

# Flashpoints Signal Hidden Inherent Instabilities in Land Use Planning

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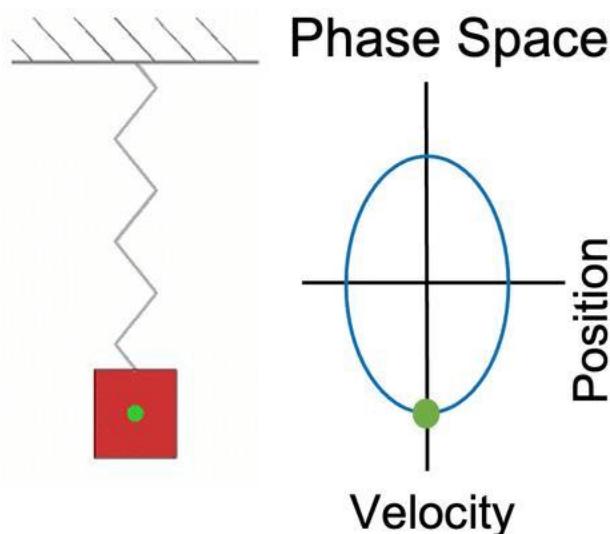
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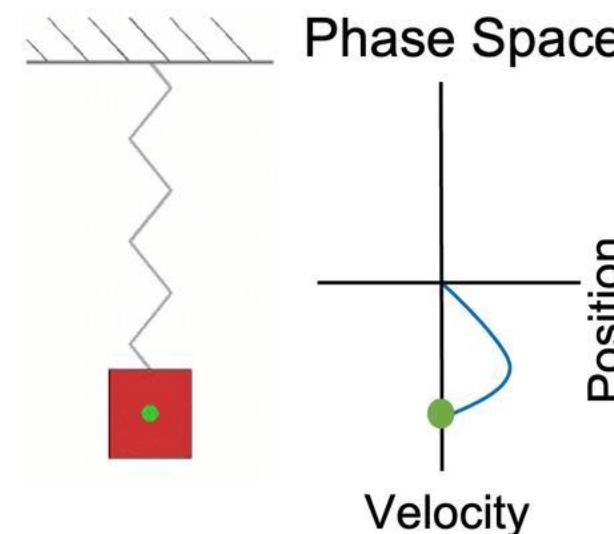
# Physics of Design Problems → Hyperoptimization

- Optimization thinks about the optimal solution.
- Physics thinks about the whole solution space!

