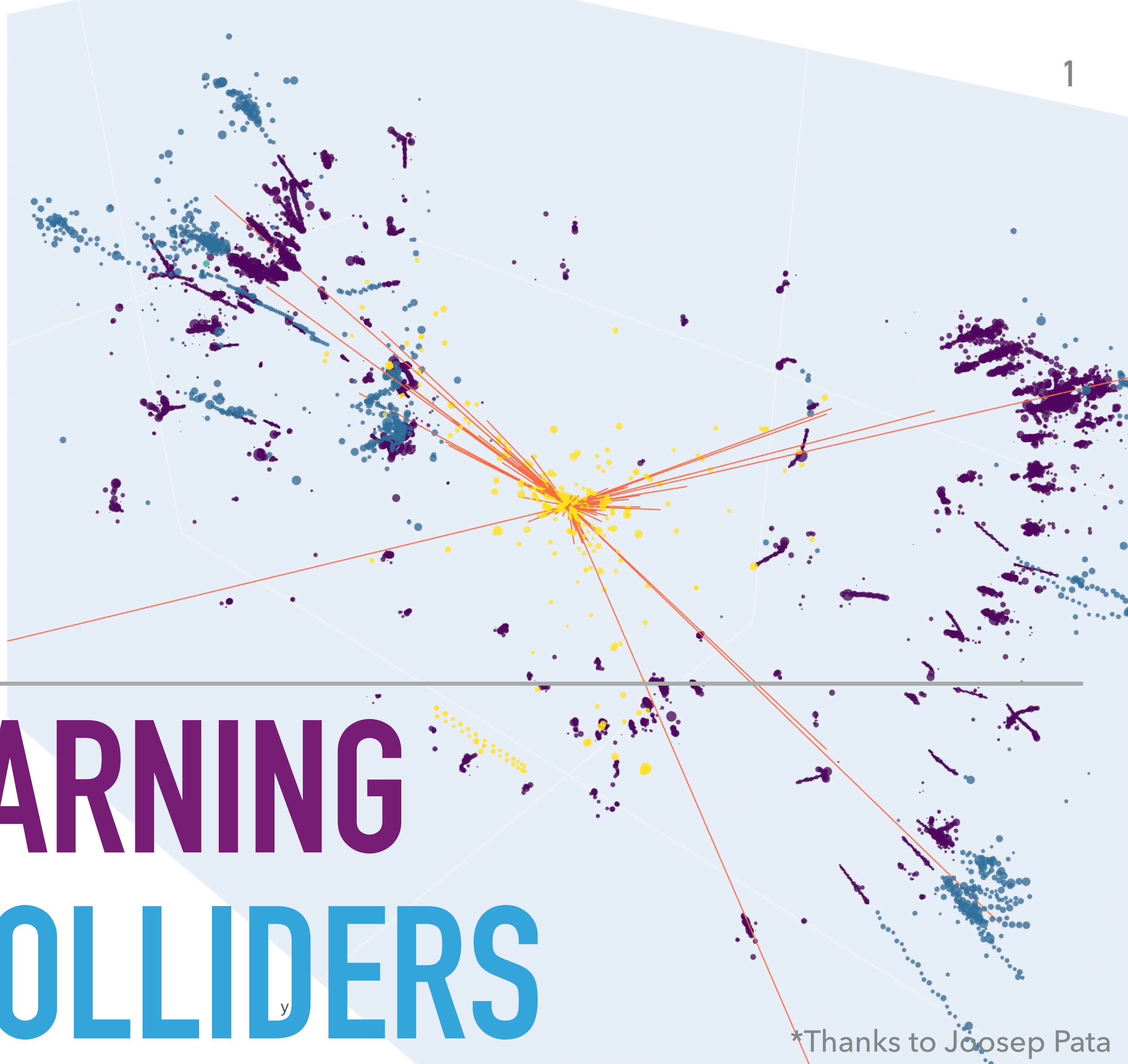


JAVIER DUARTE*
FUTURE OF HIGH ENERGY PHYSICS
ASPEN CENTER FOR PHYSICS
MARCH 29, 2024

MACHINE LEARNING AT FUTURE COLLIDERS

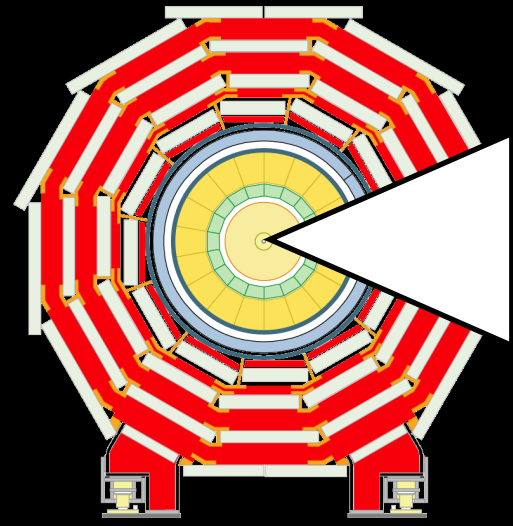


*Thanks to Joosep Pata

- ▶ Machine learning has already changed the way we do particle physics *from trigger/data acquisition to event reconstruction, simulation, data analysis, and interpretation*
 - ▶ It is an essential and versatile tool that we use to improve existing approaches
 - ▶ It enables fundamentally new approaches
- ▶ In this talk, I'll describe one thread where ML can shift/inform the paradigm

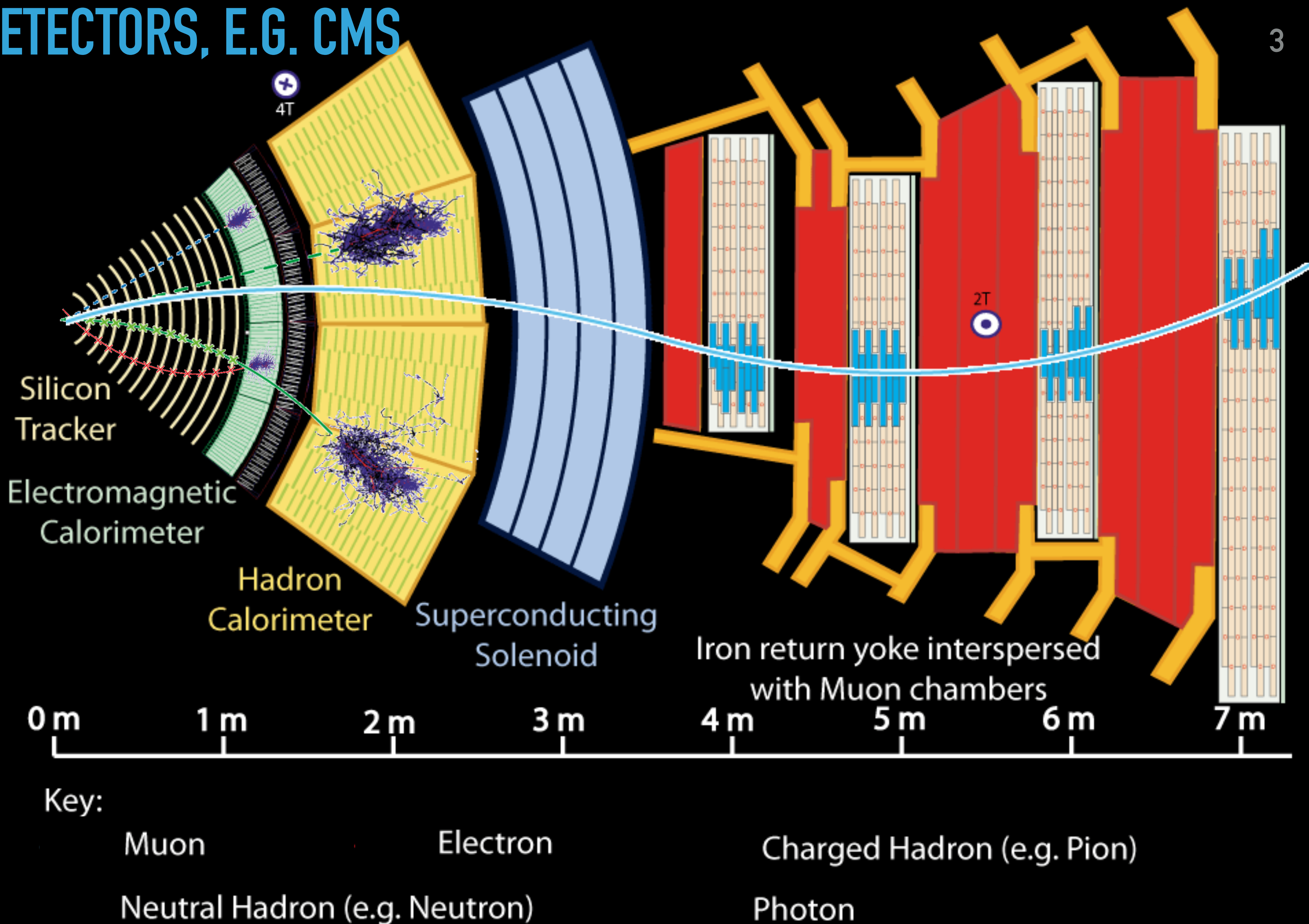


MULTILAYERED DETECTORS, E.G. CMS

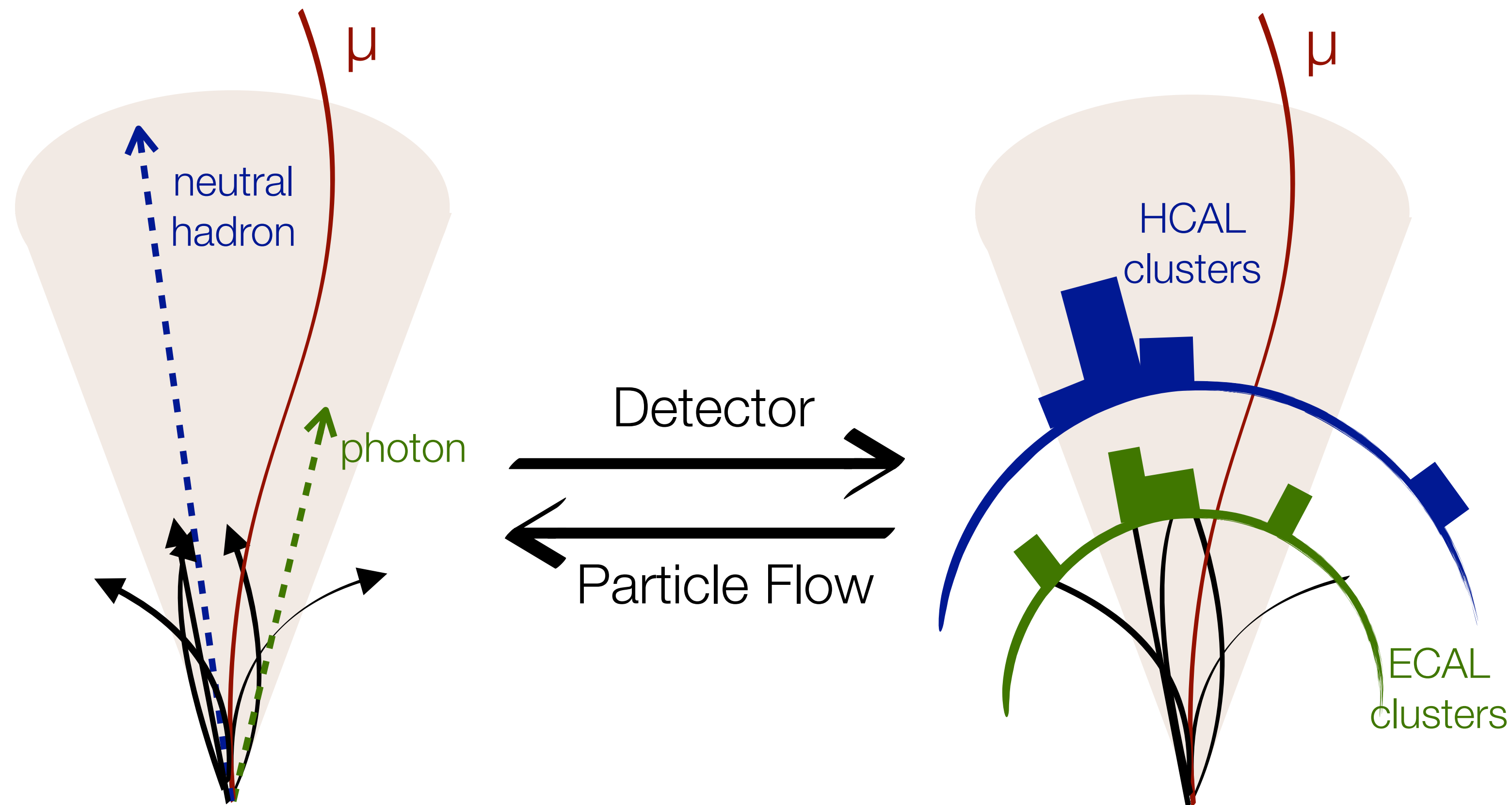


Current and future multilayered detectors...

Require complex reconstruction
→ particle-flow algorithm

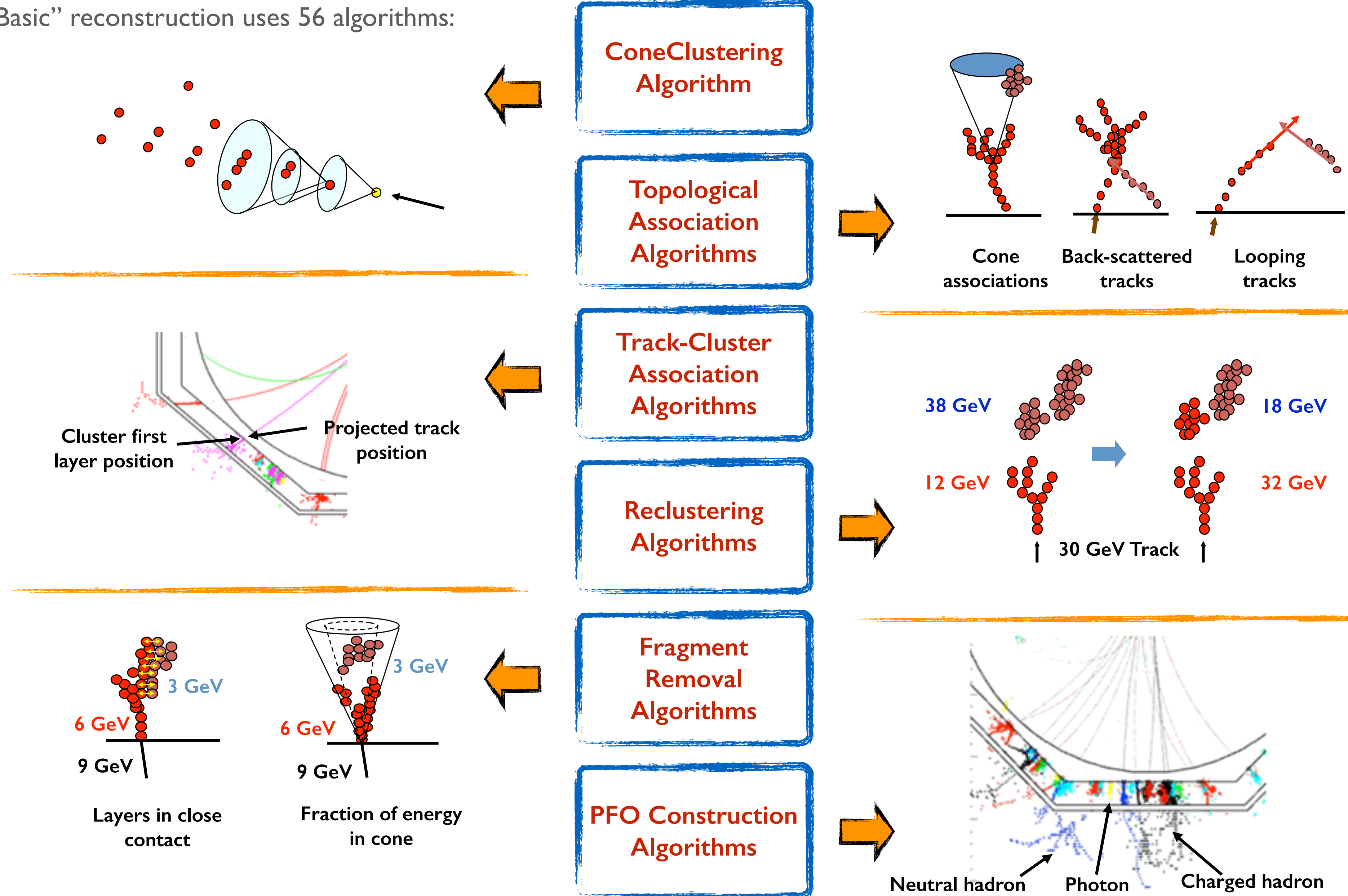


- ▶ Particles interact with detector, leaving energy deposits and tracks
- ▶ Efficient combination of info. from complementary detector subsystems to produce a holistic, particle interpretation of the event (that improves on any individual subsystem)



