

# About myself

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- Participant of the UKRATOP internship





**Project's topic:**

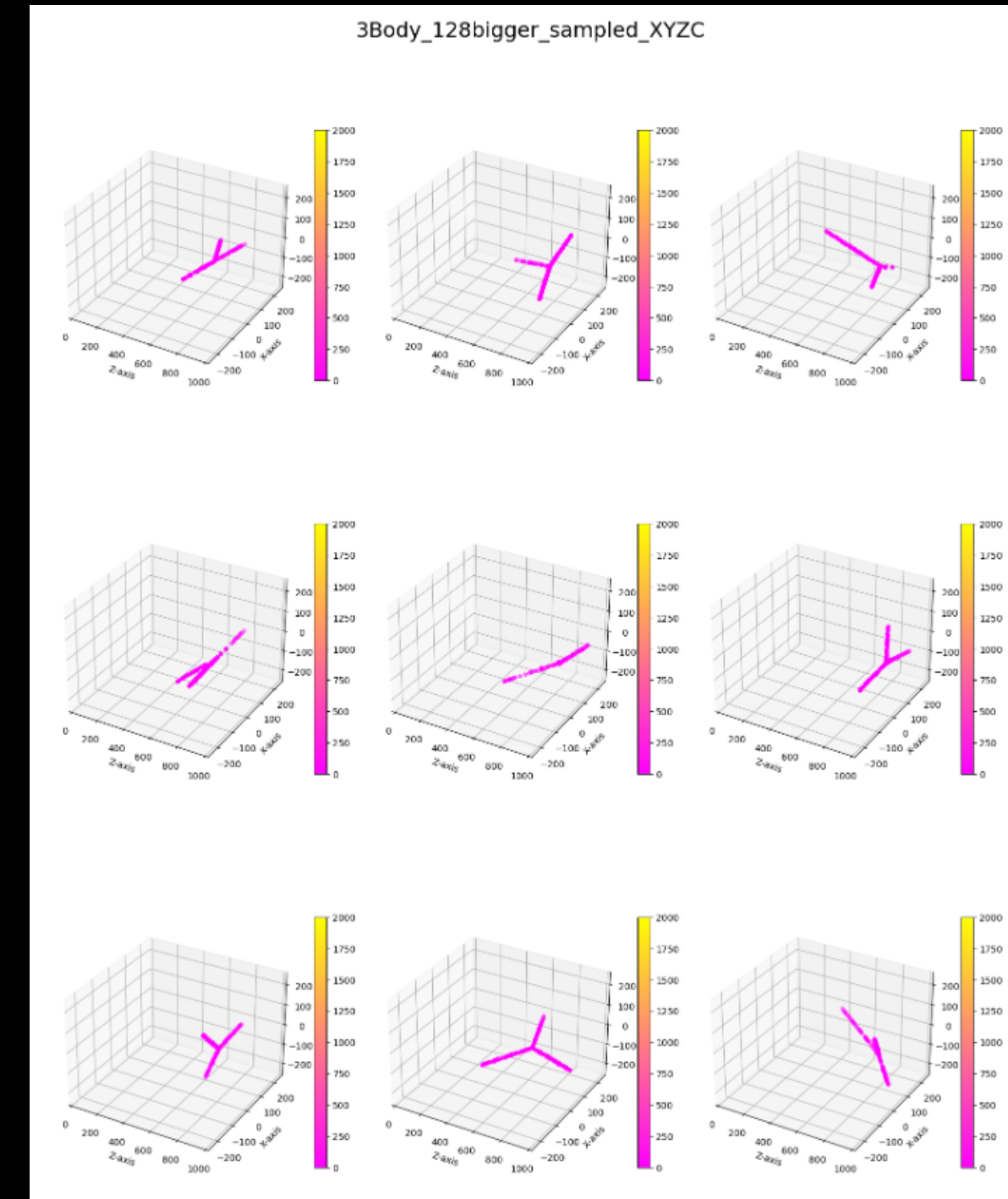
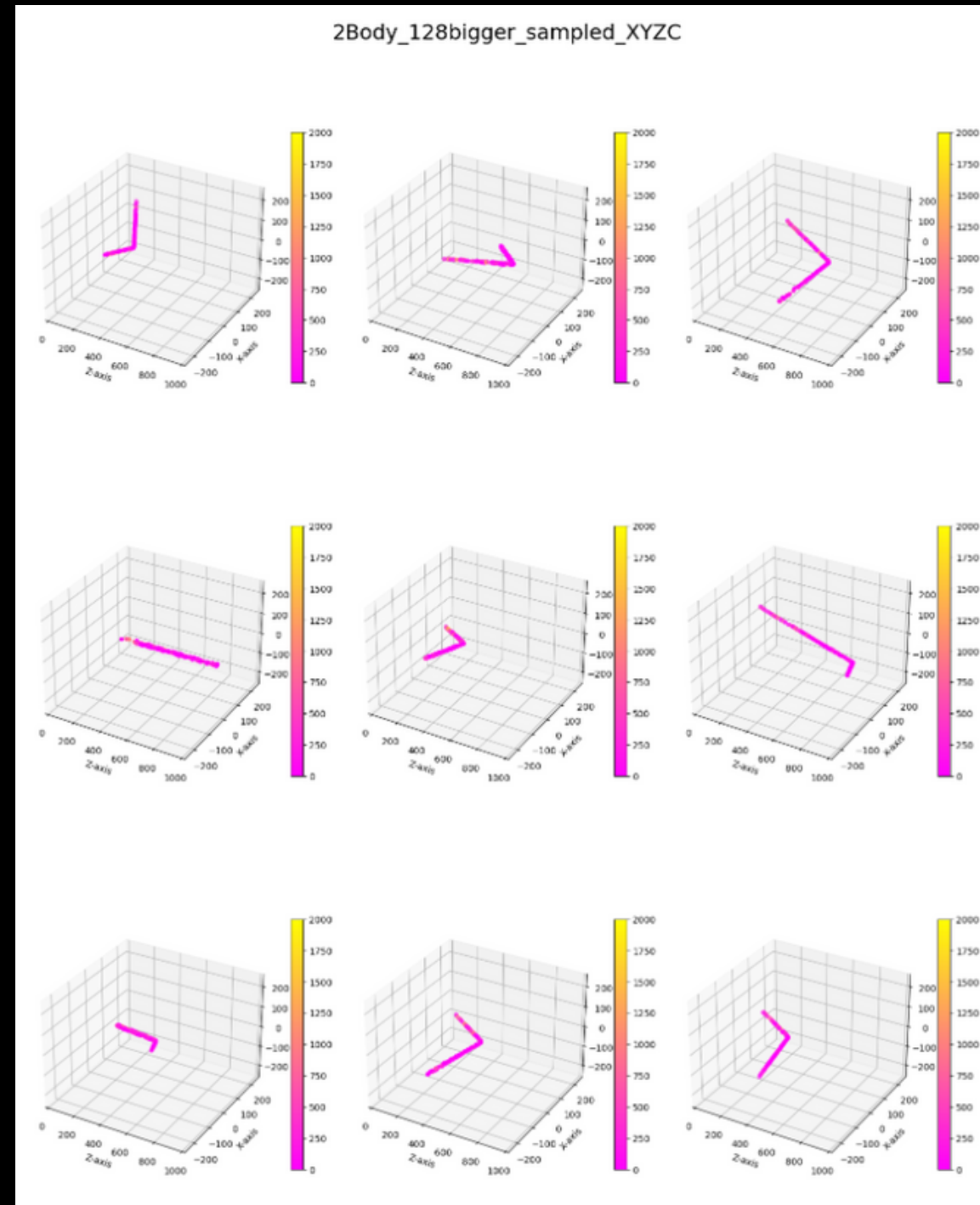
**“Using Diffusion Probabilistic Models  
for generating Tracks from AT-TPC  
Detector”**