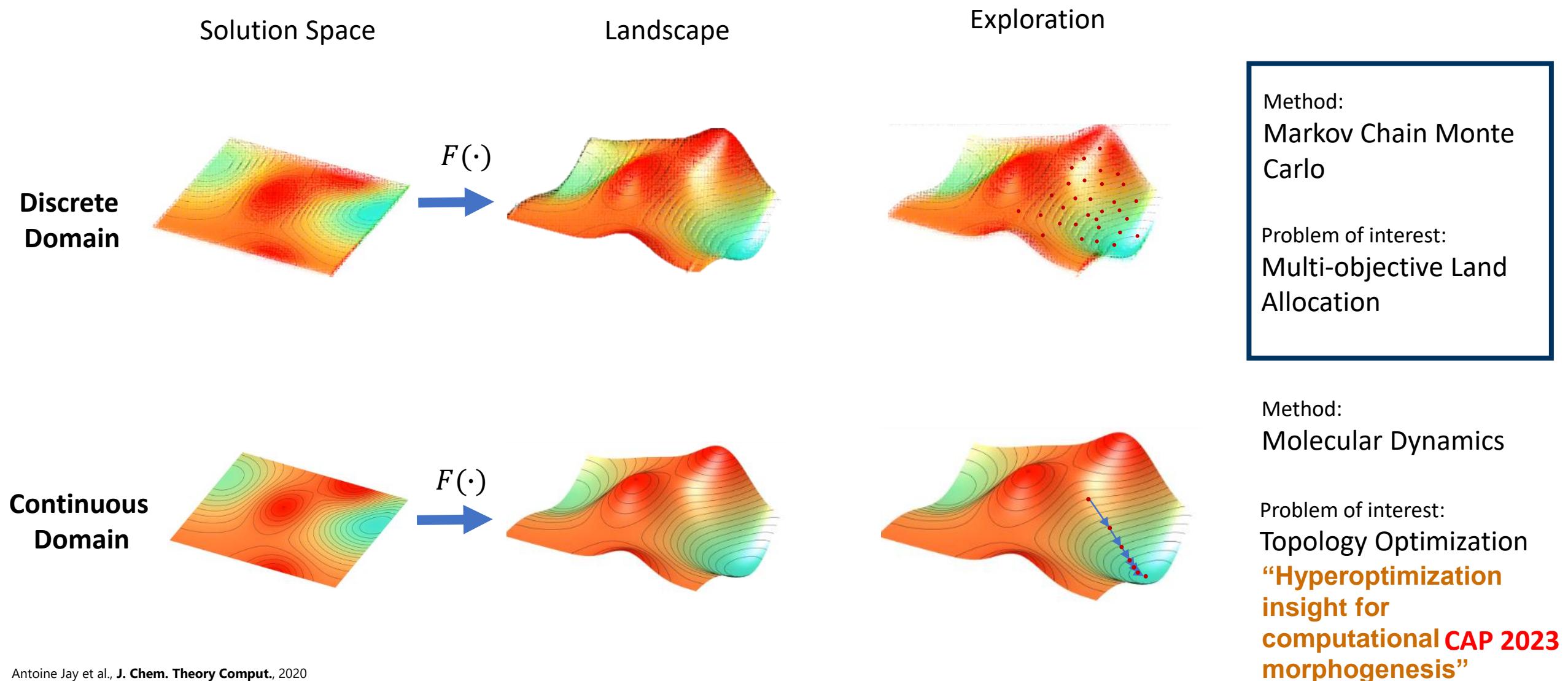
**PHYSICS**



**OPTIMIZATION**

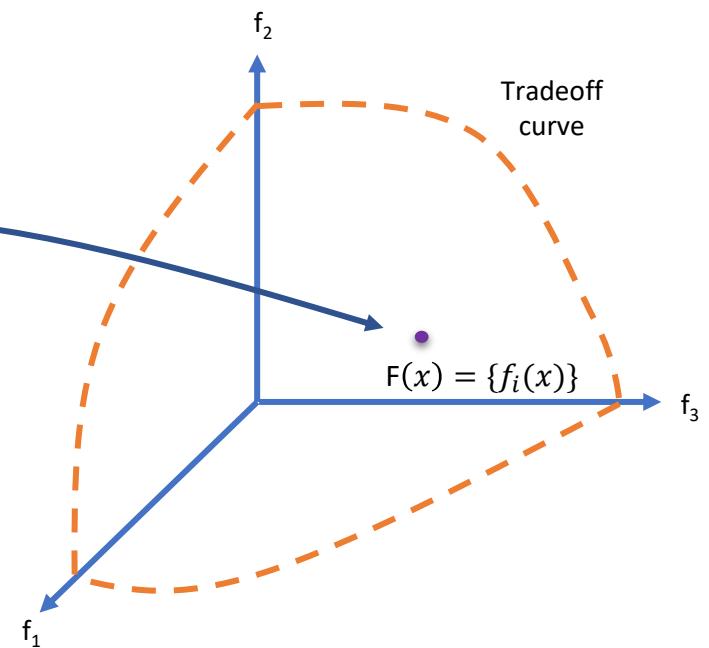
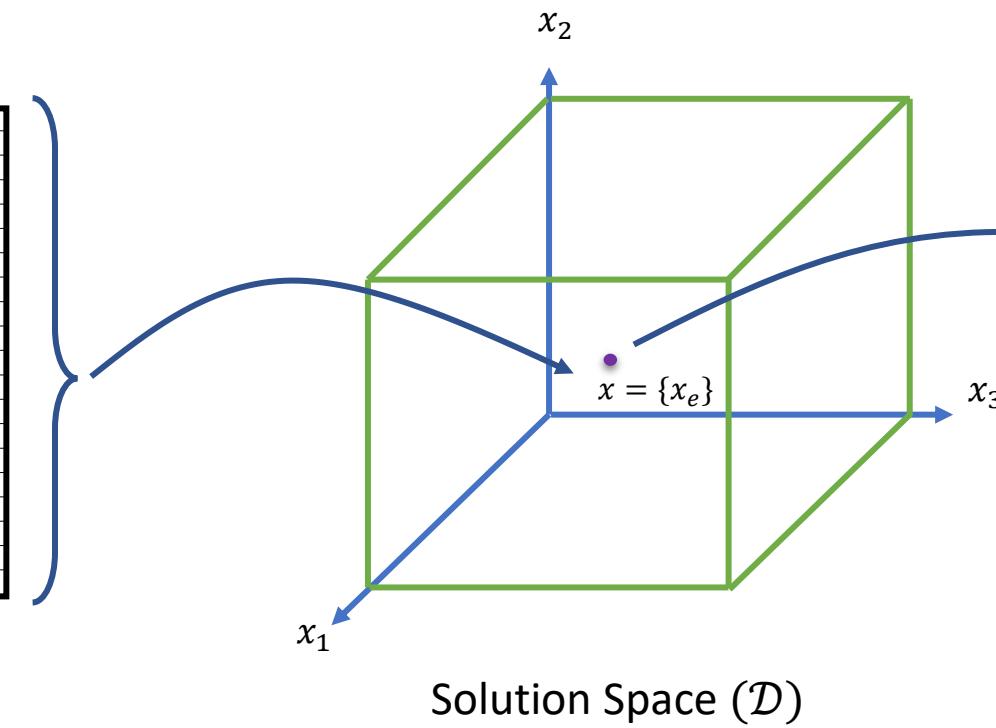
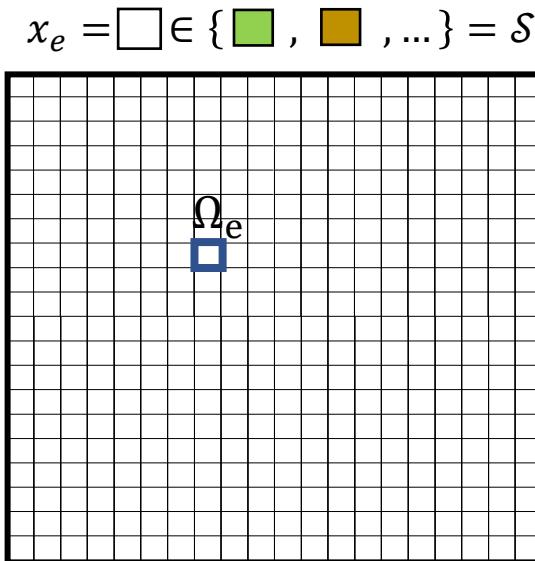