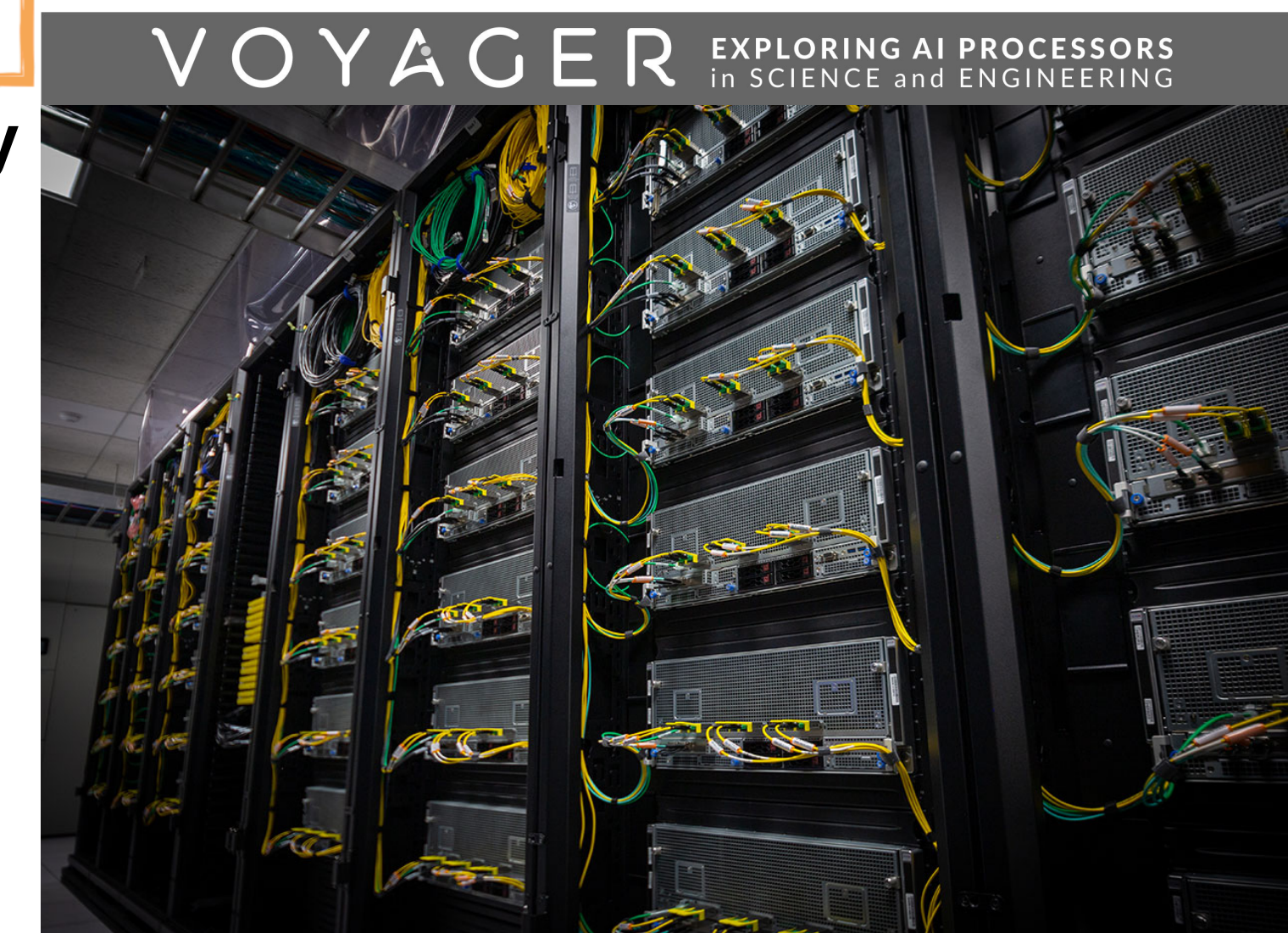
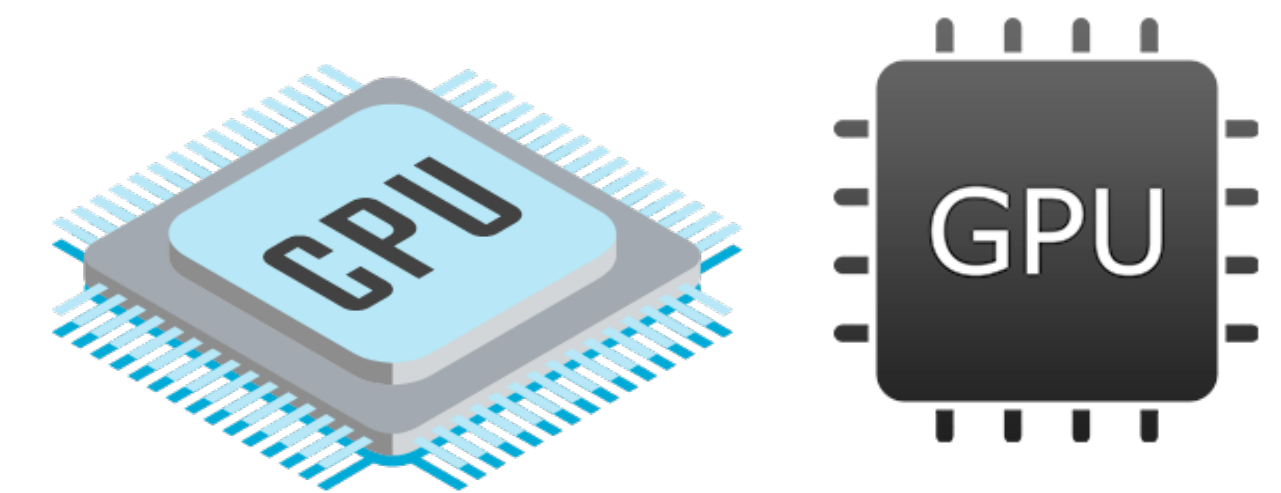
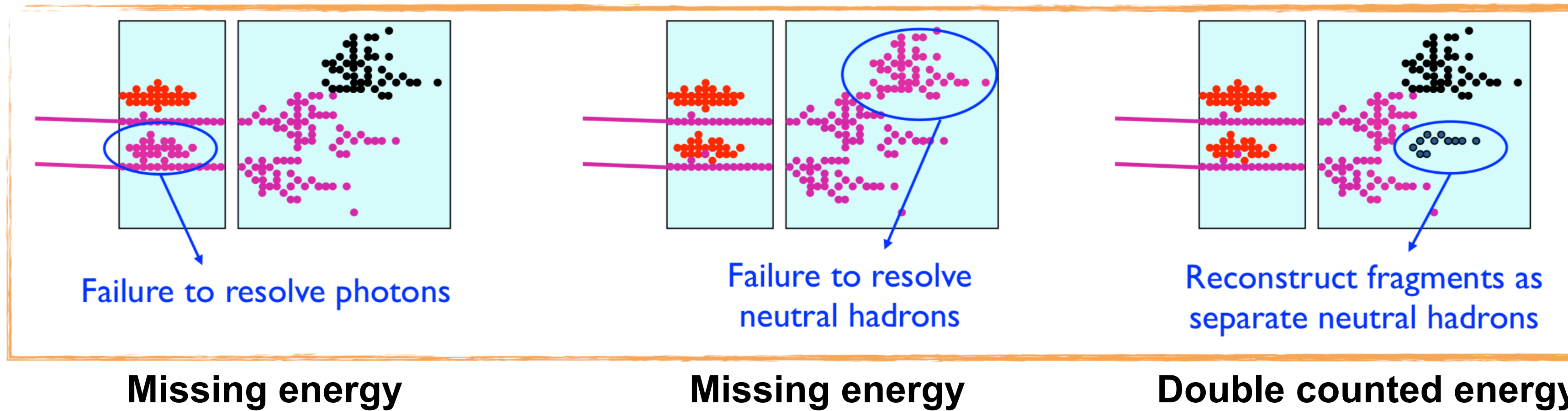
Existing particle-flow algorithms based on complex, hand-tuned heuristics work well

“Basic” reconstruction uses 56 algorithms:

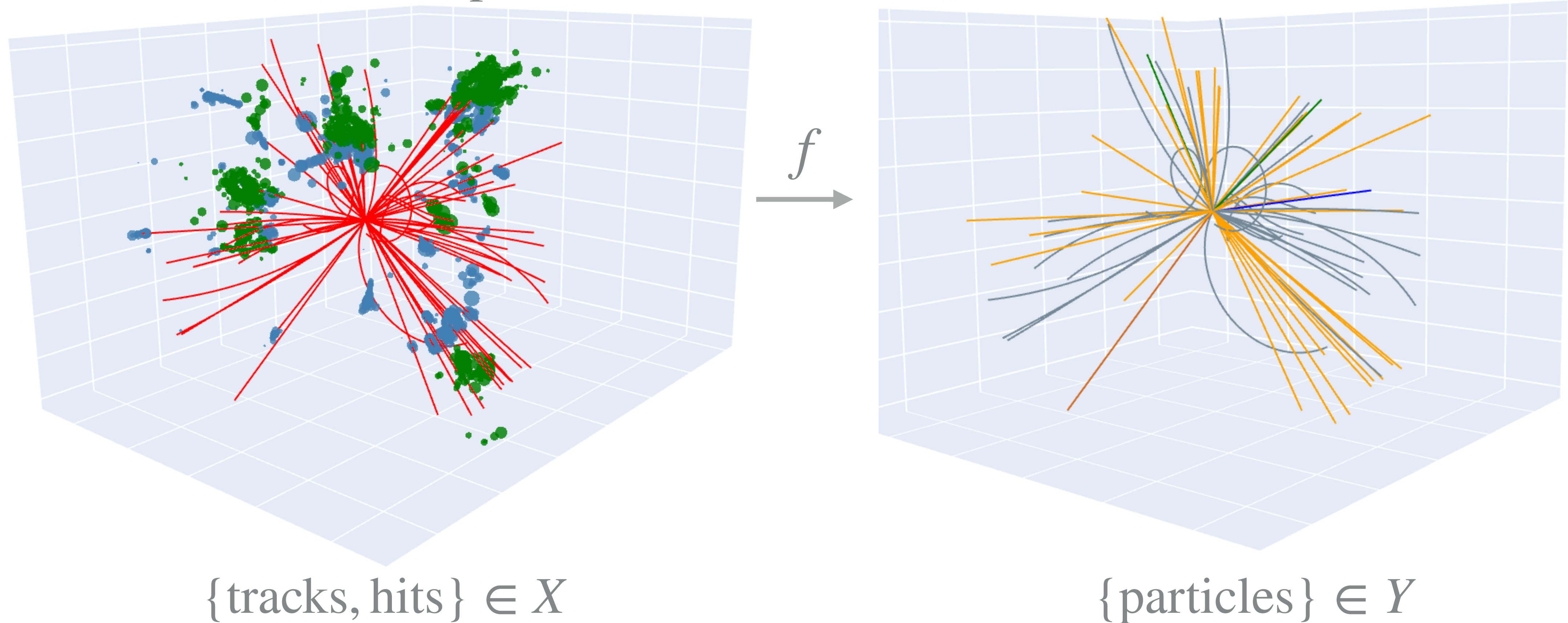


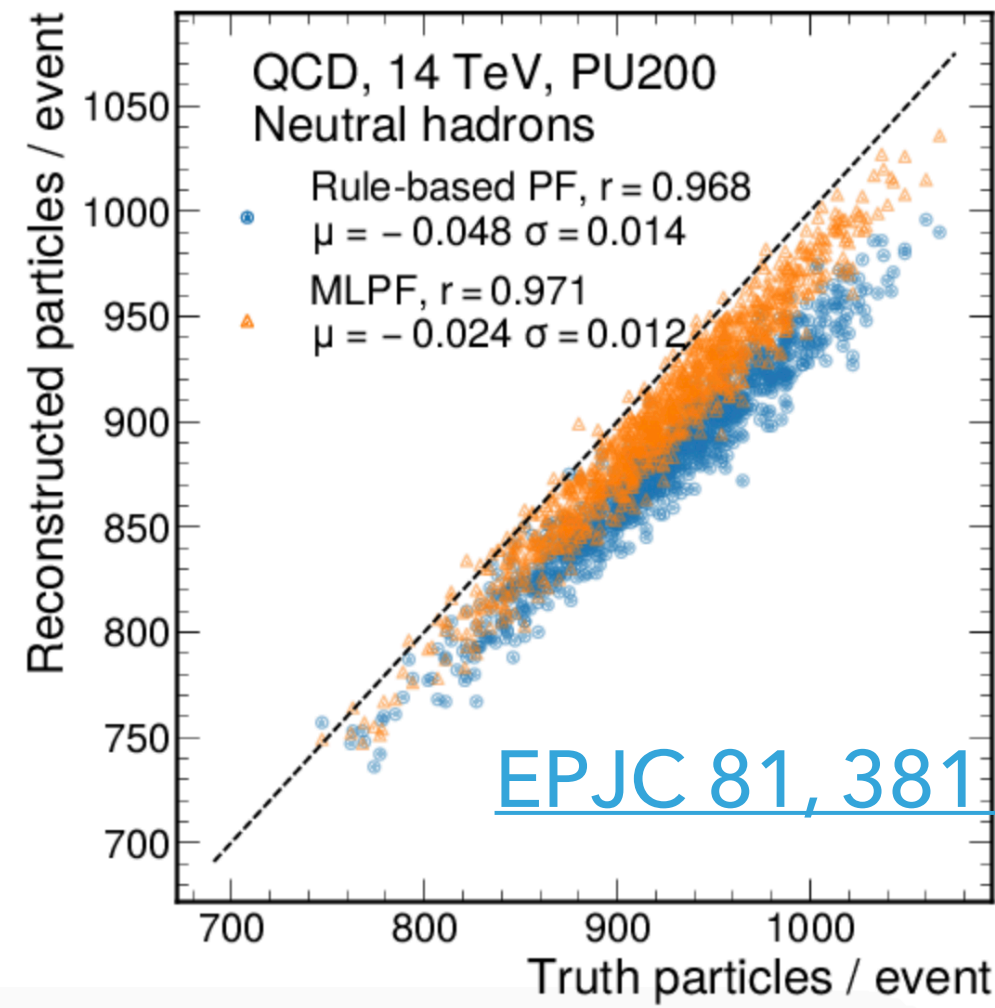
- ▶ Our heuristics fail in some ambiguous situations
- ▶ Traditional PF algorithms can be tricky to extend, tune, apply to different/new detectors, or port to new computational hardware or HPCs

Types of confusion



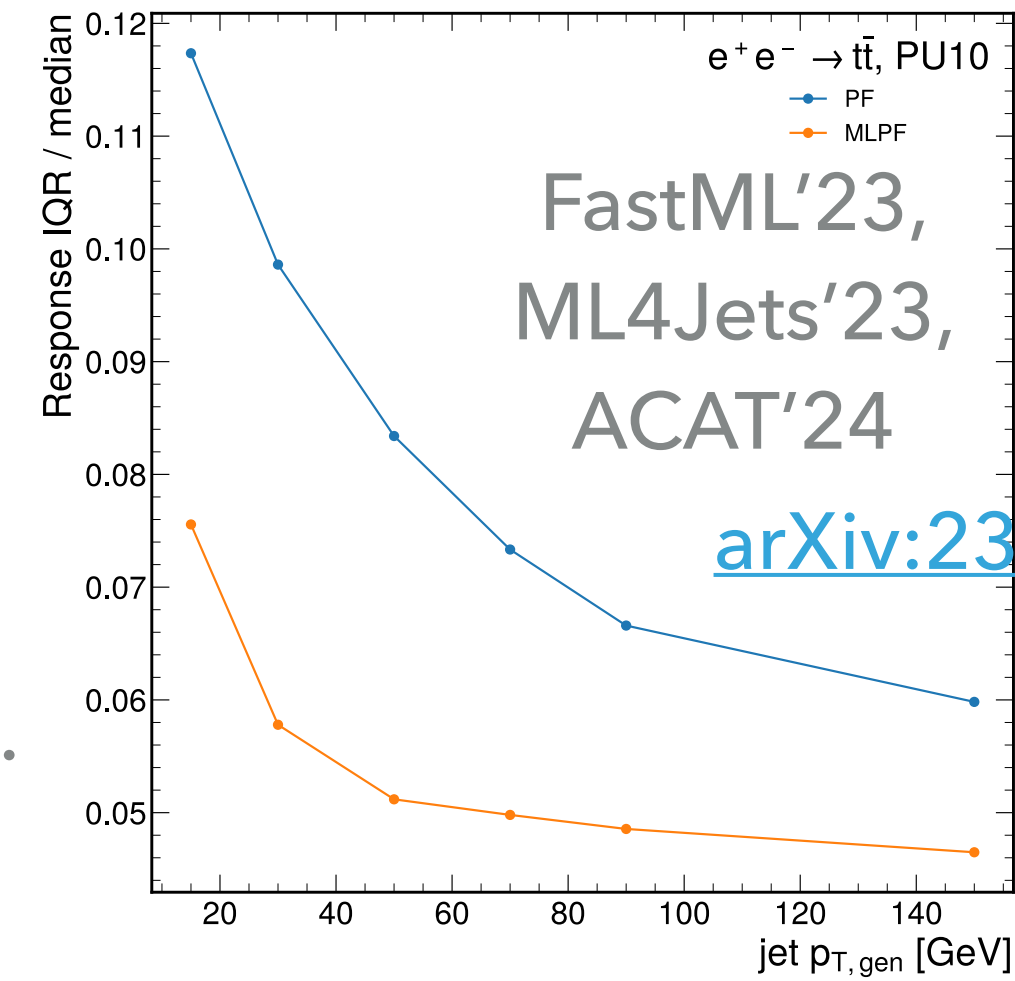
- ▶ Can we instead formulate PF as an ML task (naturally “tunable” through re-training and portable to new hardware)?
- ▶ Learn a “set-to-set” function $f: X \rightarrow Y$, where $\{\text{tracks, clusters}\} \in X$ or $\{\text{tracks, hits}\} \in X$ and $\{\text{particles}\} \in Y$





pp, generic detector,
proof of concept on Delphes sim.

[EPJC 81, 381 \(2021\)](#)



FastML'23,
ML4Jets'23,
ACAT'24

[arXiv:2309.06782](#)

e^+e^- , CLIC detector,
event-level SOTA on full sim.

