HGPflow: Particle flow as a Hypergraph learning task

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On behalf of the HGPflow team

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Reconstructing particles in jets using set transformer and hypergraph prediction networks

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³ICEPP, University of Tokyo
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⁵Max Planck Institute for Physics
⁶INFN and Sapienza University of Rome
Received: date / Accepted: date

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https://arxiv.org/pdf/2212.01328.pdf

Reconstructing particles in jets using set transformer and hypergraph prediction networks

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• Focus on Hypergraph (HGPflow)

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The roadmap...

- Dataset
- The Hyper graph approach (HGPflow)
- Performance
- Future work







- **COnfigurable CalOrimeter simulation for AI** ullet
 - ✓ Open source
 - ✓ PYTHIA8-GEANT4
 - ✓ Nearly hermetic
 - ✓ Easily configurable (json)

- 3 ECAL layers, 3 HCAL layers
- Inner tracker immersed in magnetic field \bullet

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- User friendly outpout •
 - Track, cells, topoclusters, truth particles Full truth record of energy deposit ✓ Jet clustering
 - Vearest neighbor graph

https://arxiv.org/abs/2303.02101 Read the doc link

Graph creation



- Single jet (quark/gluon initiated)
- No pileup \bullet

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Hypergraphs?



Hypergraph

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Hypergraph

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Hypergraph

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Hyperedges







Hypergraph

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Hyperedges





Hypergraph

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Hyperedges

Bipartite graph

Incidence matrix





Hypergraph

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Incidence matrix

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• Particle Flow = Learning a Hypergraph

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• Particle Flow = Learning a Hypergraph





• Particle Flow = Learning a Hypergraph



Truth particles (Unknown)

Detector readout

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Reconstructed particles

• Particle Flow = Learning a Hypergraph



Truth particles (Unknown)

Detector readout

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• Particle Flow = Learning a Hypergraph



Truth particles (Unknown)

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Detector readout

• Particle Flow = Learning a Hypergraph



Truth particles (Unknown)

Detector readout

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Reconstructed particles

• Particle Flow = Learning a Hypergraph



(Unknown)

Detector readout

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Reconstructed particles

Detector readout

• Particle Flow = Learning a Hypergraph

Target Hypergraph



Truth particles (Unknown)

Detector readout

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Predicted Hypergraph (Set2Set)



Reconstructed particles

Detector readout

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Detector data (Tracks, cells)

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Detector data (Tracks, cells)

Encoded data

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Detector data (Tracks, cells)

Encoded data

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Hypergraph



Detector data (Tracks, cells)

Encoded data

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Hypergraph



Detector data (Tracks, cells)

Encoded data

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Hypergraph



Encoding





Detector readout

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Detector data (Tracks, cells)

Encoded data

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Hypergraph

Particles



Incidence matrix

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Incidence matrix

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Particles 30 GeV Topocluster 10 GeV 40 GeV



Incidence matrix

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Particles







Incidence matrix

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Particles





Indicator

- Variable number of particles
- Indicator to the rescue!



Always k particles

Indicator

Incidence matrix

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 $(n \times n) \rightarrow (n \times k)$

Incidence matrix
Learning the Hypergraph

Recurrently Predicting Hypergraphs

David W. Zhang University of Amsterdam w.d.zhang@uva.nl

TNO

Gertjan J. Burghouts gertjan.burghouts@tno.nl

Aligns well with our Physics motivations

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https://arxiv.org/pdf/2106.13919.pdf

Recurrently learning Hypergraph

Recurrence! (X16)



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 $G(\mathcal{V}, \mathcal{E}, \mathcal{I})$

raget	E
-------	---

Recurrently learning Hypergraph

Recurrence! (X16)



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 $G(\mathcal{V}, \mathcal{E}, \mathcal{I})$

raget	E
-------	---

Recurrently learning Hypergraph

Recurrence! (X16)



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 $G(\mathcal{V}, \mathcal{E}, \mathcal{I})$





raget	E
-------	---



raget	E
-------	---



Detector data (Tracks, cells)

Encoded data

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Particles

Hypergraph

Proxy properties

With the incidence matrix, we already know a lot about the particles! lacksquare

- For charged particles, \bullet
 - The tracks are a good (but not perfect) representation of the particles
 - Let's use it and improve over it



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• E = E1 + E2 = 15GeV









• E = E1 + E2 = 15GeV

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$$\eta = \frac{7\eta_1 + 8\eta_2}{15}$$

 \bullet





• E = E1 + E2 = 15GeV

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$$\eta = \frac{7\eta_1 + 8\eta_2}{15}$$

