

# SQUIRELS



**Sascha Diefenbacher, Vinicius  
Mikuni, Benjamin Nachman**  
*ML4jets, Hamburg 2023*

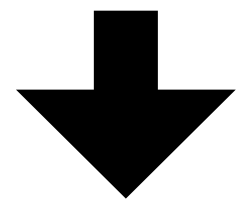


**BERKELEY LAB**



# Refinement

- Fundamentally: Refinement = mapping arbitrary distribution to other arbitrary distribution
  - Simulation refinement
  - Unfolding
  - Background estimation
  - Anomaly detection
  - Many more...

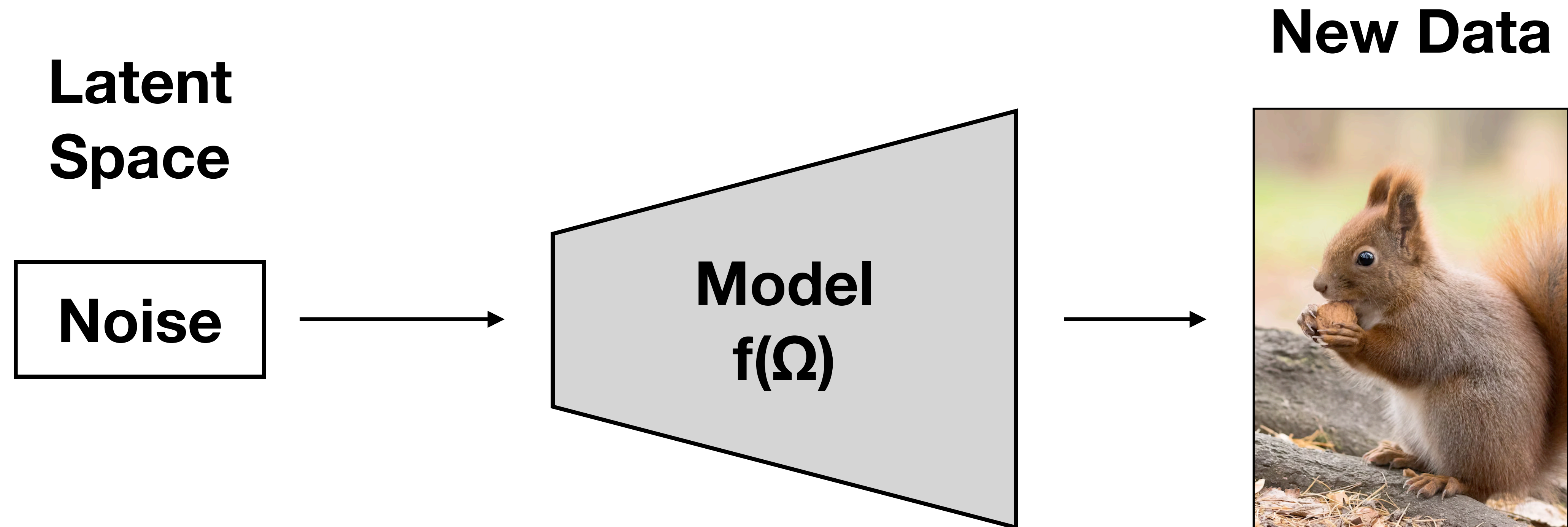




# Generative Models

First step:

- Standard generative models:
- Map random noise to new data



# Generative Models


Now: generalize to arbitrary starting distribution

- VAE:




# Generative Models

Now: generalize to arbitrary starting distribution

- VAE:  • Latent regularization needs latent space with tractable KLD
- Starting distribution cannot be arbitrary
- Needs tractable base distribution



# Generative Models

Now: generalize to arbitrary starting distribution

- VAE:  Needs tractable base distribution
- NF:

# Generative Models



Now: generalize to arbitrary starting distribution

- VAE:  Needs tractable base distribution
- NF: 
  - NLL calculation needs tractable base
  - Two-Flow trick possible
  - Requires learning full generative model






# Generative Models

Now: generalize to arbitrary starting distribution

- VAE:  Needs tractable base distribution
- NF:  NLL calculation needs tractable base
- Diffusion:




# Generative Models

Now: generalize to arbitrary starting distribution

- VAE:  Needs tractable base distribution
- NF:  NLL calculation needs tractable base
- Diffusion: 
  - Diffusion process leads to Gaussian
  - Needs Gaussian base distribution

# Generative Models





Now: generalize to arbitrary starting distribution

- VAE:  Needs tractable base distribution
- NF:  NLL calculation needs tractable base
- Diffusion:  Needs Gaussian base distribution
- GAN:








# Generative Models

Now: generalize to arbitrary starting distribution

- VAE:  Needs tractable base distribution
- NF:  NLL calculation needs tractable base
- Diffusion:  Needs Gaussian base distribution
- GAN: 
  - No point in loss calculation depends on starting distribution
  - Can have arbitrary starting distribution






# Generative Models

Now: generalize to arbitrary starting distribution

- VAE:  Needs tractable base distribution
- NF:  NLL calculation needs tractable base
- Diffusion:  Needs Gaussian base distribution
- GAN:  Can have arbitrary starting distribution
  -  Low performance (compared to SotA)
  - Difficult training

# Generative Models






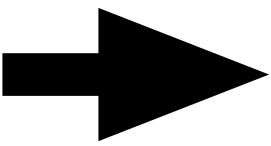
Now: generalize to arbitrary starting distribution

- VAE:  Needs tractable base distribution
- NF:  NLL calculation needs tractable base
- Diffusion:  Needs Gaussian base distribution
- GAN:  Can have arbitrary starting distribution
-  Low performance/difficult training



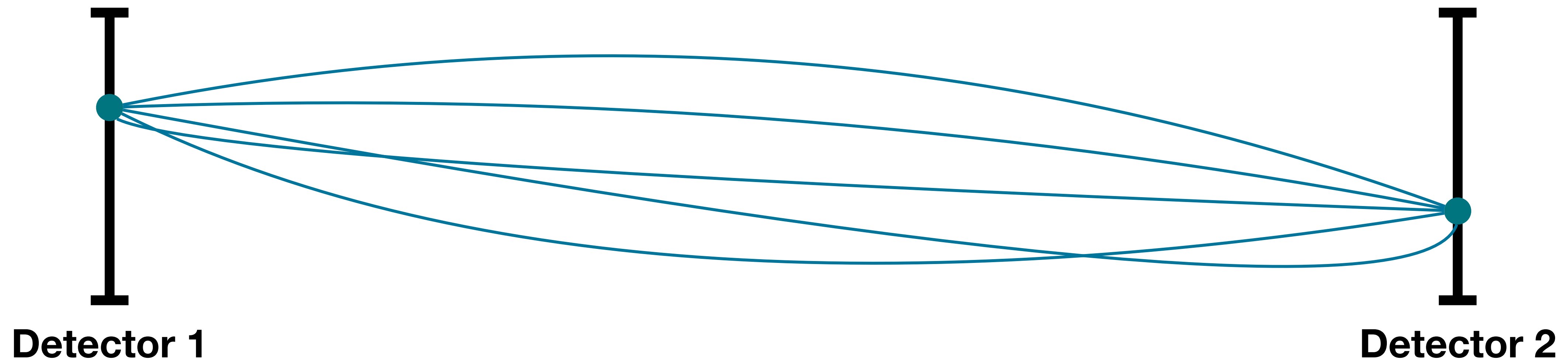
# Generative Models

Now: generalize to arbitrary starting distribution

- VAE:  Needs tractable base distribution
- NF:  NLL calculation needs tractable base
- Diffusion:  Needs Gaussian base distribution
- GAN:  Can have arbitrary starting distribution
-  Low performance/difficult training
-  **New model**

# Schrödinger Bridges

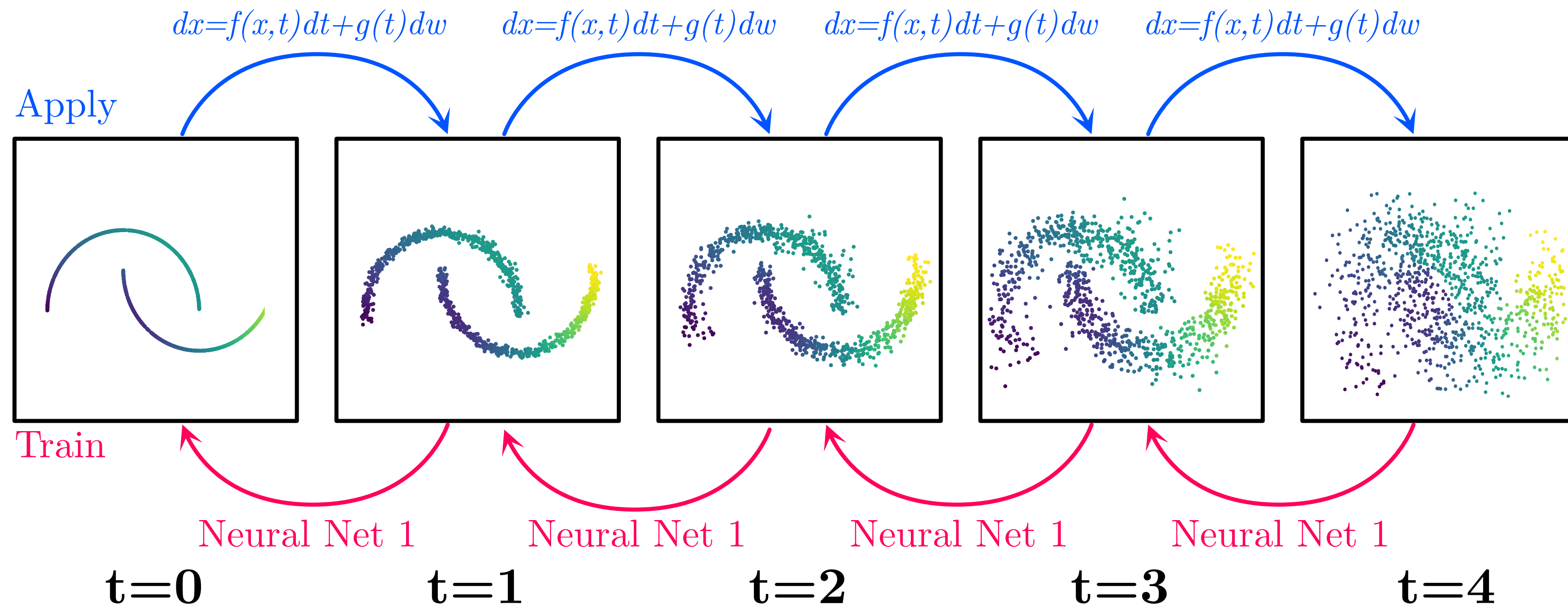
- Based on optimal transport problem



- What is the best path between the two observations
- Boundary condition:  $x(t = 0) = x_0, x(t = 1) = x_1$

# Schrödinger Bridges

Start from standard Diffusion Models

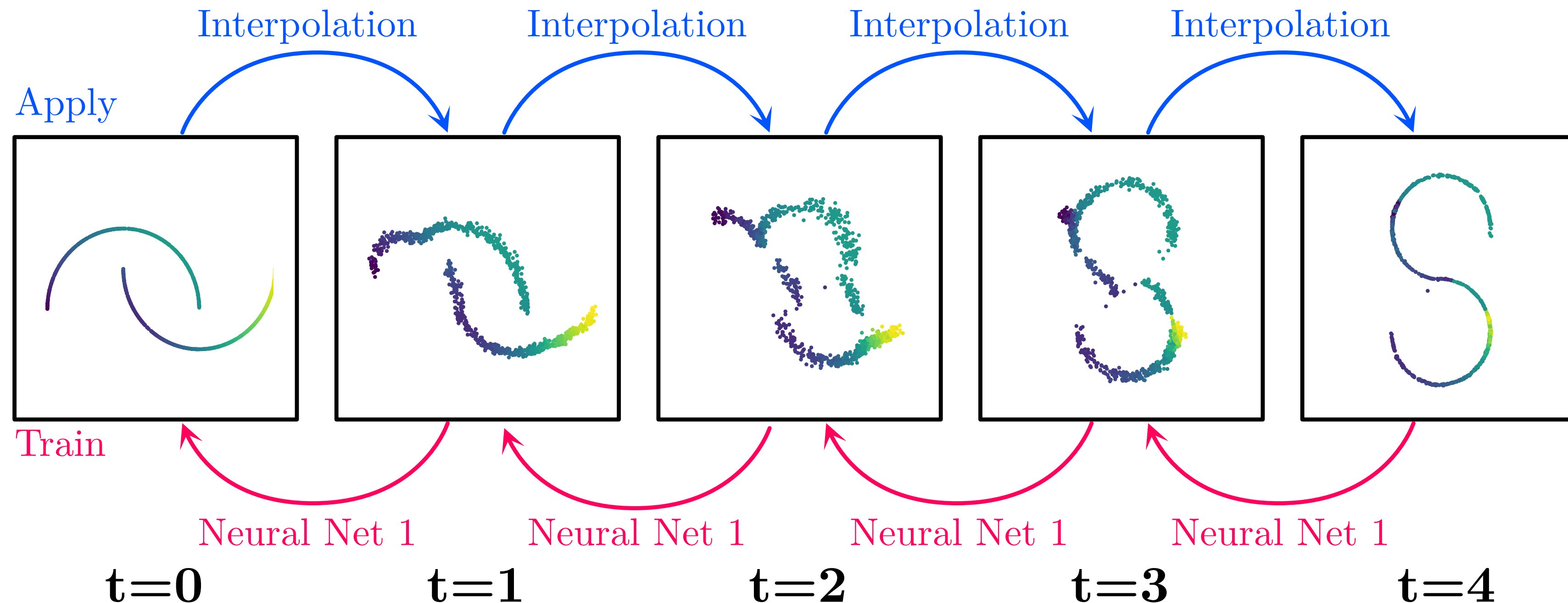


- Usually:  $f(x,t)$  diffuses to normal distribution
- Modify  $f(x,t)$  to map between start and target distribution, ensure boundary conditions are matched



# Schrödinger Bridges

## Approach 1: Stochastic interpolation



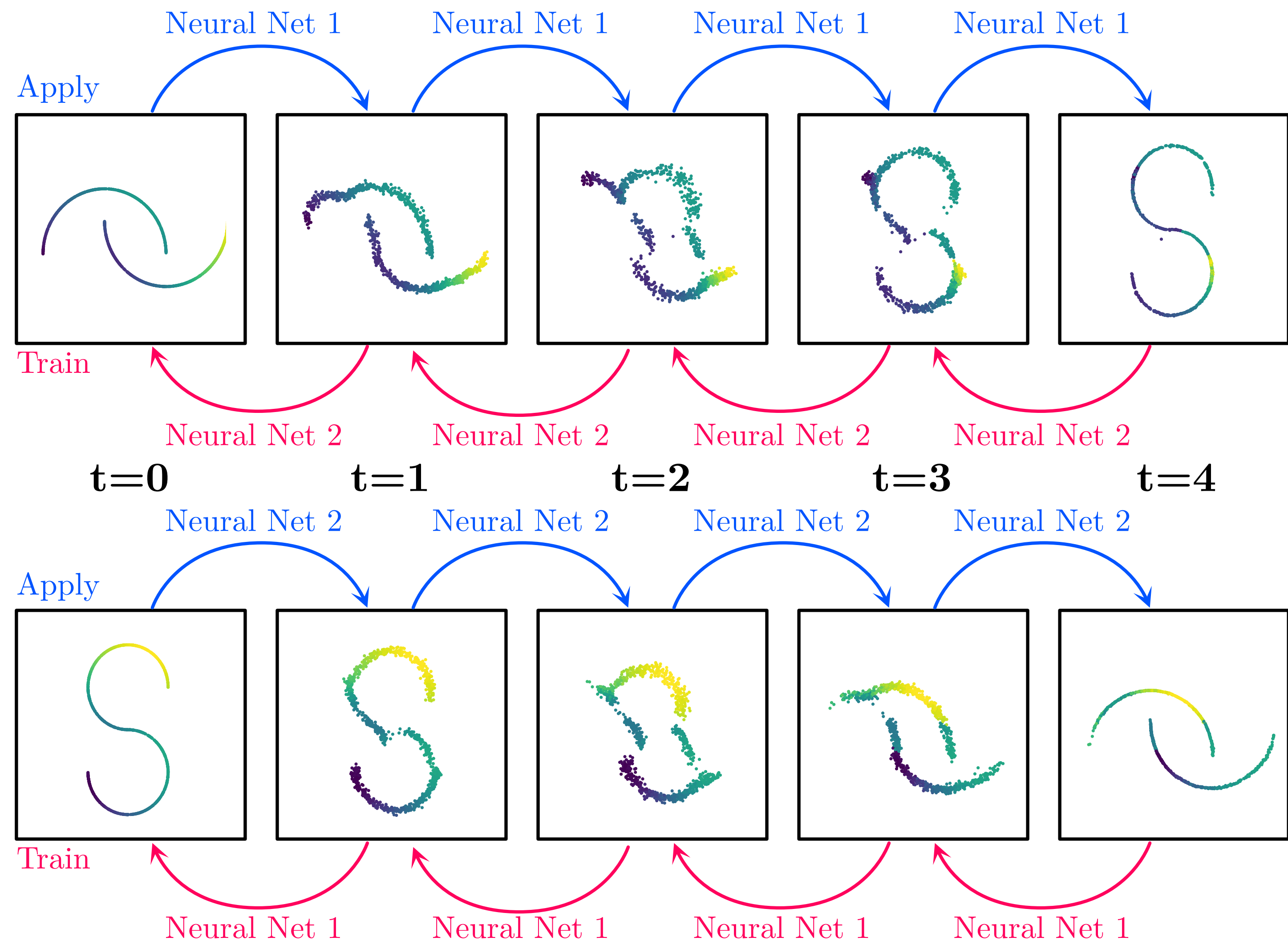
- Define random shift that ends at boundary conditions
- Requires pairs of data points

Guan-Hong Liu et. al. **I2SB: Image-to-Image Schrödinger Bridge**, [2302.05872](#)

# Schrödinger Bridges

## Approach 2: 2 Models with Iterative Fitting

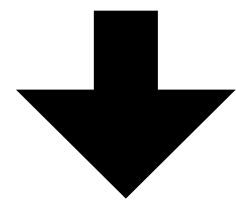
- Train NN 1 from start to target distribution
- Train NN 2 to undo NN 1
- Reverse and repeat
- No paired data required



Valentin De Bortoli et. al. **Diffusion Schrödinger Bridge with Applications to Score-Based Generative Modeling**, [2106.01357](#)

# Refinement

- Fundamentally: Refinement = mapping arbitrary distribution to other arbitrary distribution
- Simulation refinement
- Unfolding
- Background estimation
- Anomaly detection
- Many more...



