

Time-Of-Flight based muography using LGAD sensors

F. Arteché, C. Fleta, D. Flores, J. Galindo, G. Gómez,
S. Hidalgo, M. Iglesias, P. Martínez, F. Matorras,
A. Merlos, A. Molina, A. Pradas, I. Vila

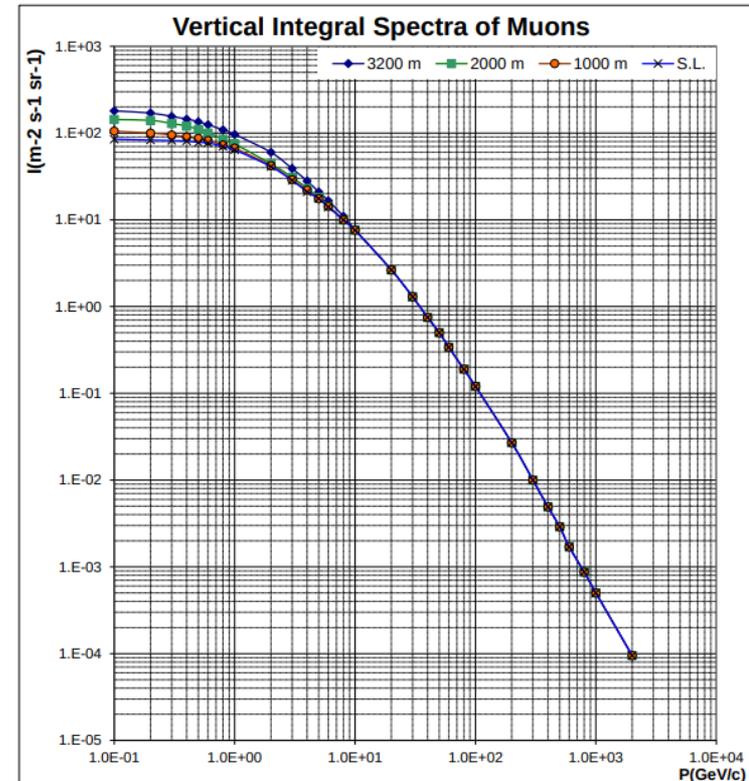
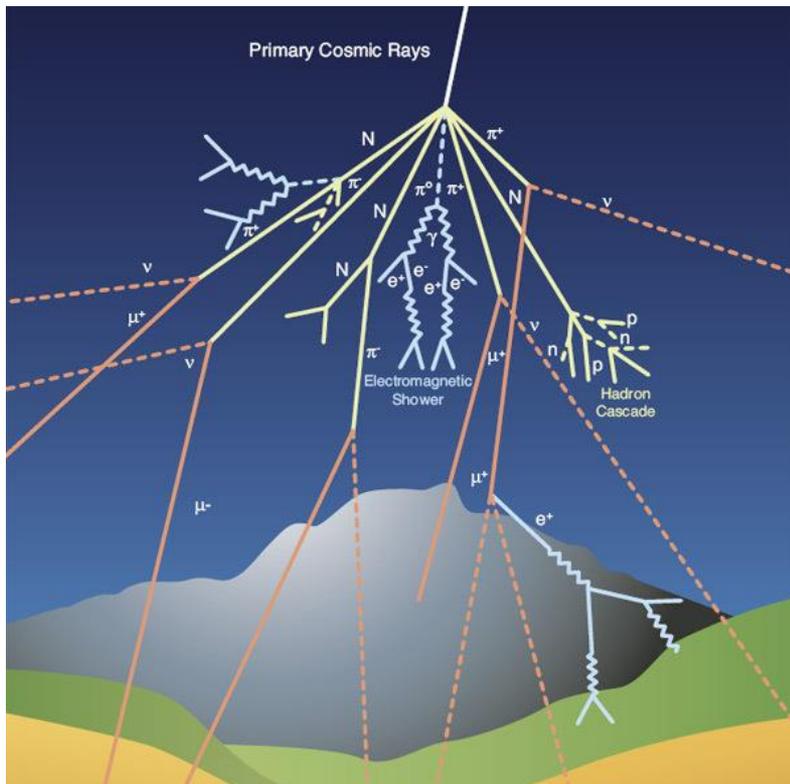
XV CPAN Days

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Cosmic Muons as Radiography source

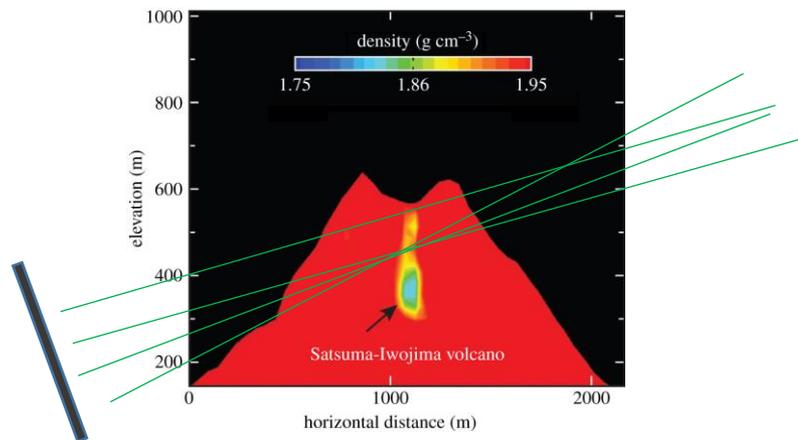
- Cosmic rays hitting the outermost layers of the atmosphere produce muons (pion decays)
- Muon momentum spectrum peaks at low values (~ 1 GeV) falling quickly right after
 - Although cosmic rays and cosmic muons can be surprisingly energetic occasionally
- Angular distribution of muons follows approximately a $\cos^2(\theta)$ with the vertical
- Muon flux is approximately constant and equal to roughly 10000 muons per minute and m^2



- Cosmics muons interact with matter mostly through energy loss and multiple scattering
- When crossing matter -> the denser the matter the more energy loss and angular deviation
- This opens the floor for using cosmic muons as a density testing tool

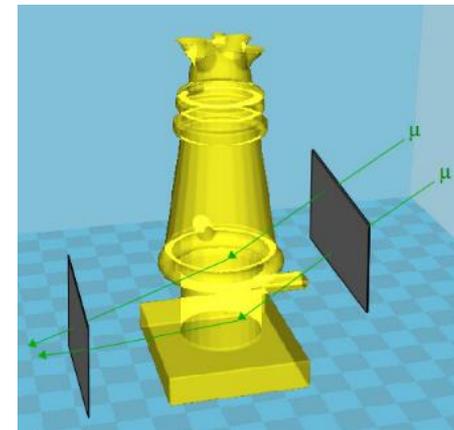
Absorption muon tomography

- Muon flux measured vs direction (attenuation)
- One single detector needed
- Need large object + long exposure times
- Typical applications: geology, volcanology, etc



