

# Searches for isotropic gravitational-wave backgrounds using ground-based interferometers

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“Data analysis challenges for stochastic GW backgrounds”

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# Outline / challenges

1. stochastic GW backgrounds in the LIGO-Virgo-KAGRA band are weak
  2. detector noise is not stationary
  3. detector noise is not Gaussian
  4. potential contamination from correlated noise
- Discuss above in the context of LVK O3 stochastic search for an isotropic GWB
  - Won't talk about anisotropy or new methods (Jishnu's and Vuk's talks)
  - Won't talk about 3G detectors e.g., Cosmic Explorer, Einstein Telescope (Angelo's talk)

Ground-based interferometers	LISA
km-long arms	million km-long arms
arm length $\ll$ GW wavelength ("long wavelength approx")	arm length $\sim$ GW wavelength at high frequencies
trivial timing response to GWs	non-trivial timing response to GWs
noise dominated	signal dominated (galactic DWD is guaranteed stochastic foreground)
currently just backgrounds (no foregrounds)	both backgrounds and foregrounds
detector noise estimated from auto-power	detector noise inferred as part of the analysis
cross correlate data from multiple detectors	cross correlation not feasible (only one LISA)
"local fit": separate searches for individual sources	"global fit"
hybrid frequentist-Bayesian analyses	Bayesian inference
potentially fix problems with instrument (on Earth)	can't go to LISA to fix problems

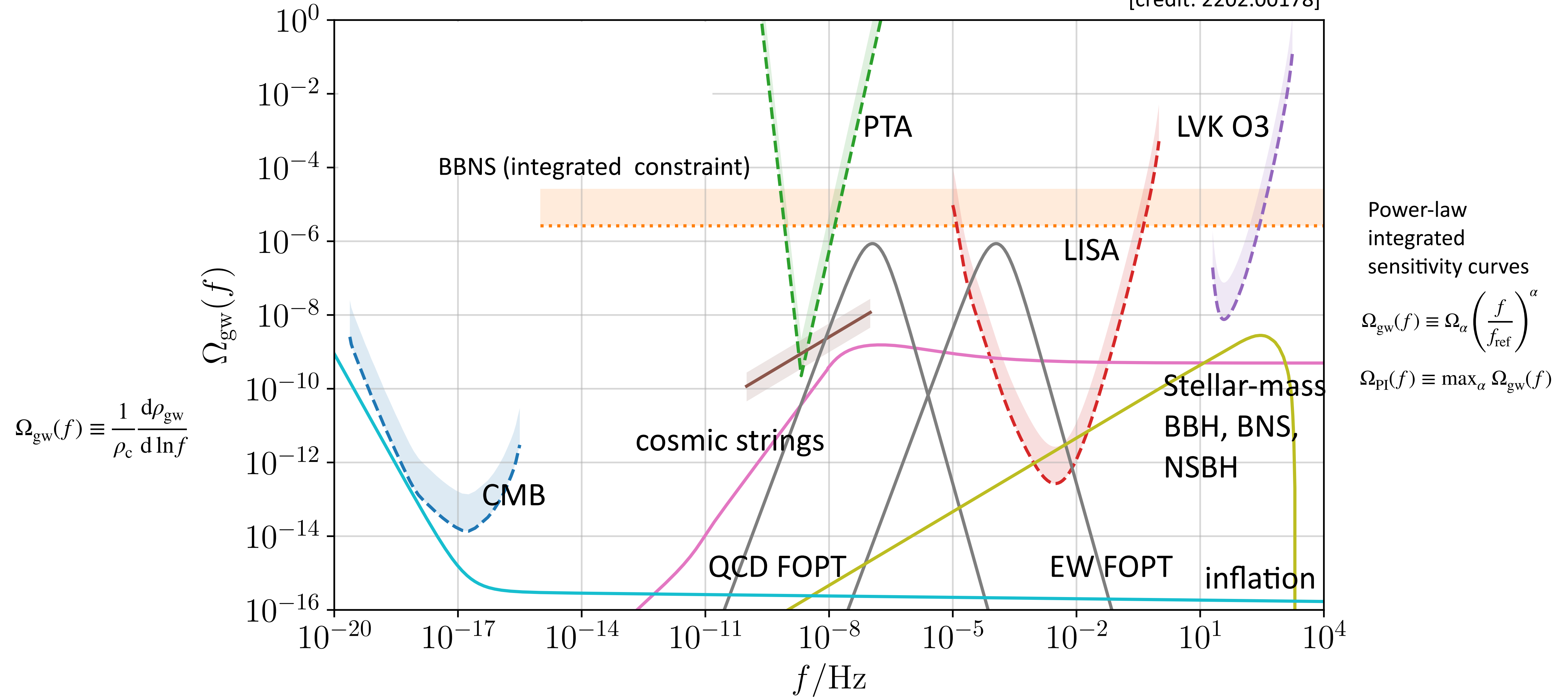
# Global network of ground-based detectors



[credit: Vuk Mandic]

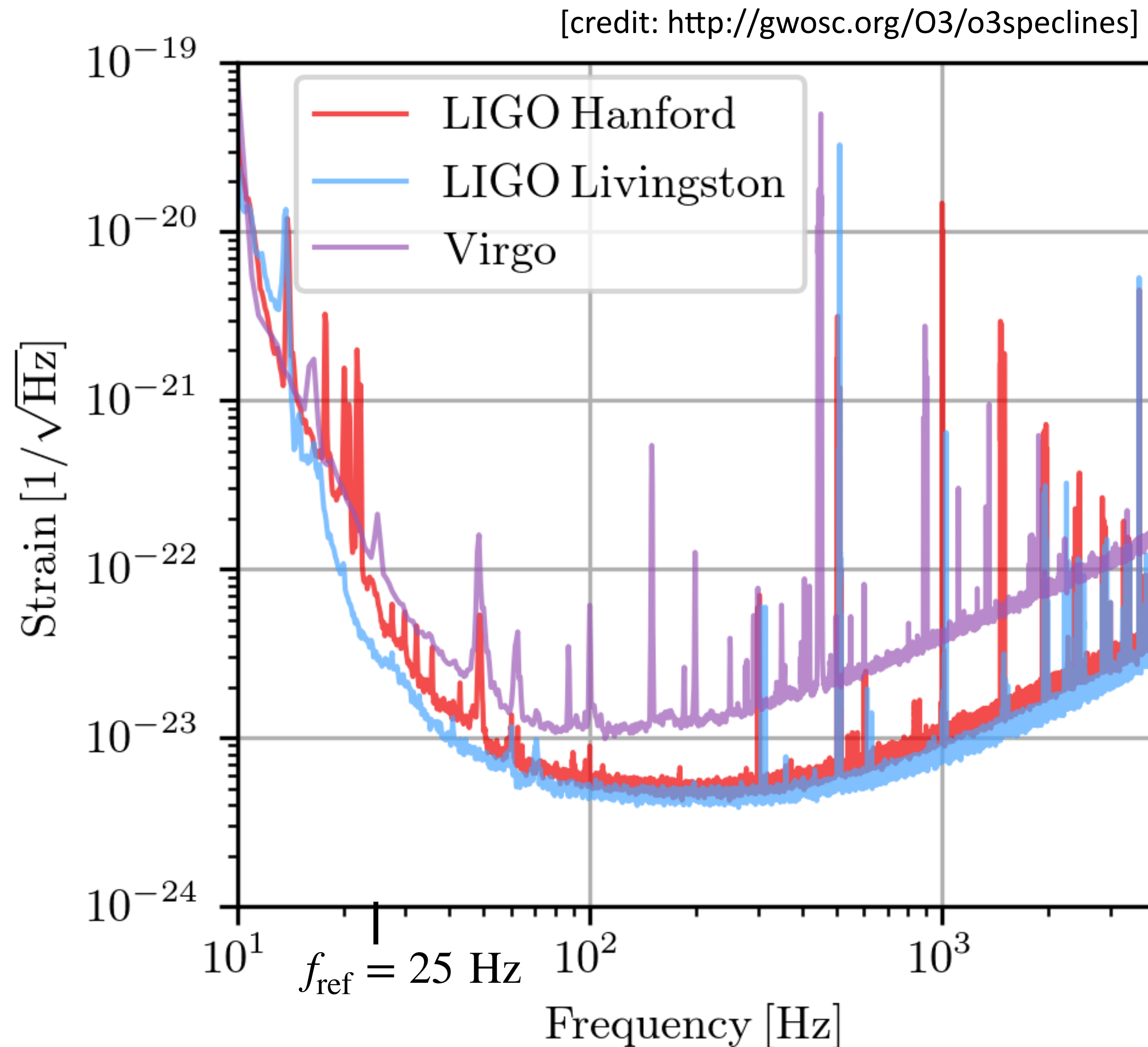
# Some potential GWB signals

[credit: 2202.00178]



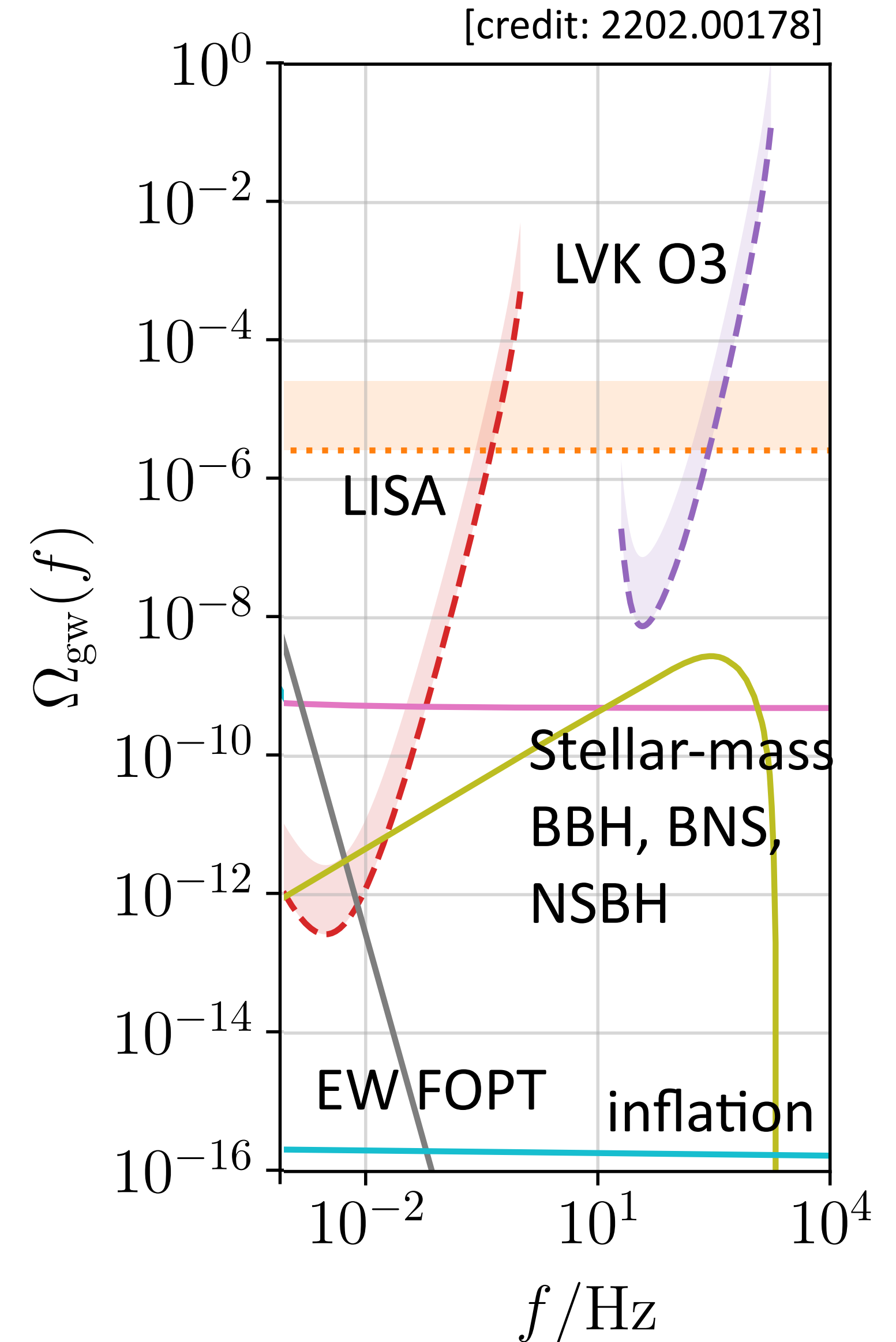
# O3 information

- Data taken by LIGO Hanford, LIGO Livingston, and Virgo detectors
- O3 split into two parts:
  - O3a: 1 Apr 2019 - 1 Oct 2019 (6 months)
  - O3b: 1 Nov 2019 - 27 Mar 2020 (~5 months)
- Total live time (before data quality cuts):
  - HL: 205.4 days
  - HV: 187.5 days
  - LV: 195.4 days
- “Flagship” search: unpolarized, isotropic, power-law  $\Omega_{\text{gw}}(f) = \Omega_{\text{ref}}(f/f_{\text{ref}})^\alpha$ 
  - $\alpha = 0$  for cosmological backgrounds
  - $\alpha = 2/3$  for binary inspiral
  - $\alpha = 3$  for “generic” source (white strain noise)