# How? Landscape exploration



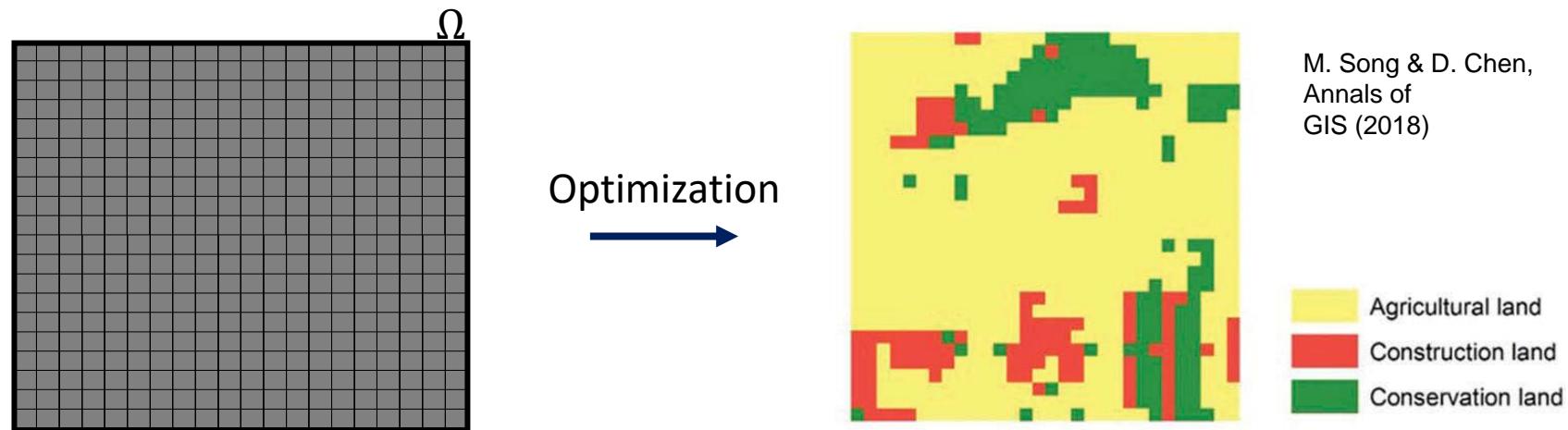
# Allocation Design Problems

$$\begin{aligned} \min_{\{x_e\} \in \mathcal{D}} \quad & F(\{x_e\}) = \sum_{i=1}^{I_f} \sum_{e=1}^{N_e} \int_{\Omega_e} w_i f_i(x_e) d\Omega_e \\ \text{s. t.} \quad & \sum_{e=1}^{N_e} \int_{\Omega_e} G_{j_e}(x_e) d\Omega_e - c_{j_e} = 0, \text{ for } j_e = \{1, 2, \dots, I_e\} \\ & \sum_{e=1}^{N_e} \int_{\Omega_e} G_{j_{ine}}(x_e) d\Omega_e - c_{j_{ine}} \leq 0, \text{ for } j_{ine} = \{1, 2, \dots, I_{ine}\} \end{aligned}$$



# Multi-Objective Land Allocation (MOLA)

- What is the best way to allocate land uses in a prescribed domain in order to find the best performance?



$$\min_{\{x_e\} \in \{0,1,2\}^N} \quad F = P_c O_c + P_s O_s$$

**MOLA**

Suitability  $O_s = -\sum_{k=1}^K \sum_{i=1}^N \sum_{j=1}^M W_k S_{ijk} x_{ijk}$

Compactness  $O_c = -\sum_{k=1}^K \sum_{i=1}^N \sum_{j=1}^M b_{ijk} x_{ijk}$

$$b_{ijk} = (\sum_{\alpha, \beta = \{-1, 0, 1\}} x_{i+\alpha, j+\beta, k}) - x_{i,j}$$

Change  
notation

$$O_s = -\sum_i S(i) \delta(s_i, i)$$

$$O_c = -\sum_{\langle ij \rangle} \delta(s_i, s_j)$$

External field  
Interaction

Potts  
Model

M. Song & D. Chen,  
Annals of  
GIS (2018)

## Problem:

There are no unique agreements on priorities

- Preferences, at the human level, play a significant role in the “optimized” solution.  
⇒ Optimization is not the best solution!

