

# **Rotational mechanism option status**

Laura Hannemann

14 February 2023

**Research Question** 



 $\rightarrow$ Is the fast wire scanner bakeable?

 $\rightarrow$ Under which conditions is it bakeable?







- → Test wire scanner parameters in its intended environment
- → Quantify change in parameters with bake-out

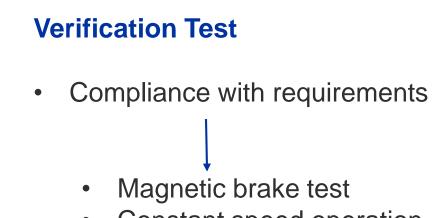




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- No additional sensors required
- Read out of control parameters



- Constant speed operation
- Calibration
- Electrical Insulation Test

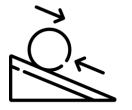
#### **Validation Test**

Scans

Perform indented purpose in desired
 environment

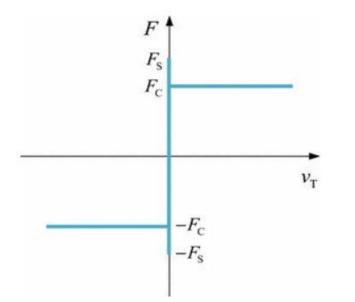


## **Friction Torque Studies**



**Expectation: Dry Coulomb friction** 

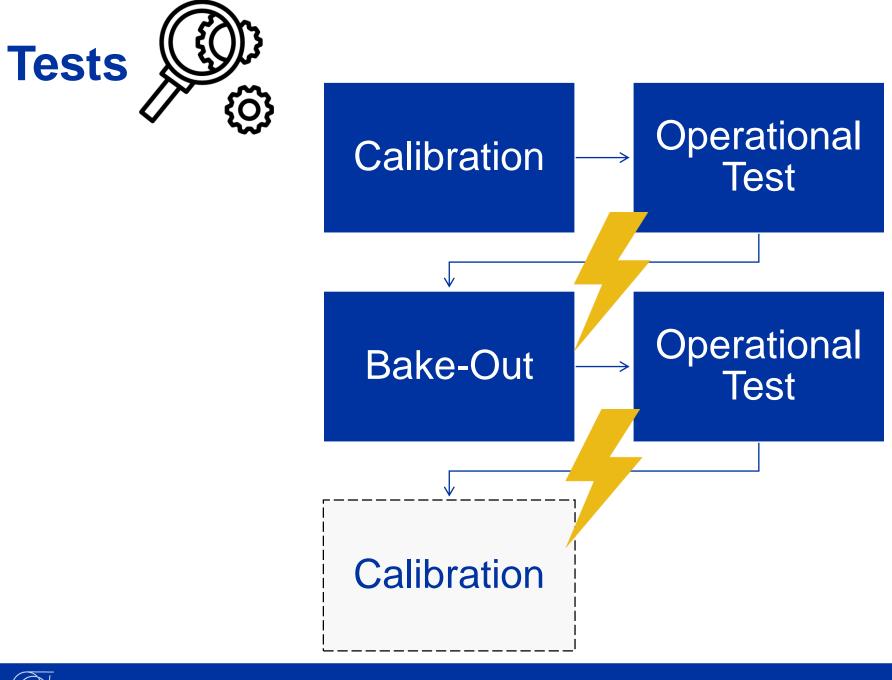
- Static friction at zero speed
- Dynamic friction at non zero speed



- No lubrication
- Increased friction after bake-out

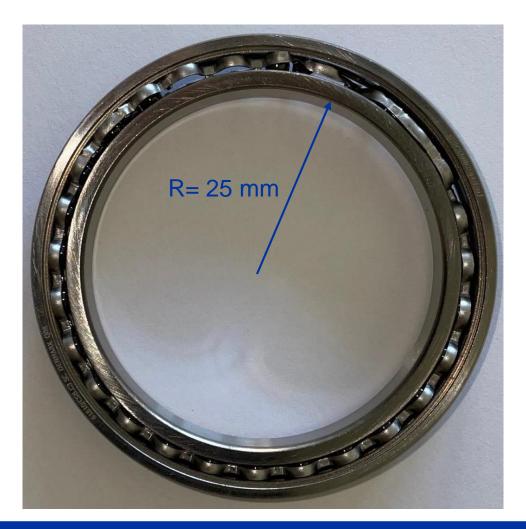
Before bake-out	After bake-out
$T_{\rm fr_{st}} = 150.27 Nmm$	$T_{\rm fr_{st_{bakeout}}} = 535.05Nmm$
	$\begin{array}{l} T_{\rm fr_{dyn_{bakeout}}} = \\ 540.97 Nmm \end{array}$







