



# Vertex fitting update



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FCC software meeting

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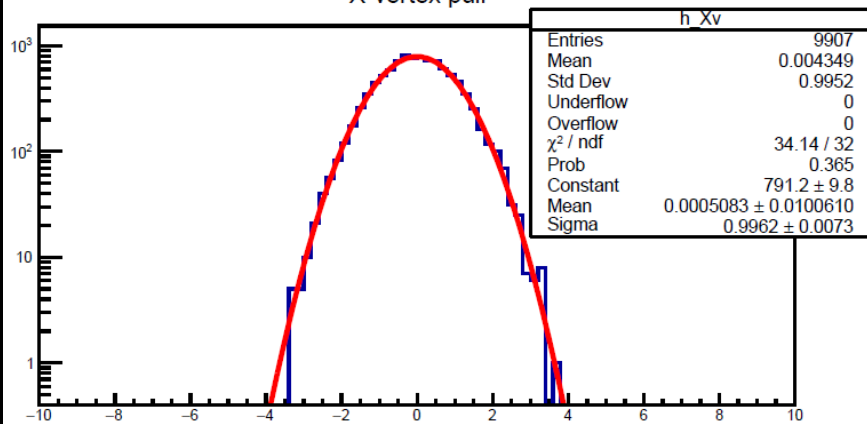
## OUTLINE

- ❖ **Primary vertex finding/fitting**
- ❖  **$B_s \rightarrow D_s \pi$  example**

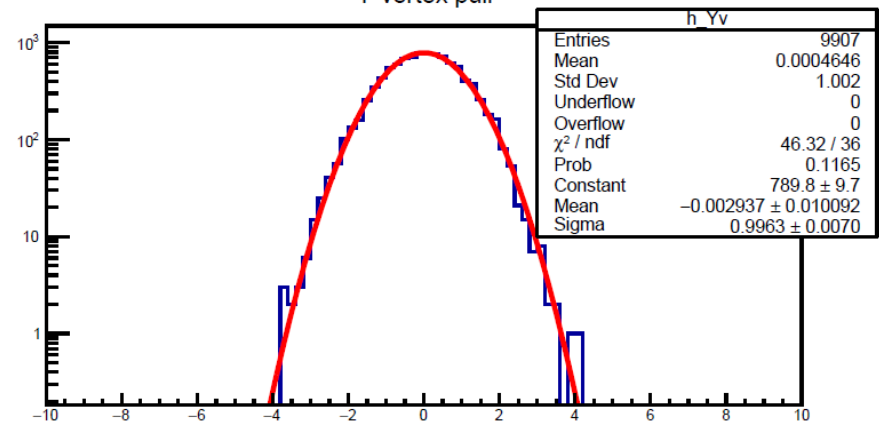
## ❖ Vertex fit with external beam spot constraint

```
//  
// Fit primary vertex with beam constraint  
//  
Int_t MinTrk = 1; // Minimum # tracks for vertex fit  
if (Ntr >= MinTrk) {  
→ VertexFit* Vtx = new VertexFit(Ntr, pr, cv);  
→ Vtx->AddVtxConstraint(xpvc, covpvc);  
→ TVectorD xvtx = Vtx->GetVtx();  
  delete Vtx;  
}
```

