

# SGWB reconstruction for a non-equilateral and unequal-noise LISA constellation

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## Data analysis challenges for SGWB workshop

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# Outline

- 1 Introduction
  - Measuring SGWBs with LISA
  - Time Delay Interferometry (TDI) and TDI variables
  - Data generation and pre-processing
- 2 Towards realistic data
  - Responses, spectra and strain noise
  - Noise and signal correlations
  - Impact on parameter estimation
- 3 A new idea for SGWB data analysis
- 4 Conclusions and future perspectives

# SGWBs detection

The **data**  $\tilde{d}$  (in frequency space) can be expressed as

$$\tilde{d} = \tilde{s} + \tilde{n}$$

For an **isotropic SGWB**  $\rightarrow \langle h_\lambda(\vec{k}) h_{\lambda'}^*(\vec{k}') \rangle = P_h^\lambda(k) (2\pi)^3 \delta_{\lambda\lambda'} \delta(\vec{k} - \vec{k}')$

Assuming  $\langle \tilde{s}\tilde{n} \rangle = 0$  and Gaussian signal and noise

$$\langle \tilde{d}^2 \rangle = \langle \tilde{s}^2 \rangle + \langle \tilde{n}^2 \rangle = \mathcal{R} P_h^\lambda + N \equiv \mathcal{R} [P_h^\lambda + S_n]$$

where we have introduced

- The **response function** of the instrument  $\mathcal{R}$
- The **signal power spectrum**  $P_h^\lambda$  (in 1/Hz)
- The **noise power spectrum**  $N$  (in 1/Hz)
- The **(square of the) Strain sensitivity**  $S_n$  (in 1/Hz)

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In order to compare with cosmological predictions it's customary to introduce

$$\Omega_{\text{GW}} \equiv \frac{1}{3H_0^2 M_p^2} \frac{\partial \rho_{\text{GW}}}{\partial \ln f} = \frac{4\pi^2}{3H_0^2} f^3 \sum_\lambda P_h^\lambda \quad \text{and} \quad \Omega_n(f) = \frac{4\pi^2}{3H_0^2} f^3 S_n(f),$$

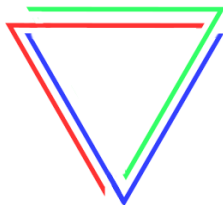
where  $H_0 \simeq 3.24 \times 10^{-18} h_0$  Hz is the Hubble constant today.

# Some common assumptions...

LISA will have three  
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dubbed XYZ basis



Diagonalize to get  
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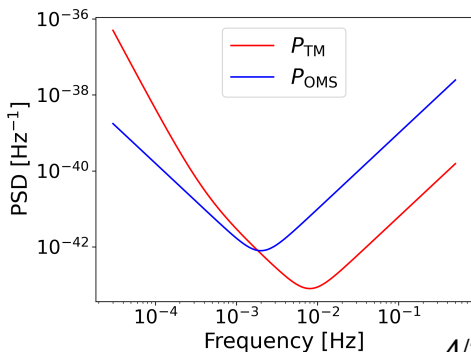
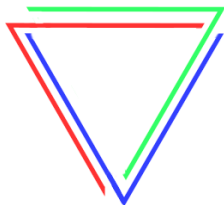
Time Delay Interferometry (TDI) to  
reduce **huge** laser noise

**Low frequencies** are dominated by  
**Test Mass (TM)** noise  
**large frequencies** by **Optical  
Metrology System (OMS)** noise:

$$P_{TM}(f, A) = A^2 \times 10^{-30} \times F_{TM}(f),$$

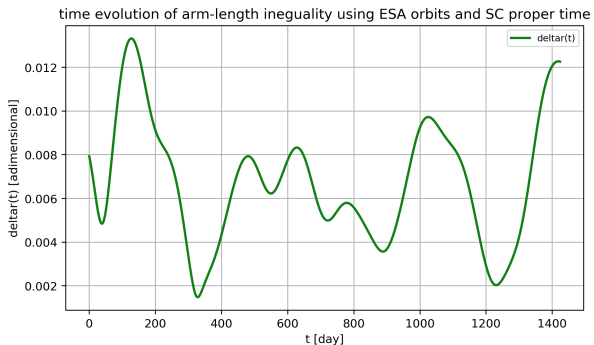
$$P_{OMS}(f, P) = P^2 \times 10^{-24} \times F_{OMS}(f),$$

where  $F_{TM}(f)$ ,  $F_{OMS}(f)$  are some  
functions of frequency.



# In reality LISA won't have equal arms...

Fluctuations in the arm-lengths of order up to  $10^{-2}$  are expected!



