



National Science Foundation

# Plii

# **On-Device Training Under 256KB Memory**



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Acknowledgment to NSF Grant OAC-2117997

## **MCUNet for TinyML Inference** Addressing memory bottleneck issues



**Cloud Al** 

Memory (Activation)

32GB



Toy applications



MCUNet: Tiny Deep Learning on IoT Devices (Lin et al., 2020)

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## **Mobile Al**

## **Tiny Al**

320kB

4GB



**Real-life applications** 

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## celerated A



# Can We Learn on the Edge?

## All systems need to continually adapt to new data collected from the sensors Not only inference, but also training

- On-device learning: better privacy, lower cost, customization, life-long learning
- Training is more **expensive** than inference, hard to fit edge hardware (limited memory)



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Cloud-based Learning

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# **Training Memory is the Key Bottleneck**

lacksquarecan easily exceed the limit.



TinyTL: Reduce Activations, Not Trainable Parameters for Efficient On-Device Learning [Cai et al., NeurIPS 2020]

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## Edge devices have tight memory constraints. The training memory footprint of neural networks

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# On-Device Training Under 256KB Memory and State of State

devices (e.g., MCU only has 256KB SRAM).



On-Device Training Under 256KB Memory [Lin et al., NeurIPS 2022]

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Training is more expensive than inference due to back-propagation, making it hard to fit IoT





# On-Device Training Under 256KB Memory a

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Training is more expensive than inference due to back-propagation, making it hard to fit IoT





# On-Device Training Under 256KB Memory 23





**1. Sparse layer/tensor** update

2. Quantization-aware scaling

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**3. Tiny Training** Engine



# On-Device Training Under 256KB Memory 23





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**3. Tiny Training** Engine

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## 1. Sparse Layer/Tensor Update **Full update** biases

7x7

weights

Updating the whole model is **too expensive**:

• Need to save all intermediate activation (quite large)

5x5

 $\rightarrow$ 

• Need to store the updated weights in SRAM (Flash is read-only)

MB3 5x5









Model: ProxylessNAS-Mobile

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# 1. Sparse Layer/Tensor Update Sparse Layer/Tensor Update



Updating the sparse tensors/layers

- Some layers are more important than others
- No need to backpropagate to the early layers
- Only need to store a subset of the activations



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an others arly layers

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### Accelerated Al Algorithms for Data-Driven Discovery

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Some layers are more helpful than others

- Fine-tune each layer on a downstream dataset to measure accuracy improvement
- Generalize well to other datasets



- Later layers are more important
- The first point-wise conv in each block contributes more

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- Attention and first FFN layers contribute more

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# 1. Sparse Layer/Tensor Update

**Our method finds better trade-off** 



Sparse update can achieve higher transfer learning accuracy using 4.5-7.5x smaller extra memory.

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**1. Sparse layer/tensor** update

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**3. Tiny Training** Engine





# 2. Address Optimization Difficulty of Quantized Graphs 33 **Quantized Training: lower memory and latency**

Full-precision training (32-bit)

2.09	<i>-0.9</i> 8	1.48	0.09
0.05	-0.14	-1.08	2.12
-0.91	1.92	0	-1.03
1.87	0	1.53	1.49

### Quantized training (2-bit)

1	-2	0	-1
-1	-1	-2	1
-2	1	-1	-2
1	-1	0	0

## More efficient, but **difficult** to update



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# 2. Address Optimization Difficulty of Quantized Graphs 33 But optimization is hard to quantization



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- Making training difficult:
- Mixed precisions: int8/int32/fp32...
- Lack BatchNorm

Performance Comparison (average on 10 datasets)



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- Why is the training convergence worse? - The scale of weight and gradients does not match in *real* quantized training!



