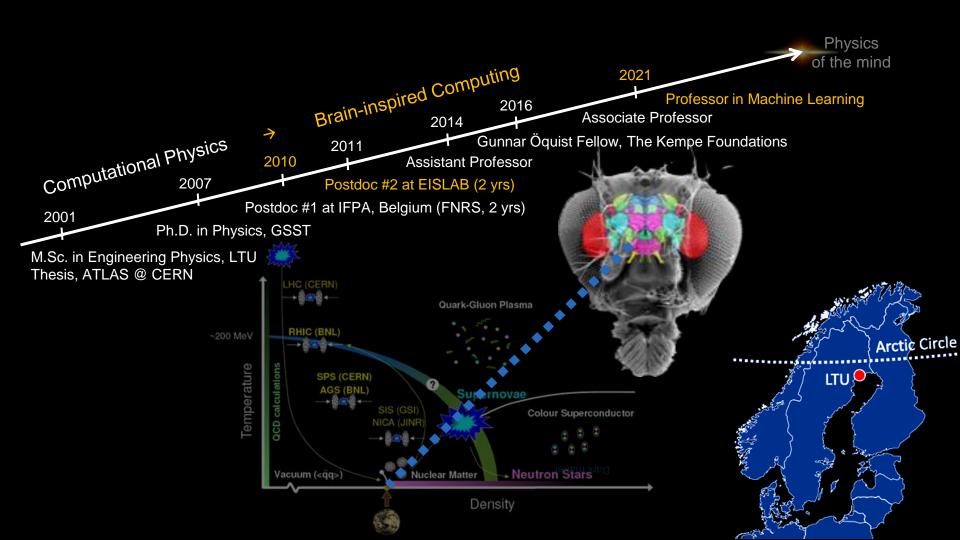
# Temporal Dynamics in Neuromorphic Computing

A New Frontier for Co-Design and Optimization in Physics and ML

Fredrik Sandin





## **Machine Learning Group**



Machine Learning for the welfare of society

## Neuromorphic Computing

Spiking Neural Networks (SNN)

Examples, work in progress

#### History of Physics

#### ... and Neuroscience

Laws of motion / gravity - Newton 1687

Maxwells equations 1864

Special theory of relativity – Einstein 1905
Bohrs model of atoms 1913
General theory of relativity – Einstein 1916
Quantum physics 1925-7
Antimatter predicted – Dirac 1928

1839 Cells, Theodor Schwann

1873 Silver staining method, continuous system viewpoint - Golgi 1888 Evidence for discontinuity, individual nerve cells - Cajal 1891 "Neuron" introduced - Waldeyer

1906 Receptive fields of neurons in the skin described – Sherrington

1943 First neuron model – McCulloch & Pitts 1949 Hebbian learning – Hebb 1952 Spiking neuron model - Hodgkin & Huxley 1958 Perceptron machine – Rosenblatt

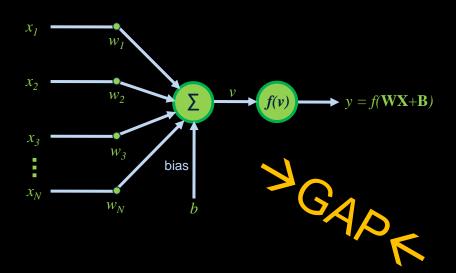
## Neuromorphic engineering aims to create computing hardware that mimics biological nervous systems

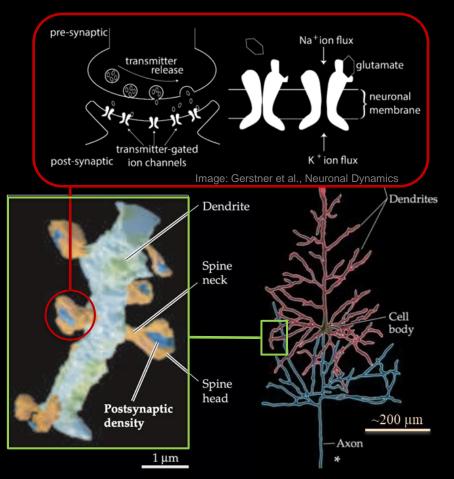


It had become clear to me that industrial practice was on a problematic path: in the race to release new product generations, it was faster to scale old designs to smaller feature sizes than to innovate at the architecture level.

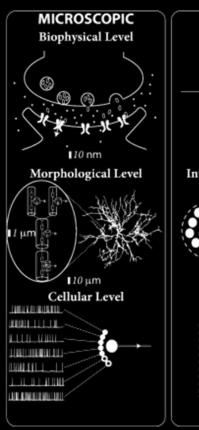
Image credit: Rodney Douglas

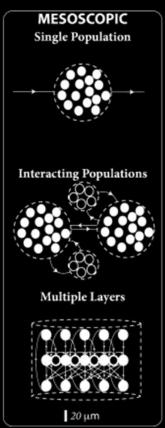
Carver Mead, How we created neuromorphic engineering, Nature Electronics (2020)

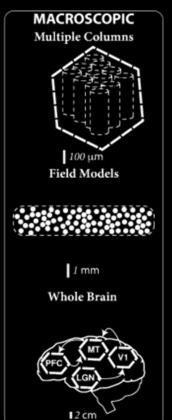




Images: Purves et al., Neuroscience







10<sup>4</sup> cells and several km of nerves (axons) per mm<sup>3</sup>

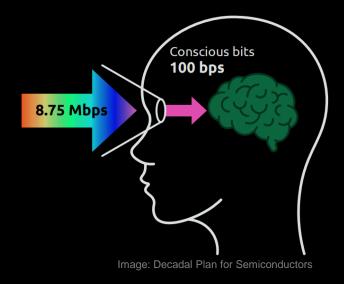
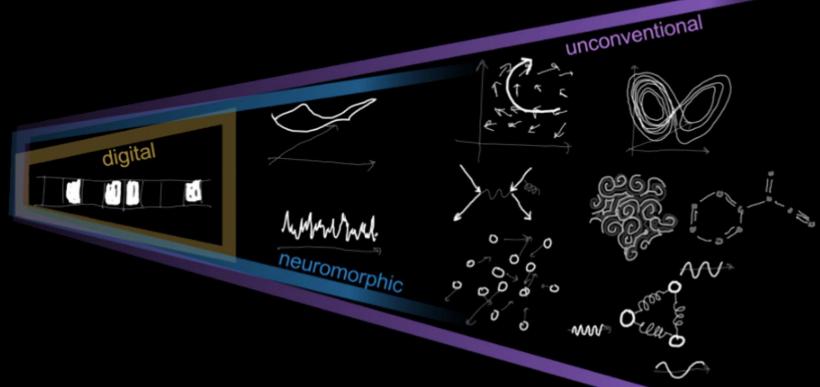


Image: Neuronal Dynamics, Chapter 12

See: Frenkel, Bol and Indiveri, Bottom-Up and Top-Down Approaches for the Design of Neuromorphic Processing Systems: Tradeoffs and Synergies Between Natural and Artificial Intelligence, Proceedings of the IEEE (2023); DOI: 10.1109/JPROC.2023.3273520.

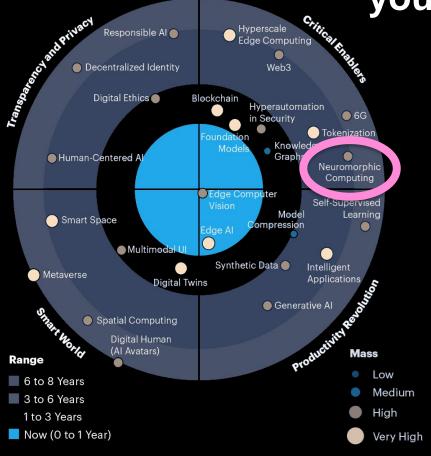
## Towards a generalized theory of computing



Herbert Jaeger, Neuromorph. Comput. Eng.1 (2021); <a href="https://doi.org/10.1088/2634-4386/abf151">https://doi.org/10.1088/2634-4386/abf151</a>

Lecture: https://www.youtube.com/playlist?app=desktop&list=PL2Mh0Lr7X-WWEk8-NRB28rUqrLXitFaZ4

