# Generative models for molecules in equillibrium

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# Why generative modeling for molecules?

find candidates for drugs and materials (inverse design)



#### advance science



understand molecular origin of diseases



#### **Some Motivation:** binding affinity prediction



#### Molecules are not static…

Potential energy



Boltzmann density  
\nBoltzmann density  
\n
$$
\mu(x) = \frac{\exp(-u(x)/kT)}{Z}
$$
\n
$$
Z_A = P(A) = \int_{A \subset \mathbb{R}^d} \mu(x)
$$
\nFree energy  
\n
$$
{}^{4}Heihood of a state
$$
\n
$$
Z_A = P(A) = \int_{A \subset \mathbb{R}^d} \mu(x)
$$
\nFree energy  
\n
$$
{}^{4}Heg. log likelihood of a state
$$
\nFree energy  
\n
$$
F_A = -kT \log Z_A
$$
\nFree energy difference  
\nComputing FED requires sampling...
$$
\Delta F_{A \to B} = F_A - F_B
$$
\n
$$
x \sim \exp(-u(x))/Z
$$

 $\Delta F_{A\rightarrow B} = F_A - F_B$ 

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Answers requires sampling…

 $\mathbf{x} \sim \exp(-u(\mathbf{x}))/Z$  $\begin{matrix} \searrow \\ \searrow \end{matrix}$ 



Classic workhorse: Molecular / Langevin dynamics simulations

 $\mathbf{x} \leftarrow \mathbf{x} - \nabla_{\mathbf{x}} u(\mathbf{x}) dt + \sqrt{2dt} \eta, \quad \eta \sim \mathcal{N}(0, I)$ 

easy to make mistakes…



Numerical precision: step size 1-4 fs

Relevant biological scales: 1 ms  $\rightarrow$  hours...

Computing FED requires sampling…

#### Classic workhorse: Molecular / Langevin dynamics simulations

#### 2ms of molecular dynamics

 $=$  ~1  $Ph.D.$  $=$  ~ 500 GJ



 $\mathsf{Null} \quad \quad \mathsf{Source:}$  Frank Noé

# Boltzmann Generators







Frank Noé Simon Hao Wu

Olsson

- 1. Sample noise from base distribution
- 2. Transform via a trainable diffeomorphism (Normalizing Flow)
- 3. Reweigh against the target



Boltzmann Generators. Noé\*, Olsson\*, JK\*, Wu. Science. 2019



1: Variational inference with normalizing flows. Rezende & Mohammed. ICML. 2015 Figure: Neural ODEs, Chen et al. NeurIPS. 2018



**Training mode I:** negative log-likelihood



Boltzmann Generators. Noé\*, Olsson\*, JK\*, Wu. Science. 2019



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Boltzmann Generators. Noé\*, Olsson\*, JK\*, Wu. Science. 2019

#### **Our setup**

1. NLL on biased samples (e.g. non-converged MD trajectory)

2. combine with KL training

3. correct with importance sampling

$$
\mathbb{E}_{\mu}[O(x)] = \mathbb{E}_{x \sim p} \left[ \frac{\mu(x)}{p(x)} O(x) \right]
$$

$$
z \sim q(z) \longrightarrow \mathcal{L}_{NLL}(\theta) \longleftarrow \text{keep modes!}
$$
\n
$$
f
$$
\n
$$
f
$$
\n
$$
f
$$
\n
$$
f^{-1}
$$
\n
$$
\sum_{x \in KL(\theta)} \sum_{x \sim \tilde{\mu}(x)} \text{biased trajectory}
$$

Joint loss:

$$
\mathcal{L}(\theta) = \alpha \cdot \mathcal{L}_{KL}(\theta) + \beta \cdot \mathcal{L}_{NLL}(\theta)
$$

better fit

convex combination

**Test systems**





dimer in particle box dimer in particle box protein (BPTI) in implicit solvent

Boltzmann Generators. Noé\*, Olsson\*, JK\*, Wu. Science. 2019

#### **Results**











Actual picture of the method at this state…

#### Topology / representation?

Internal Coordinates + Whitening



Symmetries?

What are the problems?



# Equivariant Flows





**TL/DR**: normalizing flows with group symmetries

Equivariant Flows. Köhler\*, Klein\*, Noé. ICML. 2020

Invariant energy / density Symmetries

$$
\forall R \in \rho(G) \colon u(Rx) = u(x)
$$



Arbitrary flow maps

$$
p(Rx; \theta) \neq p(x; \theta) \longleftarrow
$$
 Bad for reweighing!

Handles data inefficiently!

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Figure: Neural ODEs, Chen et al. NeurIPS. 2018

$$
R
$$
\n
$$
\begin{array}{c}\n\frac{d}{dx} \\
\frac{dy}{dx} \\
\frac{dy}{dx} \\
\frac{dy}{dx} \\
x = f(z; \theta) \sim p(x; \theta)\n\end{array}
$$
\n
$$
x = f(z; \theta)
$$

