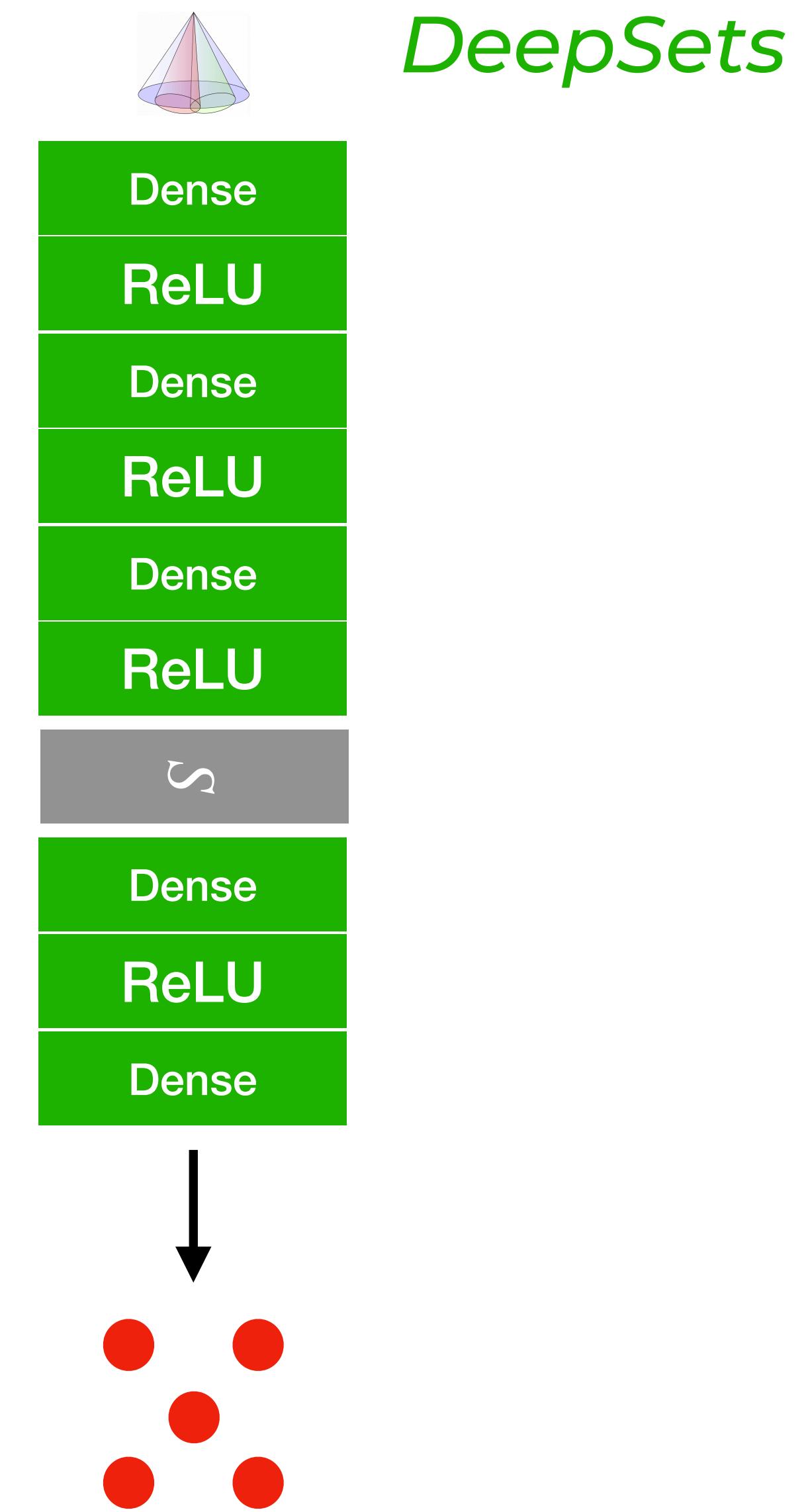
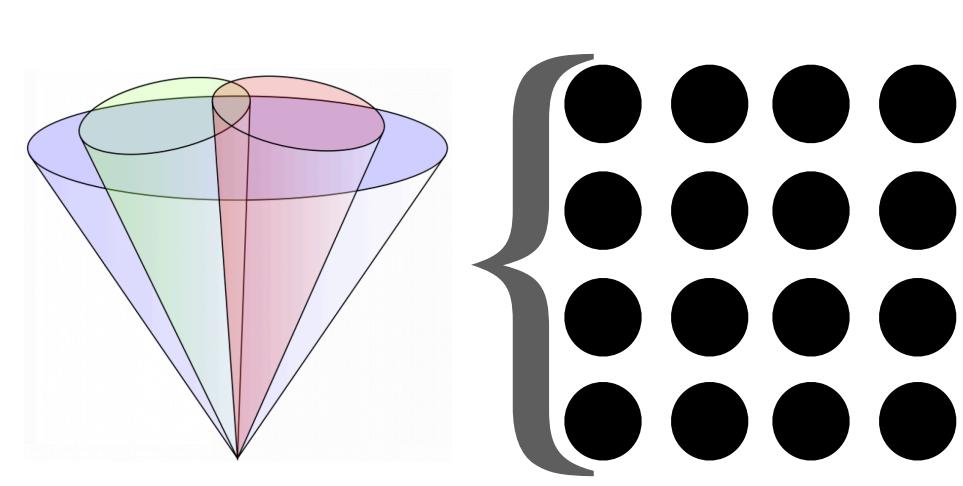