Gartner #1 emerging technology that you need to know about

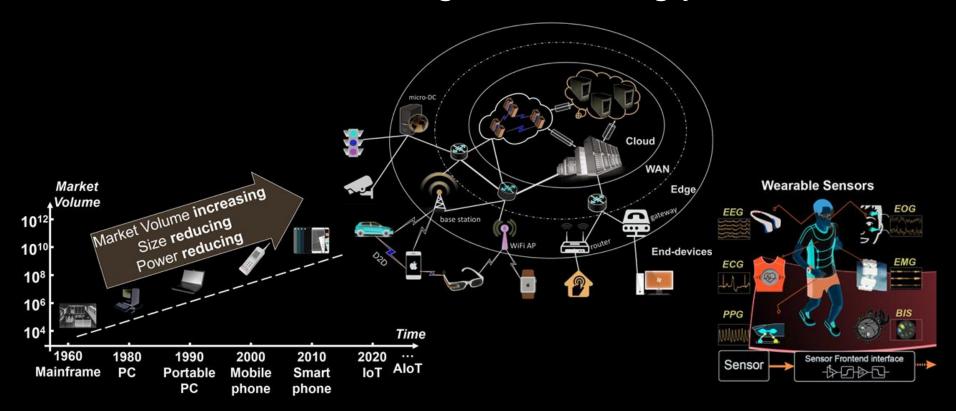


expected to disrupt many of the current AI technology developments

substantial impact on existing products and markets

3–6 yrs to cross over from earlyadopter status to early majority adoption

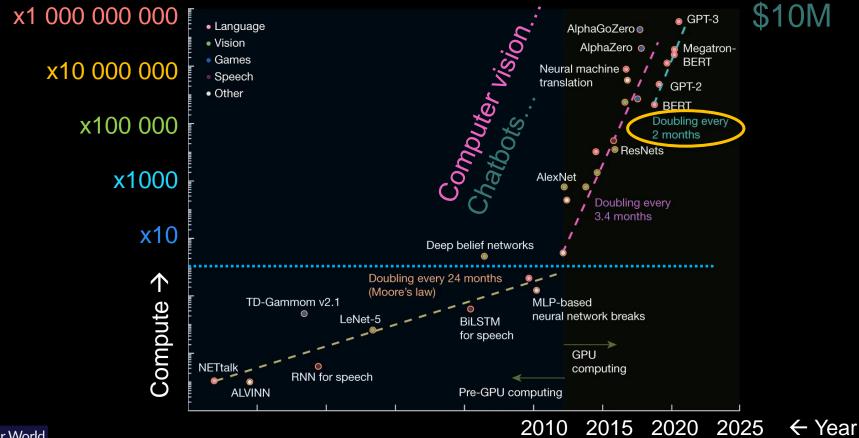
## Data at network edge increasingly valuable



Ye, et al. (2021) "Challenges and Emerging Technologies for Low-Power Artificial Intelligence IoT Systems"

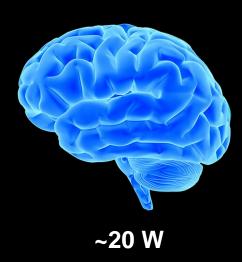
Zhou, et al. (2019) "Edge Intelligence"
Covi, et al. (2021) "Adaptive Extreme Edge Computing for Wearable Devices"

## Deep learning is too resource intensive





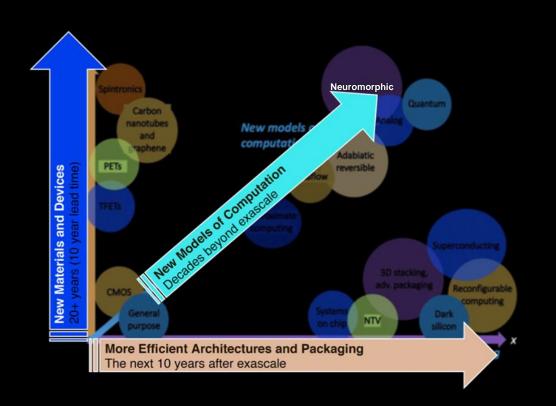
## **Energy-efficiency gap**





**21 MW** 

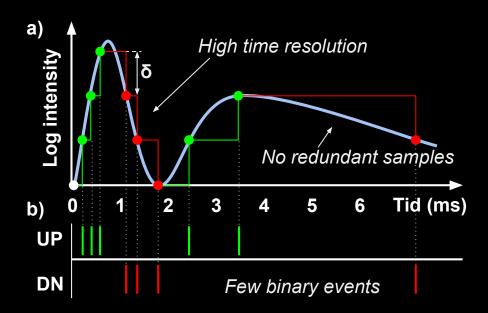
## "Beyond Moore", "Time Moore"



Rethink the constraint that "all cycles must have the same duration in time"

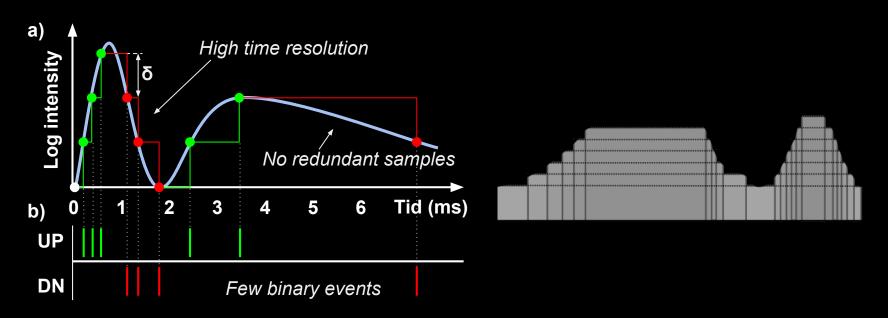
Event-triggered sampling, processing and control

## Level-crossing ADC



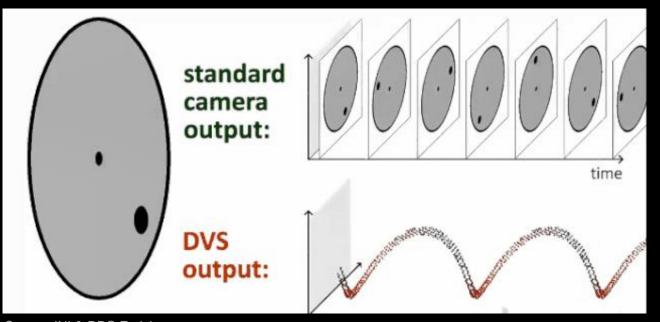
Signal changes by some delta → new information

## Lebesgue sampling paradigm



Lebesgue integration instead of Riemann integration with constant dt (clock cycle)

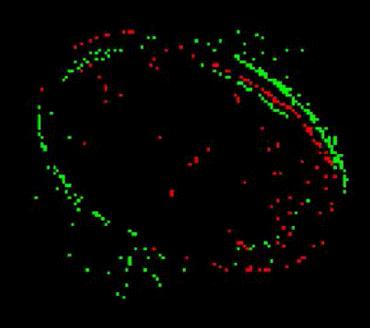
## Dynamic vision sensors (DVS)



Low time resolution, high redundancy

High time resolution, low redundancy

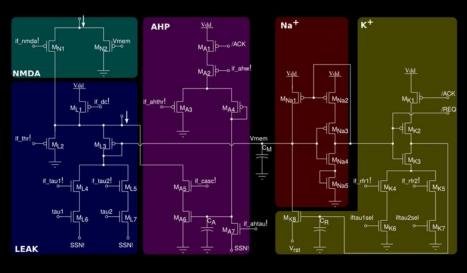
Source: INI & RPG Zurich



## Dynamic models of neurons and synapses

# $C\frac{dV}{dt} = -g_L(V - E_L) + g_L \Delta_T \exp(\frac{V - V_T}{\Delta_T}) - w + I$ $\tau_w \frac{dw}{dt} = a(V - E_L) - w$ $\int \text{Synaptic inputs } I_{j}(t)$ $\text{Input spikes } z_{j}(t)$ Input weights W $\text{Output spikes } z_{o}(t)$

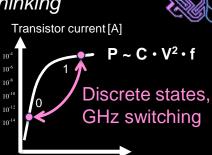
## Analog "silicon-neuron" circuit Conventional CMOS-transistor technology



## Information Processing Concepts

## Conventional computers

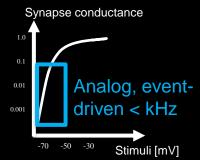
mimic logical and analytical thinking

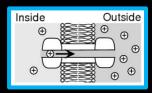


Gate voltage [V]

