

# Self-driving Telescope Schedules: A Framework for Training Reinforcement Learning Agents based on Telescope Data

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"Python in HEP" Users Workshop (online)

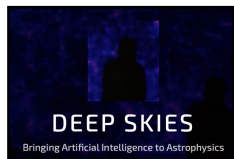
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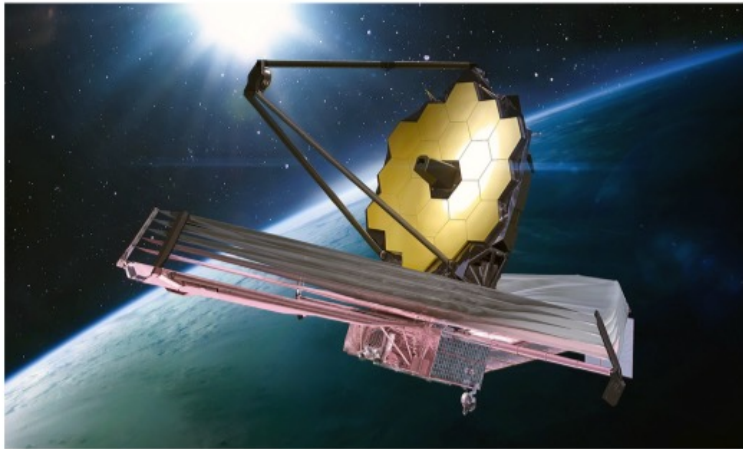


# Self-driving telescopes could revolutionize astronomy

An autonomous telescope, unburdened by human biases and complications, could be able to discover solutions we've been missing this whole time.

New telescopes such as JWST and LSST have been designed and engineered in order to capture vast amounts of data. These telescopes are the possible targets of this project.

What if we could optimize the potential of telescopes as sky watchers?



(a) An image of the James Webb Space Telescope (JWST).