Response functions and noise spectra will be modified



Orthogonality of TDI variables might be affected

An accurate description is necessary to avoid biases in the analysis





# Single link signal model

The observable is the difference in the **travel time** of a photon **from  $j$  to  $i$** :

$$\Delta t_{ij}(t) \simeq \int_0^{L_{ij}} \frac{\hat{\lambda}_{ij}^a \hat{\lambda}_{ij}^b}{2} h_{ab}(t(s), \vec{x}(s)) ds, \quad \text{or alternatively,} \quad \eta_{ij}^{\text{GW}}(t) \equiv \frac{d}{dt} \Delta t_{ij}(t).$$

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To compute this quantity we first **expand the signal in plane waves**:

$$h_{ab}(\vec{x}, t) = \int_{-\infty}^{\infty} df \int d\Omega_{\hat{k}} e^{2\pi i f(t - \hat{k} \cdot \vec{x})} \sum_A \tilde{h}_A(f, \hat{k}) e_{ab}^A(\hat{k}),$$

and **assuming homogeneity, isotropy and no-chirality** for the SGWB:

$$\langle \tilde{h}_A(f, \hat{k}) \tilde{h}_B^*(f', \hat{k}') \rangle = \delta(f - f') \delta(\hat{k} - \hat{k}') \delta_{AB} \frac{P_h^{AB}(f)}{16\pi}, \quad \langle \tilde{h}_A(f, \hat{k}) \tilde{h}_B(f', \hat{k}') \rangle = 0.$$

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The cross-spectral density for the single link measurement thus reads

$$S_{ij, mn}^{\eta, \text{GW}}(f) \equiv \sum_A \mathcal{R}_{ij, mn}^A P_h^{AA}(f) = \frac{f^2}{f_{ij} f_{mn}} e^{-2\pi i f(L_{ij} - L_{mn})} \sum_A P_h^{AA}(f) \Upsilon_{ij, mn}^A(f),$$

where  $\mathcal{R}_{ij, mn}^A$  is the **single link response** and we introduced:

$$\Upsilon_{ij, mn}^A(f) = \int \frac{d\Omega_{\hat{k}}}{4\pi} e^{-2\pi i f \hat{k} \cdot (\vec{x}_i - \vec{x}_m)} \xi_{ij}^A(f, \hat{k}) \xi_{mn}^A(f, \hat{k})^*.$$

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Assuming TDI cancels primary noises and only TM and OMS are present:

$$\eta_{ij}^N = \mathcal{D}_{ij} n_{ij}^{\text{TM}}(t) + n_{ij}^{\text{TM}}(t) + n_{ij}^{\text{OMS}}(t),$$

where  $\mathcal{D}_{ij}$  is the delay operator.

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Assuming stationarity, zero-mean and uncorrelated:

$$\langle \tilde{n}_{ij}^{\text{TM}}(f) \tilde{n}_{ij}^{\text{TM}*}(f') \rangle = \frac{1}{2} S_{ij}^{\text{TM}}(f) \delta(f - f'),$$

$$\langle \tilde{n}_{ij}^{\text{OMS}}(f) \tilde{n}_{ij}^{\text{OMS}*}(f') \rangle = \frac{1}{2} S_{ij}^{\text{OMS}}(f) \delta(f - f'),$$

the only non-zero cross spectral densities are:

$$S_{ij,ij}^{\eta,N}(f) = S_{ij}^{\text{TM}}(f) + S_{ji}^{\text{TM}}(f) + S_{ij}^{\text{OMS}}(f),$$

$$S_{ij,ji}^{\eta,N}(f) = e^{2\pi i f L_{ji}} S_{ij}^{\text{TM}}(f) + e^{-2\pi i f L_{ij}} S_{ji}^{\text{TM}}(f),$$

where  $S_{ij}^{\text{TM}}(f) = A_{ij}^2 \times F_{\text{TM}}(f)$  and  $S_{ij}^{\text{OMS}}(f) = P_{ij}^2 \times F_{\text{OMS}}(f)$ .

# Time Delay Interferometry

Compare measurements at  
different times (delay operator)



Noise reduction!

