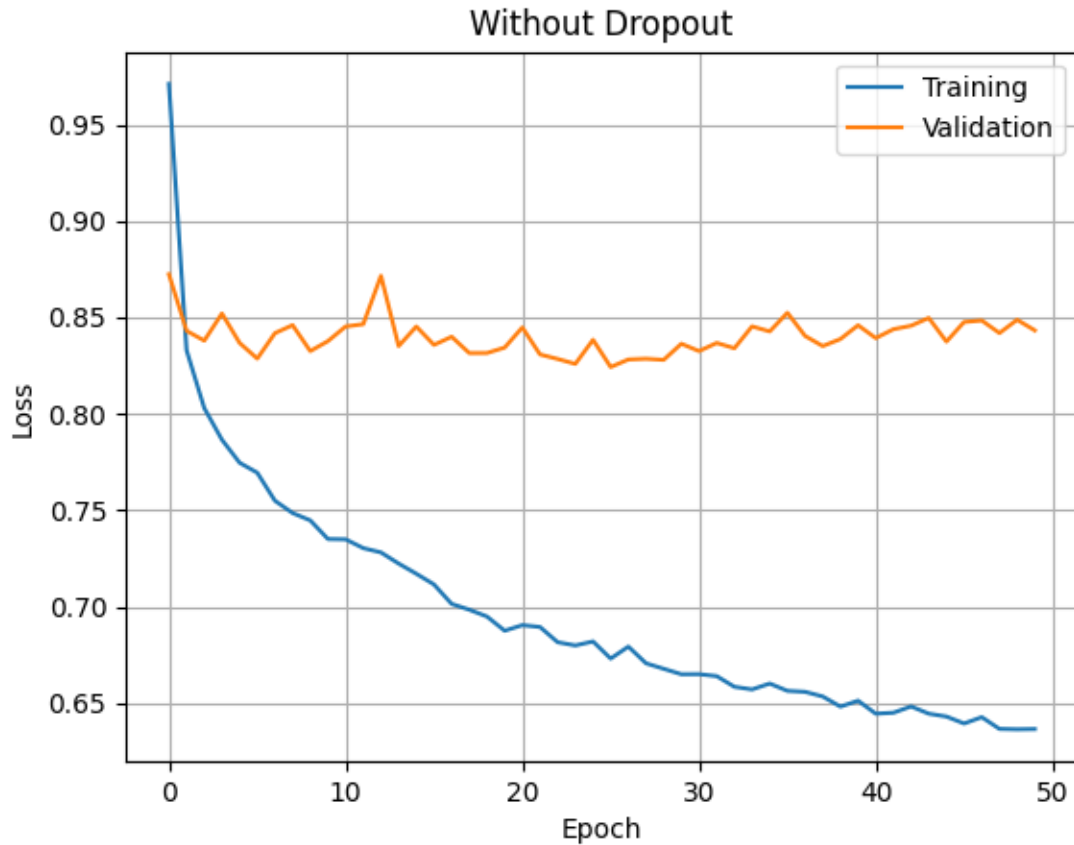


New Model



Model Performance (1/2)

- Adding dropout layers between the hidden layers addressed our overfitting problem.

