

Hyperbolic Machine Learning for Jet Physics

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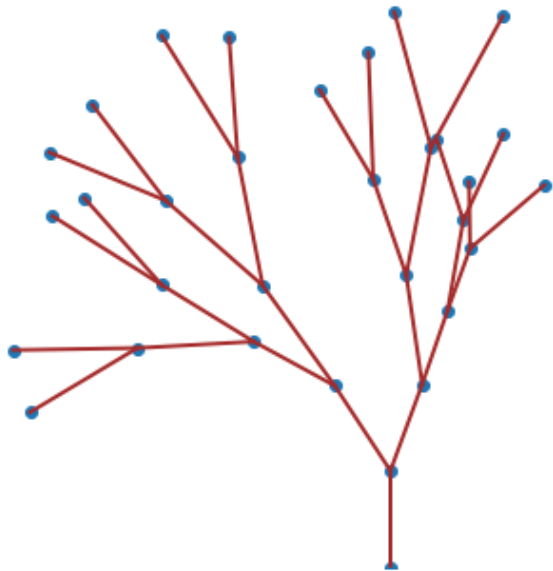
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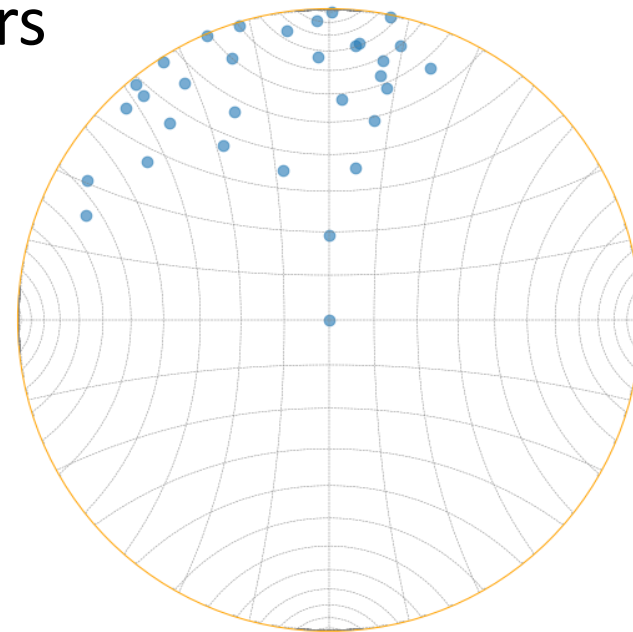
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Motivation

- Optimal representations of jets are key for maximizing performance
- New jet representation fruitful for jet analysis (ParticleNet Qu et al. 1902.08570)
- Non-Euclidean geometries provide a powerful method to better represent physics data & reduce parameters



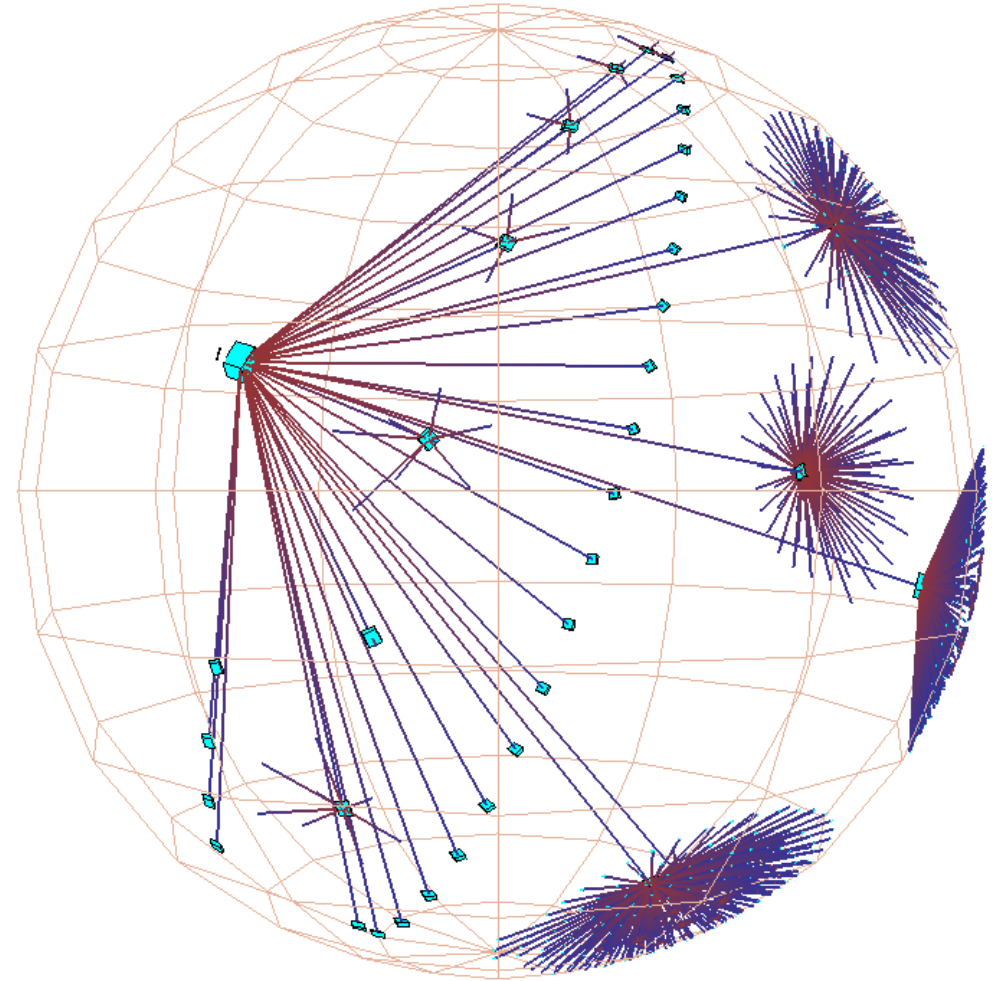
Graph Representation



Non-Euclidean Representation

Overview

- Hyperbolic geometries naturally represent inherent hierarchies
 - Exponential growth in surface area with distance
- Showering & hadronization exhibits hierarchical structure [Park et al. 2208.05484]
- Investigate optimal representation geometry
 - Quark & gluon jets exhibit varying jet curvature
- Need non-Euclidean aspect to fully represent jets?



Munzner, Tamara. "Exploring Large Graphs in 3D Hyperbolic Space"