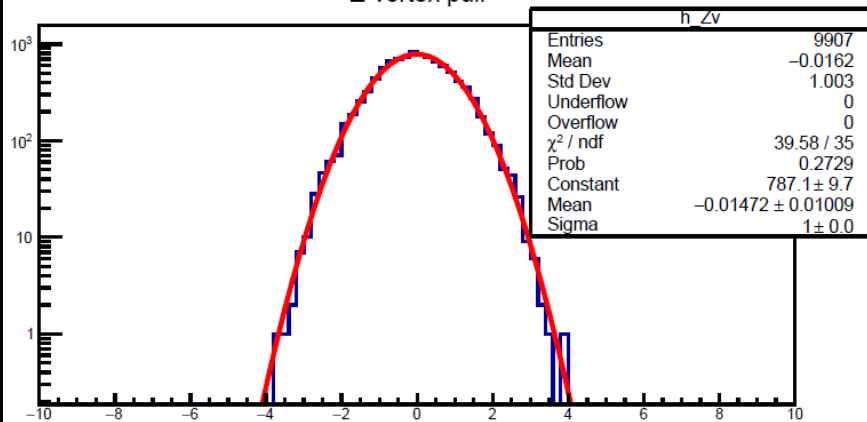
X-vertex pull



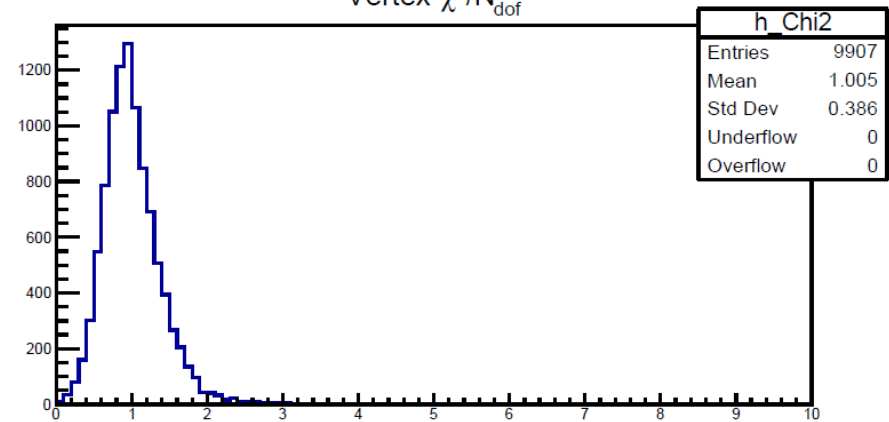
Y-vertex pull



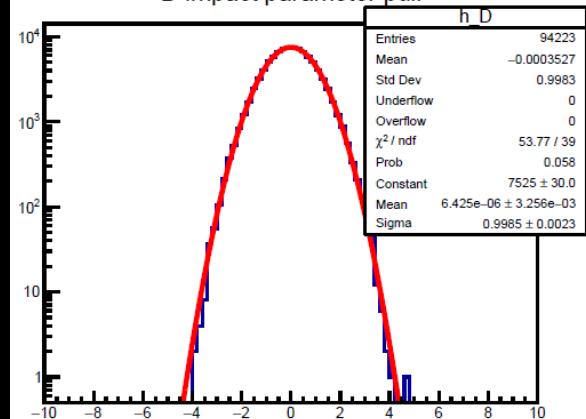
Z-vertex pull



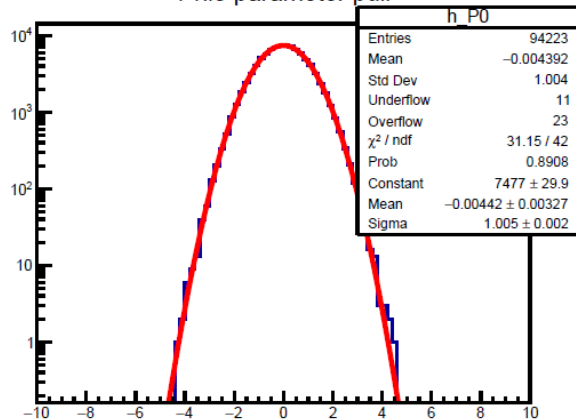
Vertex  $\chi^2/N_{\text{dof}}$



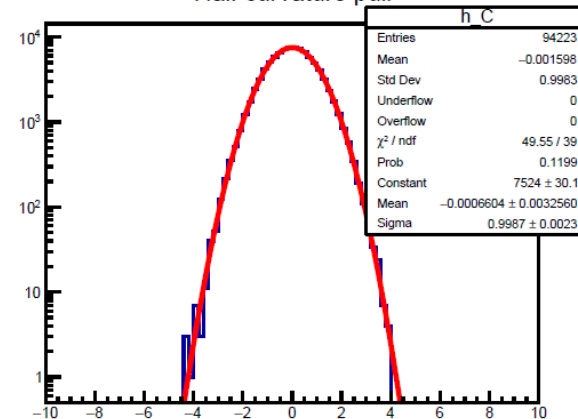
D impact parameter pull



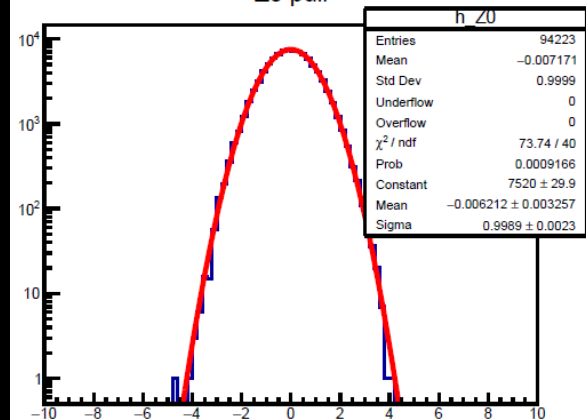
Phi0 parameter pull



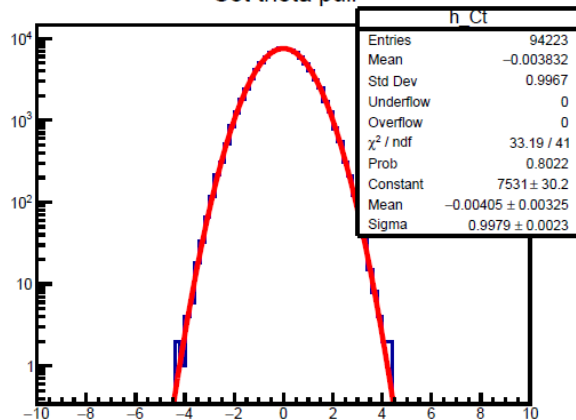
Half curvature pull



Z0 pull



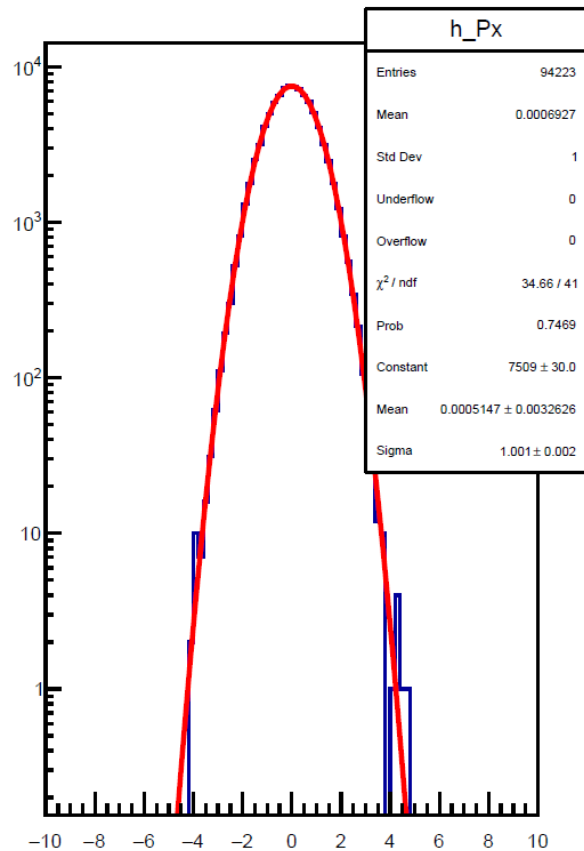
Cot theta pull



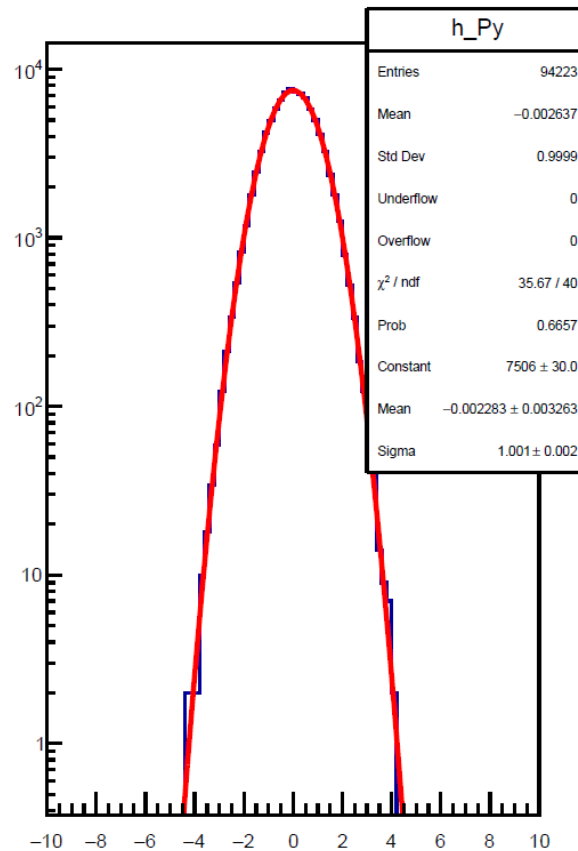
## ❖ Get track momenta at vertex

```
Bool_t Mm = kTRUE;  
→ VertexMore* Vmore = new VertexMore(Vfit, Mm);  
  //  
  // Get fit momenta momenta  
  //  
→ TVector3 pRec = Vmore->GetMomentum(i);  
