

# Topological equivalence and invariants of Calabi-Yau threefolds

*New invariants, and identification of topological data.*



Kit Fraser-Taliente

based on (upcoming) work with Andre Lukas, Thomas Harvey, Aditi Chandra, and Andrei Constantin

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a Gould-Watson  
scholarship

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  - How many pairs of Hodge numbers in Kreuzer-Skarke? 30,108. At **least this many distinct manifolds**.
  - Very loose upper bounds on KS -  $1.65 \times 10^{428}$  manifolds. Mostly one polytope!

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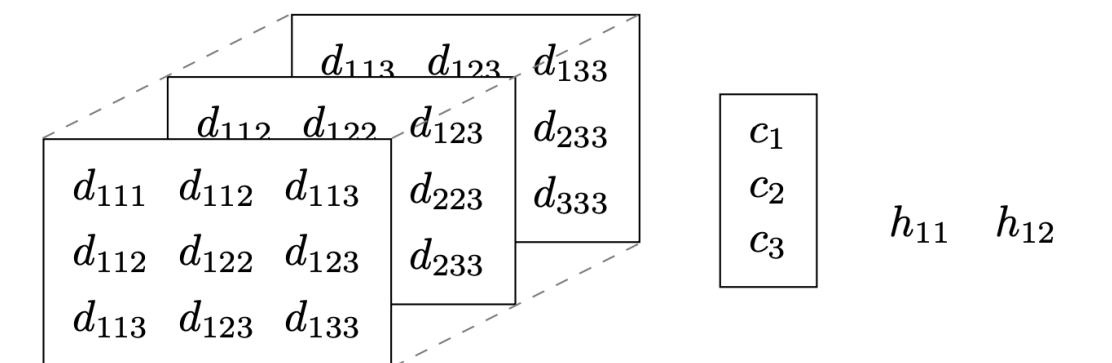
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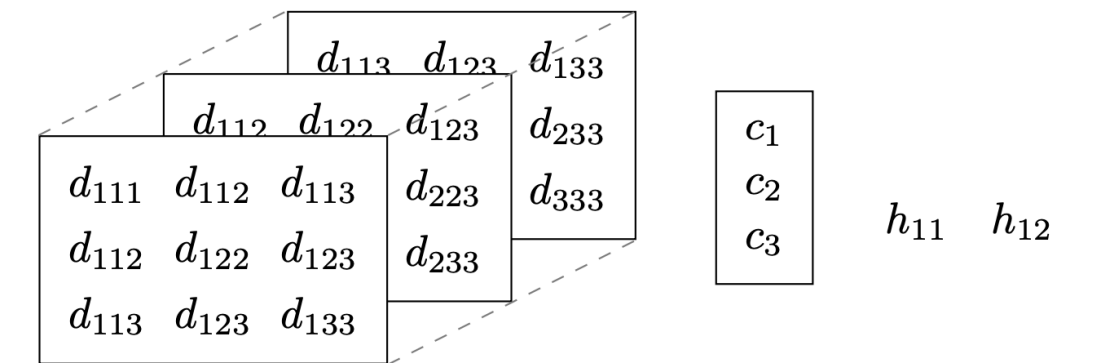
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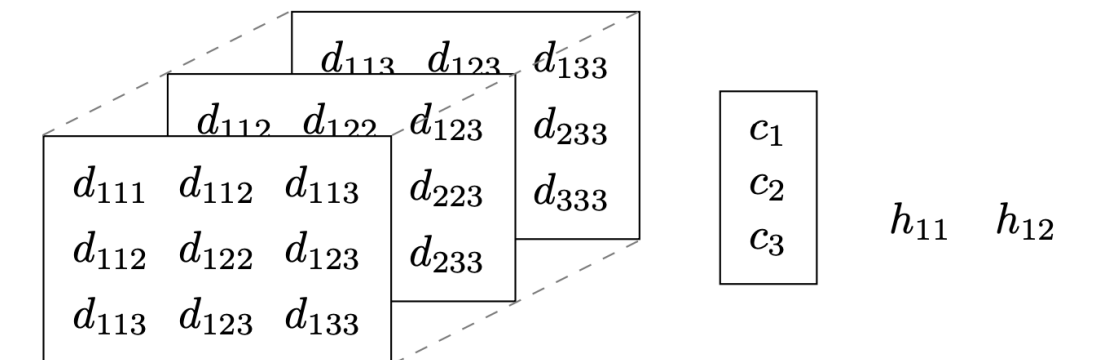
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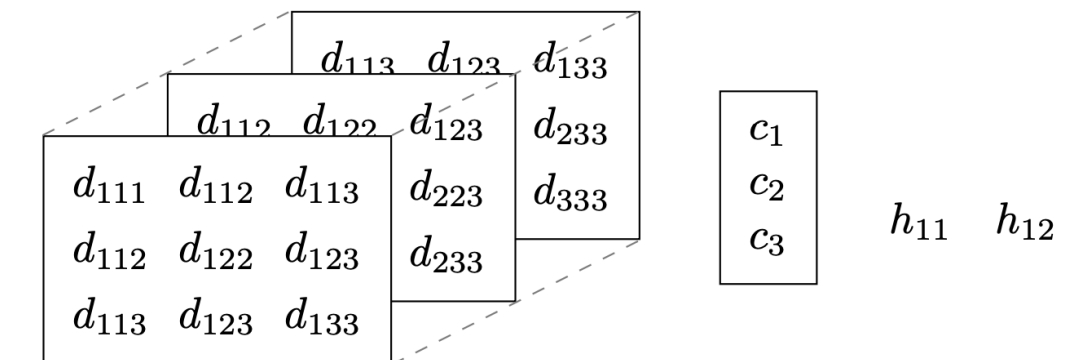
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For equivalence of two  $X$  and  $X'$ : find an isomorphism  $P_r^s : H^2(X, \mathbb{Z}) \rightarrow H^2(X', \mathbb{Z})$ .

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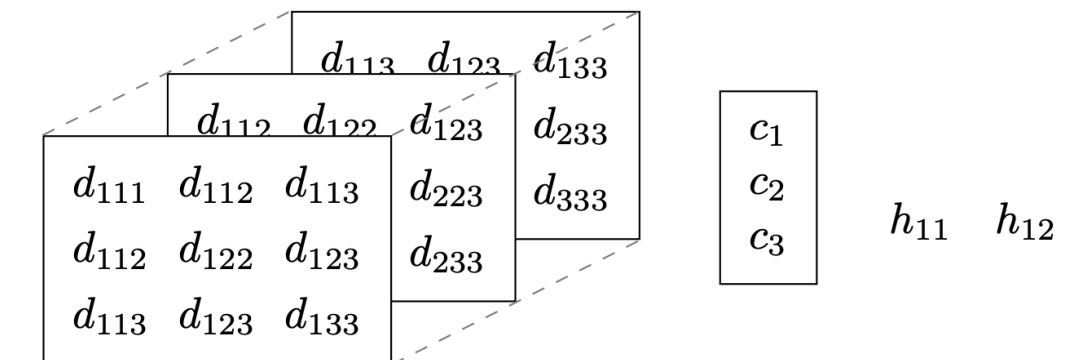
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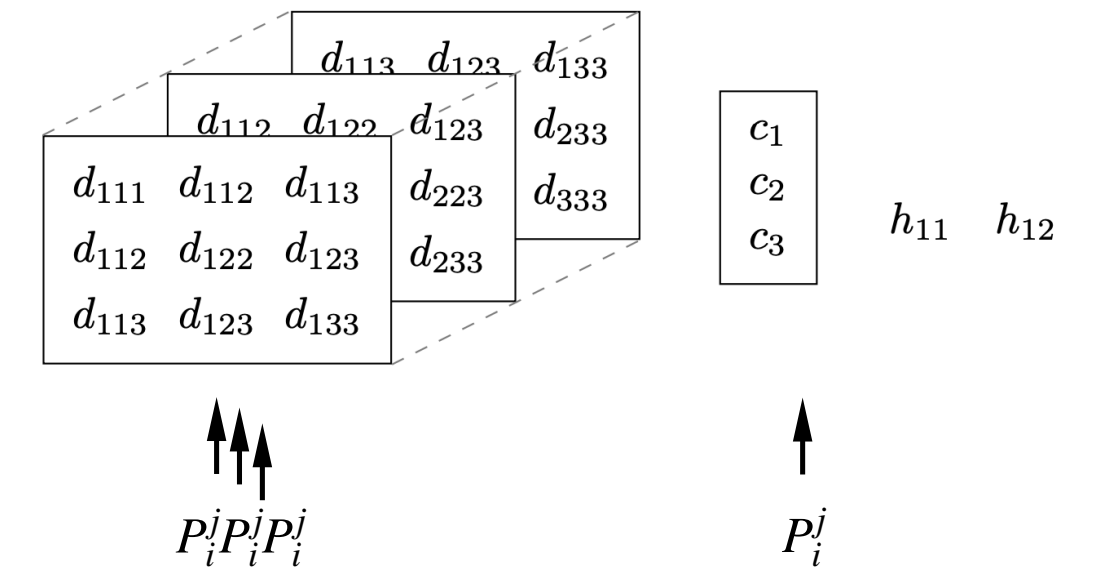
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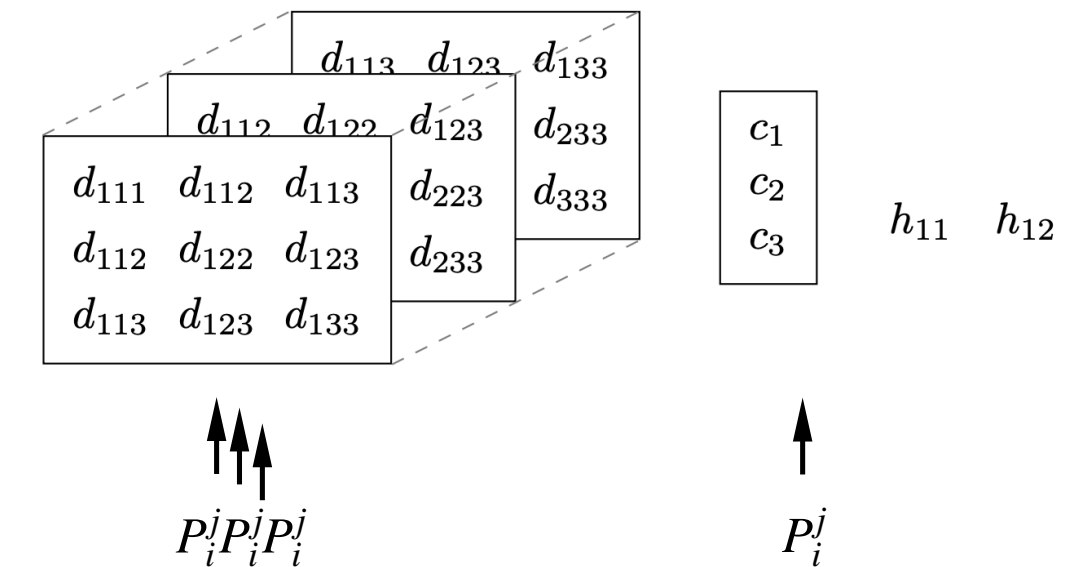
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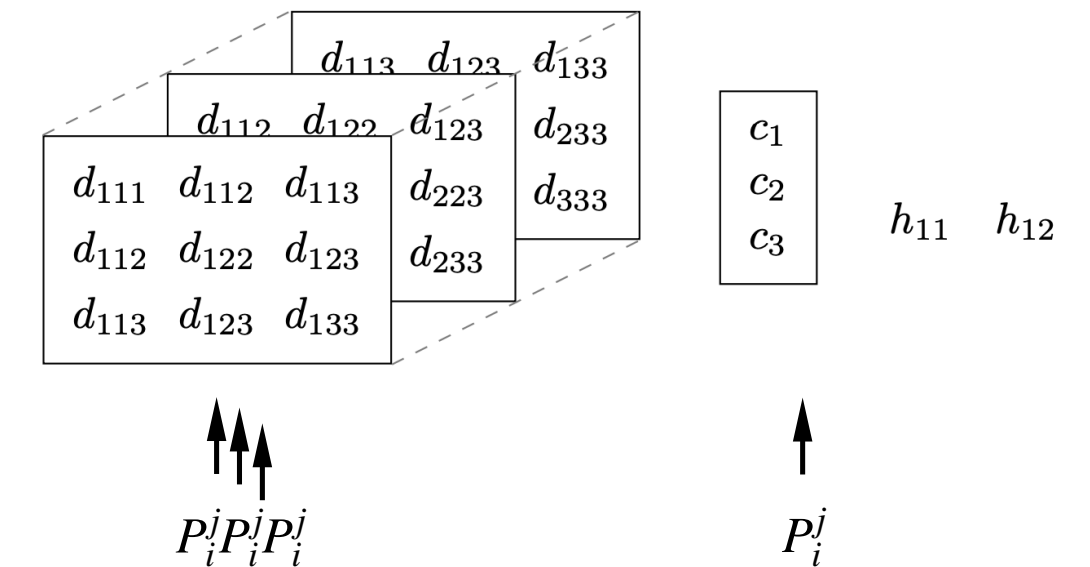
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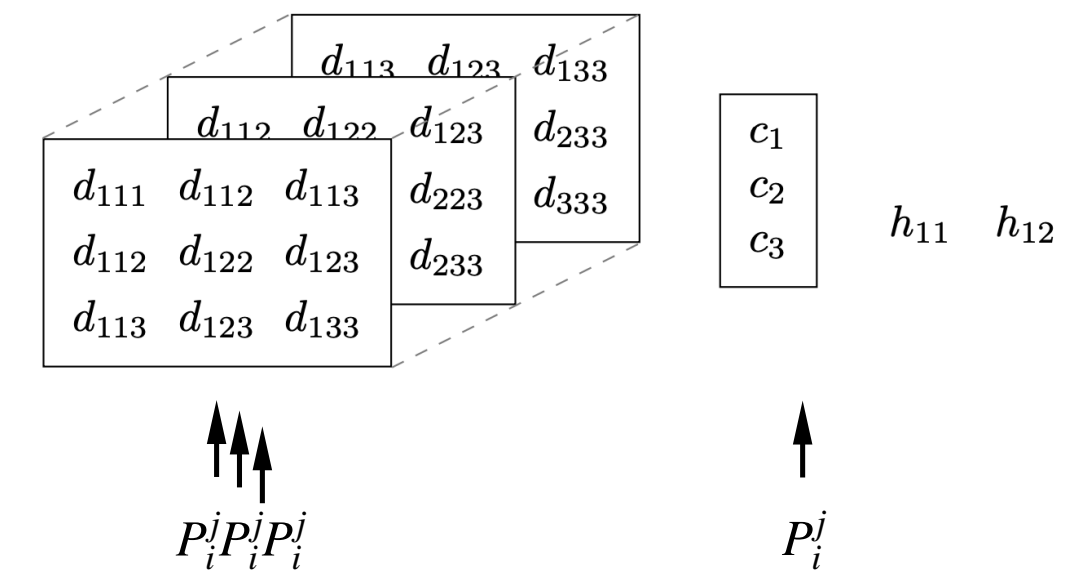


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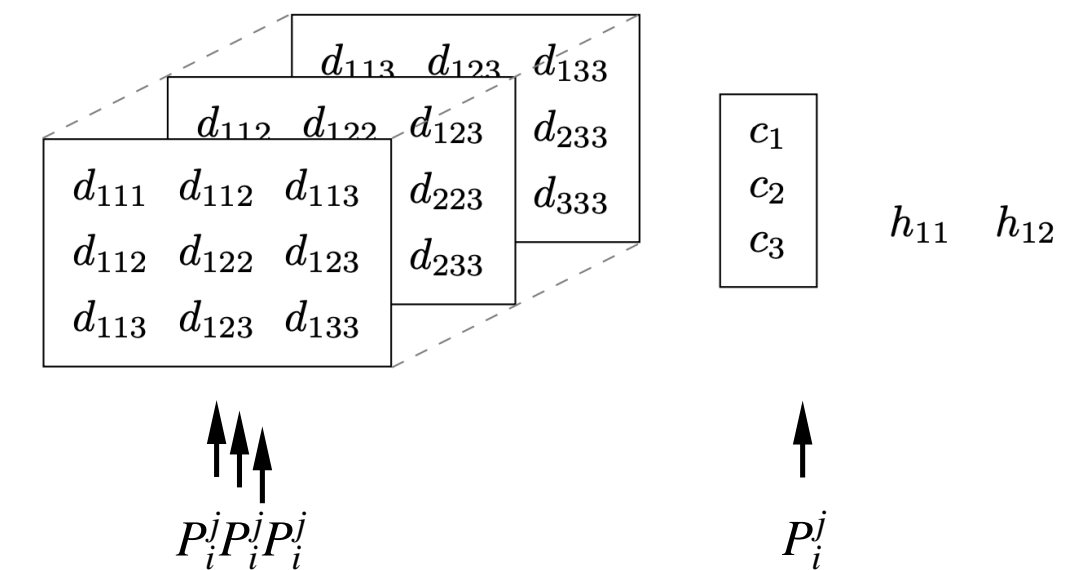
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Quadratic and cubic forms are **much more complicated**.

**Clearly  $\gcd(\{d_{rst}\})$  and  $\gcd(\{c_r\})$  are preserved [Hubsch, '92].**

- Some more complicated GCD invariants exist, related to (e.g.) the GCD of the diagonal elements  $\{d_{rrr}\}$ .
- Other invariants related to limiting mixed Hodge structures in infinite distance limits exist [Grimm, Ruehle, van de Heisteeg, '19]. For the cases in this talk, these are less powerful than those discussed below.