Goals

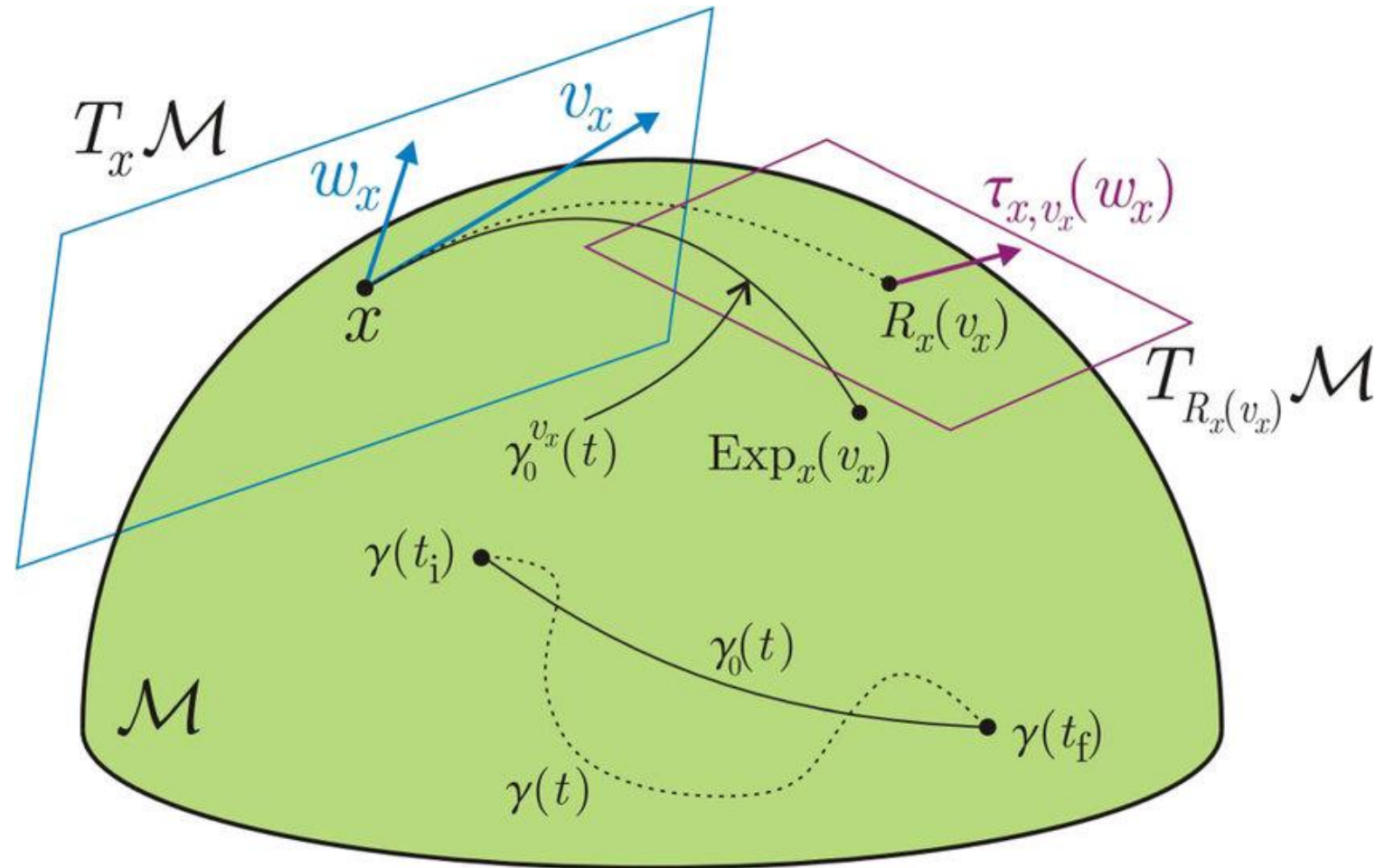
Demonstrate **equivalence** or **superiority** of geometric representations

Develop **low-parameter** models for jet classification in non-Euclidean geometries

Mathematical Prerequisites

Riemannian Manifolds

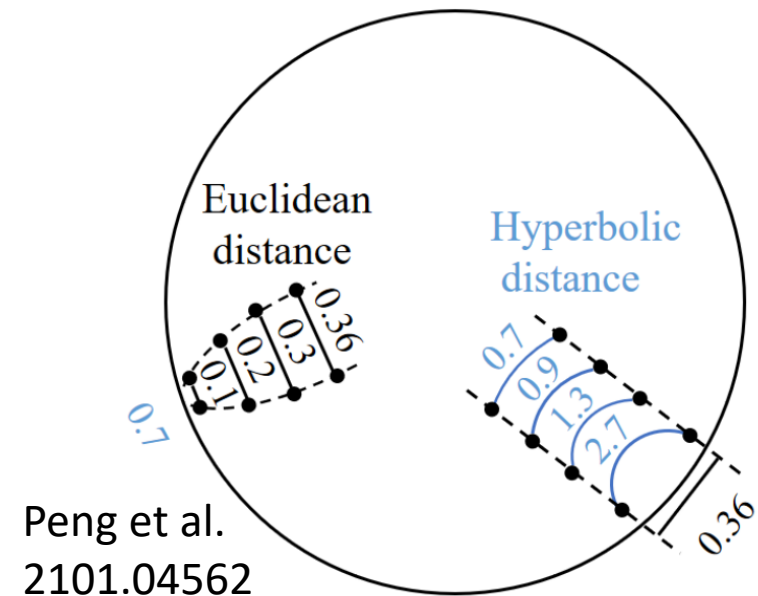
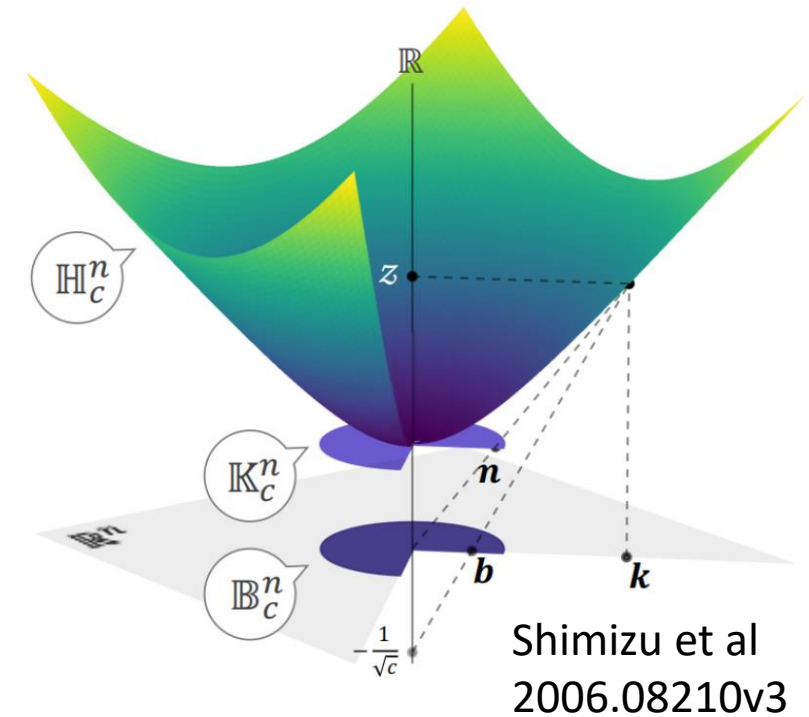
- Riemannian manifold M is a **real, smooth manifold** with a **positive definite inner product** on the tangent space $T_x M$ at each point.
- $Exp_x(v_x): T_x M \rightarrow M$
- $Log_x(z): M \rightarrow T_x M$



Luchikov et al. 2007.01287

Hyperbolic Geometry

- 5 Isometric representations: we choose the **Poincaré ball**
- Gyrovectors spaces **replaces vector space** through Möbius transformations
- Employ the follow geometries:
 - Flat: E^n
 - Hyp: B_c^n
 - Simple Product: $E^{\frac{n}{2}} \times B_c^{\frac{n}{2}}$
 - QG Product: $E^{\frac{n}{3}} \times B_{c_{quark}}^{\frac{n}{3}} \times B_{c_{gluon}}^{\frac{n}{3}}$



Gromov– δ Curvature

A metric space (X, d) is δ –hyperbolic iff for all $x, y, u, v \in X$

$$(d(x, y) + d(u, v)) - (d(x, u) + d(y, v)) \leq 2\delta$$

- Define space by min δ
- δ –hyperbolicity metric notion of **tree-likeness** [Adcock et al. 2013]
- **δ computable from jet data**

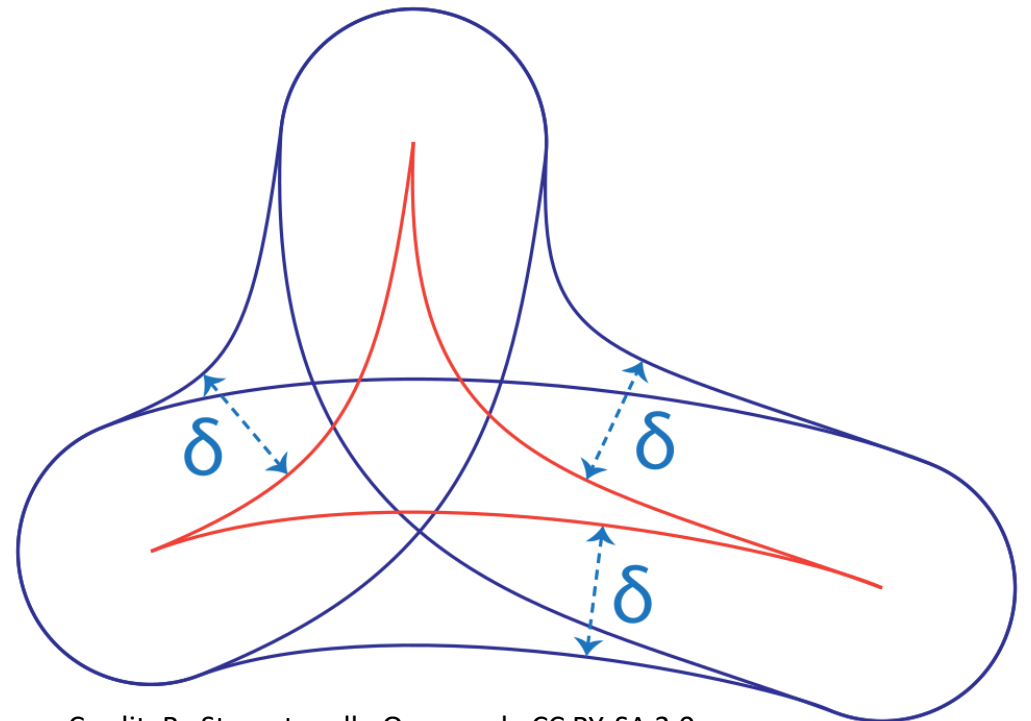


Image Credit: By Stomatapoll - Own work, CC BY-SA 3.0,
<https://commons.wikimedia.org/w/index.php?curid=22898943>