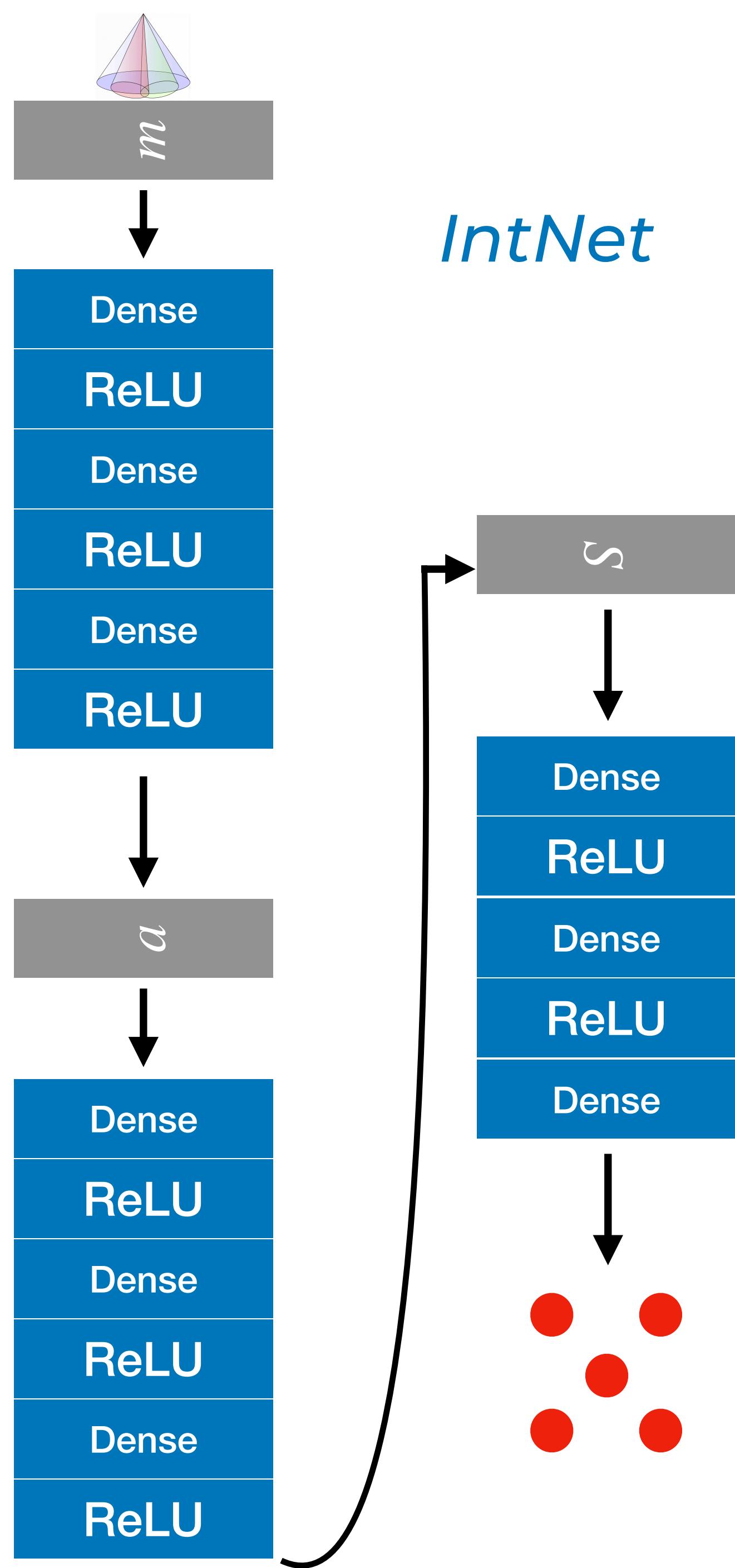
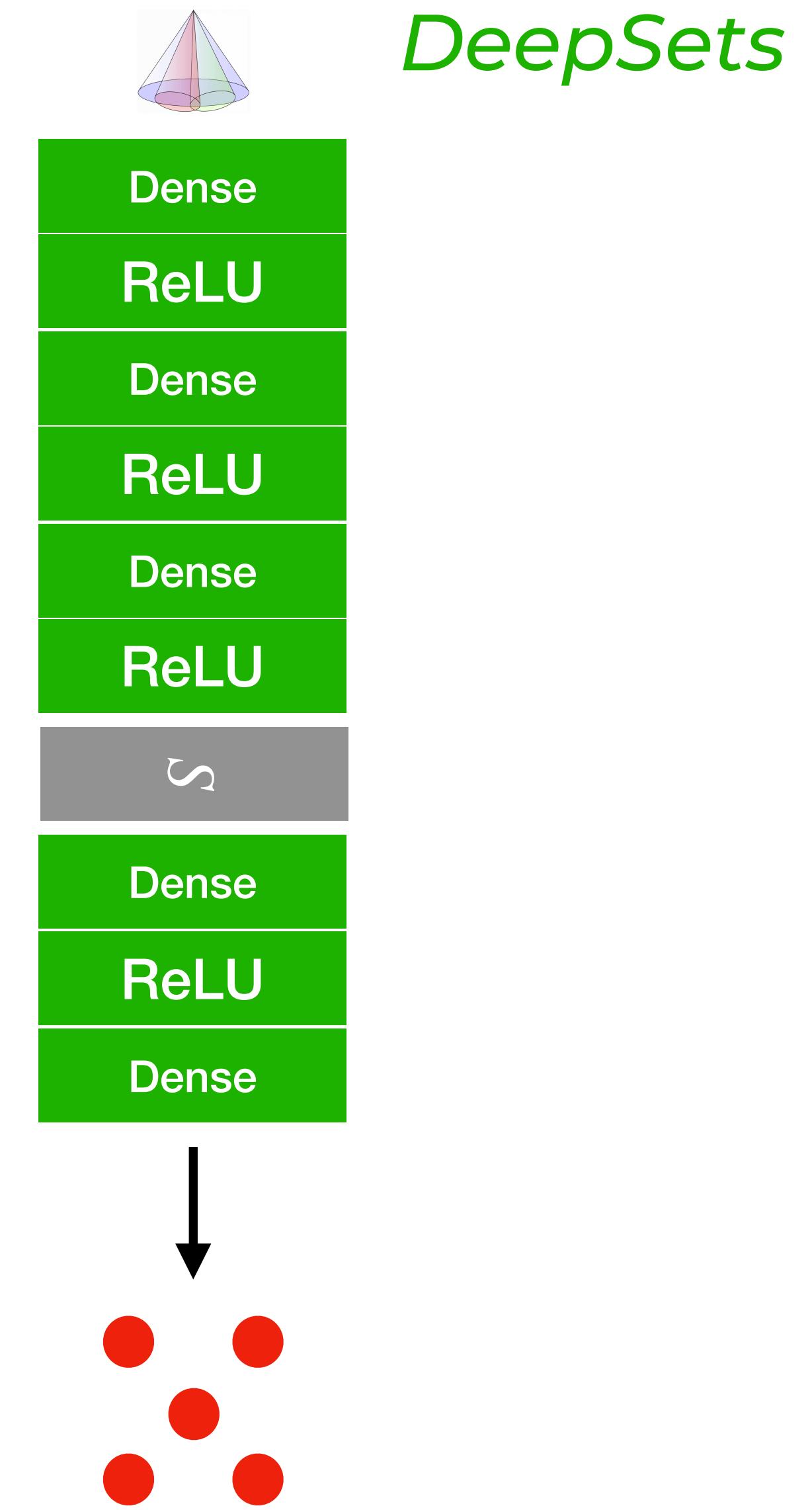
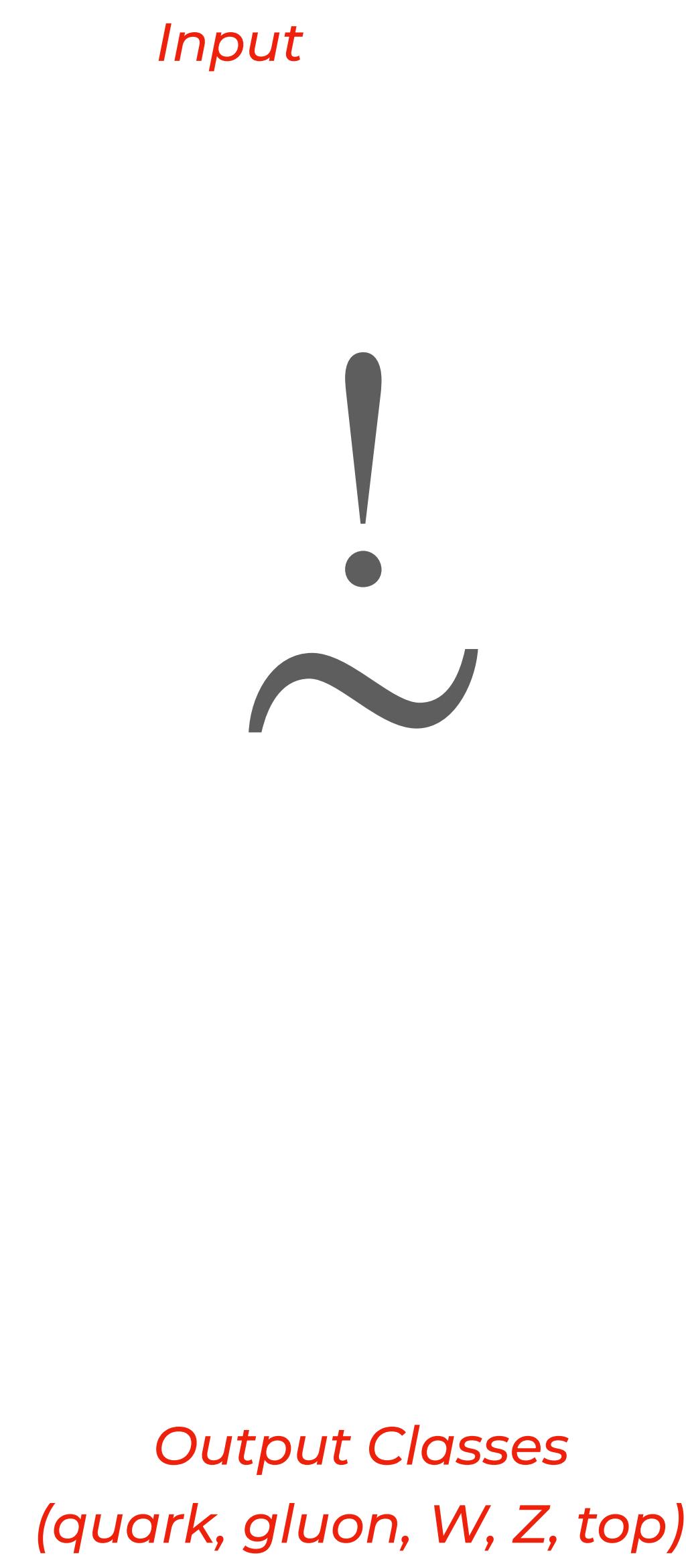