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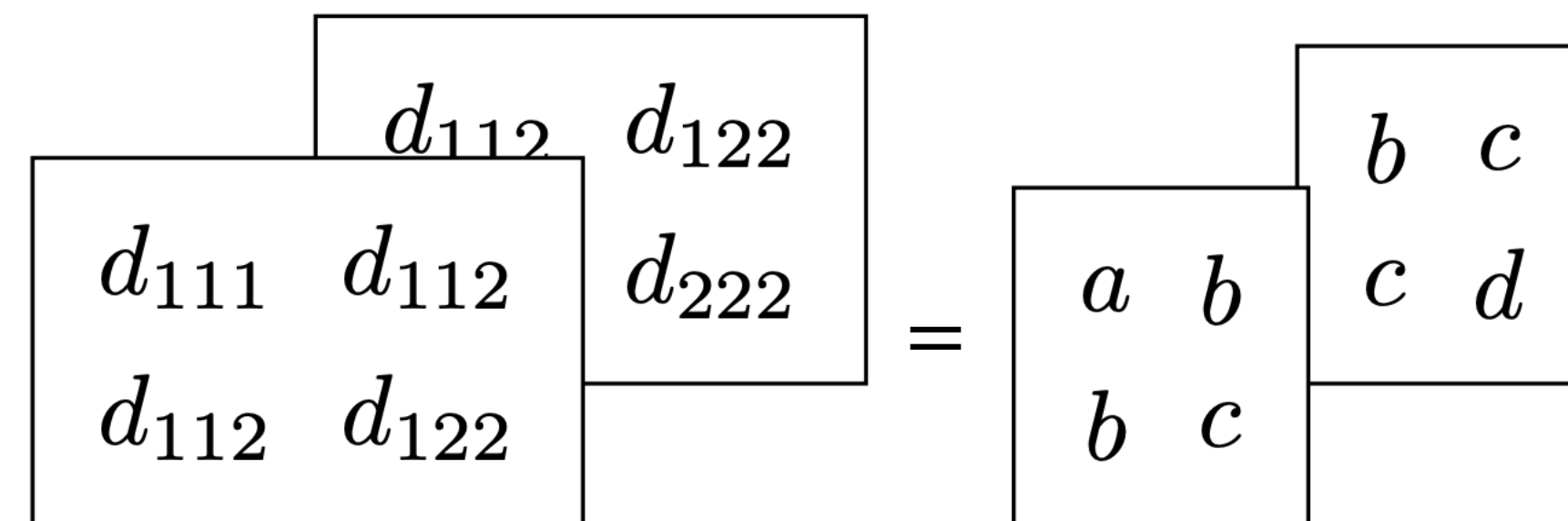
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- Representation algebra. For  $h^{11} = 2$ ,  $\mathbf{N} = \mathbf{2}$  and  $\mathbf{R} = \mathbf{4}$ :

Linears:  $\text{Sym}^1(\mathbf{4}) = \mathbf{4}$

Quadratics:  $\text{Sym}^2(\mathbf{4}) = \mathbf{3} \oplus \mathbf{7}$

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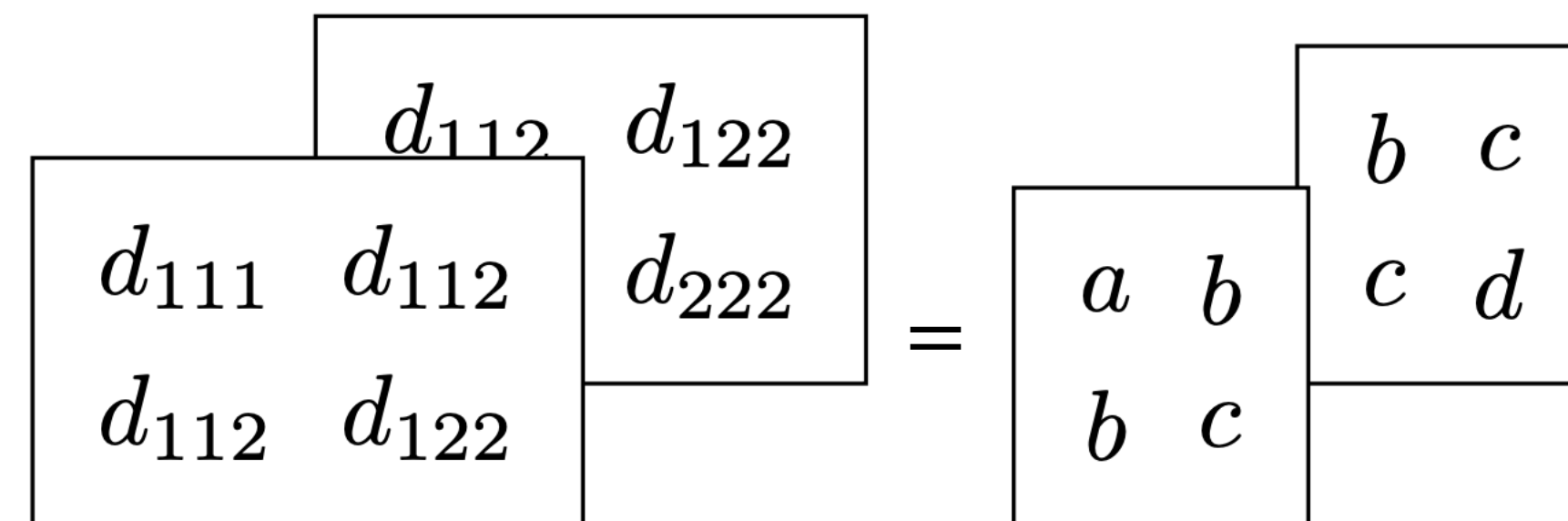
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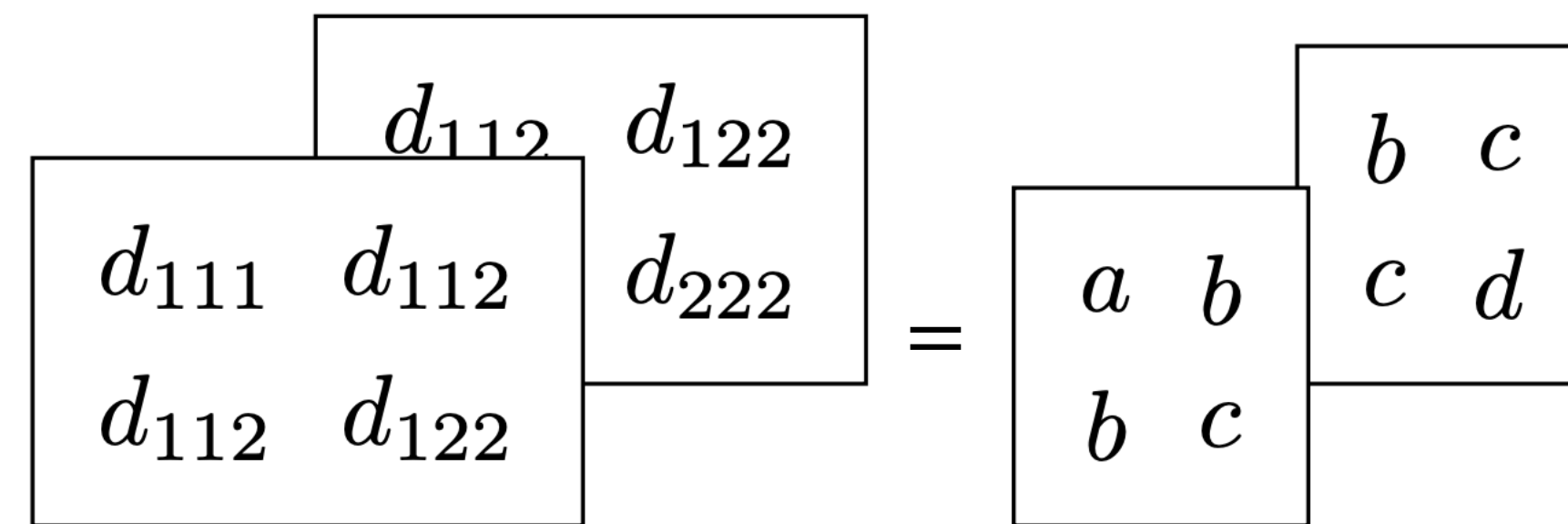
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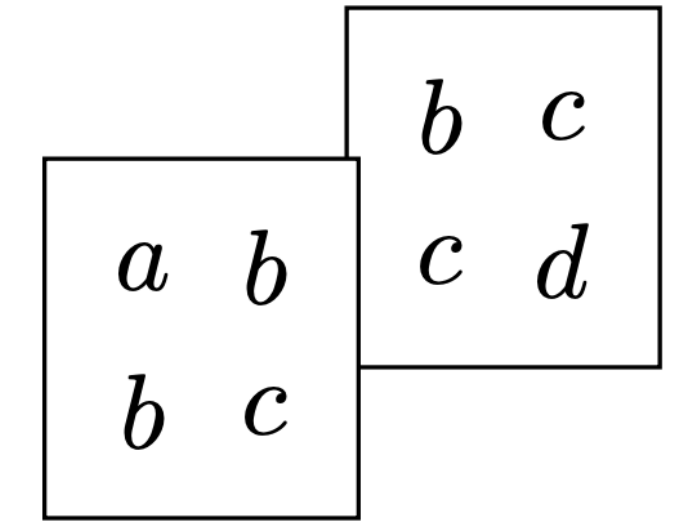
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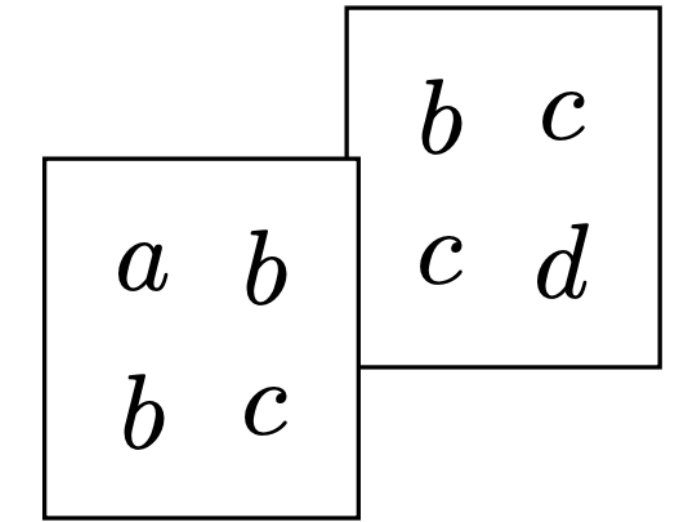


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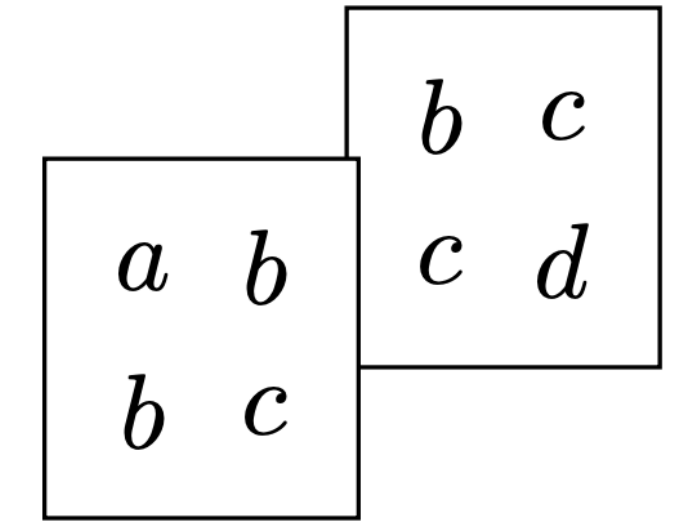


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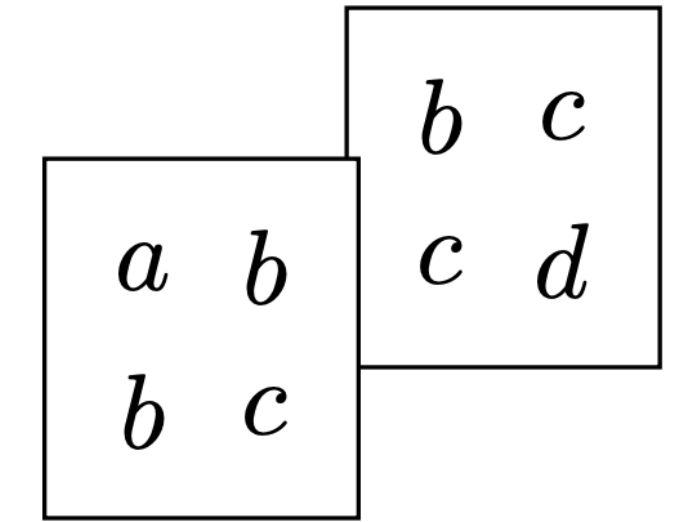
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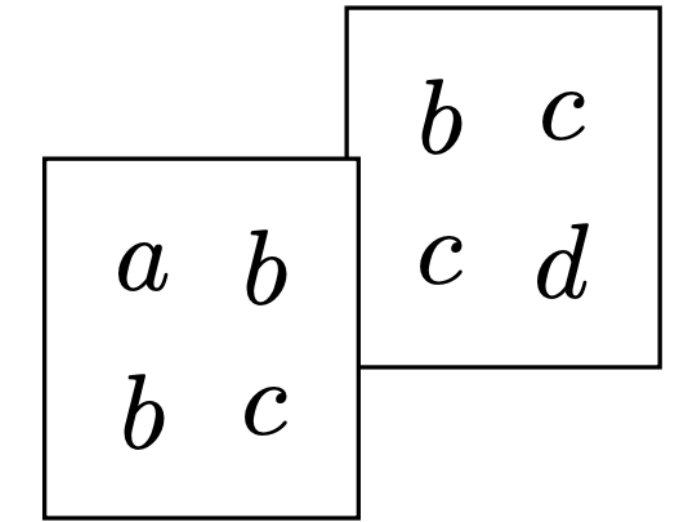
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$h^{1,1}$	1	2	3	4	5	6	7
Degrees	1	4	4,6	8,16*	10	10*,12*	14*
# expected	1	1	2	5	11	21	36

- Known lowest degrees of singlets and total number of (algebraically independent) singlets expected. Starred have not been determined explicitly

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The results, for  $h^{11} \leq 5$ :

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- E.g. - the degree-10  $h^{11} = 5$  invariant has 7000 independent coefficients, each multiplying an  $S_5$  orbit of a particular monomial. **It is large.**





