



Vassily Kandinsky, *Several Circles*, 1926



Flavour Tagging with Graph Neural Network at ATLAS

19th July 2024

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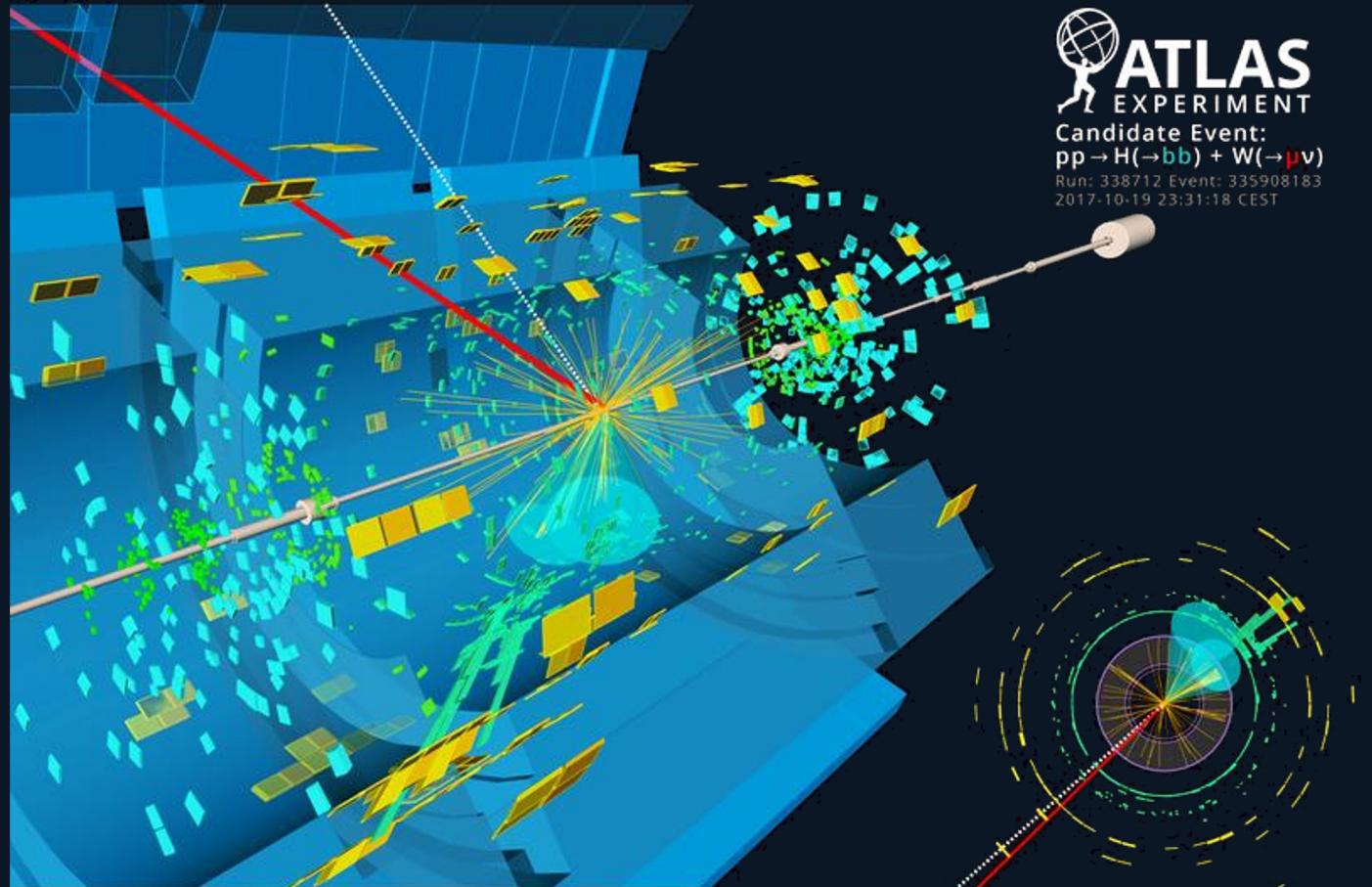
On behalf of the ATLAS Experiment

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INTRODUCTION

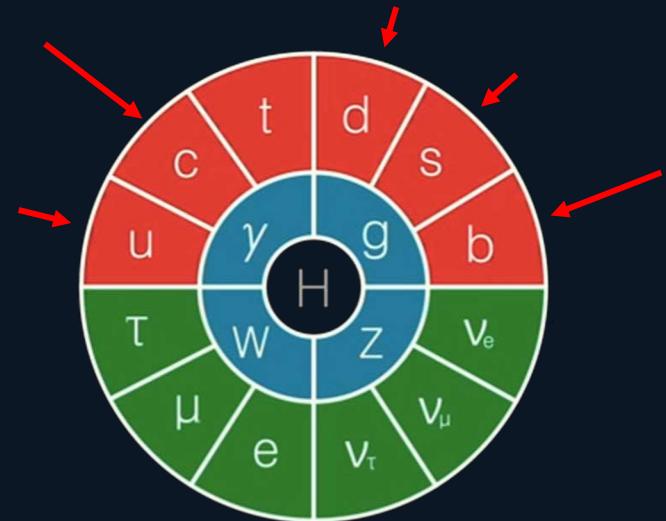
ATLAS event display of a Higgs boson decaying to two b-quarks with an associated W boson decaying into a muon and a neutrino



Example: $VH \rightarrow b\bar{b} / c\bar{c}$ presented this morning



ATLAS Collaboration relies on
heavy-flavour jets classifiers



Used in many analyses:
 $H \rightarrow b\bar{b}$, $H \rightarrow c\bar{c}$, di-Higgs, ...

These classifiers are
ML TAGGERS

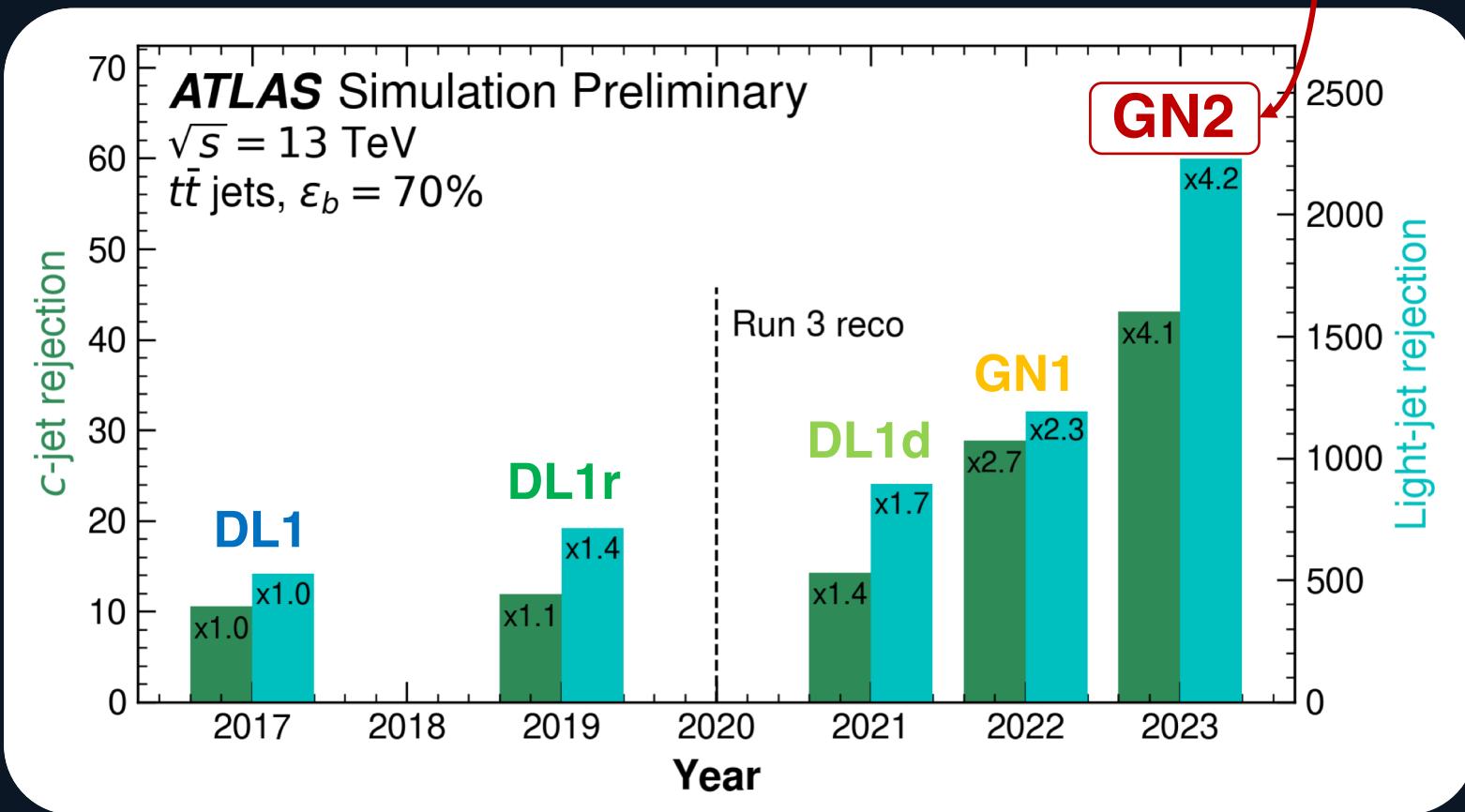
JET FLAVOUR TAGGING

CONTINUOUS EVOLUTION



→ BDT → Deep Network → RNN → DeepSet → Graph Attention → Transformer

Mission
Continuously
improve the
performance of the
ATLAS tagger
for $\{b, c, \text{light}^*, \tau^{**}\}$
jet discrimination