Diefenbacher et. al. **Refining Fast Calorimeter Simulations with a Schrödinger Bridge**, [2308.12339](#)



# SQUIRELS





# SQUIRELS

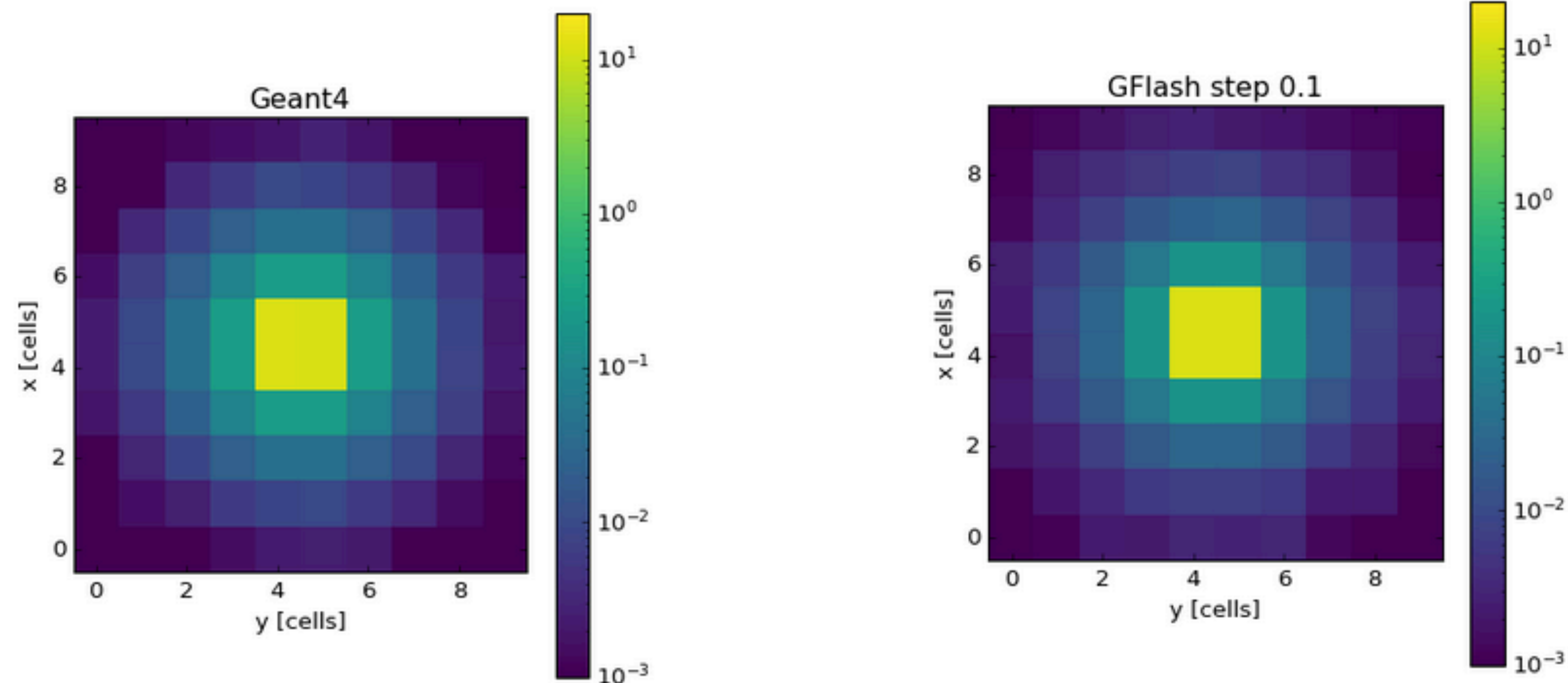


**Schrödinger bridge Quality Improvement via  
Refinement of Existing Lightweight Simulations**

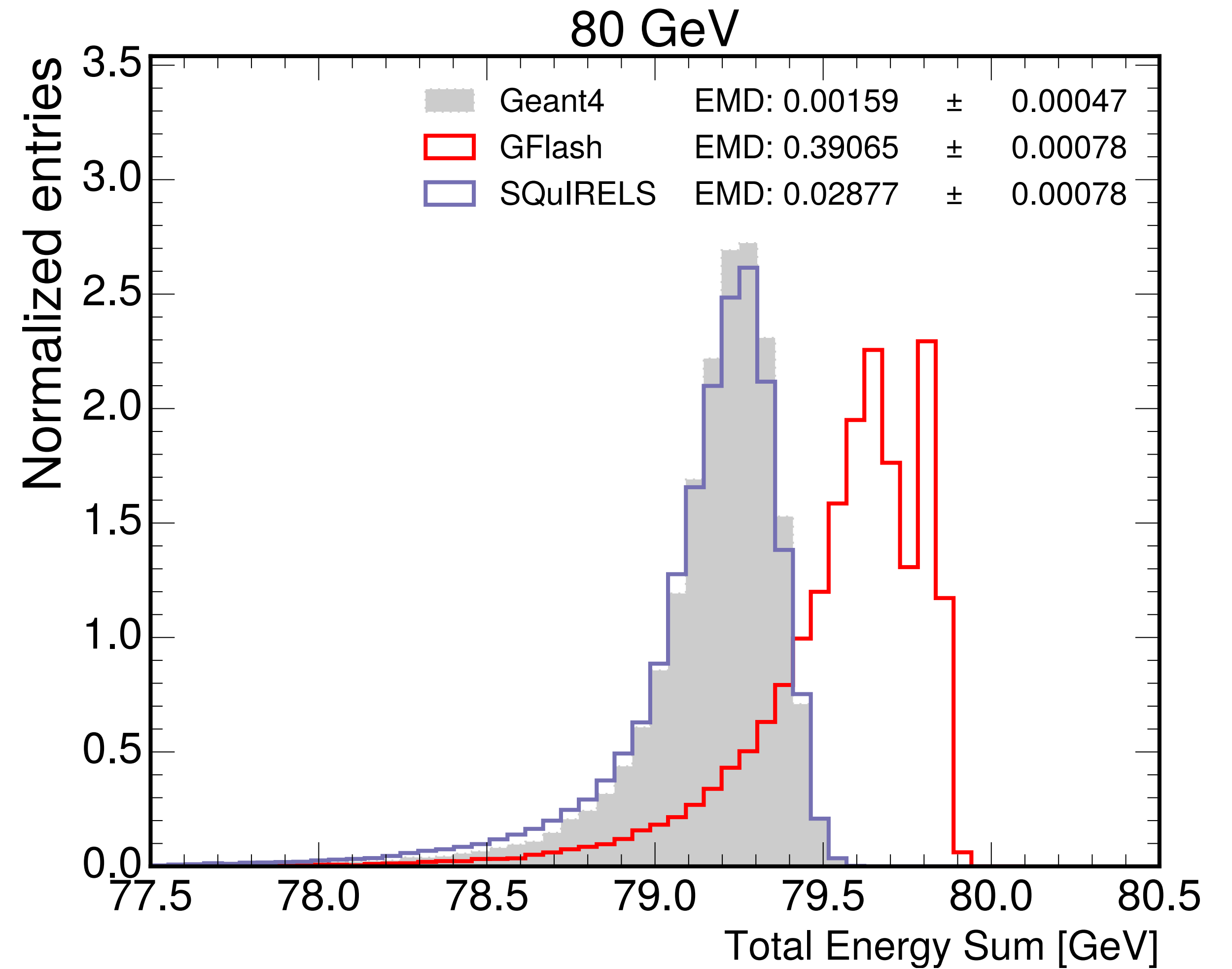
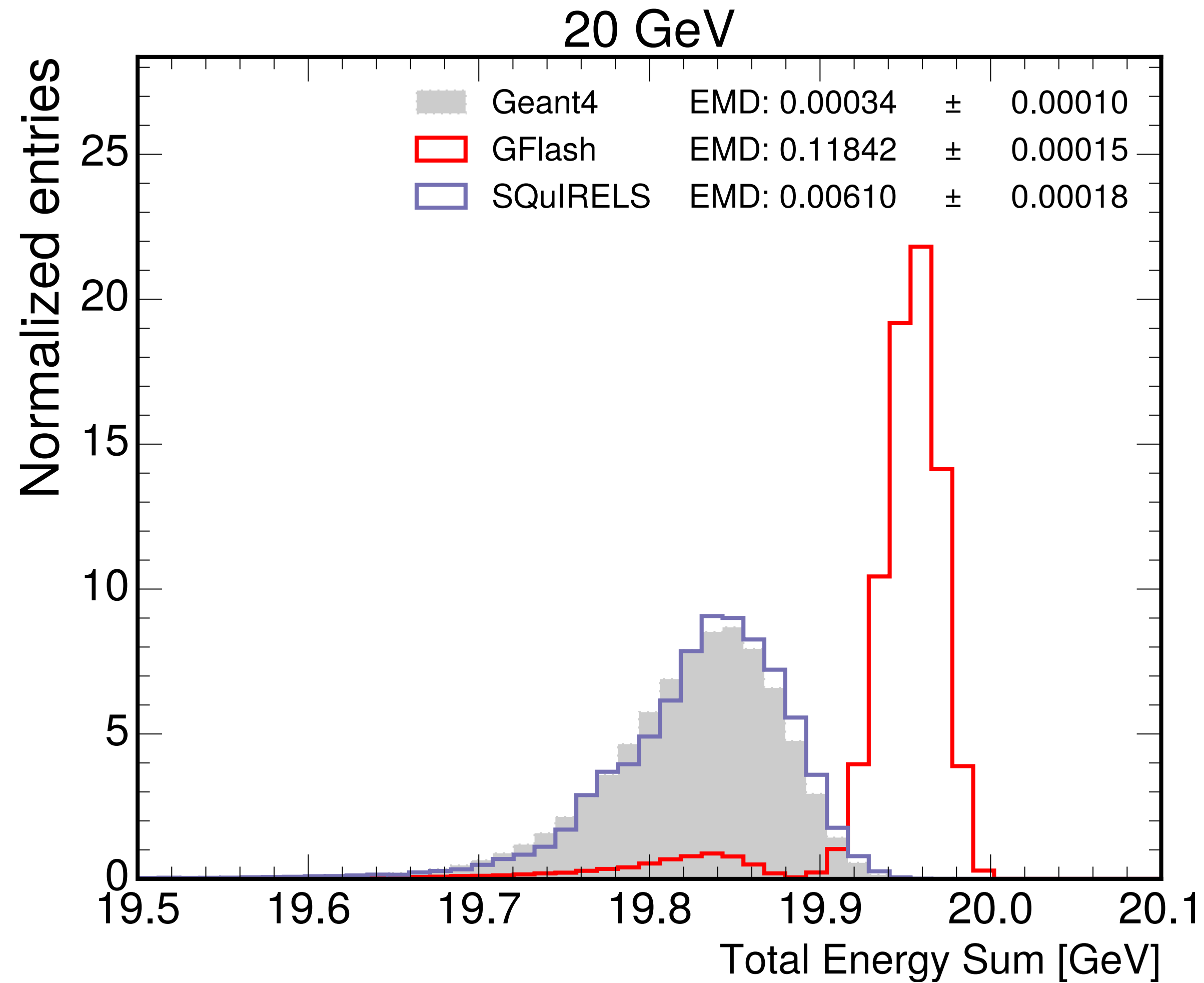
- [2308.12339](https://doi.org/10.2308.12339)

# Data

- 10x10 homogeneous crystal calorimeter
- Simulate electron showers for particle energies 10-100 GeV
- Starting distribution: GFlash fast simulation
- Target distribution: Geant4 full simulation

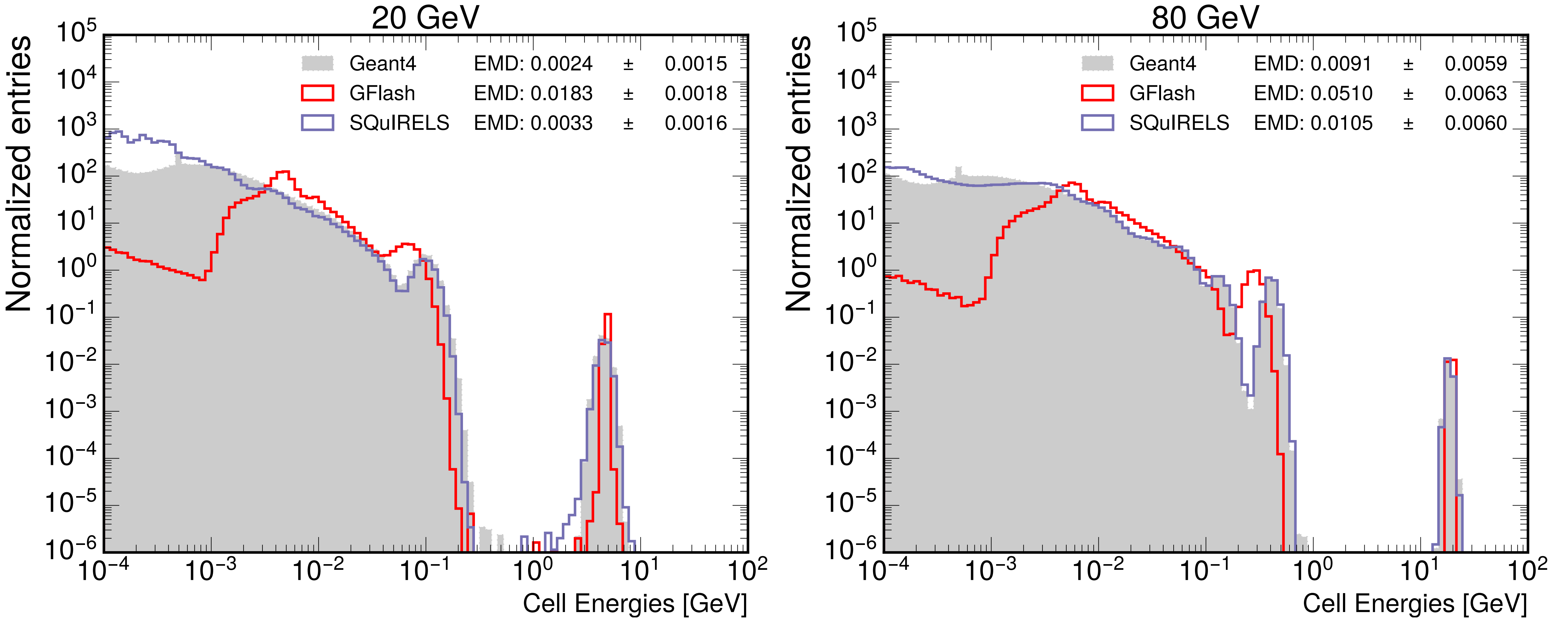


# Energy sum

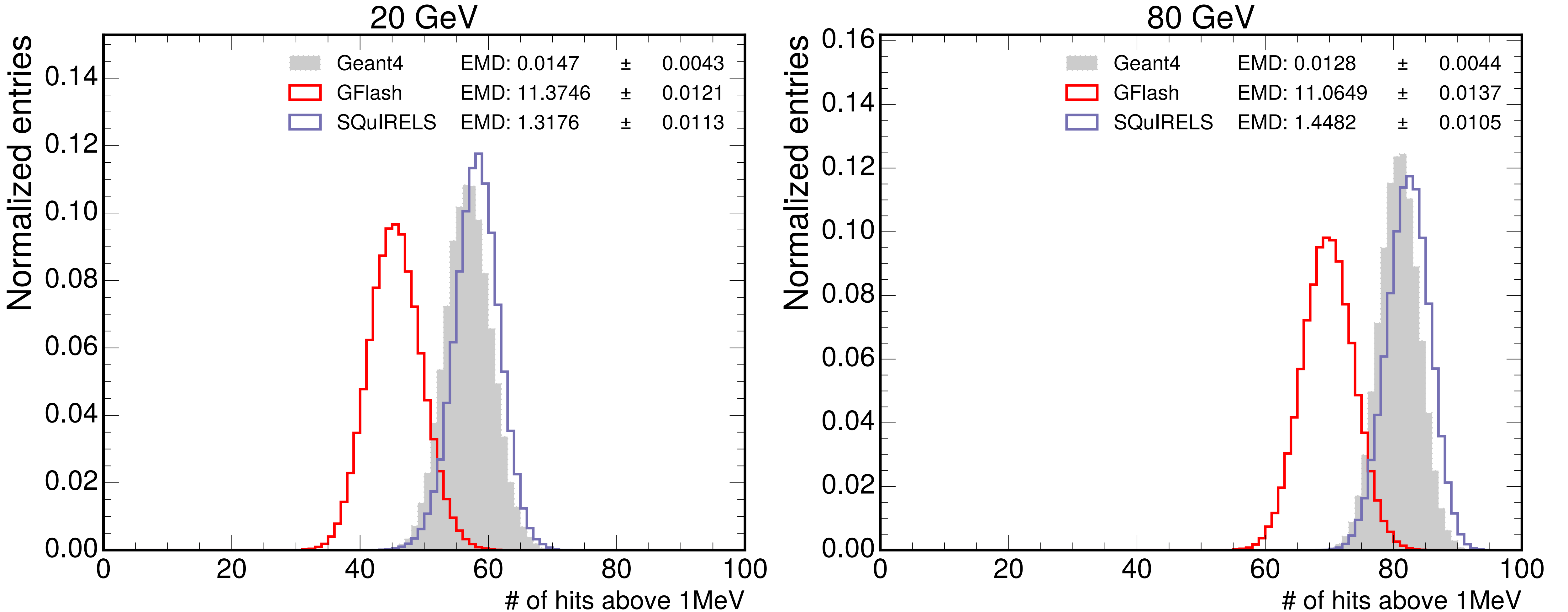




# Energy Spectrum



# Number of Hits



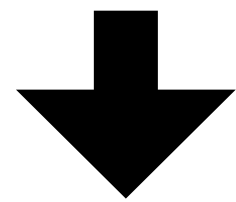


# Timing Results

Simulator	CPU [ms/shower]	GPU [ms/shower]
GEANT4	$404.8 \pm 8.5$	/
GFLASH	$8.5 \pm 0.4$	/
SQuIRELS (refine)	$7.21 \pm 0.04$	$0.0522 \pm 0.00002$
SQuIRELS (full)	$15.7 \pm 0.4$	$8.5 \pm 0.4$

