# Transformers, Attention, and Symmetries for Inverse Problems in High Energy Physics

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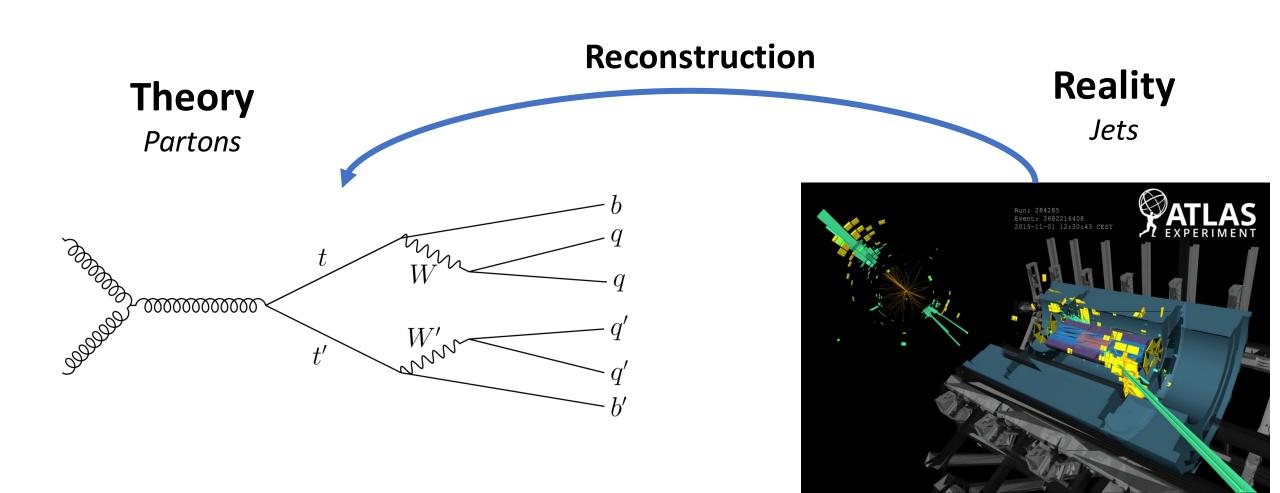
Based on work performed for

SPANet: Generalized Permutationless Set Assignment for Particle Physics using Symmetry Preserving Attention Alexander Shmakov, Michael James Fenton, Ta-Wei Ho, Shih-Chieh Hsu, Daniel Whiteson, Pierre Baldi SciPost Phys. 12, 178 (2022)

https://github.com/Alexanders101/SPANet

### **Problem Overview Reconstruction**

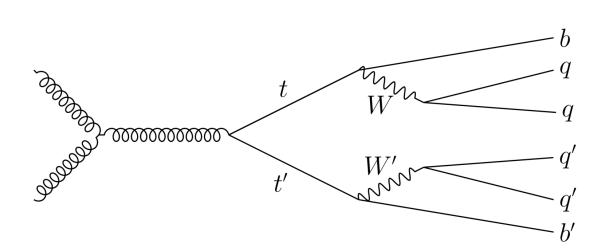
- The Large Hadron Collider (LHC) at CERN produces observations from decays of high energy particle collisions.
- The LHC reproduces the conditions present in the early universe, shortly after the Big Bang.
- We work with the ATLAS detector, which provides calorimetric momentum measurements of decay products

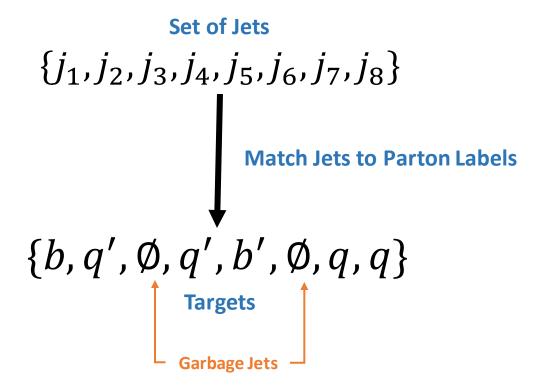


# **Problem Overview Jet-Parton Matching**

The simplest initial step to reconstruction: What are each of these jets?

- Could be many simultaneous decays in each event.
- Typically many more jets than partons.
- Initial cuts and requirements eliminate most of the garbage jets, but most events have at least 2 extra jets.
- Two additional complications.
  - Inputs are unordered collections (Sets) of jets.
  - Outputs are not unique! Notice that every top produces two q partons, producing four symmetric answers.





# **Problem Overview Set Assignment**

This modeling task reduces to a unique set assignment problem.