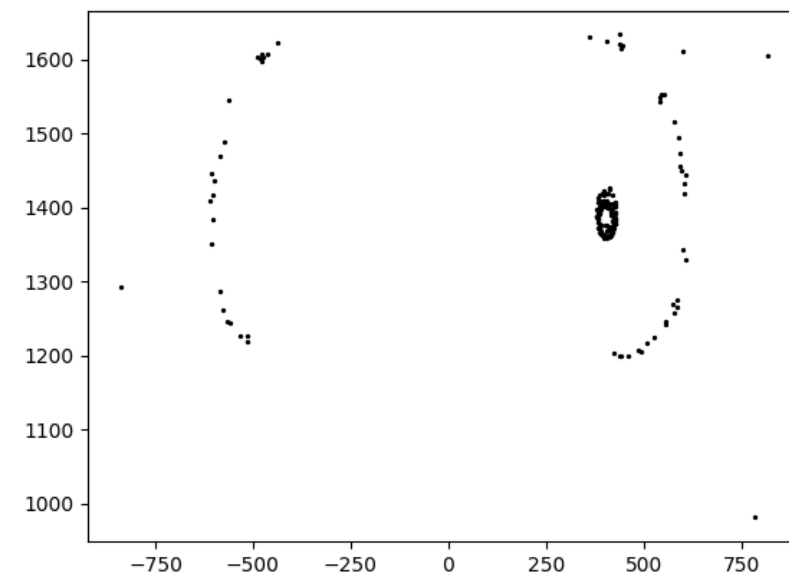
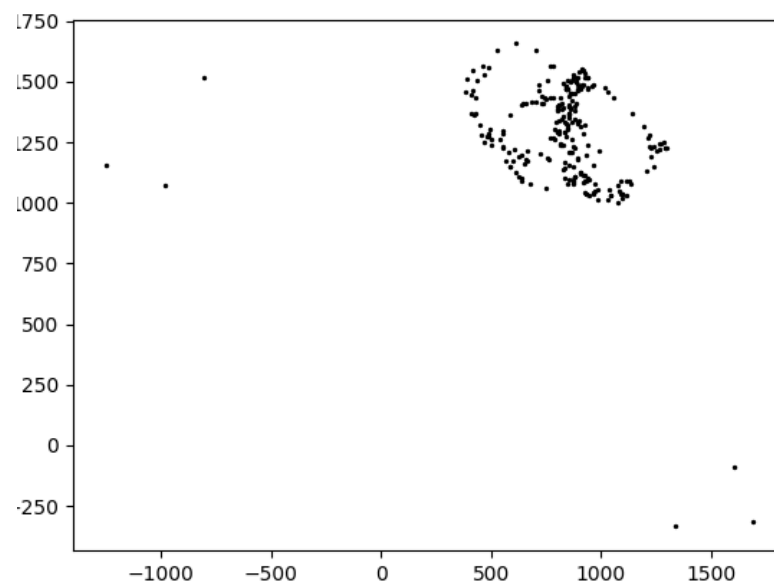
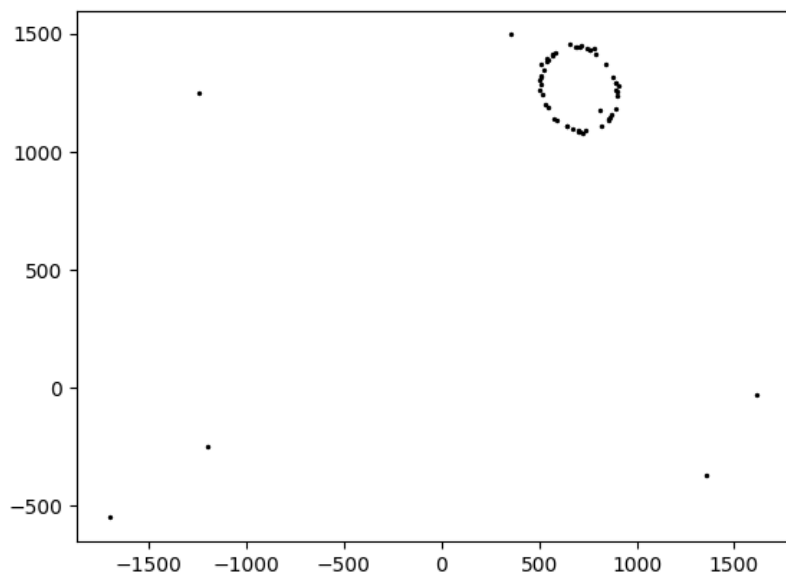


Model Performance (2/2)

- With the magnetic field disabled, we get an accuracy of 96.75% for the test dataset.
- With the magnetic field enabled, we have a 93.82% accuracy for the test dataset.
- As expected, the magnetic field introduces more noise which decreases the accuracy of our model.

Particle	Events	Accuracy
Pion	9677	95.44%
Electron	8339	95.57%
Kaon	2635	76.81%
Proton	215	4.55%