→ TMatrixDSym pCov = Vmore->GetMomentumC(i);
```

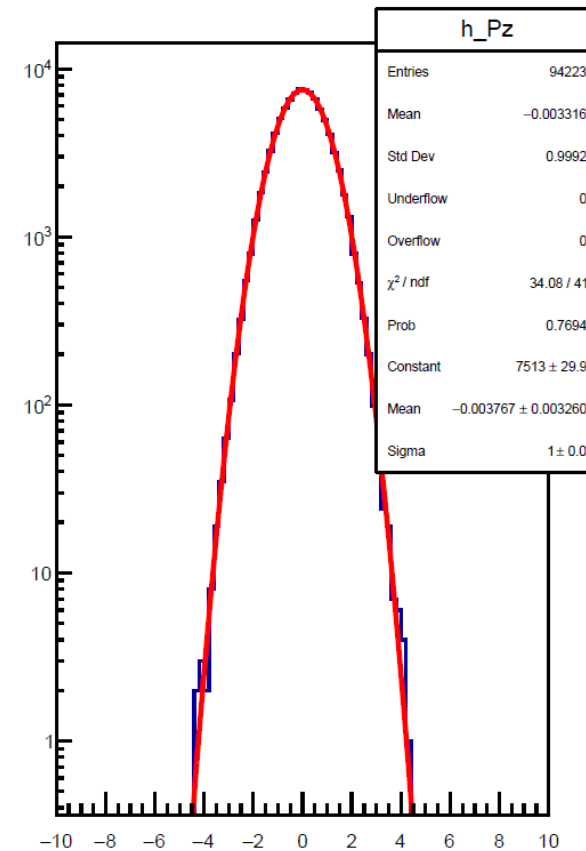
Momentum x pull



Momentum y pull



Momentum z pull



## ❖ Skim tracks

```

//
// Skim tracks
Int_t nSkim = 0;
Int_t* nSkimmed = new Int_t[NtrG];
TVectorD** PrSk = new TVectorD * [1];
TMatrixDSym** CvSk = new TMatrixDSym * [1];
Double_t MaxChi2 = 9.;
for (Int_t n = 0; n < NtrG; n++) {
    PrSk[0] = new TVectorD(*pr[n]);
    CvSk[0] = new TMatrixDSym(*cv[n]);
    VertexFit* Vskim = new VertexFit(1,PrSk, CvSk);
    Vskim->AddVtxConstraint(xpvc, covpvc);
    Double_t Chi2One = Vskim->GetVtxChi2();
    if(fprvx[n])hChi2SngP->Fill(Chi2One);
    else hChi2SngN->Fill(Chi2One);
    //
    if (Chi2One < MaxChi2) {
        nSkimmed[nSkim] = n;
        nSkim++;
    }
}

