Pushing Normalizing Flows for higher-dimensional Detector Simulations

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Structure



2 Models

- INN
- VAE

3 Results

- Classifier results
- High level features

4 Backup Slides

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Pushing	INNs

CaloChallenge 2022



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Datasets

Three datasets of increasing dimensionality



INN

Generation with an INN

Models

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ININ			

Architecture



INN

Preprocessing



INN

Advantages and Disadvantages

Models

Advantages

- Very accurate generations
- Fast in both directions

Disadvantages

• Bad scaling (time and memory)

VAE

Compression with a VAE

Models

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Derivation

- Assume \exists true joint distribution of data x and latent z.
- Minimize $D_{\mathsf{KL}}[E(z|x), D(z|x)]$.
- $\Rightarrow \mathcal{L} = -\sum_{x \in TS} \langle \log D(x|z) \rangle_{E(z|x)} + \beta \cdot D_{\mathsf{KL}} \left[E(z|x), p_{\mathsf{latent}}(z) \right]$

Preprocessing



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VAE

Results

Architecture



Classifier results

Results

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Classifier results			

Classifier — Dataset 1 (photons)

2305.16774



Classifier results

Classifier — Dataset 1 (pions)

2305.16774



Results

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Classifier — Dataset 2

2305.16774



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Classifier results			

Classifier — Dataset 3

2305.16774



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High level features

High level features — Dataset 1



Results

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High level features

High level features — Dataset 2 & 3







- Coupling blocks are a viable and faster possibility for normalizing flows
- VAE compression is possible but results in worse samples
- VAEs perform best for hadronic showers, while pure INNs perform best for electromagnetic showers.

High level features

The End

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Backup Slides

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Pushing INNs

ΤP

Parameter	INN ds1/ds2	INN (After VAE)
coupling blocks	RQS / Cubic	RQS
# layers	4 / 3	3
hidden dimension	256	32
# of bins	10	10
# of blocks	12/14	18
# of epochs	450 / 200	200
batch size	512 / 256	256
lr scheduler	"one cycle"	"one cycle"
max. Ir	$1 \cdot 10^{-4}$	$1\cdot 10^{-4}$
$\beta_{1,2}$ (ADAM)	(0.9, 0.999)	(0.9, 0.999)
Ь	$5 \cdot 10^{-6}$	/
α	$1 \cdot 10^{-8}$	$1\cdot 10^{-6}$

N			el	
0	0	0	0	
0	0	0	0	

Parameter	VAE	
lr scheduler	Constant LR)
lr	$1 \cdot 10^{-4}$	
hidden dimension	5000, 1000, 500 (Set 1)	
	1500, 1000, 500 (Set 2)	
	2000, 1000, 500 (Set 3)	
latent dimension	50 (Set 1,2) / 300 (Set 3)	Sinner VAE
# of epochs	1000	
batch size	256	
β	$1\cdot 10^{-9}$	
threshold <i>t</i> [keV]	2 (Set 1) / 15.15 (Set 2,3)	J
hidden dimension	1500, 800, 300)
kernel size	7	Kernel
kernel stride	3 (Set 2), 5 (Set 3)	J

Results









INN derivation

$$dx \ p_{\text{model}} (x \mid \theta) = dz \ p_{\text{latent}} (z)$$

$$\Leftrightarrow \quad p_{\text{model}} (x \mid \theta) = p_{\text{latent}} (z) \left| \frac{\partial G_{\theta}(z)}{\partial z} \right|^{-1} = p_{\text{latent}} \left(\bar{G}_{\theta}(x) \right) \left| \frac{\partial \bar{G}_{\theta}(x)}{\partial x} \right|.$$

$$\Rightarrow \quad \mathcal{L}_{\mathsf{INN}} = -\left\langle \log p_{\mathsf{model}}\left(x|\theta\right)\right\rangle_{p_{\mathsf{data}}\sim TS} \\ = -\left\langle \log p_{\mathsf{latent}}\left(\bar{G}_{\theta}(x)\right) + \log\left|\frac{\partial \bar{G}_{\theta}(x)}{\partial x}\right|\right\rangle_{p_{\mathsf{data}}\sim TS}.$$