* light = u, d, s, gluon

** hadronic τ decays resemble c-jets

rejection = 1 / miss-classification efficiency

JET FLAVOUR TAGGING

CONTINUOUS EVOLUTION



→ BDT → Deep Network → RNN → DeepSet → Graph Attention → Transformer

Inputs

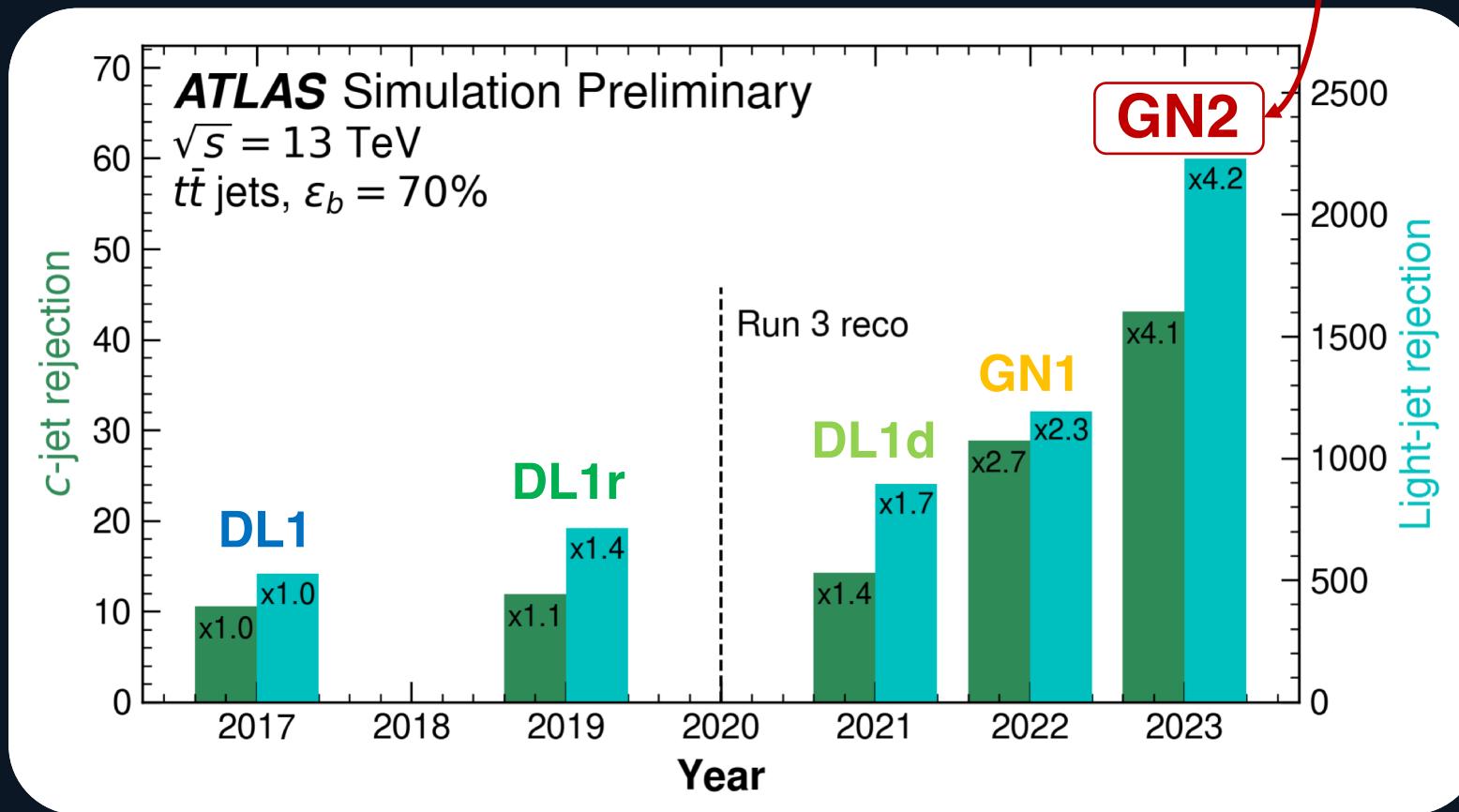
Tracks & jet

Outputs

Per-flavour*
probabilities
& discriminant

Trained on
simulated data

Calibrated on
real data



*{ b , c , light, τ }

rejection = 1 / miss-classification efficiency

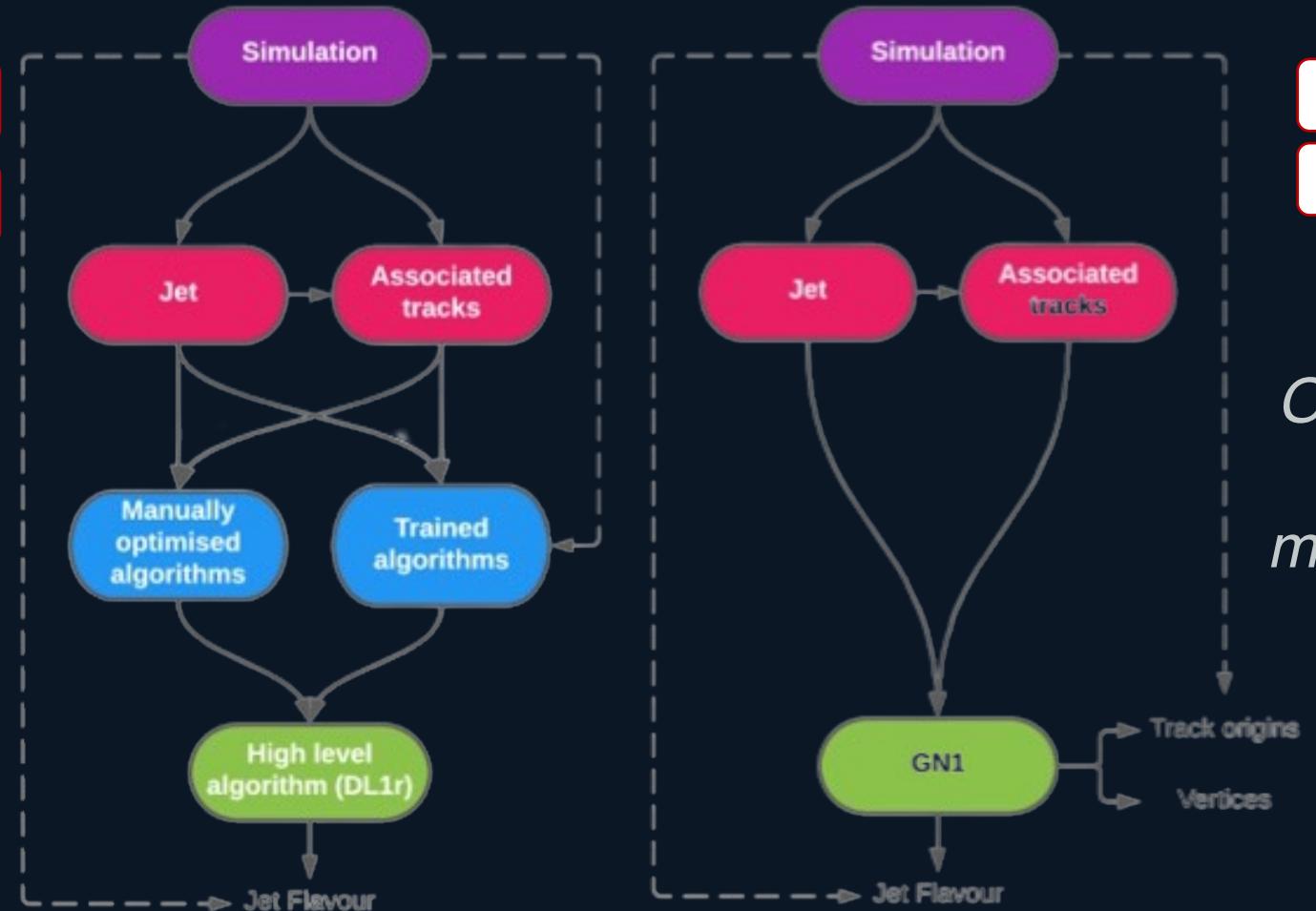
JET FLAVOUR TAGGING



New design adopted by ATLAS for GN1 & GN2

Hierarchical
Many small submodels, cumbersome to maintain, limited use of Deep Learning

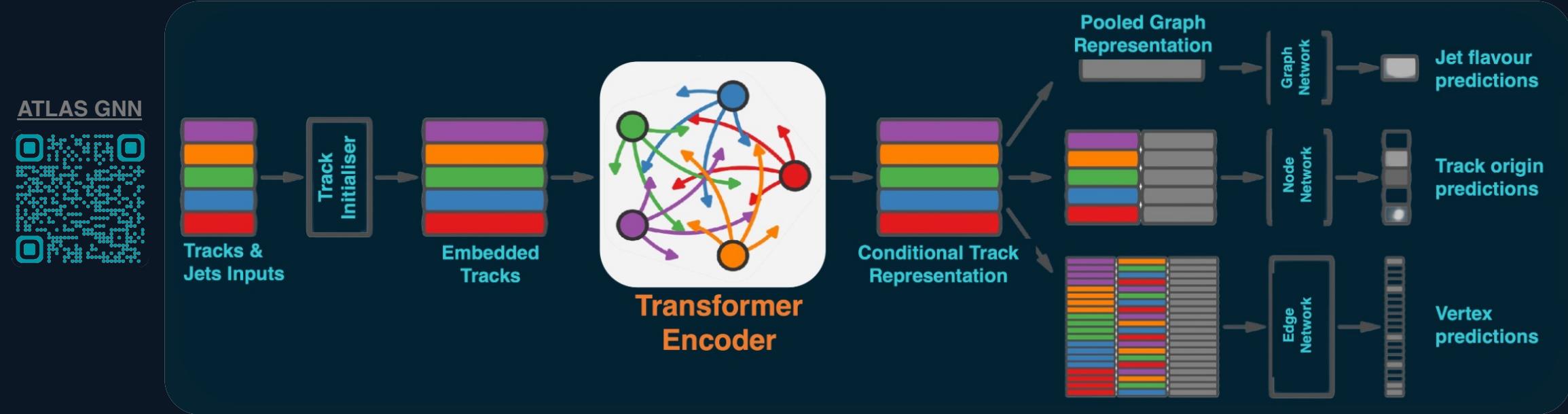
DL1d
DL1r



GN2
GN1

Integrated
One large network to rule them all, multitask, multimodal, agile and easy to update, fully leveraging Deep Learning

Large Multimodal Multitask Transformer Model

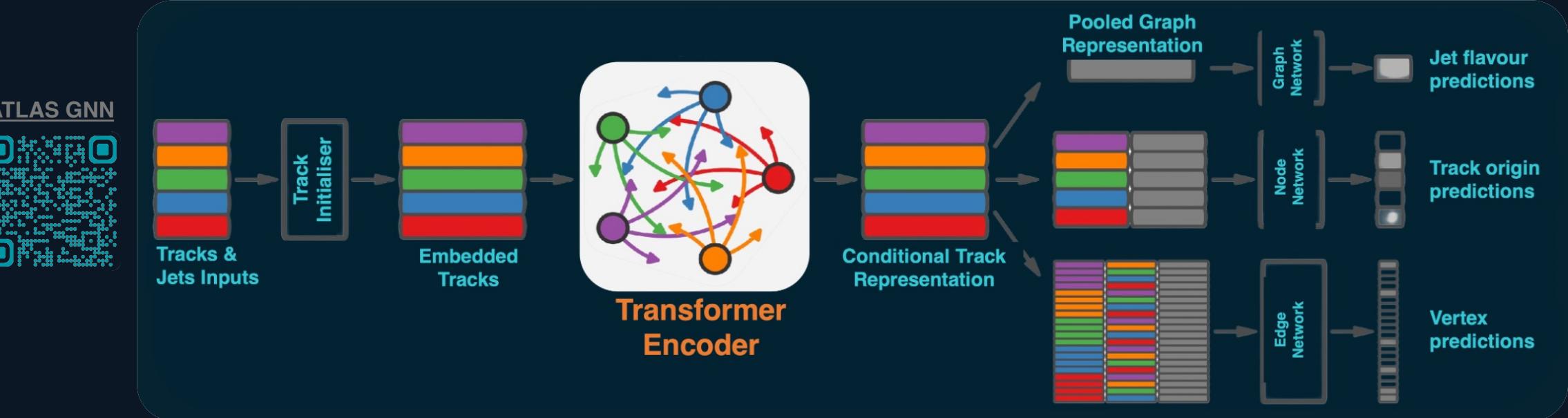


Multimodal
Combines **multiple**
physics input types

Architecture
Single network with
SOTA performance

Multitask
Per-flavour probabilities
+ auxiliary objectives

Large Multimodal Multitask Transformer Model



DL1d — 130k parameters

“Large” **GN1** ————— 800k parameters

GN2 ————— 2600k parameters

GN2 *Inputs*



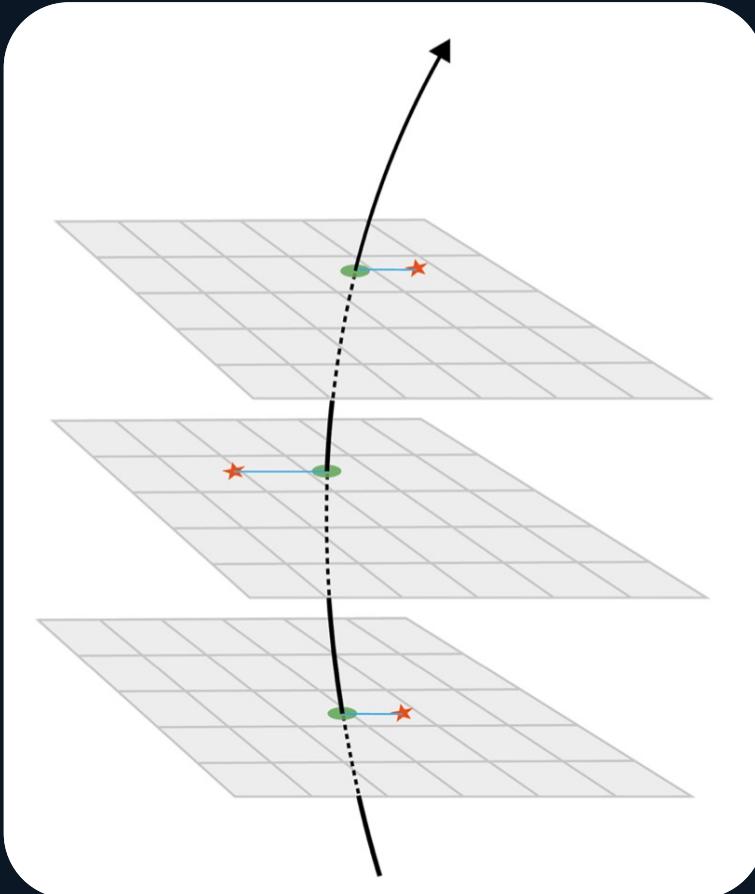
Multimodal Tracks + Jet Variables

Tracks

- Track parameters
- Uncertainties
- Impact parameters

Jet

- p_T & η
- Resampled / flavour



192,000,000 simulated jets for training

Thanks to new pre-processing software +
Stabilising architecture choices:
Layer Normalisation
Dropout