Let us start with two possibilities:

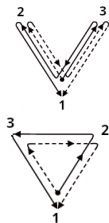
- **Michelson variables**, dubbed **XYZ**, defined as (YZ are permutations):

$$X \equiv (1 - D_{13}D_{31})(\eta_{12} + D_{12}\eta_{21}) + (D_{12}D_{21} - 1)(\eta_{13} + D_{13}\eta_{31})$$

- **Sagnac variables**, dubbed  **$\alpha\beta\gamma$** , defined as ( $\beta\gamma$  permutations):

$$\alpha \equiv \eta_{12} + D_{12}\eta_{23} + D_{12}D_{23}\eta_{31} - (\eta_{13} + D_{13}\eta_{32} + D_{13}D_{32}\eta_{21})$$

$D_{ij}$  delay operator,  $\eta_{ij}$  measurement in  $i$  coming from  $j$



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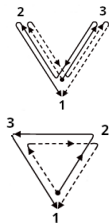
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Both **signal and noise are correlated** in these variables!

For equal arms, diagonalization via:

(diagonal variables dubbed AET and  $\mathcal{AET}$ )

$$\rightarrow \begin{pmatrix} -1/\sqrt{2} & 0 & 1/\sqrt{2} \\ 1/\sqrt{6} & -2/\sqrt{6} & 1/\sqrt{6} \\ 1/\sqrt{3} & 1/\sqrt{3} & 1/\sqrt{3} \end{pmatrix}$$





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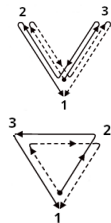
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Let us also introduce the **fully symmetric  $\zeta$**  variable:

$$\zeta = D_{12}(\eta_{31} - \eta_{32}) + D_{23}(\eta_{12} - \eta_{13}) + D_{31}(\eta_{23} - \eta_{21}).$$



# Single link to TDI in a more formal way

It is convenient to define **TDI variables using vector notation**:

$$\tilde{V}(f) = \sum_{ij \in \mathcal{I}} c_{ij}^V(f) \tilde{\eta}_{ij}(f),$$

i.e., starting from the (FTs of the) 6 single link measurement  $\tilde{\eta}_{ij}(f)$ , we use a  $3 \times 6$  matrix ( $c_{ij}^V(f)$ ), to project onto any TDI basis.

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In this formalism, the cross spectral densities

$$\langle \tilde{U}(f) \tilde{V}^*(f') \rangle = \frac{1}{2} S^{UV}(f) \delta(f - f'),$$

can be expressed as:

$$\begin{aligned} \langle \tilde{U}(f) \tilde{V}^*(f') \rangle &= \sum_{ij, mn \in \mathcal{I}} c_{ij}^U(f) c_{mn}^{V*}(f') \langle \tilde{\eta}_{ij}(f) \tilde{\eta}_{mn}^*(f') \rangle, \\ &= \frac{1}{2} \sum_{ij, mn \in \mathcal{I}} \underbrace{c_{ij}^U(f) c_{mn}^{V*}(f)}_{C_{ij, mn}^{UV}(f)} S_{ij, lm}^{\eta}(f) \delta(f - f'). \\ &\quad \underbrace{\hspace{10em}}_{S^{UV}(f)} \end{aligned}$$

Study the **properties of  $C_{ij, mn}^{UV}(f)$**  → make general **statements on TDI basis**. 10/30

# Data generation (in frequency domain)

Assuming signal and noise to be Gaussian, stationary, and isotropic independent realizations for each **data segment and frequency** are drawn:

$$\tilde{s}_c(f_i) = \frac{\mathcal{N}(0, \sqrt{\Omega_{\text{GW}}(f_i)}) + i \mathcal{N}(0, \sqrt{\Omega_{\text{GW}}(f_i)})}{\sqrt{2}}$$

$$\tilde{n}_c(f_i) = \frac{\mathcal{N}(0, \sqrt{\Omega_n(f_i)}) + i \mathcal{N}(0, \sqrt{\Omega_n(f_i)})}{\sqrt{2}}$$

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Given that:

- LISA will be operating for **4yrs** (and assume also **75% efficiency**)
- We choose **data segments** of **roughly 12 days**

in practice we have:

- Roughly **95 independent measurements at each frequency**.
- A frequency **resolution** of **around  $10^{-6}\text{Hz}$**

# Data modeling and likelihood

Which likelihood should we use for our dataset?

Whittle likelihood should work (see any of the existing reviews):

$$-2 \ln \mathcal{L}(\tilde{d}|\theta) \propto \sum_f \tilde{d}_i C_{ij}^{-1}(f|\theta) \tilde{d}_j^* + \ln [\det C_{ij}(f|\theta)] ,$$

where  $C_{ij}$  is the covariance matrix for  $\langle \tilde{d}_i \tilde{d}_j^* \rangle$  given by:

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For fast estimates of the errors on parameter reconstruction use Fisher:

$$\mathbf{F}_{ij} \equiv - \left. \frac{\partial^2 \ln \mathcal{L}(\tilde{\mathbf{d}}|\theta)}{\partial \theta_i \partial \theta_j} \right|_{\theta_0} = \sum_{\mathbf{f}} = \text{Tr} \left[ \mathbf{C}^{-1} \frac{\partial \mathbf{C}}{\partial \theta_i} \mathbf{C}^{-1} \frac{\partial \mathbf{C}}{\partial \theta_j} \right] ,$$

However, this cannot tell us anything about possible biases!

