

Support Structures for SI detectors



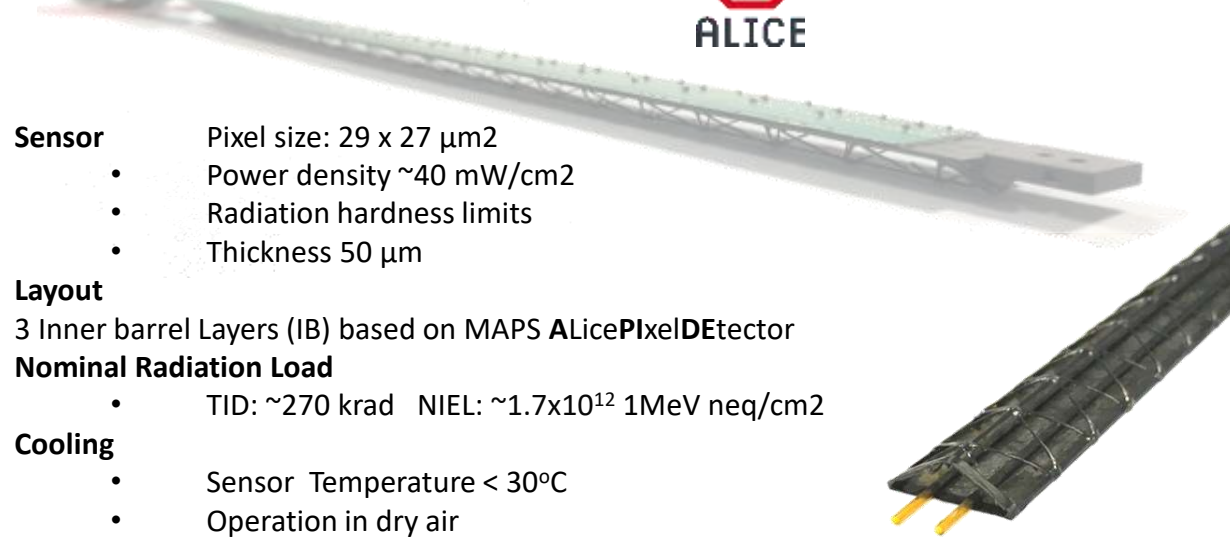
7th FCC PHYSICS Workshop
January 19th – February 2, 2024

Corrado Gargiulo



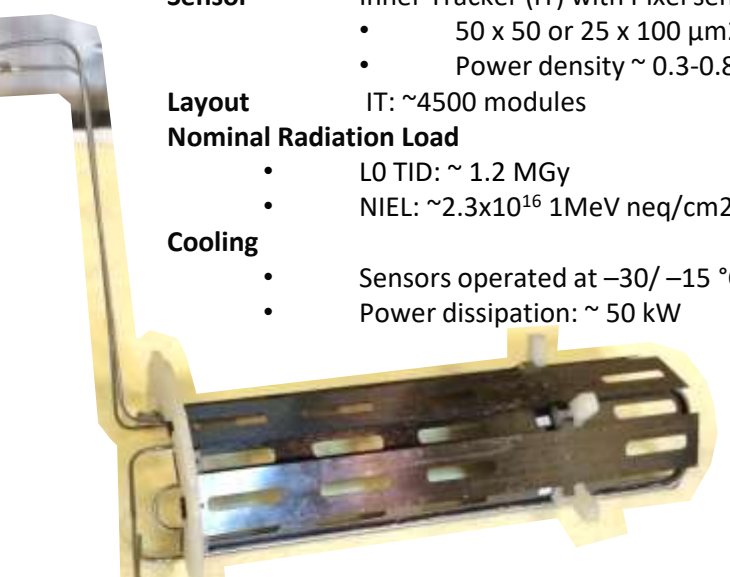


- Sensor**
- Pixel size: 55 x 55 μm^2
 - Power density $\sim 28\text{W}/\text{module}$
 - read out by the VeloPix ASIC (bump bonded)
 - Radiation hardness
- Layout**
- 2-retractable halves
 - 26 silicon pixel modules each
- Nominal Radiation Load**
- NIEL: $\sim 8 \times 10^{15}$ 1MeV neq/cm 2 for 50 fb $^{-1}$
- Cooling**
- Sensor tip temperature < -20 °C
 - Operation under secondary vacuum

