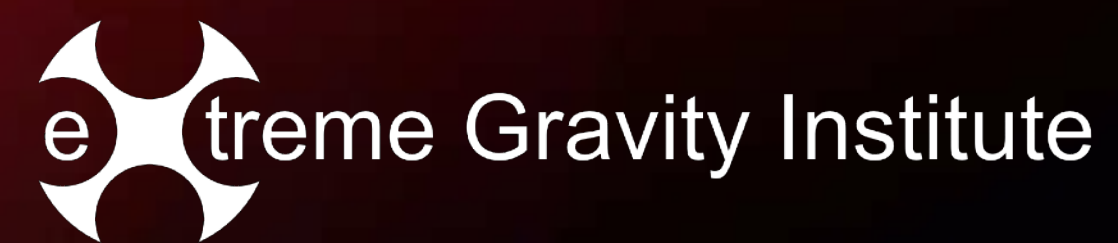


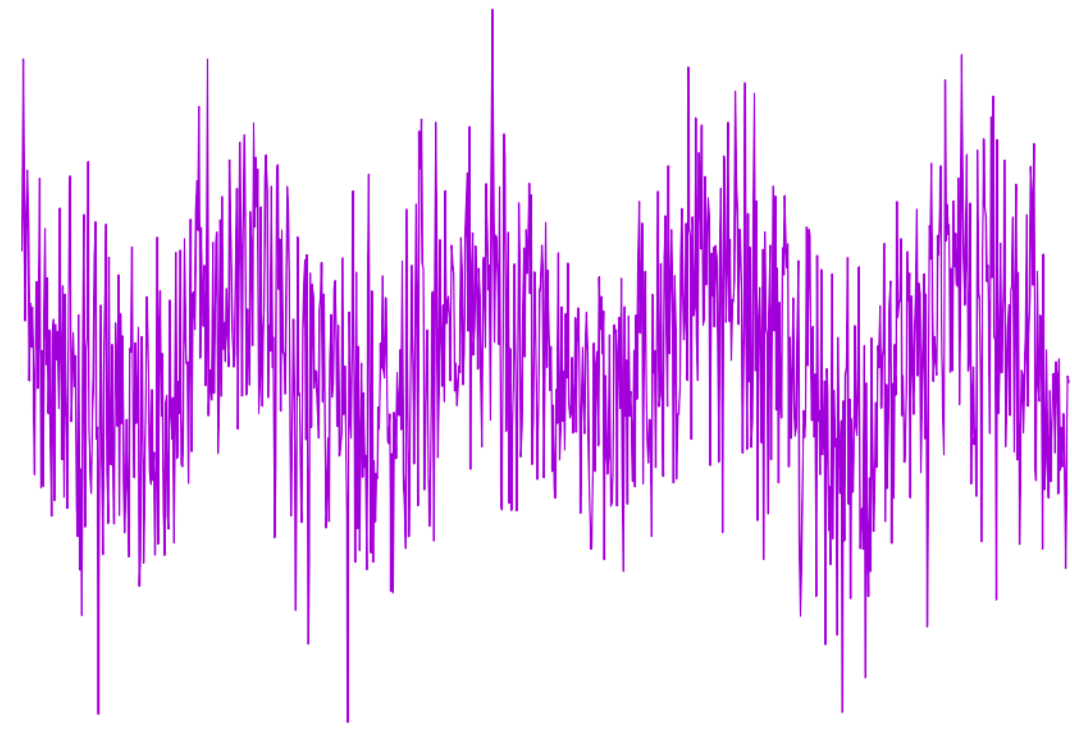
# LISA Data Analysis - Global Fit

Neil J. Cornish

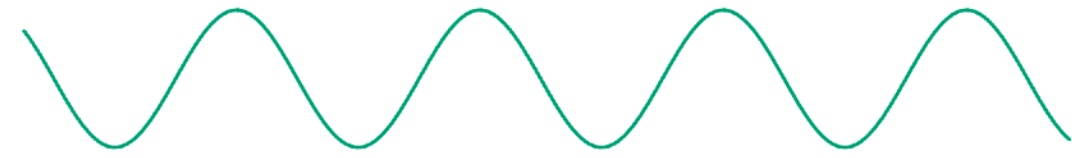




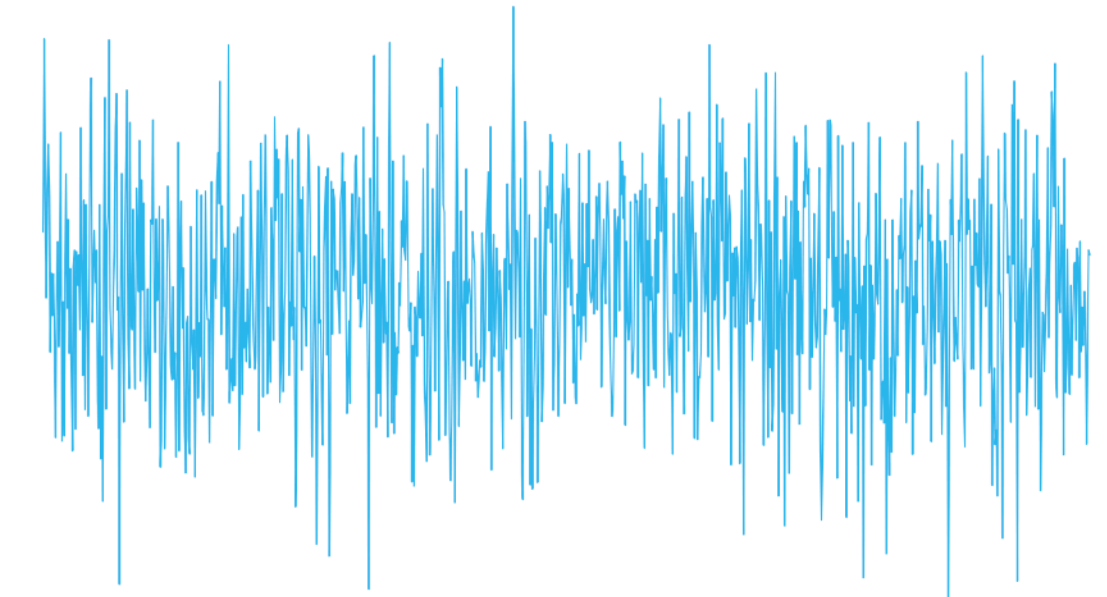
# Data analysis 101



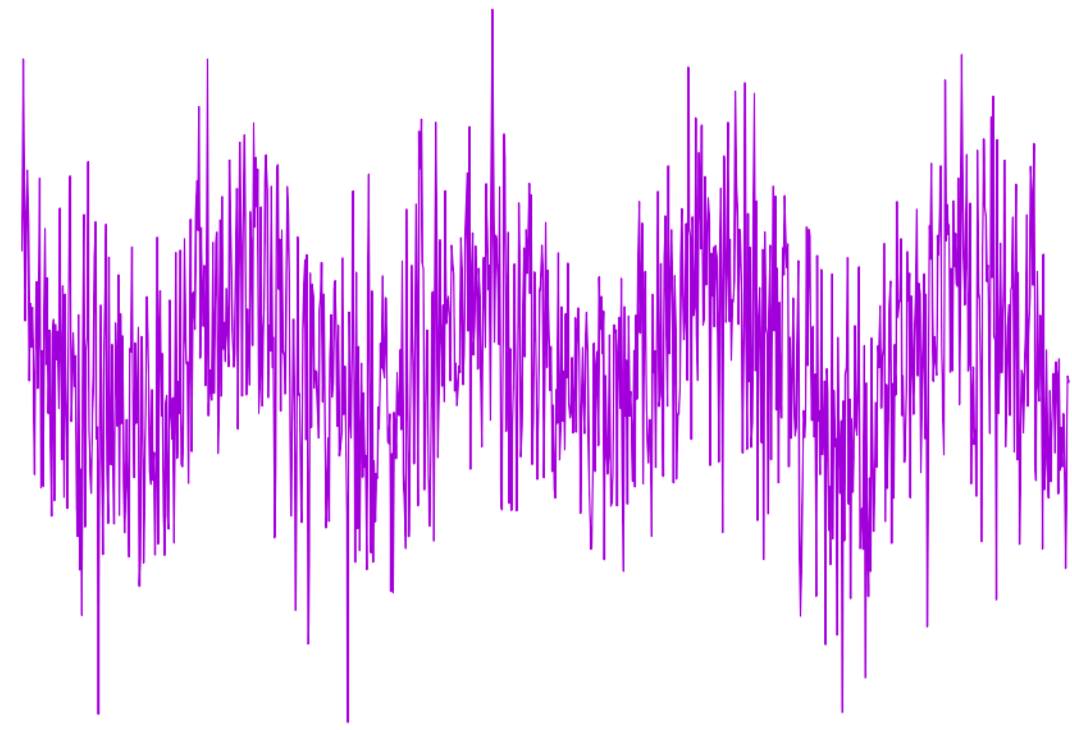
=



+

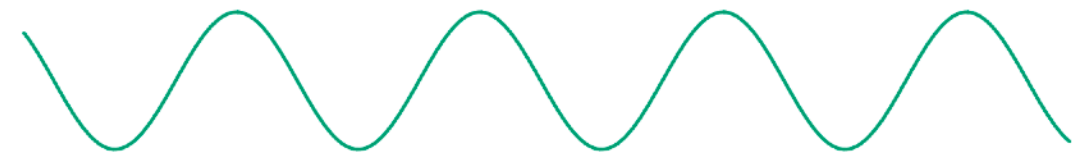


# Data analysis I 01



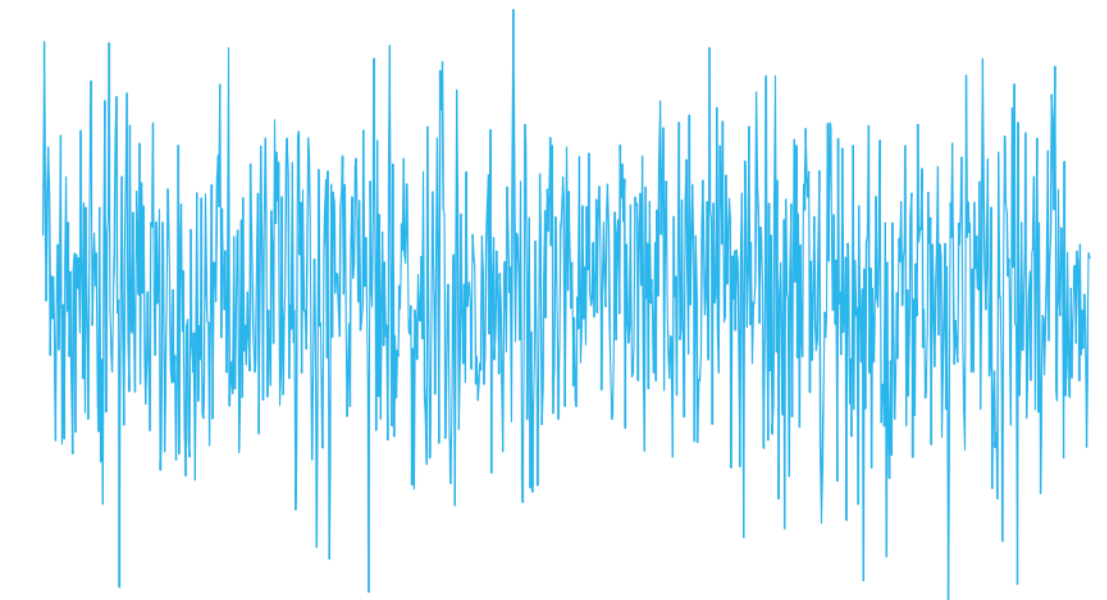
**d**

**=**



**h**

**+**



**n**

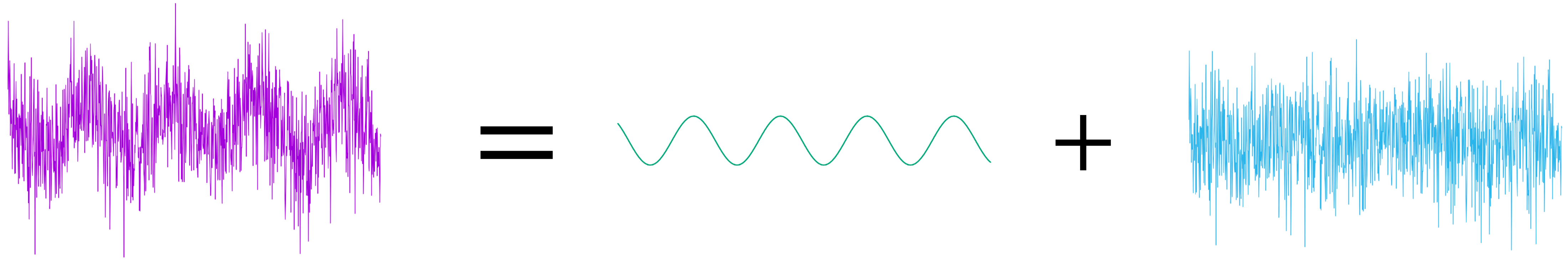
**=**

**+**

**⇒**

$$\mathbf{n} = \mathbf{d} - \mathbf{h}$$

# Data analysis I 01

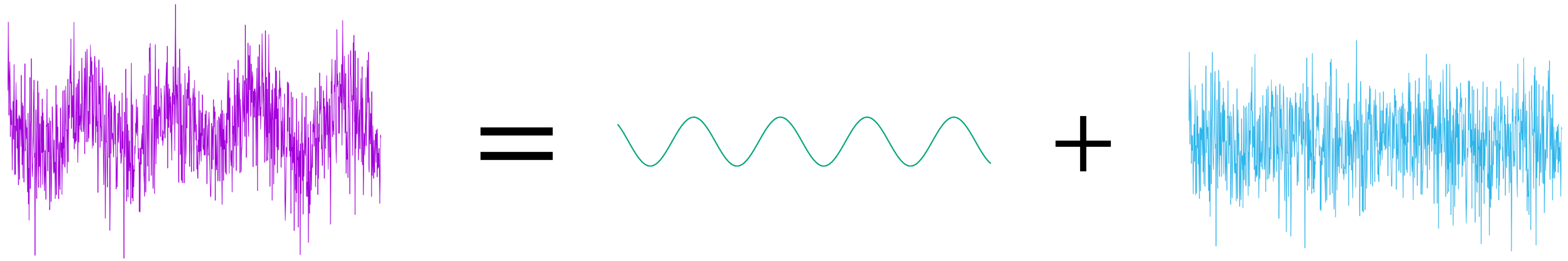


Noise model

$$p(\mathbf{n}) = \frac{1}{\sqrt{\det(2\pi \mathbf{C})}} e^{-\frac{1}{2} \mathbf{n}^\dagger \cdot \mathbf{C}^{-1} \cdot \mathbf{n}}$$



# Data analysis I 01



Noise model

$$p(\mathbf{n}) = \frac{1}{\sqrt{\det(2\pi \mathbf{C})}} e^{-\frac{1}{2} \mathbf{n}^\dagger \cdot \mathbf{C}^{-1} \cdot \mathbf{n}}$$

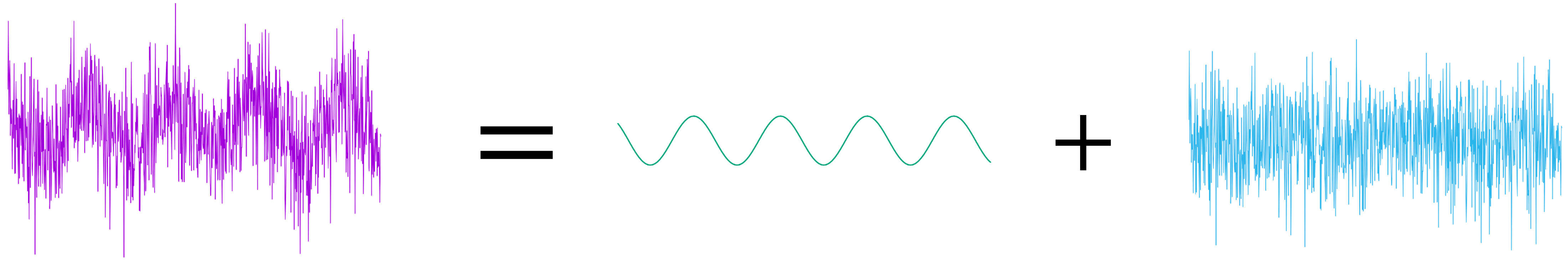
Integrate over noise realizations

$$p(\mathbf{d} | \mathbf{h}) = \int p(\mathbf{n}) \delta(\mathbf{n} - (\mathbf{d} - \mathbf{h})) d\mathbf{n} = \frac{1}{\sqrt{\det(2\pi \mathbf{C})}} e^{-\frac{1}{2} (\mathbf{d} - \mathbf{h})^\dagger \cdot \mathbf{C}^{-1} \cdot (\mathbf{d} - \mathbf{h})}$$

Likelihood



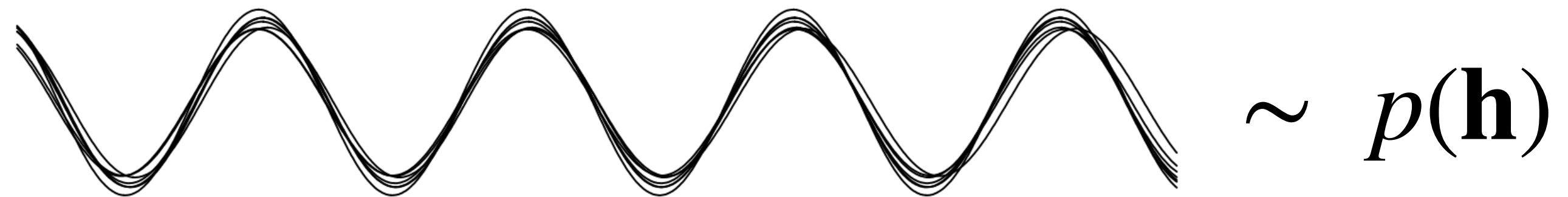
# Data analysis 101



Bayes Theorem

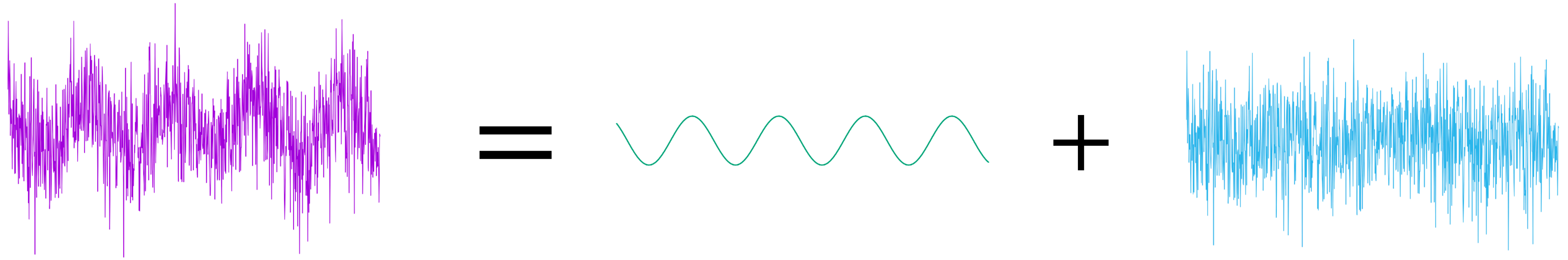
$$p(\mathbf{h}) = \frac{p(\mathbf{d} | \mathbf{h}) p(\mathbf{h})}{p(\mathbf{d})}$$