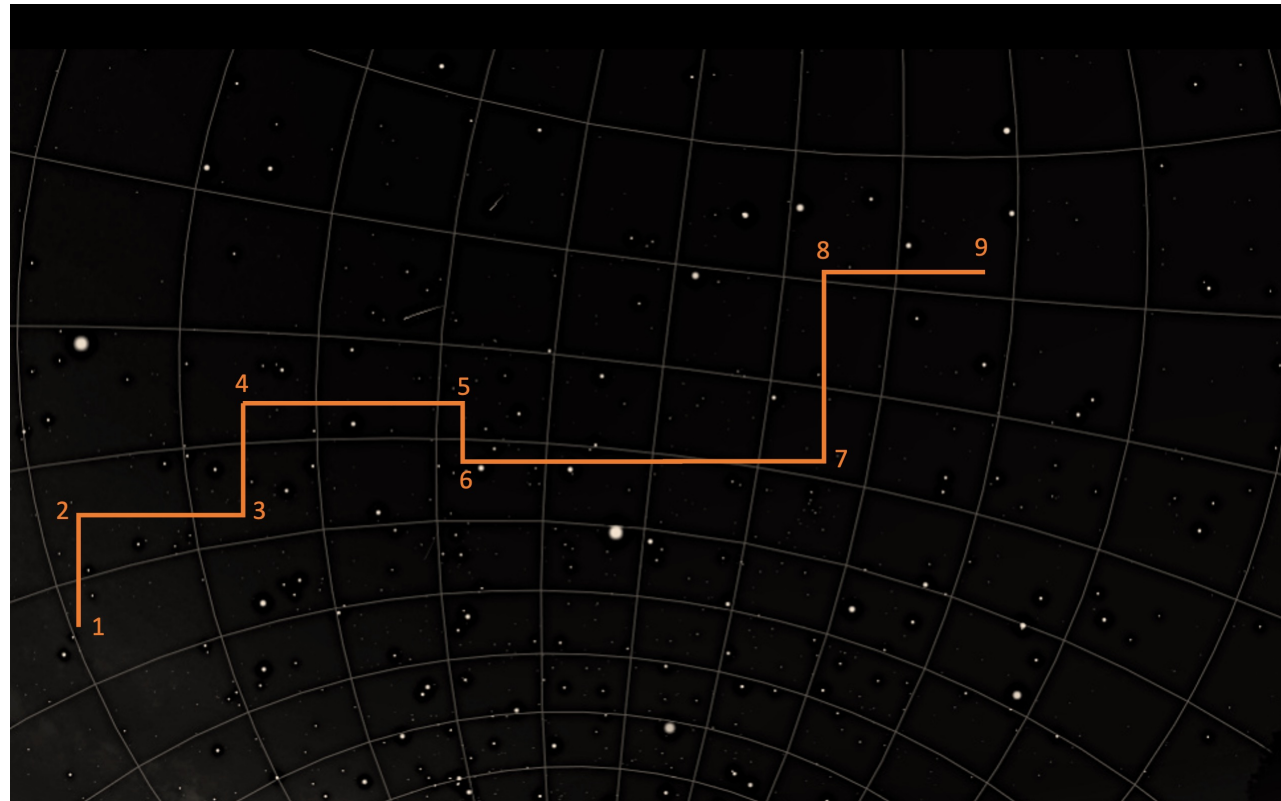


(b) An image of the Large Synoptic Survey Telescope (LSST).

# Start from the optimization of a sequential schedule

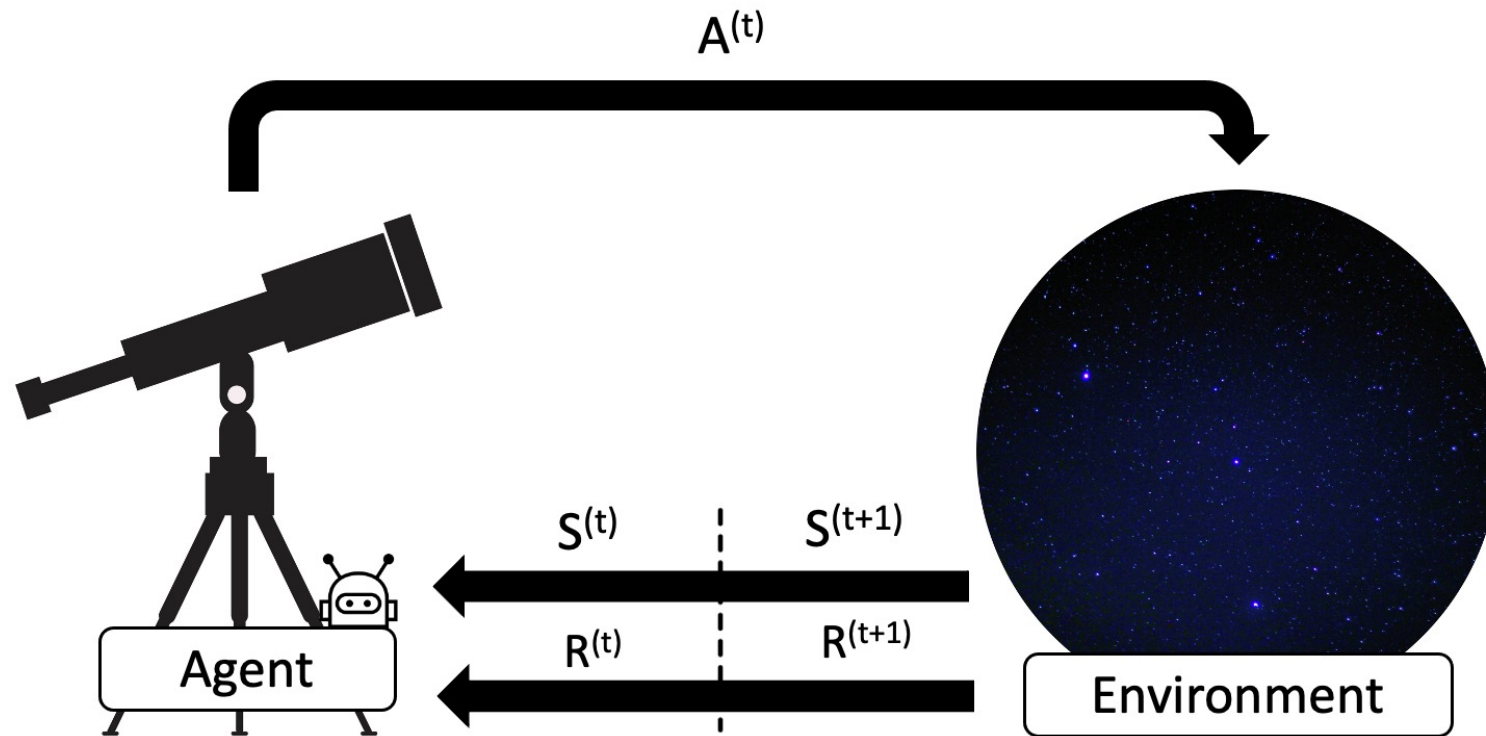
The journey toward achieving this vision begins with the crucial task of scheduling observations, a well-known NP-hard problem.