### Equivariant Flows

Constraint on group representations

 $\mu(\rho(g)x) = \mu(x)$  $|\det \rho(g)| = 1.$ 

Important for molecules:

$$
G \leq O(n)
$$
\n
$$
\sum_{\text{permutations}}^{G \leq O(n)}
$$



### Smooth Flows



### **TL/DR:** fix broken topology with smooth transforms on hypertorus!

Smooth Normalizing Flows. Köhler\*, Krämer\*, Noé. NeurIPS. 2021



2000

# Rigid body flows for molecular crystals



Pim de Haan

Michele Pim de Frank Noé Invernizzi

**TL/DR**: smooth and equivariant flows on SE(3)

### Motivation: solvent systems and crystals





0-0	2e $\mathbb{R}^{n-a.3}$	2e $\mathbb{R}^{n-a.3}$
0-0	2e $\mathbb{R}^{n-a.3}$	2f <sub>0</sub> <i>2x boud length</i>
0-0	2f <sub>0</sub> <i>water a=3</i>	
0-0	2f <sub>0</sub> <i>water a=3</i>	
0-0	2g <sub>0</sub> <i>water a=3</i>	
0-0	2g <sub>0</sub> <i>water a=3</i>	
0-0	2h <sub>0</sub> <i>water a=3</i>	
0-0	2h <sub>0</sub> <i>water a=3</i>	
0-0	2h <sub>0</sub> <i>water a=3</i>	
0-0	2h <sub>0</sub> <i>water a=3</i>	
0-0	2h <sub>0</sub> <i>water a=3</i>	
0-0	2h <sub>0</sub> <i>water a=3</i>	
0-0	2h <sub>0</sub> <i>water a=3</i>	
0-0	2h <sub>0</sub> <i>water a=3</i>	
0-0	2h <sub>0</sub> <i>water a=3</i>	
0-0	2h <sub>0</sub> <i>water a=3</i>	

# **Charting**

Cut manifold open into charts and apply flow to chart

- Easy to implement
- **Fast**



Figure: Gemici (2015)

● Non-smooth solutions!



Figure: Wikipedia

# Continuous flows on manifolds

Integrate NN dynamics on manifold

- Works on every Riemannian manifold
- **Smooth**
- Difficult to train
	- Likelihood easy with flow-matching...
	- Rev. KL: adjoint method
- **Slow integration**
- Not scalable to high dimensions



Covering flows  $\pi: \mathbb{R} \to \mathbb{S}^n$ ,  $x \mapsto exp(i \cdot x)$  $p(x)$  $\overline{\phantom{a}}$  $V - i$  $V_{-1}$   $V_{A}$ V,  $\mathbb R$  $\mathcal T$  $\pi^{-1}(u) \cong u \times \mathbb{Z}$  $\widetilde{\rho}$  (r) =  $\sum_{k \in \mathbb{Z}} \rho(x+k)$  $\mathbf 0$  $2\pi$ 

Qualenious:	\n $4 \cdot 4 \cdot 6 \cdot 1 + c \cdot 1 + d \cdot 6$ \n	\n $e R^4$ \n	\n $e R^6$ \n
Conjugate:	\n $4^2 \cdot 4 - b \cdot 1 - c \cdot 1 - d \cdot 6$ \n	\n $e^2 \cdot 4 - b \cdot 1 - c \cdot 1 - d \cdot 6$ \n	
action on $R^3$ : $P = (\alpha, y_1 e) e R^3 \longrightarrow \hat{P} (0, \alpha, y_1 e) e R^4$ \n\n			
action on $R^3$ : $P = (\alpha, y_1 e) e R^3 \longrightarrow \hat{P} (0, \alpha, y_1 e) e R^4$ \n\n			
For $q e S^3 = \{ q e R^4   l   q l - 1 \}$ : $Q + Q$ is 3D rotation?\n      \n			
For $q e S^3 = \{ q e R^4   l   q l - 1 \}$ : $Q + Q$ is 3D rotation?\n      \n			
For $q e S^3 = \{ q e R^4   l   q l - 1 \}$ : $Q^3 \rightarrow Q (3) \}$ is also a rotation?\n      \n			



# Return of the gradient flows

Strictly convex 
$$
\phi: \mathbb{R}^4 \to \mathbb{R}
$$

$$
\Phi_{CG}(\boldsymbol{x}) = \frac{\nabla_{\boldsymbol{x}}\phi(\boldsymbol{x})}{\|\nabla_{\boldsymbol{x}}\phi(\boldsymbol{x})\|}
$$

Result: 
$$
\phi
$$
 sigu-invaiaut  $\Rightarrow$   $\Phi_{cg}$  sahisfies constants!

 $\mathbf{r}$ 

Boltzmann Geuerators:  
\n
$$
\begin{array}{ccc}\n & \text{(eared Free Energy Petrationbox)} \n\\ \n\text{Simple prior} & \mathcal{N}(0,1) & \text{v easy} \text{ system} & \text{exp}(-\mathcal{U}, (\mathbf{x})) & \text{high temp.} \\
 & \text{flow} & \text{E} & \text{flow} & \text{E} & \text{flow} & \text{temp.} \\
\text{Eagger} & \text{Epsilon} & \text{flow} & \text{E} & \text{low} & \text{temp.} \\
\end{array}
$$
\n
$$
\begin{array}{ccc}\n & \text{target} & \text{exp}(-\mathcal{U}, (\mathbf{x})) & \text{low term} \\
 & \text{target} & \text{exp}(-\mathcal{U}, (\mathbf{x})) & \text{low term}\n\end{array}
$$

Targeted free energy estimation via learned mappings, Wirnsberger et. al., JCP 2020



### Results: Ice in different thermodynamic states

 $\sim$ 









#### Thanks!









**DAEDALUS** RTG 2433