### **Bearing Failures**



At constant speed operation  $\rightarrow$  cage rupture



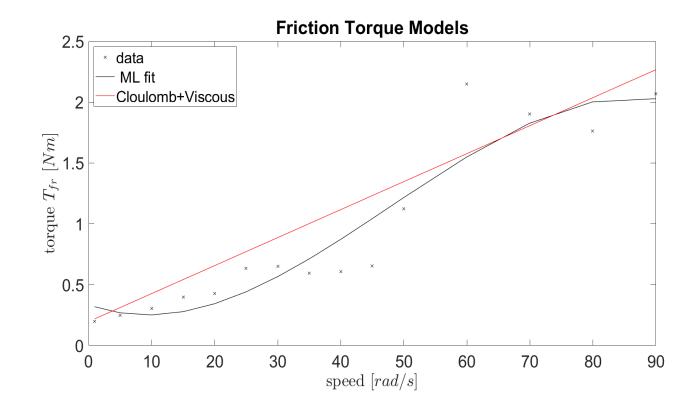
## **Friction Torque Studies**



**Test Results before Bake-out:** 

- Linear regression model
- Linear dynamic friction model:

$$T_{fr} = F_C + \mu_v \cdot \omega = 0.197 Nm + 0.023 \frac{Nm}{\frac{rad}{s}} \cdot \omega$$





# Friction Torque Studies



**Test Results after Bake-out:** 

Friction Torque Model Post Bake-Out 0.8 **Static and dynamic friction:** data ML fit 0.75  $T_{fr} = \begin{cases} 0.79 \ Nm & for \ \omega < 0.3 \frac{rad}{s} & [I]_{L}^{\infty} 0.65 \\ 0.49 \ Nm & for \ \omega > 0.3 \frac{rad}{s} & [I]_{L}^{\infty} 0.65 \\ 0.55 \end{bmatrix}$ 0.7 0.5 0.45 0.2 0.9 0 0.1 0.3 0.4 0.5 0.6 0.7 0.8 speed [rad/s]





Test Results after Bake-out:

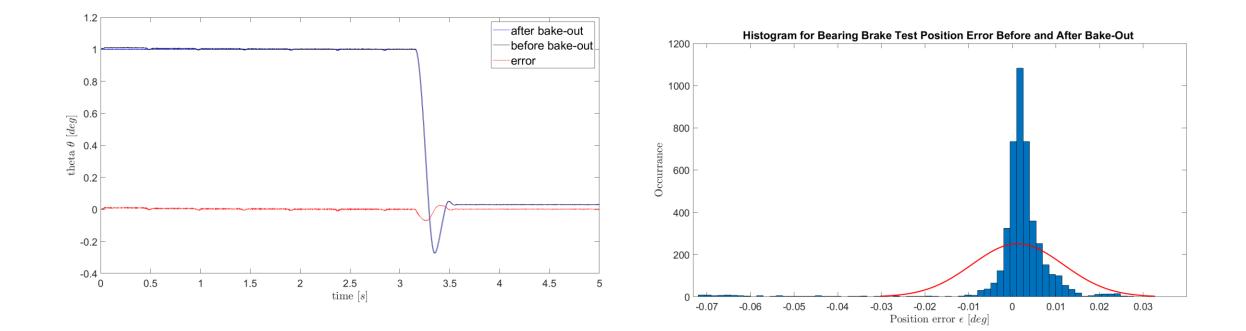
friction torque post bake-out 2.5 Speed dependent dynamic friction linear data model Coulomb & viscous 2 torque  $T_{fr} \ [Nm]$  - c . c  $T_{fr} = 0.253Nm + 0.018 \frac{Nm}{\underline{rad}} \cdot \omega$ 0.5 0 15 20 25 30 35 40 45 50 55 60 65



speed [rad/s]

