

Modelling Dust Interactions Using a Fully Kinetic Numerical Framework

Jan Deca

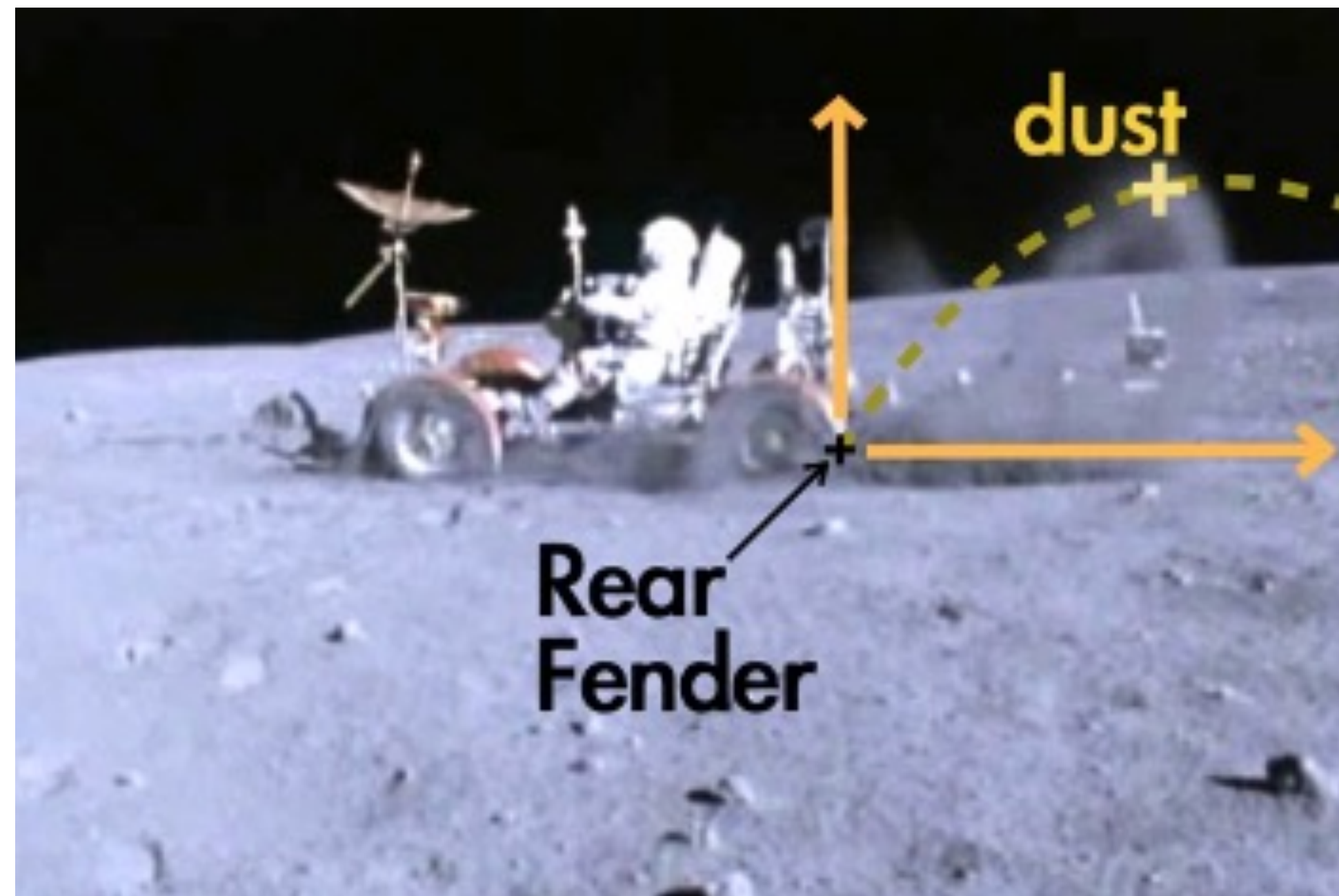
**Laboratory for Atmospheric & Space Physics
University of Colorado Boulder**

In collaboration with M. Horányi, H.-W. Hsu, and X. Wang.

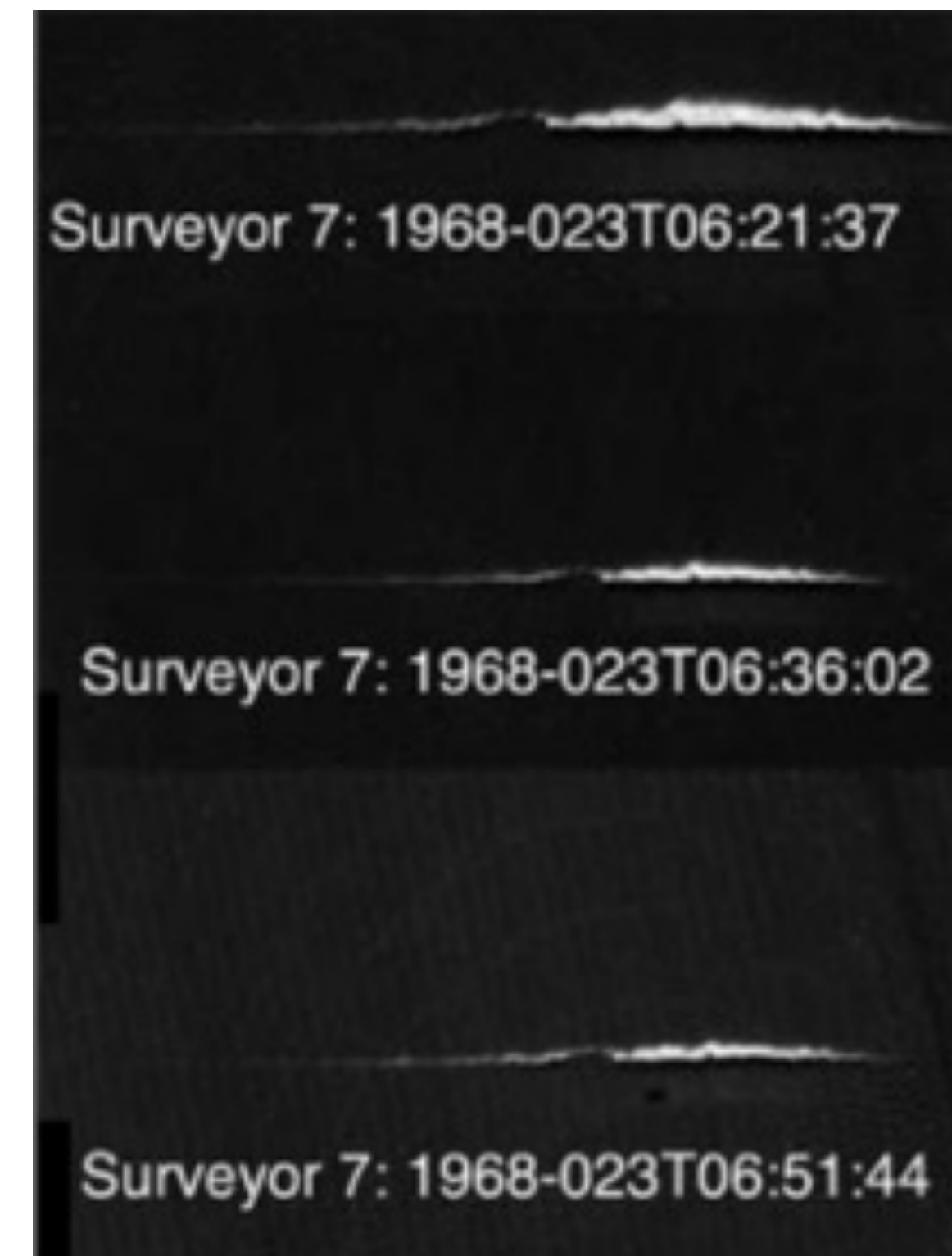
This work was supported in part by NASA's Early Stage Innovation (ESI) Appendix of SpaceTech-REDDI, Grant No. 80NSSC21K0226, and the NASA High-End Computing (HEC) Program through the NASA Advanced Supercomputing (NAS) Division at Ames Research Center.

Dust Transport.

- Dust transport - driven by impacts, exposure to solar wind plasma and ultraviolet radiation - shapes the properties of the lunar regolith.
- Dust is also mobilised by human activities, representing both a technical and a health hazard.

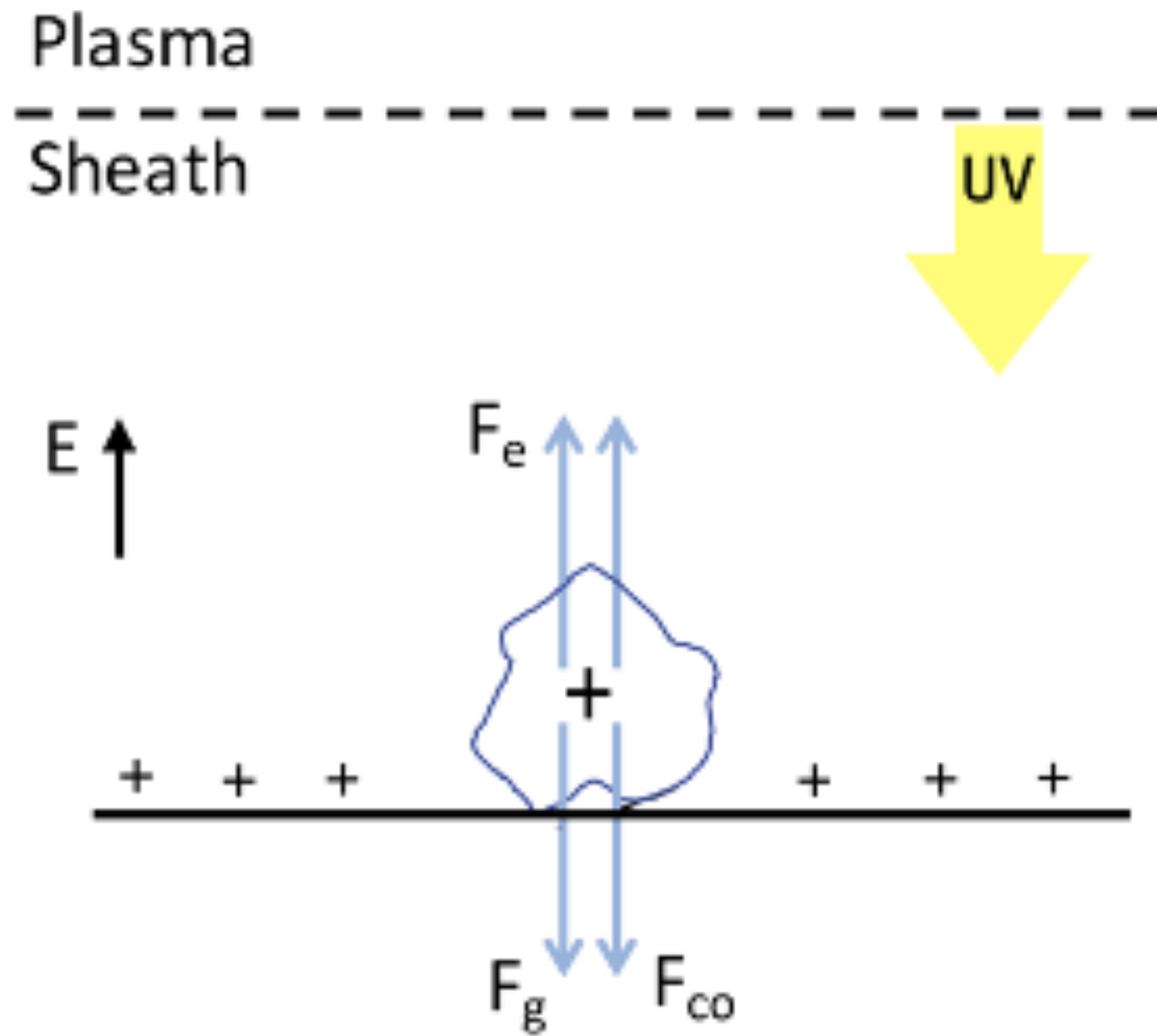


[Dust particles in the LRV trails; Hsu & Horányi 2012]

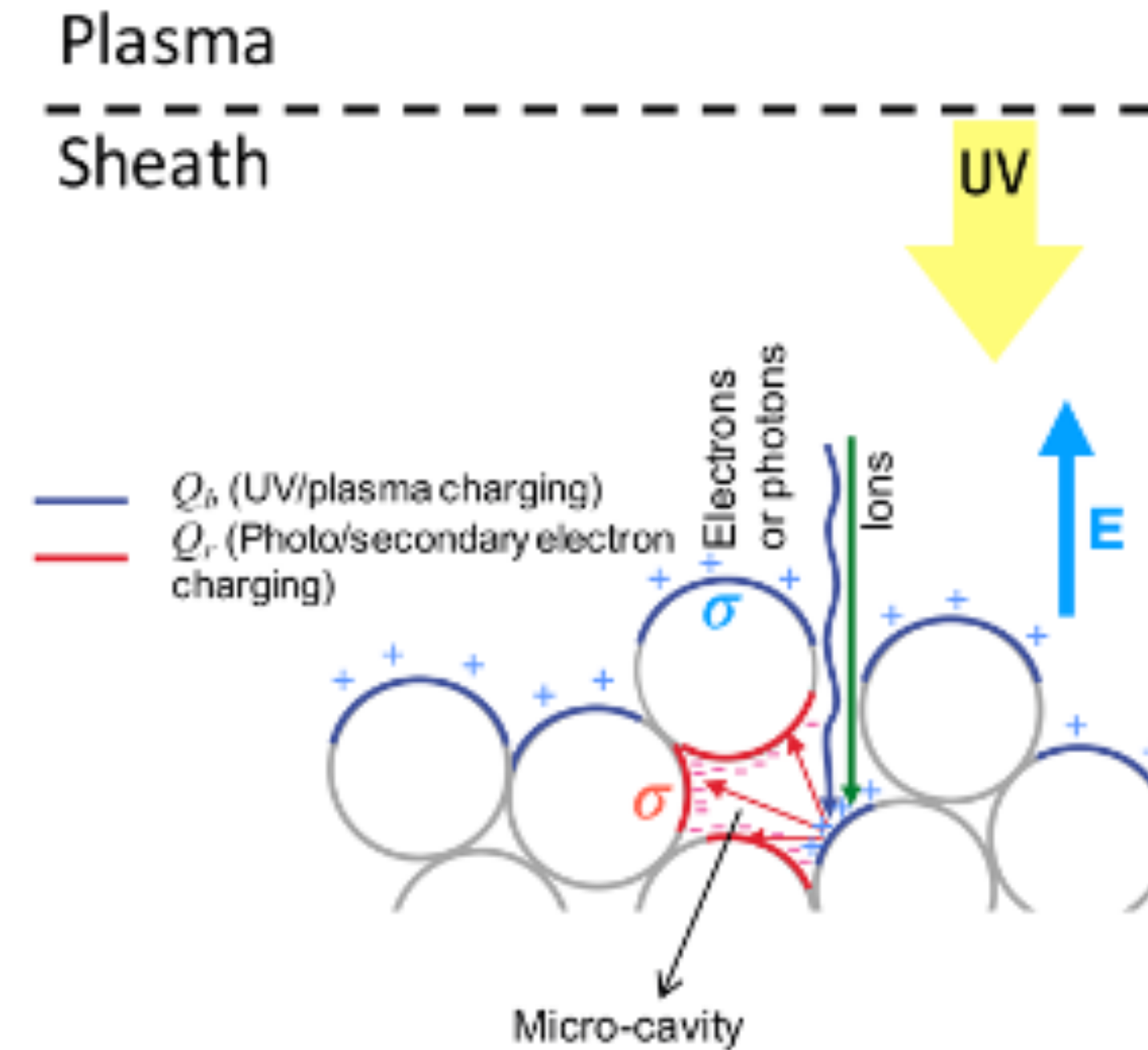


[Lunar Horizon Glow; Criswell 1973]

Grain Charging on a Surface.



Conventional view



Patched Charge Model
[Wang et al. 2016; Schwan et al., 2017]

Lofting Criterium: $Q_d E = F_e + F_c > F_g + F_{co}$

Modeling Dust Dynamics.

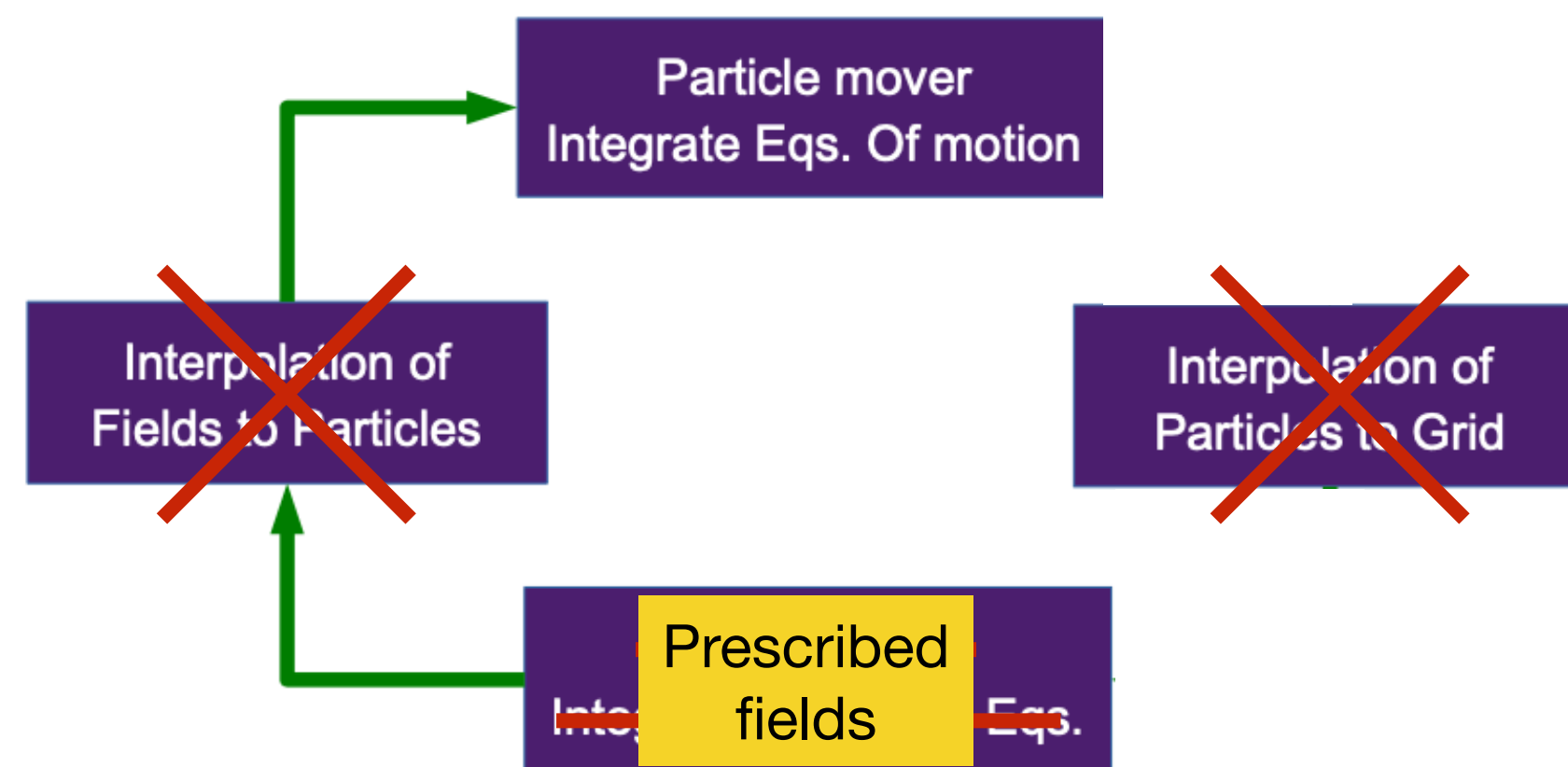
- From a numerical/modelling point of view, the current capabilities to study the dynamics of grain-scale charging processes and their interactions are limited due to the need to *self-consistently* merge several orders of magnitude in length and time scales.

