



MODE

Способы обработки нерегулярностей в симуляционных данных на коллайдерных экспериментах

[The use of new methods for processing data of a physical experiment.
Application of machine learning methods on the NICA complex. 28-29 Aug 2023](#)

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See also:

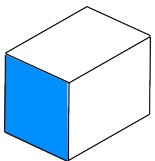
- [1] [JINST 15 C05032 \(2020\)](#)
- [2] [JINST 15 C09030 \(2020\)](#)
- [3] [EPI Web of Conferences 245, 02019 \(2020\)](#)
- [4] [J. Phys.: Conf. Ser.1740 012047 \(2021\)](#)
- [5] [Reviews in Phys. 10 100085 \(2023\)](#)

Challenges for detector sim+reco

- R&D of HEP detector requires a lot of simulations
- Level of detail of a simulation may vary:
 - Toy model
 - Sketching
 - (Intermediate options)
 - Detailed modelling
 - Describes engineering constraints and detector alignment
 - Real data imitation
- Desired figure of merit of a simulation can be achieved by a reconstruction similar to that used in physical analysis



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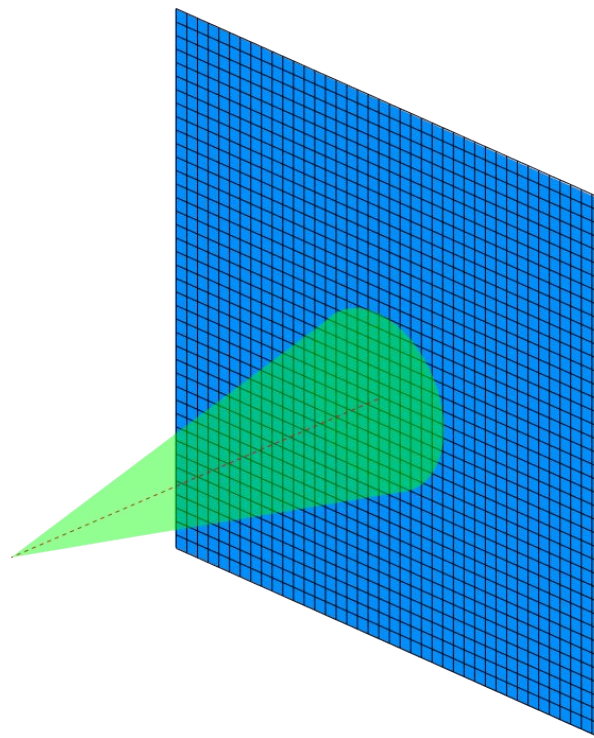
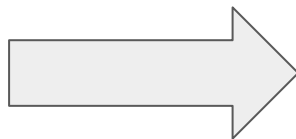


Sensitive element



Typical area
of a response

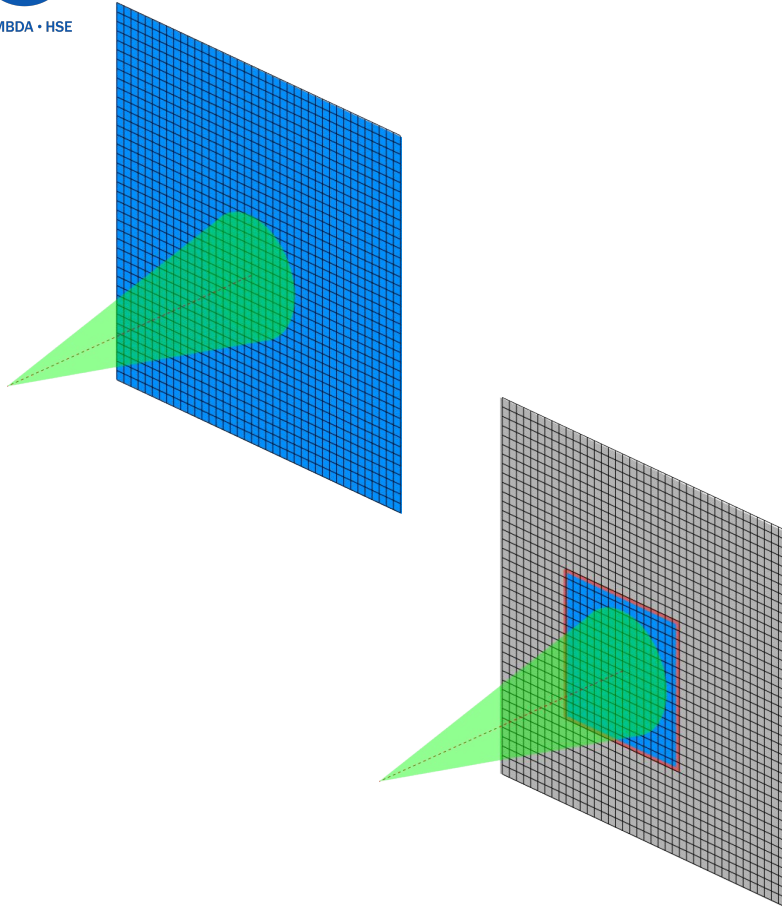
Desired η coverage



(planar case)