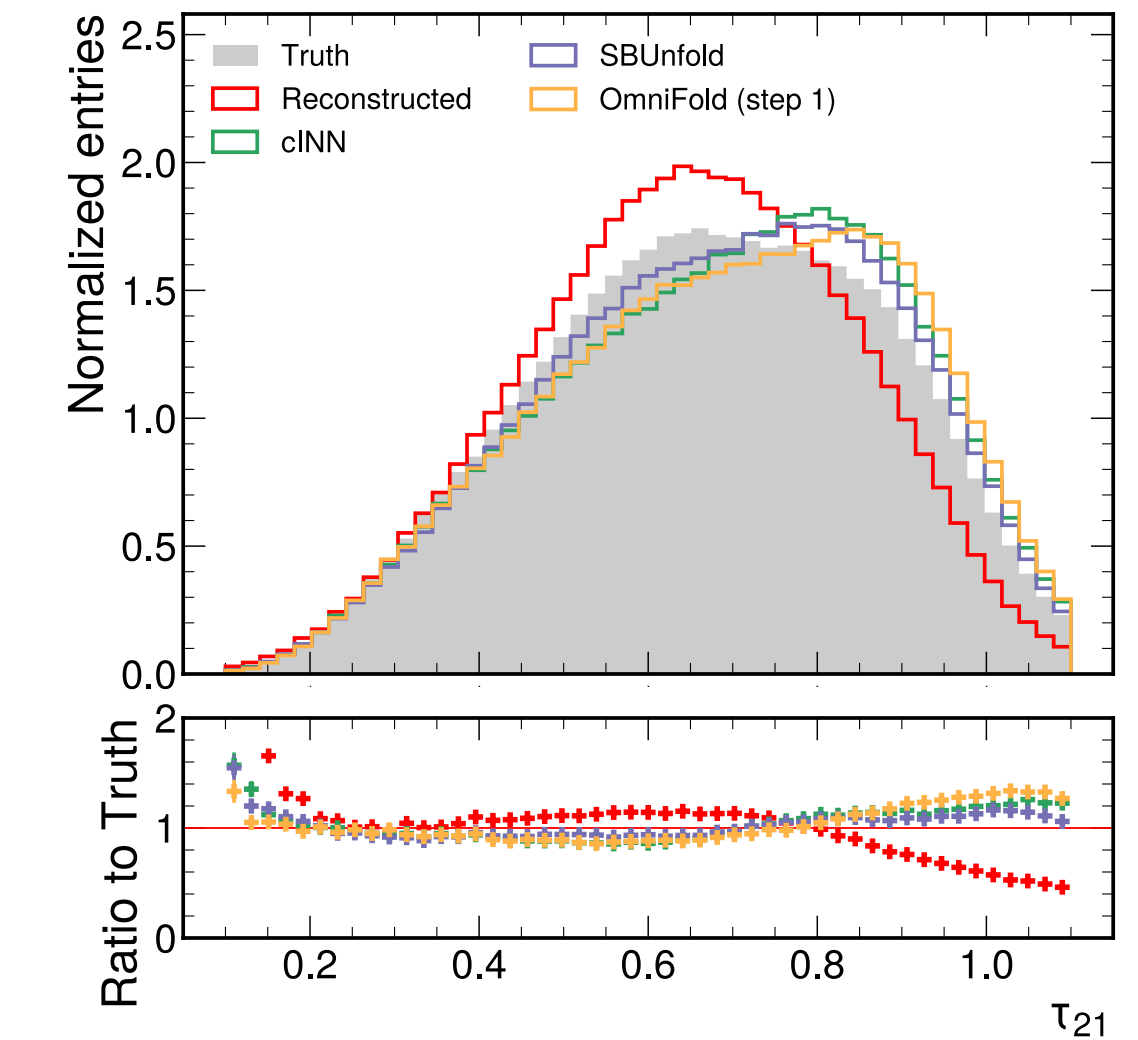
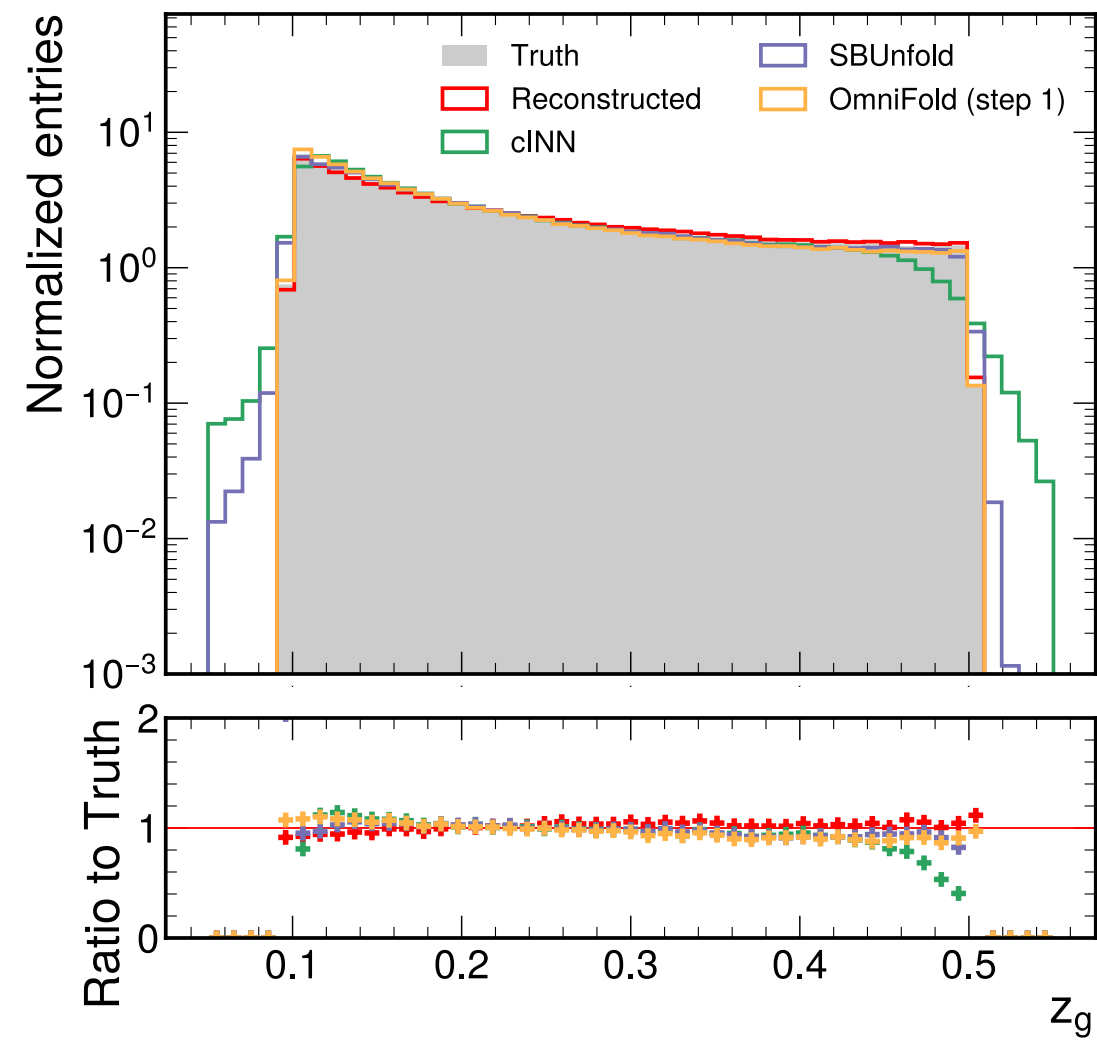
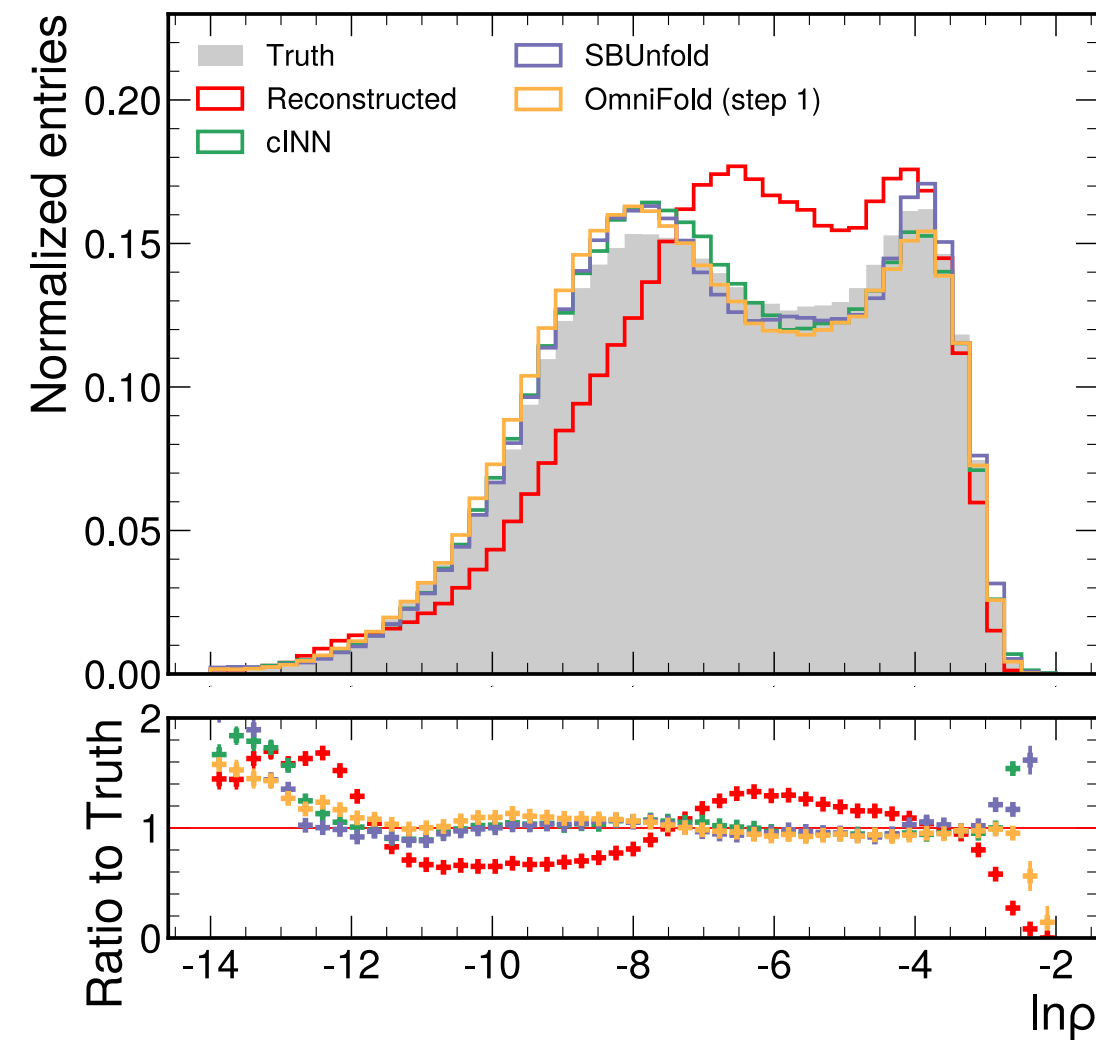
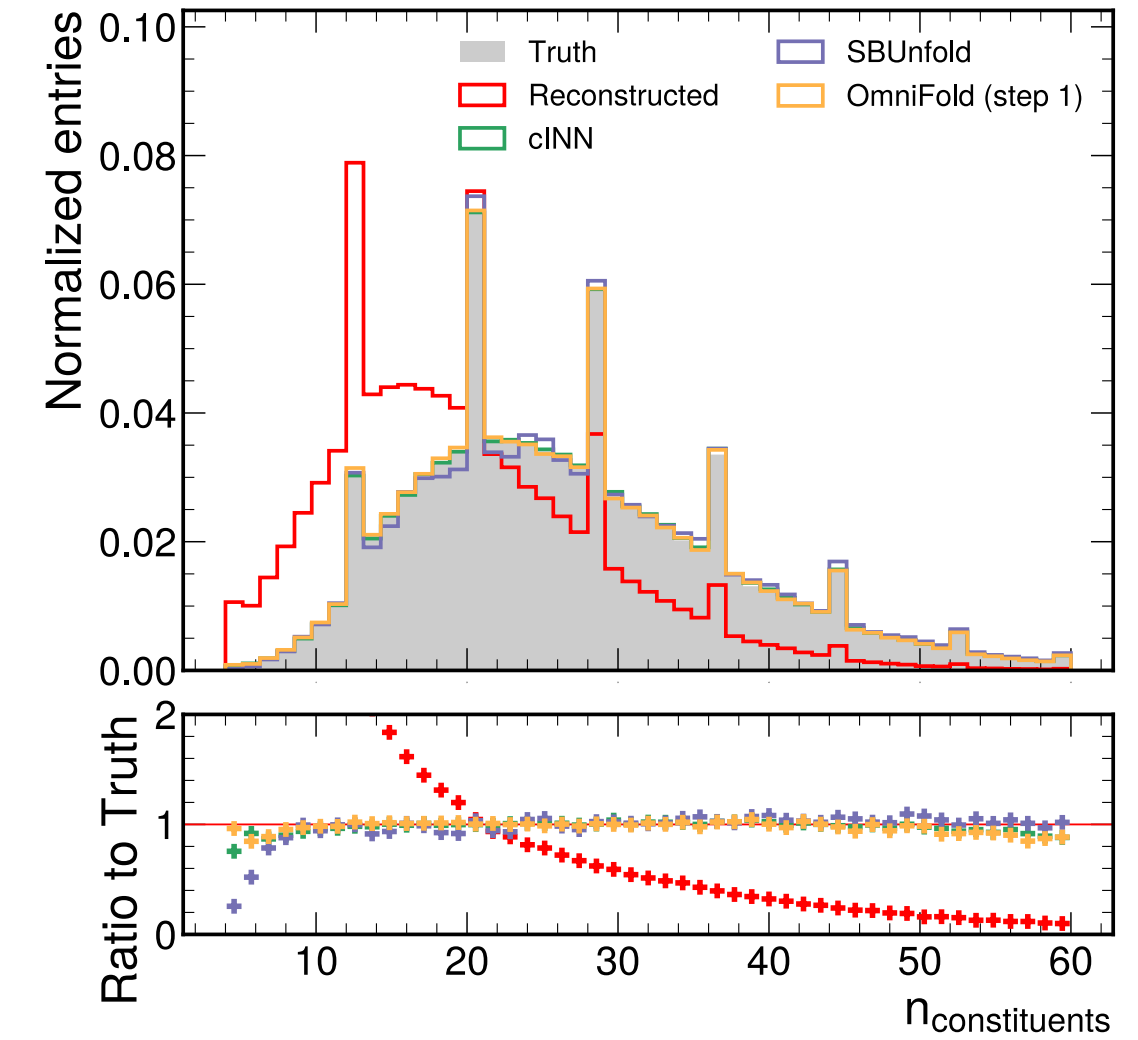
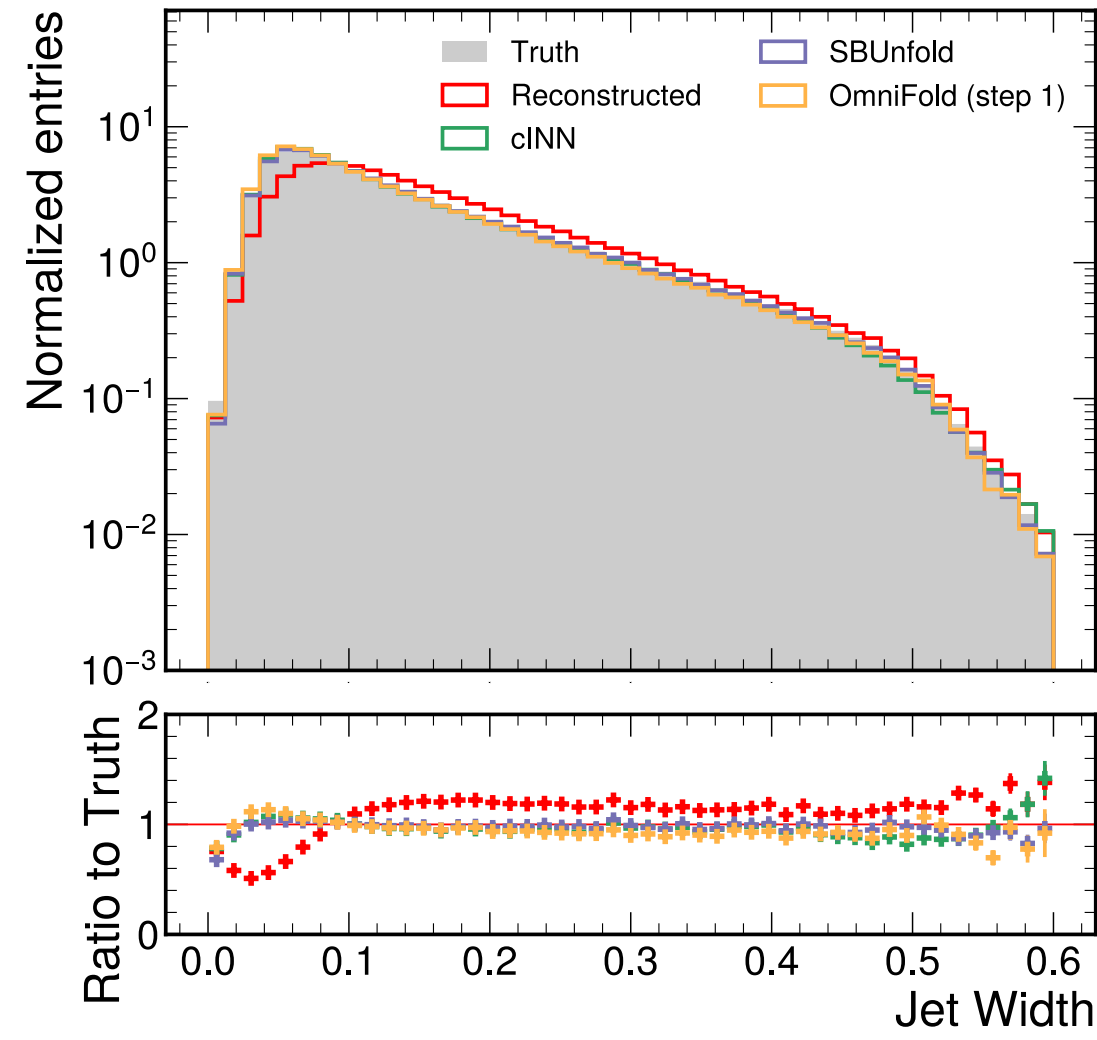
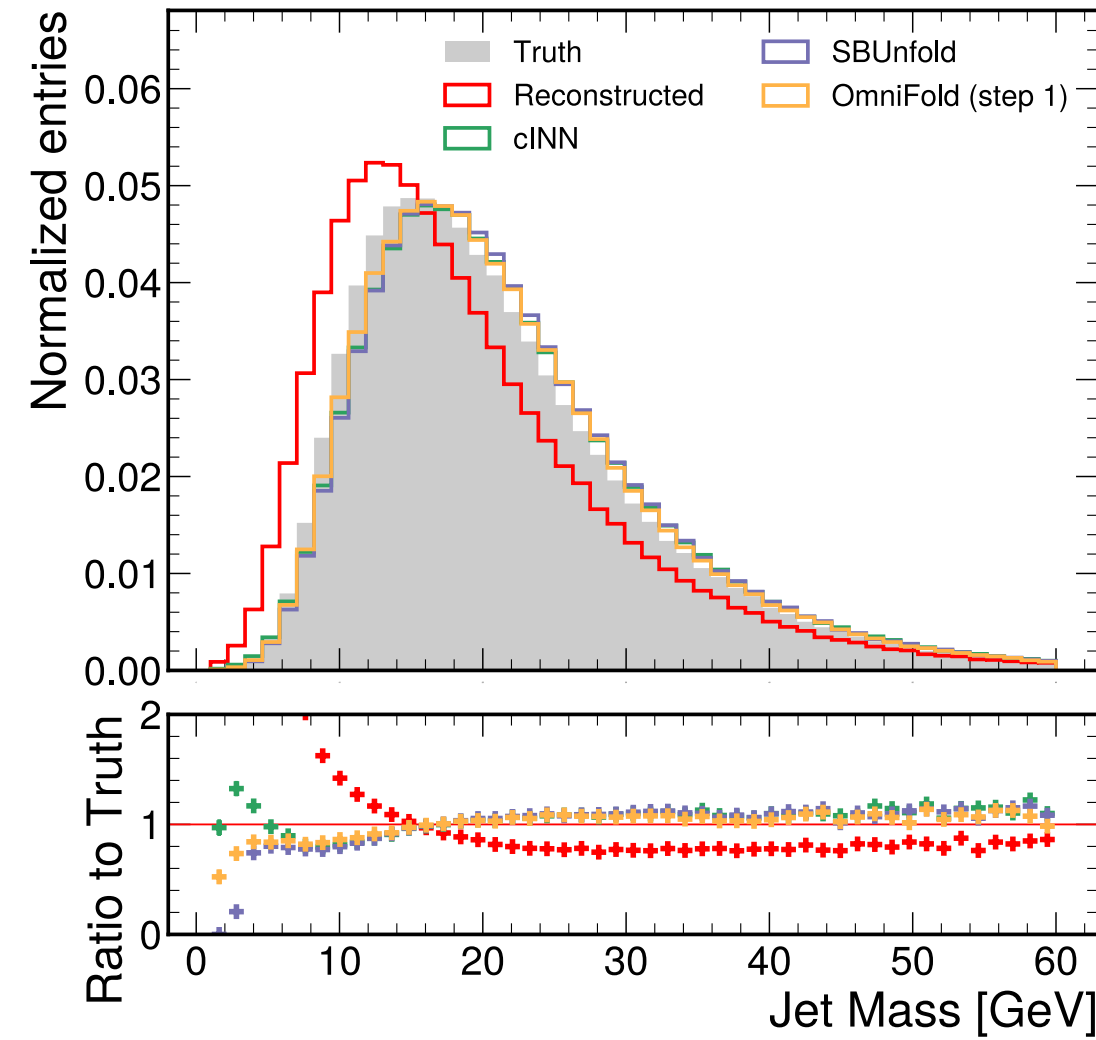
# Refinement

- Fundamentally: Refinement = mapping arbitrary distribution to other arbitrary distribution
- Simulation refinement
- Unfolding
- Background estimation
- Anomaly detection
- Many more...