Posterior draws

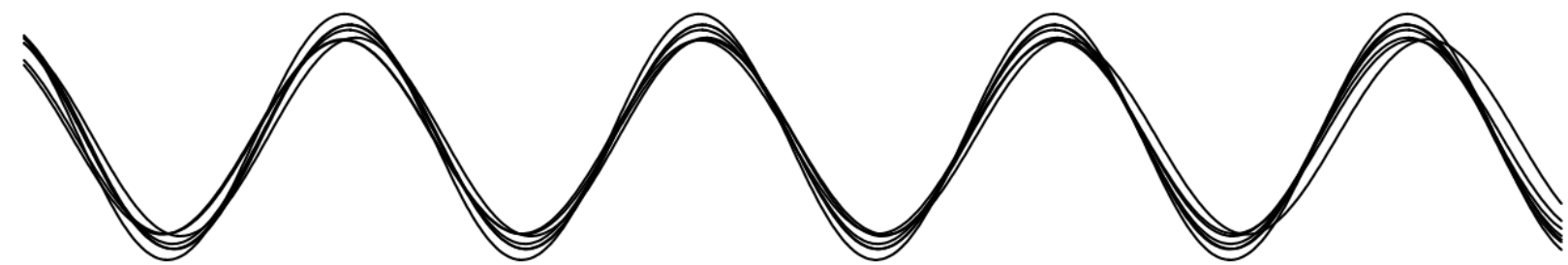




# Data analysis 101

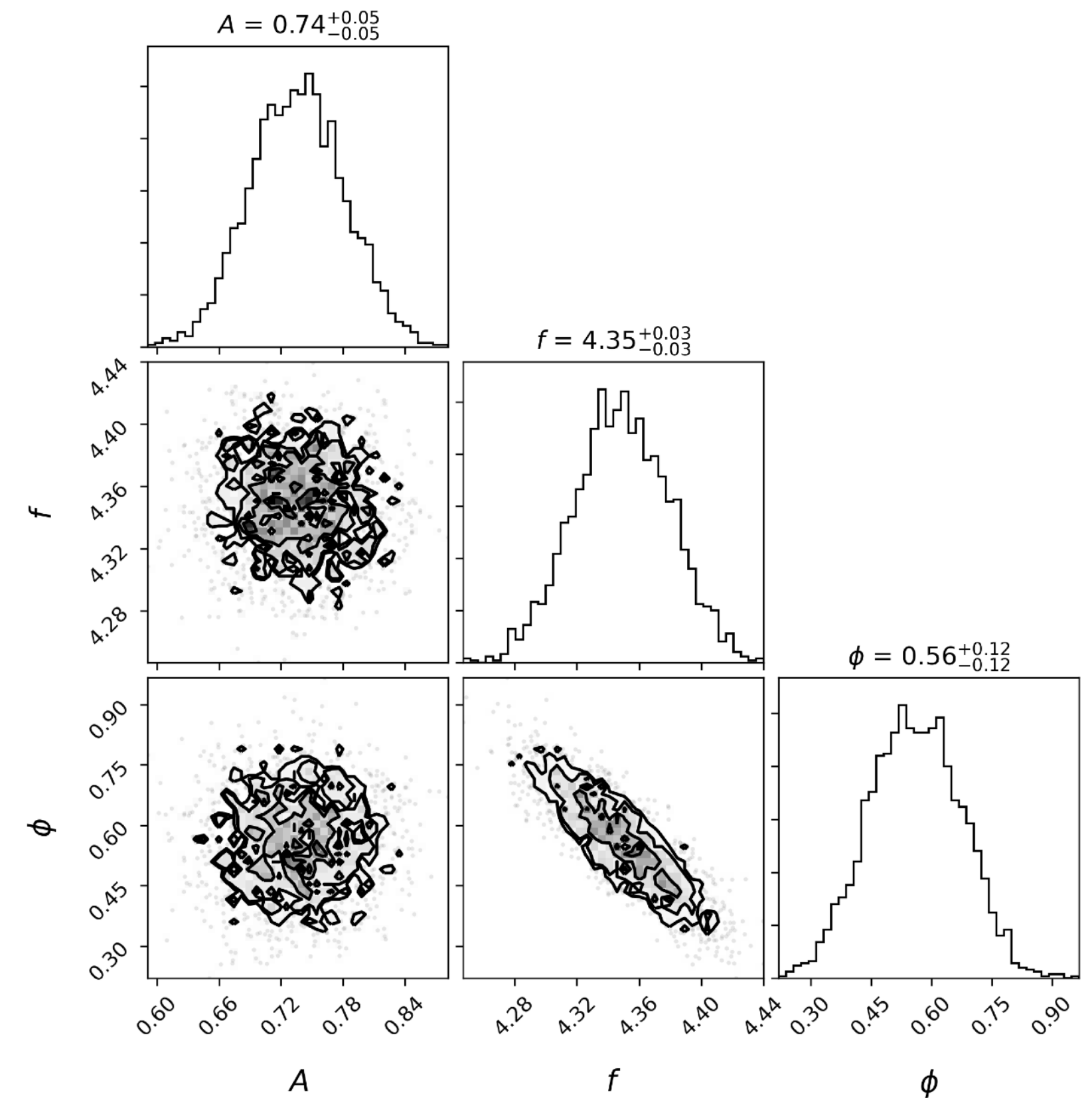


$$h(t, \vec{\lambda}) = A \cos(2\pi f t + \phi)$$

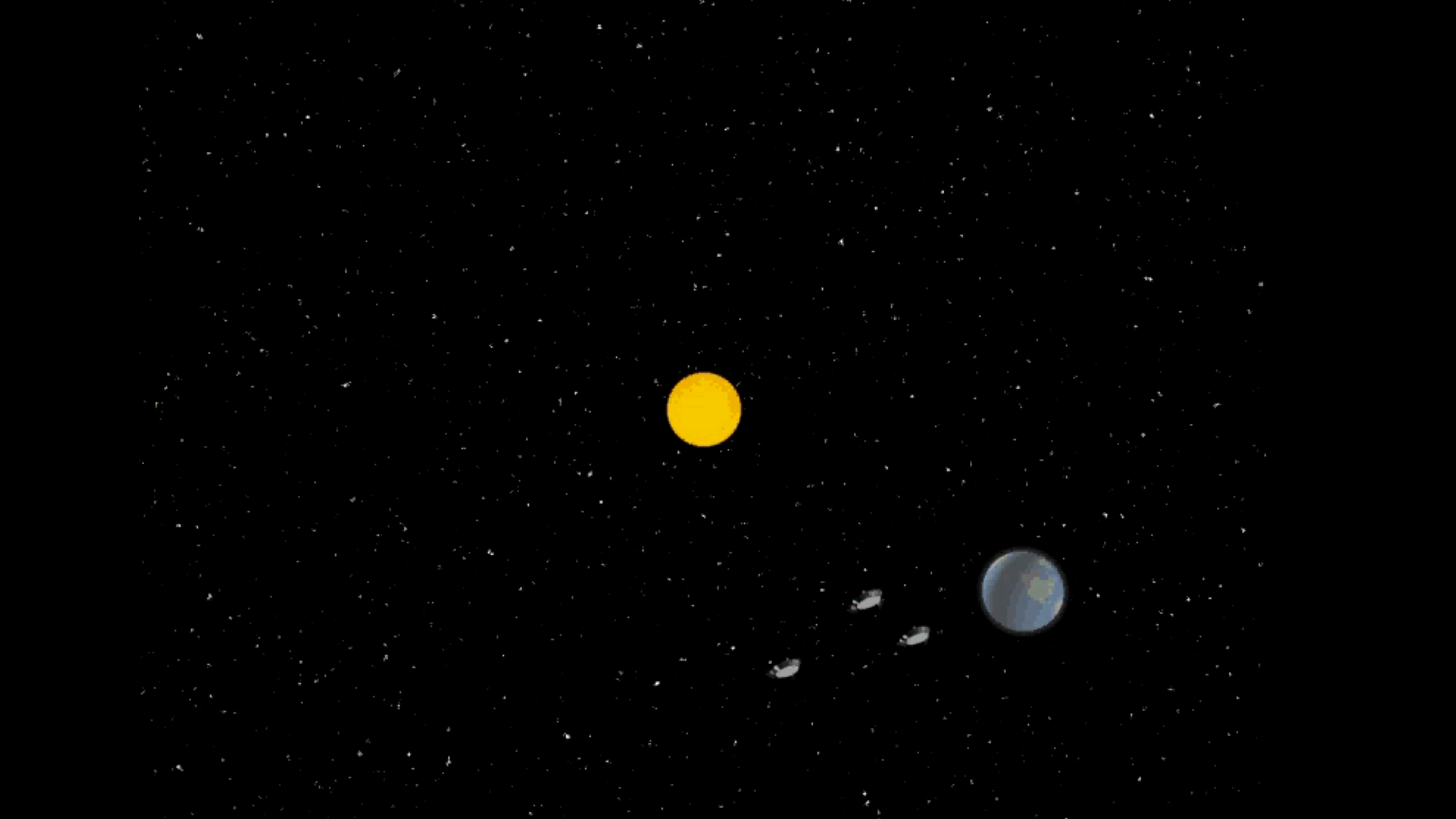


$$p(\mathbf{h}) \rightarrow p(\vec{\lambda})$$

Same idea for LISA, just with hundreds of thousands of parameters

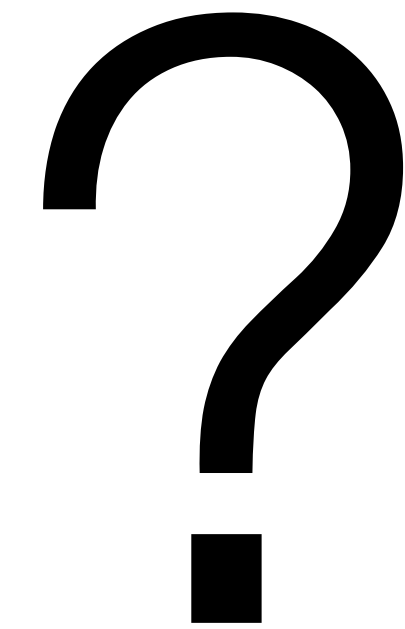
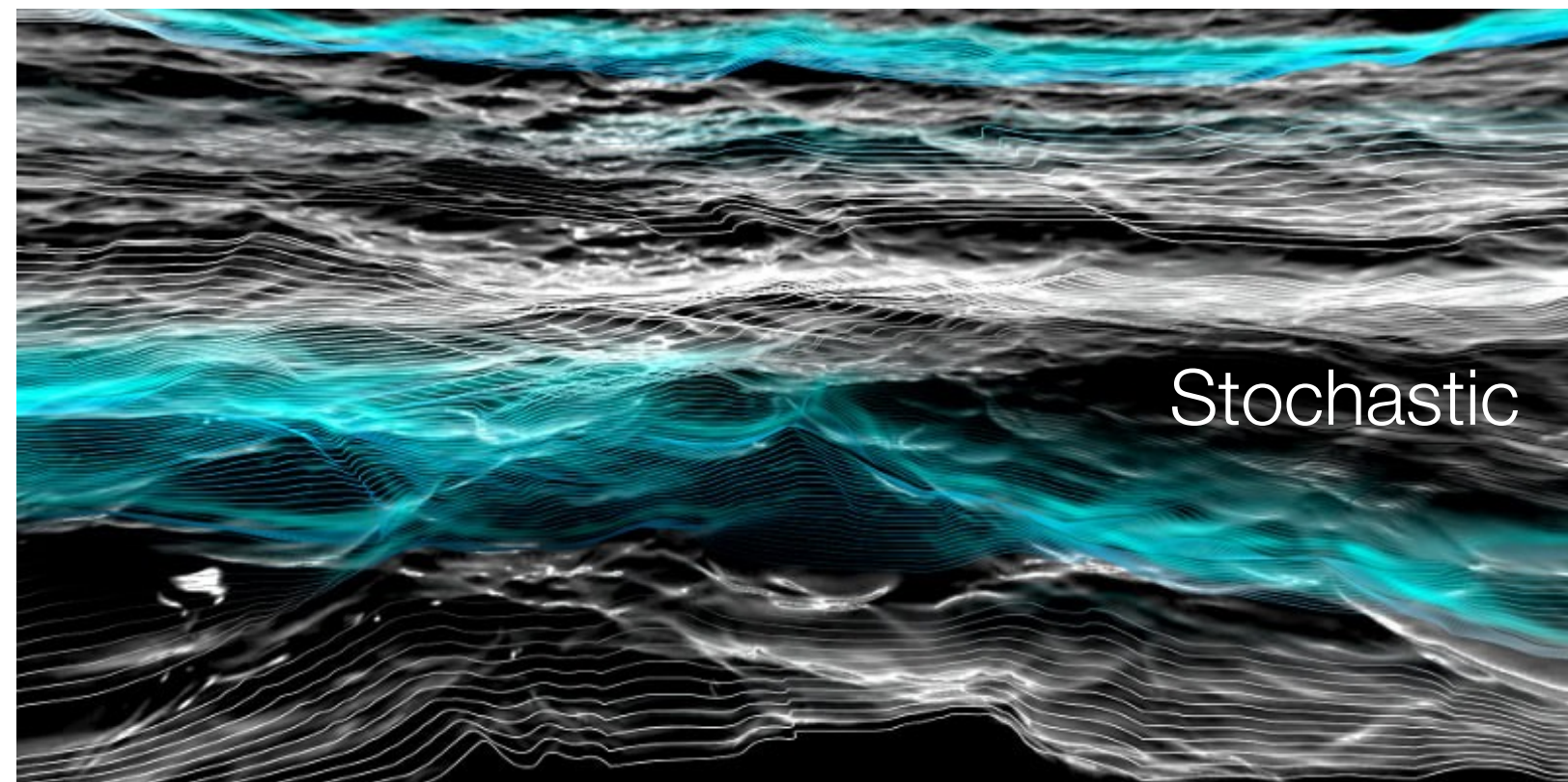
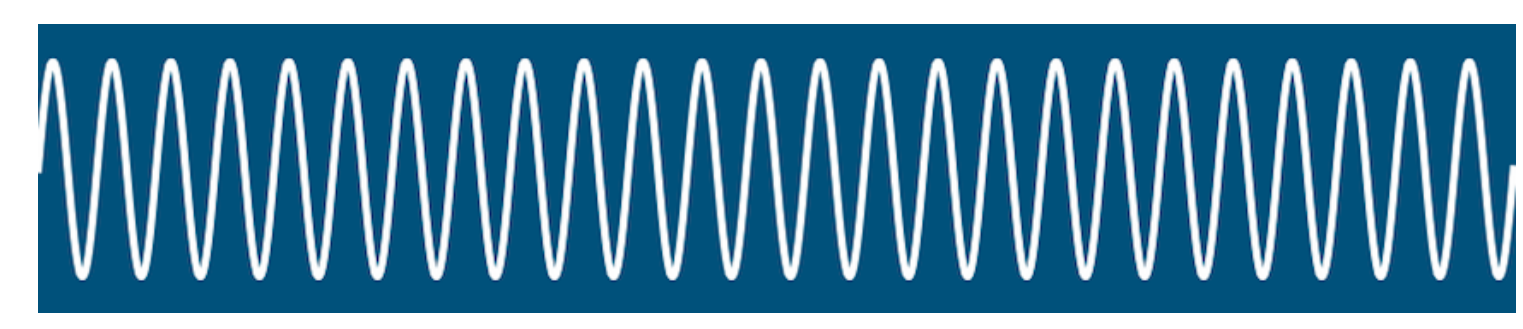
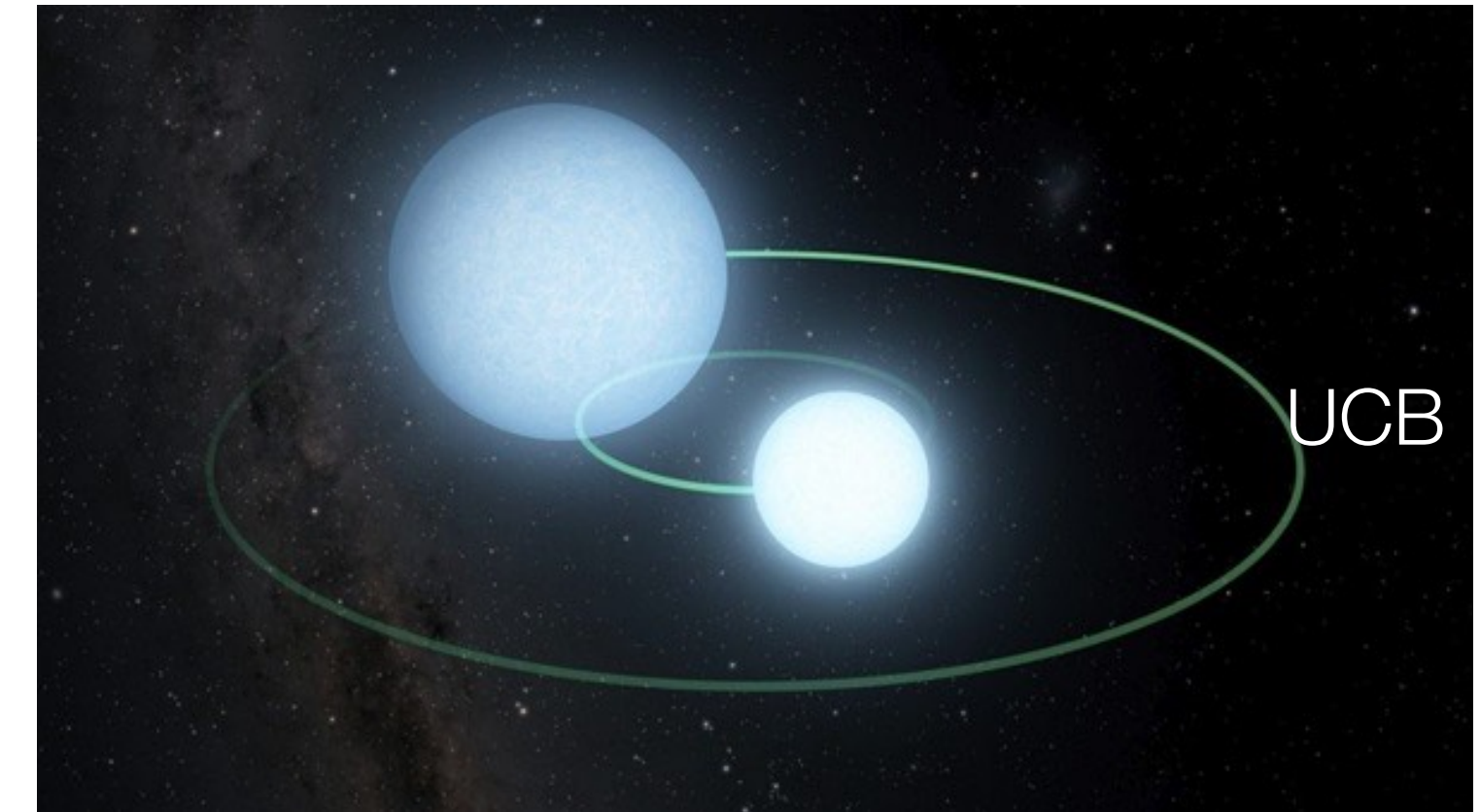
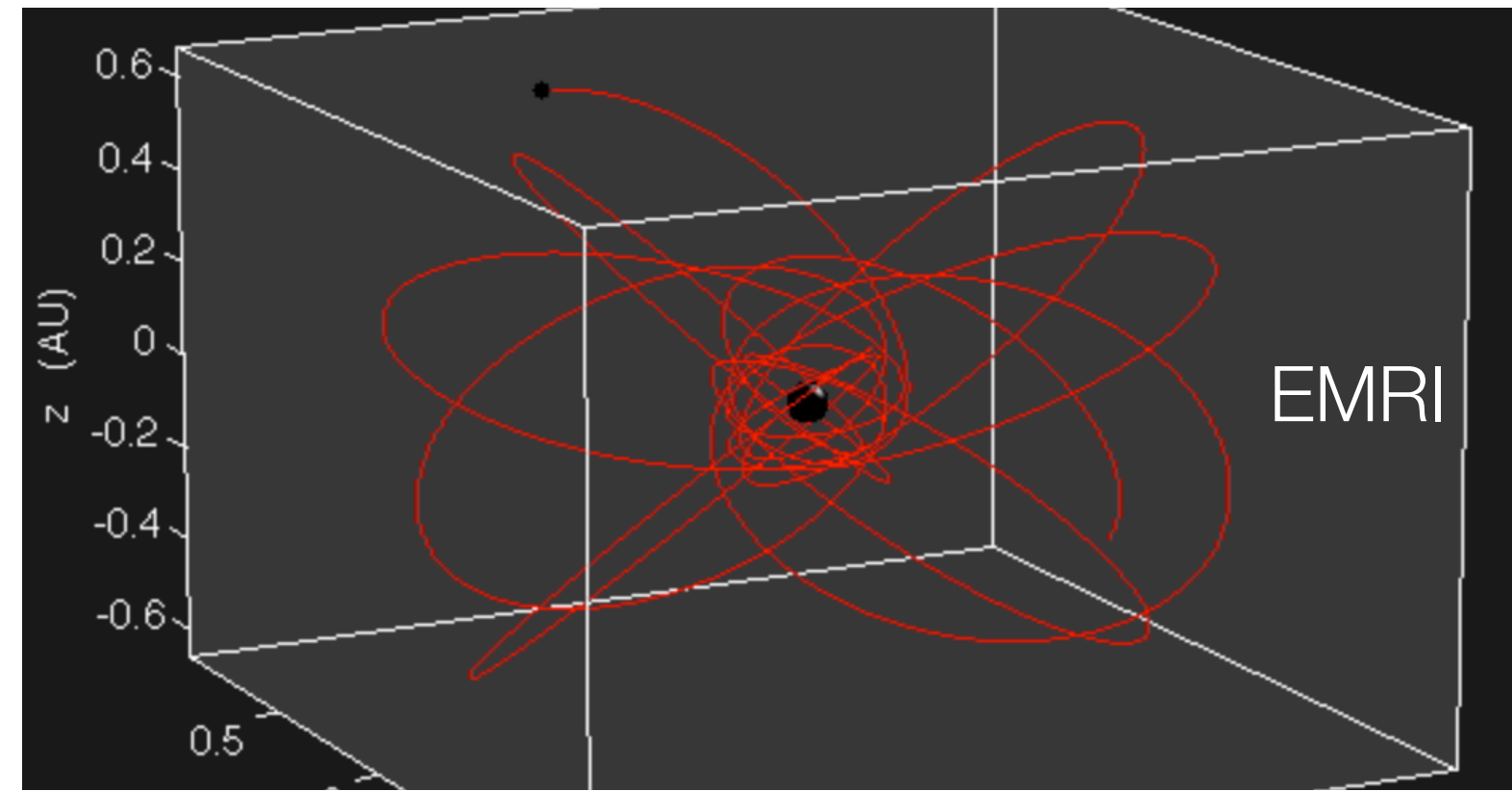
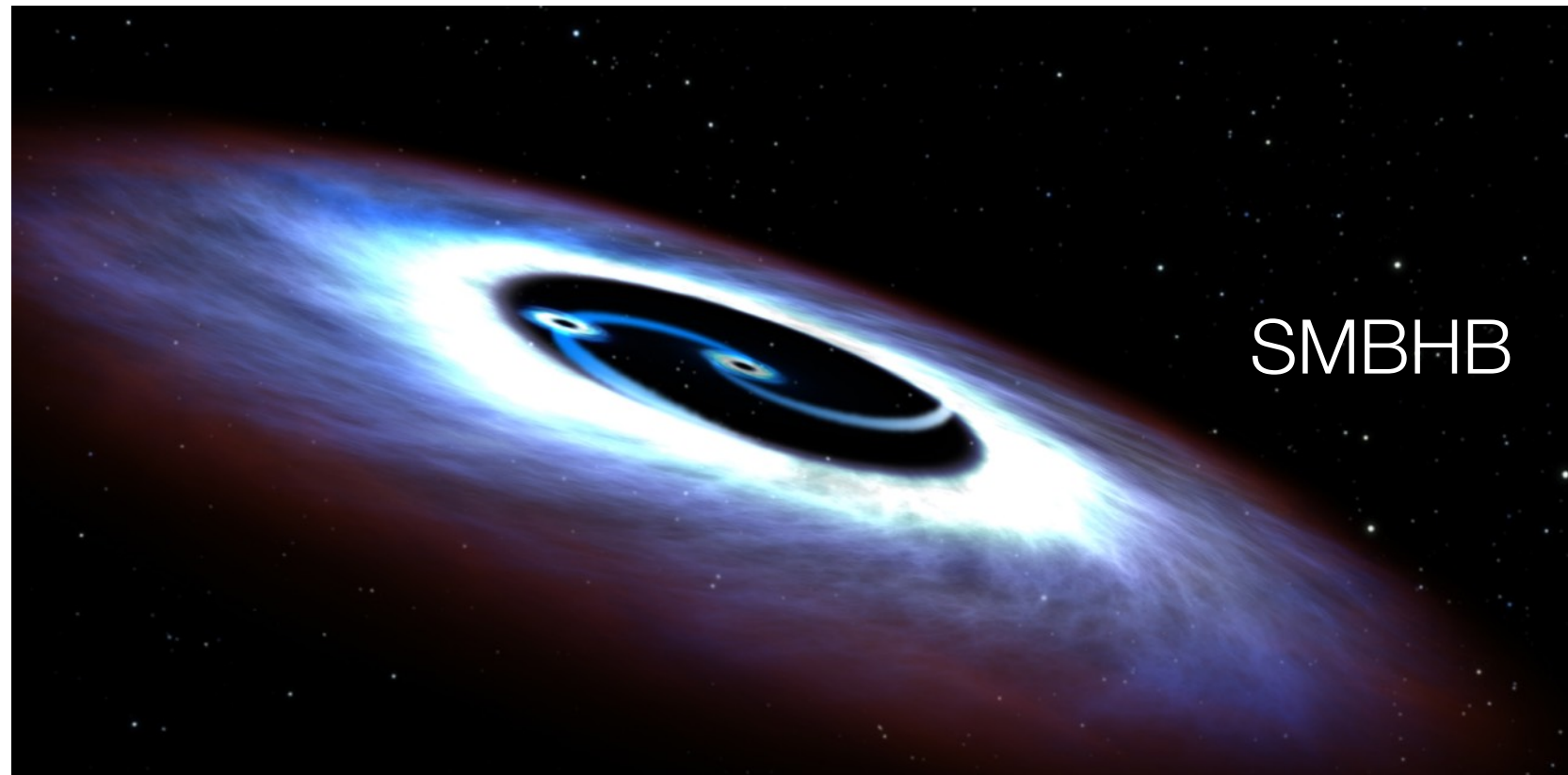








# LISA Sources





# LIGO/Virgo

- Short duration, non overlapping
- Low Latency Search
  - Maximum likelihood inspired
  - Analyze short time segments
  - Grid based search, simple templates
- Longer latency Bayesian follow up
- Also Continuous Wave, Un-modeled and Stochastic searches

# LISA

- Millions of overlapping signals
- High dimensional search space
  - Grid based searches impractical
  - Stochastic search methods
- Signal duration often comparable to mission lifetime
- Need a Global Fit: Binaries of all kinds, stochastic signals and un-modeled signals. All together

Because of the signal overlaps, a global fit to all the signals has to be performed

## PHYSICAL REVIEW D

covering particles, fields, gravitation, and cosmology

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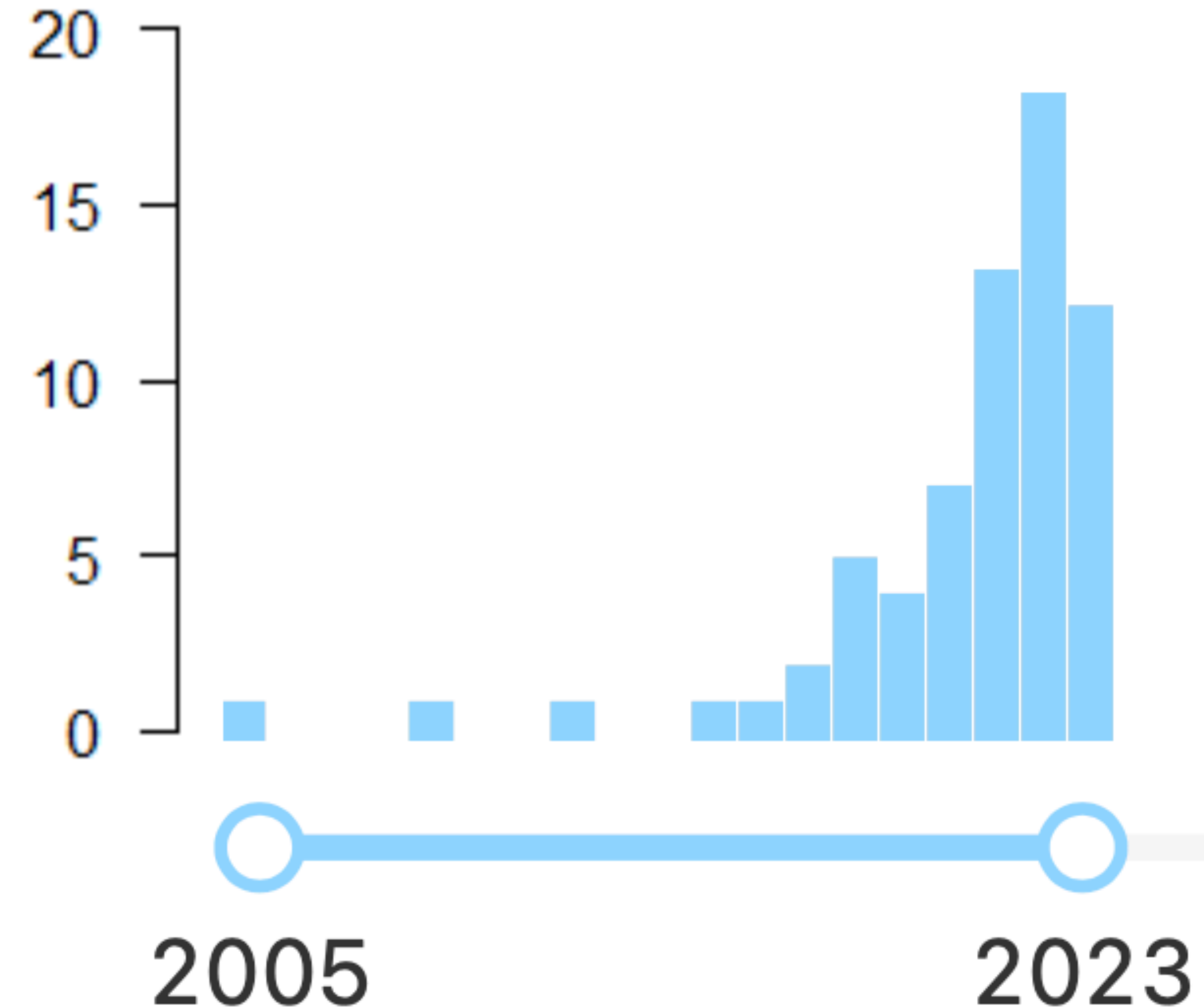
### LISA data analysis using Markov chain Monte Carlo methods

Neil J. Cornish and Jeff Crowder  
Phys. Rev. D **72**, 043005 – Published 22 August 2005

Article References Citing Articles (85) PDF HTML Export Citation

#### ABSTRACT

The Laser Interferometer Space Antenna (LISA) is expected to simultaneously detect many thousands of low-frequency gravitational wave signals. This presents a data analysis challenge that is very different to the one encountered in ground based gravitational wave astronomy. LISA data analysis requires the identification of individual signals from a data stream containing an unknown number of overlapping signals. **Because of the signal overlaps, a global fit to all the signals has to be performed** in order to avoid biasing the solution. However, performing such a global fit requires the exploration of an enormous parameter space with a dimension upwards of 50000. Markov Chain Monte Carlo (MCMC) methods offer a very promising solution to the LISA data analysis problem. MCMC algorithms





# The Global Solution

Likelihood function  
for Gaussian noise

$$p(\mathbf{d}|\vec{\lambda}) = \frac{1}{\sqrt{(2\pi)^M \det \mathbf{C}}} e^{-\frac{1}{2}(\mathbf{d}-\mathbf{h}) \cdot \mathbf{C}^{-1} \cdot (\mathbf{d}-\mathbf{h})}$$

$$\mathbf{h} = \sum_{i=1}^N \mathbf{h}_i = \text{GW signal model}$$

$N$  unknown, mix of signal types

$\mathbf{C}$  = noise correlation matrix

Jointly inferred with signal model. Up to  $M^3$  cost to invert

$\vec{\lambda}$  = model parameters

Signal and noise  $\mathcal{O}(10^6)$  parameters

# The Global Solution

Likelihood function  
for Gaussian noise

$$p(\mathbf{d}|\vec{\lambda}) = \frac{1}{\sqrt{(2\pi)^M \det \mathbf{C}}} e^{-\frac{1}{2}(\mathbf{d}-\mathbf{h}) \cdot \mathbf{C}^{-1} \cdot (\mathbf{d}-\mathbf{h})}$$

