

# LHC BWS Mechanics

BWS project team meeting

13/6/2023

# Action in progress since the last meeting

- Build 2 additional Hybrid+ designs for installation in YETS23-4
  - Modified bellows extremity incorporating a mini-conflat(?) and support for the cable connector
  - No change to the fork/wire design
  - No change(?) to the bellows design – perhaps use recovered bellows?
- Work on the assumption that the Hybrids designs installed in LS2 can be considered ‘operational’ by YETS23-4
  - This means we are free to choose the best locations for the new Hybrid+ instruments

# Fully consolidated design status

- ML still not able to fully commit to working on this design
  - SPS and LHC operational wire scanner issues are more urgent
  - Teresa still not out of the SPS-BGI production launch, but hopes to be (~fully) available in 2 weeks
  - New Quest will be Autumn 2023 earliest

# Fully consolidated design development tasks

## SLAC-type double bellows design

- Mass-optimisation for drive
- 45 degree design issues
- Impedance design due to 'double-sided' fork

## BAT coupled drive design

- BAT development
- In-vacuum position sensor development
- [45 degree design issues]
- [Impedance design due to 'double-sided' fork]

## 'Optional' common development tasks

- Linear motor, either for SLAC or BAT design
- Wire 'card' for CNT-type wires

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2/5/2023

# Some 'definitions'

- Hybrid design

- 2 instruments currently installed in the LHC
- Compatible with the LIU control system
- Using the existing support and infrastructure
- 0/90 measurement configuration
- Ball screw drive and encoder
- All vacuum components (bellows, fork assemblies, feedthroughs) unchanged

- Hybrid+ design

- Nothing currently installed in the LHC
- Compatible with the LIU control system
- Using the existing support and infrastructure
- 0/90 measurement configuration
- Ball screw drive and encoder
- Re-design fork assemblies and feedthrough
- Magnetically coupled drive depends on ongoing development

- Full Consolidated design

- Nothing currently installed in the LHC
- Compatible with the LIU control system
- New support design
- 45 degree measurement configuration?
- Drive and fork position system to be decided
- Fork assembly and feedthrough to be decided
- Drive coupling (bellows/magnetic?) and (linear?) motor to be decided

# Current list of 'urgent' questions

- Do we agree on the hybrid strategy that:
  - We aim to consider the 2 'Hybrid' instruments as available for operations by end 2023
  - We aim to build and install 2 additional 'Hybrid+' designs, replacing 2 'legacy' designs for YETS 23-4
- As a strategy for the Fully consolidated design...
  - We design and build a linear motor test bench
    - Procure one or more linear drives to test technology
  - We design and build a 45° tank
    - Do we install it in the SPS, LHC in YETS23-4 or just on a test bench?
  - Position sensor R&D
    - Depends on magnetically or bellows coupled