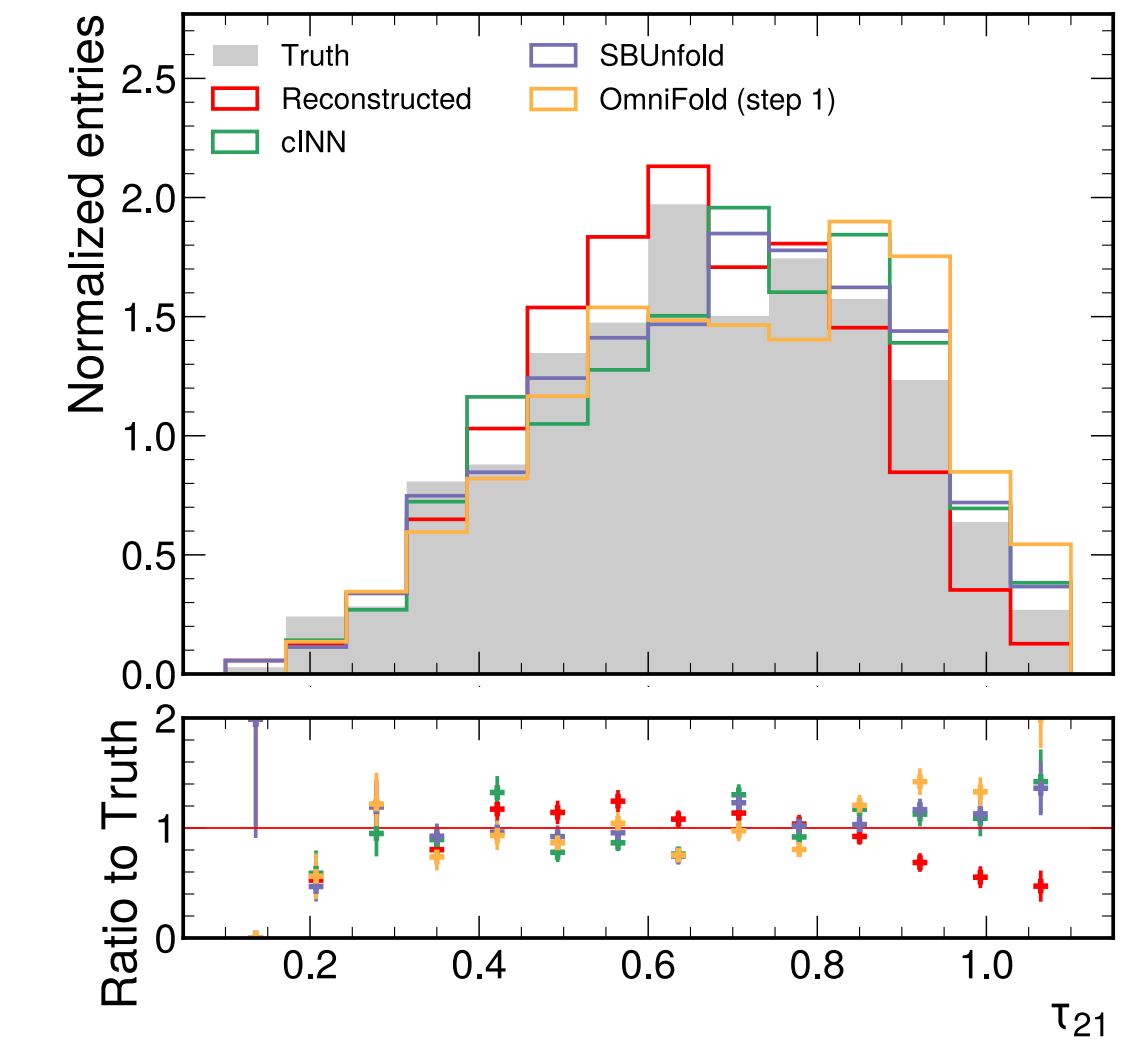
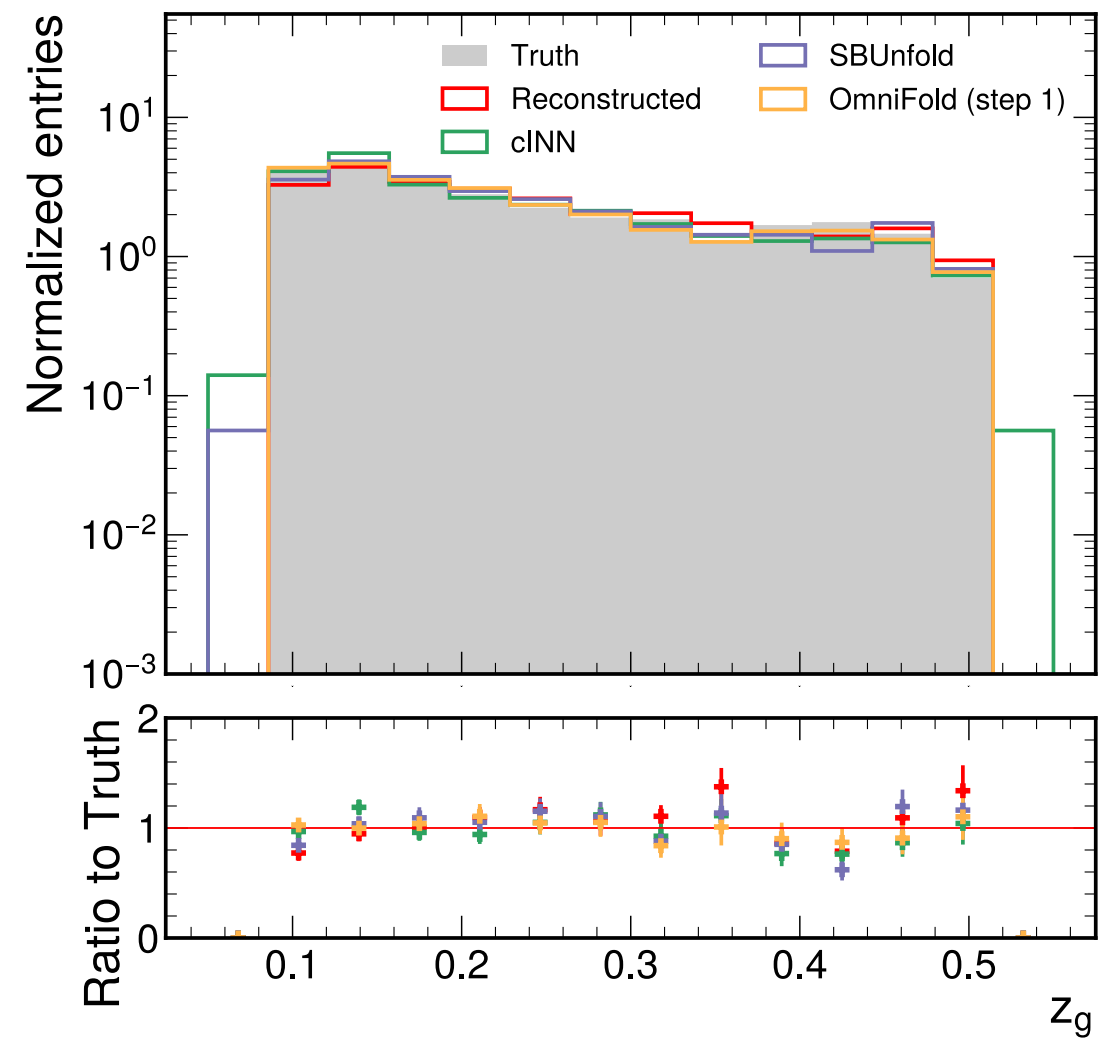
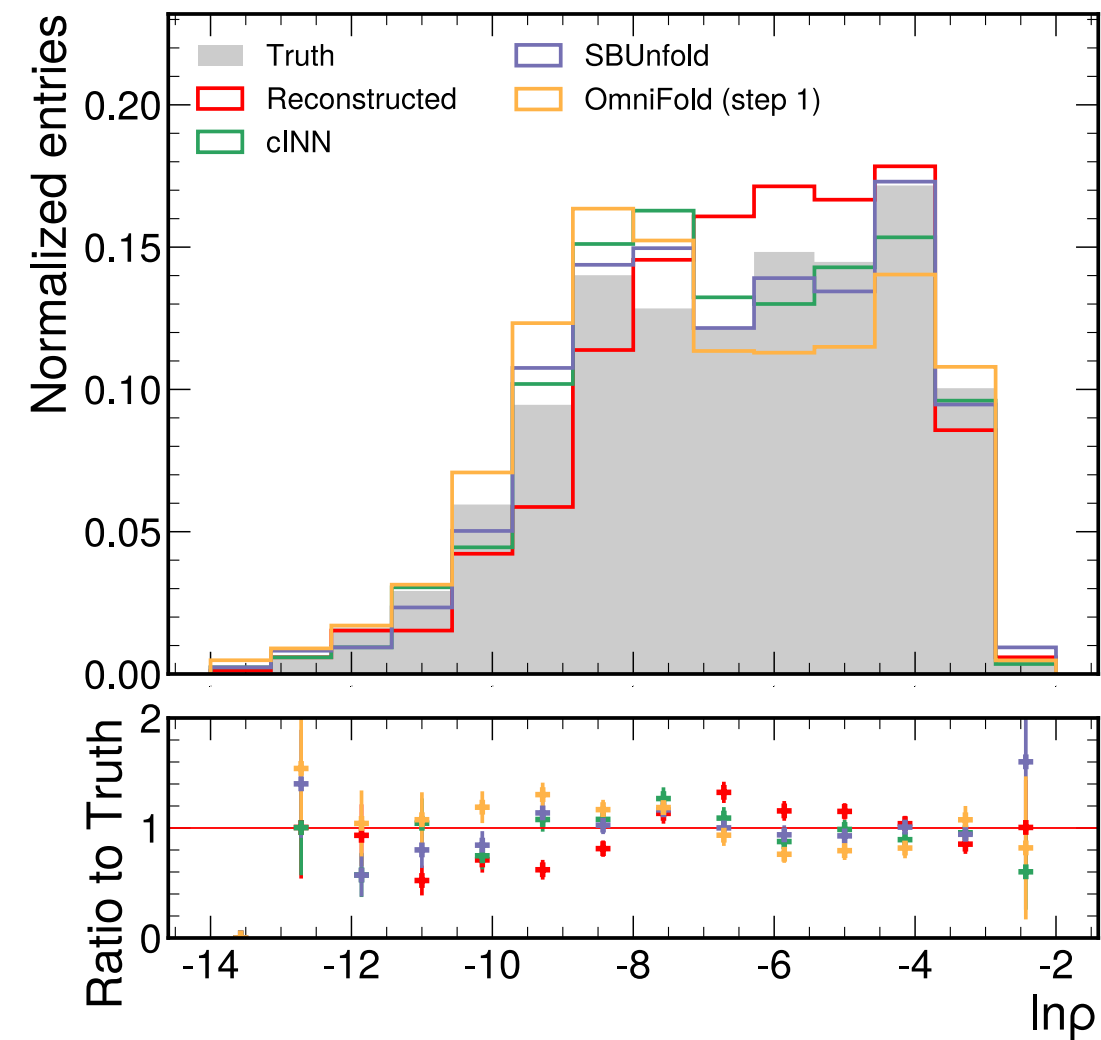
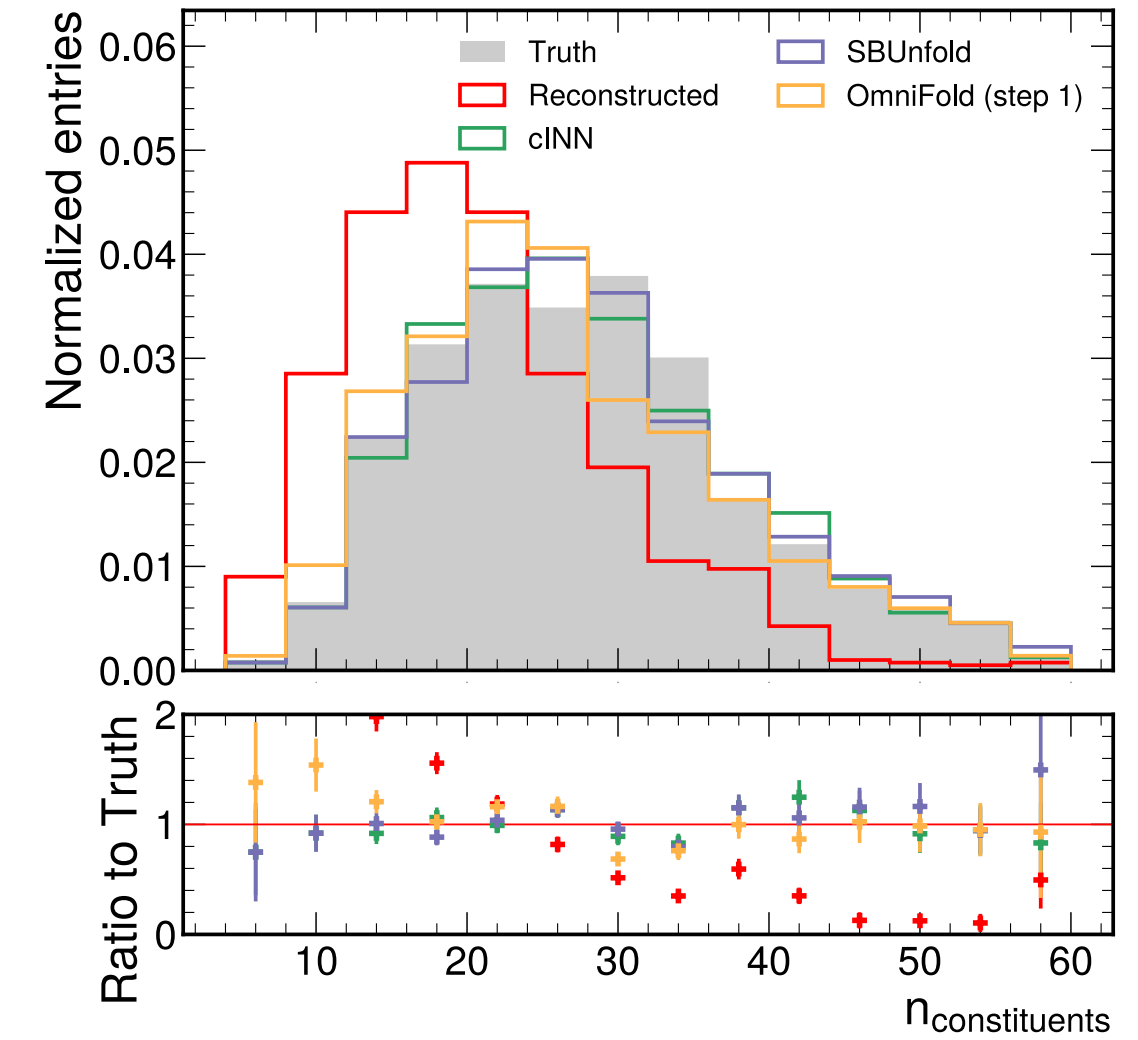
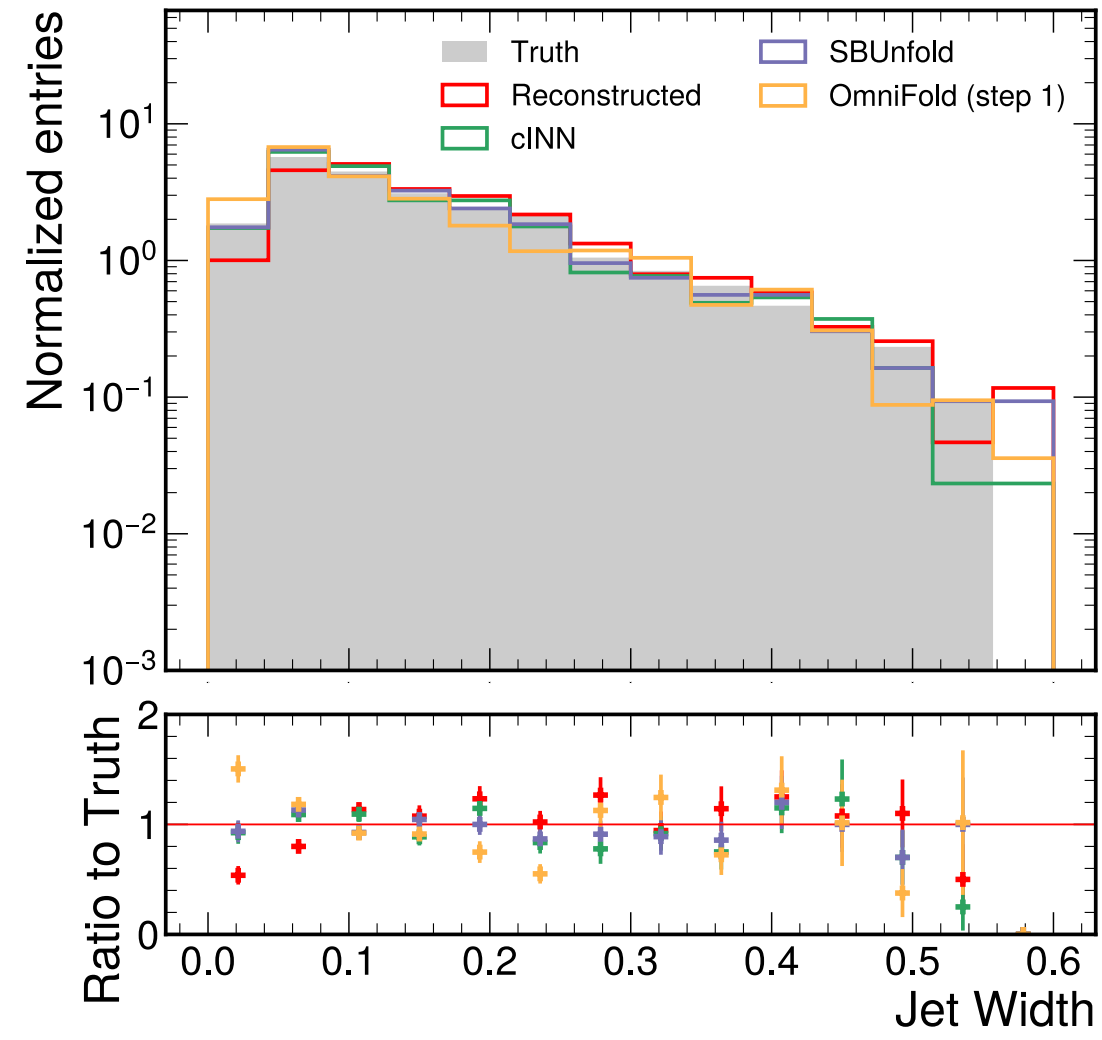
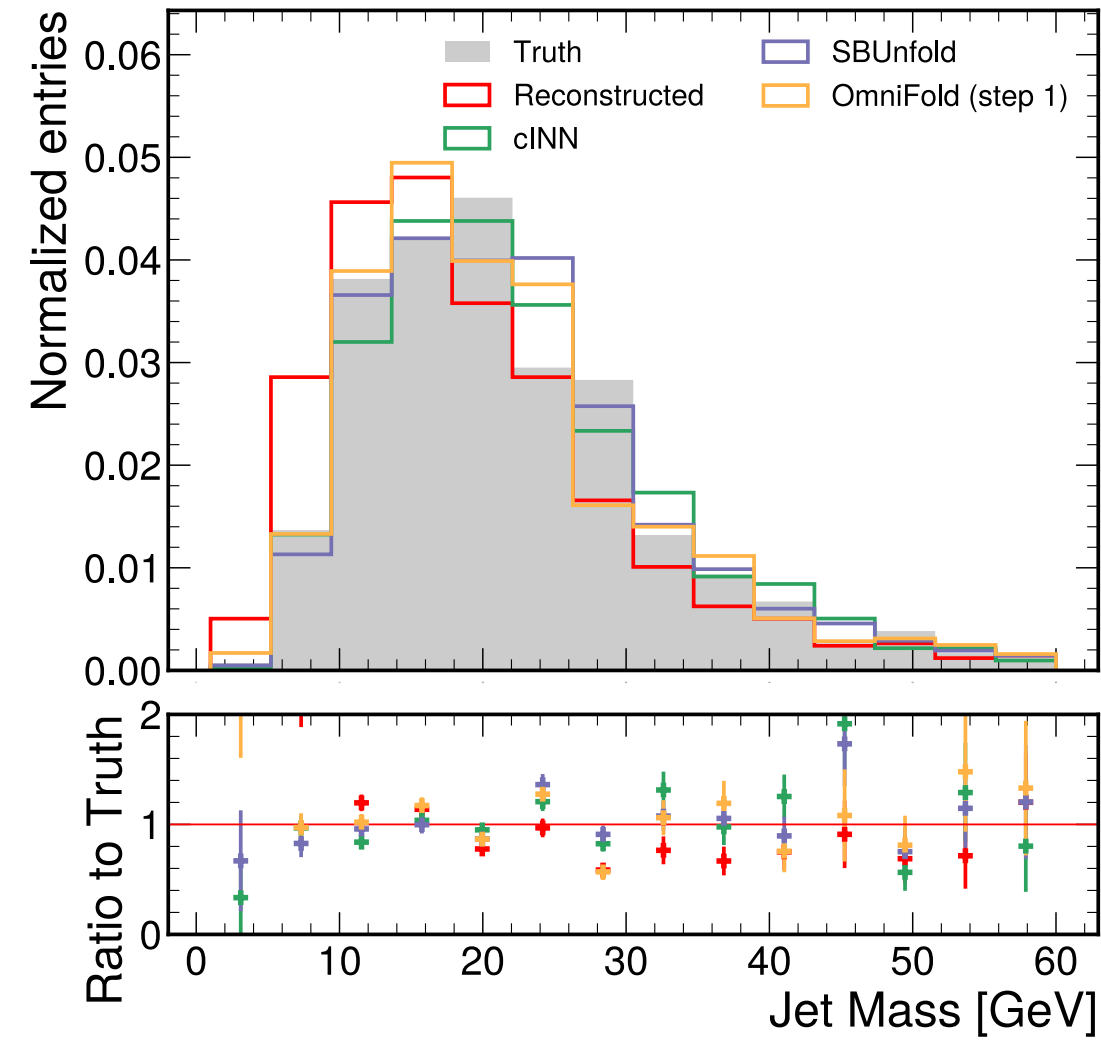


