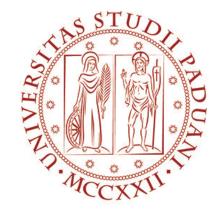
MuCol: training on detector design and physics performance tools



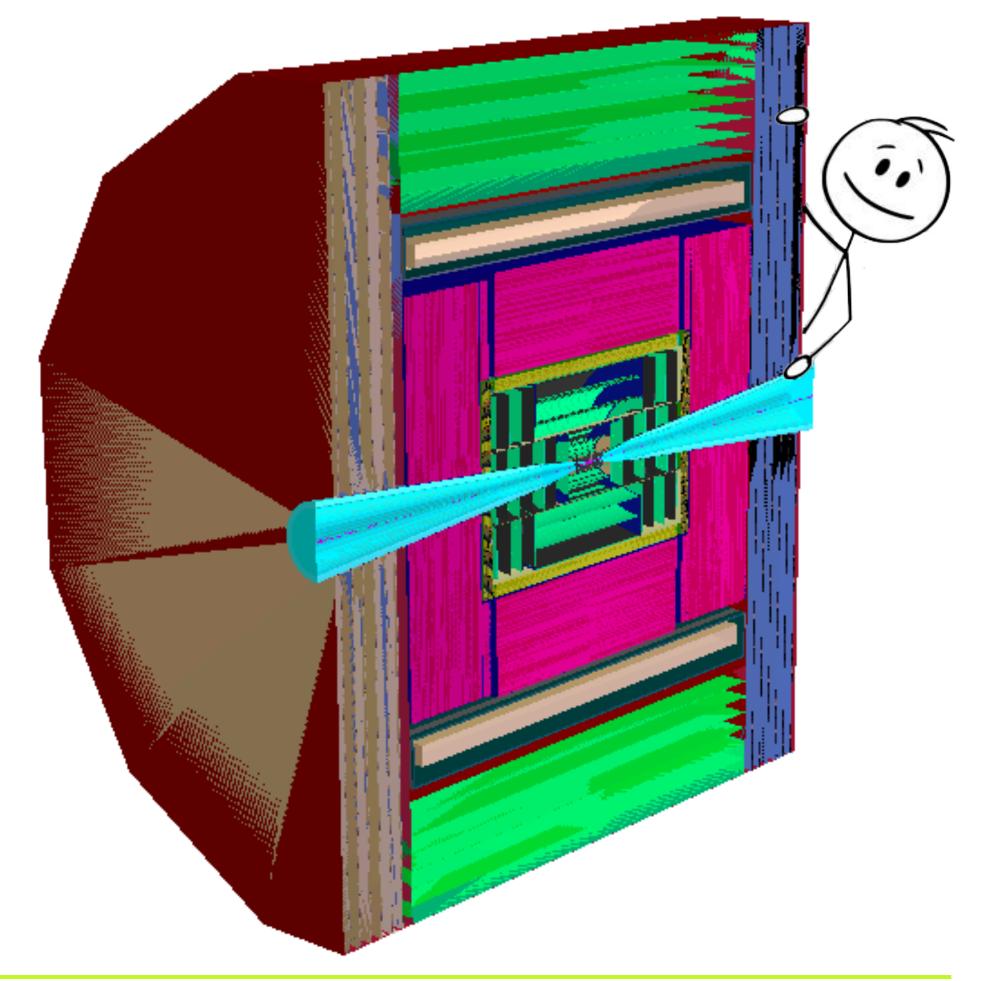




Università degli Studi di Padova



# Description of the actual detector



DAVIDE ZULIANI<sup>1,2\*</sup>

¹UNIVERSITÀ DI PADOVA, ²INFN PADOVA





### Introduction

- This talk will describe the detector used so far in our studies and considered in this tutorial
  - 1. Detector overview
  - 2. Sub-detectors description
  - 3. Detector and Machine-Detector Interface (MDI)
  - 4. Conclusions





### Detector: overview

- The starting point to design the Muon Collider detector is CLIC's detector
- Insertion of two nozzles to mitigate the impact of the Beam Induced Background (BIB)