Input is a set of size N

$$\{j_1, j_2, \dots, j_N\}$$

Possible Targets are a set of size  $C \leq N$  and a special null target  $\emptyset$ 

$$\{\emptyset, t_1, t_2, ..., t_C\}$$

Output is another set of size N

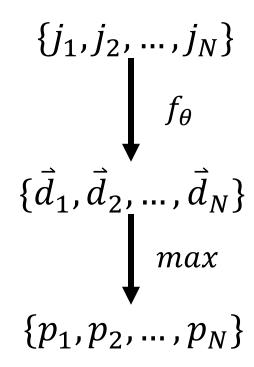
with each 
$$p \in \{\emptyset, t_1, t_2, ..., j_C\}$$
  $s.t.p_i \neq p_j$  or  $p_i = \emptyset$   $\{p_1, p_2, ..., p_N\}$ 

# **Set Assignment Itemized Approach**

The simplest approach to unique set classification would be independent classification.

**Train** a jet classifier  $f_{\theta}$  which treats each jet as a separate object.

**Postprocess** your predictions and select the highest probability assignment.



#### **Big Problems!**

- How to prevent two identical targets being predicted? Maybe removing elements?
- How to pick order to go through targets? Different ordering could change the prediction!
- The network has no information about the uniqueness. No context for each input!

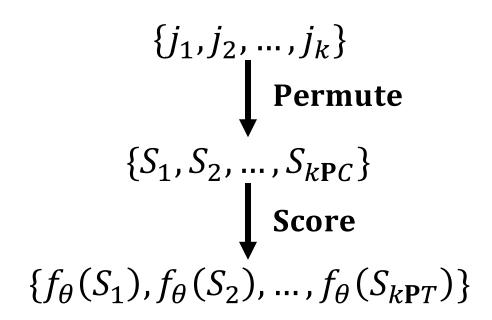
# **Set Assignment Permutation Approach**

A more invariant approach to this would be the **permutation score function**.

**Generate** every C-permutation of your set.

**Score** each permutation with DNN  $f_{\theta}(S) \in \mathbb{R}$ .

**Predict** the highest scoring permutation.



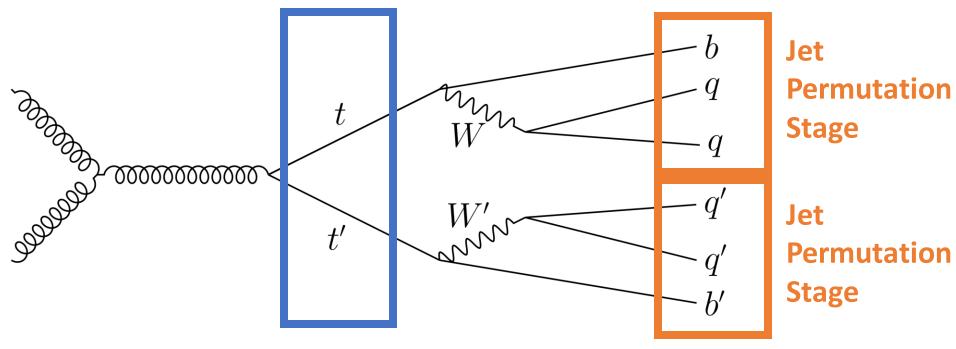
#### Good approach but terrible run-time

- Currently used in many baseline methods
- Need to generate every permutation! Runtime is  $O(N^C)$ .

# **SPANet A Combined Approach**

Merge these two approaches to get the best of both **plus symmetry**!

Output independent sub-permutations scores for each top-level particle and learn to differentiate sub-permutations with classification.



**Particle Classification Stage** 

# **Symmetry Input Permutation Equivariance**

- Input has not inherent order, just a collection of observations.
- Outputs match the order of input.
- Any approach must work for any initial ordering inputs.

$$\{j_1, j_2, j_3, j_4, j_5, j_6, j_7, j_8\} \cong \{j_3, j_7, j_1, j_2, j_8, j_4, j_6, j_5\}$$
$$\{b, q', \emptyset, q', b', \emptyset, q, q\} \cong \{\emptyset, q, b, q', q, q', \emptyset, b'\}$$

- Enforce an arbitrary consistent ordering? Hard to justify.
- Feed in all the permutations and average? Very expensive.
- Use a permutation equivariant architecture from the start!

#### **Attention**

### **Attention Overview**

Continuous, differentiable key-value database

Vectors

$$Q = \{q_1, q_2, \dots, q_m\}$$
 Queries

 $K = \{k_1, k_2, \dots, k_n\}$  Keys

 $V = \{v_1, v_2, \dots, v_n\}$  Values

Pick a **SIMILARITY** function. Compute and normalize similarity between query-key pairs.

