





Accelerated demonstrator of electromagnetic Particle Transport

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Simulation on GPU - can we do that?

Functionality: make all simulation components work on GPU

- Physics, geometry, field, but also user sensitive detector code and hits?
- Simulate e^+ , e^- and γ electromagnetic shower
- Correctness: validate results and ensure reproducibility
 - Producing compatible results with Geant4 equivalent?
- Usability: integrate in a hybrid CPU-GPU Geant4 workflow
 - Usable within real experiment frameworks?
- Performance: understand/address bottlenecks limiting performance
 - Can we actually use the GPU in an efficient/beneficial way?
 - Show stoppers? Bottlenecks? Can we overcome them?

The AdePT project

- Trying to get answers for most of these questions
 - GitHub <u>repository</u>, initial commit in Sep 2020, θ (10) contributors
- Strategy: integrate gradually features as new examples
 - No library/framework, just core infrastructure, to maximize flexibility to explore different directions and adapt to different requirements

ant-sim / AdePT Publ

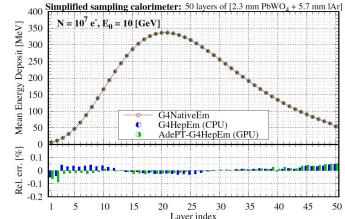
- Minimal external dependencies
 - Geometry: <u>VecGeom</u> library, enhancing its GPU-related features
 - Physics: <u>G4HepEm</u> library, a GPU-friendly port of Geant4 EM interactions
- Understand and improve the integration with experiments and their frameworks
 - Discussions/collaboration with ATLAS, CMS and LHCb ongoing

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At a glance: physics

- G4HepEm: GPU-friendly compact rewrite of EM processes for HEP
 - Covers the <u>complete physics</u> for e⁻, e⁺ and γ particle transport
- Design of library very supportive for heterogeneous simulations
 - Stateless interfaces working on both CPU and GPU
 - Data: physics tables and other data structures relying on Geant4, but standalone after being copied to GPU
- Verified against Geant4 standalone
 - At ‰ level in the sampling calorimeter test case





At a glance: geometry

Relying on the builtin VecGeom CUDA support

- Identical object model for CPU and GPU, non-specialized for the GPU use case
- CUDA-specific, non-portable
- Improved gradually the GPU support
 - Developed index-based navigation state handling, single-precision support, faster GPU init
 - Moving from a simple non-optimized to a more efficient **BVH navigator**
 - Adopting modern CMake GPU support

The current geometry approach is a major GPU bottleneck

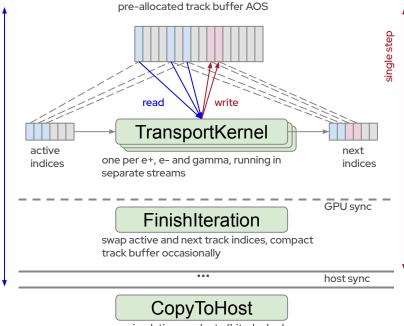
- Strong motivation to develop a surface model for GPU support
 - Portable less complex & less divergent code, creating a surface-based view on device
 - Our major work <u>item</u> (see: surface model presentation link)

Parallelization in AdePT

- Simulation is done in steps, moving particles to either boundaries or physics processes
- All active tracks available are stepped at once (Geant4 transports one particle at a time)
 - Much higher degree of parallelism and more uniform work for the GPU
- No "thread-local" state, everything embedded in the track
 - Energy, position/direction, state needed across steps
 - Random number generator state (RANLUX++) per track to ensure reproducibility
 - Strategy to spawn a new sequence for daughter particles from the current state
 - Tracks pre-allocated per particle type in thread-safe containers
 - Atomic counter to hand on track slots to be filled by kernels

Stepping loop

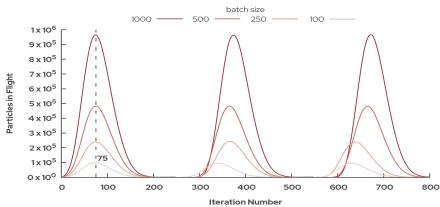
- Pre-allocated track buffer
- Separate kernels per particle type
- while (nactive > 0) Separate kernels for continuous and different discrete processes also possible
- Double buffer of active/next track indices
 - Atomic access, next-unused slot track allocation policy
 - Dead tracks leave holes, track container compacted occasionally
- Copy to host simulation products at the end (hits, leaked tracks)