2020

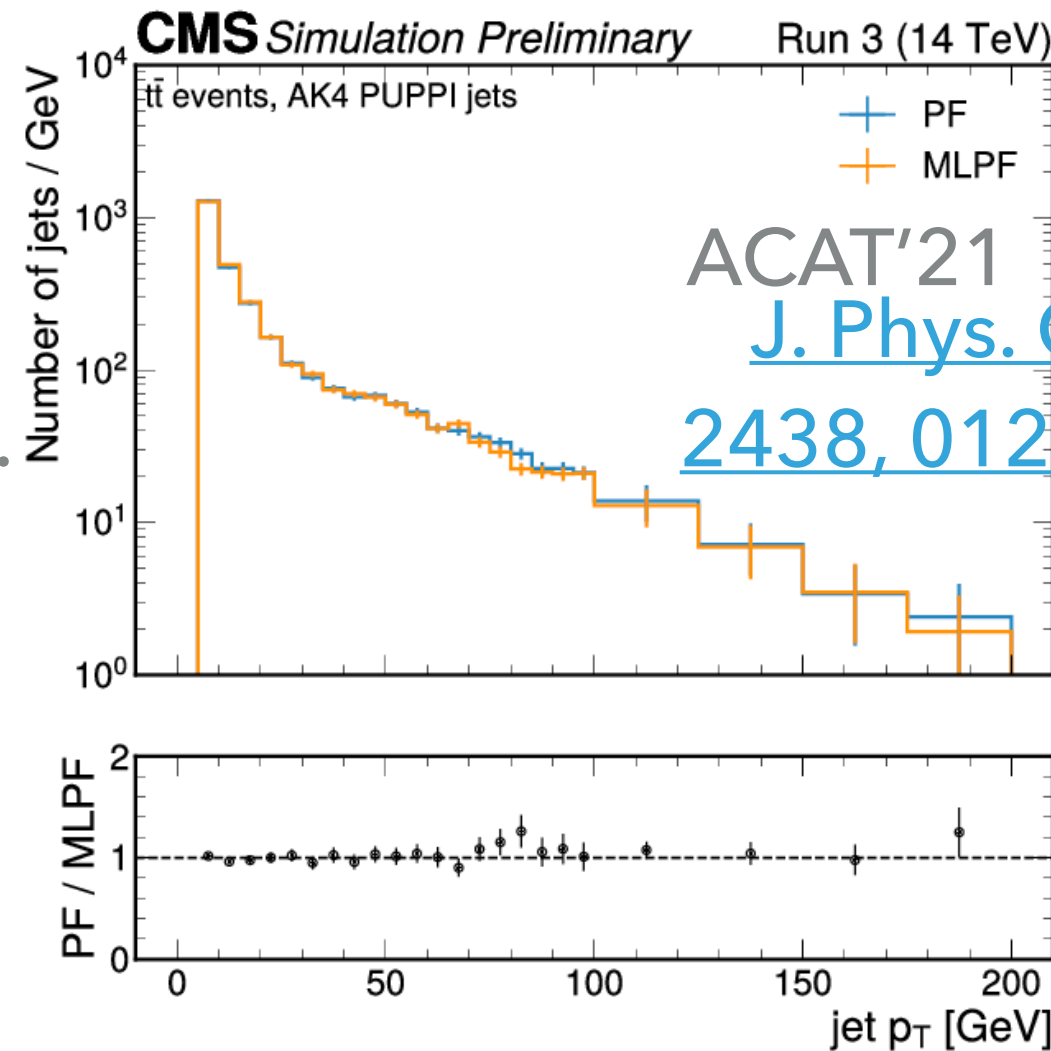
2021

2022

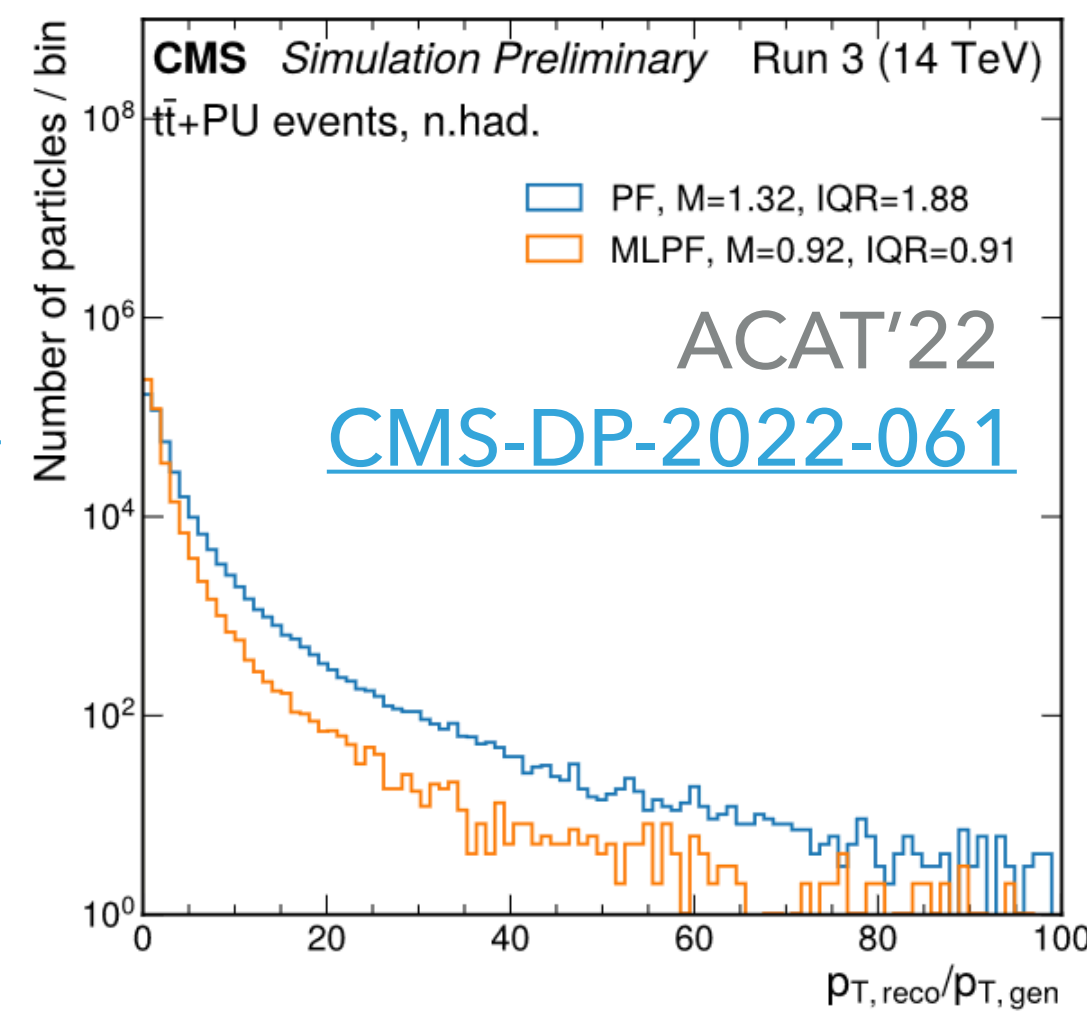
2023

2024

pp, CMS detector,
proof of concept on full sim.



ACAT'21
[J. Phys. Conf. Ser.](#)
[2438, 012100 \(2023\)](#)



ACAT'22
[CMS-DP-2022-061](#)

pp, CMS detector,
particle-level SOTA on full sim.

Improved particle-flow event reconstruction with scalable neural networks for current and future particle detectors

Joosep Pata^{1*}, Eric Wulff², Farouk Mokhtar³, David Southwick²,
Mengke Zhang³, Maria Girone², Javier Duarte³

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Switzerland.

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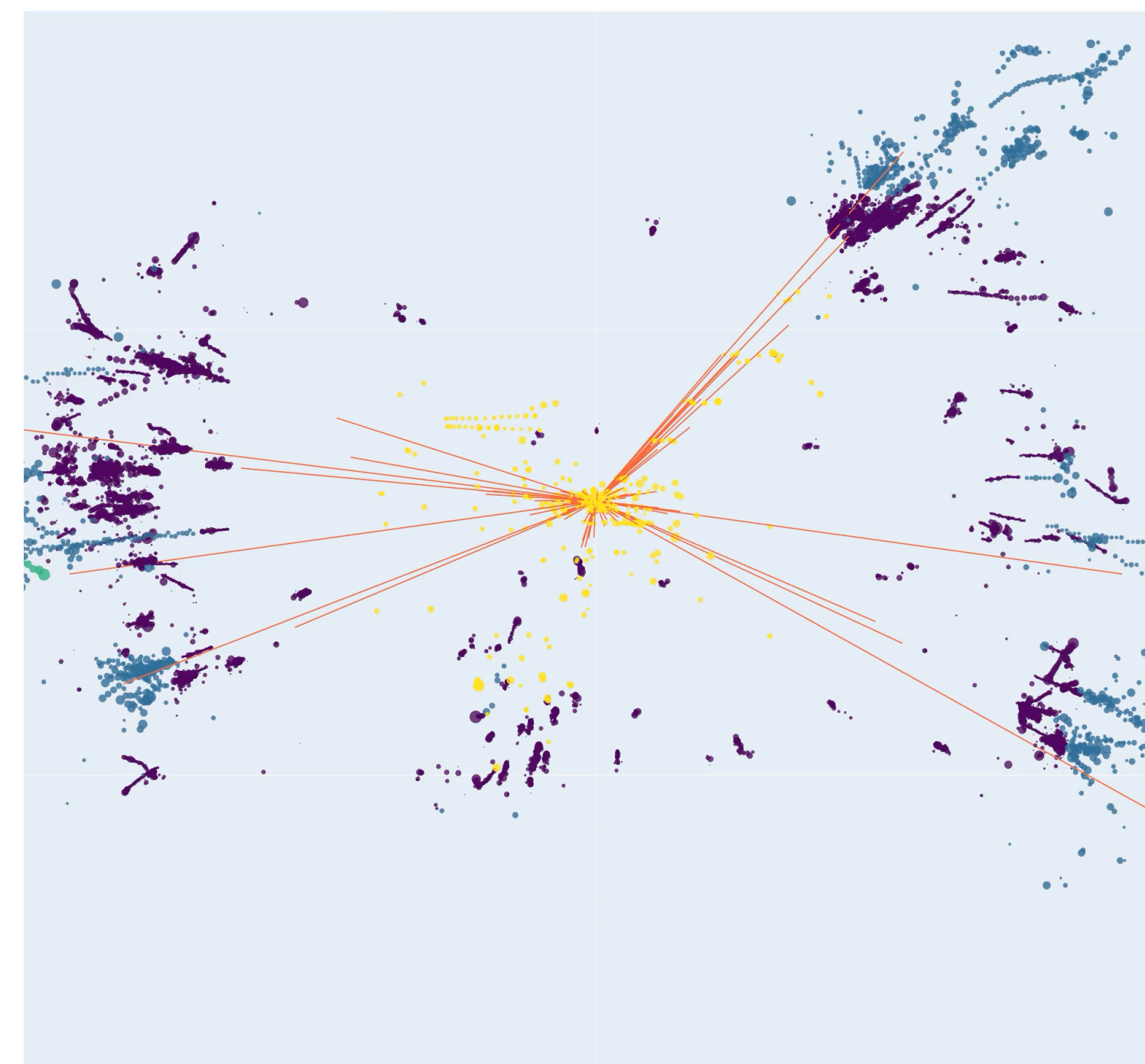
*Corresponding author(s). E-mail(s): joosep.pata@cern.ch;
Contributing authors: eric.wulff@cern.ch; fmokhtar@ucsd.edu;
david.southwick@cern.ch; mezhang@ucsd.edu; maria.girone@cern.ch;
jduarte@ucsd.edu;



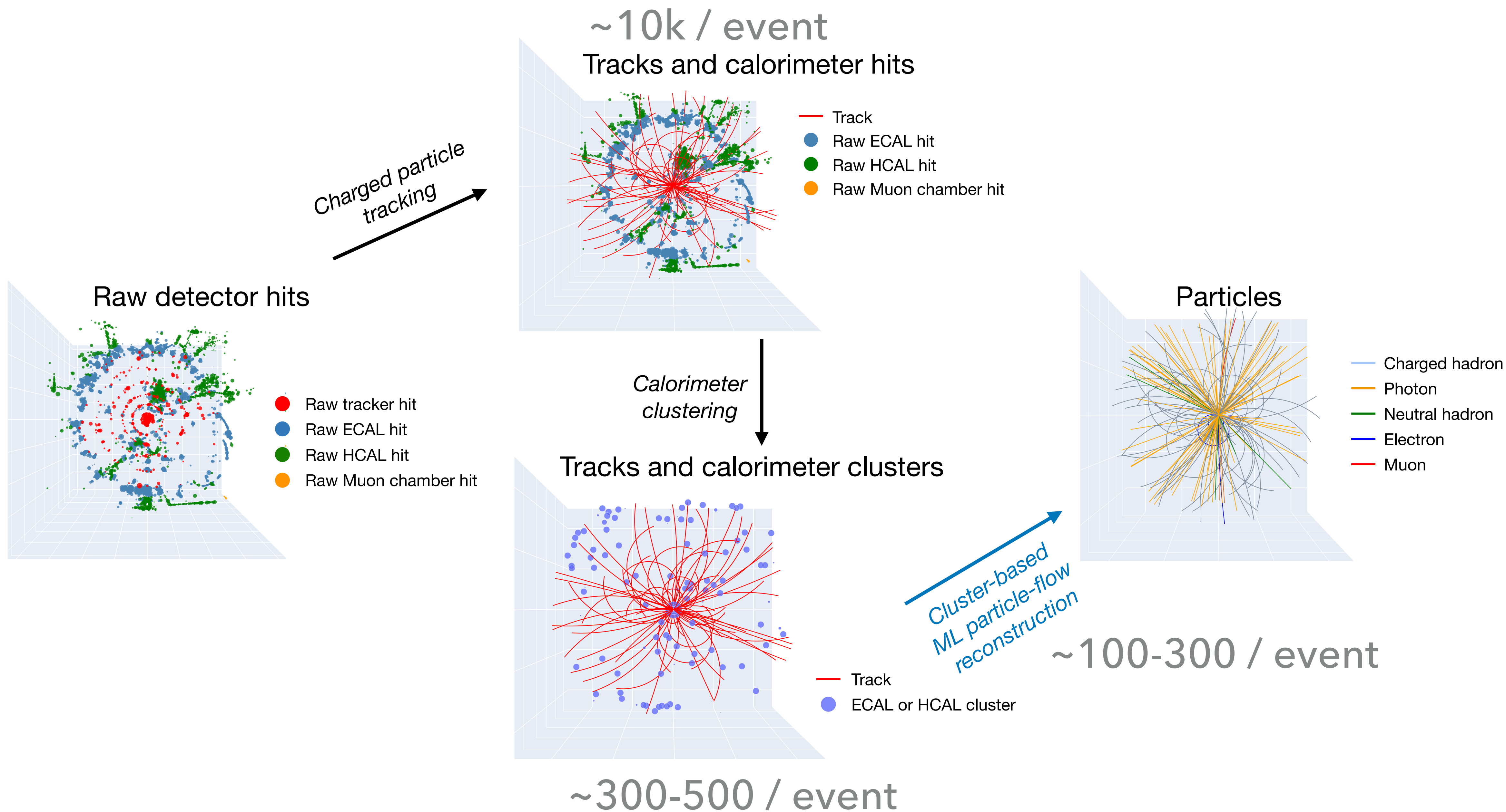
- ▶ Gen. particles, reco. tracks and calorimeter hits, reco. Pandora PF particles in EDM4HEP format
- ▶ CLIC detector ([CLIC_o3_v14](#)) simulation with Geant4, reco. with Marlin interfaced via Key4HEP including Pandora PF reco.
- ▶ Processes generated with Pythia8 at $\sqrt{s} = 380 \text{ GeV}$
 - ▶ $e^+e^- \rightarrow t\bar{t}, q\bar{q}, ZH(\tau\tau), WW, t\bar{t} + \text{PU10}$
 - ▶ Single-particle: $e^\pm, \mu^\pm, K_L^0, n, \pi^\pm, \gamma$ between $[1, 100] \text{ GeV}$
- ▶ 2.5 TB, 6 million events in total

Particle Flow Reconstruction

Scalable Neural Network Models and Terascale Datasets



<https://www.coe-raise.eu/od-pfr>

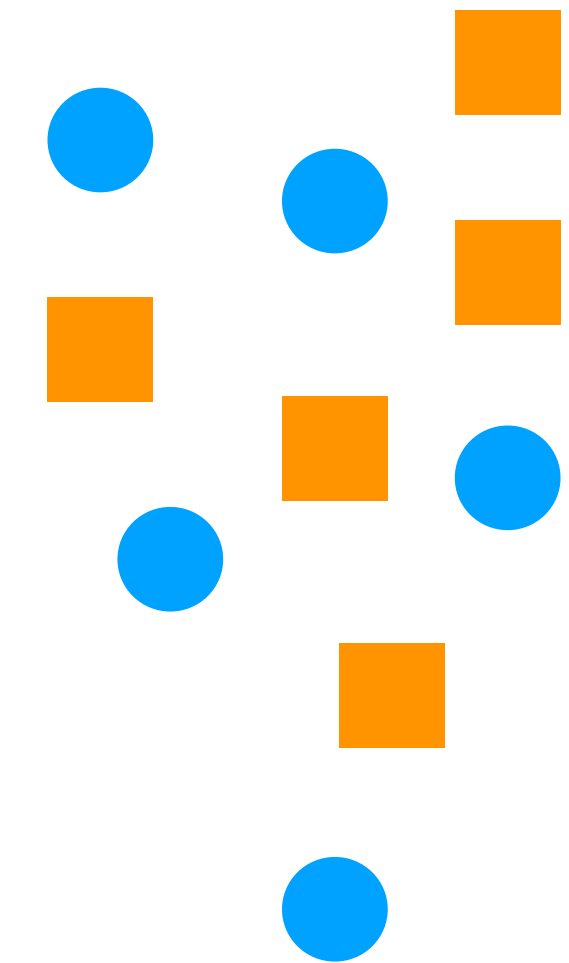


- ▶ Formulate task as node prediction with data preprocessing
- ▶ Input set arranged in (arbitrarily ordered) matrix

$$x_i^{\text{track}} = [p_T, \eta, \phi, \chi^2, N_{\text{dof}}, \tan \lambda, D_0, \Omega = \text{sign}(q)/R, Z_0]$$

$$x_i^{\text{cluster}} = [E_T, \eta, \phi, E_{\text{ECAL}}, E_{\text{HCAL}}, x, y, z, N_{\text{hit}}, \sigma_x, \sigma_y, \sigma_z]$$