- **Test-particle models.**

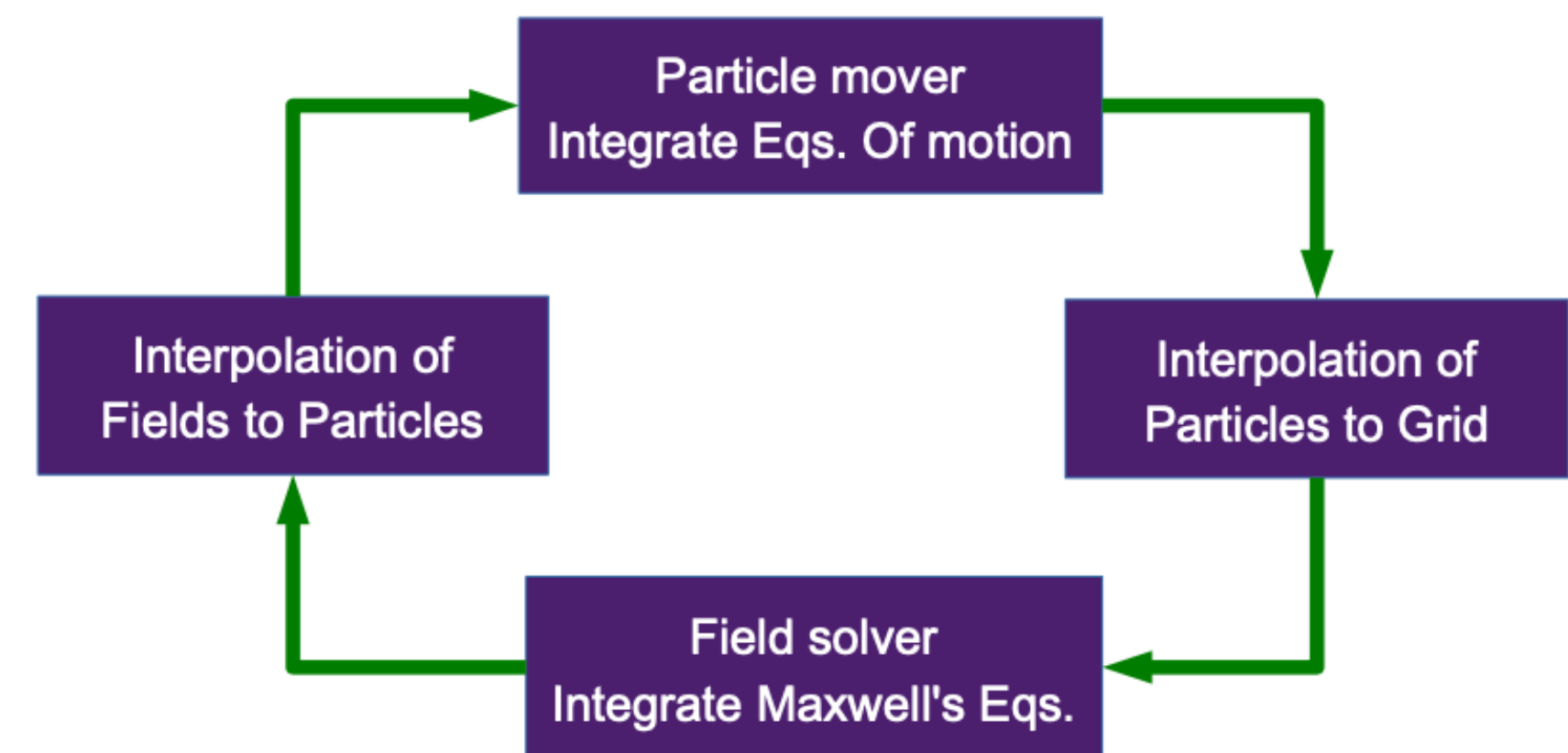
(Major drawback: no feedback mechanism is implemented between the particle-generated and the external electromagnetic fields.)

- **Particle-in-cell models.**

(Major drawback: needed computational resources skyrocket quickly due to the need to resolve Debye scales.)



Test-particle approach



Particle-in-cell approach

Modeling Dust Dynamics.

- *From a numerical/modelling point of view*, the current capabilities to study the dynamics of grain-scale charging processes and their interactions are limited due to the need to self-consistently merge several orders of magnitude in length and time scales.
 - **Test-particle models.**
(Major drawback: no feedback mechanism is implemented between the particle-generated and the external electromagnetic fields.)
 - **Particle-in-cell models.**
(Major drawback: needed computational resources skyrocket quickly due to the need to resolve Debye scales.)
- *No framework currently exists that provide a clear path from the grain-scale mechanism responsible for lofting/removing a dust particle from a regolith surface to an operational environment to develop and test the effectiveness of dust mitigation techniques.*

Theory and Simulation.

- **Objective**

Develop a framework of numerical models that couple the microphysics of grain-scaled processes with the self-consistent solution of the near-surface plasma environment.

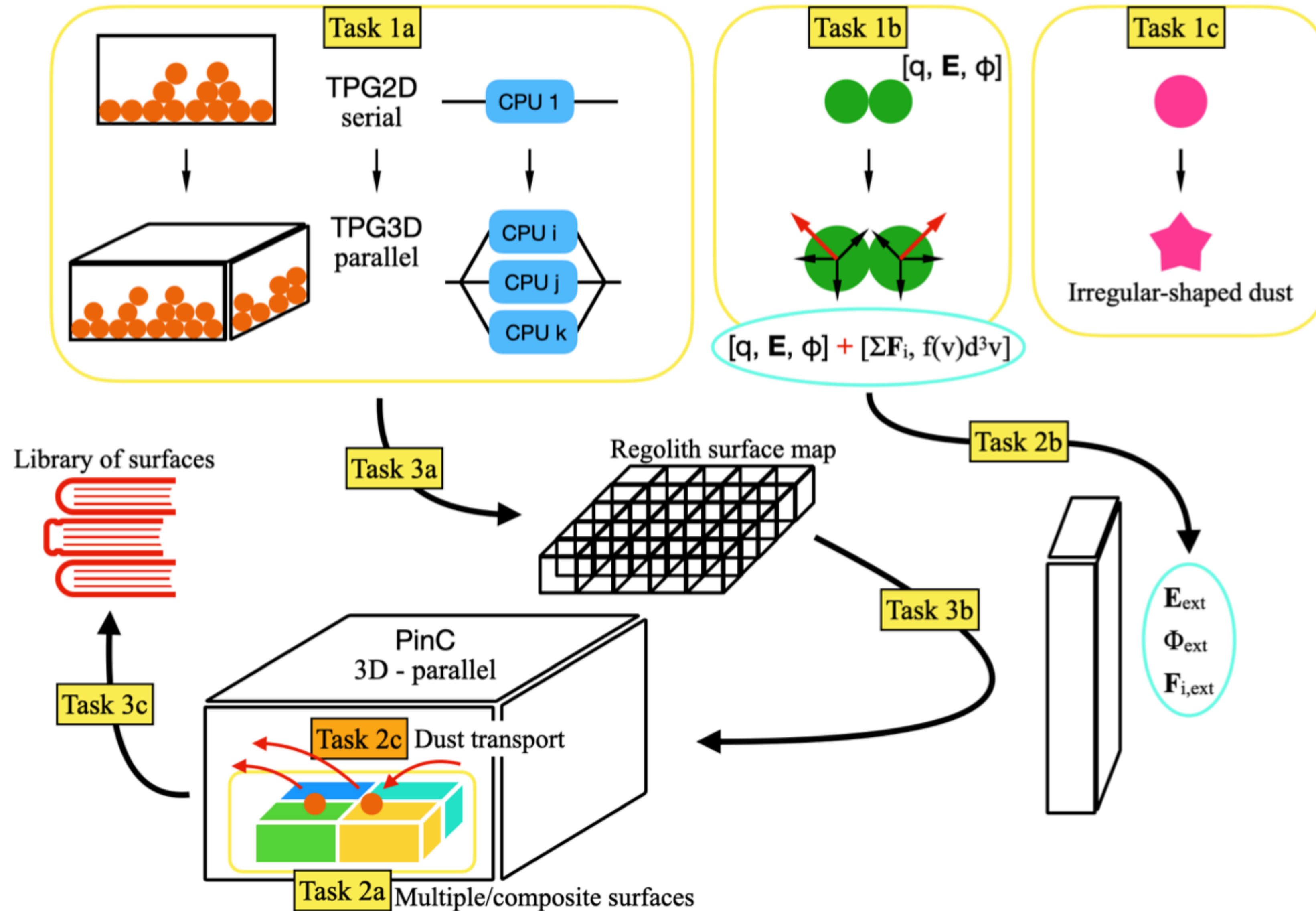
- **Impact/Innovation**

The proposed framework will be used to merge the qualitative understanding of the microscopic processes to the macroscopic behaviour of the lunar regolith, providing a much-needed tool to advance the effectiveness of dust mitigation techniques.

- **Approach**

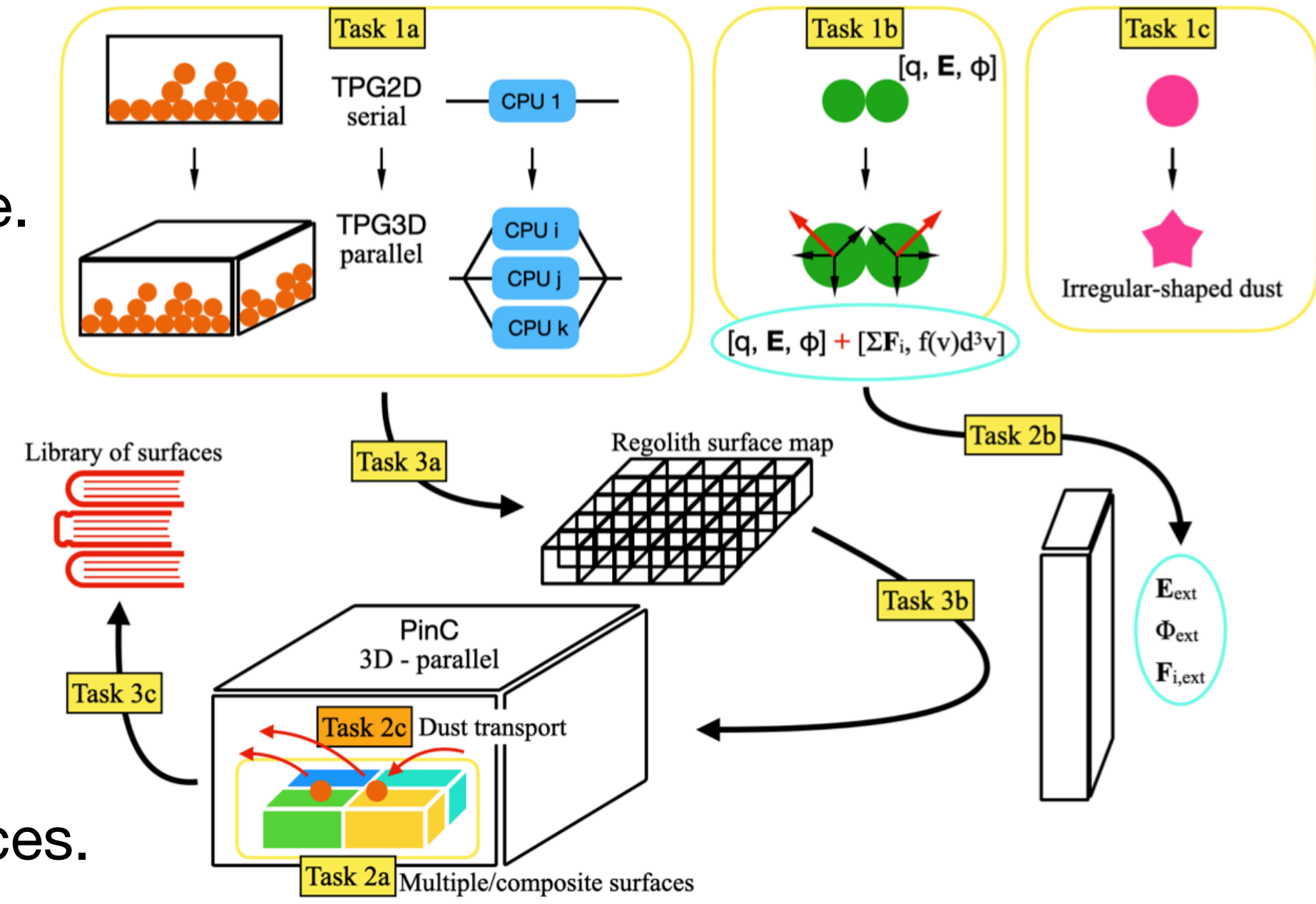
We equip a basic particle-particle and a particle-in-cell code with a comprehensive multi-physics model and the necessary code-coupling mechanisms.

Modelling Approach.



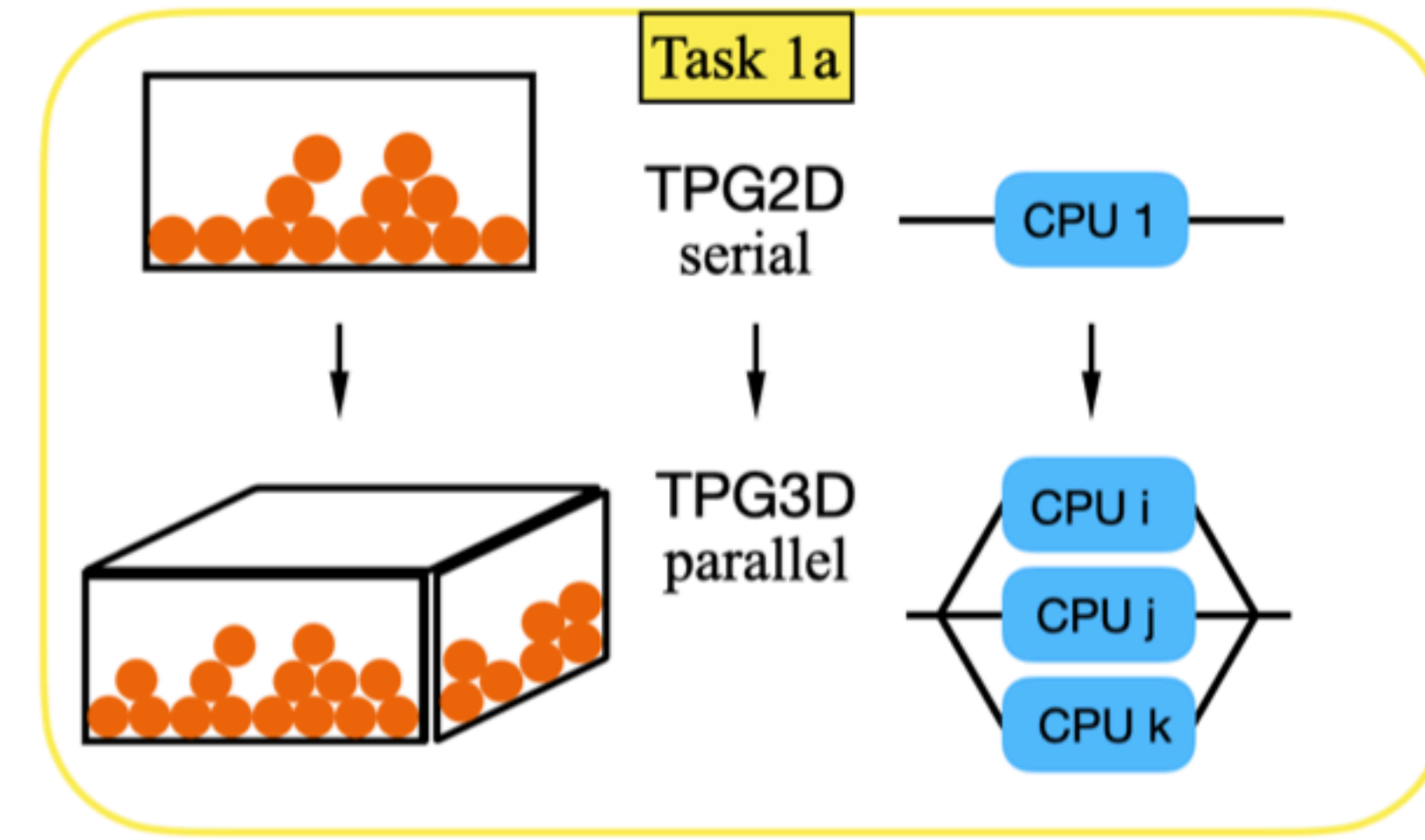
Modelling Approach.

- Task 1 (TPG2D→TPG3D):
 - a. Expand the numerical model from 2D to 3D and parallelise the code.
 - b. Develop a force-balance model, including cohesion, adhesion, and microgravity effects.
 - c. Develop the option to include non-spherical, irregular-shaped dust particles.
- Task 2 (PinC):
 - a. Expand the model to include multiple and composite objects/surfaces.
 - b. Develop the option for prescribed electromagnetic fields and secondary particle effects.
 - c. Develop a dust-kinetic model to evaluate dust transport phenomena.
- Task 3 (Code coupling):
 - a. Provide a mapping structure that merges the TPG3D components into a surface.
 - b. Develop the code structure in PinC to load TPG3D regolith mapping structures.
 - c. Build a library of realistic regolith surfaces.



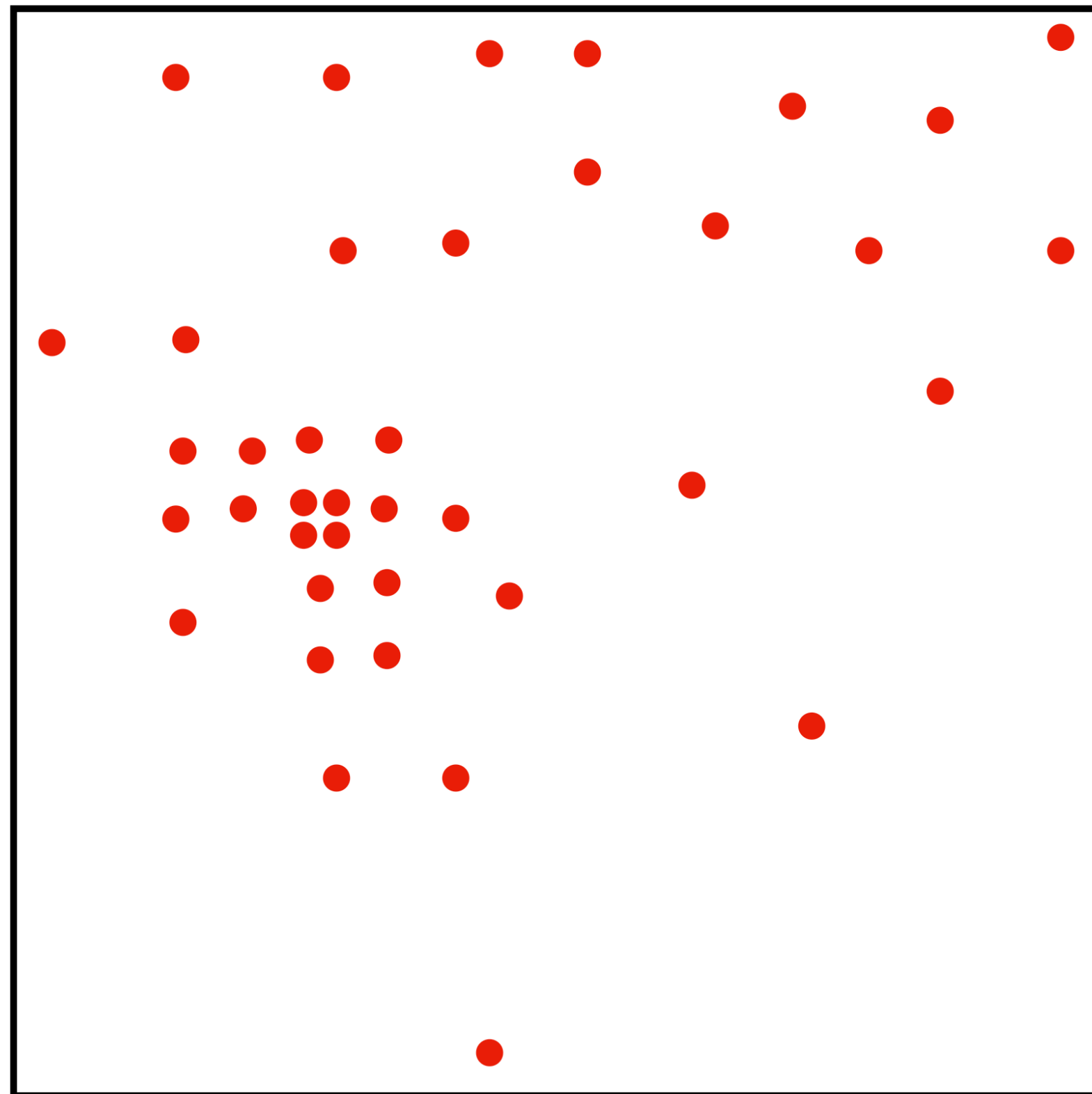
TPG3D.

- Parallelisation.
 - OpenMP approach (shared memory).
 - ▶ No major redesign needed.
 - ▶ Limits the code to run within one computing node.
 - MPI approach (distributed memory).
 - ▶ Major redesign needed.
 - ▶ No limit on the amount of computing power that can be used.
(apart from overhead considerations).
- **Major hurdle:** TPG's computational cycle implements the Barnes-Hut tree algorithm (i.e., a reduction operation). Parallelisation is therefore not efficient at the root level.



