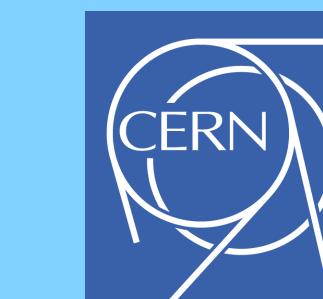
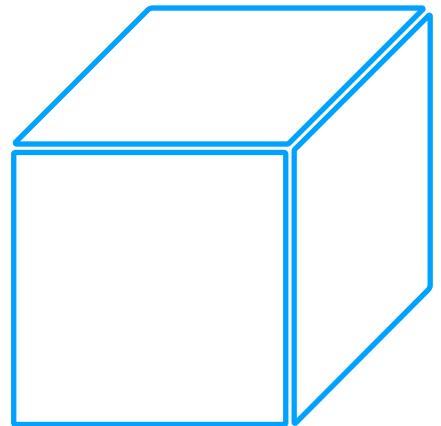


Geometry module



A. Salzburger (CERN) for the ACTS project

Selected Core modules

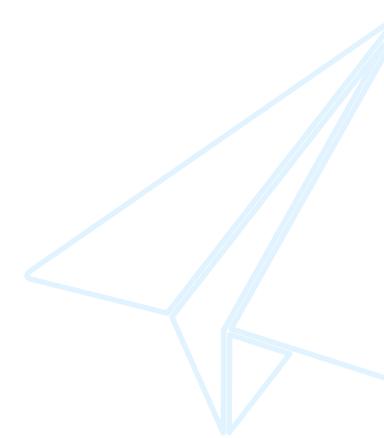


Geometry/Detector*
(Surface based geometry)

Plugins to DD4hep, TGeo, etc.



Event Data Model
target track reconstruction
backend separation
with different I/O models



Propagation
parameter + covariance
transport through
magnetic field



Seeding
Seed finding with
Triplet seeder,
OrthogonalSeedFinder



Track Fitting
parameter estimation
with Kalman Filter,
GSF, GX2F**



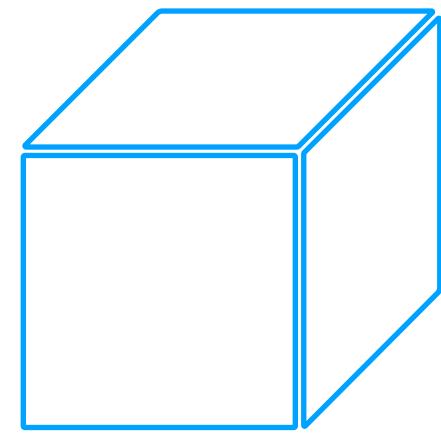
Combinatorial track finding
Combinatorial Kalman Filter
for track finding



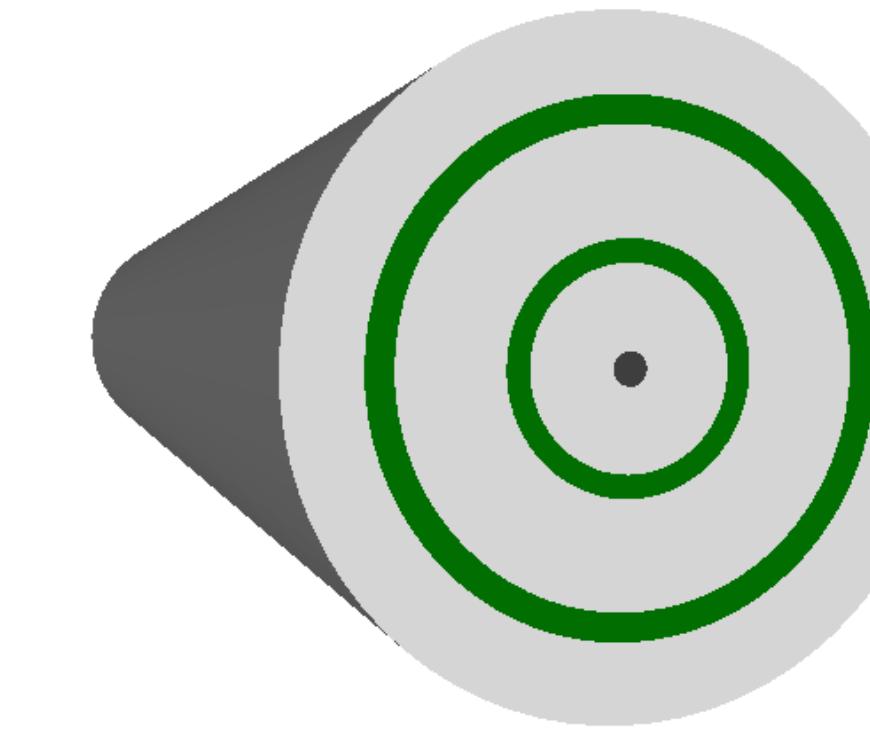
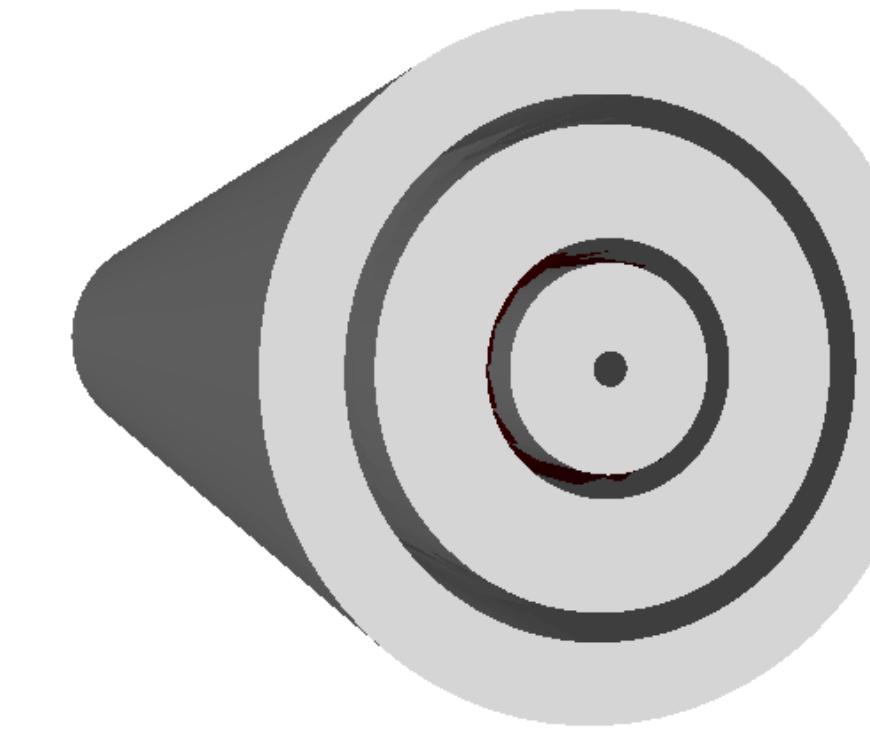
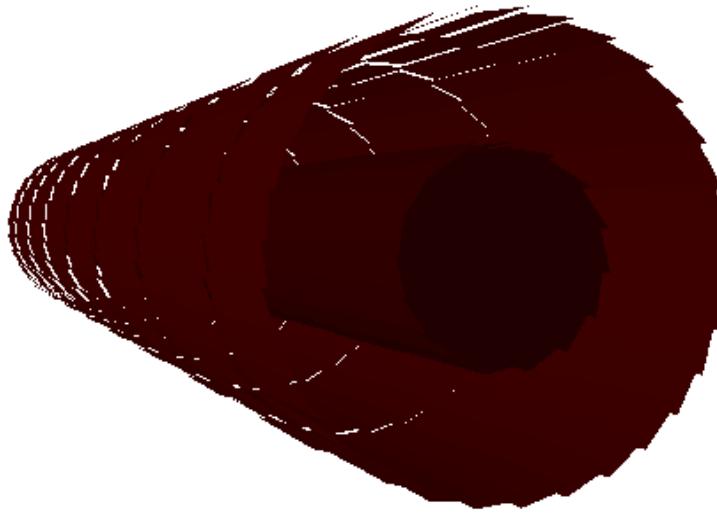
Vertex finding + fitting
Iterative, multi variant
primary vertex finders
and fitters