Given a potential set of sites from which to gather data, the optimization of telescope resources is crucial.

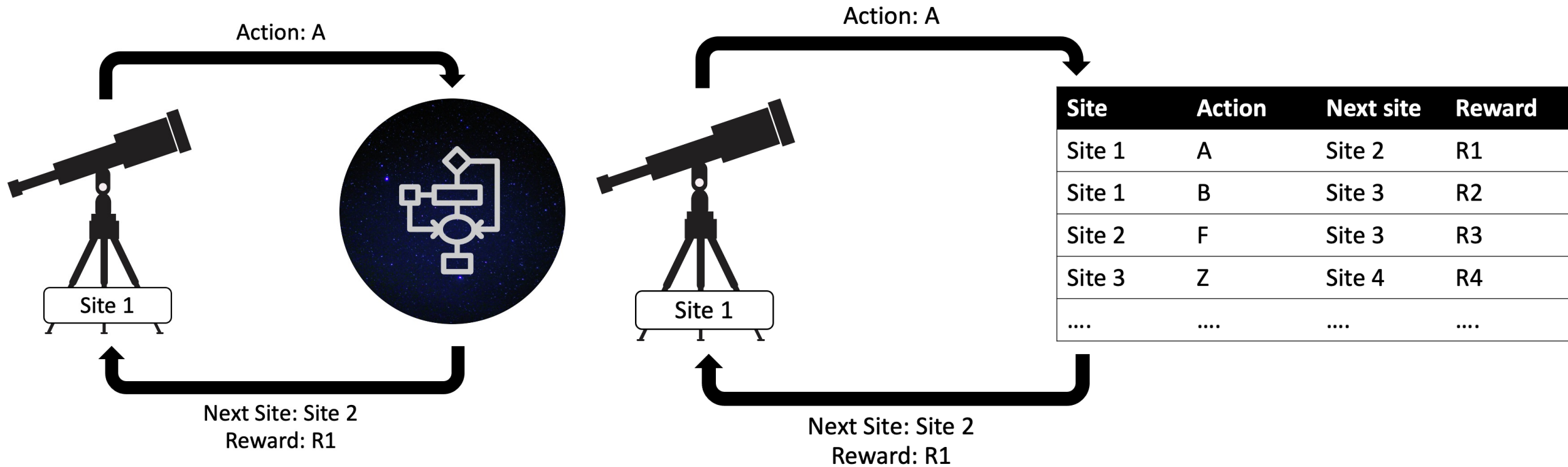


# Reinforcement Learning

Reinforcement Learning (RL) is a paradigm of Machine Learning used to train an autonomous agent able to behave optimally in a given environment.



# Reinforcement Learning: Online vs Offline



# Environment overview

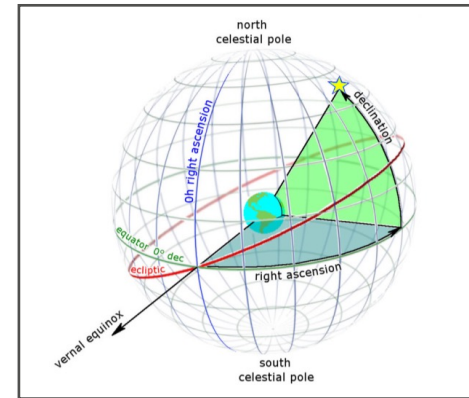
ID	az	alt	....	sun_ ra	sun_ decl	....	moon_ airmas s	moon _ angle	sky_ mag
ID_1	10.01	31.03	....	64.77	21.41	....	5.89	112.2	18.91
ID_2	10.01	31.03	....	64.77	21.41	....	5.89	112.2	18.91
....	....	....	....	....	....	....	....	....	....

State space

- Metrics related to the telescope, the moon, the sky, and the sun
- Variables that can be sensed from the environment

Right Ascension	Declination
79.0	324.0
24.0	221.0
....	....