```

## ❖ Fit skimmed

```

//
// Load tracks for primary fit
Int_t MinTrk = 1; // Minumum # tracks for vertex fit
std::vector<Int_t> trnum;
if (nSkim >= MinTrk) {
    TVectorD** PrFit = new TVectorD * [nSkim];
    TMatrixDSym** CvFit = new TMatrixDSym * [nSkim];
    for (Int_t n = 0; n < nSkim; n++) {
        PrFit[n] = new TVectorD(*pr[nSkimmed[n]]);
        CvFit[n] = new TMatrixDSym(*cv[nSkimmed[n]]);
        trnum.push_back(nSkimmed[n]);
    }
    delete[] nSkimmed;
    Int_t Nfound = nSkim;
    if(entry%500 ==0)std::cout << "Found tracks " << Nfound << std::endl;
    const Int_t MaxFound = 100;
    Double_t Chi2LL[MaxFound]; Double_t *Chi2L = Chi2LL;
    VertexFit* Vtx = new VertexFit(nSkim, PrFit, CvFit);
    //std::cout << "Vertex fit created " << std::endl;
    Vtx->AddVtxConstraint(xpvc, covpvc);
}

```



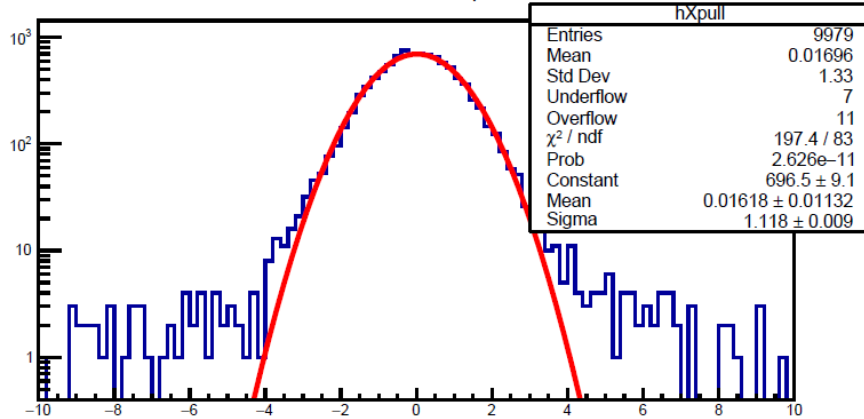
## ❖ Remove iteratively large Chi2 contributions

```

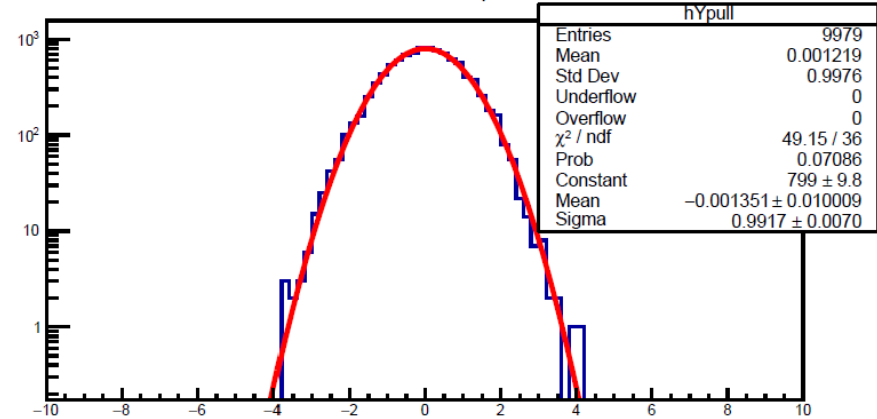
//
// Remove tracks with large chi2
Double_t MaxChi2Fit = 8.0;
Bool_t Done = kFALSE;
while (!Done) {
    // Find largest Chi2 contribution
    TVectorD Chi2List = Vtx->GetVtxChi2List(); // Get contributions to Chi2
    Chi2L = Chi2List.GetMatrixArray();
    Int_t iMax = TMath::LocMax(Nfound, Chi2L);
    Double_t Chi2Mx = Chi2L[iMax];
    if(fprvx[trnum[iMax]])hChi2MaxP->Fill(Chi2Mx);
    else hChi2MaxN->Fill(Chi2Mx);
    if (Chi2Mx > MaxChi2Fit && Nfound > 1) {
        Vtx->RemoveTrk(iMax);
        trnum.erase(trnum.begin() + iMax);
        Nfound--;
    }
    else {
        Done = kTRUE;
    }
}