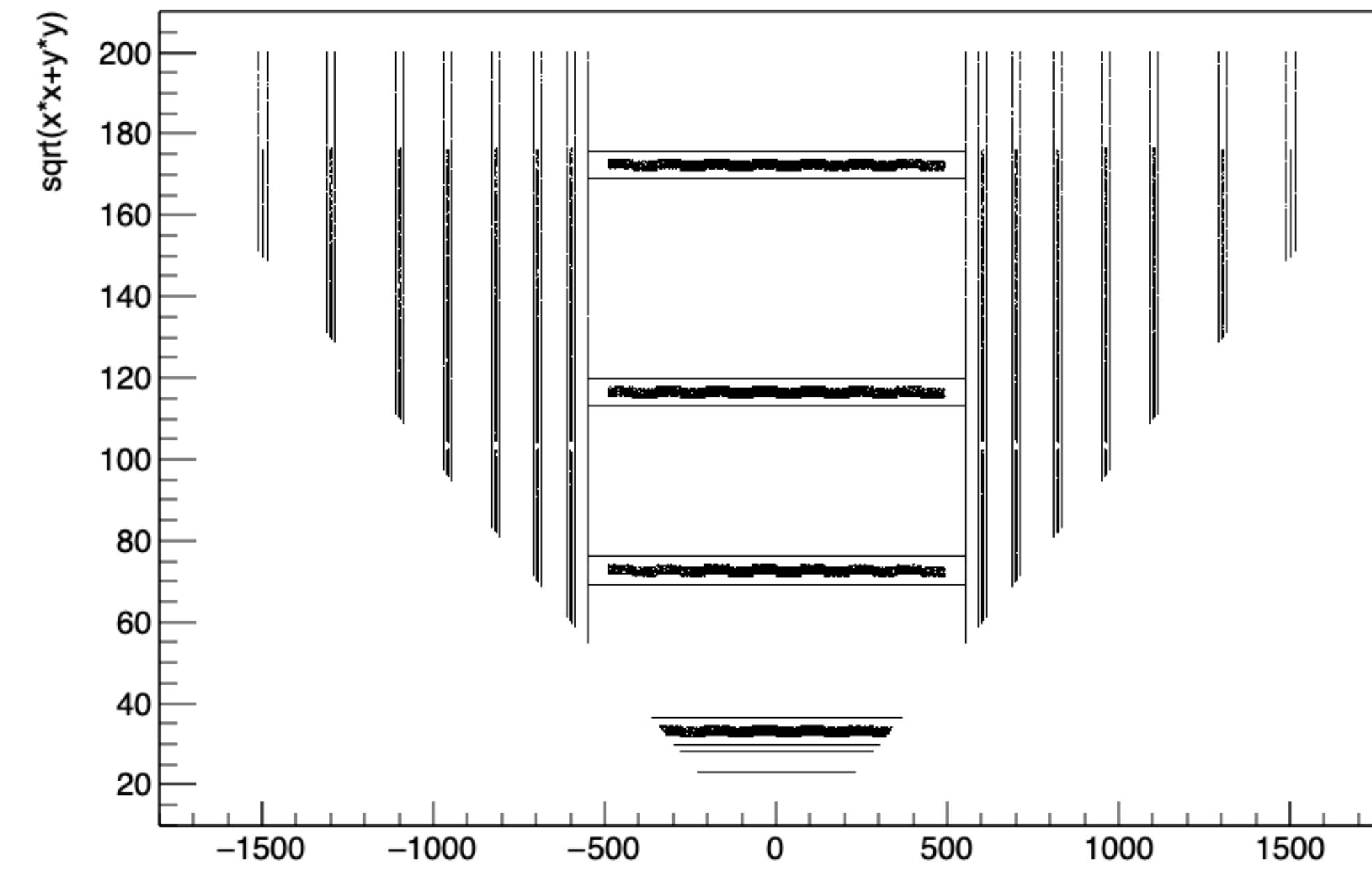
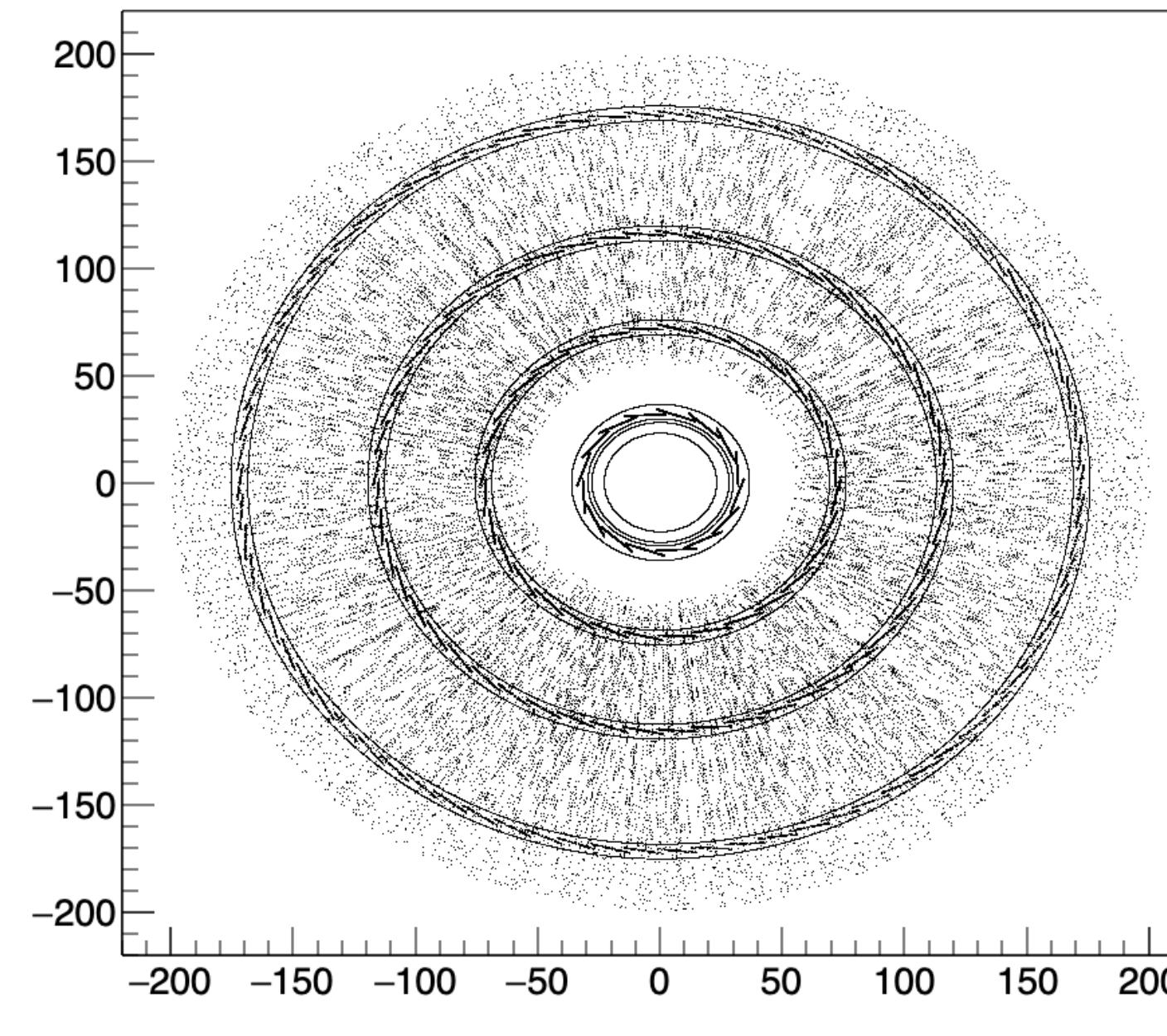
Detector alignment
KF based alignment
functionality

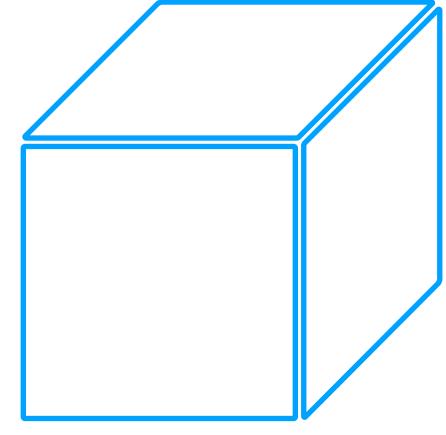


Geometry + Navigation



Surface based geometry model, optimised for reconstruction,
can be **connected to standard HEP geometry modellers**





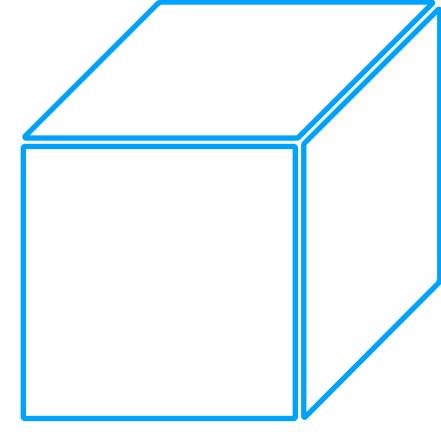
Geometry + Interfacing

connected to standard HEP geometry modellers



Detailed geometry model,
e.g. DD4hep, TGeo, GeoModel, etc.