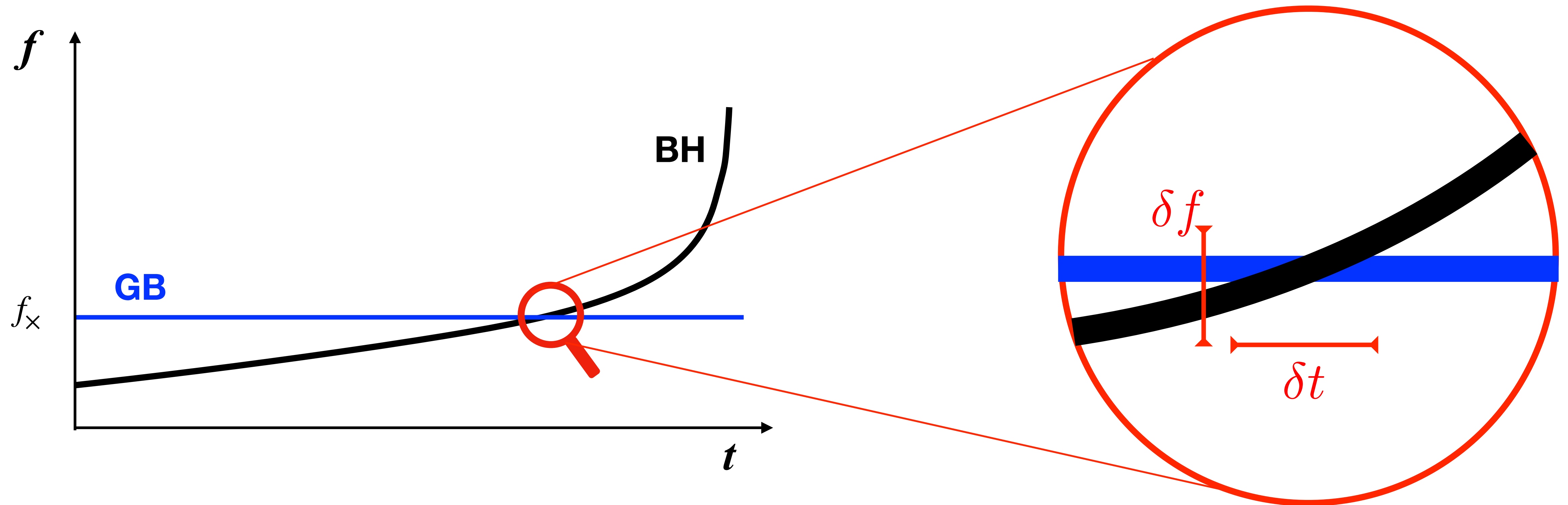
$$\log L = (d|h) - \frac{1}{2}(h|h) = \sum_i^N \log L_i - \frac{1}{2} \sum_{i \neq j} (h_i|h_j)$$

Per-source likelihood

Signal overlaps - why we need  
a global solution



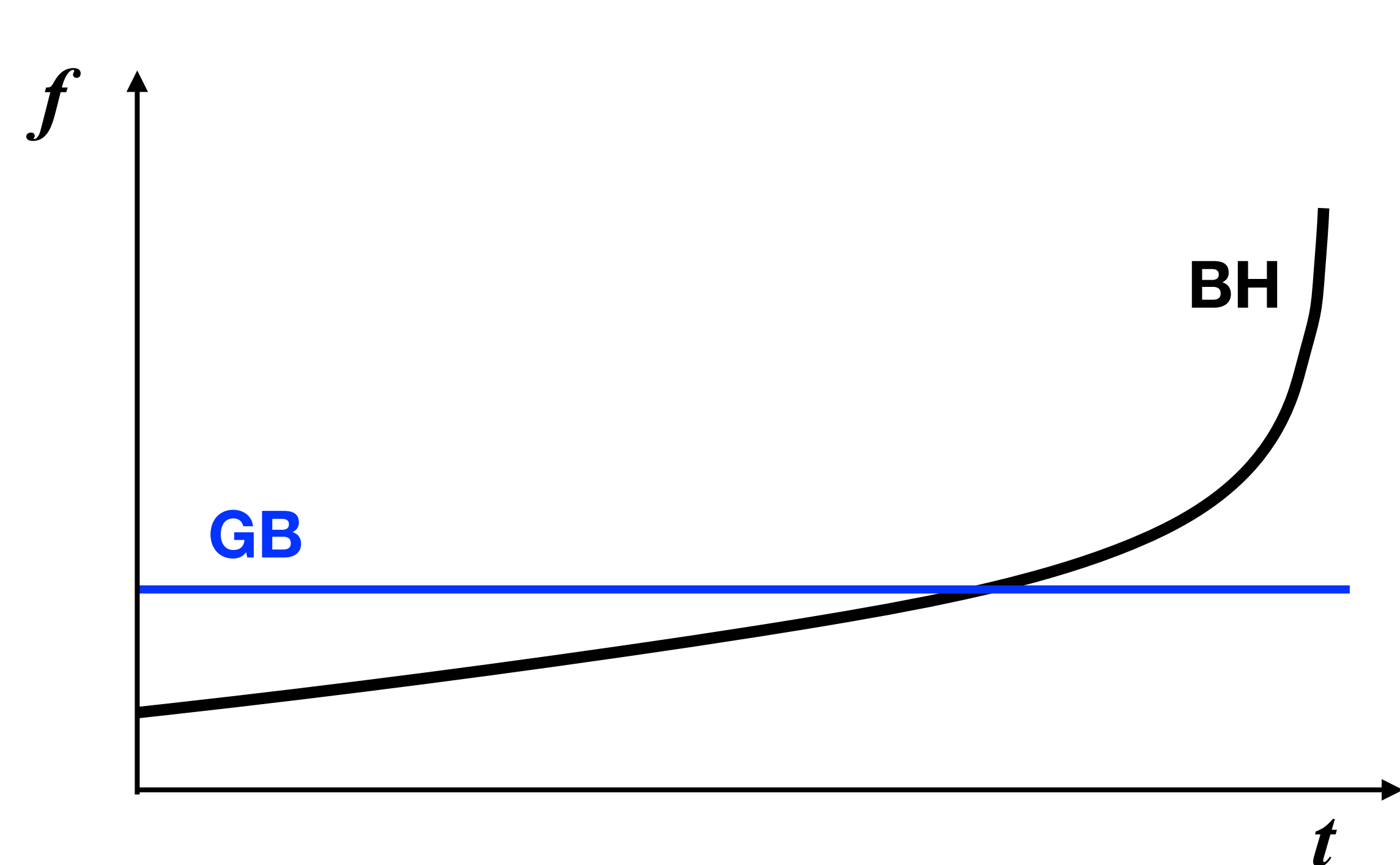
# Example: SMBHB-GB Signal Overlaps



$$\delta f = 3 \times 10^{-7} \text{ mHz} \left( \frac{\mathcal{M}_{\text{GB}}}{0.25 M_{\odot}} \right)^{5/6} \left( \frac{f_x}{1 \text{ mHz}} \right)^{11/6}$$

$$\delta t = 1.7 \times 10^3 \text{ s} \left( \frac{10^6 M_{\odot}}{\mathcal{M}_{\text{BH}}} \right)^{5/6} \left( \frac{1 \text{ mHz}}{f_x} \right)^{11/6}$$

# Example: SMBHB-GB Signal Overlaps



$$\begin{aligned}
 (\mathbf{h}_{\text{BH}} | \mathbf{h}_{\text{GB}}) &= \left( \frac{S_{\text{BH}}(f_{\times})}{S_{\text{n}}(f_{\times})} \right)^{1/2} \rho_{\text{GB}} \cos \delta \\
 &\approx 10^{-3} \rho_{\text{BH}} \rho_{\text{GB}} \cos \delta
 \end{aligned}$$

Instantaneous BH SNR

↓

Random phase mismatch

↓

Individual overlaps are small, but there will be tens of thousands of them

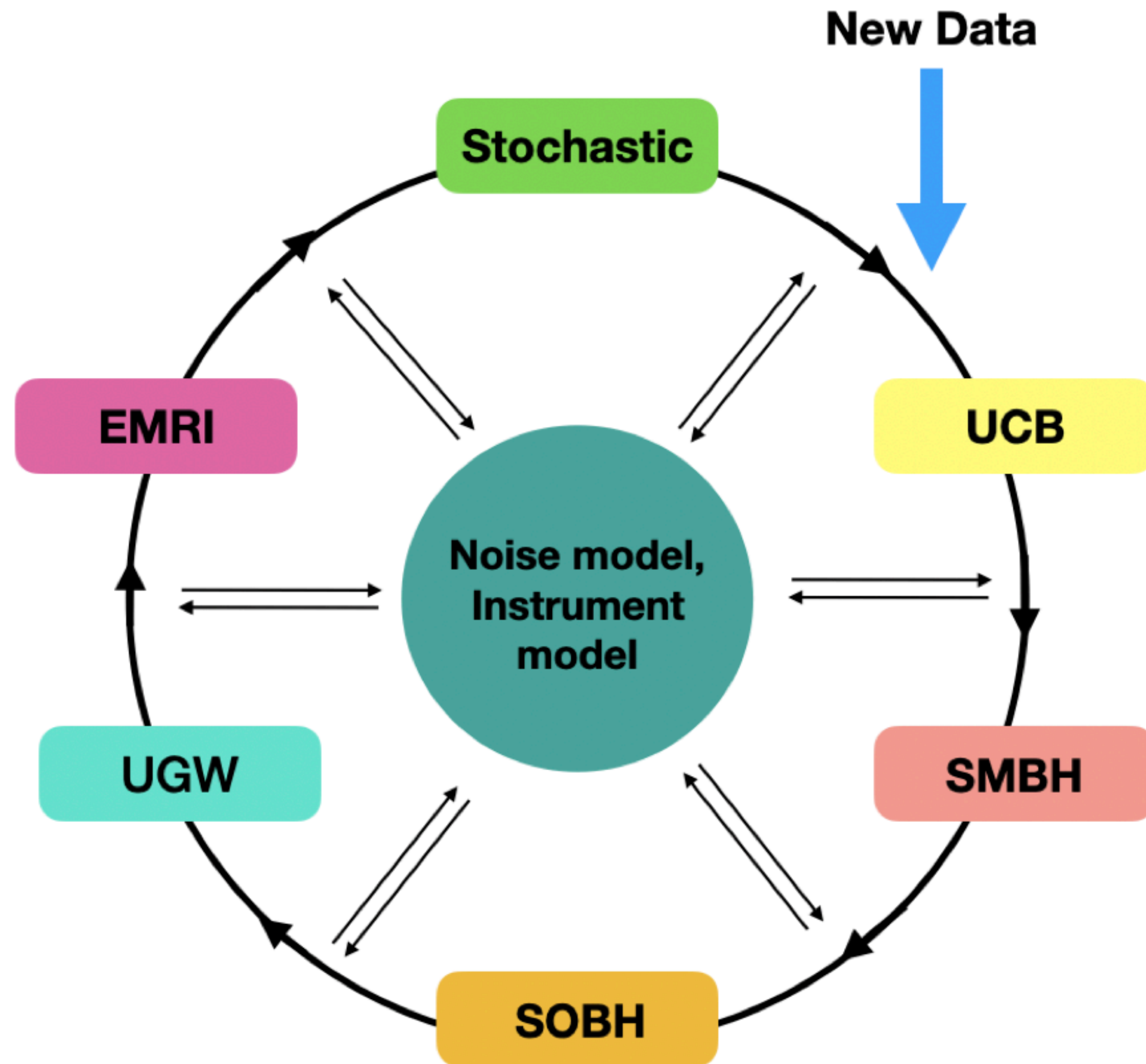
$$\sum_{\text{GB}} (\mathbf{h}_{\text{BH}} | \mathbf{h}_{\text{GB}}) \approx \sqrt{N_{\text{GB}}} 10^{-3} \rho_{\text{BH}} \rho_{\text{GB}} \approx 0.2 \rho_{\text{BH}} \rho_{\text{GB}}$$

Significant bias if not solved for simultaneously

[see Cutler & Harms (2008), Robson & Cornish (2018)]



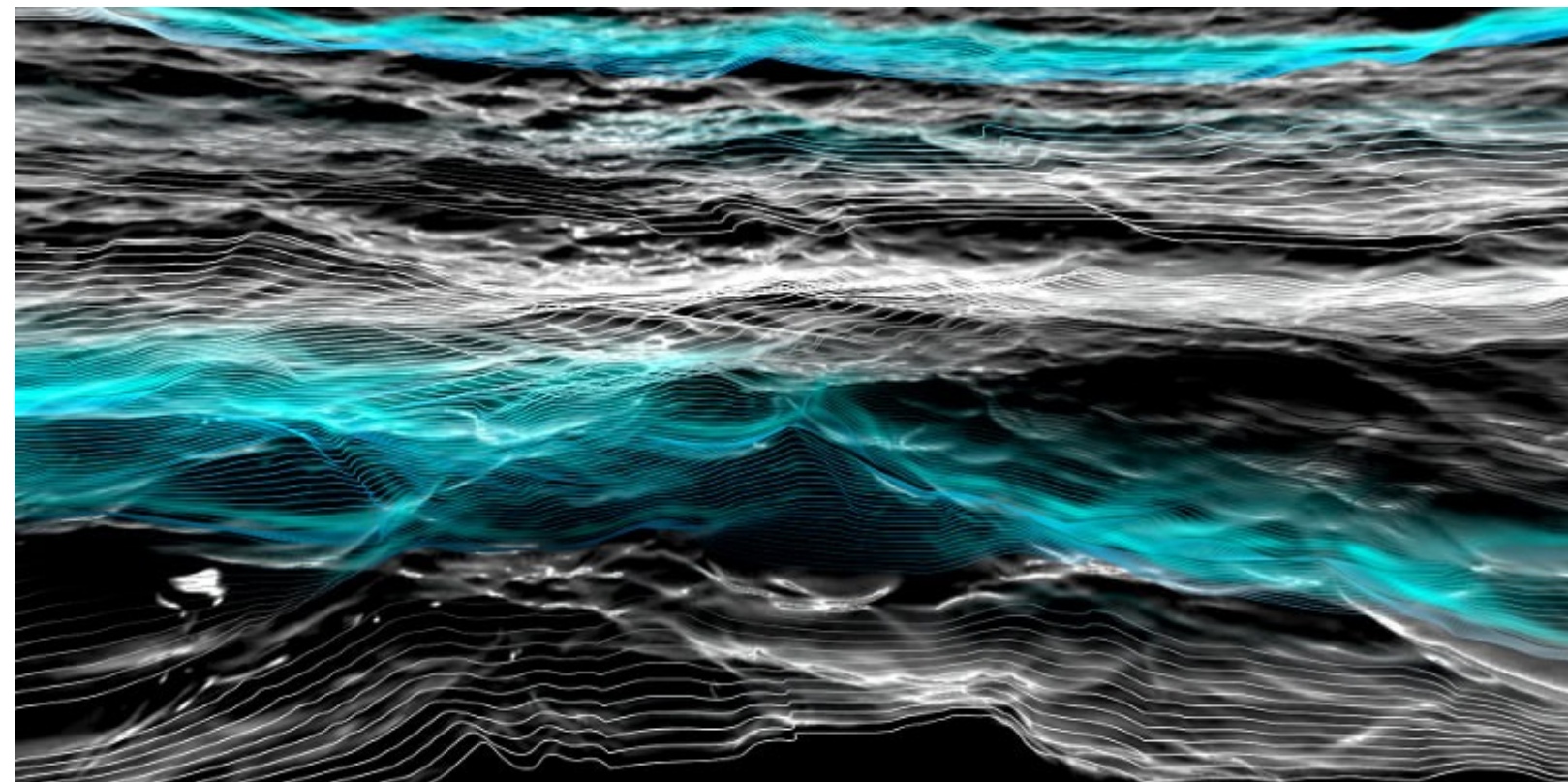
# Global Fit via Blocked Sampling



- Transdimensional Markov Chain Monte Carlo (RJMCMC)
- Blocked Metropolis Hastings— update each component of the signal/noise model in circular sweeps
- Only pass residuals - decouples the analysis types
- Update the fit every ~week as new data arrives

How does the stochastic background fit into all this?

$$p(\mathbf{d}|\vec{\lambda}) = \frac{1}{\sqrt{(2\pi)^M \det \mathbf{C}}} e^{-\frac{1}{2}(\mathbf{d}-\mathbf{h}) \cdot \mathbf{C}^{-1} \cdot (\mathbf{d}-\mathbf{h})}$$



$$\mathbf{h} = \sum_{i=1}^N \mathbf{h}_i = \text{GW signal model}$$

$$\mathbf{h}_s = \sum_f \tilde{a}_f e^{2\pi i f t}$$

Just another template to be included in the signal model

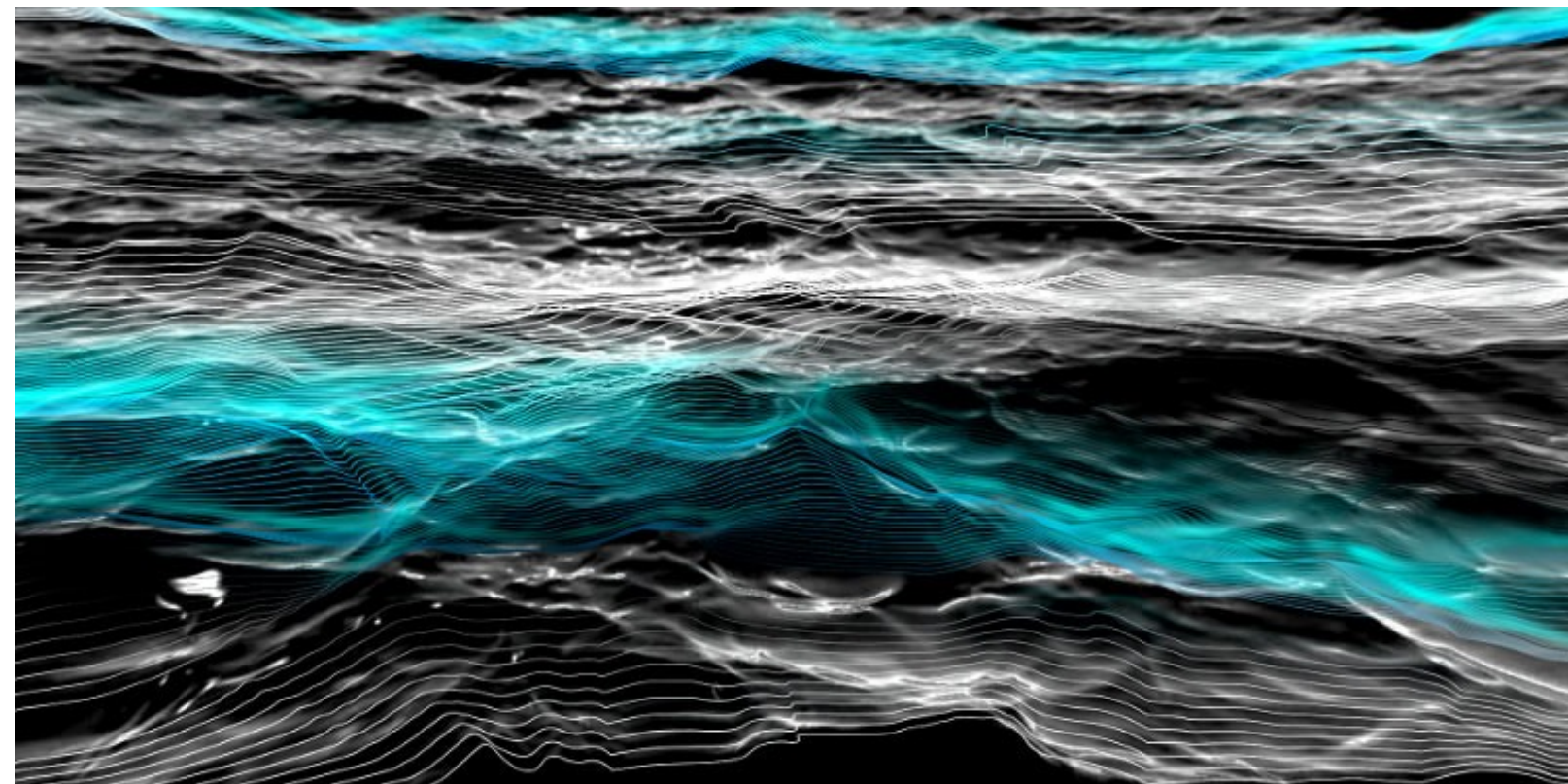


How does the stochastic background fit into all this?

$$\mathbf{h}_s = \sum_f \tilde{a}_f e^{2\pi i f t}$$

Just another template to be included in the signal model

“Stochastic template”. Gaussian prior with spectrum  $S_h(f)$



$$p(\tilde{a}_f) = \prod_f \frac{1}{2\pi S_h(f)} \exp\left(\frac{-\tilde{a}_f \tilde{a}_f^*}{S_h(f)}\right)$$



How does the stochastic background fit into all this?

$$\mathbf{h}_s = \tilde{a}_f e^{2\pi i f t} \quad p(\tilde{a}_f) = \prod_f \frac{1}{2\pi S_h(f)} \exp\left(\frac{-\tilde{a}_f \tilde{a}_f^*}{S_h(f)}\right)$$

Typically we are not interested in the particular realization of the random amplitudes so we can integrate them out. e.g. for stationary data in the frequency domain we get

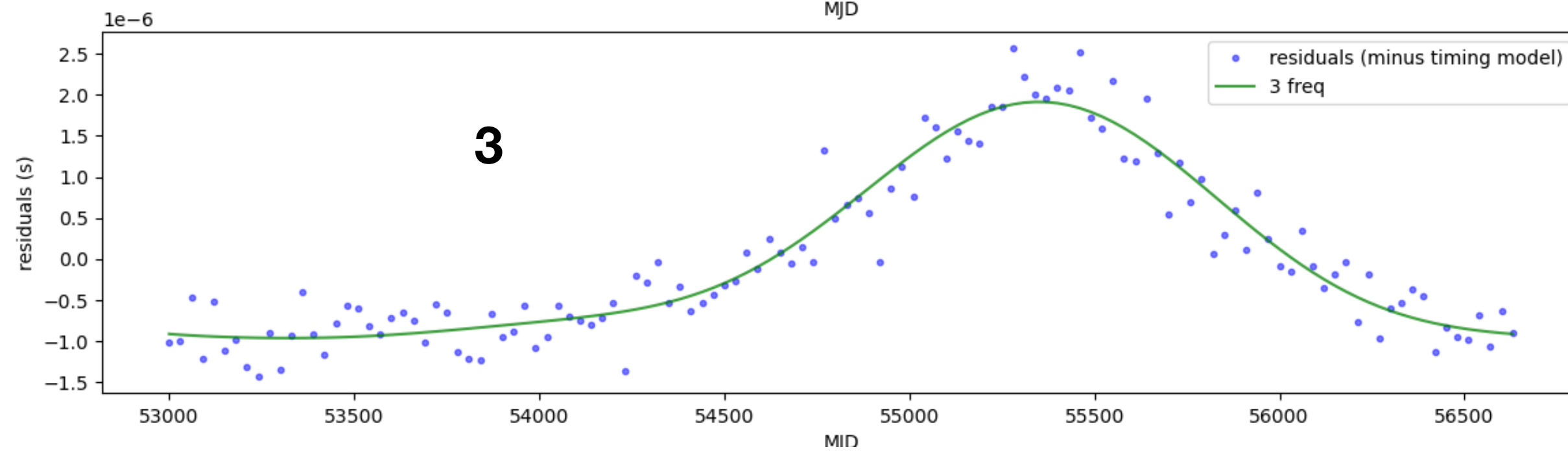
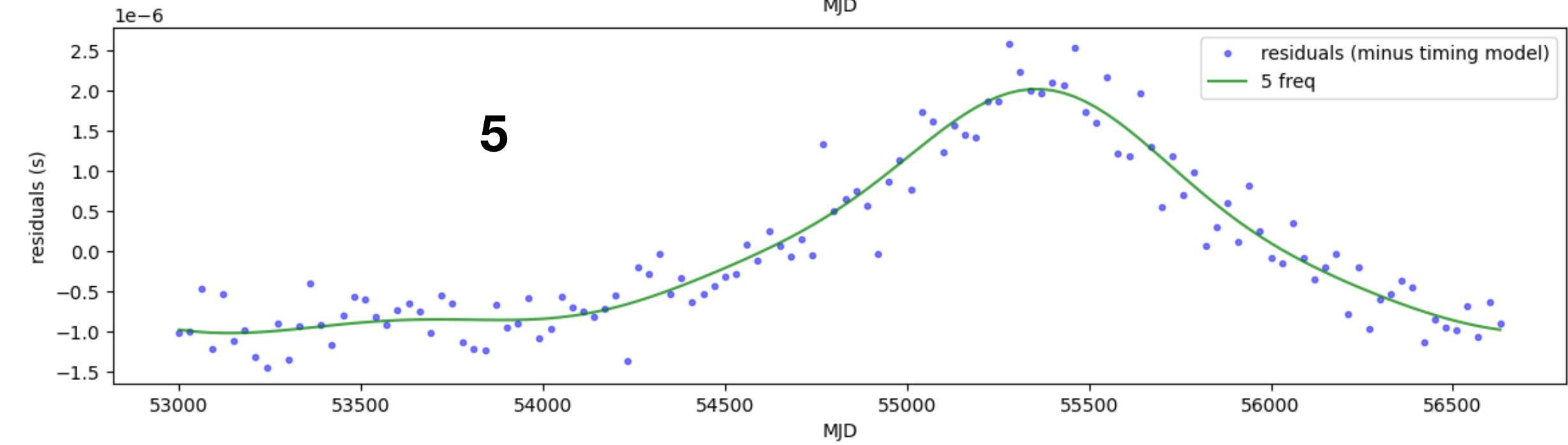
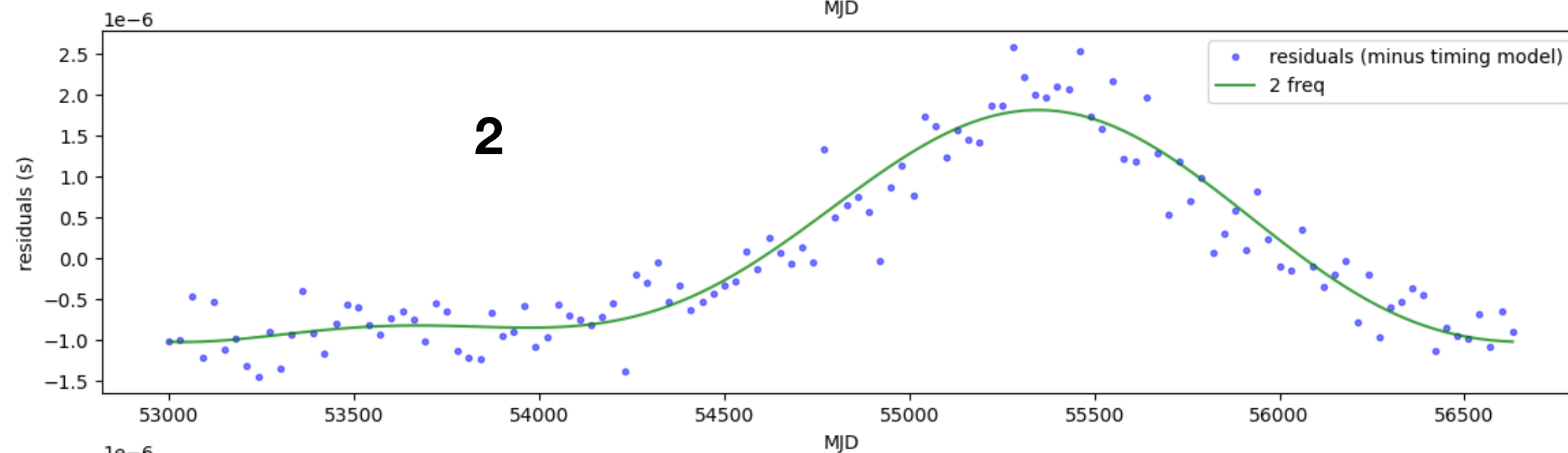
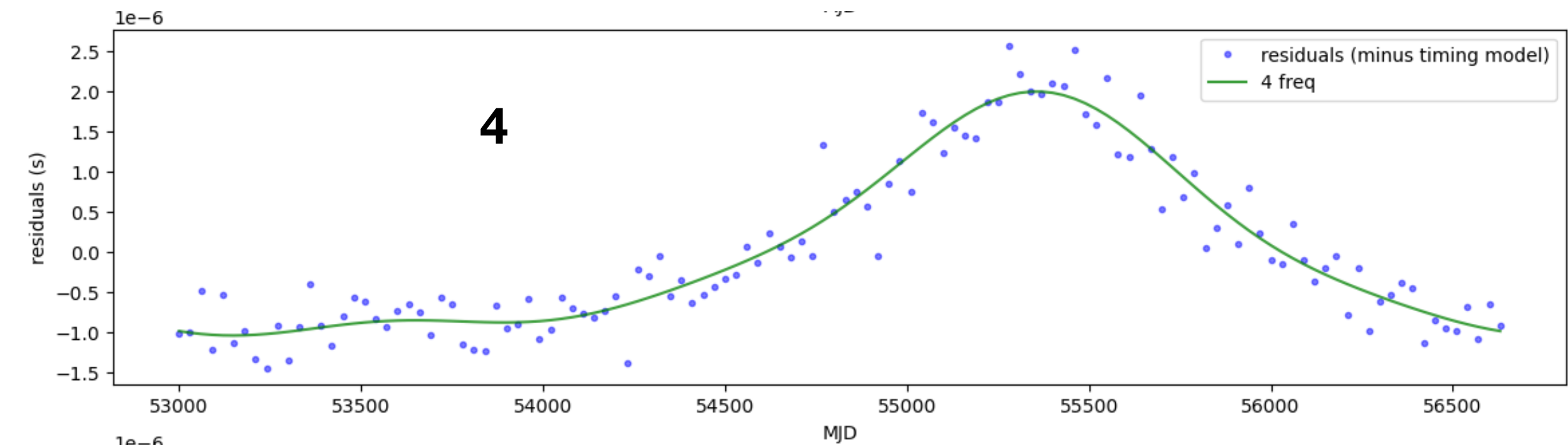
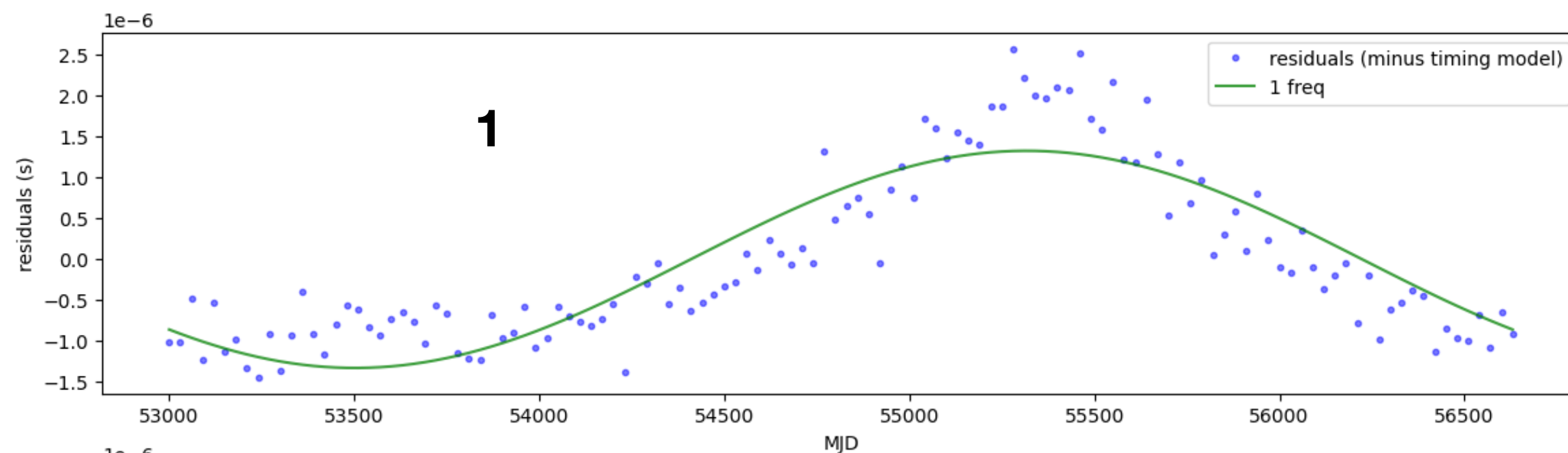
$$p(\mathbf{d}) = \frac{1}{\det(2\pi\mathbf{G})} \exp\left[-(\tilde{d}(f) - \tilde{h}(f))_i^* \mathbf{G}_{ij}(f)^{-1} (\tilde{d}(f) - \tilde{h}(f))_j\right]$$