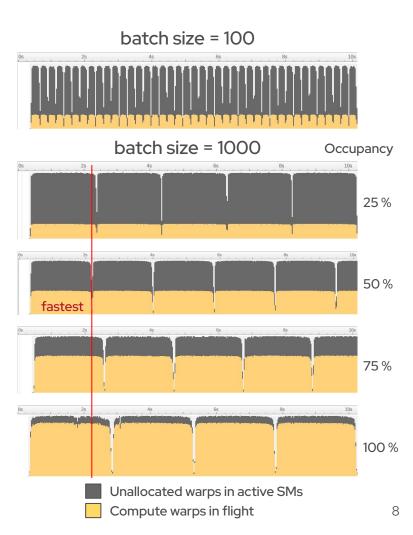


copy simulation products (hits, leaked tracks) back to host

Run Time Characteristics

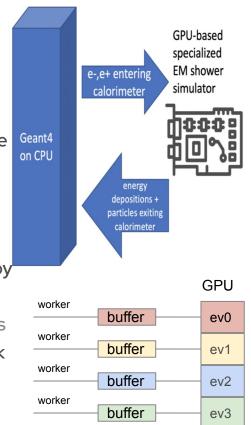
- putting more work per batch does more work in the same #iterations (steps)
 - limited by available memory AND available tracks
- hints already to using strategies to fill the gaps
 - e.g. more CPU threads doing concurrent events
- performance: sweet spot at about 50% occupancy (register-hungry code)
- 36 SM GPU ≈64 CPU threads: a consumer card can double the throughput of a dual socket machine





AdePT-Geant4 integration

- AdePT only provides EM physics for e⁺, e⁻ and γ
 - Cannot be used standalone for simulating a full experiment
 - In a first phase it could be used as accelerator for the EM part, in the same way as fast simulation models can be used in Geant4
- Developed an integration interface allowing a Geant4 region to become the "GPU region"
 - Intercepting and buffering for GPU particles sent asynchronously by Geant4 threads
 - Available from Geant4 11.1, patches available for older versions
 - Sensitive detector code run on device, hits+leaked tracks sent back to host
 - An initial approach under evaluation by several experiments

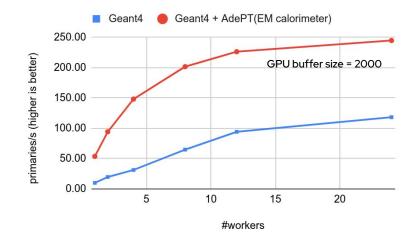


Integration performance

Performance in this approach increases with :

- Fraction of time spent in the GPU-accelerated region (Amdahl law)
- GPU buffer size and event size (to fill it)
- Performance degrades with :
 - Number of exchanges CPU-GPU per event
 - Number of CPU threads (GPU saturation)
- Why not the full detector on GPU?
 - Not limited by geometry
 - Possible for EM particles
 - Except lepto-nuclear processes (rare) that can be delegated to CPU
 - Limited by sensitive detector code GPU awareness - incentive to write GPU-friendly scoring

Throughput for batches of 100×10 GeV e⁻/event gun, 85% of simulation time in the EM calorimeter

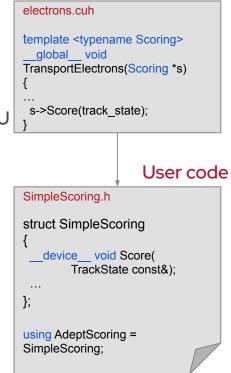


cms_2018 setup, Xeon(R) CPU E5-2630v3 + RTX2070

Hooking user code

AdePT

- AdePT advanced <u>examples</u> provide a mechanism to implement Geant4-like sensitive detector code
 - Scoring type to be implemented and aliased as *AdeptScoring*
 - Transport kernels templated on this type, calling back directly on GPU
- Fairly straightforward interfaces
 - GPU data management (hits) allocation and cleanup, copy to host
 - A very simple atomic calorimeter cell accumulator as example
 - *AdeptScoring::Score* method to intercept current step as in Geant4
- One of the main challenges for experiment code integration
 - Cannot be identical with Geant4 code (different types)
 - Working directly with experiments to understand realistic cases



Experiment integrations

AdePT is not a framework/library at this stage

- Compiling the specific experiment integration will compile AdePT
- This makes easier to fit on specific user scoring requirements
- Interacting with experiments in different phases
 - Understand how AdePT works: modifying advanced examples and adding a custom detector module
 - Understanding which detectors/workflows may benefit from such GPU integration
 - "Biting the bullet" and actually dealing with the concrete case integration problems
 - AdePT dependencies, experiment framework, specific detector scoring code