## Neuromorphic processors

mimic the senses, learning and perception





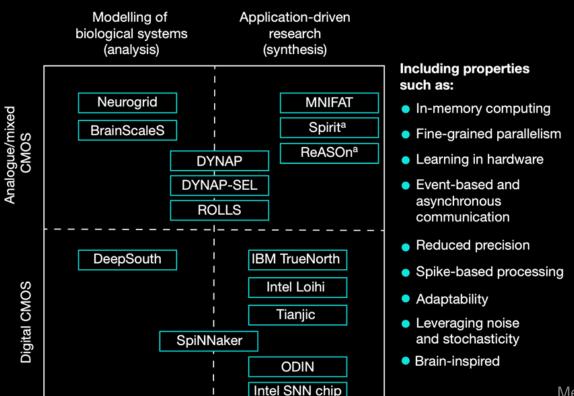
## Quantum processors

exploit quantum superpositions for probabilistic inference



Cell membrane ion diffusion

## **Neuromorphic Computing Systems**



Mehonic & Kenyon, Nature, 2022 DOI: 10.1038/s41586-021-04362-w

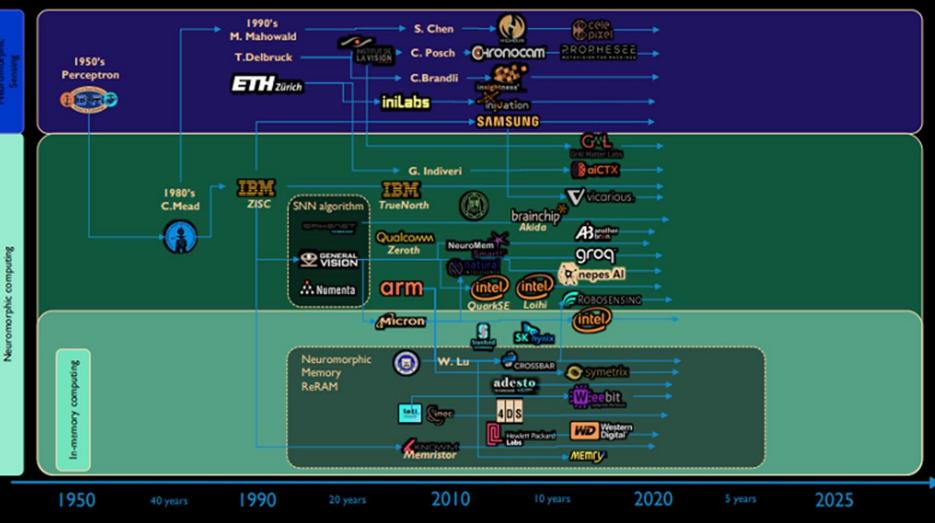
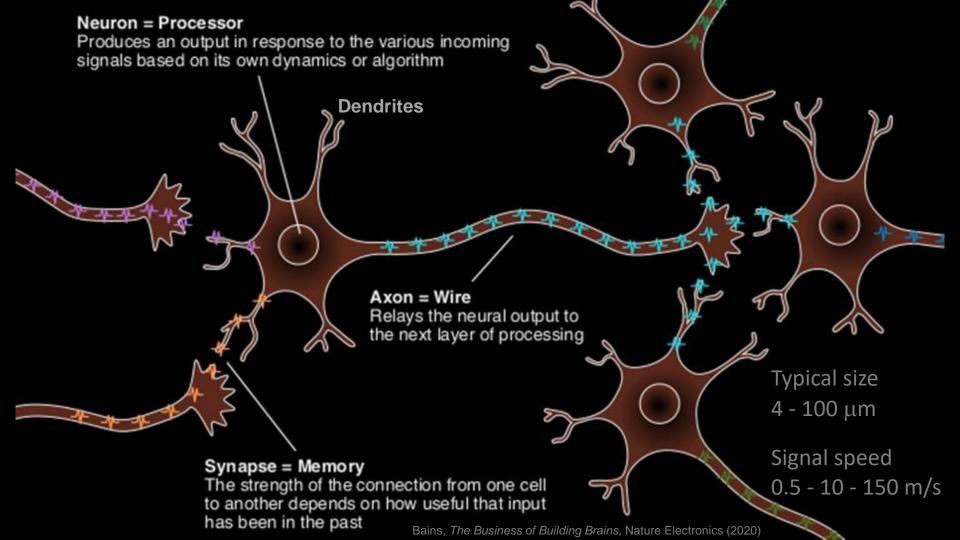


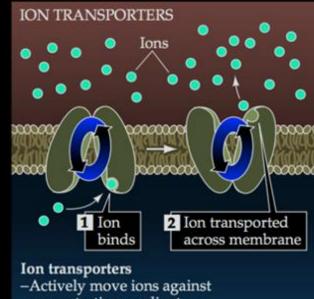
Image credit: Yolé

## **Energy-efficiency comparison**

	Human brain	Technology	Chip	Worse by
Housekeeping	4.8E-11	9.8E-07	RTX2070	2.0E+04
Resting potential	5.8E-11	3.8E-08	Spikey	6.6E+02
Action potential	2.0E-11	4.4E-10	Spikey	2.2E+01
Spike transmission	8.2E-15	1.1E-11	Spikey	1.3E+03
Single neuron	2.5E-10	1.5E-06	Spikey	1.3E+03
Full brain	2.1E+01	1.3E+05	Spikey	6.2E+03

## Neurons

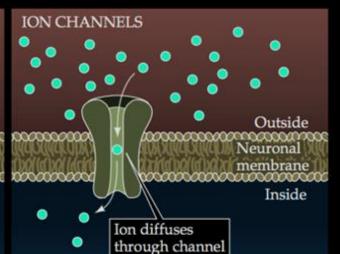




### concentration gradient

-Create ion concentration gradients

Image credit: Neuroscience, D. Purves et al.



#### Ion channels

- -Allow ions to diffuse down concentration gradient
- to certain ions

#### Nernst potential

$$\Delta u = \frac{kT}{q} \ln \frac{n_2}{n_1}$$

TABLE 2.1

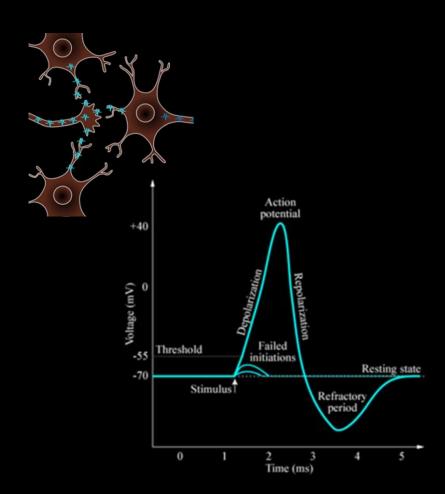
-Cause selective permeability Extracellular and Intracellular Ion Concentrations

	Concentration (mM)			
Ion	Intracellular	Extracellular		
Squid neuron				
Potassium (K+)	400	20		
Sodium (Na <sup>+</sup> )	50	440		
Chloride (Cl <sup>-</sup> )	40-150	560		
Calcium (Ca <sup>2+</sup> )	0.0001	10		
Mammalian neuron				
Potassium (K+)	140	5		
Sodium (Na+)	5–15	145		
Chloride (Cl-)	4–30	110		
Calcium (Ca <sup>2+</sup> )	0.0001	1–2		

## **Action potentials**

About -65 mV resting potential Surrounding bath ≡ 0 mV

Positive Na<sup>+</sup> feedback process if threshold voltage reached



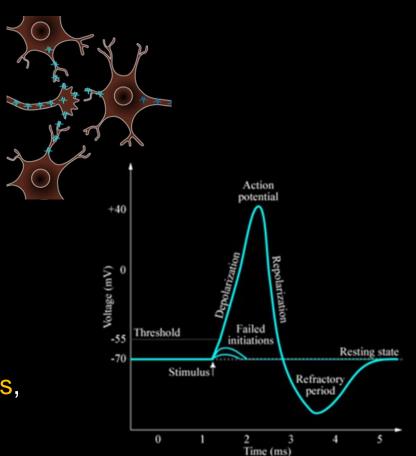
## Action potentials and "spike" approximation

About -65 mV resting potential Surrounding bath ≡ 0 mV

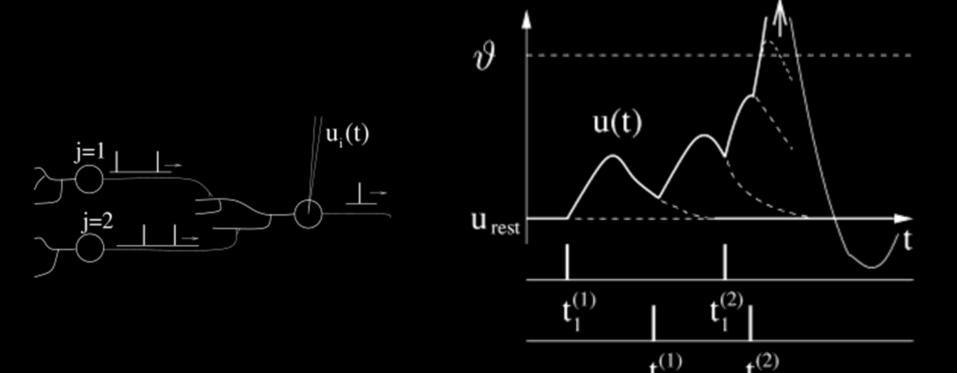
Positive Na+ feedback process if threshold voltage reached