Input set $X = \{x_i\}$

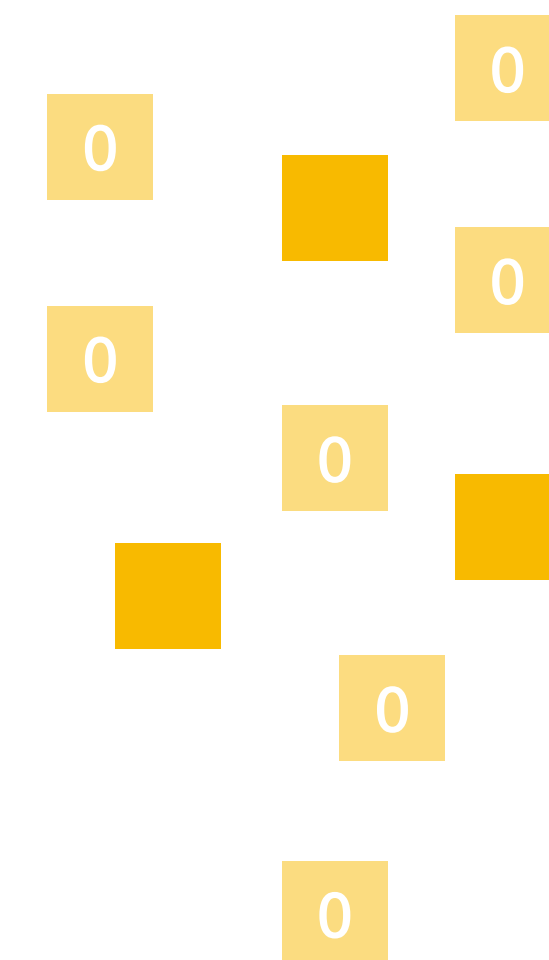


- ▶ Target set zero-padded to same size $|X| = |Y|$, with each output particle arranged in same array position as best-matched input element

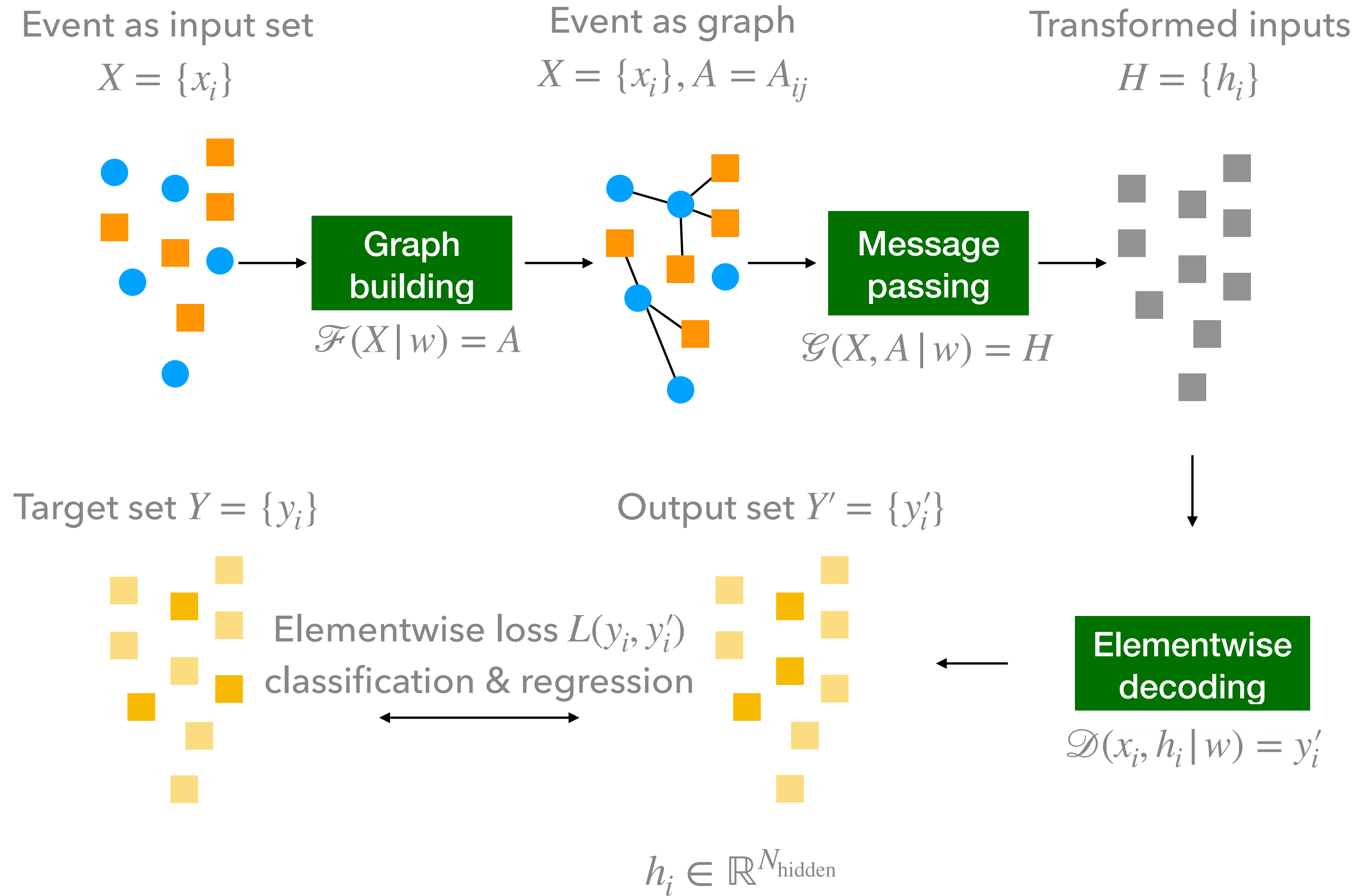
$$y_i = [\text{PID}, p_T, E, \eta, \phi, q]$$

$\text{PID} \in \{\text{none}, \text{charged hadron}, \text{neutral hadron}, \gamma, e^\pm, \mu^\pm\}$

Target set $Y = \{y_i\}$



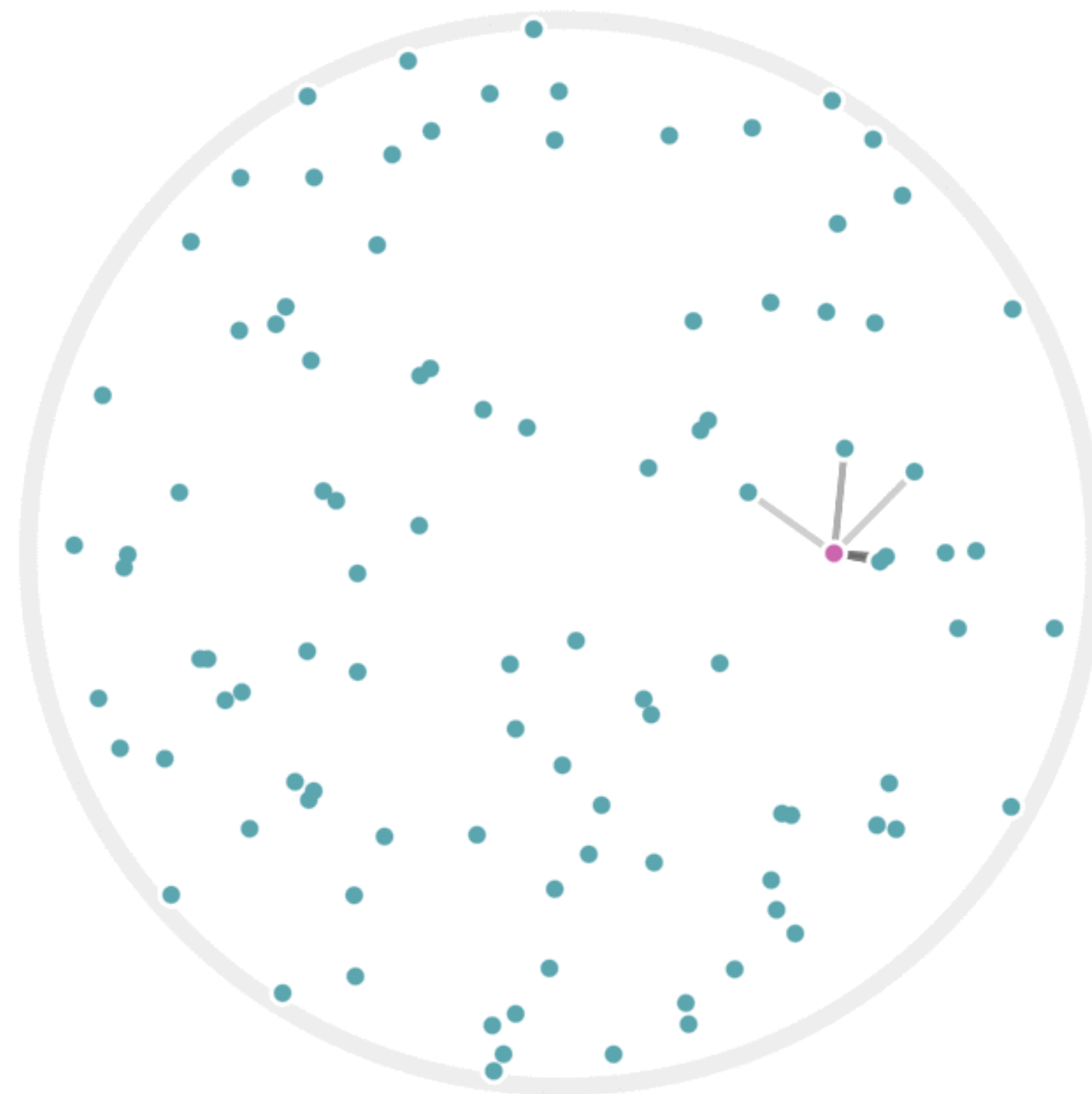
- ▶ Convert input set to a locally, **sparsely connected** graph
- ▶ Message-passing NN to transform features
- ▶ Decode transformed inputs elementwise
- ▶ (During training) Compare to target set, optimize weights



Trainable neural networks: $\mathcal{F}, \mathcal{G}, \mathcal{D}$

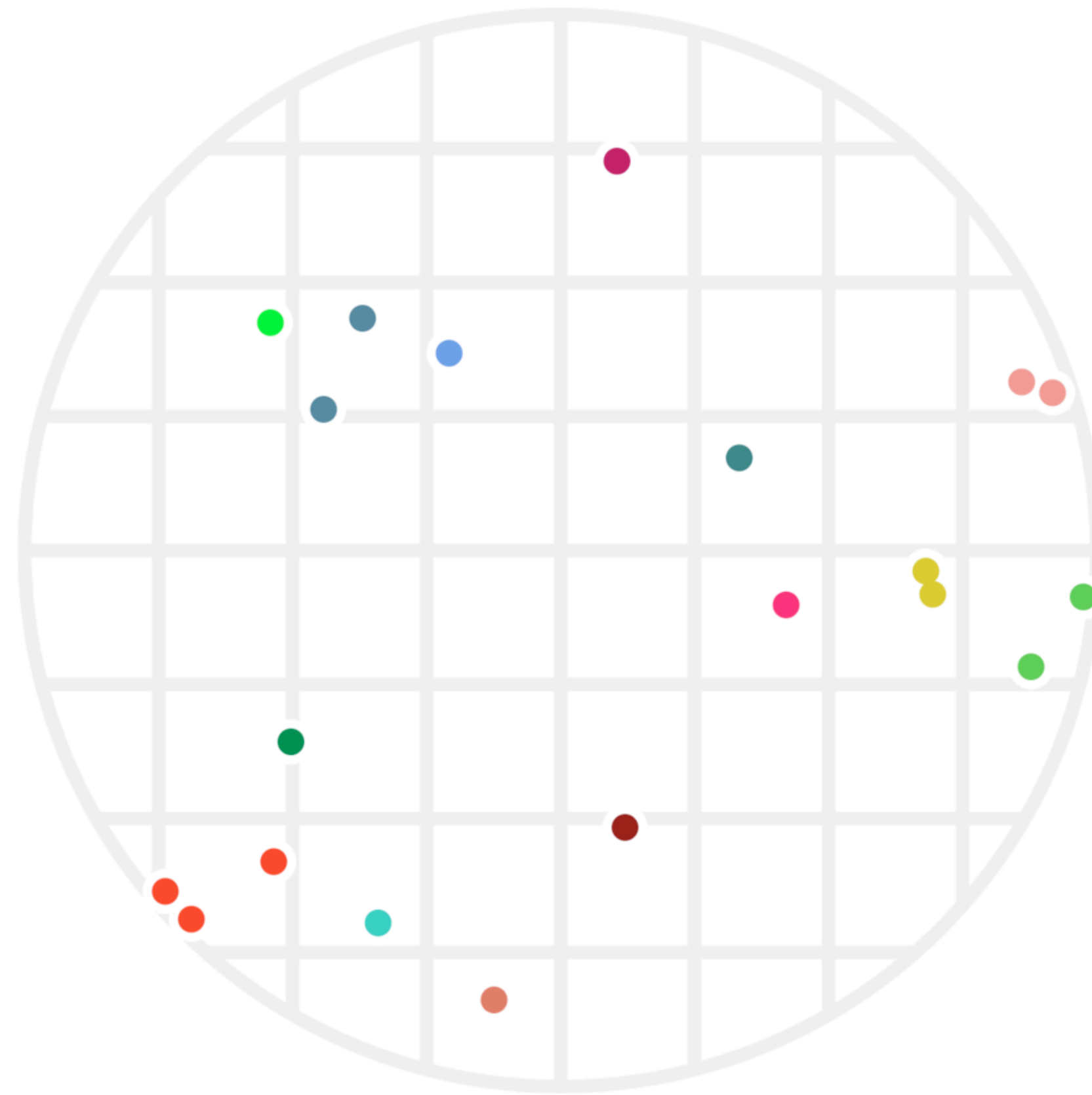
- Track, ■ Calorimeter cluster, ■ Encoded element
- Target (predicted) particle, ■ No target (predicted) particle

Naive nearest neighbors graph building: need to compare each pair of particles, $\mathcal{O}(N^2)$ complexity



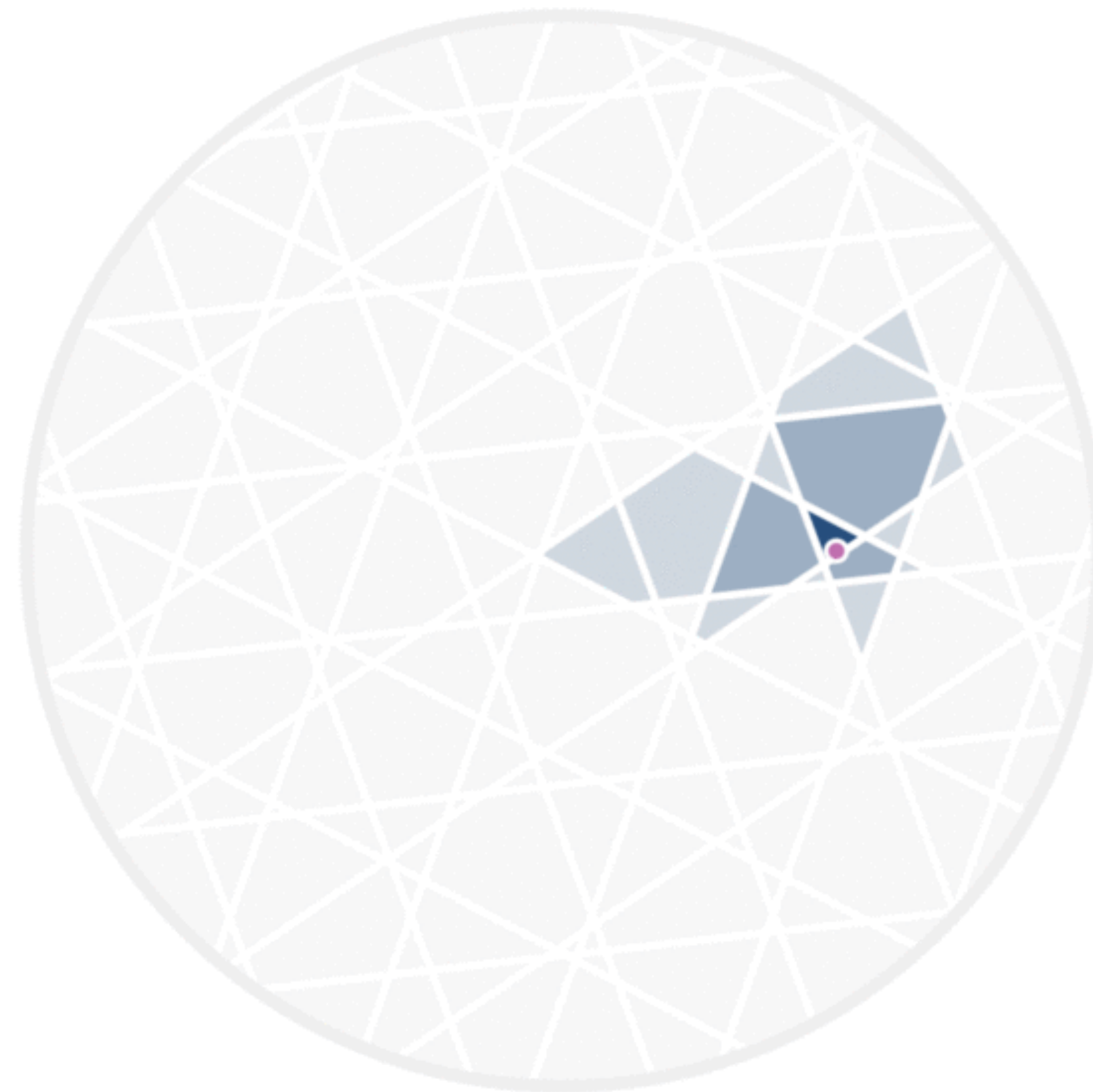
$\mathcal{O}(N^2)$ complexity plagues other SOTA ML approaches like *transformers*

Divide space into bins, particles are *connected* if they are in the same bin



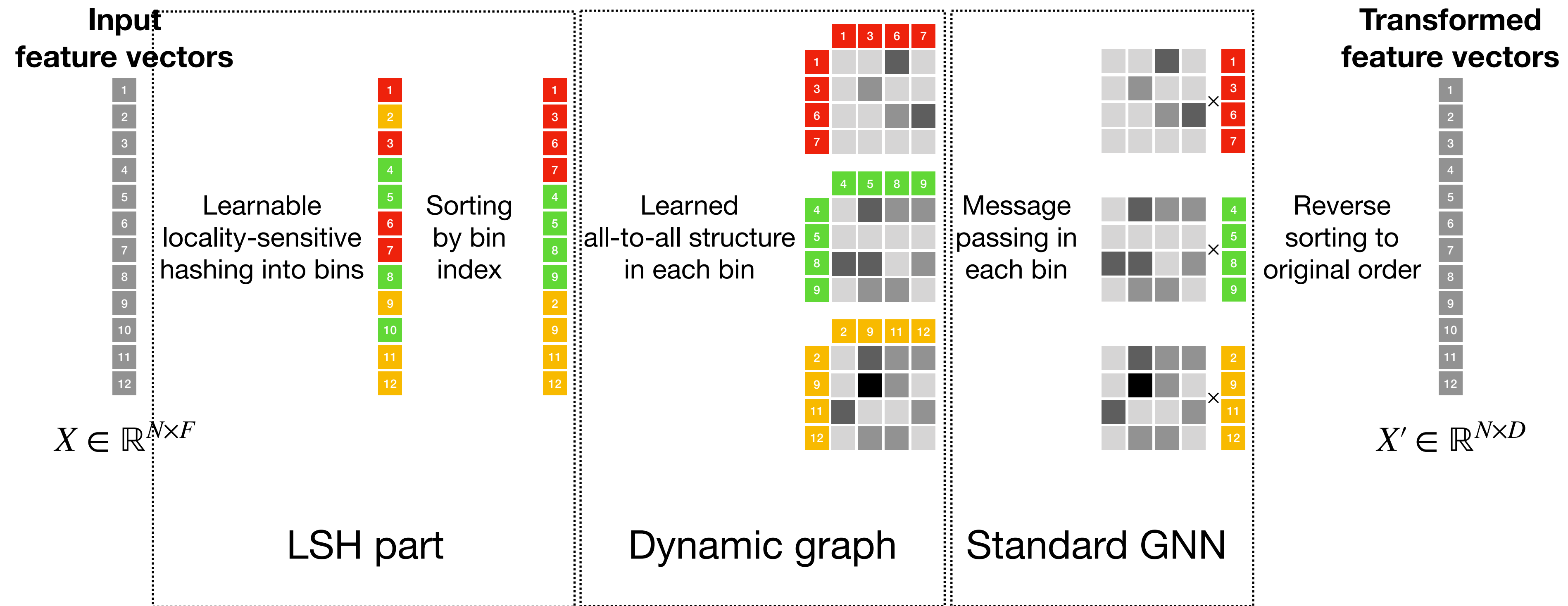
Hash function: particle features to bin index

Randomized bins (hash functions) work even better!