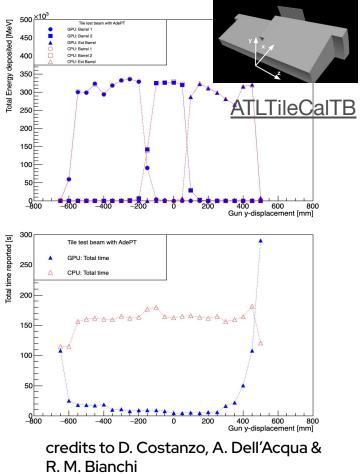
Towards integration with CMSSW

- Targeting Phase 2 setup, in particular CMS HGCal
 - Load geometry setup in AdePT Example14 (exported from CMSSW)
 - Configure HGCalRegion to offload electrons, positrons and gammas
 - Load HepMC3 file with minimum bias events
- Started with integration fo G4HepEm on CPU
 - Library built with CMSSW since November 2022
 - Integrate as option into EMM physics list, only for e- below 100 MeV
- Investigate sensitive detector code on GPUs
 - Right now only accumulated energy deposit
 - Also need to deal with sparsity of HGcal hits (important data volume)
- Prepare prototype for integration with CMSSW
 - How to request GPU resources from multiple threads
 - Ways to extract particles for the GPU, send back results and feed into framework

ATLAS trying out AdePT

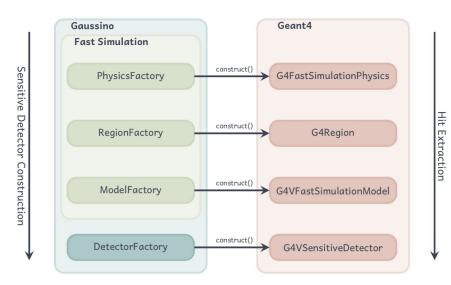
Forked AdePT & modified example14(17)

- Taking a test beam setup geometry GDML
 - Scintillator as active element
- Modifying BasicScoring.cu
 - Adapting to specific Geant4 scoring code
- Scanning with electron gun tilted along Y axis
 - Getting same results + speedup GPU vs. CPU
- Main challenge: adapting G4Step-based scoring
- Take-away & next steps
 - "Ideal environment to build a sensitive detector" (working on GPU)
 - More complex scoring (e.g. Birk's law on device)
 - Code duplication? How to handle?
 - Thinking about integration with *FullSimLight*



Integration as fast simulation algorithm?

- Different versions of LHCb upgrade geometry usable with AdePT advanced examples
 - Ongoing investigation enabling AdePT with the EMCAL, using MCParticles at entrance taken from realistic simulation
- Ongoing discussions about AdePT integration in Gaussino
 - Via AdePT buffer and FastSim hook (requires patching Geant4)
 - Stopping particles entering the ECAL and giving them to Gaussino calling AdePT as fast simulation algorithm



credits to G.Corti & M. Mazurek

Outlook

A challenging project, the problem is far from a perfect match for GPU

- Full EM shower transport functionality implemented and validated
- A first phase of evaluation completed, answering most of the initial R&D questions
- Efficiency blockers identified, triggering a new project on GPU geometry

Prototypes for standalone and Geant4-integrated workflows available

- Realistic examples for LHC setups, GPUs can be used in a Geant4 native application
- Optimization work ongoing, performance not yet on a GPU-efficient baseline
- GPUs appears to be a valid accelerating alternative for particle transport simulation
 - Still to be validated by integration with concrete experiment use cases
 - Discussions and collaboration with experiments ongoing



Kernel Launch Configurations

1024 Threads / SM

- 4 schedulers x 8 warps/scheduler x 32 threads/warp
- 65536 Registers / SM
 - 4 register files x 16384 registers
 - 1 float = 1 register, 1 double = 2 registers
- 96 KB L1 Data Cache / Shared Memory
- Theoretical Occupancy (-maxregcount or __launch_bounds__)
 - 256 regs/thread (256 threads, 8 warps) \Rightarrow 25%
 - 160 regs/thread (320 threads, 10 warps) \Rightarrow 38%
 - 128 regs/thread (512 threads, 16 warps) \Rightarrow 50%
 - 96 regs/thread (640 threads, 20 warps) \Rightarrow 63%
 - 80 regs/thread (768 threads, 24 warps) \Rightarrow 75%
 - 64 regs/thread (1024 threads, 32 warps) ⇒ 100%