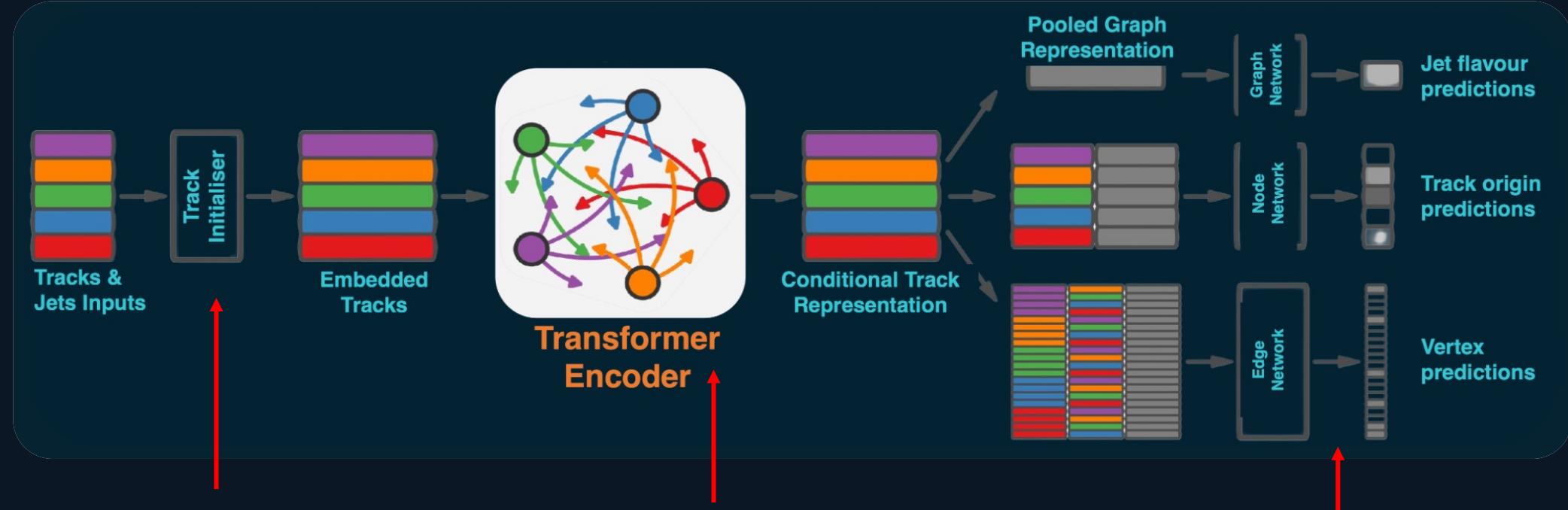
GN2 Architecture



1

2

3

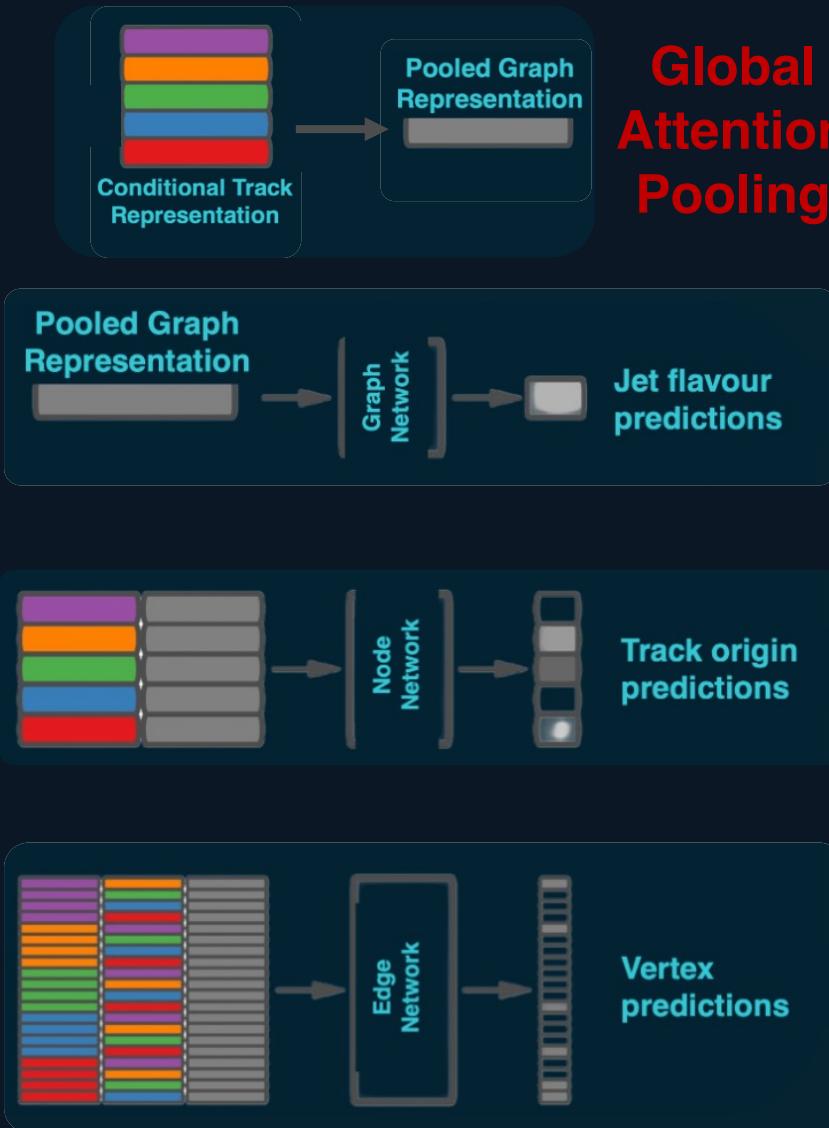


Neural network
for combined
representations
embedding

Transformer Encoder
for conditional track
representation

Auxiliary tasks for
expert knowledge
distillation

GN2 Loss



1

Predict jet flavour probabilities + tagging discriminant

2

Predict origin process of each track

3

Predict track-pairs vertex compatibility

$$\mathcal{L}_{Total} = \mathcal{L}_{Jet} + \alpha \mathcal{L}_{Track} + \beta \mathcal{L}_{Vertex}$$

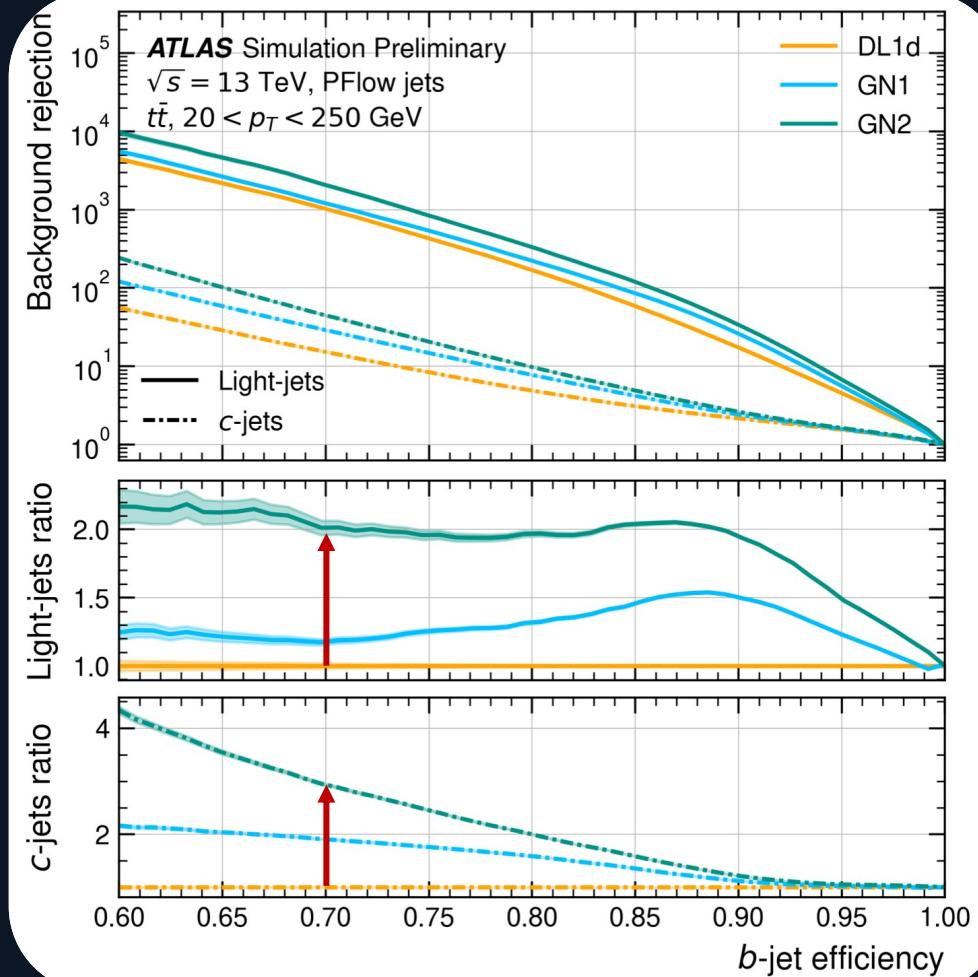
Model	f_c
DL1d	0.018
GN1	0.05
GN2	0.1

$$D_b = \frac{p_b}{f_c p_c + (1 - f_c) p_{light}}$$

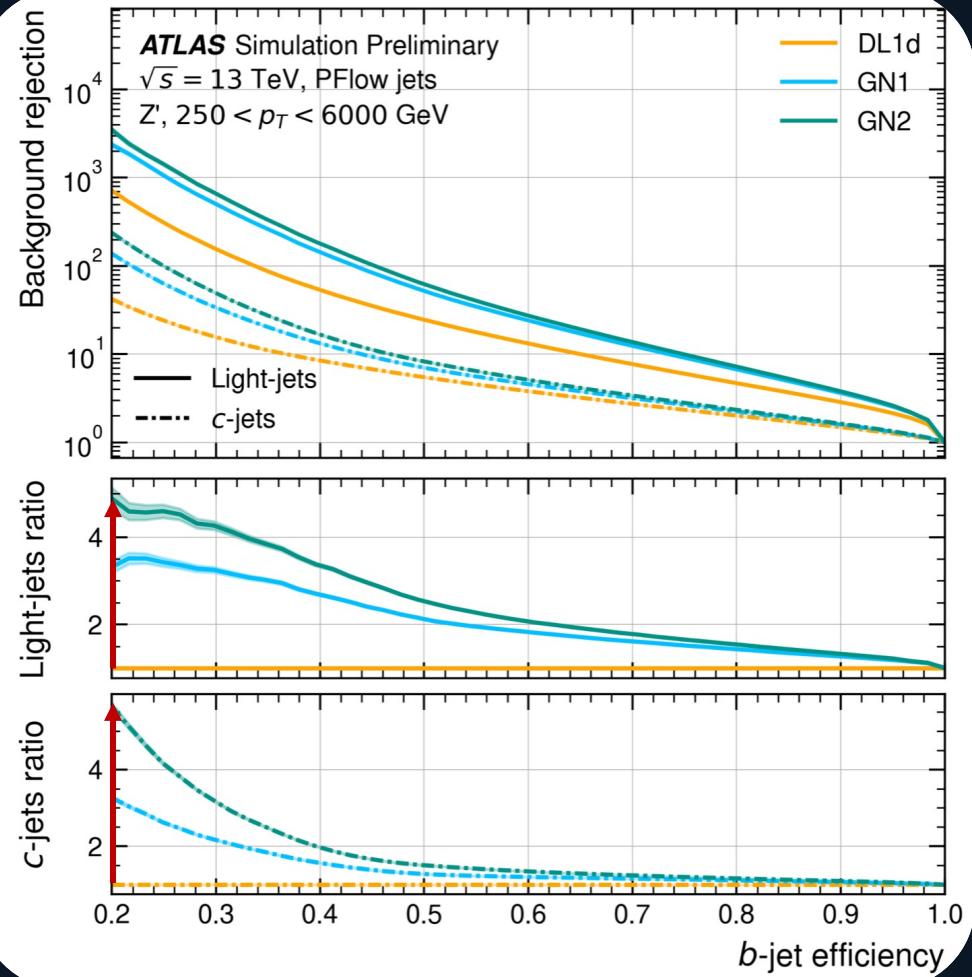
Truth Origin	Description
Pileup	From a $p\bar{p}$ collision other than the primary interaction
Fake	Created from the hits of multiple particles
Primary	Does not originate from any secondary decay
fromB	From the decay of a b -hadron
fromBC	From a c -hadron decay, which itself is from the decay of a b -hadron
fromC	From the decay of a c -hadron
OtherSecondary	From other secondary interactions and decays