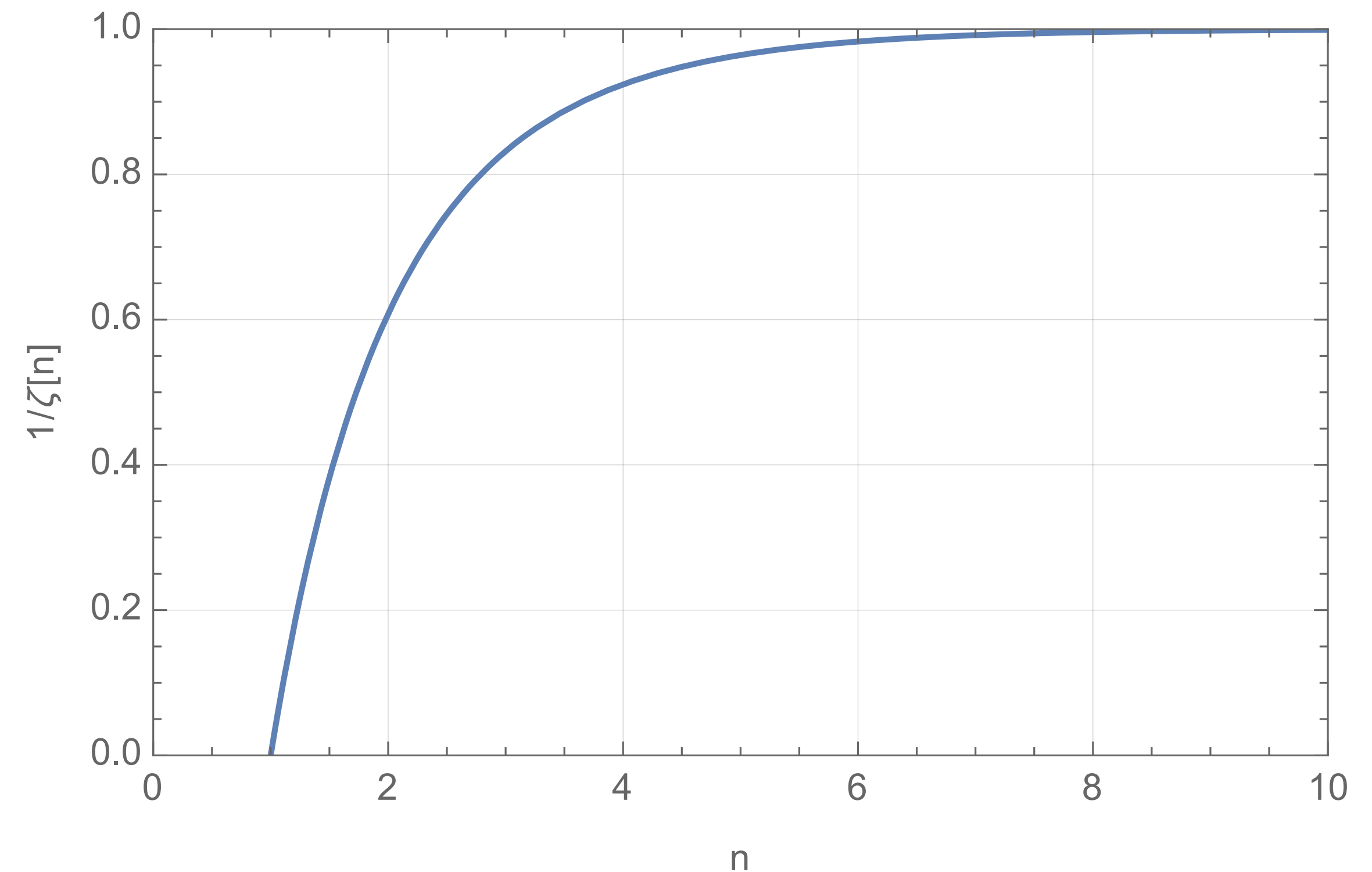
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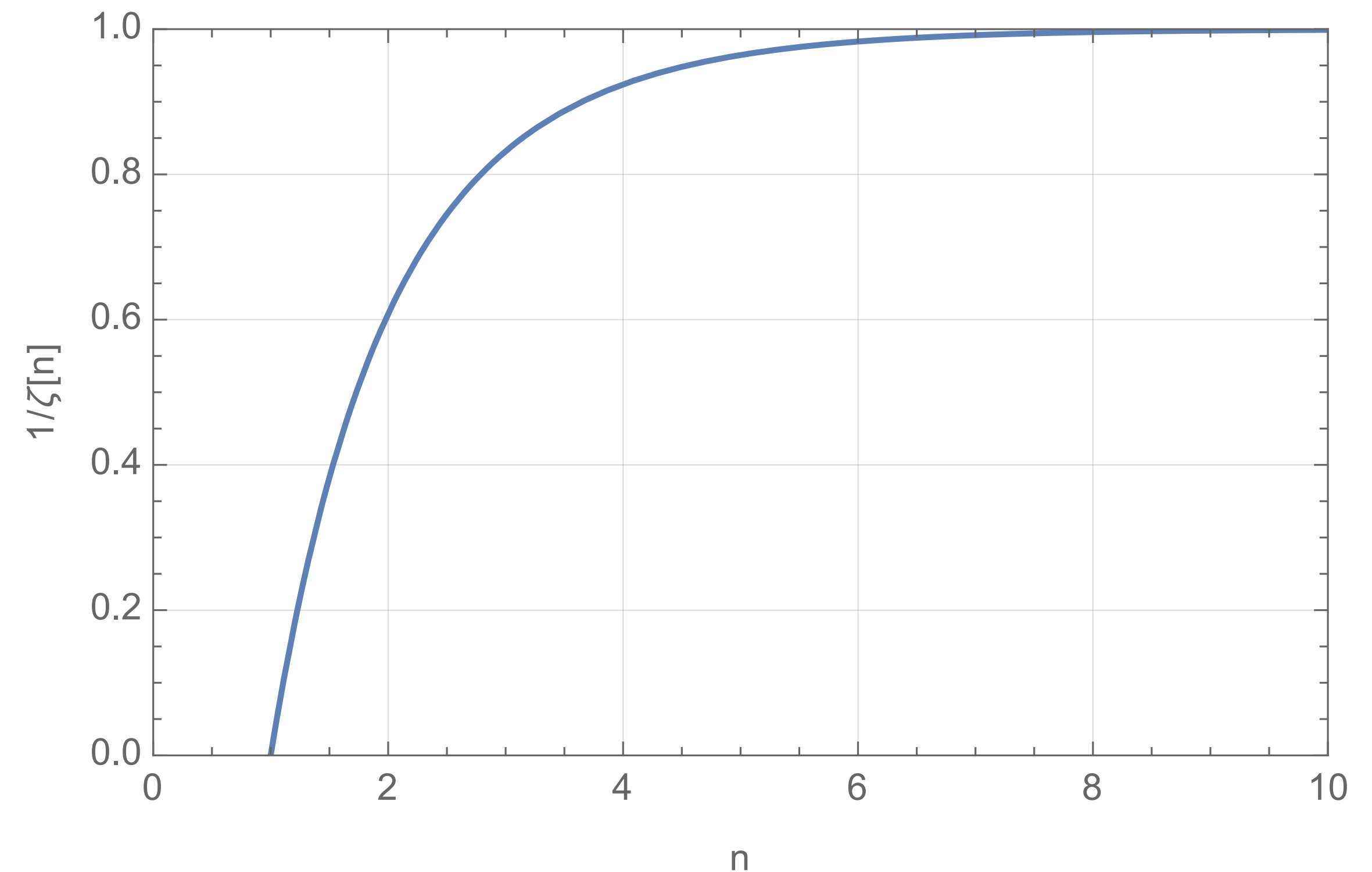
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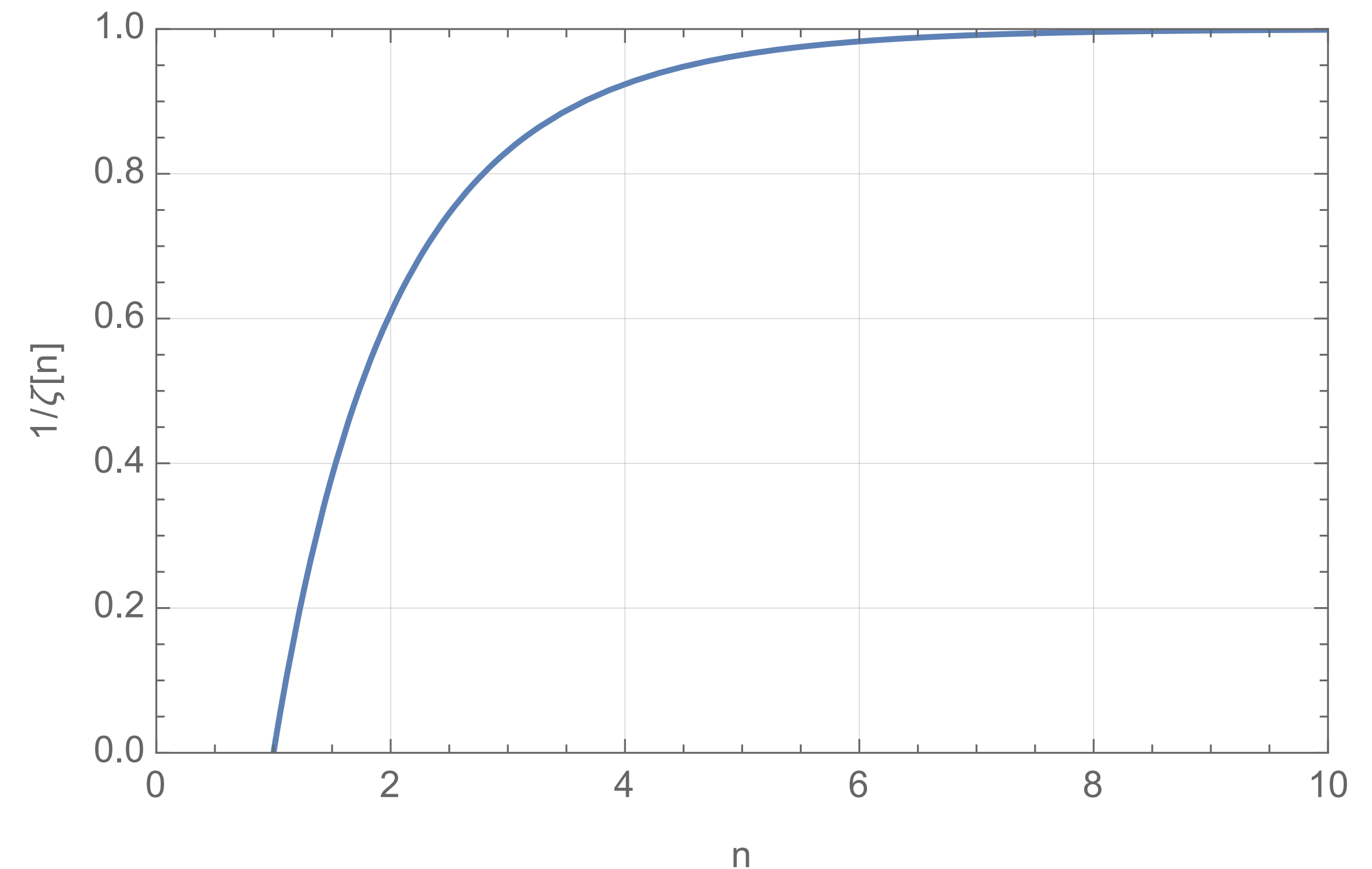
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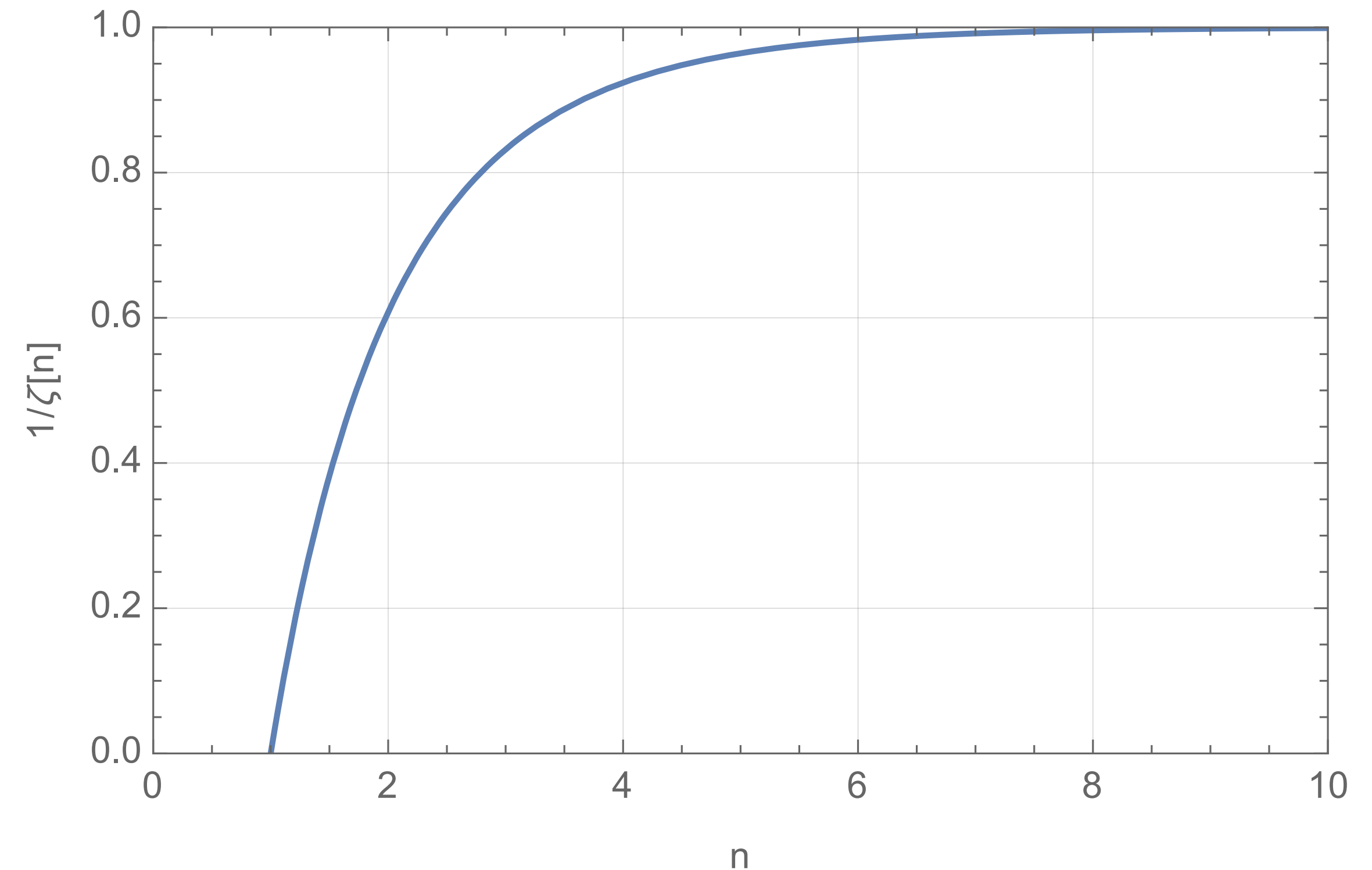
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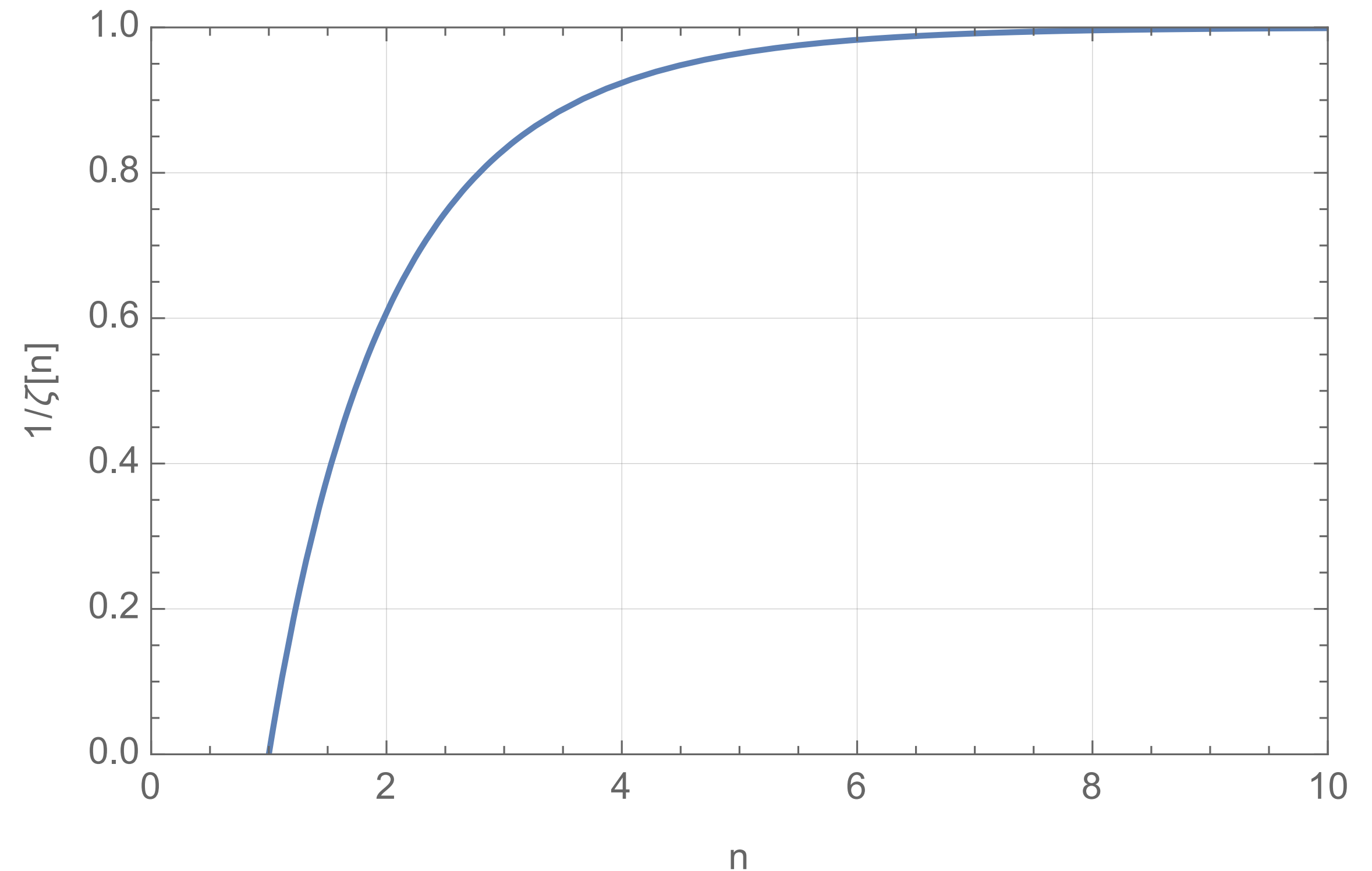
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- from this heuristic we should also expect them to worsen at larger  $h^{11}$ .