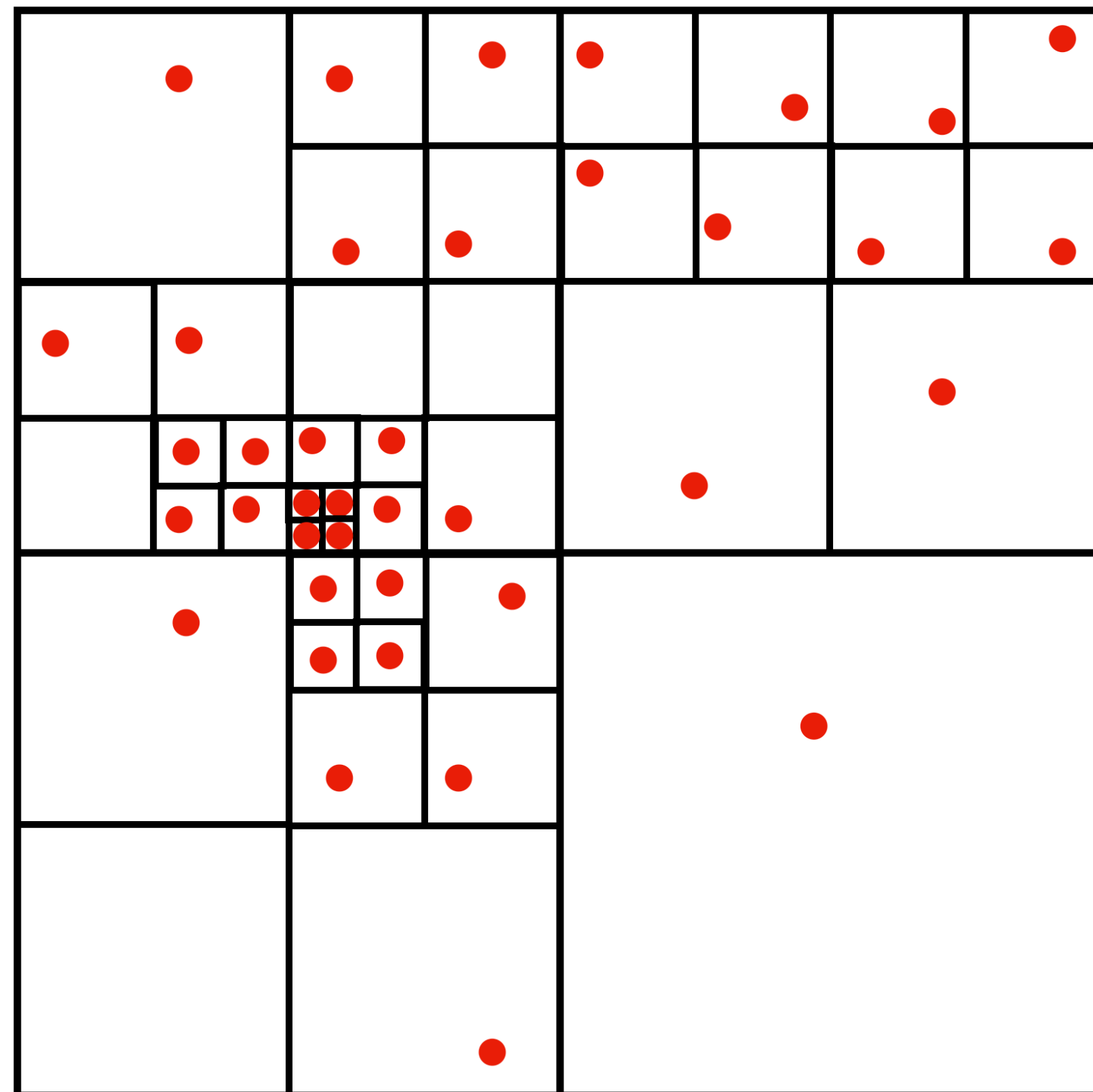
Barnes-Hut tree algorithm.

- Approximation algorithm designed for n-body simulations.
 - No fixed grid, so not bound by CFL constraints.



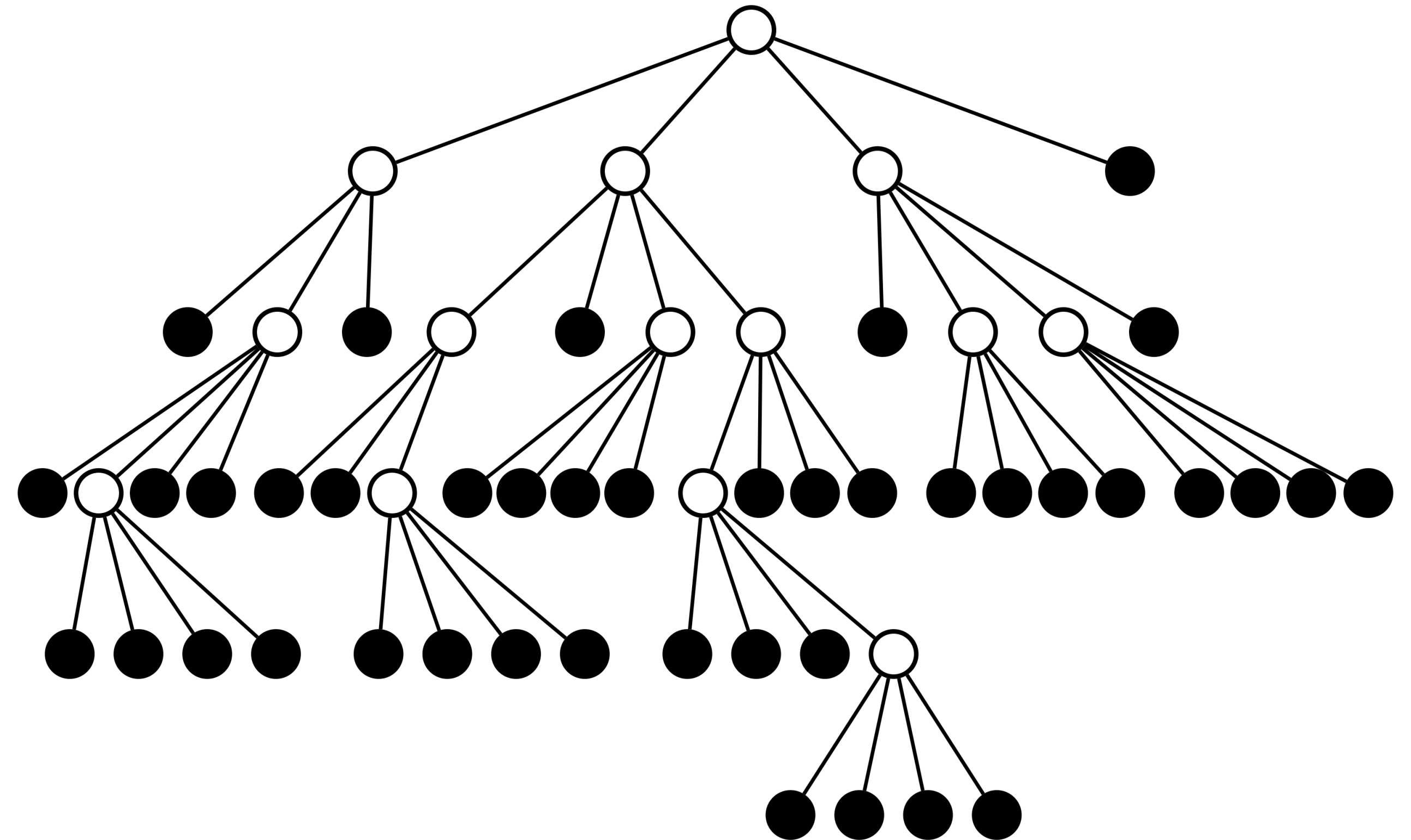
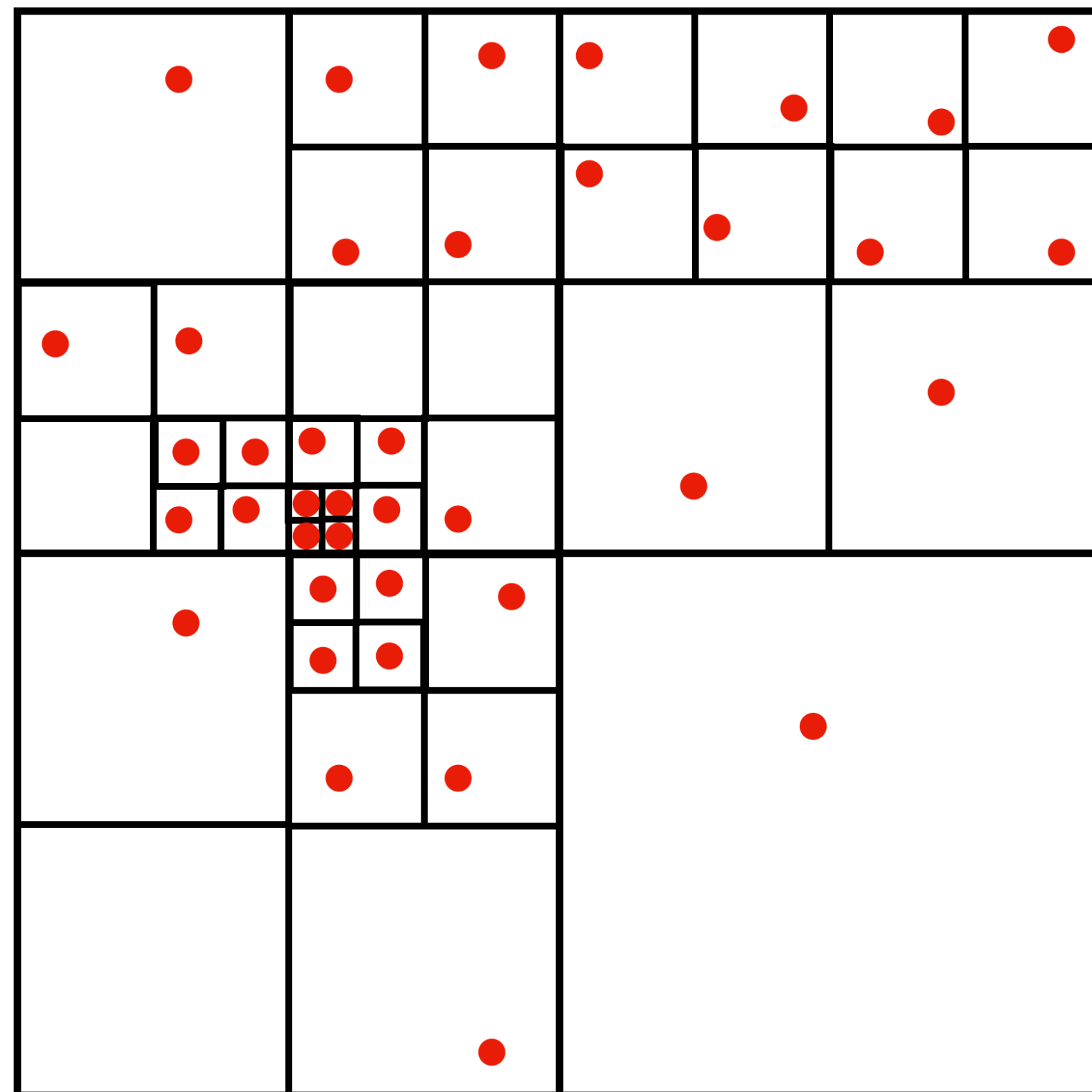
Barnes-Hut tree algorithm.

- Approximation algorithm designed for n-body simulations.
 - No fixed grid, so not bound by CFL constraints.
 - Divisions are constructed depending on particle/surface segment density.



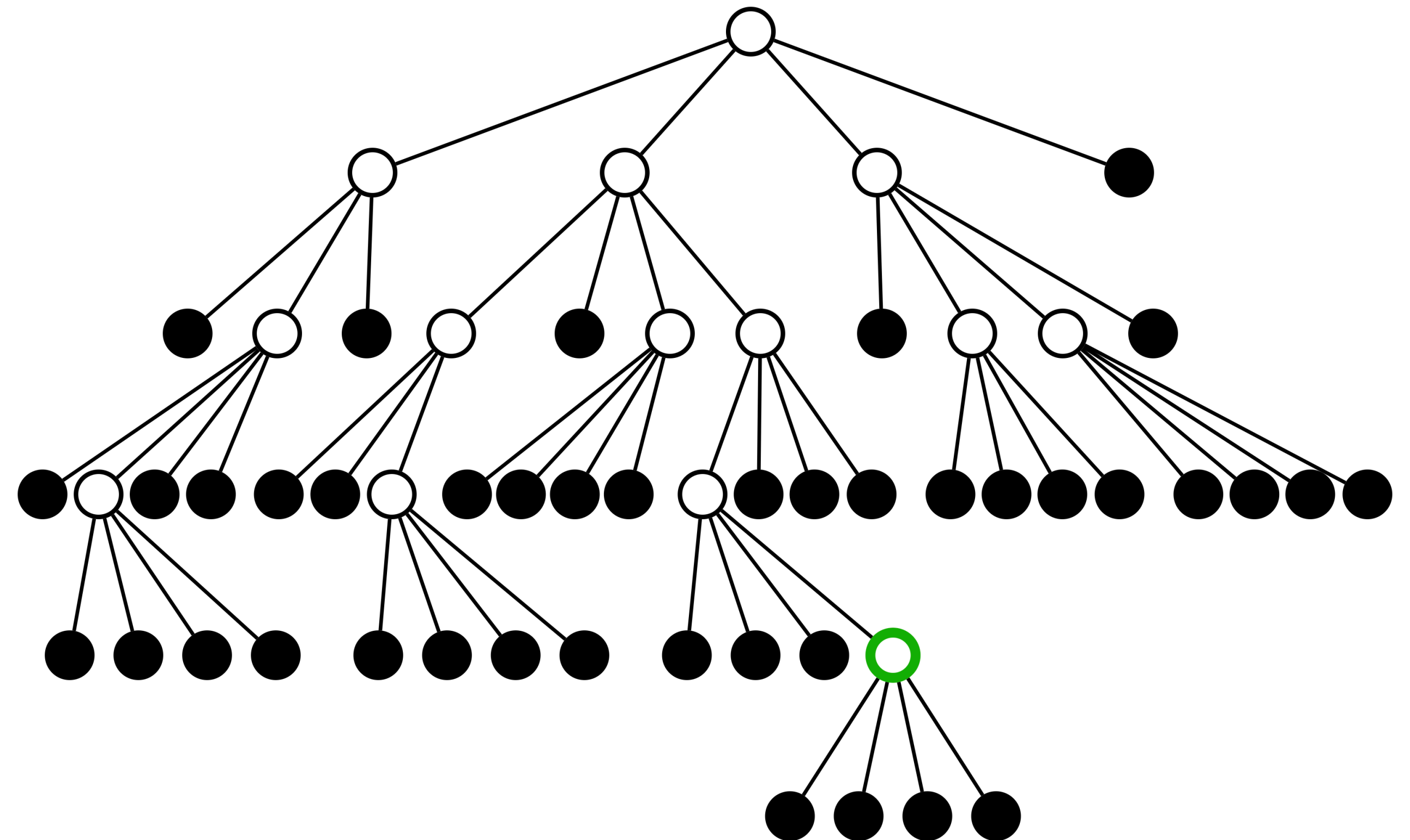
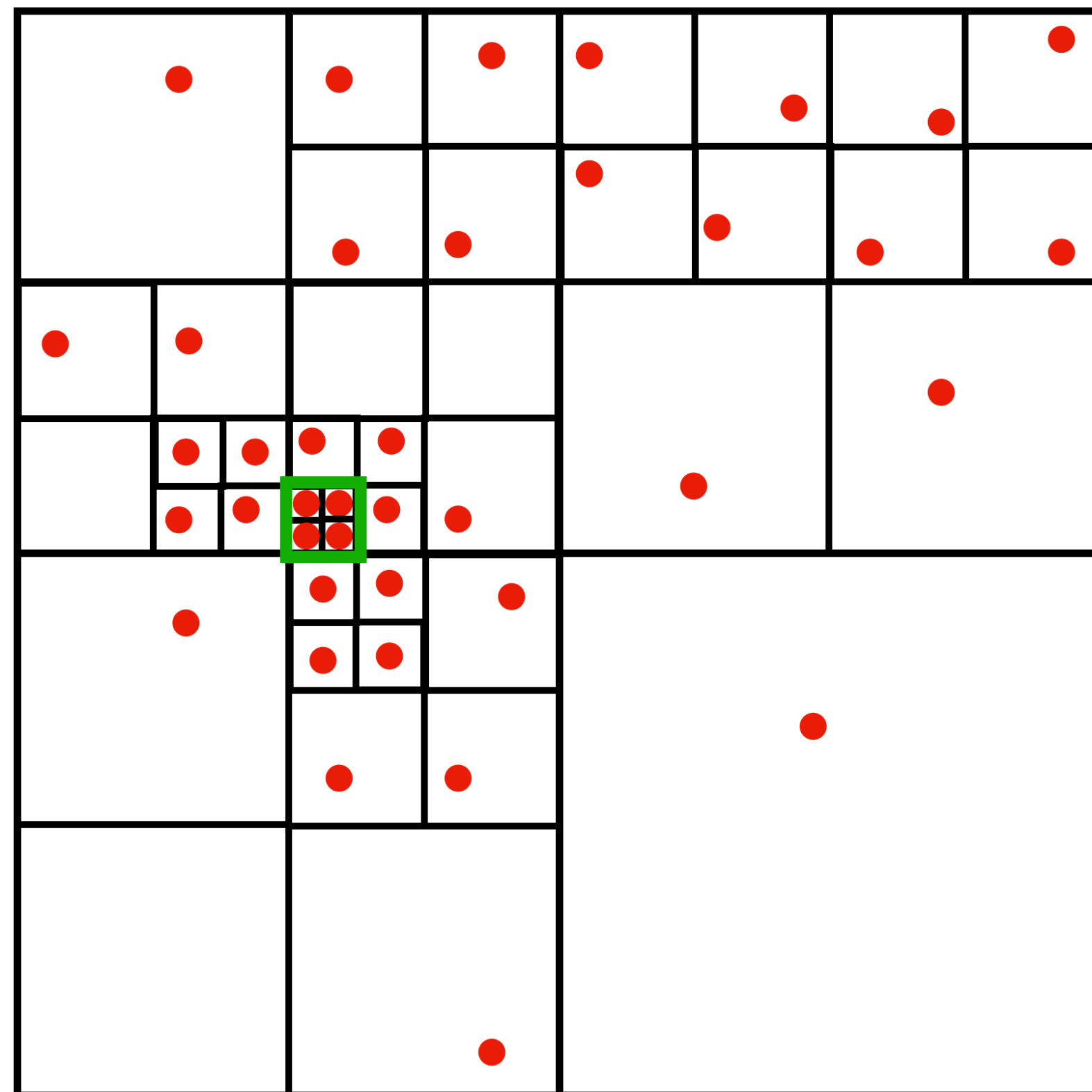
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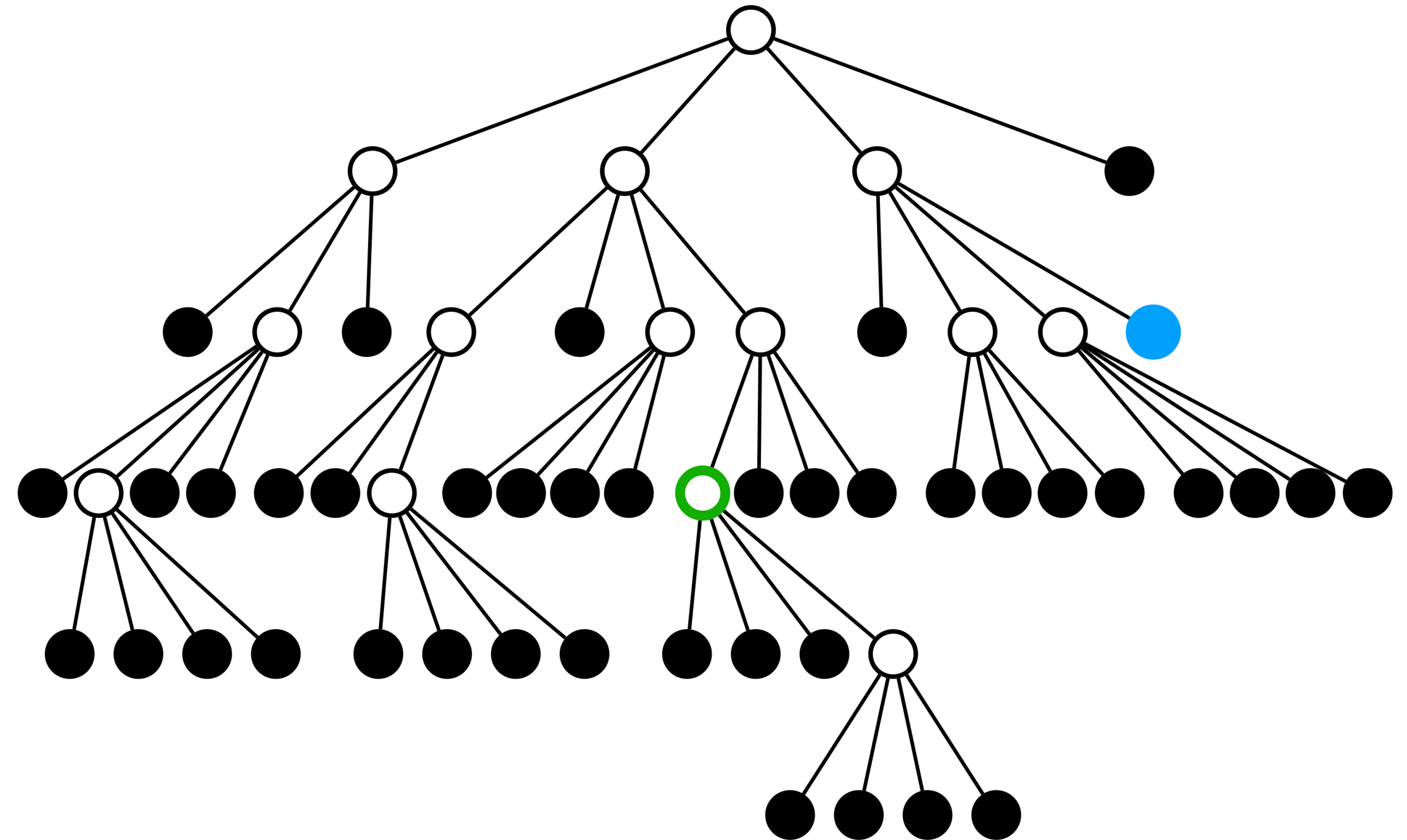
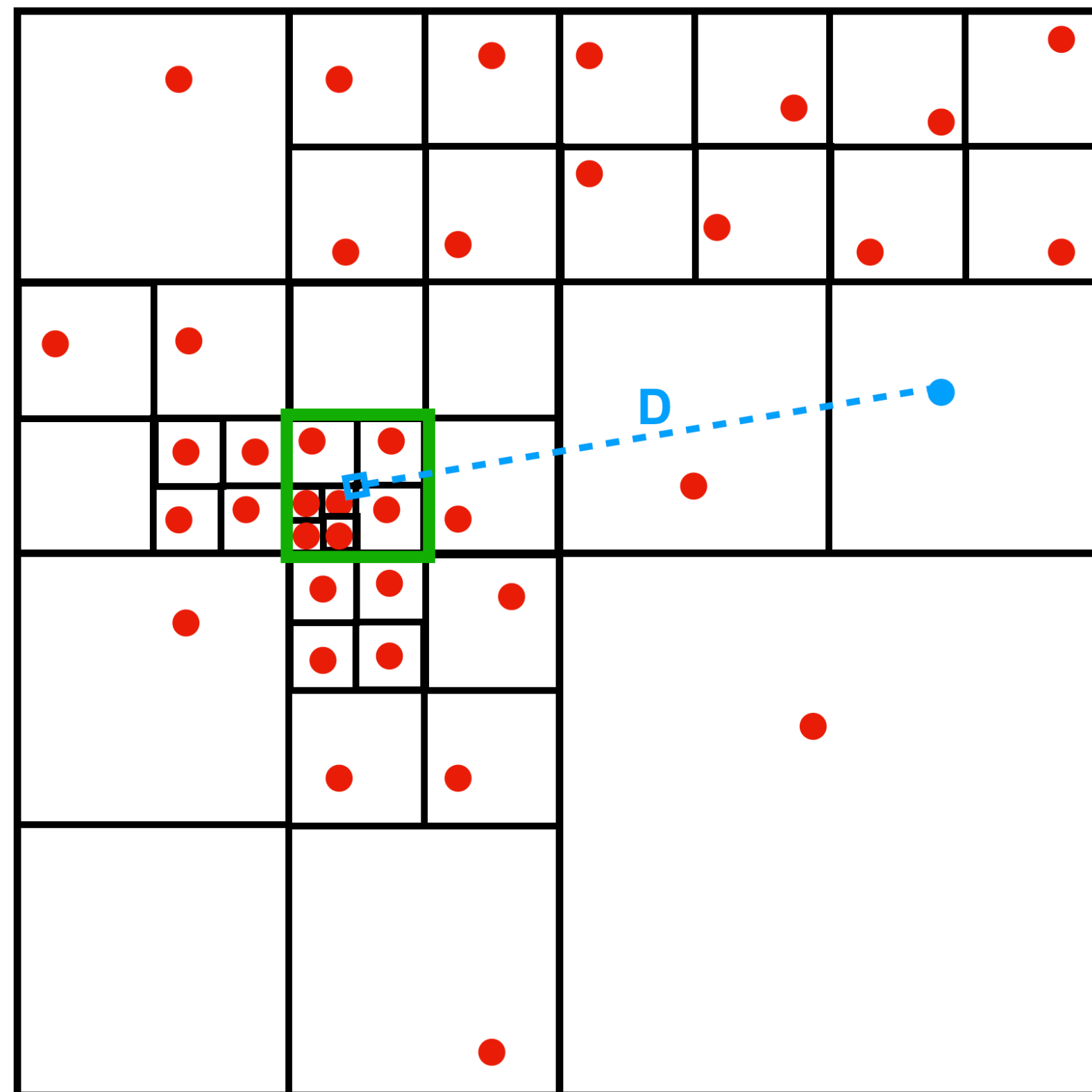
Barnes-Hut tree algorithm.