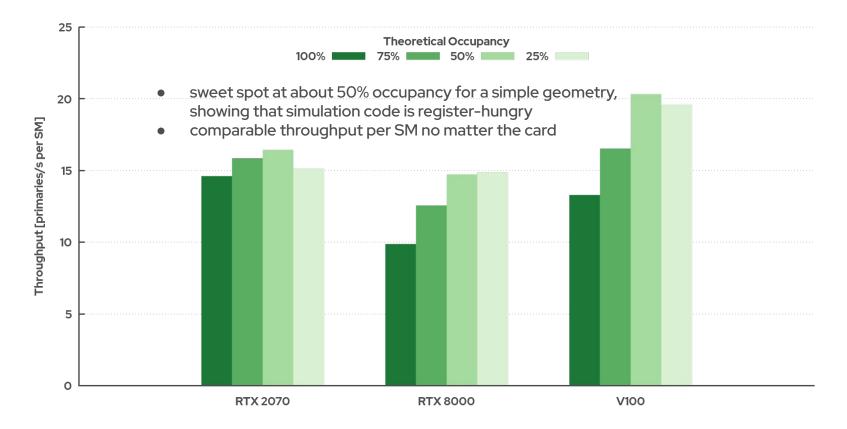




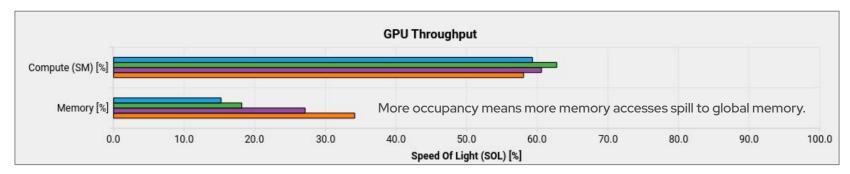
Higher parallelism

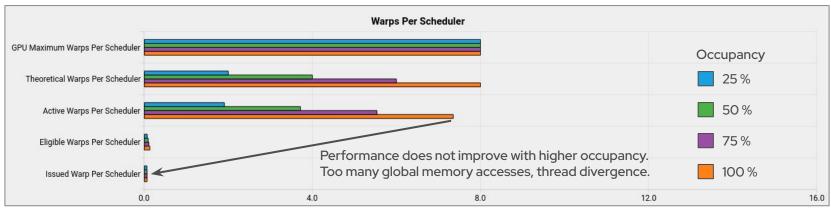
Faster Threads

Relative Performance per SM

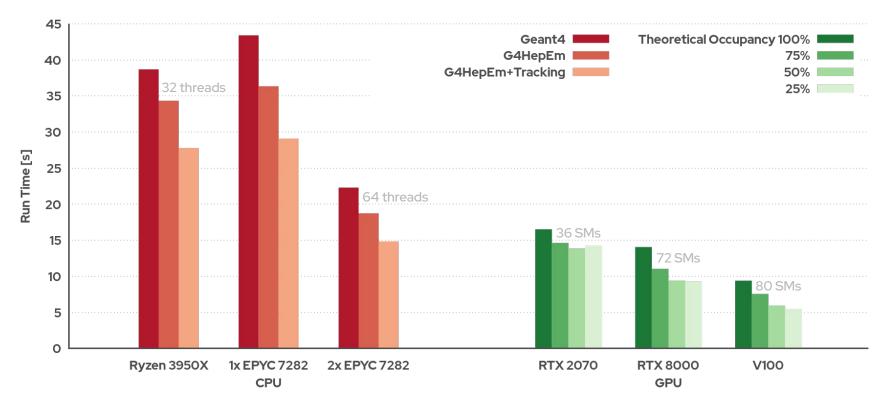


GPU Throughput (RTX 2070)



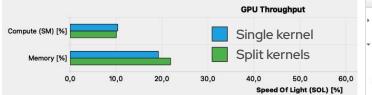


CPU vs GPU Performance



AMD Ryzen 3950X (16 cores, 32 threads, 3.5-4.7GHz), AMD EPYC 7282 (16 cores, 32 threads, 2.8-3.2GHz)

Case Study: Thread Divergence



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V100

Problem: Threads in transport kernels diverge because of diverging interactions \rightarrow 13 / 32 threads active on average

Here: Split off interaction computations from cross-section and geometry kernels (one kernel for pair creation, one for ionisation, ...)

Result: 17 / 32 threads active for physics + geo 29 / 32 threads active for Bremsstr. Run time: $6.4 \text{ s} \rightarrow 5.5 \text{ s}$

Conclusion: Keeping threads coherent is key for detector simulation Generally difficult; stochastic processes