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This leaves us with some  $D(f_i)$  (the averaged data) and an estimate of the error  $\sigma(f_i)$  (the standard deviation or the data).

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*i.e.* from the initial linear  $10^{-6}$ Hz spacing ( $\sim 5 \times 10^5$  points)  
→ we go to some final (and less dense) set of frequencies  $f_i$   
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To gain a factor  $\sim \mathcal{O}(100 \times 100)$  in computation time!

# An accurate likelihood for the compressed data

A Gaussian likelihood would give a systematic low bias!

(astro-ph/9808264, astro-ph/0205387, astro-ph/0302218, 0801.0554)

Consider the Gaussian likelihood:

$$\ln \mathcal{L}_G(\vec{\theta}, \vec{n}) \propto -\frac{N_{\text{chunks}}}{2} \sum_{i,j} \sum_k w_{ij}^{(k)} \left( \frac{D_{ij}^{(k)} - h^2 \Omega_{\text{GW}}(f_{ij}^{(k)}, \vec{\theta}) - h^2 \Omega_{n,ij}(f_{ij}^{(k)}, \vec{n})}{h^2 \Omega_{\text{GW}}(f_{ij}^{(k)}, \vec{\theta}) + h^2 \Omega_{n,ij}(f_{ij}^{(k)}, \vec{n})} \right)^2$$

and the Lognormal likelihood:

$$\ln \mathcal{L}_{LN}(\vec{\theta}, \vec{n}) \propto -\frac{N_{\text{chunks}}}{2} \sum_{i,j} \sum_k w_{ij}^{(k)} \ln^2 \left( \frac{h^2 \Omega_{\text{GW}}(f_{ij}^{(k)}, \vec{\theta}) + h^2 \Omega_{n,ij}(f_{ij}^{(k)}, \vec{n})}{D_{ij}^{(k)}} \right)$$

Then we define our likelihood as (astro-ph/0302218, 2009.11845)

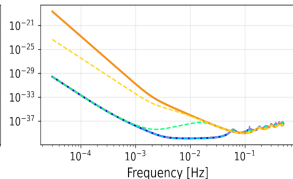
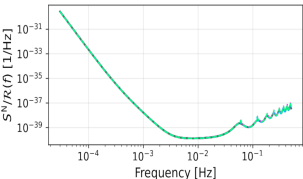
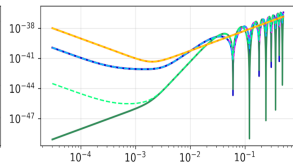
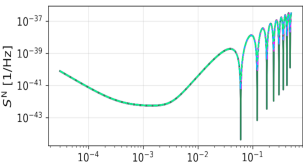
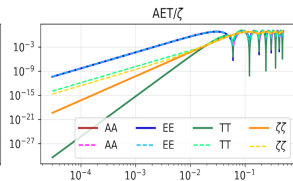
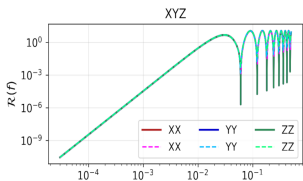
$$\ln \mathcal{L} = \frac{1}{3} \ln \mathcal{L}_G + \frac{2}{3} \ln \mathcal{L}_{LN}$$

which removes the skewness contributions and thus is more accurate.

Responses, spectra and strain noise

# Signal and noise Michelson

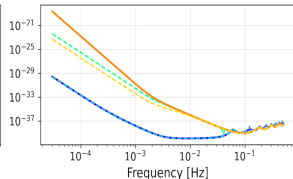
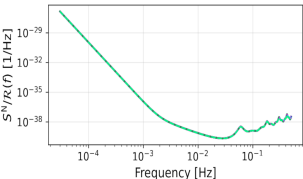
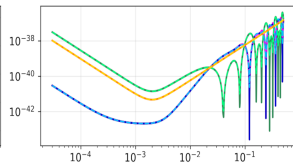
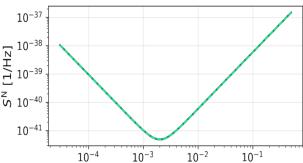
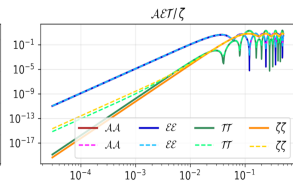
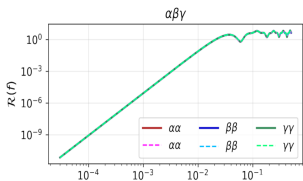
- Solid lines → equal arms
- Dashed lines → unequal arms
- Most TDI variables are mildly affected
- Slight displacement of the zeros
- T Michelson loses signal orthogonality!
- $\zeta$  is clearly more robust to unequal arm corrections!