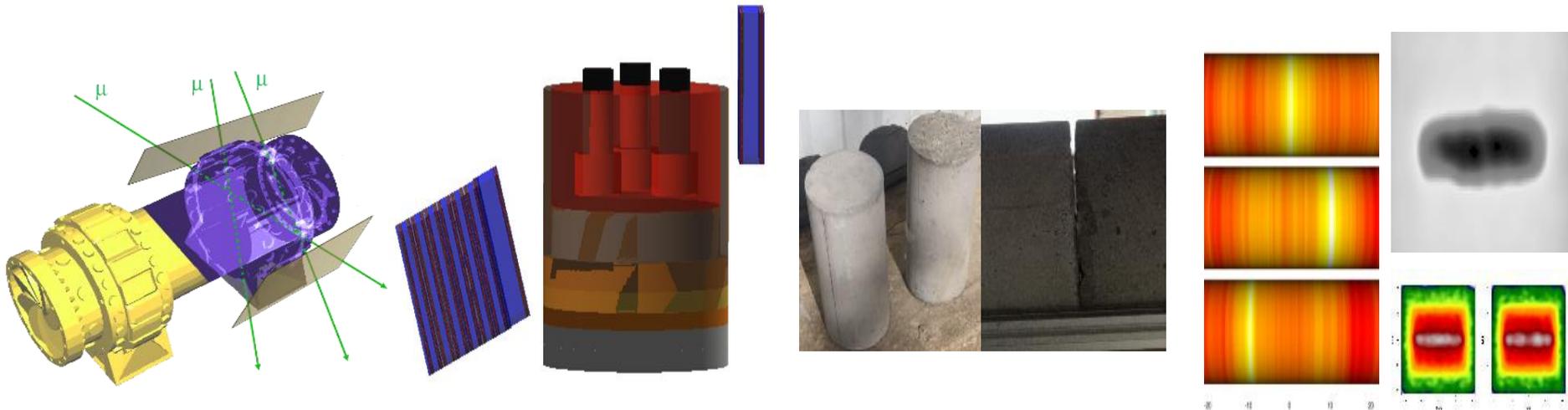
Scattering muon tomography

- Muon angular deviation (scattering)
- Two detectors needed
- Small-medium size objects + short exposure times
- Typical applications: border security, nuclear, etc



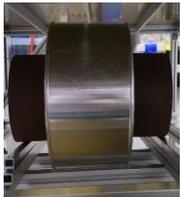
Muon Tomography in the industry

- Idea: use muon tomography as a Non-Destructive Testing (NDT) technique in the industry
 - Preventive maintenance of equipment (estimation of the degradation)
 - Quality control of the production process (measurement of liquid interfaces, tolerances, etc)
 - Risk assessment and evaluation (continuous monitoring of structural integrity)
- Muography has some unique properties that can be very useful for these applications
 - Large power of penetration (no problema to deal with several meters of steel)
 - No need to physically “touch” the object -> can be applied to equipment in production



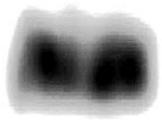
Pipe corrosion

Measure of the wear: 1mm resolution
1 min exposure



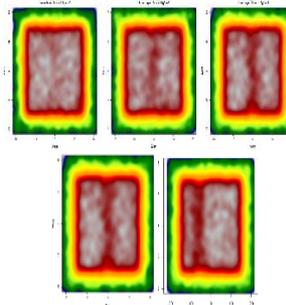
Cracks in concrete

Measure of the crack size:
2mm resolution
10 min exposure time



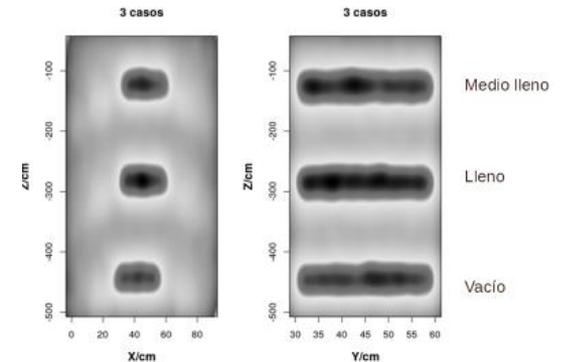
Tailings

0.2g·cm⁻³ density loss detection



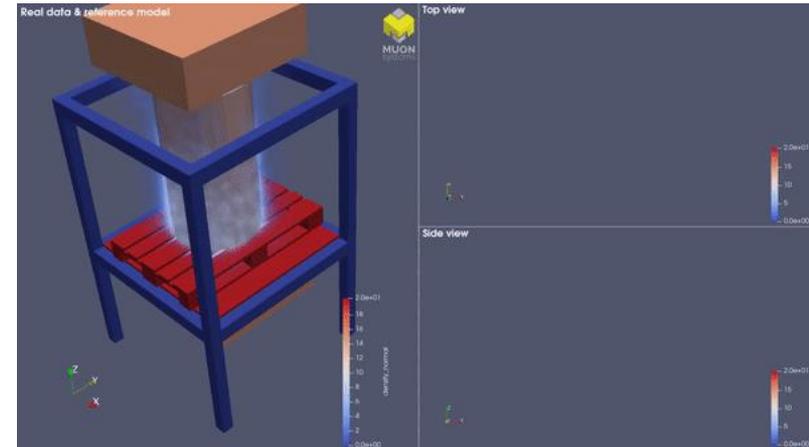
Prestressed concrete

grout level detection



Furnace hearth

Measure of the wall refractory:
1cm resolution
15 min exposure



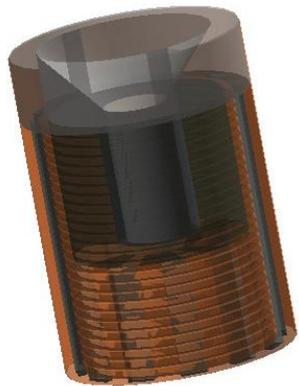
Real data 3D reconstruction of a silicon smelting furnace