Significant improvement with GN2

Low p_T
($t\bar{t}$)
 $70^* b\text{-eff}$



High p_T
(Z')
 $20^* b\text{-eff}$



Left working point corresponds to right one

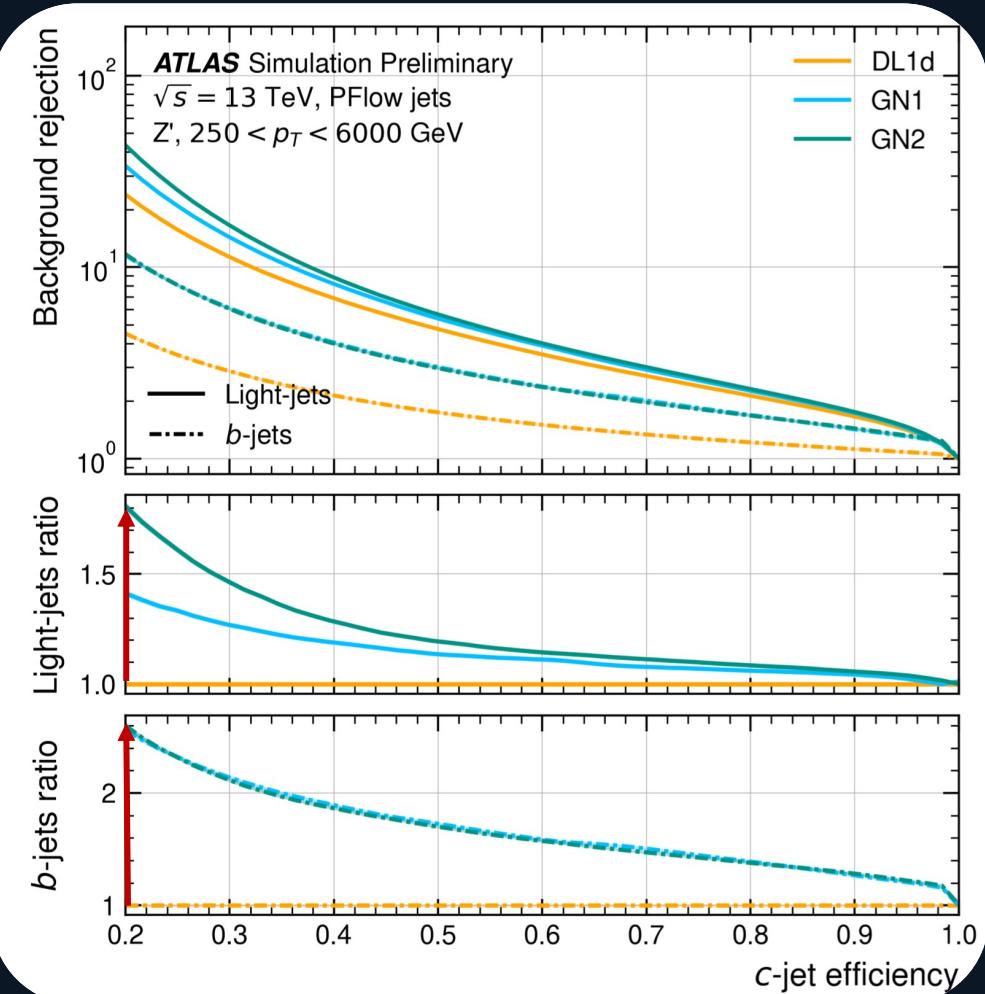
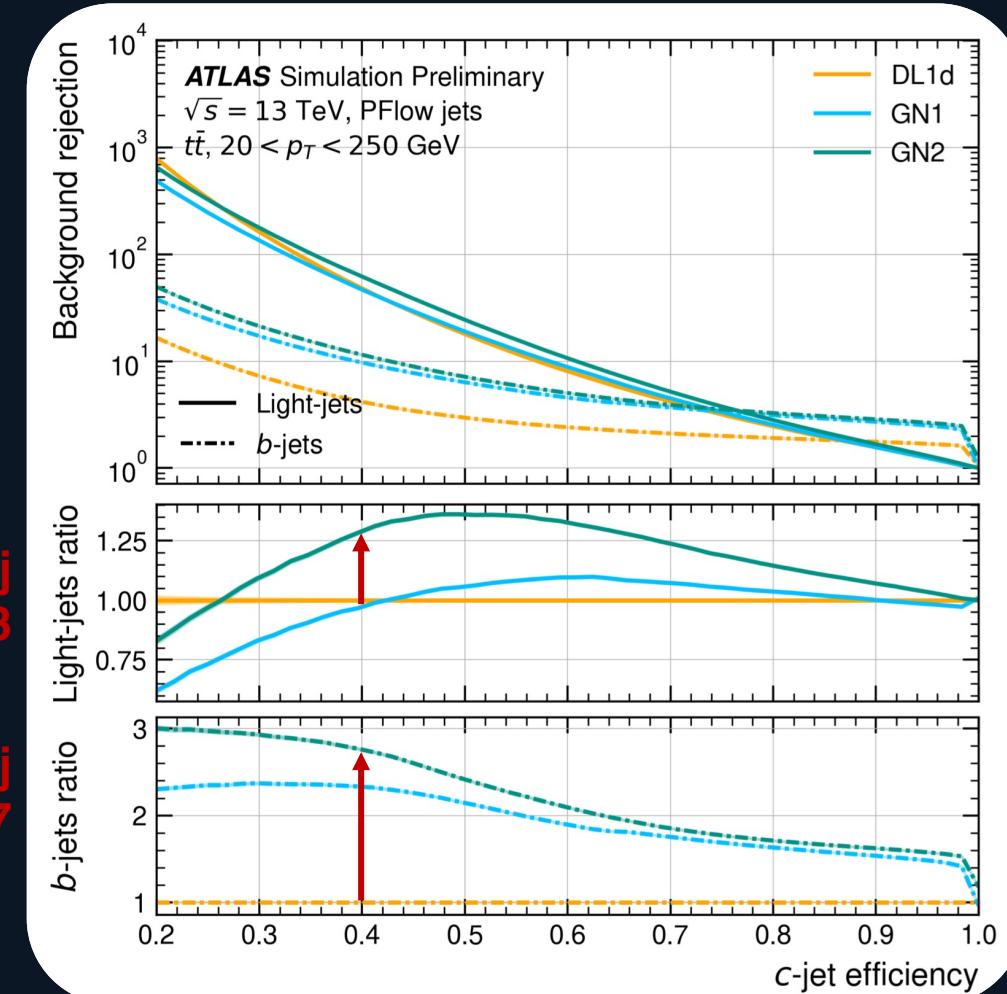