Responses, spectra and strain noise

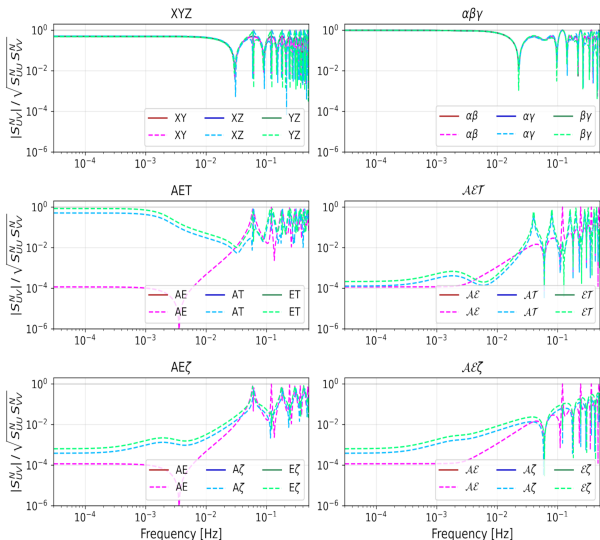
## Signal and noise Sagnac

- Solid lines → equal arms
- Dashed lines → unequal arms
- Sensitivity is similar to Michelson variables (but less zeros)
- $\mathcal{T}$  is way more robust than  $\mathcal{T}$ !
- $\mathcal{T}$  and  $\zeta$ 's signal orthogonality are comparable!



# Noise correlations

- Solid lines → equal arms
- Dashed lines → unequal arms
- Unequal arms break orthogonality
- Correlations involving T are most affected
- $\mathcal{AET}$  is again more robust
- Replacing T with  $\zeta$  might help
- No real benefit in trading  $\mathcal{T}$  for  $\zeta$

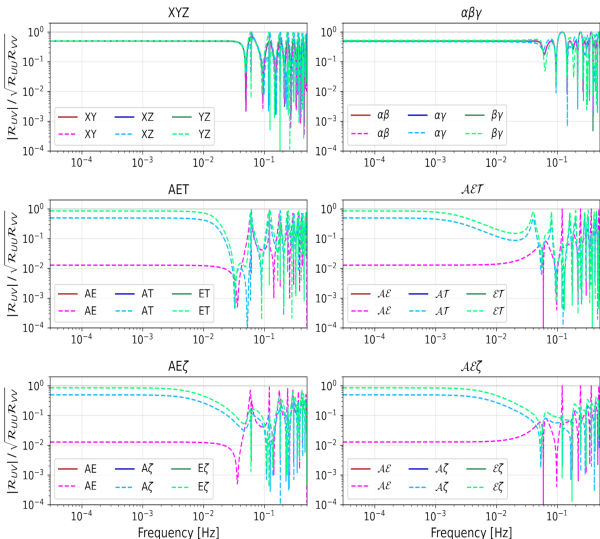




Noise and signal correlations

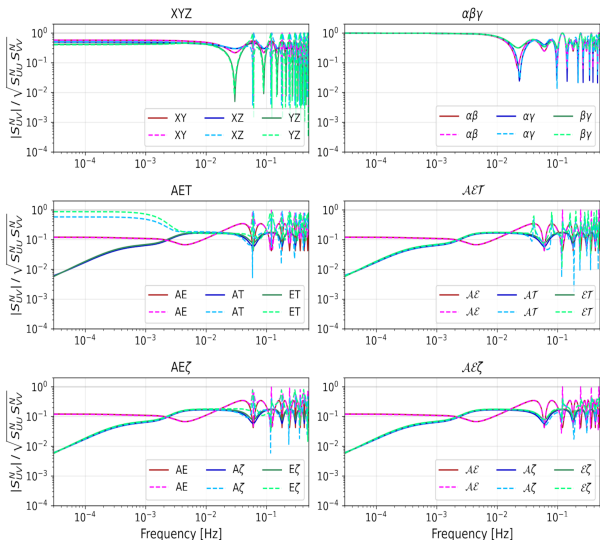
# Signal correlations

- Solid lines → equal arms
- Dashed lines → unequal arms
- All bases are affected ( $\sim$  in the same way)!
- Leakage into  $T$ ,  $\mathcal{T}$ ,  $\zeta$  induces correlations
- Signal-sensitive channels stay orthogonal