~100 mV fluctuation for ~1 ms

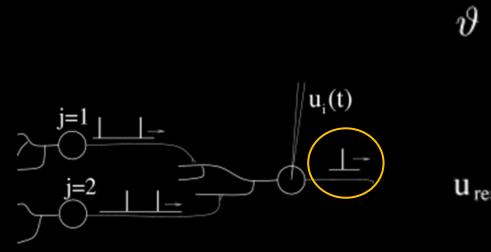
- Action potential
- Mostly stereotype events, spikes, characterized by the spike time



## Spiking Neural Networks (SNN)

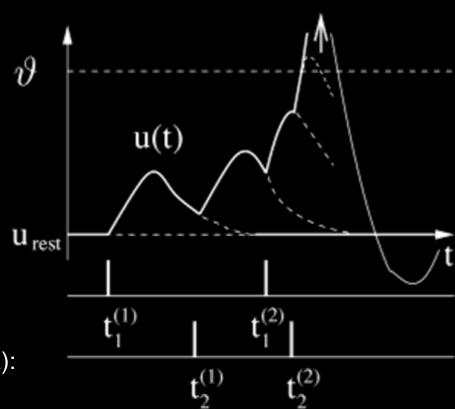


## **Spiking Neural Networks (SNN)**

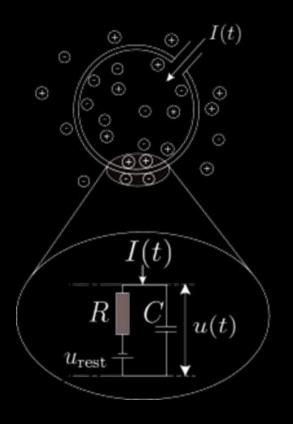




Address Event Representation (AER):
Address of source neuron
Spike time = Physical time



## Leaky Integrate and Fire (LIF) neuron model



$$\tau_m \frac{du}{dt} = u_{rest} - u(t) + RI(t)$$

Threshold condition:  $u(t) = \vartheta$ 

Then generate spike at t and set  $u = u_r < \vartheta$ 

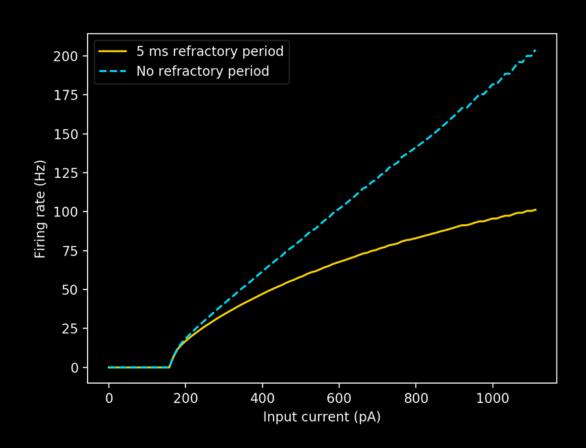
```
#!/usr/bin/env python
from brian2 import *
n = 100
                            # No. of neurons
duration = 2*second
                            # Simulation time
                            # Membrane resistance, Ohm
                            # Leakage time constant
                            # Leakage resting potential
                            # Threshold potential
# LIF equations, define RI = R*I(t) as a voltage for simplicity
# Define a population of LIF neurons
group = NeuronGroup(n, eqs, threshold='v > v thres',
            reset='v = E L', refractory=5*ms, method='linear')
# Define the initial value of the membrane potential
group.v = E L
# Each neuron is fed by a different current via the RI term
group.RI = '100*mV * i / (n-1)'
# Create monitors to enable plotting of variables
monitor1 = SpikeMonitor(group)
monitor2 = StateMonitor(group, 'v', record=True)
# Run the simulation
run(duration)
# Plot results
figure (figsize=(12,4))
subplot (121)
plot(group.RI*(1e-3/mV)/R/1e-12, monitor1.count / duration, '-b')
xlabel('Input current (pA)')
ylabel('Firing rate (Hz)')
subplot(122)
plot(monitor2.t, monitor2.v[15]*1e-3/mV, '-r', label='Neuron 15')
plot(monitor2.t, monitor2.v[20]*le-3/mV, '--q', label='Neuron 20')
legend()
xlabel('Time (s)')
ylabel('Membrane potential (mV)')
show()
```



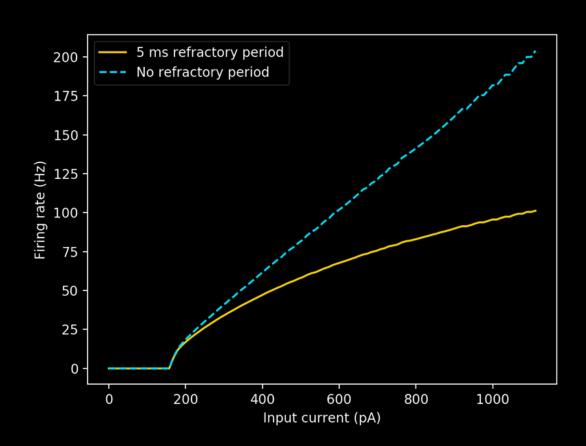
http://brian2.readthedocs.io

Brette, Goodman, Stimberg, 2016

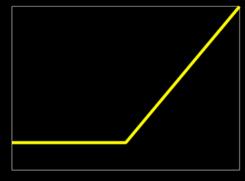
#### LIF model spike rate versus input current



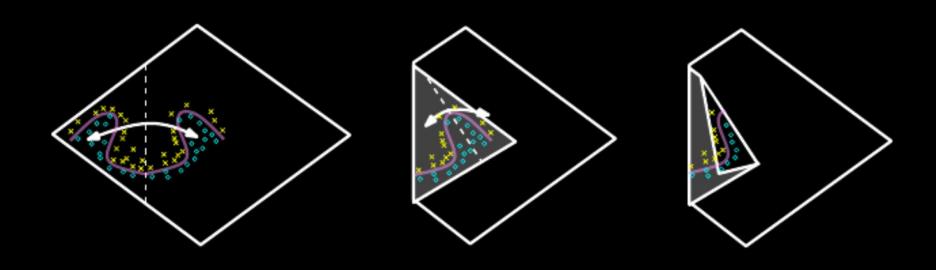
#### Similar to ReLU in quasistatic regime



#### **ReLU** activation in ANN

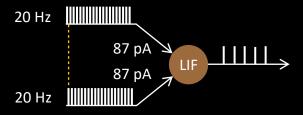


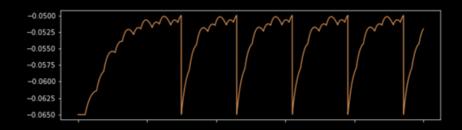
$$f(x) = \left\{egin{array}{ll} 0 & ext{for } x < 0 \ x & ext{for } x \geq 0 \end{array}
ight.$$



## LIF-model example

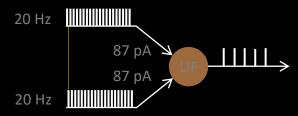
1) Neuron responds to 20Hz stimuli that is out of phase



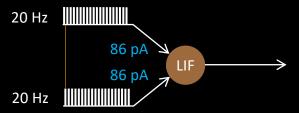


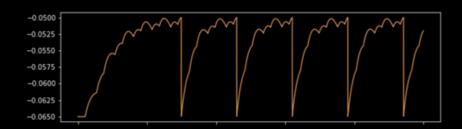
#### LIF-model example

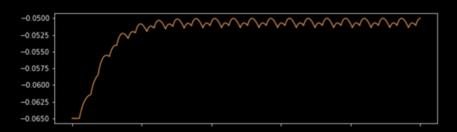
1) Neuron responds to 20Hz stimuli that is out of phase



2) Weights are lower. Neuron does not respond anymore

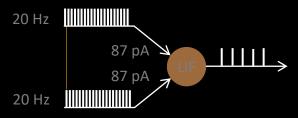


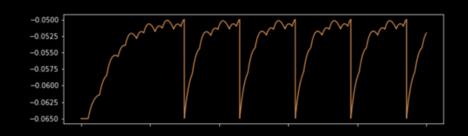




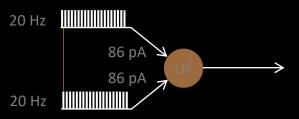
#### LIF-model example

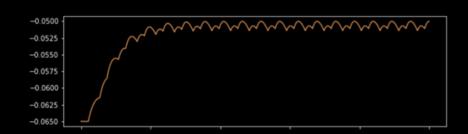
1) Neuron responds to 20Hz stimuli that is out of phase



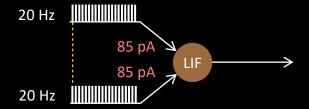


2) Weights are lower. Neuron does not respond anymore



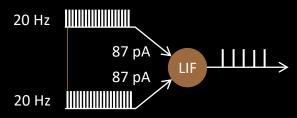


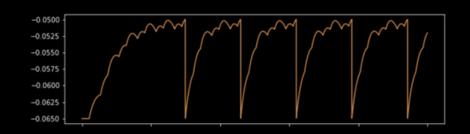
3) Lower weights more. Does it respond to 20Hz in-phase stimuli?