Significant improvement with GN2

Low p_T
($t\bar{t}$)
 40^* c-eff

Light-rej
 $\times 1.3$

c-rej
 $\times 2.7$



Left working point corresponds to right one

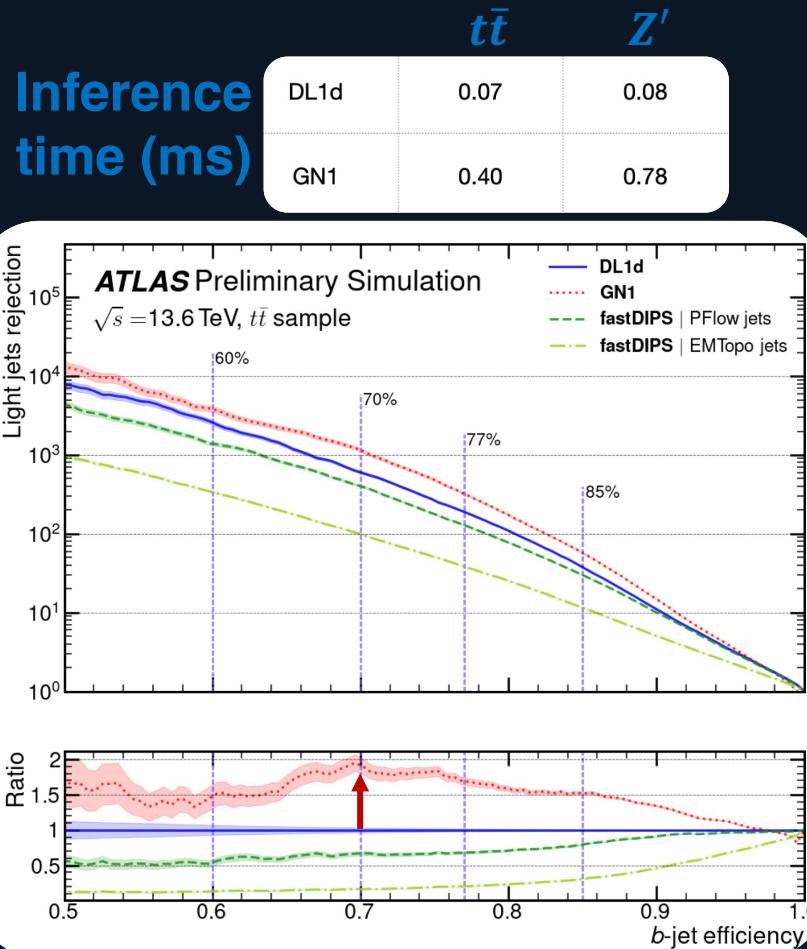
GN2 Aftermath



GN models bring a remarkable improvement to ATLAS

Quickly Proliferating

Boosted $X \rightarrow b\bar{b} / c\bar{c}$

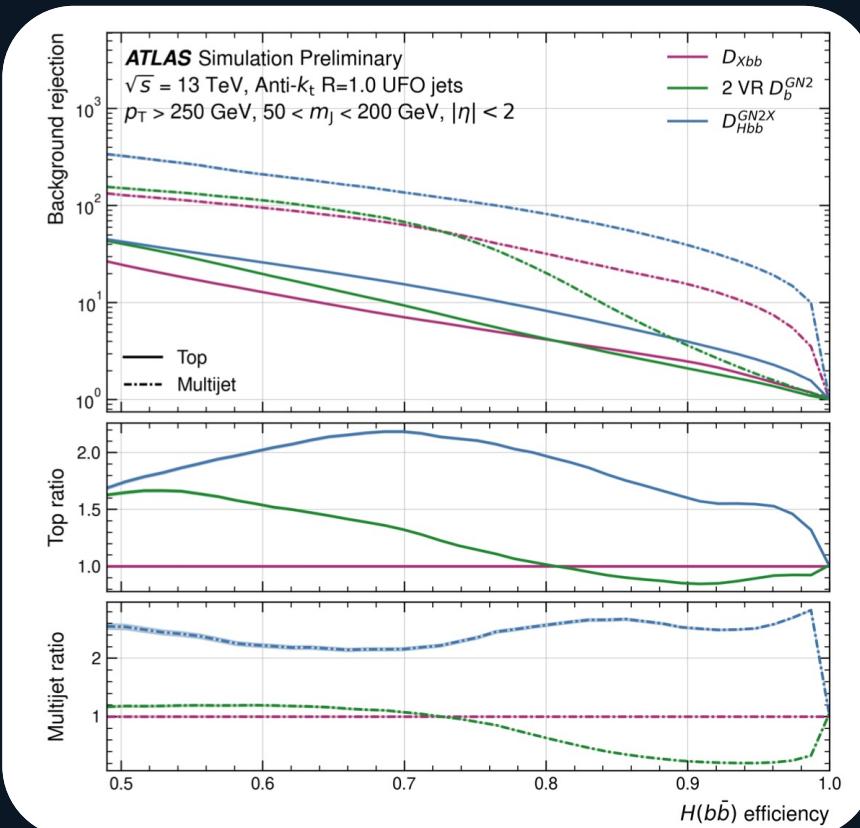


T
R
I
G
G
E
R
S

For
Higgs
tagging

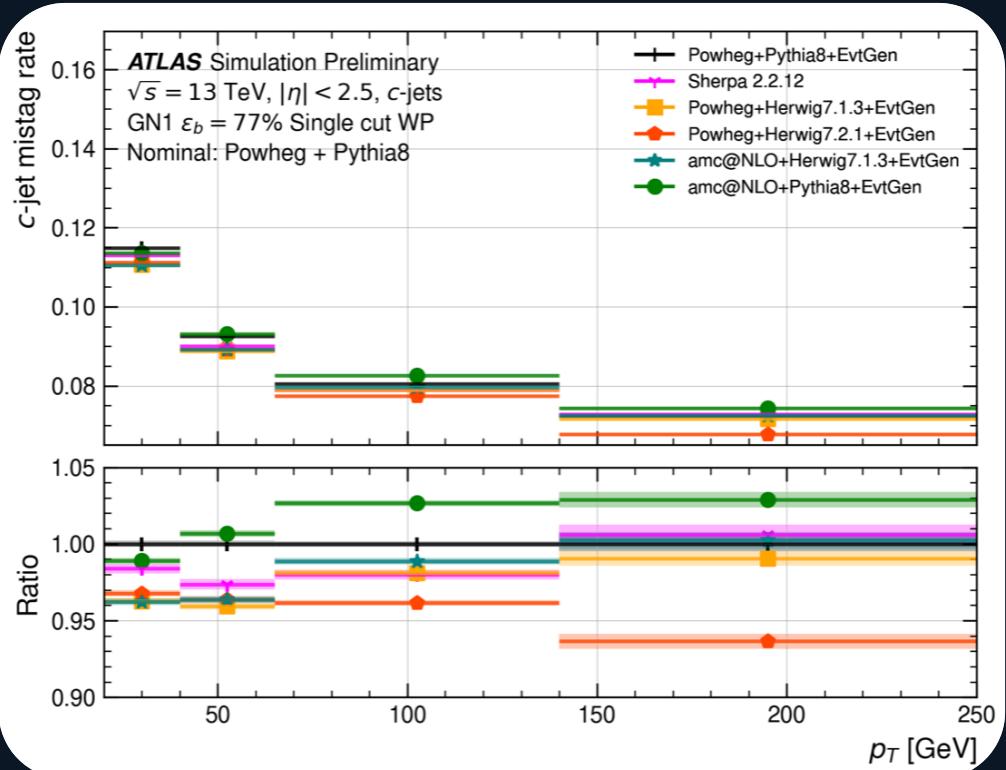
Top-rej

Multi-jet-rej



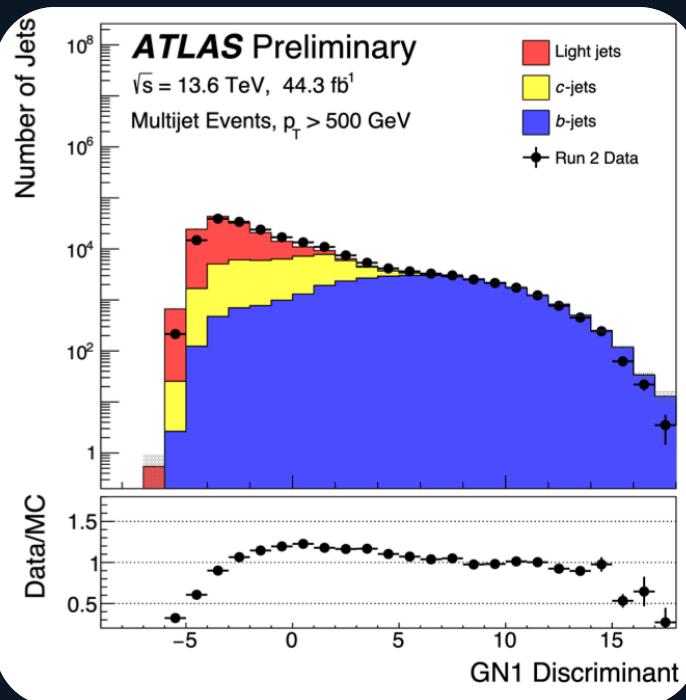
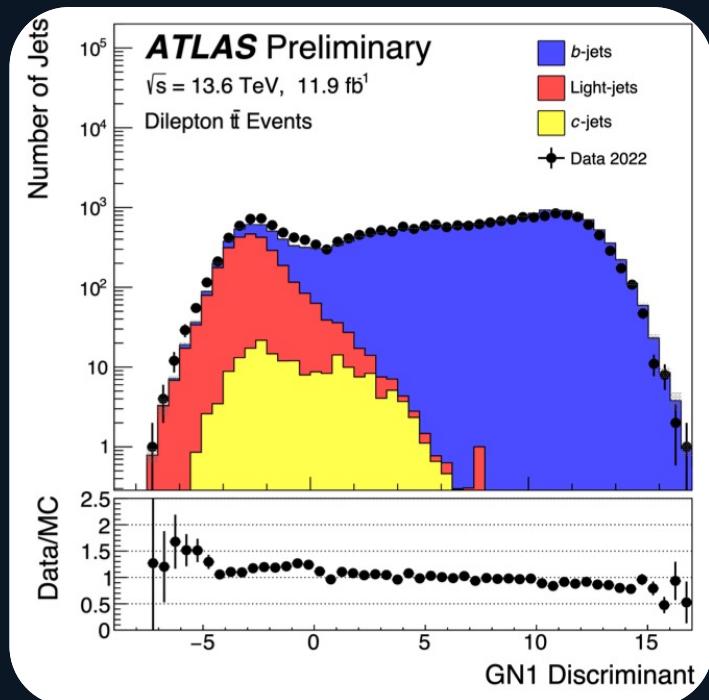
+ HL-LHC forecast, application to other part of the Collaboration, ...

MC Dependence



GN models bring a remarkable improvement to ATLAS Ongoing Calibration

Data / MC Agreement



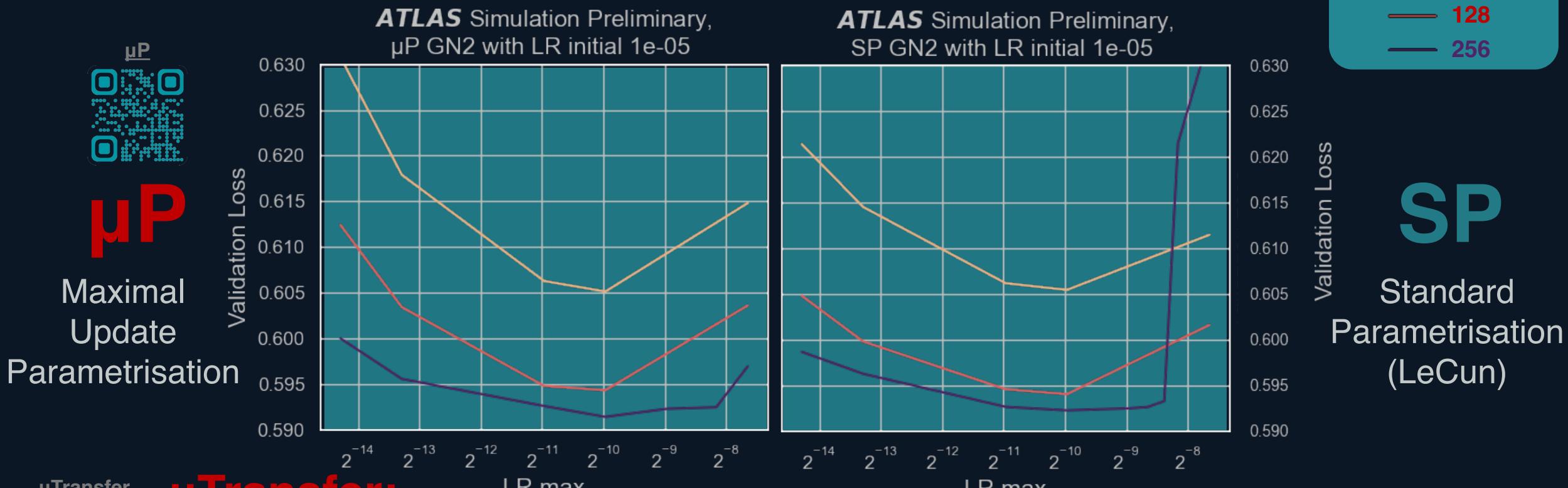
✓ Overall generator dependence $\sim O(3\text{-}6\%)$

✓ Good agreement in the bulk



GN models bring a remarkable improvement to ATLAS

Ongoing Hyperparameters Tuning



μP
Maximal
Update
Parametrisation

$\mu Transfer$

$\mu Transfer$:

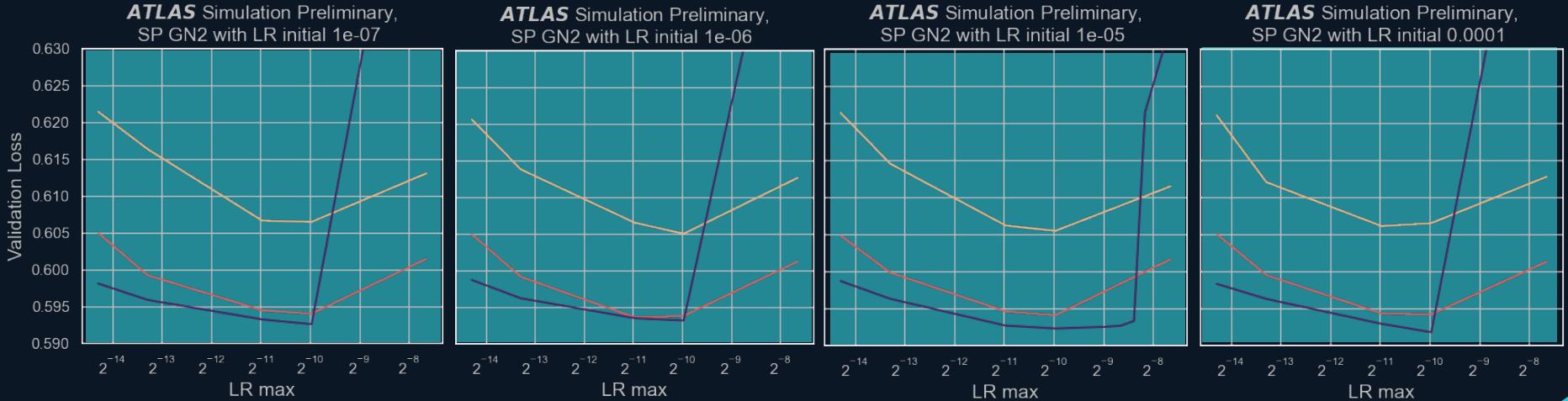
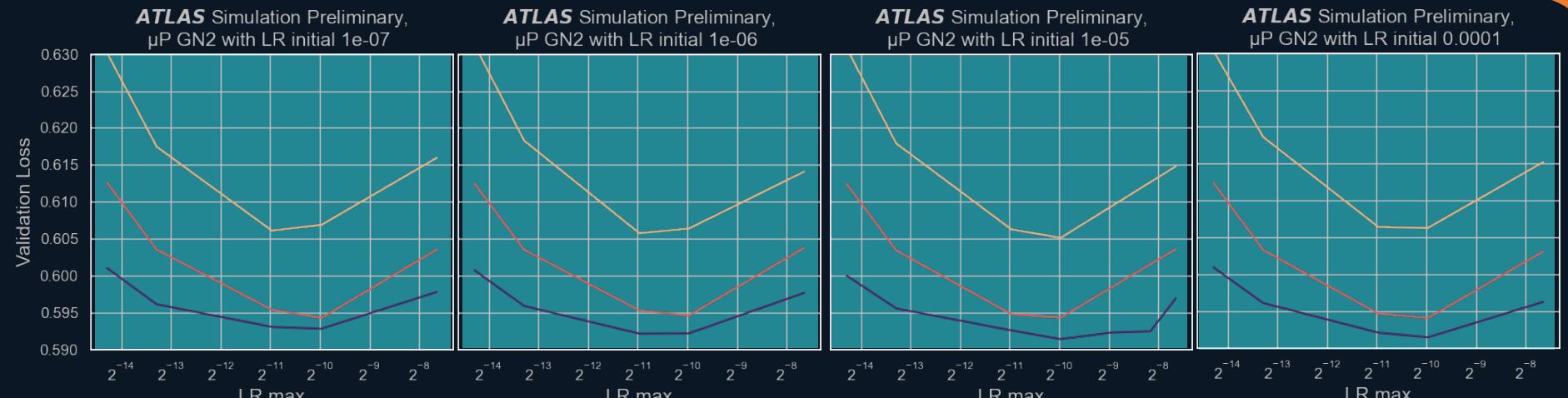
- HPO on the smaller model → faster training → better coverage
- Zero-shot transfer: best HP small model = best HP large model

Embedding Width
— 64
— 128
— 256

SP
Standard
Parametrisation
(LeCun)