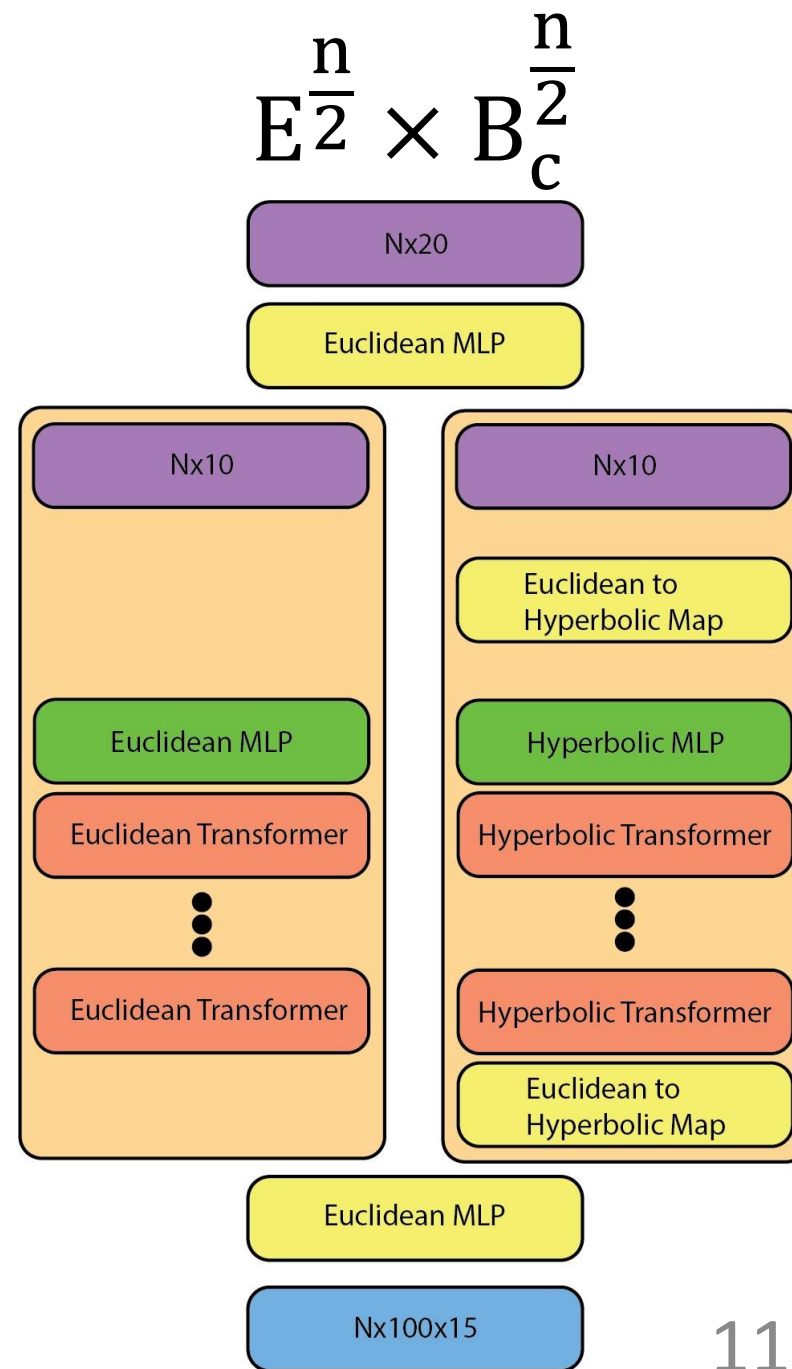
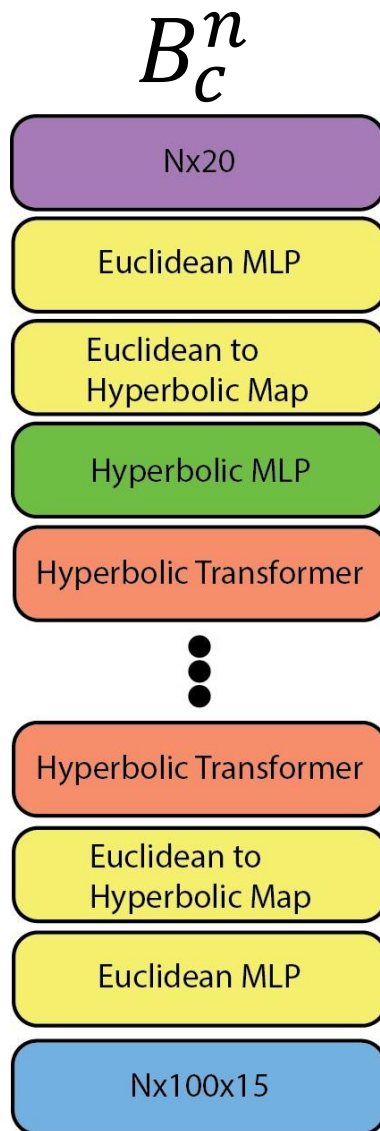
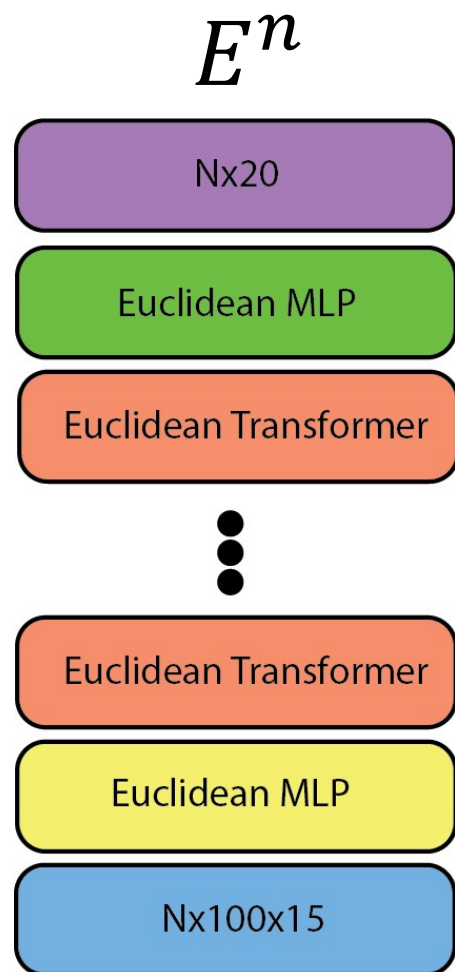
Riemannian Analogs for Euclidean ML

Euclidean	Riemannian Analog
Fully connected layer	Gyrovector matrix formulation or robust formulation from [Shimizu et al. 2006.08210v3]
Batch normalization	Differentiable Fréchet batch norm by [Lou et al. 2003.00335]
Attention aggregation	Hyperbolic distance metric & Einstein weighted midpoint
Optimization algorithms	Manifold aware versions of Adam, SGD, Lion

*Implementation specifics in *Additional Slides*

Model Architectures

Model Architectures



Physics Results

Quark Gluon Dataset Overview

- Public Quark-Gluon [Jet Class](#) dataset from Qu et al.
- 2 million training, 200k validation
- Zero-padded highest 100 pT particles per jet
- Particle features:
 - Particle pT/Jet pT
 - p_x, p_y, p_z
 - η, ϕ
 - $\Delta\eta, \Delta\phi$
 - Charge
 - Particle hot encoding