Action space



T-Effective
38
29
....

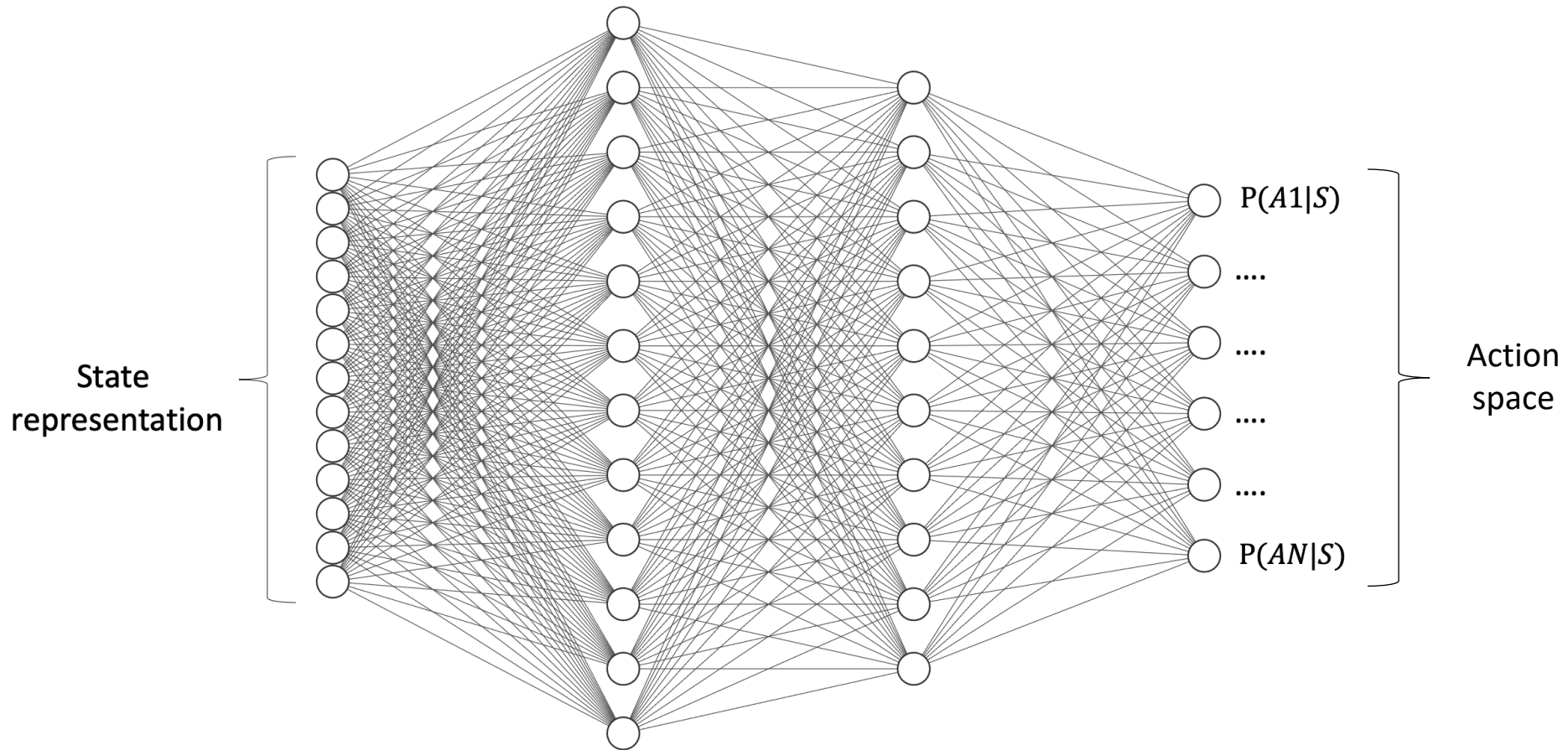
Reward

- A measure of the depth of the image
- It measures the quality of an observation