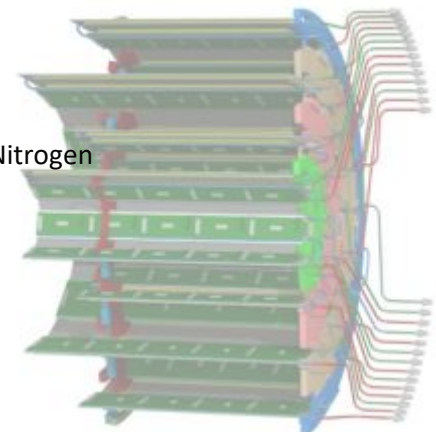


- Sensor**
- Pixel size: 29 x 27 μm^2
 - Power density ~ 40 mW/cm 2
 - Radiation hardness limits
 - Thickness 50 μm
- Layout**
- 3 Inner barrel Layers (IB) based on MAPS ALicePixelDEtector
- Nominal Radiation Load**
- TID: ~ 270 krad NIEL: $\sim 1.7 \times 10^{12}$ 1MeV neq/cm 2
- Cooling**
- Sensor Temperature < 30 °C
 - Operation in dry air

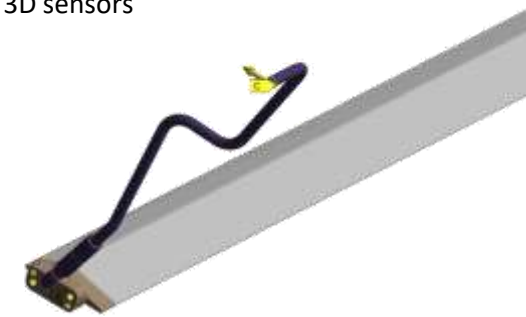
CMS (RUN4)  mechanics is inherently linked to cooling  ATLAS (RUN4)



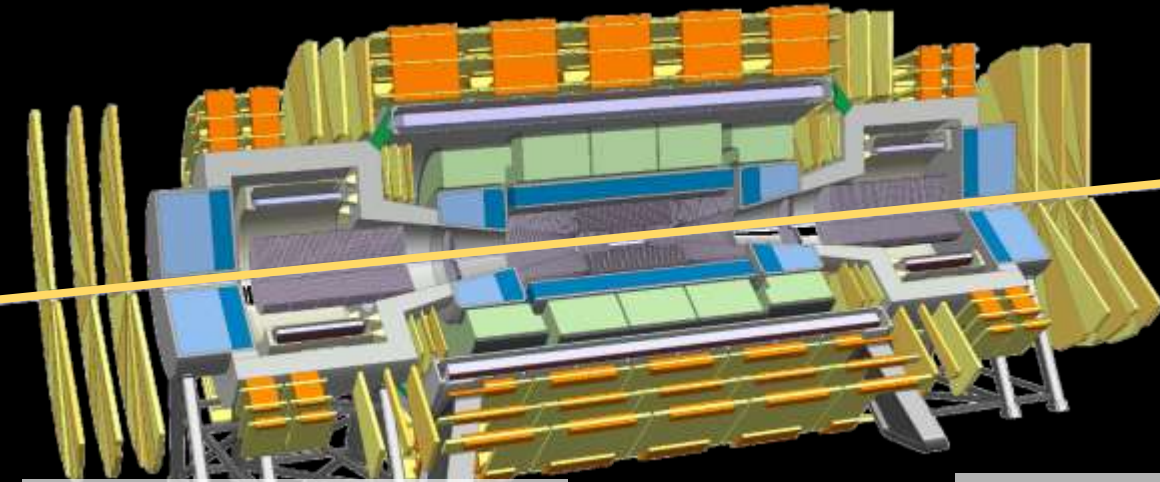
- Sensor**
- Inner Tracker (IT) with Pixel sensors
 - 50 x 50 or 25 x 100 μm^2
 - Power density $\sim 0.3-0.8$ W·cm $^{-2}$
- Layout**
- IT: ~ 4500 modules
- Nominal Radiation Load**
- L0 TID: ~ 1.2 MGy
 - NIEL: $\sim 2.3 \times 10^{16}$ 1MeV neq/cm 2
- Cooling**
- Sensors operated at $-30/ -15$ °C , in Nitrogen
 - Power dissipation: ~ 50 kW