Real Deployment

LR Scheduler Optimisation: LR Max per LR Initial

SP **μ P****Embedding Width**

64

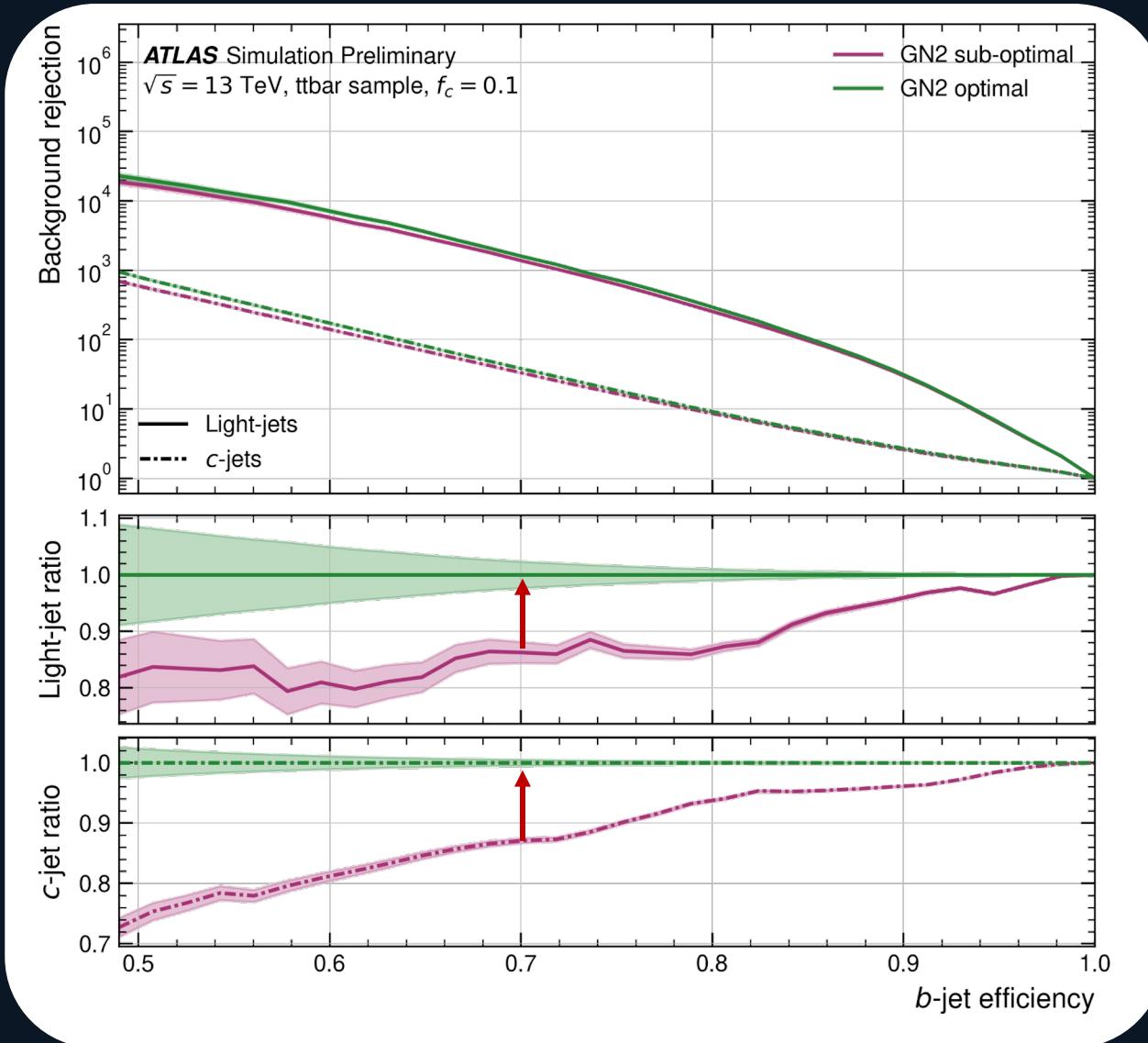
128

256

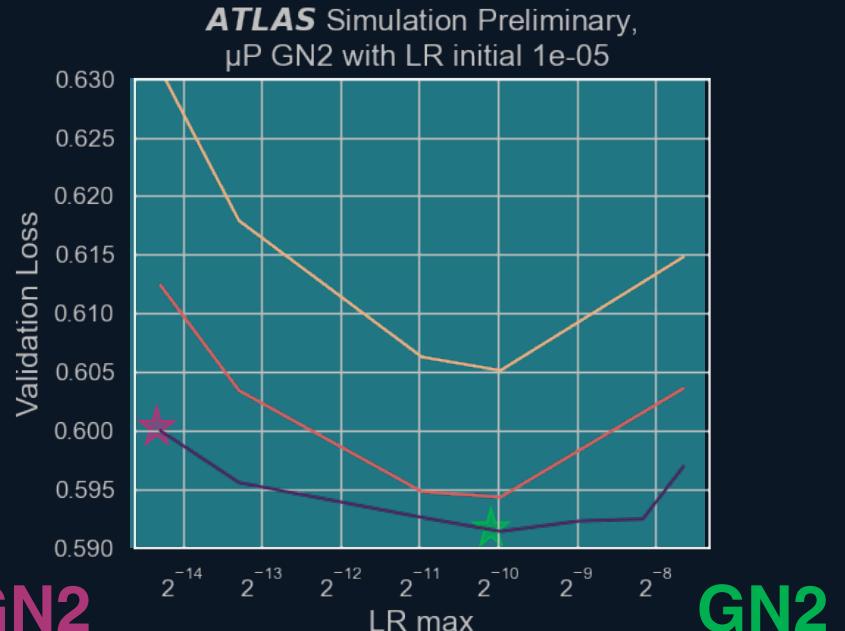
- ❖ Some SP trainings unstable
- ❖ No guarantee optimum shared across width

- ✓ μ P trainings always stable
- ✓ Guaranteed shared optimum for sufficient width

HPO matters ...



ROC curves on $t\bar{t}$



GN2 Sub-optimal **GN2 Optimal**
Significant performance dependency on HP

$$D_b = \frac{p_b}{f_c p_c + (1 - f_c) p_{light}}$$



Vassily Kandinsky, *Several Circles*, 1926



**Thank you
for your attention!**

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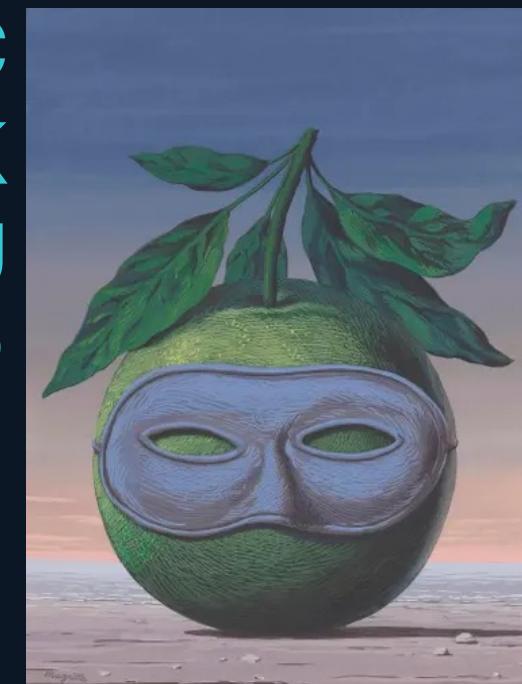
B
A
C
K
U
P



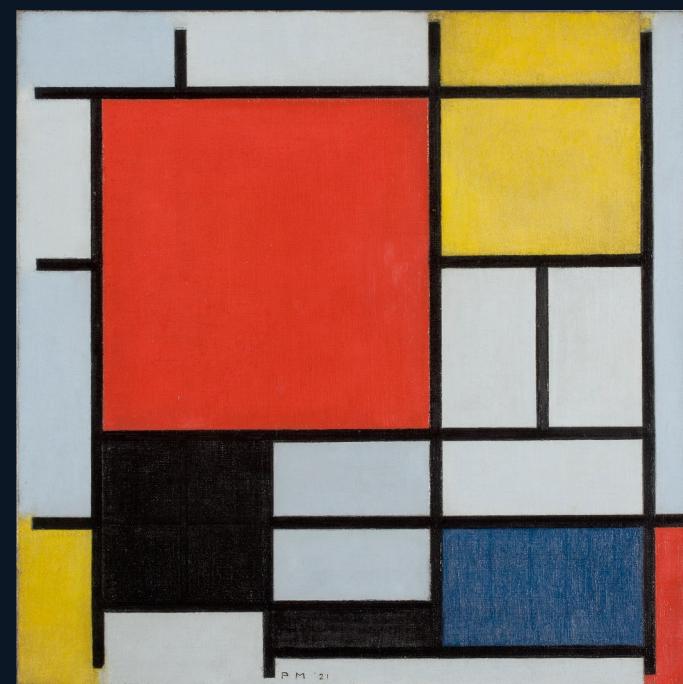
René Magritte – *Le Retour*



Monet – *Les Coquelicots*



René Magritte – *Souvenir de Voyage*



Piet Mondriaan
– *Composition with Red, Yellow, and Blue*

GN2 *Inputs*



Jet Input	Description
p_T	Jet transverse momentum
η	Signed jet pseudorapidity
Track Input	Description
q/p	Track charge divided by momentum (measure of curvature)
$d\eta$	Pseudorapidity of the track, relative to the jet η
$d\phi$	Azimuthal angle of the track, relative to the jet ϕ
d_0	Closest distance from the track to the PV in the longitudinal plane
$z_0 \sin \theta$	Closest distance from the track to the PV in the transverse plane
$\sigma(q/p)$	Uncertainty on q/p
$\sigma(\theta)$	Uncertainty on track polar angle θ
$\sigma(\phi)$	Uncertainty on track azimuthal angle ϕ
$s(d_0)$	Lifetime signed transverse IP significance
$s(z_0)$	Lifetime signed longitudinal IP significance
nPixHits	Number of pixel hits
nSCTHits	Number of SCT hits
nIBLHits	Number of IBL hits
nBLHits	Number of B-layer hits
nIBLShared	Number of shared IBL hits
nIBLSplit	Number of split IBL hits
nPixShared	Number of shared pixel hits
nPixSplit	Number of split pixel hits
nSCTShared	Number of shared SCT hits
nPixHoles	Number of pixel holes
nSCTHoles	Number of SCT holes
leptonID	Indicates if track was used in the reconstruction of an electron or muon (only for GN1 Lep)

GN2 *Track Selection*



Parameter	Selection
p_T	$> 500 \text{ MeV}$
$ d_0 $	$< 3.5 \text{ mm}$
$ z_0 \sin \theta $	$< 5 \text{ mm}$
Silicon hits	≥ 8
Shared silicon hits	< 2
Silicon holes	< 3
Pixel holes	< 2

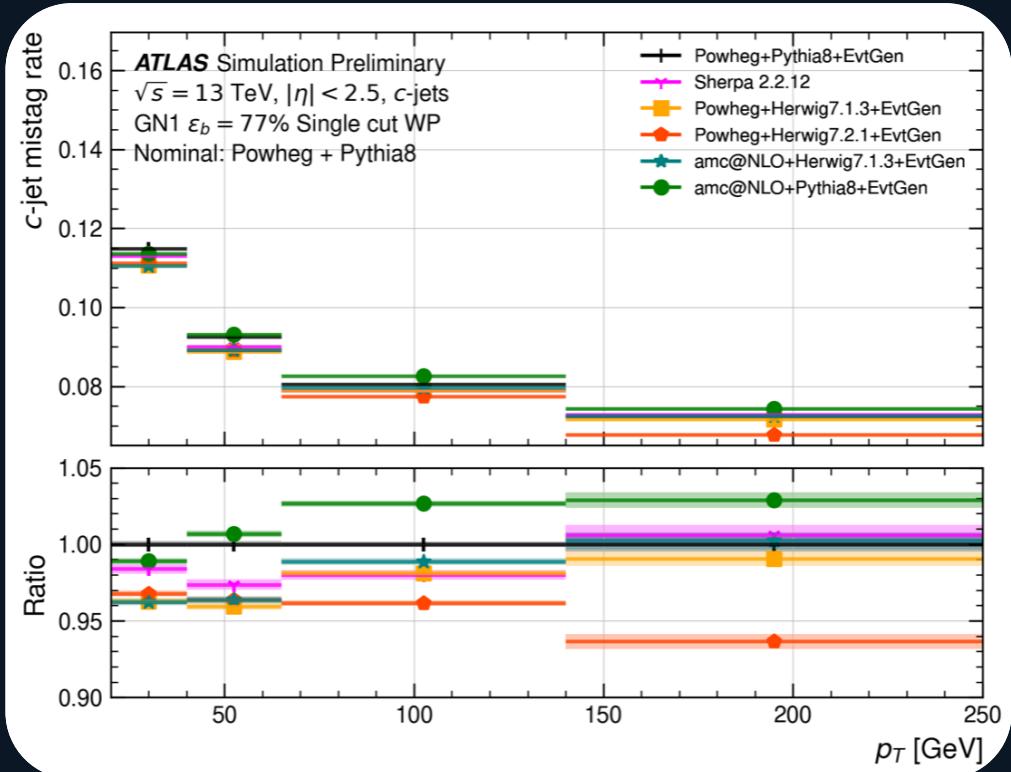
"Quality selections applied to tracks, where d_0 is the transverse IP of the track, z_0 is the longitudinal IP with respect to the PV and θ is the track polar angle. Shared hits are hits used on multiple tracks which have not been classified as split by the cluster-splitting neural networks. Shared hits on pixel layers are given a weight of 1, while shared hits in the SCT are given a weight of 0.5. A hole is a missing hit, where one is expected, on a layer between two other hits on a track".