ACTS geometry model
with built-in navigation



New Acts::Detector model

detray geometry was developed w/o layers

- **this worked**, developed a new, alternative geometry model for Acts/Core as well

Geometry | Surface - Layer - Volumes

Layers with sub structure have a volume-like feel already

```
/// Return the abstract volume that represents the layer
///
/// @return the representing volume of the layer
const AbstractVolume* representingVolume() const;
```

can be represented by a volume

```
/// return the LayerType
LayerType layerType() const;
```

To represent the internal structure of the layers

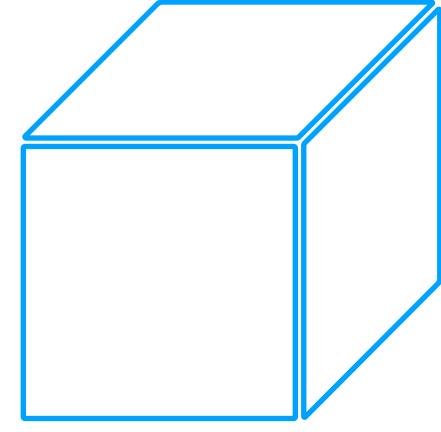
Geometry | Surface - Layer - Volumes

Consequence: Navigator code is complicated & brittle

Navigator	
LOC	760
Comments	452

Suggestion: Remove Layer concept & only glue volumes with internal structure

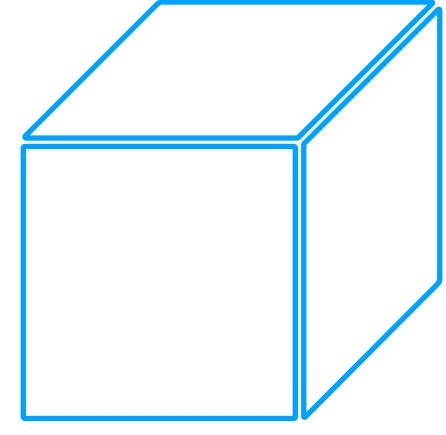
Nov. 2022



New Acts::Detector model - glossary

This geometry is currently still under the **Experimental** namespace

Acts::Surface	Acts::Surface	Surface objects are unchanged, allows client code to be untouched
Acts::Layer		Layer objects do not exist anymore, they are represented by volumes
Acts::TrackingVolume	Acts::Experimental::DetectorVolume	Double serving of volumes as containers or navigation volumes omitted
Acts::BoundarySurfaceT<Acts::TrackingVolume>	Acts::Experimental::Portal	Portal objects are not templated anymore, they are holder classes of surfaces and volume switches
Acts::TrackingGeometry	Acts::Experimental::Detector	Portal objects the top level entry point that will guide into the root volumes



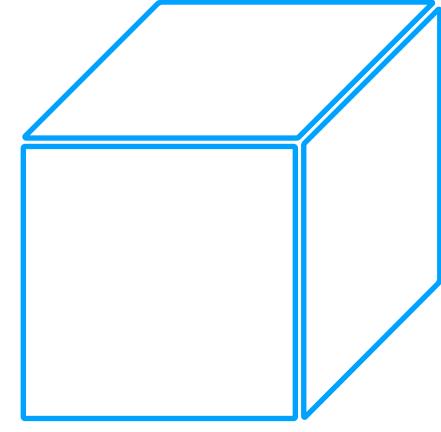
Acts::Detector features (1)

Navigation paradigm shift

- **DetectorVolume** carries a navigation delegate that provides candidate surfaces (i.e. sensitive, passive, portal surfaces) to the propagator
- Allows to switch navigation strategy in different parts of the detector
- Used for ATLAS Muon System geometry templating (see Tomohiros' talk tomorrow)

Detector building const correctness

- Dedicated care for const correctness in the detector building
(TrackingGeometry building is a bit bit of a mess in this respect)
- Strategy: non-const objects until the **final Detector class** is built, only **const access** afterwards



Acts::Detector features (2)

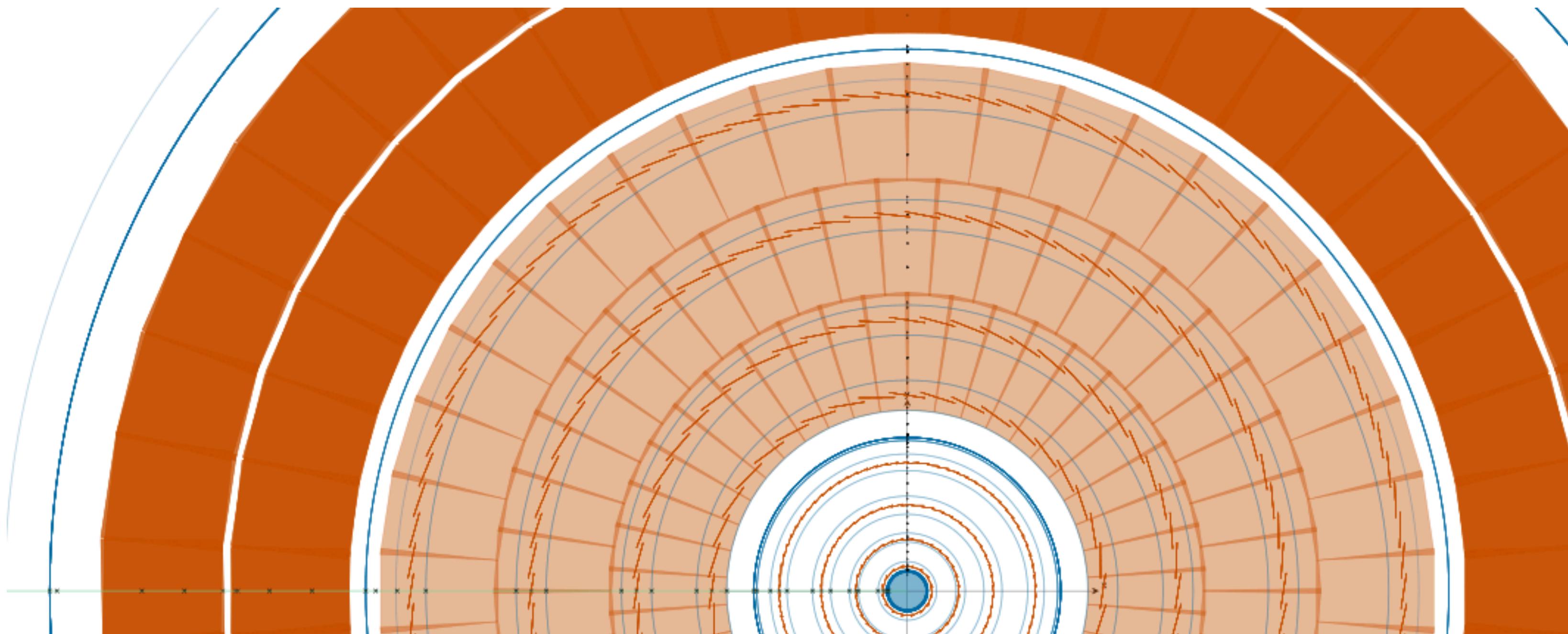
Json writing and reading

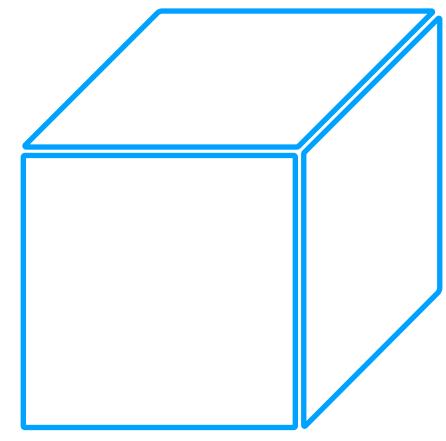
- **Full detector** can be written to Json file and back, including navigation structure
- Possible through indexed based navigation structures