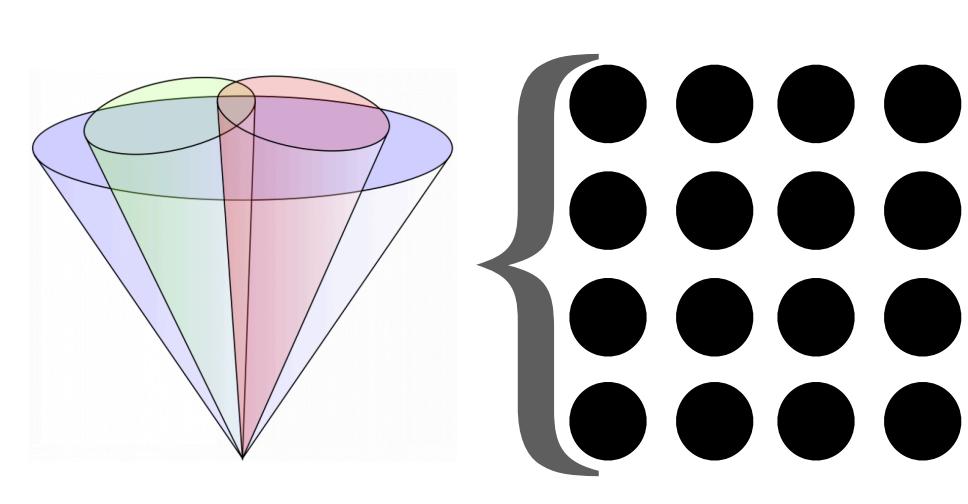
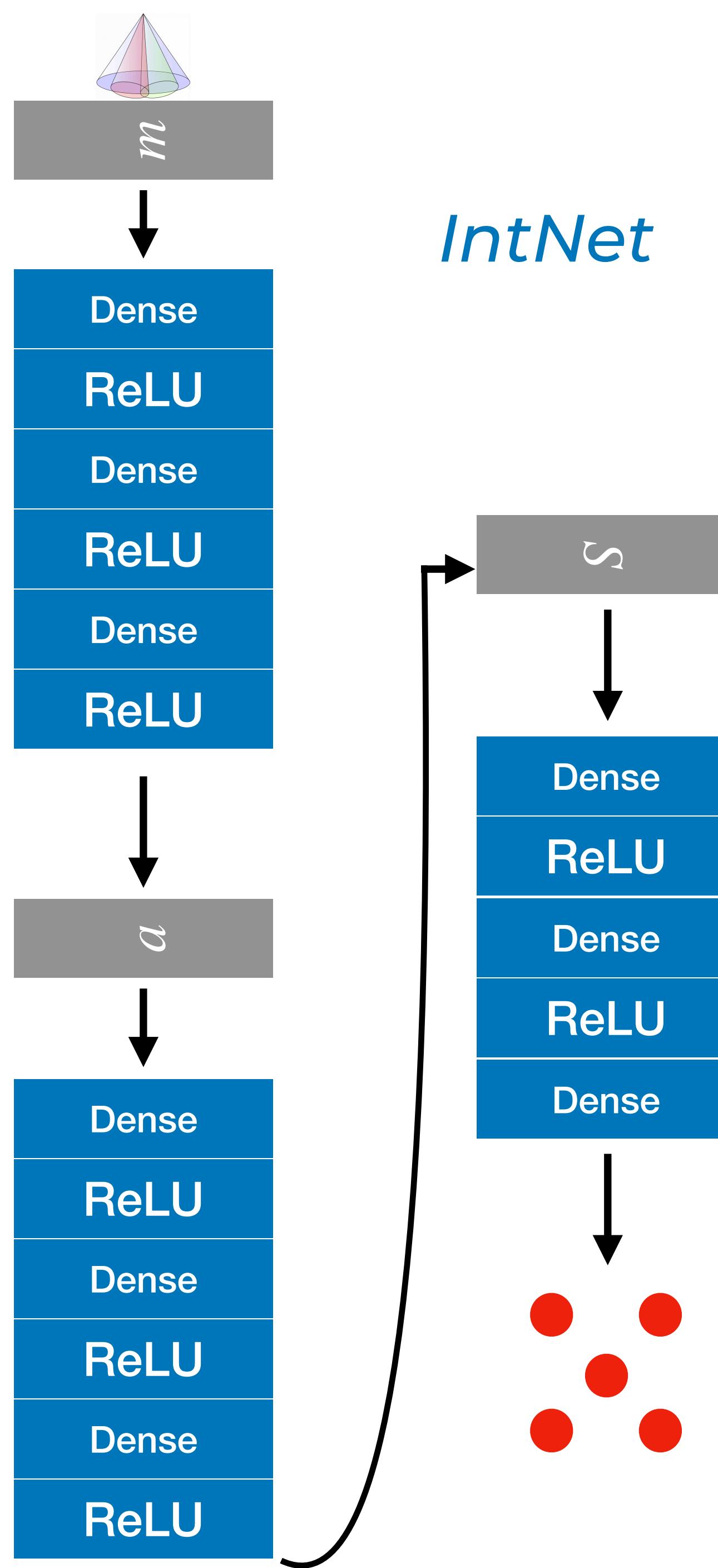