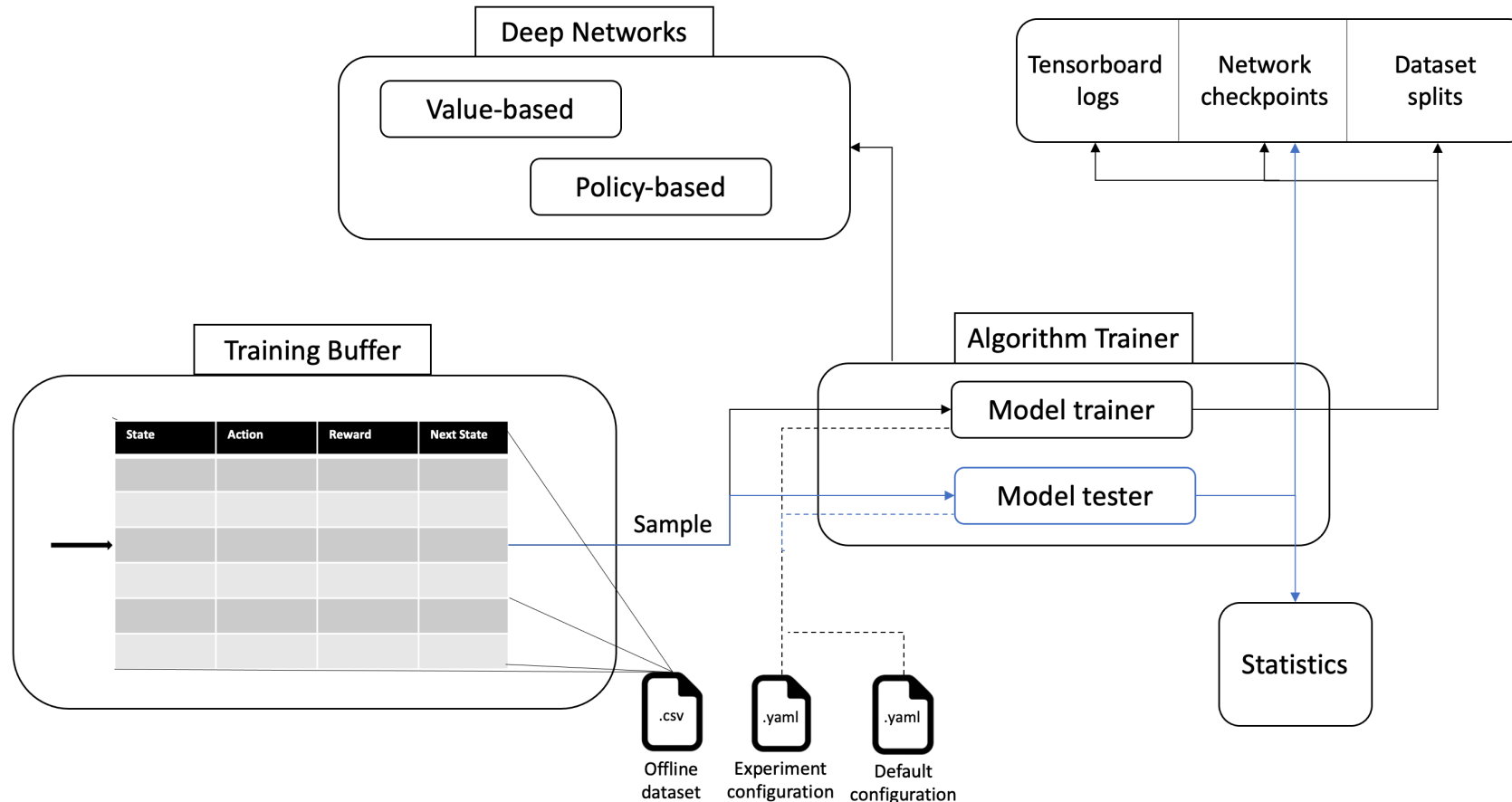
New State
ID_29
ID_46
....

Next state

# Deep Neural Network as Function Approximator



# Framework for training/testing RL agents on any offline dataset





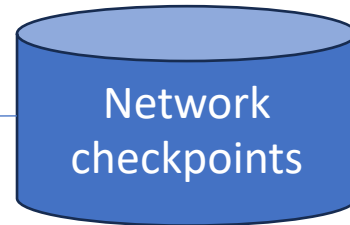
# Framework Command Line Interface (CLI): Examples of use

```
> python model_train.py -a a2c --dataset new_dataset.csv -mni 1000 ...
```

Algorithm

Dataset 

Number of iterations



```
> python model_test.py -a a2c -f PATH/file.dat -data test.csv ...
```

Algorithm

Checkpoint path

Test set 

# Features & Algorithms supported

## Algorithms available:

- Deep Q-Network (DQN) and modifications
- REINFORCE method
- Actor-Critic (A2C) method
- Covariance Matrix Adaptation Evolutionary Strategy (CMA-ES)
- Genetic Algorithm\*

\*based on the paper "Deep neuroevolution: Genetic algorithms are a competitive alternative for training DNNs for RL" by F. P. Such et al.

