

Playing the devil's advocate to bound hidden systematic uncertainties

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Overview

- Motivation
- Previous works
- Current goals
 - Branching Ratio prediction model
 - Generative model
 - Background finder
 - Reinforcement Learning approach
 - Genetic Algorithm approach



Motivation

- Performing a particle physics analysis involves:
 - simulation
 - thinking about all the backgrounds
 - checking possible mismodellings

 - ... This can lead to **human errors**.
- Our goal is to use **Machine Learning** (ML) to:
 - automatize the workflow
 - improve the accuracy



Previous works: efficiency mismodelling

Previous works on the Devil's Advocate project:

https://link.springer.com/article/10.1140/ epic/s10052-023-11925-w

- Proposal of a new method based on **machine learning** to play the devil's advocate and investigate the **impact of** detector or physics **mismodellings** in a quantitative way
 - Focused on the signal efficiency



Efficiency mismodelling introduced up to a 30% relative bias (on differential Branching Ratio (BR))

Current goals: backgrounds

- Design an algorithm to automatize the procedure of finding the **most problematic backgrounds** (events that mimic the response of the signal in the detector) for a signal specified by the user
- Missing backgrounds have led to confusion in analyses performed in the past
 - Example:

https://journals.aps.org/prd/abstract/10.1103/PhysRevD.108.032002



- R_{K,K*} measurements initially showed **discrepancies** w.r.t. SM predictions (the expected value was 1)
- Statistical fluctuations? Detector or physics mismodellings? New physics?
 - Reason for discrepancy: missing background



Workflow



BR predictions

- Branching Ratio (BR) predictions for decays not present in the Particle Data Group (PDG)
 - Graph Neural Network (GNN) model trained on the PDG data
 - **Graphs** to represent decays
 - Graph is invariant under particle ordering
 - Using a Bayesian architecture to obtain uncertainty on predictions
 - First results seem promising
 - We just need a rough estimate in most cases







Workflow



Generative model: generator level variables

- Given masses of daughter particles, their **momentum distribution** can be estimated to obtain the **kinematic overlap** between signal and background.
- ML is already being used for fast simulation in particle physics, for example, in: <u>https://link.springer.com/article/10.1140/epjc/s10052-022-10258-4</u>.
- Using Monte Carlo as truth.
- Example: $D^- \rightarrow K^0 e^-$ anti- v_e

Variational Autoencoder (VAE) model



Generative model: reconstructed variables

- Detector performance on reconstructed variables can also be modelled with generative models
- Using reconstructed Monte Carlo as target
- Model: Wasserstein Generative Adversarial Network with Gradient Penalty (WGAN-GP)
- Example:
 - Distribution of
 B_plus_ENDVERTEX_CHI2 variable
 - Very good agreement between the sampled and the reco MC



Reward

- **Reward** describes how problematic a background is w.r.t. a signal
- Currently using a toy model for the reward. In the future, ML models previously mentioned will provide input to the agent.





Uncovering of hidden backgrounds

- A nested **for loop** to iterate over the PDG recursively to build all possible decay chains?
 - Impractical. Need a smarter approach.
- Genetic Algorithm (GA) approach
- **Reinforcement Learning (RL)** approach
- GAs perform an efficient exploration while RL allows generalization

Background finder: GAs

- Genetic Algorithm (GA) approach:
 - **AI** technique to solve **optimization** problems. Inspired by evolution process and natural selection theory.
 - Population of individual solutions represented by its genes. Selection of best individuals.
 Combination and mutation to obtain offspring. Iterative process towards an optimal solution.
 - Advantages: Robustness with respect to local maxima or minima. Better results in problems that do not adapt properly to traditional optimization techniques
 - Goal: optimize a fitness function that describes how problematic a background is w.r.t. a signal
 - Individuals are backgrounds

GAs for background finder

- **Genes** of individuals are represented by a **tree structure** that describes the decay chain
- Apart from the traditional **variation processes** (combination and mutation) we introduced custom variation processes:
 - To build **intermediate resonances**

Signal: $B^0 \rightarrow K^{*+}(K^+ \pi^0) \pi^-$

- To make the search more efficiently based on the **physical properties**
- To be able to use **learnt information** in future optimization problems

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Mutation

Combination

Offspring

Background finder: RL

- Reinforcement Learning (**RL**) approach
 - RL is a type of ML where an **agent learns to make decisions** by performing actions in an environment to maximize cumulative rewards.
 - RL is suitable for exponentially growing spaces. Outperforms humans in games like chess and Go.
 - Goal: **train a ML model** that can successfully **predict** the most problematic backgrounds for new signals. Agent will learn the decay modes.