```

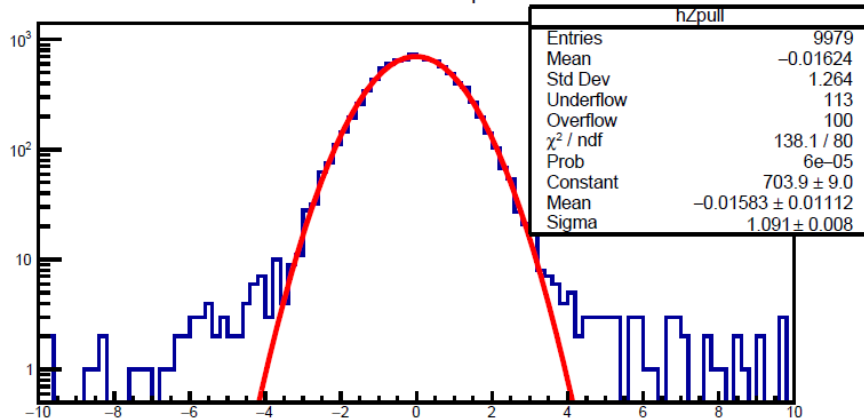
Pull X vertex component



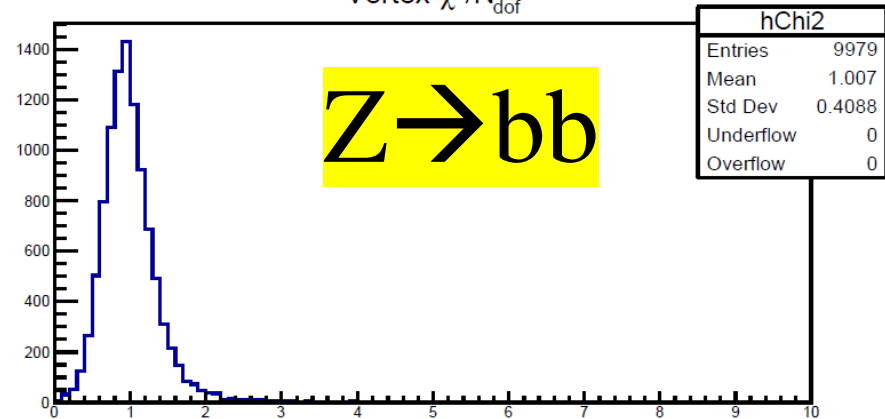
Pull Y vertex component



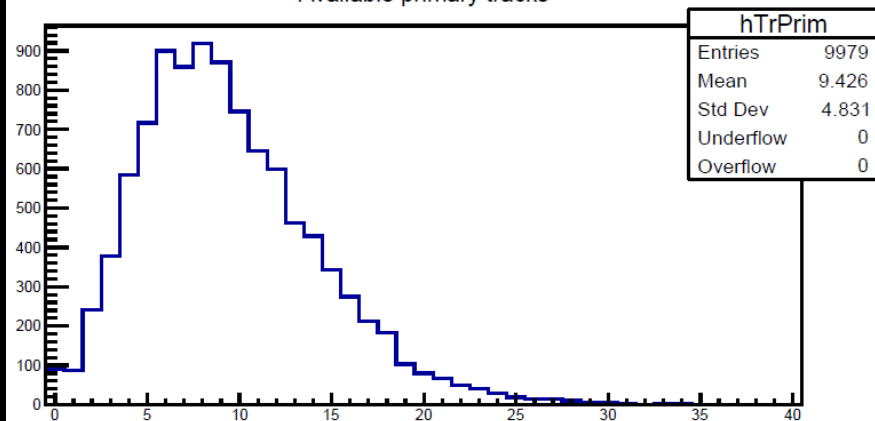
Pull Z vertex component



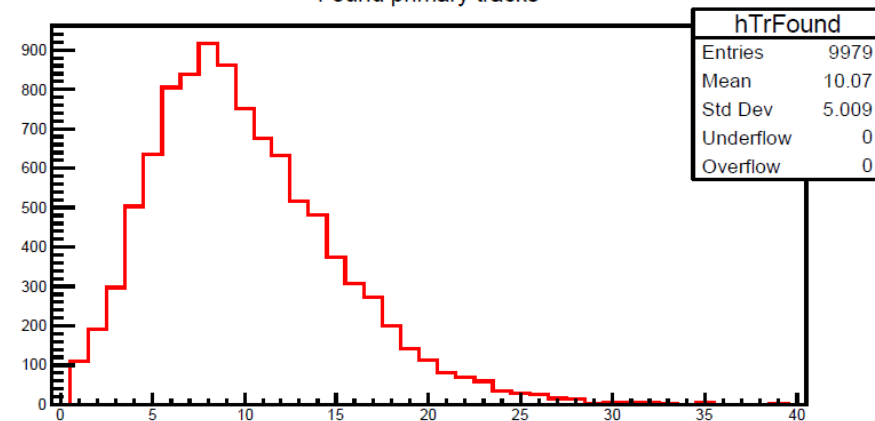
Vertex  $\chi^2/N_{\text{dof}}$



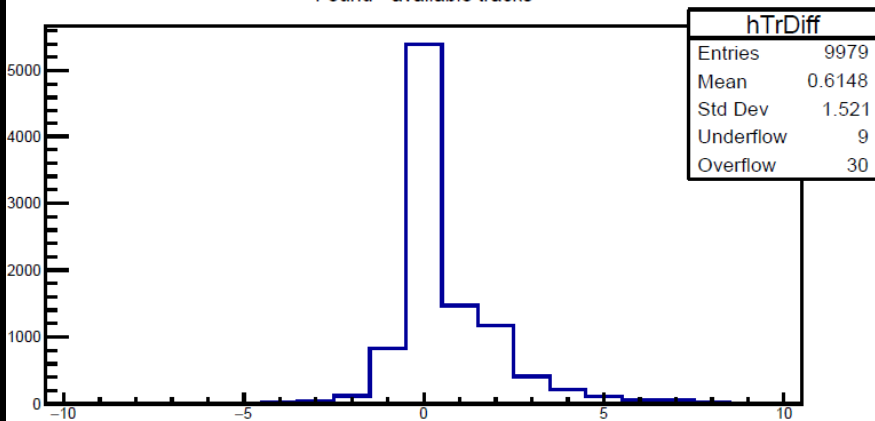
Available primary tracks



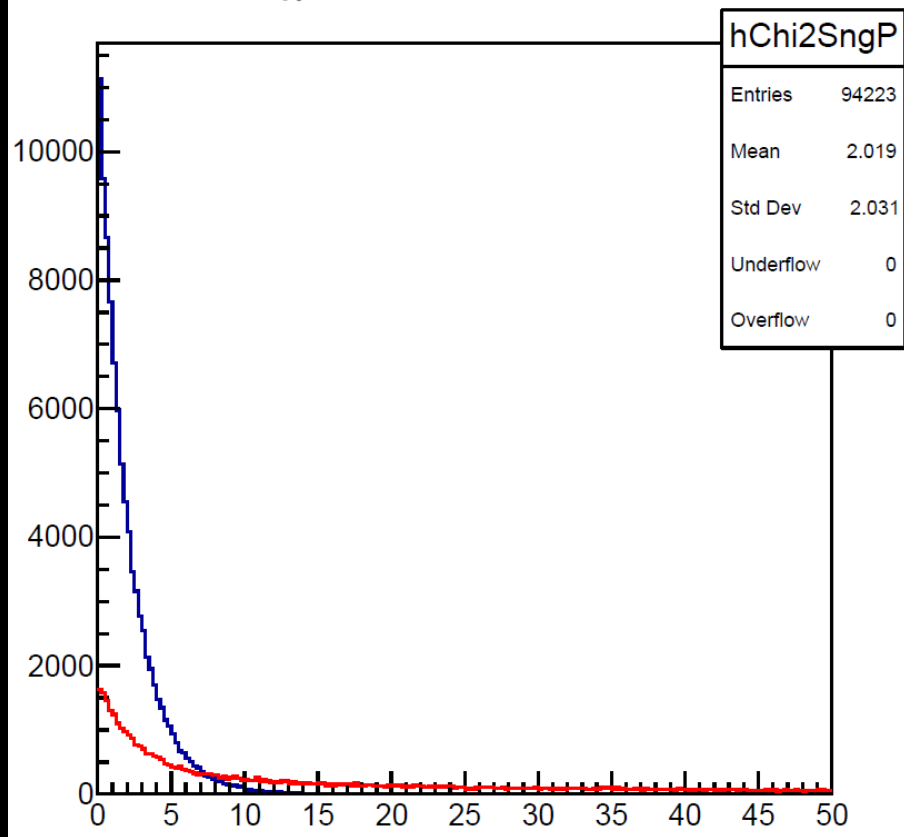
Found primary tracks