Json export to detray

- Dedicated `toJsonDetray(...)` function to write the detector in detray format

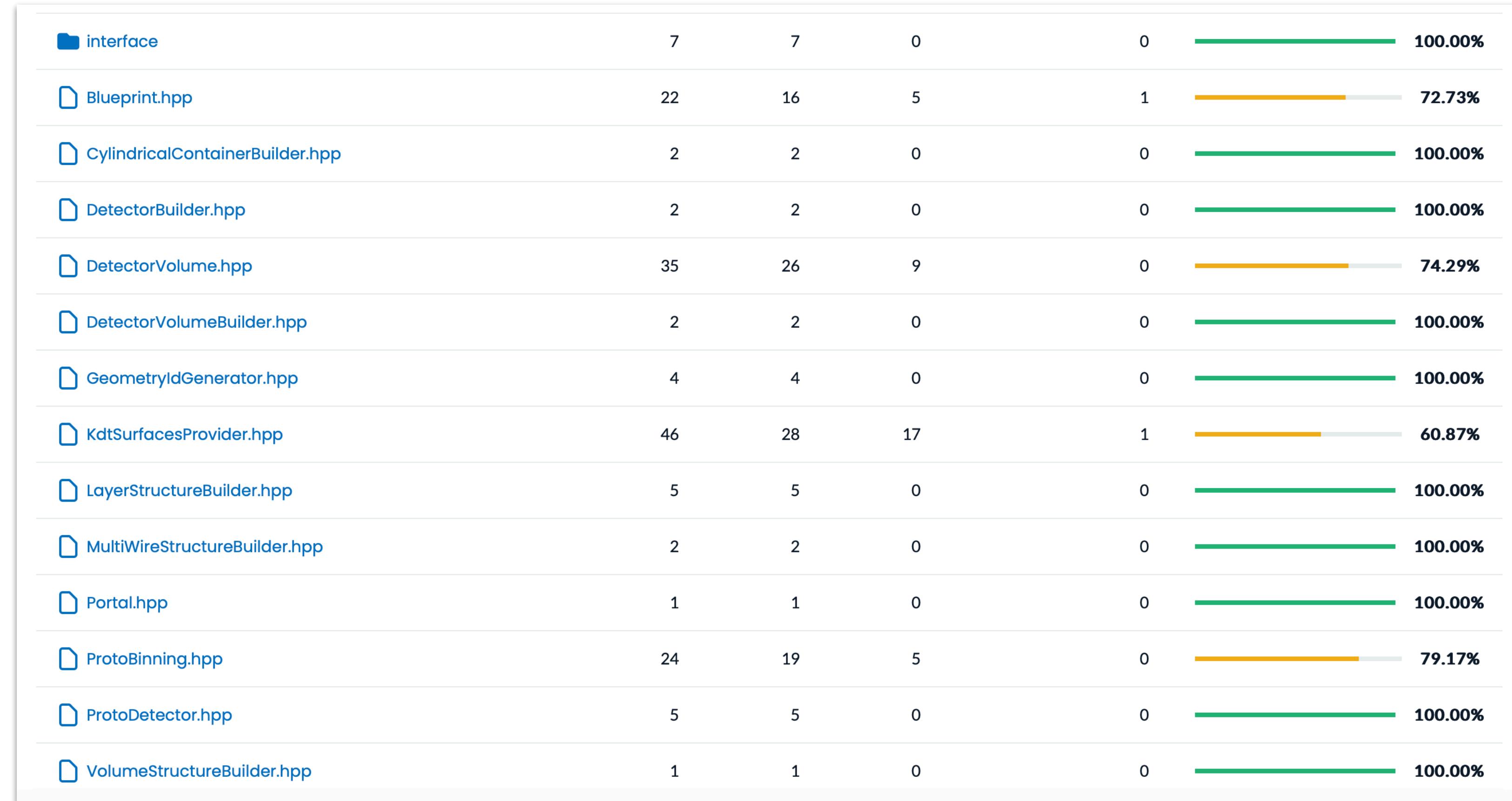
ODD exported to detray json,
read back in displayed with actsvg

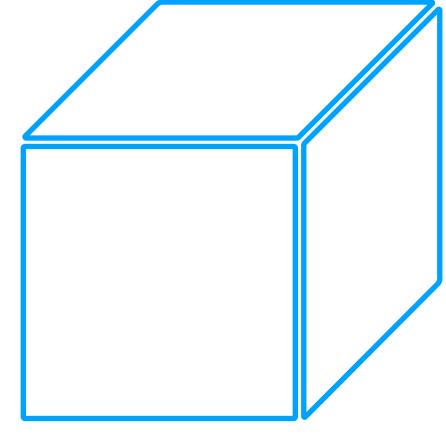




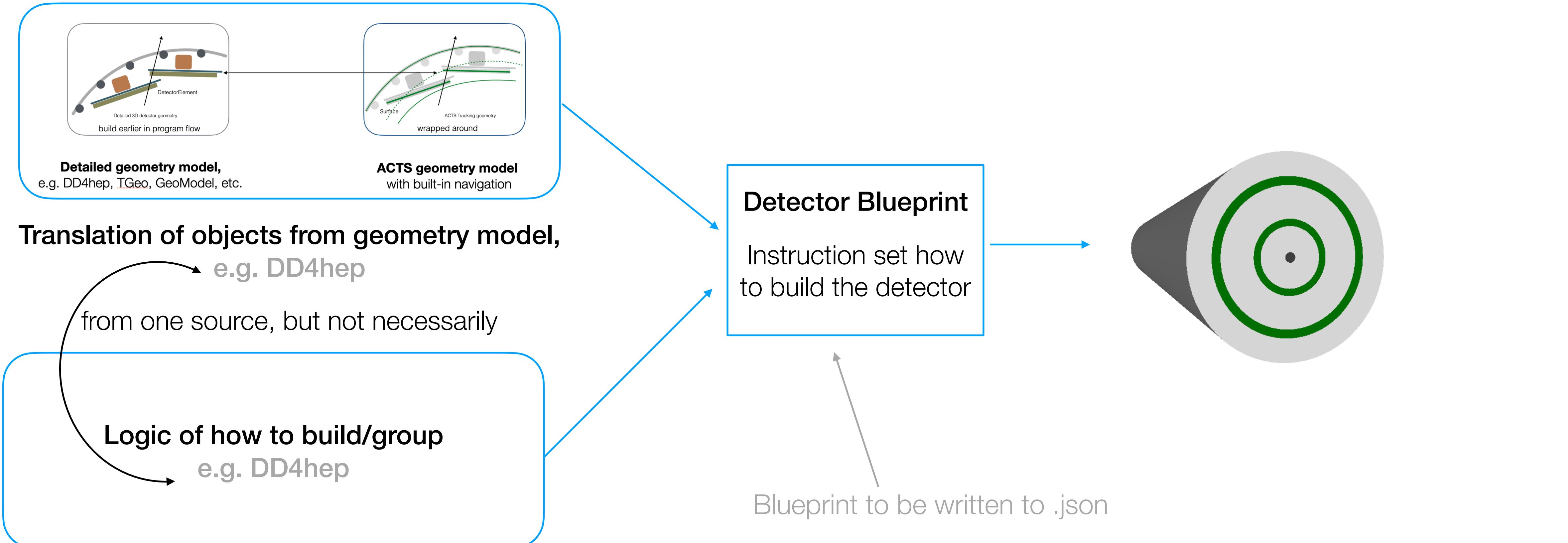
Acts::Detector features (2)

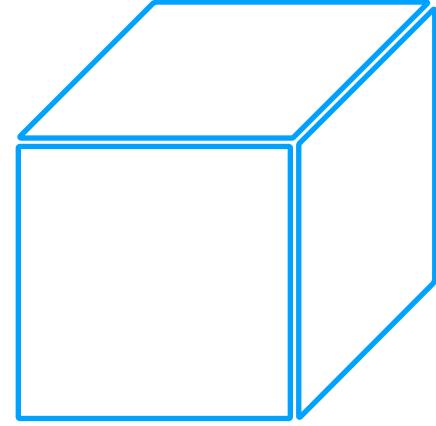
- **Detector** folder is relatively well unit tested, even the building code