- Approximation algorithm designed for n-body simulations.
 - Divisions are constructed depending on particle/surface segment density.
 - Short range interactions, use brute force, i.e., Coulomb's Law.



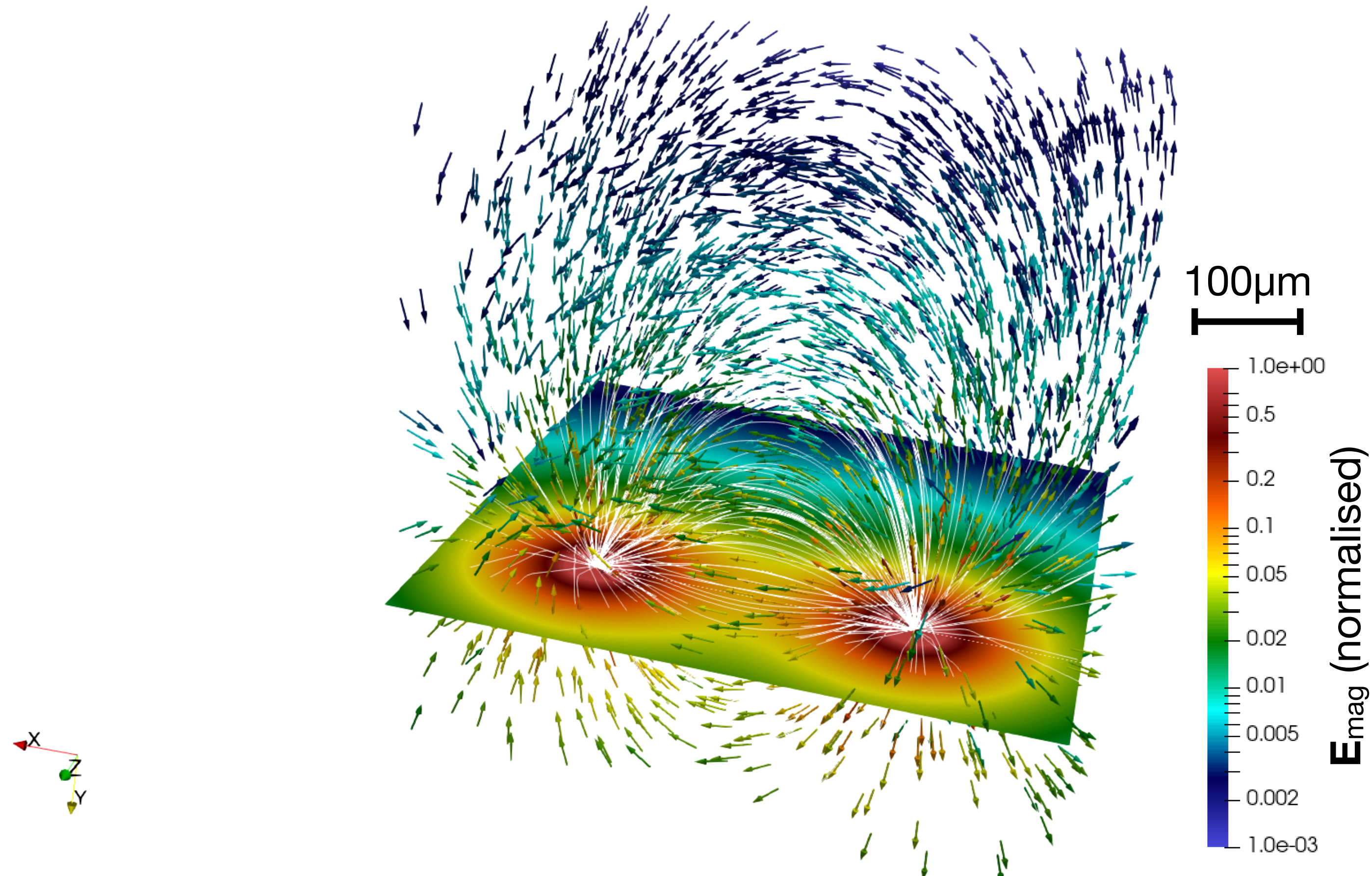
Barnes-Hut tree algorithm.

- Approximation algorithm designed for n-body simulations.
 - Divisions are constructed depending on particle/surface segment density.
 - Long-range interactions, use multipole expansion.



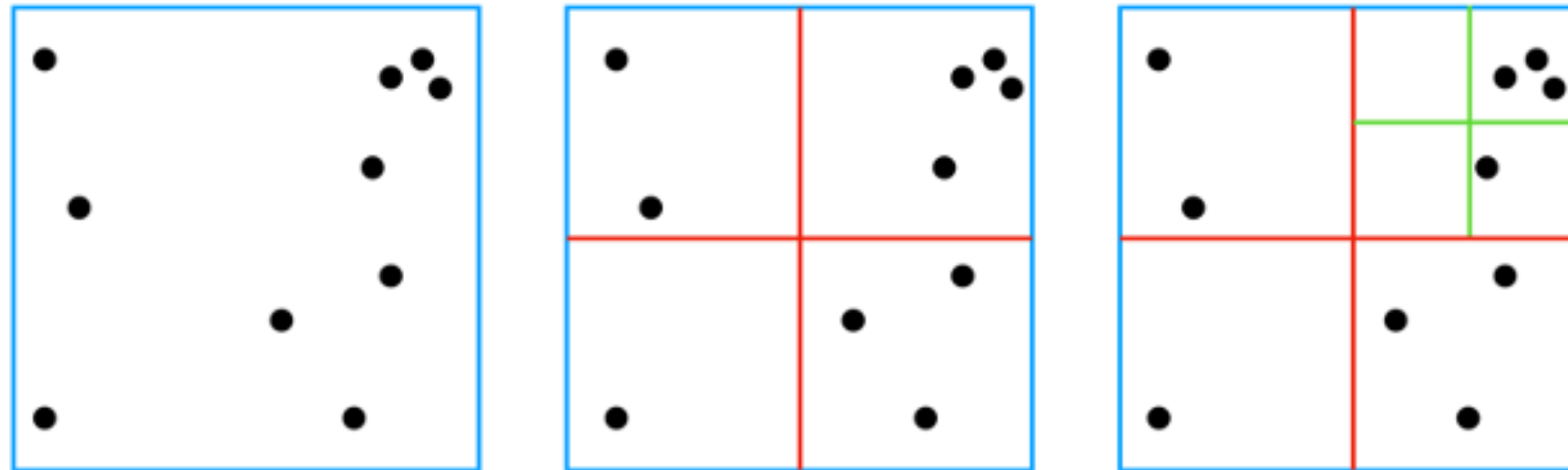
Barnes-Hut tree algorithm.

- Key Points:
 - ▶ Correct electric field values computed.
 - ▶ Smooth transition between the 'brute force' and multipole part of the solver.

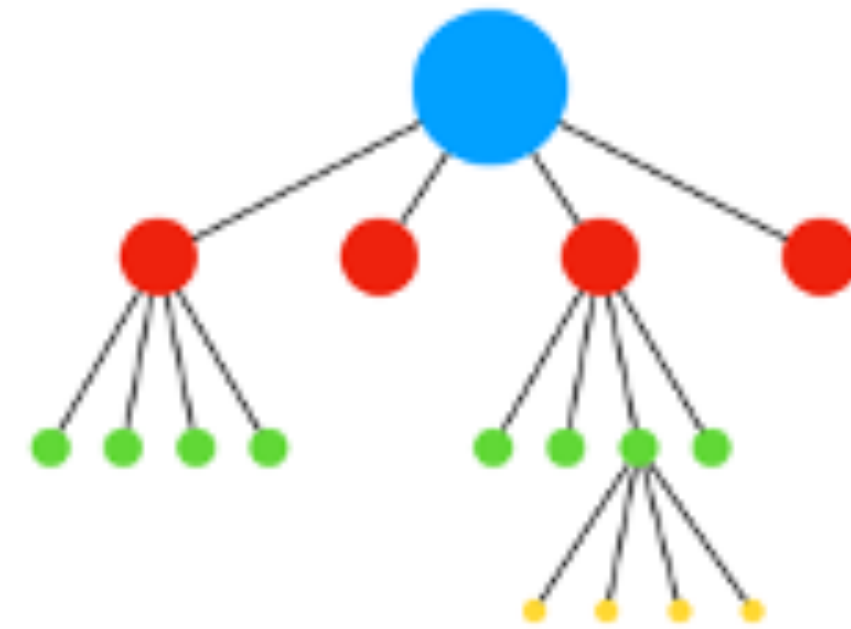
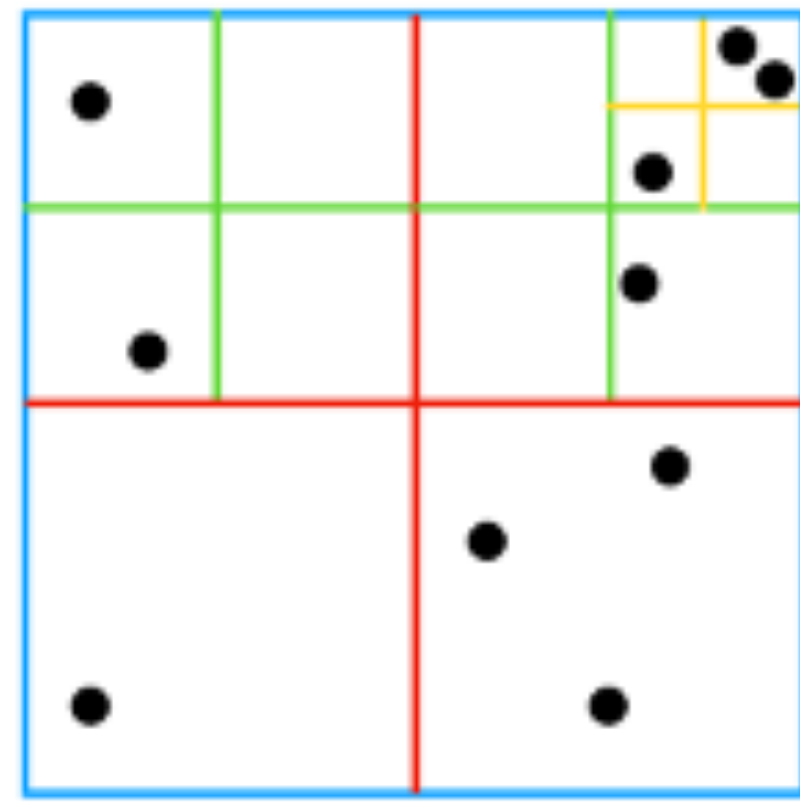


Parallelisation.





- **Paradigm:**
 - ▶ Every MPI thread/CPU is responsible for a specific part of the computational domain, i.e., domain decomposition (temporary solution).
 - ▶ Every MPI thread/CPU corresponds to at least one leaf of the Barnes-Hut tree.
- **Key Point:**
 - ▶ Plasma particles are distributed, grain information is ‘global.’




Parallelisation.



2D example, assume 16 CPUs.

-  1 leaf, all CPUs perform the same work.
-  4 leaves, 2 CPUs perform the same work.
-  16 leaves, no CPUs perform the same work.
-  64 leaves, CPUs handle more than 1 leaf.

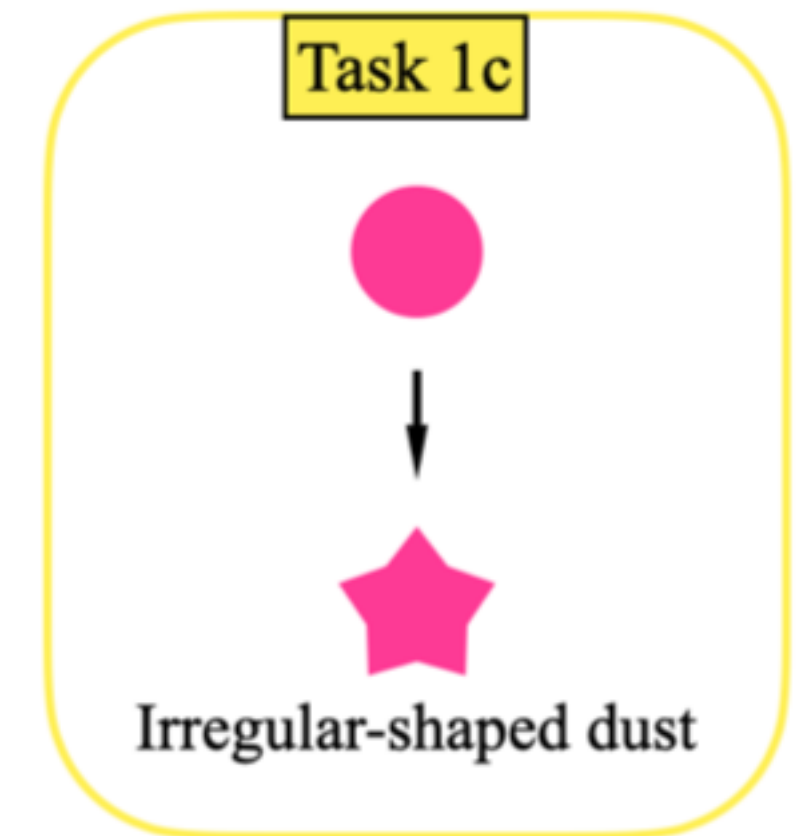
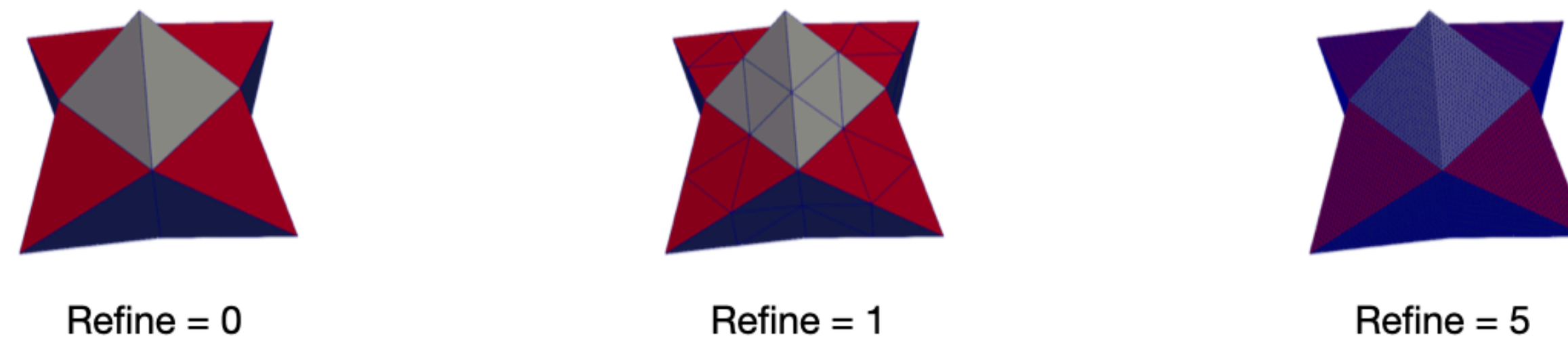
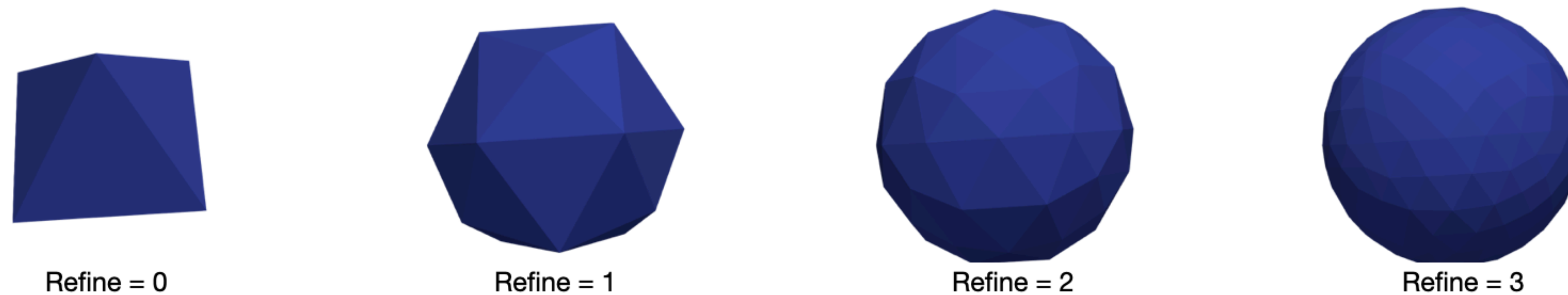
- **In practice:**
 - ▶ After a few computational cycles, you always end up in the  scenario.
 - ▶ This approach allows for the MPI and particle reduction operation to run in unison.