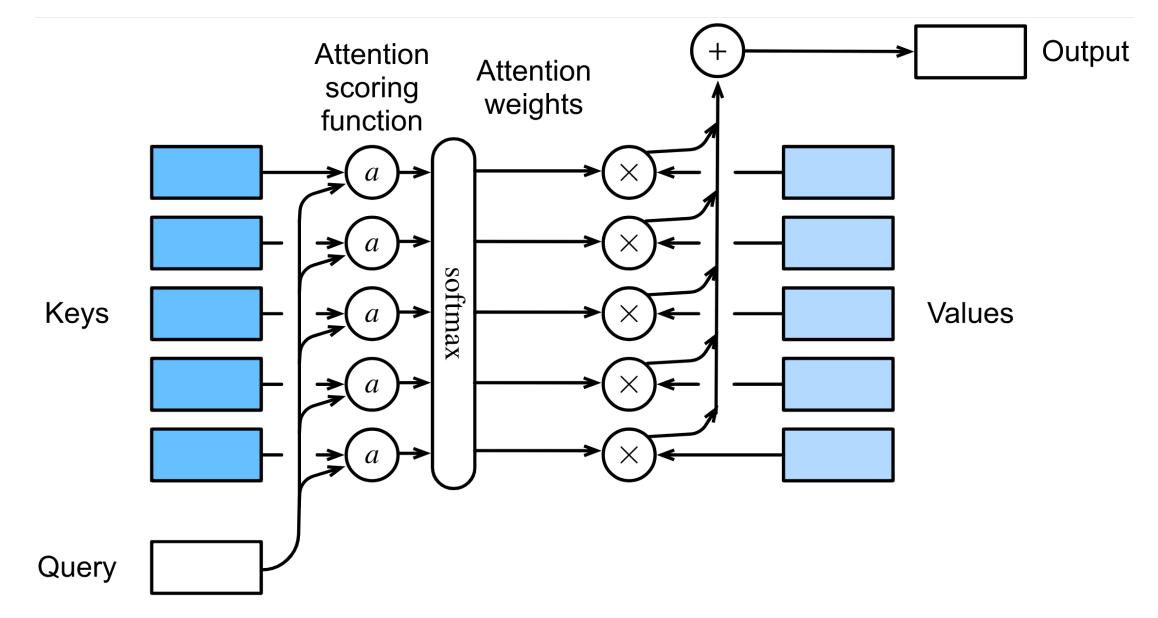
$$S_{ij} = \text{Similarity}(q_i, k_j)$$

$$A_{ij} = \text{Normalize}(S_{ij}) = \frac{e^{S_{ij}}}{\sum_{l=1}^{n} e^{S_{il}}}$$

Output a weighted average of all values based on similarity.

$$O_i = A_{ij} V^j$$

# **Attention Overview**



### **Attention Self-Attention**

Special Case of attention where we use the same input stream, X, as the queries, keys, and values.

Used to add **context** to collections of objects. Make every element aware of the other elements and learn the relationship between them.

$$Q = f_{\theta}^{Q}(X)$$

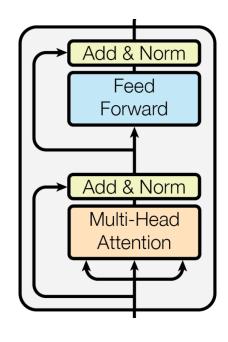
$$K = f_{\theta}^{K}(X)$$

$$V = f_{\theta}^{V}(X)$$

### **Attention Transformers**

Similarity
$$(q_i, k_j) = \frac{q_i \cdot k_j}{\sqrt{D}}$$

Self-attention<sup>1</sup> with scaled dot-product as the similarity measure.



#### The transformer encoder<sup>2</sup> combines

- Scaled dot-product attention
- Skip-connections
- Layer Normalization
- Position-independent feed-forward layers.

- 1. The full transformer uses "multi-head" self-attention, but this is conceptually equivalent for our purposes.
- 2. Vaswani, Ashish, et al. "Attention Is All You Need." Dec. 2017.

# **Attention Permutation Equivariance**

Scaled dot-product is permutation equivariant!

$$P_{\pi} \in \mathbb{P}^{N \times N}$$

$$A_{\pi} = \text{NORMALIZE} \left( \frac{(P_{\pi}Q)(P_{\pi}K)^{T}}{\sqrt{D}} \right)$$

$$= \text{NORMALIZE} \left( \frac{P_{\pi}(QK^{T})P_{\pi}^{T}}{\sqrt{D}} \right)$$

$$= P_{\pi}\text{NORMALIZE} \left( \frac{(QK^{T})}{\sqrt{D}} \right) P_{\pi}^{T}$$

$$= P_{\pi}AP_{\pi}^{T}$$

$$O_{\pi} = A_{\pi}(P_{\pi}V) = P_{\pi}AP_{\pi}^{T}P_{\pi}V = P_{\pi}O$$

# **Symmetry Target Symmetries**

One very interesting property of Feynman Diagram matching is the presence of symmetries. The following target sets are equivalent due to charge symmetry.

$$q_1q_2bq_1'q_2'b' \leftrightarrow q_2q_1bq_1'q_2'b'$$
 $q_1q_2bq_1'q_2'b' \leftrightarrow q_1q_2bq_2'q_1'b'$ 
We call these jet symmetries.