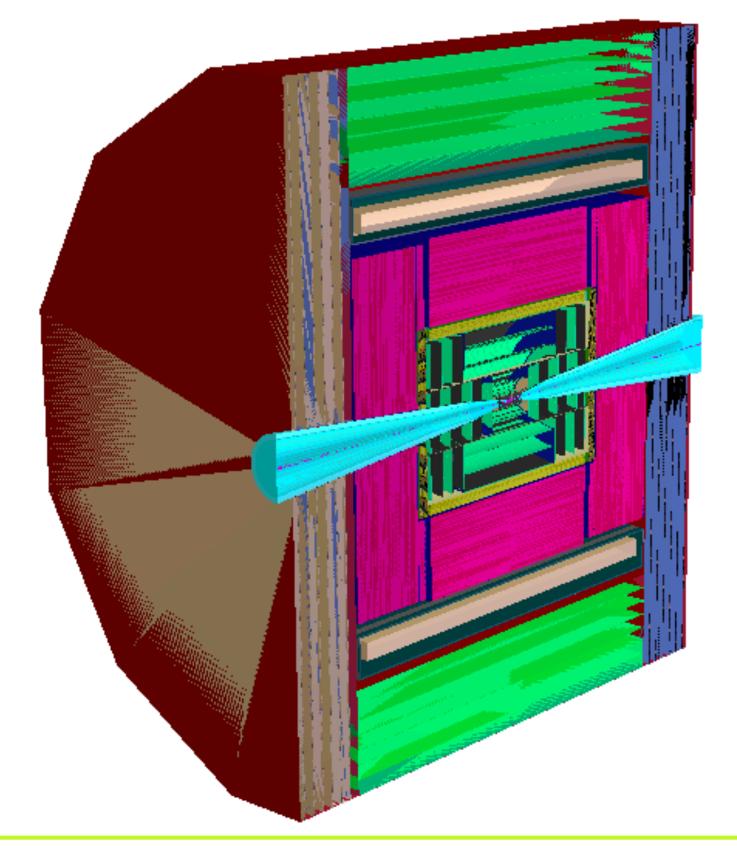


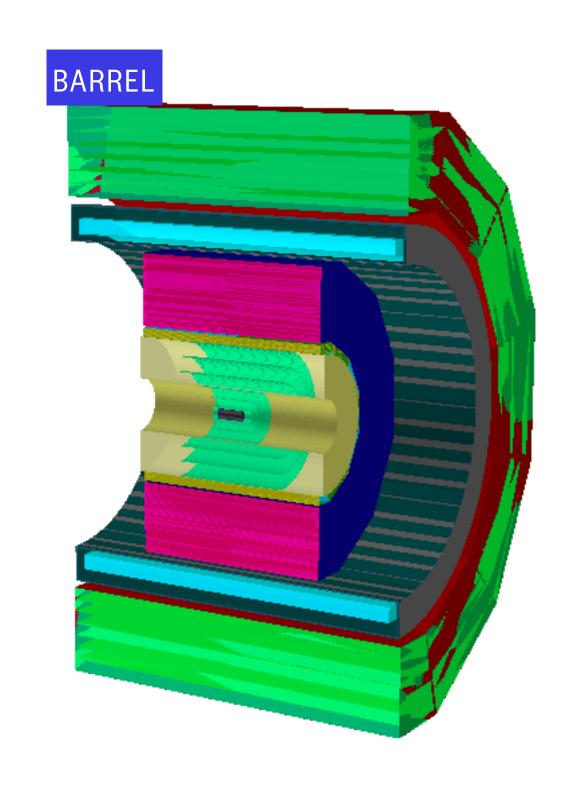


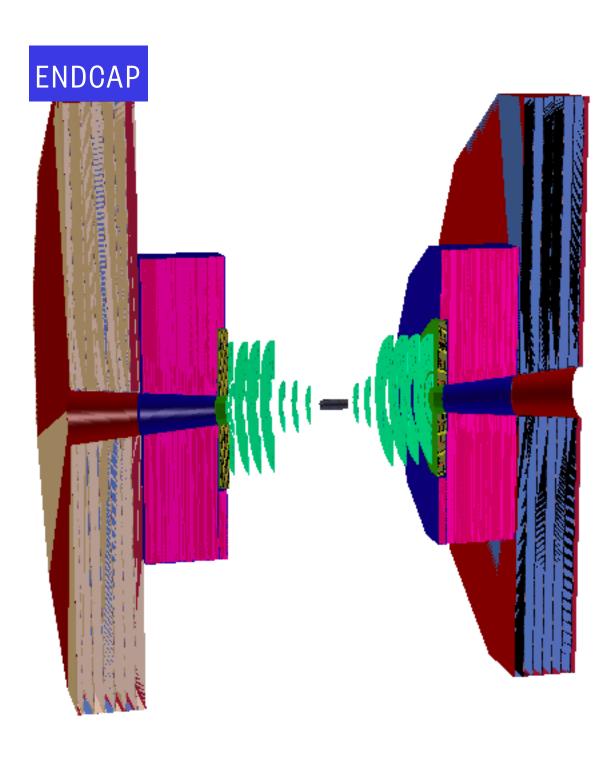


### Detector: overview

- Given the broad physics target, cylindrical geometry with an angular coverage close to  $4\pi$
- Namely, the detector is divided in two parts: barrel (central region) and endcap (forward region)