- Sensors**
- Pixel Hybrid module (300 μm) with Planar or 3D sensors
 - Pixel size 50 x 50 μm^2 or 25 x 100 μm^2
 - Power density $\sim 0.25-0.8$ W·cm $^{-2}$
- Layout**
- Total pixel active area ~ 13 m 2 .
 - Replaceable Inner System;
 - Inclined section in L2, L3 and L4
- Nominal Radiation Load**
- L0-L1 (2000fb $^{-1}$) TID: ~ 10 MGy
 - NIEL: $\sim 1.3 \cdot 10^{16}$ 1MeV neq/cm 2
- Cooling**
- Sensors operated at $-30/ -15$ °C , in Nitrogen
 - Evaporative CO $_2$ cooling ($T_{\text{sat}} \sim -30$ °C), operated in Nitrogen
 - Power dissipation: 0.25-0.8 W·cm $^{-2}$
 - TFM ($T_{\text{sensor}} - T_{\text{CO}_2}$ /Heat Flux) between ~ 18 and ~ 30 °C·cm $^{-2}$ ·W $^{-1}$



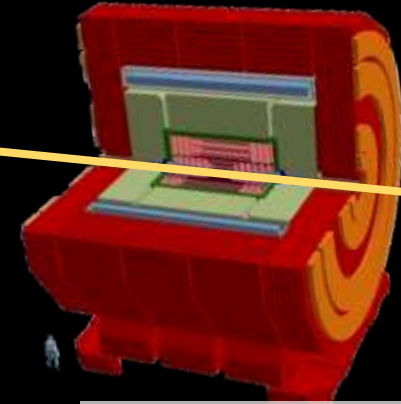
Vertex detectors (Next)



FCChh, HE-LHC, ...

hh collisions

e⁺e⁻ collisions



CLIC, FCCee, ILC, CEPC, ...

- Large dimensions (50m)
- **High radiation Level (~ 100 MGy/10years)**
- Magnetic B-field: 4T 10m solenoid, Forward solenoids 4T
- Tracker Radius 1.6m, Length 32m
radiation damage is a concern

- Standard dimensions
- Low radiation Level: TID (<200 Gy/yr)
- Magnetic B-field: 4T, 2T
- unprecedented spatial resolution (1-5 μm point resol.)
- **very low material budget (0.1X%)**
- Dissipated power (vertex) (<50mW/cm²)
- **Stability**
- **Proximity to IP**