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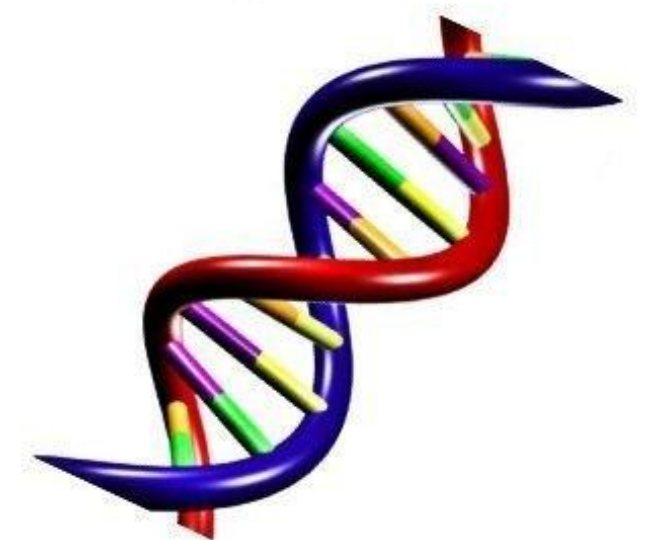
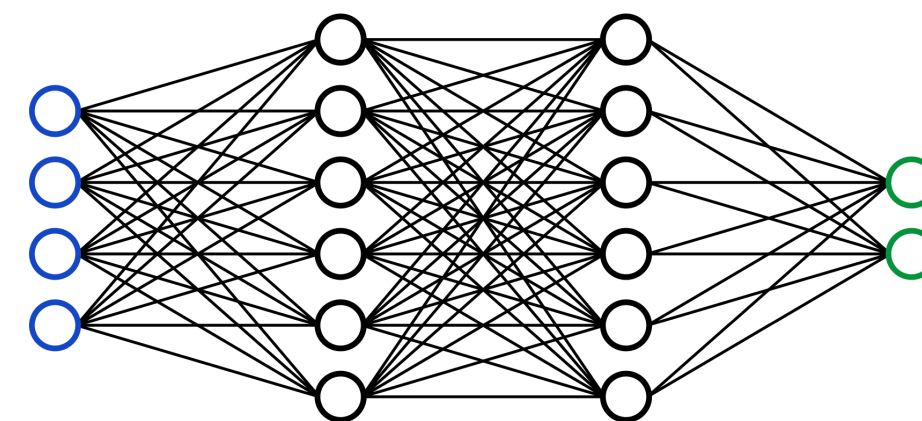
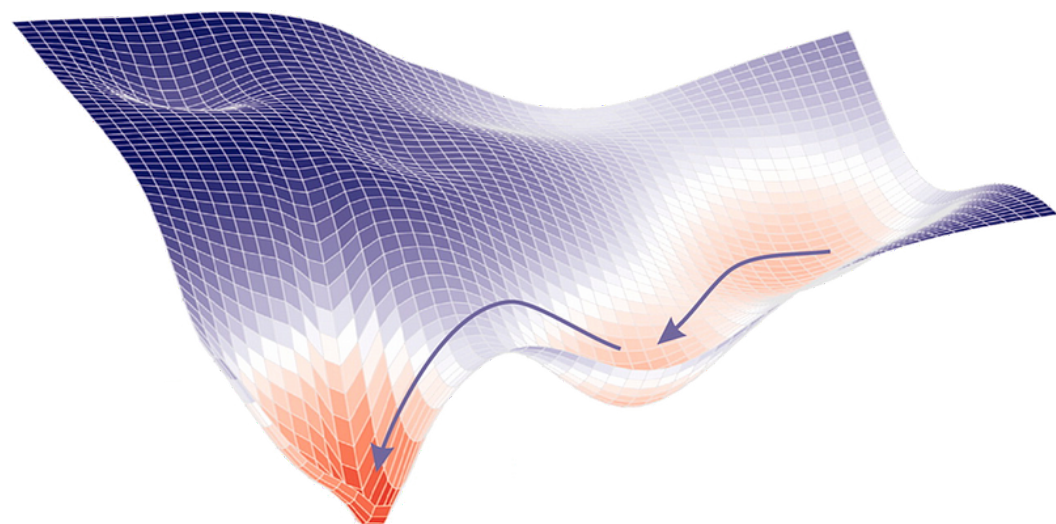
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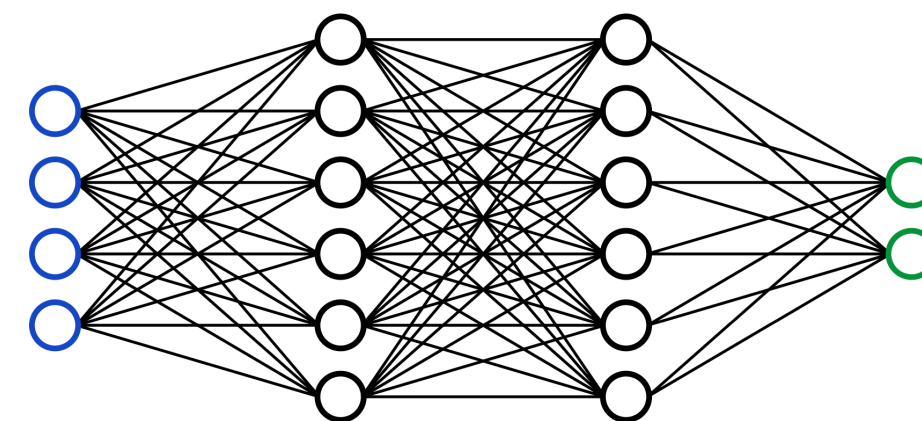
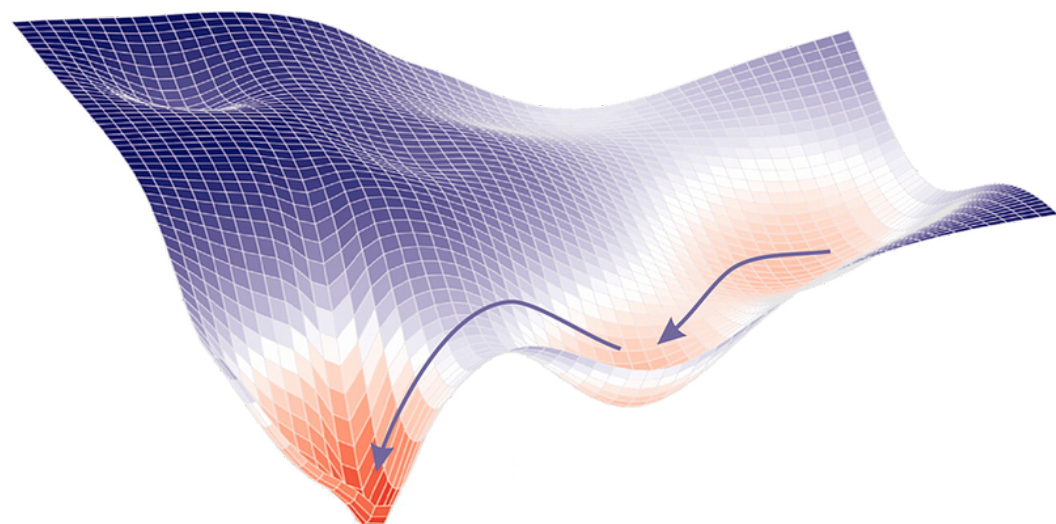
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Moderate success, but not good enough.



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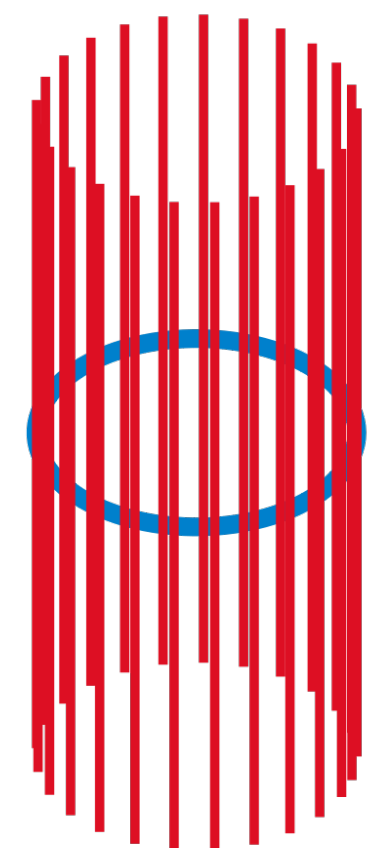
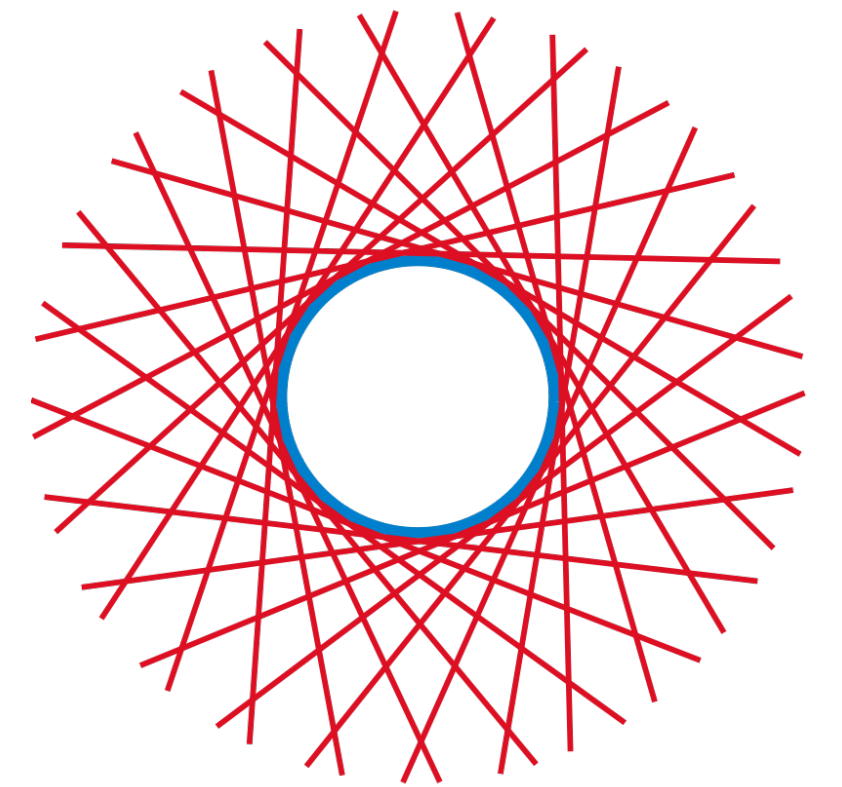
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Use line bundle cohomology to distinguish between  $X$  and  $X'$ . The quantity that is sensitive only to  $c_2(X)$  and  $d_{rst}(X)$  is the **Euler characteristic**.

*Full line bundle cohomology contains too much info (e.g. about the complex structure)/too slow to generate.*

$$\chi(X, L) = \frac{1}{12} (2 c_1(L)^3 + c_1(L) c_2(TX)) = \frac{1}{6} d_{rst} c_1^r(L) c_1^s(L) c_1^t(L) + \frac{1}{12} c_r c_1^r(L)$$





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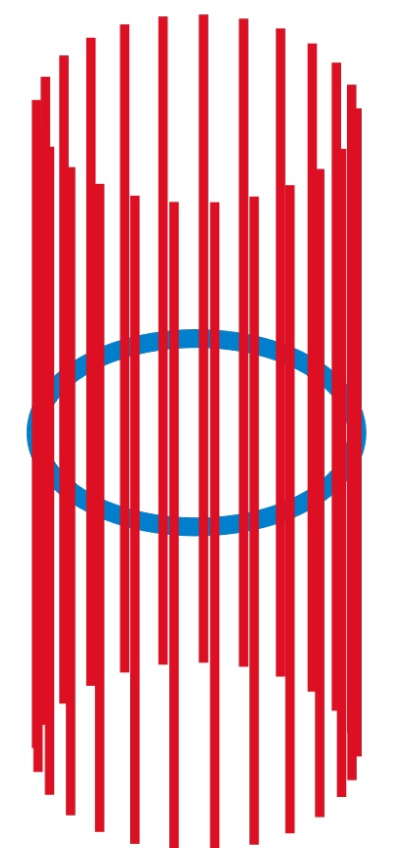
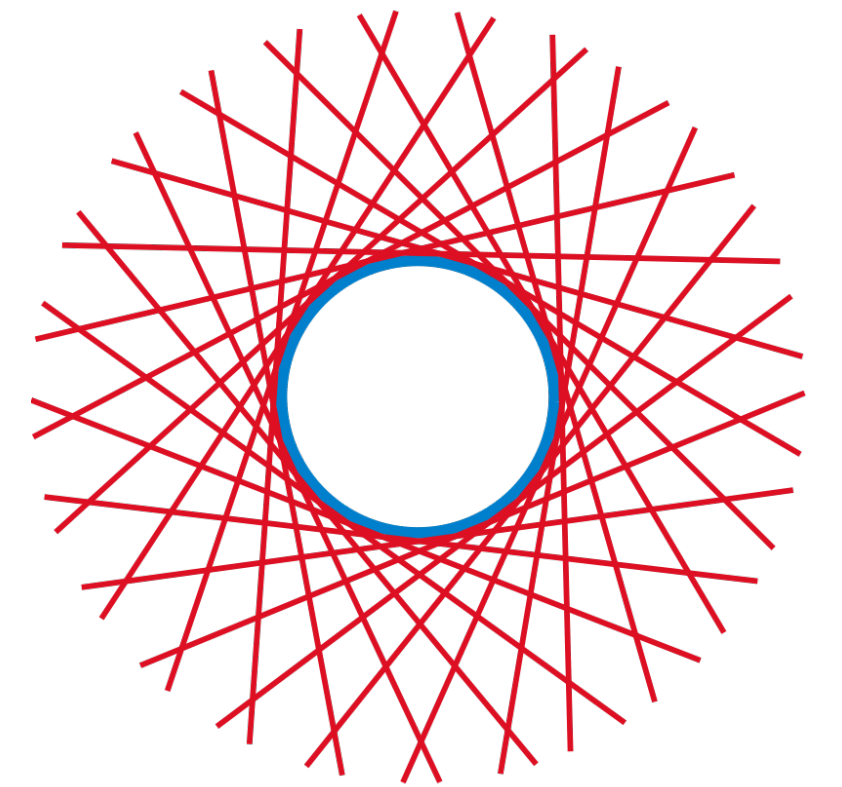
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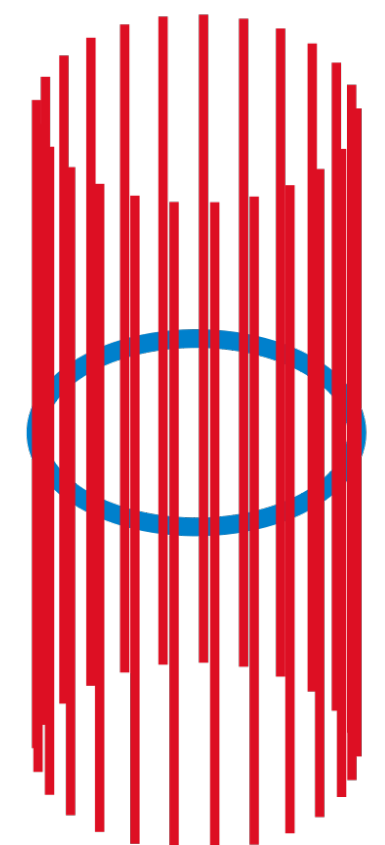
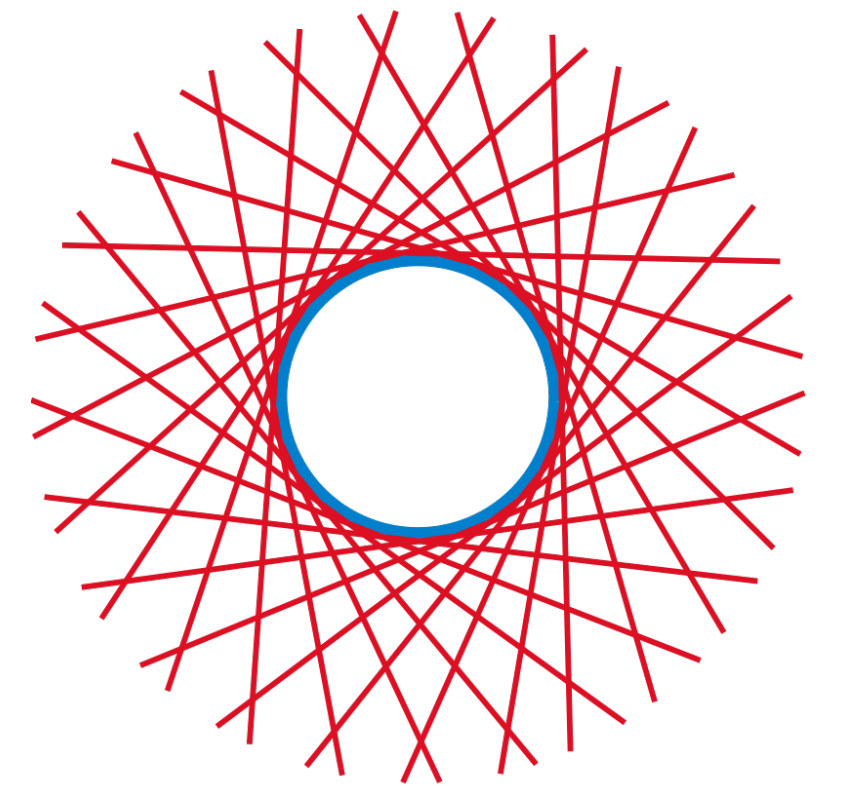
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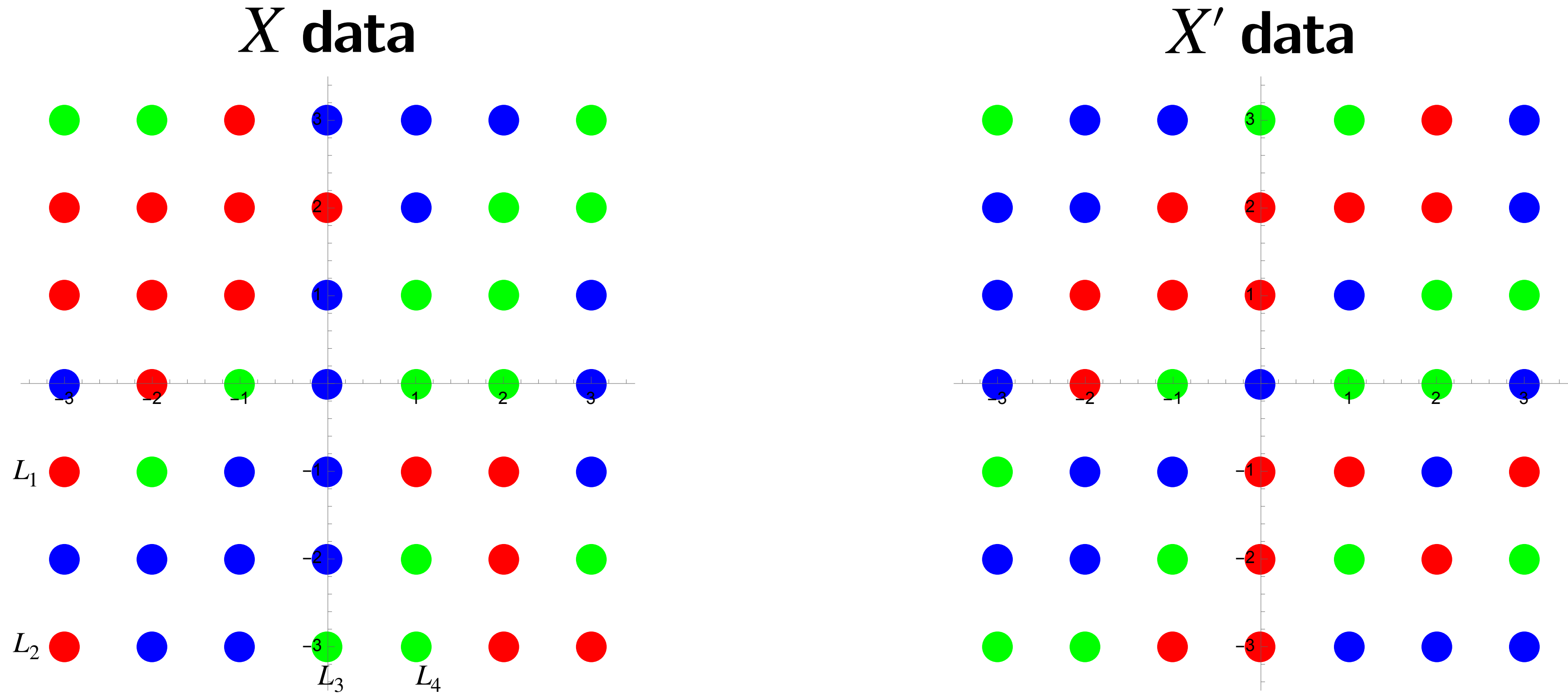
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Line bundle  $c_1^r(L)$  is an **integer** vector  $k^r$ , and so we can **reframe the problem** to that of finding which  $L$  (or  $k^r$ ) on  $X$  are mapped to which  $L'$  (or  $k'^r$ ) on  $X'$ . **Do this in a box.**