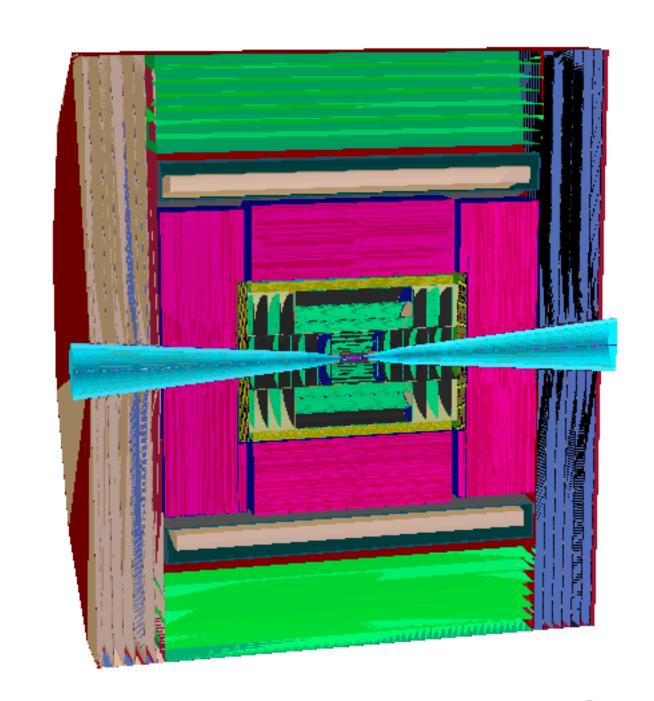


### Detector: overview

Standard sub-detector structure (from interaction point to outside)