The problem of the momentum

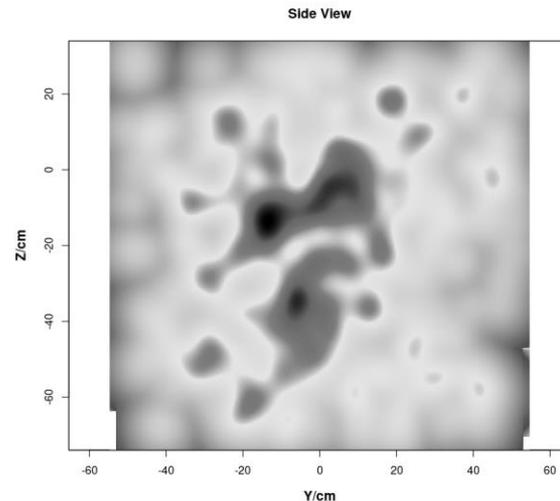
- Muon momentum operates with an intrinsic assumption in the reconstruction algorithms
 - Muon momentum is assumed to be known and equal to the most probable value
- The momentum plays an important role in Molière's scattering formula

$$\theta_0 = \frac{13.6}{\beta c p} z \sqrt{x/X_0} [1 + 0.038 \ln(x/X_0)]$$

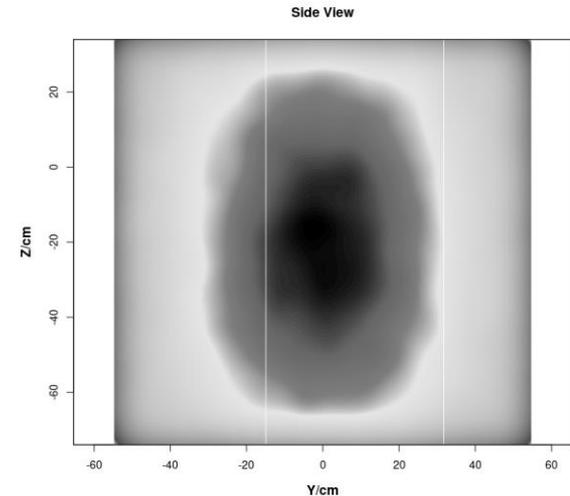
- There's entanglement between the momentum and the material radiation length
 - This produces a degradation of the resolution of the images
- On the other hand, measuring the muon momentum is not an easy task (in a cost-effective manner)



Voltaic Arc furnace



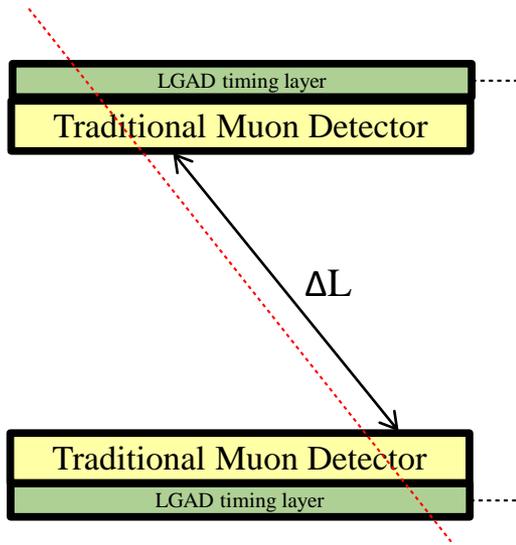
No momentum



10% momentum resolution

Time-Of-Flight momentum measurement

- Muon momentum can be estimated directly through the Time-Of-Flight of the muon
 - Need to estimate the muon time at the upstream and downstream detectors



$$\Delta T = T_2 - T_1 \longrightarrow \beta = \frac{1}{c} \frac{\Delta L}{\Delta T} \longrightarrow p = m_{\text{muon}} \frac{\beta}{\sqrt{1 - \beta^2}}$$

Time resolution $\sim 50\text{ps}$ and $\Delta L \sim 1\text{m}$ \rightarrow momentum resolution $\sim 10\text{-}30\%$ for low momentum muons

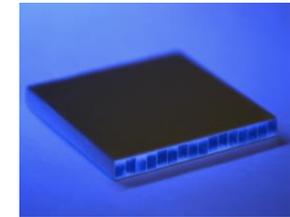
- Two layers of detectors with timing capabilities are needed in order to measure $T_2 - T_1$
- **Low Gain Avalanche Diodes (LGADs) are a perfect match for this task**

LGADs as timing detectors in CMS

- The MIPs Timing Detector (MTD) is part of the Phase-2 upgrade Project in CMS
 - Provide time measurement of charged particles with 30-40 ps resolution
 - Endcap Timing Layer (ETL) using LGAD technology
 - Large involvement from CNM, IFCA and ITAINNOVA

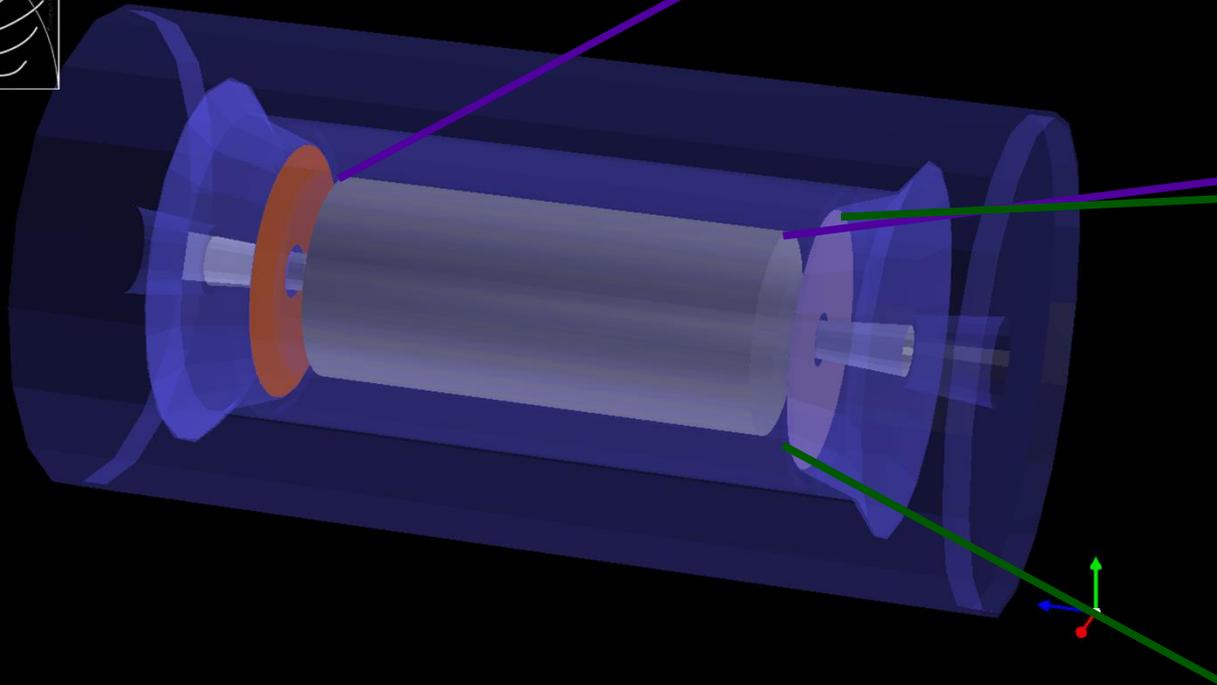
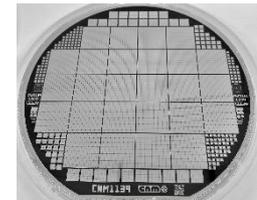
BTL: LYSO bars + SiPM read-out