### **Results Nominal Bearings**

# Magnetic Brake Restoring Test Position



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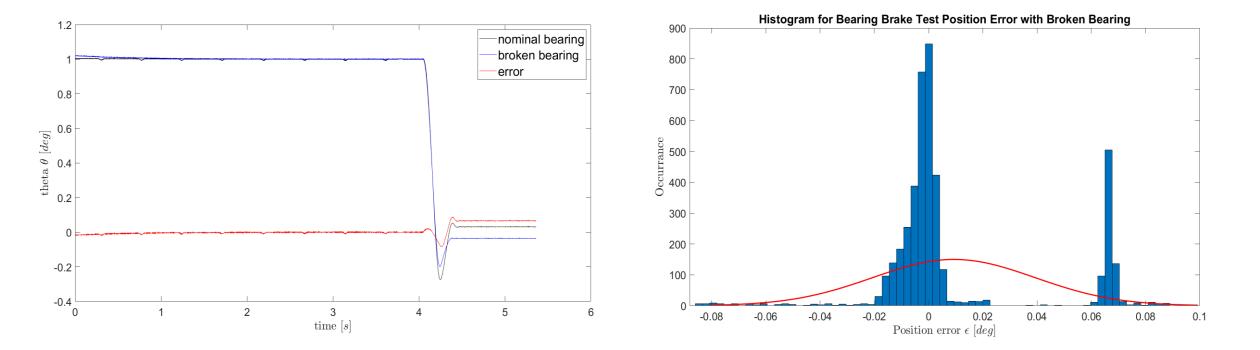
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**Error Histogram** 

### **Results Broken Bearings**

#### Magnetic Brake Restoring Test Position



#### CERN

**Error Histogram** 



- Wire scanner is operational after bake-out
- Successfully conducted tests:
  - Insulation resistance
  - Calibration
  - Magnetic brake restoring mechanism
  - Scan operation
  - Friction torque measurements
- Wire scanner can operate with constant speed
- Ball bearing cages are source of failure
- Friction torque in current system is speed dependent





- No clearance issues according to manufacturer
- Inspection for wear in the racers
- Possibility to add solid lubricant



## **Solid Lubricants**

#### **Requirements:**

- UHV compability  $(10^{-10}mbar)$
- High temperature resistance
- Radiation resistance
- Durability
- Chemical cleaning approved



### **Solid Lubricants**

- Soft metal coatings: lead, gold, silver
- Lamellar solids: molybdenum disulfide (MoS2) and tungsten disulfide (WS2)
- Polymers: PTFE and PEEK



#### **Soft metals**

• Lower outgassing rate than MoS2

Ion-plated lead	<ul> <li>Used in space applications</li> <li>Limited life in ambient conditions due to oxidation</li> </ul>
Ion-plated silver	<ul> <li>Good electrical conductor.</li> <li>Lowest mechanically stimulated outgassing rates reported</li> <li>Better wear life in high load conditions than led or gold</li> <li>Frequently used in rotating anode X-ray tubes.</li> </ul>
Ion-plated gold	<ul><li>Best conductor</li><li>Non-reactive metal</li></ul>

https://edms.cern.ch/ui/file/976275/1/Bearings\_in\_vacuum.pdf



## Molybdenum-Disulfide

- ✓ Vacuum acceptance test for ELENA
- ✓ Bake-out at 250°C
- ✓ Low friction coefficient:  $\mu$  < 0.01
- ✓ Good radiation stability
- ✓ Low electrical conductance
- Poor performance under atmospheric conditions
- Oxidation due to storage
- Corrosion



## **Tungsten-Disulfide**

- ✓ Better oxidation resistance
- ✓ Worse sliding endurance in vacuum than MoS2
- ✓ Friction coefficient:  $\mu = 0.03$  to 0.09
- ✓ Thermal stability:  $-188^{\circ}C$  to  $1316^{\circ}C$
- $\checkmark\,$  Chemical cleaning with acid  $\otimes\,$