Vertex detector

Tracking system



Muon system

Calorimeters

Solenoid



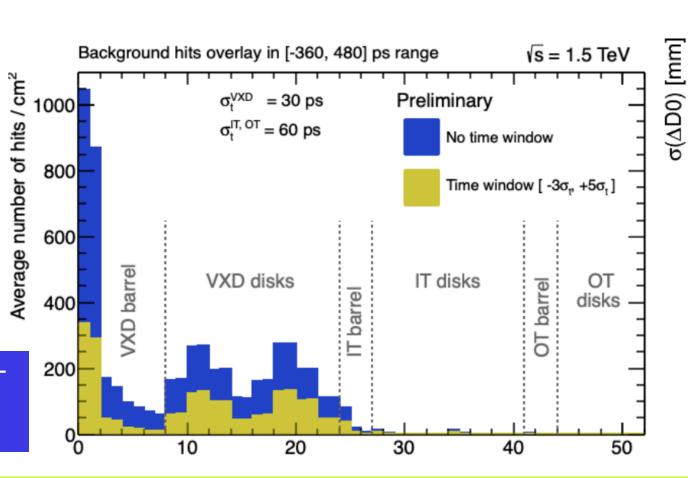


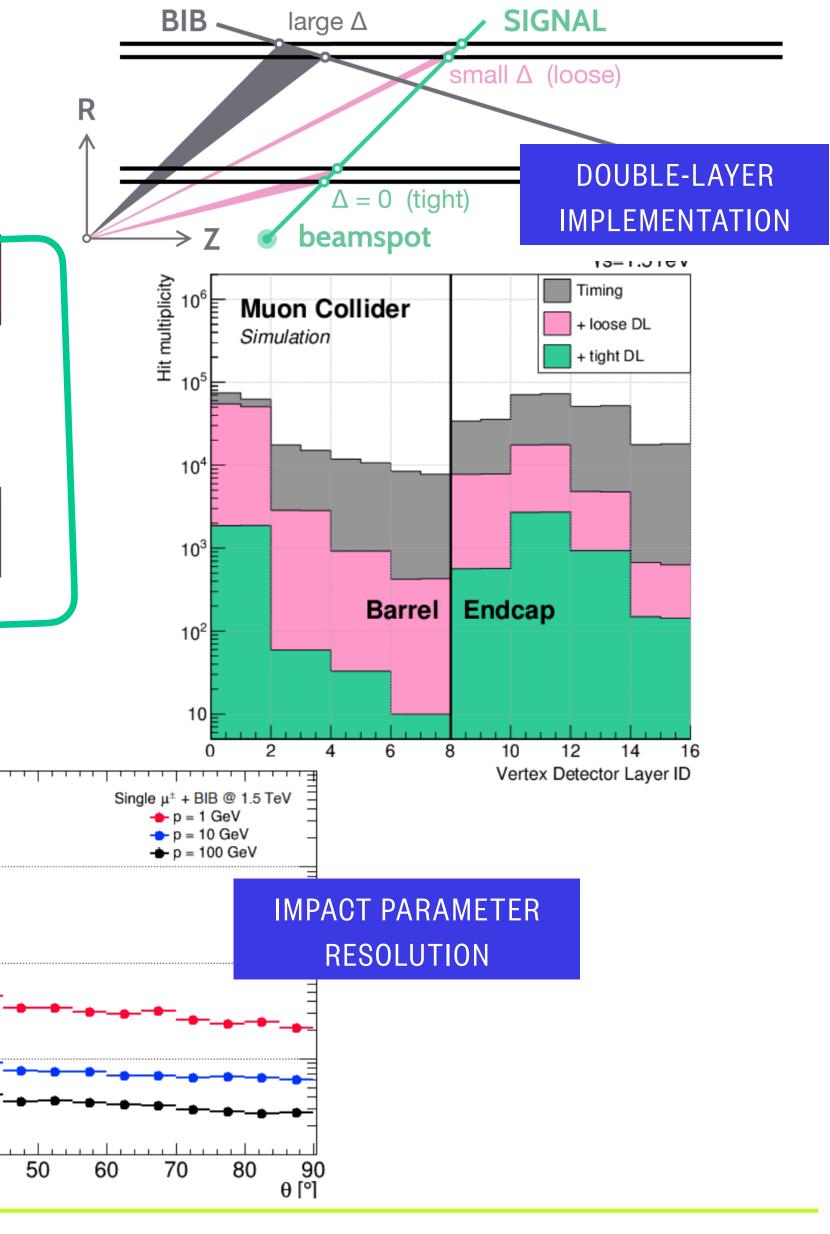
### Vertex detector

• Barrel: 4 cylindrical layers

• Endcap: 4+4 disks

- Radiation hardness!
- Silicon sensors with double-layer technology
  - $25x25 \mu m^2$  pixels
  - Sensor thickness:  $50 \mu m$
  - $\sigma_{r-\phi} = 5 \ \mu \text{m}$
  - $\sigma_z = 5 \ \mu \text{m}$
  - $\sigma_t = 30 \text{ ps}$





**TOWARDS A MUON COLLIDER** 

EFFECT OF TIMING CUT
ON OCCUPANCY

**Muon Collider** 

Simulation







### Tracking system

#### • Inner Tracker

Barrel: 3 cylindrical layers

Endcap: 7+7 disks

Silicon macro-pixels sensors with  $50 \mu m \times 1 mm size$ 

• Sensor thickness =  $100 \mu m$ 

•  $\sigma_t = 60 \text{ ps}$ 

•  $\sigma_{r-\phi} \times \sigma_z = 7 \ \mu\text{m} \times 90 \ \mu\text{m}$ 

#### **Outer Tracker**

• Barrel: 3 cylindrical layers

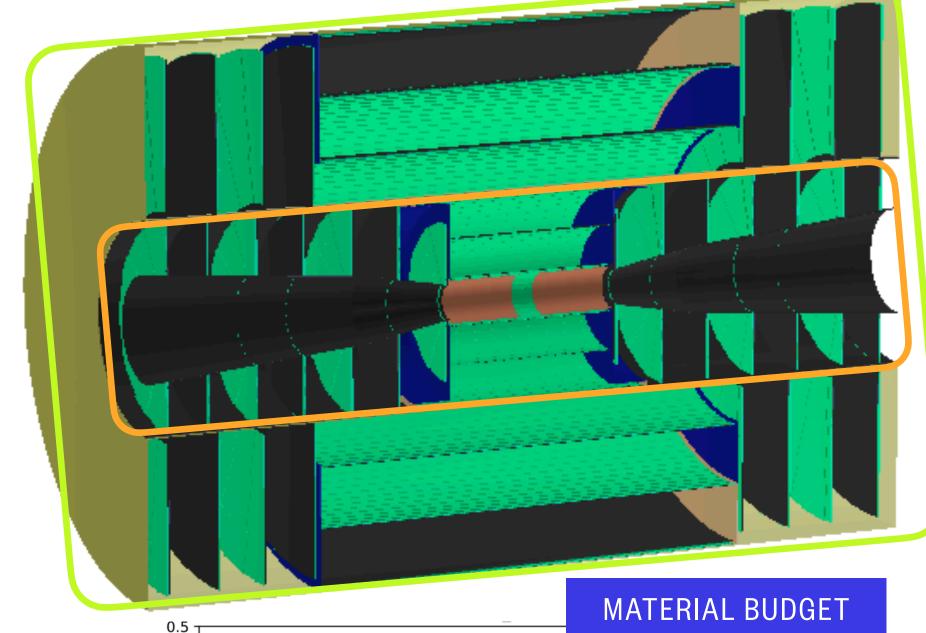
Endcap: 4+4 disks

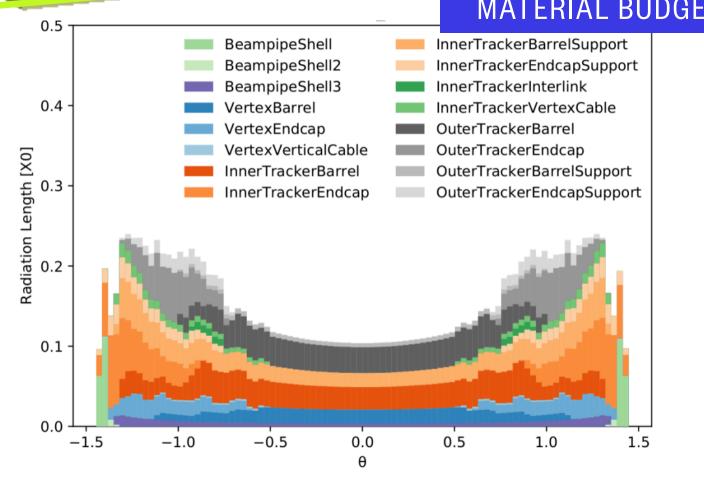
Silicon micro-strip sensors with  $50 \mu m \times 10 mm size$ 