# Challenge 1: GWB signal is weak relative to noise

- in LVK band, amplitude of GWB  $\ll$  noise, unlike LISA or PTA searches for GWBs
- an optimal analysis should model GWB contribution to auto-power, BUT...
  - for a weak GWB, cross-power and estimates of auto-power are “sufficient statistics”
  - cross-correlation allows one to “dig down” below noise
- weak-signal approx may break down for searches for intermittent GWBs (segment SNR  $\sim 1$ )
  - might need to model GWB contribution to auto-power estimates




# Cross-correlation: basic idea

Data from two detectors:

$$d_1 = R_1 h + n_1$$

$$d_2 = R_2 h + n_2$$

 **common** GW signal component

Expected value of cross-correlation:

$$\langle C_{12} \rangle = \langle d_1 d_2 \rangle = R_1 R_2 \langle h^2 \rangle + R_1 \langle \cancel{h n_2} \rangle^0 + R_2 \langle \cancel{n_1 h} \rangle^0 + \langle n_1 n_2 \rangle = R_1 R_2 \langle h^2 \rangle + \langle n_1 n_2 \rangle$$

Assuming detector noise is uncorrelated:

$$\langle C_{12} \rangle = R_1 R_2 \langle h^2 \rangle = \gamma_{12} S_h$$



# Hybrid frequentist-Bayesian analysis for weak GWBs

Cross and auto-power estimates for detectors I, J:

$$C_{IJ}(t; f) = \frac{2}{T} \text{Re}[\tilde{d}_I^*(t; f) \tilde{d}_J(t; f)]$$

$$P_I(t; f) = \frac{2}{T} |\tilde{d}_I(t; f)|^2$$

Estimator of  $\Omega_{\text{GW}}(f)$  and its variance (weak-signal):

$$\hat{\Omega}_{\text{GW},IJ}(t; f) = \frac{C_{IJ}(t; , f)}{\gamma_{IJ}(f) S_0(f)} \quad \sigma_{\text{GW},IJ}^2(t; f) \approx \frac{1}{2T\Delta f} \frac{P_I(t; f) P_J(t; f)}{\gamma_{IJ}^2(f) S_0^2(f)}$$

$$S_0(f) = \frac{3H_0^2}{10\pi^2 f^3}$$

Likelihood function for model  $\Omega_{\text{GW}}(f)$ :

$$p(\hat{\Omega}_{\text{GW},IJ}(f) | \vec{\lambda}) \propto \exp \left[ -\frac{1}{2} \sum_{IJ} \sum_f \frac{\left( \hat{\Omega}_{\text{GW},IJ}(f) - \Omega_{\text{model}}(f | \vec{\lambda}) \right)^2}{\sigma_{\text{GW},IJ}^2(f)} \right]$$

where

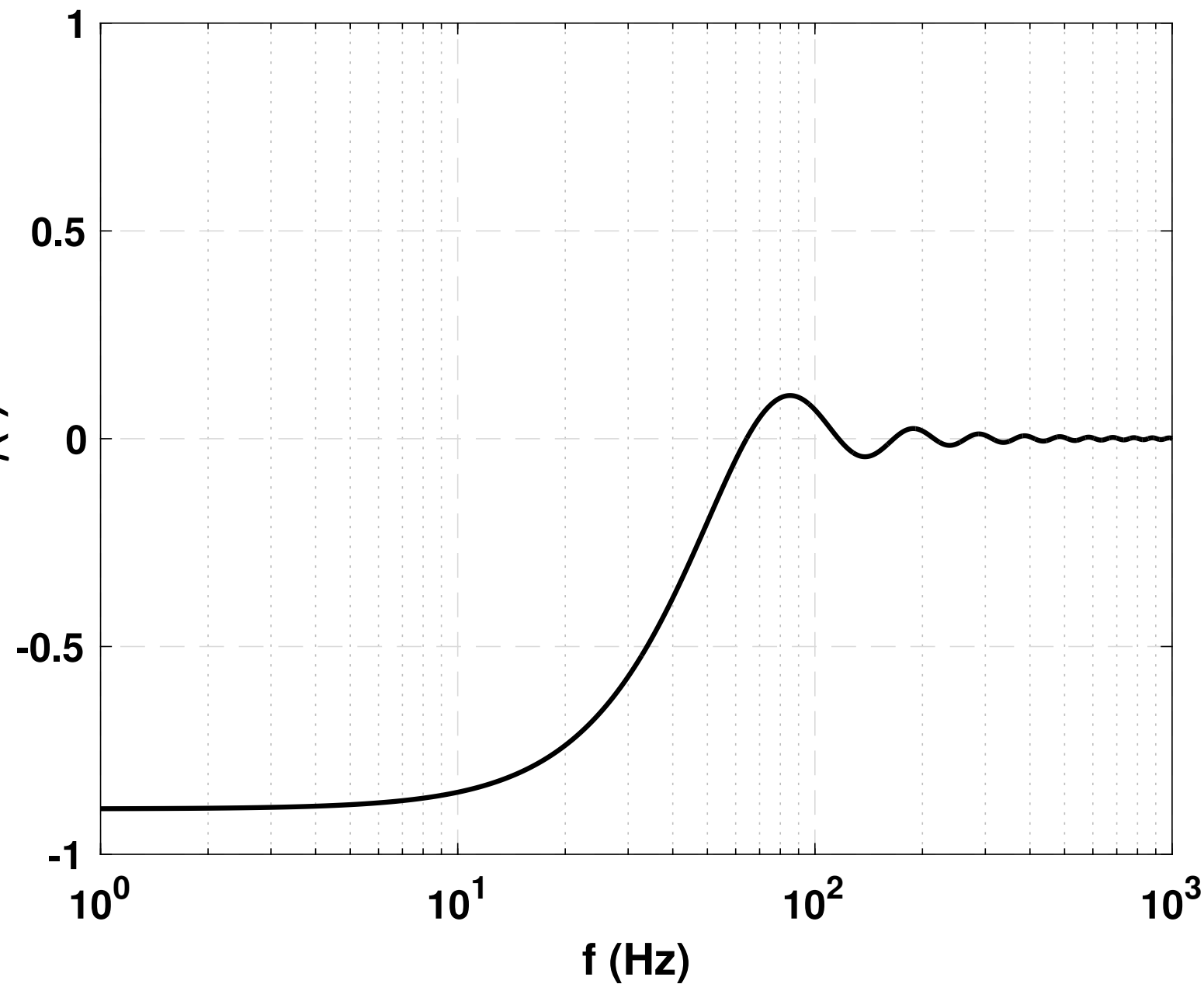
$$\hat{\Omega}_{\text{GW},IJ}(f) = \frac{\sum_t \Omega_{\text{GW},IJ}(t; f) / \sigma_{\text{GW},IJ}^2(t; f)}{\sum_t 1 / \sigma_{\text{GW},IJ}^2(t; f)}$$

$$\frac{1}{\sigma_{\text{GW},IJ}^2(f)} = \sum_t \frac{1}{\sigma_{\text{GW},IJ}^2(t; f)}$$

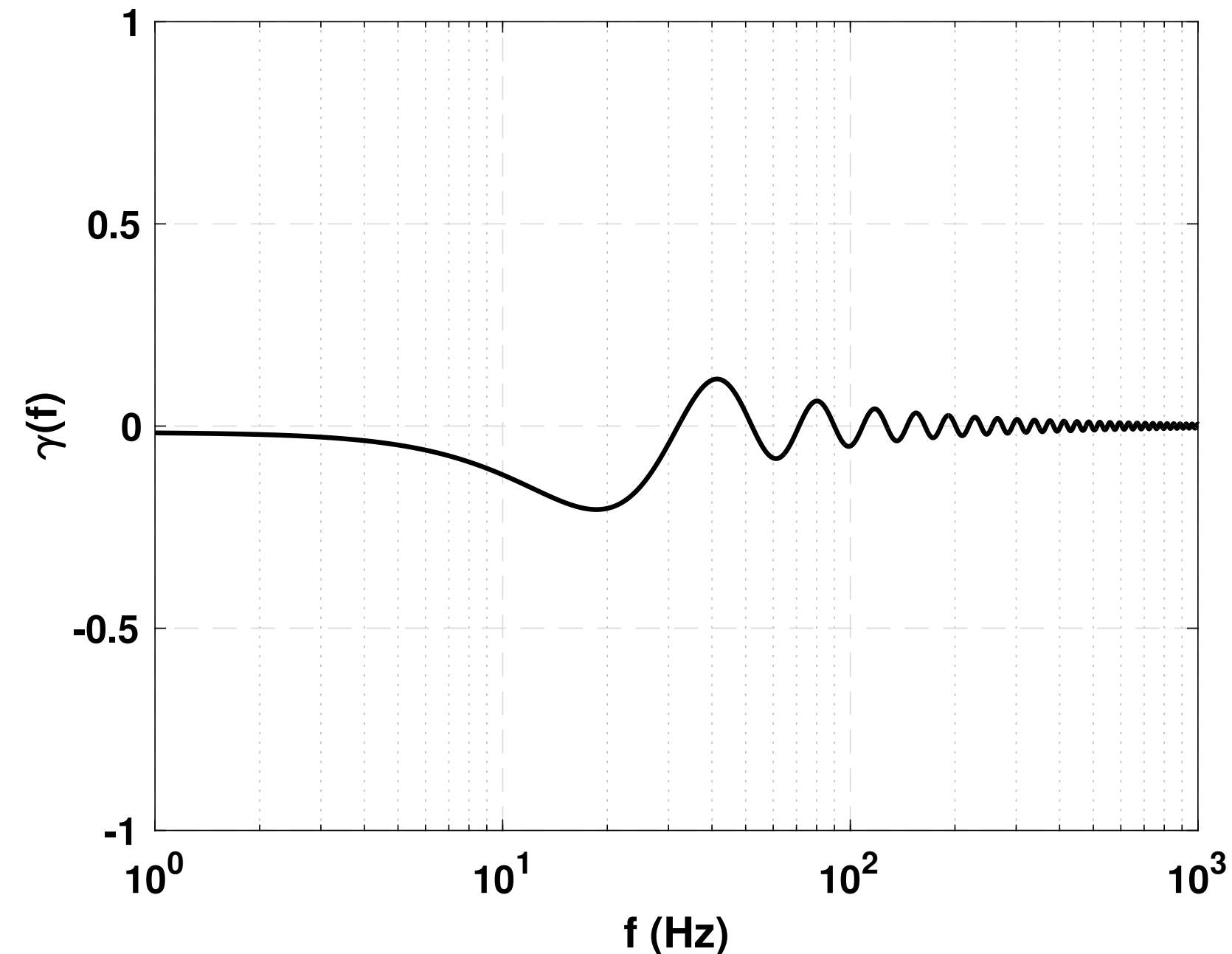
# Overlap functions for cross-correlated data

$$C_{IJ}(f) = \gamma_{IJ}(f) S_h(f) \quad \text{where} \quad \gamma_{IJ}(f) = \frac{5}{8\pi} \sum_A \int d\hat{k} F_I^A(\hat{k}) F_J^A(\hat{k}) e^{-i2\pi f \hat{k} \cdot (\vec{x}_I - \vec{x}_J)}$$