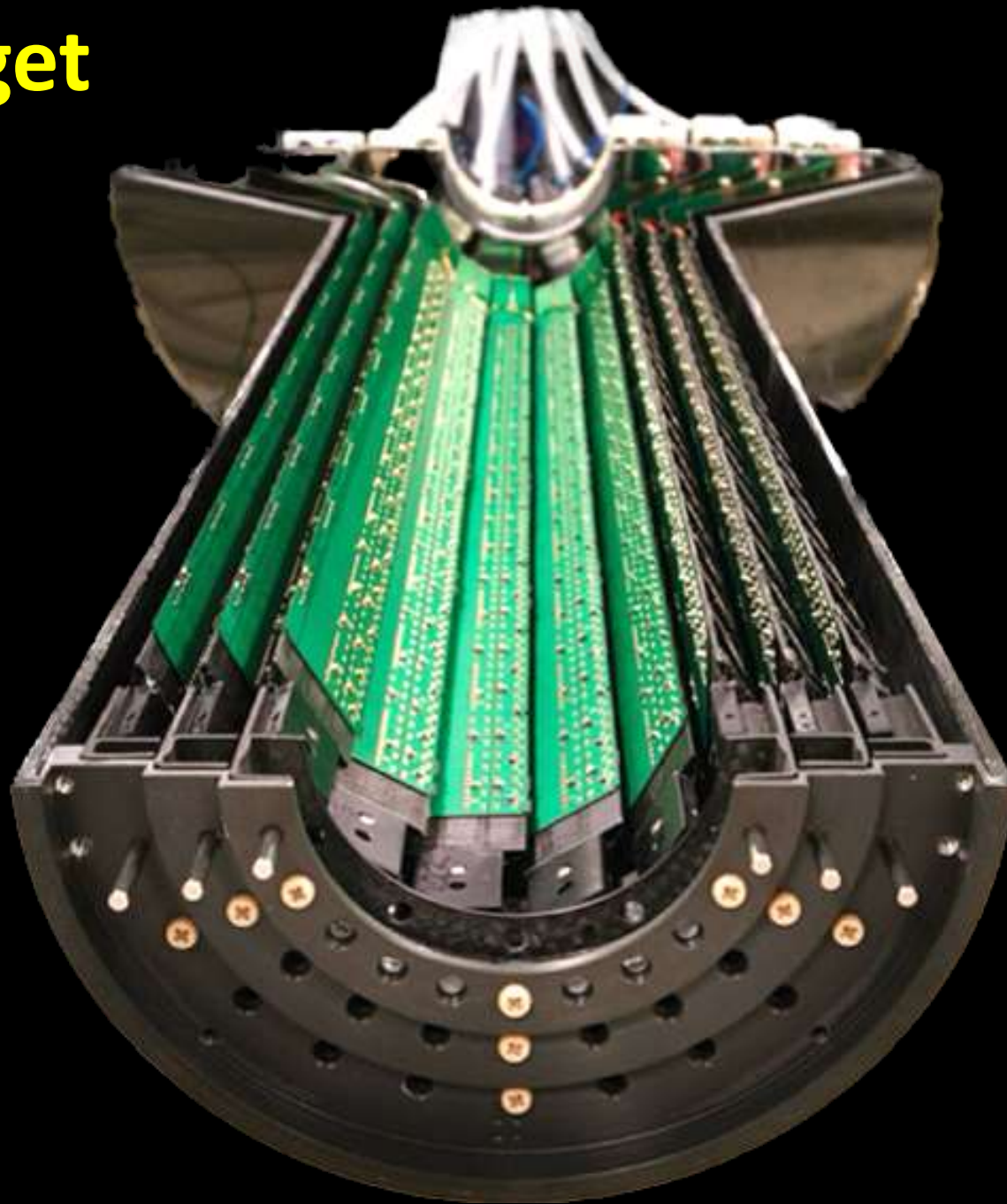


<-40°C very low temperature.....