Diefenbacher et. al. **Improving Generative Model-based Unfolding with Schrödinger Bridges**, [2308.12351](#)

# Herwig → Pythia (High Stat.)



# Herwig → Pythia (Low Stat.)





# Herwig → Pythia

High Stat:

Model	EMD( $\times 10$ )/Triangular Discriminator( $\times 10^3$ )		
	OMNIFOLD Step 1	cINN	SBUNFOLD
Jet mass	<b>6.1<math>\pm</math>0.1/1.5</b>	10.1 $\pm$ 1.2/2.4	9.0 $\pm$ 0.1/3.1
Jet Width	0.06 $\pm$ 0.001/1.1	0.05 $\pm$ 0.003/0.7	<b>0.02<math>\pm</math>0.001/0.2</b>
N	<b>1.7<math>\pm</math>0.1/0.2</b>	6.1 $\pm$ 4.0/0.2	3.0 $\pm$ 0.1/0.6
log $\rho$	1.35 $\pm$ 0.03/1.1	3.1 $\pm$ 2.1/0.8	<b>0.4<math>\pm</math>0.1/0.7</b>
$z_g$	0.086 $\pm$ 0.001/1.2	0.3 $\pm$ 0.1/12.7	<b>0.049<math>\pm</math>0.001/3.5</b>
$\tau_{21}$	0.23 $\pm$ 0.02/4.6	0.7 $\pm$ 0.4/3.5	<b>0.12<math>\pm</math>0.02/1.4</b>

Low Stat:

Model	EMD( $\times 10$ )/Triangular Discriminator( $\times 10^3$ )		
	OMNIFOLD Step 1	cINN	SBUNFOLD
Jet mass	<b>8.7<math>\pm</math>1.8/13.6</b>	9.2 $\pm$ 3.0/8.4	<b>7.7<math>\pm</math>2.5/6.9</b>
Jet Width	0.14 $\pm$ 0.02/18	0.07 $\pm$ 0.02/5.7	<b>0.05<math>\pm</math>0.02/4.6</b>
N	12 $\pm$ 3/10.9	<b>5.4<math>\pm</math>1.3/3.8</b>	<b>5.8 <math>\pm</math>1.6/3.7</b>
log $\rho$	4.0 $\pm$ 0.8/11	1.6 $\pm$ 0.5/6.2	<b>1.2<math>\pm</math>0.3/4.4</b>
$z_g$	0.08 $\pm$ 0.02/1.5	0.08 $\pm$ 0.03/7.2	<b>0.06<math>\pm</math>0.01/7.1</b>
$\tau_{21}$	0.4 $\pm$ 0.07/16	0.2 $\pm$ 0.05/12	<b>0.1<math>\pm</math>0.04/8</b>



# Conclusion

- Schrödinger Bridges promising for any refinement
- Calorimeter refinement
  - Faster than full simulation
  - More accurate than fast sim.
- Unfolding
  - Beats state of the art unfolding methods



**Backup**

# Schrödinger Bridges

- Start from initial distribution  $p_0(x_0) = p_\alpha$

$$p(x_0, N) = p_0(x_0) \prod_{k=0}^{N-1} p_{k+1|k}(x_{k+1}|x_k)$$

- Apply transition kernels  $p_{k+1|k}$
- This defines path  $\pi$
- Now demand that path fulfills boundary condition:

$$\pi^* = \operatorname{argmin} \{ \text{KL}(\pi|p) : \pi_0 = p_\alpha, \pi_N = p_\beta \}$$



# Schrödinger Bridges

- Can be approximated using iterative fitting procedure:

$$\pi^{2n+1} = \arg \min \{ \text{KL}(\pi | \pi^{2n}) : \pi_N = p_\beta \}$$

$$\pi^{2n+2} = \arg \min \{ \text{KL}(\pi | \pi^{2n+1}) : \pi_0 = p_\alpha \}$$

- Gradually brings endpoints of path closer to target distributions
- For generative application, distr. unknown, KLD hard to calculate
- Instead: define Gaussian transition kernels in both directions

$$p_{k+1|k}^n(x_{k+1}|x_k) = \mathcal{N}(x_{k+1}; F_k^n(x_k), 2\gamma_{k+1})$$

$$q_{k|k+1}^n(x_k|x_{k+1}) = \mathcal{N}(x_k; B_{k+1}^n(x_{k+1}), 2\gamma_{k+1})$$

# Schrödinger Bridges

- Instead: define Gaussian transition kernels in both directions

$$p_{k+1|k}^n(x_{k+1}|x_k) = \mathcal{N}(x_{k+1}; F_k^n(x_k), 2\gamma_{k+1})$$

$$q_{k|k+1}^n(x_k|x_{k+1}) = \mathcal{N}(x_k; B_{k+1}^n(x_{k+1}), 2\gamma_{k+1})$$

- New recursive updating method:

$$B_{k+1}^n = \operatorname{argmin}_B \mathbb{E} \|B(x_{k+1}) - x_{k+1} - F_k^n(x_k) + F_k^n(x_{k+1})\|^2$$

$$F_k^{n+1} = \operatorname{argmin}_F \mathbb{E} \|F(x_k) - x_k - B_{k+1}^n(x_{k+1}) + B_{k+1}^n(x_k)\|^2$$

- Approximate F and B as neural networks, and define forward steps:

$$x_{k+1} = F_\sigma^n(k, x_k) + \sqrt{2\gamma_{k+1}}Z,$$

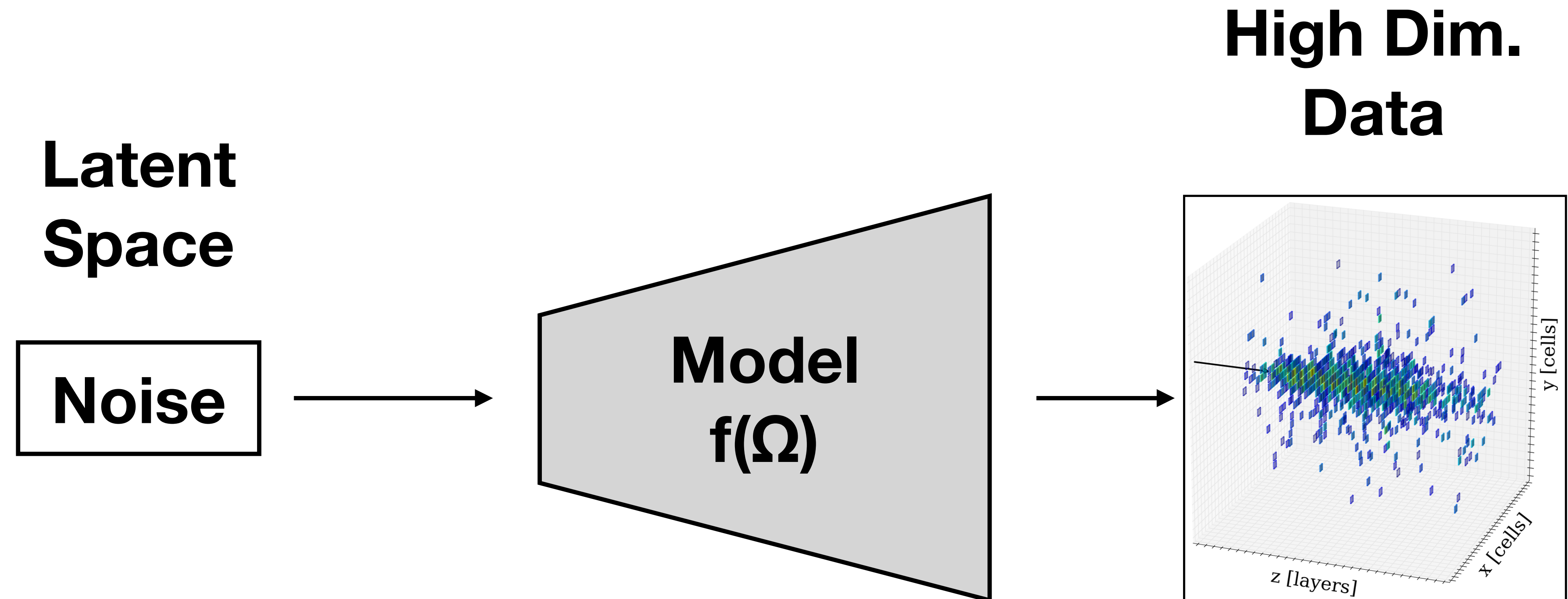
$$x_{k-1} = B_\theta^n(k, x_k) + \sqrt{2\gamma_k}\tilde{Z},$$

- Alternatingly fix F/B and update B/F



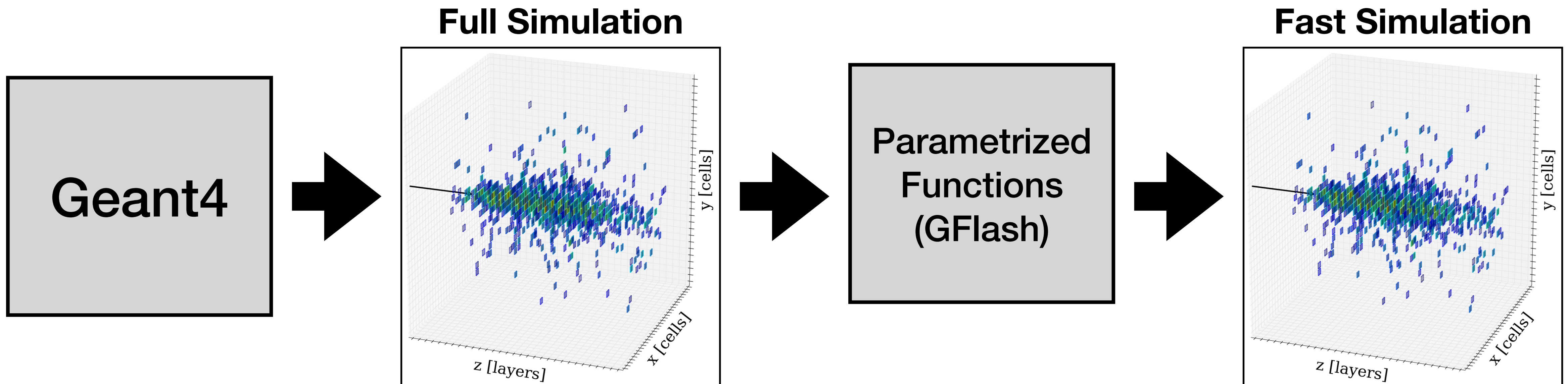
# Generative Fast Sim

Standard generative approach:  
Map random noise to new data



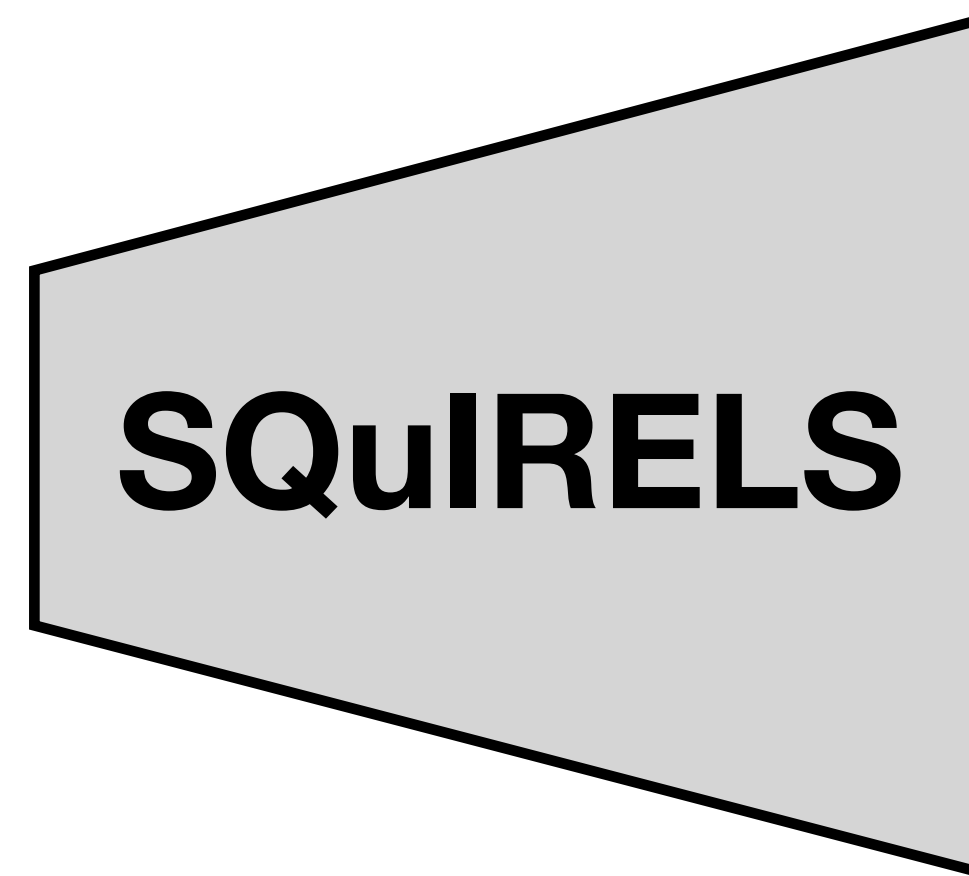
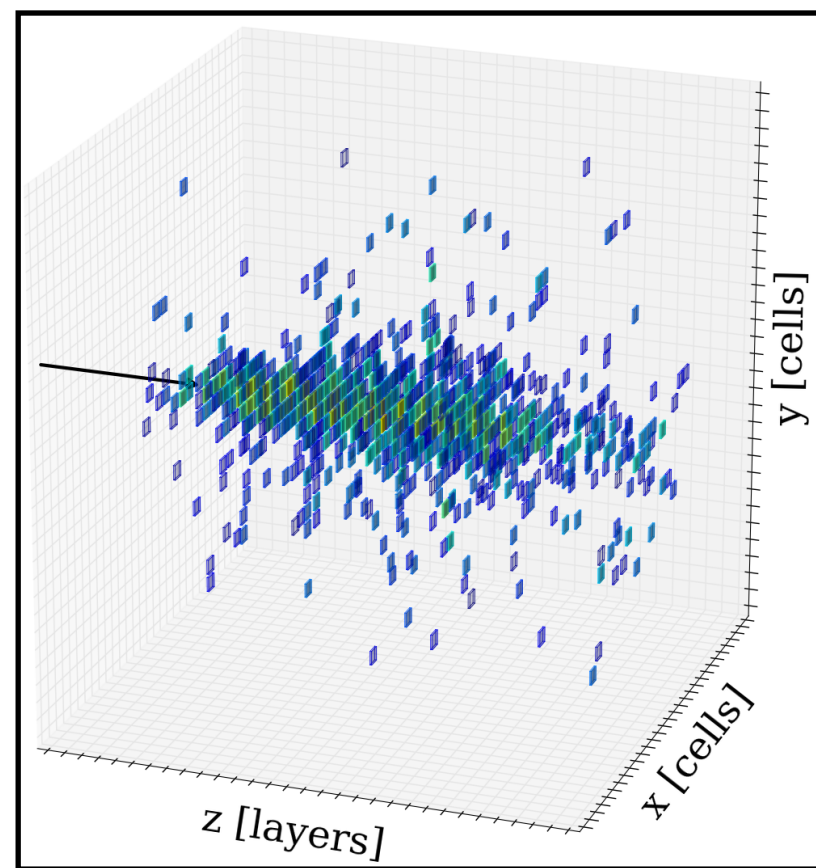
# Classical Fast Sim

- Build reference shower set using full sim
- Define parametrized functions on full sim showers
- Quickly sample from parametrized model