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Tensor Index

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# 2. QAS: Quantization-Aware Scaling

## QAS addresses the optimization difficulty of quantized graphs

$$\tilde{\mathbf{G}}_{\bar{\mathbf{W}}} = \mathbf{G}_{\bar{\mathbf{W}}} \cdot s_{\mathbf{W}}^{-2}, \quad \tilde{\mathbf{G}}_{\bar{\mathbf{b}}} = \mathbf{G}_{\bar{\mathbf{b}}} \cdot s_{\mathbf{W}}^{-2} \cdot s_{\mathbf{x}}^{-2} = \mathbf{G}_{\bar{\mathbf{b}}} \cdot s^{-2}$$



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## **Tensor Index**

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# On-Device Training Under 256KB Memory 23





**1. Sparse layer/tensor** update

2. Quantization-aware scaling

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**3. Tiny Training** Engine





# **3. Tiny Training Engine (TTE)**

## **Existing frameworks cannot fit**

- **Runtime** is heavy  $\bullet$ 
  - Heavy dependencies and large binary size (>100MB static memory)
  - Auto-diff at runtime; low edge efficiency
- **Memory** is heavy  $\bullet$ 
  - A lot of intermediate (and unused) buffers
  - Has to compute full gradients







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# **3. Tiny Training Engine (TTE)**





**Tiny Training Engine** (ours) **separate** the environment of runtime and compile time.

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Conventional training framework performs most tasks at runtime.

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# **3. Tiny Training Engine (TTE)** Smaller memory usage, faster training speed



## **20x** smaller memory

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(c) Training latency *vs.* models

**23x** faster speed

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## **3. Tiny Training Engine (TTE)** Scalable to diverse edge hardware platforms

Forward





The measured timed includes the complete forward + backward.

The benchmark model is MobilenetV2-035 with input resolution 128x128.

Our engine supports various platforms and our sparse update shows consistent speedup 1.4 to 3.0x.

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Dense Update Sparse Update (ours) Jetson Nano GPU

Backward

Dense Update Sparse Update (ours) Raspberry Pi 4B+ CPU



80.0





. . . . . . . . . . . . . . . .

3.0x

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## Coverage **Media Report**

## **MIT News**

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### System brings deep learning to "internet of things" devices

Advance could enable artificial intelligence on household appliances while enhancing data security and energy efficiency.

Watch Video

Daniel Ackerman | MIT News Office November 13, 2020

✓ PRESS INQUIRIES



MIT researchers have developed a system, called MCUNet, that brings machine learning to microcontrollers. The advance could enhance the function and security of devices connected to the Internet of Things

### **MIT News** ON CAMPUS AND AROUND THE WOR



## (Homepage highlight)

MCUNet: Tiny Deep Learning on IoT Devices [Lin et al., NeurIPS 2020] MCUNetV2: Memory-Efficient Patch-based Inference for Tiny Deep Learning [Lin et al., NeurIPS 2021] On-Device Training Under 256KB Memory [Lin et al., NeurIPS 2022]

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## **MIT News**

### Learning on the edge

A new technique enables AI models to continually learn from new data on intelligent edge devices like smartphones and sensors, reducing energy costs and privacy risks.

Adam Zewe | MIT News Office October 4, 2022



✓ SEARCH NEWS ✓ PRESS INQUIRIES A machine-learning model on an intelligent edge device allows it to adapt to new data and make better predictions. For instance, training a model on a smart keyboard could enable the keyboard to continually learn from the user's writing. Image: Digital collage by Jose-Luis Olivares, MIT, using stock images and images derived from MidJournev Al. < >

## (Homepage highlight)

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https://forms.gle/UW1uUmnfk1k6UJPPA

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onfigs	prepare open source		2 days ago	Releases
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### **On-Device Training Under 256KB Memory**

### Packages

No packages published







# Thank you!

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### Accelerated Al Algorithms for Data-Driven scovery



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### Accelerated Al Algorithms for Data-Driven iscovery



# 1. Sparse Layer/Tensor Update

## **Updated synapses are sparse**







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# 1. Sparse Layer/Tensor Update Last layer update



Updating only the last layer is cheap

- No need to backpropagate to previous layers
- But the accuracy is low and not ideal.



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Model: ProxylessNAS-Mobile

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# 1. Sparse Layer/Tensor Update

## **Bias-only + last layer update**



Updating the only the bias part

- No need to store the activations
- Back propagating to the first layer.



