Benchmark on MUC magnetic field calculation

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Outline

- Geometry of the tapering and chicane coils implemented
- Spatial components of the magnetic field computed along three paths of points (one path along the coils axis and two oblique off axis paths)
- Three different numerical codes (ANSYS, Current-loop approximation, Daniele C++ code) used to run the simulations
- Four sets of data computed among the three codes and compared
- Conclusions

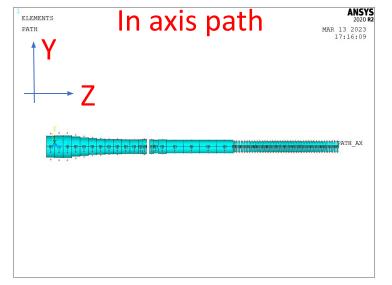
Geometry	Tapering Coil #	Rc(m)	Zc(m)	DR(m)	DZ(m)	NR
	1	0.820	-0.200	0.440	0.800	11
	2	0.840	0.600	0.480	0.800	12
	3	0.840	1.400	0.480	0.800	12
	4	0.780	2.200	0.360	0.800	9
	5	0.740	3.000	0.280	0.800	7
	6	0.700	3.800	0.200	0.800	5
	7	0.680	4.600	0.160	0.800	4
	8	0.660	5.400	0.120	0.800	3
	9	0.660	6.200	0.120	0.800	3
	10	0.640	7.000	0.080	0.800	2
	11	0.640	7.800	0.080	0.800	2
	12	0.640	8.400	0.080	0.400	2
	13	0.660	8.800	0.120	0.400	3
	14	0.640	9.500	0.080	0.400	2
	15	0.620	9.900	0.040	0.400	1
	16	0.640	10.500	0.080	0.800	2
	17	0.620	11.700	0.040	1.600	1
	18	0.620	13.300	0.040	1.600	1
	19	0.620	14.900	0.040	1.600	1
	20	0.620	16.500	0.040	1.600	1
	41 Chicane coils: Inner radius: 430 mm Outer radius: 530 mm Length: 180 mm				}	Paramo in C. Ro simula

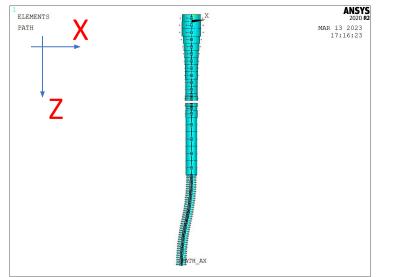
Current Density: 16.57 A/mm2 Placed at 0.625 deg intervals (250 mm in s) Parameters assumed in C. Rogers past simulations

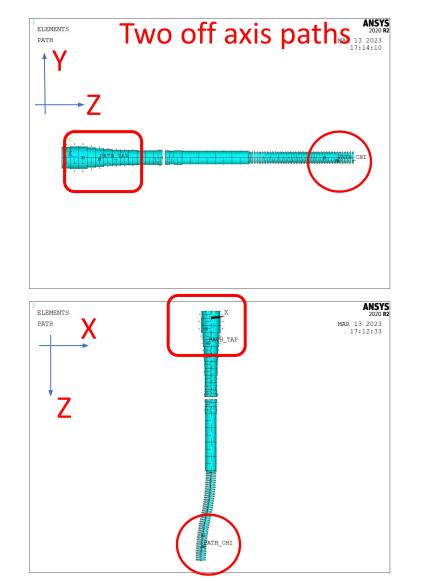
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Paths of points to compute the magnetic field







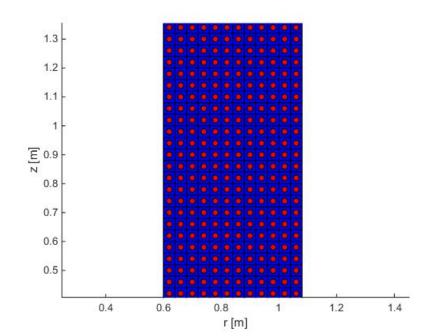
Numerical codes: ANSYS

- ANSYS in the case of magnetostatic and linear problems implements a formulation based on the integration of the Biot Savart law *
- It uses a primitive (meshless) current carrying elements (SOURC36)
- Magnetic field can be computed either directly at specific locations or by a finite element mesh made of SOLID96 elements

*Biot-Savart Integration for Bars and Arcs, Miklos Gyimesi et al. IEEE TRANSACTIONS ON MAGNETICS, V OL. 29. NO. 6. NOVEMBER 1993