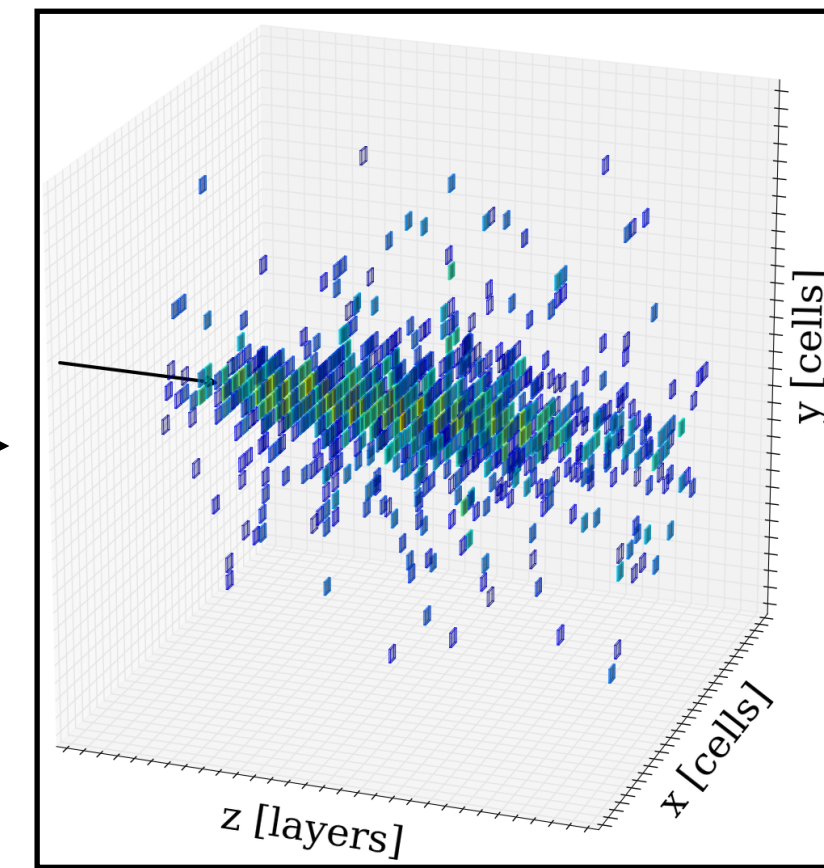


# SQURELS Setup

**Fast Simulation**

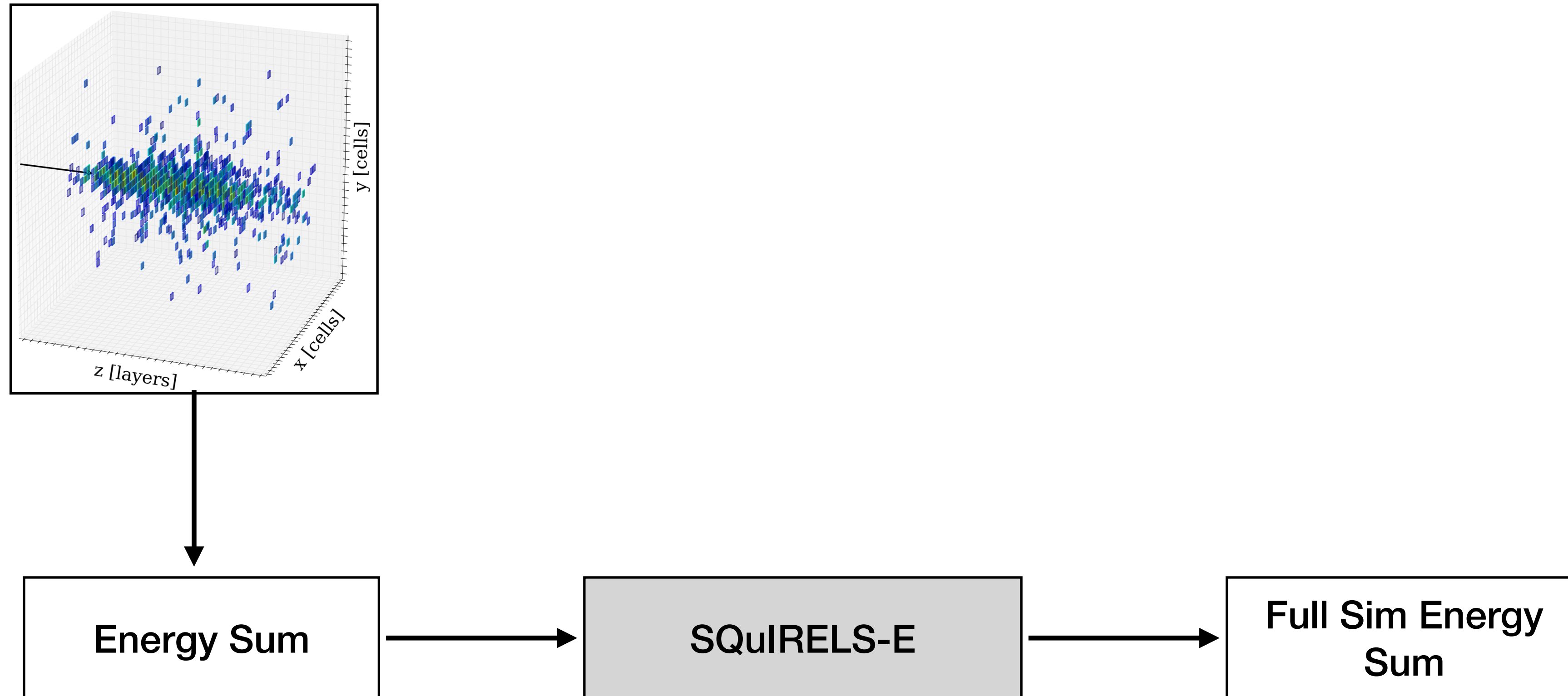


**Full Simulation**



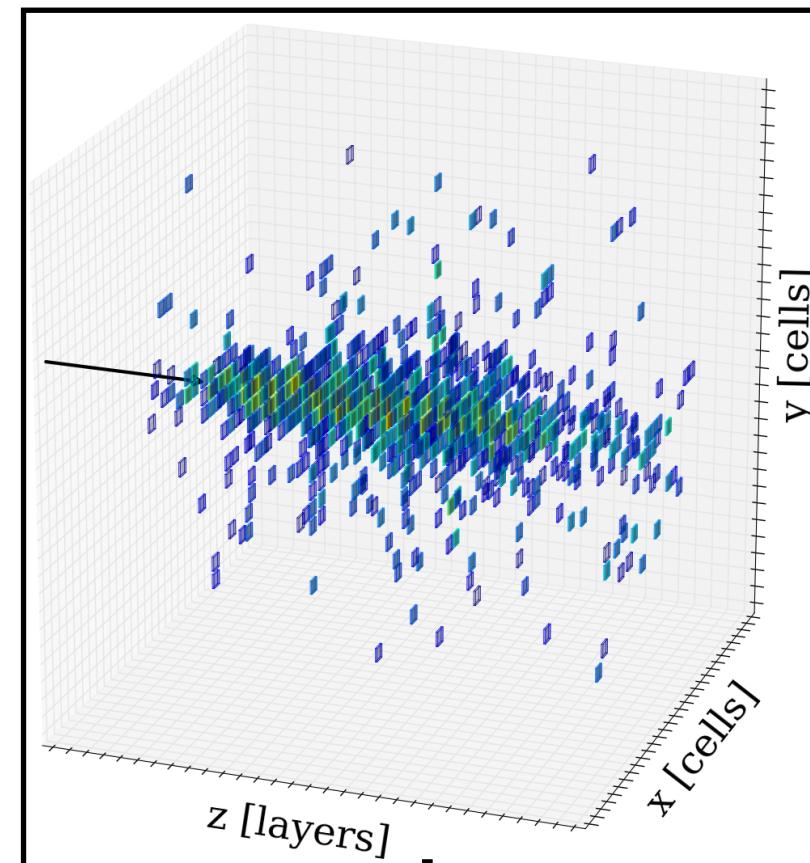
# SQURELS Setup

## Fast Simulation



# SQURELS Setup

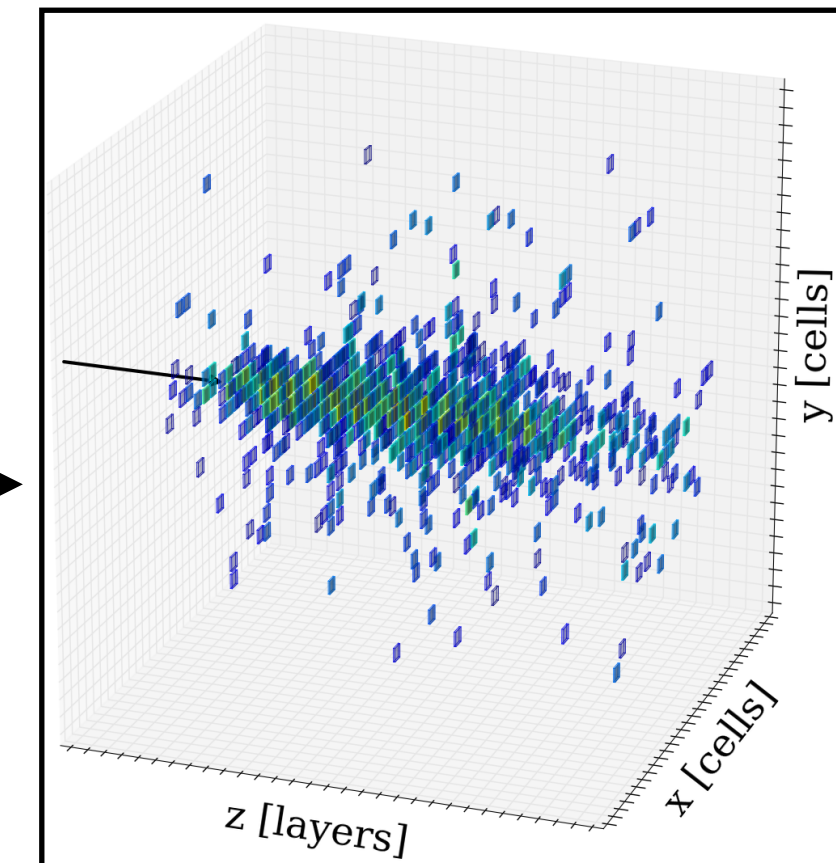
Fast Simulation



Energy Sum