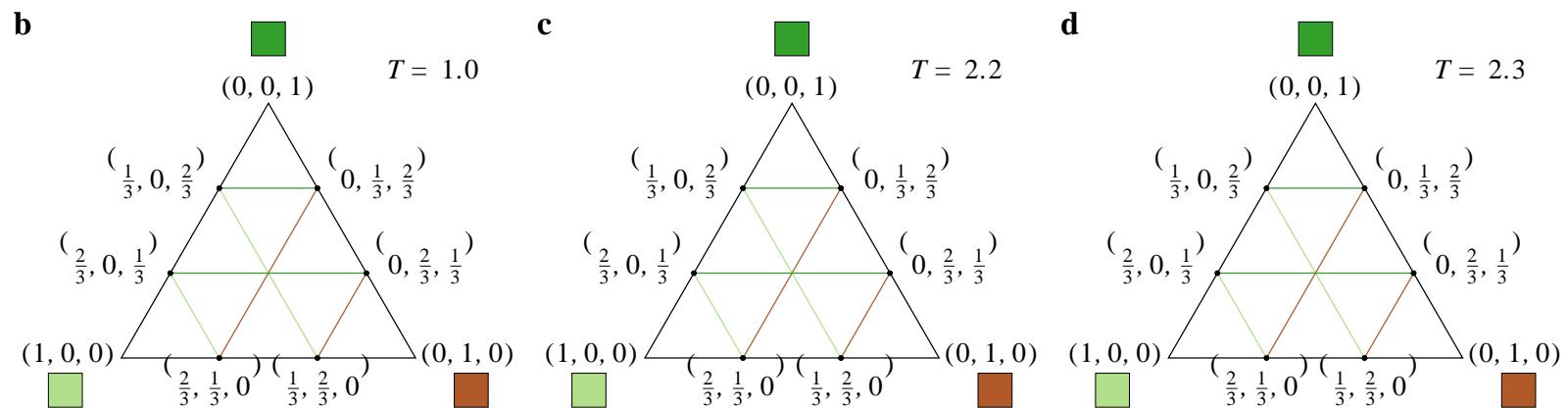
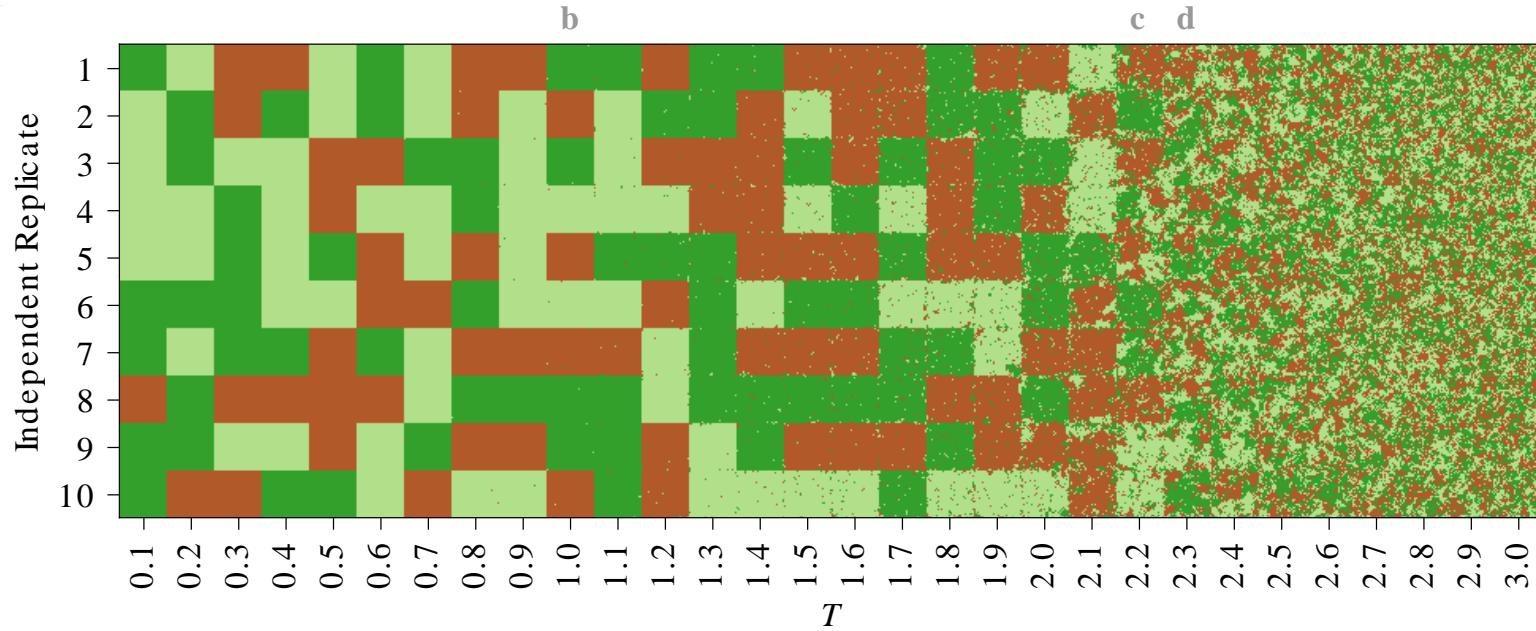
## Question:

How do land-use patterns depend on MOLA weights?

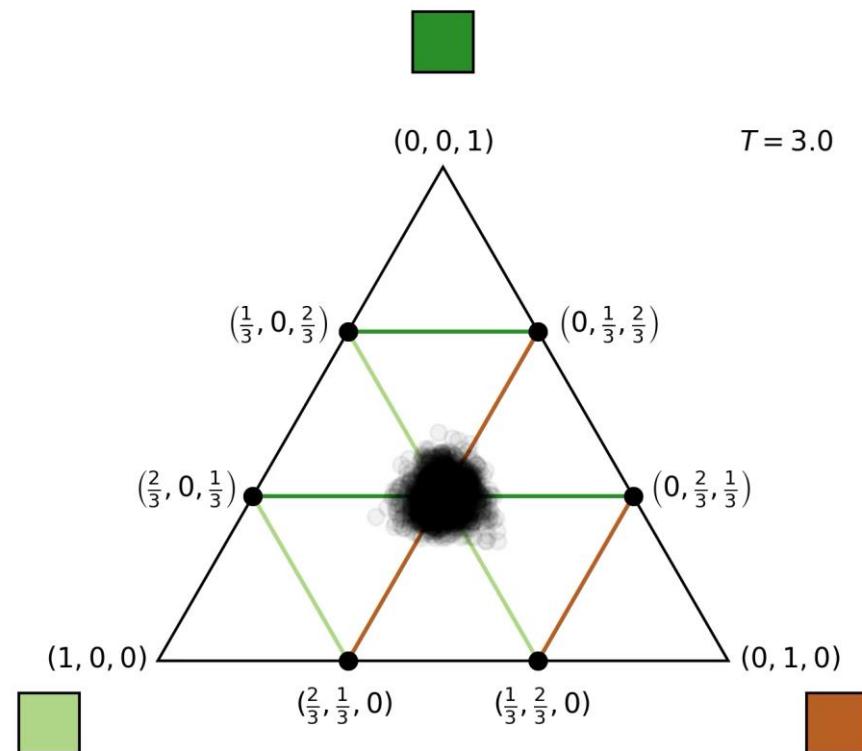
# Method

- Metropolis Algorithm -> Critical slowing down -> Wolff Algorithm [Wolff Phys Rev Lett 62 361 (1989)]
- Wolff Algorithm -> No external field -> Ghost-Site Cluster MC [Kent-Dobias & Sethna Phys Rev E 98 063306 (2018)]
- Implementation
  - MATLAB for Proof of Concept
  - C++ for the main core
  - Python for the wrapper and Data management
  - Typical Run time <10 s on 2019 CPU core
  - For Annealing: more than 2300 trials
  - For Flashpoints: 82,500 trials