Mentor: Dr. Michelle Kuchera

Artem Havryliuk

# AT-TPC

The Active Target Time Projection Chamber (AT-TPC) experiment is a state-of-the-art particle detector used to study nuclear physics.



# DPM - Diffusion Probabilistic Models

Forward process: Real Point Cloud of a desired shape -> Noisy Point Cloud

Reverse process: Noisy Point Cloud -> Generated Point Cloud of a desired shape

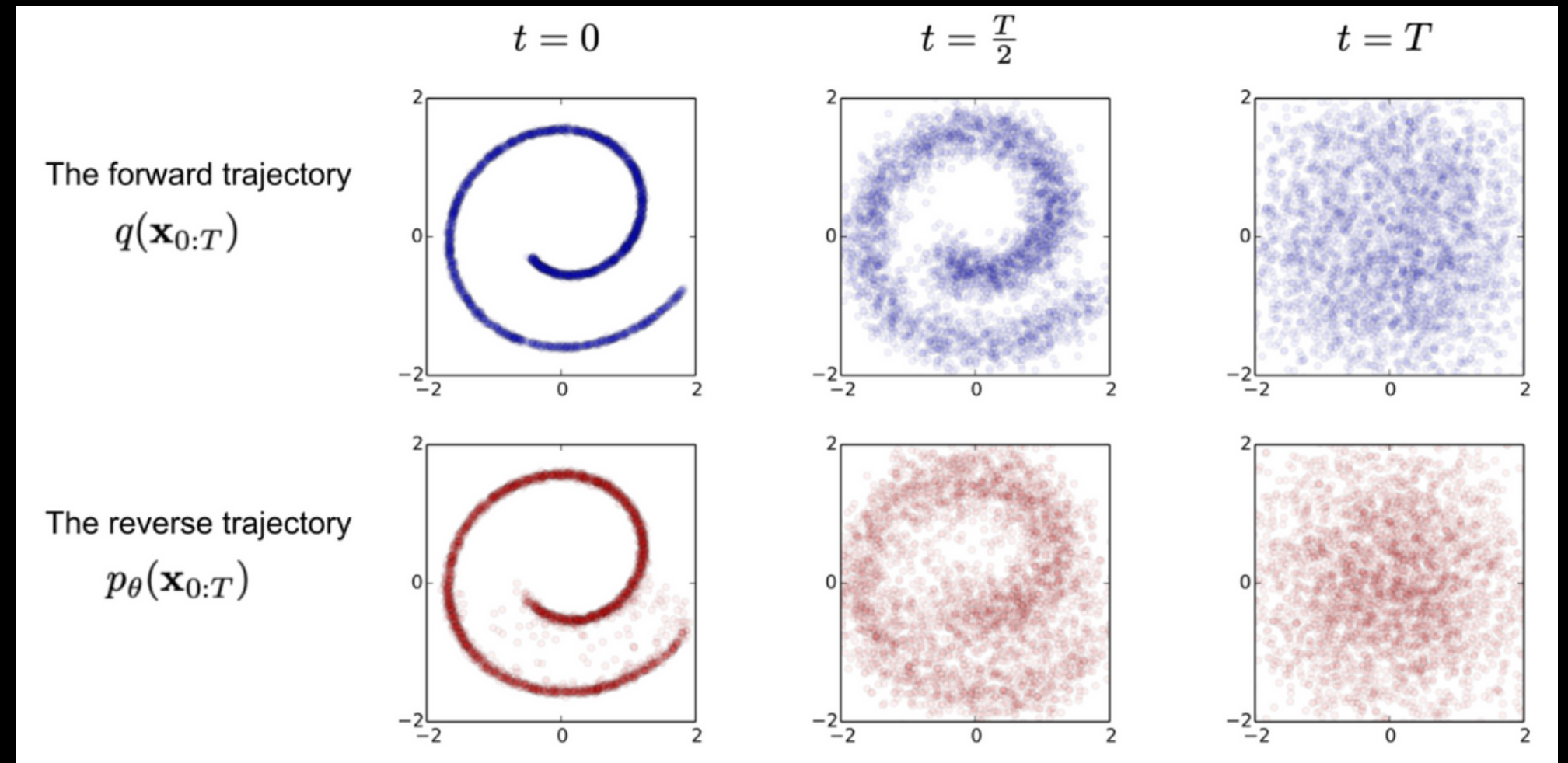


Fig.1 An example of training a diffusion model for modeling a 2D swiss roll data. Image source: [3] Sohl-Dickstein et al., 2015

Learn the reverse diffusion process that transforms the noise distribution to the distribution of a desired shape



# A starting point

- Article: Diffusion Probabilistic Models for 3D Point Cloud Generation.
- Preliminary work in Dr. Kuchera's group
- What is missing: conditions for generation, the existing approach uses different models for different objects, and our goal is to create one model with which it will be possible to generate certain point clouds