We will handle this with attention.

$$\mathcal{T}_1$$
  $\mathcal{T}_2$   $\mathcal{T}_2$   $\mathcal{T}_1$  We call this **particle symmetries**. We will handle this with a **special loss function**.

**Note**: this is not the same as allowing duplicate targets because the target groupings **must remain together**.

$$q_1q_2bq_1'q_2'b' \neq q_1'q_2bq_1q_2'b'$$

### **Tensor Attention Overview**

We can also use attention to produce **joint distributions over N dimensions**. Generalization of dot-product attention: **Tensor Attention** 

Suppose X is our list of vectors. This can be viewed as a (1,1)-tensor with ranks (N,D).

Suppose  $\Theta$  is a (0, K)-tensor of learnable weights with rank (D, D, ..., D).

- 1. Perform generalized dot-product self-attention on X with the mixing weights  $\Theta$ .
- 2. Create a K-joint distribution P by normalizing O.

$$O^{j_1 j_2 \dots j_N} = X_{n_1}^{j_1} X_{n_2}^{j_2} \dots X_{n_N}^{j_N} \Theta^{n_1 n_2 \dots n_N}$$

$$\mathcal{P}^{j_1 j_2 \dots j_N} = \frac{\exp O^{j_1 j_2 \dots j_N}}{\sum \exp O}$$

### **Tensor Attention Symmetric Attention**

Suppose we want our joint distribution to obey **permutation symmetries**. For example:  $p(j_1, j_2, ...) = p(j_2, j_1, ...)$ .

We encode this as a symmetry group on the indices of  $\Theta$ 

Suppose  $G_P \subseteq S_K$  is a permutation group acting on the indices  $\{j_1, j_2, ..., j_K\}$ .

- 1. Create a symmetric weights tensor S by summing over the symmetric indices of  $\theta$  according to  $G_P$ .
- 2. Perform generalized dot-product on the list of input vectors X with a symmetric weights tensor S.
- 3. Create a **symmetric** joint distribution **P** by normalizing **O** just like before.

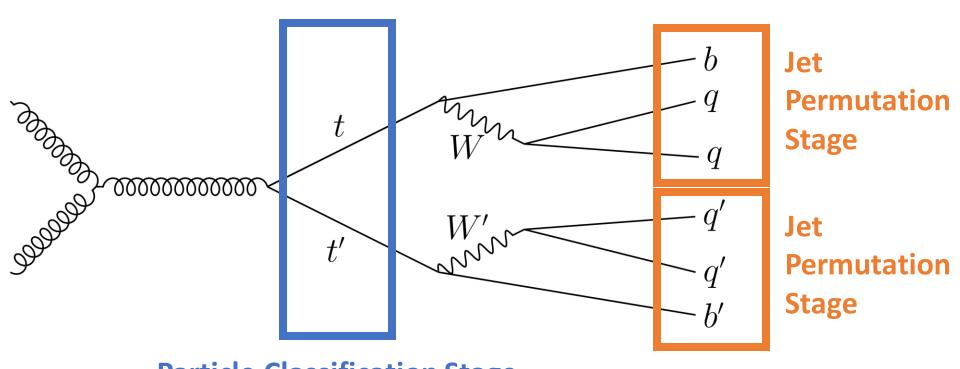
$$S^{i_1 i_2 \dots i_K} = \sum_{\sigma \in G_P} \Theta^{i_{\sigma(1)} i_{\sigma(2)} \dots i_{\sigma(K)}}$$

$$O^{j_1 j_2 \dots j_K} = X^{j_1}_{i_1} X^{j_2}_{i_2} \dots X^{j_K}_{i_K} S^{i_1 i_2 \dots i_K}$$

$$\mathcal{P}^{j_1 j_2 \dots j_K} = \frac{\exp\left(O^{j_1 j_2 \dots j_K}\right)}{\sum_{j_1, j_2, \dots, j_K} \exp\left(O^{j_1 j_2 \dots j_K}\right)}$$