Sensor thickness =  $100 \mu m$ 

•  $\sigma_t = 60 \text{ ps}$ 

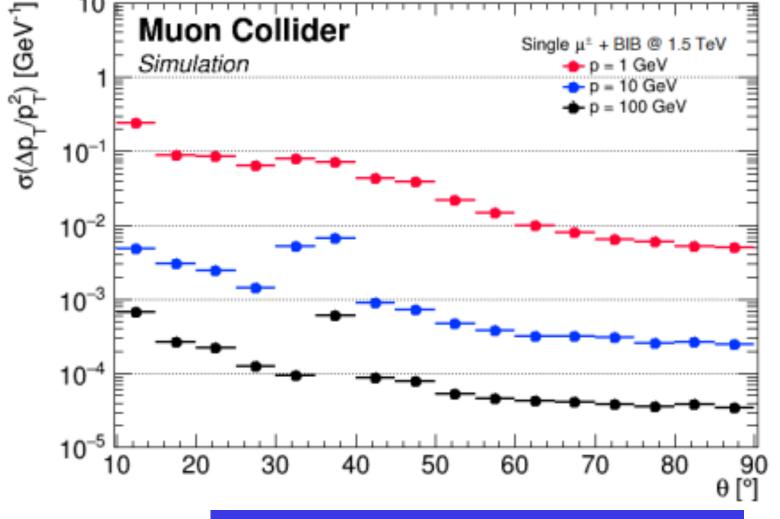
•  $\sigma_{r-\phi} \times \sigma_z = 7 \ \mu\text{m} \times 90 \ \mu\text{m}$ 