Particle Shapes

- **Design decisions:**

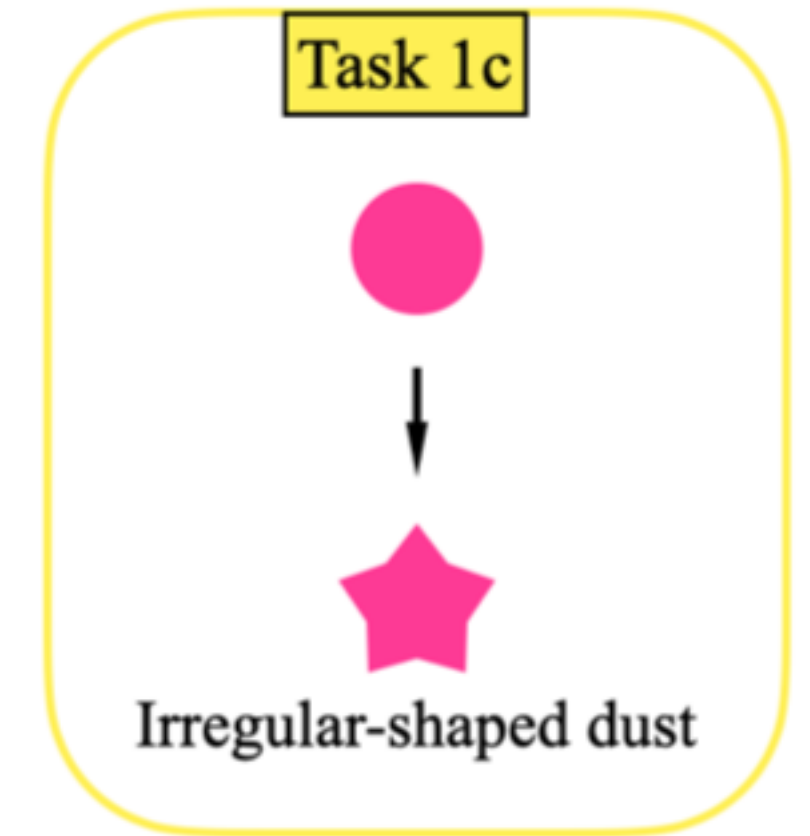
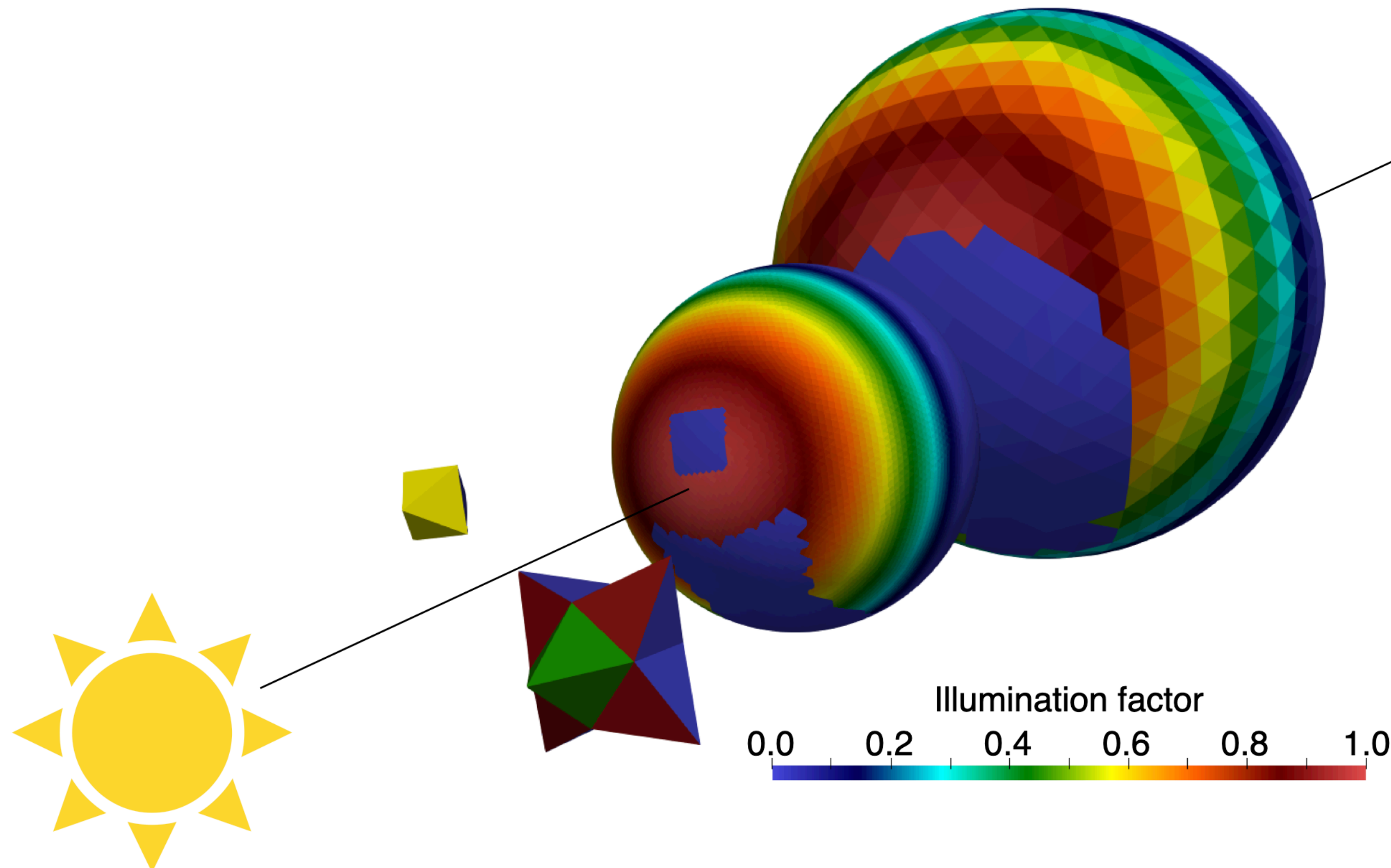
- ▶ Keep grain information 'global' to reduce complexity.
- ▶ Standalone input file for irregular volumes.
- ▶ Mesh refinement to obtain preferred resolution.

Illustration of the mesh refinement for spherical and irregularly shaped dust grains.

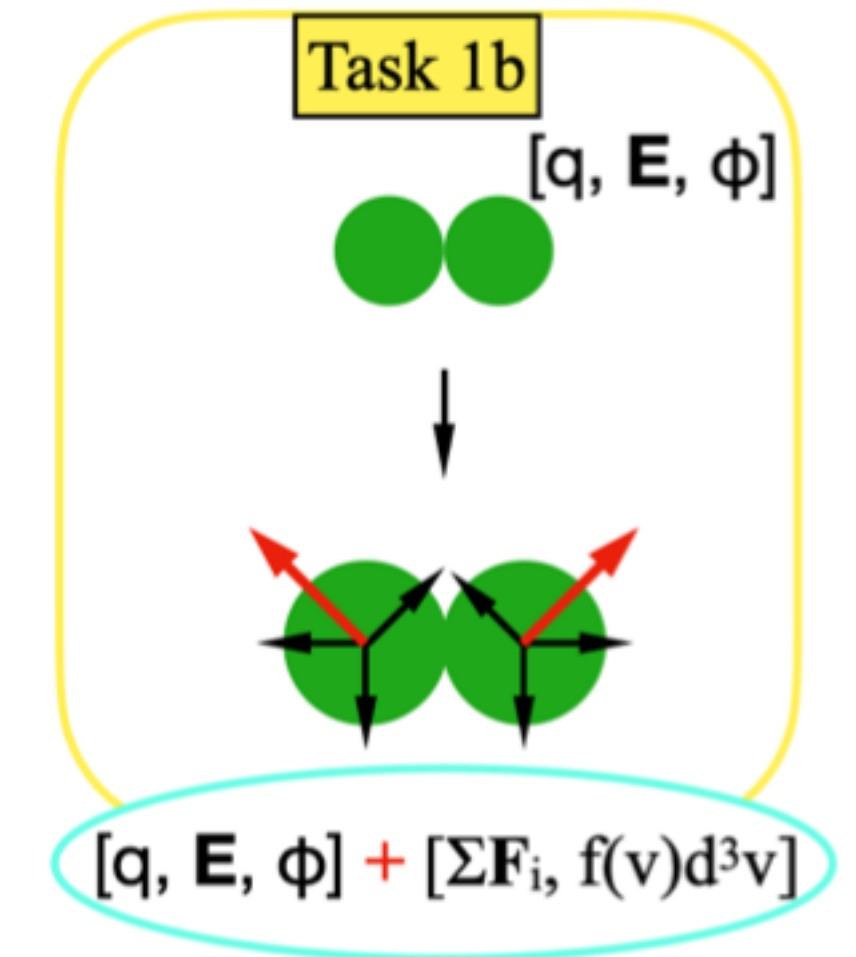
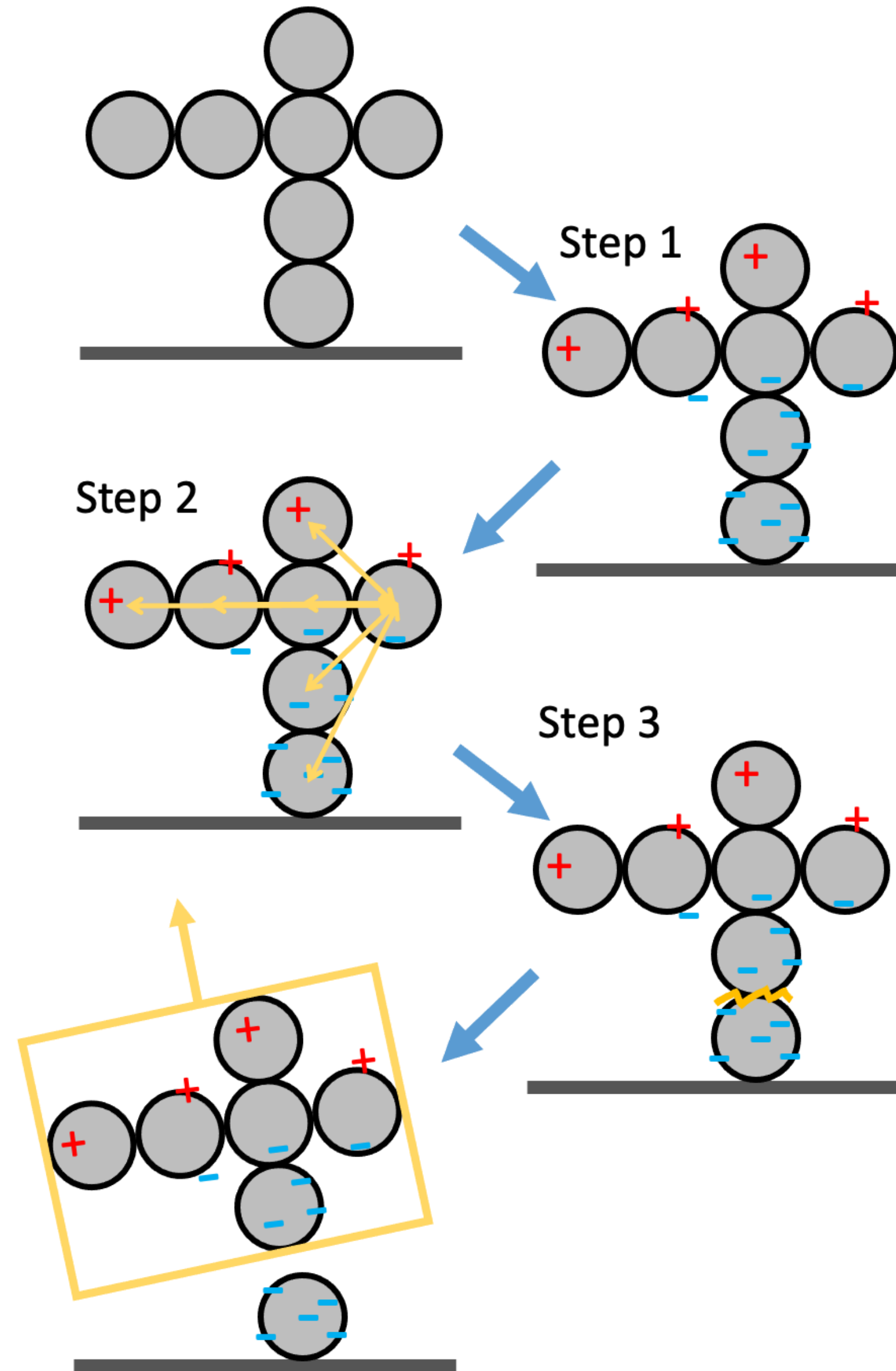
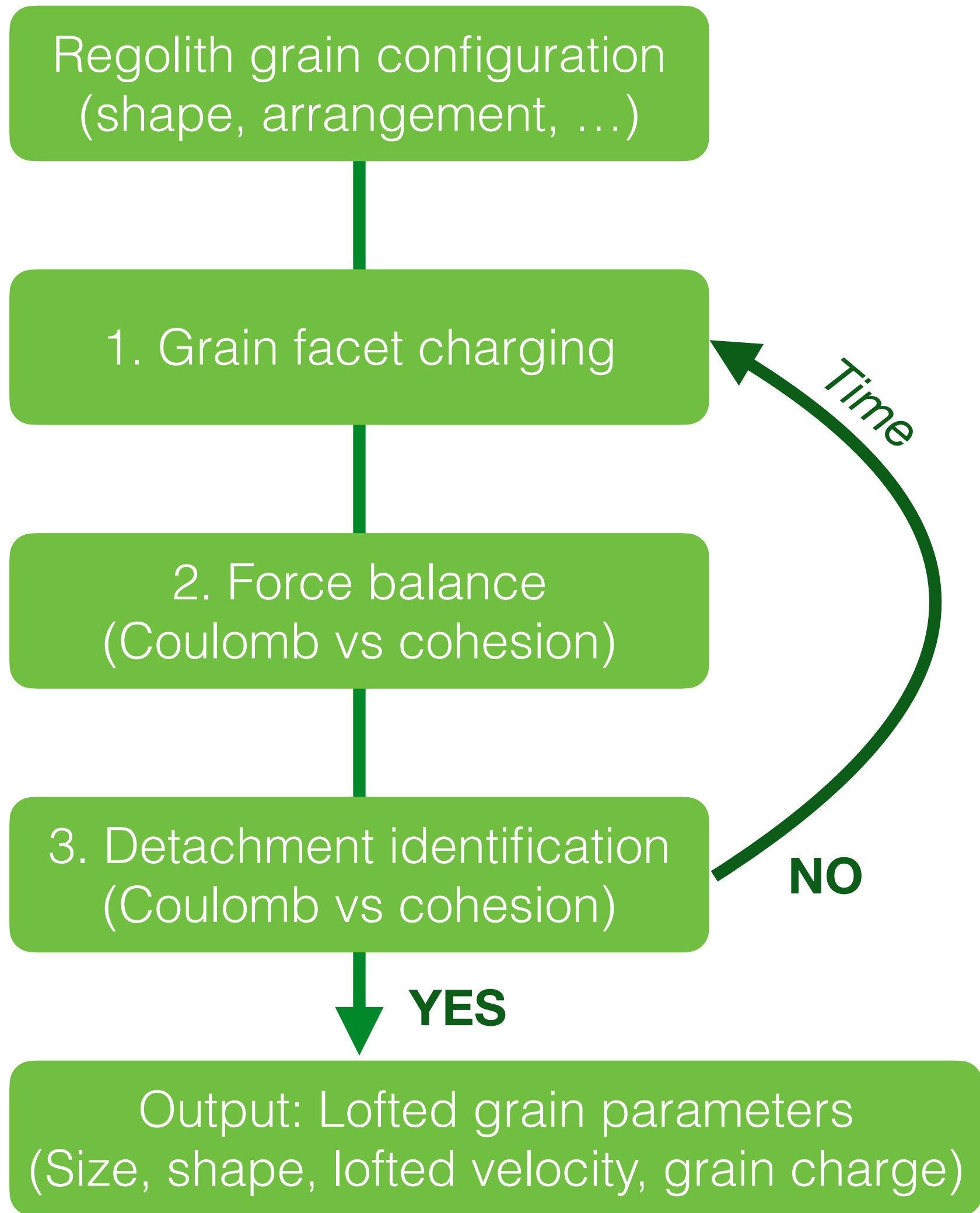


Particle Shapes

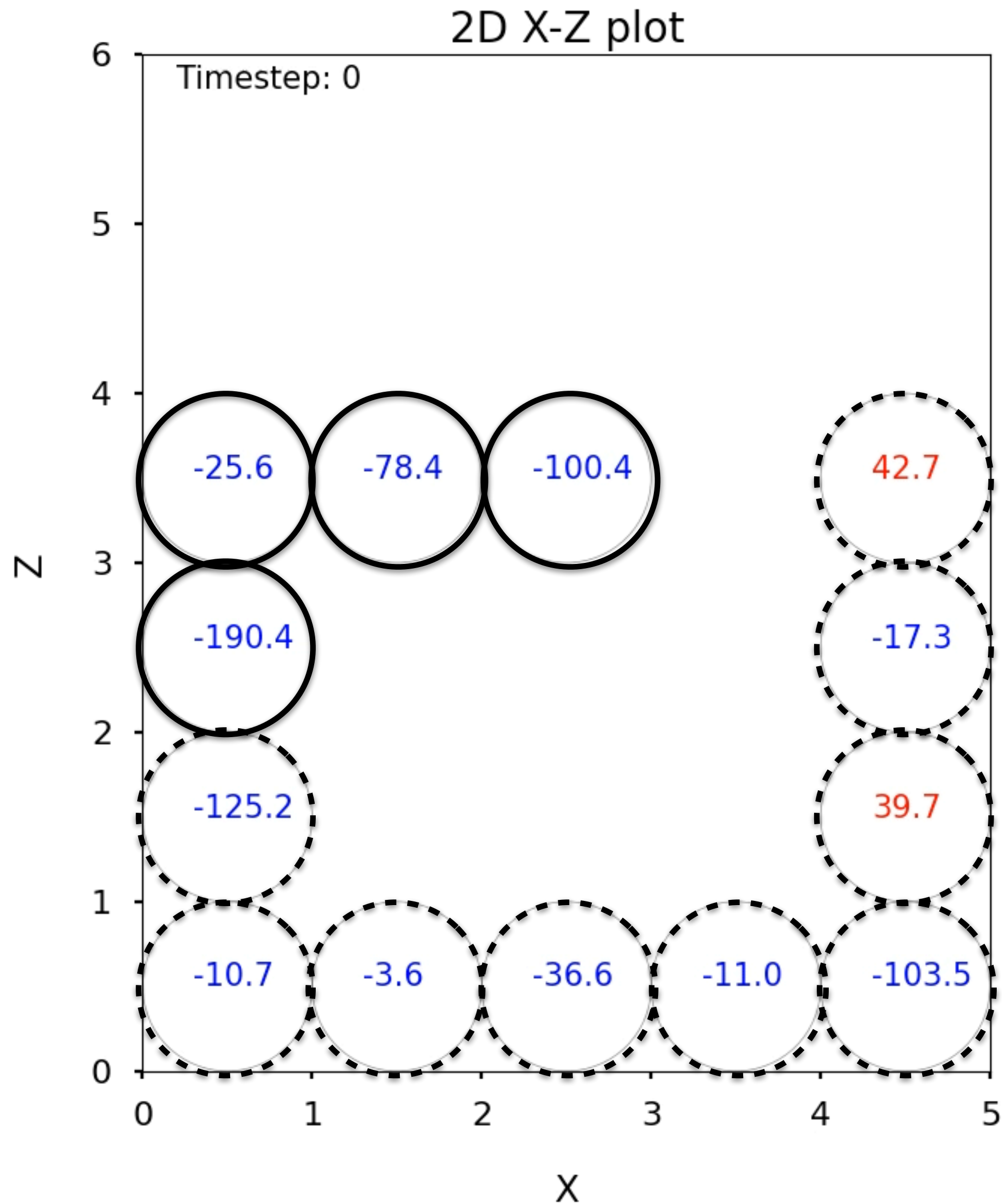
- **Design decisions:**
 - ▶ Mesh refinement to obtain preferred resolution.
 - ▶ Raytracing to obtain grain illumination/shadowing.