 \bullet

$$\bullet \quad \phi = \frac{7\phi_1 + 8\phi_2}{15}$$

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• E = E1 + E2 = 15GeV
•
$$p_T = \frac{E}{cosh(\eta)}$$



$$\eta = \frac{7\eta_1 + 8\eta_2}{15}$$

 \bullet

$$\bullet \quad \phi = \frac{7\phi_1 + 8\phi_2}{15}$$

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Additional network

Proxy properties Neural Network

 p_T

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Correction to proxy properties

Particle $pT = p_T + \Delta p_T$

 Δp_T

Overall architecture



Input

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Output







Neutral particles

- HG can understand overlapping showers more precisely
- Helps in better reconstruction

0.07

0.06

0.05 0.04 -

- . 9.03 9.03
 - 0.02
 - 0.01
 - 0.00





Neutral particles



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Neutral particles (photons)



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Neutral particles (neutral hadrons)



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lacksquare

PPflow is optimized for jet 0.14 resolution,

ML algos were not trained on this \bullet objective

0.1210.10-0.08 م 0.06

- 0.04
- 0.02
- 0.00

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Improved Resolution!



Jet constituent



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Jet constituent



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Generalization (gluon jets)

Similar story as before \bullet 0.14 -HGPflow generalizes pretty well to \bullet 0.12the gluon jets as well! U.10 . 0.08 0.06 0.06 0.04

- 0.00



Interpretability

- Advantages of learning energy-based incidence matrix
 - Inductive-bias towards energy conservation (softmax)
 - Proxies

- Interpretable fake, inefficiency
 - Supervised links b/w particle and input nodes

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Nodes (Tracks, topoclusters)



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What's next?

What's next?

- Moving onto full event
 - Try training on full events
 - Partition the events and run HGPflow on each partition; combine the output
 - Conserves locality

Pileup lacksquare

Event Display

Reconstruction with HGPflow



Thank you...

Thank you

Data composition

•	Cardinality	tracks -
•	Track	
		topoclusters [10 ¹]
		graph edges [10 ³]
		photons -
		nu. hadrons -
		ch. particles -

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Hungarian matching

- Truth particles and predicted particles are both sets
- Need to find matches b/w the two sets of particles

• Hungarian matching with the metric

•
$$\left(\frac{\Delta p_T}{p_T}\right)^2 + \Delta R^2$$

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Initialization of the HG

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Initialization of the HG



Initialization of the HG

Nodes, $\mathcal{V}_{i}^{t=0} = \text{output of Encoding}$

Hyperedges, $\mathscr{E}_{i}^{t=0} =$ Random initialization from Gaussian noise

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Initialization of the HG

Hyperedges, $\mathscr{E}_{i}^{t=0} =$ Random initialization from Gaussian noise

Incidence, $\mathscr{I}_{i,i}^{t=0} = 0$; (no connectivity)

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Nodes, $\mathcal{V}_{i}^{t=0} = \text{output of Encoding}$

Refinements

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 $G^{t}(\mathcal{V}^{t}, \mathscr{E}^{t}, \mathscr{I}^{t})$



 $G^{t}(\mathcal{V}^{t}, \mathcal{E}^{t}, \mathcal{I}^{t})$

 $\mathcal{J}_{i,j}^{t} = \phi_{I} \left(v_{j}^{t-1}, e_{i}^{t-1}, \mathcal{J}_{i,j}^{t-1} \right)$



 $G^{t}(\mathcal{V}^{t}, \mathscr{E}^{t}, \mathscr{I}^{t})$





 $G^{t}(\mathcal{V}^{t}, \mathscr{E}^{t}, \mathscr{I}^{t})$



 $v_j^{t-1}, \rho_{e \to v}(j, t), v_j^0$





 $G^{t}(\mathcal{V}^{t}, \mathcal{E}^{t}, \mathcal{I}^{t})$





 $G^{t}(\mathcal{V}^{t}, \mathscr{E}^{t}, \mathscr{I}^{t})$





 $G^{t}(\mathcal{V}^{t}, \mathcal{E}^{t}, \mathcal{I}^{t})$





 $G^{t}(\mathcal{V}^{t}, \mathscr{E}^{t}, \mathscr{I}^{t})$

DeepSet





 $G^{t}(\mathcal{V}^{t}, \mathscr{E}^{t}, \mathscr{I}^{t})$

 $\mathcal{I}_{i,j}^t = \phi_I \left(v_j^{t-1}, \right)$

DeepSet $\mathcal{V}^{t} = \phi_{V} \left(\begin{cases} \left[v_{j}^{t-1}, \rho_{e \to v} \right] \right) \right)$

 $\mathscr{E}^{t} = \phi_{E} \left(\left\{ e_{i}^{t-1}, \rho_{e \to v}(i, t) \right\} \right)$

$$(j, t), \quad v_{j}^{0}] | j = 0, 1, 2, ... \}$$

Composition



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Charged particle pT resolution

- Improvement in resolution
- Specifically at high pT



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