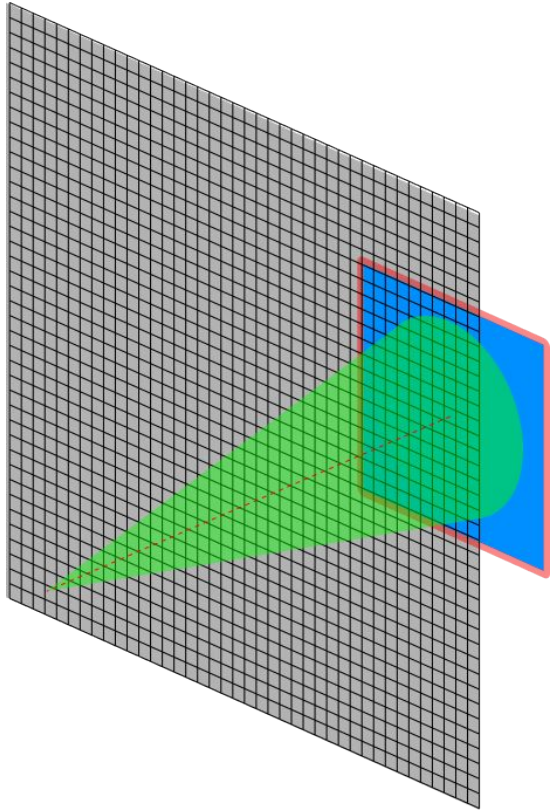
Simplest case processing

Two scenarios for the use of simulation outputs by following (ML) reconstruction:



- **All available channels at once**
 - Computation limitations (typically, $10^3 \dots 10^6$ channels)
- **Scanning window**
 - Cells/pixels are selected only around fired sensitive elements
 - Rely on the seed finder algorithm
 - Window size should be larger than typical area of a response

Simplest case: scanning window



Possible pitfall

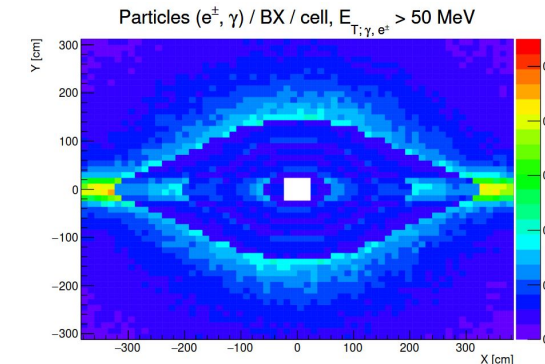
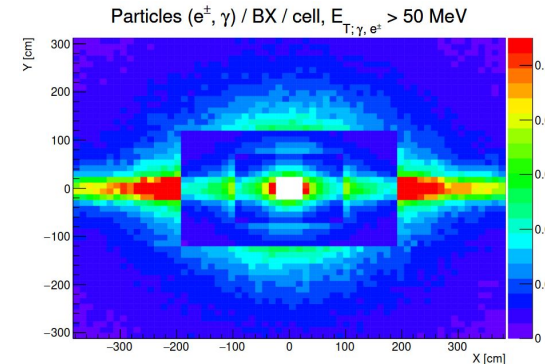
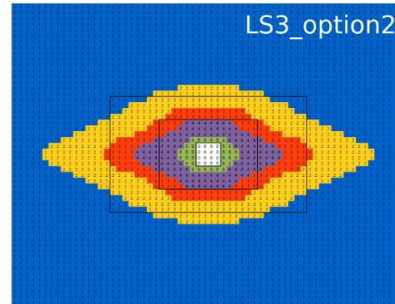
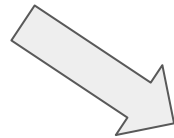
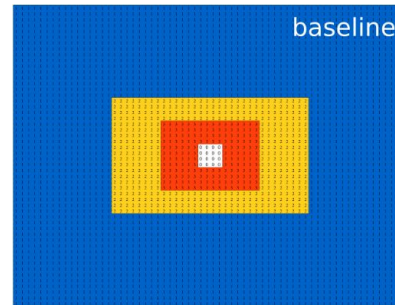
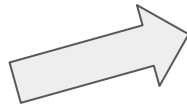
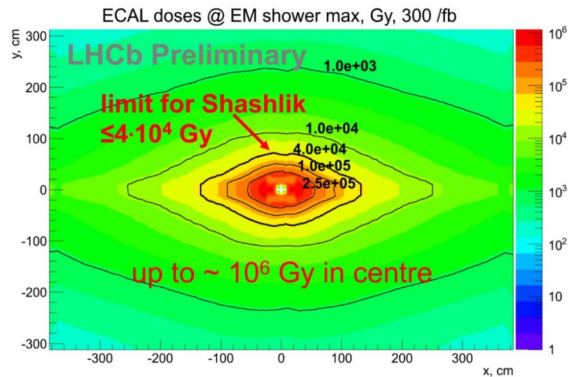
- The scanning window extends beyond the detector boundary