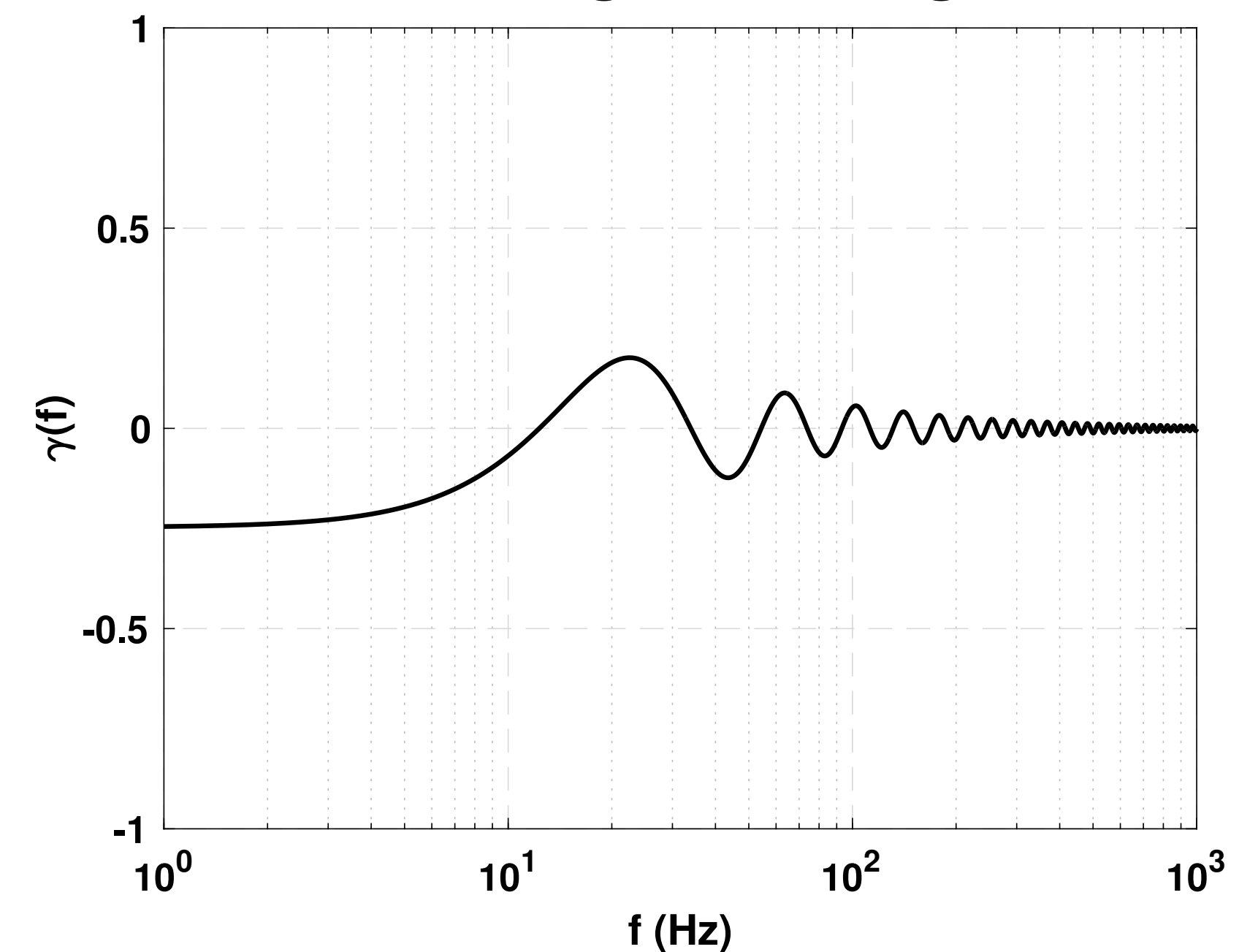
LIGO Hanford - LIGO Livingston



LIGO Hanford - Virgo



LIGO Livingston - Virgo



- overlap functions reduce frequency band where most of the SNR is accumulated
- extent of sensitive frequency band depend on spectral index:
  - 20-100 Hz for  $\alpha = 0$ ; 20-100 Hz for  $\alpha = 2/3$ ; 20-400 Hz for  $\alpha = 3$

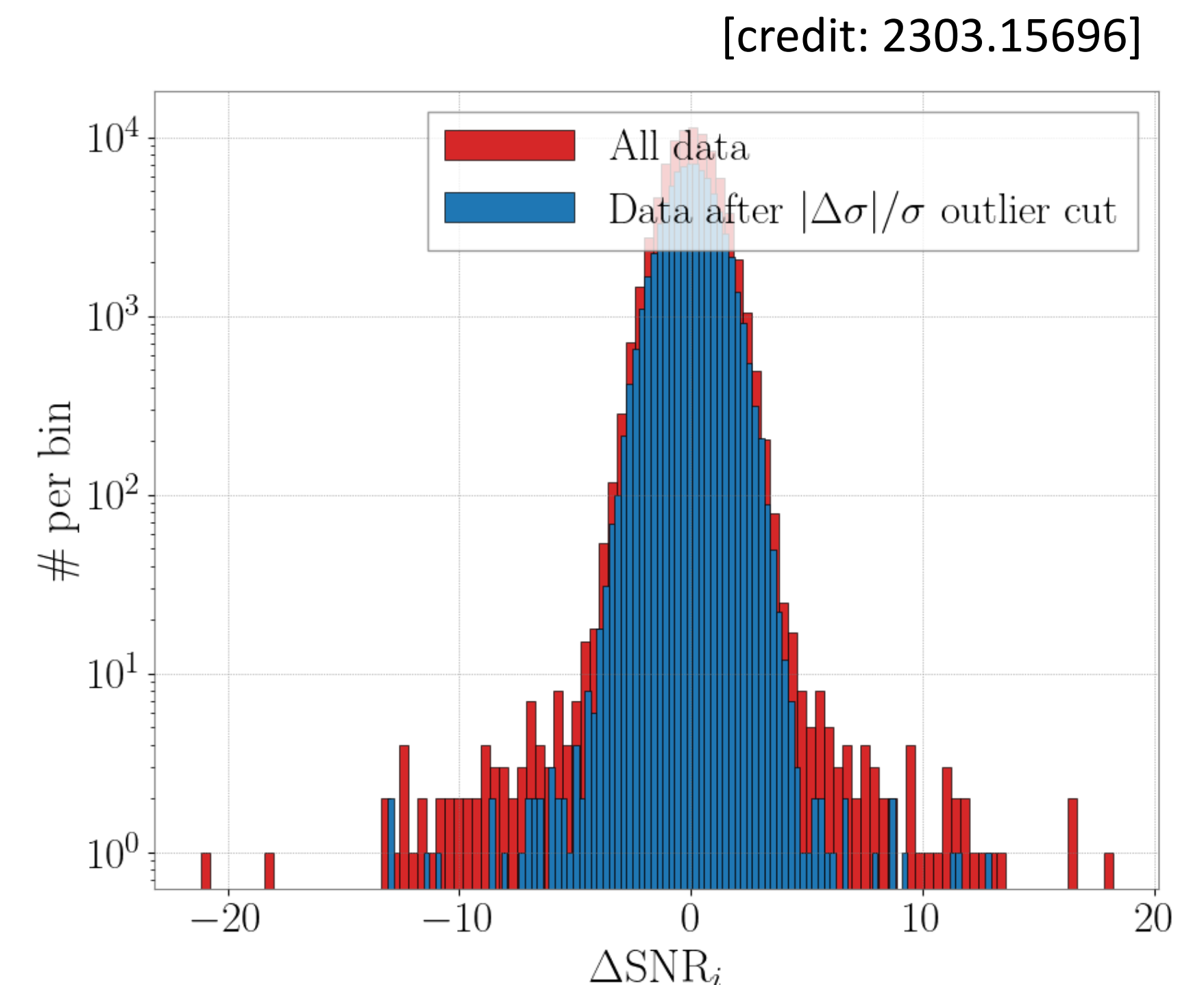
# Challenge 2: detector noise is not stationary

- interferometers are non-stationary on  $\sim$  minutes time scale
  - break year-long observation into short duration segments (192 s for O3)
  - compare estimated power spectra in neighboring segments with that in analysis segment
  - reject segment if

$$\frac{|\Delta\sigma|}{\sigma} \equiv \frac{|\sigma_{\text{neighbor}} - \sigma_{\text{analysis}}|}{\sigma_{\text{analysis}}} > 0.20$$