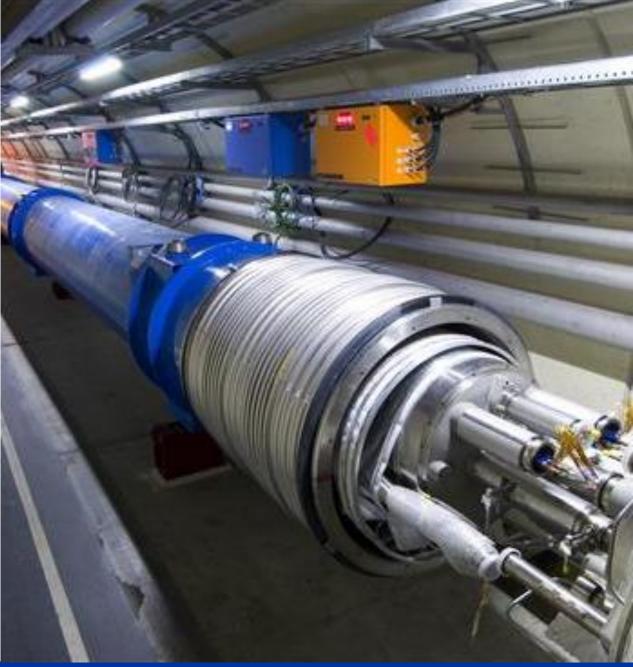




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### **LHC Beam**

Characteristic	Values
Top Energy	E = 13 TeV
Injection Energy	E = 0.45 TeV
Injection Profile	$\sigma_x = 0.53 mm$
	$\sigma_y = 0.8 mm$
Required Position Accuracy	$\epsilon_y = 20 \ \mu m$

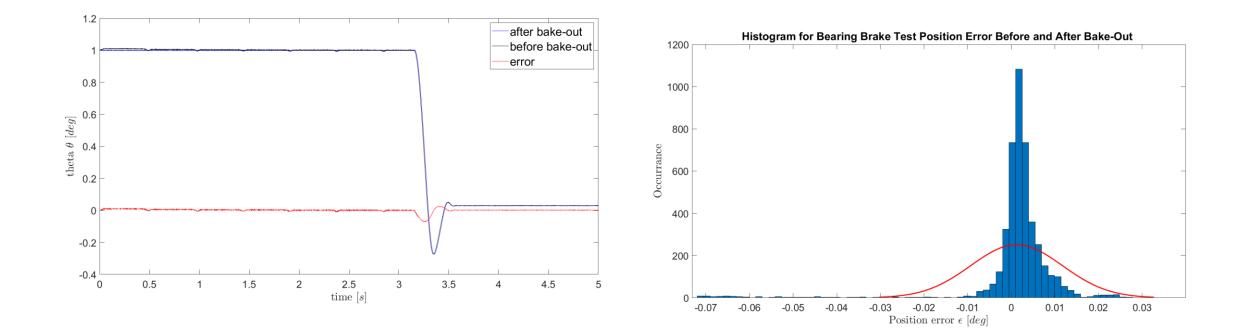




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## **Results Nominal Bearings**