SQURELS

Full Simulation



Full Sim Energy Sum

SQURELS-E

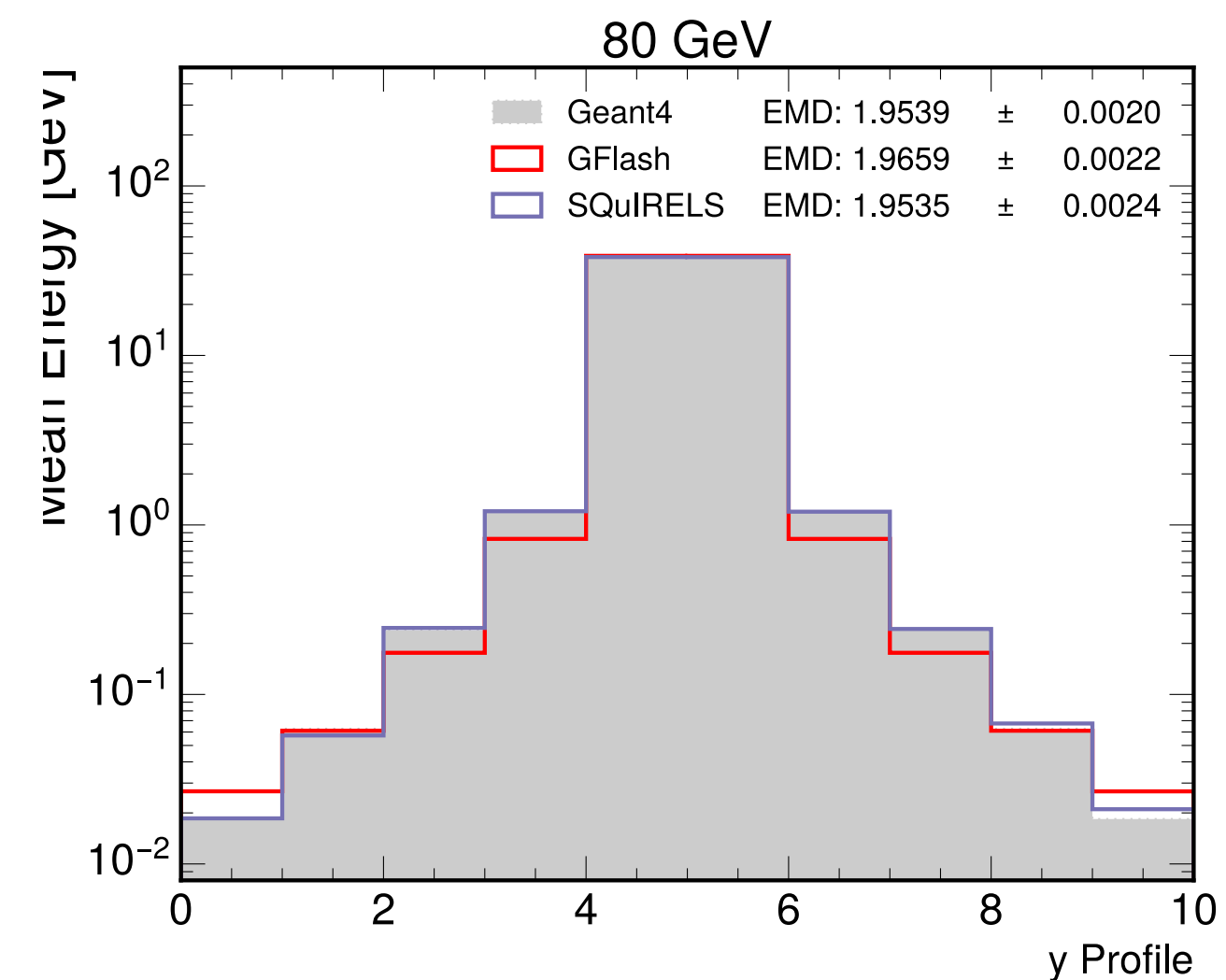
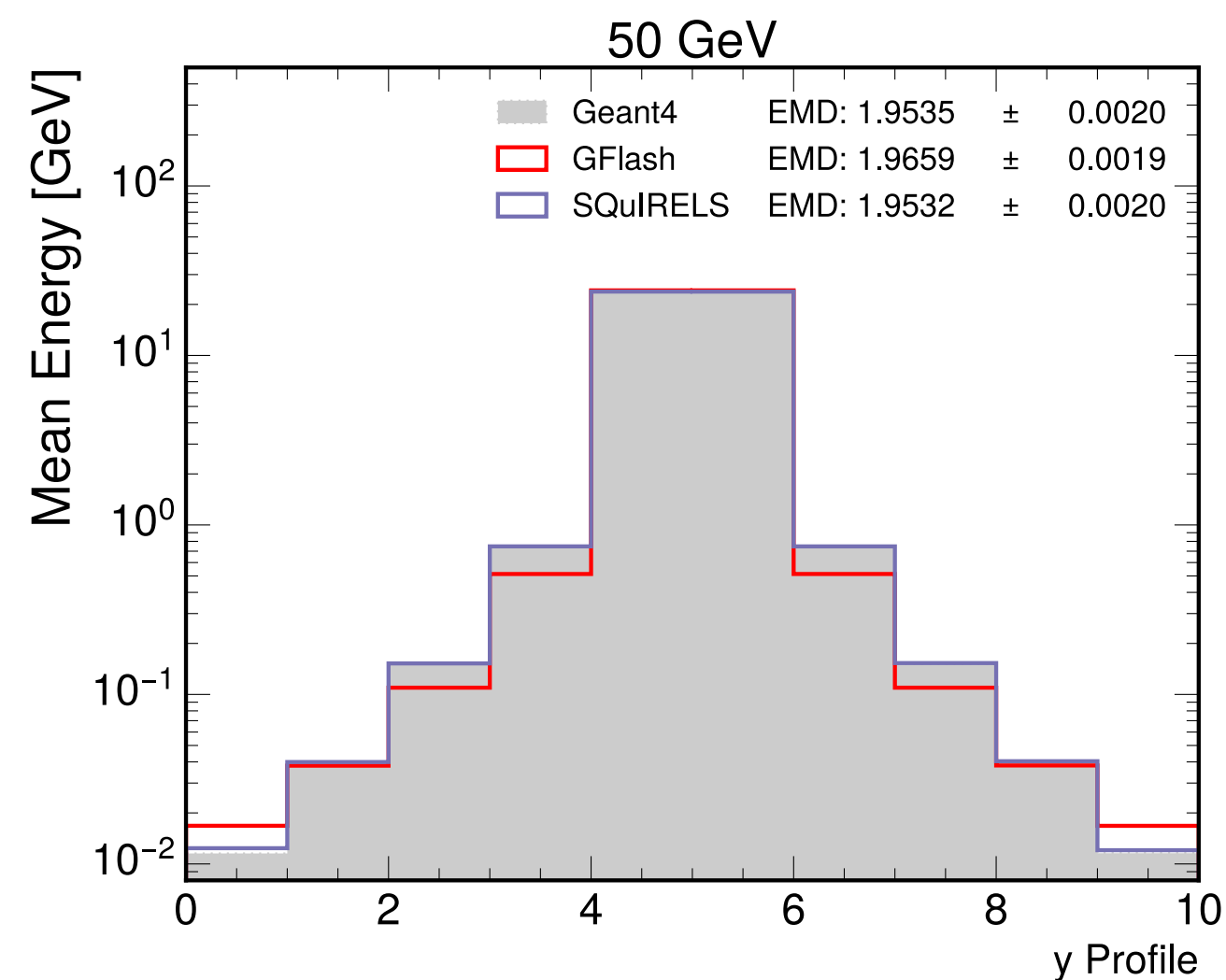
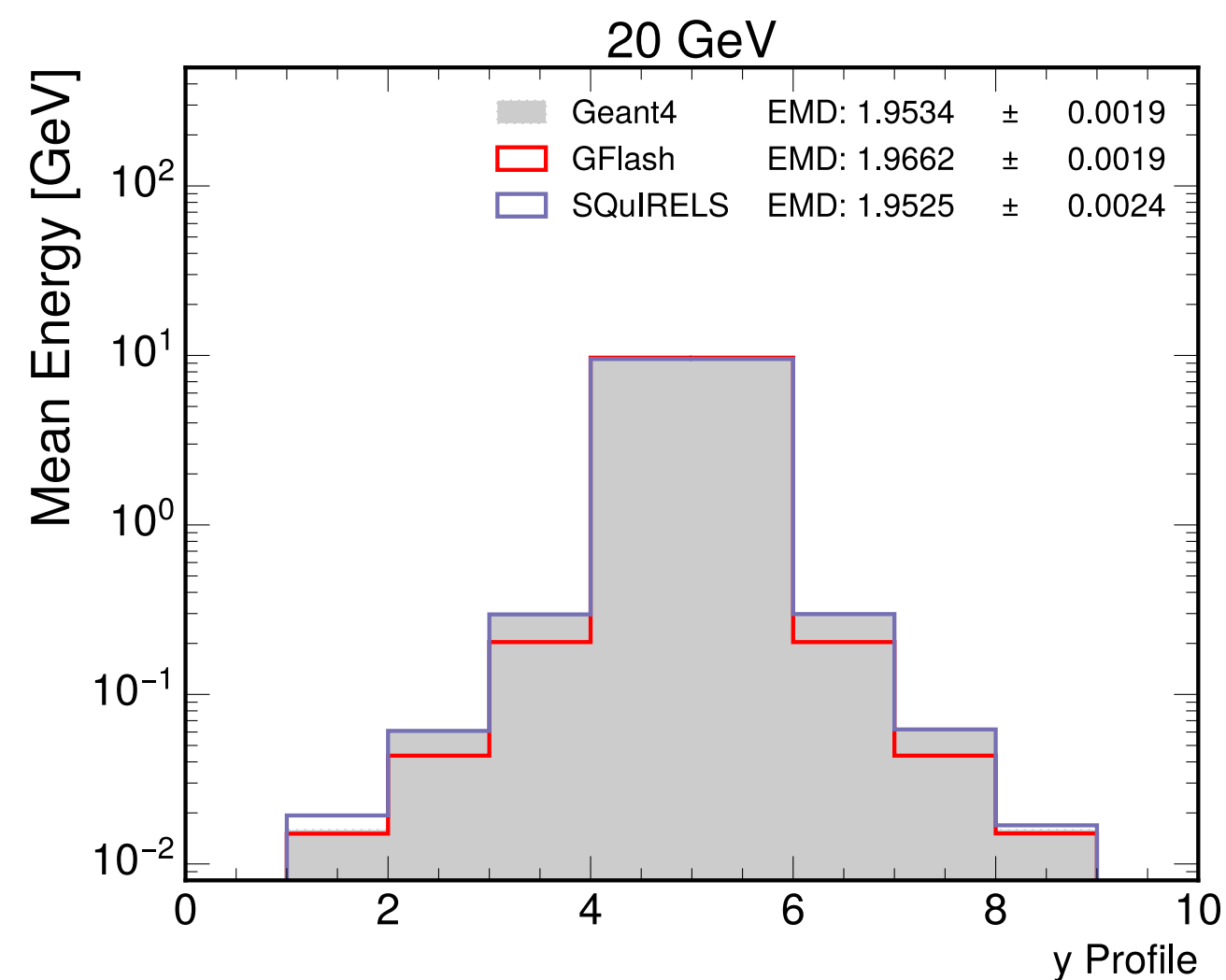
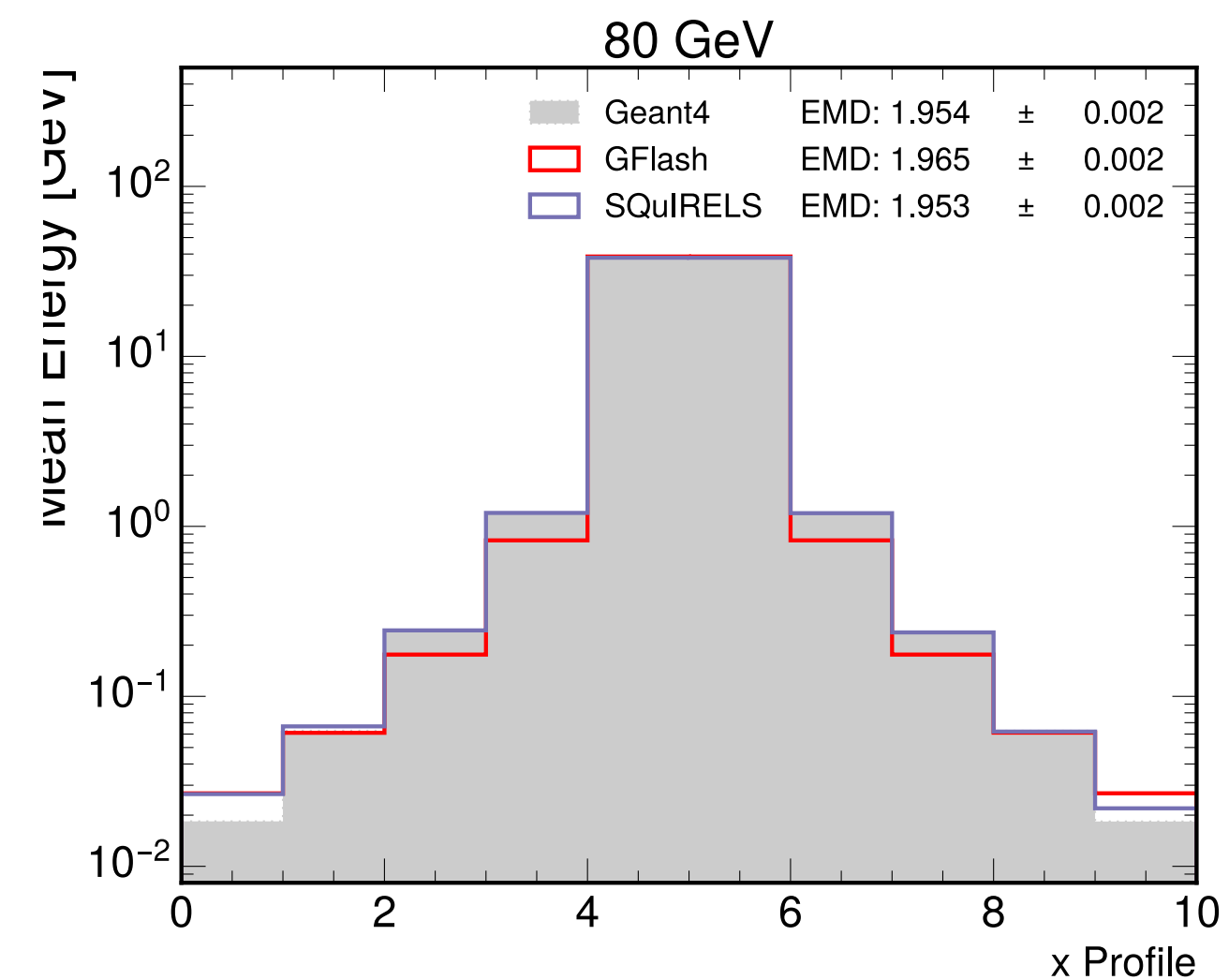
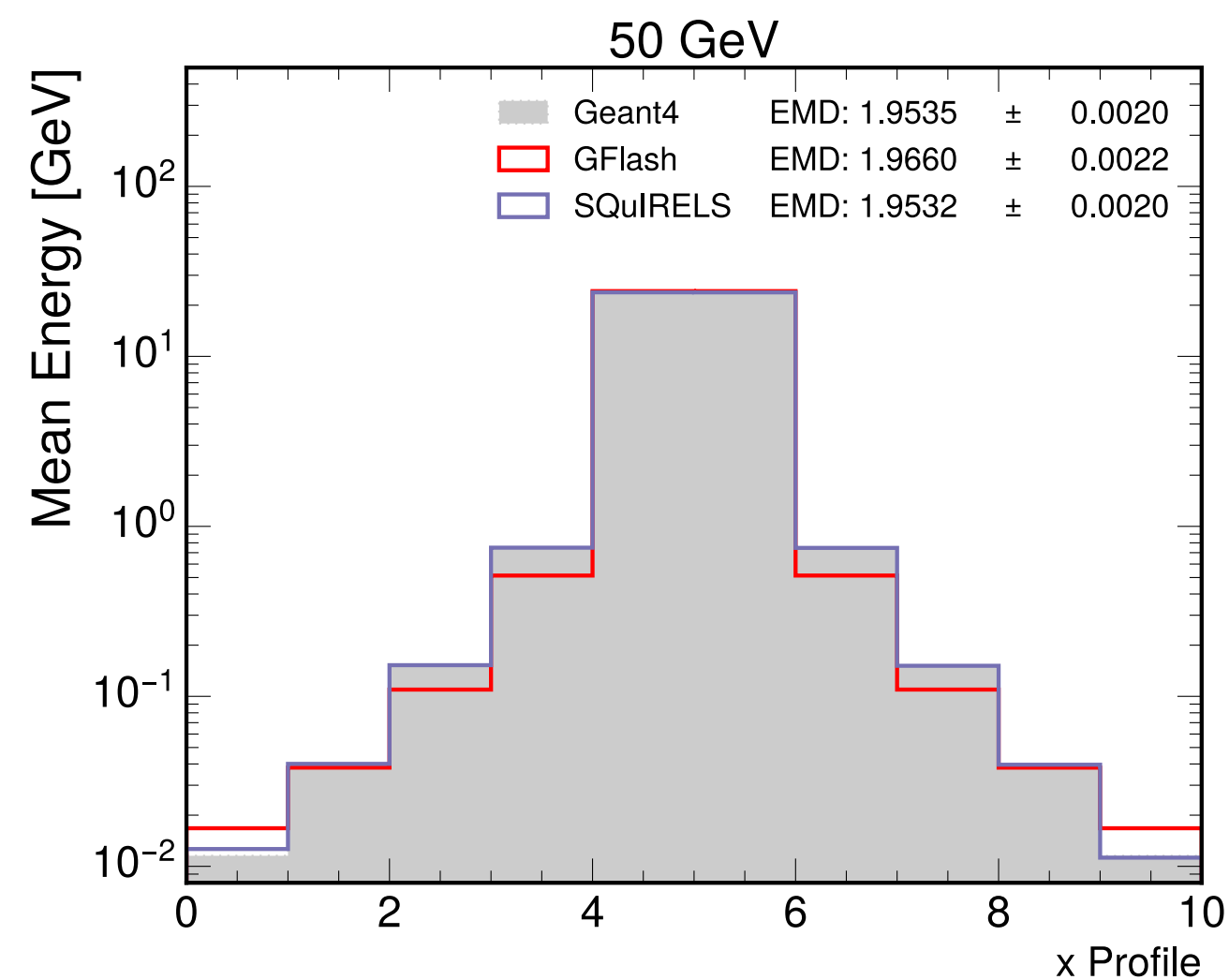
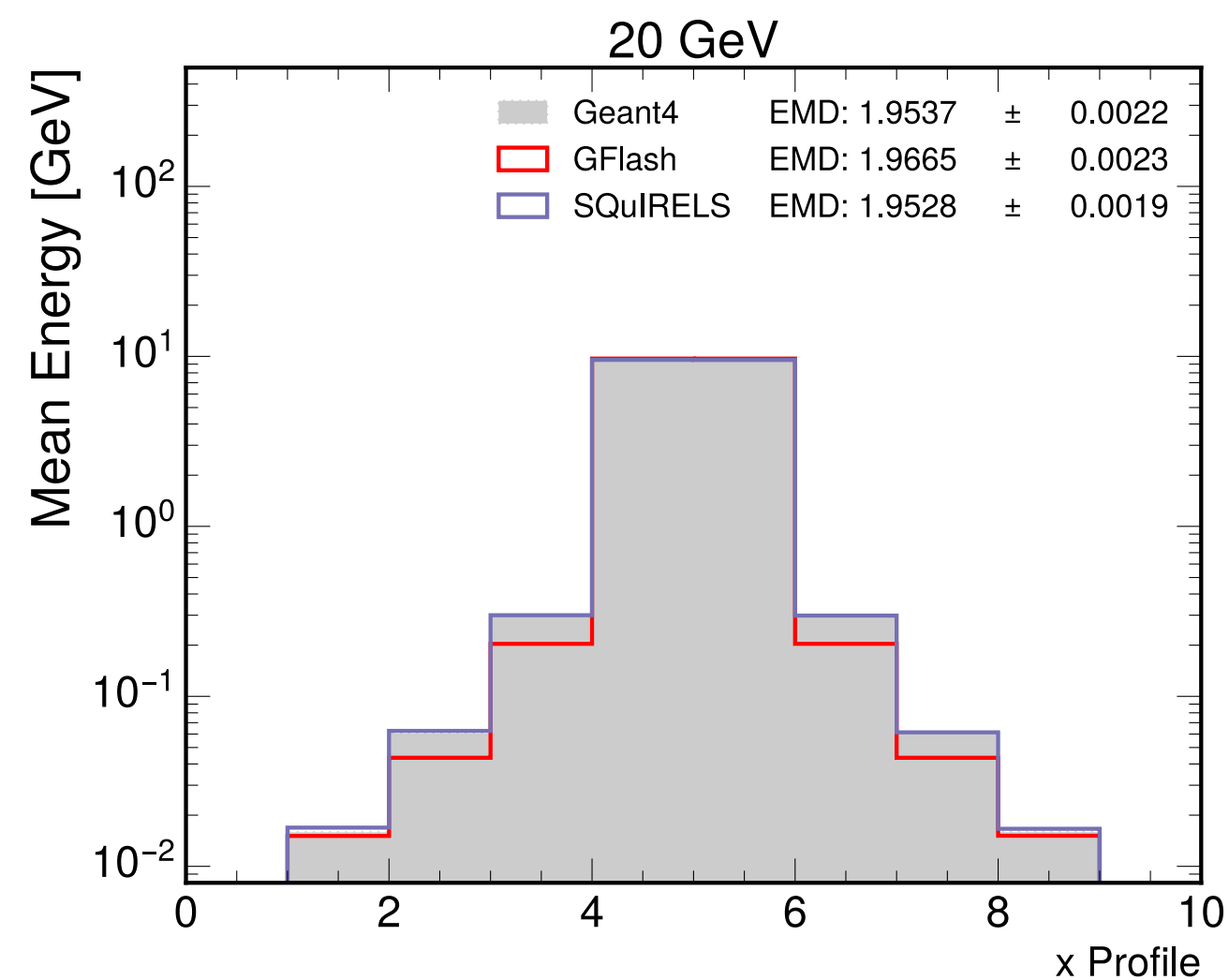
Re-Scale