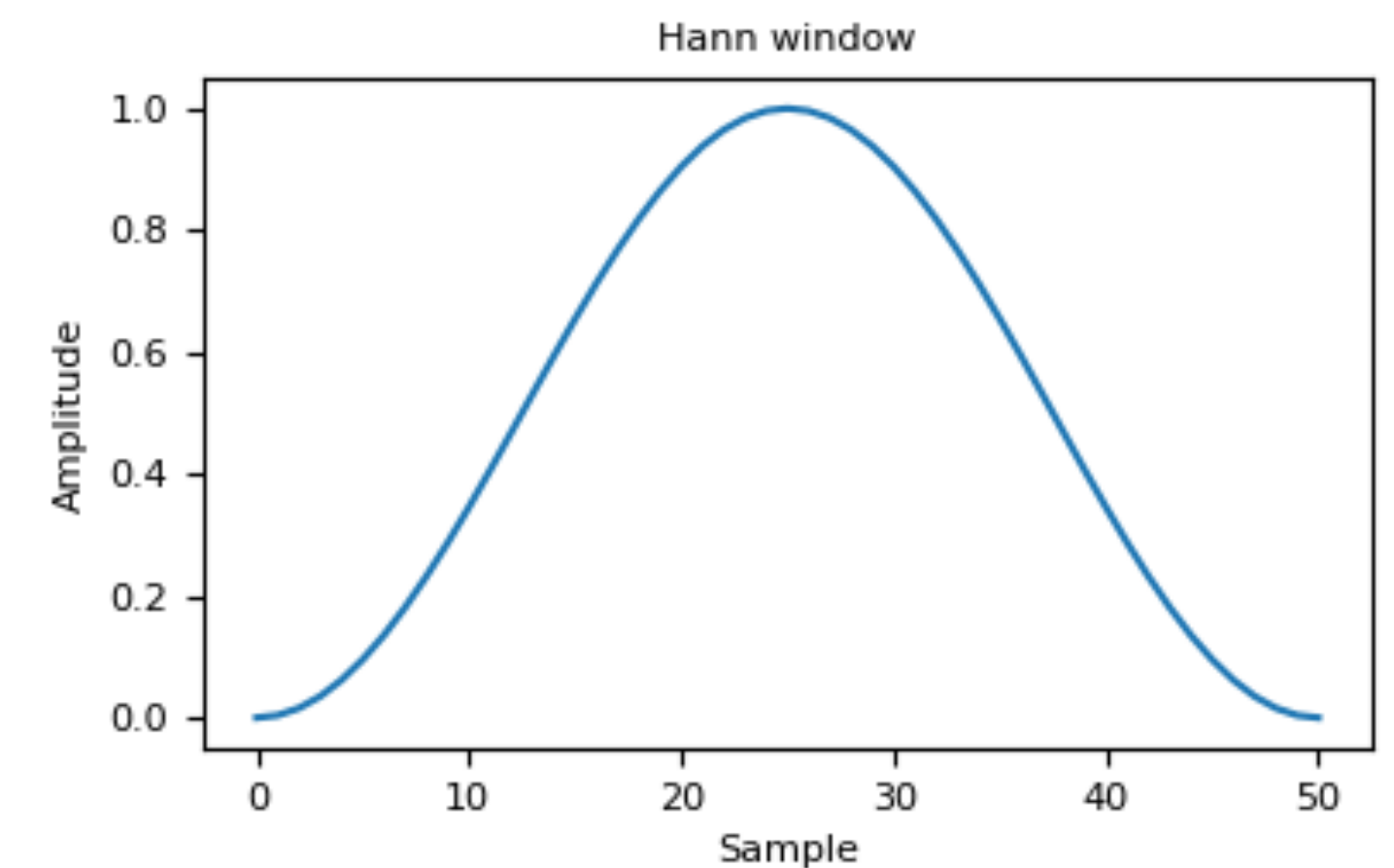
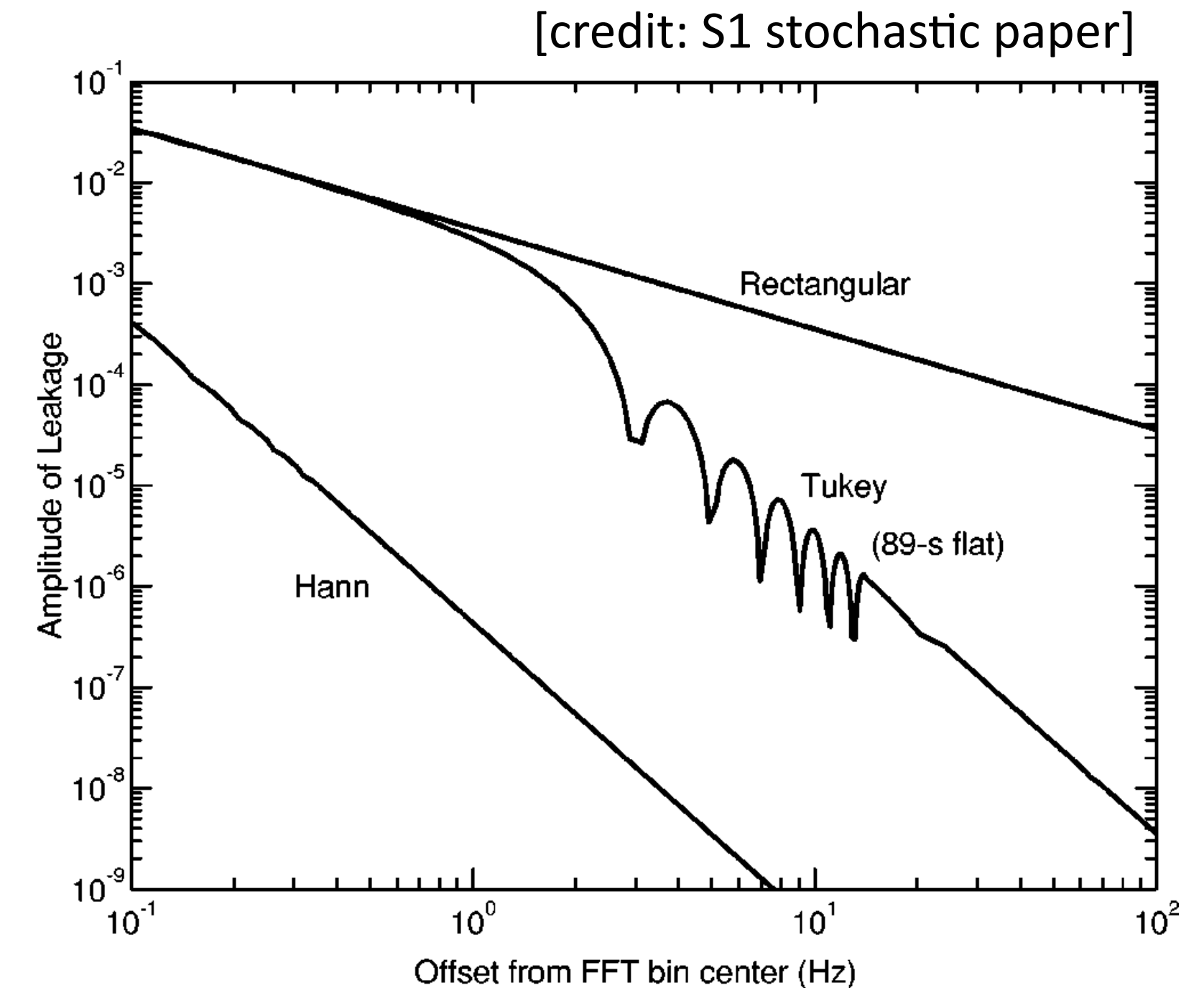
- effective at removing noisy segments
- lose  $\sim 20\%$  of available live-time from  $\Delta\sigma$ -cut:
  - 17.9% for HL
  - 22.1% for HV
  - 21.9% for LV

$$\Delta\text{SNR}_i = \frac{\hat{\Omega}_i - \Omega_{\text{opt}}}{\sigma_i}$$

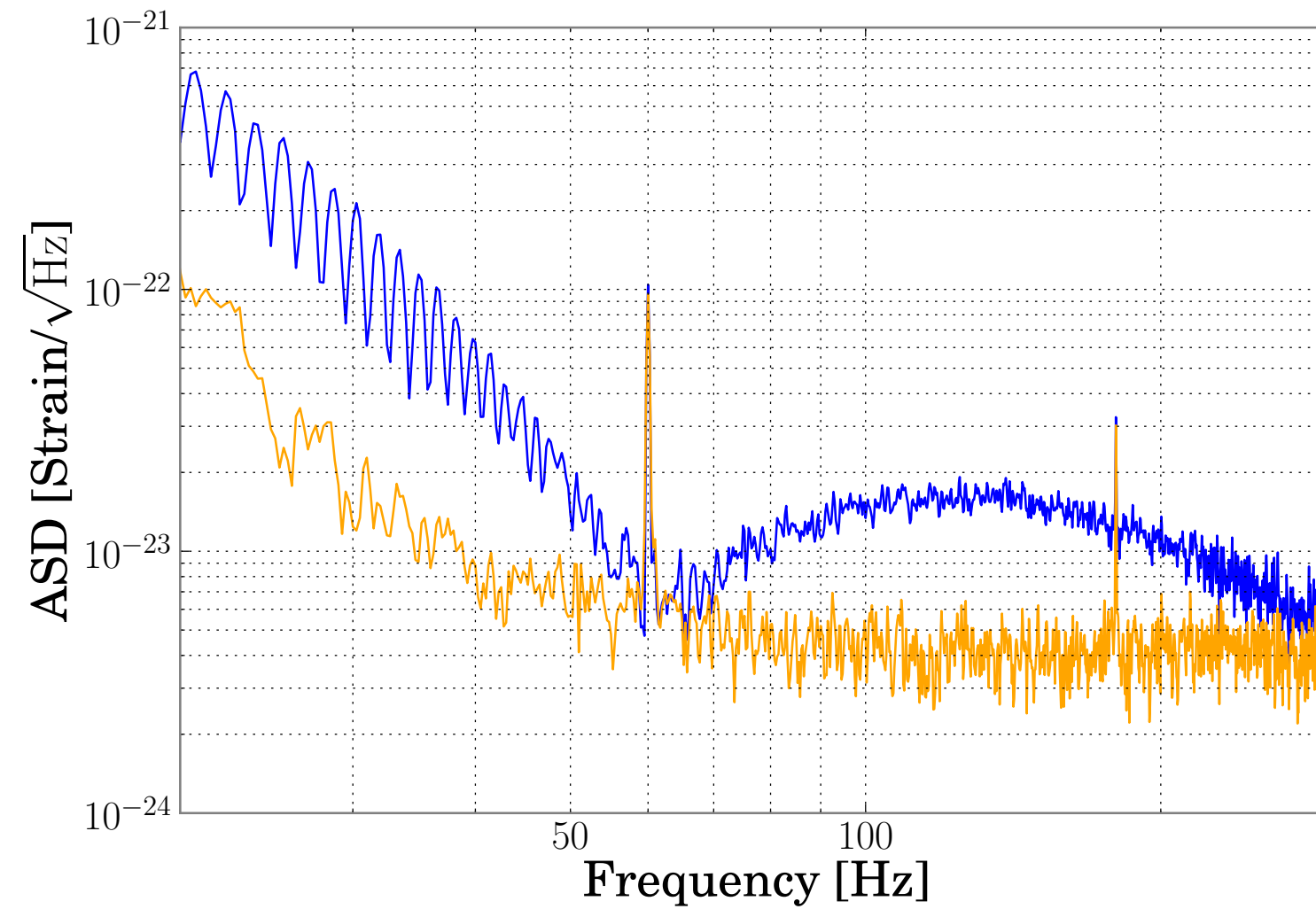
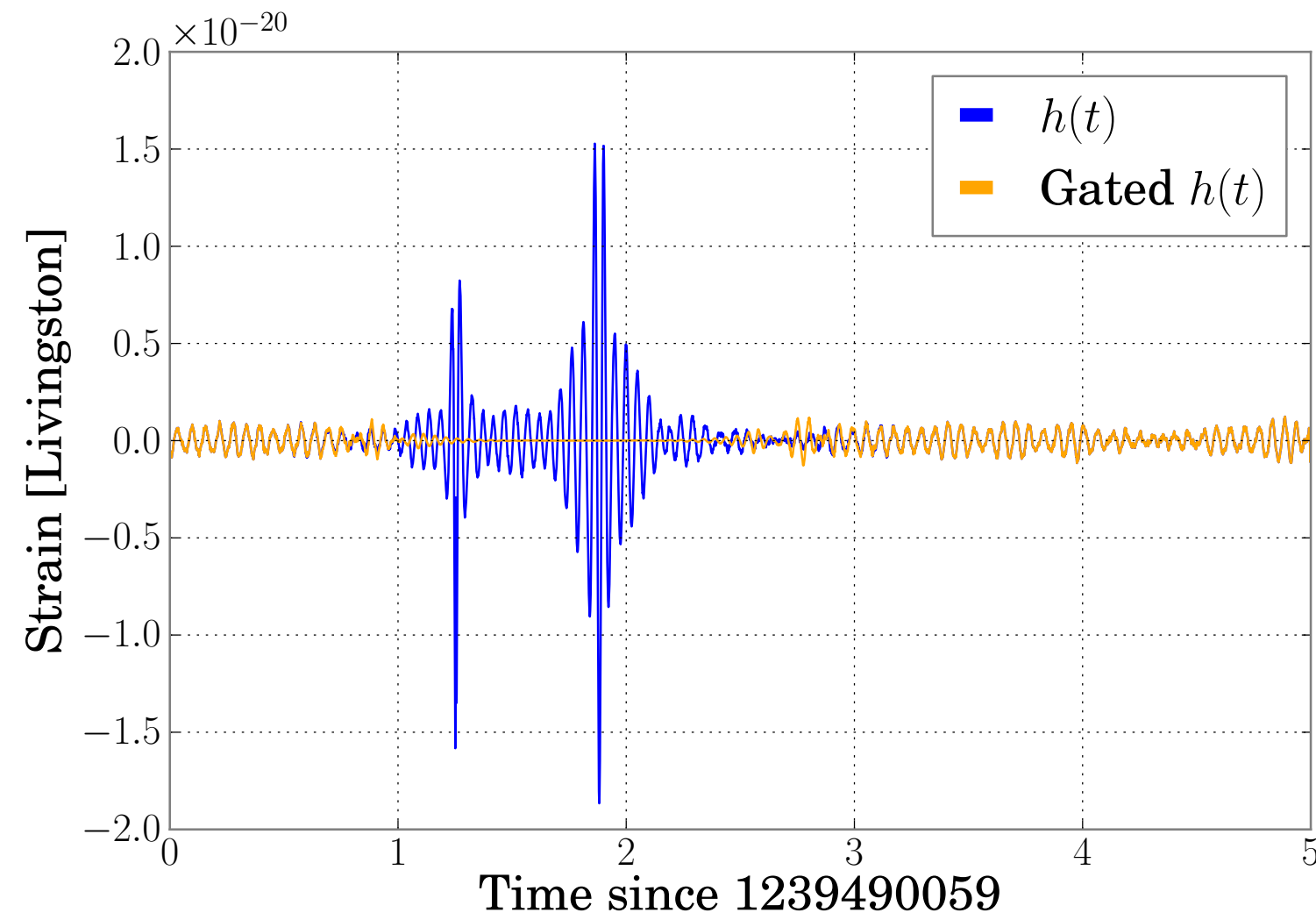