Kaon Performance

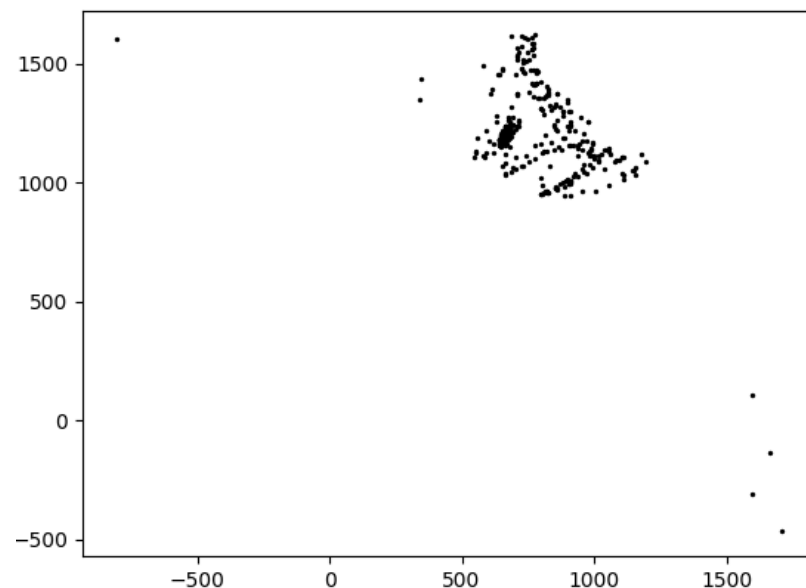
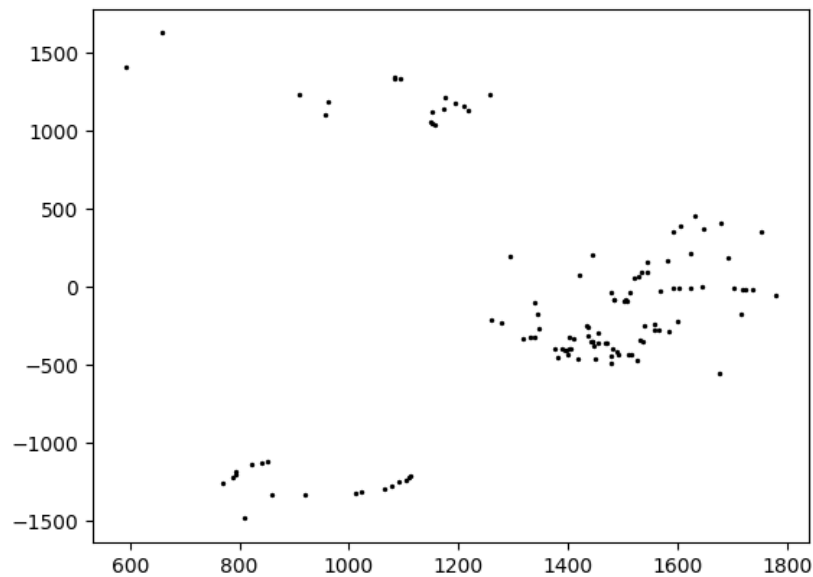
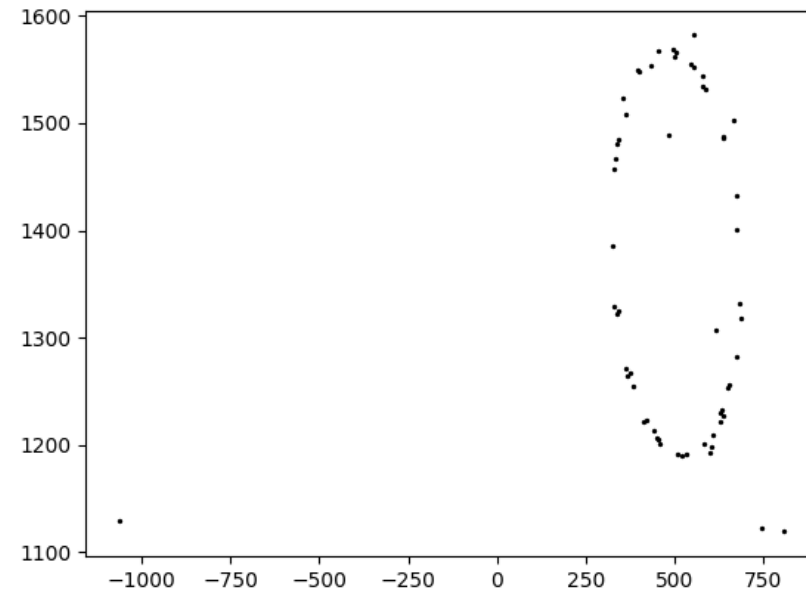
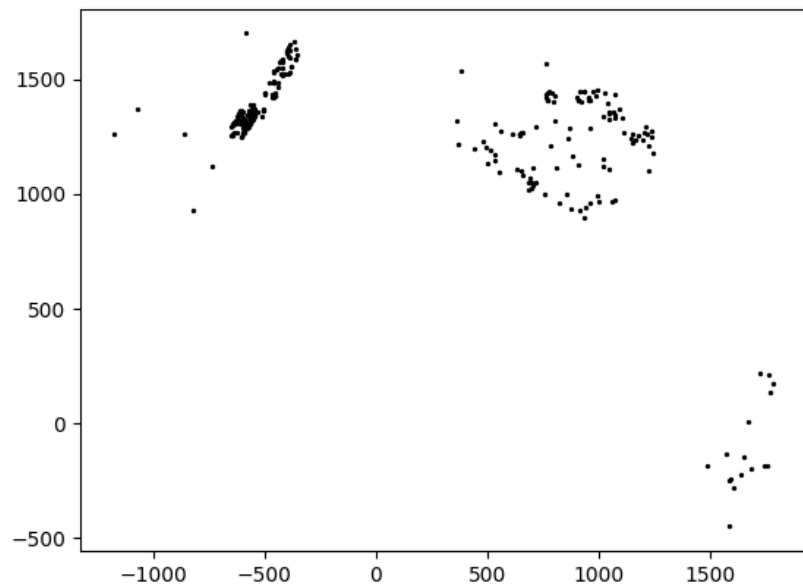