IntNets and DeepSets for Fast Jets

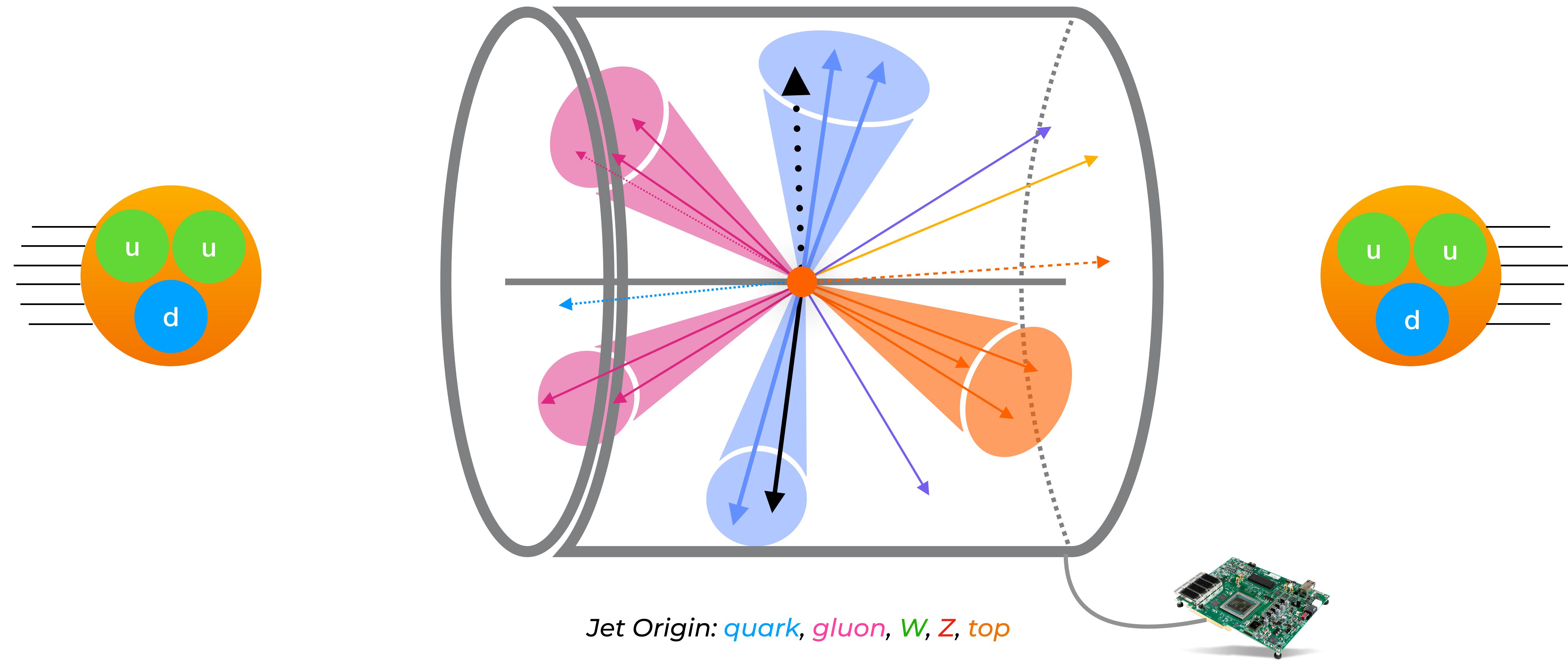
Patrick Odagiu

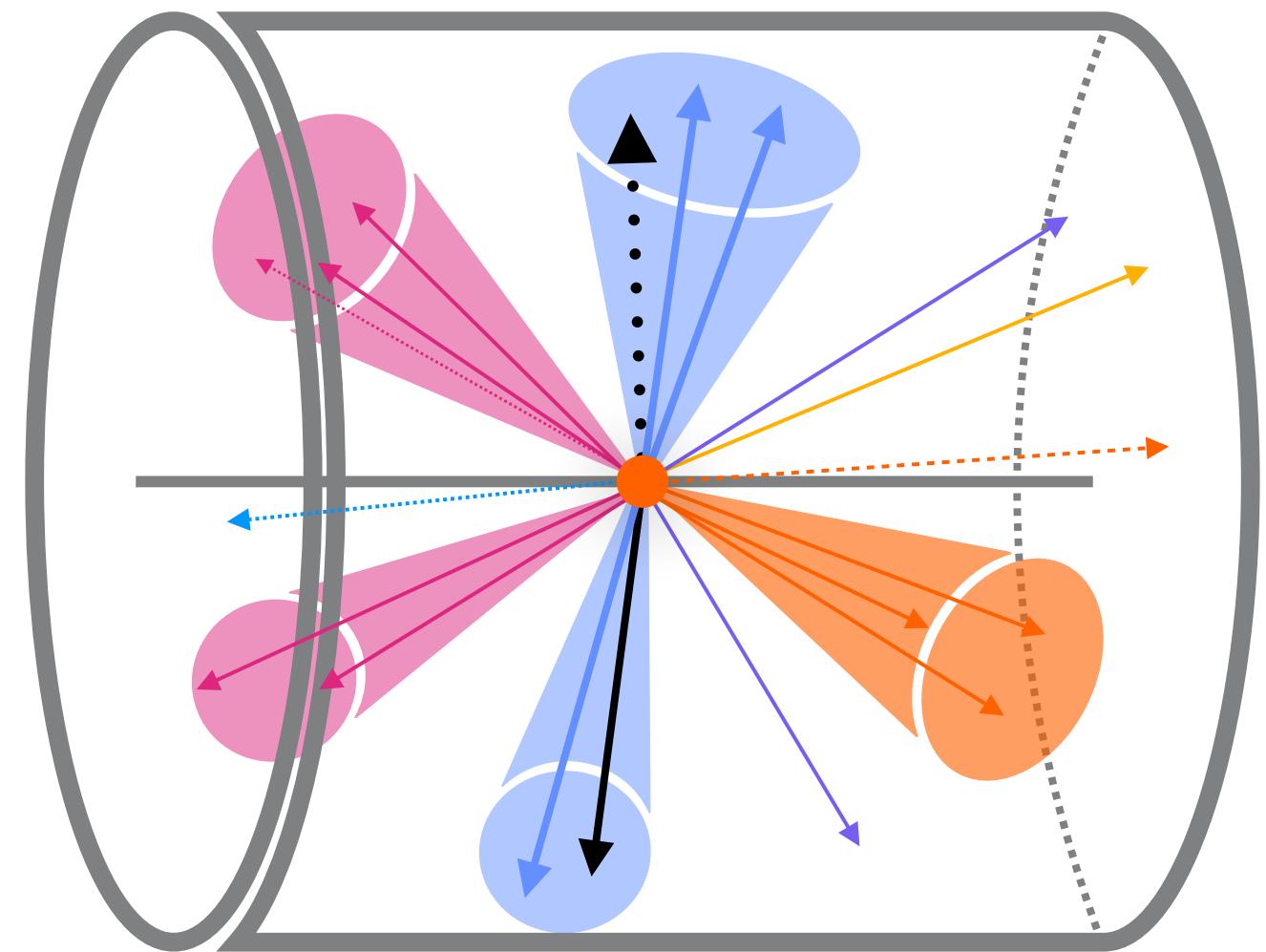
Andre Sznader, Zhiqiang Que, Javier Duarte, Thea Arrestad, Vladimir Loncar, Jennifer Ngadiuba, Philipp Rincke, Johannes Haller, Gregor Kasieczka, Ihor Komarov, Finn Labe, Artur Lobanov, Matthias Schroder, Maurizio Pierini, Arpita Seksaria, Wayne Luk, and Sioni Summers