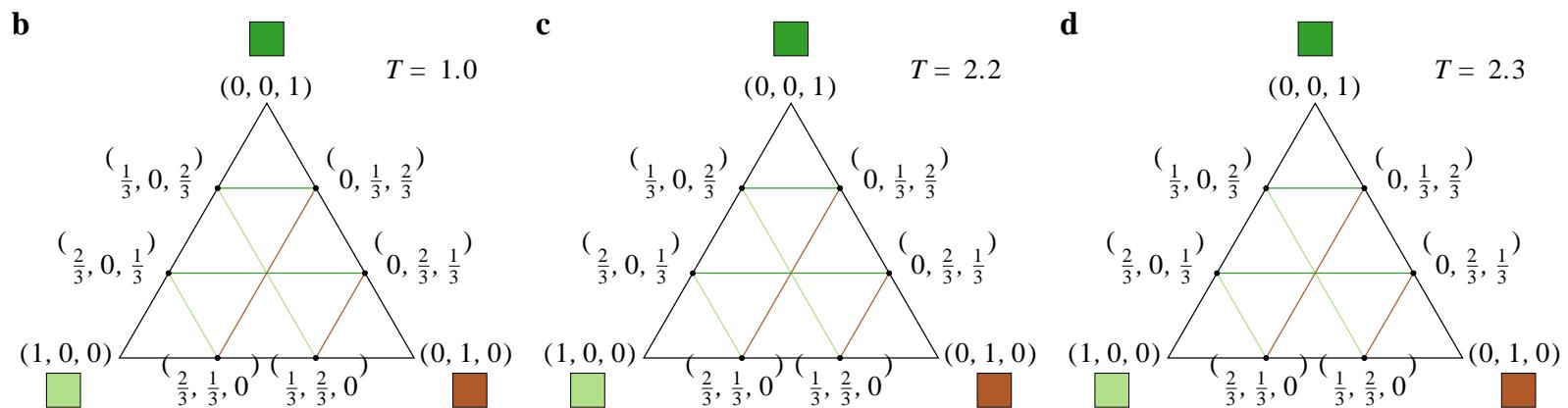
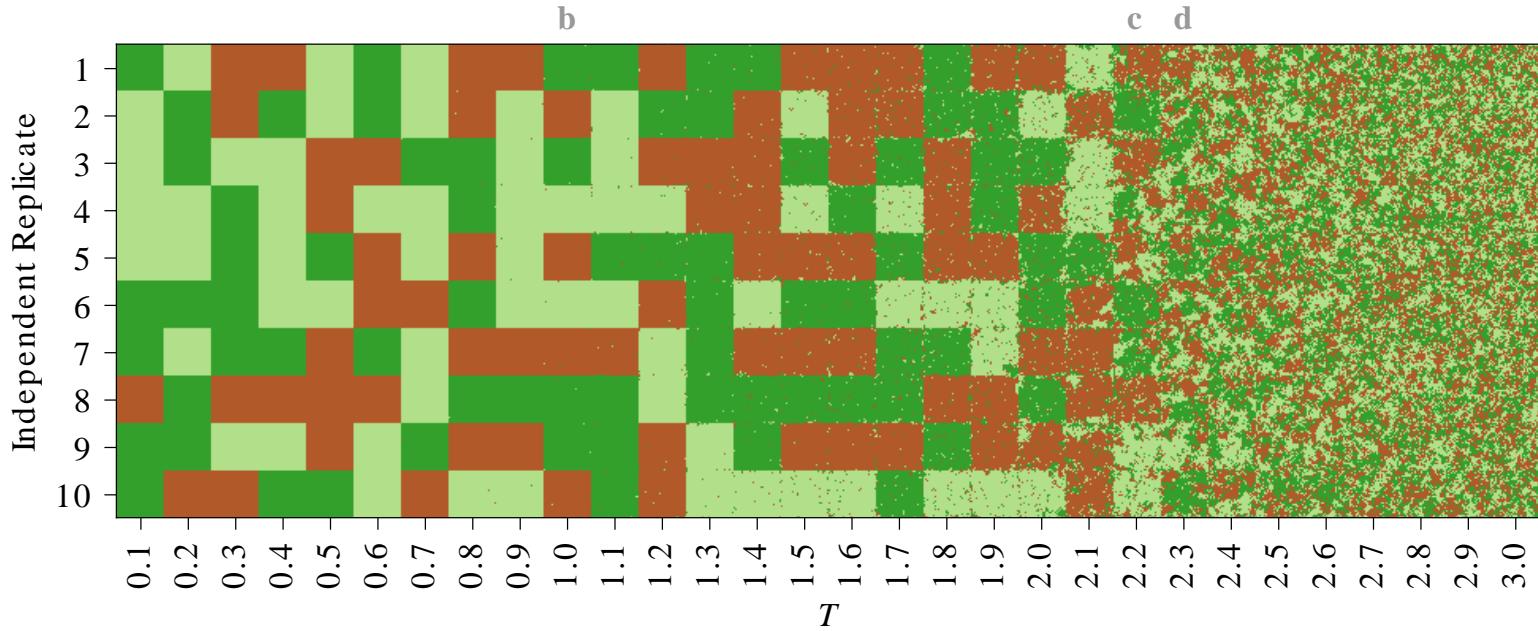
# Result: Symmetry-Breaking



