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Solving a Feynman integral depending on two elliptic
curves: the 5 mass Kite family

or how to solve an integral by (almost) never integrating

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based on 2401.14307 with Mathieu Giroux, Andrzej Pokraka and Franziska Porkert

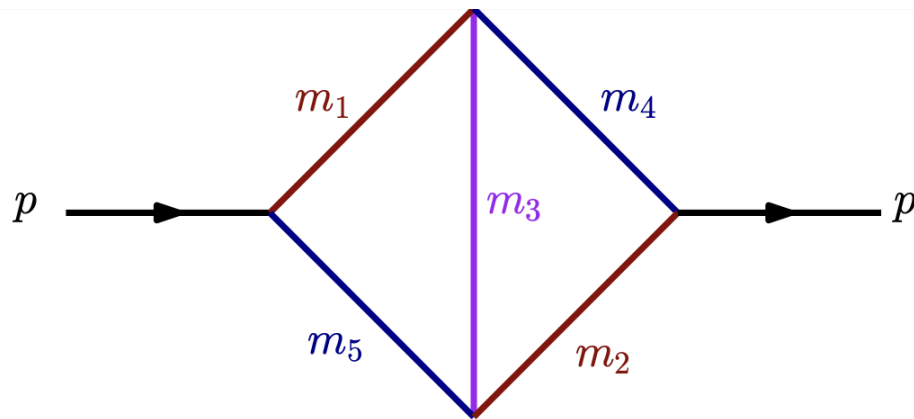
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Feynman Integrals (FI)

- **Applications:** **Perturbative** expansion of **QCD**, **Black Hole** Scattering, **EFT** of Large Scale-Structures...

- Most solved **FIs** evaluate to **multiple polylogarithms (MPLs)**,

From 2-loops this is isn't enough [[Bloch, Vanhove, 1309.5865](#)]



- Most general 2-point, 2-loop **FI**
- Dependent on **elliptic MPLs**
- Mixes two different **elliptic curves**
- The first **elliptic FI** involving > 3 scales

Differential Equations [Kotikov, 1991]

- State of the art is to set up a set of **MI**s and find an associated Deq:

$$d\mathbf{MI}s = \mathcal{A}(D, p^2, m_i^2, dp^2, dm_i^2) \mathbf{MI}s; \quad D = 2 - 2\epsilon$$

- We try to find the “**canonical form**” to this equation through the gauge transformation $\mathbf{U} \cdot \mathbf{MI}s := \mathbf{J}$ s.t. [Henn, 1304.1806]:

$$d\mathbf{J} = \underbrace{\epsilon \tilde{\mathcal{A}}(p^2, m_i^2, dp^2, dm_i^2)}_{\epsilon \text{ independent}} \mathbf{J} \quad \rightarrow \quad \mathbf{J} = \mathbb{P} \exp \left[\epsilon \int_{\gamma} \tilde{\mathcal{A}} \right] \mathbf{J}_0$$

- \mathbf{U} will depend on the Periods of **both** elliptic curves:

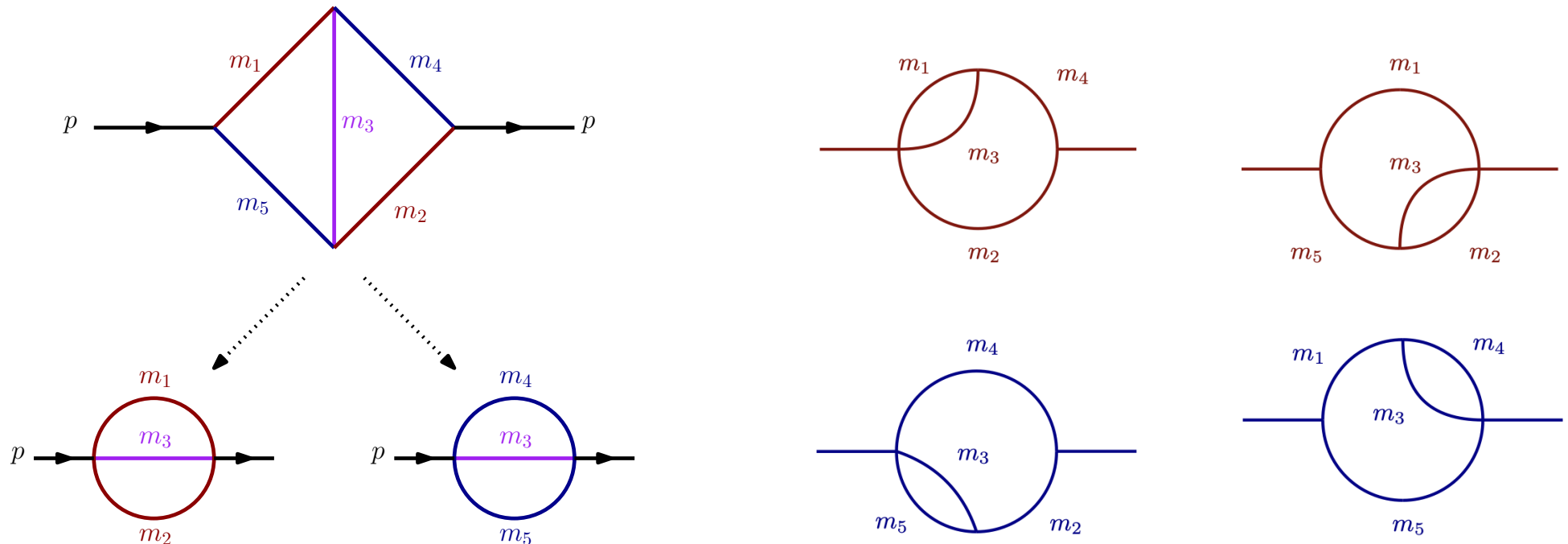
$$\psi_1(p^2, m_1, m_2, m_3) \propto \int dx ((x - r_1)(x - r_2)(x - r_3)(x - r_4))^{-1/2}$$

$$\psi_1(p^2, m_3, m_4, m_5) \propto \int dx ((x - q_1)(x - q_2)(x - q_3)(x - q_4))^{-1/2}$$

The Kite integral family

- The Kite integral family has **30 Master Integrals**, most notably:

$$\text{MIs} = \left(\underbrace{\dots, I_{111100}, I_{211100}, I_{121100}, I_{111200}, I_{001111}, I_{002111}, I_{001211}, I_{001112},}_{\text{existing results [Bogner, Müller-Stach, Weinzierl, 1907.01251]}} \right. \\ \left. \underbrace{I_{111110}, I_{111101}, I_{011111}, I_{101111}, I_{111111}}_{\text{our results}} \right)$$



The Kite integral family

- The differential equation organises into **blocks**¹:

$$\begin{array}{c}
 \left(\begin{array}{c}
 I_{11100} \\
 I_{21100} \\
 I_{12100} \\
 I_{11200} \\
 I_{00111} \\
 I_{00211} \\
 I_{00121} \\
 I_{00112} \\
 I_{11110} \\
 I_{11111}
 \end{array} \right)
 \end{array}
 =
 \begin{array}{c}
 \left(\begin{array}{cccccccccc}
 \mathcal{A}_{1,1} & \mathcal{A}_{1,2} & \mathcal{A}_{1,3} & \mathcal{A}_{1,4} & 0 & 0 & 0 & 0 & 0 & 0 \\
 \mathcal{A}_{2,1} & \mathcal{A}_{2,2} & \mathcal{A}_{2,3} & \mathcal{A}_{2,4} & 0 & 0 & 0 & 0 & 0 & 0 \\
 \mathcal{A}_{3,1} & \mathcal{A}_{3,2} & \mathcal{A}_{3,3} & \mathcal{A}_{3,4} & 0 & 0 & 0 & 0 & 0 & 0 \\
 \mathcal{A}_{4,1} & \mathcal{A}_{4,2} & \mathcal{A}_{4,3} & \mathcal{A}_{4,4} & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & \mathcal{A}_{5,5} & \mathcal{A}_{5,6} & \mathcal{A}_{5,7} & \mathcal{A}_{5,8} & 0 & 0 \\
 0 & 0 & 0 & 0 & \mathcal{A}_{6,5} & \mathcal{A}_{6,6} & \mathcal{A}_{6,7} & \mathcal{A}_{6,8} & 0 & 0 \\
 0 & 0 & 0 & 0 & \mathcal{A}_{7,5} & \mathcal{A}_{7,6} & \mathcal{A}_{7,7} & \mathcal{A}_{7,8} & 0 & 0 \\
 0 & 0 & 0 & 0 & \mathcal{A}_{8,5} & \mathcal{A}_{8,6} & \mathcal{A}_{8,7} & \mathcal{A}_{8,8} & 0 & 0 \\
 \mathcal{A}_{9,1} & \mathcal{A}_{9,2} & \mathcal{A}_{9,3} & \mathcal{A}_{9,4} & 0 & 0 & 0 & 0 & \mathcal{A}_{9,9} & 0 \\
 \mathcal{A}_{10,1} & \mathcal{A}_{10,2} & \mathcal{A}_{10,3} & \mathcal{A}_{10,4} & \mathcal{A}_{10,5} & \mathcal{A}_{10,6} & \mathcal{A}_{10,7} & \mathcal{A}_{10,8} & \mathcal{A}_{10,9} & \mathcal{A}_{10,10}
 \end{array} \right)
 \cdot
 \begin{array}{c}
 \left(\begin{array}{c}
 I_{11100} \\
 I_{21100} \\
 I_{12100} \\
 I_{11200} \\
 I_{00111} \\
 I_{00211} \\
 I_{00121} \\
 I_{00112} \\
 I_{11110} \\
 I_{11111}
 \end{array} \right)
 \end{array}
 \end{array}$$

¹we only display some of the sectors

The Eyeball integral family

$$\text{Ansatz: } d \underbrace{\left(\frac{I_{111110}}{I_{11110}^{(0)}} + F \tilde{I}_{11110} \right)}_{\text{new master Integral } \tilde{I}_{11110}} = \epsilon(\dots)$$

- where $I_{11110}^{(0)}$ is the **Maximal Cut**, determining F is the actual challenge and requires the definition of the **Moduli space**:

$$(p^2, m_1^2, m_2^2, m_3^2, m_4^2, m_5^2) \rightarrow \underbrace{(\tau, z_1, z_2, z_3)}_{\text{known result}}, \underbrace{(z_4, z_5)}_{\text{new method!}}$$

- with a **Jacobian**:

$$\begin{pmatrix} d\tau \\ d\vec{z} \end{pmatrix} = \begin{pmatrix} \frac{\partial \tau}{\partial p^2} & \frac{\partial \tau}{\partial \vec{m}^2} \\ \frac{\partial \vec{z}}{\partial p^2} & \frac{\partial \vec{z}}{\partial \vec{m}^2} \end{pmatrix} \begin{pmatrix} dp^2 \\ d\vec{m}^2 \end{pmatrix}$$

The Eyeball integral family

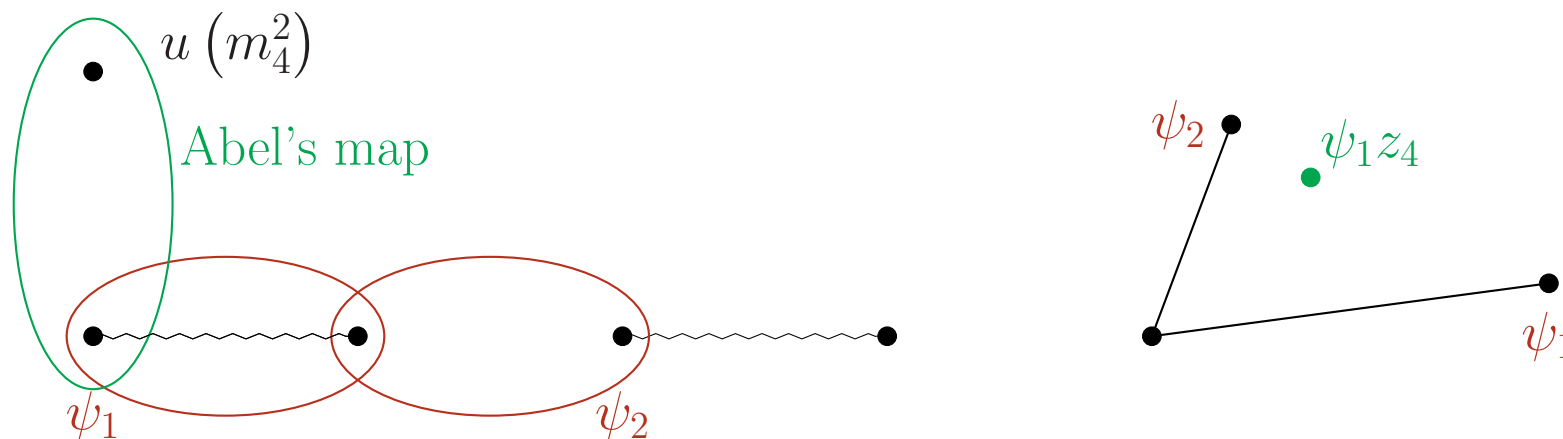
- F can be shown to be expressed as (with $f(\dots)$ some rational function):