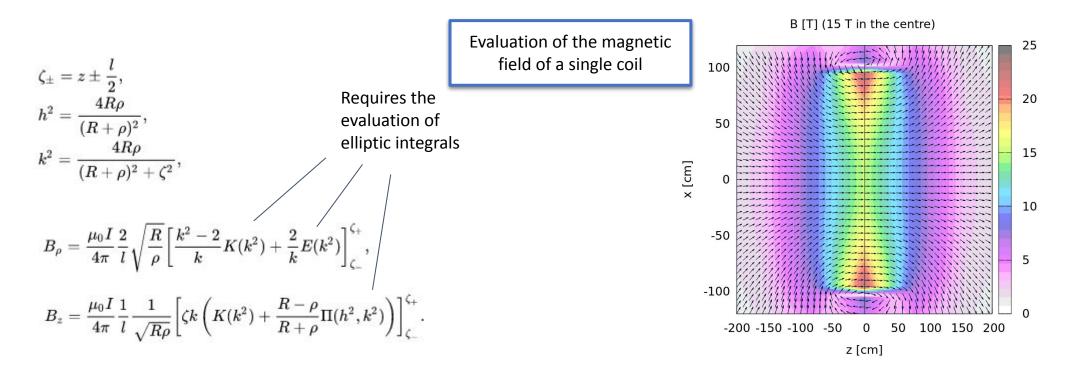
Numerical codes: Current-loop approximation

- Based on the well-known analytical solution of the magnetic field produced by a current-carrying ring with infinitely small cross section.
- The solution diverges at the source points (fine as long as we are not interested in the field inside the coil).
- Each coil is sub-divided in several loops in radial and vertical directions.
- Each loop is characterized by its radius, center position, direction cosines of axis, and current.
- Straightforward computation of net vertical forces if concentric non-tilted coils.



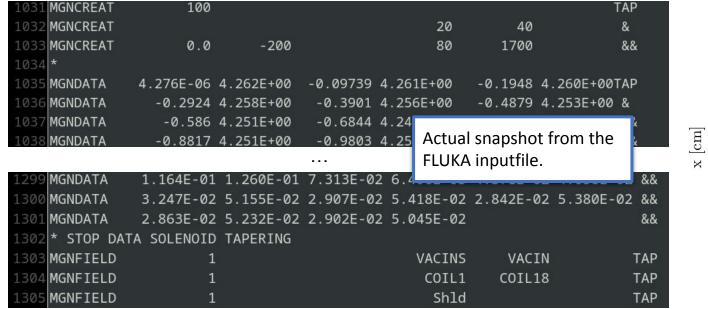
Numerical codes: Daniele

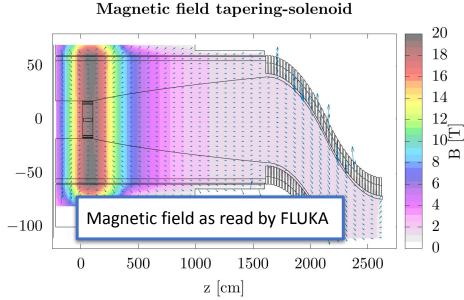
- The C++ code provides a numerical integration of the Biot Savart law.
- The code has been written ~1 year ago. It was a quick attempt to have a realistic magnetic field to set up simulation.
- Magnetic field can be computed either directly at specific locations or on a cartesian mesh.



Results to FLUKA

- Magnetic fields can be implemented in FLUKA via dedicated user routines or magnetic cards.
- Using the magnetic cards is less error prone and (in general) the preferred approach.
- It is possible to have 3D cartesian meshes or 2D when dealing with cylindrical symmetry.



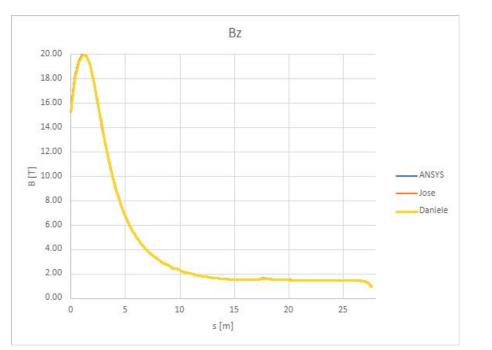


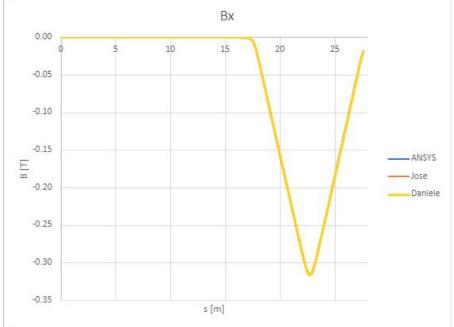
Sets of data

- 1. in axis points with tapering and chicane coils ON
- 2. in axis points with only chicane coils ON
- 3. off axis points in the tapering region with tapering and chicane coils ON
- 4. off axis points in the chicane region with tapering and chicane coils ON