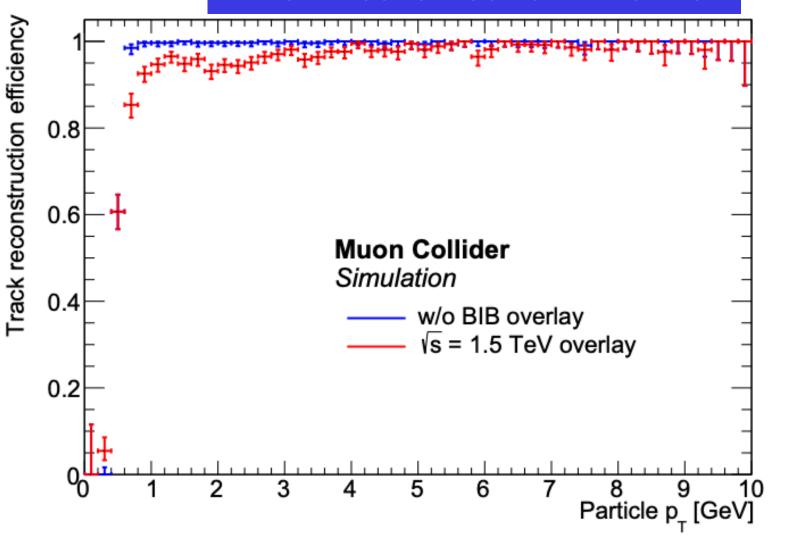


#### **TOWARDS A MUON COLLIDER**

#### TRANSVERSE MOMENTUM RESOLUTION



#### TRACK RECONSTRUCTION EFFICIENCY





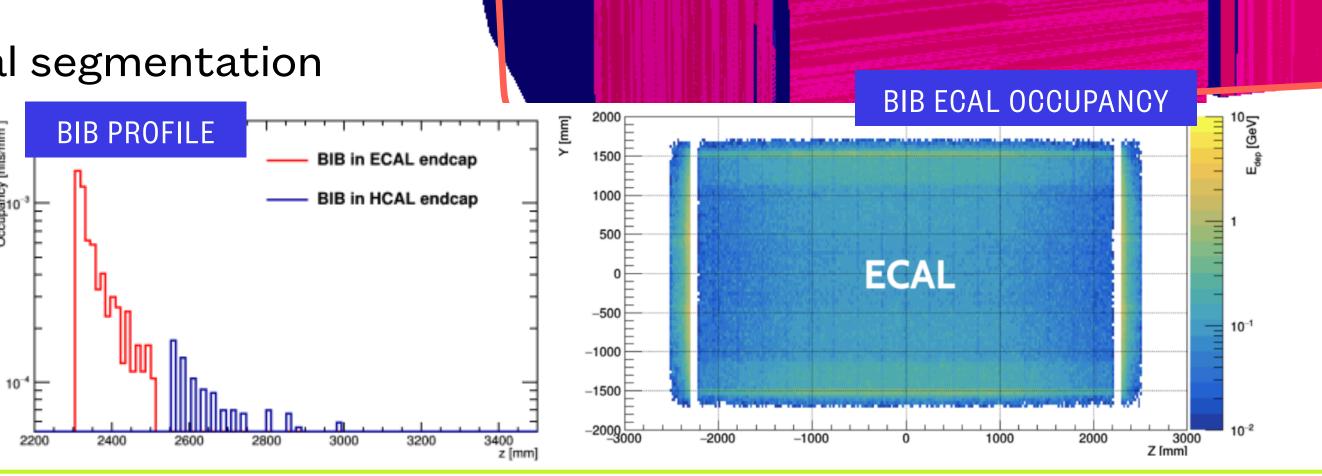


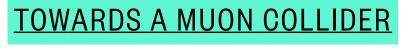


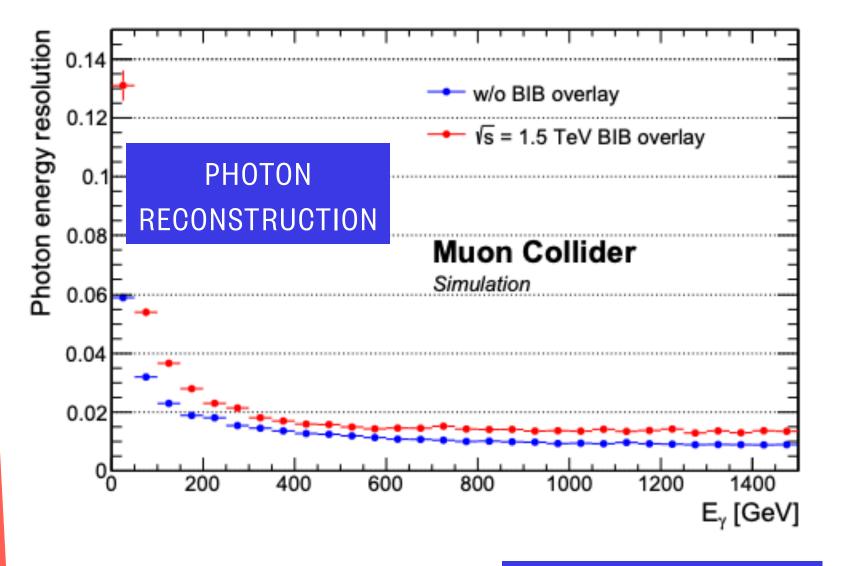




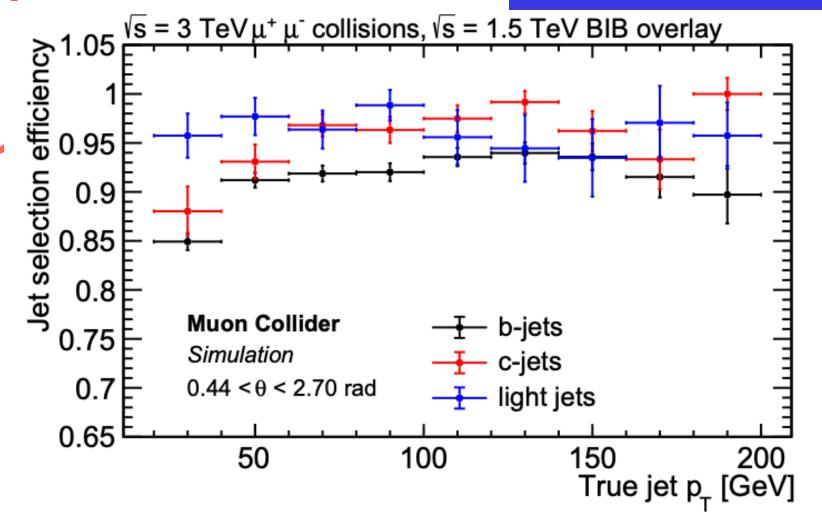
- - silicon+tungsten technology
  - 40 layers with 5x5 mm<sup>2</sup> cells
- HCAL
  - steel+plastic scintillating tiles
  - 60 layers with  $30x30 \text{ mm}^2$ cells
- Good timing performance (~100 ps)
- Longitudinal segmentation