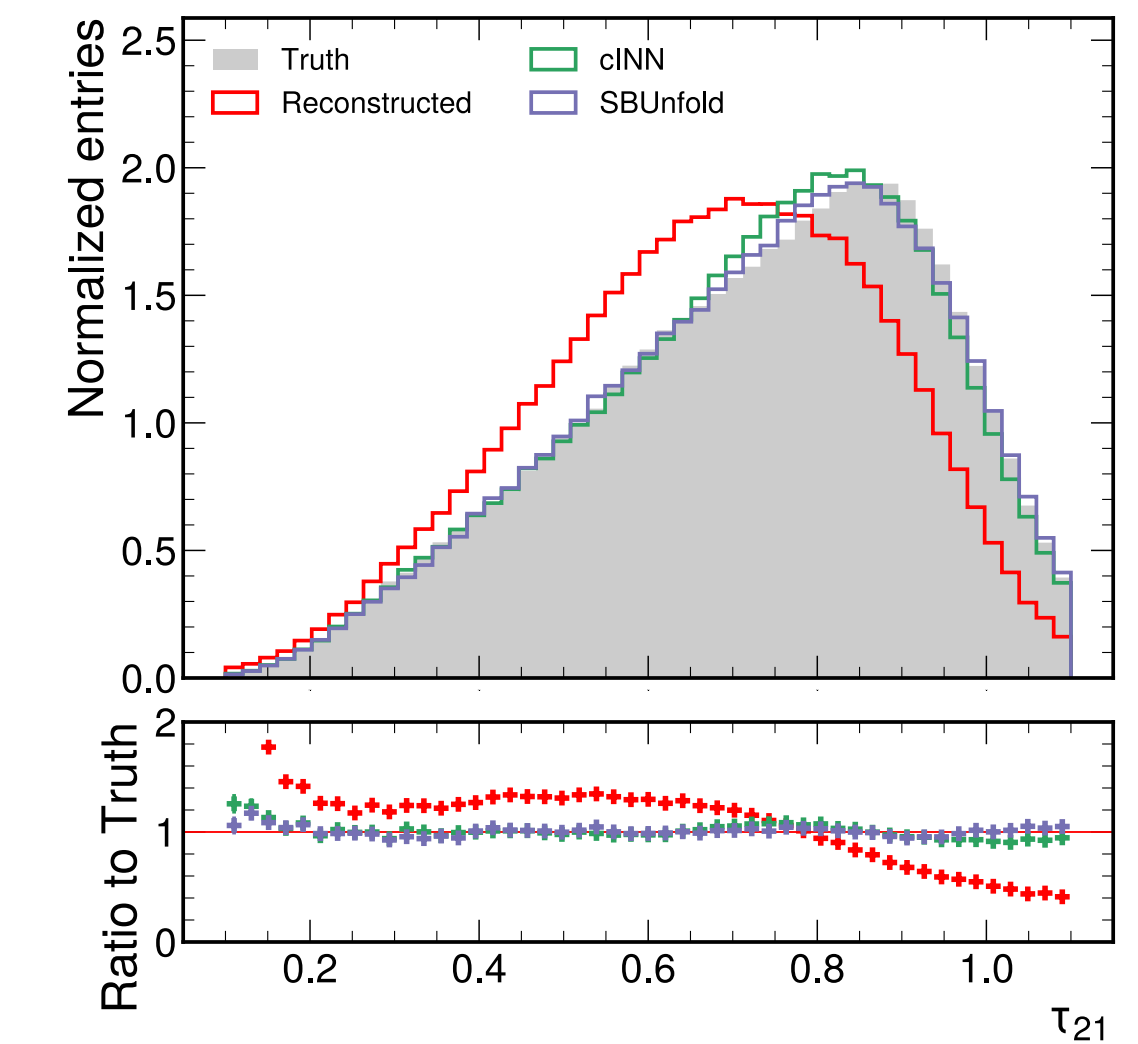
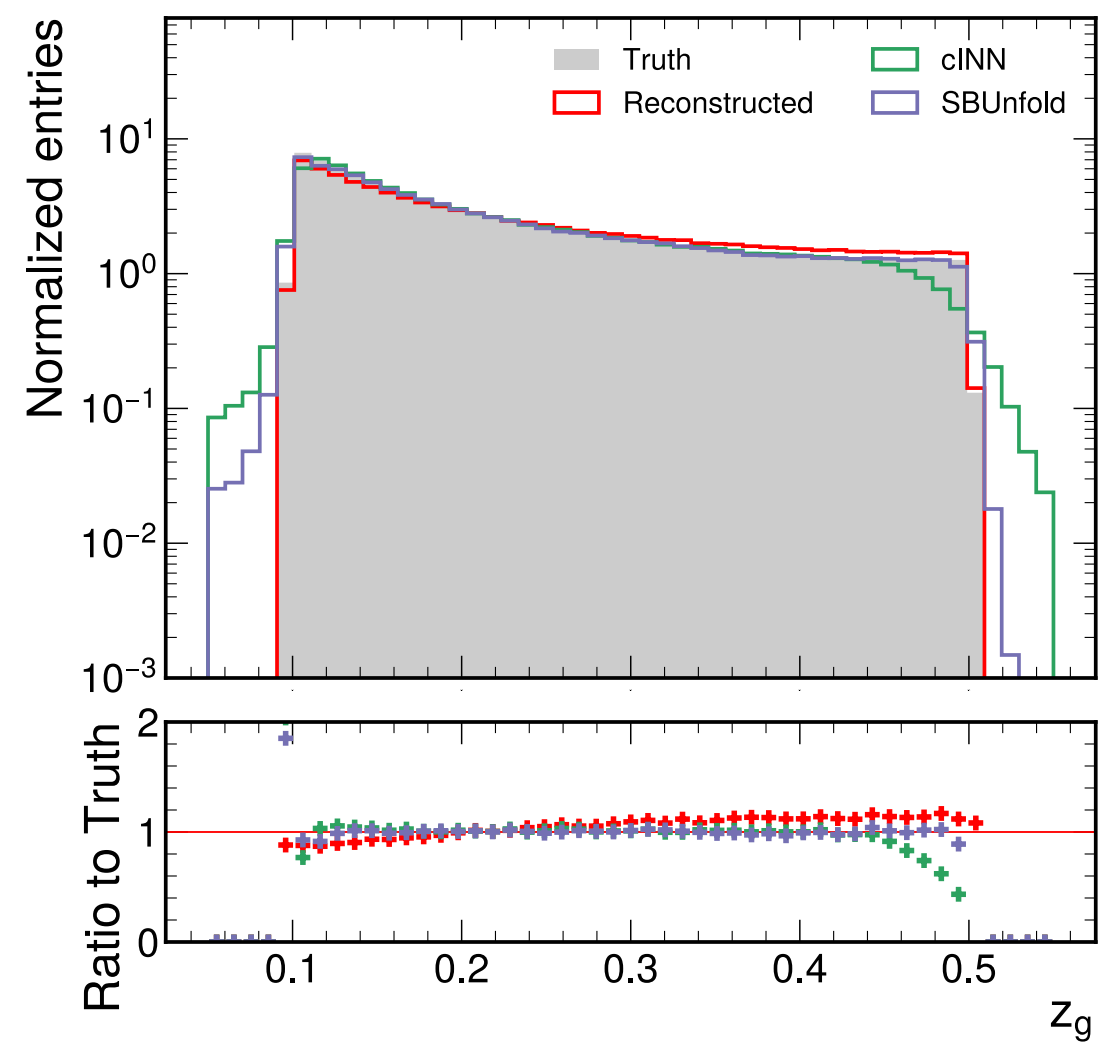
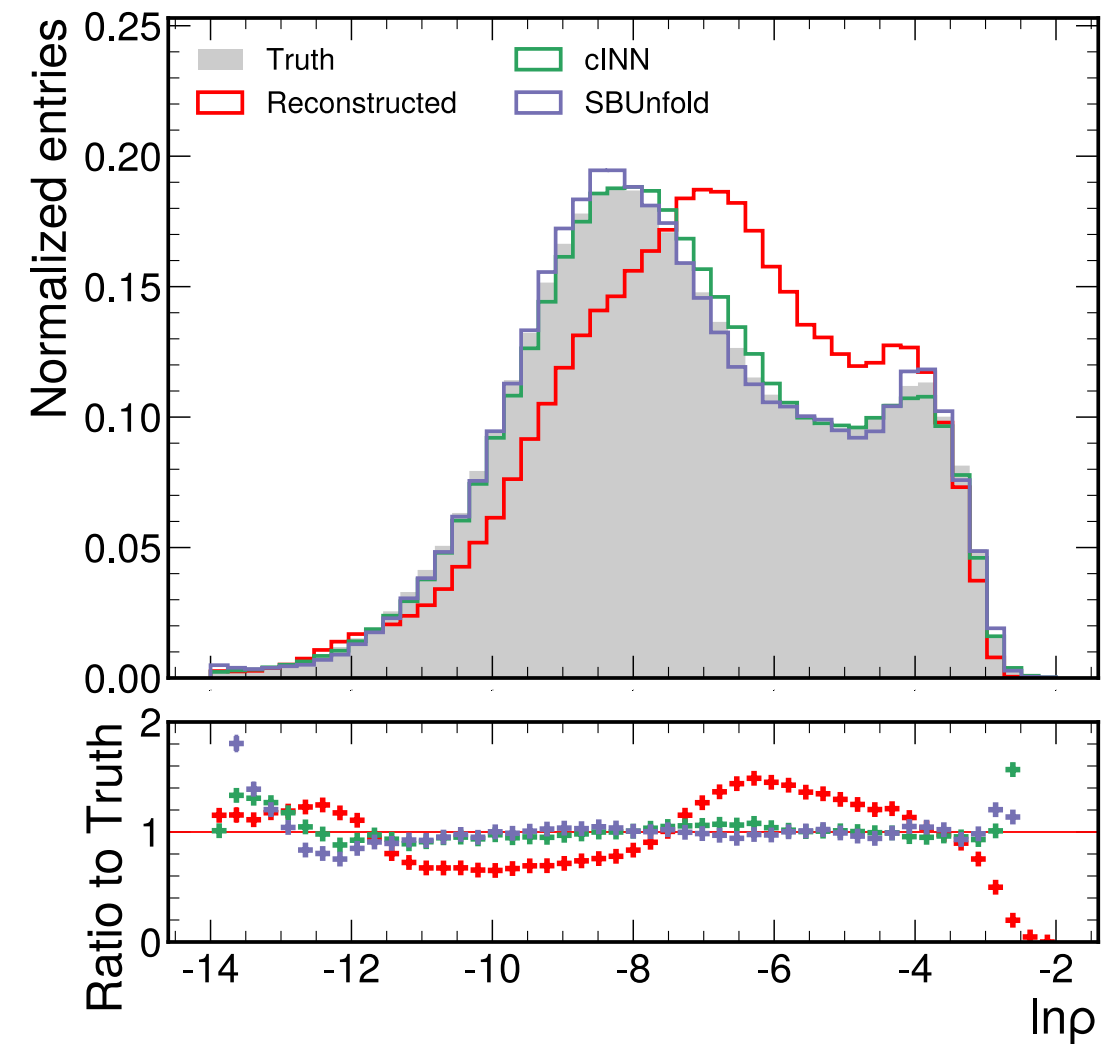
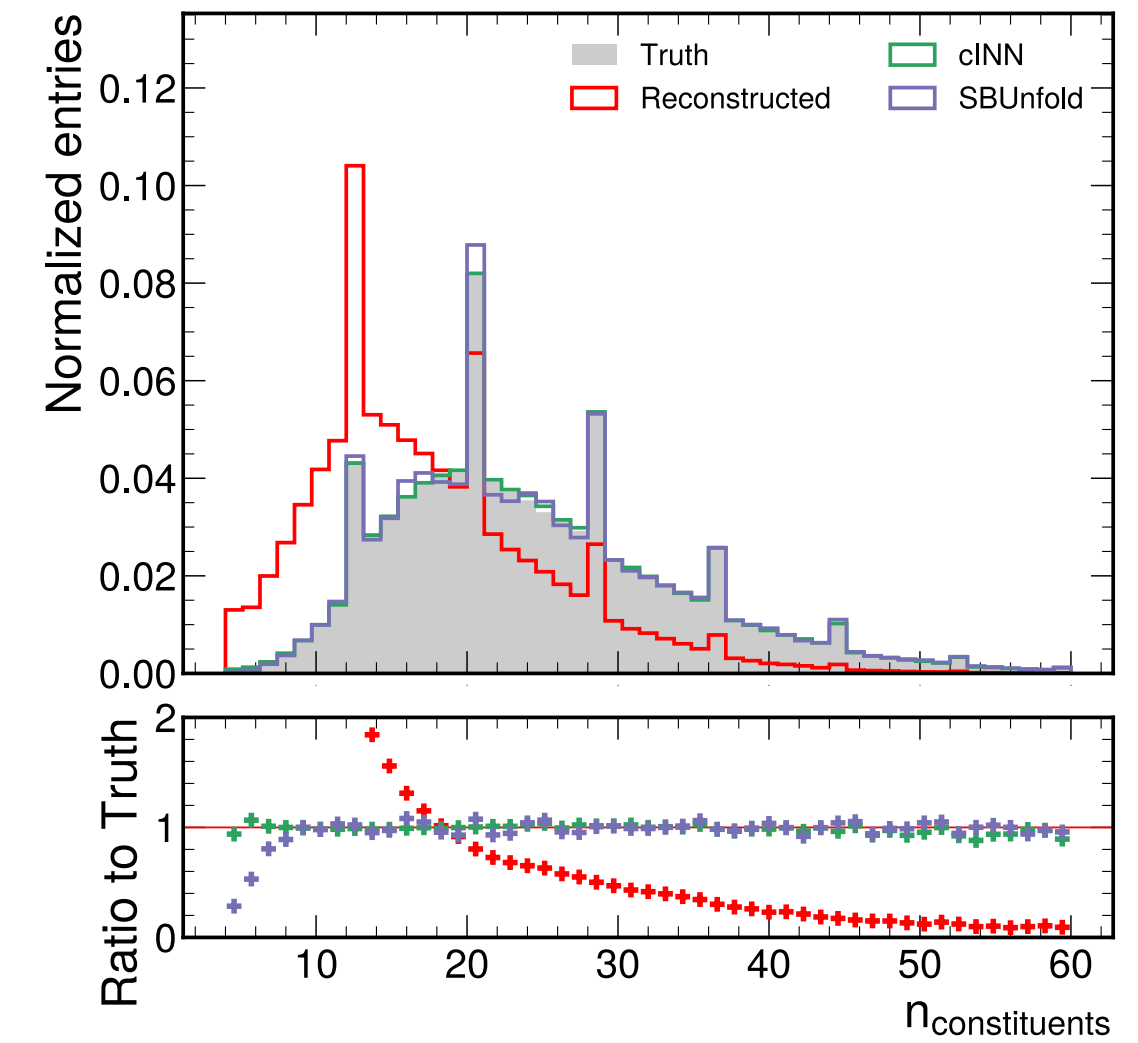
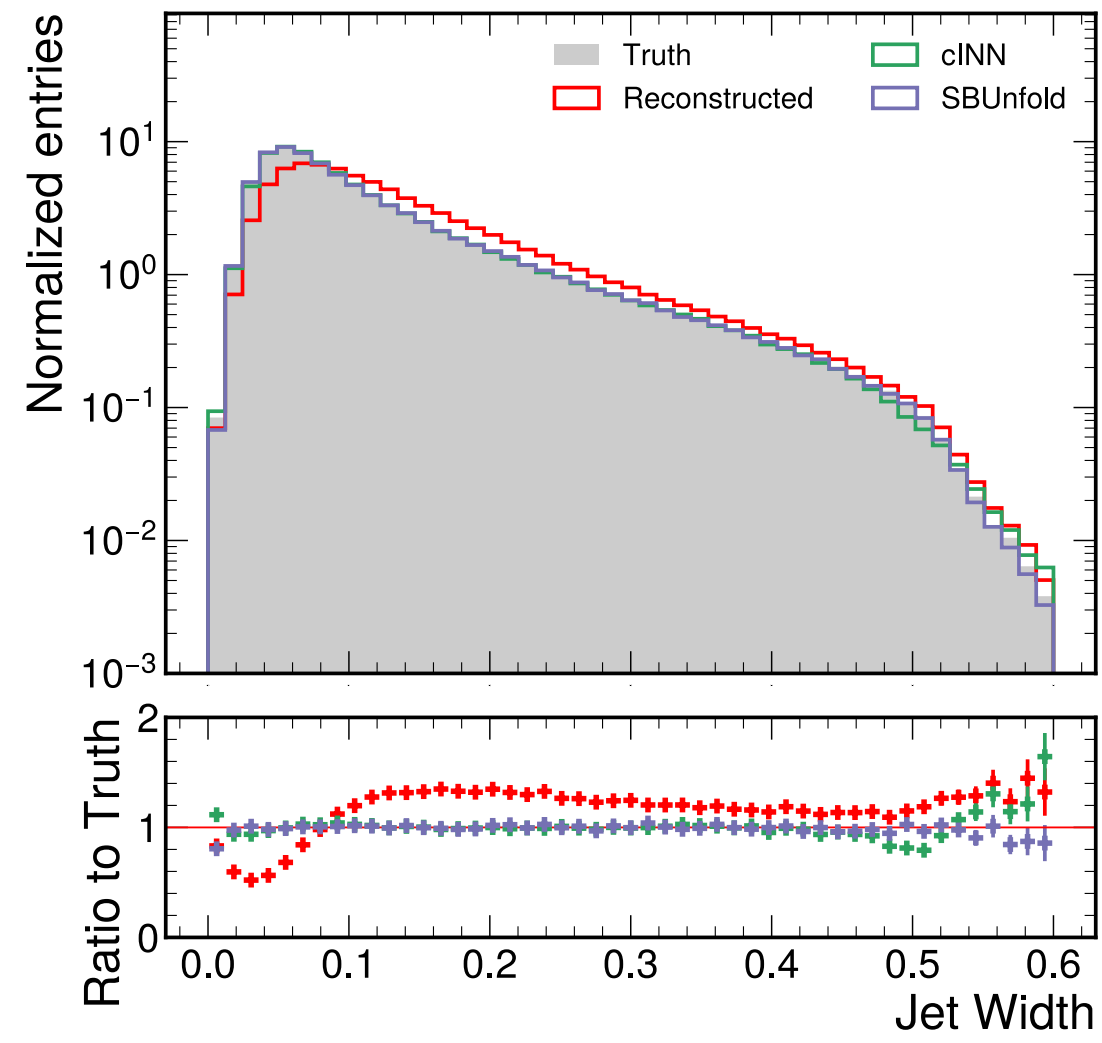
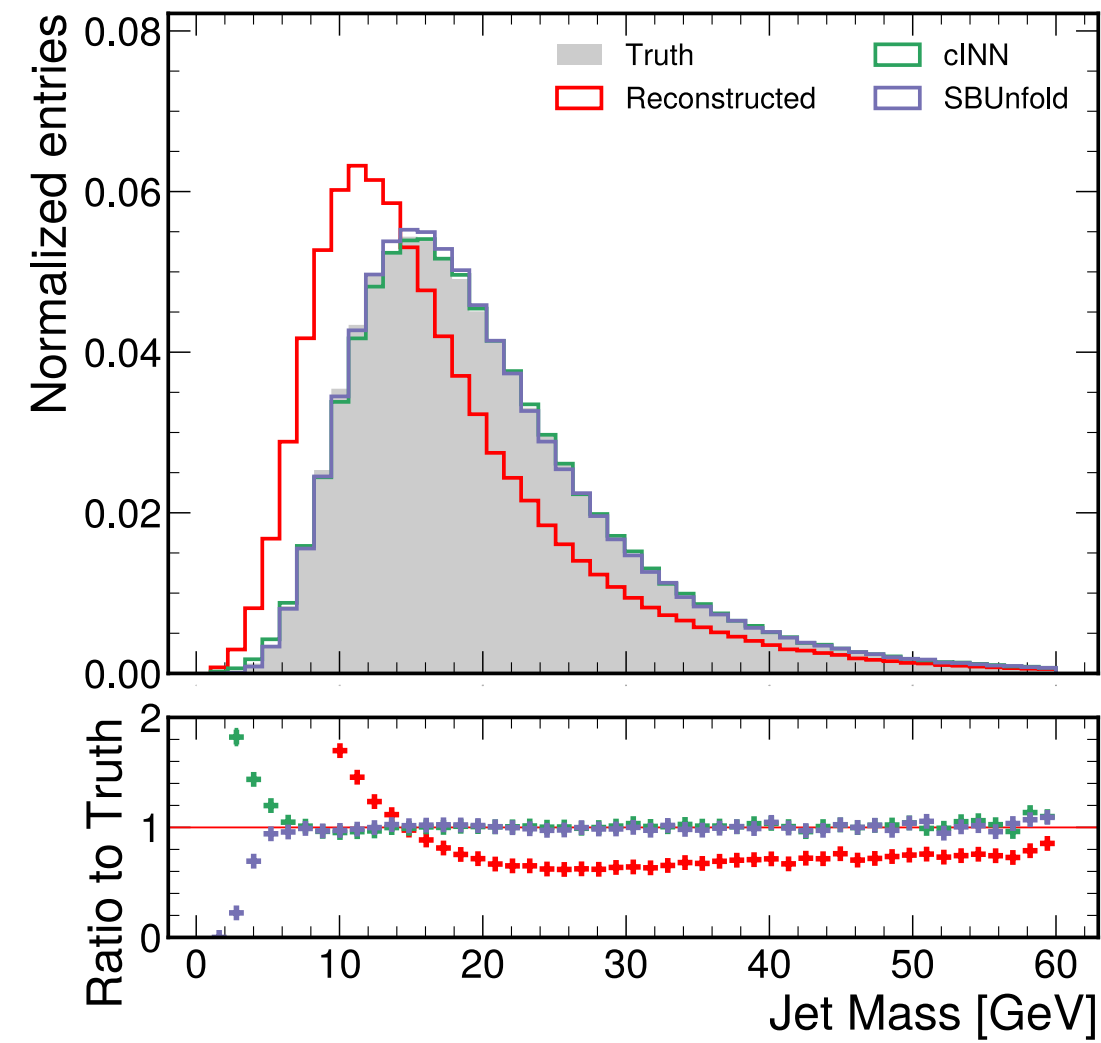
# Results

Observalbe	EMD		
	GEANT4	GFLASH	SQuIRELS
$E_{\text{sum}}$ 20 GeV	0.0003(1)	0.1184(2)	0.0061(2)
$E_{\text{sum}}$ 50 GeV	0.0009(2)	0.2599(6)	0.0147(4)
$E_{\text{sum}}$ 80 GeV	0.0016(5)	0.3906(8)	0.0288(8)
$E_{\text{spec}}$ 20 GeV	0.002(1)	0.018(2)	0.003(2)
$E_{\text{spec}}$ 50 GeV	0.006(4)	0.034(3)	0.007(4)
$E_{\text{spec}}$ 80 GeV	0.009(6)	0.051(6)	0.011(6)
$N_{\text{hit}}$ 20 GeV	0.015(4)	11.37(1)	1.32(1)
$N_{\text{hit}}$ 50 GeV	0.015(5)	11.84(1)	0.085(7)
$N_{\text{hit}}$ 80 GeV	0.013(4)	11.06(1)	1.45(1)
$E_{\text{max}}$ 20 GeV	0.0014(5)	0.3379(2)	0.0490(9)
$E_{\text{max}}$ 50 GeV	0.0021(7)	0.4342(4)	0.083(1)
$E_{\text{max}}$ 80 GeV	0.0027(9)	0.4757(5)	0.106(2)
profile <sub>x</sub> 20 GeV	1.954(2)	1.967(2)	1.953(2)
profile <sub>x</sub> 50 GeV	1.954(2)	1.966(2)	1.953(2)
profile <sub>x</sub> 80 GeV	1.954(2)	1.965(2)	1.953(2)
profile <sub>y</sub> 20 GeV	1.953(2)	1.966(2)	1.953(2)
profile <sub>y</sub> 50 GeV	1.954(2)	1.966(2)	1.953(2)
profile <sub>y</sub> 80 GeV	1.954(2)	1.966(2)	1.953(2)

# Profiles



# Pythia → Pythia (vs Diffusion)





# Pythia → Pythia (vs Diffusion)

Model	EMD( $\times 10$ )/Triangular Discriminator( $\times 10^3$ )		
	FPCD	cINN	SBUNFOLD
Jet mass	$0.74 \pm 0.08 / \mathbf{0.19}$	$1.4 \pm 0.2 / 0.29$	$\mathbf{0.70 \pm 0.06 / 0.30}$
Jet Width	$0.0087 \pm 0.0006 / 0.9$	$0.013 \pm 0.002 / 0.25$	$\mathbf{0.0029 \pm 0.0005 / 0.04}$
N	$0.81 \pm 0.06 / 0.1$	$2.3 \pm 0.8 / \mathbf{0.09}$	$\mathbf{0.57 \pm 0.04 / 0.9}$
$\log \rho$	$0.34 \pm 0.01 / 0.77$	$1.1 \pm 0.3 / \mathbf{0.64}$	$\mathbf{0.27 \pm 0.01 / 0.68}$
$z_g$	$0.035 \pm 0.007 / 12.4$	$0.095 \pm 0.003 / 10.9$	$\mathbf{0.009 \pm 0.001 / 3.1}$
$\tau_{21}$	$0.024 \pm 0.002 / 0.3$	$0.2 \pm 0.1 / 0.6$	$\mathbf{0.016 \pm 0.001 / 0.2}$