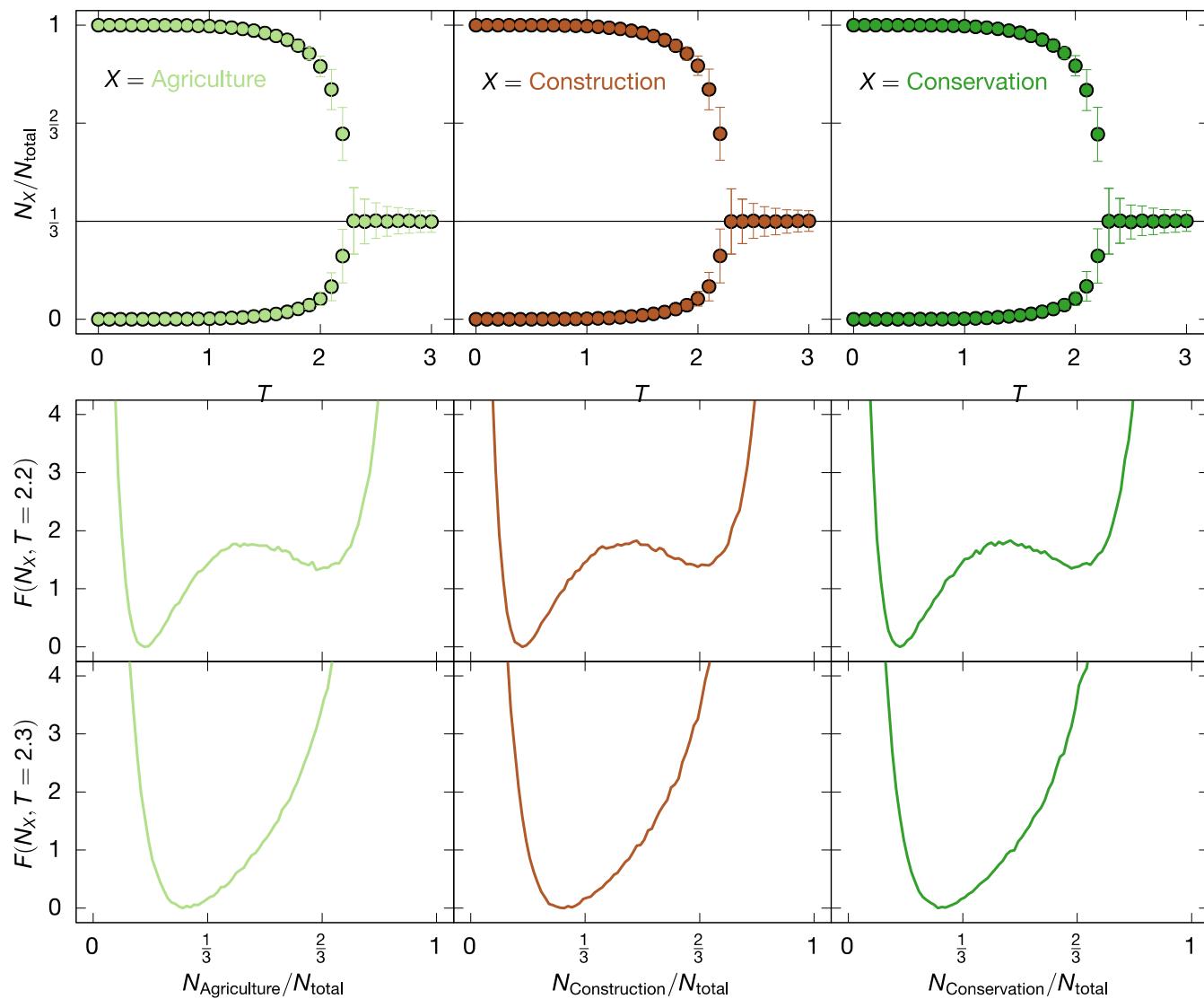
# Result: Symmetry-Breaking (cont.)