Overlap reduction function (LIGO), Hellings-Downs Curve (PTAs)

$$\mathbf{G}_{ij}(f) = \delta_{ij} S_{n,i}(f) + \gamma_{ij}(f) S_h(f) \quad \gamma_{ij}(f) = \frac{1}{4\pi} \int (F_i^+(\hat{n})F_j^+(\hat{n}) + F_i^\times(\hat{n})F_j^\times(\hat{n})) e^{2\pi i f(\vec{x}_i - \vec{x}_j) \cdot \hat{n}} d\Omega_{\hat{n}}$$

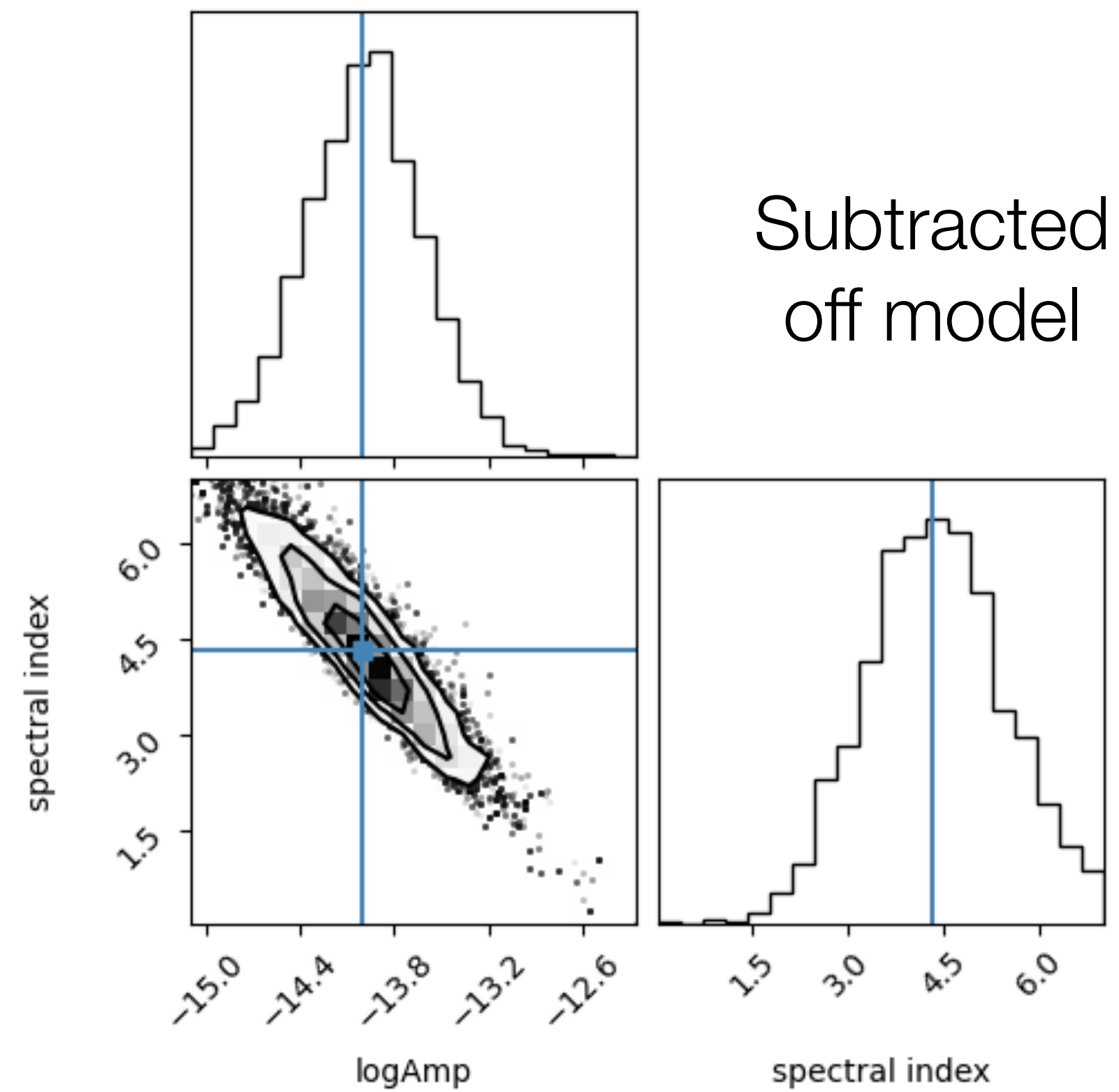
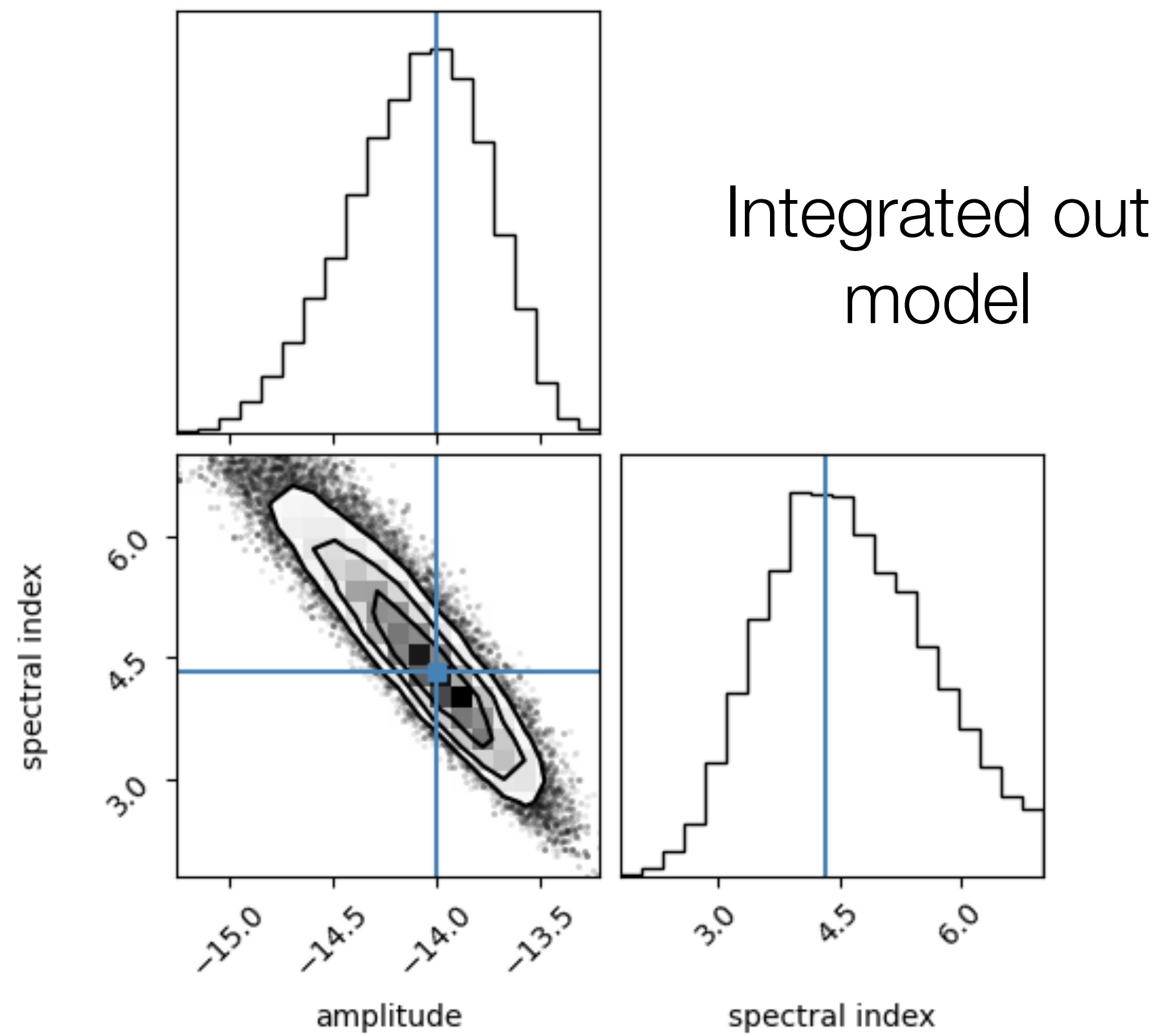
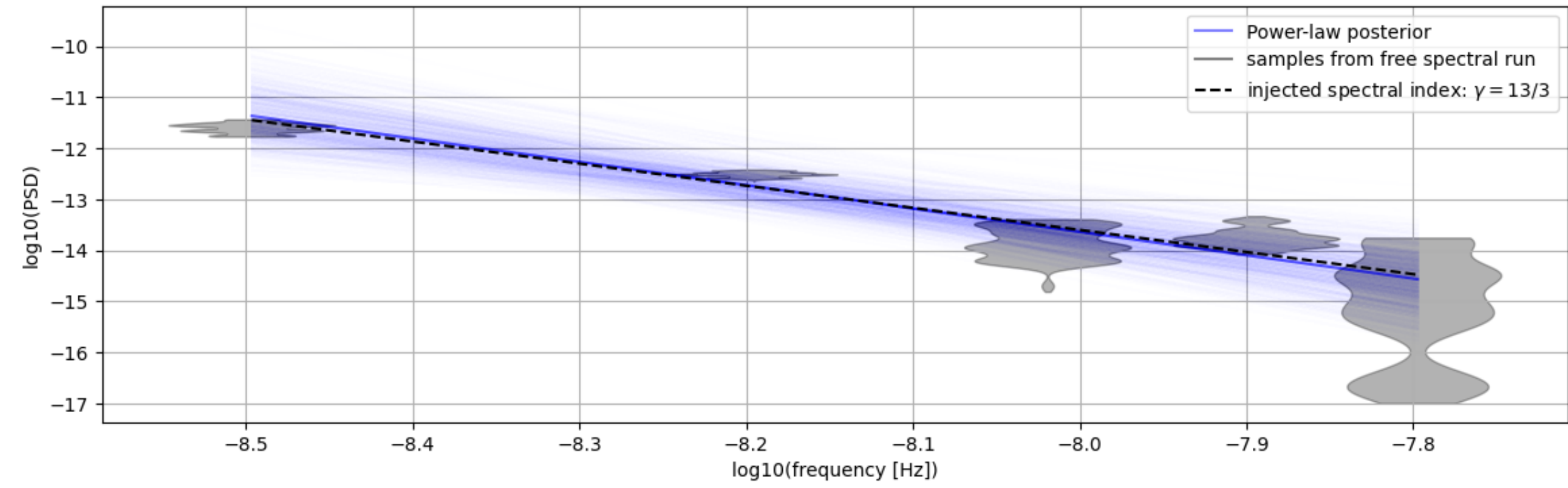
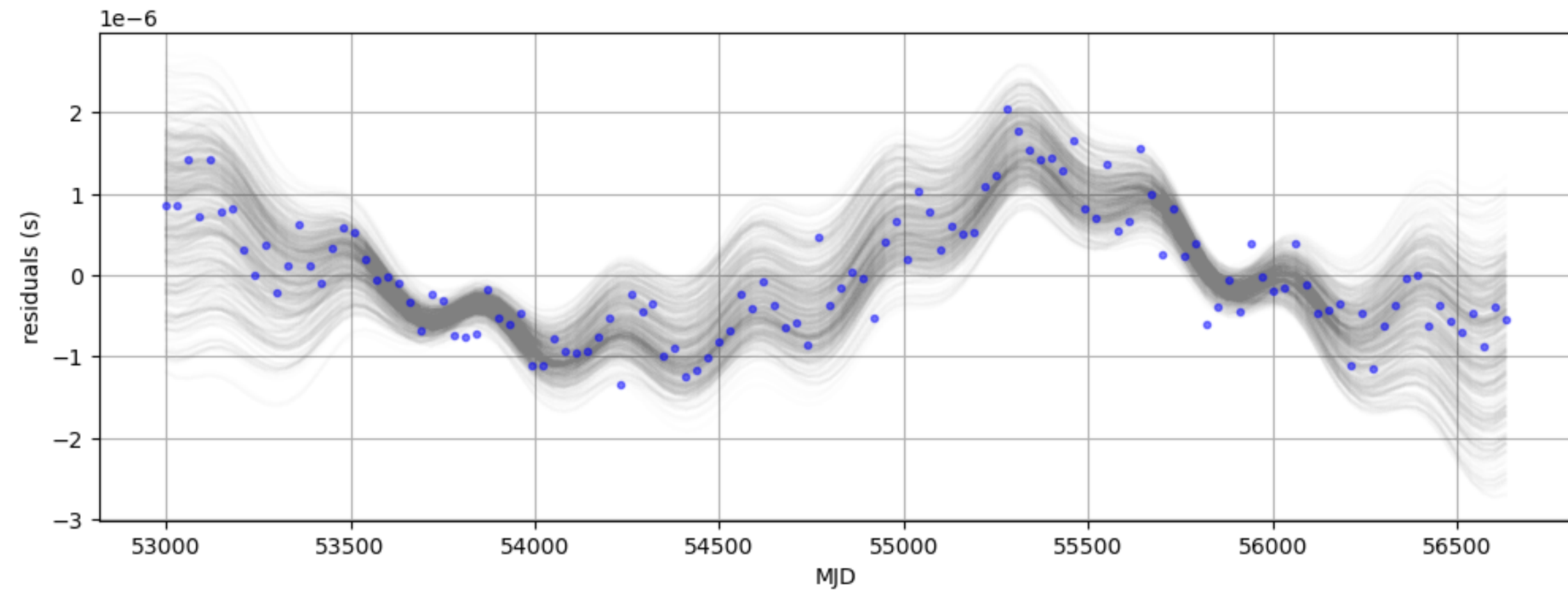
# If preferred, can instead subtract the stochastic background signal

*(This is for Germano and Chiara, who at the cosmology working group meeting in Hamburg, October 2016 kept on talking about subtracting the stochastic background)*



NANOGrav 15 yr Pulsar Timing example.  
Just 5 frequency components needed to  
subtract stochastic signal

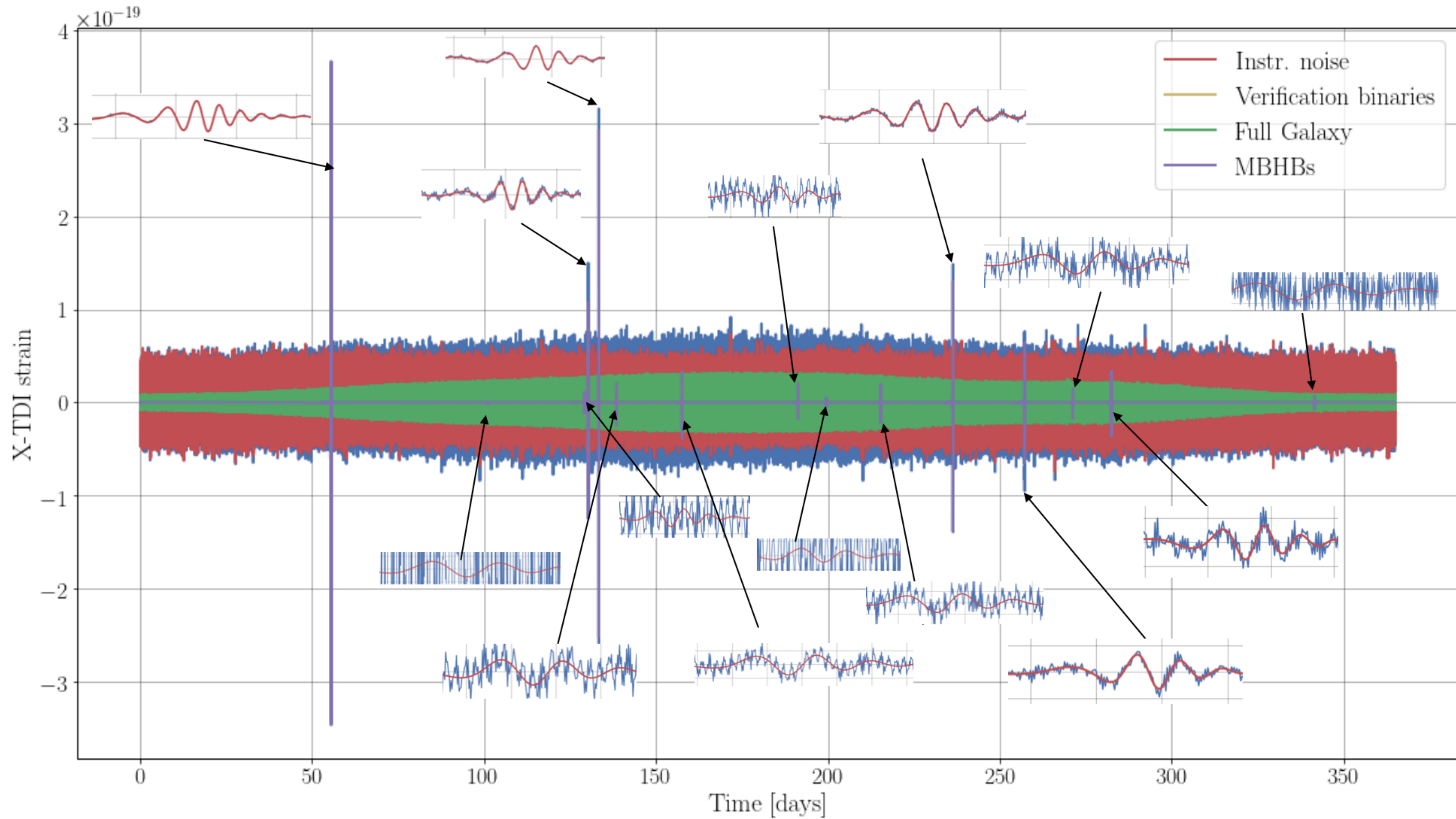
# Draws from the MCMC



Analysis by Aiden Gundersen



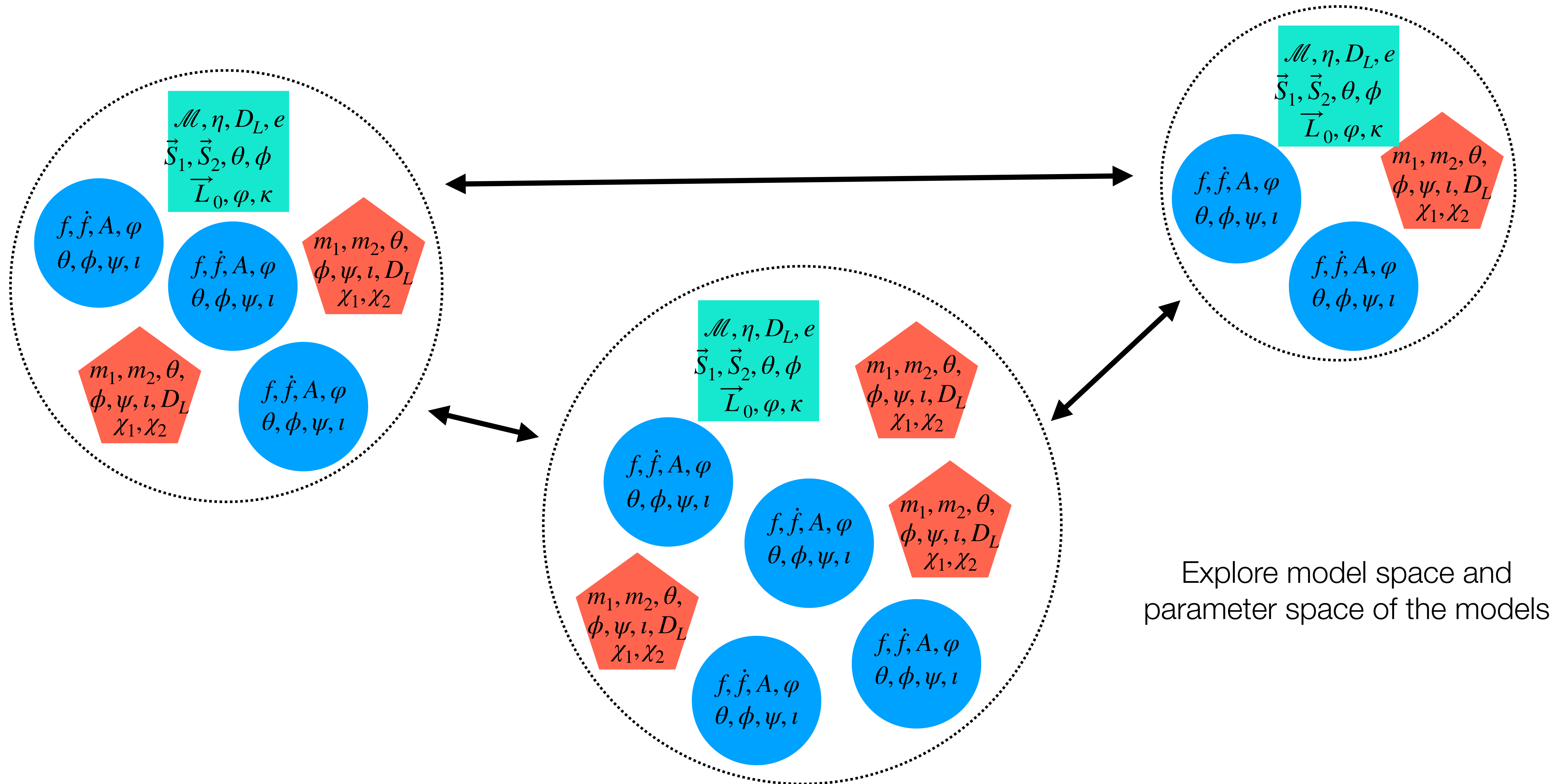
# LISA Data Challenge: Sangria Edition



# LISA Global Fit (One approach)

- Trans-dimensional modeling using Reversible Jump MCMC
- Build highly informative jump proposal from initial search stage
- Searches typically use stochastic hill climbing, approximate likelihoods, phenomenological models, likelihood maximization etc (anything goes)
- Time annealing - build up solution as new data arrives. Posteriors become proposals for next stage