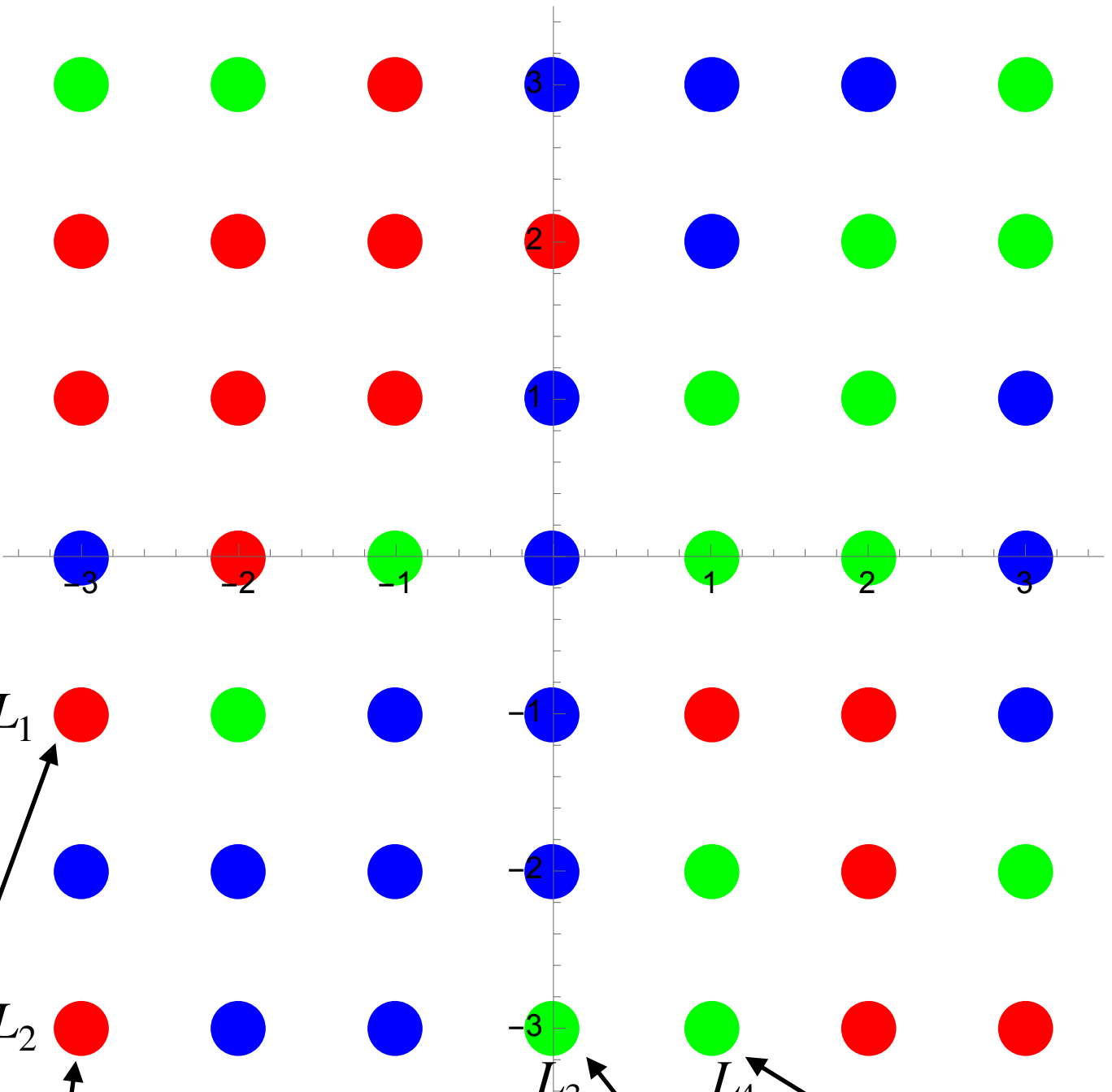


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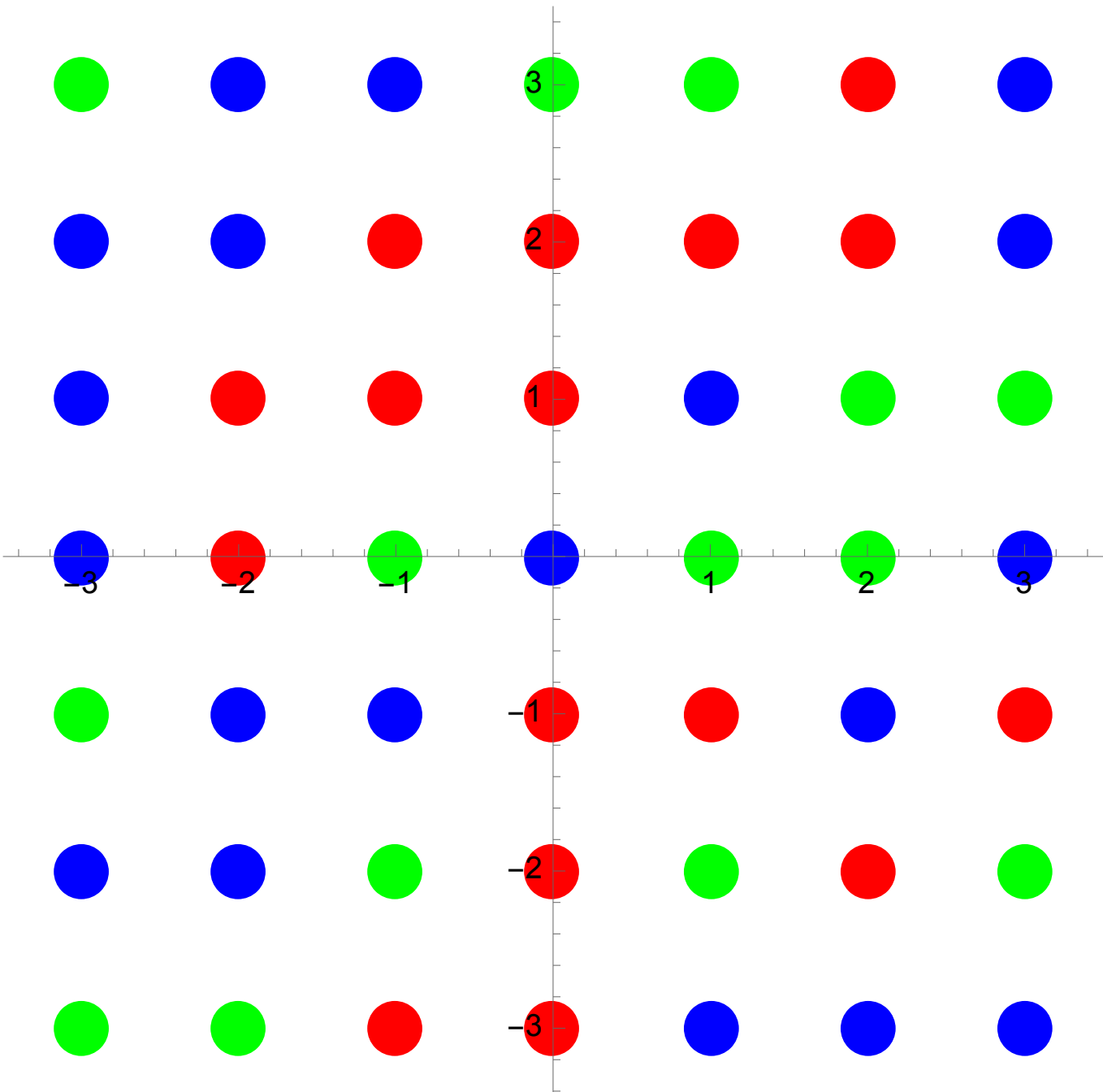
$X$  data