5 random hash functions, where darkest blue = 5 hash collisions, lightest blue = 3 hash collisions

Simple to implement in TensorFlow, PyTorch, JAX using native operations: high portability to Nvidia, AMD, Intel Gaudi, etc. today

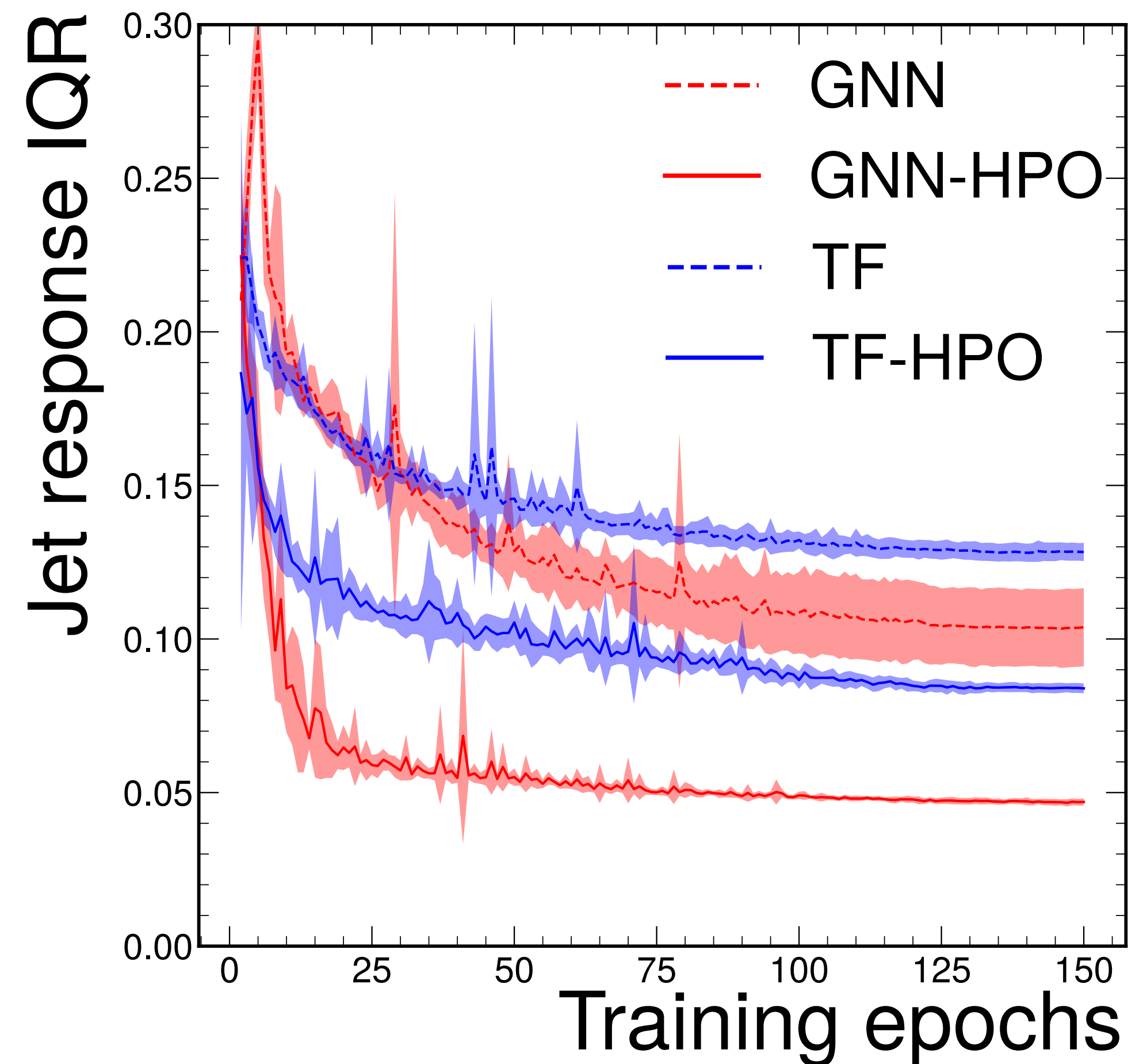
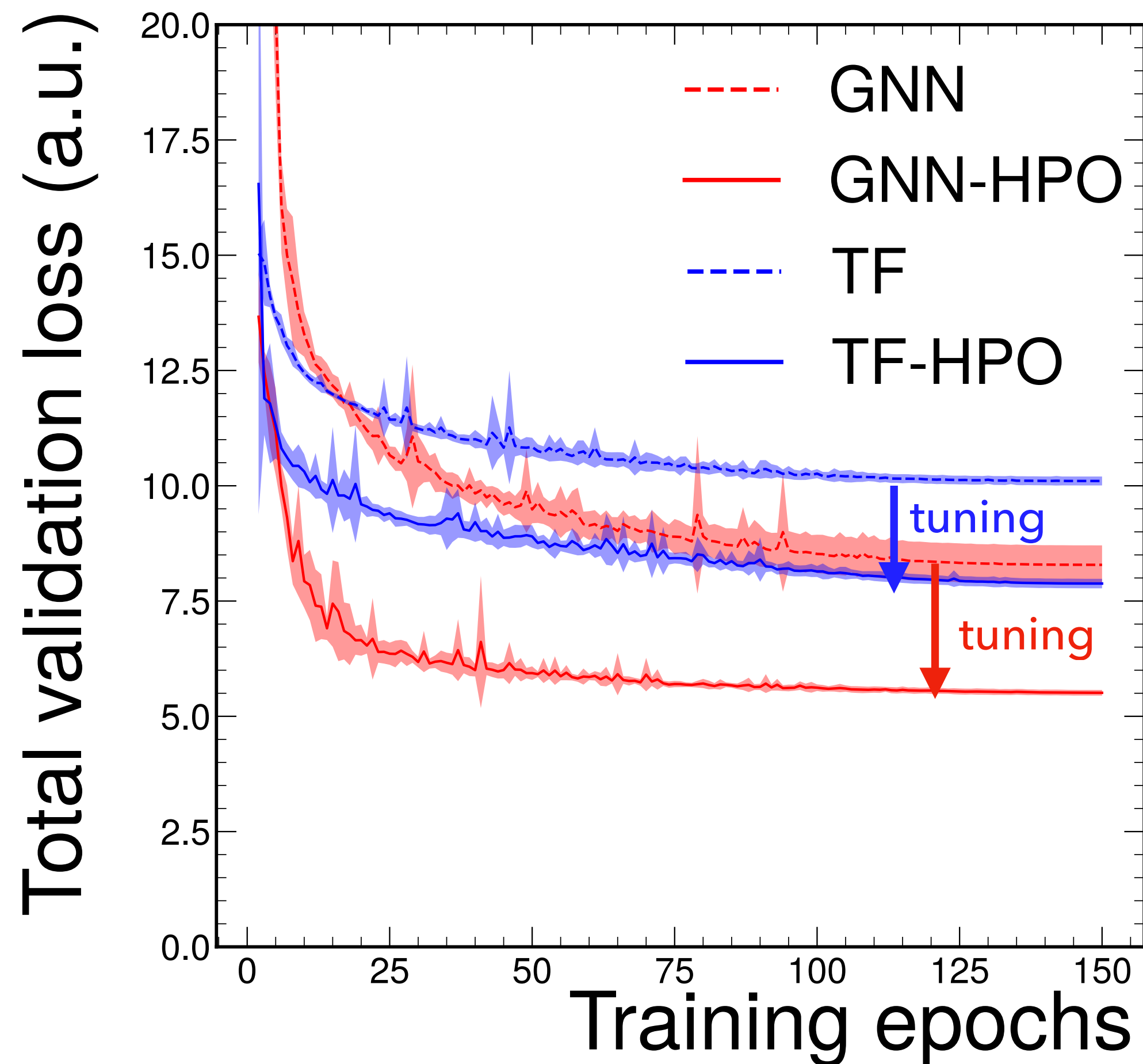


- ▶ One layer of scalable GNN based on Reformer [[arXiv:2001.04451](https://arxiv.org/abs/2001.04451)]
- ▶ Can stack them to form multilayered network that learns higher-level representations

- ▶ Many hyperparameters to tune, e.g. number of layers, hidden dimension of each layer, and LSH bin size
- ▶ Requires large compute

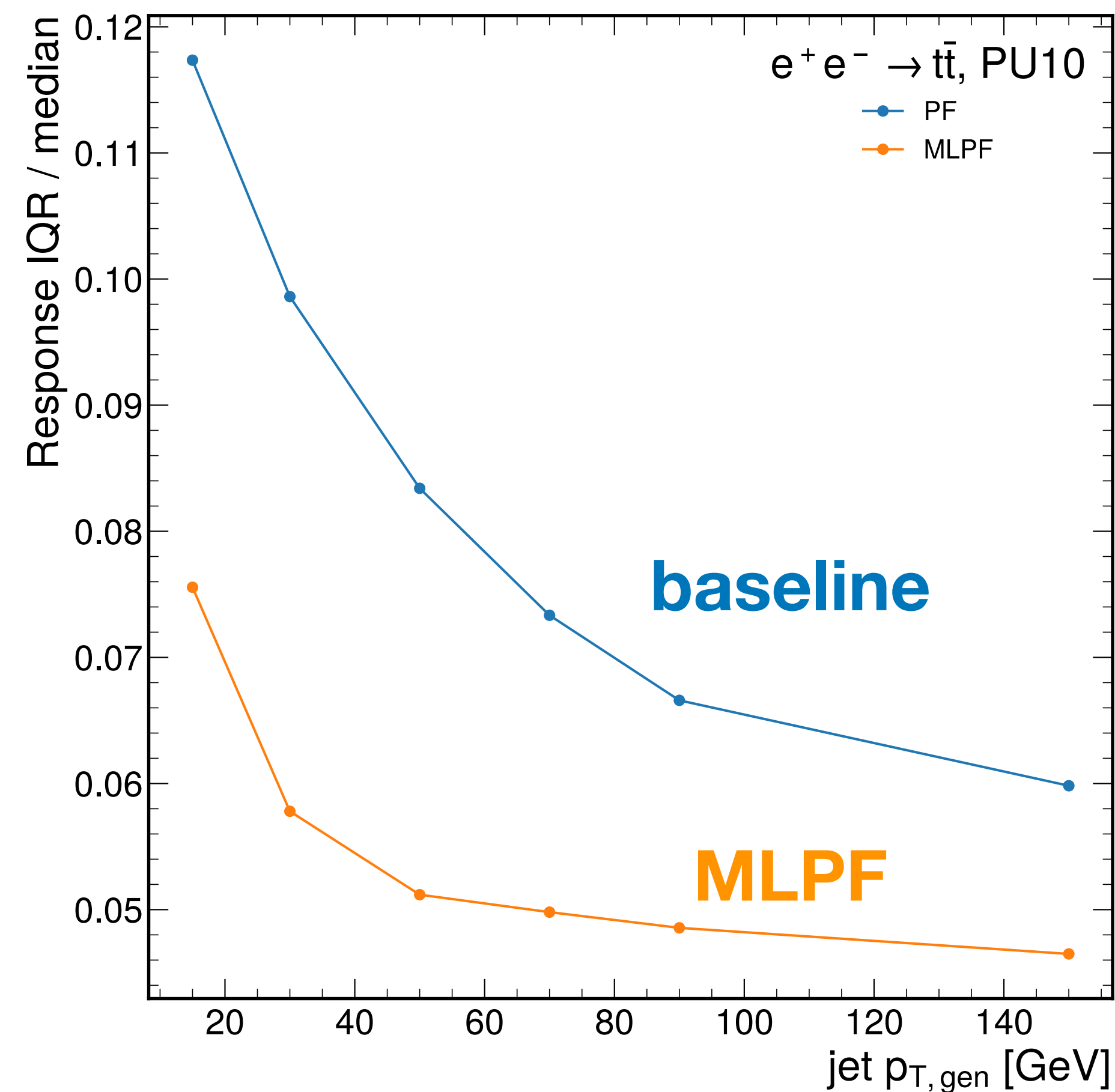
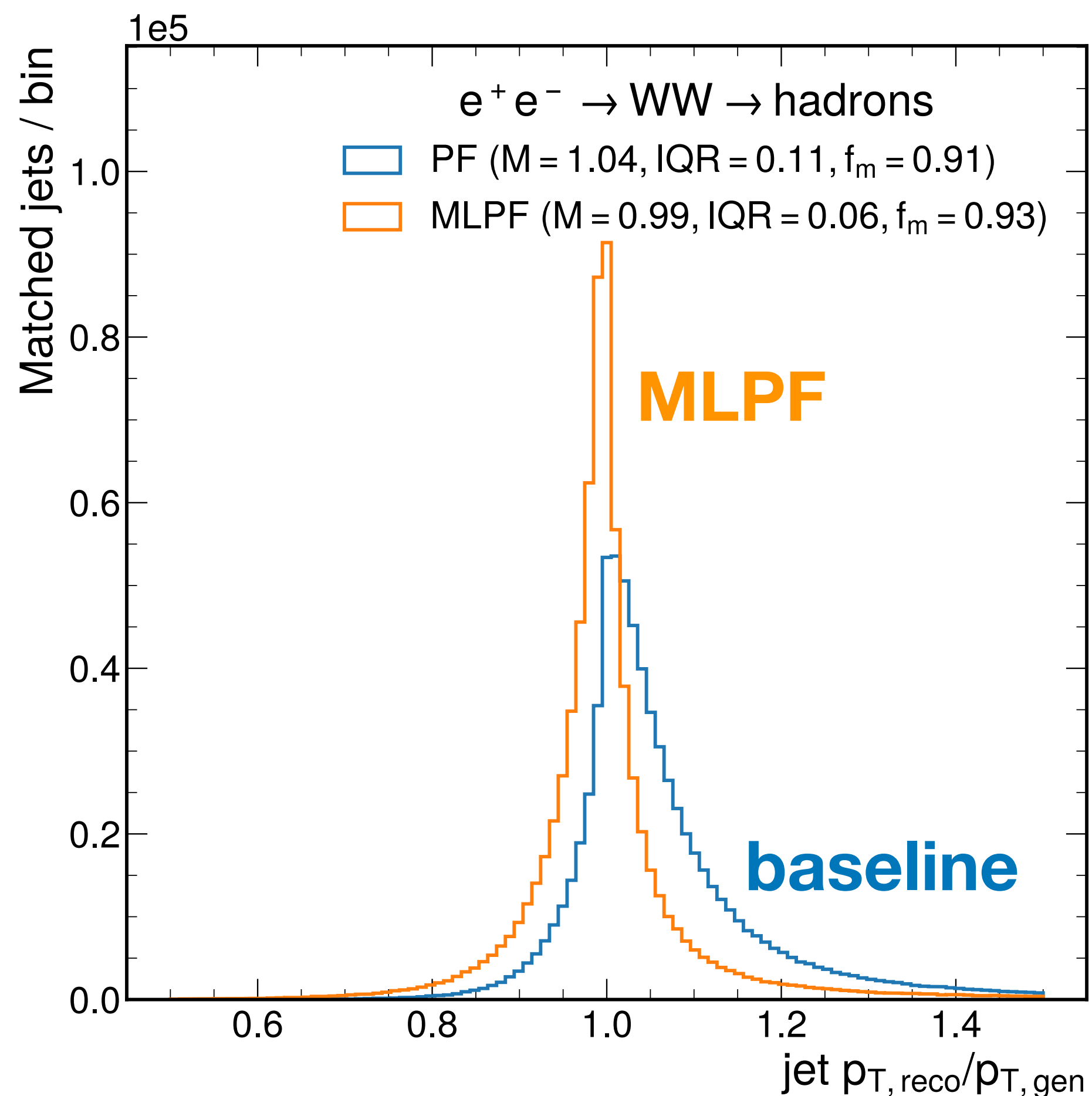


- ▶ Tuning improves particle-level performance dramatically (trained on $q\bar{q}, t\bar{t}$)
- ▶ Though we optimize a particle-level loss, also achieve better jet/MET resolution