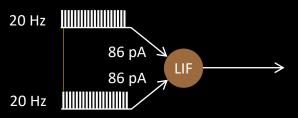
#### LIF-model example

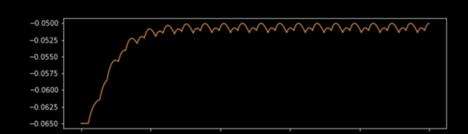
1) Neuron responds to 20Hz stimuli that is out of phase



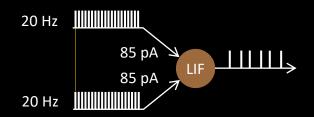


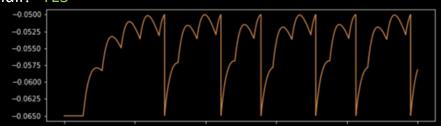
2) Weights are lower. Neuron does not respond anymore



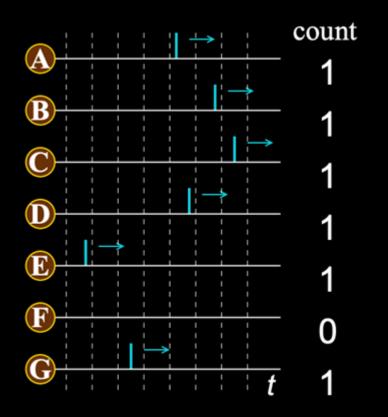


3) Lower weights more. Does it respond to 20Hz in-phase stimuli? -YES





#### Representational power of spike coding schemes?



Population rate code  $\sim \log_2(n+1)$  bits (inefficient)

Binary code ~n bits

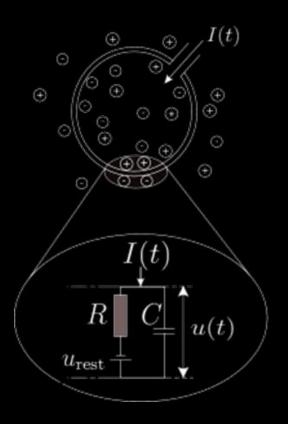
Timing code ~n log<sub>2</sub>(time precision)

Ordering code ~n log<sub>2</sub>(n)

•••

Neural coding in biology?

# Comment on end-to-end optimization of SNNs



#### Discretize the LIF model

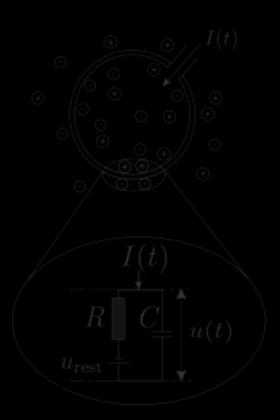
$$\tau_m \frac{du}{dt} = u_{rest} - u(t) + RI(t)$$

Threshold condition:  $u(t) = \vartheta$ 

Then generate spike at t and set  $u = u_r < \vartheta$ 

$$\frac{du}{dt} \approx \frac{u[t+1] - u[t]}{\Delta t}$$

$$u[t+1] = \alpha u[t] + \beta I[t] + \mu$$



#### Define spiking output, S

$$\frac{du}{dt} \approx \frac{u[t+1] - u[t]}{\Delta t}$$

$$u[t+1] = \alpha u[t] + \beta I[t] + \mu$$

$$S[t+1] = H(u[t+1] - u_{thr})$$

 $u \rightarrow u_{reset}$ 

A time-discretized feed-forward SNN can be implemented and optimized as a recurrent ANN

$$\frac{du}{dt} \approx \frac{u[t+1] - u[t]}{\Delta t}$$

$$S[t+1]$$

$$u[t+1] = \alpha u[t] + \beta I[t] + \mu$$

$$S[t+1] = H(u[t+1] - u_{thr})$$

$$u \to u_{reset}$$

$$I[t]$$

$$S[t+1]$$

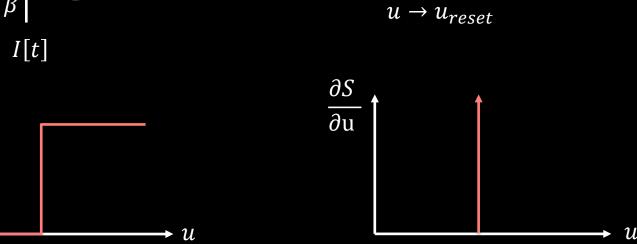
$$S \downarrow u$$

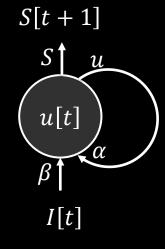
$$u[t]$$

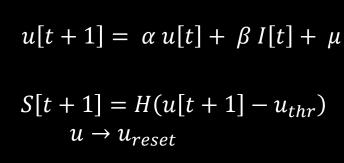
$$\beta \uparrow$$

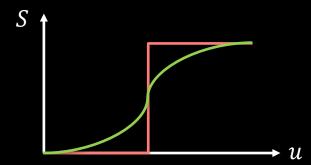
$$I[t]$$

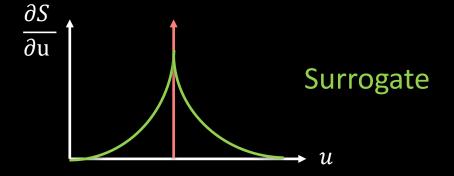
$$u[t+1] = \alpha u[t] + \beta I[t] + \mu$$
  
 $S[t+1] = H(u[t+1] - u_{thr})$ 



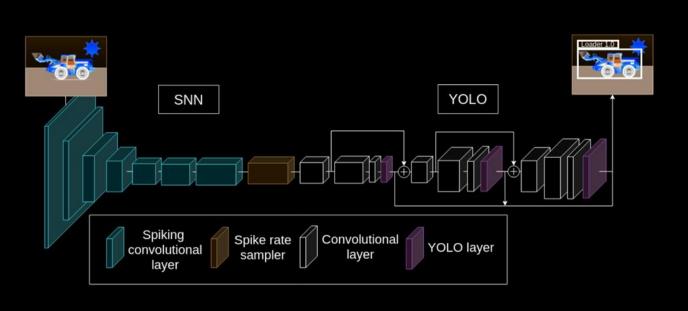


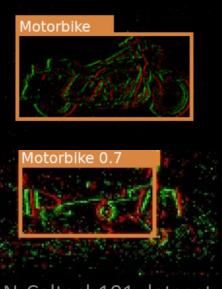






#### **Example: Optimization of Hybrid SNN-ANN**

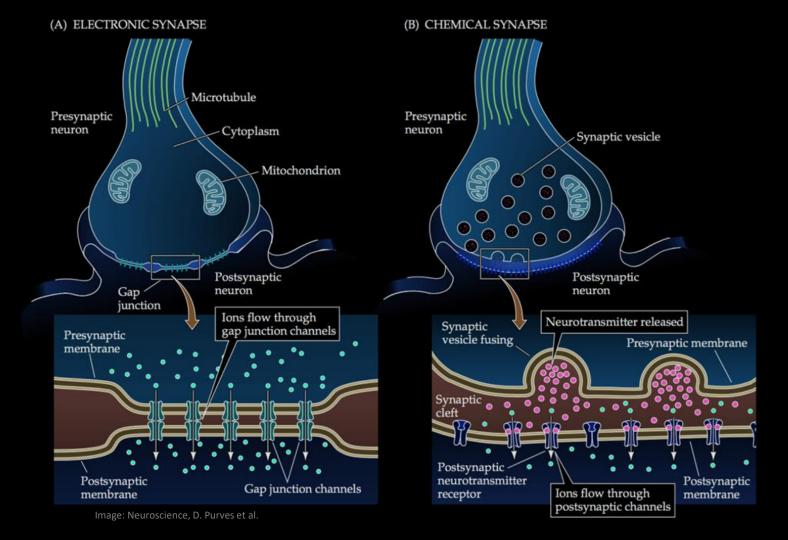


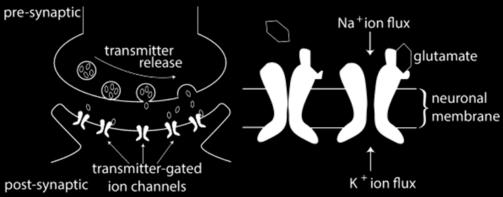


N-Caltech101 dataset

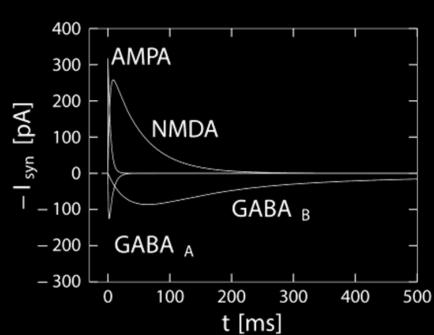
Olof Johansson, Training of Object Detection Spiking Neural Networks for Event-Based Vision, MSc thesis, LTU (2021) See also Kugele et al, Hybrid SNN-ANN: Energy-Efficient Classification and Object Detection for Event-Based Vision (January 2022)