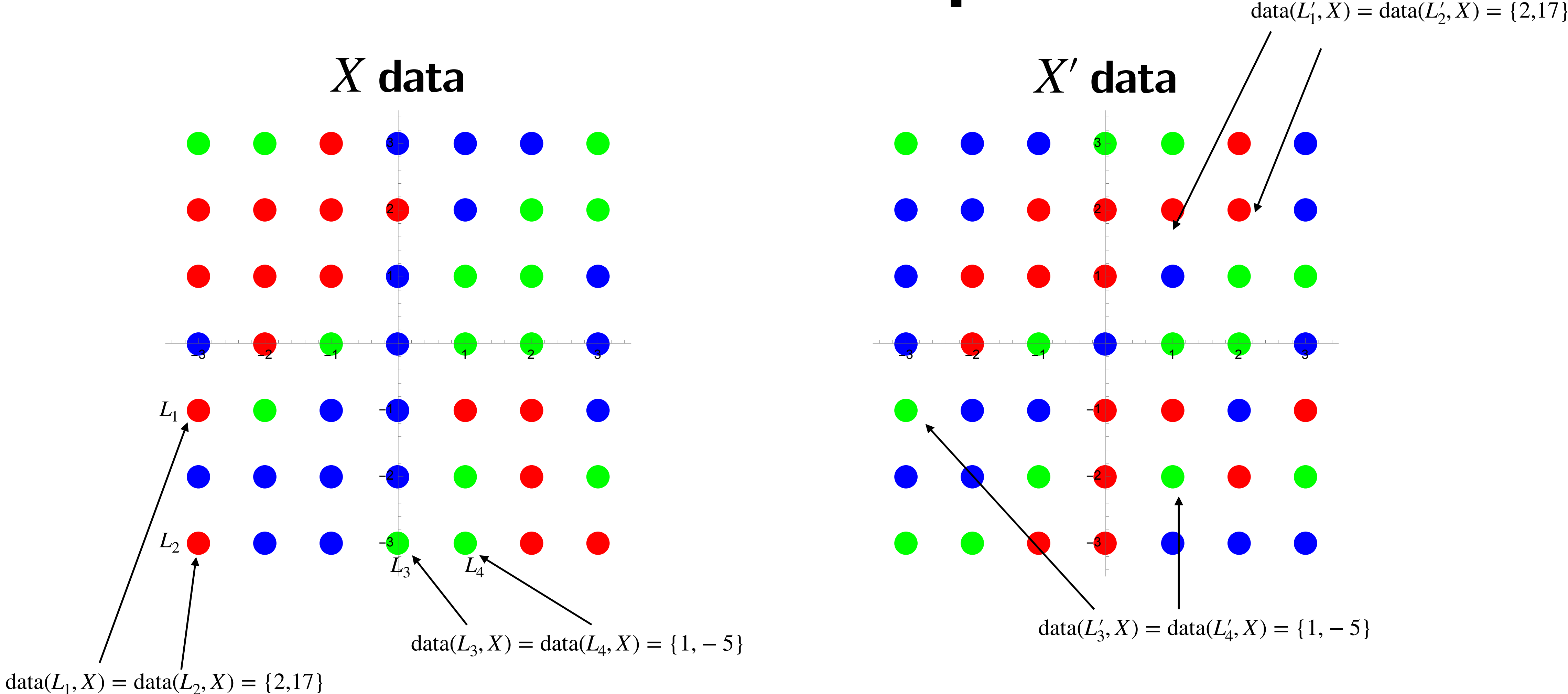
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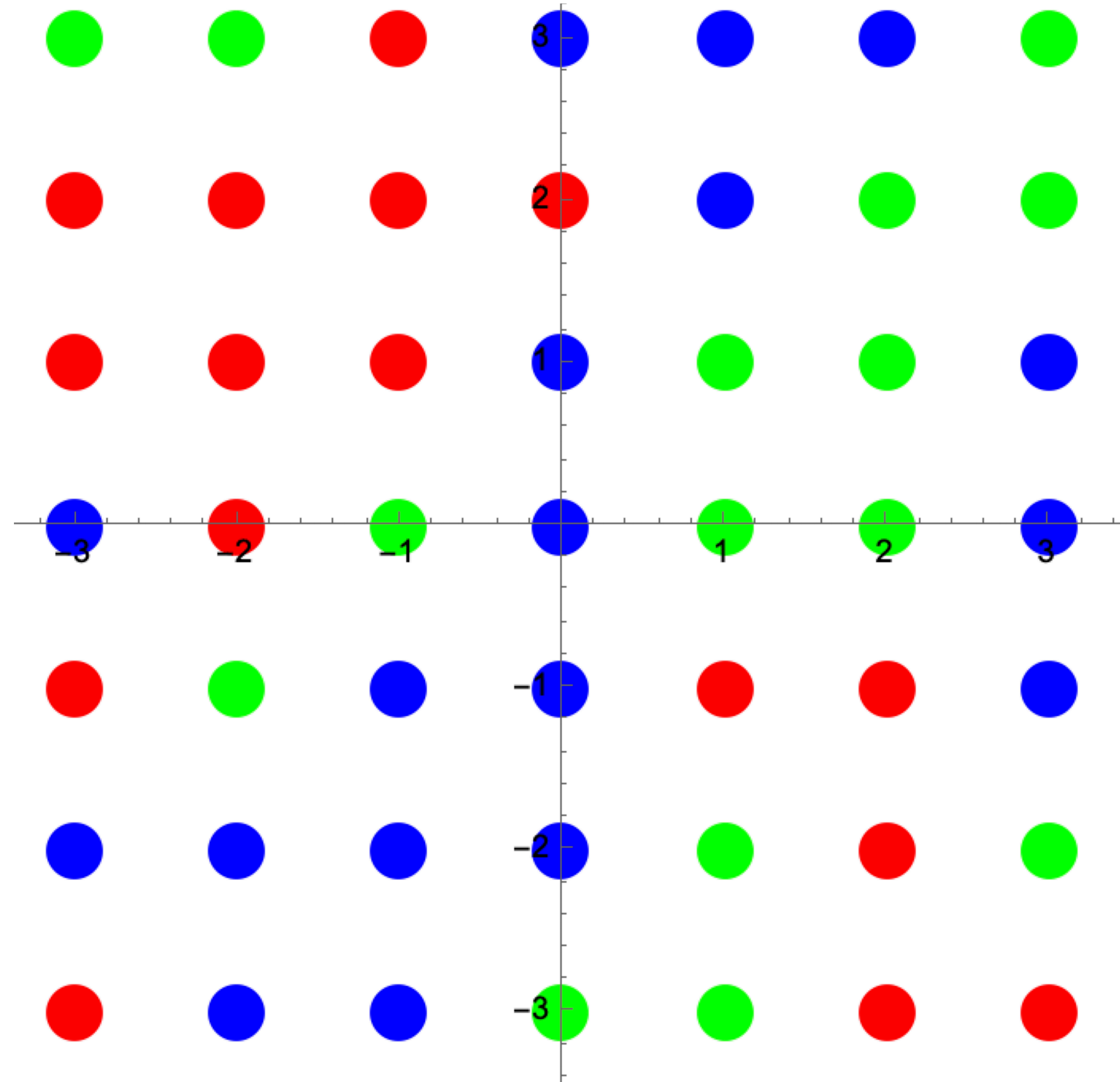
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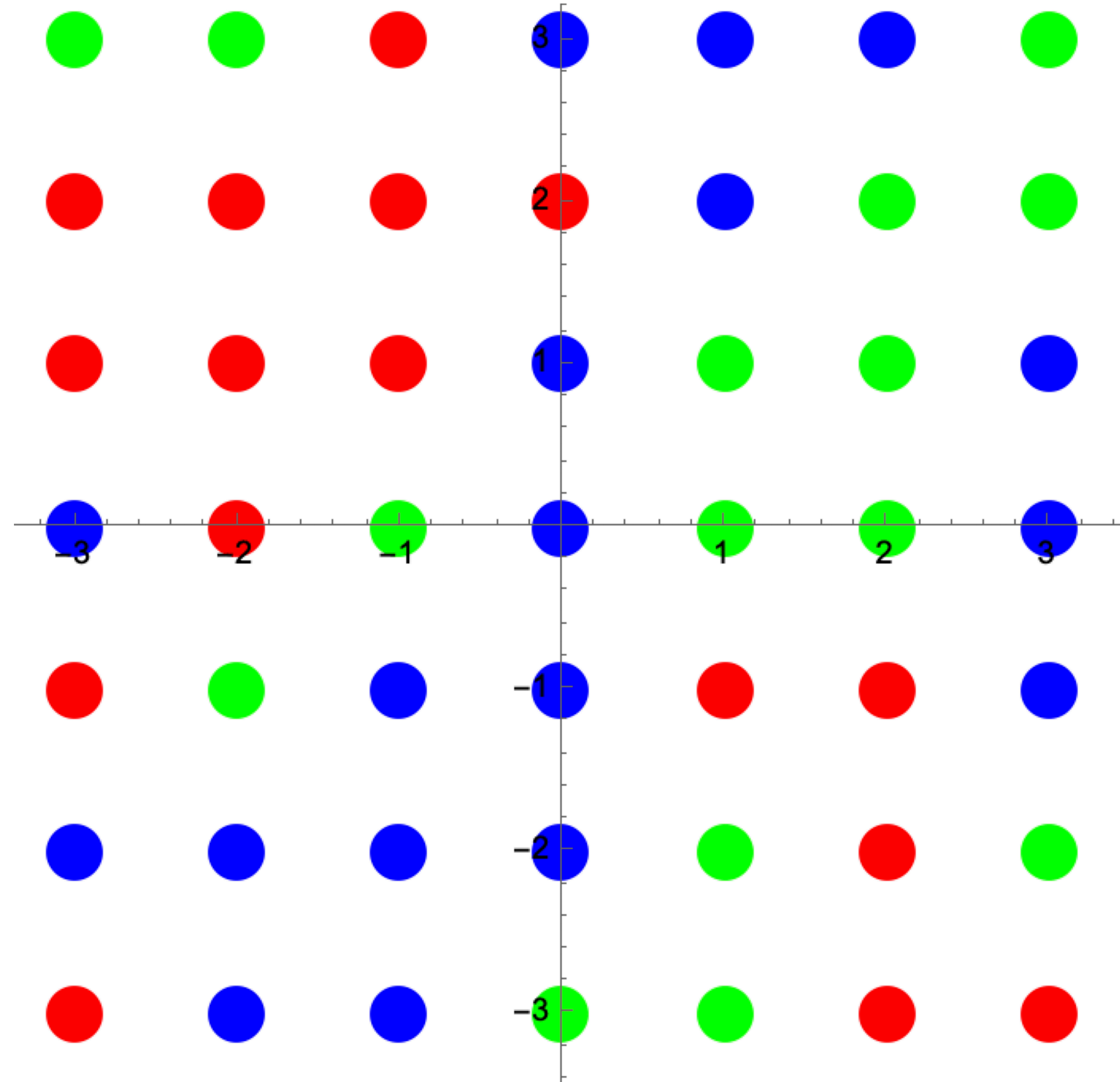
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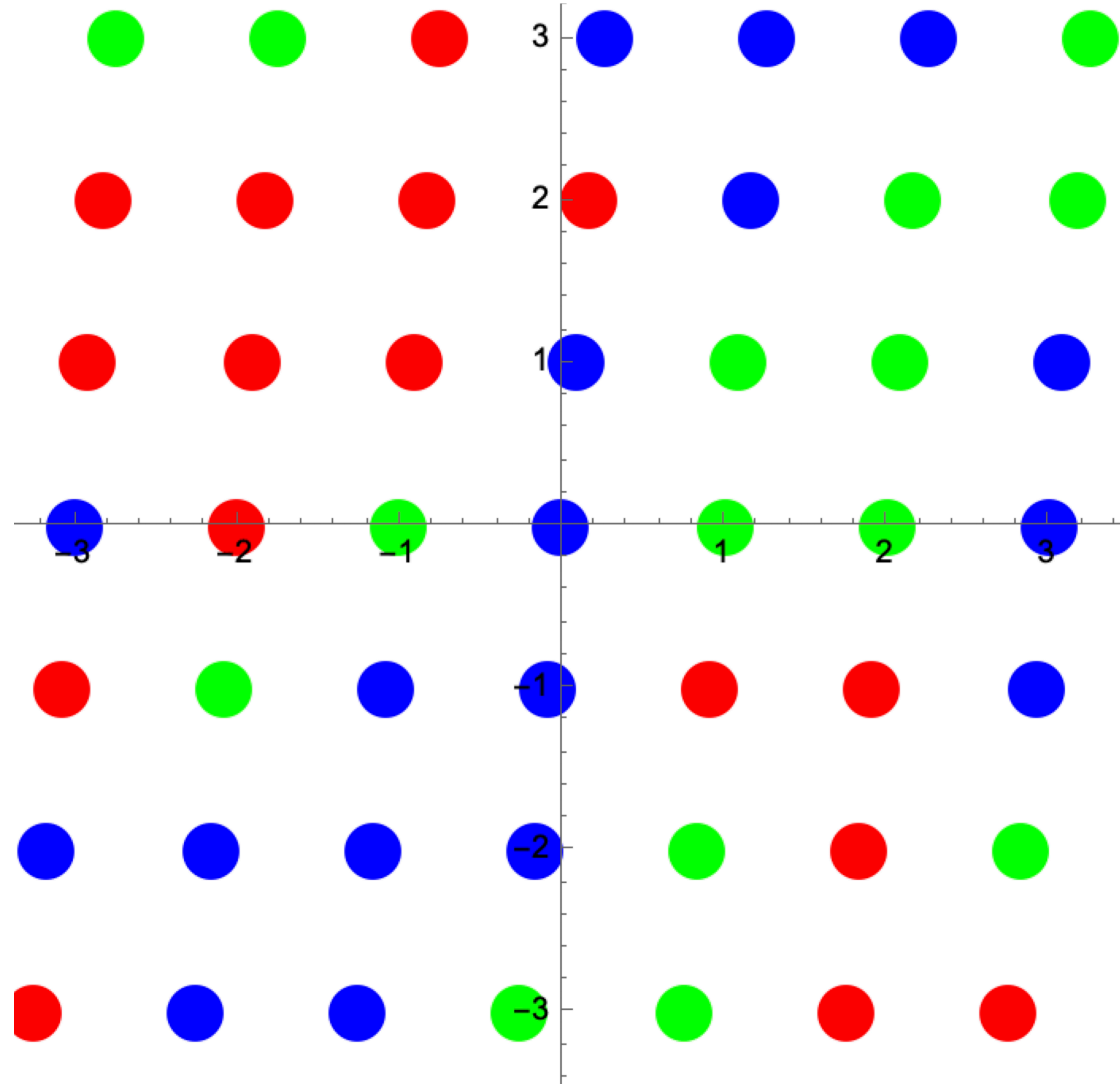
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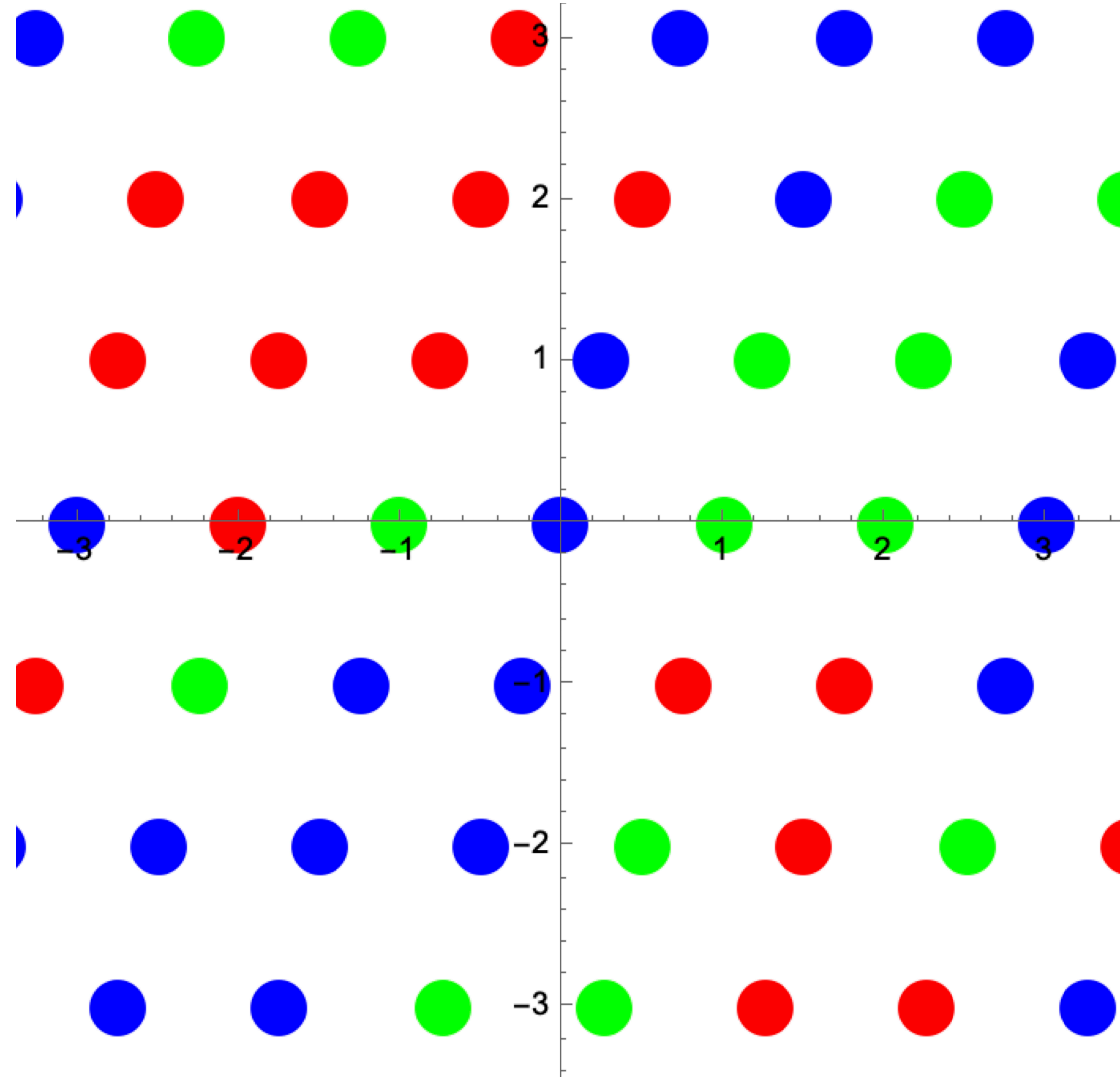


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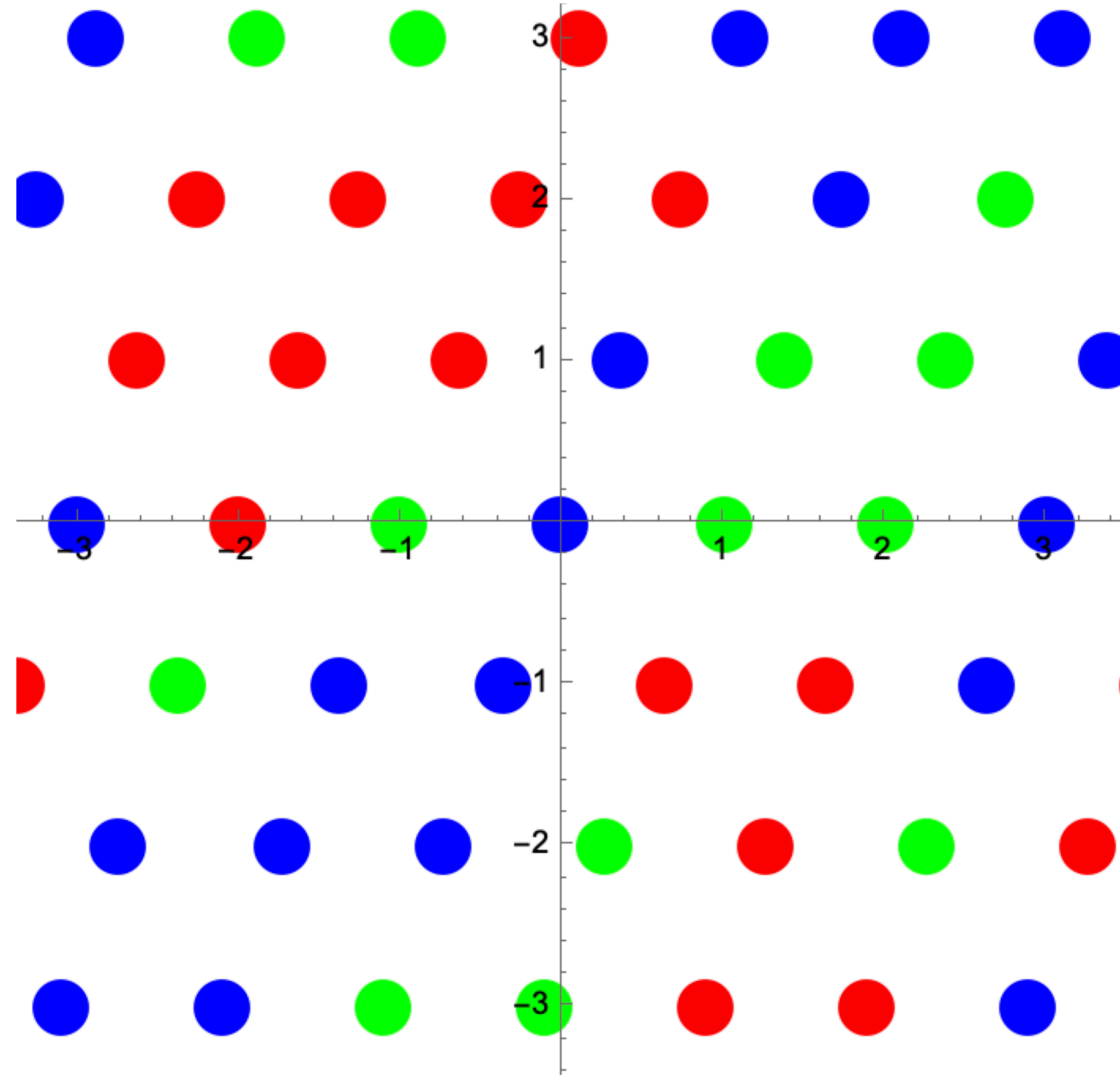