Proton Performance

Results (4/6)

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- The proton events are highly irregular and too noisy. Independent of magnetic fields.
- The low number of events leads to less training data and therefore a much worse accuracy.
- A few good events stand out but it is overwhelmingly comprised of non-rings.



- An octree-based framework like O-CNN outperforms Minkowski Engine in both memory efficiency and speed.
- Datasets are not evenly balanced, protons had very few events remaining after cleaning relative to the rest of the particles.
- The number of points per event will be affected once the quantum efficiency of the detectors, dead areas between pixels, and safety factor are considered. This is because we don't have an exact pixel count since it isn't a flat grid.

- Make sure that the model has equal data for each particle type.
- Replace Minkowski Engine with O-CNN for memory and speed benefits.
- Implement momentum as another factor during training, alongside coordinates.
- Deploy model in C++ interface for speed boost.
- Improve the accuracy even further and deploy the model in the facility.

Acknowledgements & Resources

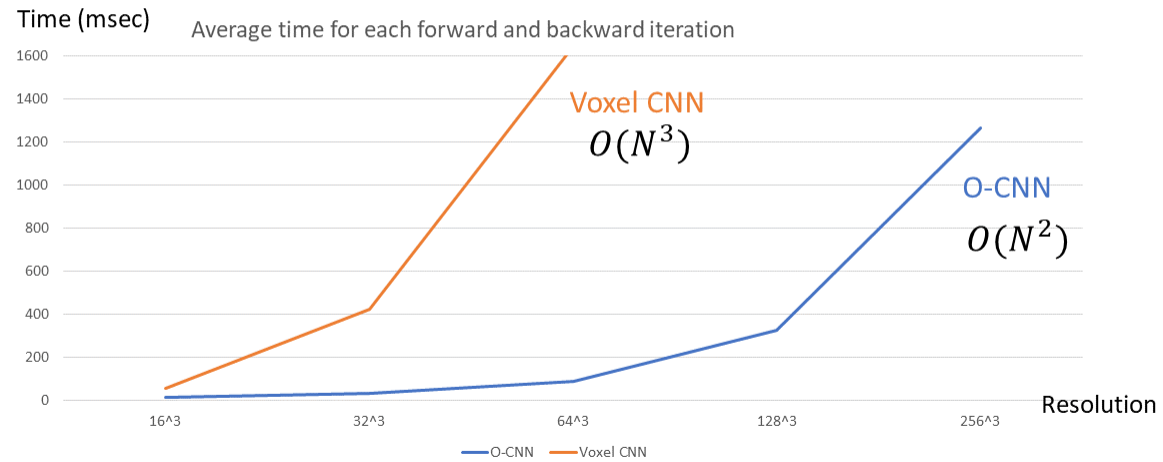
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- I'd like to acknowledge Dr. Wouter Deconinck and Dr. Zhiyang Zhou's help during my thesis.
- I'd also like to thank Sakib Rahman & Max Fatouros for their help with regards to hyperparameter optimization and dropout layers respectively.
- My code and thesis can be found at: <https://github.com/ohassn/Particle-Identification-Using-CNNs>