# Noise correlations v2 (unequal noise levels)

- Solid lines → equal arms
- Dashed lines → unequal arms
- Equal arms also have non-zero correlations!
- Correlations in all TDI bases
- Again, Michelson performs worse than other bases



# Case study

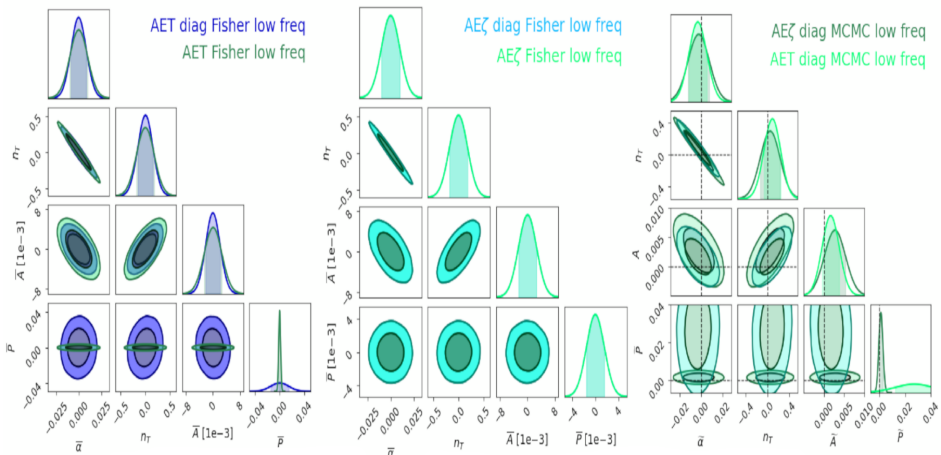
Let's test the impact of including these effects on parameter reconstruction.

Let us consider the following scenario:

- Constant but unequal armlenghts
- Noise described by a template (controlled by some parameters)
- Constant (check both equal and unequal) noise parameters
- Signal described by a power law  $h^2\Omega_{GW} = 10^{\alpha} (f/f_*)^{n_T}$
- Injection with quite large SNR ( $\alpha = -11.5, n_T = 0 \rightarrow \text{SNR} \sim 270$ )
- Fisher matrix to get uncertainties and assess the impact of CSDs
- MCMC to validate Fisher results and look for biases
- Compressed data only uses the diagonal (still can check biases)

Impact on parameter estimation

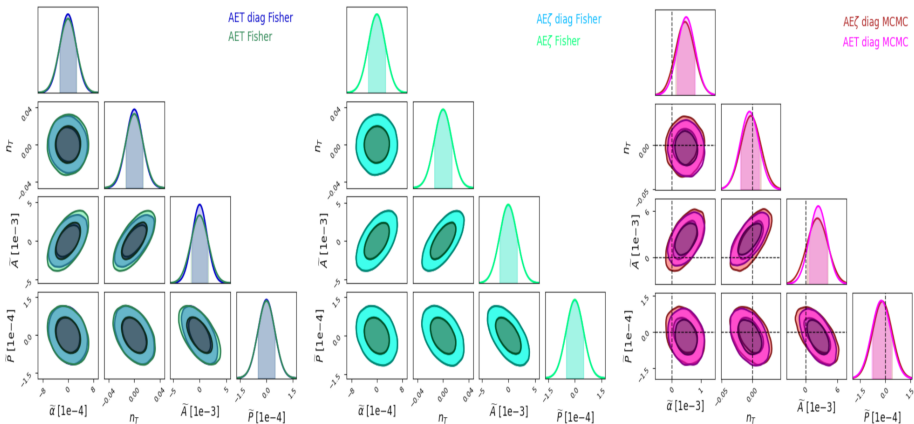
# Low frequency (equal noise) analysis



- MCMC (diagonal only): Fisher approximation works quite well
- Fisher: Neglecting correlations is dangerous for AET, but not much for AE $\zeta$ !
- MCMC/Fisher: AET performs much worse than AE $\zeta$