More realistic cases of pixels/cells arrangement



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Driven by expected radiation doses or occupancy maps



It brings us regions with:

- Different technologies
- Different granularities



More realistic cases of pixels/cells arrangement

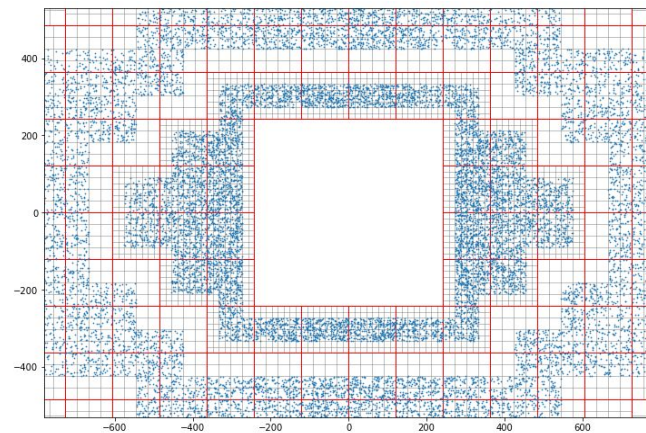
More realistic cases imply **additional boundaries** between regions of different granularities (technologies).

Naïve strategy: avoid irregularities of the geometry

- For 5x5 cells scanning window and 'romboidal' shape of the regions we can lose ~20% of reconstructible events

Better strategy: interpolation of the cells for equalization of granularity on both sides of the border

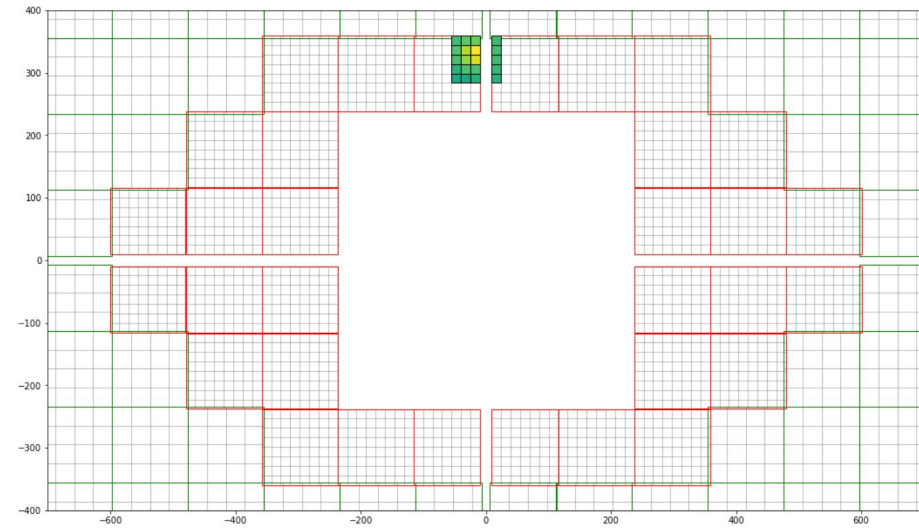
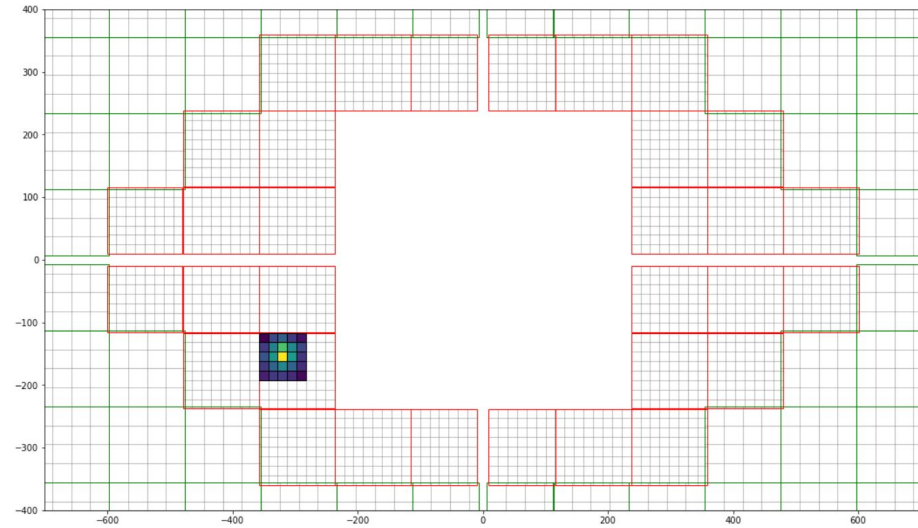
- We can use all reconstructible events



More realistic cases of pixels/cells arrangement

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More realistic cases also involve engineering gaps or infrastructure objects.

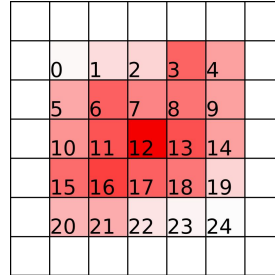


Naïve strategy also leads to additional inefficiency close to such gaps or objects.