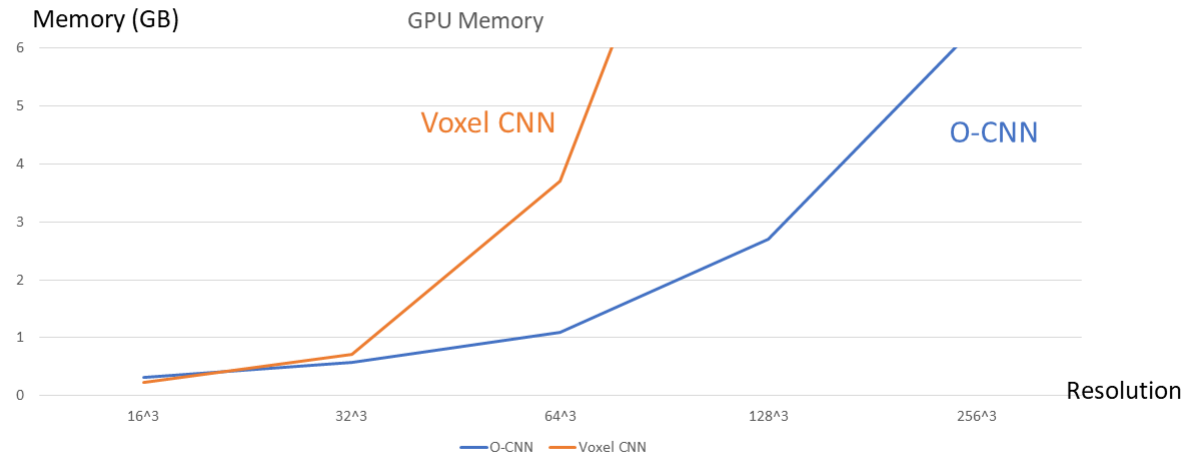
Q&A

Appendix (1/4)