Curvature Calculation for Quark & Gluon Jets

Initial geometry: B_c and $E \times B_c$, c is calculate from entire Q-G dataset

- $c = 1.139$

Q-G Curvatures: $E \times B_{c_{quark}} \times B_{c_{gluon}}$, calculate c separately

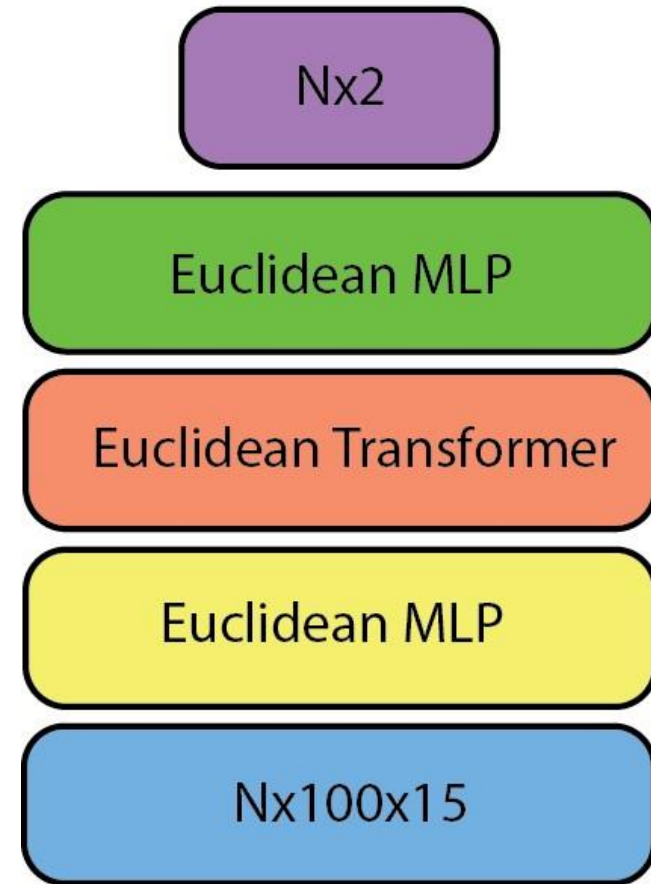
- $c_{quark} = 4.925$

- $c_{gluon} = 1.086$

Different physics can manifest through different curvature

Initial Tests

- Bottleneck models to output 2D representation of jet
 - **Only possible** 2D geometries are E^2 and B_c^2
- Minimize model architecture
- Scan over broad range of total model parameters



Example model

Results 2D Bottlenecking

Params	Flat ROC	Hyp ROC	Flat SE @ 5%	Hyp SE @ 5%
0.9k	0.8711	0.8769	0.4499	0.4521
1.4k	0.8823	0.8871	0.4660	0.4800
3.1k	0.8889	0.8880	0.4874	0.4886
9.4k	0.8821	0.8928	0.4604	0.4905
33k	0.8941	0.8947	0.5002	0.5095

Product Space Geometric Learning

Inspired by work from Gu et al. 2019

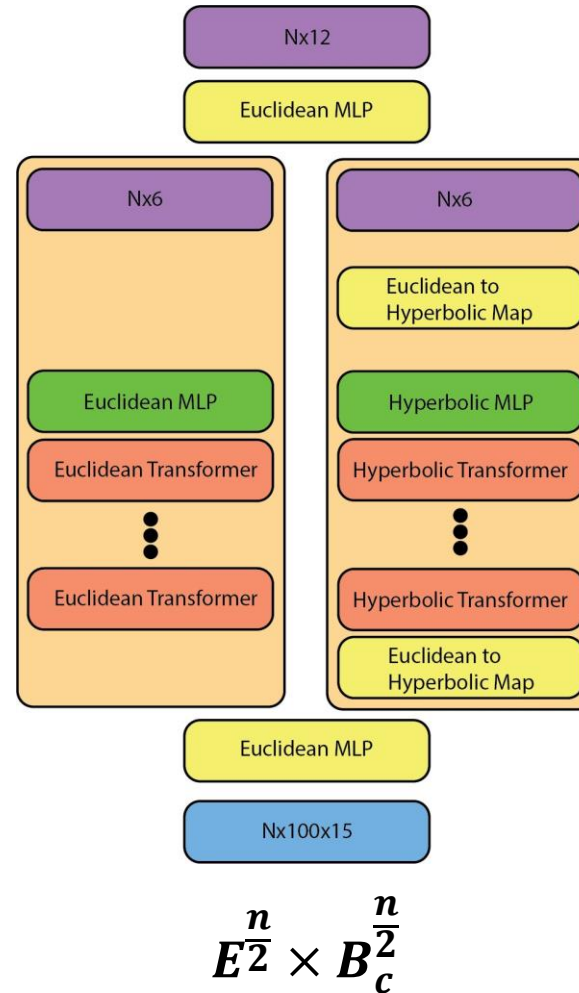
Product Space models

- Hyperbolic geometries succeed on small param models & low dimensions
- Now we explore physically motivated product space representations in 12D:

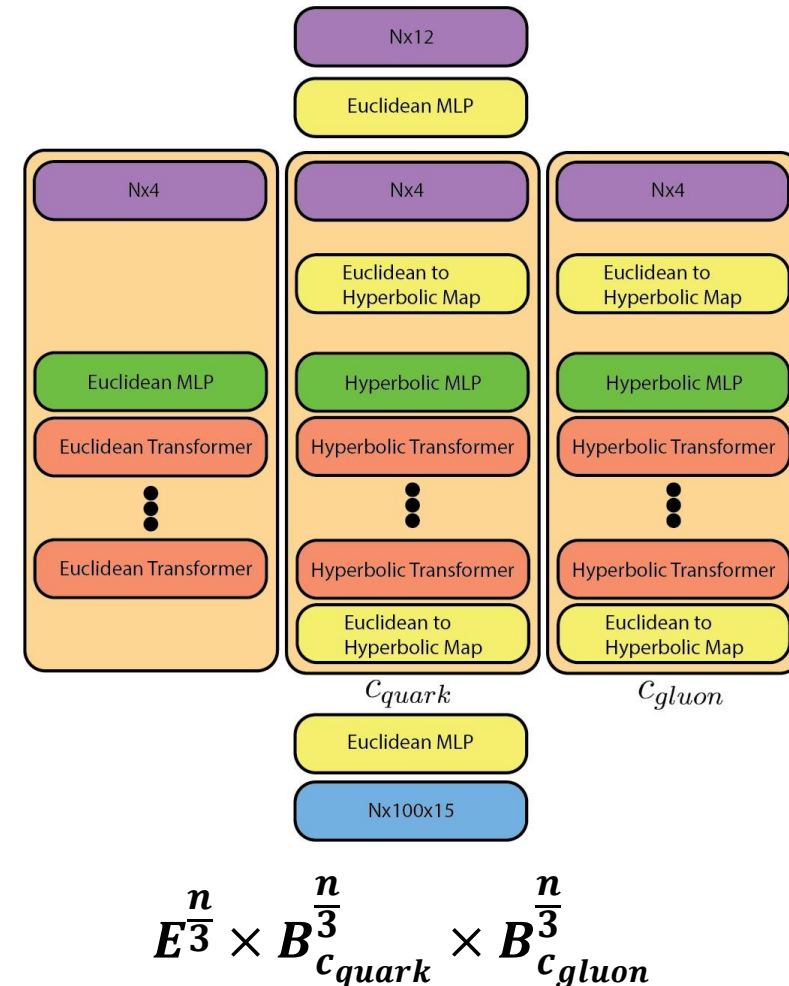
- Simple Product: $E^{\frac{n}{2}} \times B^{\frac{n}{2}}_c$