Strategies to have geometry agnostic inputs

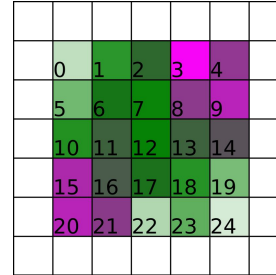


energy deposits

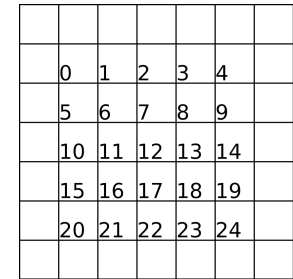


+

timing information

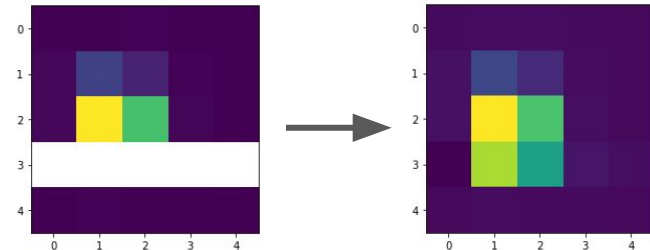


cell position info.



Better strategy:

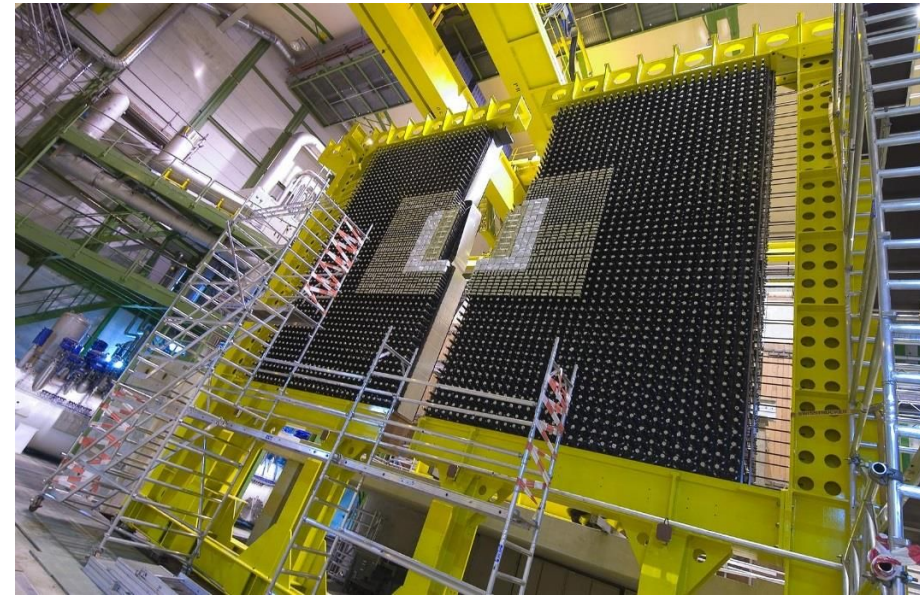
- Cell position matrix as addition input to ML regressors
- Interpolation of non-existing cells outside of the outer borders
- Interpolation of cells for equalization of granularity on both sides of the boundaries between