RL approach

Token: element of a sequence that needs to be converted into numerical data to provide input to a language model

- **State** will be described by a sequence of tokens
 - State is initialized with the information of the signal
- Agent will predict one token in each step, filling up the information of the background
- We can deal with **intermediate resonances**, **misidentifications** and **partially reconstructed backgrounds** with a few tokens.
- Example:

• Signal:
$$B^0 \rightarrow K^+ \pi^0 \pi^-$$

• Background: $B^+ \rightarrow K^{*+}(K^+ \pi^0 \pi^- K^-)$

 π^+ is not detected

RL strategy

- Agent: transformers are an ideal architecture for dealing with tokenized sequences
- Action masking is applied to mask the tokens that do not make sense for the current state
- **Pretraing of** the agent to improve learning
- Playing a complete game on a **GA suggestion** with the desired frequency during training of agent
 - **Guided search** to reach high rewards

Pretraining: example

- The agent can be pretrained in a supervised way to **output possible backgrounds** given a signal.
- This also makes the agent **learn how to build decay sequences** that make sense
- Example:

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• Signal:

 $B^{+} \rightarrow \pi^{+} \text{ anti-}D^{0}(K^{+} \pi^{-})$ Background: $B^{+} \rightarrow \pi^{+} \text{ anti-}D^{0}(K^{+} \pi^{-} \pi^{0})$ Most problematic background correctly predicted

Experiments

- 50 signals analyzed
- Target: 4 most problematic backgrounds (hall of fame) of each signal
- Technique: Genetic Algorithms
 - Population of 1.000 individuals and evolution of 40 generations
- Results:

	Experiment 1	Experiment 2
Space size	~ 1.000.000	<i>≃</i> 300.000.000
Explored space	4.7%	0.04%
Found backgrounds	99.5%	71%

- Example:
 - Signal: $B^- \rightarrow e^- \text{ anti-} v_e D^0(\pi^+ K^- pi^0)$
 - Hall of fame (according to toy model reward):
 - $\blacksquare \quad B^{-} \to e^{-} \operatorname{anti-v}_{e} D^{*0}(\pi^{0} \operatorname{D0}(\pi^{+} \operatorname{K}^{-}))$
 - $\blacksquare \quad B^{-} \to e^{-} \pi^{0} \text{ anti-} v_{e} D^{0}(\pi^{+} K^{-})$

GAs are performing a very efficient search

$$B^{-} \to \mu^{-} \operatorname{anti-v}_{\mu} D^{0}(\pi^{+} \mathrm{K}^{-} \pi^{0})$$

$$B^{-} \to \mu^{-} \operatorname{anti-v}_{\mu} D^{*0}(\pi^{0} \mathrm{D}^{0}(\pi^{+} \mathrm{K}^{-}))$$
²³

Conclusions

- Goal:
 - Design an algorithm that can successfully find the most problematic backgrounds to:
 - **accelerate the workflow** in particle physics
 - avoid human errors.
- Results:
 - The **performance** of each of the models involved seems to be very **promising**
- What is next?
 - Improve the performance of each of the models as much as possible
 - RL/GAs:
 - Implement/improve variation processes to make the search more efficient
 - Increase gradually the complexity of the problem, and explore each of the approaches to identify their weak spots
 - **GAs and RL** can be **combined** to overcome these weak spots
 - GAs perform an efficient exploration while RL allows generalization
 - Wrap all 3 subprojects together in order to apply this tool to **real case scenarios**

Thank you very much for your attention

Auxiliar slides

Motivation

https://arxiv.org/pdf/2212.09153

- Lepton Flavour Universality (LFU) test initially showed discrepancies w.r.t. SM predictions
- Statistical fluctuations? Detector or physics mismodellings? New physics?

$$R_{K^{(*)}} = \frac{\mathcal{B}(B \to K^{(*)}\mu\mu)}{\mathcal{B}(B \to K^{(*)}ee)}$$

Reward/fitness function

- **Backgrounds** give a similar response to the signal in the detector
- The **reward/fitness function** describes how problematic a background is w.r.t. a signal
- The reward/fitness function takes into account several factors:
 - BR of the background: **Probability** to see this certain decay.
 - misID factor: Possible **misidentifications** of particles
 - PartReco factor: To deal with **partially reconstructed backgrounds** (some particles might not be detected)
- Currently a toy model for the reward/fitness function is being used:
 - BR is read from **decay.dec** file
 - Apply a penalty for every **misID**. Consider misIDs just between particles of same charge
 - Apply a penalty for every **not detected particle**. Number of detected particles in signal and background needs to be the same
- In the future, the ML models previously mentioned will provide input to the agent