- QG Product:

$$E^{\frac{n}{3}} \times B^{\frac{n}{3}}_{c_{quark}} \times B^{\frac{n}{3}}_{c_{gluon}}$$



$$E^{\frac{n}{2}} \times B^{\frac{n}{2}}_c$$

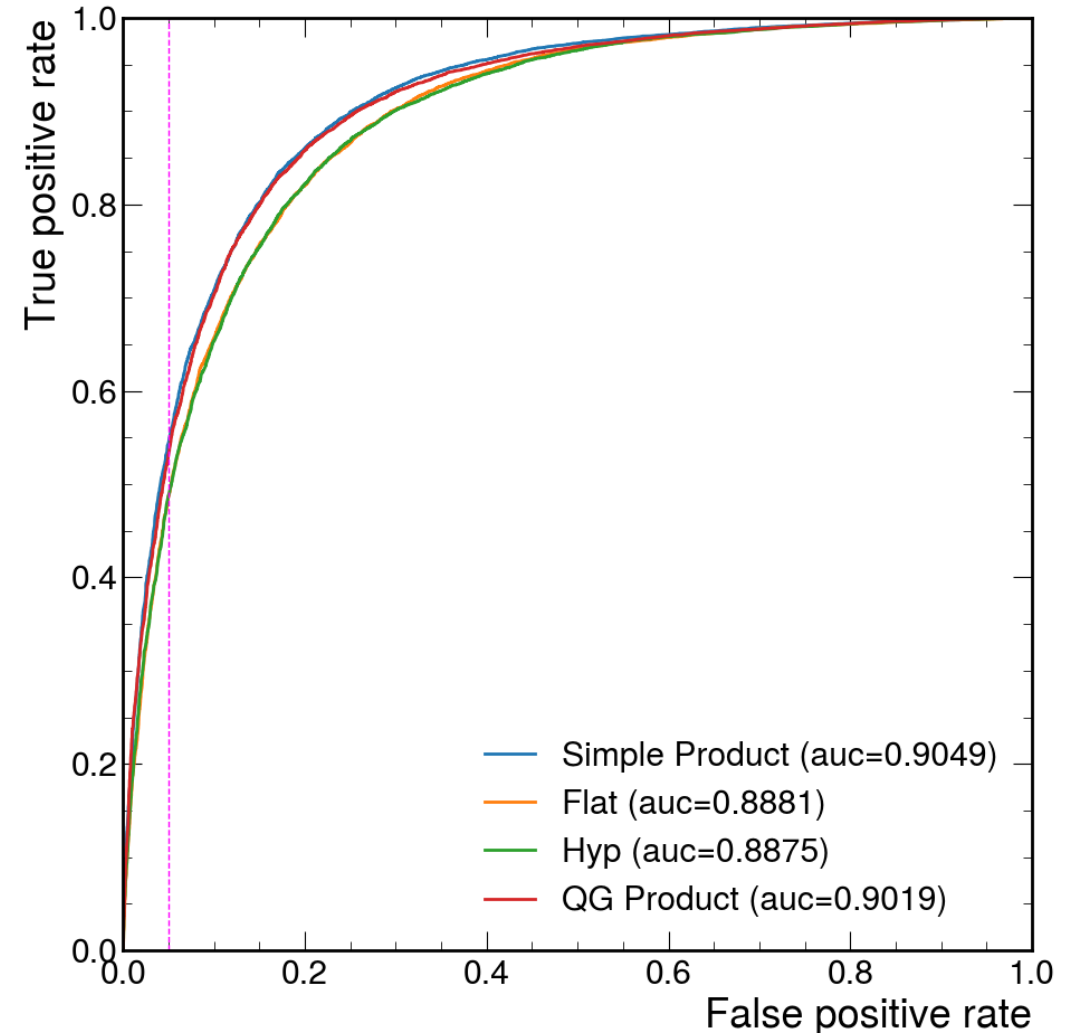


$$E^{\frac{n}{3}} \times B^{\frac{n}{3}}_{c_{quark}} \times B^{\frac{n}{3}}_{c_{gluon}}$$

12D Jet Tagging: Quark vs. Gluon

Signal Efficiency at 5%

- **Simple Product: 0.4969**
 - QG Product: 0.4906
 - Hyp: 0.4849
 - Flat: 0.4660
- **Product space models outperform** other geometries at QG tagging
 - Combines **convenience of Euclidean** geometries with **expressive power of hyperbolic** geometry.



Conclusion

Conclusion

Results

- Hyperbolic models **equal/better** in small param & embedding dim
- **Product space models extend these improvements** to larger models & representations

Takeaway

- Non-Euclidean representations are an **efficient** avenue to improve jet physics analyses

Next Steps

- **Full comparison of non-Euclidean** models to popular jet tagging approaches

Additional Slides

Details: Machine Learning by Manifold Preserving Operations

Fully connected (FC) layers & Activation

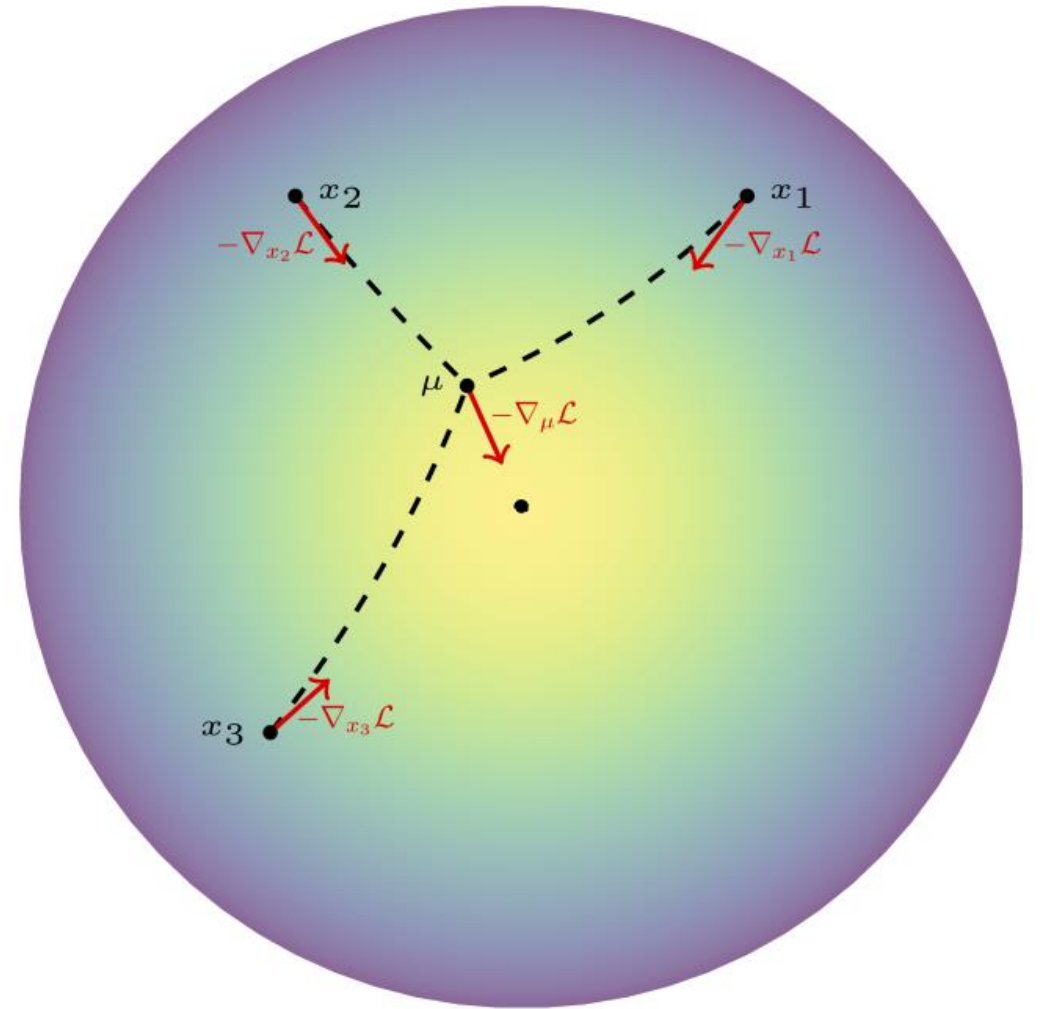
- Naive formulation: reformat FC propagation through gyrovector operations:

$$y = Wx \oplus_c b$$

- Where $W = [v_1, v_2, \dots, v_n]$ for $v_i \in B_c^m$, $x \in B_c^n$, $b \in B_c^m$
- We employ more robust formulations from the literature [Shimizu et al. 2006.08210v3]
- We utilize ReLU and LeakyReLU as they are norm reducing manifold preserving activation functions [Liu et al. 1910.12892]