- TK/ECAL interface ~ 45 mm thick
- $|\eta| < 1.45$ and $p_T > 0.7$ GeV
- Active area ~ 38 m² ; 332k channels
- Fluence at 3 ab⁻¹: 2×10^{14} n_{eq}/cm²



ETL: Si with internal gain (LGAD)

- On the HGC nose ~ 65 mm thick
- $1.6 < |\eta| < 3.0$
- Active area ~ 14 m²; 8.5M channels
- Fluence at 3 ab⁻¹: up to 2×10^{15} n_{eq}/cm²



The 4D-TOMULGAD project

- Target: build a muography demonstrator with Time-Of-Flight momentum measurement capabilities

PDC2021-121718: 2 years project



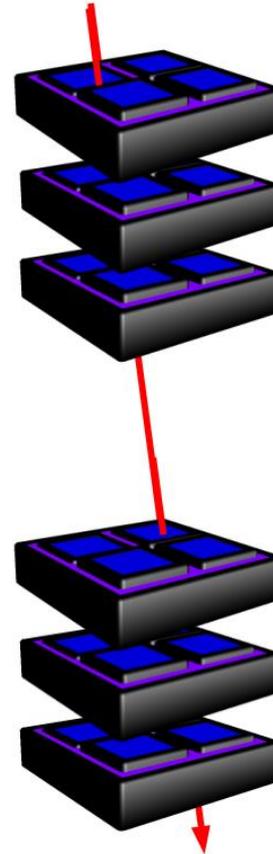
Optimization and fabrication of LGAD sensors



Integration, validation and 4D muon image reconstruction



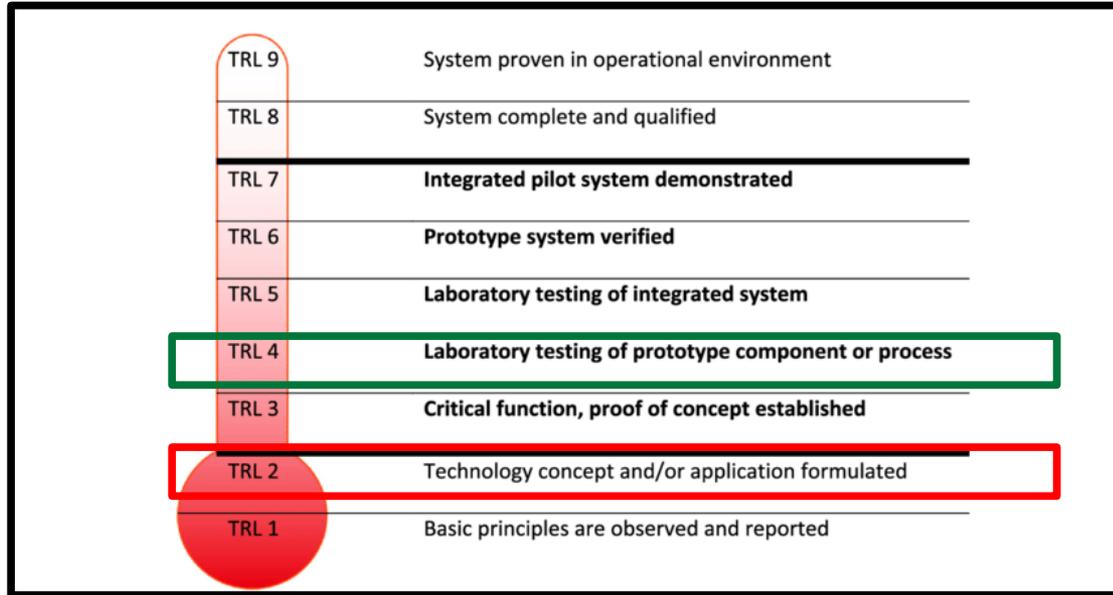
Distributed Clock network and power distribution system



Stakeholders



TOMULGAD goals and status



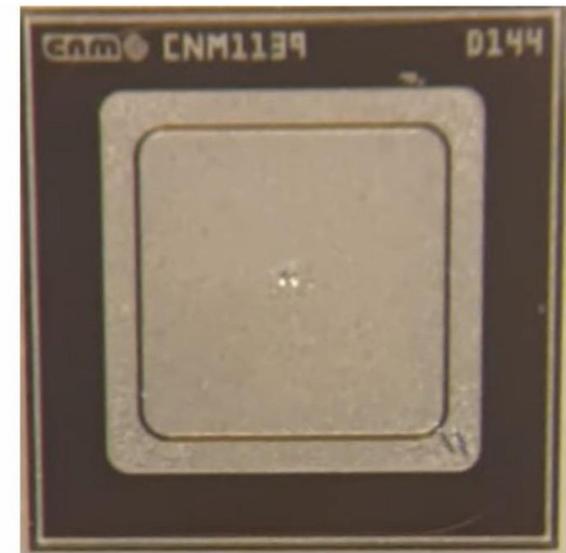
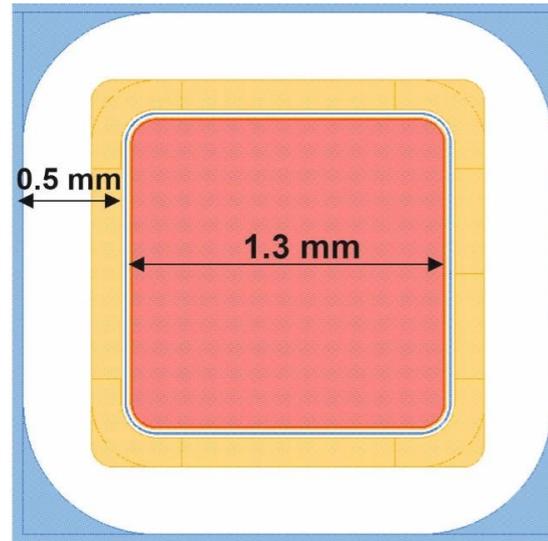
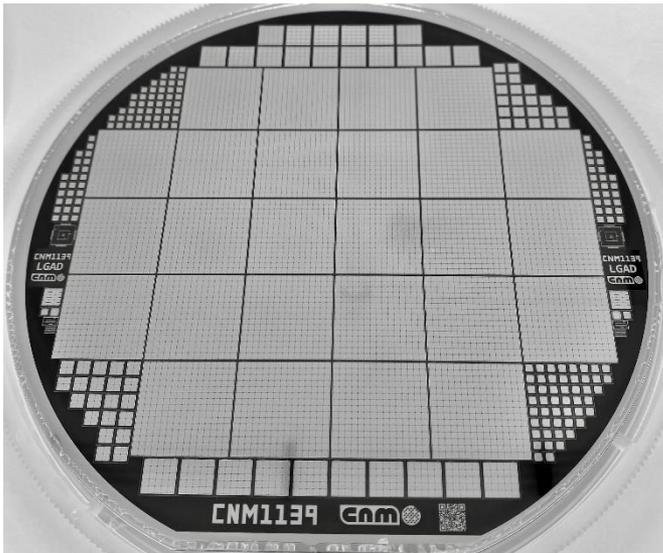
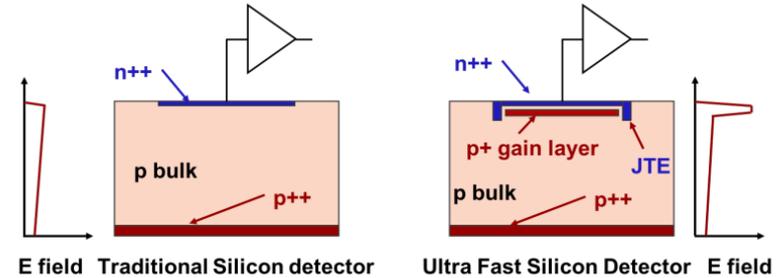
GOAL:
Small-area technological demonstrator and experimental assessment of the feasibility of a large scale muon tomograph