# Challenge 3: detector noise is not Gaussian

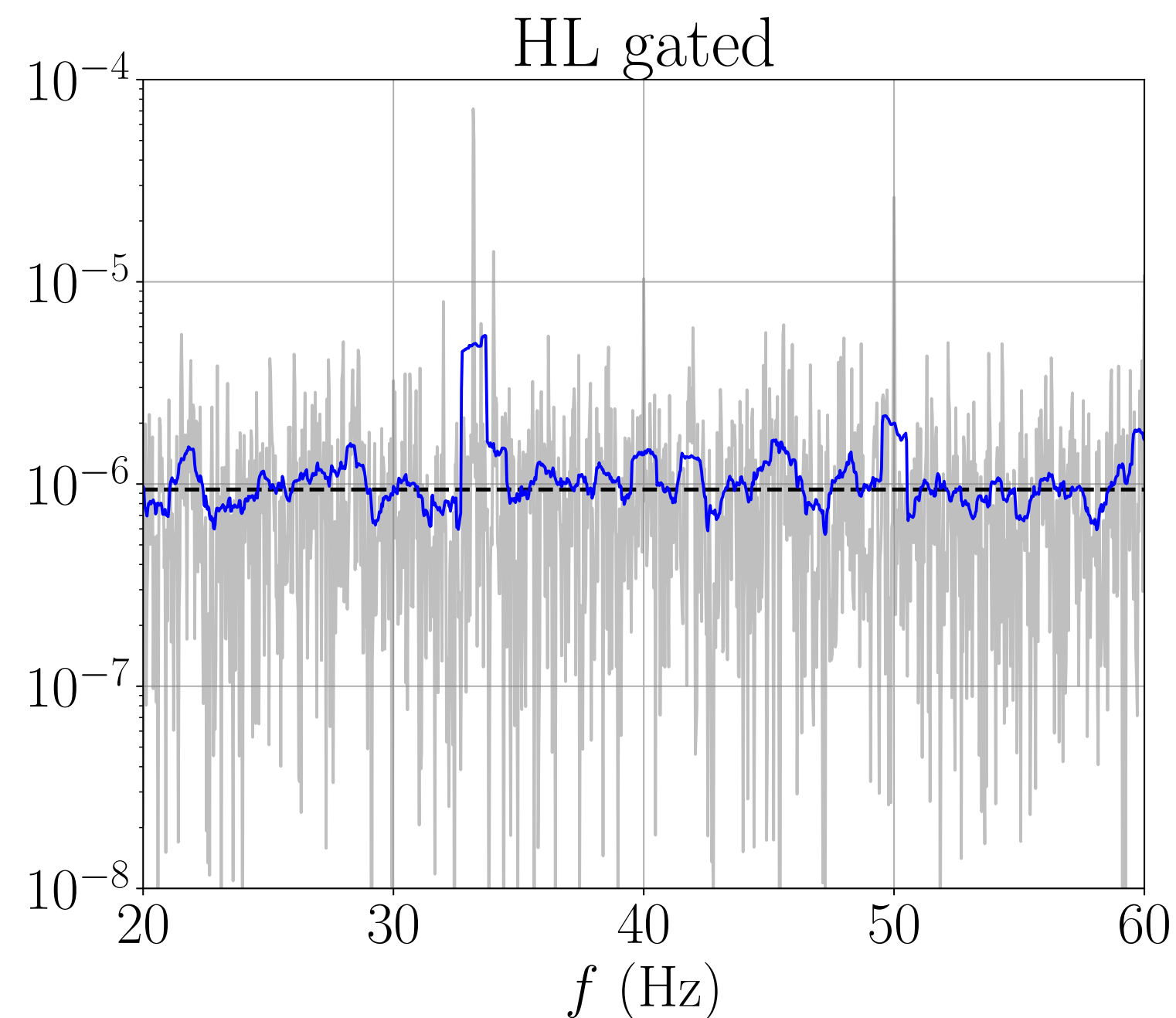
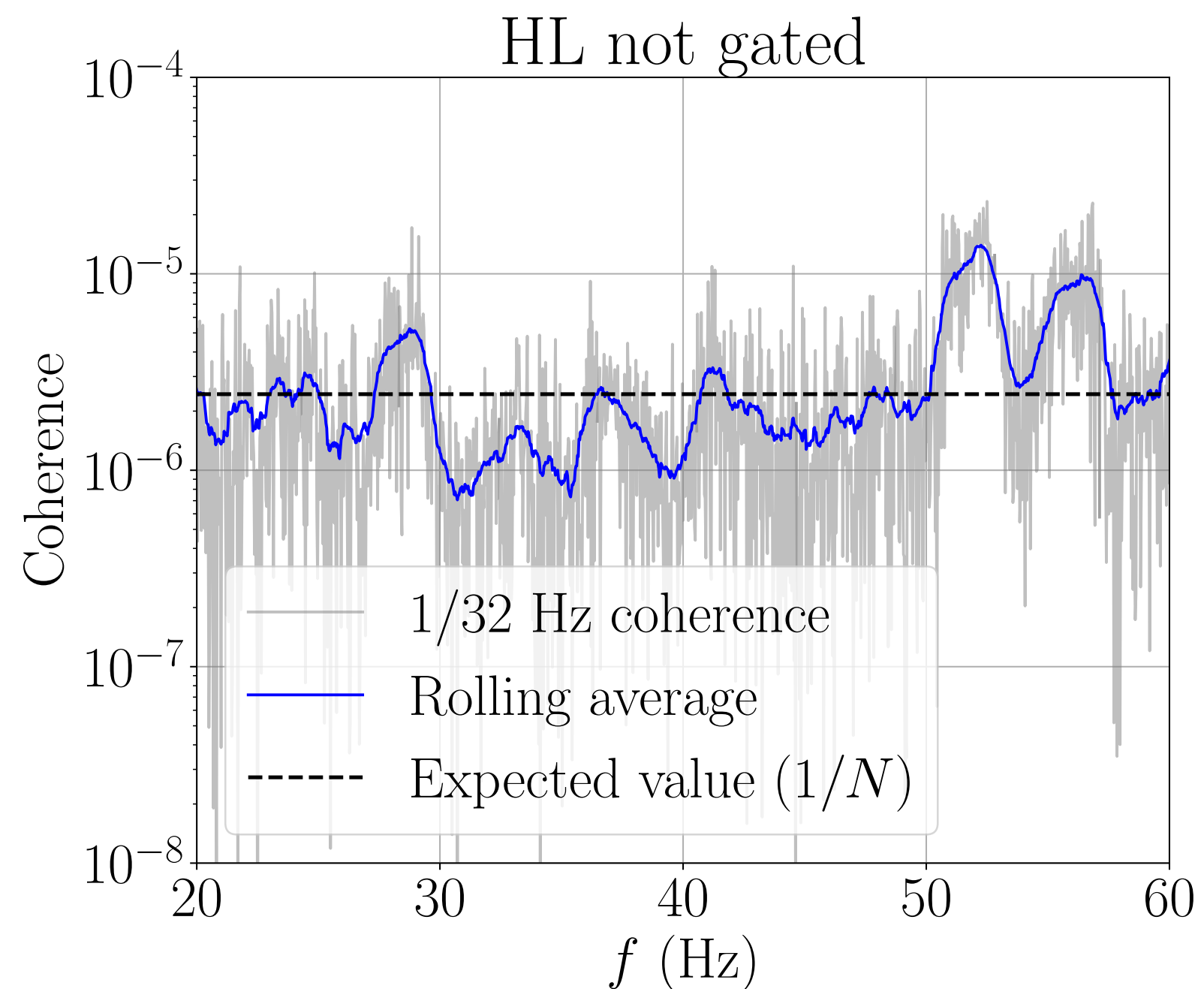
- power from strong “lines” (nx60 Hz, calibration, violin modes, ...) may leak into nearby freq bins
  - Hann window data, 50% overlap
  - notch lines in frequency domain
  - O3: lose 3.2% HL, 9.3% HV, 5.9% LV of freq band <300 Hz
- large glitches in LHO, LLO were an issue for O3:
  - $\Delta\sigma$  cut removes more than 50% of segments!!
  - “gating” required (notch bad data with inv Tukey window)
  - gating bad data leads to loss of only 0.4% of data for LHO, 1% for LLO (not needed for Virgo)
  - gating doesn’t introduce spurious correlations
- new features often arise with each observing run!!



# Example of gated vs non-gated data



[credit: LIGO P2000546-v2]

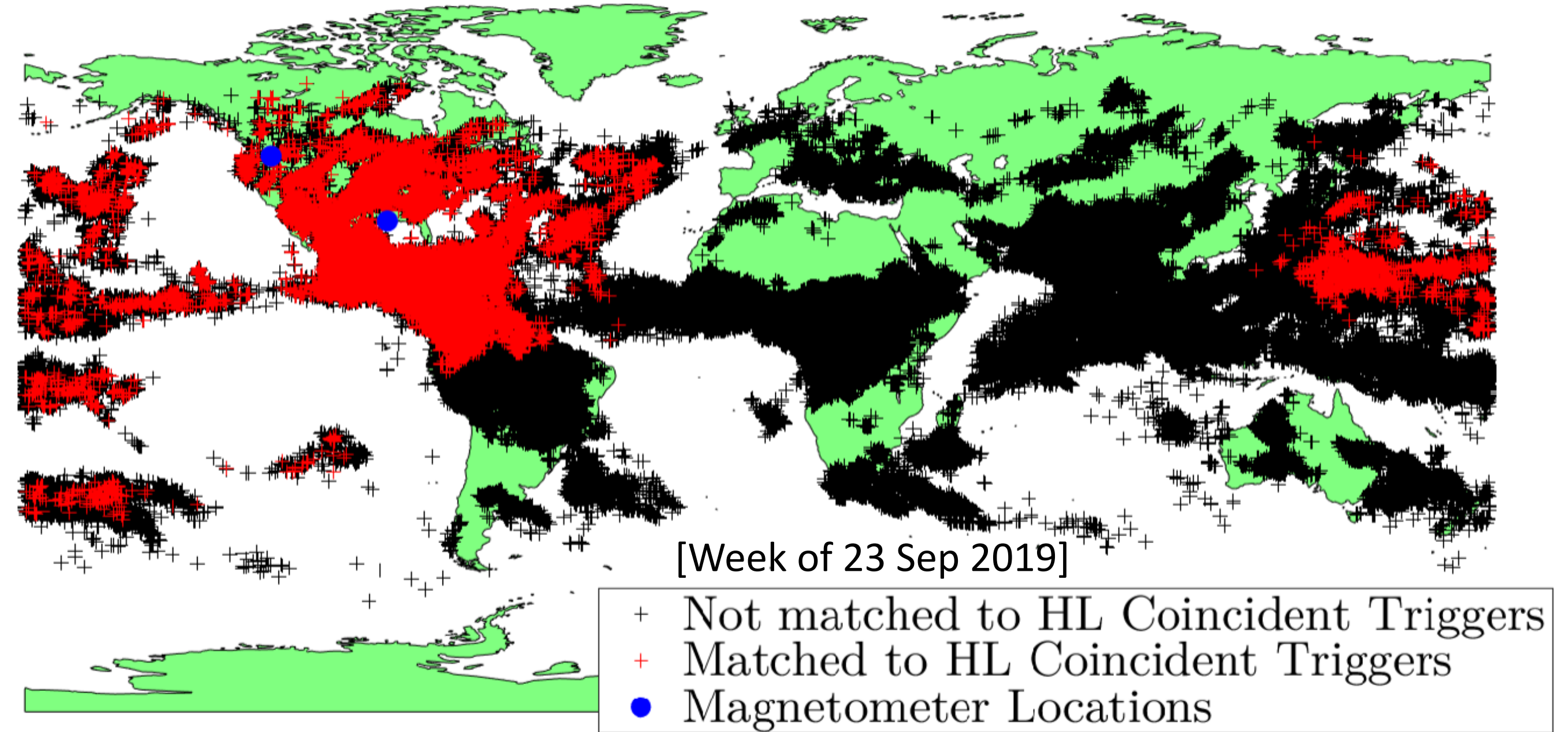


[credit: O3 isotropic paper]

$$\Gamma_{IJ} = \frac{\langle |\tilde{d}_I^*(f)\tilde{d}_J(f)|^2 \rangle}{\langle |\tilde{d}_I(f)|^2 \rangle \langle |\tilde{d}_J(f)|^2 \rangle}$$