#### Magnetic Brake Restoring Test Position

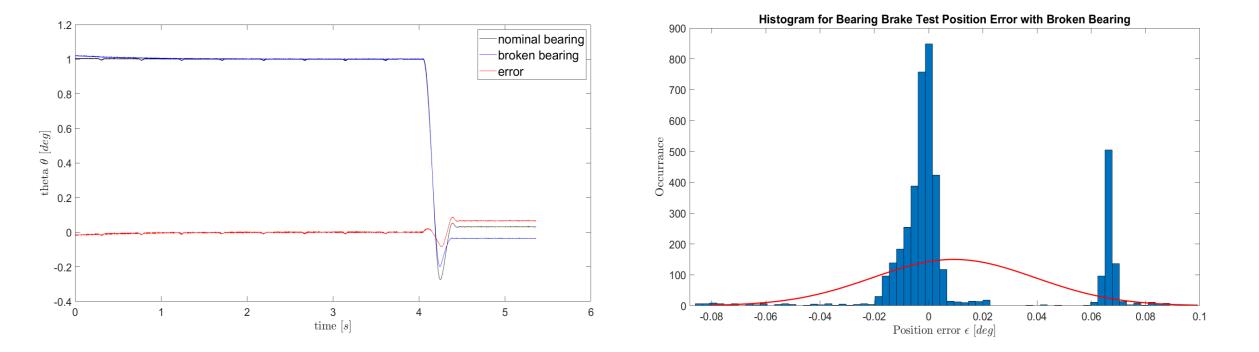


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**Error Histogram** 

## **Results Broken Bearings**

#### Magnetic Brake Restoring Test Position



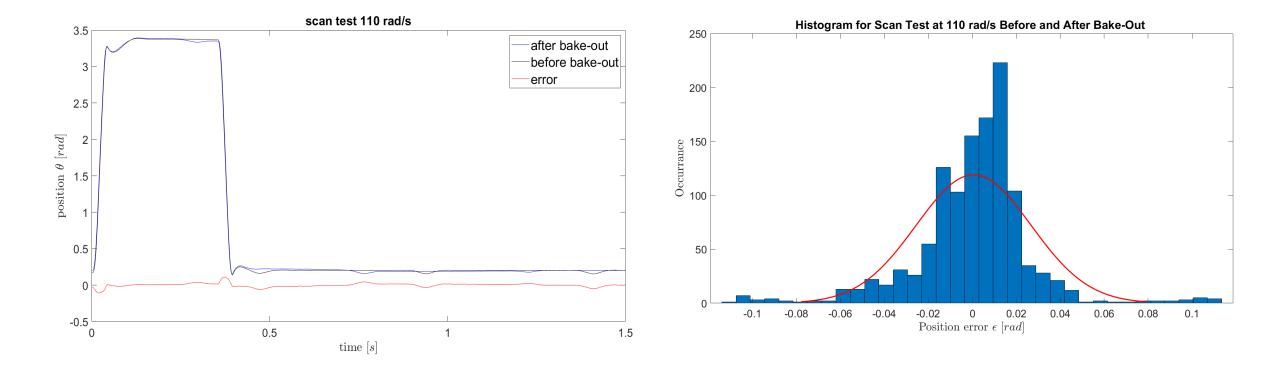


**Error Histogram** 

**S**cans

## Scan Test at $110\frac{rad}{s}$

#### **Error Histogram**

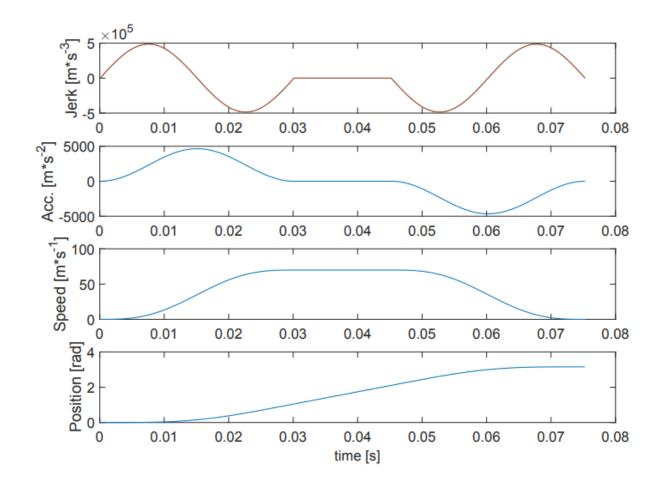




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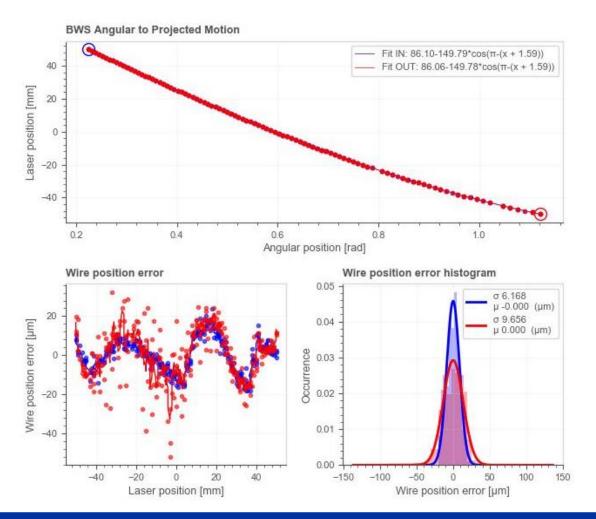
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#### **Motion Profile**





### **Calibration Results**



- Scan at  $55\frac{rad}{s}$
- Expected wire position error:
  - **IN-OUT offset:** 31.9 μm
- Measured wire position error:
  - **IN-OUT offset:** 26 μm