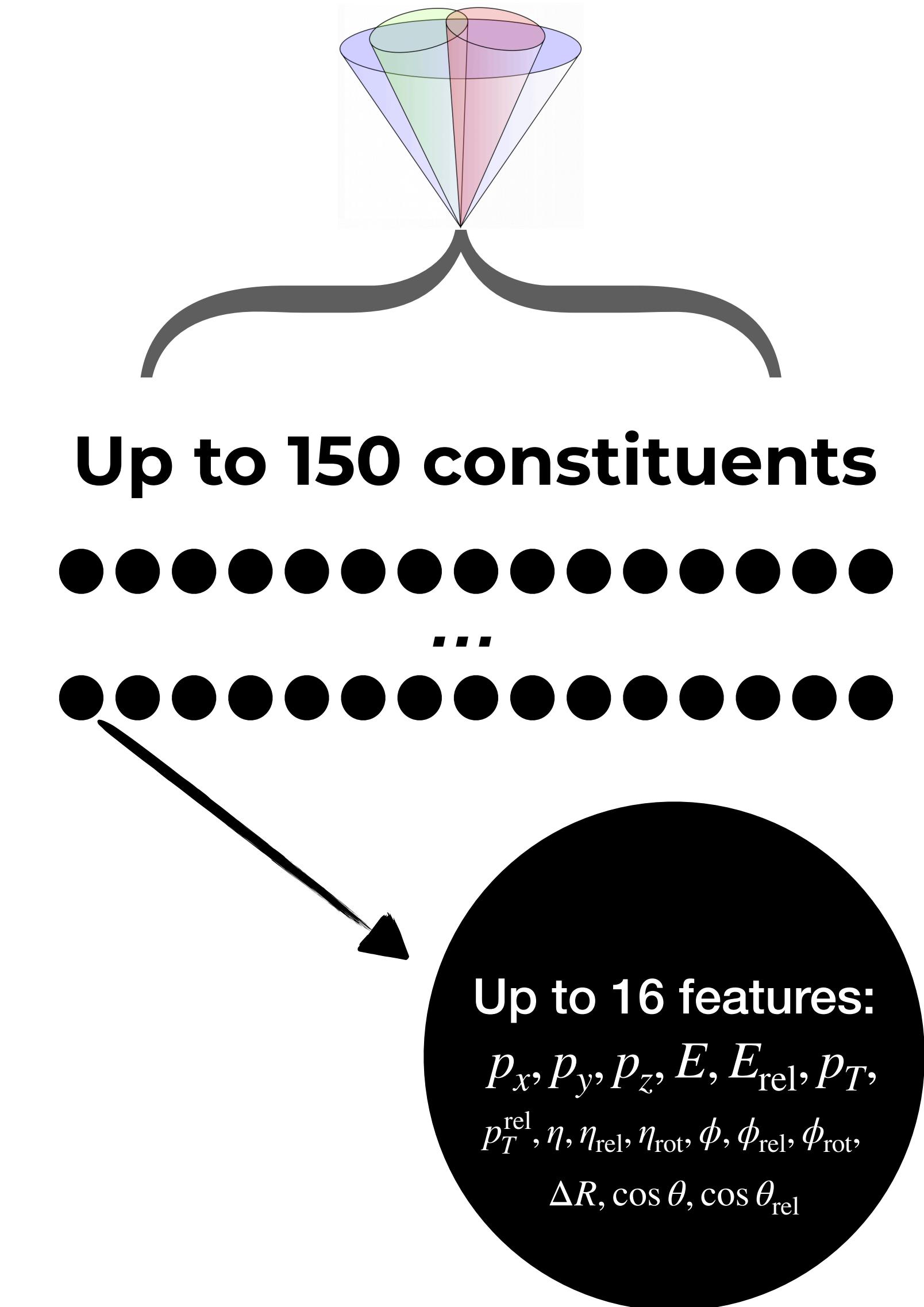


Collision every 25 ns: ~60 Tb/s data influx

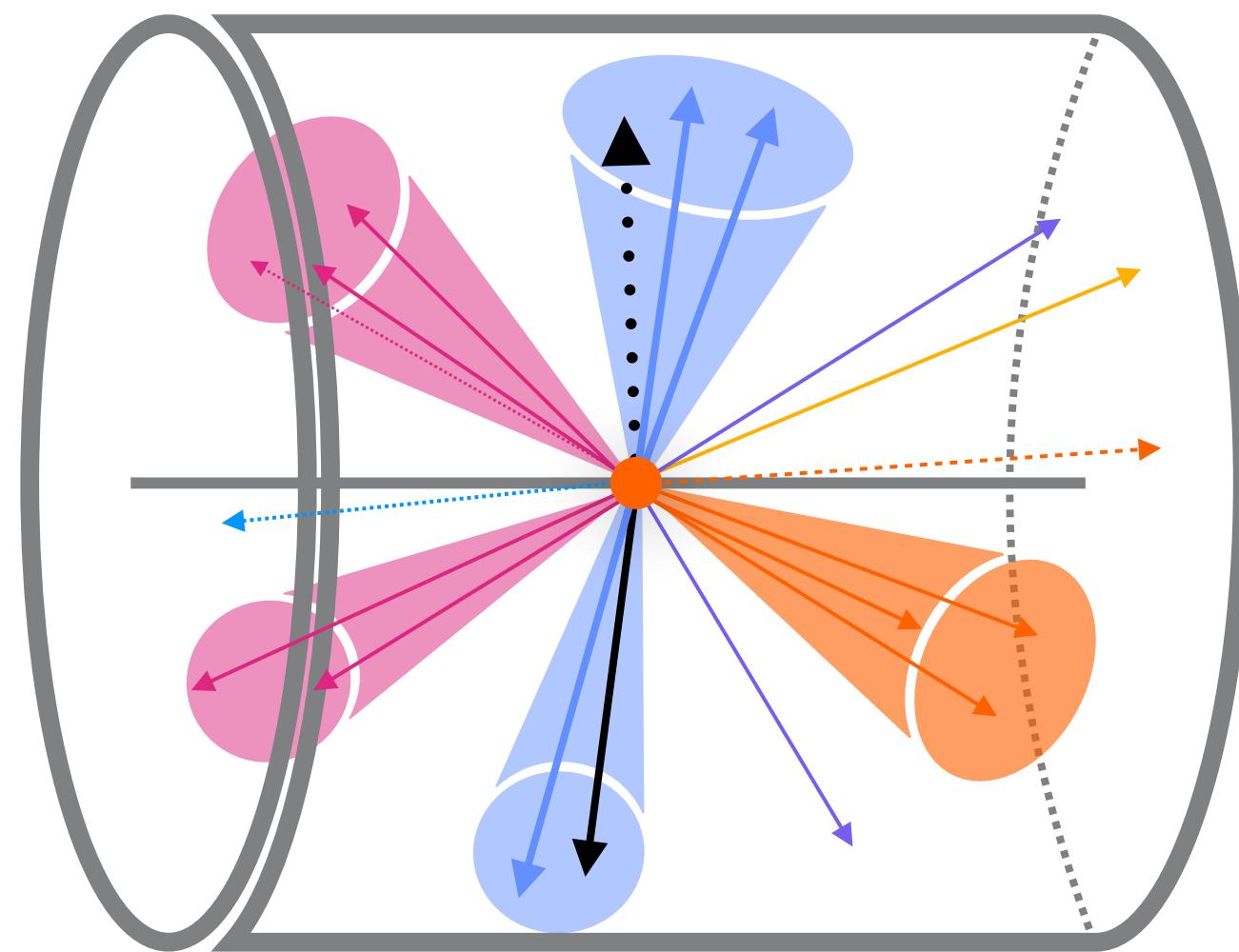




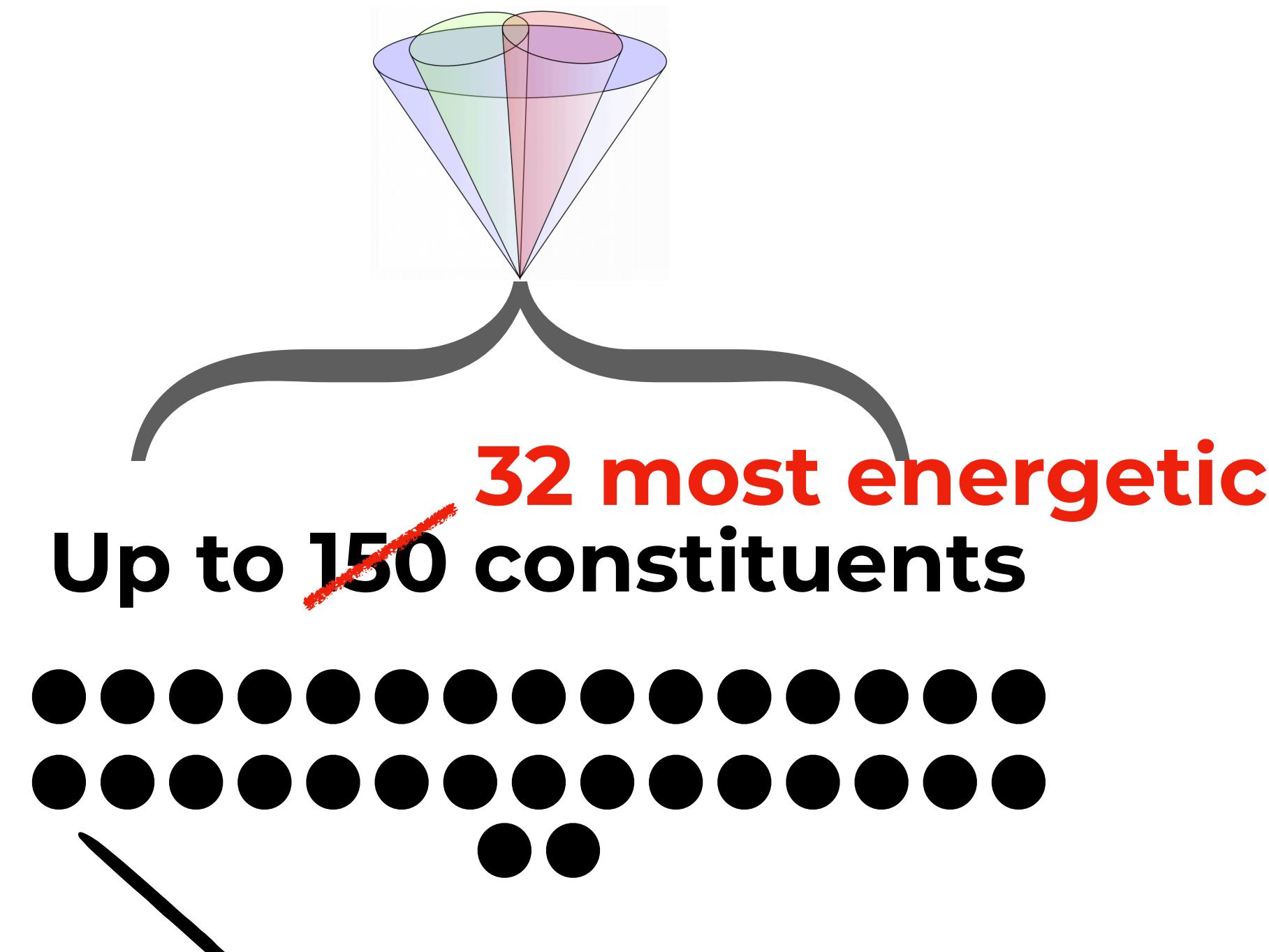
853 390 jets



***speed reasons**

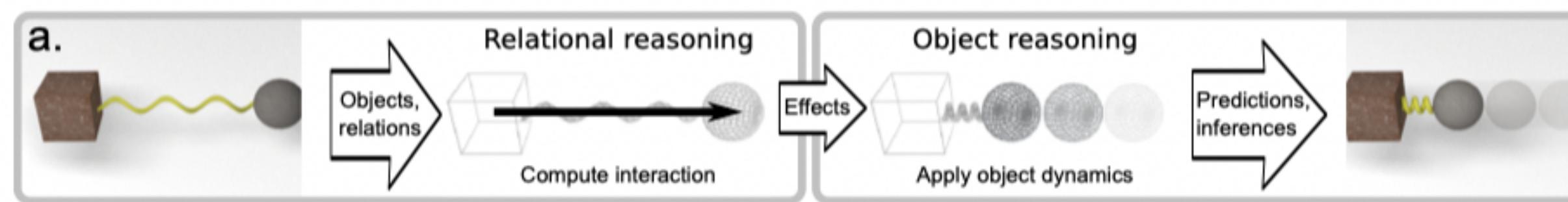


853 390 jets



3
Up to 16 features:
 ~~$p_x, p_y, p_z, E, E_{\text{rel}}, p_T,$~~
 ~~$p_T^{\text{rel}}, n, n_{\text{rel}}, n_{\text{tot}}, \phi, \phi_{\text{rel}}, \phi_{\text{tot}}$~~
 ~~$\Delta R, \cos \theta, \cos \theta_{\text{rel}}$~~