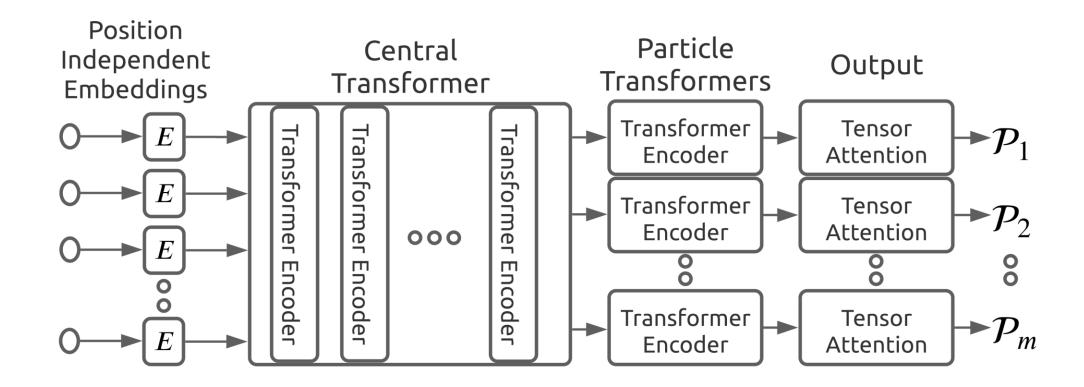
# **SPANet A Combined Approach**

**Tensor Attention** produces relatively small (2-4) dimensional joint distributions over jets.



**Particle Classification Stage** 

### **SPANet** Architecture



### **SPANet** Training the Permutation Ranker

- Train symmetric joint-distributions using a simple categorical cross-entropy.
- One special difference
  - The target T is not a delta distribution!
  - T will be non-zero for every valid symmetric assignment.

$$\mathcal{L}_P(\mathcal{P}, \mathcal{T}) = \sum_{j_1, j_2, \dots, j_N} -\mathcal{T}^{j_1 j_2 \dots j_N} \log \mathcal{P}^{j_1 j_2 \dots j_N}$$

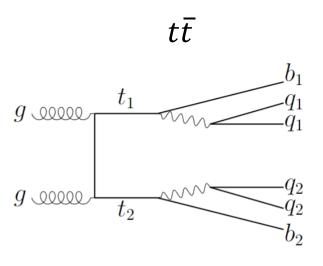
### **SPANet** Symmetric Training

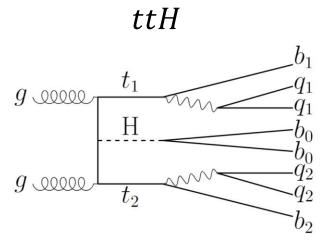
- Handle event symmetries using a symmetric loss function.
- Define an event-level symmetry group  $G_E \subseteq S_m$  acting on particles  $\{P_1, P_2, ..., P_m\}$
- Loss function simply takes the minimum achievable loss over valid permutations.
- Also tried other methods such as *sum* of *soft-min*. Simple *min* works the best.

$$\mathcal{L} = \min_{\sigma \in G_E} \sum_{i=1}^{m} \mathcal{L}_P \left( \mathcal{P}_{\sigma(i)}, \mathcal{T}_{\sigma(i)} \right)$$

### **SPANet** Results

- Compare to a common baseline used in CERN analyses A permutation-based  $\mathcal{X}^2$  approach.
- Greatly improve accuracy over baseline methods. On average around ~25% improvement.
- ullet Drastically increase runtime performance. Baseline method cannot tractably evaluate tttt!





ττττ	
$\_b$	1
q	1
$t_1$	
g 00000 $b$	$\frac{2}{2}$
$q_2$	2
$t_3$	
$g = \frac{1}{2} $	
$t_4$ $q$	4
q	
b	4

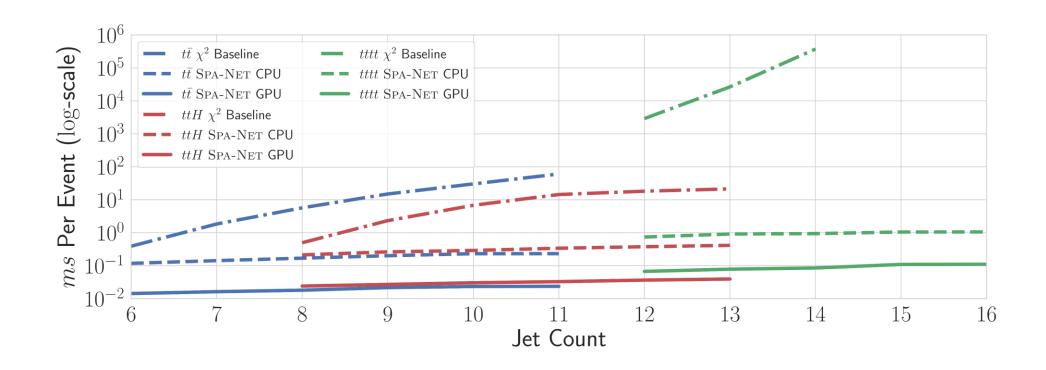
		Event	SPA-NET Efficiency		$\chi^2$ E	Efficiency
	$N_{ m jets}$	Fraction	Event	Top Quark	Event	Top Quark
All Events	== 6	0.245	0.643	0.696	0.461	0.523
	== 7	0.282	0.601	0.667	0.408	0.476
	$\geq 8$	0.320	0.528	0.613	0.313	0.395
	Inclusive	0.848	0.586	0.653	0.387	0.457
Complete Events	== 6	0.074	0.803	0.837	0.664	0.696
	== 7	0.105	0.667	0.754	0.457	0.556
	$\geq 8$	0.145	0.521	0.662	0.281	0.429
	Inclusive	0.325	0.633	0.732	0.426	0.532