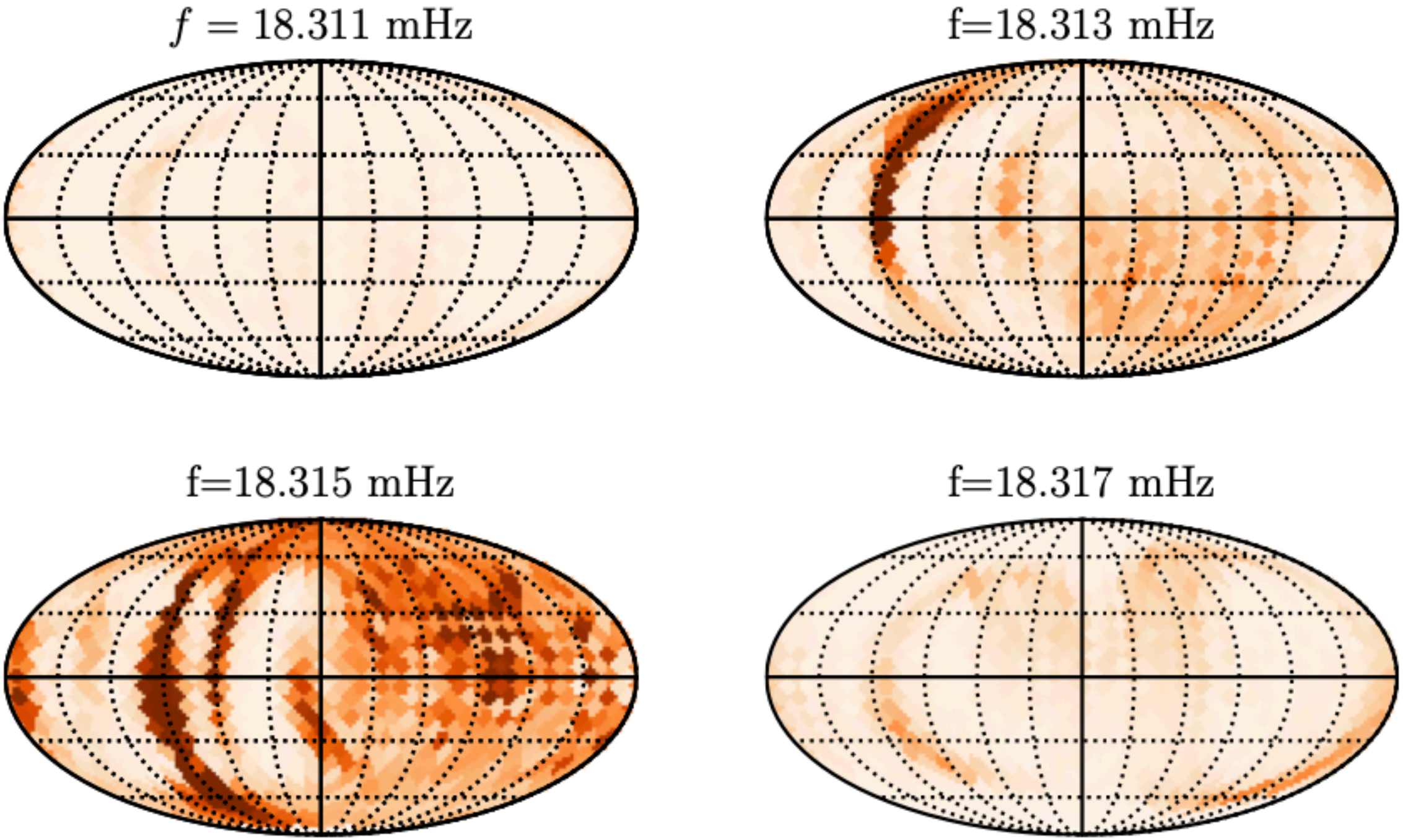
# Trans-dimensional Inference



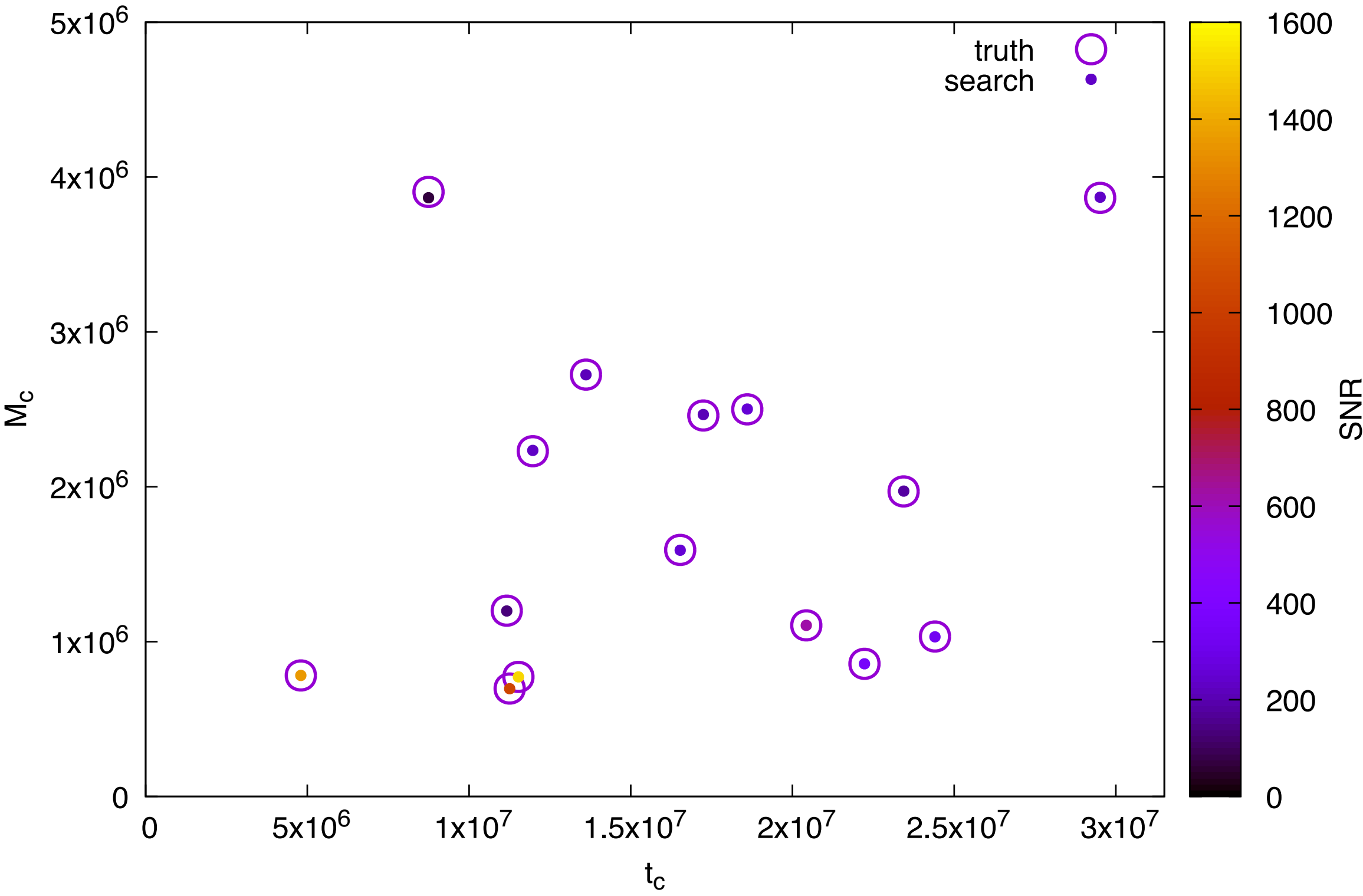


# Low latency single-source search results used as proposals in global fit

## F-statistic maps for GBs



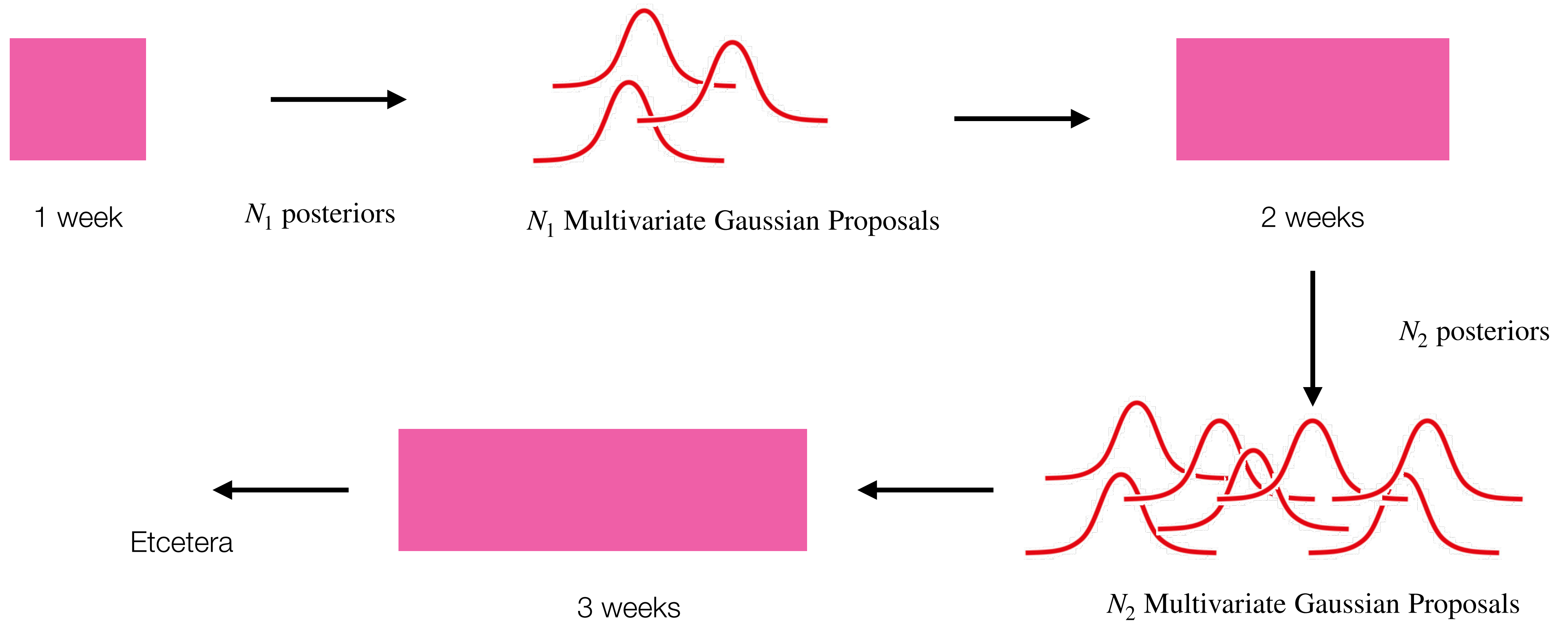
## Low latency BH search



[Littenber, Cornish, Lackeos & Robson, arXiv:2004.08464]

[Cornish, arXiv: 2110.06238]

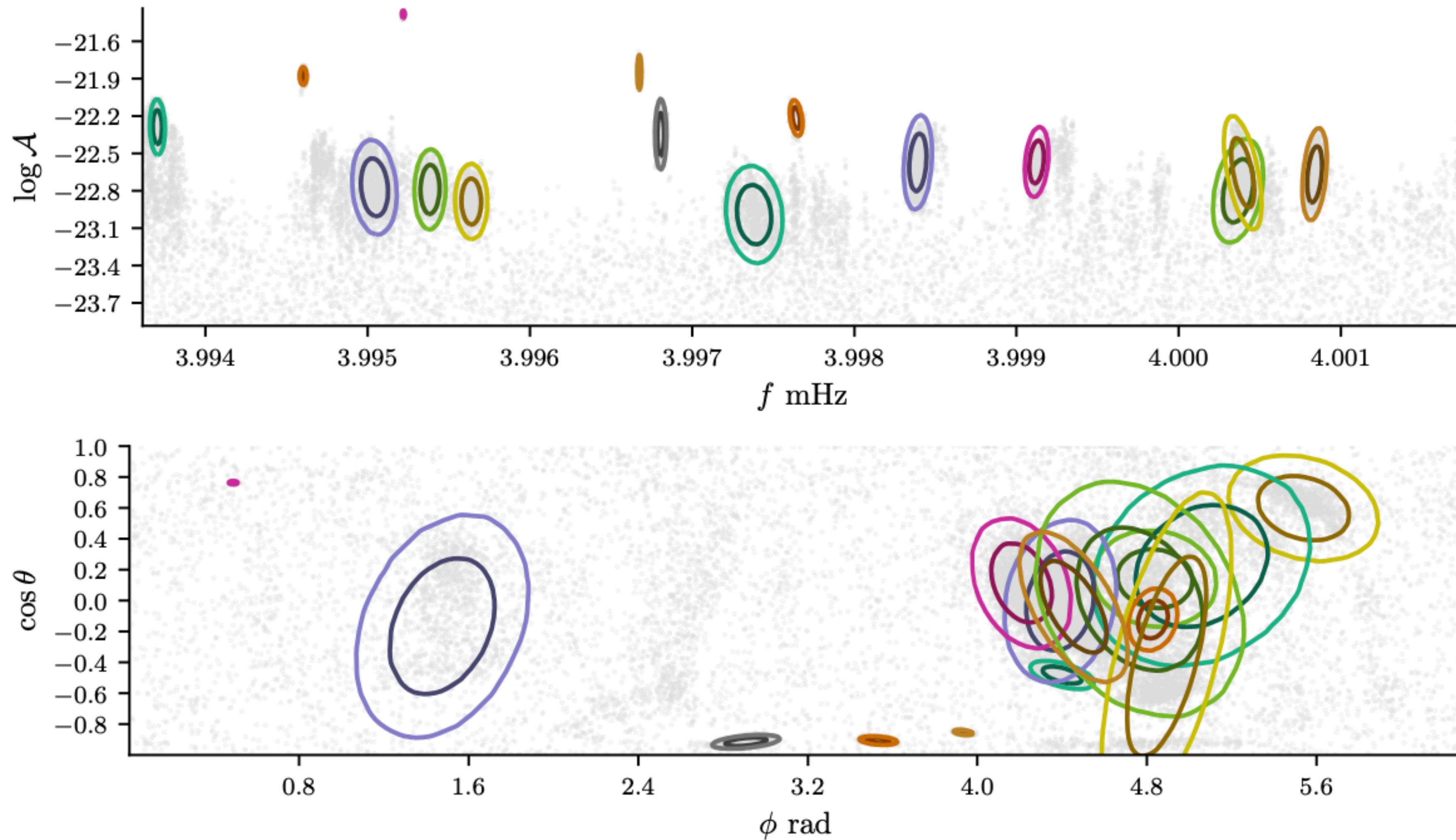
# Building up the solution - "time annealing"



We used 1 month -> 3 months -> 6 months -> 12 months



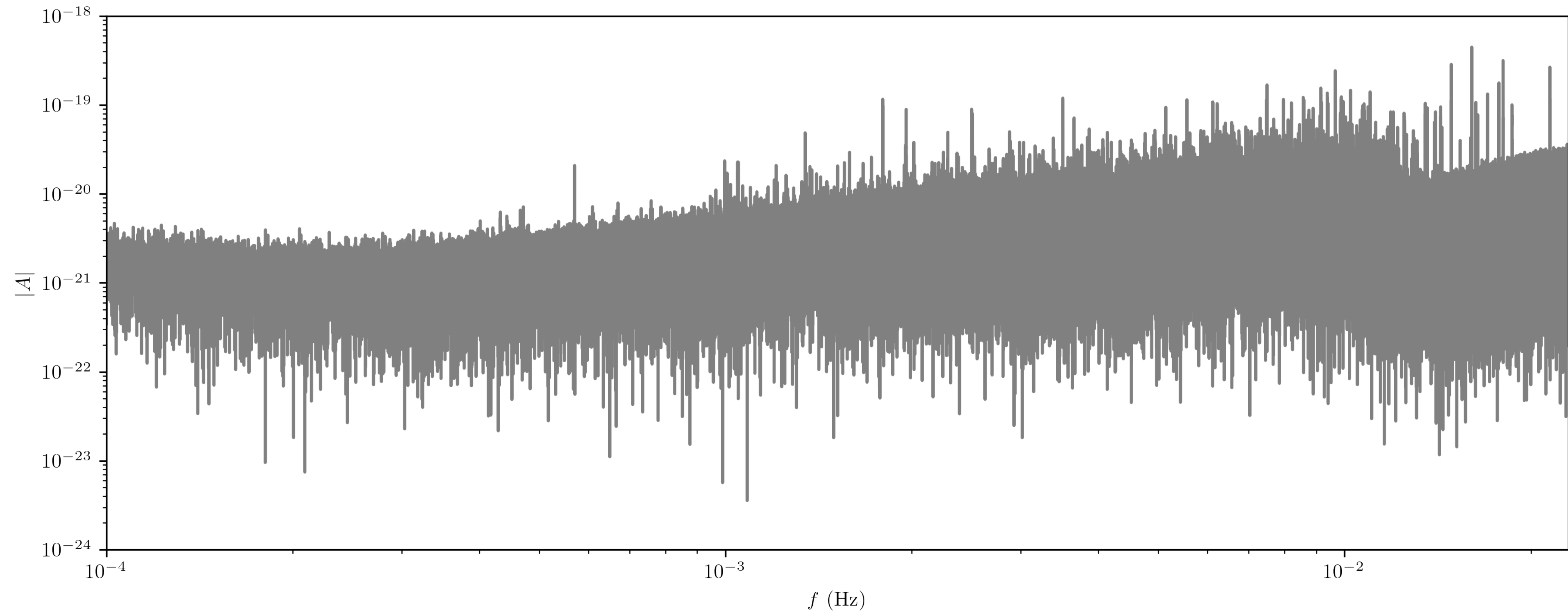
# Building up the solution - “time annealing”



We used 1 month -> 3 months -> 6 months -> 12 months

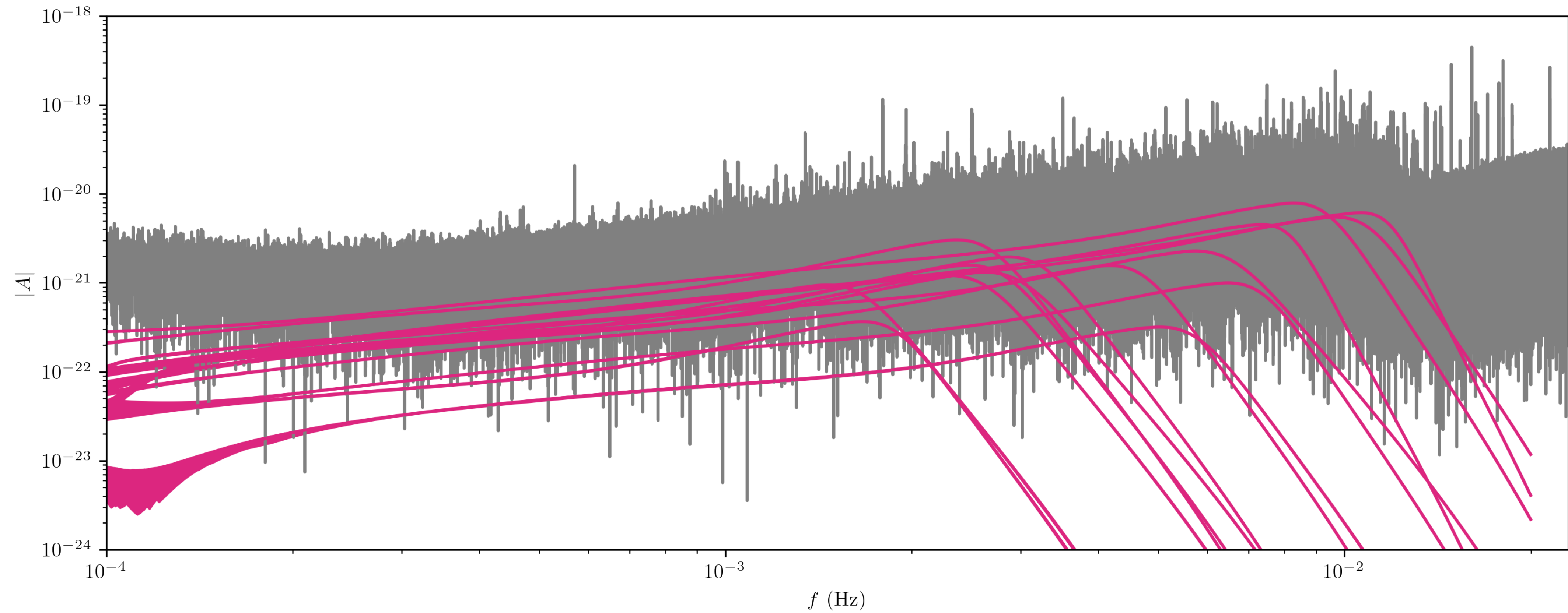


# 12 months of Sangria data - A TDI channel

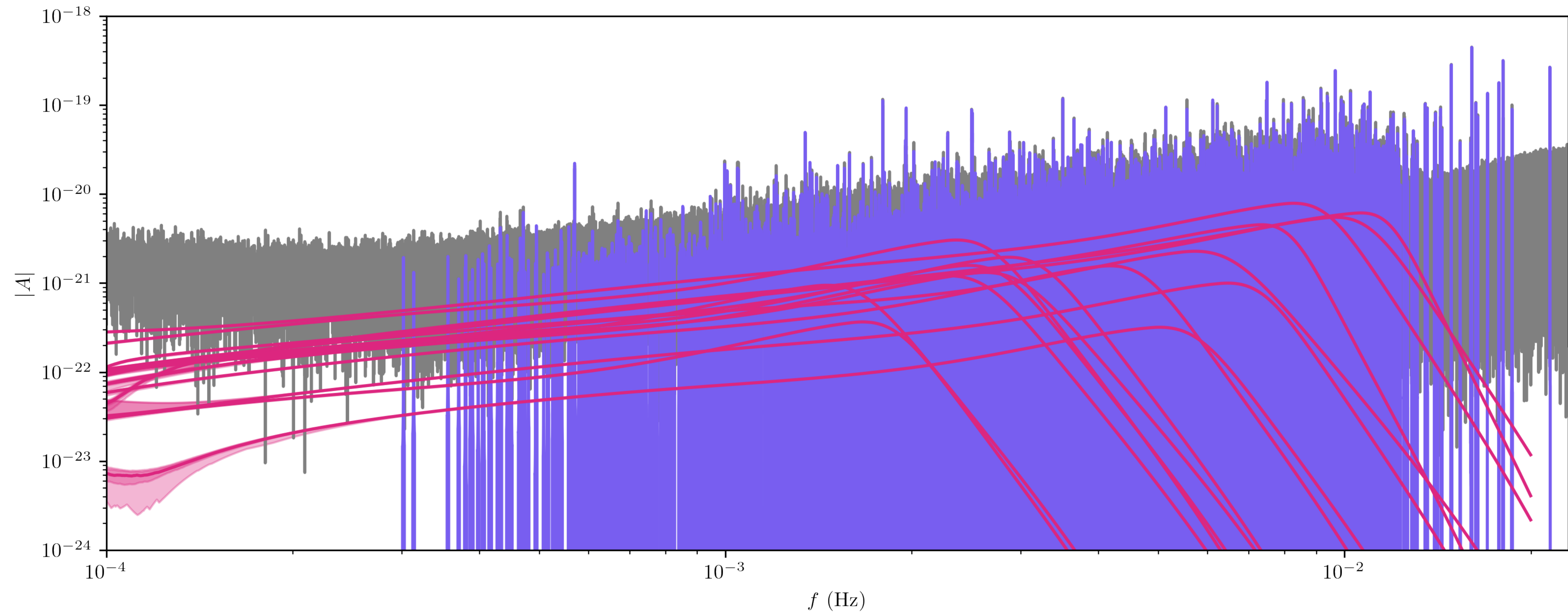


[Litttenberg & Cornish, [arXiv: 2301.03673](https://arxiv.org/abs/2301.03673)]