An interaction network looks at a complex system in terms of objects and relations, and then in terms of the dynamics and interactions of these elements.



arXiv:1612.00222

$$\text{IN} = \phi_O(a(G, X, \phi_R(m(G))))$$

$$1. m(G) \equiv \langle o_i, o_j, r_k \rangle \equiv b_k$$

$$2. \phi_R(\langle o_i, o_j, r_k \rangle) = e_k$$

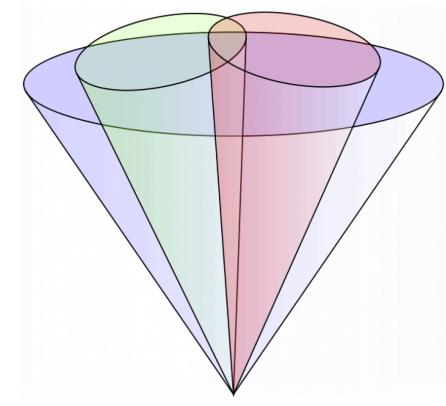
$$3. a(G, X, E) \equiv C$$

$$4. \phi_O(C) = P$$

In simulation, can be interpreted as state
of the constituents of G at (t+1).

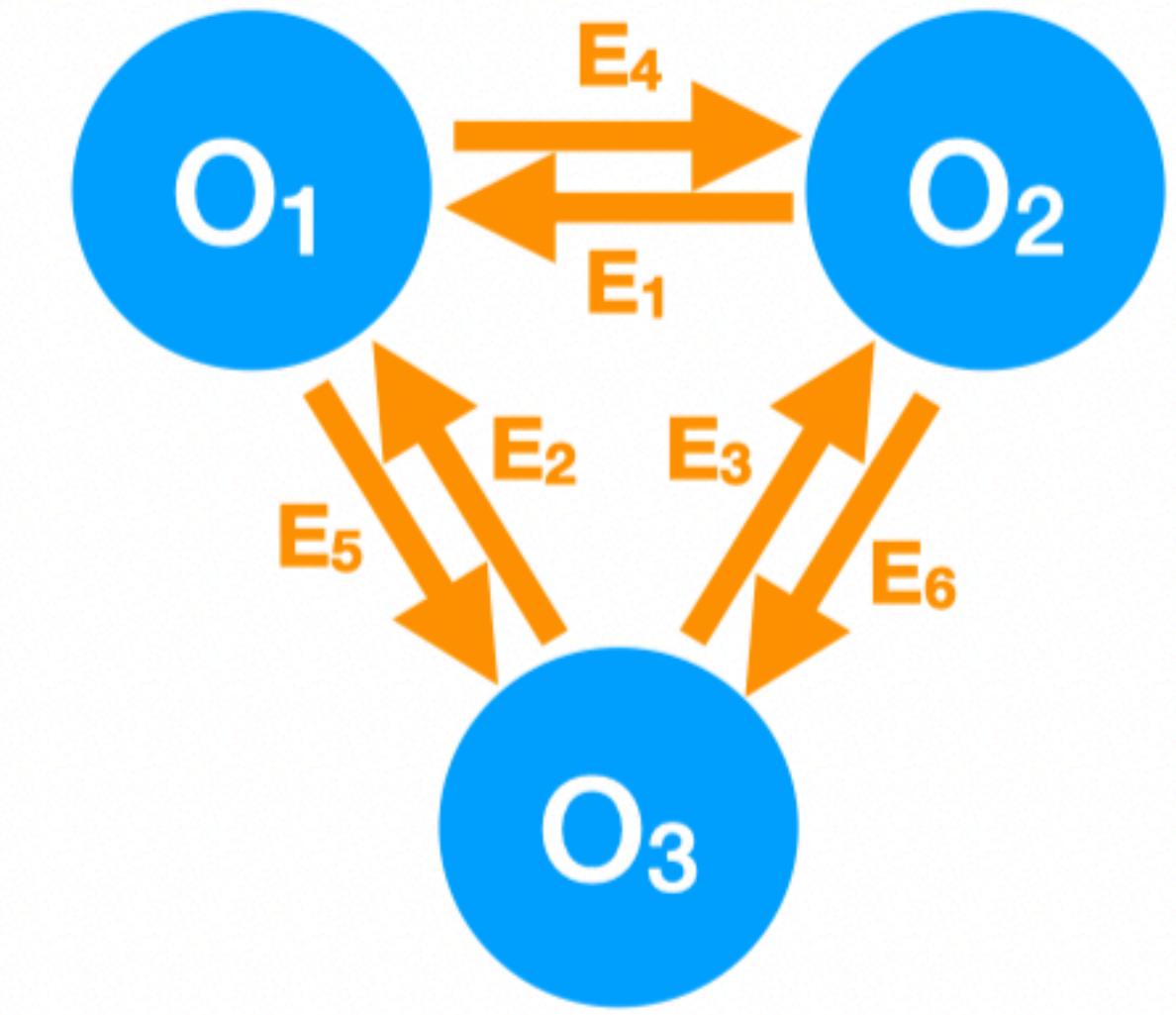
$$5. \phi_A(P) = A$$

Can learn order of P.