### **JET SELECTION EFFICIENCY**



-10

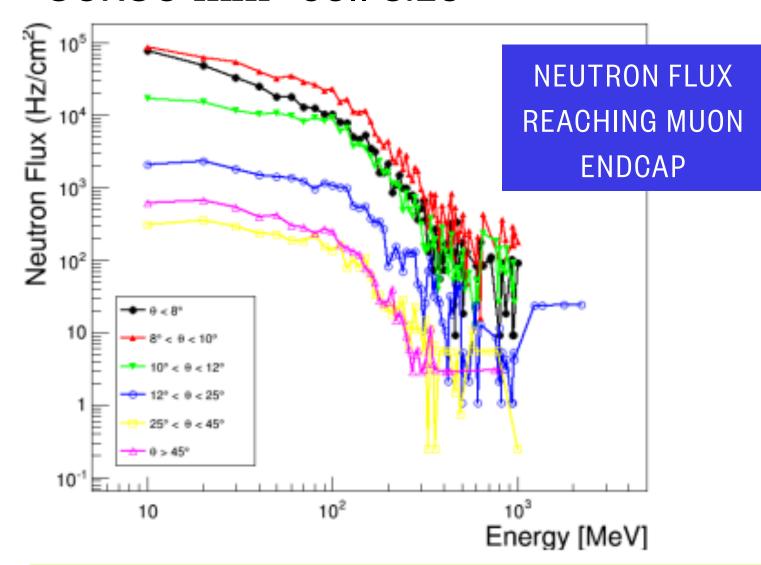
-40

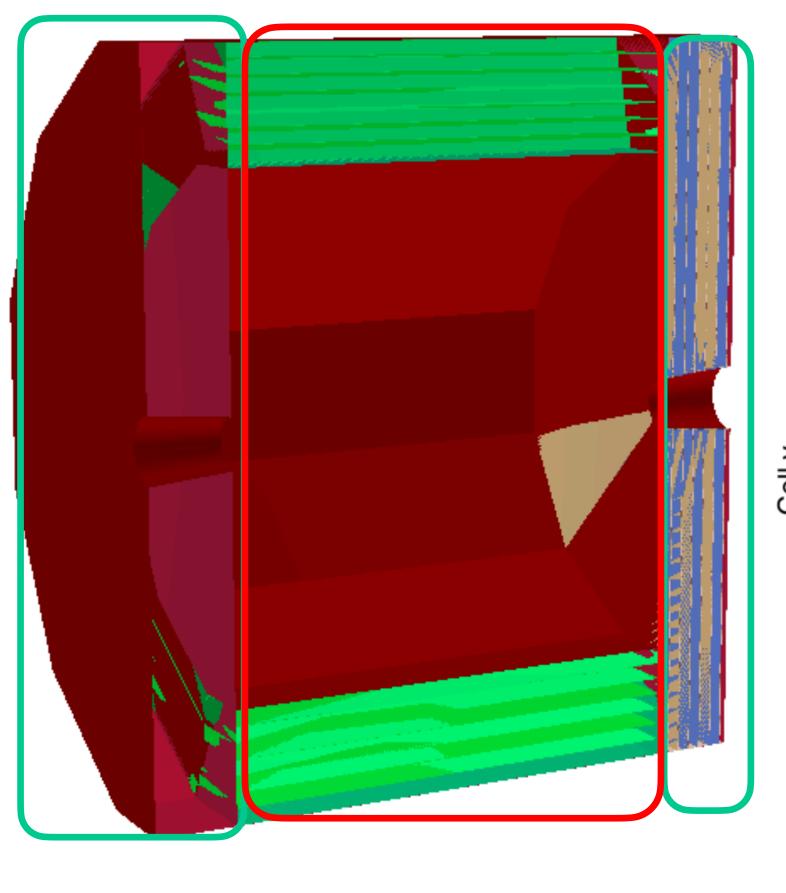


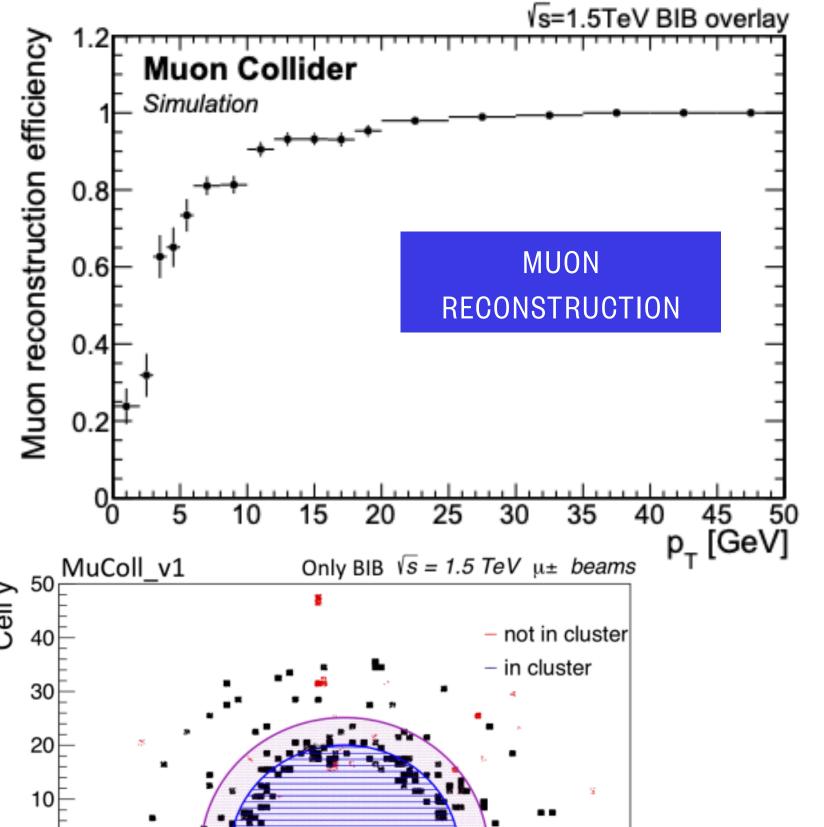


## Muon system

- Barrel: 7 cylindrical layers
- Endcap: 6+6 disks
- Steel layers to return magnetic field
- Technology: Resistive-Plate Chambers
  - Low cost
  - But low acquisition rate
- 30x30 mm<sup>2</sup> cell size