Batch normalization

- The Fréchet mean generalizes centroids to metric spaces
- Work by [Lou et al. 2003.00335] developed differentiable Fréchet mean for Riemannian Batch Norm
- No analytic solution, but iterable

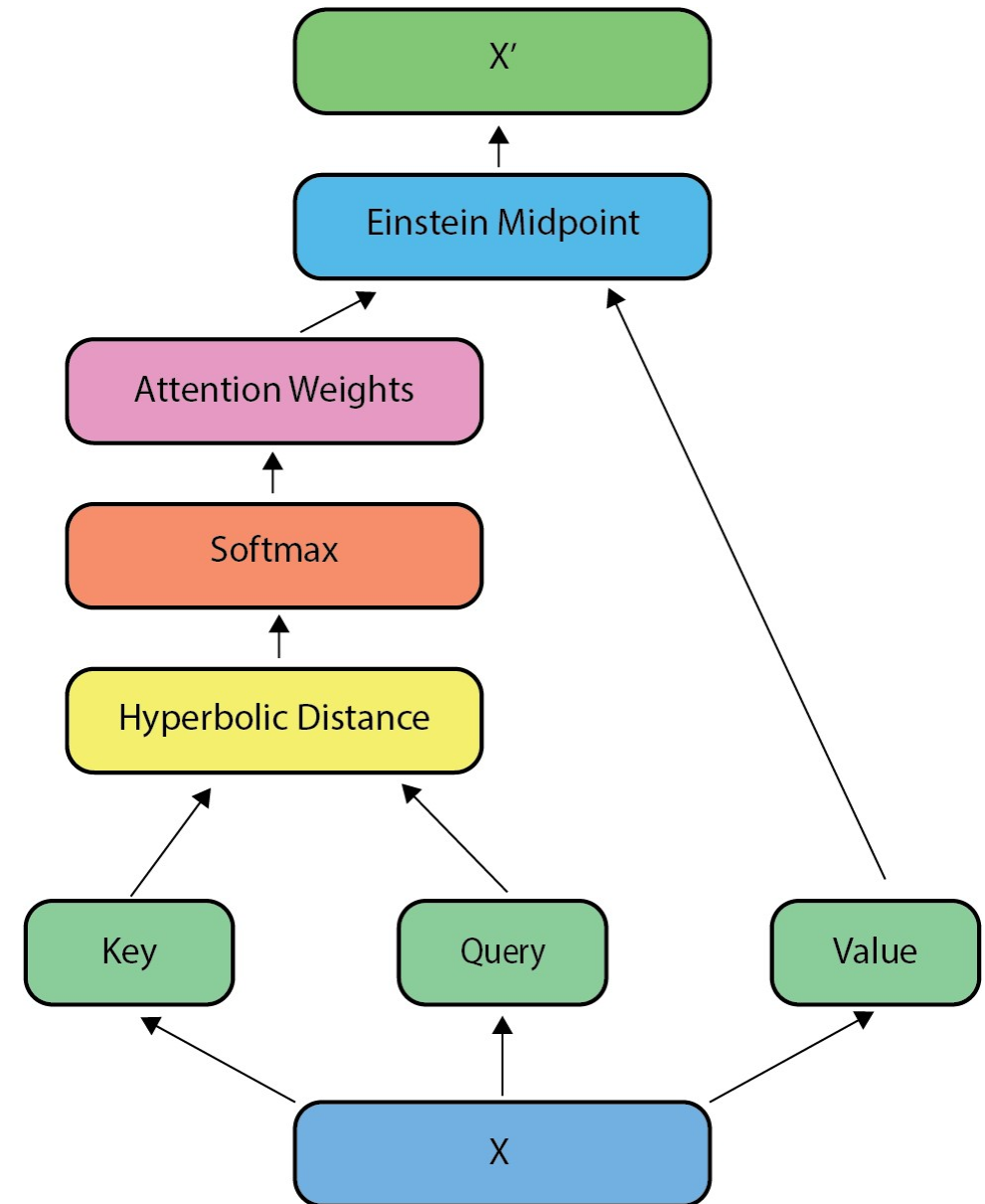


Lou et al. 2003.00335

Attention

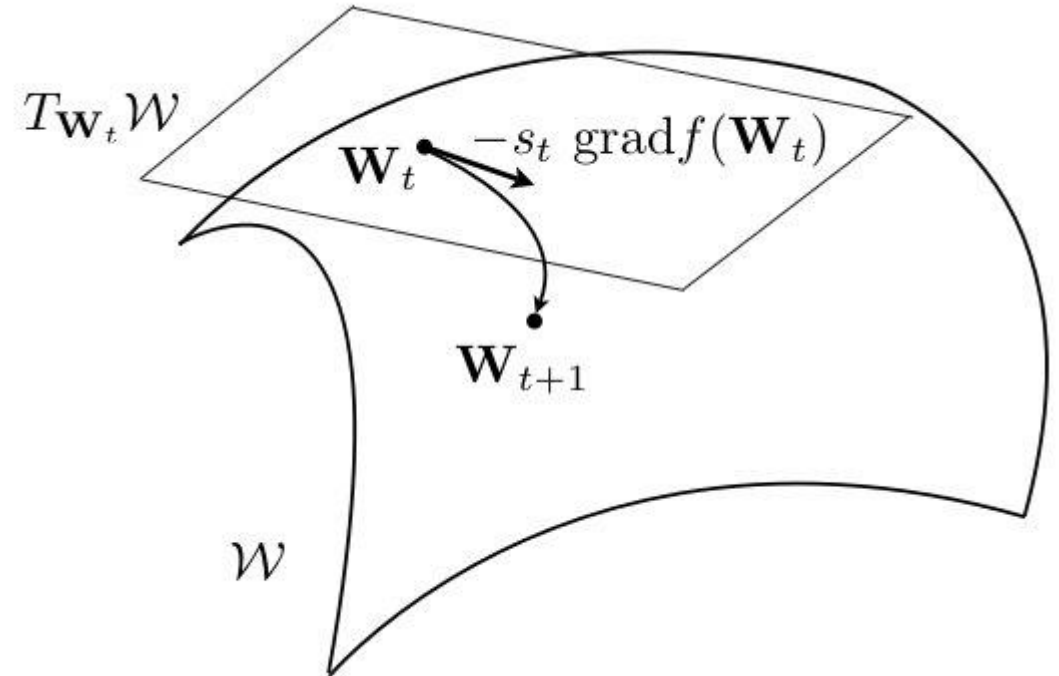
- Attention weights calculated through hyperbolic distance metric
- Attention aggregation through weighted Einstein midpoint [Gulcehre et al. 1805.09786v1]
- $v_i \in B_C^m$, $w \in \mathbb{R}$, and γ is the conformal factor

$$m_{Ein}(v_1, \dots, v_h; w_1, \dots, w_h)$$
$$= \frac{1}{2} \oplus \frac{\sum_{k=1}^h p_k \gamma_k v_k}{\sum_{k=1}^h p_k (1 - \gamma_k)}$$



Optimization algorithms

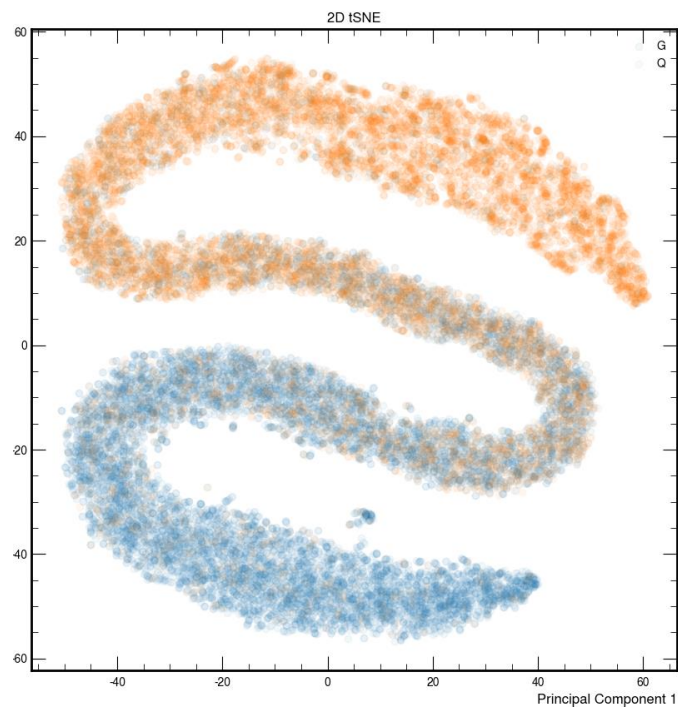
- Adjustments for manifold optimization:
 1. Adjust gradient magnitude for manifold
 2. Update using parallel transport
- Available algorithms:
 - RiemannianAdam , RiemannianSGD
 - RiemannianLion