Algorithm implementations used are based on the PyTorch AgentNet (PTAN) library!

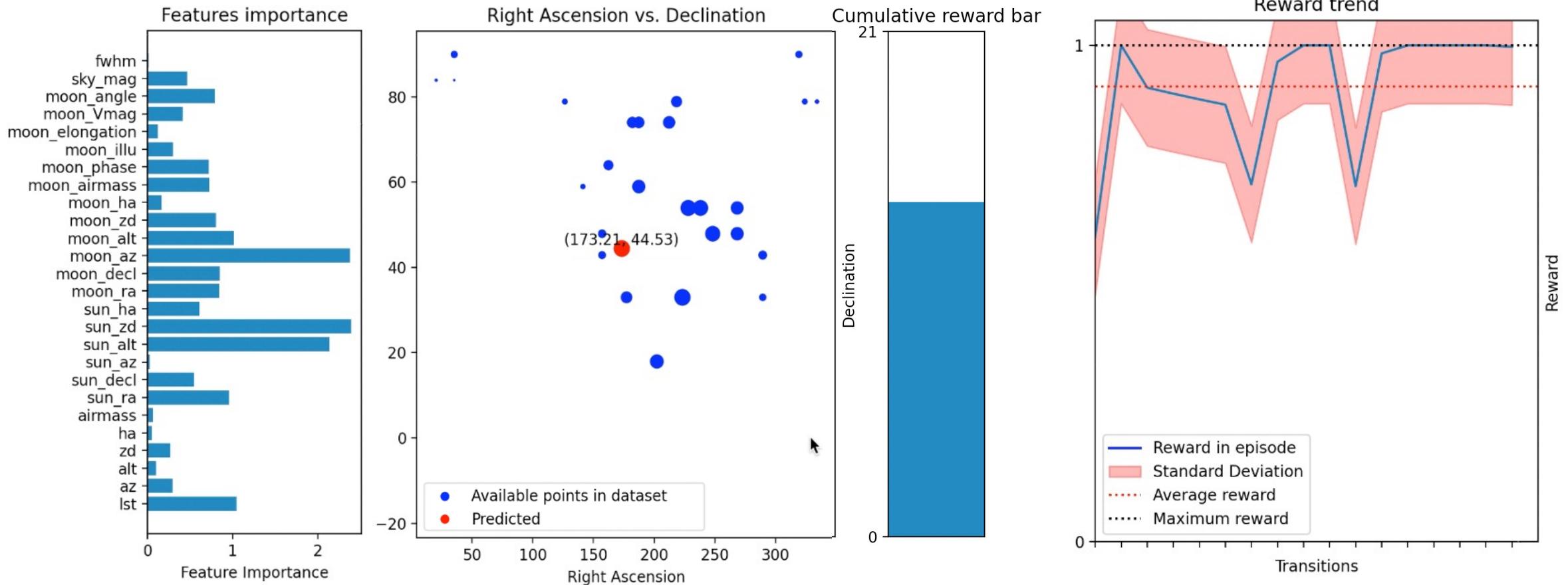
■ Value-based methods

■ Policy-based methods

## Features supported:

- Splitting strategies by Modified Julian Date (MJD) such as the Holdout method and K-Fold Cross Validation (K-Fold CV)
- Normalization strategies
- State space reduction (Multi-collinearity reduction, PCA, etc.)
- Hyper-parameters optimization based on the Optuna library
- Reward penalization strategy to trade-off quality of observations and the variety of the data gathered
- ....

# Rendering: Visualization and Interpretability



# Conclusions & Future work

- Developed a framework for training RL agents based on any offline dataset (soon available on Github)
- Results on the SEO simulation dataset demonstrated how RL could optimize telescope scheduling observations
  
- An online environment could increase the amount of data available for training
- A continuous action space may push the boundaries of the problem to a higher level



Stone Edge Observatory (SEO), a privately owned observatory in California