LHCb ECAL case

LHCb ECAL

Current configuration

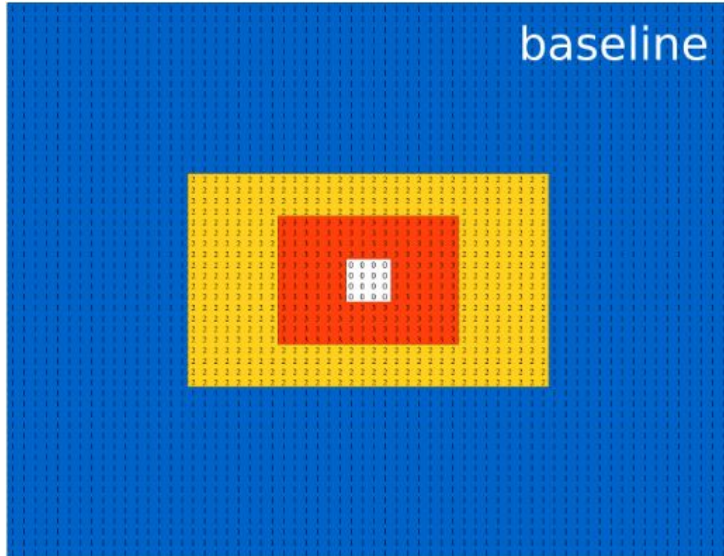





Wall dims: $7.8 \times 6.3 \times 0.5 \text{ m}^3$



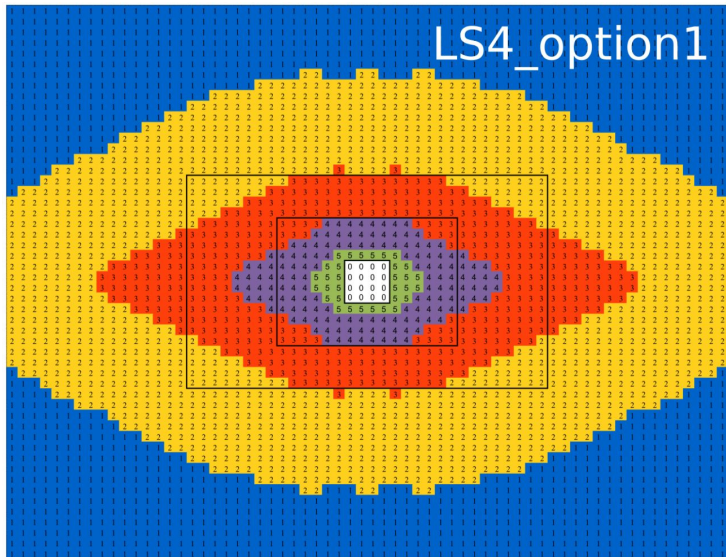
Calo modules of size $12 \times 12 \text{ cm}^2$

176 inner: 9 cells with size $4 \times 4 \text{ cm}^2$
448 middle: 4 cells with size $6 \times 6 \text{ cm}^2$
2688 outer: 1 cell with size $12 \times 12 \text{ cm}^2$



Module type	# of modules
 (inner): 3x3 cells (4.04x4.04 cm ² each)	176 (1536 ch.)
 (middle): 2x2 cells (6.06x6.06 cm ² each)	448 (1792 ch.)
 (outer): single cell (12.12x12.12 cm ²)	2688 (2688 ch.)

Starting from current configuration



Reuse of current “Shashlik” modules

New “SpaCal” modules

- 1 : Outer region, cell size = $12.12 \times 12.12 \text{ cm}^2$
- 2 : Middle region, cell size = $6.06 \times 6.06 \text{ cm}^2$
- 3 : Inner region, cell size = $4.04 \times 4.04 \text{ cm}^2$

- 4 : cell size = $3.03 \times 3.03 \text{ cm}^2$
- 5 : cell size = $1.515 \times 1.515 \text{ cm}^2$
(+ longitudinal split)



Questions for future ECAL:

- What is the best configuration for given modules (fix cost) in terms of given physics metric?
- What is the best way to arrange a certain number of new modules?

Input

Differentiable chain

Output

MC Truth

Signal

Background

Detector simulation (+ digitization)		Detector reconstruction + digitization	Physics reconstruction
Particle transport	Geant4 Calo simulation		
	Optimized parameters: Granularity Molière radius Timing	Energy, Spatial and Timing resolutions	Signal yield, Significance + their derivatives
Is differentiable?	Yes	Hardly	Yes
	Local surrogate modelling using CaloGAN		

Label:

1 event accepted

0 event rejected

Possible inputs for Calo framework

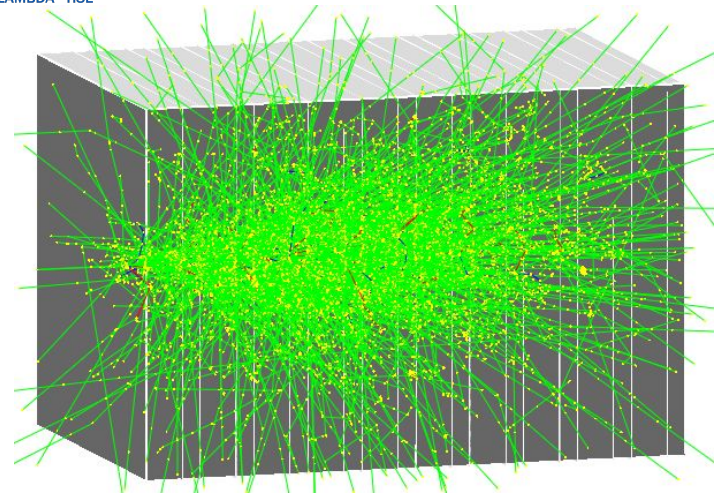
- Simulation input:
 - Particle gun (single photons)
 - Pythia with reference physics sample like $B_s^0 \rightarrow J/\psi(\rightarrow \mu^+ \mu^-) \pi^0(\rightarrow \gamma \gamma)$
 - Background sample(s)
 - Minimum Bias
 - Arbitrary pile-up modelling due to PV extraction
- ML-based reconstruction based on 3 sets of regressors to estimate:
 - Position
 - Energy
 - Time