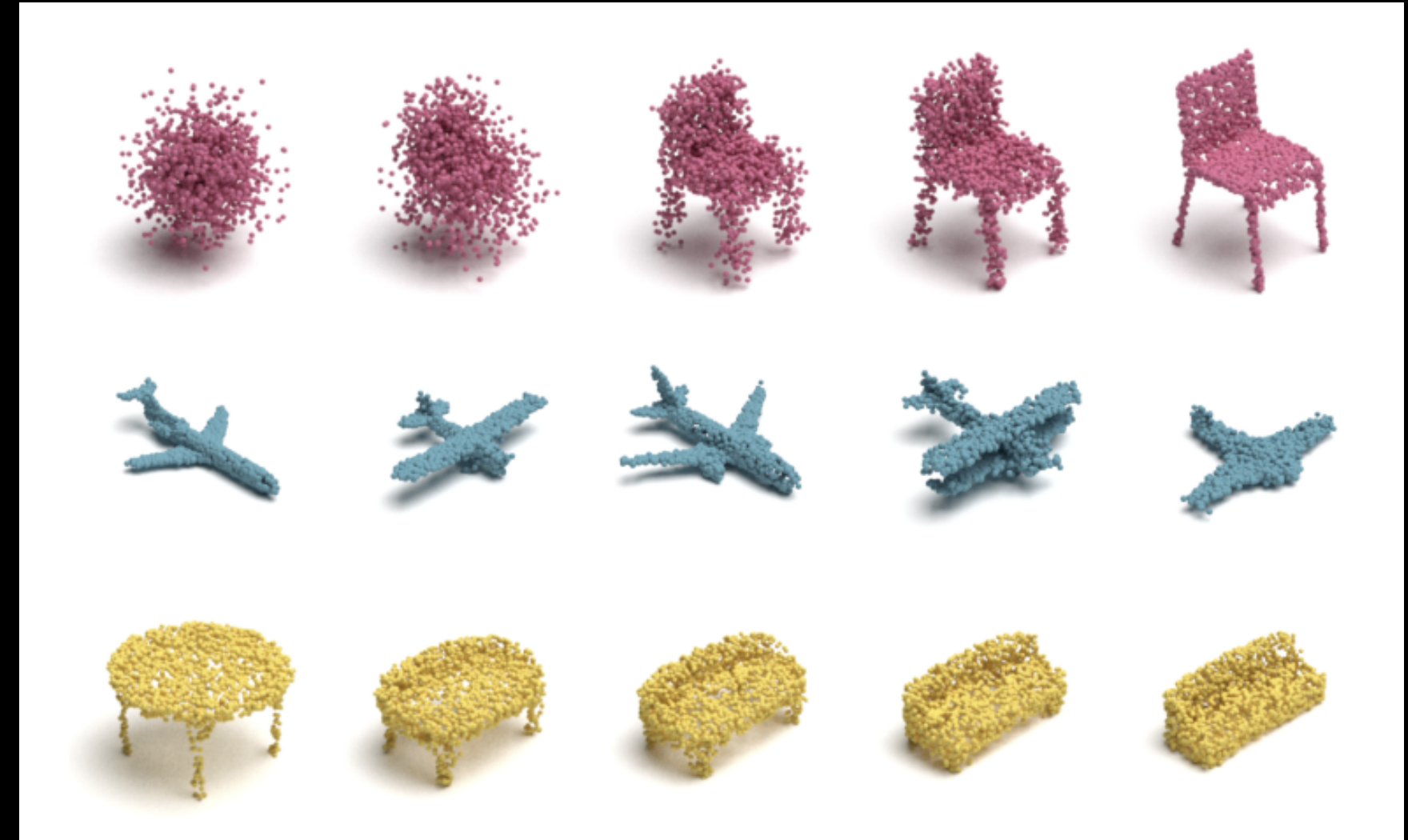
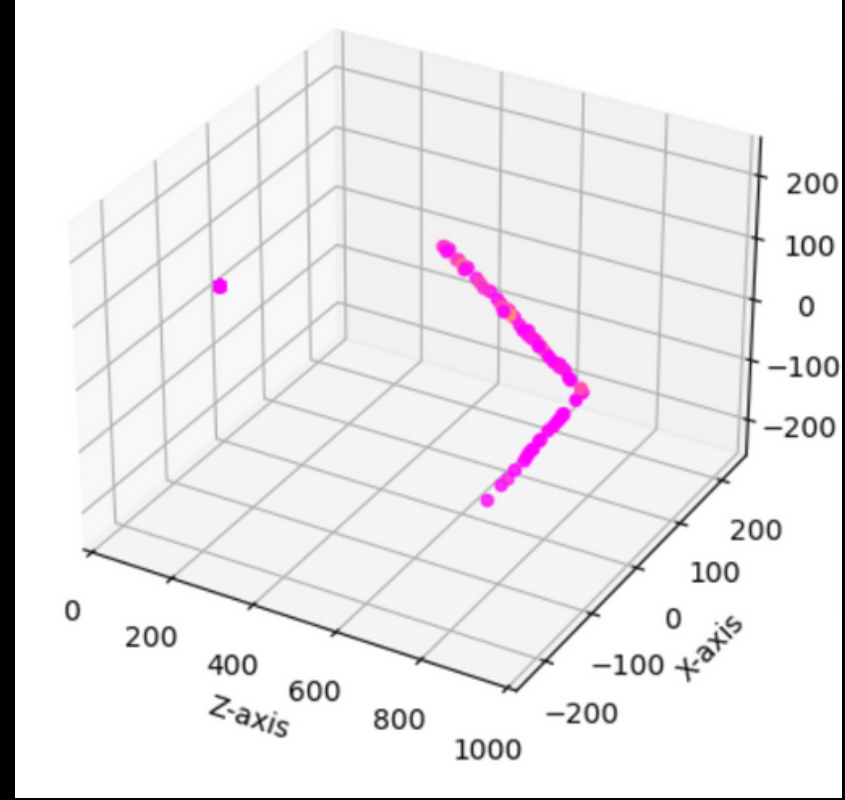
