# Longitudinal Beam Diagnostics and Phase Space Reconstruction in the LHC Using ML

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## **Motivation**

- Knowledge of **longitudinal beam parameters** (e. g. energy error, phase error, bunch length and intensity) is **essential for beam performance** 
  - Even more so in the HL-LHC era
- Leveraging the high-resolution measurements of longitudinal bunch profiles:
  - Using fitting methods, bunch length, intensity, injection errors can be calculated
  - Using **longitudinal tomography**, bunch distribution and emittance can be calculated
- Above methods too time consuming for online use —limited to single bunch
- Develop ML model to:
  - Obtain the desired **beam parameters**,
  - and the 2D longitudinal beam distribution
  - **Fast** enough to allow for **online use** with **multi-bunch beams**



## **Training Data Generation**



# Original Model Architecture: Encoder- Decoder







# **Original Model Architecture: Limitations**

### **Multi-output Regression: Bottlenecks**



### **Restricted latent space: Sub-optimal**



### **Solution: Ensemble of Encoders**

- One model per beam parameter
- No bottlenecks
- More weights (total 60M)

#### **Solution: Unsupervised latent space**

- Waterfall to phase-space directly
- Better precision (~25%)
- Does not provide beam parameters
- More weights (151M)



# Model Hyperparameter Optimization

- Huge Parameter Space
  - 8 Models
  - Convolution layers (number, filters, kernels, activation)
  - Dense layers (number, size, activation function)
  - Regularization (dropout, batch normalization)
  - Learning rate, epochs, batch size
  - Input cropping, etc...
- > 100^100 combinations  $\rightarrow$  Exhaustive search prohibitive
- 1000x difference between "good" and "ba
  - $\rightarrow$  Tuning is essential
- Grid search optimisation:
  - Intelligent sampling
  - Early-stopping
  - Faster, near-optimal
  - Optuna library

#### Search algorithms on 2d space



Grid Search

Random Search

Adaptive Selection

#### Grid space search time comparison

2						
	Method	Total Configs	Total Run	Total Pruned	Best solution	Time taken
	Optuna	154	26	128	6.78E-06	1.5h
	Exhaustive	154	154	0	6.75E-06	6h
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# Synthetic Data Evaluation: Ground truth available

#### **Encoder Ensemble Evaluation**

- Matches or surpasses precision of classical methods
- Not all parameters equally "interesting"
- Independent set of parameters
  - Easily modifiable

	95-percentile	
Phase Error	0.3 deg	
Energy Error	1.56 MeV	
LHC V_RF	0.05 MV	
<b>Bunch Length</b>	13.2 ps	
Intensity	1.2e9 p	
SPS V_RF	0.16 MV	
Distribution <b>µ</b>	0.14 a.u.	

#### **Tomoscope Evaluation**

- MAE: 0.001 (1‰)
- Visually indistinguishable





# **Evaluation on Measurements: Reality Gap**





#### • Ground truth not fully available

- Some measurements, fitting or alternative methods
- Multi-bunch measurements, single-bunch simulations

# Evaluation on Real Data: End-to-End

- Visually indistinguishable
  - Pixel-to-pixel, MAE: 0.03
- Full reconstruction (48 bunches, 300 turns)



# Model Deployment



#### Machine Learning Platform (MLP):

- Standardizes the storage, versioning and distribution of ML models.
- Exposes uniform API (load, save, fit, predict)
- Model updates transparent to downstream
- + Standalone deployment: Inference in remote server, no local installation.
- Available at: acc-py-repo.cern.ch/browse/project/mlp-

Storage for off-line processing

# **GUI** Application



Target: Minimal user interaction

- Reads input from UCAP node
- Updates with every new injection

#### Capabilities:

- Subscribe to UCAP
- Inspect Bunch Profiles
- Bunch-by-bunch beam diagnostics
- Longitudinal tomography
- Edit settings, save to file

#### **Extensions:**

- Unify with classical tomography
- Allow for direct comparison





## Conclusions

#### • ML a powerful and promising solution to both:

- Extraction of essential beam parameters in real-time
- Multi-bunch tomography in real-time
- Less than 1 min for 300 turns phasespace reconstruction of 48 bunches

#### • Tool is in operational state

- $\circ$   $\,$  To be tested on next run
- GUI for real time display
- Output data stored post-processing



## Thank you for your attention!





## **Future Work**

- Hybrid, Tracking+ML approach
  - Predict initial bunch distribution, then track with BLonD
- Domain Adaptations/ Adjustments:
  - Multi-bunch beams
  - lons
  - Phases of the acceleration
  - Machines (PS, SPS)
- Transfer learning
  - Re-use core model architecture
  - Combine with smaller, simpler model per task