STATUS:

- Manufacturing and characterization LGAD sensors for the technological demonstrator
- Integration of a small-area technological demonstrator with full capabilities
 - Sensors and readout electronics (large delays, first testbeams taking place now)
 - Reconstruction and simulation software
 - Powering and clock distribution system
 - DAQ and final integration (need readout electronics)
- Development of a high-resolution Deep Learning reconstruction algorithm using timing information

Low-Gain Avalanche Diodes at CNM

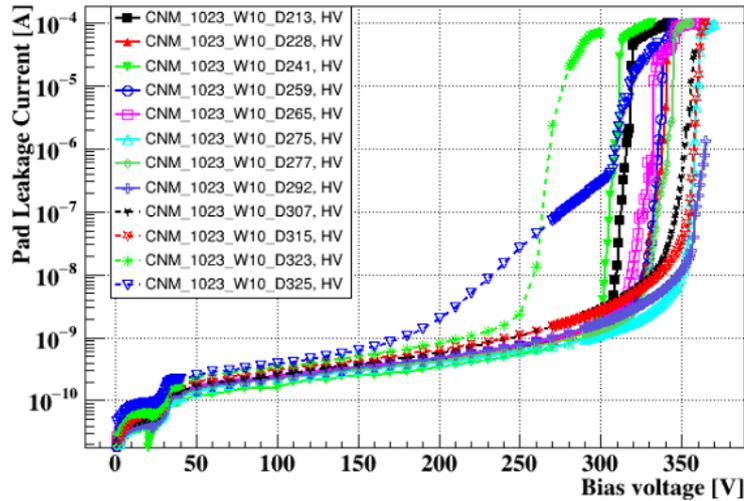
- Traditional silicon detectors with extra multiplication layer and gain in the range $\sim 10 - 20$
- Relatively large sensors $21.2 \times 21.2 \text{ mm}^2$
- Thickness of $300 \mu\text{m}$ ($50 \mu\text{m}$ depletion region)
- Pads of $1.3 \times 1.3 \text{ mm}^2$ in 16×16 matrix fashion
- Excellent timing capabilities of $\sim 50 \text{ ps}$
 - Time resolution mainly dependent on jitter and time-walk
- Readout using dedicated ASIC (ETROC2): versión 2 currently being tested in test beams



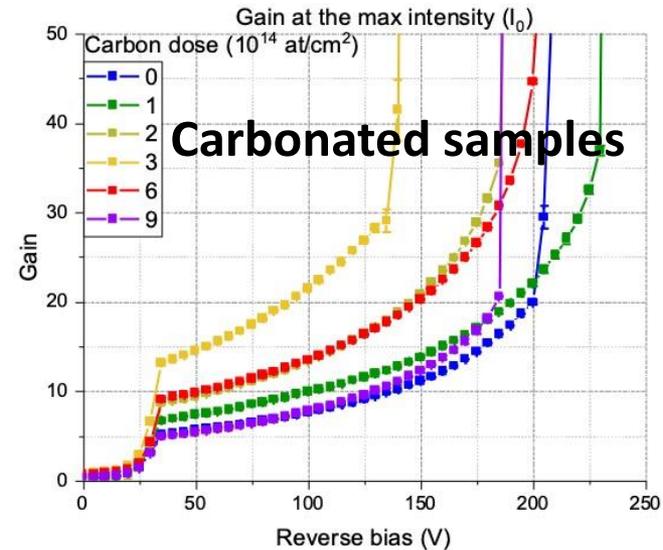
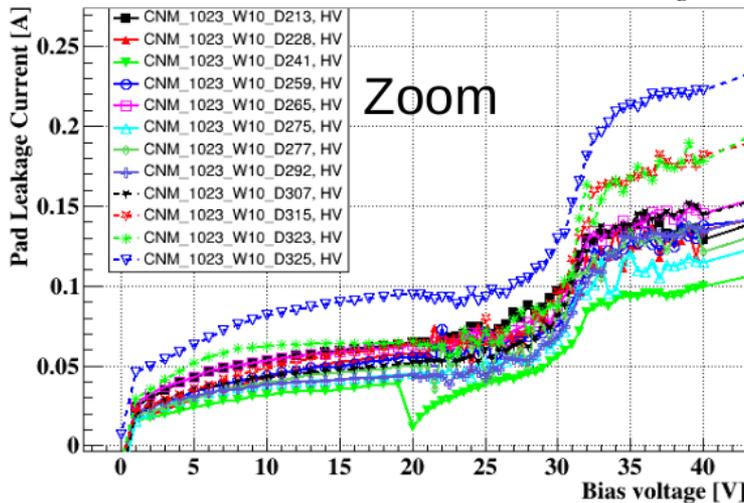
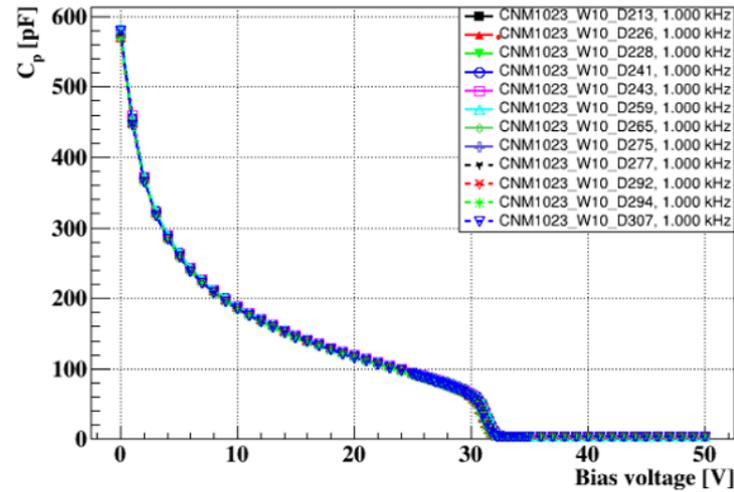
LGAD characterization