Particle mobilisation.



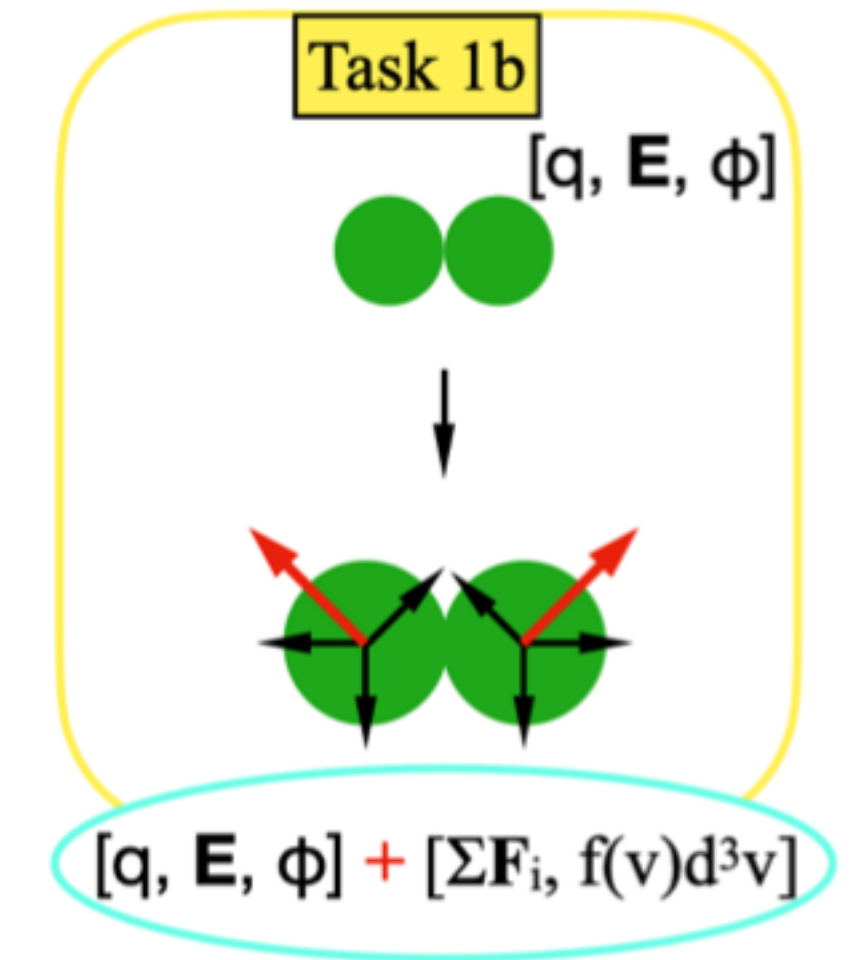
Particle mobilisation.



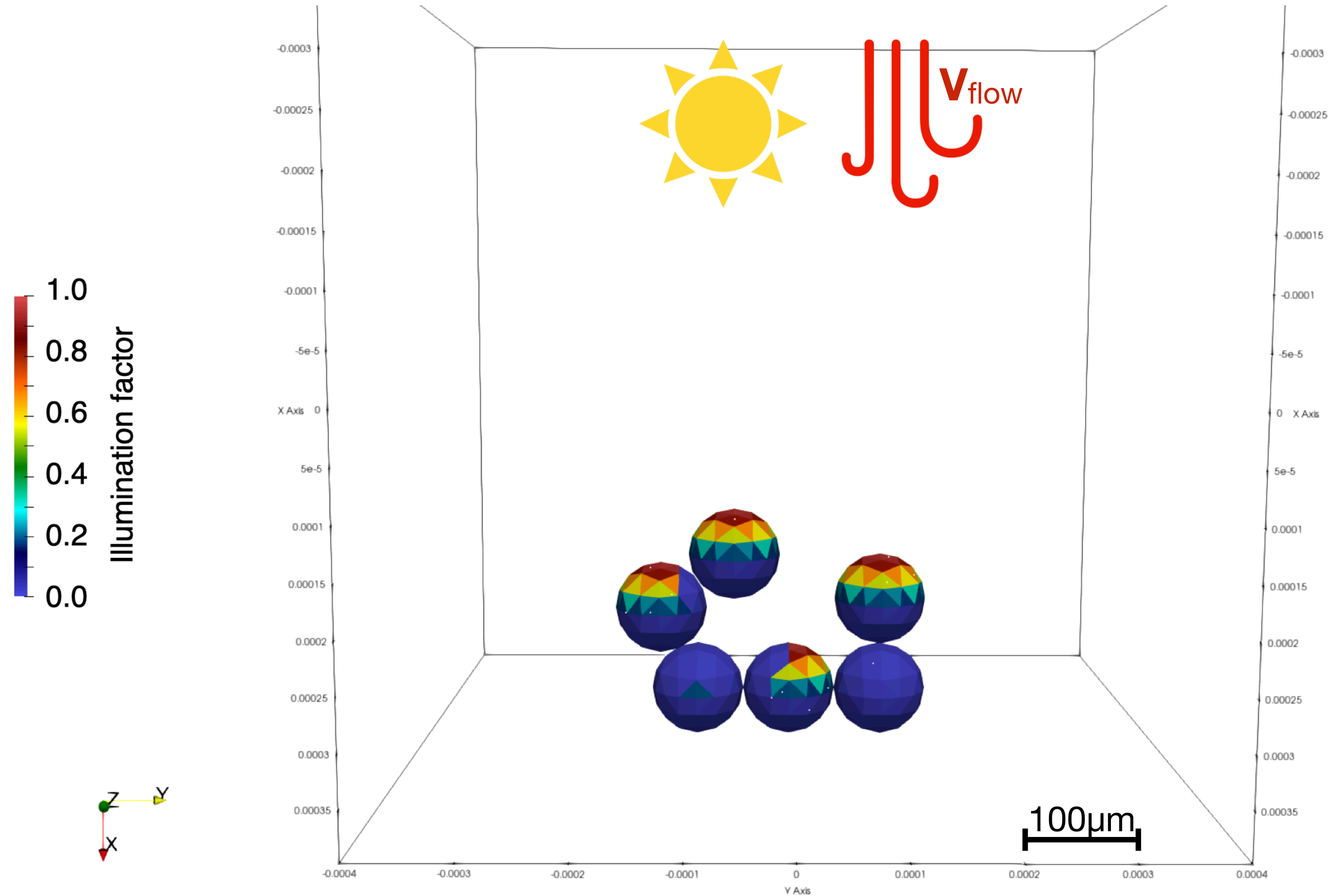
- Detachment criterion (artificial):
Adjacent grains each carrying 10^3 elementary charges of the same polarity.

- Grain charging setup:

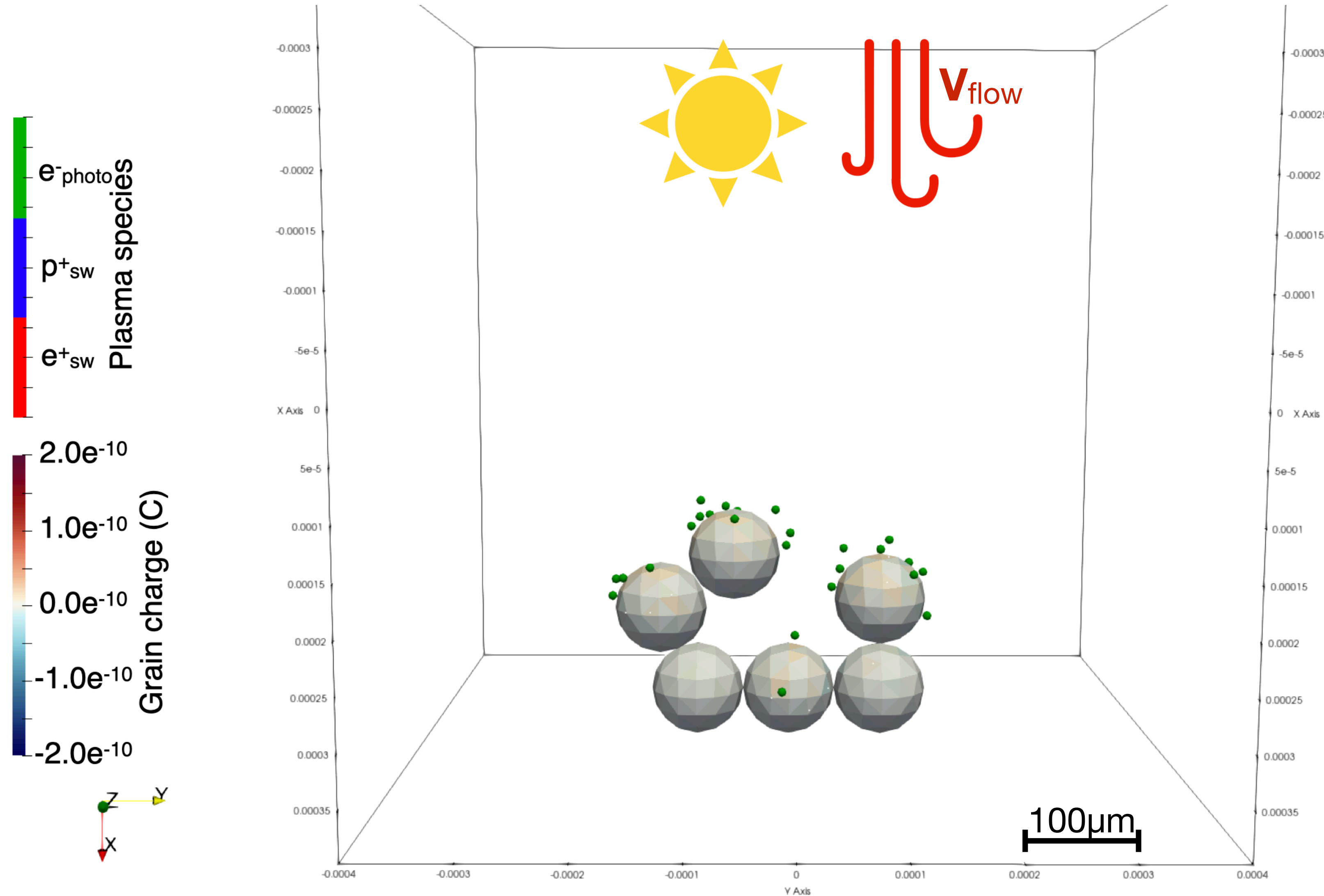
- dQ/dt follows a Gaussian:
mean = $0e^-$, sigma $50e^-$
- dQ/dt follows a Gaussian:
mean = $100e^-$, sigma = $50e^-$
- Detached from surface.



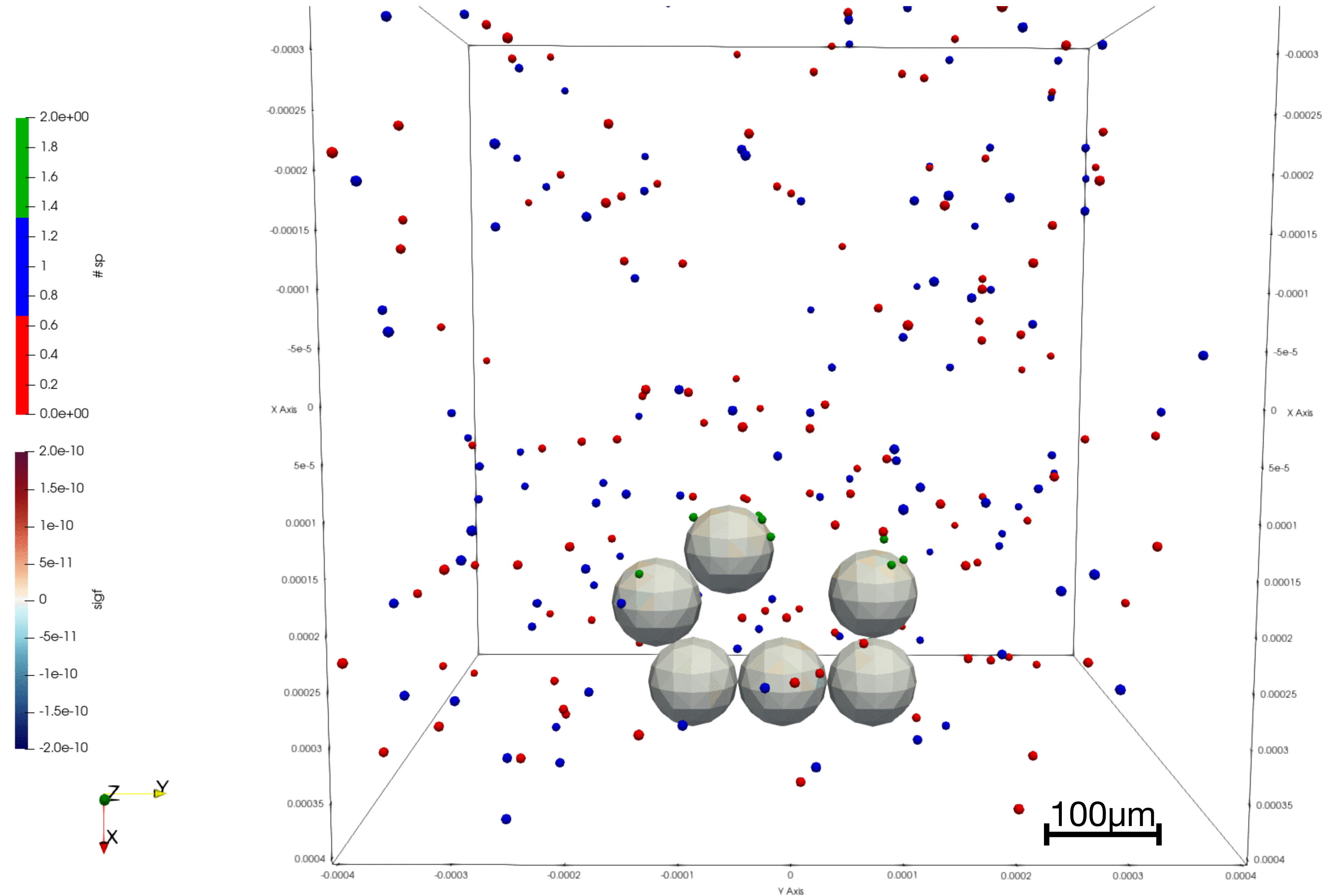
Patched Charge Model Benchmark.