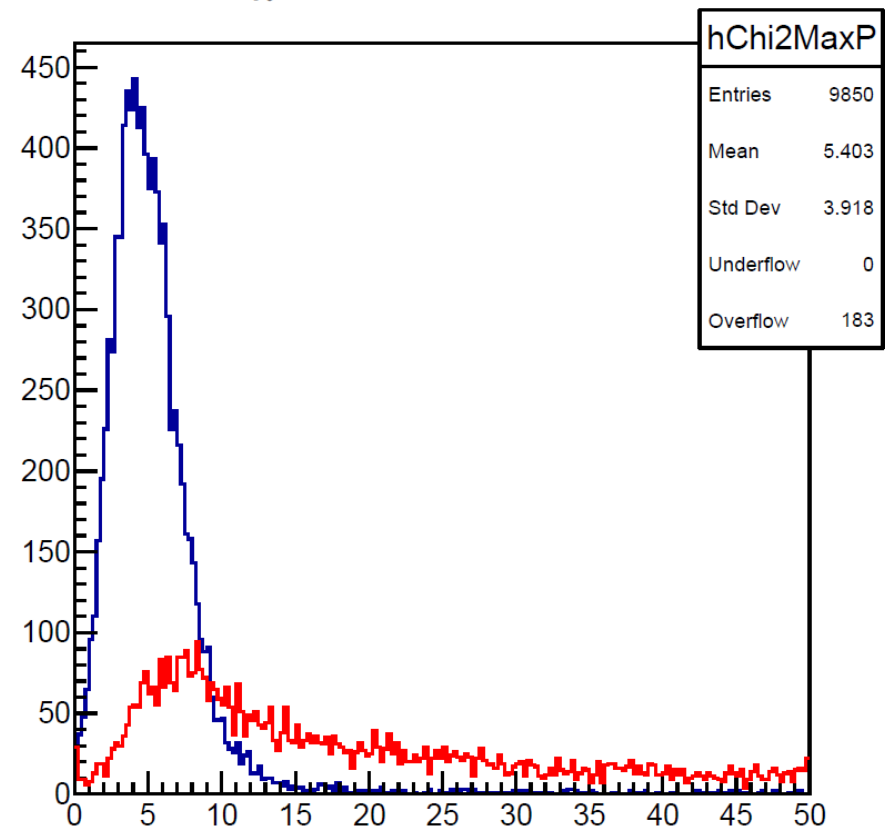
Found - available tracks



$\chi^2$  for single tracks



$\chi^2$  max contribution



```

// Fit Ds vertex
VertexFit* vDs = new VertexFit(nDsT, tDsPar, tDsCov);
Double_t DsChi2 = vDs->GetVtxChi2(); // Ds fit Chi2

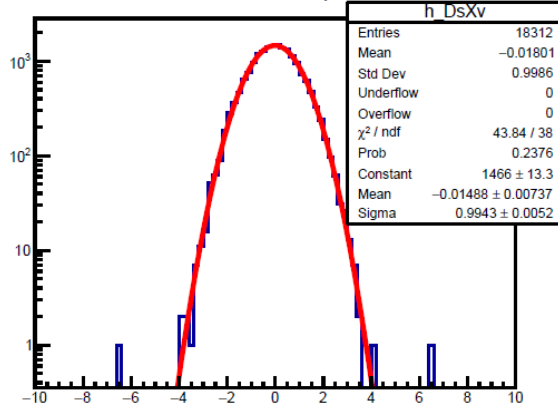
```

```

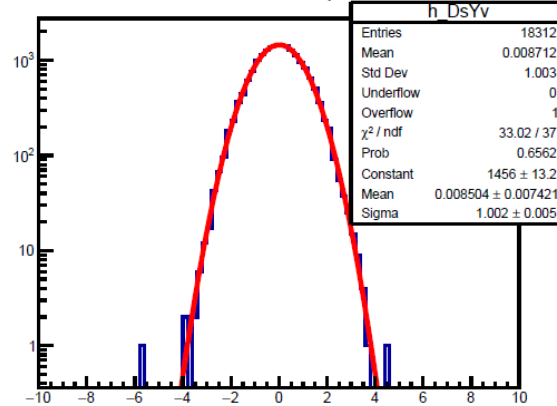
// More fitting
Bool_t Units = kTRUE; // Set to mm
VertexMore* VMDs = new VertexMore(vDs, Units);
// Mass constraint if requested
Bool_t MCst = kTRUE; // Mass constraint flag
if(MCst){
    Double_t DsMass = pBsDs->Mass; // Ds mass
    Double_t DsMasses[nDsT]; Int_t DsList[nDsT];
    for(Int_t k=0; k<nDsT; k++){
        DsMasses[k] = pDs[k]->Mass;
        DsList[k] = k;
    }
    VMDs->AddMassConstraint(DsMass, nDsT, DsMasses, DsList);
    VMDs->MassConstrFit();
}
TVectorD rDv = VMDs->GetXv(); // Ds vertex