- LGAD sensors extensively tested and characterized through different sensor production campaigns

Standard, CNM, RT



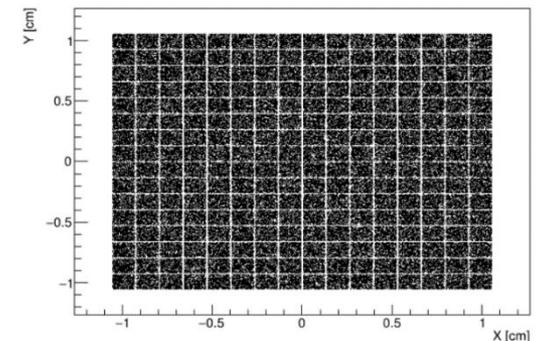
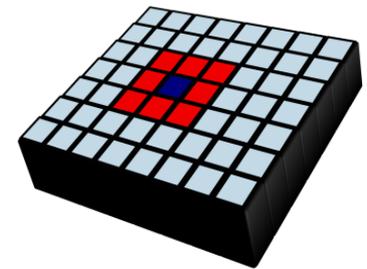
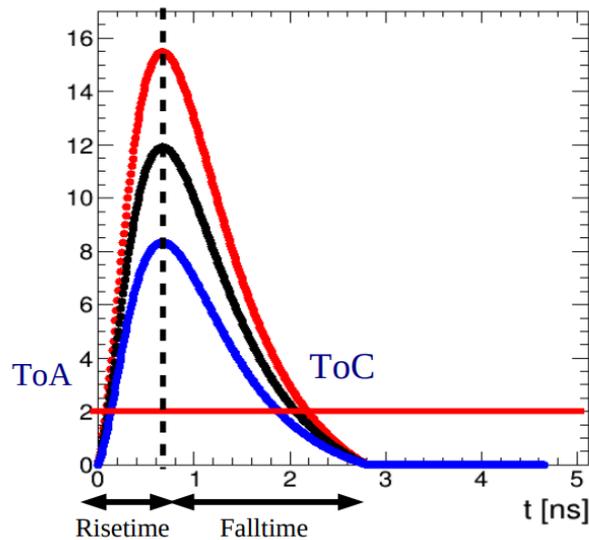
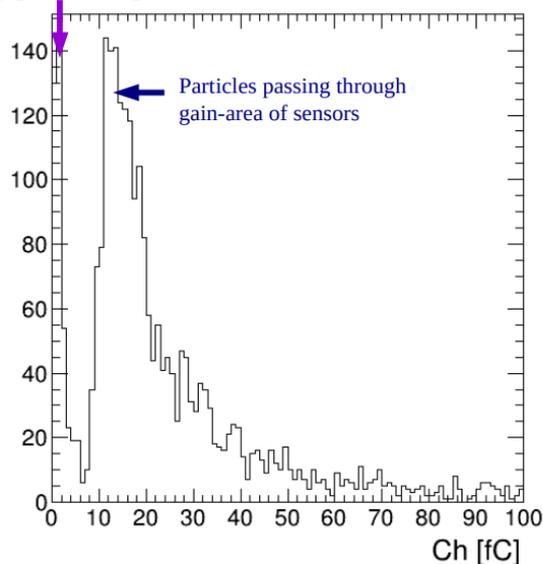
Standard, CNM, RT



Simulation software and reconstruction

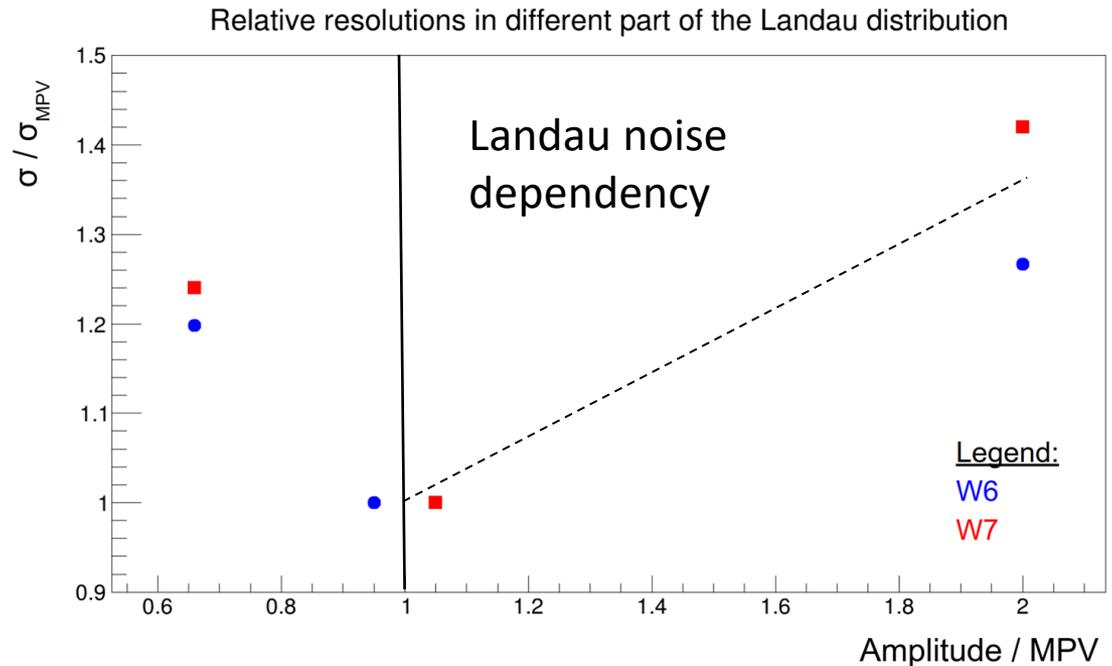
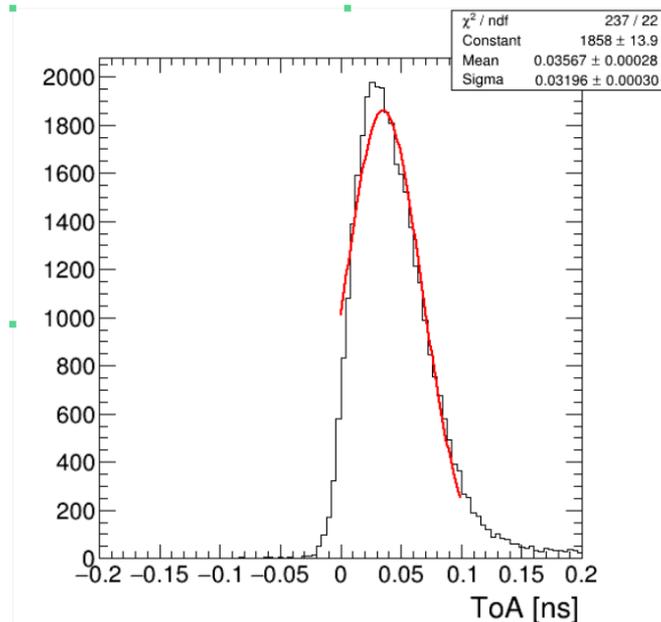
- A full GEANT4 model of the telescope has been made with 4 LGAD sensors per layer
 - Final geometry still under optimization waiting for final performance numbers
- Full simulation setup deployed including detailed digitization model with timing resolution
 - Multipad 16x16 structure of LGADs implemented logically in the digitization
 - Deposited energy from GEANT4 is converted into charge and multiplied by the gain
 - Signal shape scaled by the charge to estimate the Time-Of-Arrival and Time-Over-Threshold
 - Possibility to randomly simulate spurious hits and cross-talk among sensors

