# <span id="page-0-0"></span>**Analyzing variational quantum landscapes with information content**

Adrián Pérez-Salinas In collaboration with X. Bonet-Monroig, H. Wang

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# <span id="page-1-0"></span>**Variational Quantum Algorithms**

- In Variational Quantum Algorithms are proposed to fit the current limitations of quantum hardware
- I Quantum hardware is used to prepare a parameterized quantum circuit to construct a quantum state
- $\blacktriangleright$  The quantum state is optimized with respect to certain metric (e.g. energy)
- $\triangleright$  Quantum advantage is an open question
- $\blacktriangleright$  Several optimization issues
	- $\blacktriangleright$  Circuit and sampling noise
	- $\triangleright$  Gradient not always available
	- $\blacktriangleright$  Vanishing gradients / Barren Plateaus<sup>1</sup>
	- $\blacktriangleright$  Plethora of local minima<sup>2</sup>

#### An open question

How can we train VQAs better?



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- <sup>1</sup> Jarrod R. McClean et al. Nature Communications 9.1 (Nov. 2018),
- <sup>2</sup>Eric R. Anschuetz and Bobak T. Kiani. (Sept. 2022). eprint:  $arXiv:2205.05786$ .

<sup>3</sup>Kishor Bharti et al. Reviews of Modern Physics 94.1 (Feb. 2022),

# <span id="page-2-0"></span>**Exploratory Landscape Analysis and Information Content**

- Exploratory Landscape Analysis (ELA) is a numerical technique from classical optimization<sup>4</sup>
- $\blacktriangleright$  ELA aims to efficiently extract properties of the landscape to be optimized by sampling
	- Efficient = we need  $\mathcal{O}(m)$  samples from the loss function, where m is the number of parameters
- $\blacktriangleright$  ELA  $\rightarrow$  ensure trainability, improve initialization, find suitable optimizer

### Our approach

- $\triangleright$  We use Information Content (IC), a proxy for variability of the landscape
- $\blacktriangleright$  We connect the expected norm of the gradient with features of the landscape
- $\blacktriangleright$  Robust theoretical bounds and numerical checks

<sup>4</sup> Mario A. Muñoz, Michael Kirley, and Saman K. Halgamuge. IEEE Transactions on Evoluti[ona](#page-1-0)r[y](#page-3-0)[C](#page-3-0)[o](#page-1-0)[mp](#page-2-0)[ut](#page-3-0)[at](#page-0-0)[io](#page-1-0)[n](#page-2-0) [1](#page-3-0)[9.](#page-0-0)[1](#page-1-0) [\(](#page-2-0)[20](#page-3-0)[15](#page-0-0));  $299$ Discover the world at Leiden University **3** / 9  $\overline{3}$  / 9  $\overline{$ 

## <span id="page-3-0"></span>**Information Content**

#### **Computation**

- $\blacktriangleright$  Sample  $\mathcal{O}(m)$  points and connect them randomly through random walks
- $\triangleright$  Compute in the random walk  $\Delta C_i = \frac{C(\vec{\theta}_{i+1}) - C(\vec{\theta}_{i})}{\left\|\vec{\theta}_{i+1} - \vec{\theta}_{i}\right\|}.$ II
- $\triangleright$  Discretize the walk to a sequence  $\phi(\epsilon) = \begin{cases} \text{sgn}(\Delta C_i) & \text{if } |\Delta C_i| > \epsilon \\ 0 & \text{if } |\Delta C_i| > \epsilon \end{cases}$  $\odot$  if  $|ΔC_i| ≤ ε$
- $\blacktriangleright$  Compute the IC as

$$
H(\epsilon) = \sum_{a \neq b} -p_{ab} \log_6 (p_{ab}),
$$

for  $ab=\{-,\odot,+\}^2$ , with  $p_{ab}$  the extimated probability of the sequence (*ab*) in  $\phi(\epsilon)$ 

#### **Interpretation**

- $\blacktriangleright$  Value of IC
	- $\blacktriangleright$  Large IC means high variability in the landscape
	- $\blacktriangleright$  Low IC means no change
	- $\blacktriangleright$  IC gives insights in the probability of change
- $\blacktriangleright$  Value of  $\epsilon$ 
	- If  $\epsilon$  is large, the landscape is flat (to this scale)
	- If  $\epsilon$  is smal, variability is enforced
	- $\blacktriangleright$   $\epsilon$  provides insights in the value at which the landscape is variable
- $\triangleright$  Combining the values of IC and  $\epsilon$  we can estimate the gradient norm, in average in all directions

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## **Theoretical Results**

Gradient norms are related to  $\epsilon$ 

$$
\text{Prob}\left(\mathbb{E}_{\vec{\theta}}\left(\nabla C(\vec{\theta}) \cdot \vec{\delta}\right) \leq \epsilon\right) = \Phi_G\left(\frac{\epsilon \sqrt{m}}{\|\nabla C\|}\right),\tag{1}
$$

for  $\Phi_G$  the CDF of a normal distribution, and

$$
\|\nabla C\|^2 = \mathbb{E}\left(\left\|\nabla C(\vec{\theta})\right\|^2\right)
$$

**Maximal IC**

Let  $\epsilon_M = \mathrm{argmax}_{\epsilon}(H(\epsilon))$ , then

$$
\|\nabla C\| \in \Omega\left(\epsilon_{\mathcal{M}}\sqrt{m}\right) \tag{2}
$$

**Sensitive IC** Let  $\epsilon_S = \min\{\epsilon > 0 | H(\epsilon) \leq \eta\}$ , then

$$
\|\nabla C\| \le \frac{\epsilon_{\rm S}\sqrt{m}}{\Phi_G^{-1}\left(1 - 3\eta/2\right)}.\tag{3}
$$

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# **Numerical experiments**

- $\blacktriangleright$  Experiments in known problems for barren plateaus<sup>a</sup> (up to shot noise).
- $\triangleright$  Same circuit, different (global / local) observables show different regimes
- $\triangleright$  We match the theoretical results, while numerical scaling factors are also available



<sup>a</sup>M. Cerezo et al. Nature Communications 12.1 (Mar. 2021),



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# **Conclusions**

- $\triangleright$  We propose a data-driven method to study variational quantum algorithms
- $\triangleright$  Data-driven methods have a broader range of applicability than analytical methods
- $\triangleright$  We connect information content to the average norm of the gradient with analytical bounds
- $\triangleright$  We can characterize barren plateaus easily with remarkable accuracy
- $\triangleright$  Scaling prefactors are accessible for the first time
- ▶ Hopes for VQAs
	- $\blacktriangleright$  Learn landscapes before optimization
	- $\blacktriangleright$  Use suitable optimizers
	- $\blacktriangleright$  Estimate resources for successful optimization

#### The end

Thank you for your attention



# <span id="page-8-0"></span>**Analyzing variational quantum landscapes with information content**

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