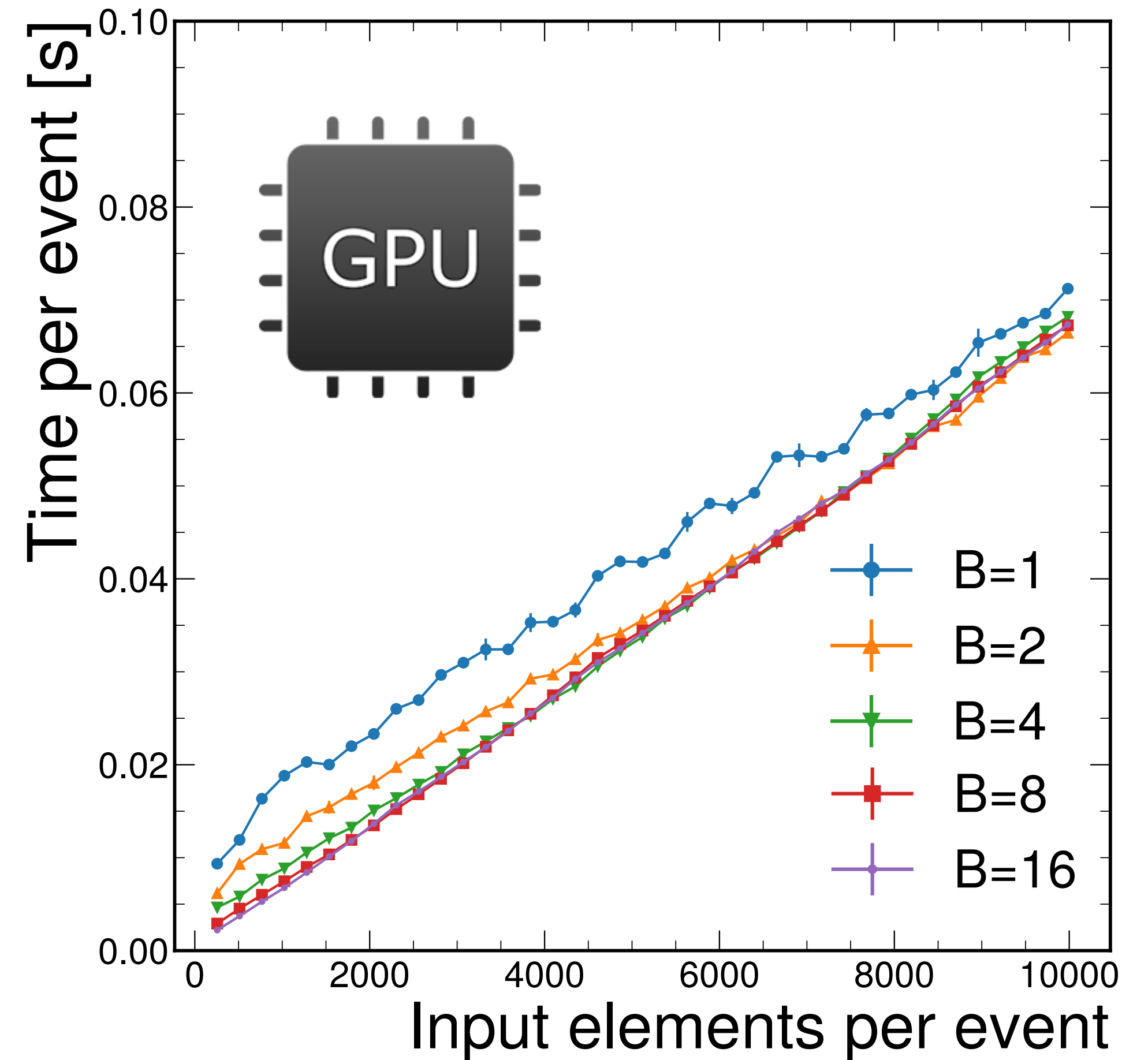
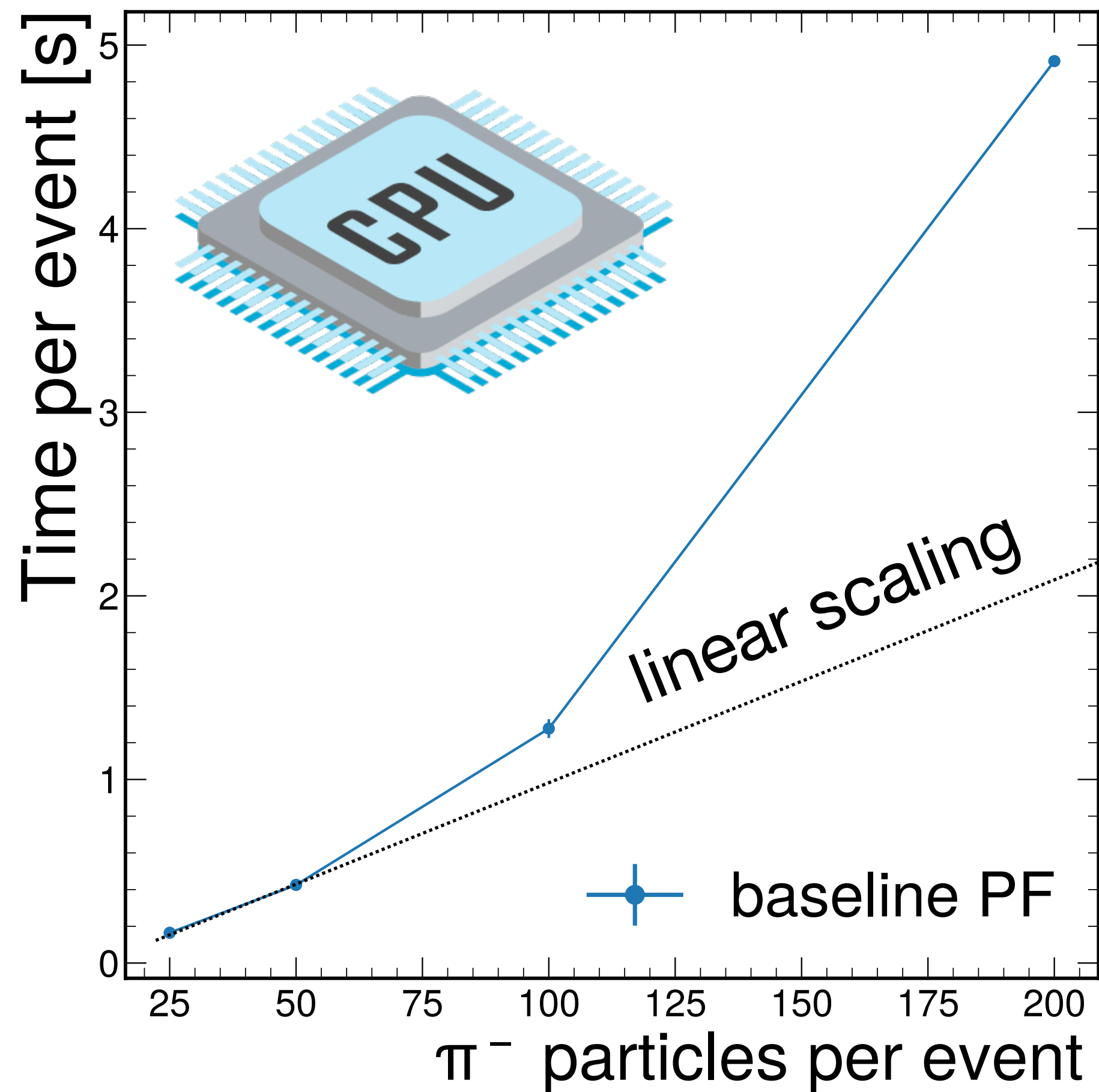


- ▶ Generalizes to samples (e.g., $e^+e^- \rightarrow WW \rightarrow$ hadrons) never used in training
- ▶ ~50% improvement in jet response width over the baseline*

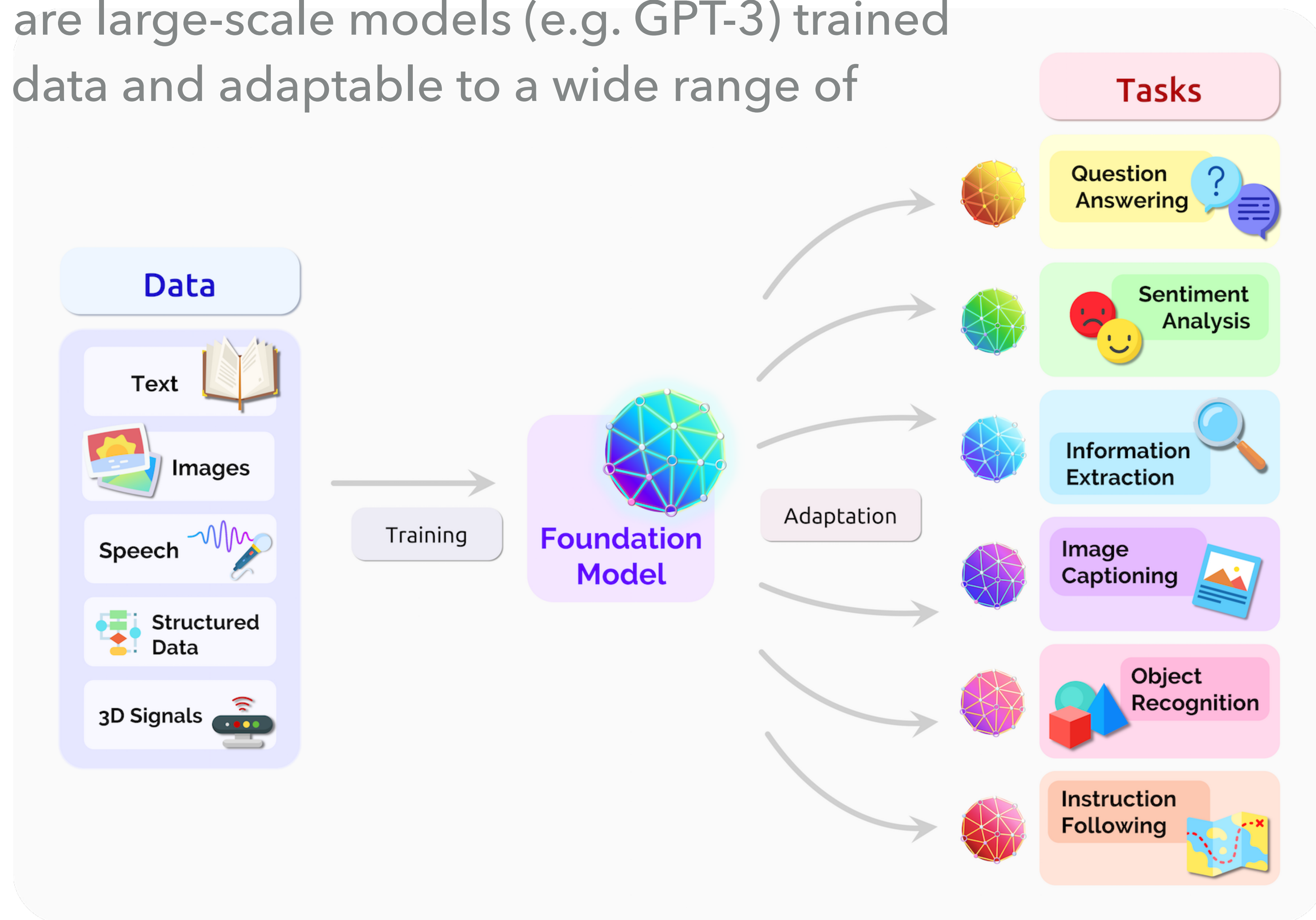
*Defined with gen. particle status = 1



- ▶ Baseline (untuned) algo. runs only on CPU, scales ~quadratically, runtime per event is in seconds
- ▶ ML model scales linearly, runs in milliseconds per event on a consumer 8 GB GPU

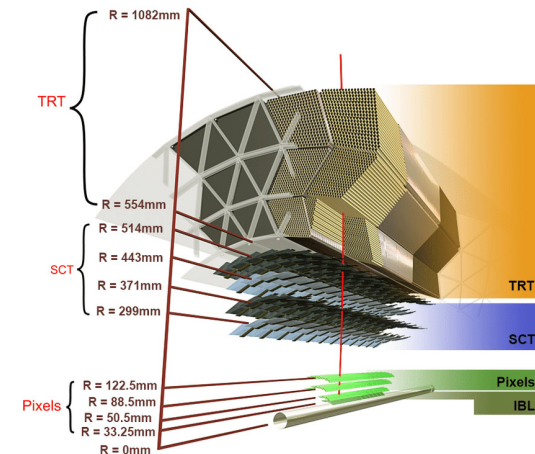


- ▶ “Foundation models” are large-scale models (e.g. GPT-3) trained on broad multimodal data and adaptable to a wide range of downstream tasks

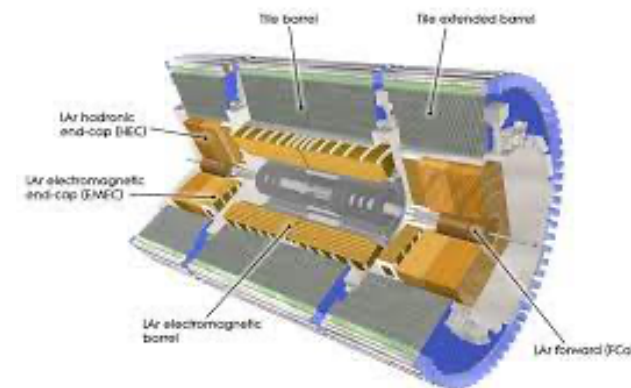


- ▶ Reconstruction in HEP is analogous to a foundation model
- ▶ With ML-based reconstruction, can take this analogy more literally and fine-tune reconstruction for different needs, e.g. analysis or new detector concepts

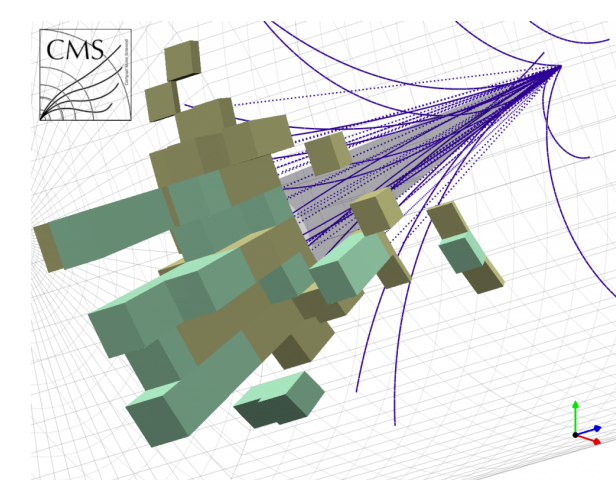
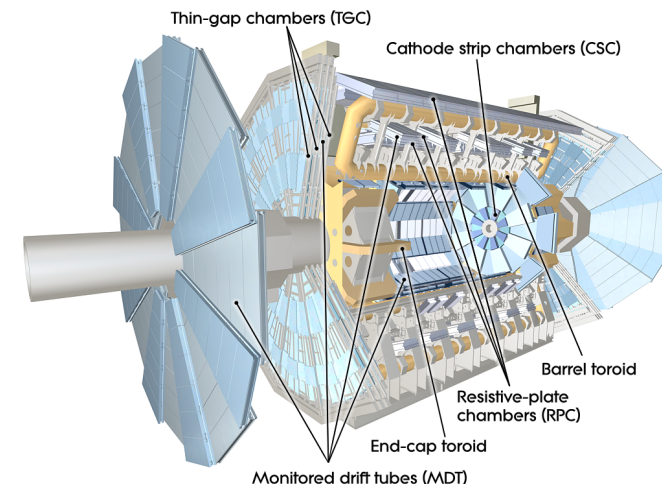
Tracking Data



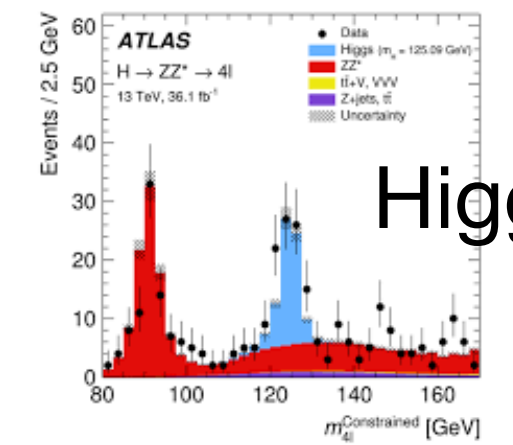
Calorimeter



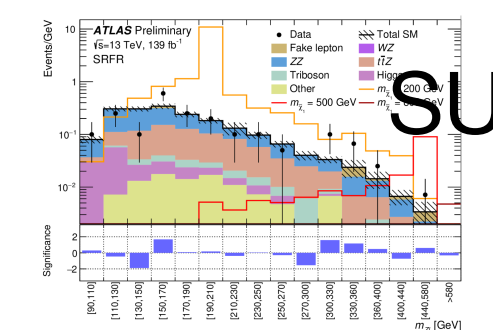
Muon Data



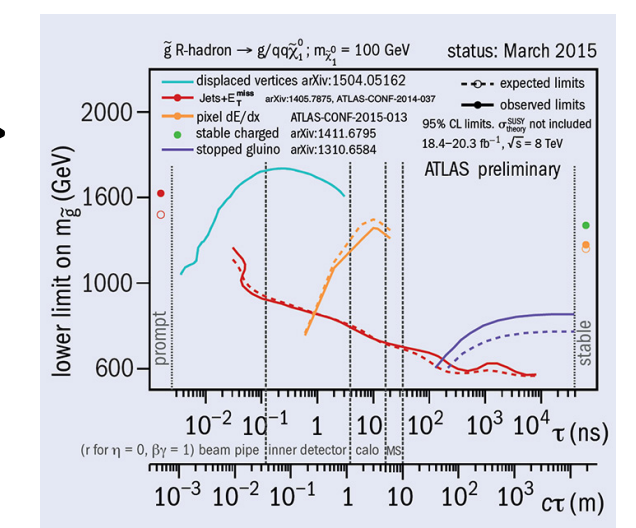
Reconstructed Event



Higgs



SUSY



Exotic Particles

- ▶ ML-based event reconstruction improves physics performance at future colliders
- ▶ End-to-end optimization can enable **new paradigms**, e.g. fine-tuning ML-based reconstruction for different use cases (analysis, detector concepts, etc.)
- ▶ Scalable ML models improve computational performance
- ▶ Open datasets and code accelerate research



Improved particle-flow event reconstruction with scalable neural networks for current and future particle detectors

Joosep Pata^{1*}, Eric Wulff², Farouk Mokhtar³, David Southwick², Mengke Zhang³, Maria Girone², Javier Duarte³

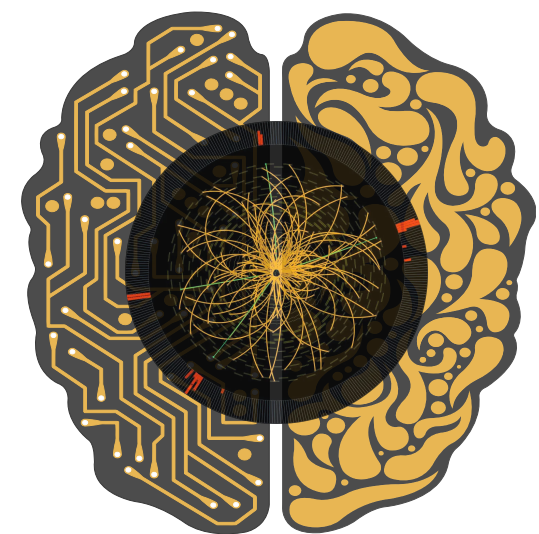
^{1*}National Institute of Chemical Physics and Biophysics (NICPB), Rävåla pst 10, 10143 Tallinn, Estonia.