Particles passing through gaps between pixels



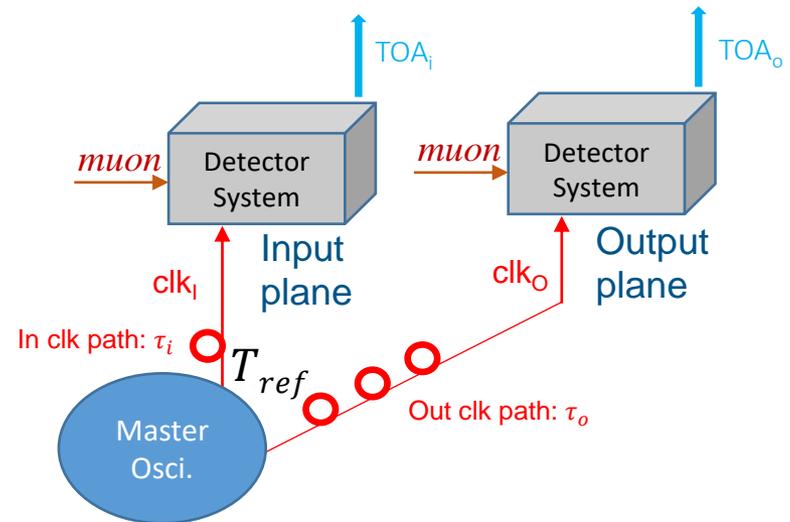
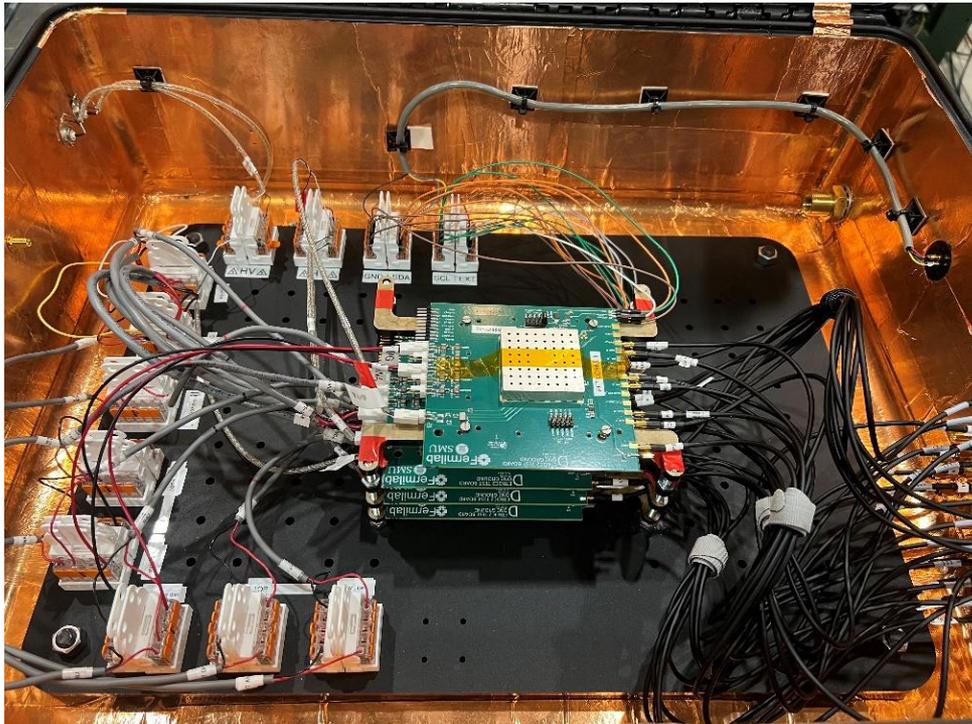
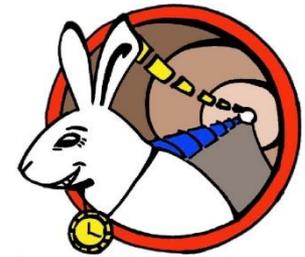
Timing resolution model in digitization

- Time resolution components are modeled in different ways
 - Landau fluctuations on the deposited energy are accounted for automatically
 - The jitter is gain-dependent and simulated as a gaussian smearing
 - The TDC and the distortion are simulated as gaussian smearing with constant sigma
 - Landau noise simulated as a gaussian smearing with sigma dependent on muon energy
- Time-walk corrections implemented right after digitization process