Impact on parameter estimation

## Full frequency (equal noise) analysis

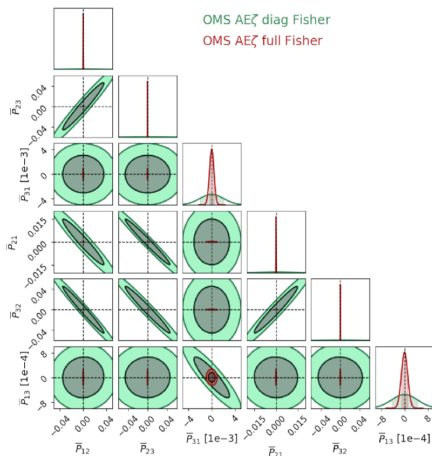
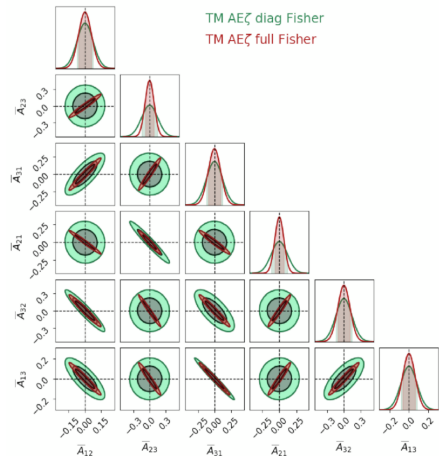


- MCMC (diagonal only): Fisher approximation works quite well
- Fisher: Neglecting correlations only marginally affects the reconstruction
- MCMC/Fisher: AET slightly underestimates errors (wrt AE $\zeta$ )

In collaboration with Olaf Hartwig, Marc Lilley and Martina Muratore

Impact on parameter estimation

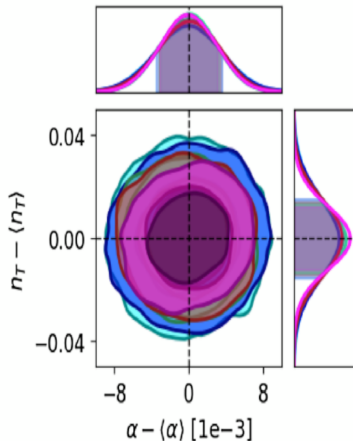
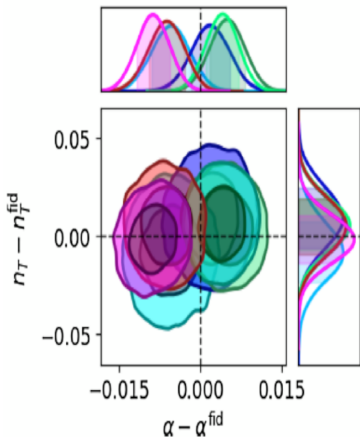
## Full frequency (unequal noise) analysis



- MCMC (diagonal only): (not shown here but) Fisher approximation works quite well
- Fisher: Neglecting correlations might be dangerous for both bases (here only AE $\zeta$ )
- MCMC/Fisher: more impact on worsley constrained (subdominant) parameters!

Impact on parameter estimation

# Signal parameters



- AEζ UA, UN
- AET UA, UN
- AEζ UA, EN
- AET UA, EN
- AEζ EA, EN
- AET AE, EN

Good news for theorists in the room:  
**Signal parameters don't care much about all this!**  
 (remember the caveats though)

## ML for SGWB data analysis

Traditional methods (MCMC, nested sampling, whatever) are quite efficient and guaranteed to converge (in some cases)

**but**

scale poorly with number of parameters and require explicit likelihoods



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Normally, with Bayesian inference, we try to study the posterior probability:

$$p(\theta|d) = \frac{p(d|\theta)\pi(\theta)}{p(d)} \equiv r(d, \theta)\pi(\theta),$$

where we have introduced:

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i.e.  $r(d, \theta)$  is the ratio between joint probability and marginal probability.

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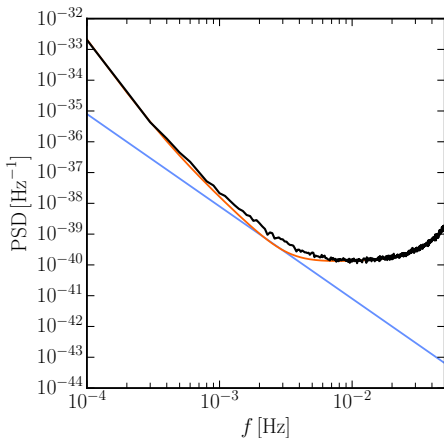
i.e.  $r(d, \theta)$  is the ratio between joint probability and marginal probability.

Given a pair  $(\theta, d)$ ,  $r(d, \theta)$  can be used to assess whether  $\theta$  can generate  $d$ !

This can be cast in a minimization problem that **can be solved with ML**  
the approach is typically referred to as **Neural Ratio Estimation**.