	Event	SPA-NET Efficiency			$\chi^2$ Efficiency		
$N_{ m jets}$	Fraction	Event	Higgs	Top	Event	Higgs	Top
== 8	0.261	0.370	0.497	0.540	0.056	0.193	0.092
== 9	0.313	0.343	0.492	0.514	0.053	0.160	0.102
$\geq 10$	0.313	0.294	0.472	0.473	0.031	0.150	0.056
Inclusive	0.972	0.330	0.485	0.502	0.045	0.164	0.081
== 8	0.042	0.532	0.657	0.663	0.040	0.220	0.135
== 9	0.070	0.422	0.601	0.596	0.019	0.152	0.079
$\geq 10$	0.115	0.306	0.545	0.523	0.004	0.126	0.073
Inclusive	0.228	0.383	0.583	0.572	0.016	0.153	0.087

	Event	SPA-NET Efficiency			
$N_{ m jets}$	Fraction	Event	Top Quark		
== 12	0.219	0.276	0.484		
== 13	0.304	0.247	0.474		
$\geq 14$	0.450	0.198	0.450		
Inclusive	0.974	0.231	0.464		
== 12	0.005	0.350	0.617		
== 13	0.016	0.249	0.567		
$\geq 14$	0.044	0.149	0.504		
Inclusive	0.066	0.191	0.529		

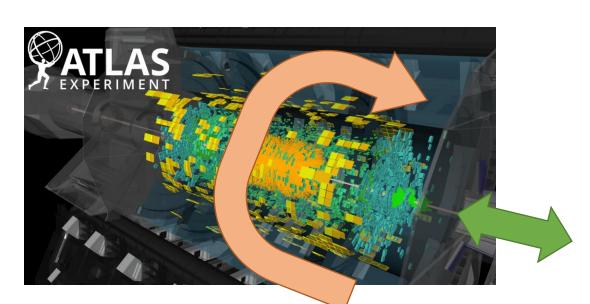
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- Greatly improve accuracy over baseline methods. On average around ~25% improvement.
- Drastically increase runtime performance. Baseline method cannot tractably evaluate tttt!



There are really three types symmetries in reconstruction.

- Mathematical permutation symmetry of sets
  - Handled with transformer attention.
- Discrete Physics symmetries such as CPT
  - Handled charge and parity symmetries with tensor attention and symmetric loss.
- Continuous Physics symmetries **Lorentz symmetries** of space.
  - We can rotate or flip the entire detector and get the exact same event.
  - Still present!



A **Reference Frame** is a conditional mapping  $\phi(u;v)$  over the input vectors. In HEP, our transform is the **Lorentz boost**, which is preserved under a global Lorentz transform.

$$\phi(u;v) = \frac{1}{1 - v \cdot u} \left( \frac{u}{\gamma_v} - v + \frac{\gamma_v}{\gamma_v + 1} (u \cdot v) v \right)$$

Keys and values become **matrix** collections of vectors. Queries remain as lists of vectors.

$$Q \in \mathbb{R}^{N \times D}$$
 Queries  $K \in \mathbb{R}^{N \times N \times D}$  Keys  $V \in \mathbb{R}^{N \times N \times D}$  Values

 $K_{i,j} = \phi(k_j; k_i)$  represents the j'th key from i'th reference frame.  $V_{i,j} = \phi(v_j; v_i)$  represents the j'th value from i'th reference frame.  $Q_i = \phi(q_i; q_i)$  represents the i'th query from i'th reference frame.

- Modified attention operation is nearly identically to regular attention.
- Just need to add some extra indices
- Output vector, O, is invariant to any global changes w.r.t the perspective operation.

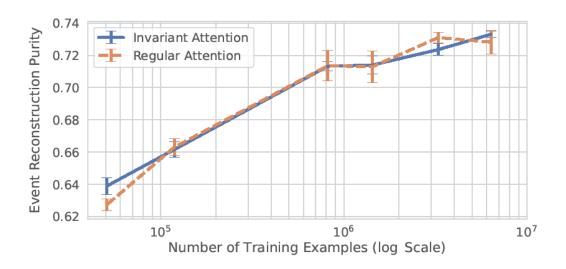
$$S_{i,j} = \frac{Q_i \cdot K_{i,j}}{\sqrt{D}} \in \mathbb{R}$$

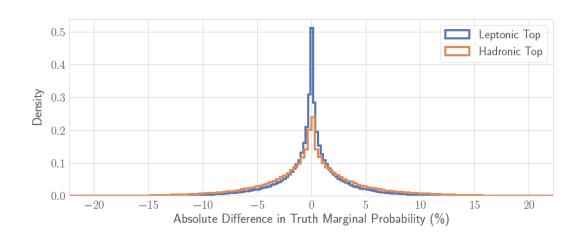
$$A_{i,:} = \text{SOFTMAX}(S_{i,:}) \in \mathbb{R}^N$$

$$O_i = \sum_{j} (A_{i,j} \odot V_{i,j}) \in \mathbb{R}^D$$

A trivial reference frame function,  $\phi(u; v) = u$ , reduces this operation regular scaled dot-product attention.