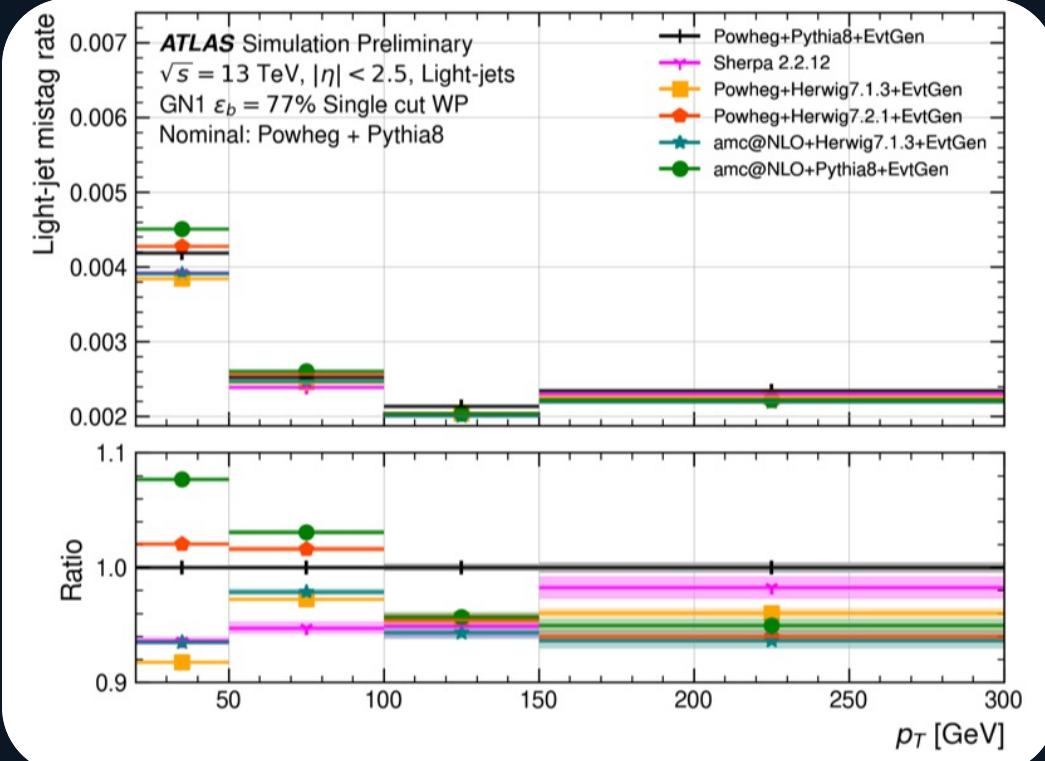
GN2 MC Dependency



C-jets



Light-jets



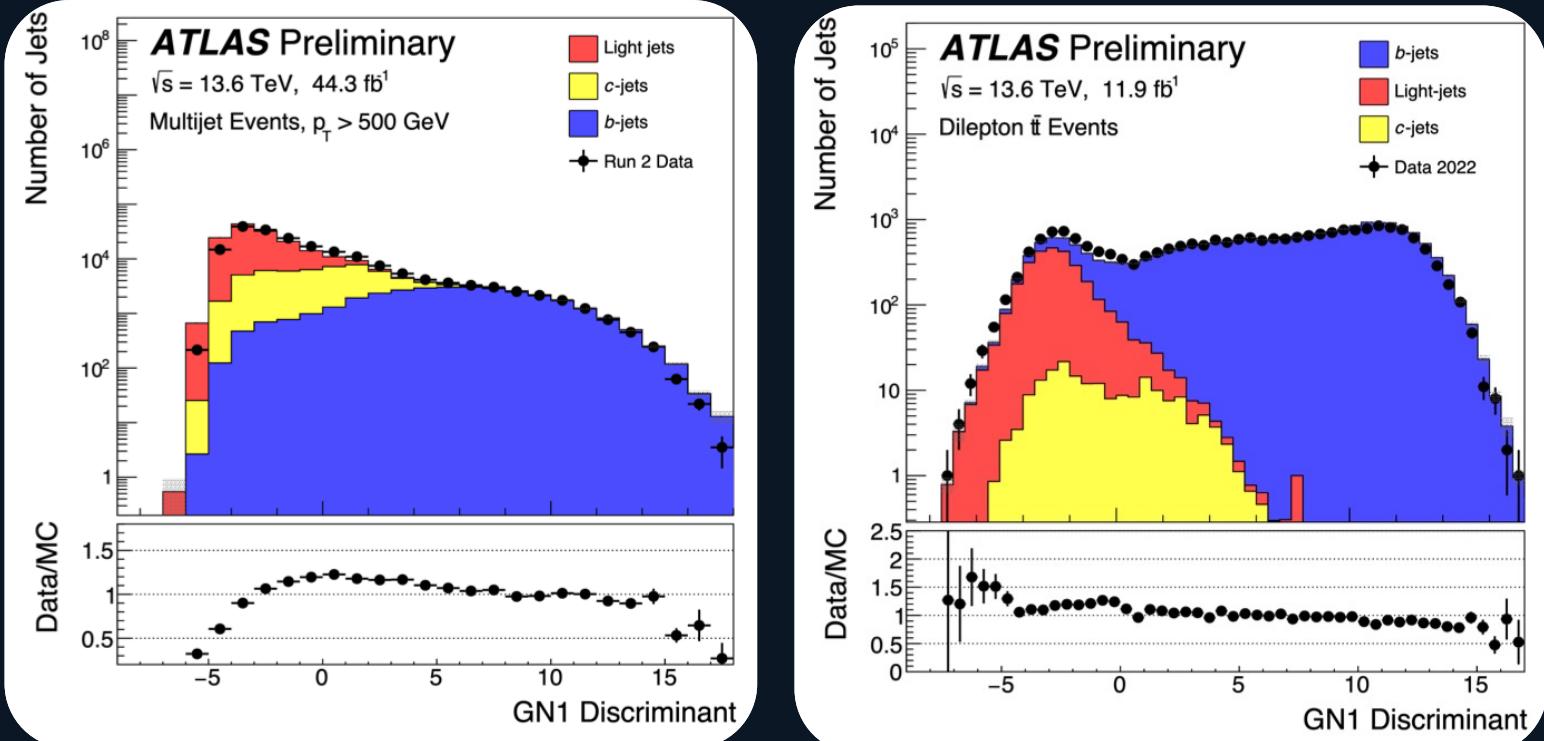
GN2 Data / MC

- “Tag and probe” event selection: tag jet must pass 85% b-eff
- Simulations are scaled to match the total yield in data

Tag jet pass
85% b-eff

$p_T > 200$
GeV

Event
 $p_T > 500$
GeV



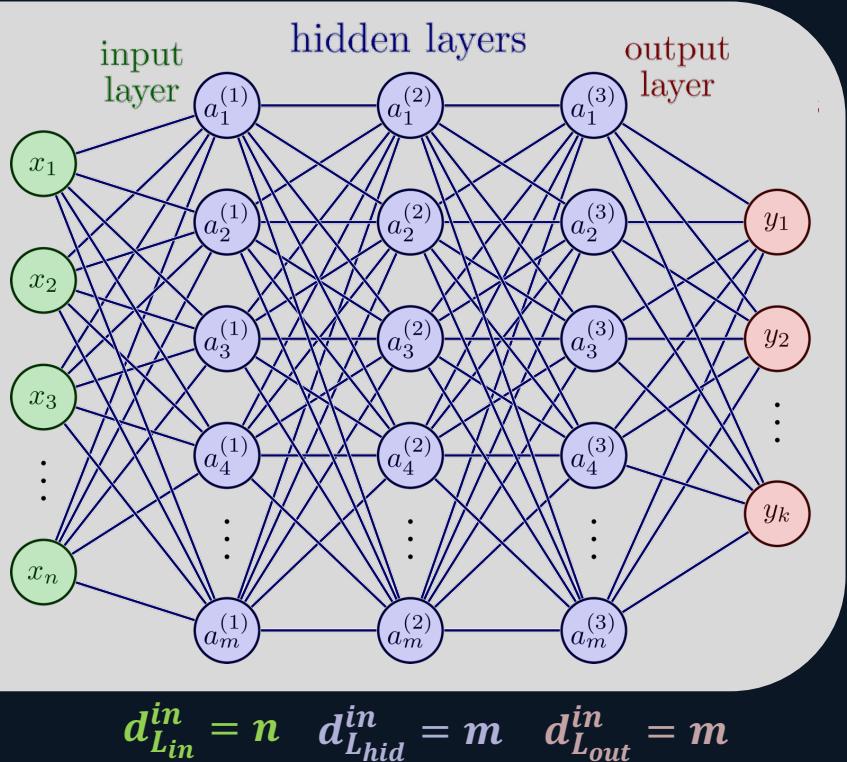
- 2-lepton 2-jet selection, 1 lepton trigger
- Opposite sign electron and muon
- Invariant mass of each lepton-jet pair < 175 GeV
- Tagger discriminant for leading jet

Maximal Update Parametrization



What if we could do HPO on a smaller model instead?

PARAMETRIZATION MATTERS!



Standard Parametrization* (SP)

$$\begin{aligned} w^{L_{in}} &\sim \mathcal{N}\left(0, \frac{1}{d_{L_{in}}^{in}}\right) \\ w^{L_{hid}} &\sim \mathcal{N}\left(0, \frac{1}{d_{L_{hid}}^{in}}\right) \\ w^{L_{out}} &\sim \mathcal{N}\left(0, \frac{1}{d_{L_{out}}^{in}}\right) \\ b^{L_{...}} &= 0 \end{aligned}$$

\forall weights η

Maximal Update Parametrization (μP)

$$\begin{aligned} w^{L_{in}} &\sim \mathcal{N}\left(0, \frac{1}{d_{L_{in}}^{in}}\right) \\ w^{L_{hid}} &\sim \mathcal{N}\left(0, \frac{1}{d_{L_{hid}}^{in}}\right) \\ w^{L_{out}} &\sim \mathcal{N}\left(0, \frac{1}{d_{L_{out}}^{in} \times d_{L_{out}}^{in}}\right) \\ b^{L_{...}} &= 0 \end{aligned}$$

$$\begin{aligned} \eta_{w^{L_{in}}} &= \eta \\ \eta_{w^{L_{hid}}} &= \eta / d_{L_{hid}}^{in} \\ \eta_{w^{L_{out}}} &= \eta / d_{L_{out}}^{in} \end{aligned}$$



INITIALISATION

LR Adam

Maximal Update Parametrization



“Effect of **updates** on activations becomes roughly **independent of width**”

“Each **weight matrix** is **maximally updated** without blowing up”



μP

$$f(x) = V^T U x \text{ with } x \in \mathbb{R} \text{ & } V^T, U \in \mathbb{R}^{n \times 1}$$



SP

$$V_i \sim \mathcal{N}\left(0, \frac{1}{n}\right) \quad U_i \sim \mathcal{N}(0, 1)$$

$$V' \leftarrow V + \theta U \quad U' \leftarrow U + \theta V$$

$$f(x) \leftarrow (V^T U + \theta U^T U + \theta V^T V + \theta^2 U^T V) x$$

By LLN* $\Theta(n)$... blows up

μP

$$V_i \sim \mathcal{N}\left(0, \frac{1}{n^2}\right) \quad U_i \sim \mathcal{N}(0, 1)$$

$$V' \leftarrow V + \frac{\theta}{n} U \quad U' \leftarrow U + \theta V$$

$$f(x) \leftarrow (V^T U + \frac{\theta}{n} U^T U + \theta V^T V + \frac{\theta^2}{n} U^T V) x$$