# 12 months of Sangria data - A TDI channel

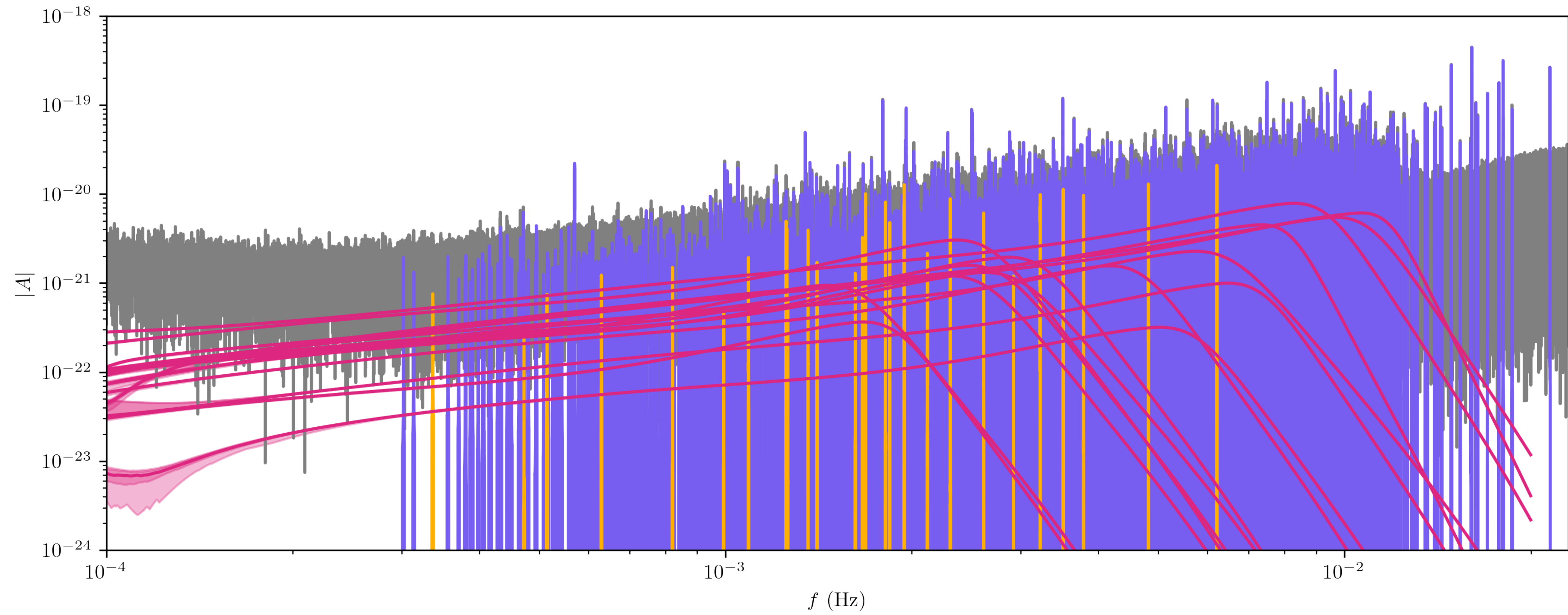


# 12 months of Sangria data - A TDI channel

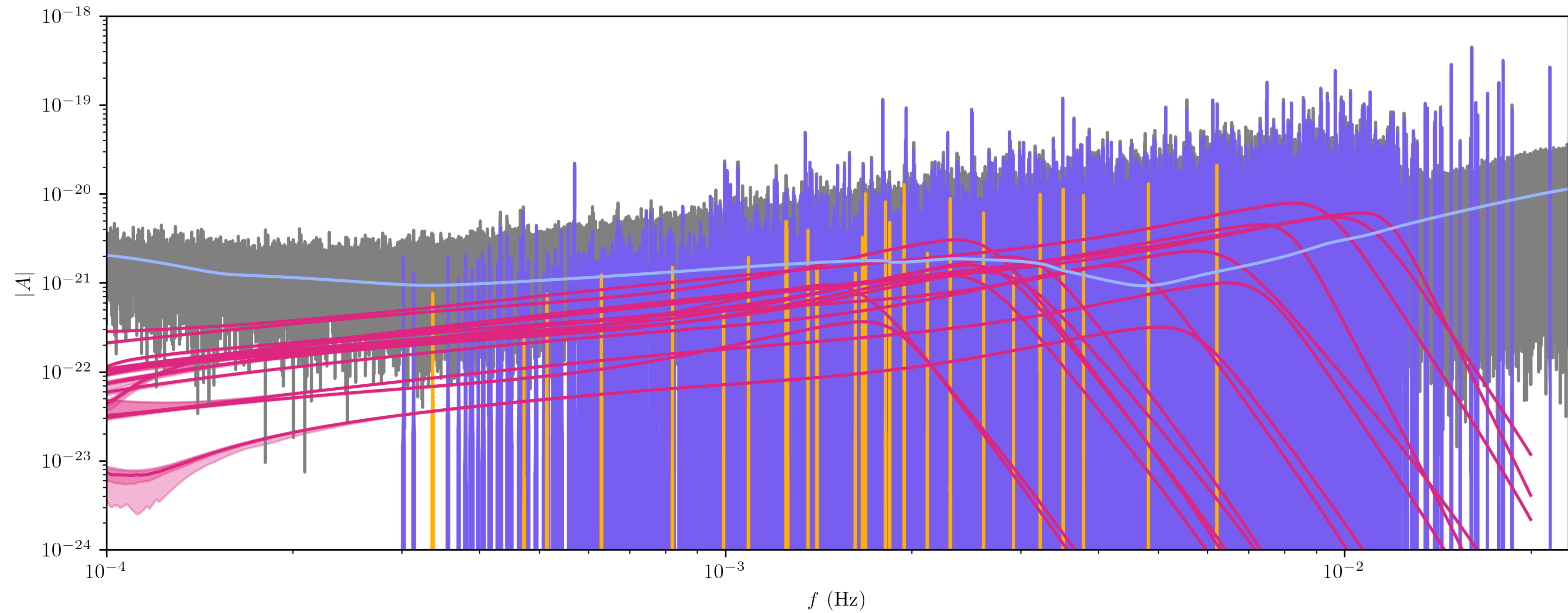




# 12 months of Sangria data - A TDI channel



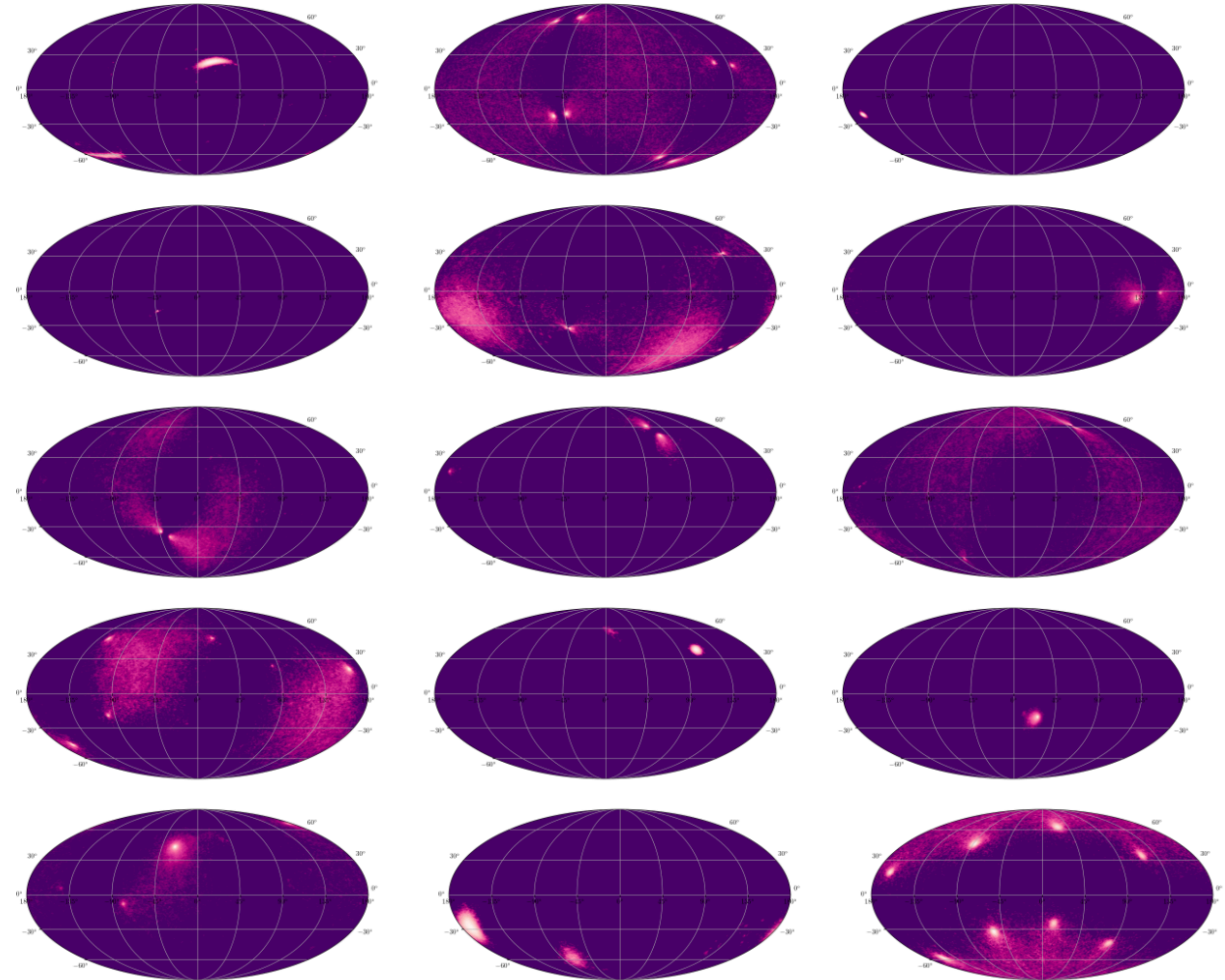
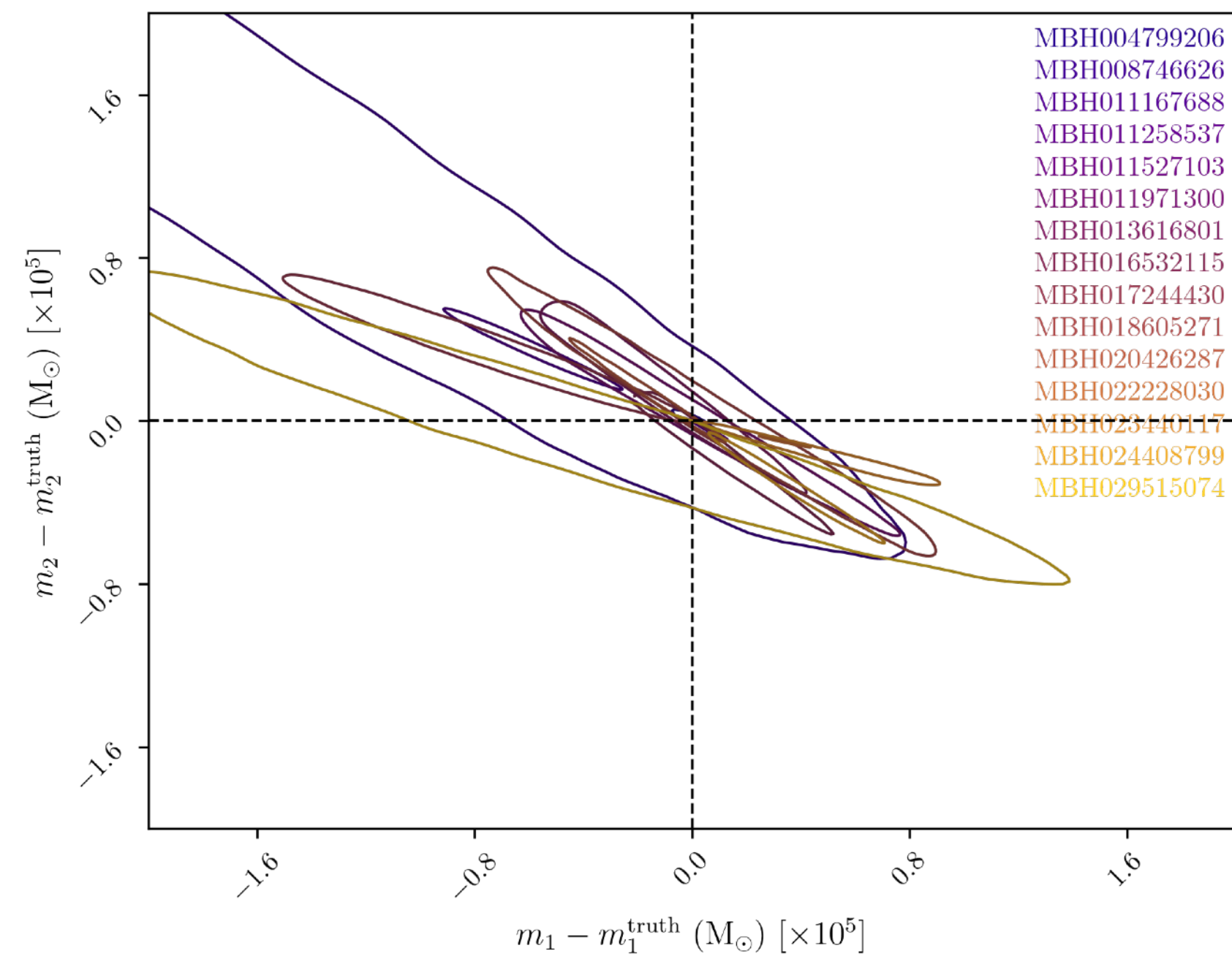
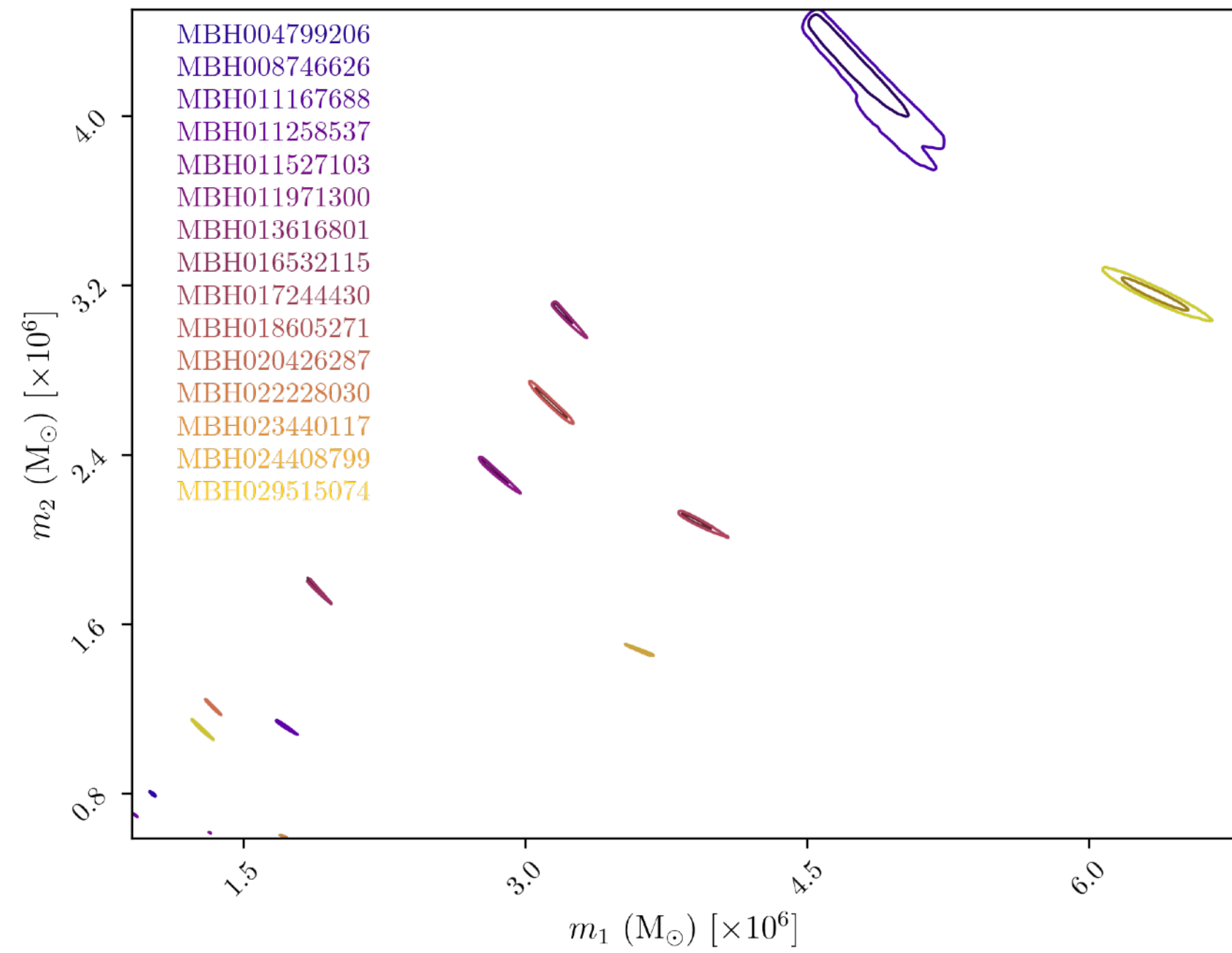
# 12 months of Sangria data - A TDI channel



Run time ~ 2 days on AWS, \$12K

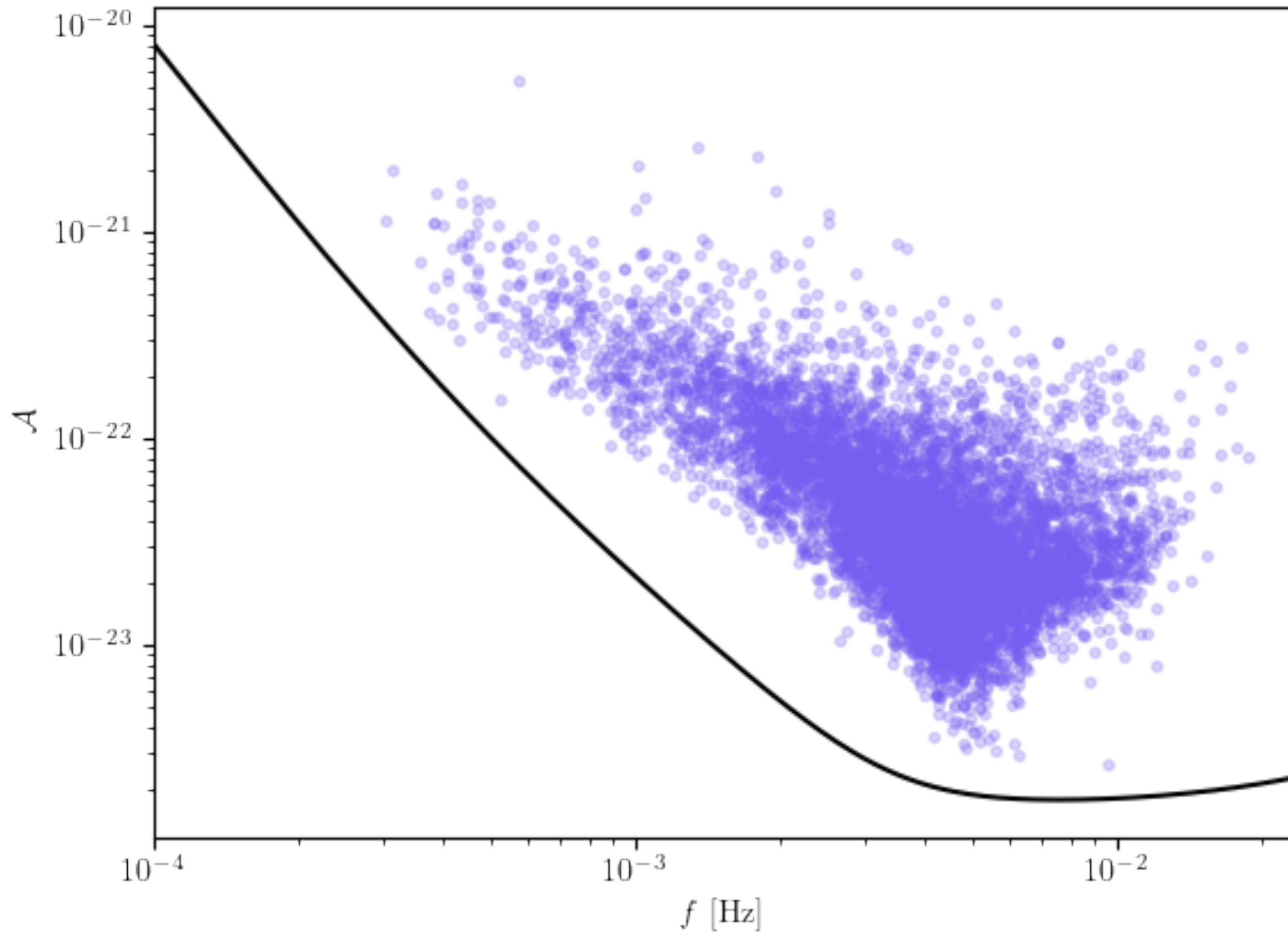


# 12 months of Sangria data - MBHBs

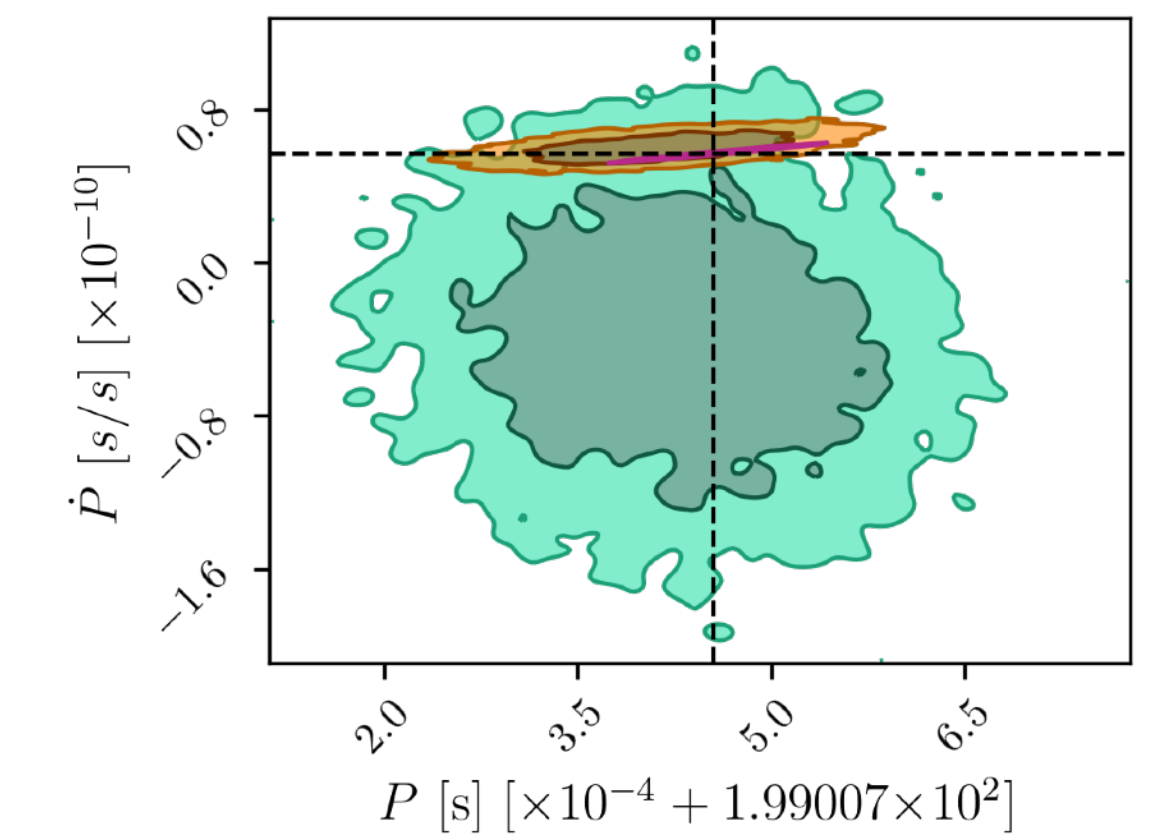
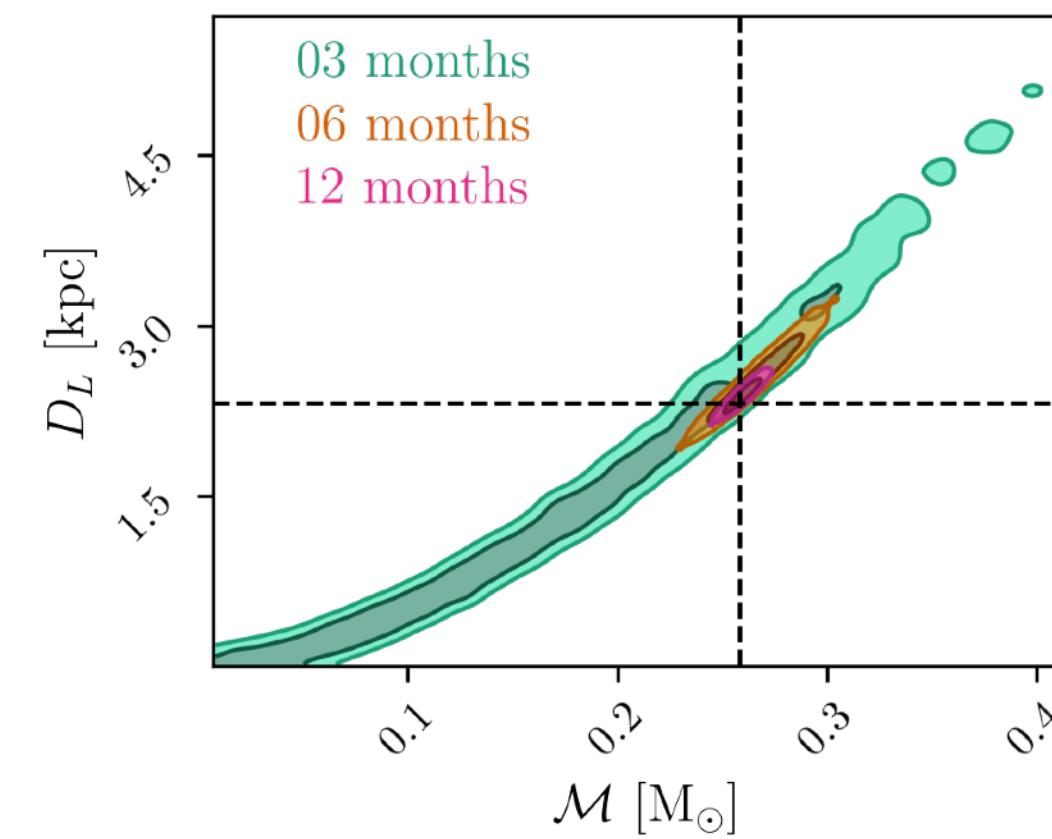
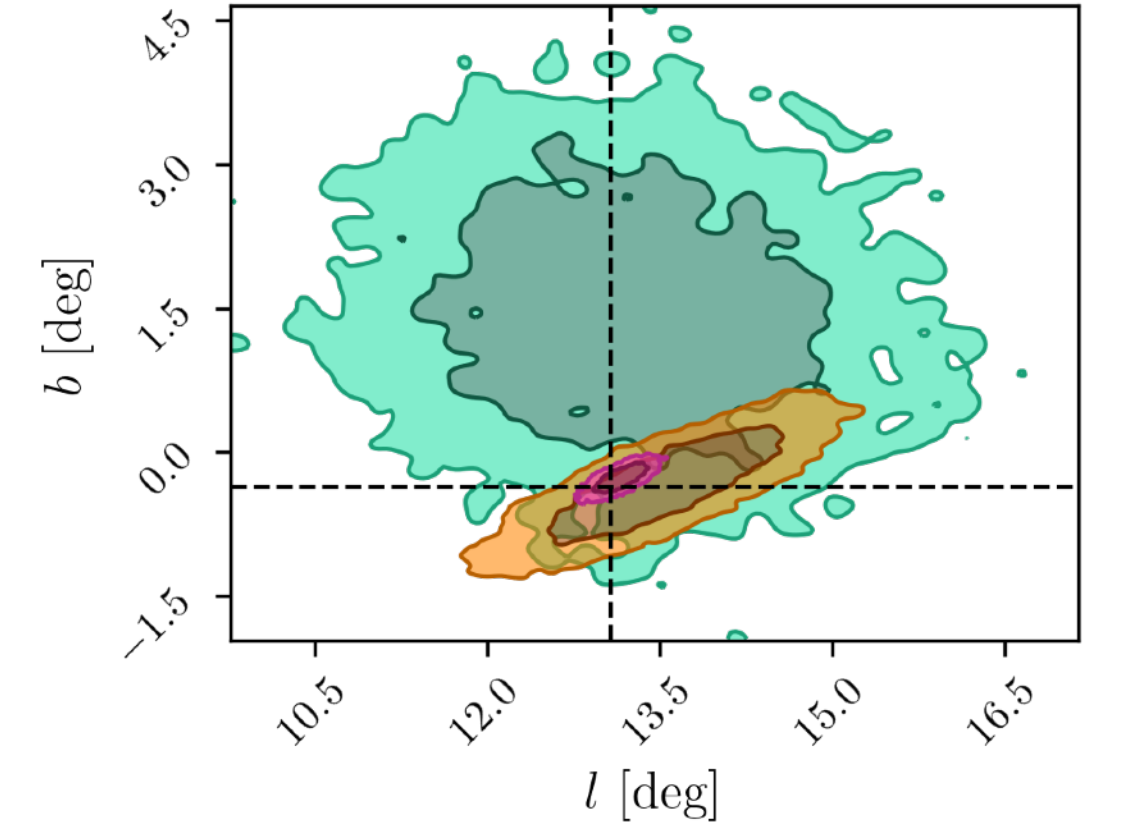
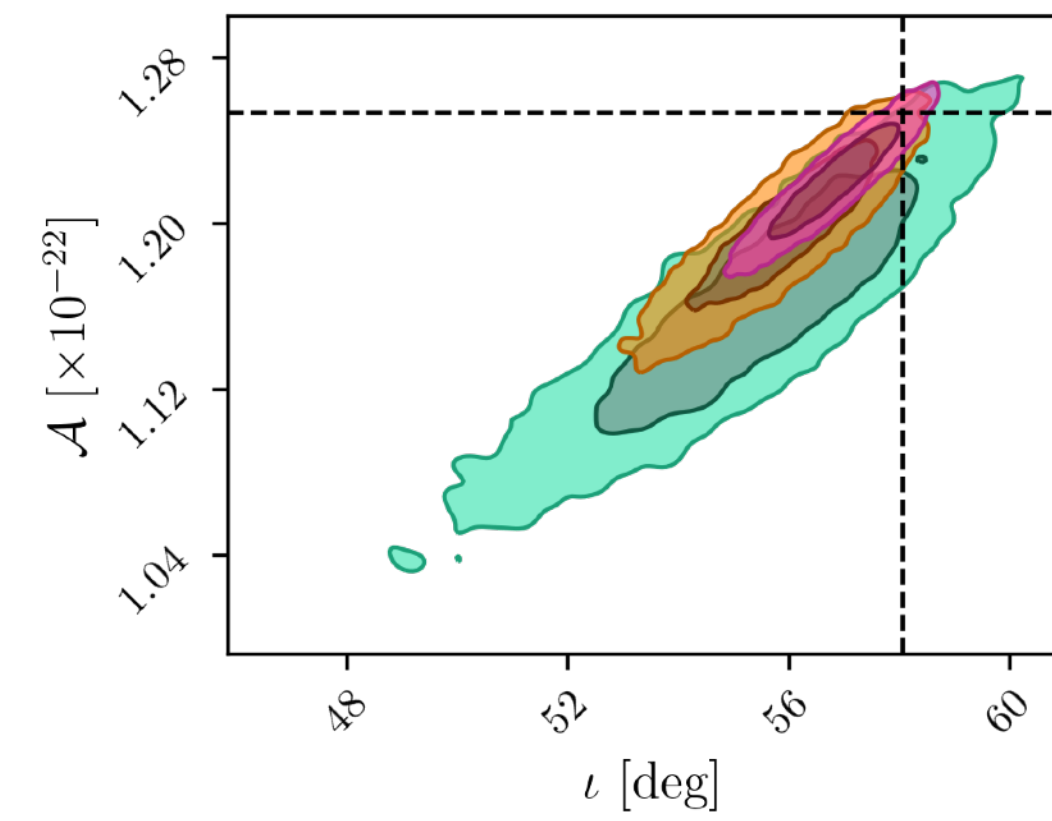