# Challenge 4: potential contamination from correlated noise

- global magnetic field fluctuations are correlated across large distances
- monitored by low-noise magnetometers installed at each site
- past analyses calculated magnetic noise budget
- for O3, also calculated Bayes factor for “magnetic correlation” model



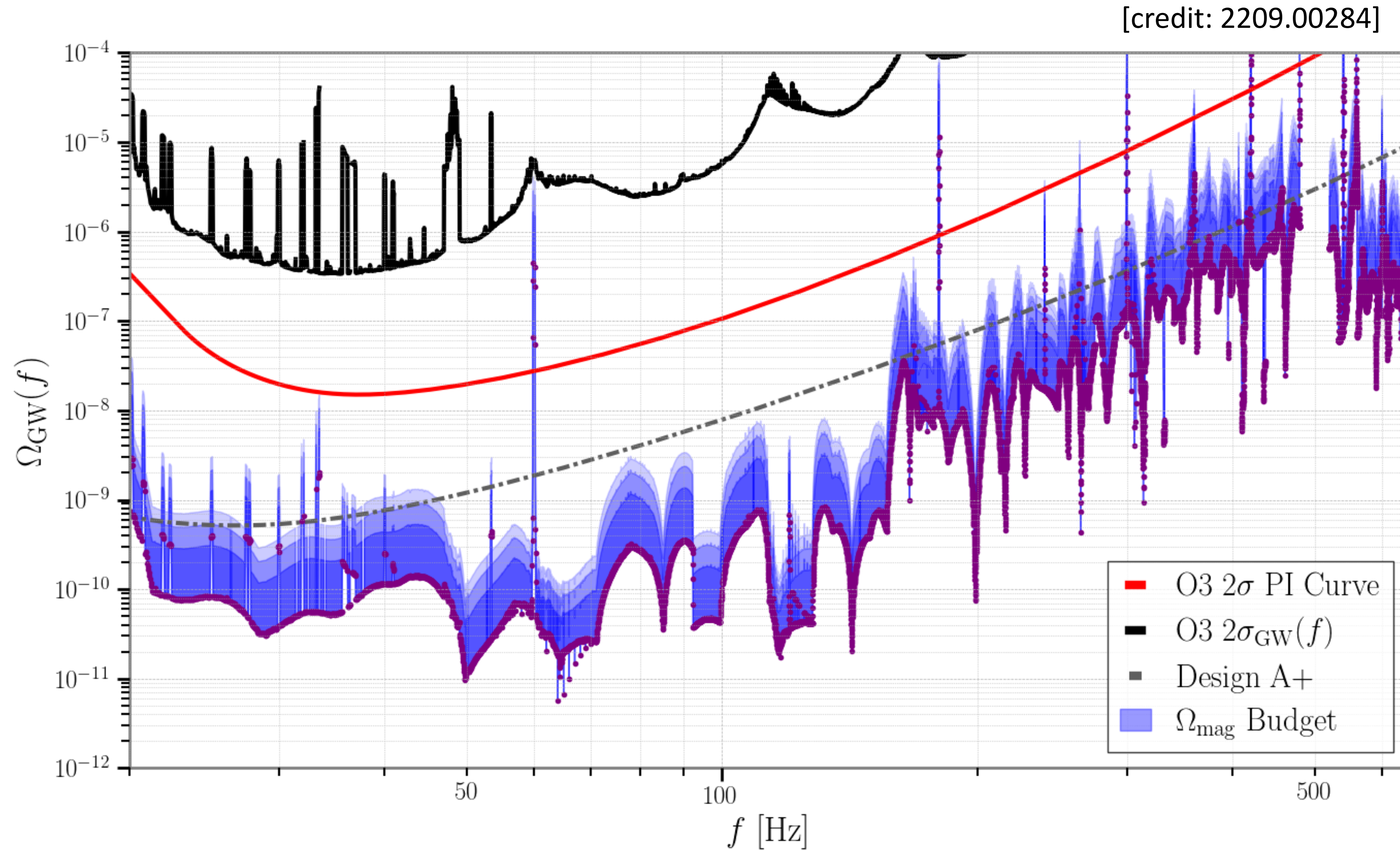
[credit: 2209.00284]

$$\hat{\Omega}_{\text{mag},IJ}(f | \vec{\lambda}) = \frac{2 |T_I(f)| |T_J(f)| \text{Re}[\tilde{m}_I^*(f) \tilde{m}_J(f)]}{T \gamma_{IJ}(f) S_0(f)}$$

$$T_I(f) = \kappa_I \left( \frac{f}{10 \text{ Hz}} \right)^{\beta_I}$$

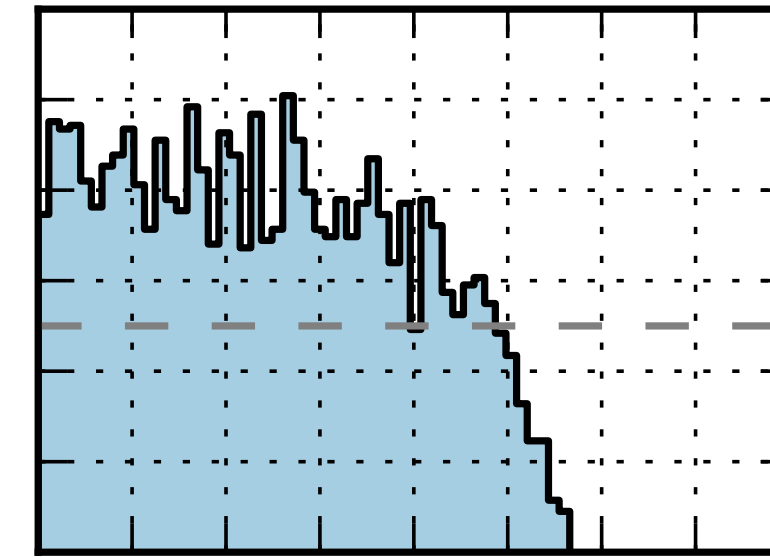
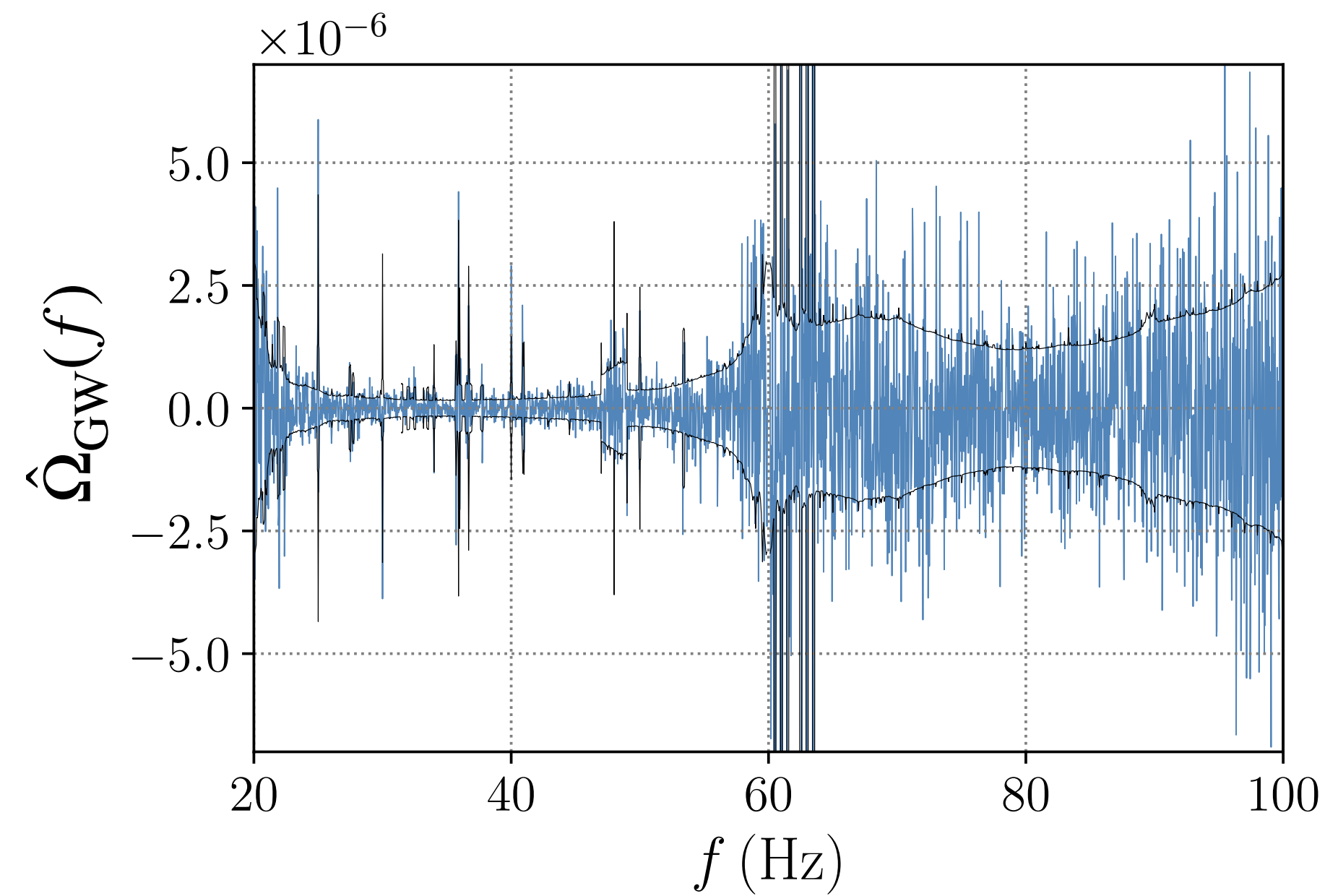
transfer function from  
magnetometer to GW channel