Challenges for new ECAL configurations

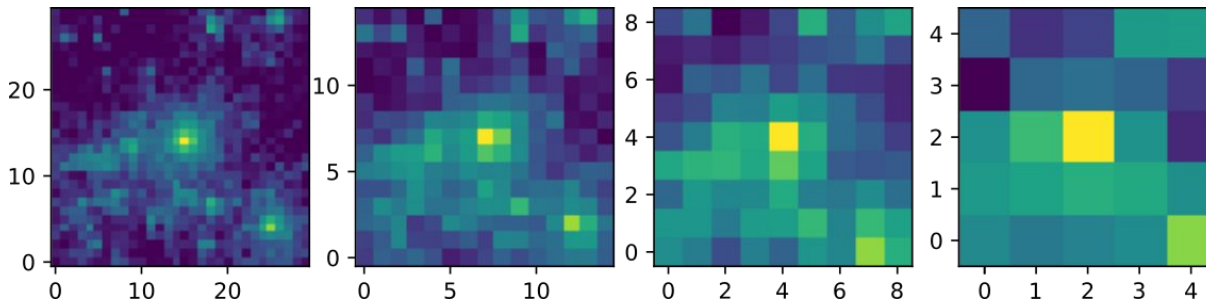
- Thousands of configurations are possible within a budget
- For each configuration one should decide:
 - Module technology options (Shashlik/SpaCal/...)
 - Granularity (cell size)
 - Longitudinal segmentation
 - Timing information
- How to factorize the above?



Geant4 simulation for granularity study

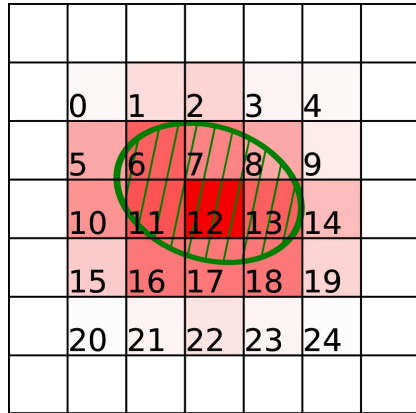


- Sampling structure with alternating scintillating tiles and lead plates
 - Roughly emulates LHCb ECAL
- $\{x, y, z, t\}$ of all hits in the ECAL are recorded
- Can represent arbitrary (regular) granularity of the ECAL cells



Input features for Reconstruction

Signal energy deposits and shower spot



Simulated Geant4 response is an array of cells

- Used as base features for the regressors on Energy and Position
- Regressor on time uses weighted energy deposits

What we have so far

- Single ECAL module:
 - ML reco performance is compatible with conventional Reco performance using detailed simulation input (& with beam tests)
- Full ECAL
 - Requires geometrical irregularities
 - There are 4 borders between the regions of different granularity
 - Some modules have to be rotated due to technology limitations

**How does that fit in with the fact that
reco algorithm needs to be geometry agnostic?**

Energy reconstruction on geometry agnostic inputs

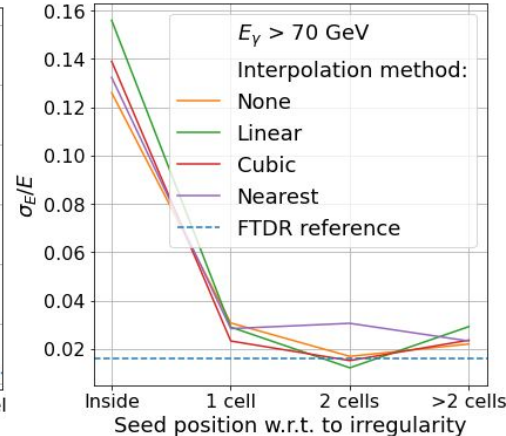
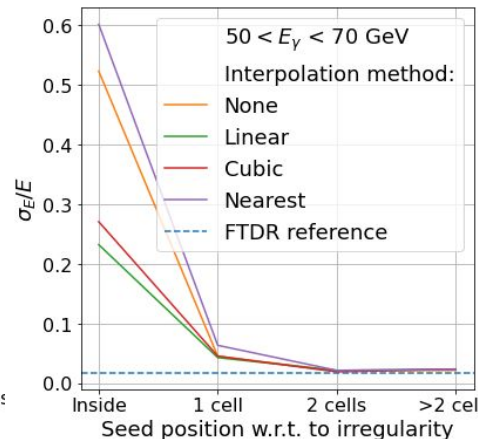
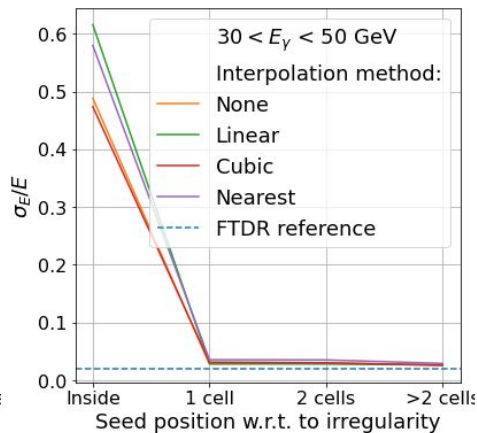
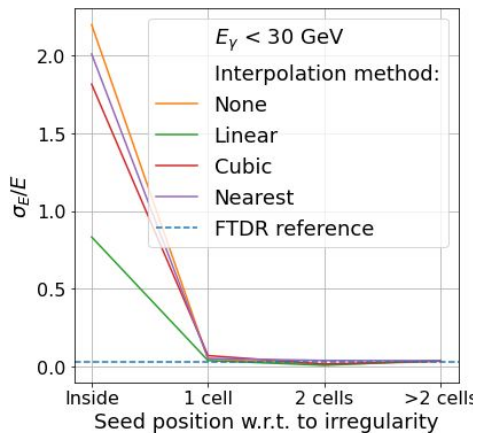
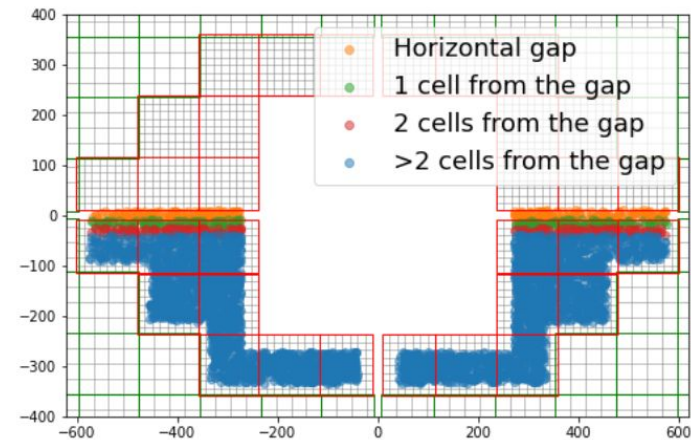
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XGB-based ML regressor