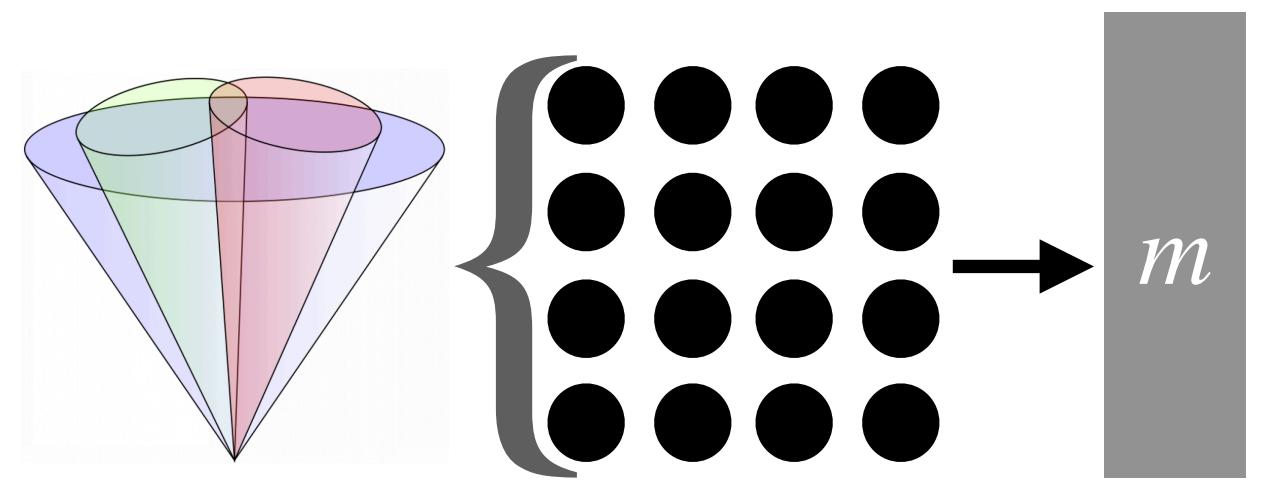
$$I \equiv \begin{pmatrix} p_T^1 & \dots & p_T^{16} \\ \eta^1 & \dots & \eta^{16} \\ \phi^1 & \dots & \phi^{16} \end{pmatrix}$$

$$\left. \begin{array}{l} R_S \equiv \begin{pmatrix} 1 & 1 & \dots & 0 \\ \dots & 0 & \dots & 1 \\ 0 & 0 & \dots & \dots \end{pmatrix} \textbf{concat.} \\ \dim(R_S) = \dim(R_R) = N_O \times N_E \\ R_R \equiv \begin{pmatrix} 0 & 0 & \dots & 0 \\ \dots & 1 & \dots & 0 \\ 1 & 1 & \dots & 0 \end{pmatrix} \end{array} \right\} m(G) = B = \begin{pmatrix} I \times R_R \\ I \times R_S \end{pmatrix}$$



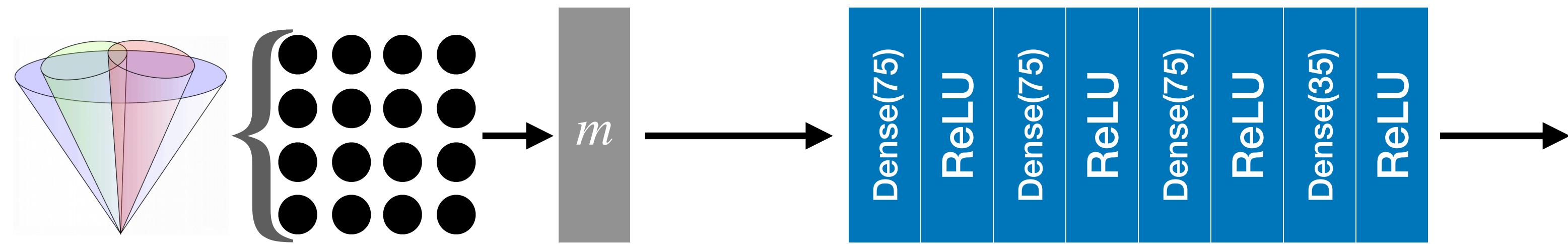
$$R_S = \begin{matrix} & E_1 & E_2 & E_3 & E_4 & E_5 & E_6 \\ \begin{matrix} O_1 \\ O_2 \\ O_3 \end{matrix} & \begin{pmatrix} 0 & 0 & 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 & 0 & 0 \end{pmatrix} \end{matrix}$$

$$R_R = \begin{matrix} & E_1 & E_2 & E_3 & E_4 & E_5 & E_6 \\ \begin{matrix} O_1 \\ O_2 \\ O_3 \end{matrix} & \begin{pmatrix} 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{pmatrix}. \end{matrix}$$



$$m(G) = B = \begin{pmatrix} I \times R_R \\ I \times R_S \end{pmatrix}$$

$$\dim(B) = (240, 6)$$



$$m(G) = B = \begin{pmatrix} I \times R_R \\ I \times R_S \end{pmatrix}$$

$$\dim(B) = (240, 6)$$

$$\phi_R(B) = E$$

Cumulative effects of interaction received by a given vertex.

$$\bar{E} = ER_R^\top$$

Concatenate to input.

$$C = \begin{pmatrix} I \\ \bar{E} \end{pmatrix}$$



$$m(G) = B = \begin{pmatrix} I \times R_R \\ I \times R_S \end{pmatrix}$$

$$\dim(B) = (240, 6)$$

$$\phi_R(B) = E$$

$$\dim(C) = (16, 38)$$

$$\phi_O(C) = P$$



$$m(G) = B = \begin{pmatrix} I \times R_R \\ I \times R_S \end{pmatrix}$$

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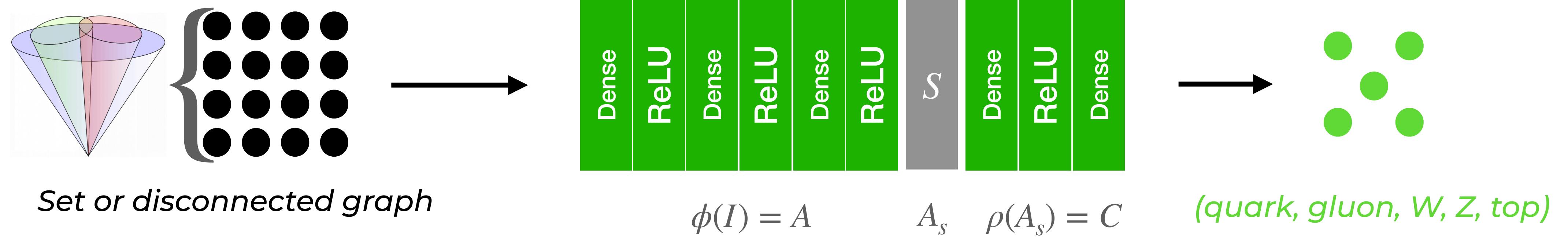