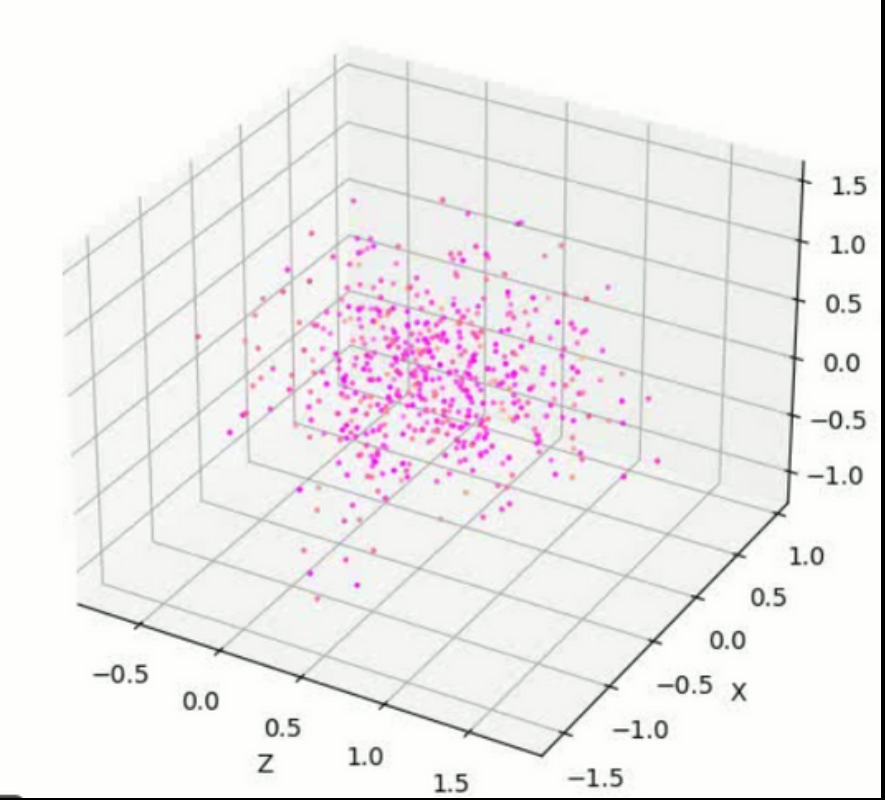