Tokenization

- Tokens for representing particles
- Index tokens: $\{1, 2, ..., N_s\} \rightarrow N_s$ tokens (N_s = number of final state particles in signal)
- Token for)
- Token for "END"
- Token for "LOST"

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- Token for separating signal and background (not an action)
- Token to represent elements with a not assigned token (not an action)

"LOST" and "index tokens" are related to the next token in the sequence and allow to describe misID and Part. Reco.

Example:

K⁻ and π ⁻ are misidentified

 π^+ is not detected

Signal: $B^0 \to K^+ \pi^- \pi^0$ Background: $B^+ \to K^{*+}(1 K^+ 3 \pi^0)$ LOST $\pi^+ 2 K^-$ END

Interesting points:

- We can deal with **intermediate resonances**, **misidentifications** and **partially reconstructed backgrounds** with a few tokens.
- Tokens (and thus actions in RL) are O(N). For example, actions like $pi^+ < -> K^+$ would be $O(N^2)$.
- We can exploit a lot the **masking** of actions/tokens. For example, if last predicted token was "LOST", then we can mask all other actions that are not final state particles

Genetic Algorithms (GAs)

- AI technique to solve optimization problems
- Inspired by **evolution process** and **natural selection theory**
- Population of individual solutions represented by its **genes**. Selection of best individuals. **Combination** and **mutation**. Iterative process towards an optimal solution.
- Some advantages:
 - Robustness with respect to local maxima or minima
 - Better results in problems that do not adapt properly to traditional optimization techniques

Genetic Algorithms (GAs)

Example:

$$f(x,y) = \left(\sum_{n=1}^{5} n \, \cos[n + x(n+1)]\right) \left(\sum_{n=1}^{5} n \, \cos[n + y(n+1)]\right)$$

https://drive.google.com/file/d/1OWyJNH0tnq4um7fEk UvOwZIG2oyjckRg/view?usp=sharing

Resonance creation

- Some genes are randomly selected to create an intermediate resonance
- The charge of the intermediate particle is computed from the selected genes, and an intermediate particle of this charge is randomly suggested
- Example:

Arrival

- Introduce into the population random individuals in each generation
 - The purpose is to be able to explore more, and to not depend that much on the initialization of the algorithm
 - Arrivals are only considered in case an individual did not suffer combinations, mutations or a resonance creation \Rightarrow We are not increasing the population size

Current population genes:

Inheriting from the signal

- With a certain probability the genes of the signal will be cloned instead of cloning an individual from the current population
- This allows to explore more the region of the space near the signal, which is more likely to have problematic backgrounds Signal:

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Previous experience learning

- When an individual has a non zero fitness value, and has an intermediate resonance in its genes that was never seen before, the GA "learns" this is a valid intermediate resonance for future games.
- With a certain probability, the genes of the individual are analyzed, and from all intermediate resonances that are possible for these genes one is randomly suggested

Experiment 1

- Description:
 - Set of particles: 4 mother particles, 10 intermediate particles, 18 daughter particles
 - Number of daughter particles in signal: 5
 - Hall of Fame size: 4
 - 2 intermediate resonances at most
 - 0 lost particles at most
 - Technique: Genetic Algorithms
 - Population of 1.000 individuals and evolution of 40 generations
- Results:
 - 50 signals were analyzed. Example: $B^- \rightarrow e^-$ anti- $v_e D^0(\pi^+ K^- pi^0)$
 - 99.5% of backgrounds were found
 - Space size:
 - Space size: 851.200
 - Number of individuals: 40.000
 - 4.7% of space explored at most

Experiment 2

- Description:
 - Set of particles: 4 mother particles, **10** 18 intermediate particles, 18 daughter particles
 - Number of daughter particles in signal: 5
 - Hall of Fame size: 4
 - 2 intermediate resonances at most
 - **θ 1** lost particles at most
 - Technique: Genetic Algorithms
 - Population of 1.000 individuals and evolution of 40 generations
- Results:
 - 50 signals were analyzed. Example: $B^- \rightarrow e^-$ anti- $v_e D^0(\pi^+ K^- pi^0)$
 - 71% of backgrounds were found
 - Space size:
 - Space size: ~ 310.000.000
 - Number of individuals: 120.000
 - 0.04% of space explored at most