# Sangria data - Galactic Binaries

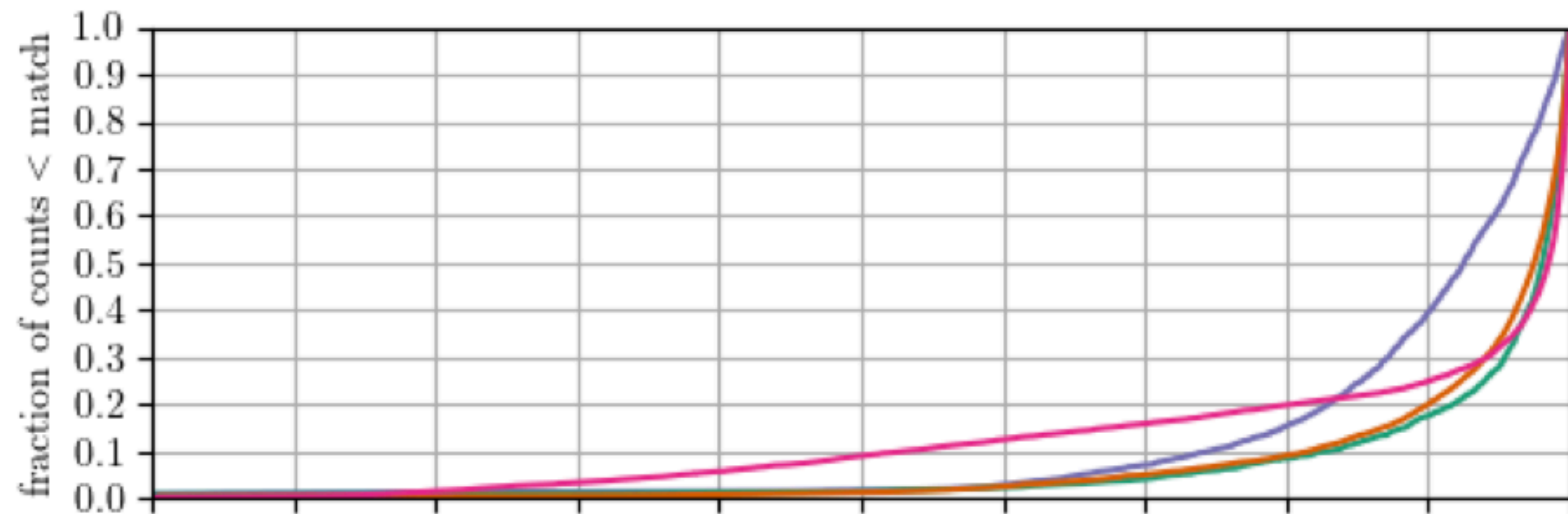


All candidate sources at 12 months

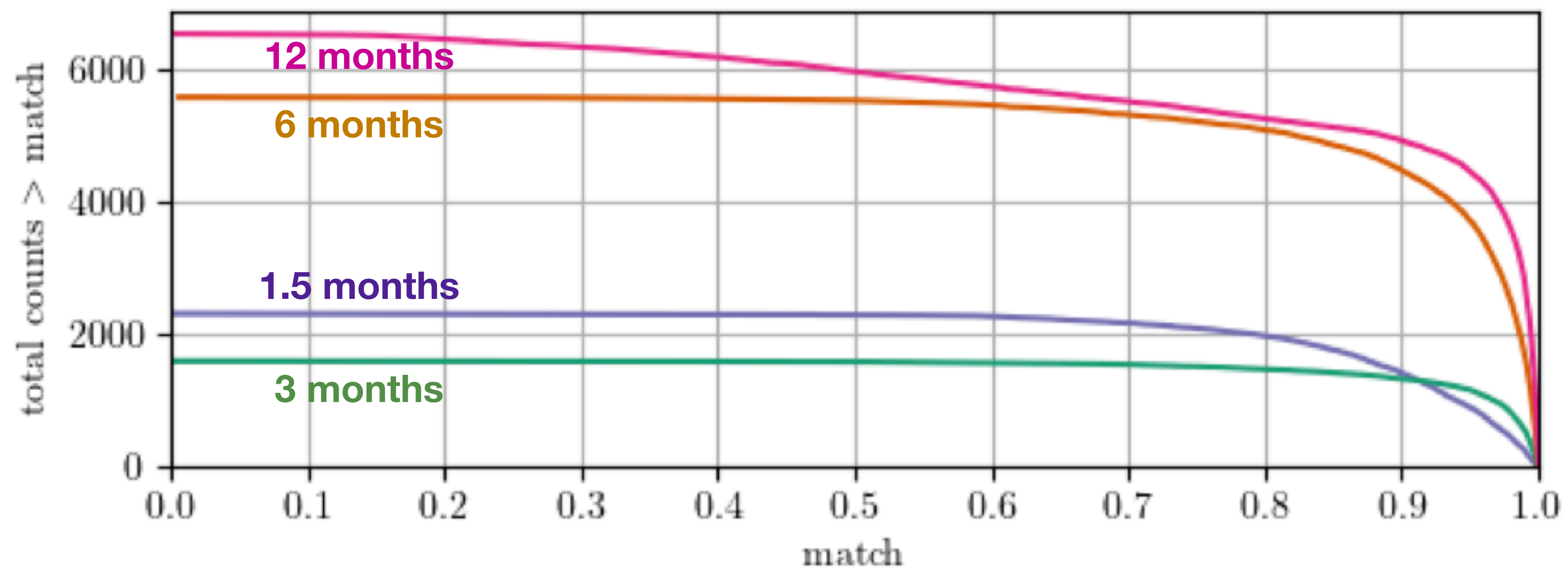


Example of how a source resolves with time

# GB matches over time for 90+% confident detections

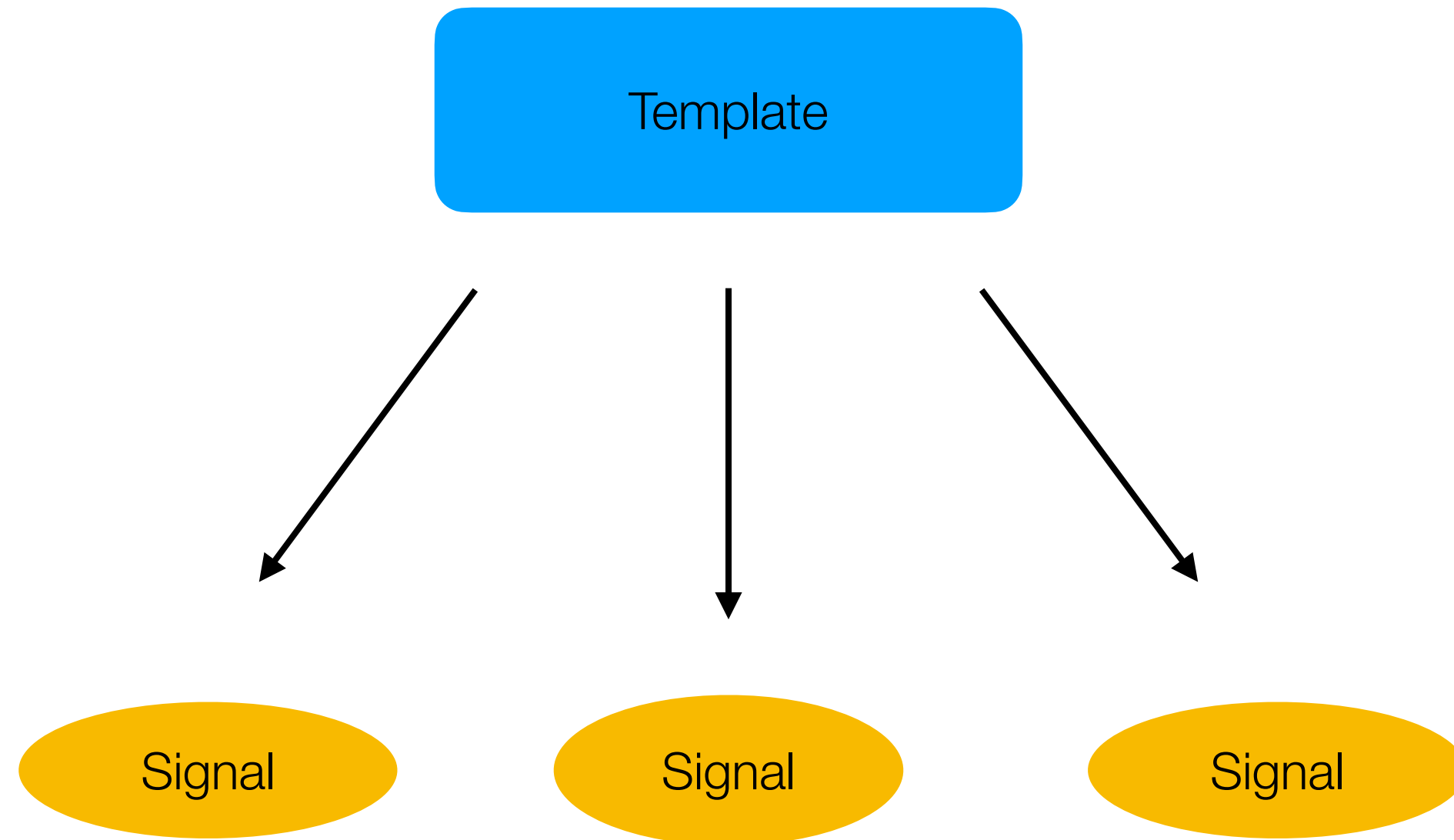


Theory:  $M \approx 1 - \frac{D}{2 \text{SNR}^2}$



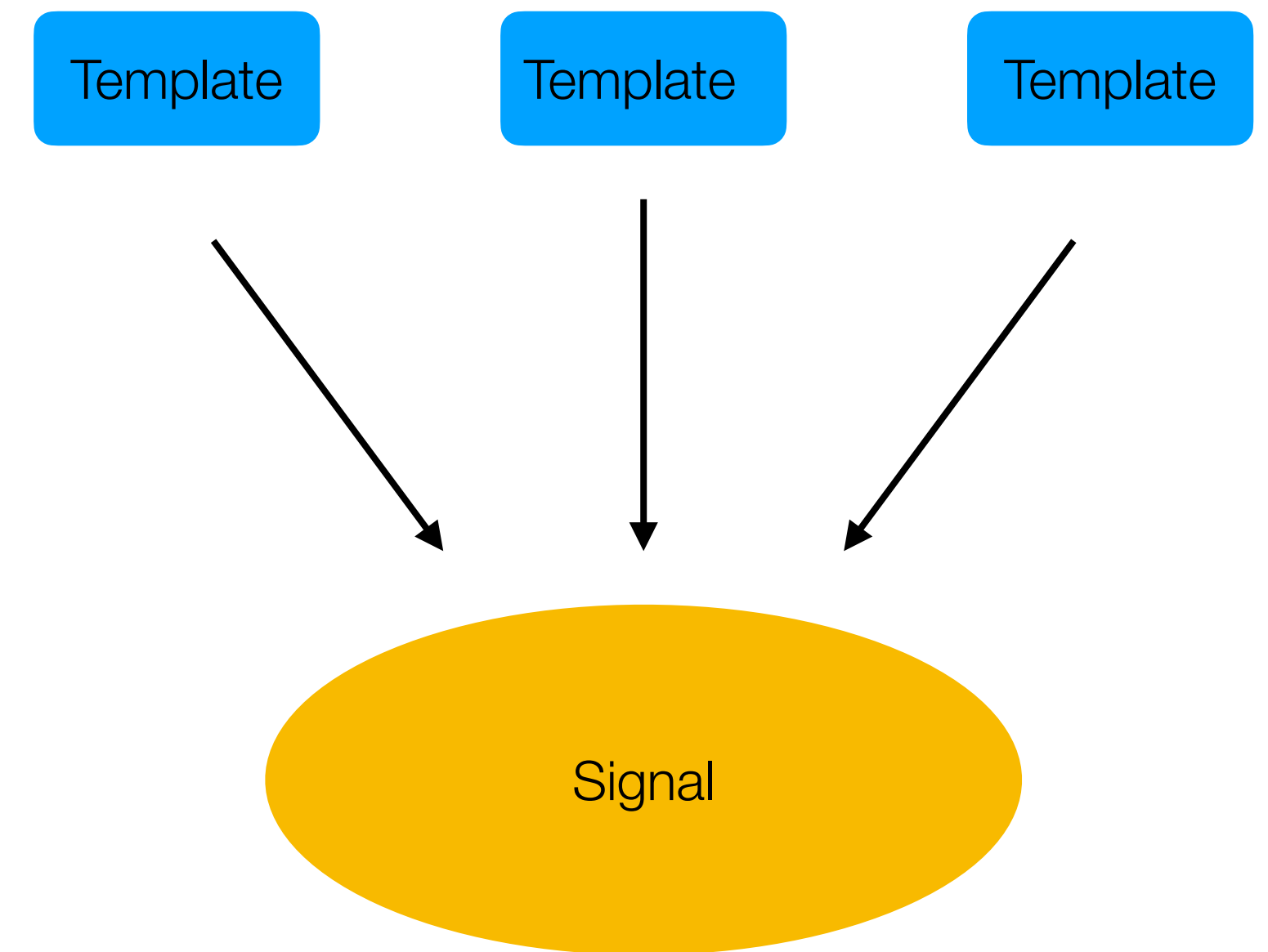
# Galactic Binaries - what went wrong at 12 months?

One to Many



Can be the right answer in a Bayesian sense

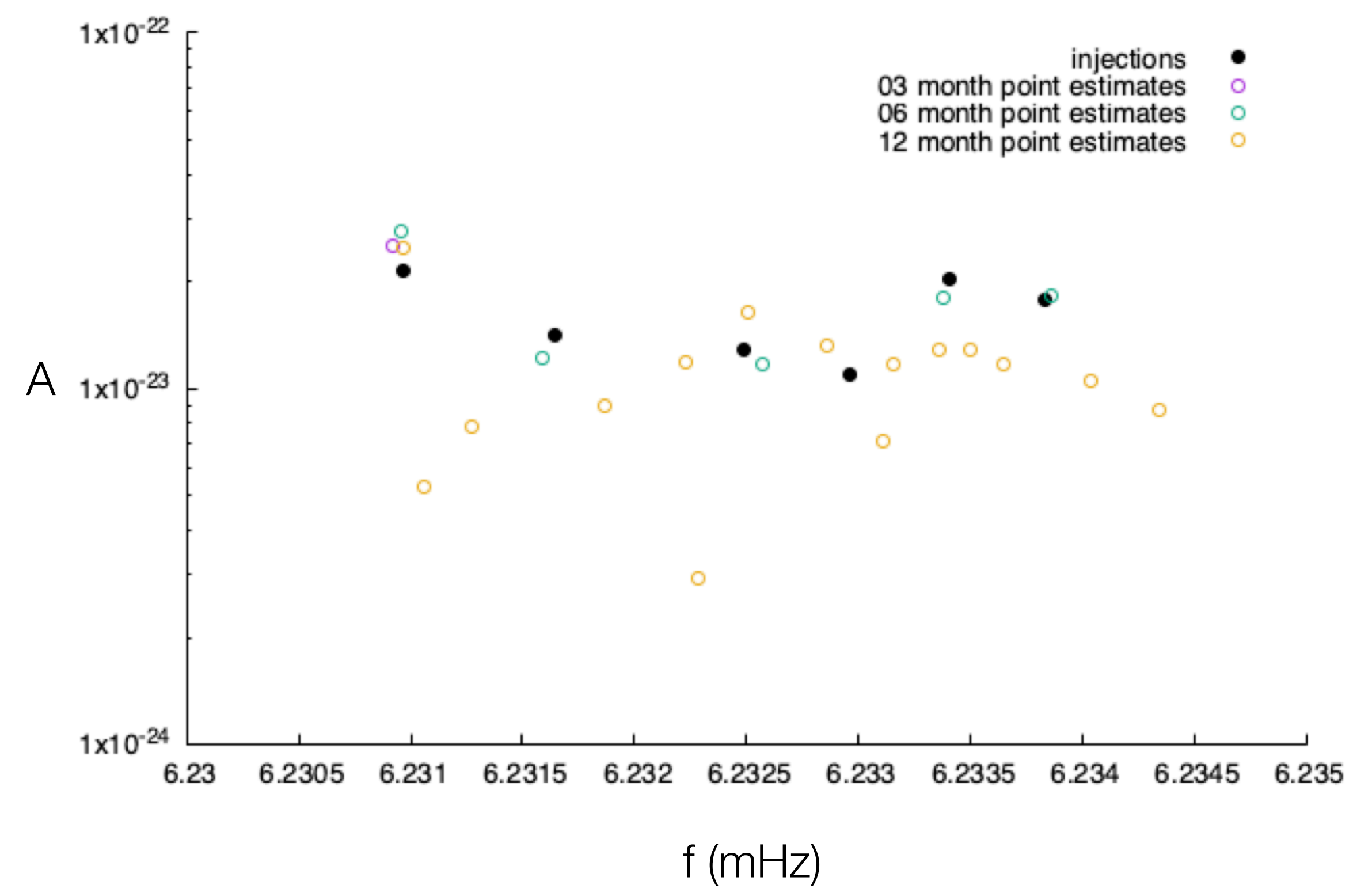
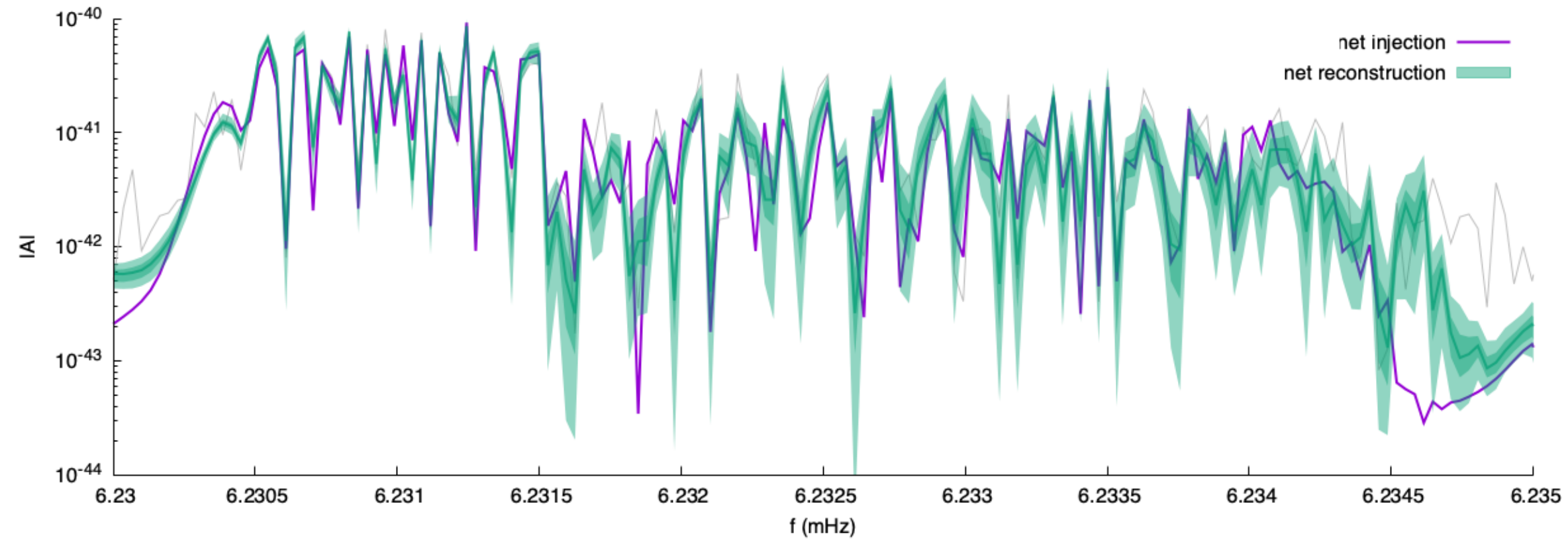
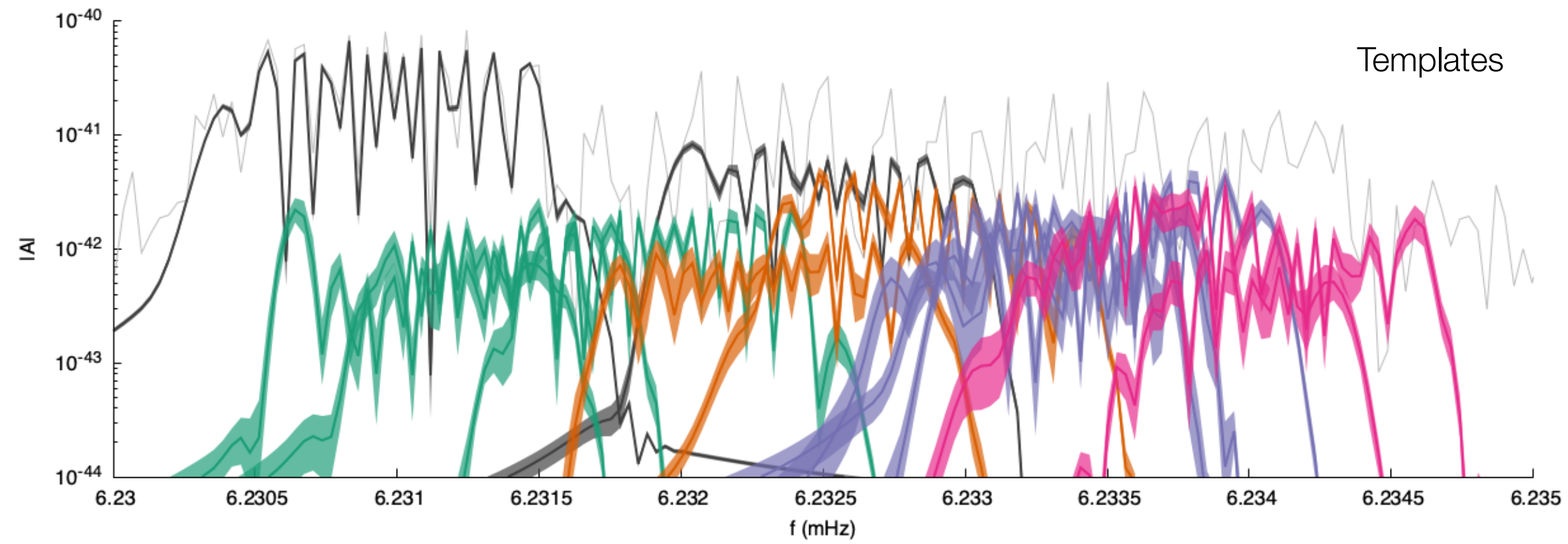
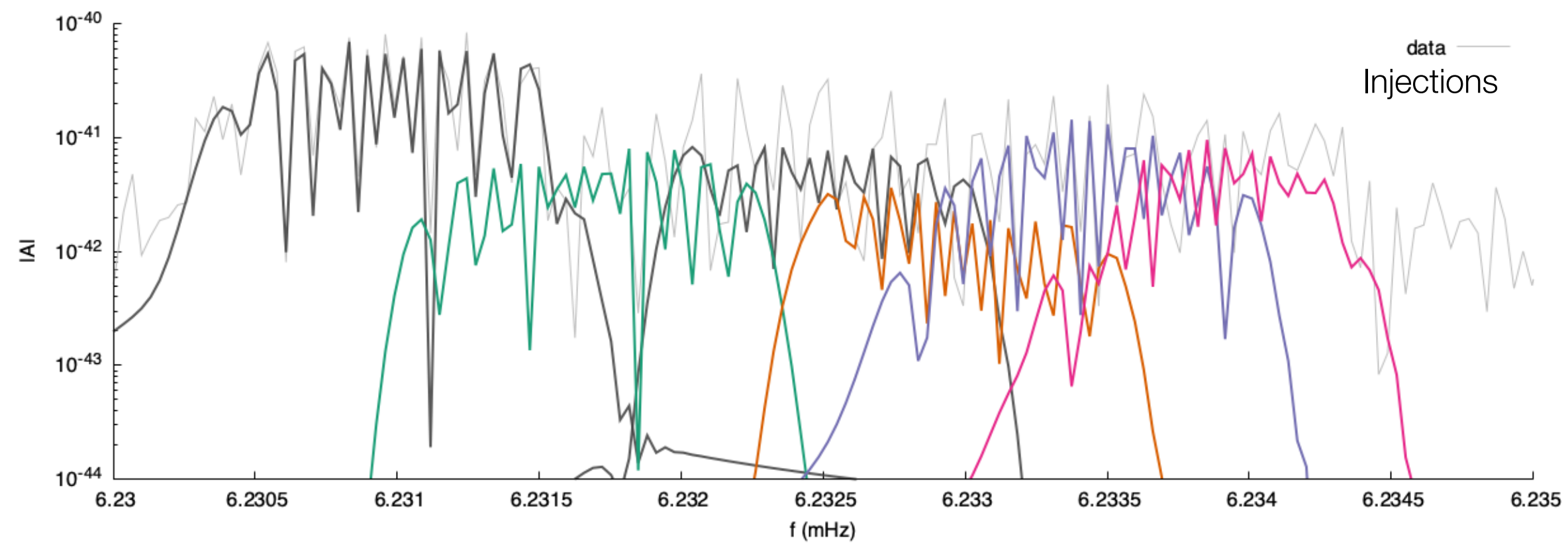
Many to One