Results: in axis point with tapering and chicane coils ON

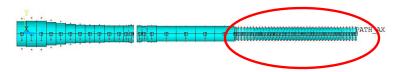
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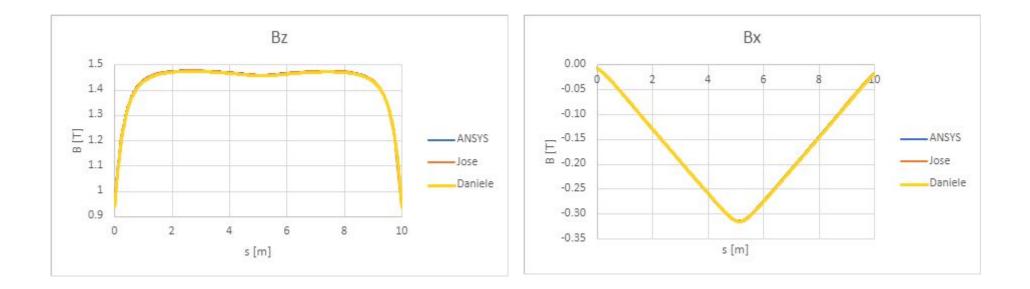




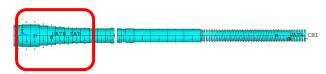
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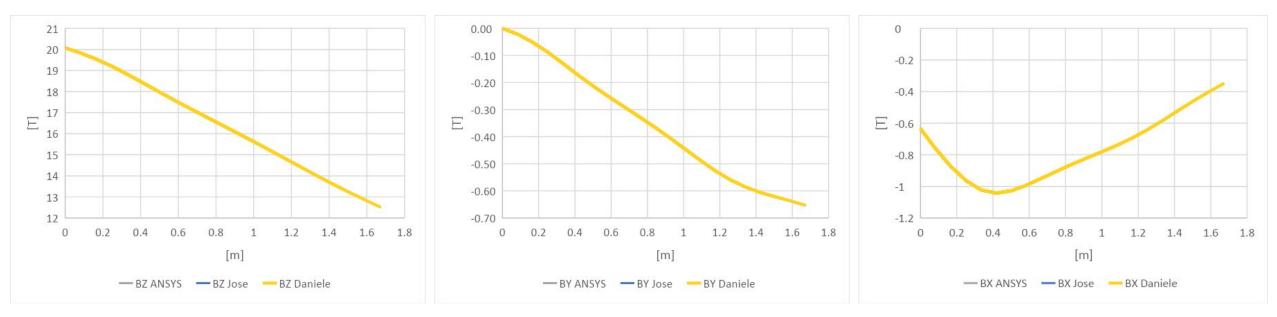
Results: in axis point with only chicane coils ON



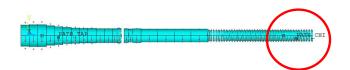


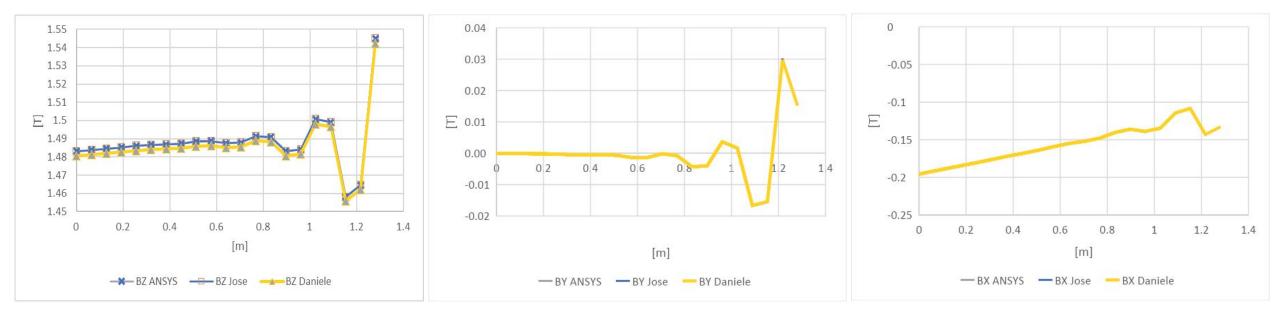
Results: off axis point in the tapering region





Results: off axis point in the chicane region





Conclusions

- A benchmark exercise has been implemented to validate three different numerical codes used for the design of the MUC
- The three components of the magnetic field have been compared along four different paths
- The benchmark outcome shows that the three codes provide results in a good agreement
- Lesson learnt: to have a satisfactory detail in the field definition, ~100 numerical slices in Daniele's code.
- Final remark: the current assumption of the tapering field follows the inverse cubic field from past MAP studies. Deviation from this function are fine as long as the magnetic field decrease is adiabatic.