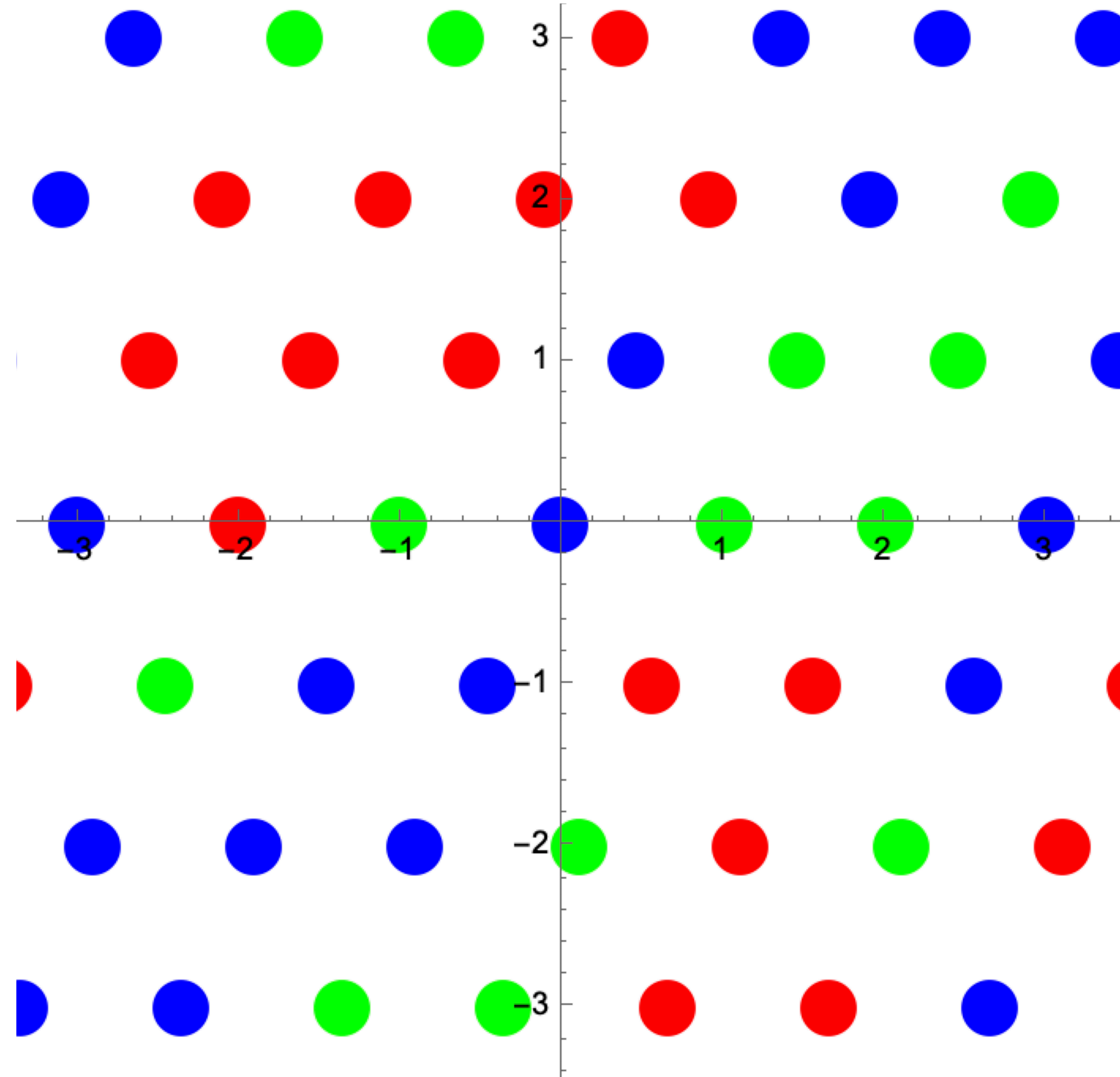
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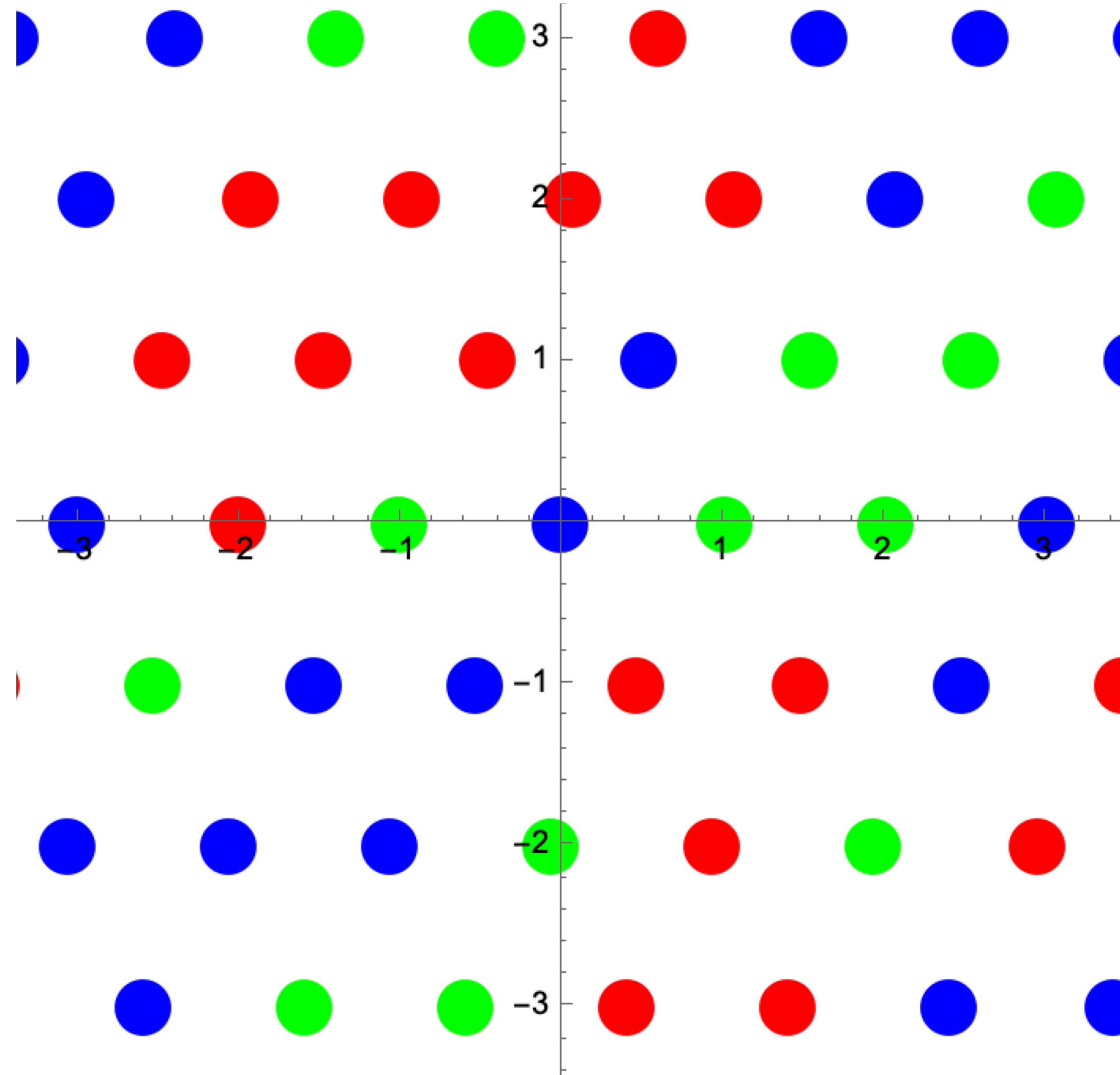
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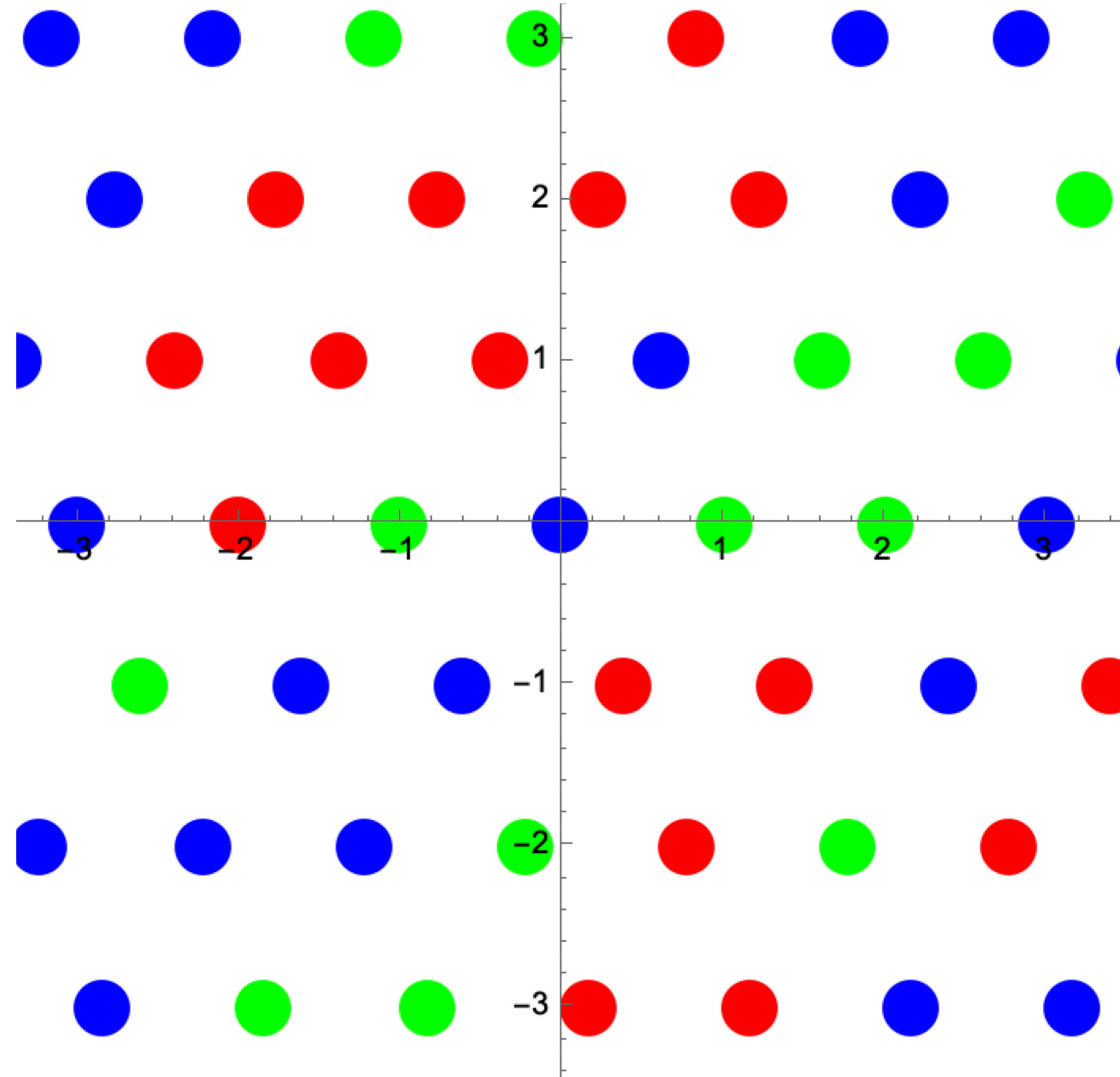
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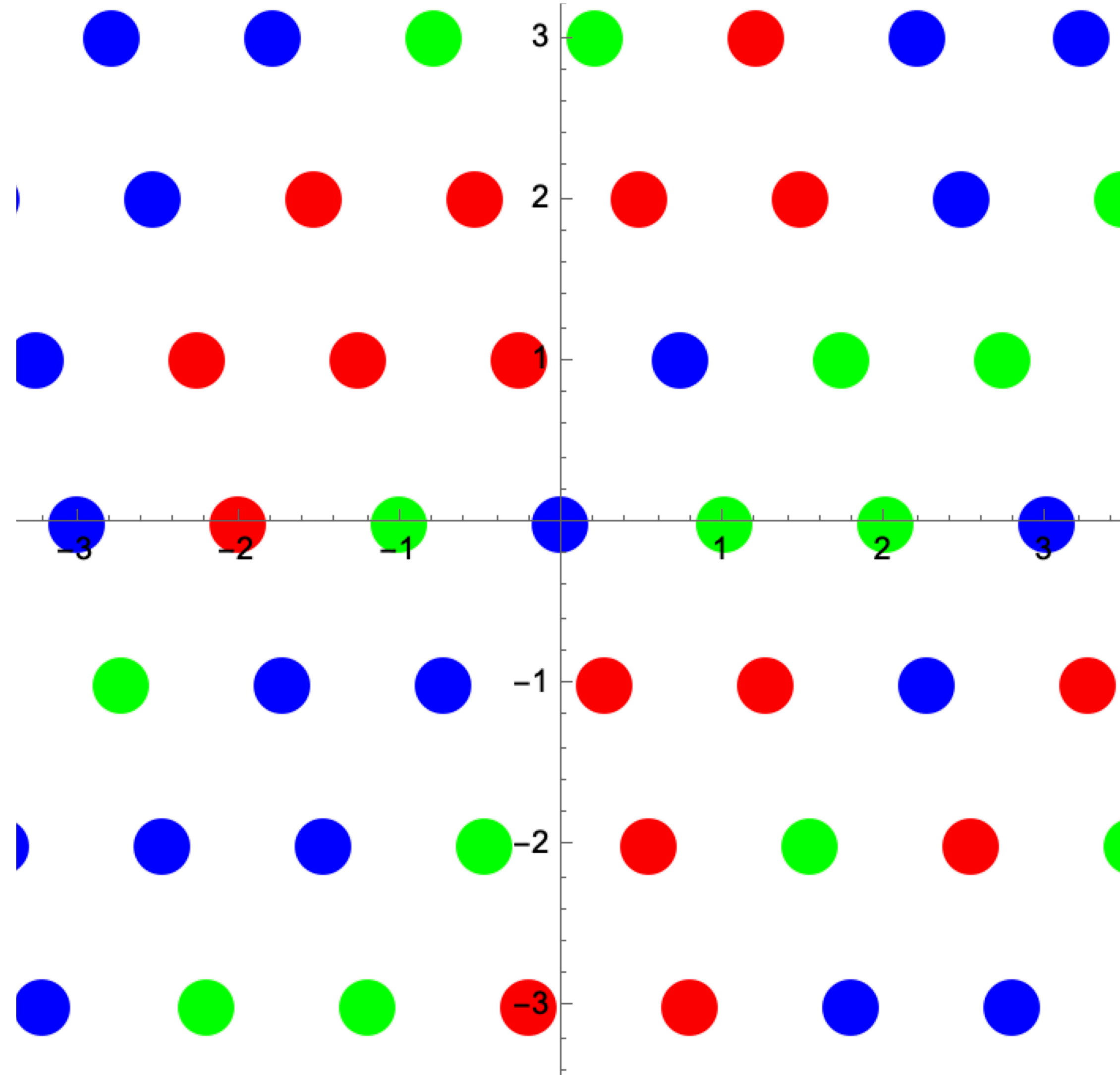
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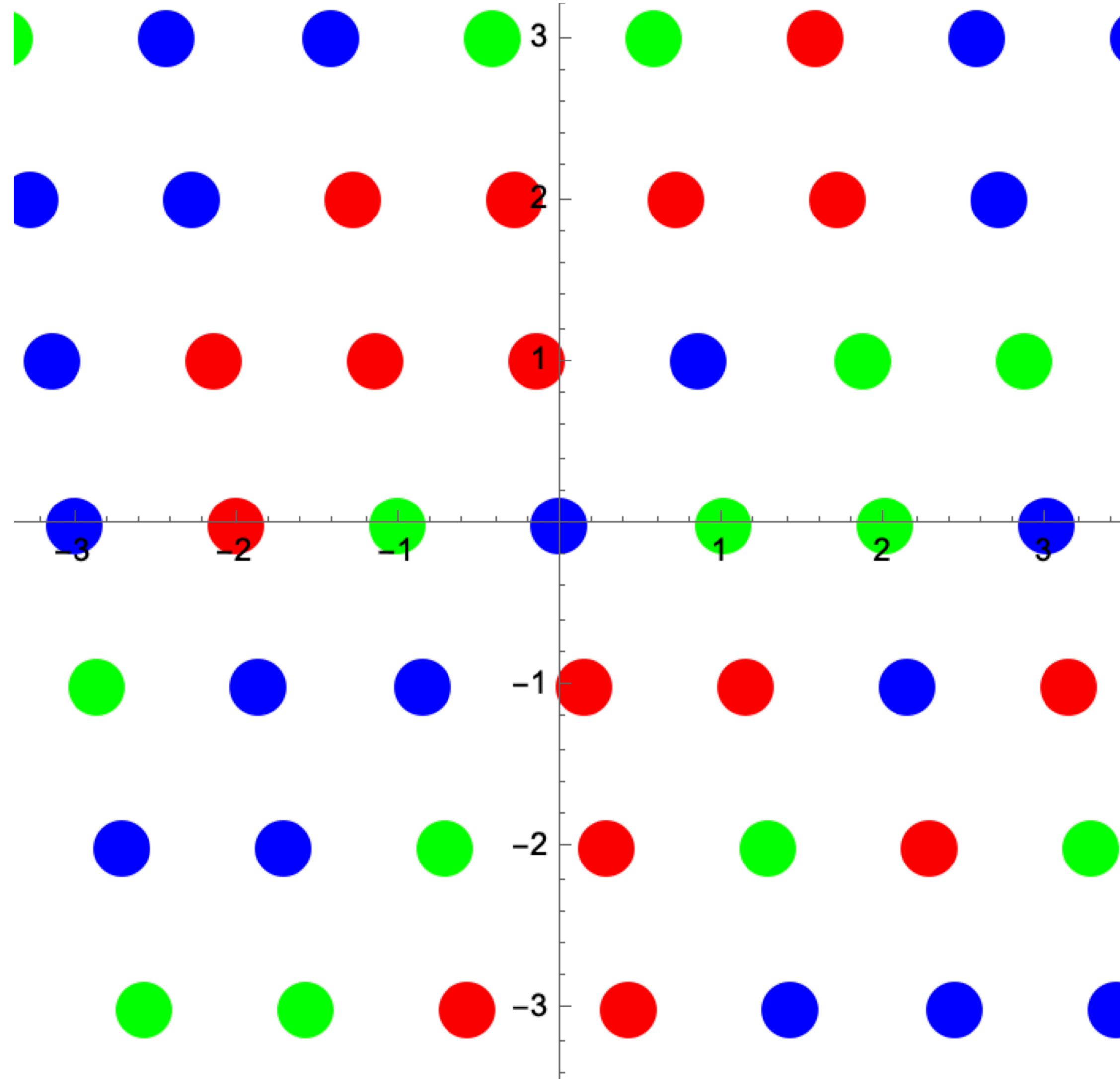
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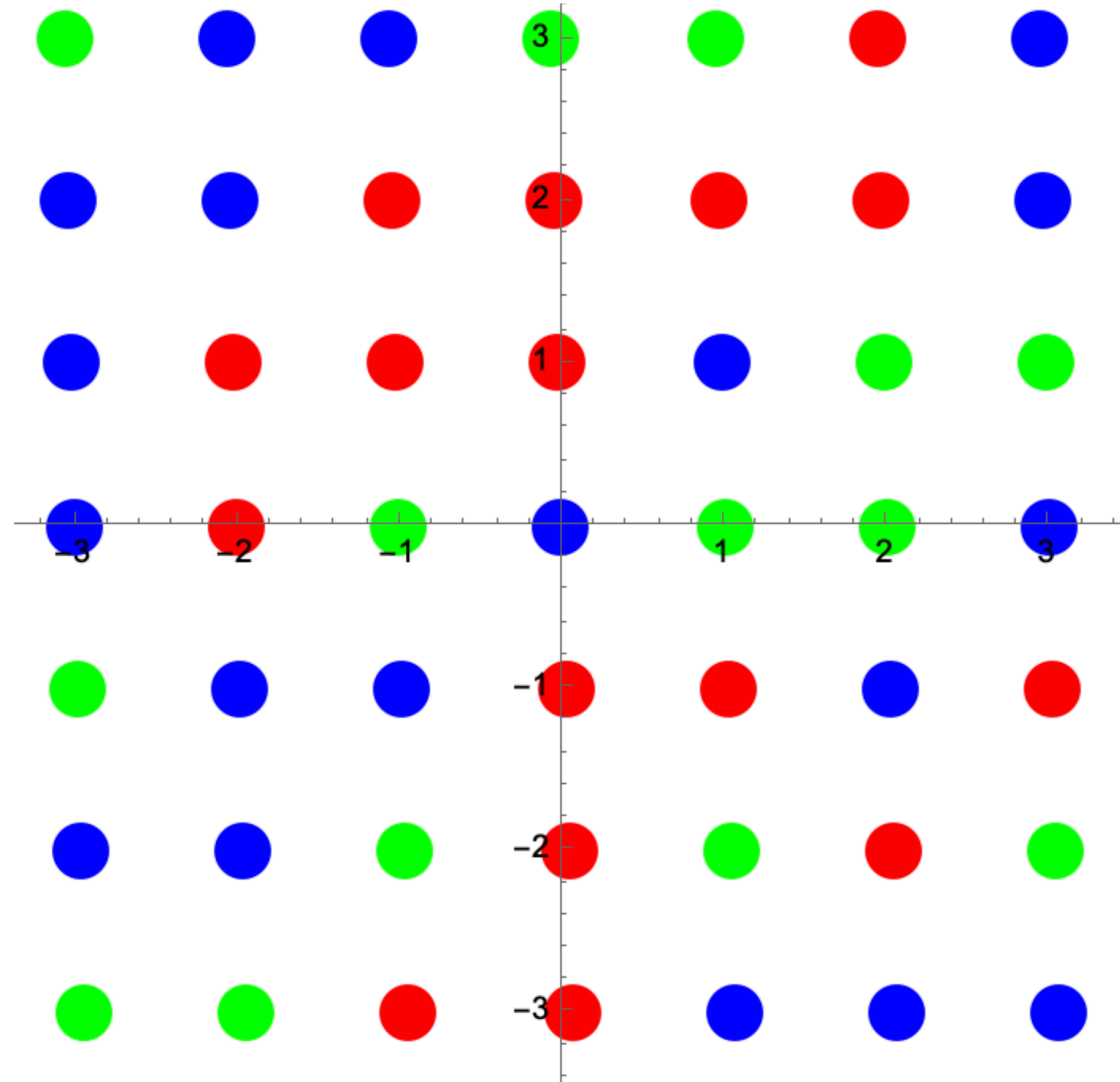
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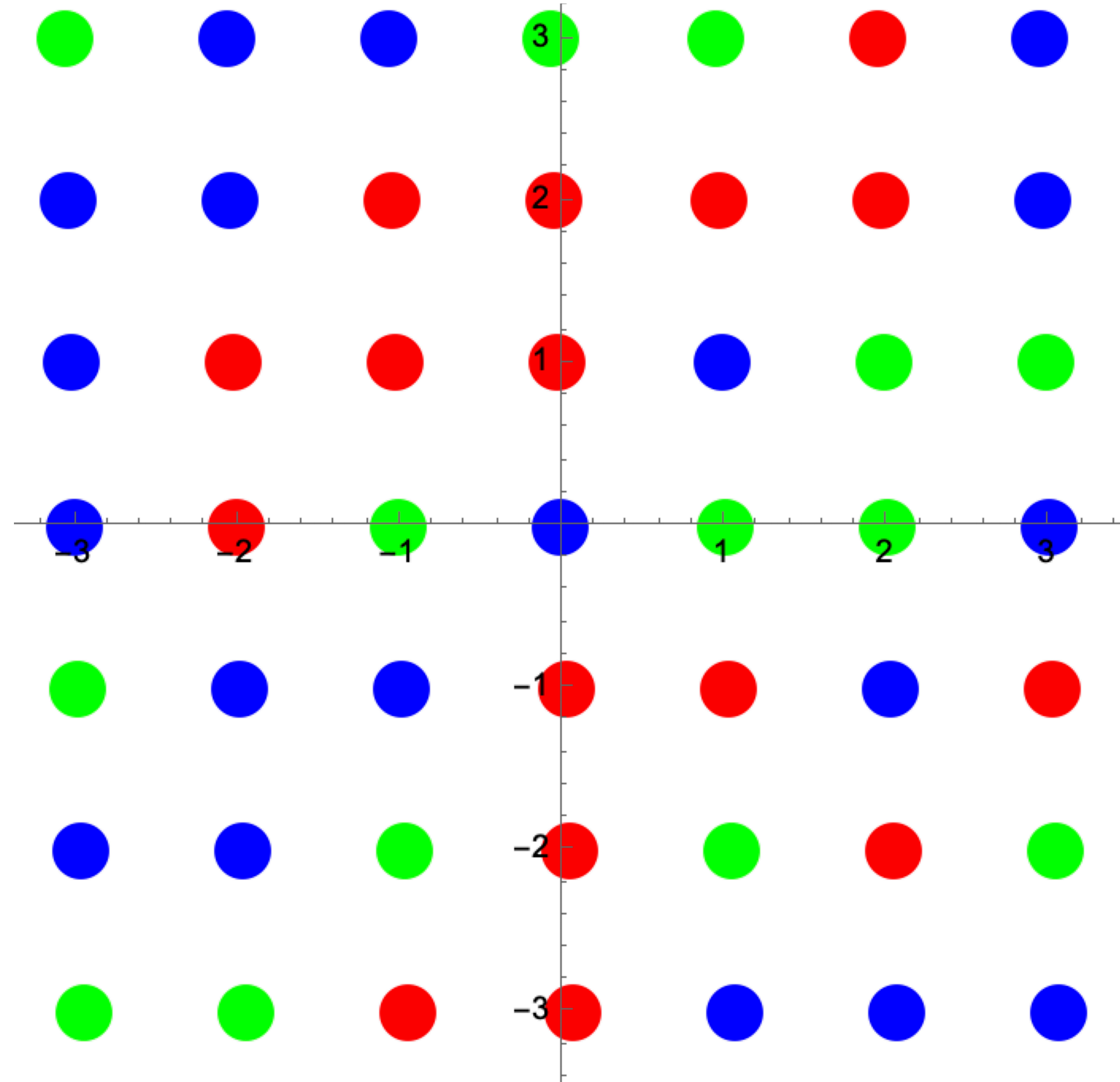