- 5x5 matrix of energy deposits
 - Missing cells recovered using

Linear, Cubic and Nearest-neighbor interpolation

- Cell position info
- Additional features

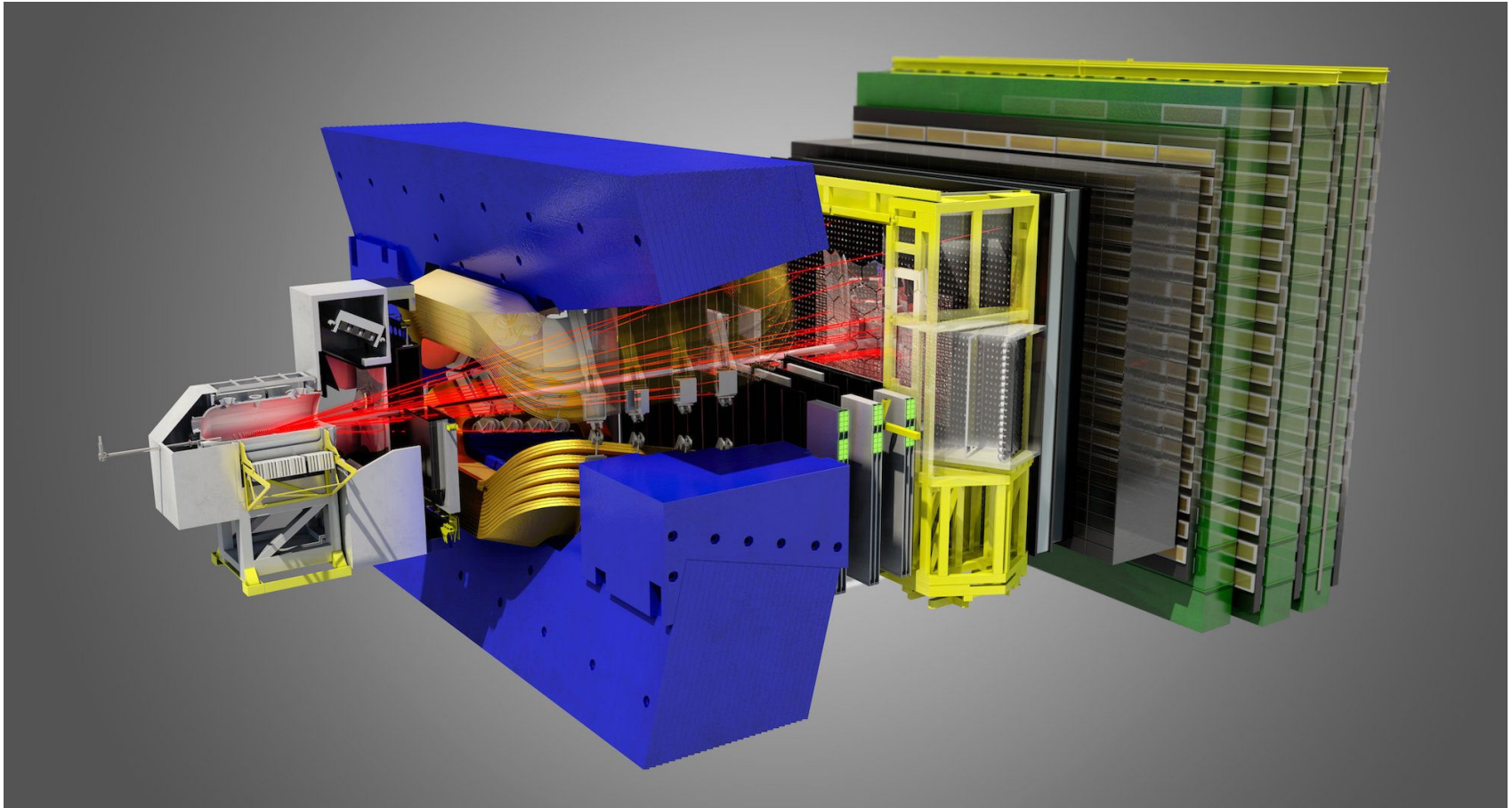


Conclusions

- The R&D process requires time consuming computation steps to evaluate physics performance for different detector techniques and configurations.
- ML reco is consistent with conventional reconstruction for single ECAL module and regular geometry
- ML reco is able to handle detailed simulation inputs using cell position matrix, interpolation of missing cells, and interpolation of low granularity cells close to high granularity cells
- Automatic training speeds up the turnover for the performance studies and ensures consistency and uniformity of obtained results

Backup slides