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Model: ProxylessNAS-Mobile

 $d\mathbf{W} = f(\mathbf{X}, d\mathbf{Y})$  $d\mathbf{b} = f(d\mathbf{Y})$ 



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# **Update Paradigms Comparison**



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# Find Layers to Update by Contribution Analysis 3-3 Finding layers to update with by optimization



(a) Investigate the contribution of last k biases  $\Delta \operatorname{acc}_{b_{[k]}}$ 

For bias update

\* Accuracy goes higher as more layers are updated, but plateaus soon.

$$k^*, \mathbf{i}^*, \mathbf{r}^* = \max_{k, \mathbf{i}, \mathbf{r}} (\Delta \operatorname{acc}_{\mathbf{b}[:k]} + \sum_{i \in \mathbf{i}, r \in \mathbf{r}} \Delta$$

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(b) Investigate the contribution of a certain weight  $\Delta acc_{W_{i,r}}$ 

For weight update

- later layers are more important
- The first point-wise conv contributes more

 $\Delta \operatorname{acc}_{\mathbf{W}i,r})$  s.t.  $\operatorname{Memory}(k, \mathbf{i}, \mathbf{r}) \leq \operatorname{constraint},$ 



# **Case study: MobileNetV2 update scheme**



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# 1. Sparse Layer/Tensor Update **Full update is too expensive**



Updating the whole model is **too expensive**:

- Need to save all intermediate activation (quite large)
- Need to store the updated weights in SRAM (Flash is read-only)

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updated □ fixed 

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# 1. Sparse Layer/Tensor Update **More efficient variants**



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(c) sparse layer update



(d) sparse tensor update

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# 1. Sparse Layer/Tensor Update

**More efficient variants** 



No need to save intermediate activation:  $d\mathbf{W} = f(\mathbf{X}, d\mathbf{Y})$  $d\mathbf{b} = f(d\mathbf{Y})$ 





(d) sparse tensor update

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# 1. Sparse Layer/Tensor Update **More efficient variants**



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(c) sparse layer update



Reduce weight and activation buffer

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# **Real quantized graphs save memory...**



## (a) Fake Quantization (quantization aware training)

Intermediate tensors are still in FP32 format in fake quantization, thus cannot save memory footprint

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(inference/on-device training)

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# 2. QAS: Quantization-Aware Scaling

## QAS addresses the optimization difficulty of quantized graphs

Quantization overview

 $\bar{\mathbf{y}}_{\text{int8}} = \text{cast2int8}[s_{\text{fp}}]$ 

Scaling

$$\mathbf{W} = s_{\mathbf{W}} \cdot (\mathbf{W}/s_{\mathbf{W}}) \stackrel{\text{quantize}}{\approx} s_{\mathbf{W}} \cdot \bar{\mathbf{W}}, \quad \mathbf{G}_{\bar{\mathbf{W}}} \approx s_{\mathbf{W}} \cdot \mathbf{G}_{\mathbf{W}},$$

Weight and gradient ratios are off by  $\|\bar{\mathbf{W}}\|/\|\mathbf{G}_{\bar{\mathbf{W}}}\| \approx \|\mathbf{W}/s_{\mathbf{W}}\|$ 

Thus, re-scale the gradients  

$$\tilde{\mathbf{G}}_{\bar{\mathbf{W}}} = \mathbf{G}_{\bar{\mathbf{W}}} \cdot s_{\mathbf{W}}^{-2}, \quad \tilde{\mathbf{G}}_{\bar{\mathbf{b}}} = \mathbf{G}_{\bar{\mathbf{b}}} \cdot s_{\mathbf{W}}^{-2} \cdot s_{\mathbf{x}}^{-2} = \mathbf{G}_{\bar{\mathbf{b}}} \cdot s^{-2}$$

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$$_{32}\cdot(\mathbf{ar{W}}_{\texttt{int8}}\mathbf{ar{x}}_{\texttt{int8}}+\mathbf{ar{b}}_{\texttt{int32}})],$$

Sw
$$\|/\|s_{\mathbf{W}} \cdot \mathbf{G}_{\mathbf{W}}\| = s_{\mathbf{W}}^{-2} \cdot \|\mathbf{W}\|/\|\mathbf{G}\|.$$

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# **3. Tiny Training Engine (TTE)**



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Conventional training framework performs most tasks at runtime.

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## **3. Tiny Training Engine (TTE) Re-ordering reduces memory footprint**



**Operator life-cycle analysis** shows memory footprint can be greatly reduced by operator re-ordering.

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