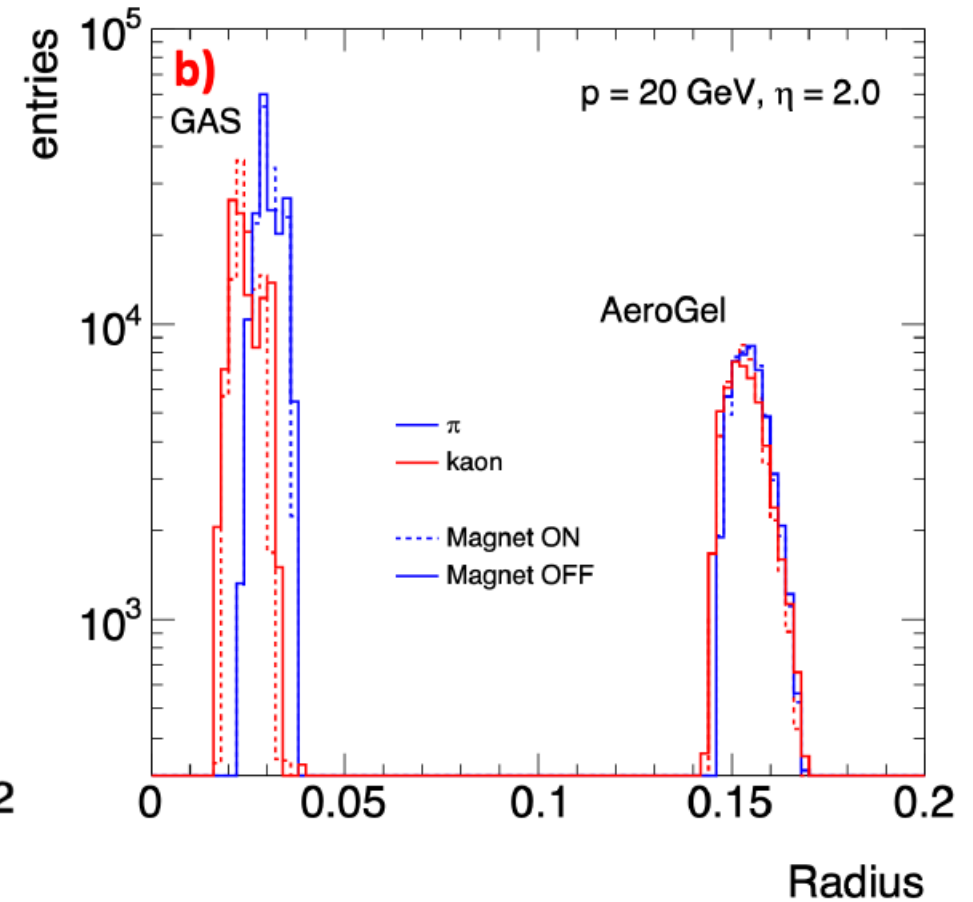
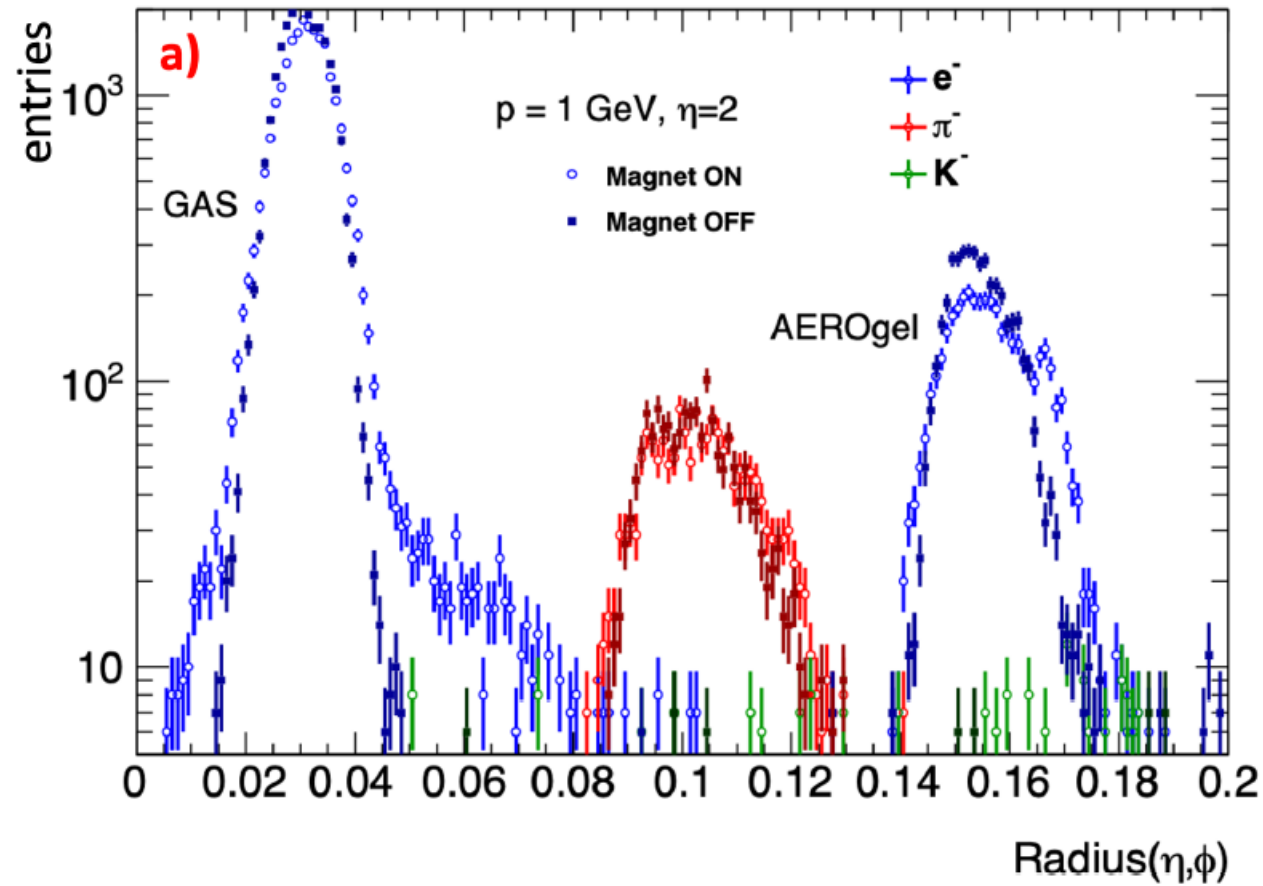
Computational Efficiency