²European Center for Nuclear Research (CERN), CH 1211, Geneva 23, Switzerland.

³University of California San Diego, La Jolla, CA 92093, USA.

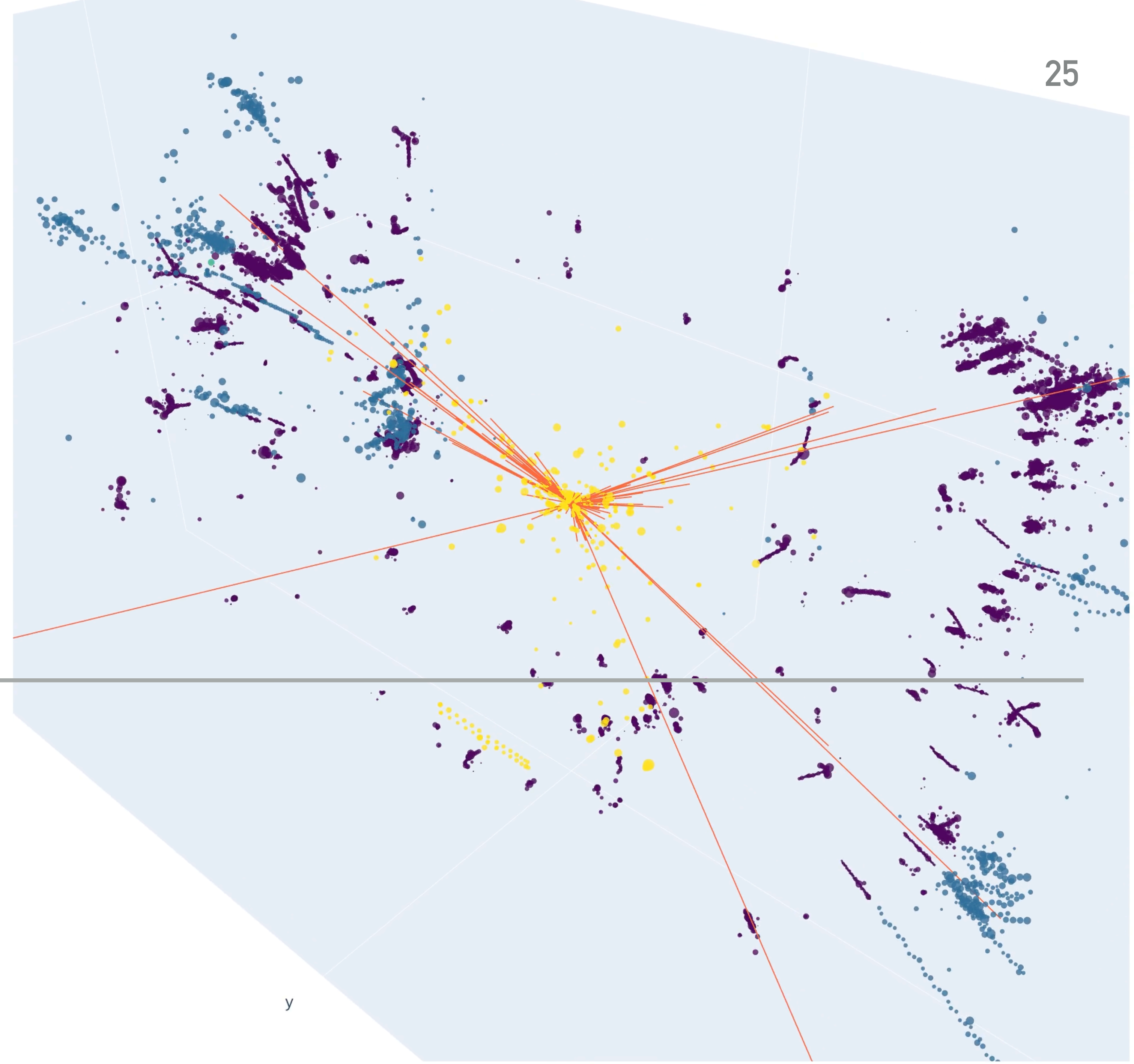
*Corresponding author(s). E-mail(s): joosep.pata@cern.ch;
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david.southwick@cern.ch; mezhang@ucsd.edu; maria.girone@cern.ch;
jduarte@ucsd.edu;

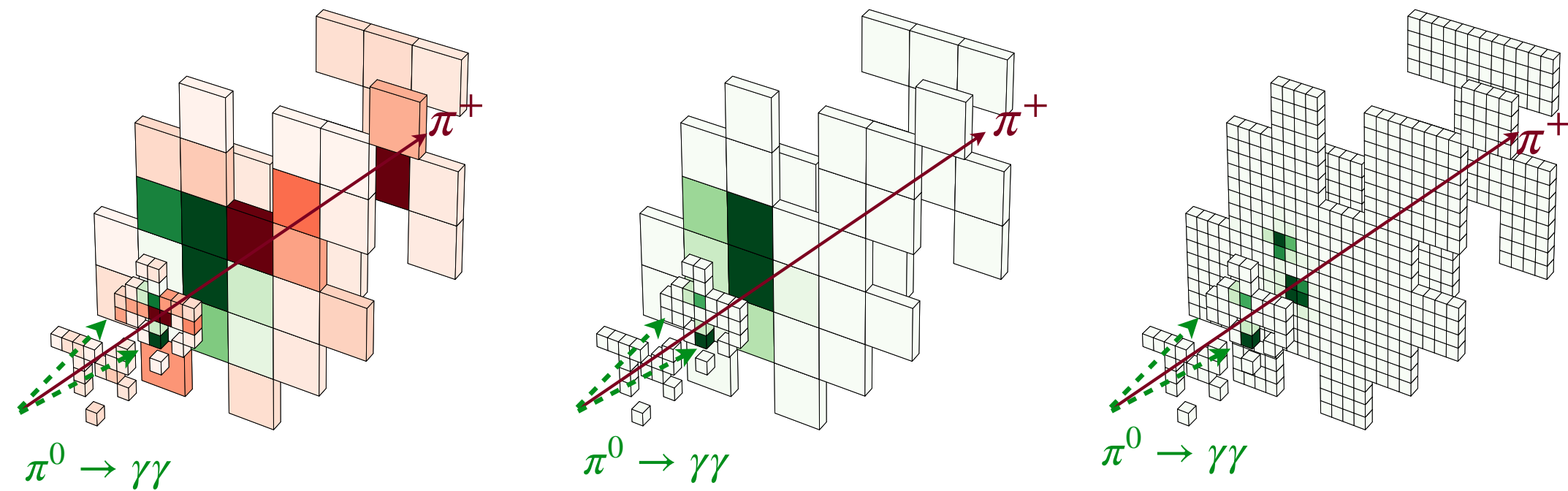




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BACKUP





Towards a Computer Vision Particle Flow [★]

Francesco Armando Di Bello^{a,3}, Sanmay Ganguly^{b,1}, Eilam Gross¹, Marumi Kado^{3,4}, Michael Pitt², Lorenzo Santi³, Jonathan Shlomi¹

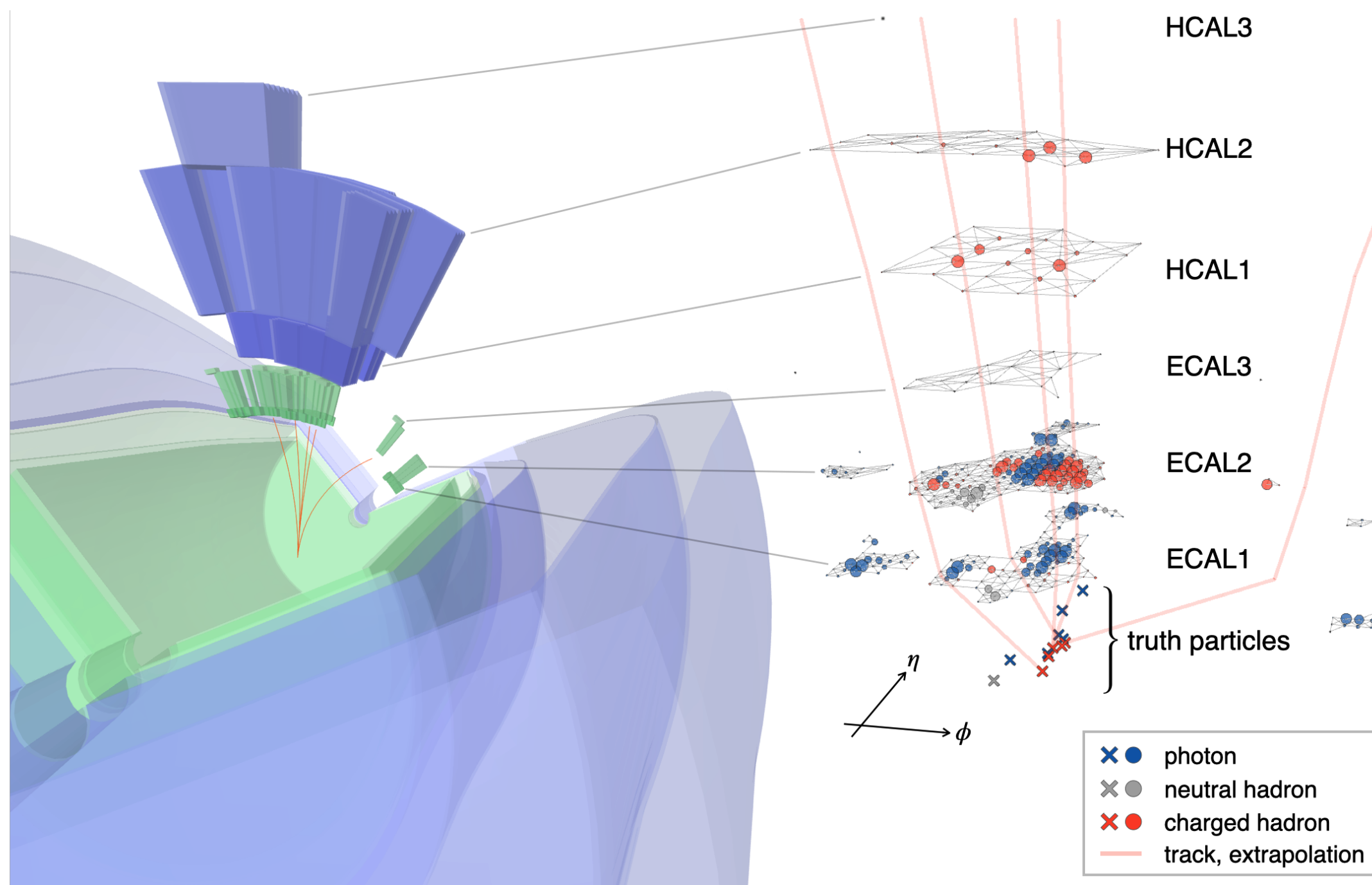
¹Weizmann Institute of Science, Rehovot 76100, Israel

²CERN, CH 1211, Geneva 23, Switzerland

³Università di Roma Sapienza, Piazza Aldo Moro, 2, 00185 Roma, Italy e INFN, Italy

⁴Université Paris-Saclay, CNRS/IN2P3, IJCLab, 91405, Orsay, France

[arXiv:2003.08863](https://arxiv.org/abs/2003.08863)



Reconstructing particles in jets using set transformer and hypergraph prediction networks

Francesco Armando Di Bello^{1,a}, Etienne Dreyer^{2,b}, Sanmay Ganguly³, Eilam Gross², Lukas Heinrich⁴, Anna Ivina², Marumi Kado^{5,6}, Nilotpal Kakati^{2,c}, Lorenzo Santi⁶, Jonathan Shlomi², Matteo Tusoni⁶