#### Almost no improvement in performance!





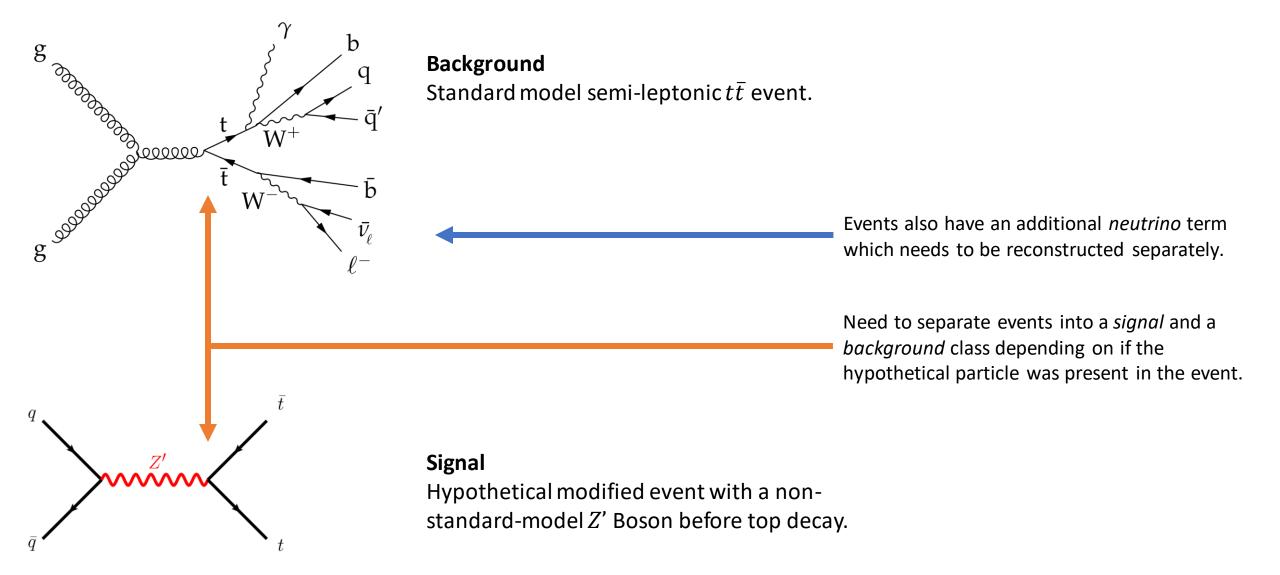
#### What's going on?

- The transformation function is just a non-linear conditional function of the original input.
- This is precisely a transformer!
- If Lorentz invariance is useful, then the network **should just learn it.**

Let's examine how much our assignment probability changes as you feed the **same event** rotated in several ways.

Even without Lorentz invariant attention, SPANet is **approximately invariant**!

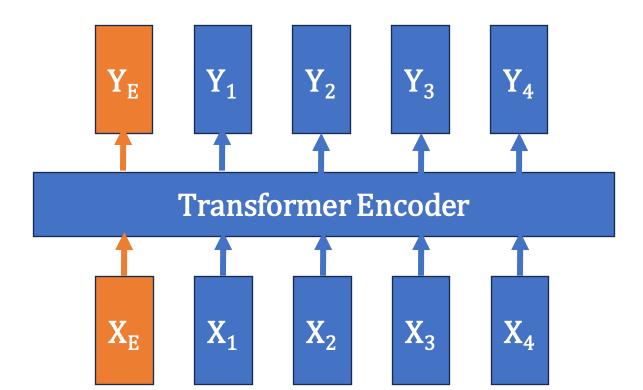
### **Upcoming Work** Search for New Particles



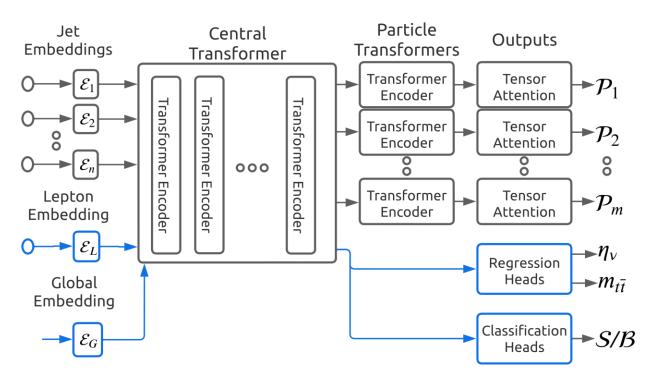
### **Upcoming Work** Search for New Particles

We can add a special **Event-Level** output to attention with a neat trick.