$$F = \left(f(m_1^2) \frac{\partial m_1^2}{\partial \tau} + f(m_2^2) \frac{\partial m_2^2}{\partial \tau} + f(p^2) \frac{\partial p^2}{\partial \tau} + f(m_4^2) \frac{\partial m_4^2}{\partial \tau} \right) \psi_1 \frac{\partial \tau}{\partial p^2}$$

- We should find how m_4 maps to the torus! We find a natural candidate:

$$\int_0^{m_4^2} dm_4'^2 I_{11110}^{(0)} = \int_0^{m_4^2} \frac{dm_4'^2}{\sqrt{P_4(m_4'^2)}} = \psi_1 z_4$$

- This turns out to be **Abel's map** (inverse of $\wp(z)$) for our torus!



The Kite integral family

- The **Kite** integral follows the following differential equation:

$$dI_{11111} = \mathcal{A}_{10,10}^{(0)} I_{11111} + \mathcal{A}_{10,1}^{(0)} \tilde{I}_{11100} + \mathcal{A}_{10,4}^{(0)} \tilde{I}_{00111} + \epsilon(\dots)$$

- Analogously to the **Eyeballs**, make the ansatz:

$$d \underbrace{\left(\frac{I_{11111}}{I_{11111}^{(0)}} + F_1 \tilde{I}_{11100} + F_2 \tilde{I}_{00111} \right)}_{\text{new master Integral } \tilde{I}_{11111}} = \epsilon(\dots)$$

- F_1 and F_2 can be determine as before since we can compute $\frac{\partial m_4^2}{\partial \tau(11100)}$,

$$\frac{\partial m_5^2}{\partial \tau(11100)}, \frac{\partial m_4^2}{\partial \tau(00111)} \text{ and } \frac{\partial m_5^2}{\partial \tau(00111)}$$

The solution

- The **Kite** integral family follows the following **canonical** differential equation:

$$d \begin{pmatrix} \vdots \\ \tilde{I}_{111111} \end{pmatrix} = \epsilon \tilde{\mathcal{A}} \begin{pmatrix} \vdots \\ \tilde{I}_{111111} \end{pmatrix}$$

- The entries of $\tilde{\mathcal{A}}$ are either **rational functions** with simple poles or “**elliptic**” functions $g^{(\alpha)}(\sum_i a_i z_i, \tau)$ on **either** torus with simple poles which are related to θ -functions through:

$$\sum_{\alpha=0}^{\infty} \eta^{\alpha-1} g^{(\alpha)}(z, \tau) = \pi \frac{\theta_1'(0, \tau) \theta_1(\pi(z + \eta), \tau)}{\theta_1(\pi z, \tau) \theta_1(\pi \eta, \tau)}$$

Conclusion and Outlook

- Opens the door to study more **multi-scale FIs** beyond **MPLs**
- Understanding how to find **Moduli space** $\mathcal{M}_{1,5}$ is **crucial**
- Structure of differential equation **never mixes elliptic curves**, what would happen for **FIs** in which they do? [[Müller, Weinzierl, 2205.04818](#)]
- Characterising the **Moduli** of more complicated geometries is an open problem!

Thank you for your attention !