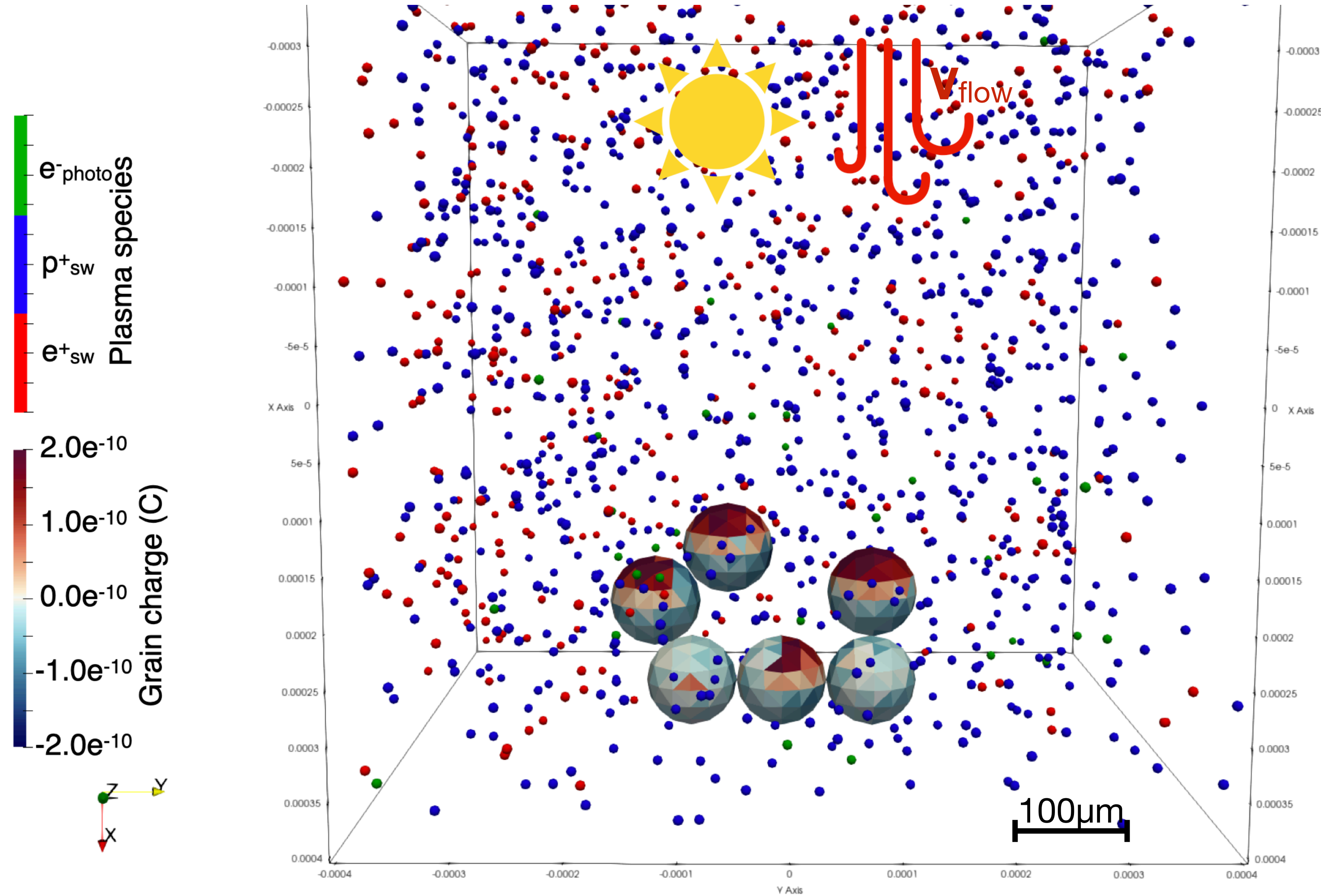
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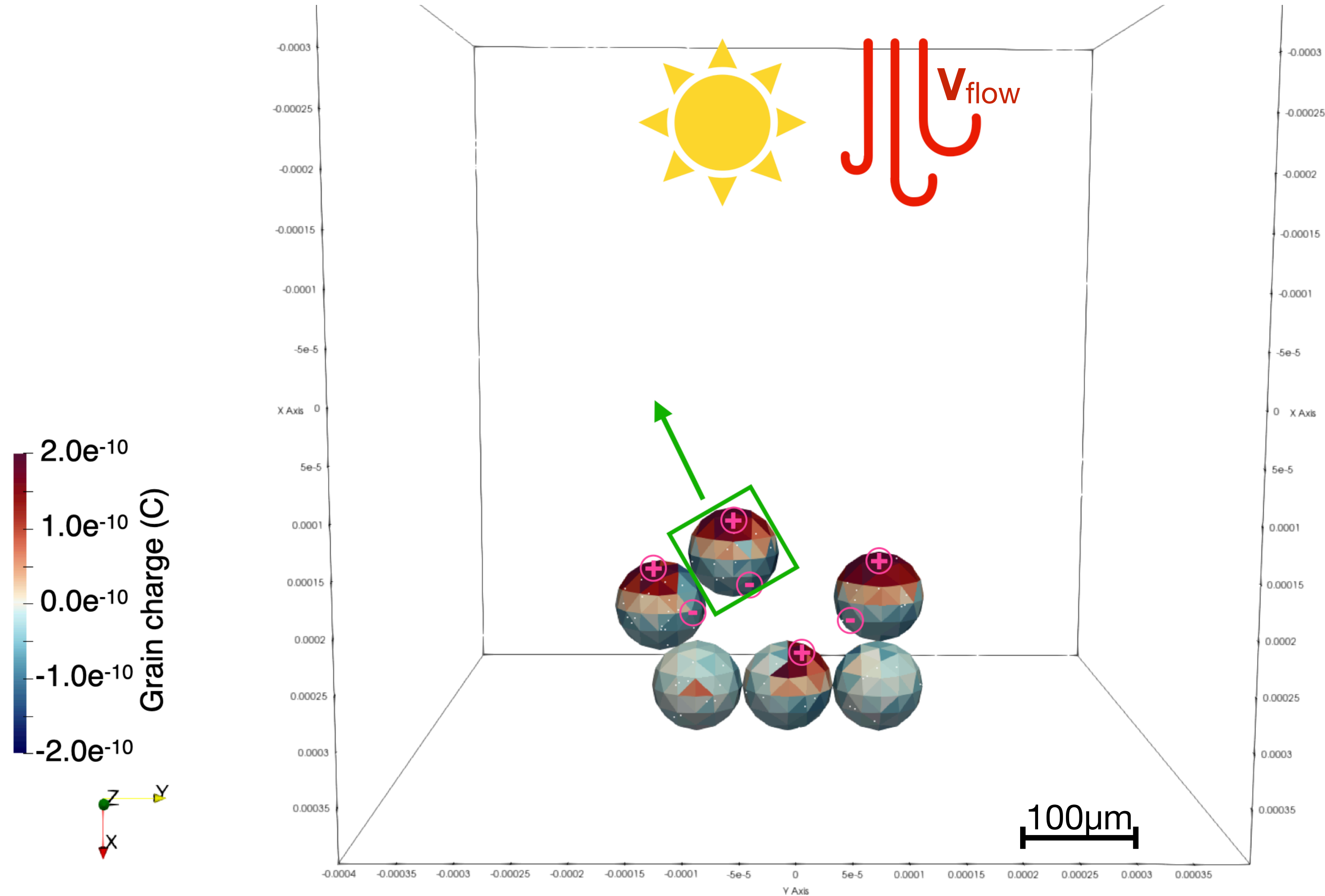
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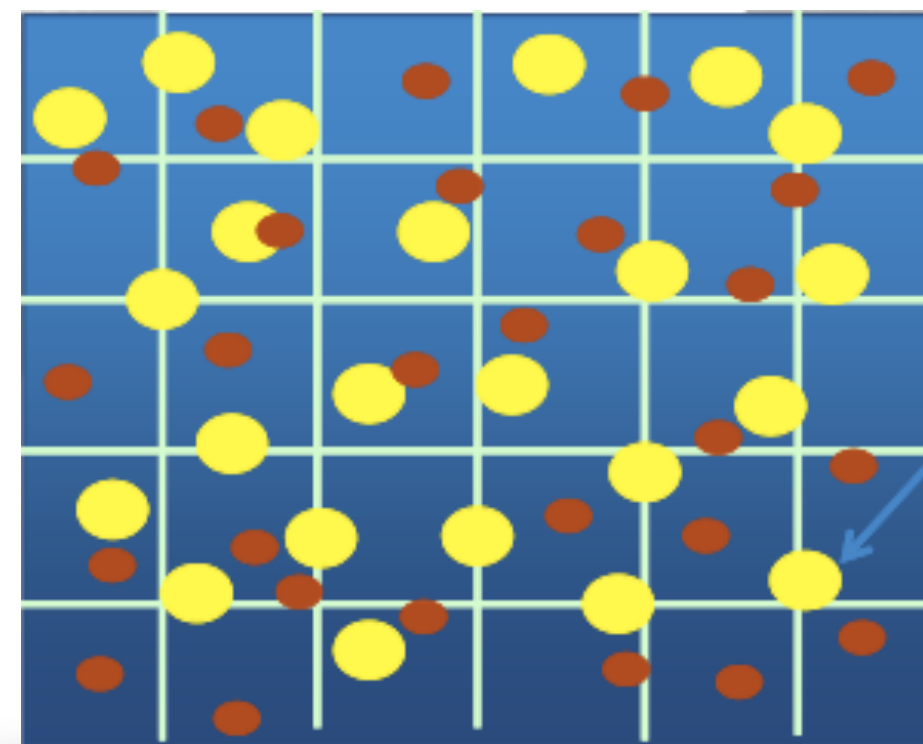
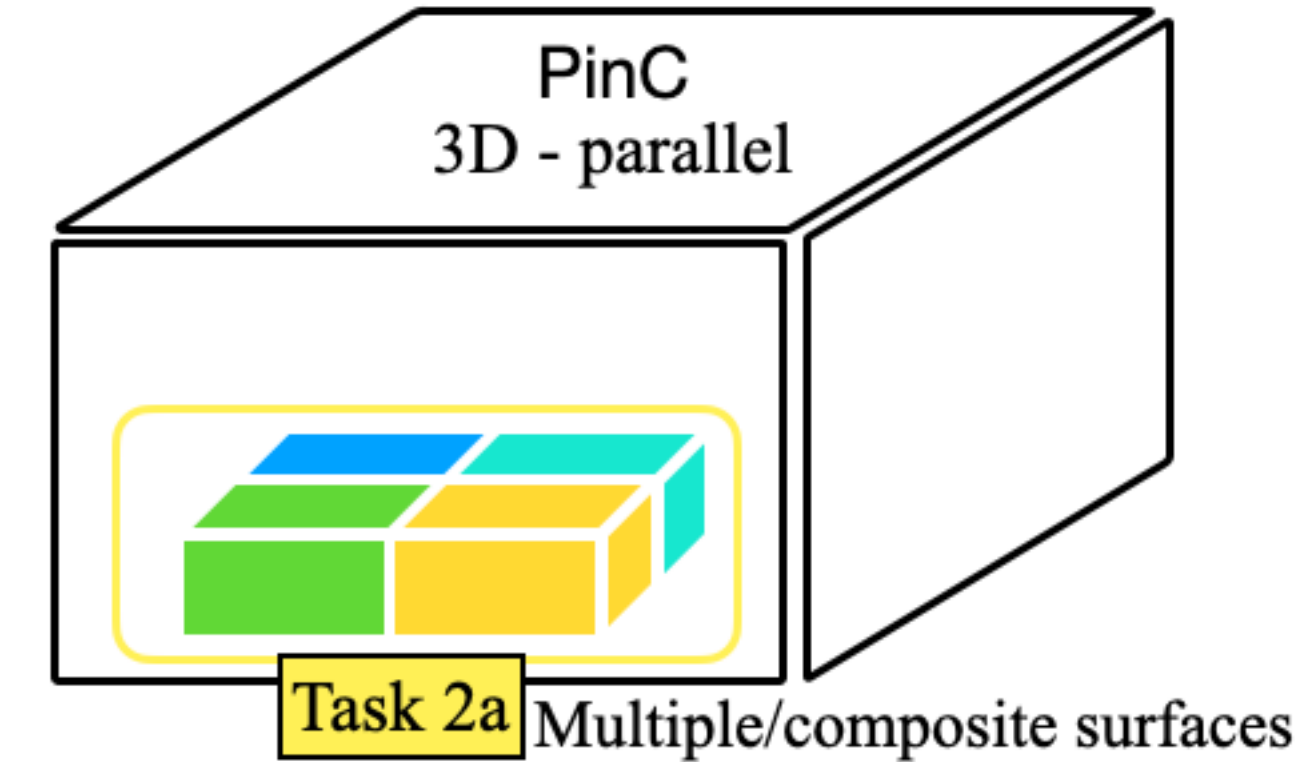


Patched Charge Model Benchmark.



Particle-in-Cell approach.

- PinC: C++/MPI-parallelised particle-in-cell code.
 - Before: Can handle 1 object/surface.
 - Today: Can handle multiple/composite objects/surfaces by leveraging the Capacitance Matrix method.
- Basic Particle-in-Cell algorithm:



$$\nabla \cdot \mathbf{E} = 4\pi\rho,$$

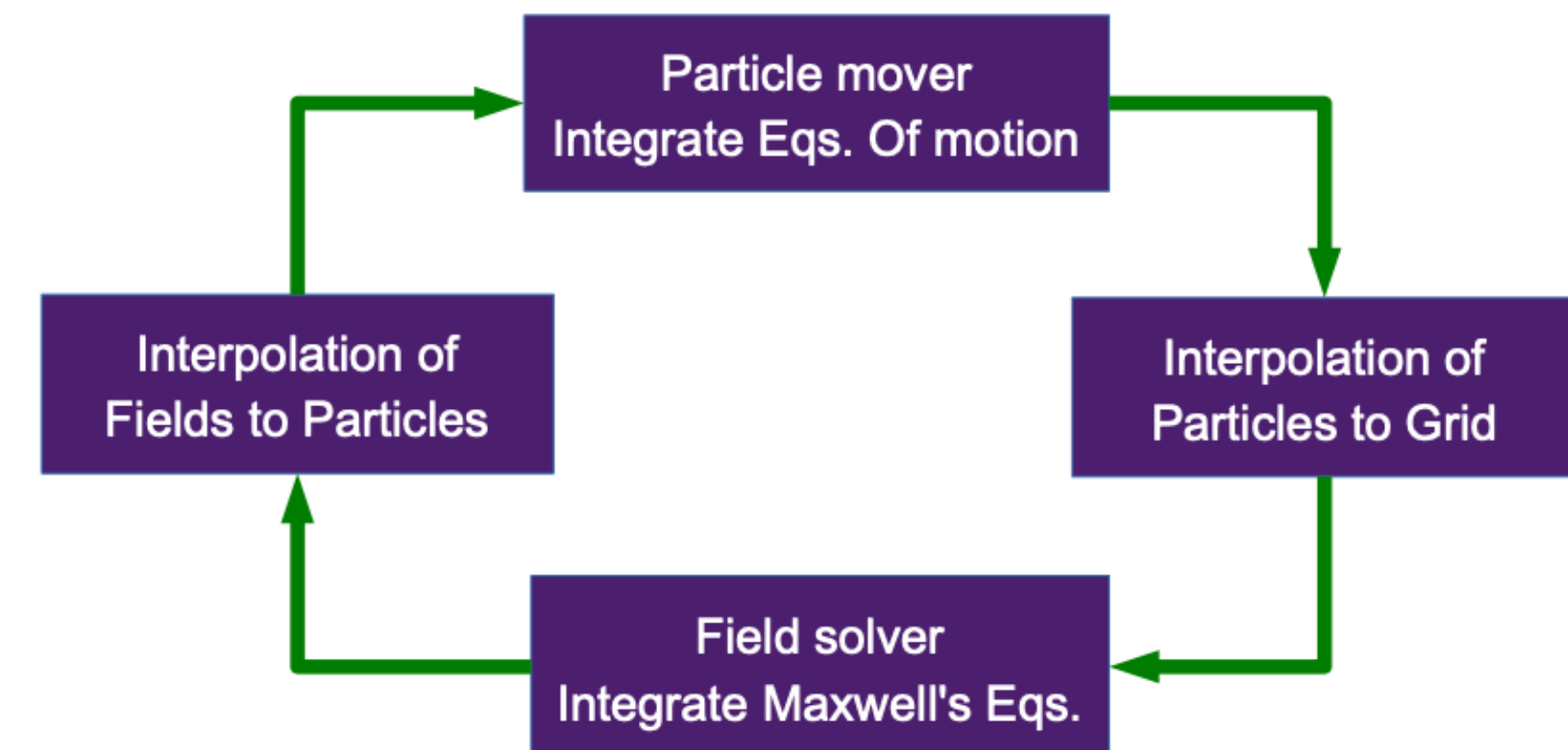
$$\nabla \cdot \mathbf{B} = 0,$$

$$\nabla \times \mathbf{E} = -\frac{1}{c} \frac{\partial \mathbf{B}}{\partial t},$$

$$\nabla \times \mathbf{B} = \frac{4\pi}{c} \mathbf{J} + \frac{1}{c} \frac{\partial \mathbf{E}}{\partial t}$$

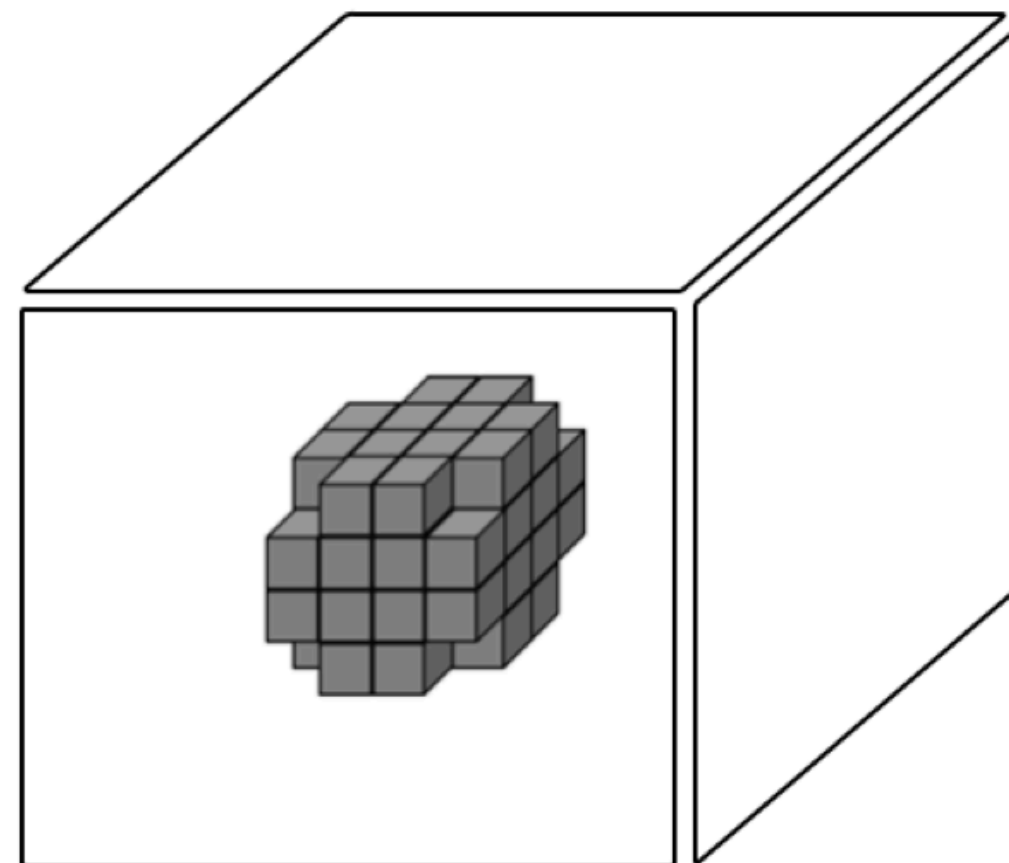
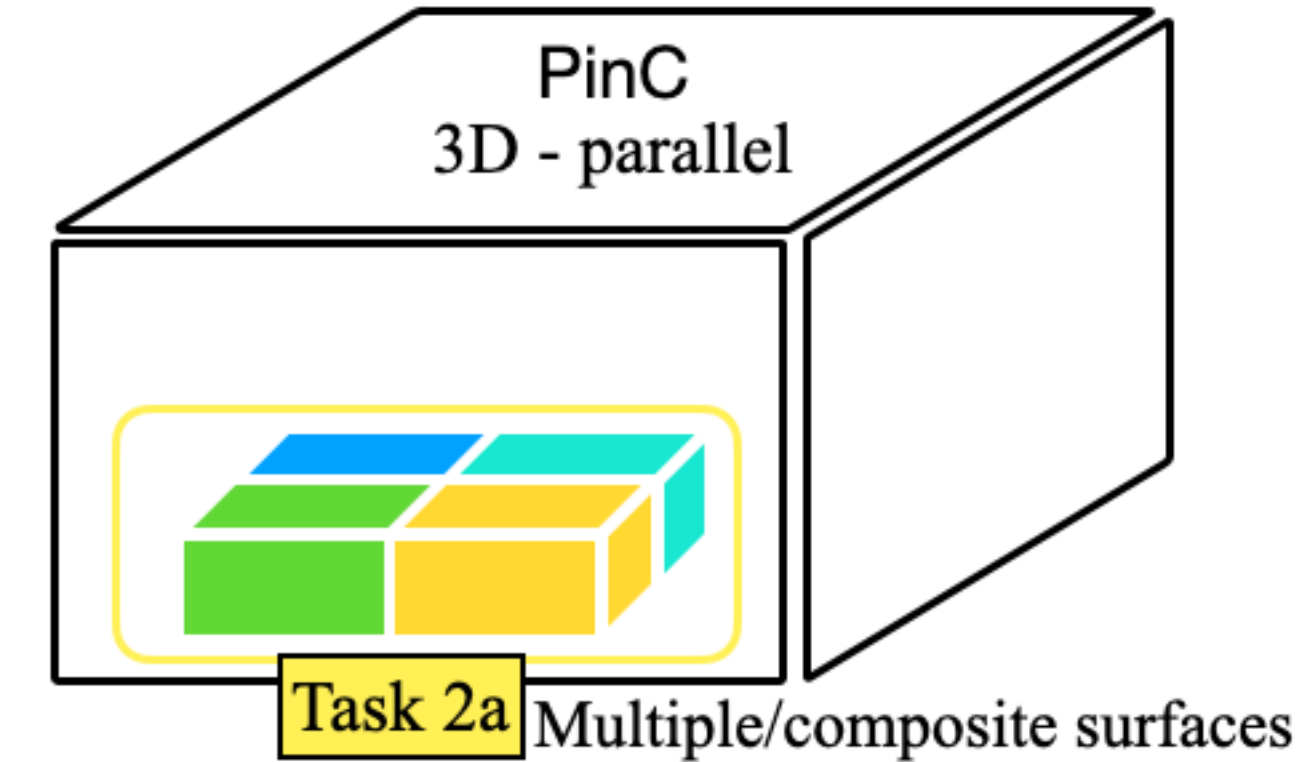
$$\frac{d\mathbf{x}_p}{dt} = \mathbf{v}_p,$$

$$\frac{d\mathbf{v}_p}{dt} = \frac{q_s}{m_s} \left(\mathbf{E}_p + \frac{\mathbf{v}_p \times \mathbf{B}_p}{c} \right)$$



Particle-in-Cell approach.

- PinC: C++/MPI-parallelised particle-in-cell code.
 - Before: Can handle 1 object/surface.
 - Today: Can handle multiple/composite objects/surfaces by leveraging the Capacitance Matrix method.
- **Capacitance Matrix method** (Miyake et al. [2009,2011]).