-50-50 -40 -30 -20 -10 0 10 20 30 40 50

**TOWARDS A MUON COLLIDER** 

HIT MAP ON MUON

ENDCAP

Cell x



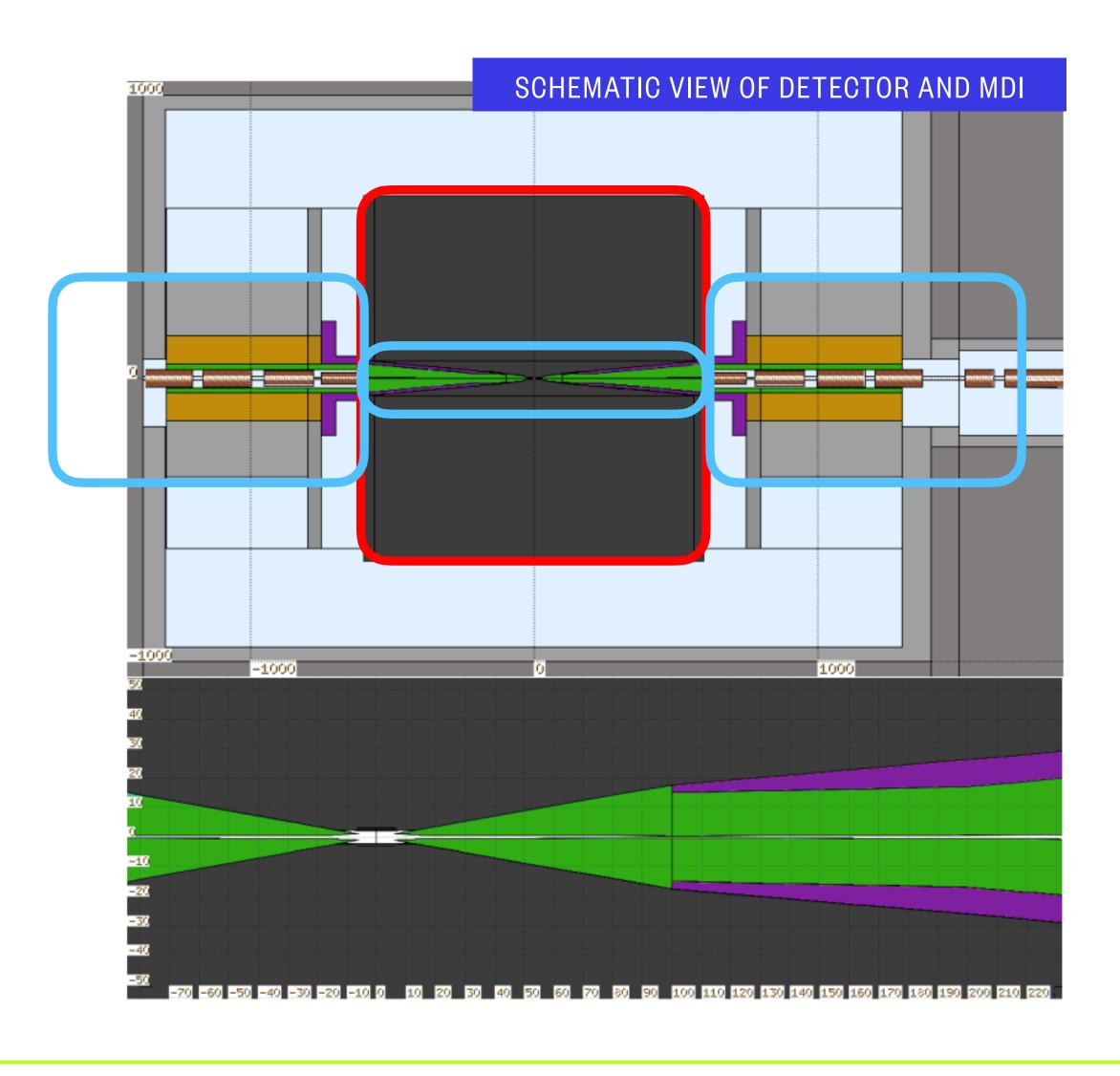




### Detector and MDI

- To mitigate BIB, fundamental cross-talk between **Detector** and **MDI**
- MDI takes care of nozzles optimisation and BIB mitigation
  - But, this influences the detector too!
- Particularly interesting when thinking about 10 TeV detector optimisation!

SEE DONATELLA'S TALK FOR MORE **DETAILS ON BIB AND MDI** 







### Conclusions

- The detector is a key player in simulations
- Fundamental to understand its features and its relation with MDI
- You will learn how to <u>use</u> it and <u>modify</u> it

Thank you for your attention, and enjoy the hands-on sessions