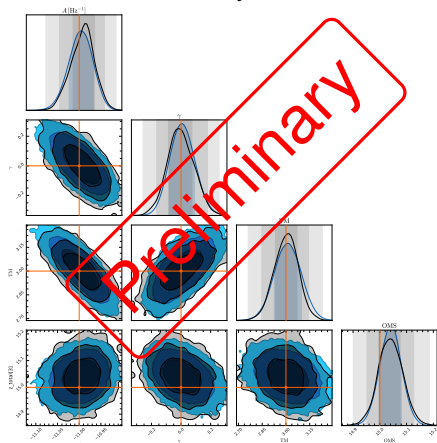
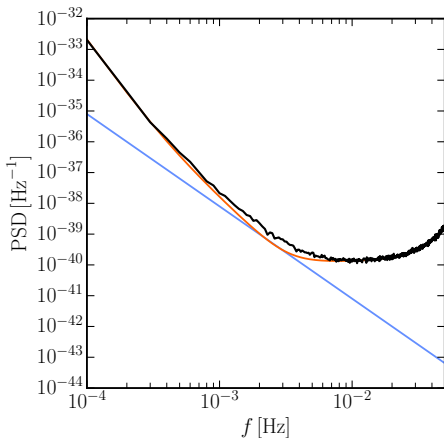
# Recover previous results I ...

Assume we inject a power law signal:  
Can we recover it with the same level of accuracy?



# Recover previous results | ...

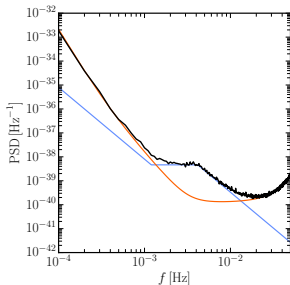
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Good news!

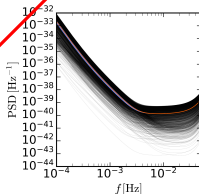
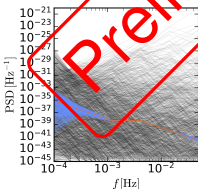
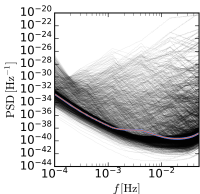
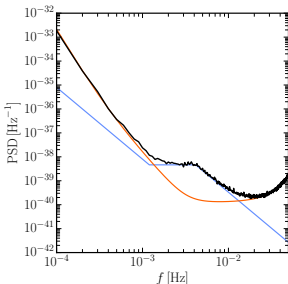
# Recover previous results II...

Can we also do something "template-free"?



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Can we also do something "template-free"?



Good news again!

## ... plus something completely new!

What if there's  
something else beyond  
SGWB and noise?

For example, assume  
some sources slightly  
below the threshold for  
detection are randomly  
injected.

Would this still work??

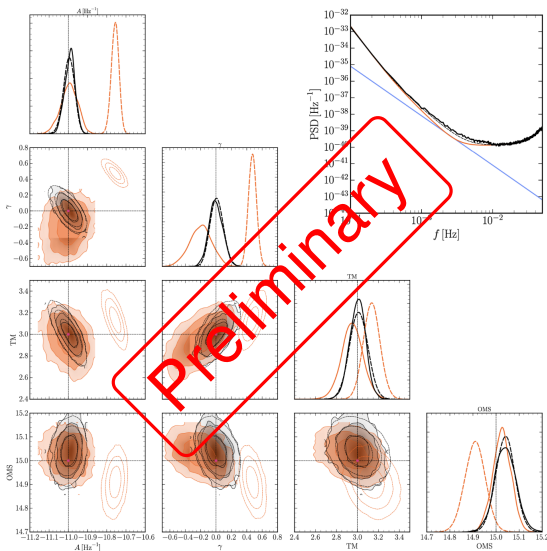


# ... plus something completely new!

What if there's something else beyond SGWB and noise?

For example, assume some sources slightly below the threshold for detection are randomly injected.

Would this still work??



# Conclusions and future perspectives

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- Unequal arms jeopardize the standard orthogonalization procedure
- Some TDI variables are more robust to unequal arm corrections
- Similarly, unequal noise levels also introduce correlations
- Signal reconstruction looks mildly affected (with caveats...)
- ML techniques for SGWB look quite promising...

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- ML techniques for SGWB look quite promising...

## Future perspectives

- Application to concrete cases (inflation, phase transitions, ...)
- Keep improving on detector modeling
- More realistic noise model and data generation procedure
- Drop stationarity (both for signal and noise)
- Include anisotropies
- New techniques?

Last Slide

# The End

Thank you