Fig.2 Diffusion Probabilistic Models for 3D Point Cloud Generation

# General idea - Create Conditional DPM Generator

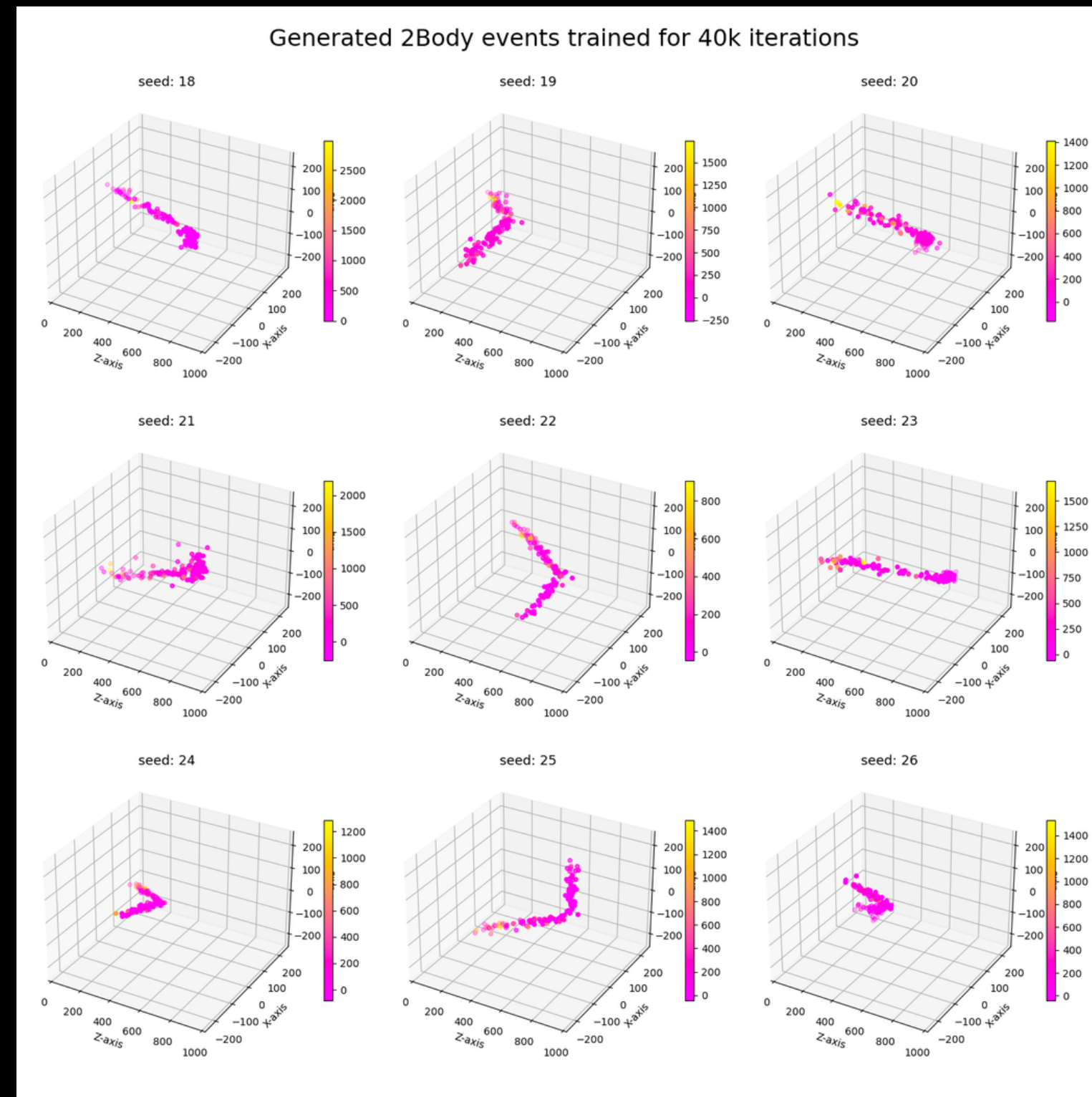
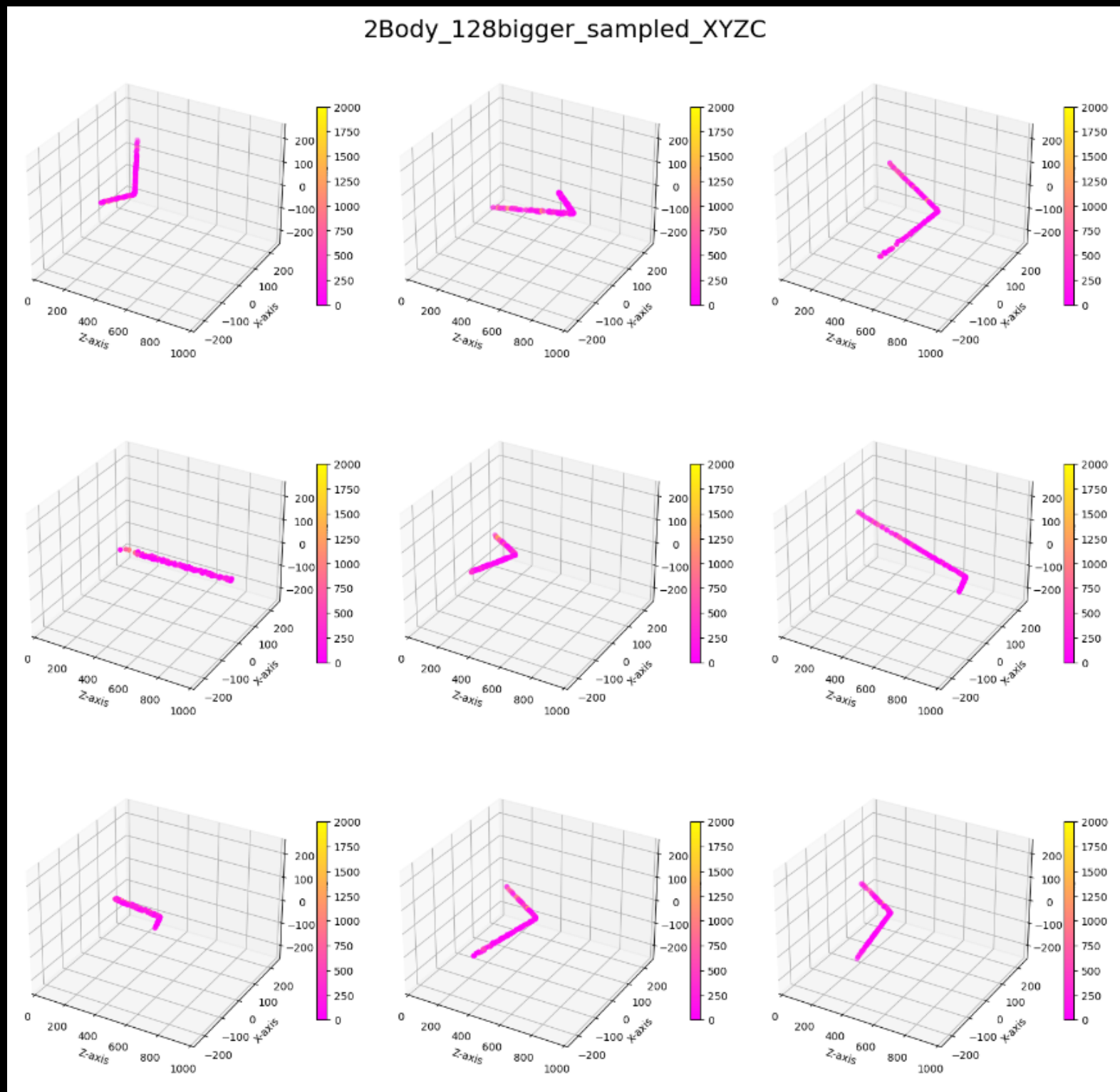