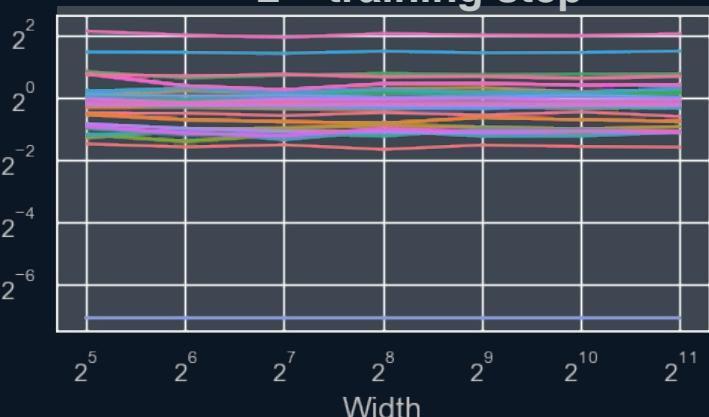
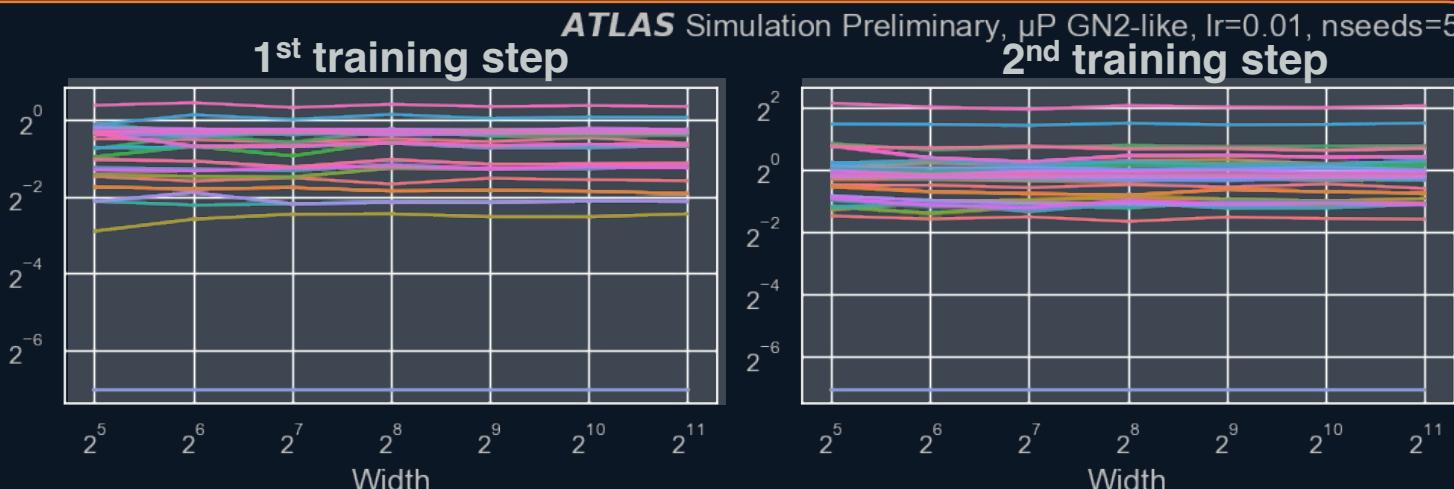
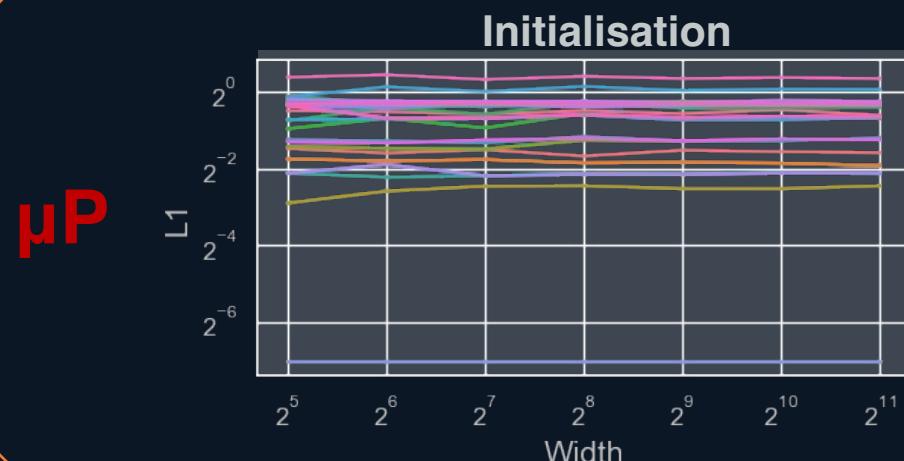
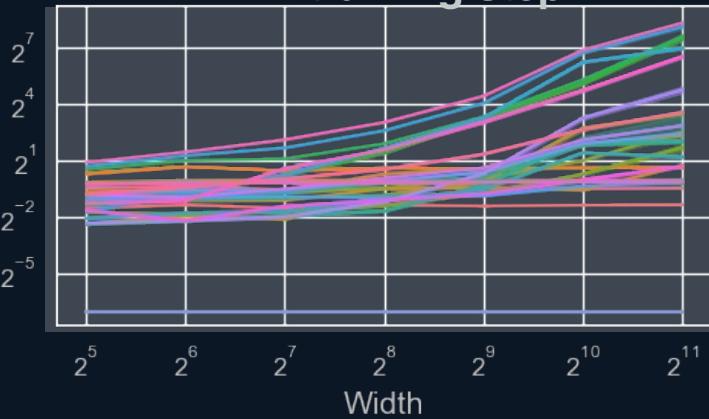
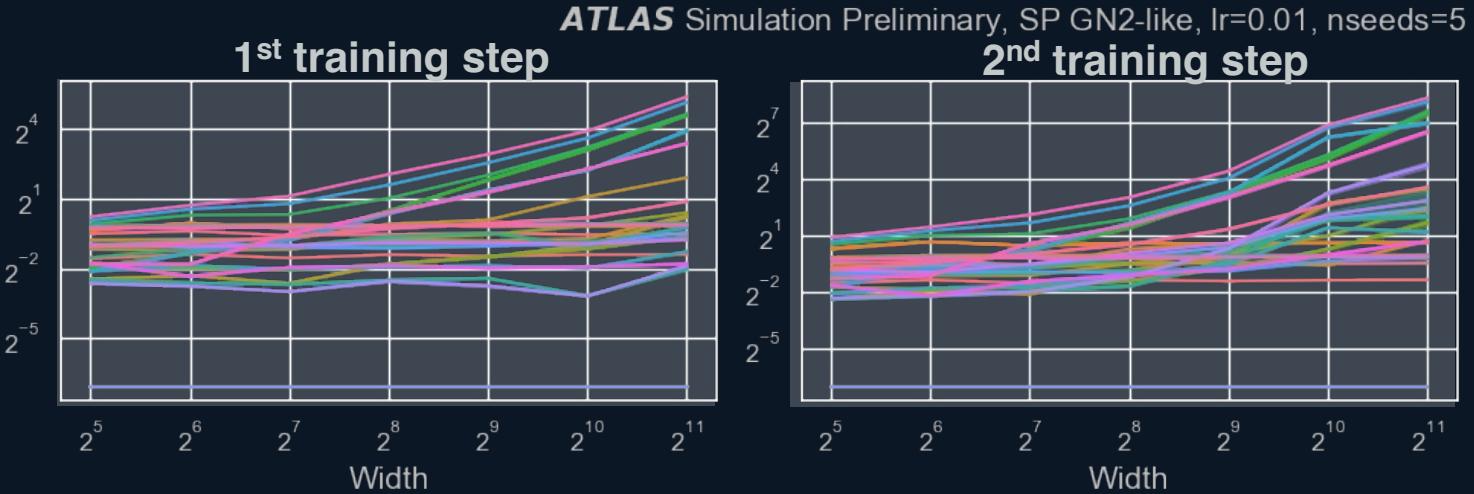
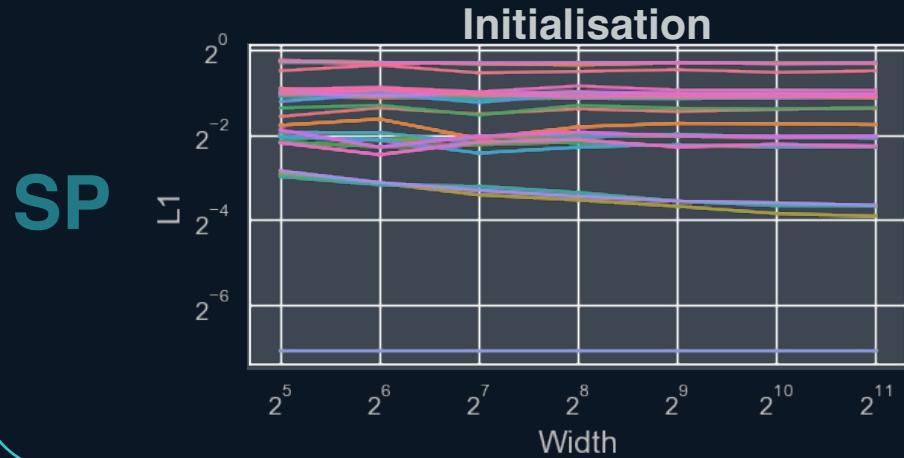
$\Theta(x)$... stable ✓

*Sum of n squared Gaussians of variance 1 is a Chi distribution of degree n

Maximal Update Parametrization

Pre-activation weights $L_1(m) = \sum |w_i^{(m)}|$

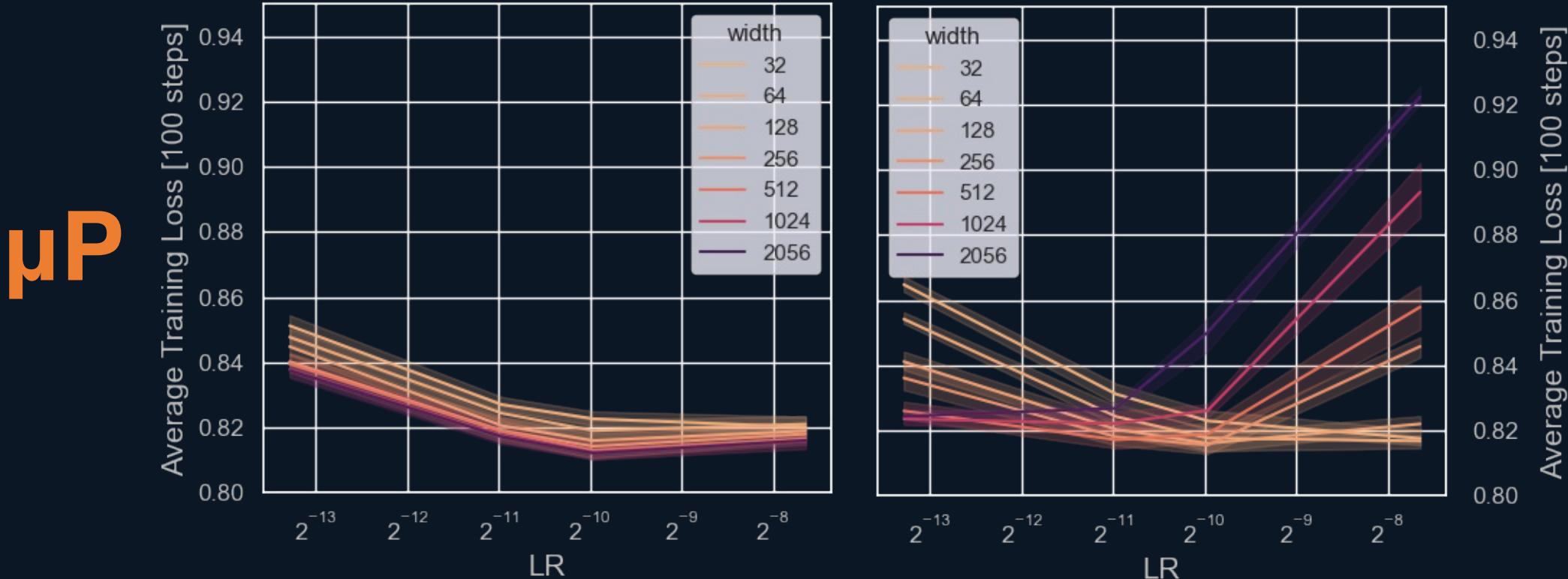
Blows up for SP, stable for μP !



Pathologic Test Case

Fixed LR Value Optimisation on Simplified Architecture

ATLAS Simulation Preliminary, μ P GN2-like, nseeds=5 **ATLAS** Simulation Preliminary, SP GN2-like, nseeds=5

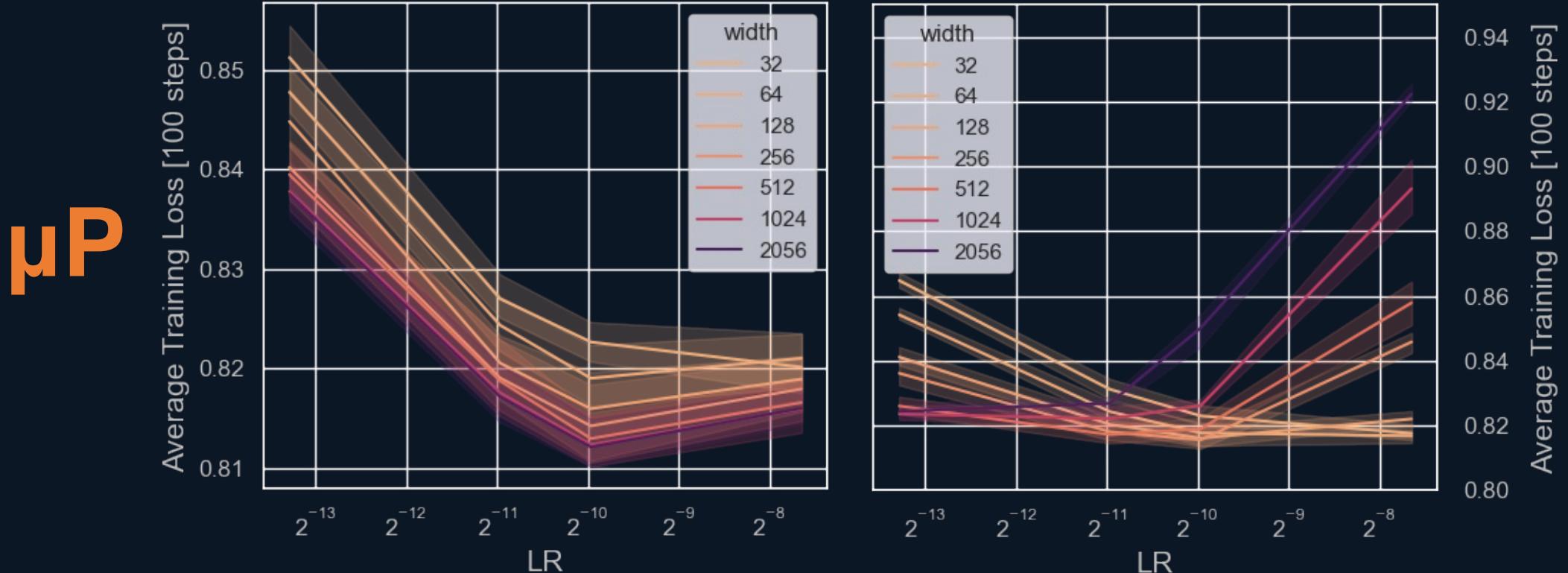


- ✓ μ P models share LR optimum across large widths differences
- ✓ Wider μ P models are better
- ✓ μ P models outperforms SP equivalent
- ✓ SP models do not share LR optimum at different widths

Pathologic Test Case

Fixed LR Value Optimisation on Simplified Architecture

ATLAS Simulation Preliminary, μ P GN2-like, nseeds=5 **ATLAS** Simulation Preliminary, SP GN2-like, nseeds=5



- ✓ μ P models share LR optimum across large widths differences
- ✓ Wider μ P models are better
- ✓ μ P models outperforms SP equivalent
- ✓ SP models do not share LR optimum at different widths

- Many variants under consideration (WIP):
 - lepton,
 - more tracks,
 - hadronic taus,
 - neutral constituents
 - trackless b-tagging with hits
 - more output classes (taus, lep/had b, ...)
 - full vertex reconstruction,
 - mass / energy regression
- Now training on combined MC data for Run3: ~ 300M jets
- Calibration & Trigger ongoing
- GN2X for boosted Higgs tagging ($H(bb)$ & $H(cc)$) vs top and QCD
- Synergies with other groups: Tau tagging, emerging jet tagging, ...