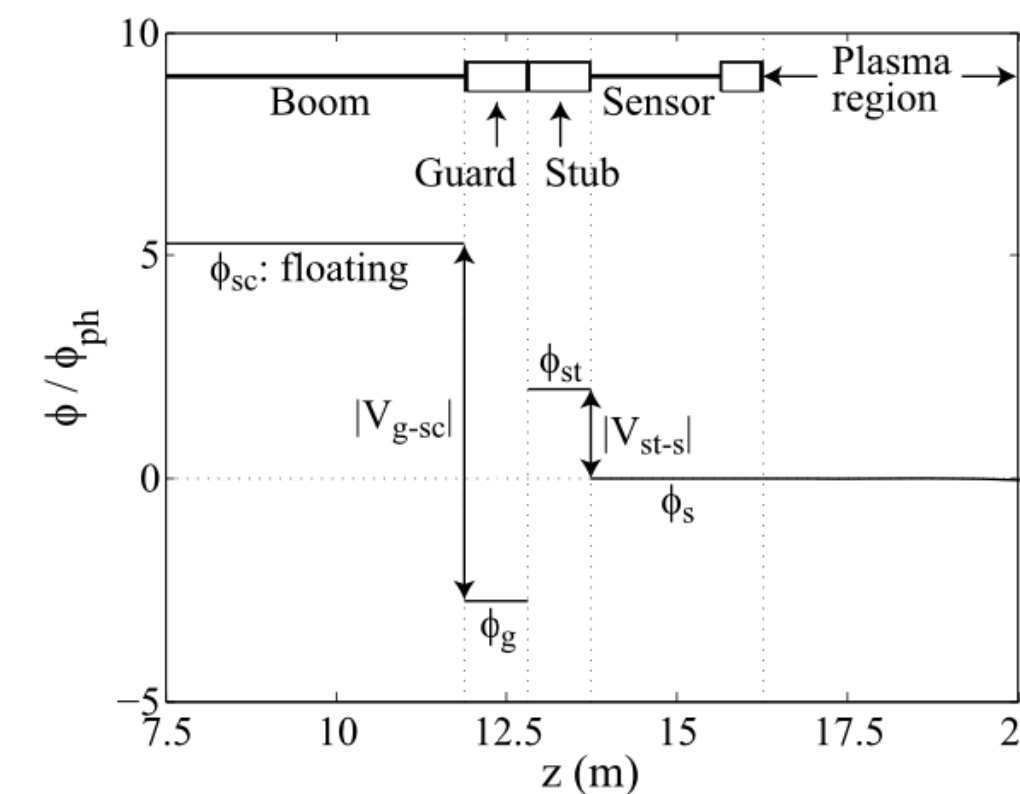


Relation between density and potential
(N_G : # grid nodes; N_B : # body nodes)

$$\rho_i = \sum_{j=1}^{N_G} A_{ij} \phi_j, \quad (i = 1, \dots, N_G),$$

$$\delta \rho_{s,i} = \sum_{j=1}^{N_B} C_{ij} \delta \phi_{s,j}, \quad (i = 1, \dots, N_B).$$

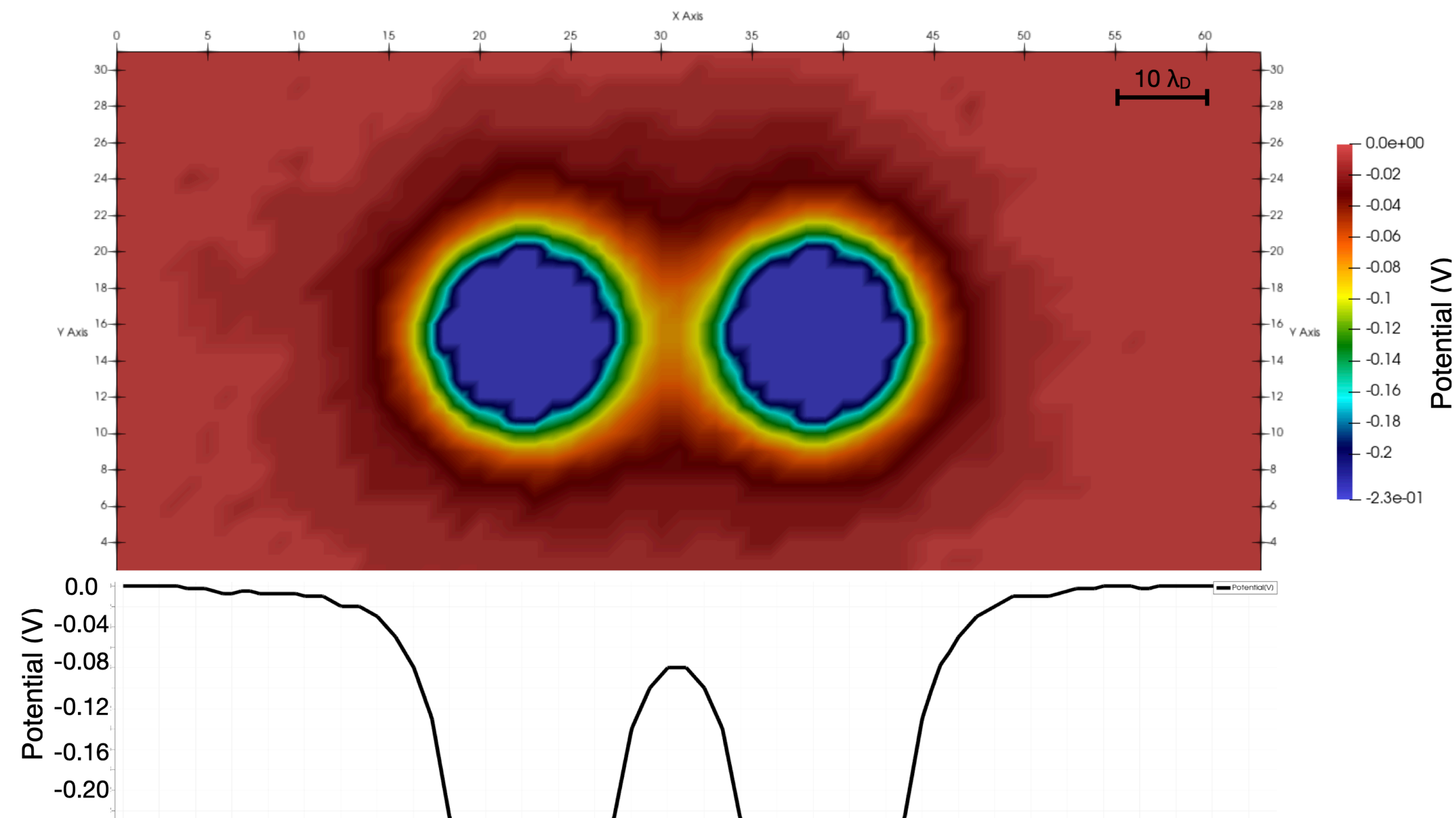
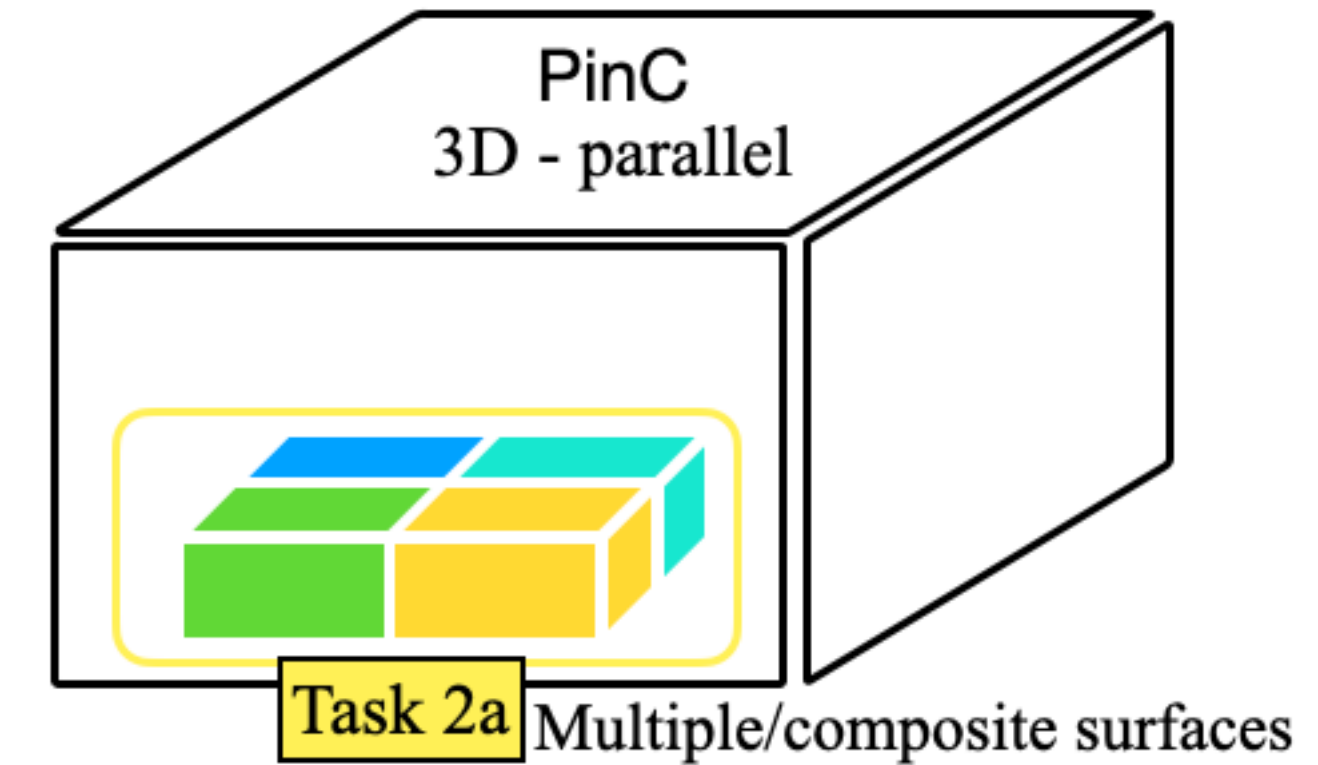
$$\phi_c = \frac{\sum_i \sum_j C_{ij} \phi_{s,j}}{\sum_i \sum_j C_{ij}}$$



$$\begin{aligned} \Delta Q_{s1} &= \sum_{i \in G_{s1}} \sum_j c_{ij} (\phi_j - \phi_j') \\ &= \phi_{s1} \sum_{i \in G_{s1}} \sum_{j \in G_{s1}} c_{ij} + \phi_{st1} \sum_{i \in G_{s1}} \sum_{j \in G_{st1}} c_{ij} \\ &\quad + \phi_{g1} \sum_{i \in G_{s1}} \sum_{j \in G_{g1}} c_{ij} + \phi_{sc} \sum_{i \in G_{s1}} \sum_{j \in G_{sc}} c_{ij} \\ &\quad + \phi_{g2} \sum_{i \in G_{s1}} \sum_{j \in G_{g2}} c_{ij} + \phi_{st2} \sum_{i \in G_{s1}} \sum_{j \in G_{st2}} c_{ij} \\ &\quad + \phi_{s2} \sum_{i \in G_{s1}} \sum_{j \in G_{s2}} c_{ij} - \sum_{i \in G_{s1}} \sum_j c_{ij} \phi_j' \\ &= \phi_{s1} \sum_{i \in G_{s1}} \sum_{j \in G_{s1+s2}} c_{ij} + V_{st1-s1} \sum_{i \in G_{s1}} \sum_{j \in G_{st1}} c_{ij} \\ &\quad + V_{g1-sc} \sum_{i \in G_{s1}} \sum_{j \in G_{g1}} c_{ij} + \phi_{sc} \sum_{i \in G_{s1}} \sum_{j \in G_{g1+sc+g2}} c_{ij} \\ &\quad + V_{g2-sc} \sum_{i \in G_{s1}} \sum_{j \in G_{g2}} c_{ij} + V_{st2-s2} \sum_{i \in G_{s1}} \sum_{j \in G_{st2}} c_{ij} \\ &\quad + \phi_{s2} \sum_{i \in G_{s1}} \sum_{j \in G_{s2+s2}} c_{ij} - \sum_{i \in G_{s1}} \sum_j c_{ij} \phi_j', \end{aligned}$$

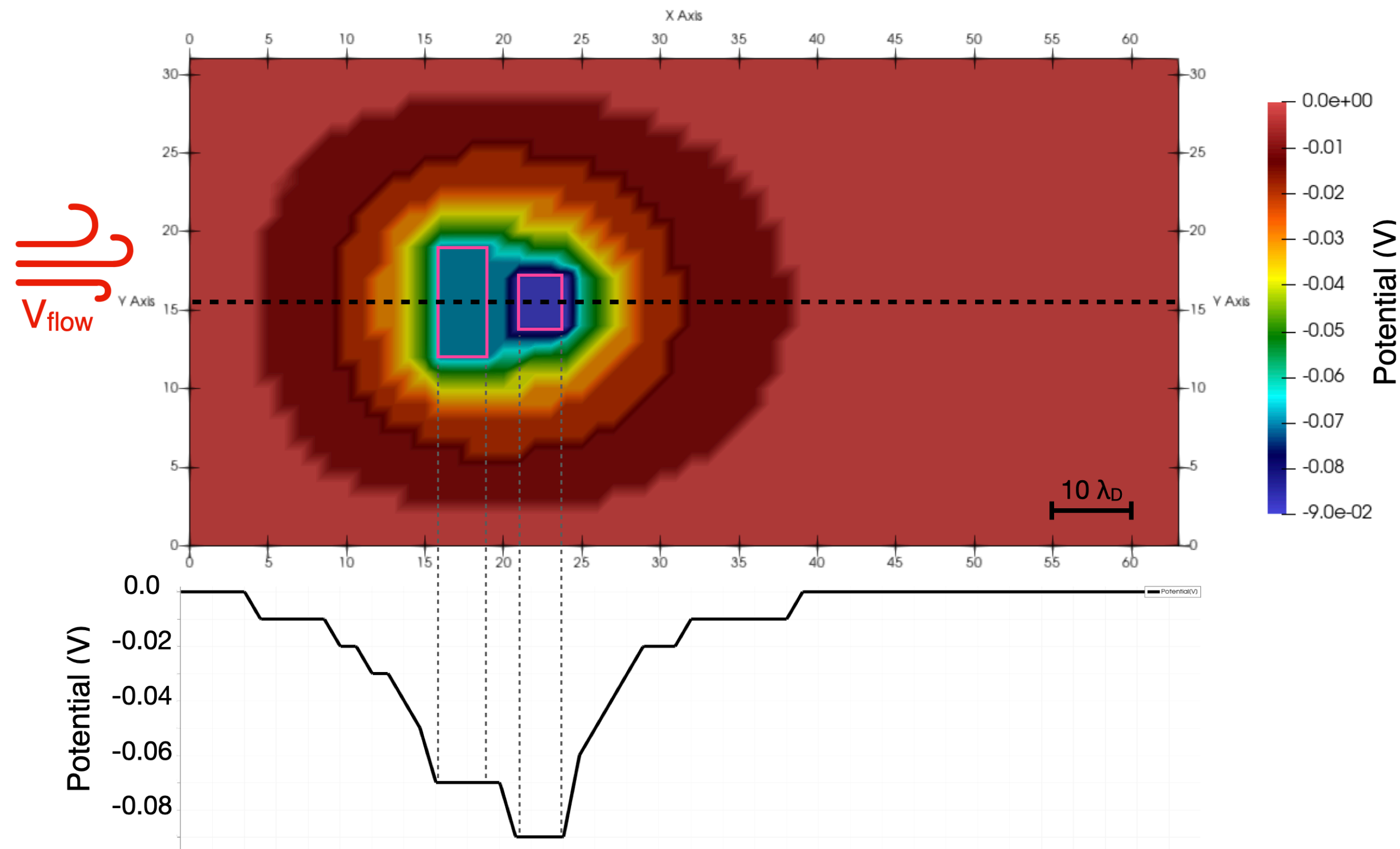
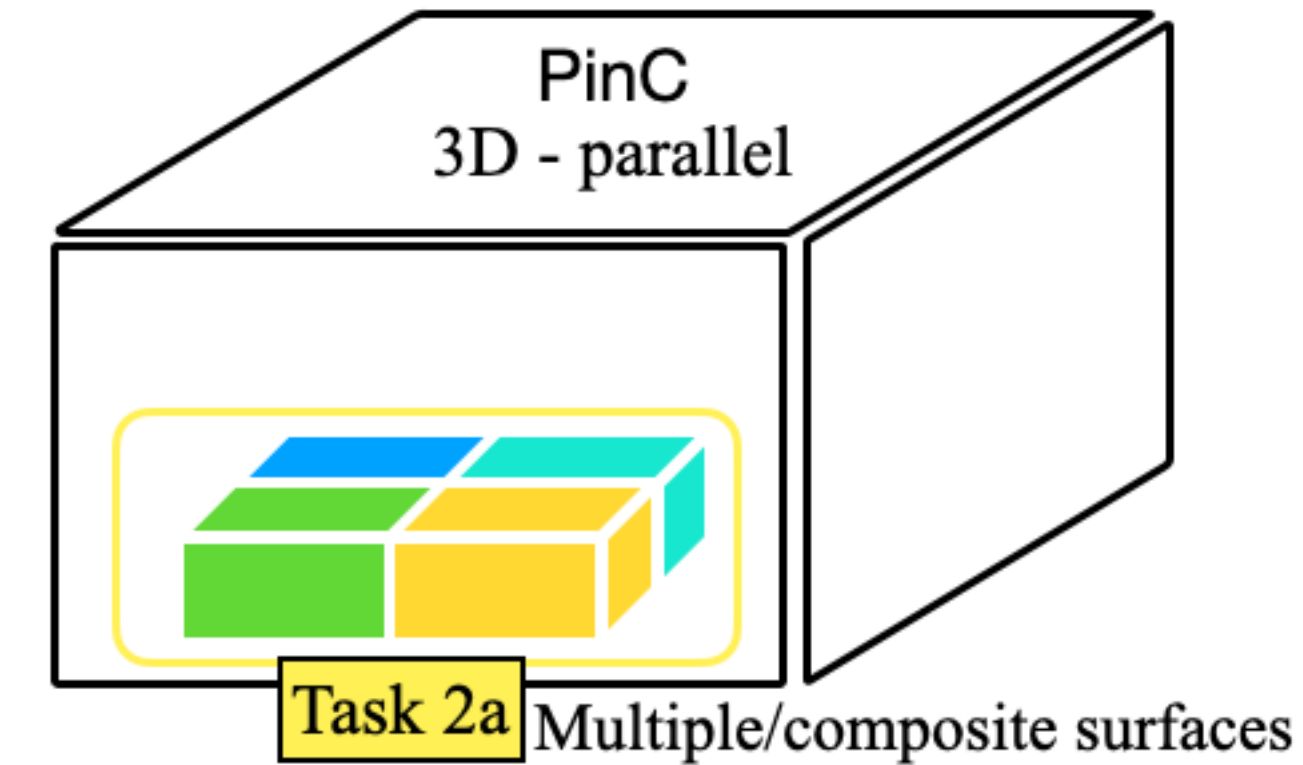
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- Example: two spheres in a stationary plasma.



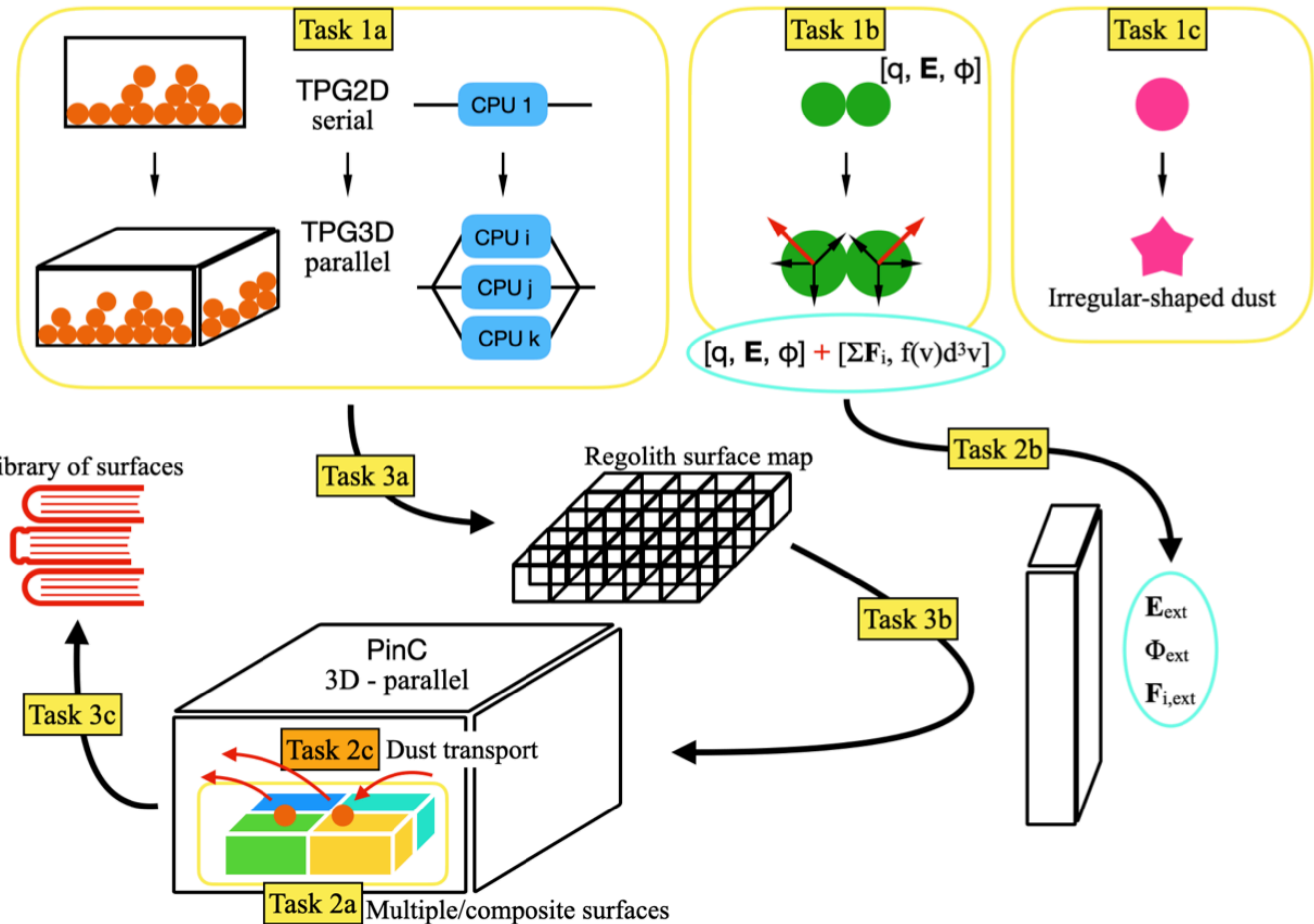
Particle-in-Cell approach.

- PinC: C++/MPI-parallelised particle-in-cell code.
 - Multiple objects by leveraging the Capacitance Matrix method.
- Example: two differently-sized prisms in flowing plasma.



To-dos

- Code-coupling (Tasks 3a-b).
- Dust transport model (Task 2c).
- Validate the framework against lab and flight results.



Thank you for your attention!

Questions?

Draw here.