Add a special *fixed* vector to our input stream,  $X_E$ , which will represent the event information. This special vector will have the same value for all events. The transformer's contextual learning will fill  $Y_E$  with relevant event information.



### **Upcoming Work Search for New Particles**



#### **Combined Training**

Train SPANet on simulated data with the hypothetical particle present and not present. This will ensure reasonable performance regardless of what the real data holds.

Regress extra neutrino terms

Classify event into signal or background

#### **Trainable Global Vector**

Will store information about the complete event.

#### **Global Outputs**

Use the encoded global vector to predict additional event-level terms.

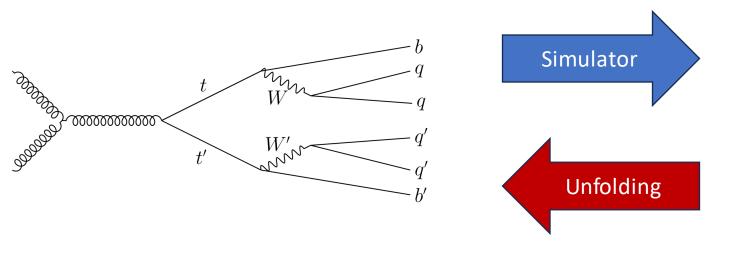
So far, we have been **assigning** jets to source partons. What if we could do more?

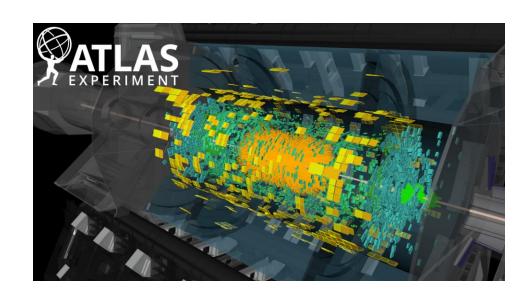
**Unfolding** Fully recovering the momenta of the source partons from observations.

Simulators (Madgraph, Delphes, etc) define the forward problem:

Parton -> Detector

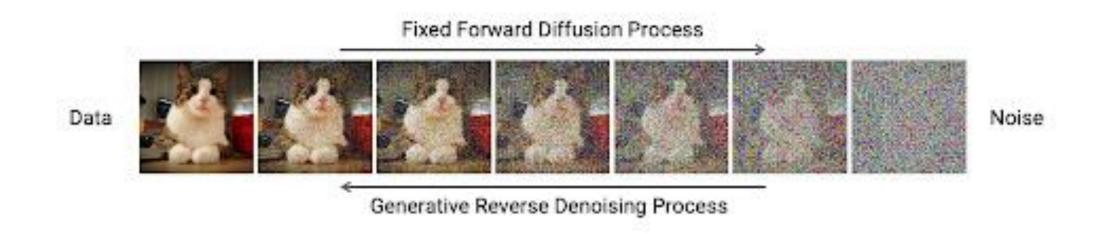
We want to solve the inverse problem: Detector -> Parton

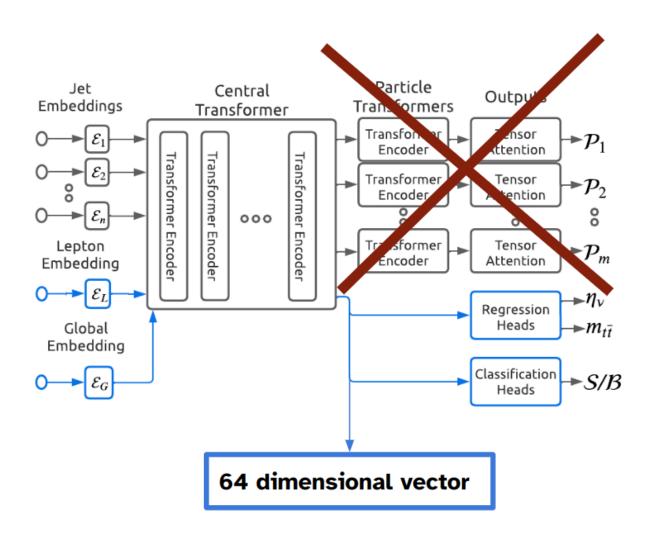




We borrow a popular idea from machine learning: **Diffusion.**Generate complex distributions *conditioned* on another observation.

Based on a principle of *denoising*: generate new samples by reversing gradual noise.





#### **Detector Encoder**

Use the special event-level output from SPANet to get an abstract conditional latent vector.

Convert a complex variable-length observation into a fixed-length vector to use for diffusion.

The whole unfolding framework will generate Parton configurations conditioned on this event vector.

