

#### **End-To-End Latent Variational Diffusion Models for Inverse Problems in High Energy Physics**

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# **Unfolding At The LHC**

- Every cross section measurement subject to detector effects
- Process of removing detector effects from measurements known as **unfolding**
	- Excellent example of an **inverse problem** in HEP
- Investigate latent diffusion model for generative unfolding



*Inverse problem: (noun) a problem with no solution* 

# **The Landscape of ML Based Unfolding**

#### **Discriminative The Generative**

- **● Omnifold** is being used to measure physics!
	- **[H1 collaboration substructure](https://arxiv.org/abs/2303.13620)** [measurement](https://arxiv.org/abs/2303.13620)
- By far the most mature high dimensional unfolding algorithm
- **What if we have limited data events?**

- Learn to generate unfolded data conditioned on detector observations
- Lots of interesting ideas, and open questions
- Could work even with limited data events
- But prior dependence, variable dimensions, etc…

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## **From Diffusion to Variational Latent Diffusion**

- **Diffusion** models are a type of *conditional (c)* generative model which learns the reverse dynamics for a Gaussian stochastic differential equation.
- Given a *noise schedule* based on log signal-to-noise ratio  $\gamma$ , define our flow.

$$
\sigma_t = \sqrt{\text{sigmoid}(\gamma_\phi(t))} \text{ and } \alpha_t = \sqrt{\text{sigmoid}(-\gamma_\phi(t))}
$$

$$
x(t) = \alpha(t)x(0) + \sigma(t)\epsilon_t \text{ where } \epsilon_t \sim \mathcal{N}(0, 1)
$$

Train a network to estimate  $\epsilon$  and sample according to inverse SDE.

$$
\mathcal{L} = \mathbb{E}_{\epsilon \sim \mathcal{N}(0,1), t \sim \mathcal{U}(0,1)} \left[ \gamma'(t) \left\| \epsilon - \hat{\epsilon}(x_t, t, c) \right\|_2^2 \right]
$$

$$
\int_1^0 f(t)x(t) + \frac{g^2(t)\hat{\epsilon}(x_t, t, c)}{2\sigma} dt
$$

[1] Yang Song, Jascha Sohl-Dickstein, Diederik P Kingma, Abhishek Kumar, Stefano Ermon, and Ben Poole. Score-based generative modeling through stochastic differential equations. ICLR 2021.

# **From Diffusion to Variational Latent Diffusion**

**● Latent Diffusion (LDM)2** performs the forward and reverse SDE in a *latent space* from a pre-trained VAE. This VAE is usually pre-trained in either unsupervised manner with only the data or with a contrastive objective such as CLIP.

$$
x \to z \sim VAE(x)
$$

**• Variational Diffusion (VDM)<sup>3</sup> Interprets the entire diffusion model as a** hierarchical variational model with infinite depth. This allows us to learn an optimal noise schedule for our diffusion.

$$
\gamma \rightarrow \gamma_{\phi}(t) \text{ with } \mathcal{L}_{\phi} = Var[\mathcal{L}_{\text{diffusion}}]
$$

[2] Robin Rombach, Andreas Blattmann, Dominik Lorenz, Patrick Esser, and Björn Ommer. High-resolution image synthesis with latent diffusion models, 2021.. [3] Diederik Kingma, Tim Salimans, Ben Poole, and Jonathan Ho. Variational diffusion models. Advances in neural information processing systems, 34:21696–21707, 2021.

# **From Diffusion to Variational Latent Diffusion**

- We combine these ideas into a single unified end-to-end model.
- VAE is optimized to find ideal space to perform diffusion in.
	- Interpreted as another layer in the hierarchical VAE, introduce additional regularization loss.
	- Latent space may be **higher dimensional** than data space!
- Noise Schedule is optimized simultaneously as in VDM.
	- Continuous time diffusion process is used for training.
	- Inference is performed in discrete time.



# **Distribution-Free Metrics Results**

- Compare each of these models to evaluate the effect of the latent space and unified training.
- Also compare the a simple Conditional VAE (CVAE) and a normalizing flow-based model  $(CINN)^4$ .
- Notice latent space is **very important** to model performance, and unified training outperformed pre-trained LDM.



[4] Marco Bellagente, Anja Butter, Gregor Kasieczka, Tilman Plehn, Armand Rousselot, Ramon Winterhalder, Lynton Ardizzone, and Ullrich Köthe. Invertible networks or partons to detector and back again. SciPost Phys., 9:074, 2020.

#### **Testing Dataset Kinematics Distributions**



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#### **Future Work**

- Want to perform **particle** level unfolding
- We lose the definite fixed-length encoding available due to the parton's feynman diagram. **Particle events are variable length!**
- Extend this method to be able to unfold an arbitrary number of objects simultaneously.
- Investigate **prior dependence** of generative unfolding
- Acceptance effects, inefficiencies, systematics, etc. etc. etc.

"Unfolding is a complicated business and one is well advised to ask in each problem if it can be avoided" - G. Cowan, A Survey of Unfolding Methods for Particle Physics

#### **Thank you**

# **Posterior Distribution Examples**

- Compare posterior distributions produced by the LVD for individual example events to an empirical estimate of the posterior from the testing dataset.
- Notice that the LVD has very tight posteriors for challenging kinematics including the Mass and Pt.
- Notice that the LVD managed to discover a bi-modal posterior for neutrino eta!