## Synapses and learning





$$g_{\text{syn}}(t) = \sum_{f} \bar{g}_{\text{syn}} e^{-(t-t^{(f)})/\tau} \Theta(t-t^{(f)})$$



#### **Current-based synapse approximation**

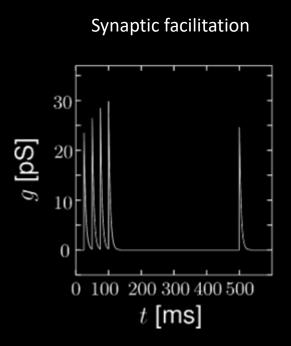
$$\tau_{syn} \frac{dI_{syn}}{dt} = -I_{syn}$$

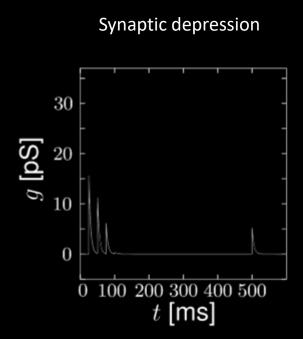
On presynaptic spike:  $I_{syn} \leftarrow I_{syn} + w$ 

$$I_{syn} \leftarrow I_{syn} + w$$

Where the weight, w, is positive for excitatory synapses and negative for inhibitory synapses.

#### Short-term plasticity (STP) of synapses





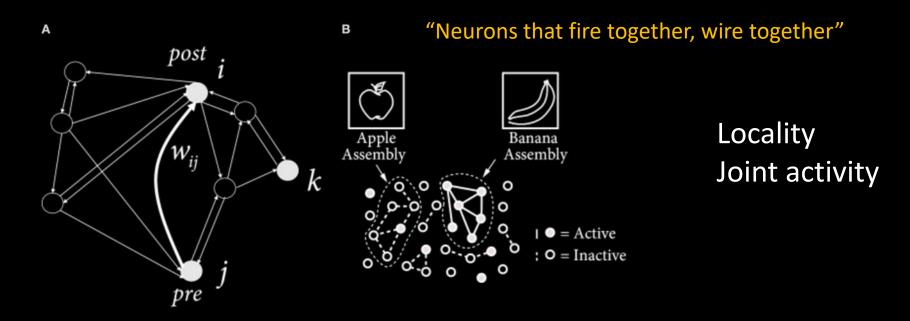
#### Long-term plasticity of synapses

Long-lasting changes of synaptic efficacies are neural correlates of learning and memory formation

Long-term potentiation (LTP)

Long-term depression (LTD)

## **Hebbian Learning**



$$\frac{\mathrm{d}}{\mathrm{d}} w_{ij} = F\left(w_{ij}; v_i, v_j\right). \tag{19.1}$$

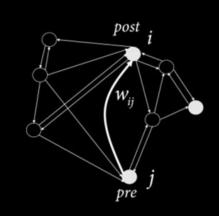
#### Stability of Hebbian learning

Hebb's postulate

$$\frac{\mathrm{d}}{\mathrm{d}t}w_{ij} = F\left(w_{ij}; v_i, v_j\right). \tag{19.1}$$

Taylor expansion of F

$$\begin{split} \frac{\mathrm{d}}{\mathrm{d} \ t} w_{ij} &= c_0 \left( w_{ij} \right) + c_1^{\ \mathrm{pre}} \ \left( w_{ij} \right) \ v_j + c_1^{\ \mathrm{post}} \ \left( w_{ij} \right) v_i + c_2^{\ \mathrm{pre}} \ \left( w_{ij} \right) \ v_j^2 \\ &+ c_2^{\ \mathrm{post}} \ \left( w_{ij} \right) \ v_i^2 + c_1^{\ \mathrm{corr}} \ \left( w_{ij} \right) \ v_i \ v_j + \mathcal{O} \left( v^3 \right) \ . \end{split}$$



(19.2)

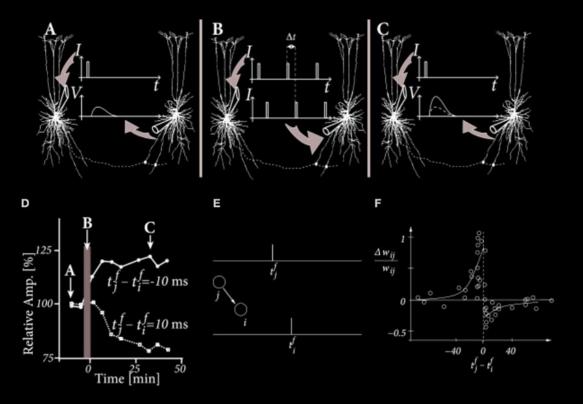
The naive learning rule, problematic since w<sub>ij</sub> cannot decrease

$$\frac{d}{dt} w_{ij} = c_{11}^{\text{corr}} v_i v_j. {19.3}$$

Stable learning rules by keeping additional terms, e.g., Oja's rule

$$\frac{\mathrm{d}}{\mathrm{d}t}w_{ij} = \gamma \left[ v_i \, v_j - w_{ij} \, v_i^2 \right] \tag{19.7}$$

#### Spike-timing-dependent plasticity (STDP)

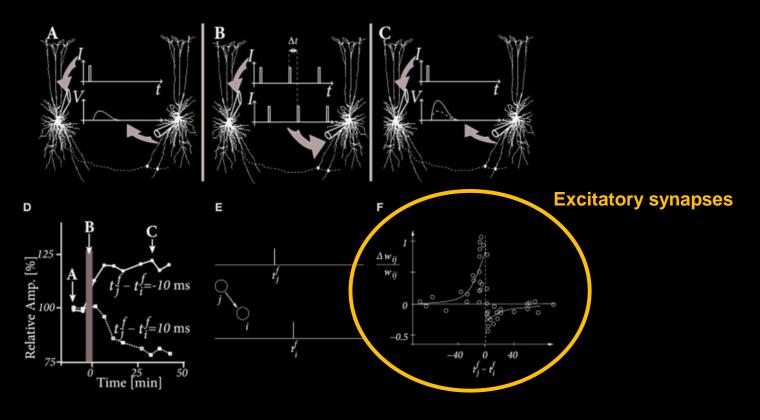


$$\Delta w_{+} = A_{+} (w) \cdot \exp(-|\Delta t|/\tau_{+}) \quad \text{at} \quad t_{\text{post}} \qquad \text{for} \quad t_{\text{pre}} < t_{\text{post}}$$

$$\Delta w_{-} = A_{-} (w) \cdot \exp(-|\Delta t|/\tau_{-}) \quad \text{at} \quad t_{\text{pre}} \qquad \text{for} \quad t_{\text{pre}} > t_{\text{post}}$$

(19.10)

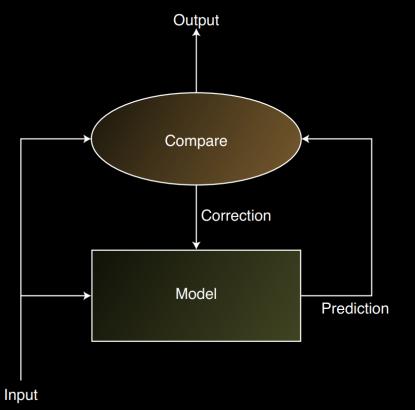
#### Spike-timing-dependent plasticity (STDP)



$$\Delta w_{+} = A_{+} (w) \cdot \exp(-|\Delta t|/\tau_{+}) \quad \text{at} \quad t_{\text{post}} \quad \text{for} \quad t_{\text{pre}} < t_{\text{post}}$$

$$\Delta w_{-} = A_{-} (w) \cdot \exp(-|\Delta t|/\tau_{-}) \quad \text{at} \quad t_{\text{pre}} \quad \text{for} \quad t_{\text{pre}} > t_{\text{post}} \quad (19.10)$$

#### Next steps?



Online learning (backprop on stored data is too resource intensive)

Dendrocentric learning (point neuron approximation is too simplistic)

Inhibitory and excitatory based learning

Image: Carver Mead, How we created neuromorphic engineering, Nature Electronics (2020)

## Examples, work on DYNAP-SE

### **DYNAP-SE** mixed-signal processor

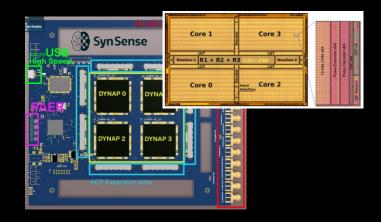
4 chips each having

1k neurons (AdEx)