# magnetic noise budget (O3 and beyond)

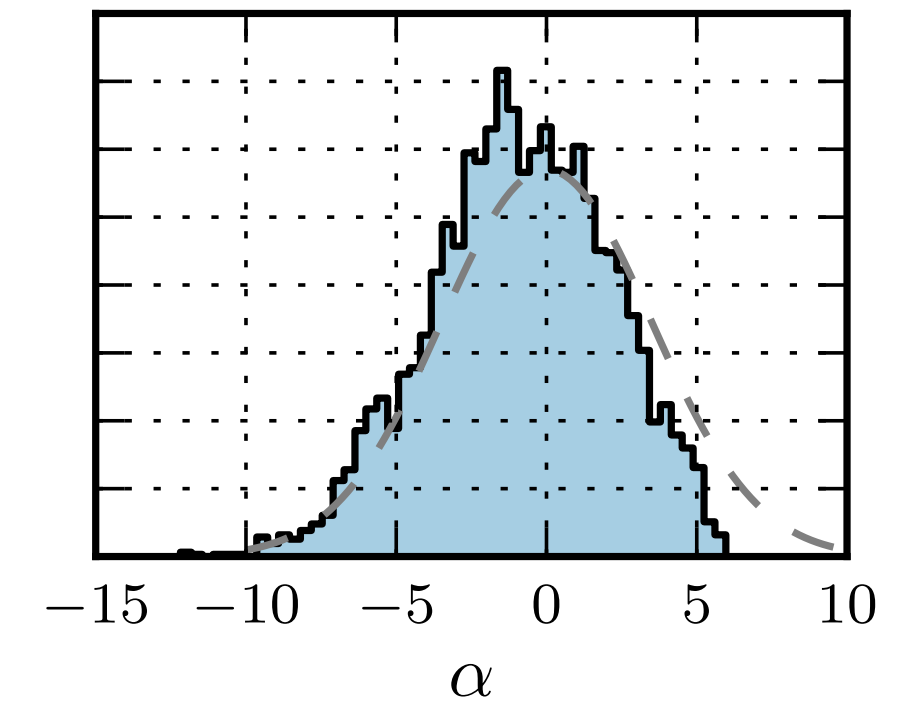
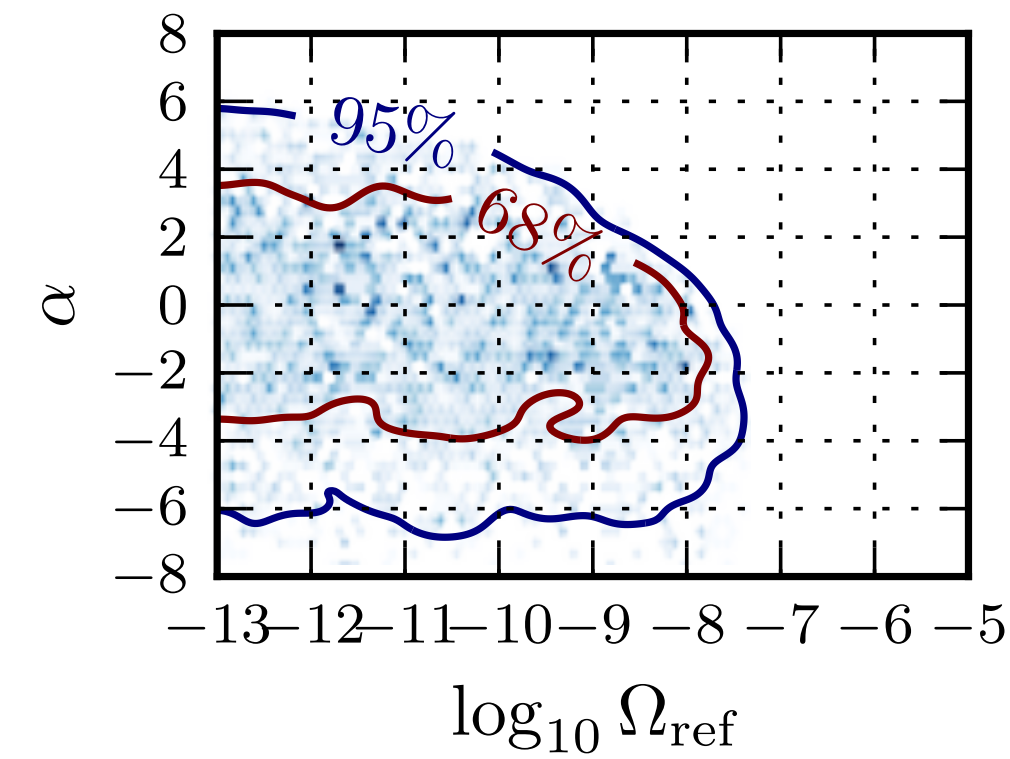


# O3 results (standard isotropic search; power law model)

H,L,V combined  $\hat{\Omega}_{\text{GW}}(f)$  cross-correlation spectrum



posterior for power law model

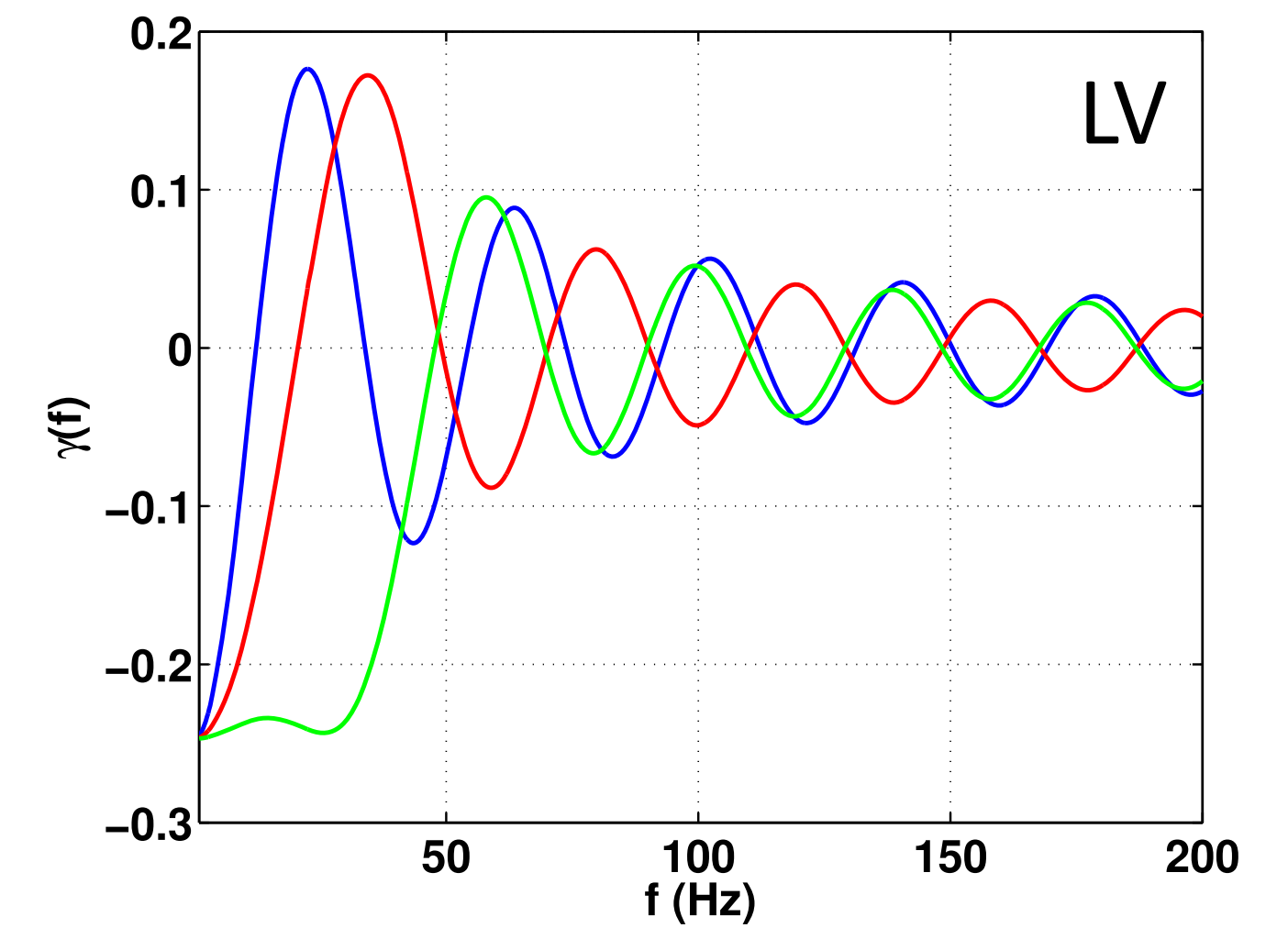
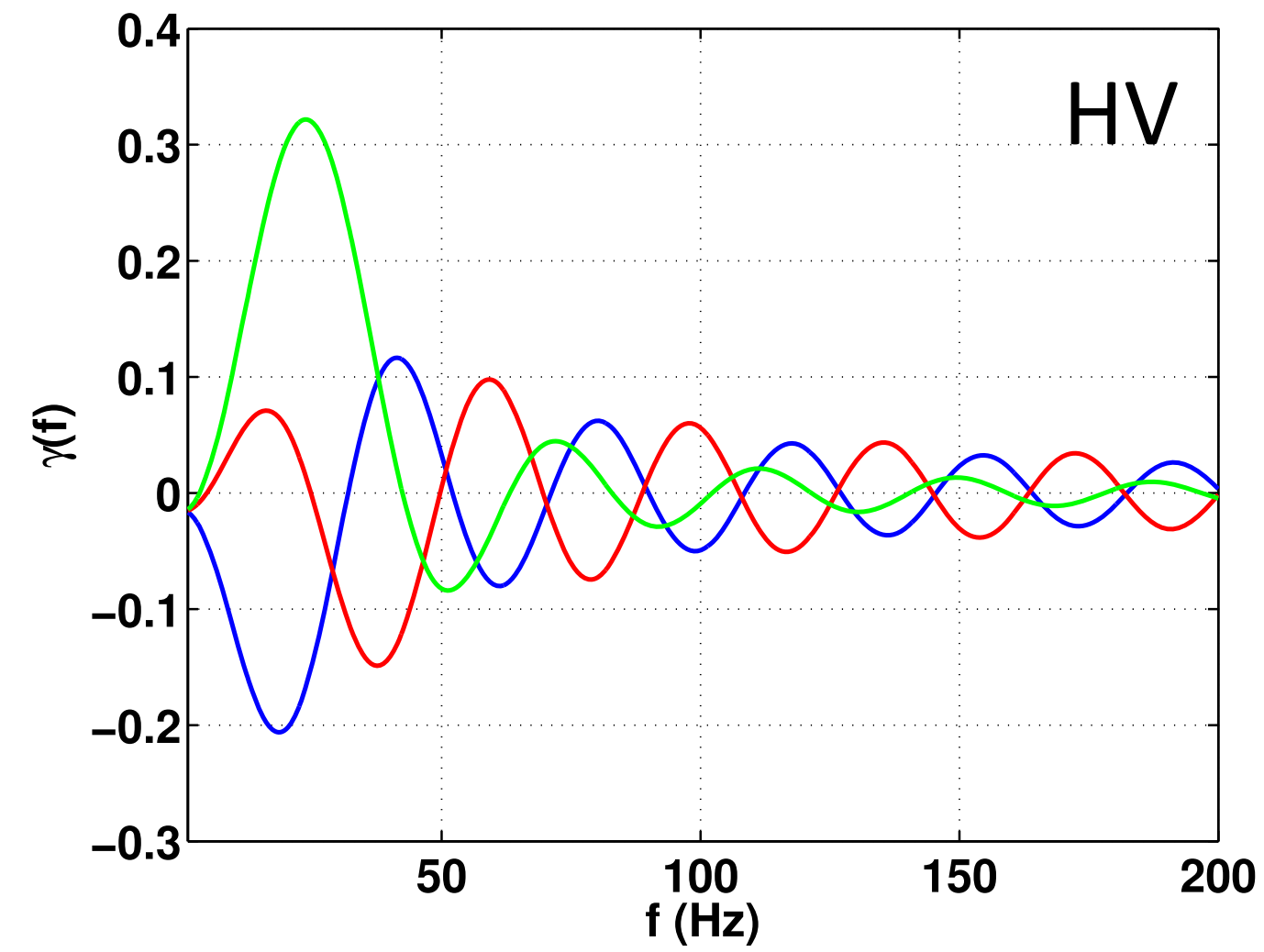
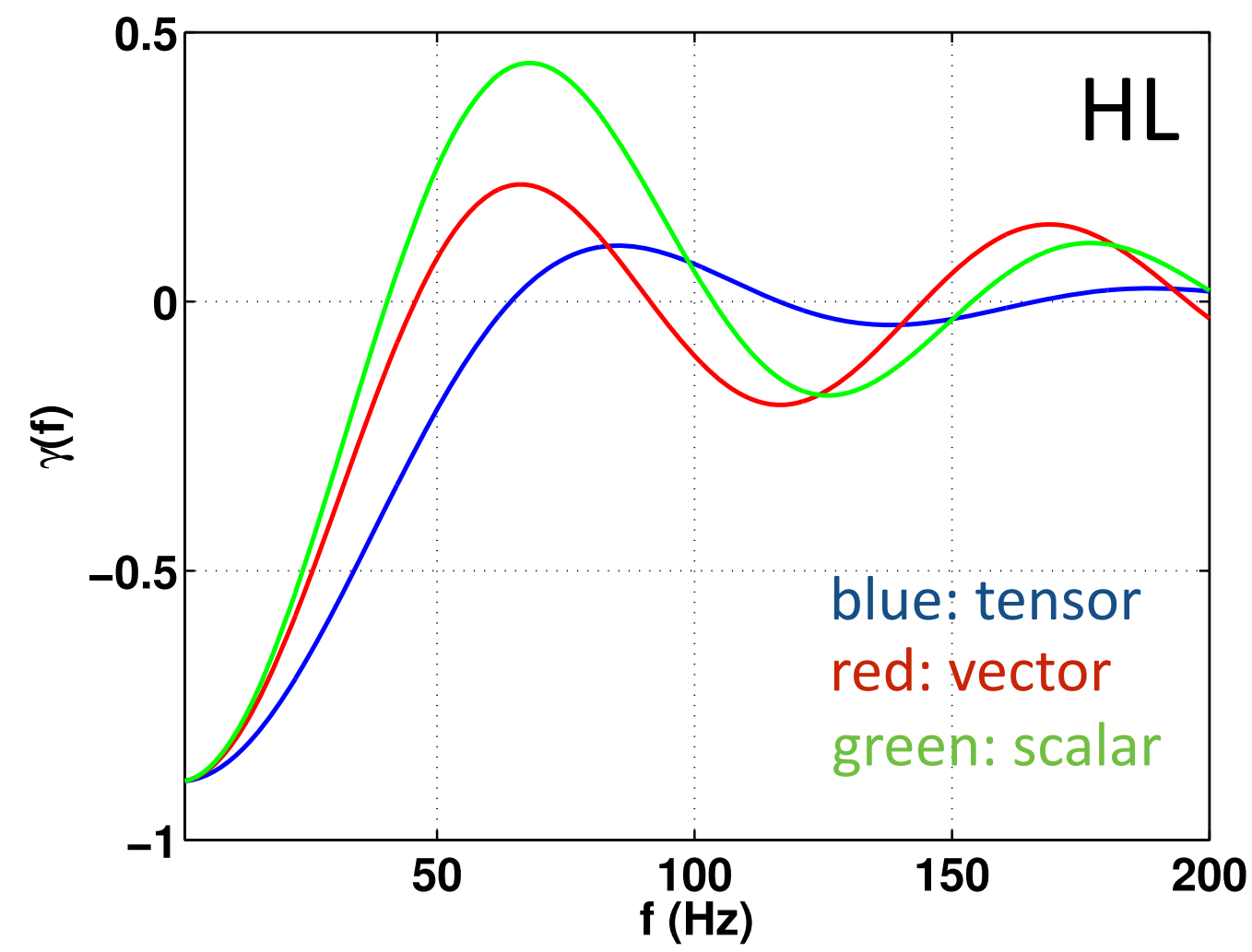