¹ INFN and University of Genova

²Weizmann Institute of Science

³ICEPP, University of Tokyo

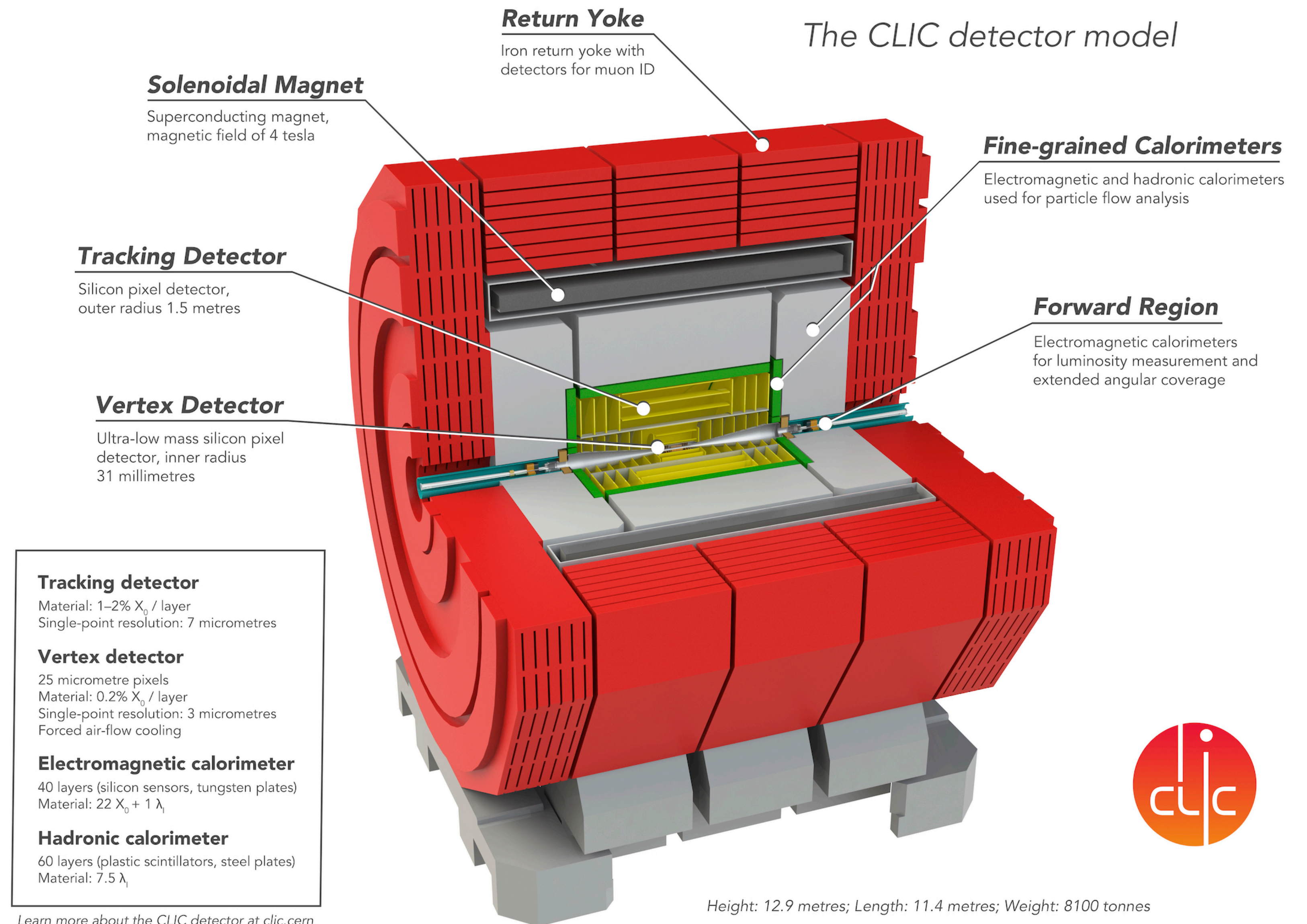
⁴Technical University of Munich

⁵Max Planck Institute for Physics

⁶INFN and Sapienza University of Rome

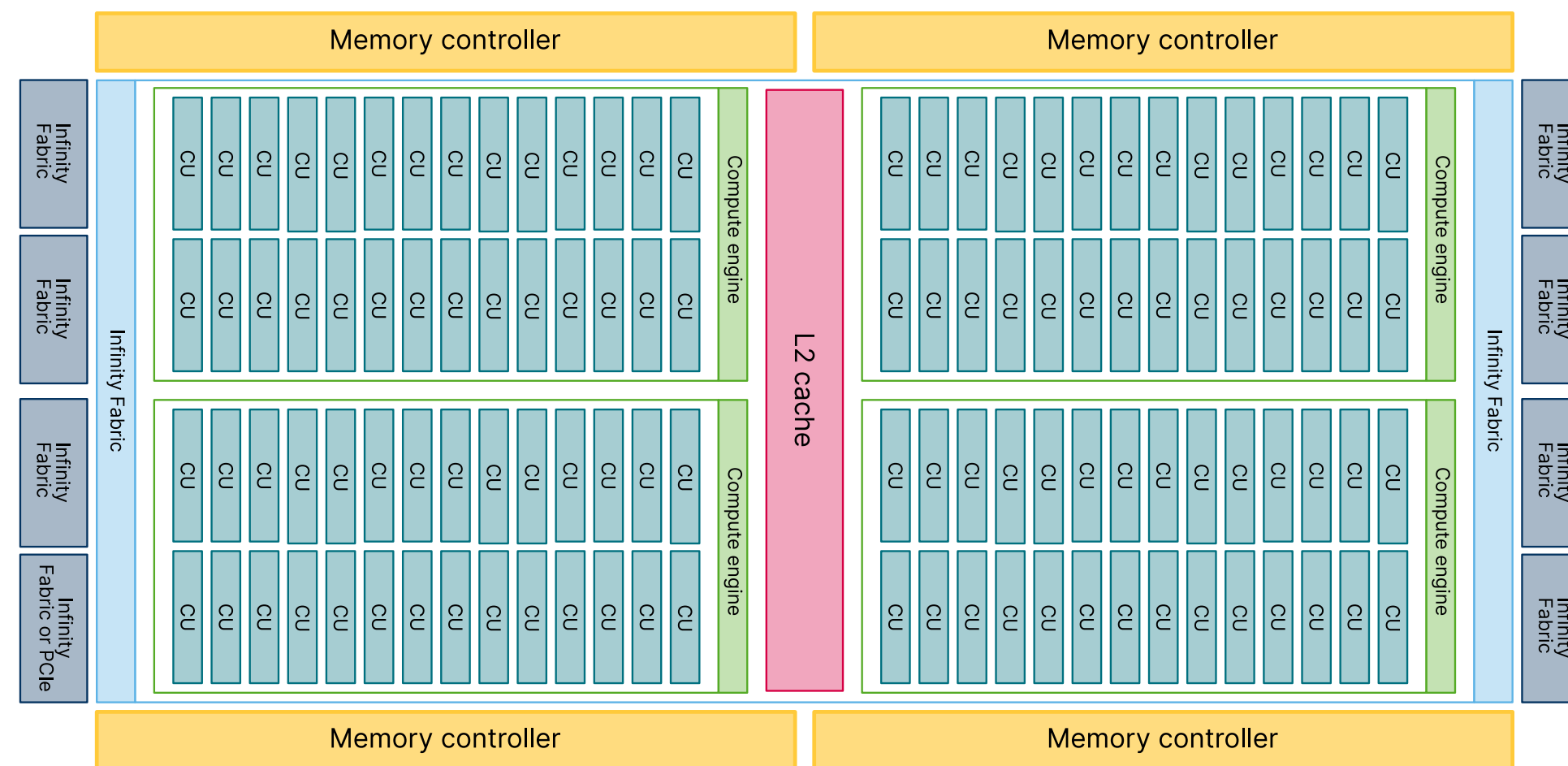
[arXiv:2212.01328](https://arxiv.org/abs/2212.01328)

► CLIC detector
([CLIC_o3_v14](#))

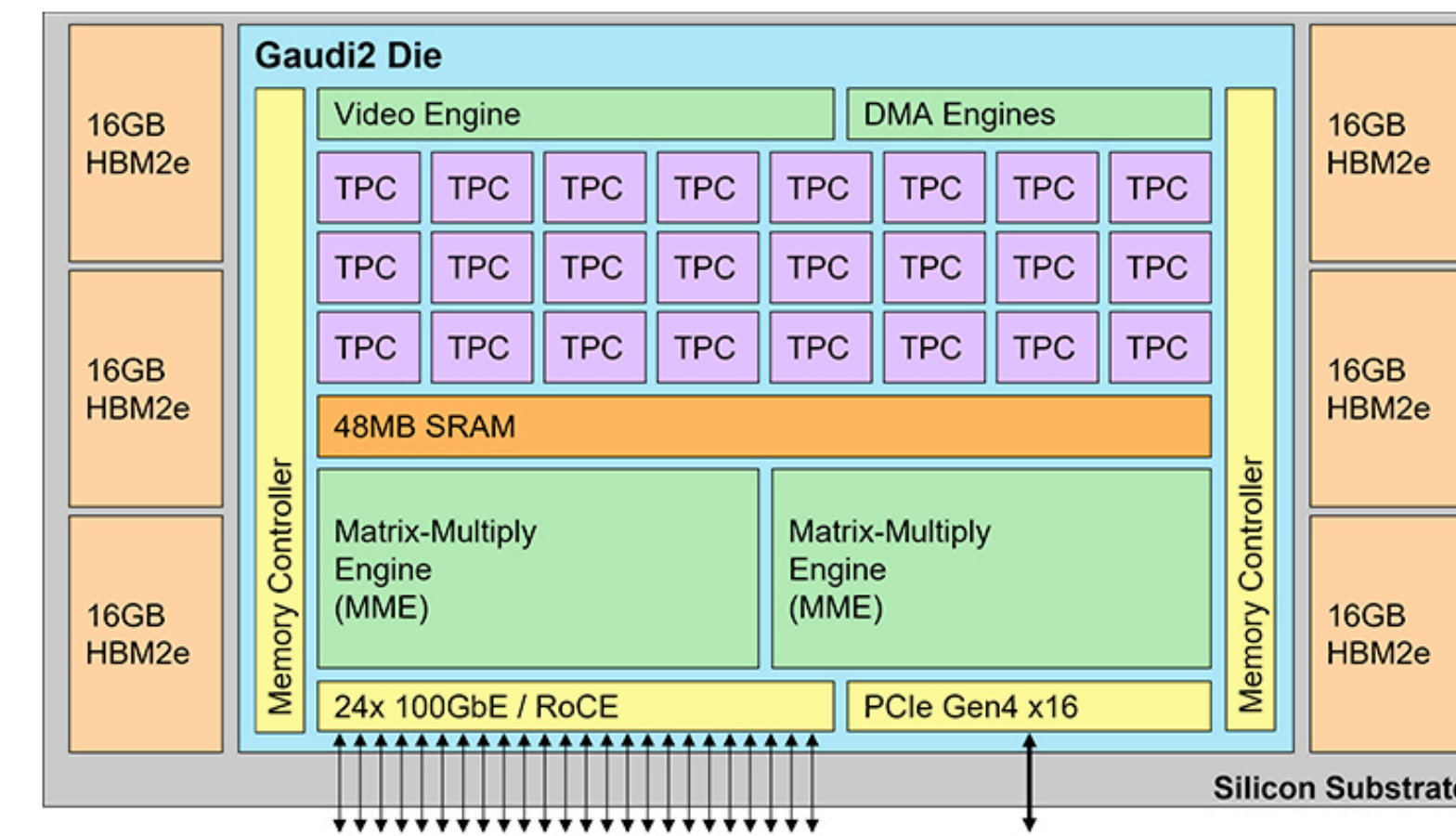


Learn more about the CLIC detector at clic.cern

The HPC AI chip landscape is diversifying



AMD MI250X GPU

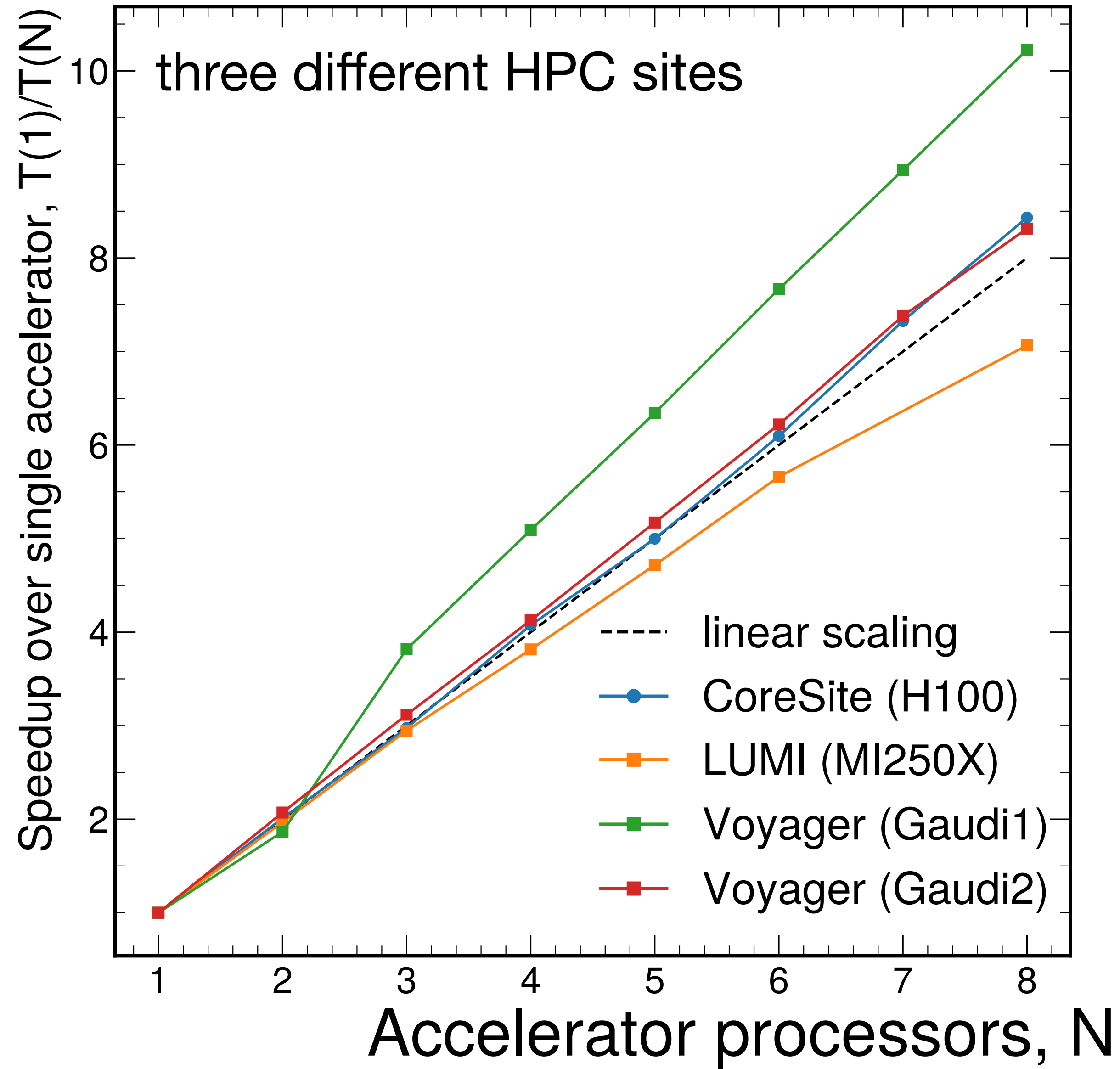


Intel Gaudi2 deep learning processor

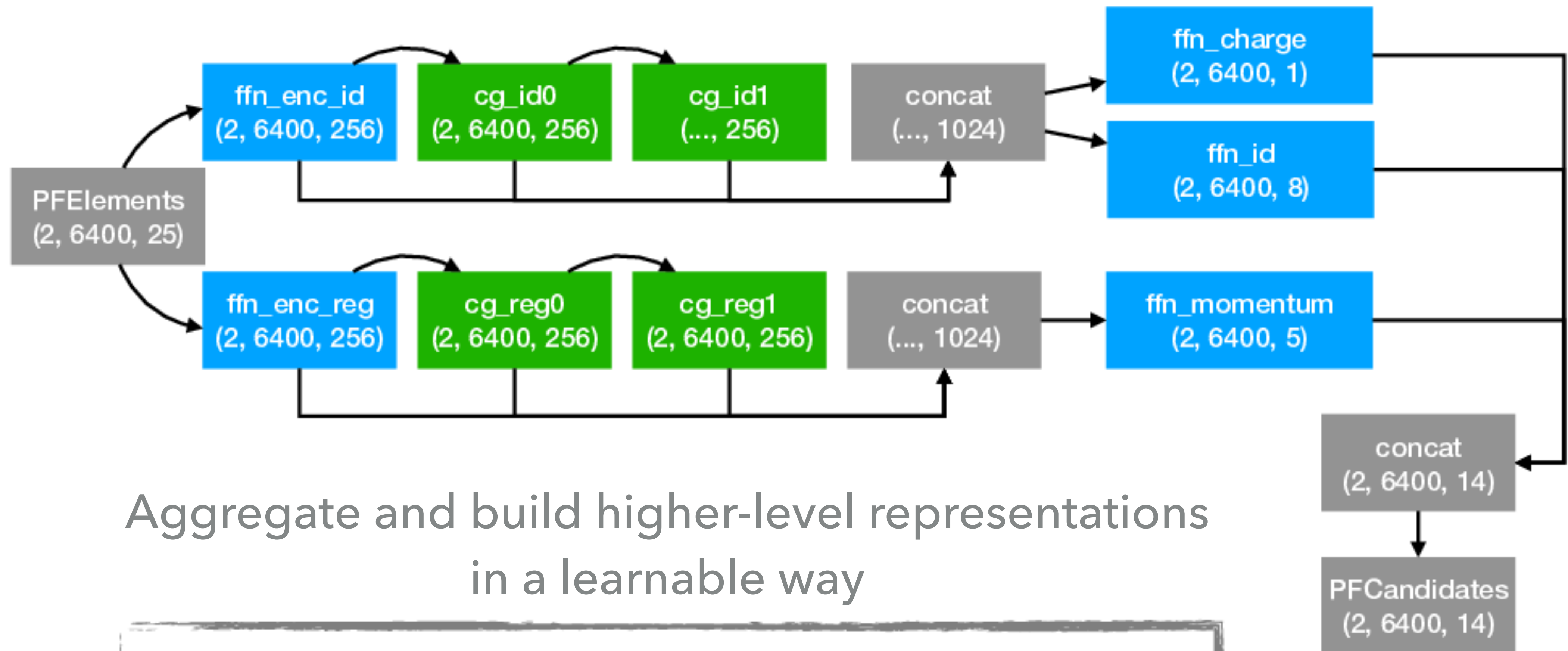
... we need flexible and portable codes to make use of these resources in the near future!

PORTABILITY

Portable on CPU,
Nvidia & AMD GPU,
Intel Habana Gaudi
chips

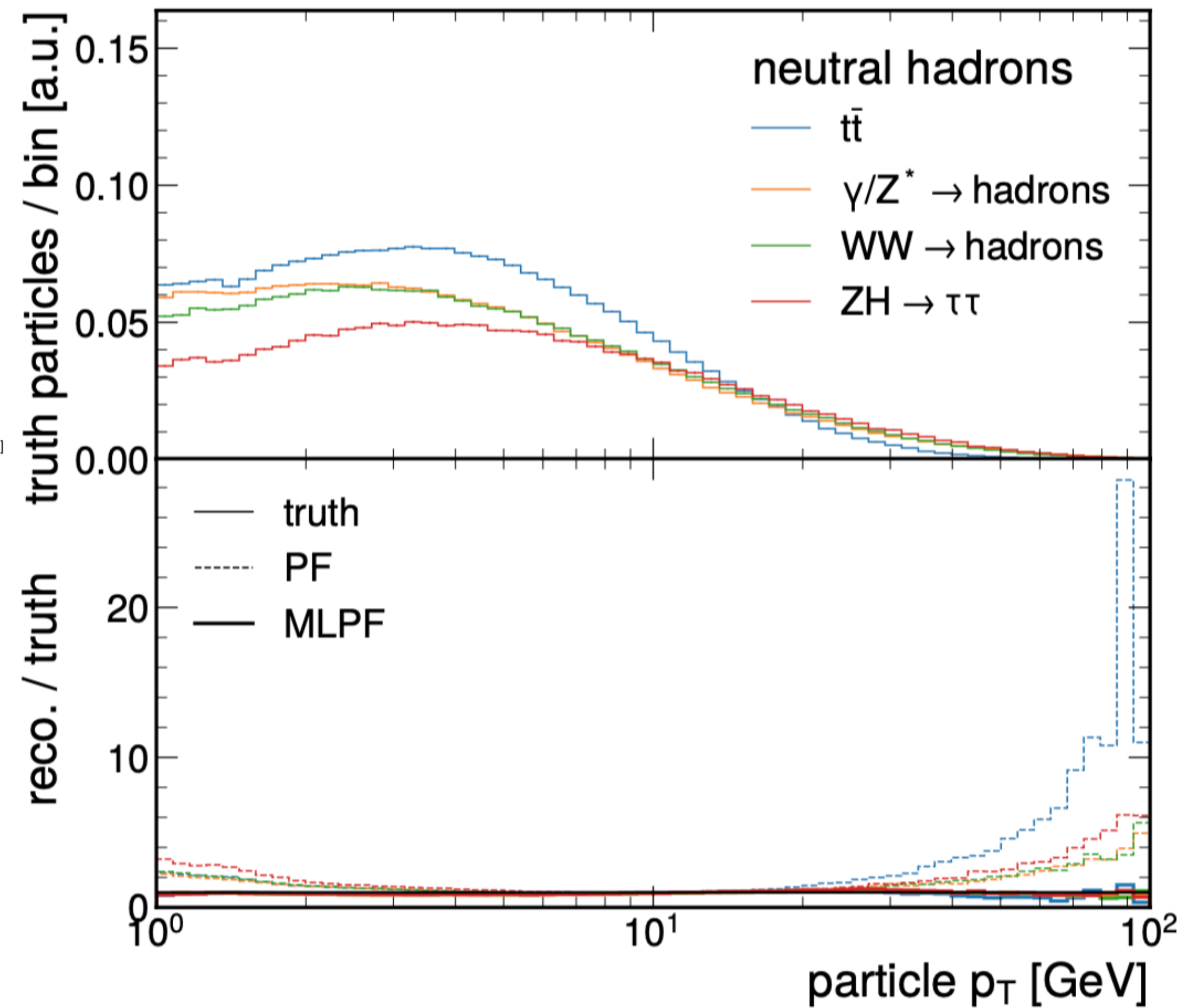


- ▶ Can construct multilayered networks from the scalable GNN-LSH building block



BULK AND TAILS

- ▶ Datasets are diverse so we have to predict the bulk and the tails well for all particle types



- ▶ Alternative: scalable transformer based on the Performer architecture
[\[arXiv:2009.14794\]](https://arxiv.org/abs/2009.14794)

One layer of kernel-based self attention with the FAVOR mechanism.