Clock distribution and sync for 4D detectors

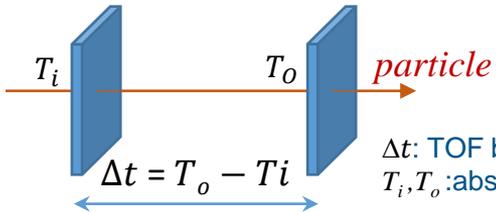
- Need to measure time of arrival of distant 4D detector planes with respect to a clock
- Depending on the application or the setup there might be different clock paths
- Move from dedicated clocking technologies requiring calibration to self-calibrated technologies
- The White Rabbit Project originated for High Accuracy Profile under the IEEE 1588 standard
 - Ethernet-based technology for deterministic distribution of timing data



TOF computation in 4D detectors

We want to compute:

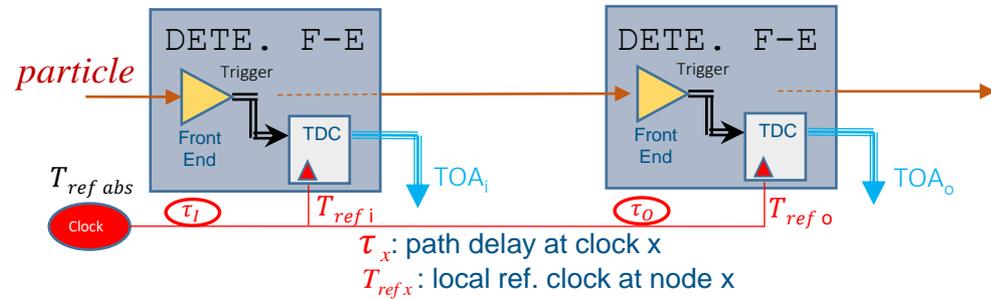
Δt : Time of Flight (TOF)



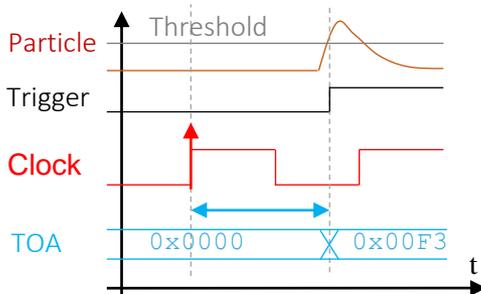
Δt : TOF between detector planes
 T_i, T_o : absolute times

We measure:

2x Time Of Arrival (TOA) w.r.t ref. clock



We use a local reference clock $T_{ref\ x}$

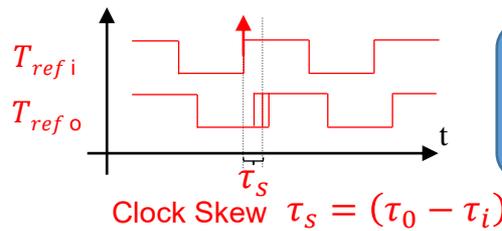


$$T_x = T_{ref\ x} + TOA_x$$

T_{ref} needs to be a common synchronized reference among all nodes

We need clean Clock distribution ensuring accuracy, precision and coping skew

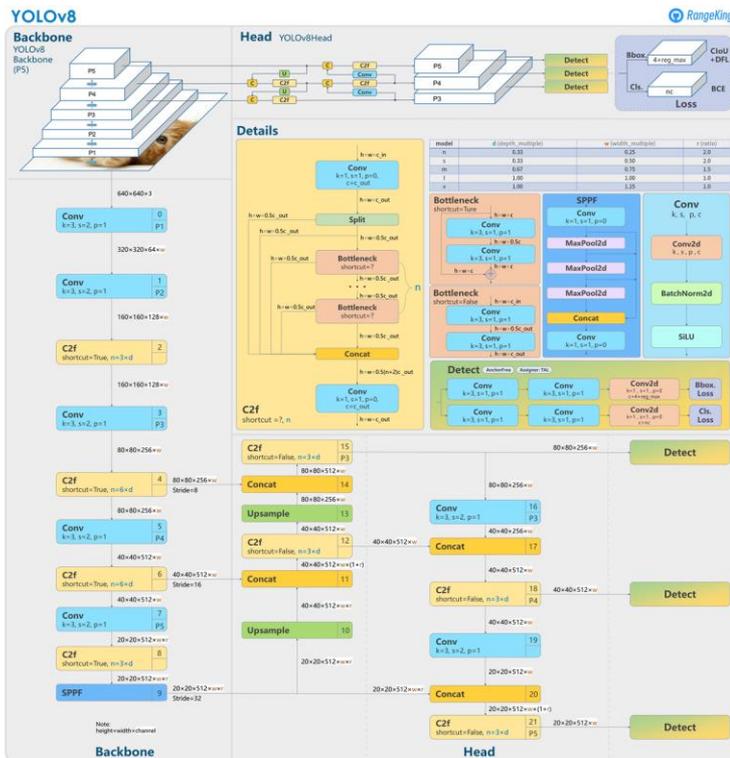
Phase of the Ref clock at Detectors



IEEE 1588 standard – High Accuracy profile???

Muon imaging with 4D capabilities

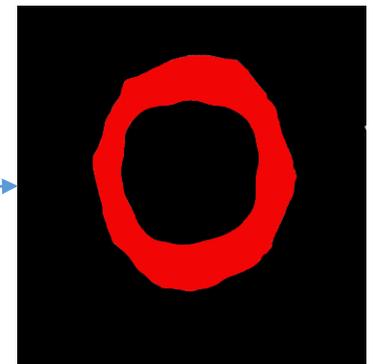
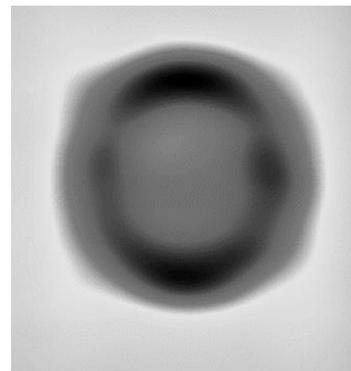
- Classic muography algorithms adapted to consider timing in reconstruction
 - Point-Of-Closest Approach (POCA) algorithm with time modulation
 - Time Maximum-Likelihood Expectation Maximization (MLME) with modern minimization
- Development of automatic Detection + Segmentation based on artificial vision algorithms
 - Training of YOLO v8 with MLME muographic images with timing



Example: transversal view of furnace

POCA with Timing

Furnace Wall mask



Semantic segmentation

Conclusions

- Muon tomography can be applied as an NDT technique of structural integrity in the industry
- The 4D-TOMUGAD Project is addressing the problema of the momentum measurement
 - Surely a game changer for many applications in the context of muon tomography
- The project aims at building a demonstrator (TRL4) but considering also scalability
- The project is now catching up with the readiness of the sensor readout electronics
- A successful outcome could motivate to build a large scale detector