64k dynamic synapses (4 types, DPI)

Programmable connectivity via CAM

25 bias-parameters/core (4 cores/chip)



### **DYNAP-SE** mixed-signal processor

4 chips each having

1k neurons (AdEx)

64k dynamic synapses (4 types, DPI)

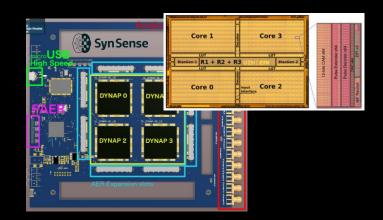
Programmable connectivity via CAM

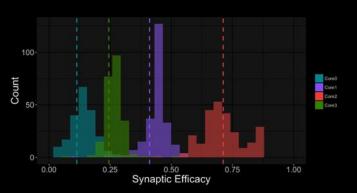
25 bias-parameters/core (4 cores/chip)

Analog neuron & synapse circuits

→ distributions of parameter values

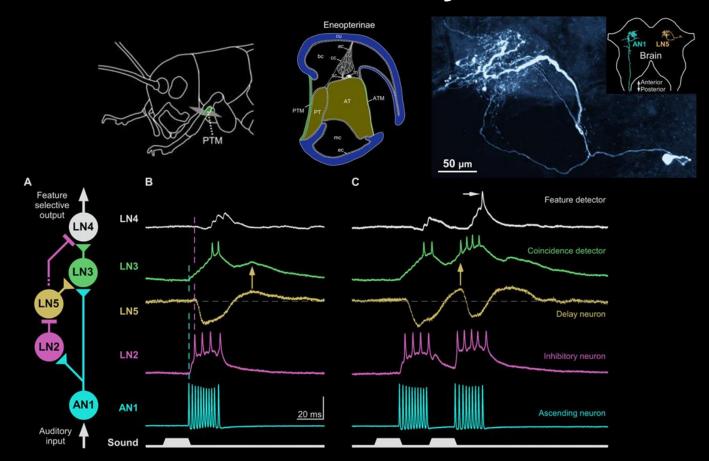
Digital spike-event communication





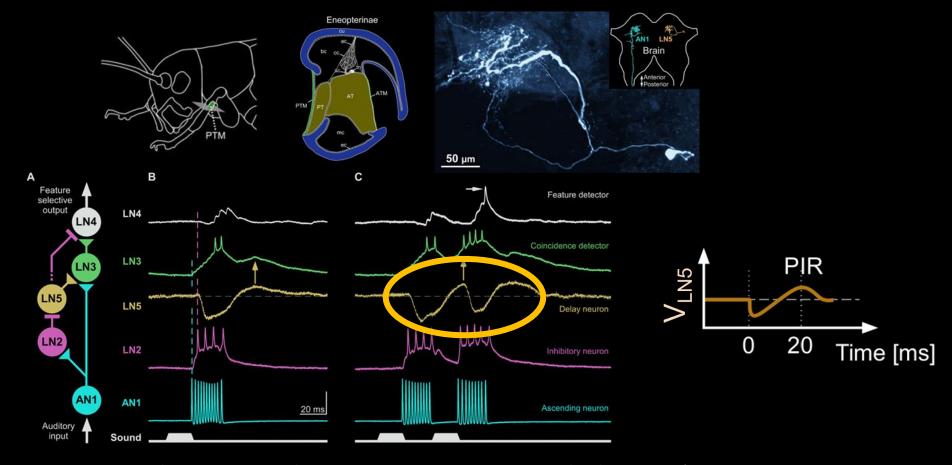
Moradi, Qiao, Stefanini, Indiveri (2018). doi: 10.1109/TBCAS.2017.2759700 Chicca, Stefanini, Bartolozzi, Indiveri (2014). doi: 10.1109/JPROC.2014.2313954

#### Cricket auditory feature detector

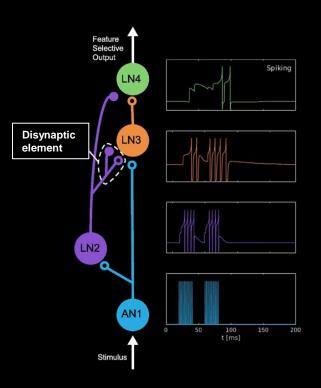


www.youtube.com/watch?v=Pb8vhbhLwBM

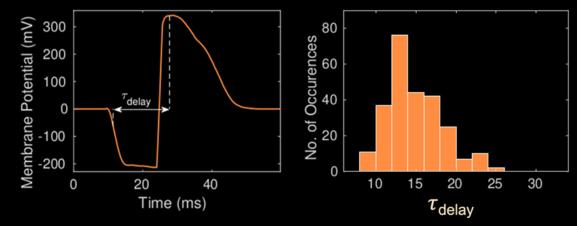
## Cricket auditory feature detector



#### Configuration of cricket circuit in DYNAP-SE

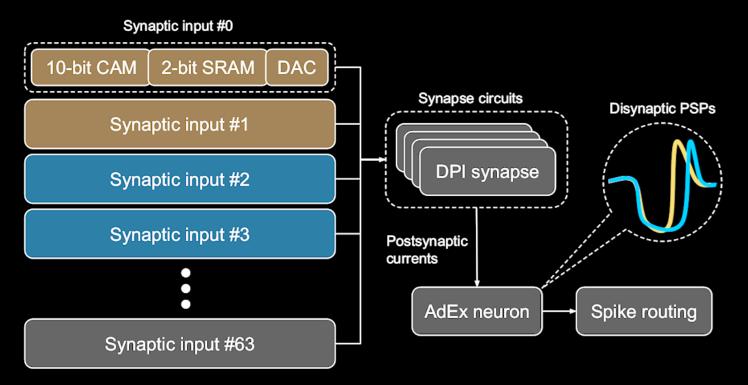


Dynamics of non-spiking LN5 approximated with two synapses (disynaptic element)



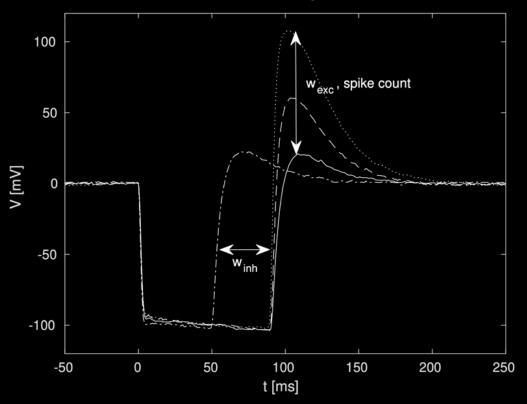
Balance of excitatory and inhibitory postsynaptic currents (via bias tuning & Hebbian learning protocol)

#### Disynaptic configuration in DYNAP-SE



Different PSPs due to DAC device-to-device mismatch

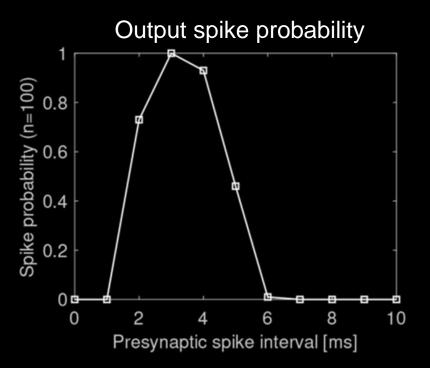
#### Control of PSP via disynaptic parameters



#### Spike-pair selectivity with one neuron

Single neuron with two disynaptic inputs

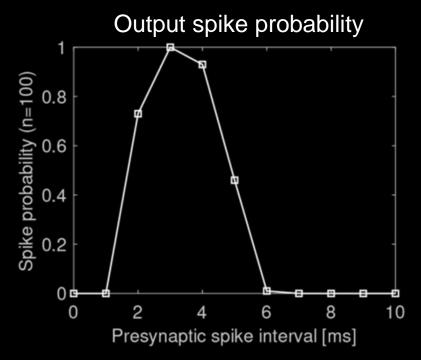




#### Spike-pair selectivity with one neuron

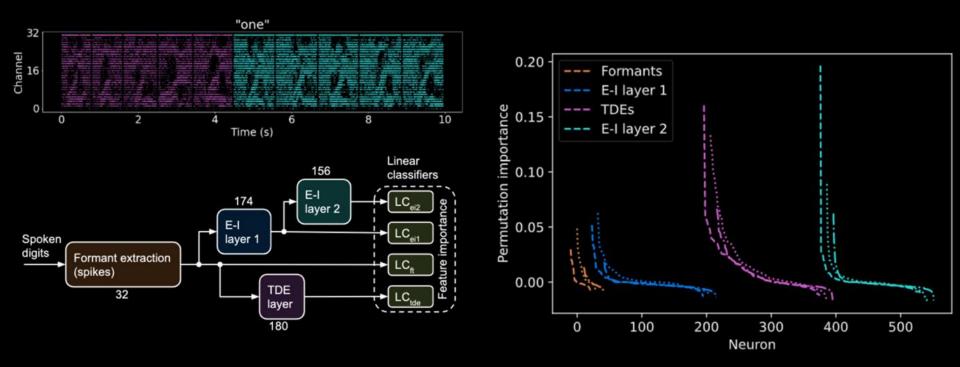
Single neuron with two disynaptic inputs