Meyer et al. 1006.1288

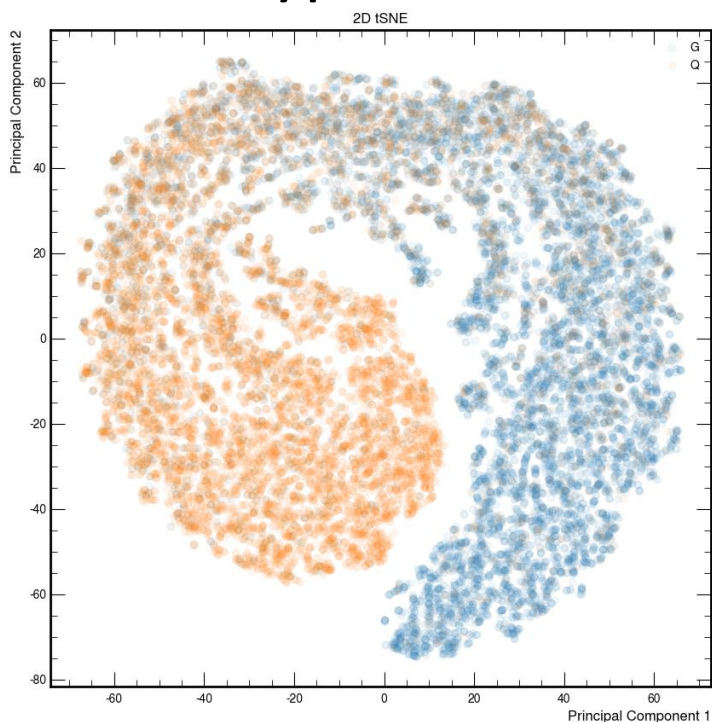
Jet Contrastive Embedding: TSNE Quark vs Gluon

Flat



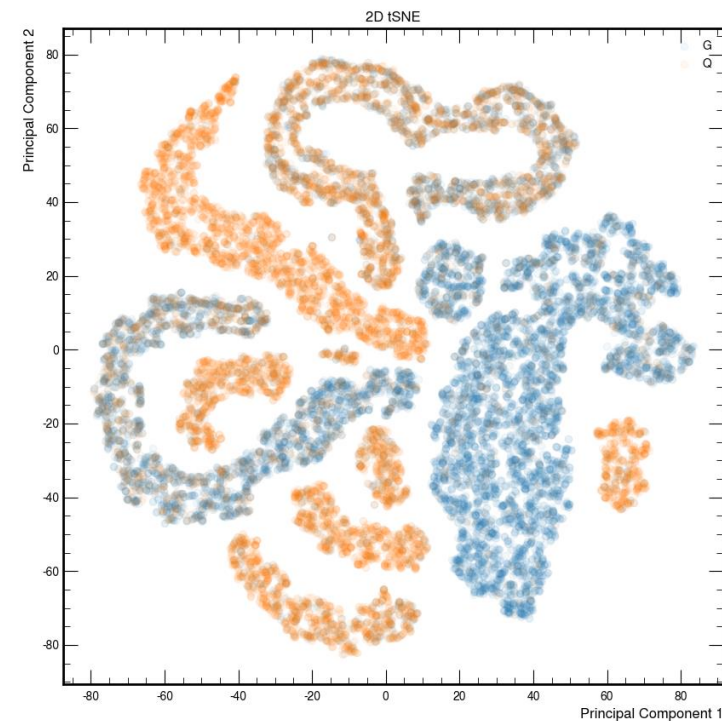
SIMCLR Loss:
5.3569

Hyperbolic



SIMCLR Loss:
5.3652

Mixed



SIMCLR Loss:
5.3554

Large Model Parameters

Architecture

- Transformers: 3
- Attention Heads: 8
- Head-size: 64
- Embedding-Dim: 160

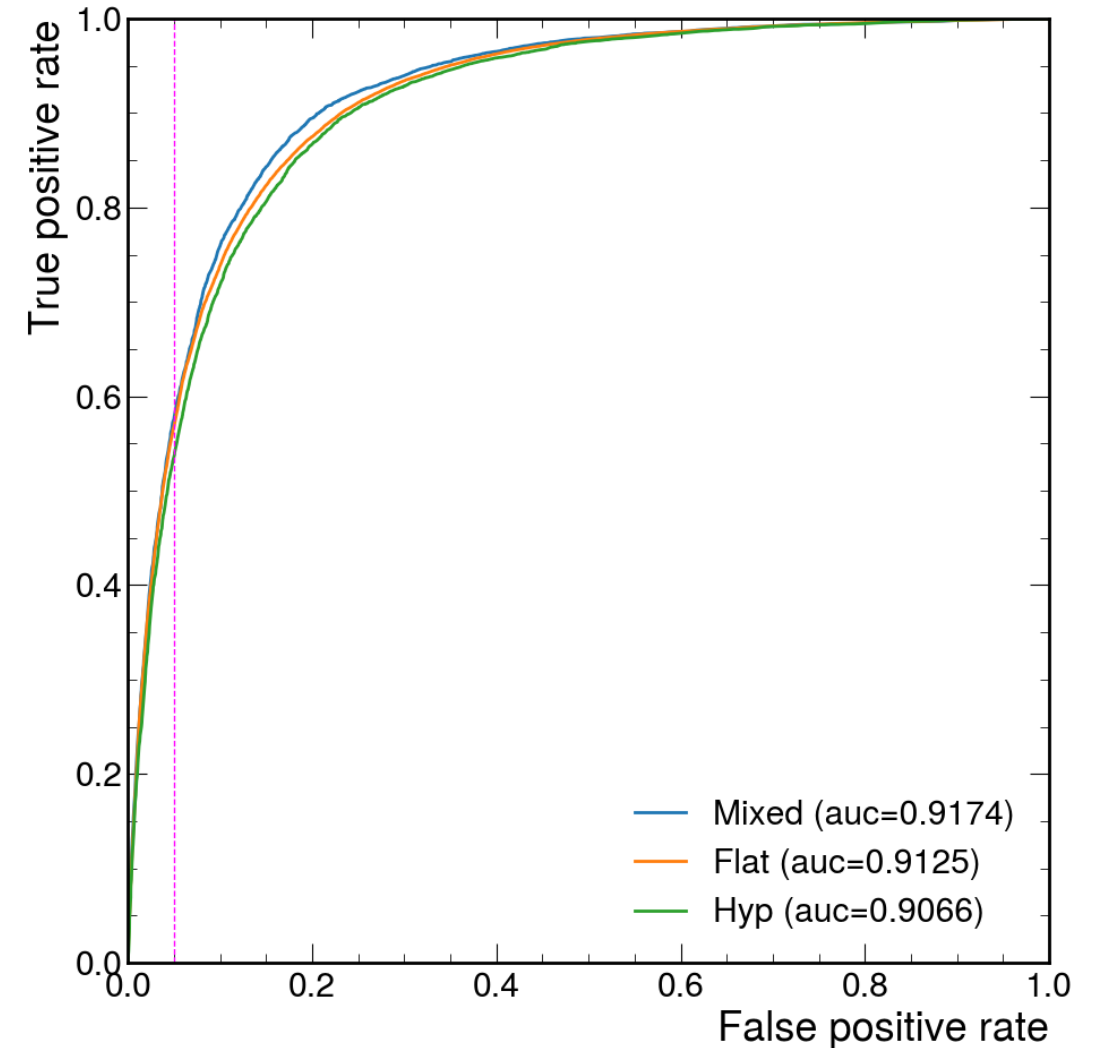
Total Parameters

- Mixed: 341486 parameters
- Flat: 419342 parameters
- Hyp: 419330 parameters

Jet Tagging: Quark vs. Gluon

Signal Efficiency at 5%

- **Mixed: 0.5759**
 - Flat: 0.5673
 - Hyp: 0.5361
- Superior performance of mixed curvature model over traditional transformer
 - Increased performance with **20% fewer** model parameters



