# Optimal Transport Wasserstein distance and <br> Hypothesis Testing 

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& Y_{1}, \ldots, Y_{m} \sim Q
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2. Should we use it for testing?

## The Wasserstein Distance

Assume that $P$ has a density (but not really required). The distance $W(P, Q)$ is defined by

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But what is the optimal transport map?

## Optimal Transport



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Can replace $(\cdots)^{2}$ with any cost.

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1. One dimension.

$$
T(x)=F_{1}^{-1}\left(F_{0}(x)\right)
$$

where

$$
F_{0}(t)=P_{0}(X \leq t) \text { and } F_{1}(t)=P_{1}(X \leq t)
$$



## What T?

2. If $P_{0}=N\left(\mu_{0}, \Sigma_{0}\right)$ and $P_{1}=N\left(\mu_{1}, \Sigma_{1}\right)$ then:

$$
T(x)=\mu_{1}+\Sigma_{1}^{1 / 2} \Sigma_{0}^{-1 / 2}\left(x-\mu_{0}\right)
$$

What $T$ ?

## What T?

3. Data clouds: $X_{1}, \ldots, X_{n}$ and $Y_{1}, \ldots, Y_{n}$. Then $T\left(X_{i}\right)=Y_{\pi(i)}$ where $\pi$ is the permutation that minimizes

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\sum_{i}\left\|X_{i}-Y_{\pi(i)}\right\|^{2}
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Brenier's theorem: $T=\nabla \phi$ where $\phi$ is the convex function that maximizes

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where $\phi^{*}(x)=\sup _{u}\{\langle x, u\rangle-\phi(u)\}$.
Now parameterize $\phi_{\theta}$ using a (convex) neural net.

What if there is no such $T$ ?: More General Definition

The distance $W(P, Q)$ is defined by

$$
W^{2}(P, Q)=\inf _{\pi} \mathbb{E}_{\pi}\|X-Y\|^{2}
$$

where

$$
\begin{aligned}
& X \sim P \\
& Y \sim Q
\end{aligned}
$$

and the infimum is over all joint distributions $\pi$ with marginals $P$ and $Q$.

## Optimal Transport



Joint distribution $\pi$ with a given $X$ marginal and a given $Y$ marcinal Imaro crodit. M/ikinodia

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Why use Wasserstein?
It has nice properties ...

## Wasserstein versus $\int|p-q|^{2}$ (image from Santambrogio)



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Wasserstein distance is geometry sensitive.
Let $P$ be a point mass $x$. Let $Q$ be a point mass $y$.
$K S(P, Q)=1$.
$W(P, Q)=|x-y|$
Suggests that this may have more power for certain deviations from the null.

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The solution is

$$
B=N(0,1)
$$

## Connection to Fluid Dynamics

$$
W^{2}(P, Q)=\min _{v} \int_{0}^{1} \int\|v(x, t)\|^{2} \rho_{t}(x) d x d t
$$

where

$$
\begin{aligned}
& \rho_{0}=P_{0} \\
& \rho_{1}=P_{1}
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$$

and

$$
\partial_{t} \rho_{t}+\nabla\left(\rho_{t} v_{t}\right)=0
$$

## Negative Sobolov Norm

$$
c\|p-q\|_{\dot{H}^{-1}} \leq W(P, Q) \leq C\|p-q\|_{\dot{H}^{-1}}
$$

where

$$
\|f\|_{\dot{H}^{-1}}=\sup \left\{\int g f: \int|\nabla g|^{2} \leq 1\right\}
$$

## How Do We Estimate $W(P, Q)$ ?

Plugin estimator: Estimate $W(P, Q)$ with

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\widehat{W}=W\left(P_{n}, Q_{n}\right)
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where $P_{n}$ is the empirical distribution of the data that puts mass $1 / n$ at each $X_{i} . Q_{n}$ is the empirical distribution of the data that puts mass $1 / n$ at each $Y_{i}$.

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Two problems:

1. This is slow.
2. $\widehat{W}$ is a poor estimate of $W$ :

$$
\widehat{W}-W=O\left(n^{-1 / d}\right)
$$

where $d=$ the dimension of $X$.

## Better estimator

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where $T \in \operatorname{Holder}(\alpha)$.
If $\alpha+1>d / 2$ then

$$
\sqrt{n}\left(\widehat{W}^{2}-W^{2}\right) \rightsquigarrow N\left(0, \sigma^{2}\right)
$$

which can simplify inference.
(Manole et al arXiv:2107.12364)

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