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Event of desired type

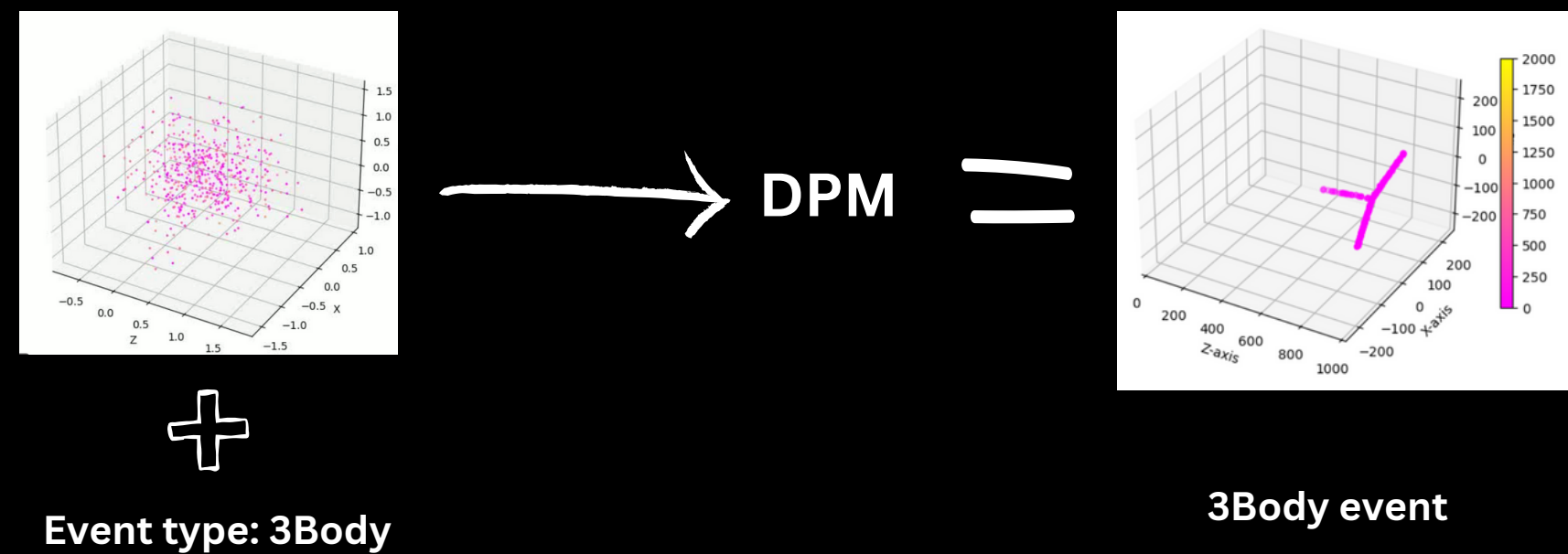
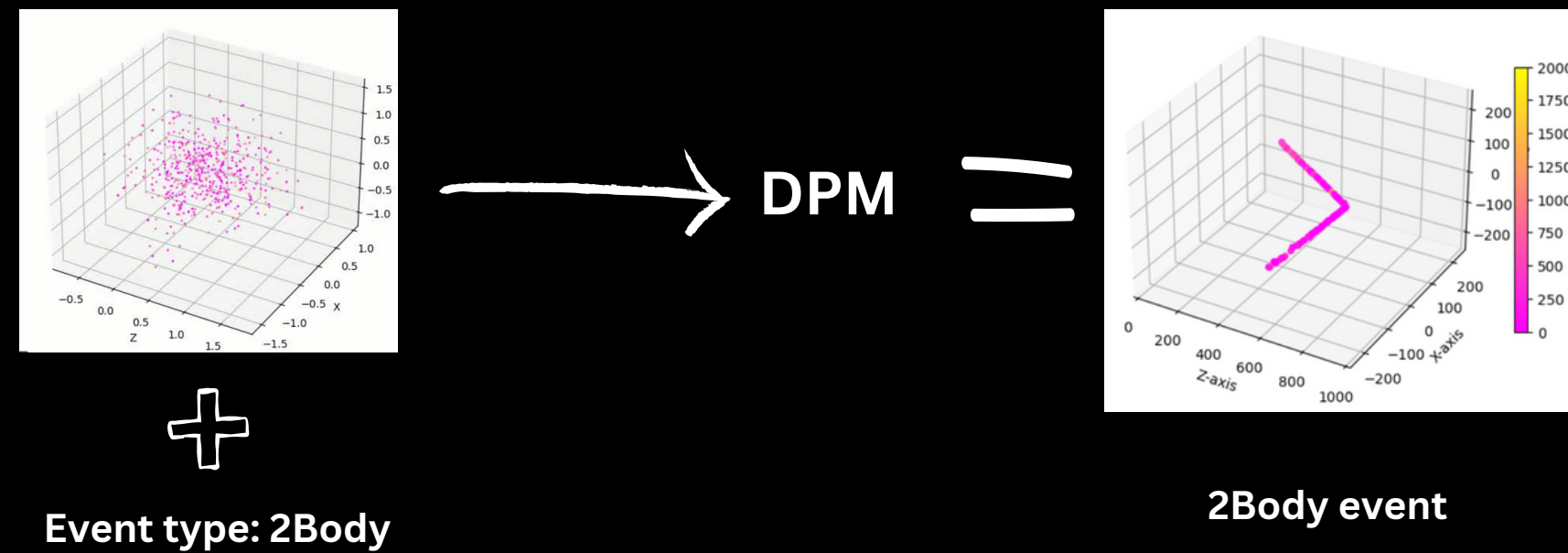
# First results: Real 2Body and Generated 2Body Events





# Next Steps

- Adding the condition of what type of event to generate





*Thank  
you!*