Sandin & Nilsson, Frontiers in Neuroscience (2020). doi: 10.3389/fnins.2020.00150
For spike triplets: Nilsson, Liwicki and Sandin, IJCNN (2020). doi: 10.1109/IJCNN48605.2020.9207210
More general: Nilsson, Liwicki and Sandin, ICONS (2022)

### **Keyword Spotting with Few (~10) Neurons**



Nilsson et al, A Comparison of Temporal Encoders for Neuromorphic Keyword Spotting with Few Neurons, IJCNN 2023; arXiv:2301.09962

## Work in progress

#### Optimize vibration monitoring system design

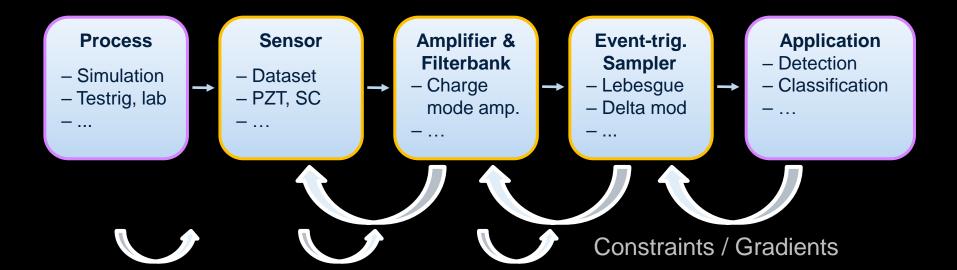
Modular software for optimization of the sensor, filterbank, amplifier and event-triggered sampler



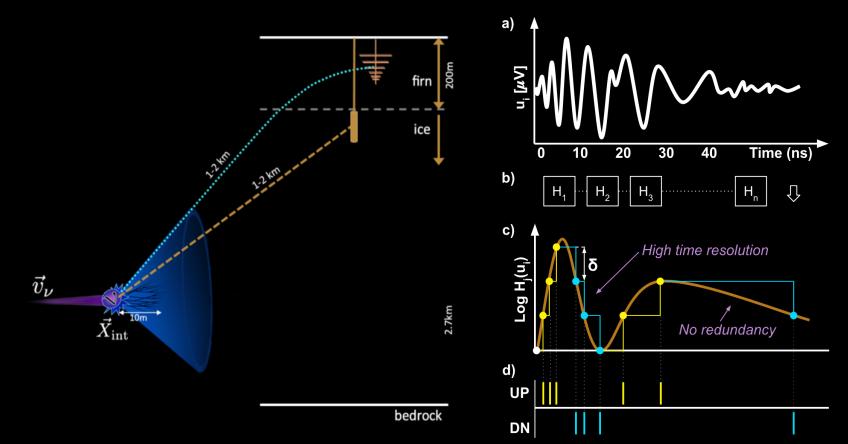


Daniel

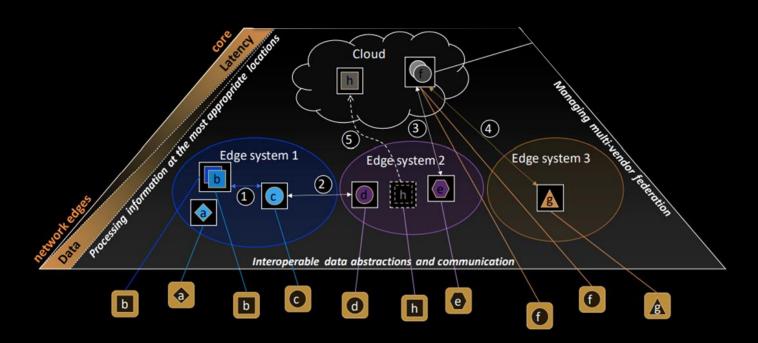
Ashwani



# Proposal with Christian Glaser (Uppsala) & Tommaso: Improving radio-detection methods for neutrino astronomy



#### Cloud-to-Edge Computing Continuum Optimization



Proposal under review

Related paper: <a href="https://doi.org/10.3389/fnins.2023.1074439">https://doi.org/10.3389/fnins.2023.1074439</a>



#### **Acknowledgements**

STINT (IG2011-2025)

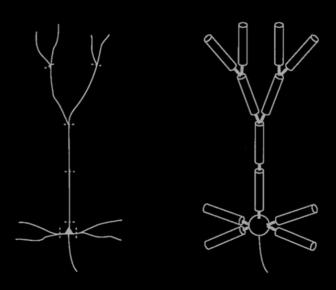
The Kempe Foundations (SMK1429, JCK-1809, SMK21-0046)

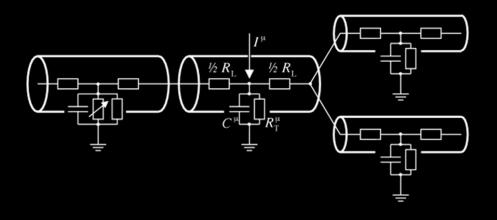
ECSEL JU (Arrowhead Tools, 737459)

LTU Jubilee Fund & Creaternity

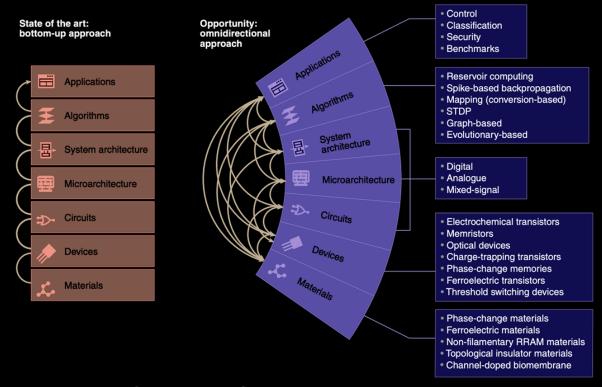
CapoCaccia Neuromorphic Engineering Workshop

### Dendrites (compartment models), AdEx, ...



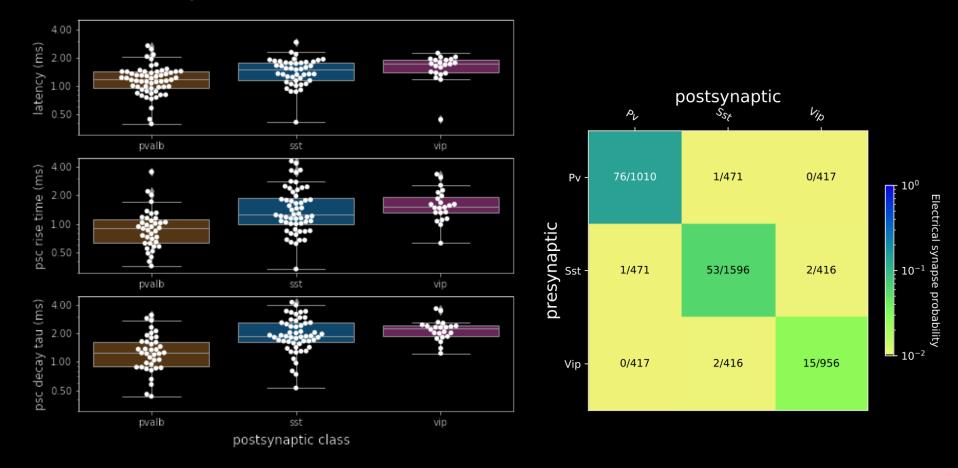


#### **Neuromorphic Compute Stack Co-design**



Catherine D. Schuman et al., Nature Computational Science, 2022; https://doi.org/10.1038/s43588-021-00184-y

#### Synaptic Physiology Dataset, three inhibitory interneuron subclasses (Pv, Sst, and Vip)



# Idea of Tommaso Dorigo: High-Granularity Hadron Calorimeters with Embedded Neuromorphic Computing

Charged pions, kaons, and protons constitute the bulk of the hadrons flowing into a hadron calorimeter

Being able to distinguish them would bring in very large gains:

- to flavour tagging (killer app: H→ss at a future collider, where you need to tag the fast kaon from s hadronization)
- to energy reconstruction (improved through particle flow techniques)
- to boosted-jet tagging (from improved inner structure reconstruction of jet cores)