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    - *NB - if the Picard number gets too high, we will have to return to the less consistent methods described above.*

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- Two approaches:
  - **Inspired by the ‘point-set registration’** ( $\sim$  machine vision) problem above - use **coherent point drift**, a **noise-tolerant** algorithm, modified to accept ‘coloured’ line bundle data.
  - **Unit vector search algorithm.** Finds all candidate **image** points  $k'^r$  on  $X'$  of basis vectors  $\hat{k}^s$  on  $X$  (for  $k'^r$  in a box of width  $w$ ), and ensures consistency. **Guaranteed** to find any basis transformation matrix with all entries in our  $w^{(h^{11})}$  box.
    - *NB - if the Picard number gets too high, we will have to return to the less consistent methods described above.*

# Application to Kreuzer-Skarke



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**KS data up to  $h_{11} = 6$ .** (generated with *cytools* [Demirtas, Rios-Tascon, McAllister, '22])

- **Lower bound** on the number of classes comes from considering invariants
- **Upper bound** comes from explicitly finding basis transformations using line bundle algorithm with adaptive box size.

Good invariants are crucial if you want to find an **upper bound in reasonable time.**

# Application to Kreuzer-Skarke

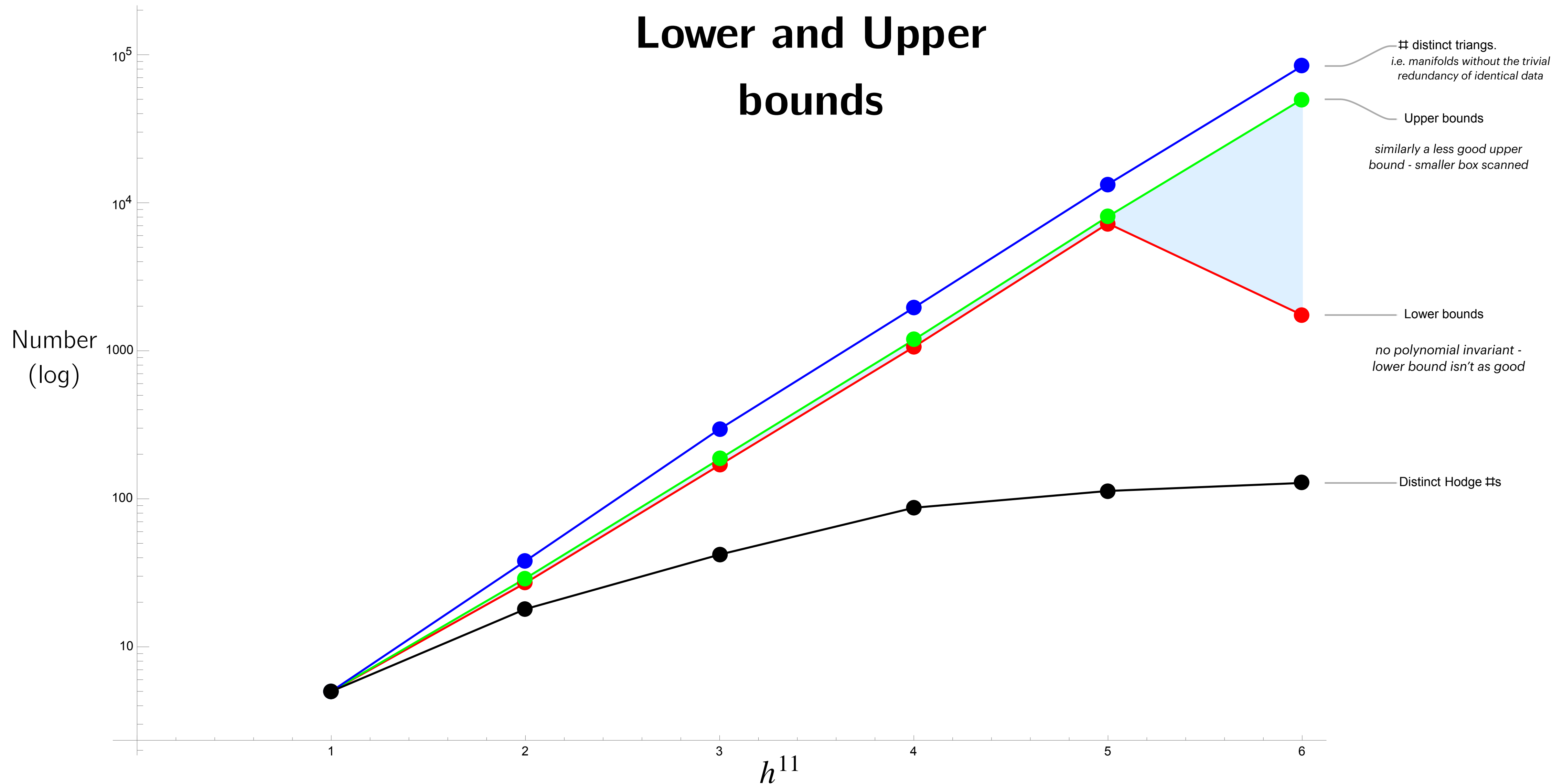
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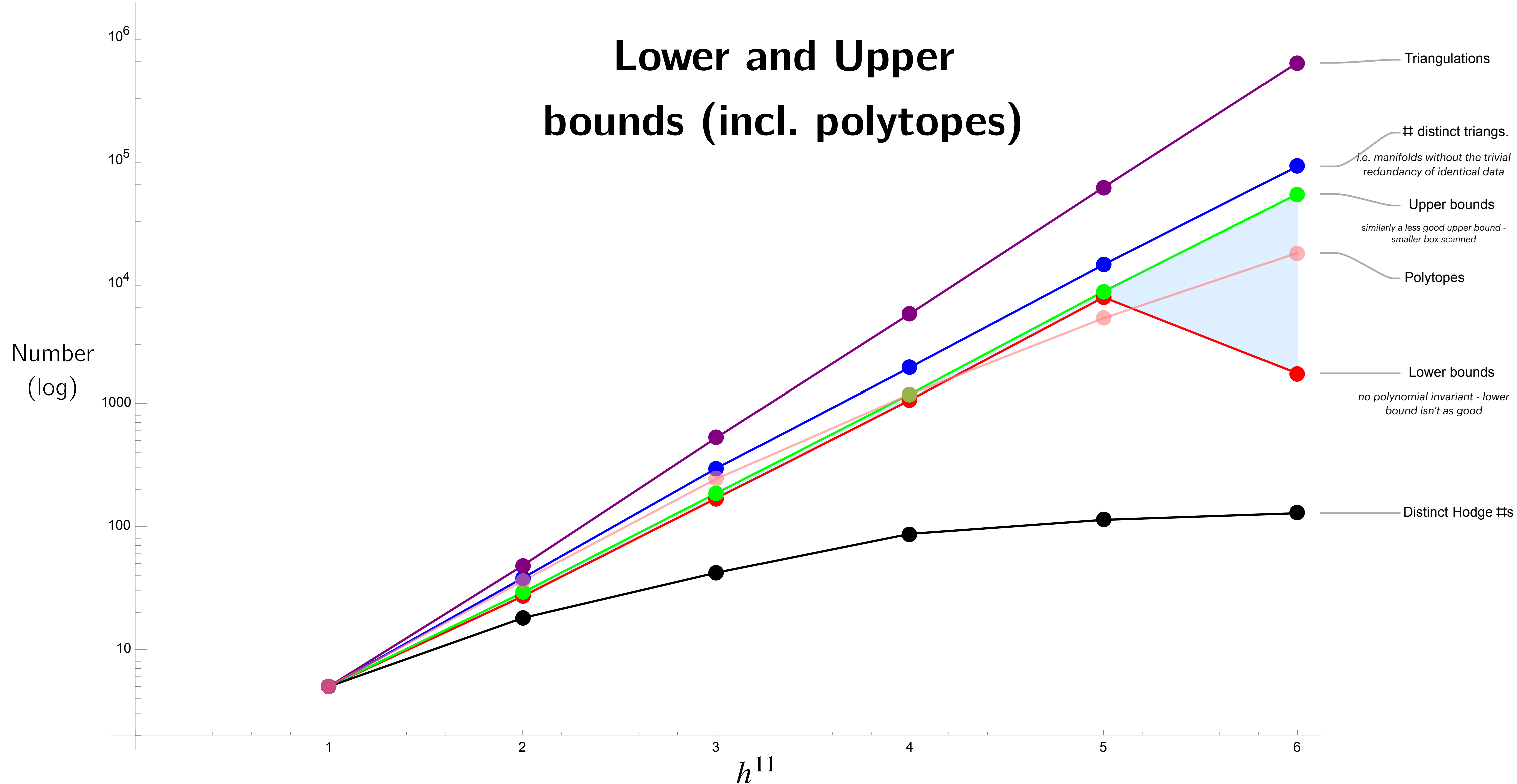
$h^{1,1}$	# Polytopes	# Triangs.	# Distinct Triangs.	Hodge #s	Lower Bound	Upper Bound
1	5	5	5	5	5	5
2	36	48	38	18	27	29
3	243	525	296	42	169	186
4	1185	5,330	1,954	87	1,061	1186
5	4896	56,714	13,330	113	7,244	8078
6	16607	584,281	83,906	128	1,744	TBC

# Lower and Upper bounds



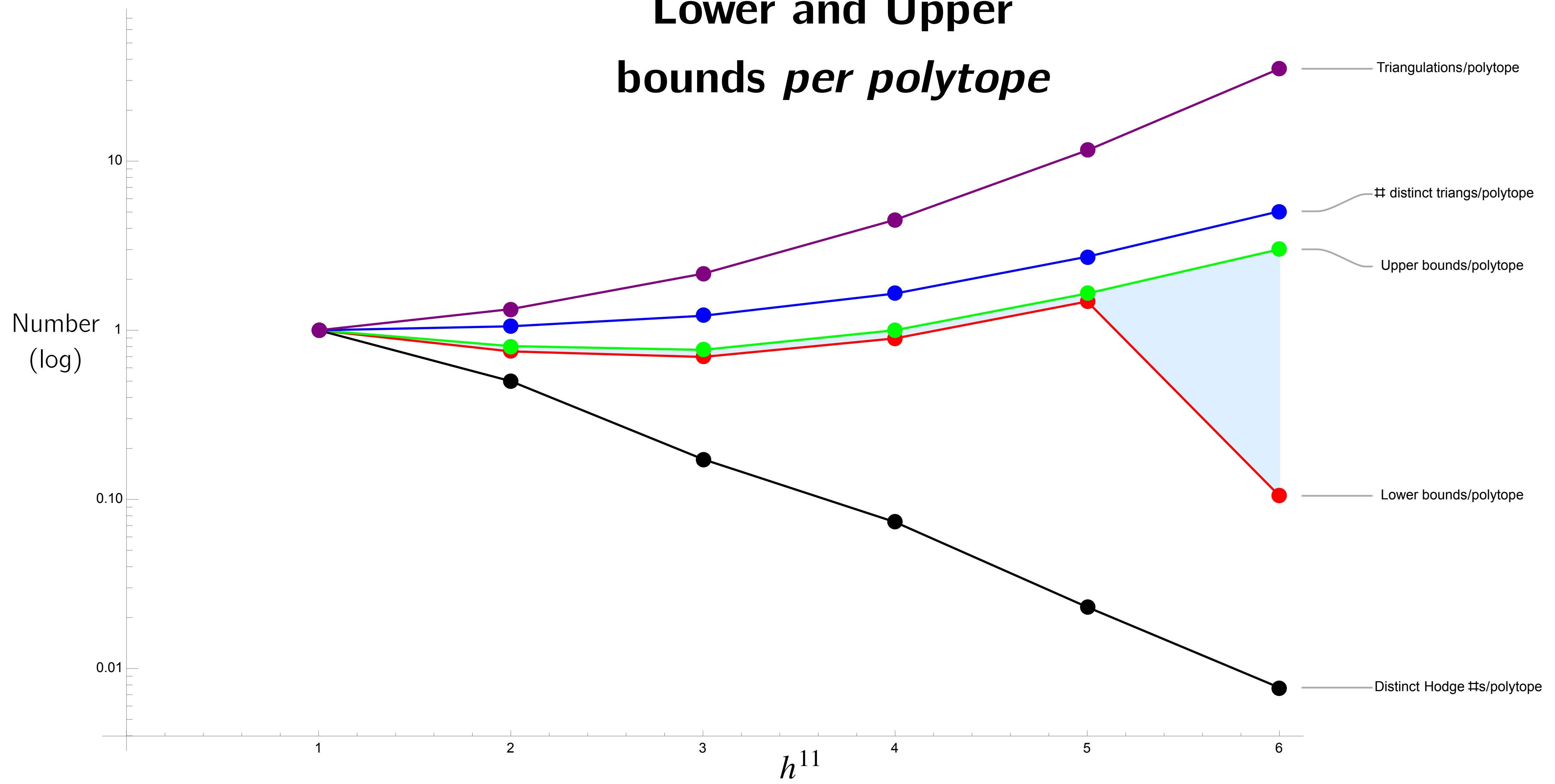
- Lesson:** the number of topological classes is increasing at **roughly the same rate** ( $\sim 10^{h^{11}}$ ) as the (numerically distinct) triangulations. We have **significantly more than the absolutely minimum** given by the distinct Hodge numbers.

# Lower and Upper bounds (incl. polytopes)



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# Lower and Upper bounds *per polytope*



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- **New techniques** for deciding equivalence of multilinear forms
- **Bounds on Kreuzer-Skarke data** for low Picard number
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## Outlook

- Is there **topological meaning** to a GCD invariant? What about the polynomial singlets? Do they represent interesting properties of the CYs?
- If we want to **extend to higher Picard number** - can we generate them more efficiently? Linear algebra may be too slow.
  - A **partial recurrence relation** exists for the degree- $2h^{11}$  invariant. Can it be completed to a full recurrence relation?
  - Can these invariants be used to **bound** the number of Calabi-Yaus at a particular  $h^{11}$ ?
  - Add the limiting mixed Hodge structure invariants mentioned above.