Acts::Detector building process



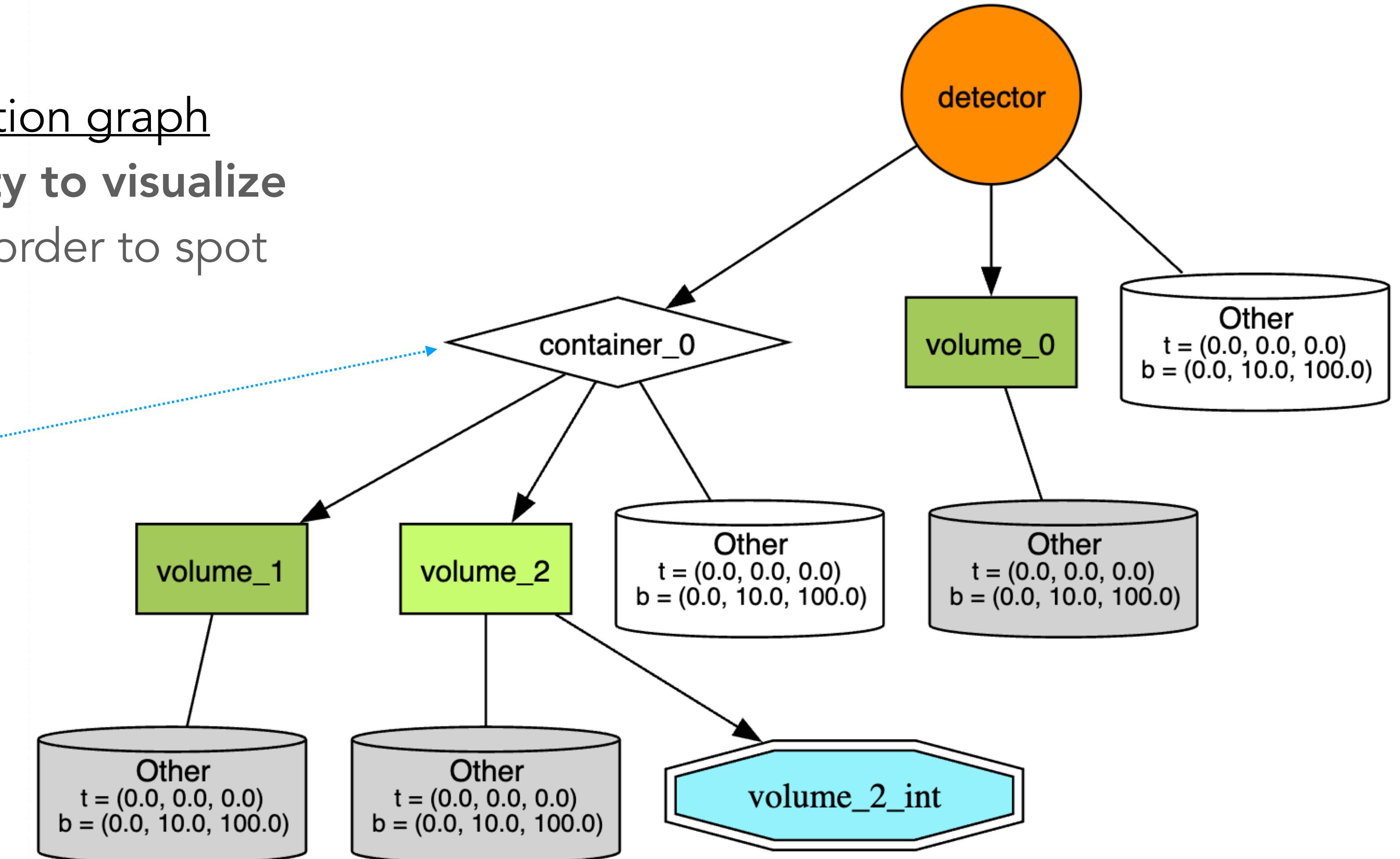


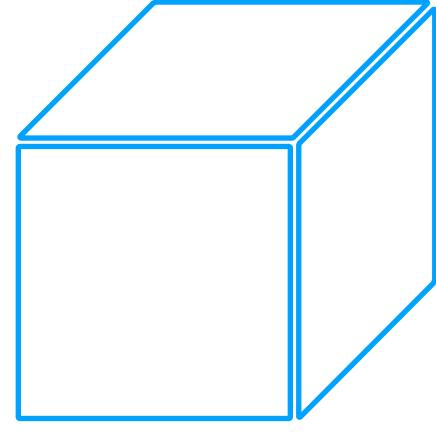
Blueprint visualisation

Blueprint is an instruction graph

- **Added functionality to visualize** before building, in order to spot problems

non-coloured nodes
are virtual containers



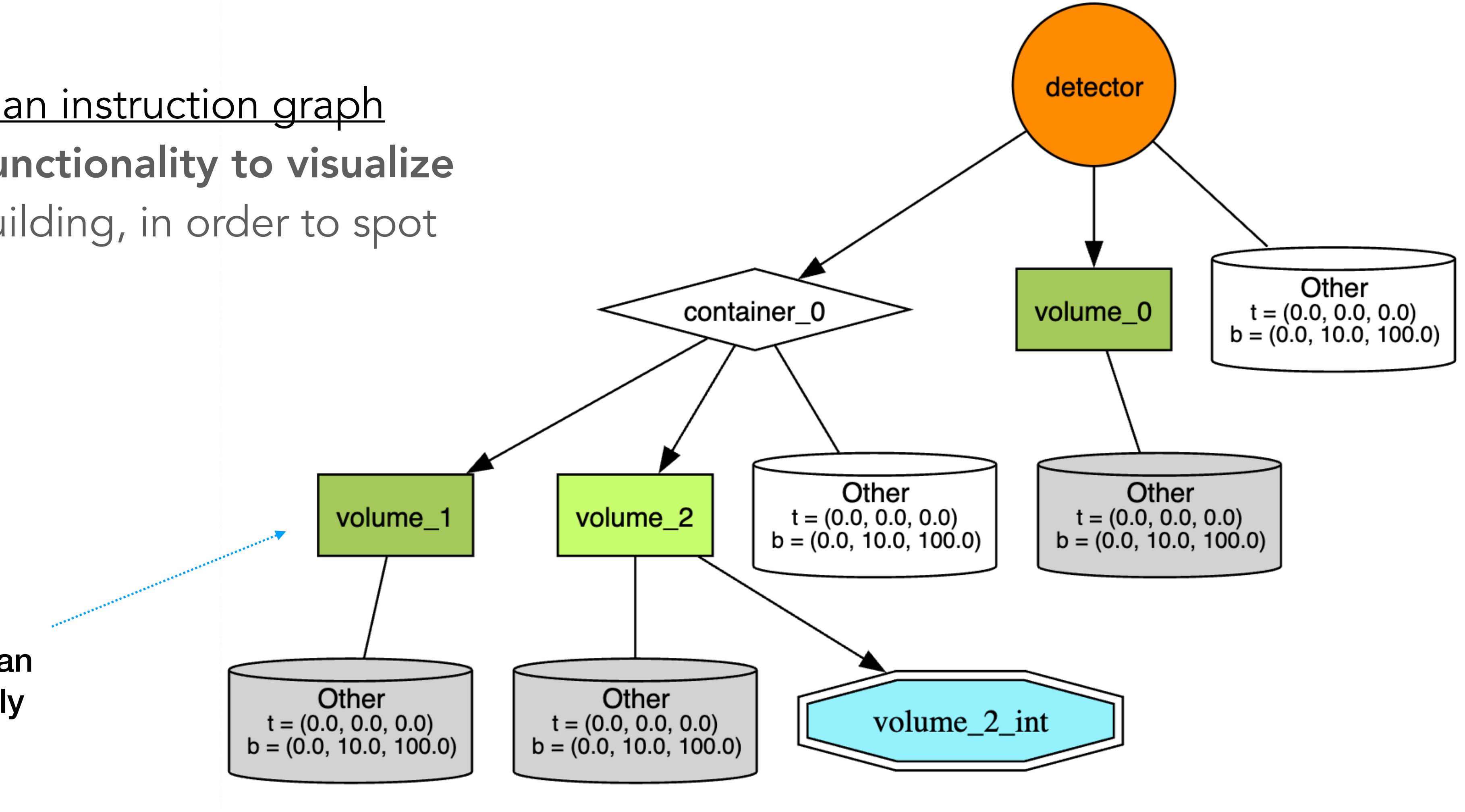


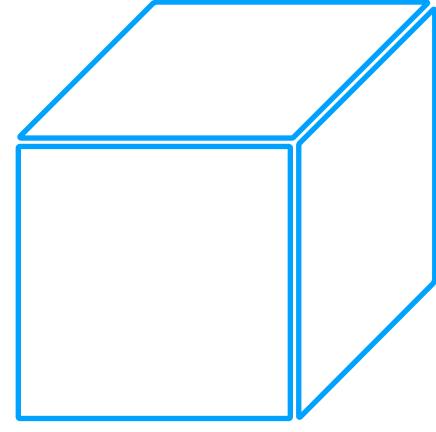
Blueprint visualisation

Blueprint is an instruction graph

- **Added functionality to visualize** before building, in order to spot problems