```

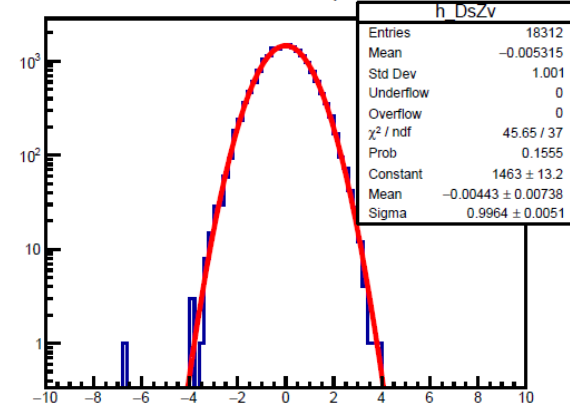
Ds X-vertex pull



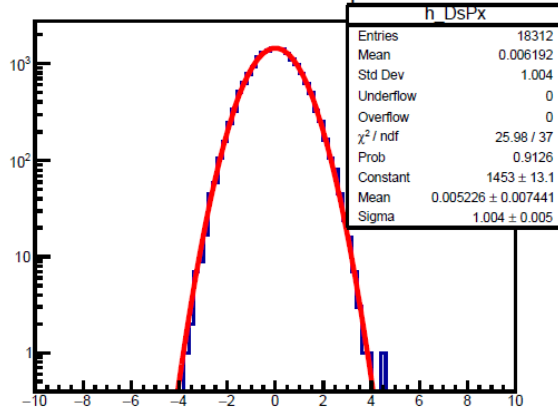
Ds Y-vertex pull



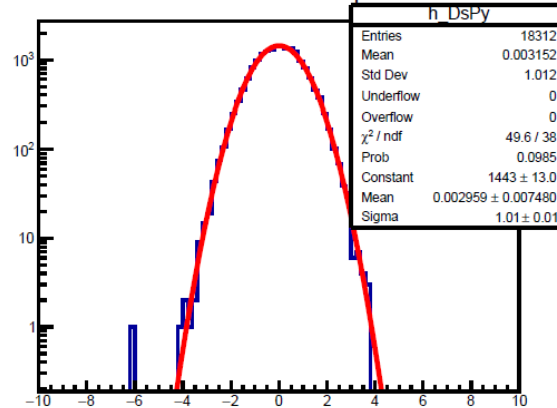
Ds Z-vertex pull



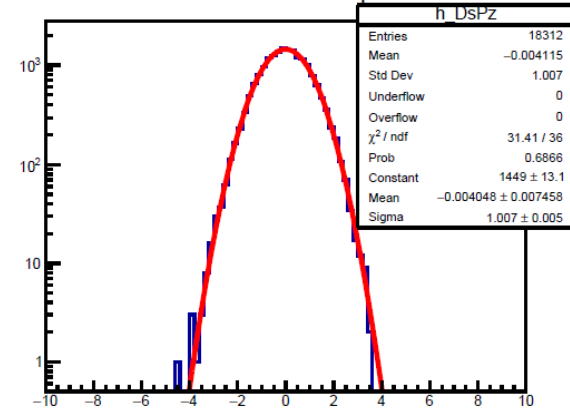
Ds X-momentum pull



Ds Y-momentum pull



Ds Z-momentum pull

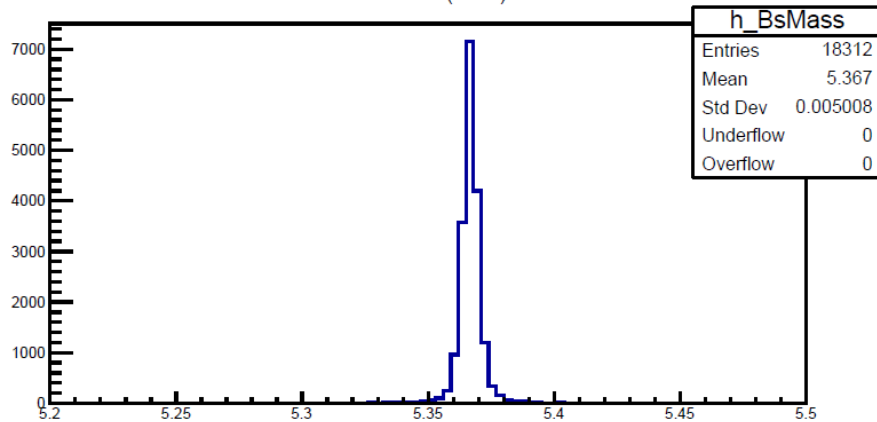


```

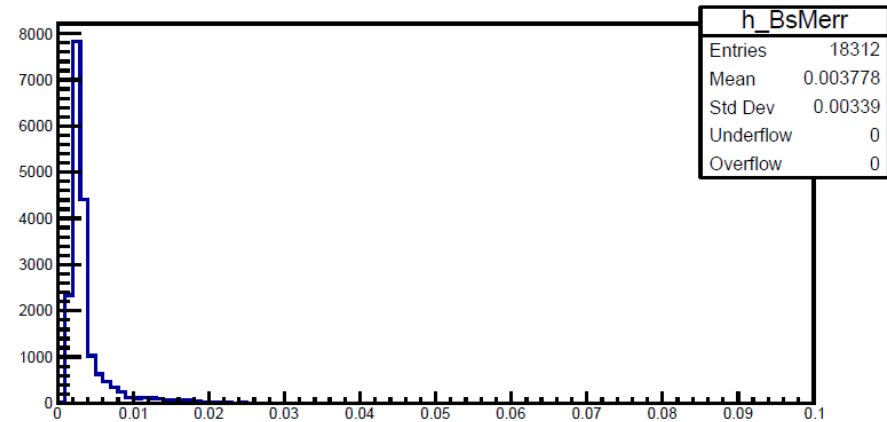
//
// Load Bs tracks
TVectorD* tBsPar[nBsT];
TMatrixDSym* tBsCov[nBsT];
TVectorD par(5); TMatrixDSym cov(5);
TrkToVector(tBs[0], par, cov);
tBsPar[0] = new TVectorD(par);           // Bs pion
tBsCov[0] = new TMatrixDSym(cov);
→ tBsPar[1] = new TVectorD(VMDs->GetVpar()); // Ds from previous fit
→ tBsCov[1] = new TMatrixDSym(VMDs->GetVcov());
//
// Fit Bs vertex
→ VertexFit* vBs = new VertexFit(nBsT, tBsPar, tBsCov);
vBs->SetStartR(RDs);
Double_t BsChi2 = vBs->GetVtxChi2();

```

Bs mass (GeV)



Bs mass error



Bs mass pull