	Uniform prior			Log-uniform prior		
$\alpha$	O3	O2 [43]	Improvement	O3	O2 [43]	Improvement
ULs						
(95%)						
0	$1.7 \times 10^{-8}$	$6.0 \times 10^{-8}$	3.6	$5.8 \times 10^{-9}$	$3.5 \times 10^{-8}$	6.0
2/3	$1.2 \times 10^{-8}$	$4.8 \times 10^{-8}$	4.0	$3.4 \times 10^{-9}$	$3.0 \times 10^{-8}$	8.8
3	$1.3 \times 10^{-9}$	$7.9 \times 10^{-9}$	5.9	$3.9 \times 10^{-10}$	$5.1 \times 10^{-9}$	13.1
Marg.	$2.7 \times 10^{-8}$	$1.1 \times 10^{-7}$	4.1	$6.6 \times 10^{-9}$	$3.4 \times 10^{-8}$	5.1



# O3 results (search for alternative polarization modes)

- simple modification: just swap out tensor ORFs with vector and scalar ORFs

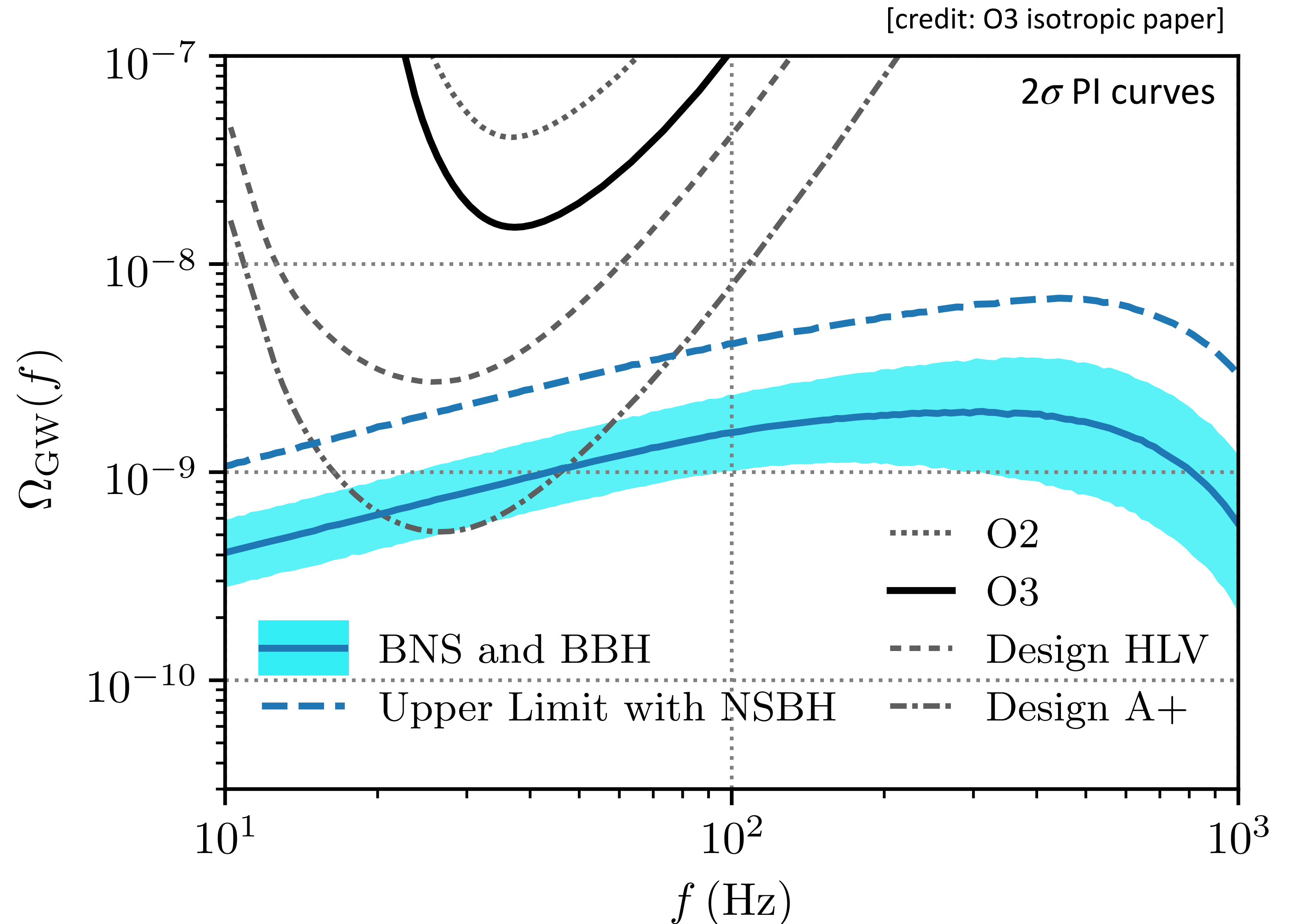


	Polarization	O3	O2 [43]	Improvement
ULs (95%)	Tensor	$6.4 \times 10^{-9}$	$3.2 \times 10^{-8}$	5.0
	Vector	$7.9 \times 10^{-9}$	$2.9 \times 10^{-8}$	3.7
	Scalar	$2.1 \times 10^{-8}$	$6.1 \times 10^{-8}$	2.9

[credit: O3 isotropic paper]

# O3 results (prospects for CBC background detection)

- detection of individual CBCs + assumptions about merger rate density -> revised estimate of CBC background
- CBC background probably not detectable by end of O4 unless new methods used (see Vuk's talk)



# O3 results (constraining the BBH merger rate history $R(z)$ )

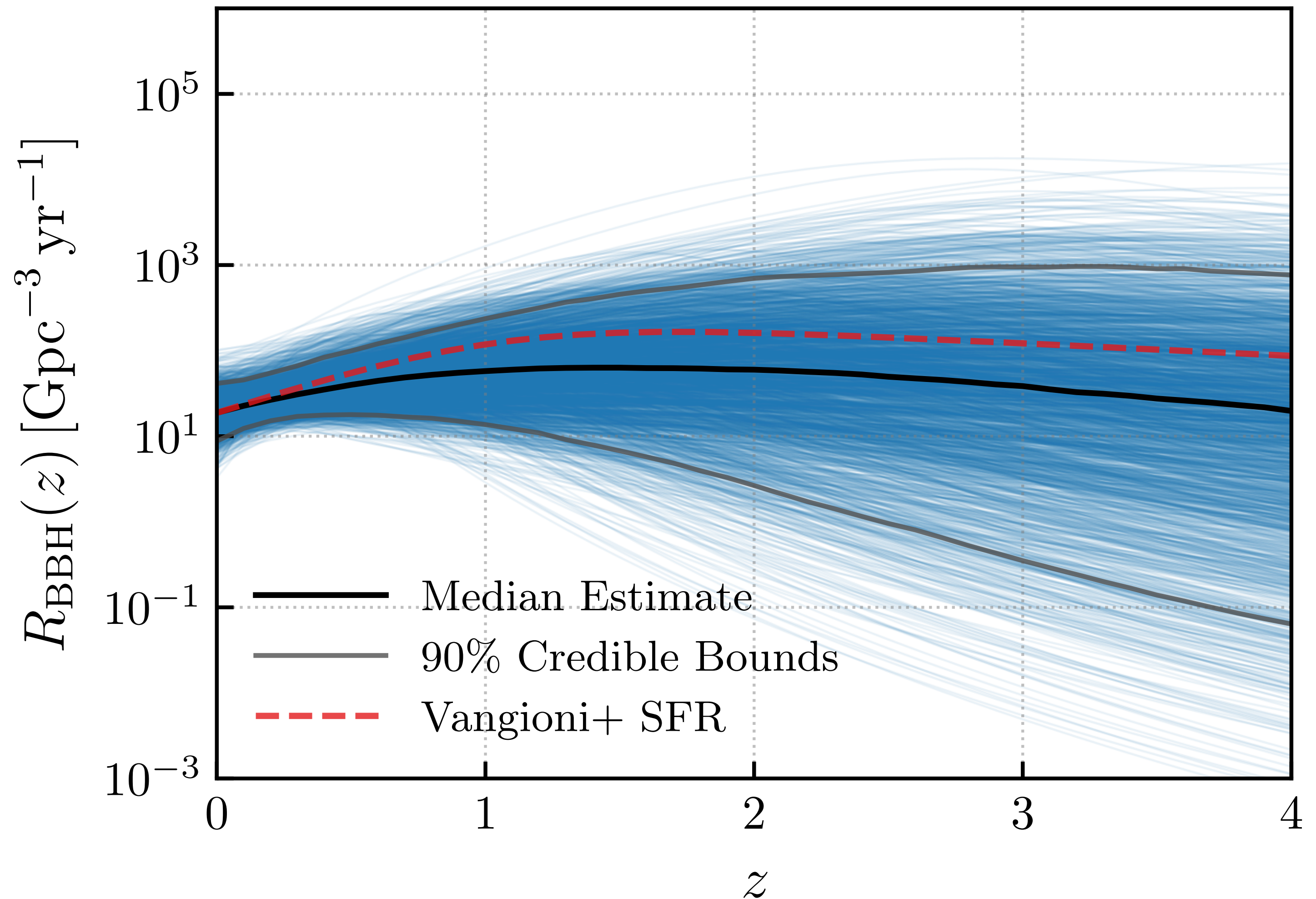
- constrain parameters describing BBH mass distribution and merger rate history using a joint CBC + stochastic analysis

[credit: O3 isotropic paper]

$p_{\text{BBH}}(\{d\} | \vec{\lambda}_{\text{BBH}}) p_{\text{stoch}}(\hat{\Omega}_{\text{GW}}^{IJ} | \vec{\lambda}_{\text{BBH}})$

↑  
evaluated using posterior samples for masses and redshifts of O3a BBH detections

↑  
parameters defining empirical form of BBH mass distribution and merger rate history



# Summary

1. even the “simplest” LVK search for an isotropic GWB has challenges
2. new challenges seem to arise with each observation run!!
3. nonetheless, improvements in detector -> lower ULs  
 $\Omega_{\text{gw}} \lesssim 10^{-9} - 10^{-8}$  (for O3) vs.  $\Omega_{\text{gw}} \lesssim 40$  (for S1, twenty years ago)
4. new search methods may be needed to accelerate detection (e.g., intermittent search for population of BBH mergers)