Never the right answer - poor sampling



# Galactic Binaries - what went wrong at 12 months?



# How to do better?

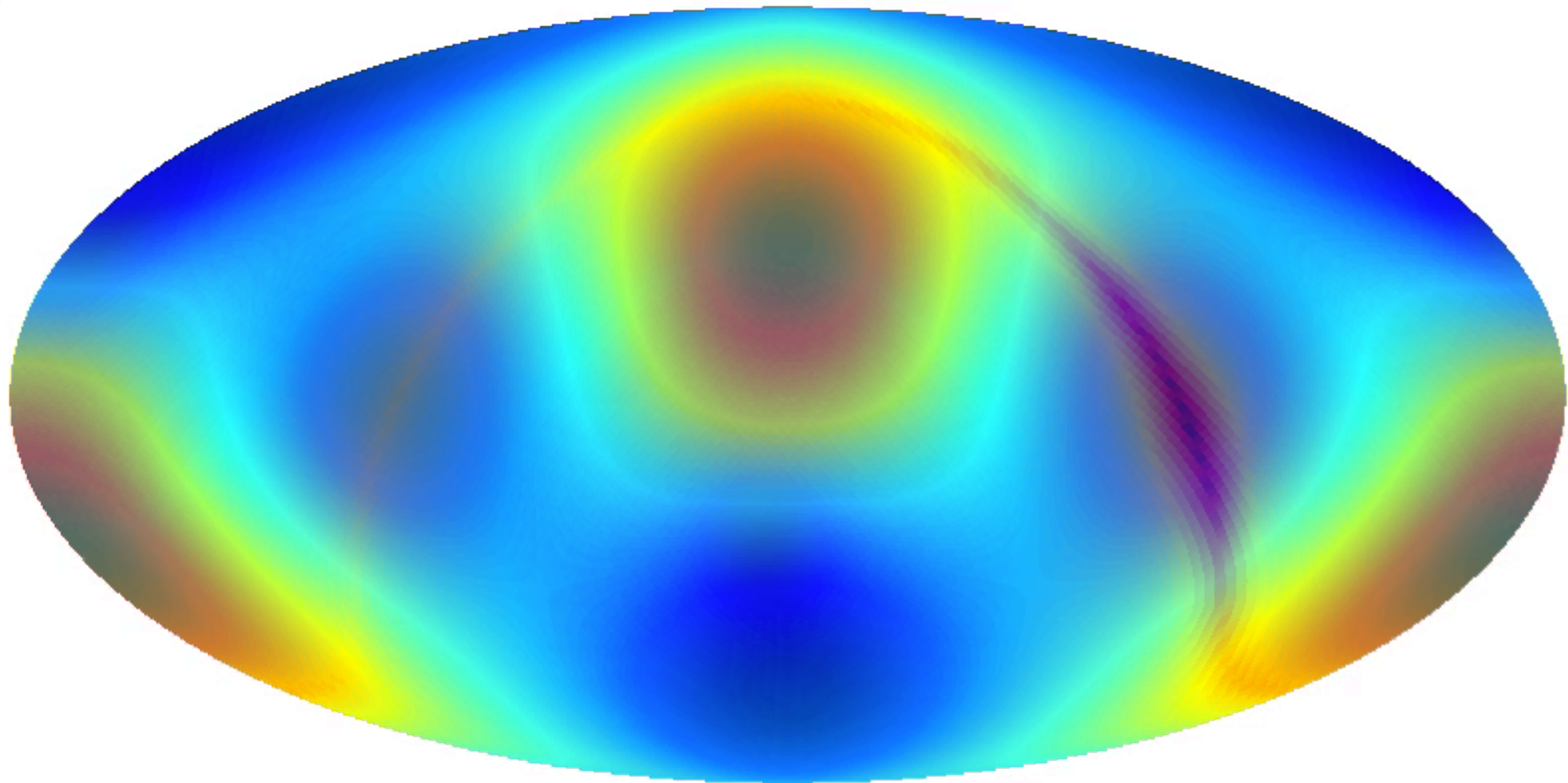
- Better proposals - easiest fix is to increment by smaller amounts in time
- Time-frequency modeling of signals and noise
- Include all three data channels, A, E & T
- Treat the unresolved binaries as a stochastic background (signal), and model the noise component by component
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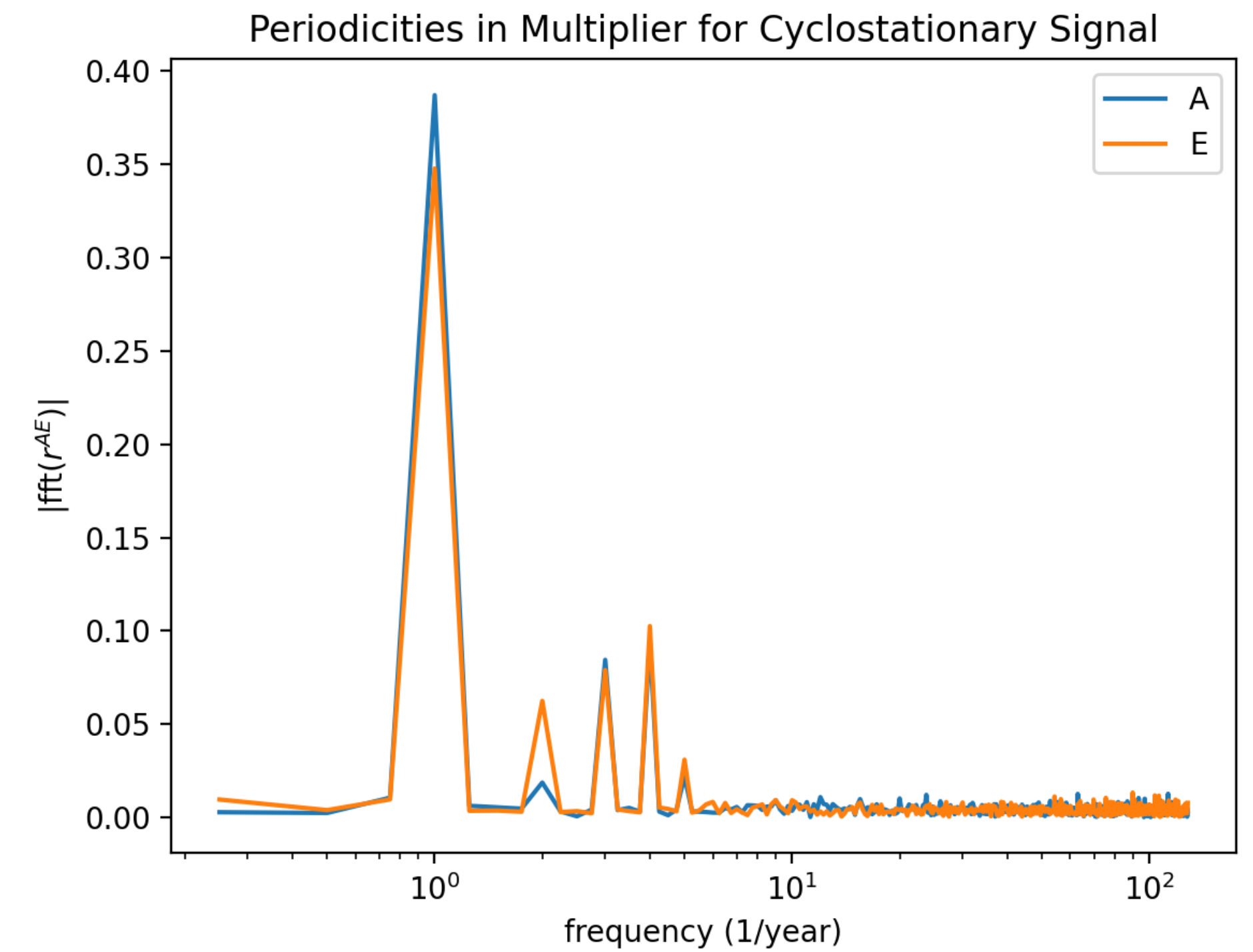
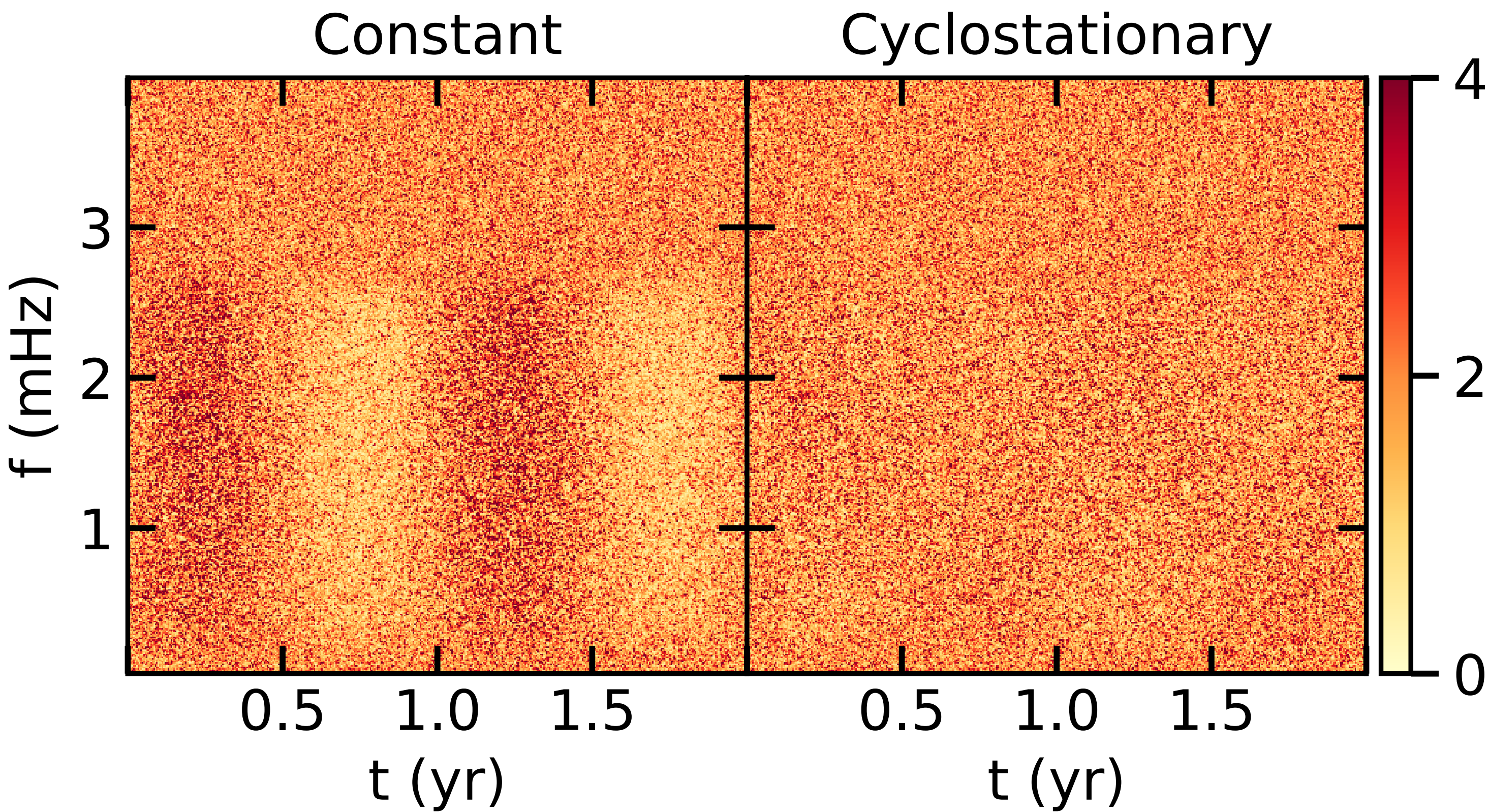


# Non-Stationary Data





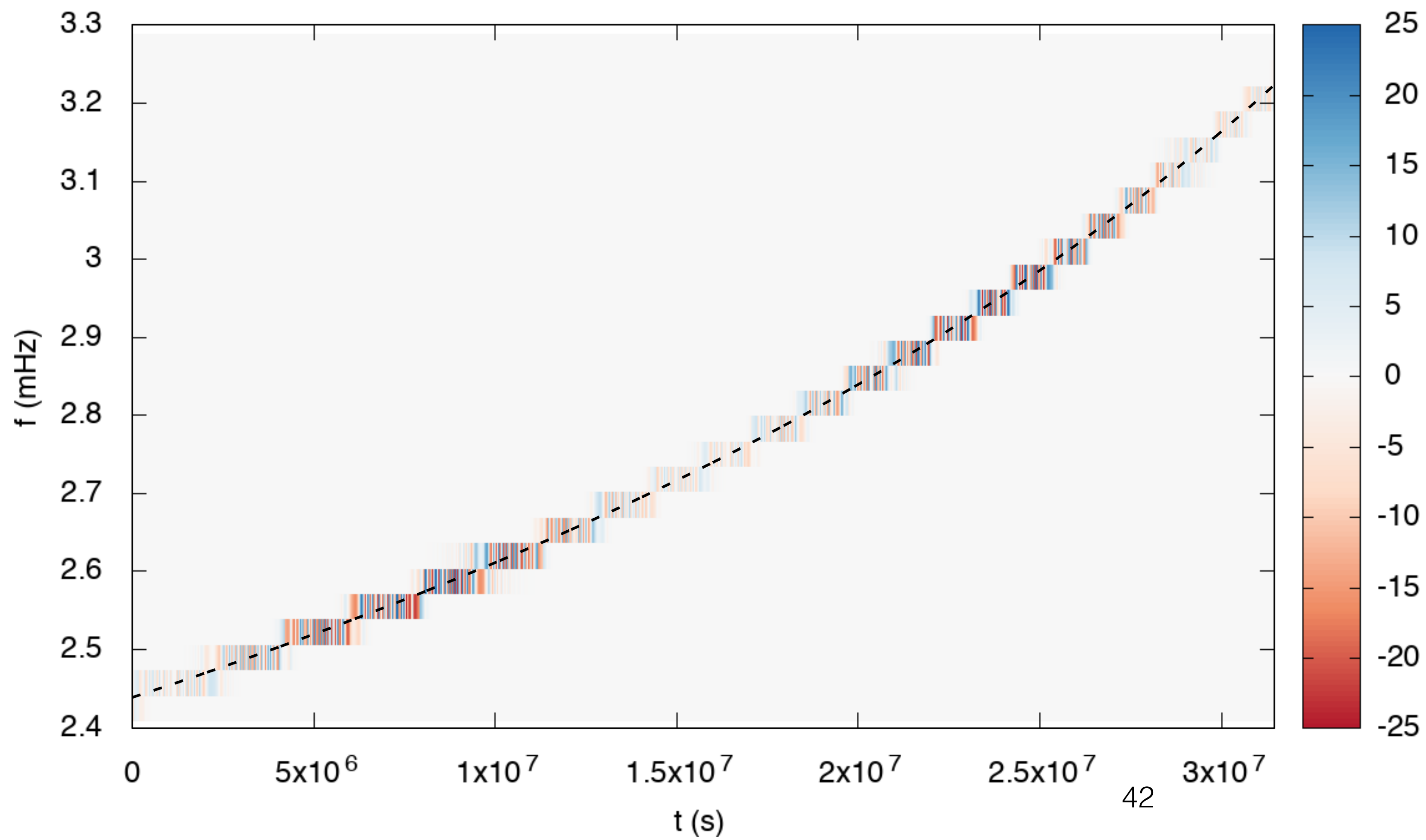
# Cyclostationary Noise



Whitening using constant PSD and dynamic PSD

# Wavelet domain waveforms

$$p(\mathbf{d}|\mathbf{h}) = \frac{1}{\sqrt{\det(2\pi\mathbf{C})}} e^{-\frac{1}{2}(\mathbf{d}-\mathbf{h})^\dagger \mathbf{C}^{-1}(\mathbf{d}-\mathbf{h})}$$



Fast wavelet transforms of the signals for computational efficiency

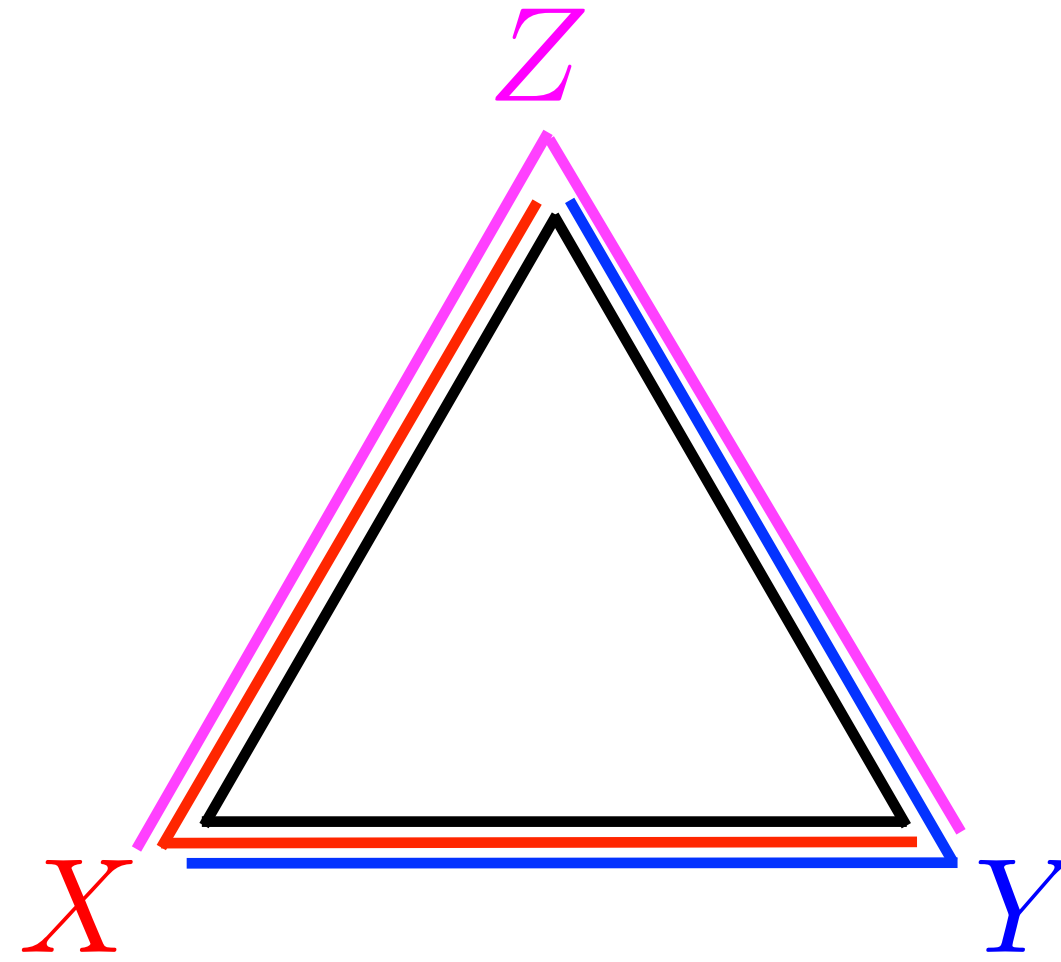
Faster than frequency domain,  $\sqrt{N}$  scaling



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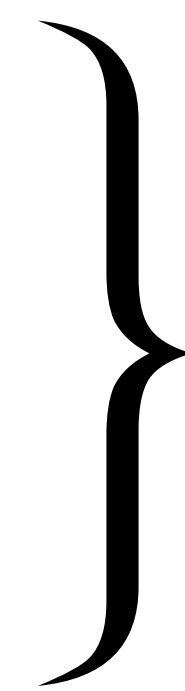
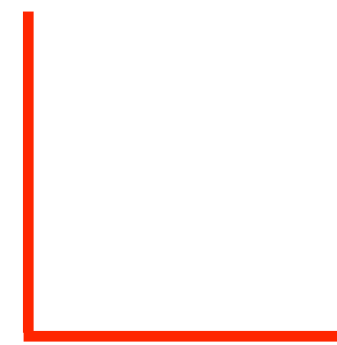
# Multiple Data LISA Channels



**A**

$$S_+ = \frac{\sqrt{3}}{2} X$$

$\Rightarrow$



Sensitive to GWs

**E**

$$S_\times = \frac{1}{2} (X + 2Y)$$

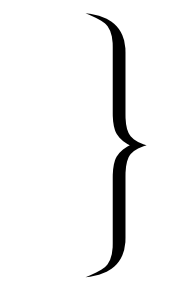
$\Rightarrow$



**T**

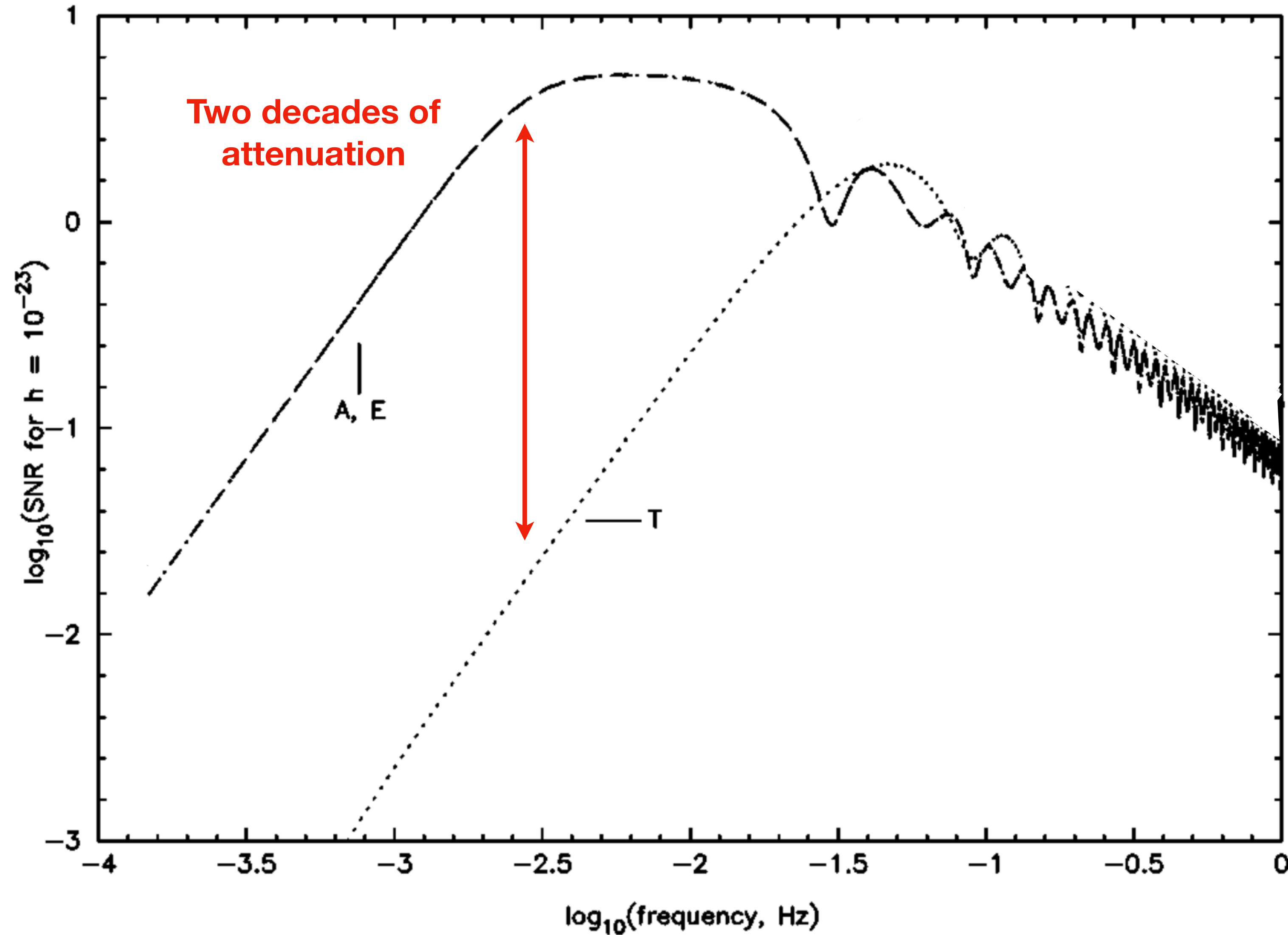
$$S_\odot = \frac{1}{3} (X + Y + Z)$$

$\Rightarrow$



Insensitive to GWs

# LISA Sensitivity - T channel as noise monitor



Key to detecting a stochastic background

[Prince et al, Phys. Rev. D66 (2002)]

[Tinto, Armstrong & Estabrook, Phys.Rev.D63 (2001)]

[Hogan & Bender, Phys. Rev. D64 (2001)]

[Adams & Cornish, Phys. Rev. D86 (2010)]



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# Galaxy shape prior with hyper-parameters

$$\rho(x, y, z) = \rho_0 \left( A_b e^{-r^2/R_b^2} + (1 - A_b) e^{-\sqrt{x^2 + y^2}/R_d} \operatorname{sech}^2(z/Z_d) \right)$$