gap volumes can
be automatically
Created

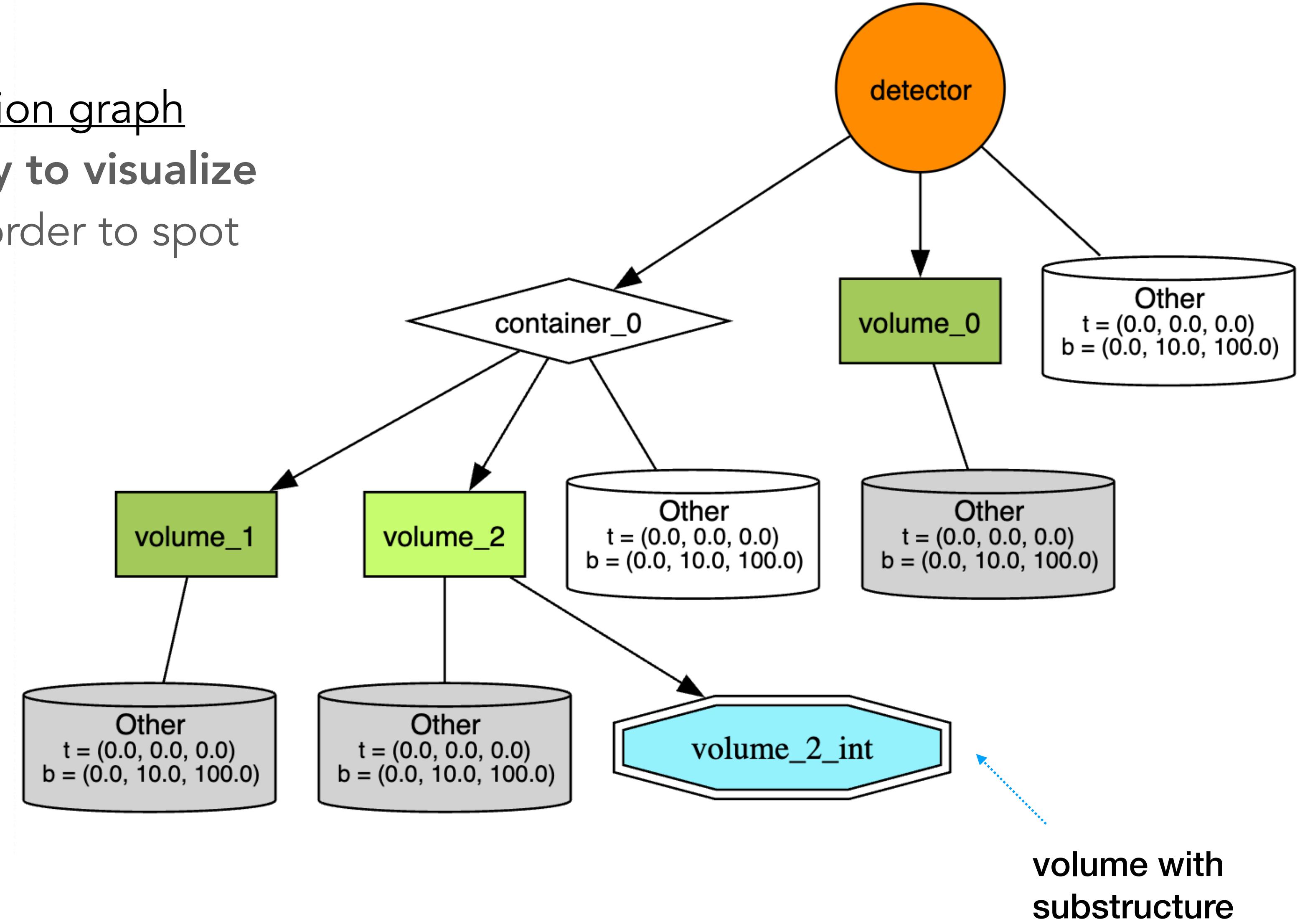


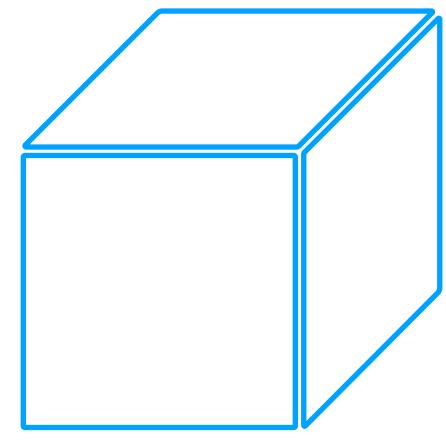


Blueprint visualisation

Blueprint is an instruction graph

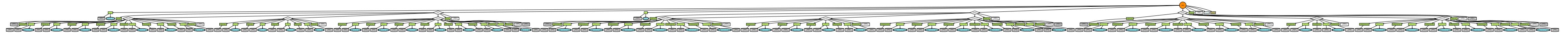
- **Added functionality to visualize** before building, in order to spot problems



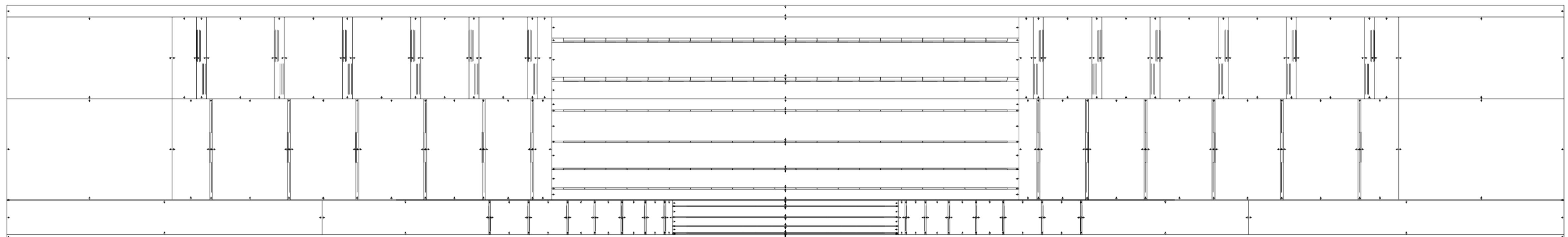


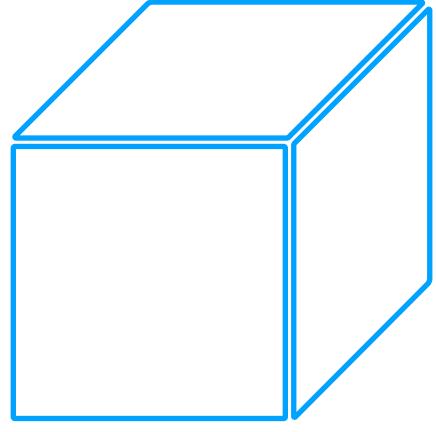
Visualisation

ODD building blueprint from DD4hep:



Resulting ODD detector





Building the ODD

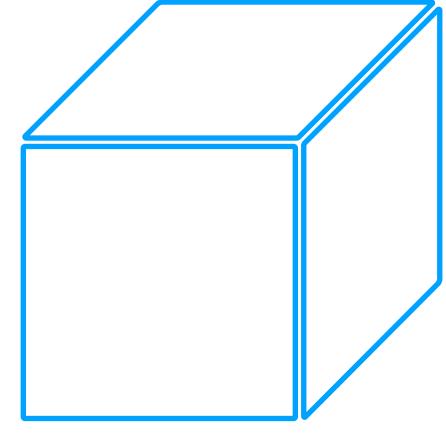
Extensively use the variant parameters plugin from DD4hep, purely in XML

A container definition:

```
<plugin name="DD4hep_ParametersPlugin">
  <argument value="PixelBarrel"/>
  <argument value="layer_pattern=PixelLayer\d"/>
  <argument value="acts_container: bool = true"/>
  <argument value="acts_container_type: int = 3"/>
  <argument value="acts_container_bvalues_n: int = 3"/>
  <argument value="acts_container_bvalues_0: double = pix_env_rmin"/>
  <argument value="acts_container_bvalues_1: double = pix_env_rmax"/>
  <argument value="acts_container_bvalues_2: double = pix_b_dz"/>
  <argument value="acts_container_binning: str = r"/>
</plugin>
```