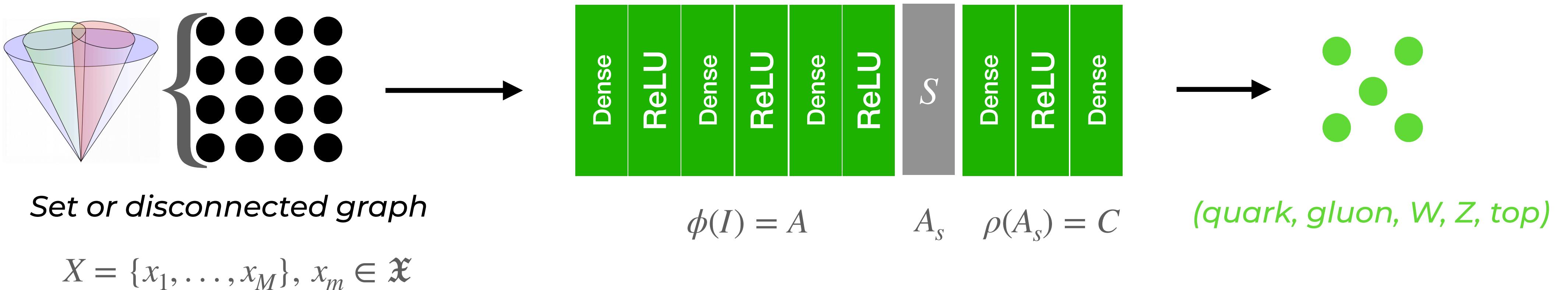
invariant

$$\dim(P) = 20$$

$$\phi_A(P) = A$$

(quark, gluon, W, Z, top)



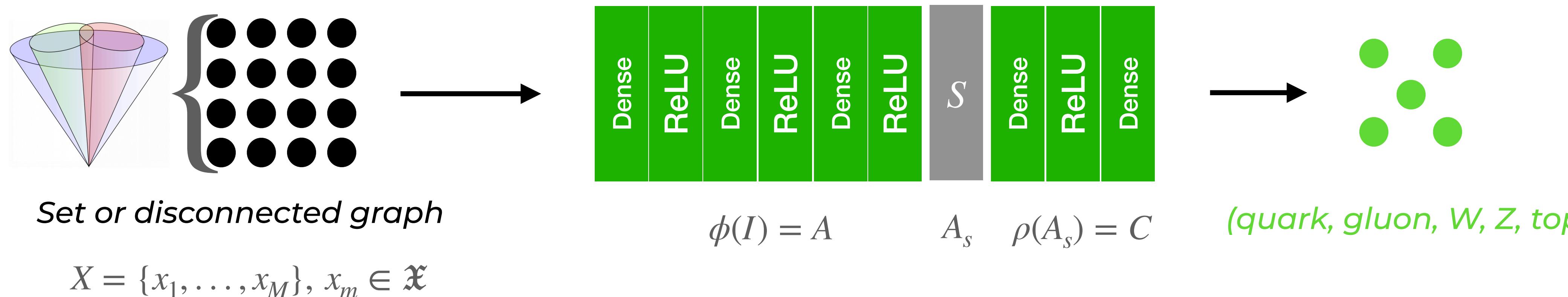


$$f: 2^{\mathfrak{X}} \rightarrow \mathcal{Y}$$

$$f(\{x_1, \dots, x_M\}) = f(\{x_{\pi(1)}, \dots, x_{\pi(M)}\})$$

invariant

$$\rho\left(\sum_{x \in X} \phi(x)\right)$$

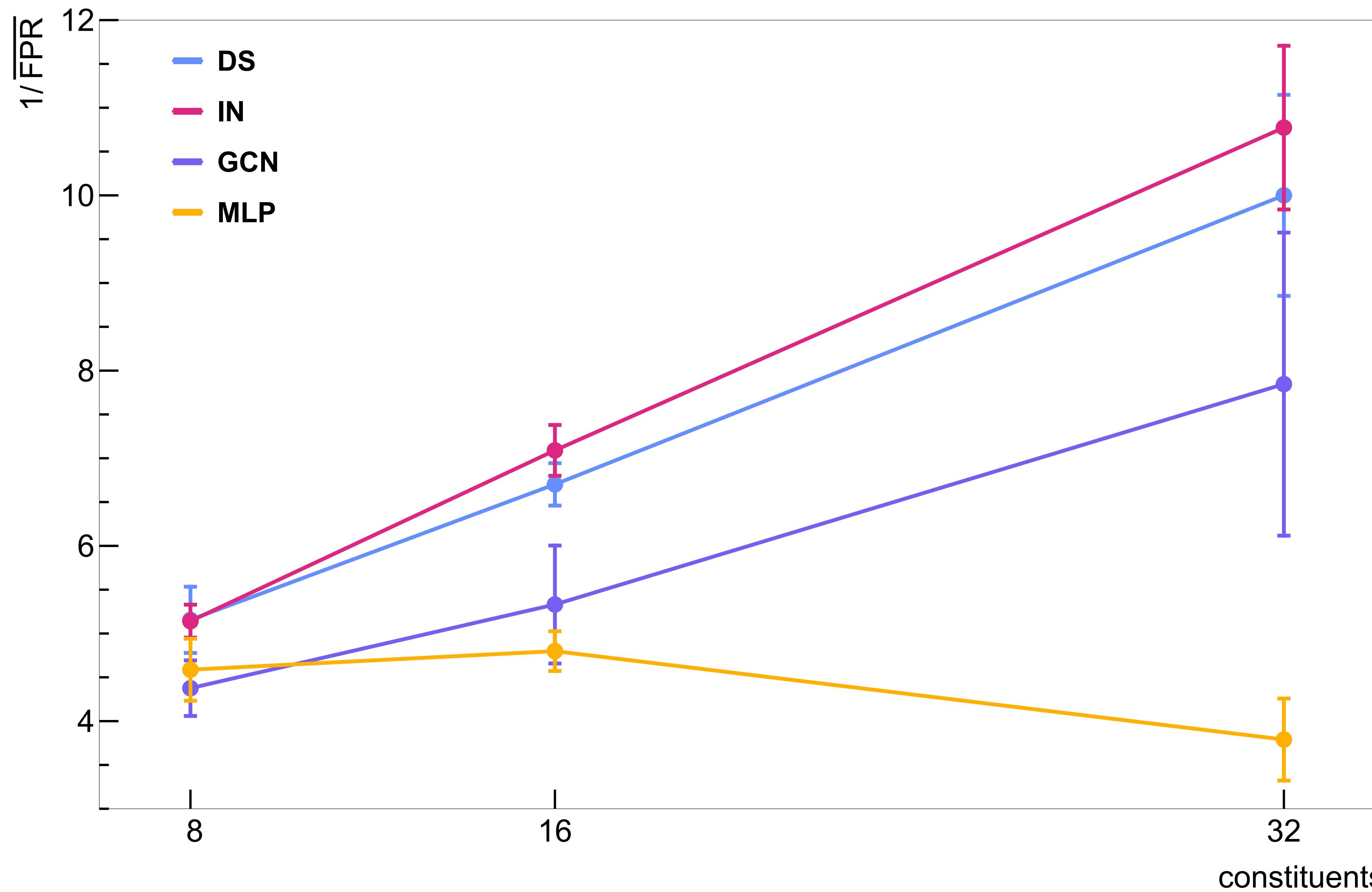


$c : \mathfrak{X} \rightarrow \mathbb{N}$ then $\sum_{x \in X} \phi(x)$ is a unique representation for every $X \in 2^{\mathfrak{X}}$

$\phi(x) = 4^{-c(x)}$

similarly construct $\rho : \mathbb{R} \rightarrow \mathbb{R}$ s.t. $f(X) = \rho\left(\sum_{x \in X} \phi(x)\right)$

*Countable Sets



Xilinx VU9P



*Latencies
(ns)*

*8 bit quantised

n particles	MLP	DS	IN
8	55	75	175
16	55	95	230
32	55	130	265

Xilinx VU9P



Resources (LUTs)

*8 bit quantised

n particles	MLP	DS	IN
8	7.6%	31%	30.8%
16	7.5%	63%	57.6%
32	7.2%	118%	97.2%

★ Set representation ~ fully connected graph (for this data!)

- * better representation yet to be found?
- * other symmetries to be exploited? e.g. rotational invariance

★ Incorporate symmetries bottom-up

- * gain intimate understanding of symmetries in data
- * test each hypothesis separately

★ Geometrical models: smart but more importantly, FAST!