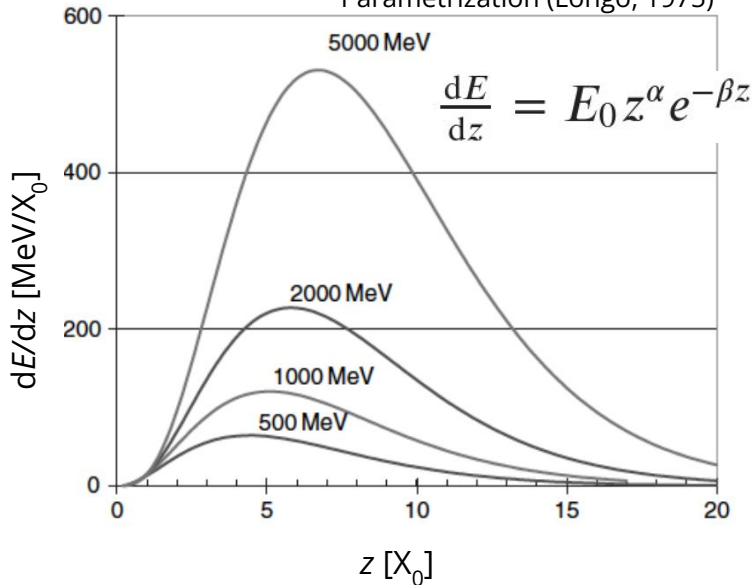
LHCb detector



Calorimetry in a nutshell

Longitudinal EM shower profile

Parametrization (Longo, 1975)

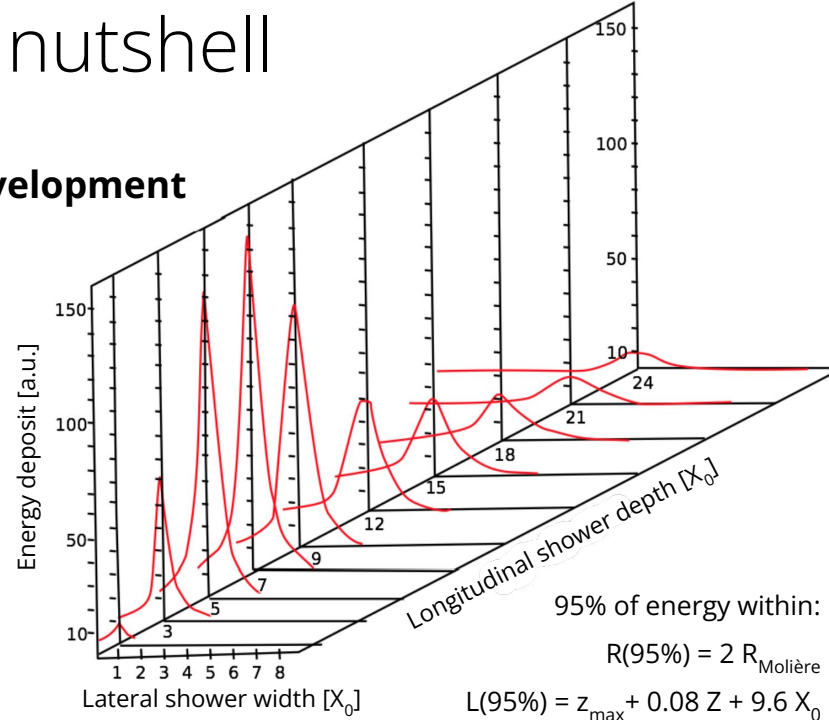


Differences between showers induced by γ & e

$$z_{\max} = \frac{\alpha - 1}{\beta} = \ln\left(\frac{E_0}{E_C}\right) + C$$

$$C_\gamma = -0.5, C_e = -1.0$$

EM Shower development



Energy resolution

$$\frac{\sigma_{\text{reco}}}{E_{\text{reco}}} = \frac{a}{\sqrt{E_{\text{gen}}}} \oplus b \oplus \frac{c}{E_{\text{gen}}}$$

Timing resolution

$$\sigma_t = A/\sqrt{E} \oplus B$$

- Collect GEANT responses for the calorimeter technology of track parameters in standalone setup
- Train conditional generative model on simulated data
- Use the model to generate response for the given particle