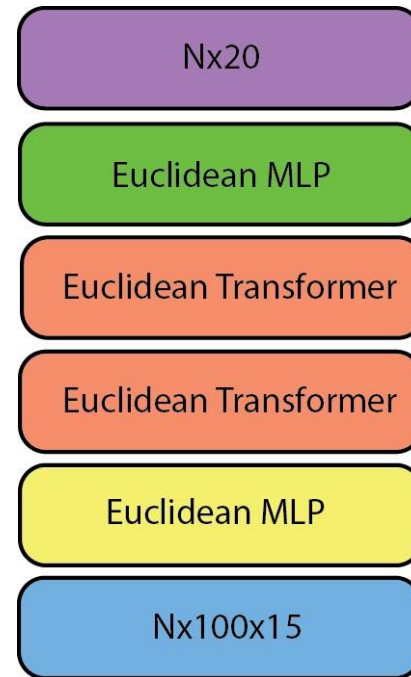
Small Models

(SUPER SMALL 1k params, embed 2d, 8d, 16d)

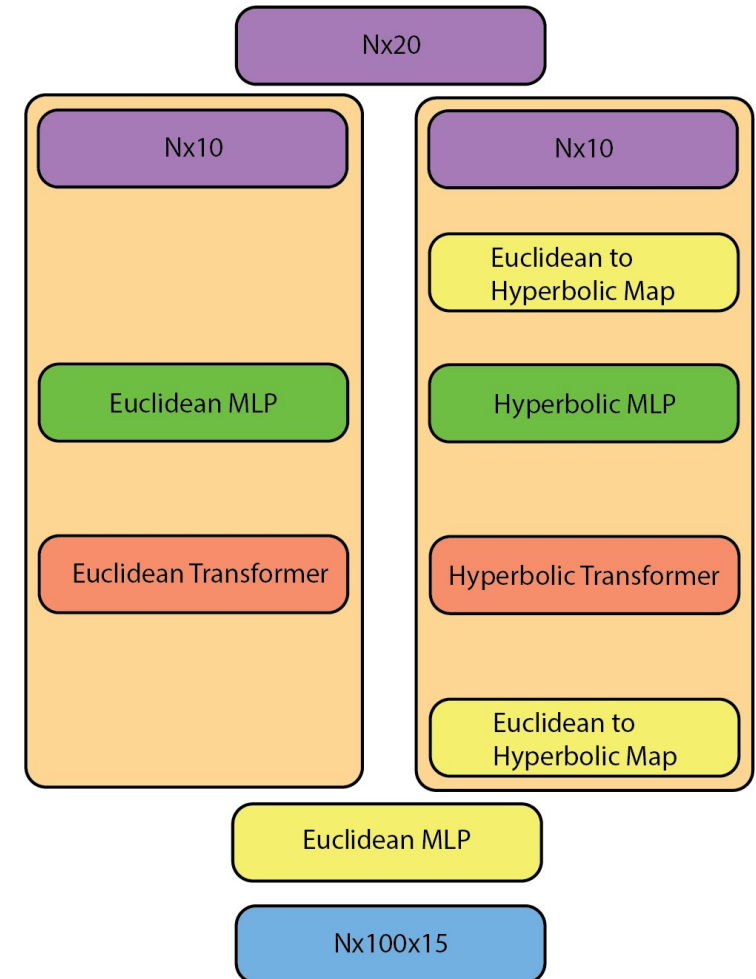
Model Architectures

- Limit model to 2 transformers
- What is optimal model architecture?
- Architectures:
 - 10% previous parameters
 - Euclidean: 31k params
 - Product Space: 38k params

Euclidean Model



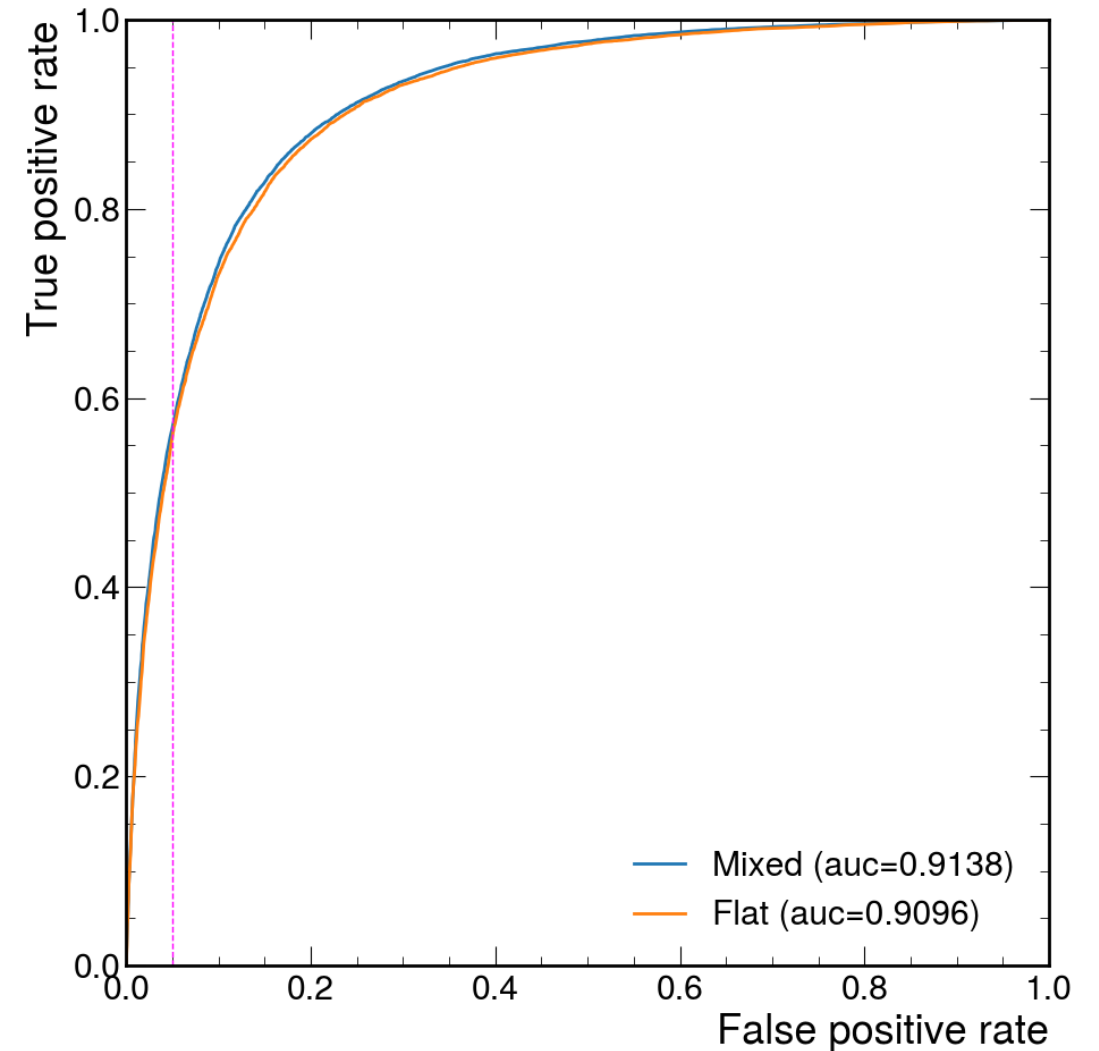
Product Space Model



Small Jet Tagging: Quark vs. Gluon

ROC at 5%

- **Mixed: 0.5682**
- Flat: 0.5588
- Superior on Quark-Gluon tagging
- Non-Euclidean representations provide superior jet representation



Expanded Product Space Models

Expanded Mixed Models Jet Tagging: Quark vs. Gluon

ROC at 5%

- **Mixed: 0.5750**
- Flat: 0.5475
- Product space model superior to sequential Euclidean
- Non-Euclidean representations more easily extract jet information