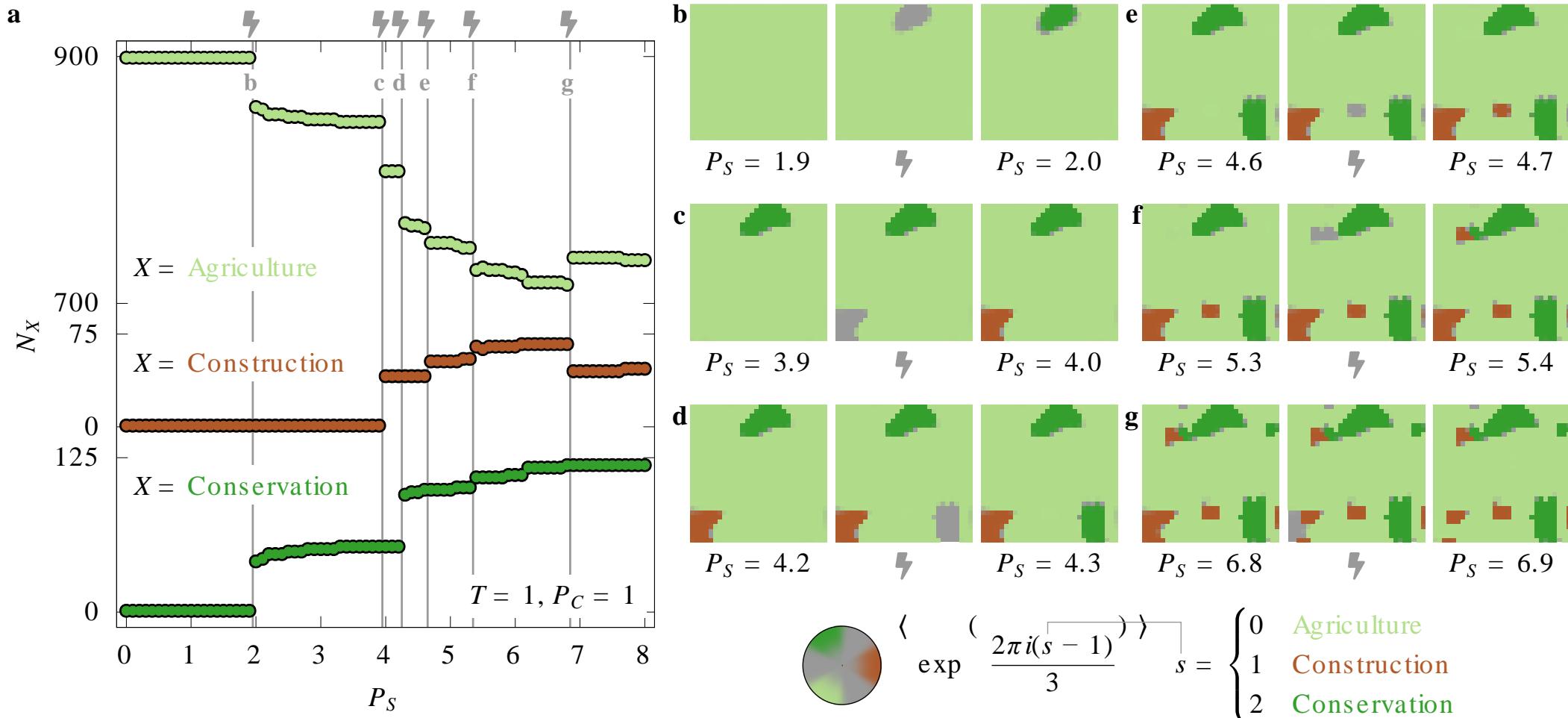
# Result: Symmetry-Breaking



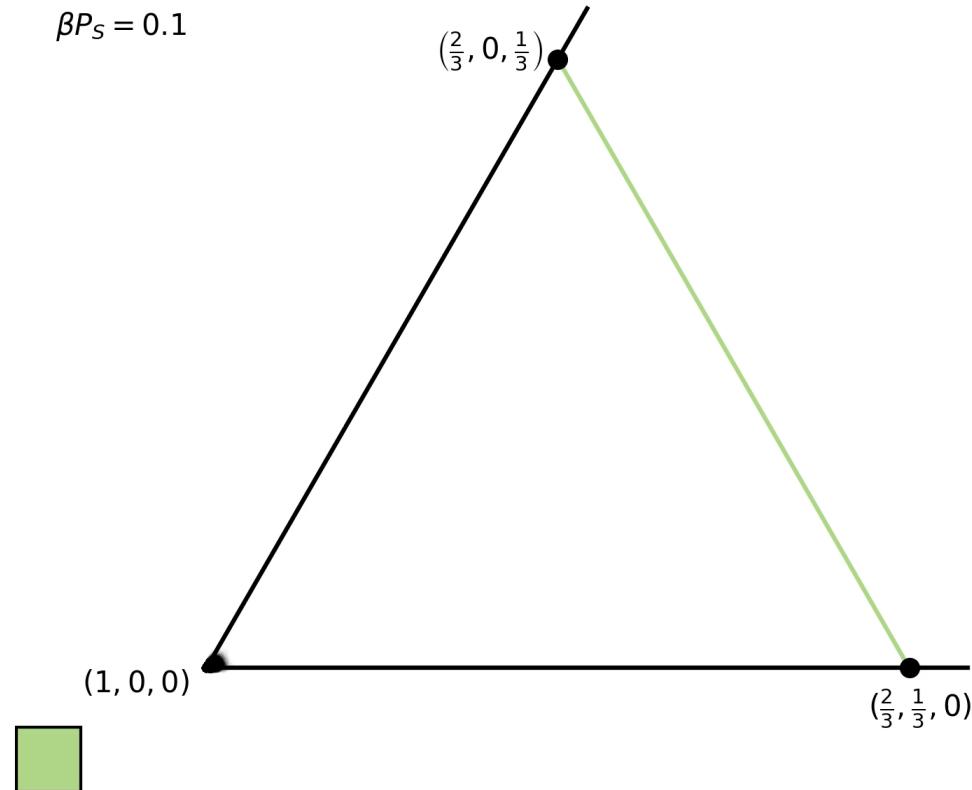
# Validation: Landau Free Energy



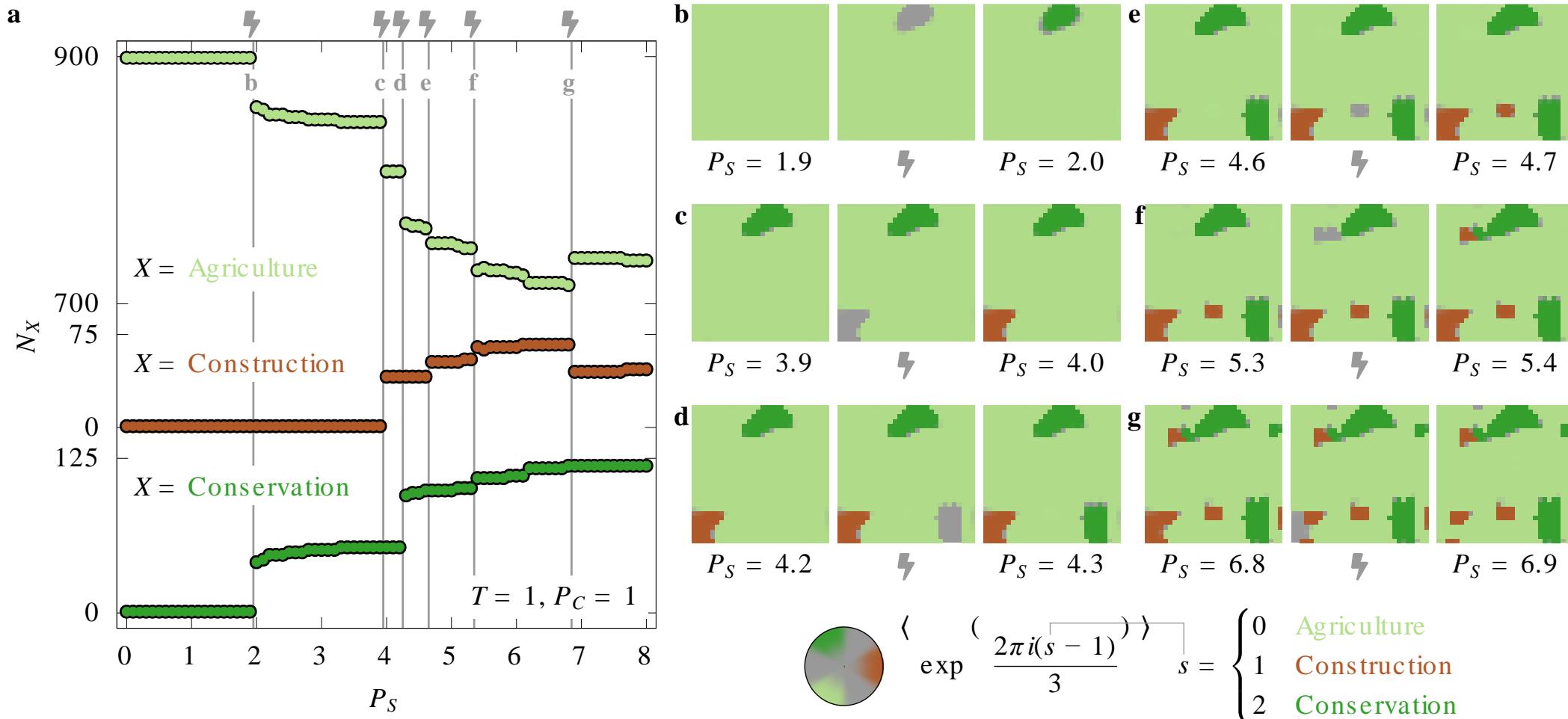
# Main Result: Flashpoints!



# Main Result: Flashpoints! (cont.)

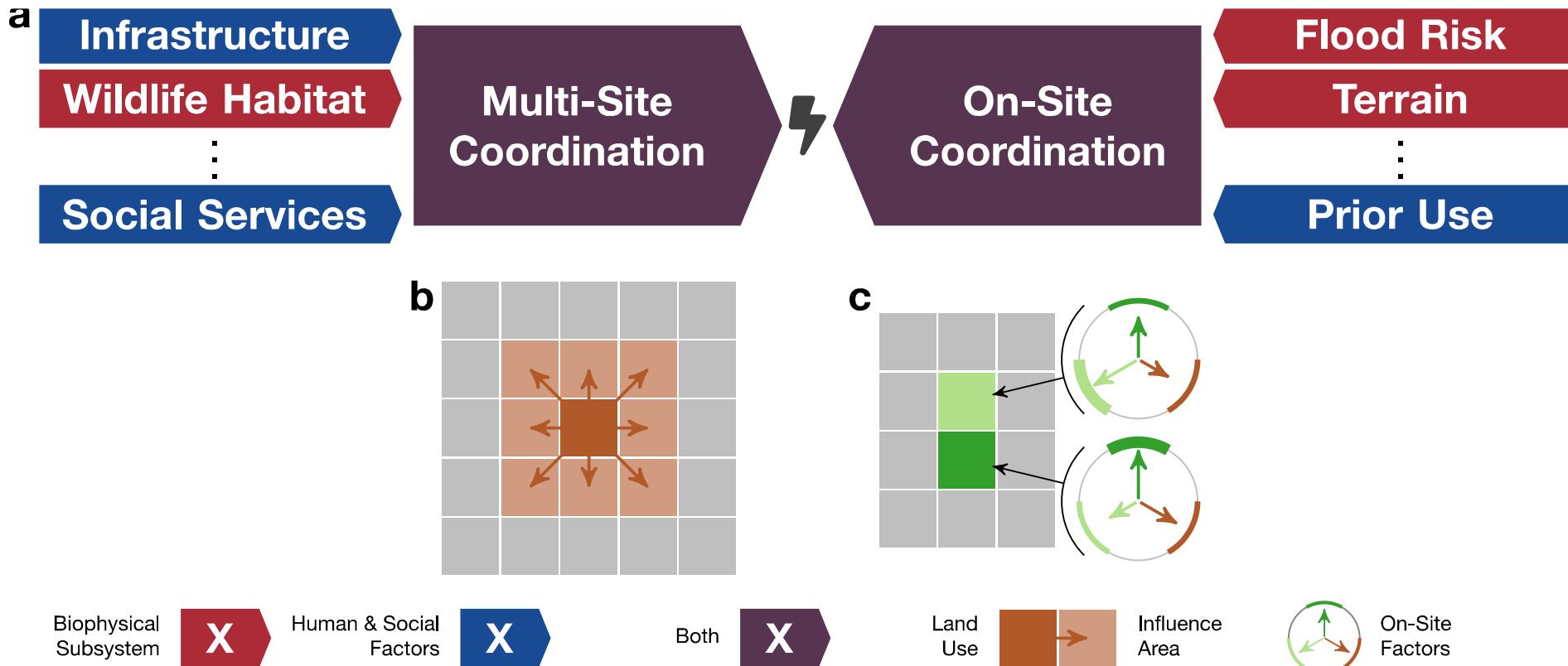


# Main Result: Flashpoints!



$$\left\langle \exp \left( \frac{2\pi i(s-1)}{3} \right) \right\rangle_s = \begin{cases} 0 & \text{Agriculture} \\ 1 & \text{Construction} \\ 2 & \text{Conservation} \end{cases}$$

# Why?



# Thank you!