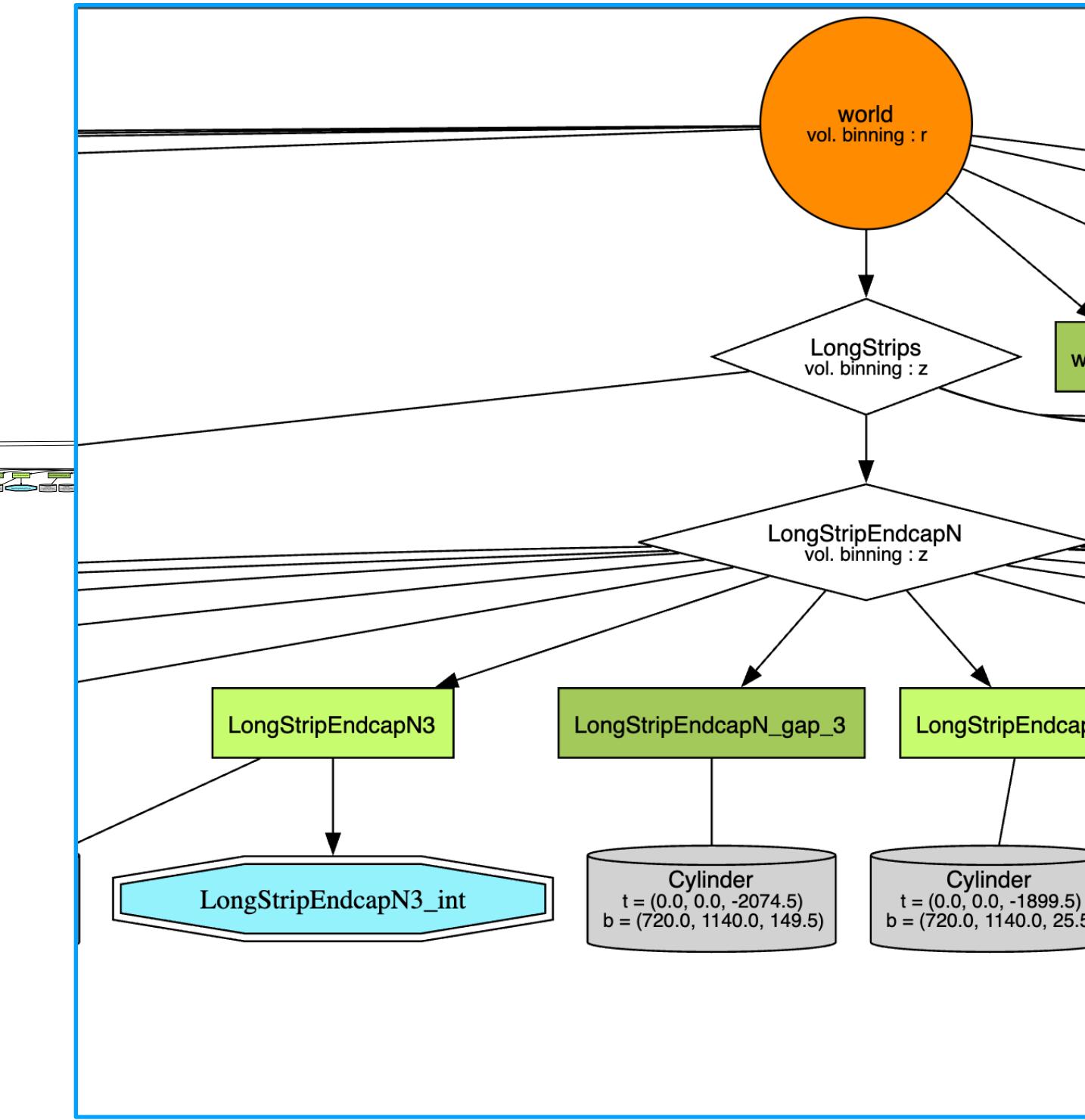
A layer volume:

```
<plugin name="DD4hep_ParametersPlugin">
  <argument value="/world/OpenDataDetector/Pixels/PixelBarrel/PixelLayer1"/>
  <argument value="acts_volume: bool = true"/>
  <argument value="acts_volume_type: int = 3"/>
  <argument value="acts_volume_internals: bool = true"/>
  <argument value="acts_volume_internals_type: str = layer"/>
  <argument value="acts_volume_internals_measure: str = z,r,r"/>
  <argument value="acts_volume_internals_clearance: double = pix_b_clear"/>
  <argument value="acts_surface_binning_dim: int = pix_b_sf_b"/>
  <argument value="acts_surface_binning_z_n: int = pix_b_sf_b_z"/>
  <argument value="acts_surface_binning_z_exp: int = pix_b_sf_e_z"/>
  <argument value="acts_surface_binning_phi_n: int = pix_b1_sf_b_phi"/>
  <argument value="acts_surface_binning_phi_exp: int = pix_b_sf_e_phi"/>
</plugin>
```

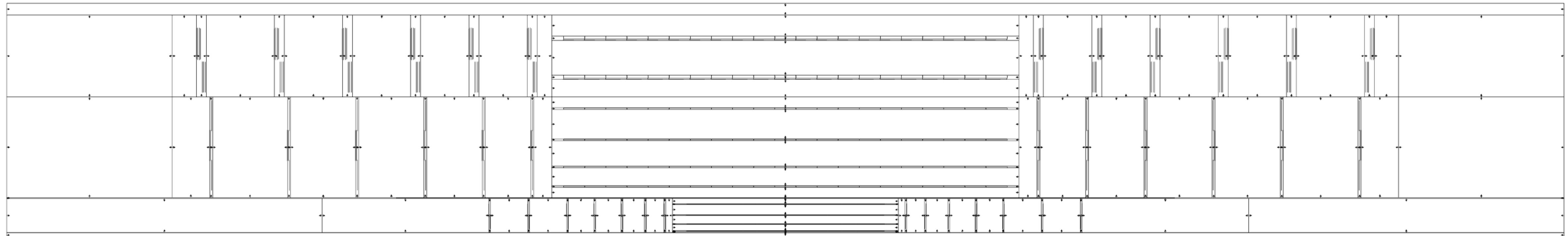


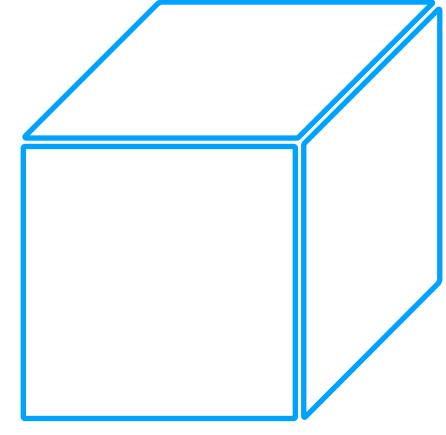
Visualisation

ODD building blueprint from DD4hep:

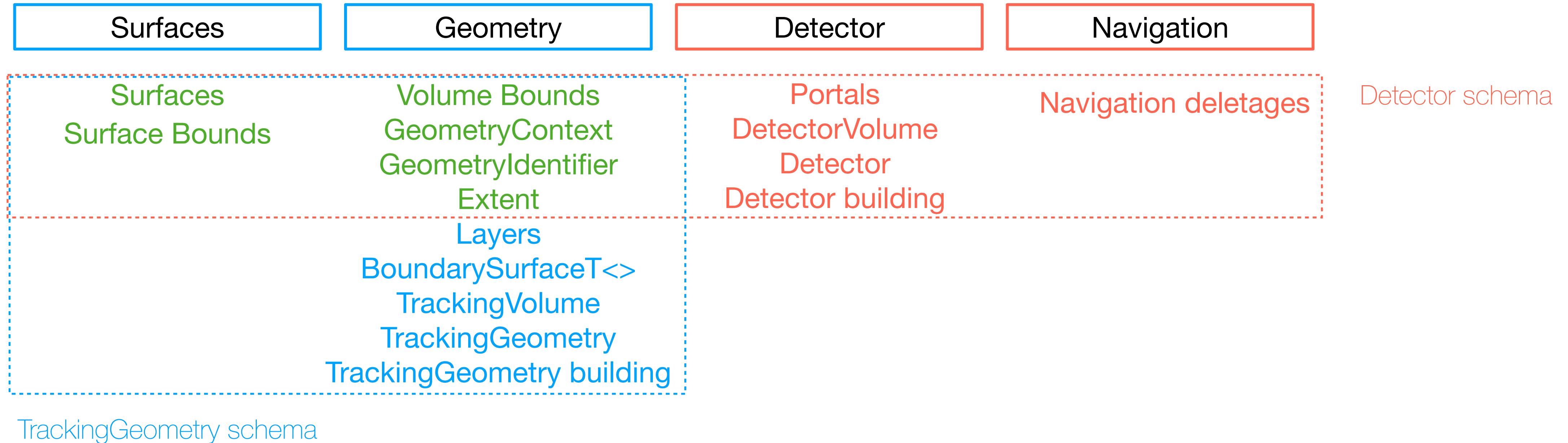


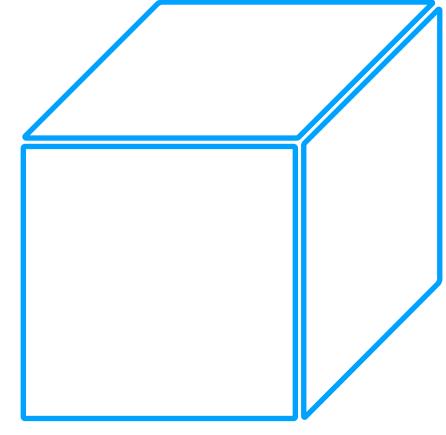
Resulting ODD detector



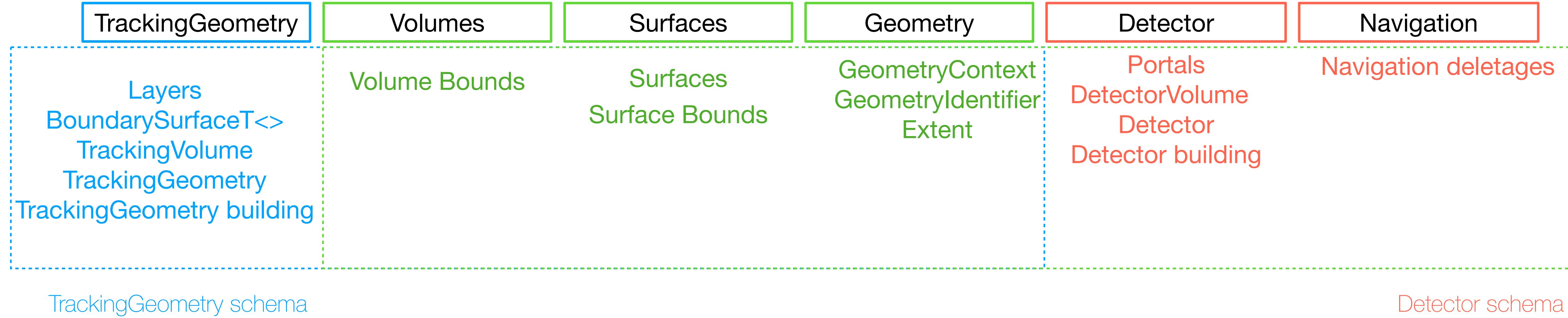


New detector strategy - current code organisation



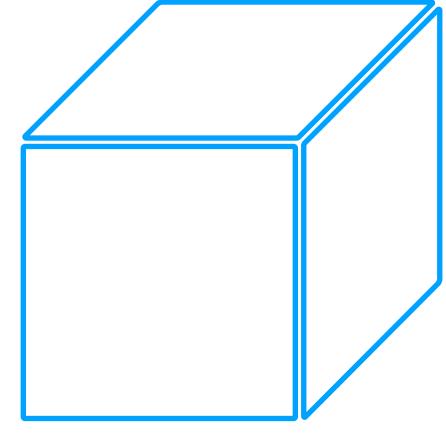


New detector strategy - suggested code organisation



Benefit

- This would allow to build TrackingGeometry/Detector model with a ACTS_DETECTOR_MODEL=On flag
- See also discussion afterwards with contribution from Andreas Stefl



Acts::Detector status & plans

Infrastructure

- Full building infrastructure **for cylindrical detectors** in place (and merged)
- **DD4hep** translation **for cylindrical detectors** available (and merged)

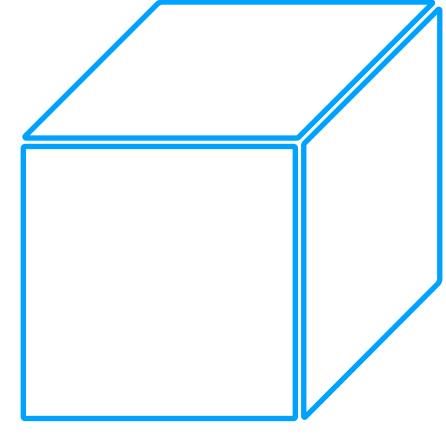
ODD as test template:

- branch with updated OpenDataDetector (with variant description) open, plan to make a MR to ODD in O(week)
- Next steps:

The screenshot displays two GitHub pull request cards against the v31.0.0 branch:

- Pull Request #2473:** feat!: volume agnostic material mapping. Status: **User Action Needed**. Labels: Component - Core, Component - Examples, Component - Plugins. Description: "User Action Needed" icon. Created by asalzburger on Sep 21.
- Pull Request #2625:** refactor: Rewrite navigation. Status: **WIP**. Labels: Breaks Athena build, Component - Core, Component - Examples, Infrastructure, Track Finding, Track Fitting. Description: "WIP" icon. Created by andiwand last week.

+ include infrastructure for **cubic Detectors**, branch exists, should be there in O(1 month)

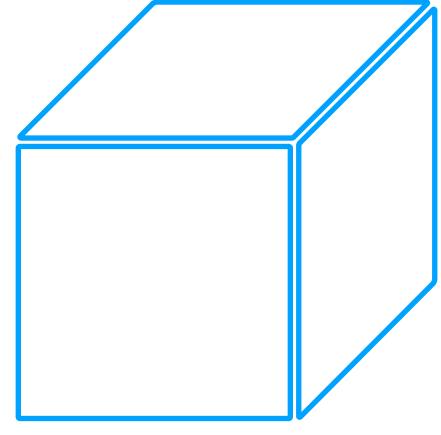


transform(): copy vs. const reference



Detailed geometry model,
e.g. DD4hep, TGeo, GeoModel, etc.

ACTS geometry model
with built-in navigation



transform(): copy vs. const reference

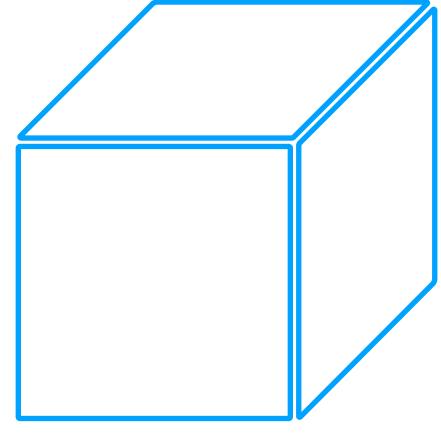
```
/// @class DetectorElementBase
///
/// This is the default base class for all tracking detector elements
/// with read-out relevant information. It provides the minimal interface
/// for the Acts proxy mechanism for surfaces, i.e. surfaces in the
/// Tracking geometry representing actual detection devices
///
class DetectorElementBase {
public:
    DetectorElementBase() = default;
    virtual ~DetectorElementBase() = default;

    /// Return the transform for the Element proxy mechanism
    ///
    /// @param gctx The current geometry context object, e.g. alignment
    virtual const Transform3D& transform(const GeometryContext& gctx) const = 0;
```

Alignment:
aligned position
can not be generated
on the fly

Wire chambers:
surfaces need to
be precomputed

Performance
No copy/allocation
needed



transform(): copy vs. const reference

[PR #2527](#)

This PR tests how much performance loss we would experience when changing the return object of `Surface` objects from

```
const Transform& transform(const GeometryContext& gctx) const;
```

to

```
Transform transform(const GeometryContext& gctx) const;
```

This change would allow us to create surfaces on the fly, (or at least their transforms) for e.g. Drift straws, etc.

Initial tests - running the propagation test only, which is relatively highly effected by this - shows.

Propagation test

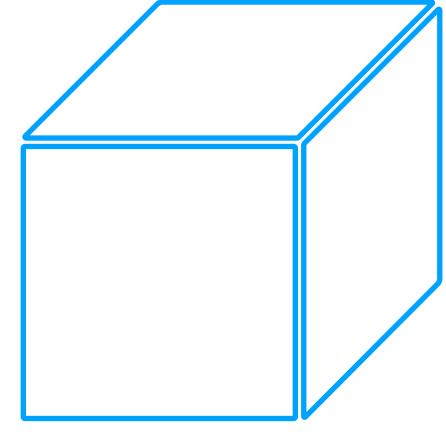
without this change

```
09:57:30    Sequencer    INFO    Average time per event: 19.184849 ms/event
```

with this change

```
09:56:55    Sequencer    INFO    Average time per event: 20.279401 ms/event
```

It indicates a 5% penalty in this workflow.



transform(): copy vs. const reference

[PR #2527](#)

Truth Tracking

```
14:07:33    Sequencer    INFO    Average time per event: 44.465655 ms/event
```

vs.

```
14:07:42    Sequencer    INFO    Average time per event: 45.216276 ms/event
```

So, closer to 2 % effect there, already interesting, I will do a full chain run as well.

- Next steps:
 - Test with ODD full chain example and then we should decide on it in a future developers meeting.