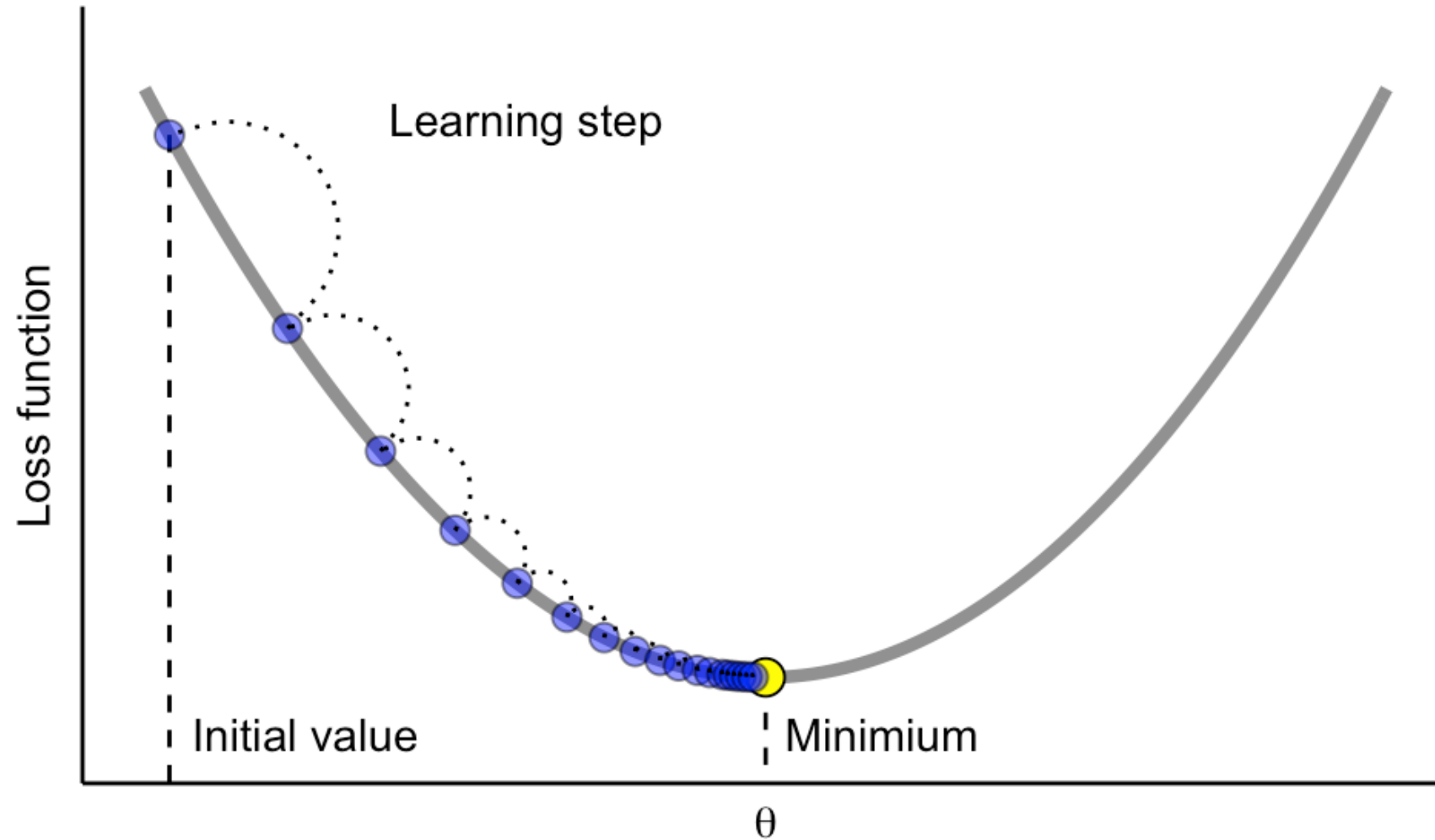
Memory Efficiency



Appendix (2/4)



Appendix (3/4)



Appendix (4/4)

- Dropout layer percentage is unknown, as it is unstated in the documentation
- 600 epochs, 0.0001 learning rate.
- Average and standard deviation of multiple runs for accuracy is preferable to accuracy based on one run.