.....Room Temperature

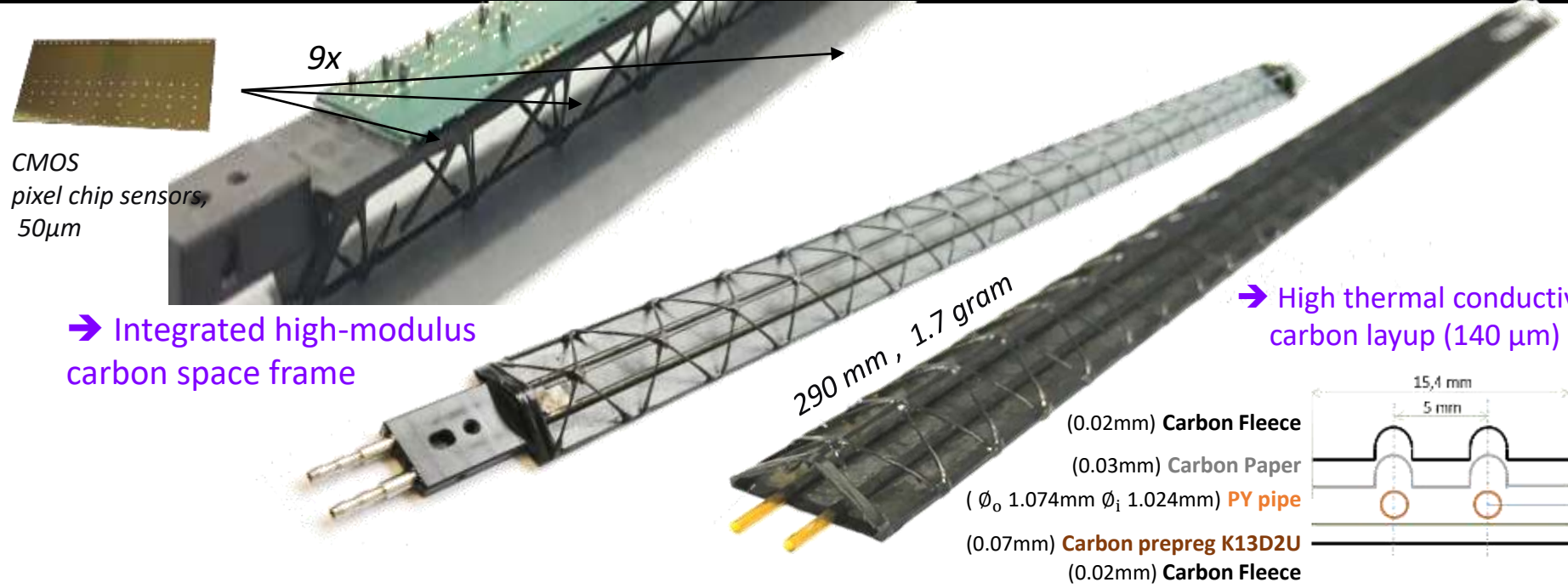


Material budget



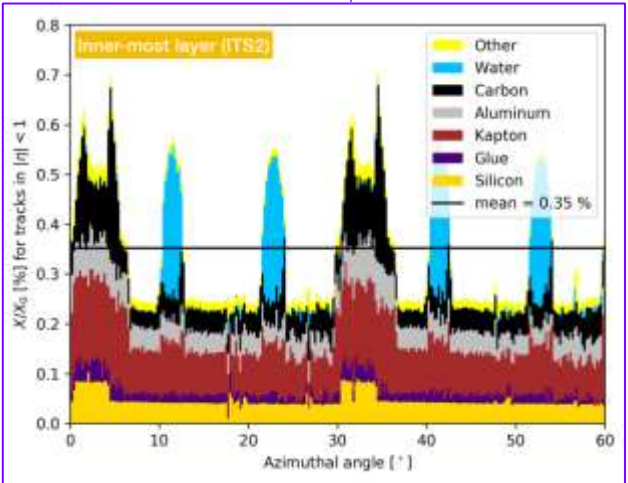
Stability

Material budget 0.35 X/X0 (LHC RUN3)



→ Integrated high-modulus carbon space frame

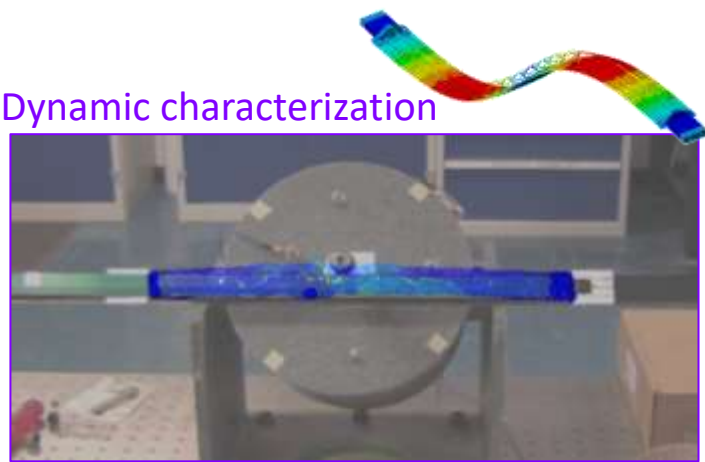
Material budget



Thermal characterization

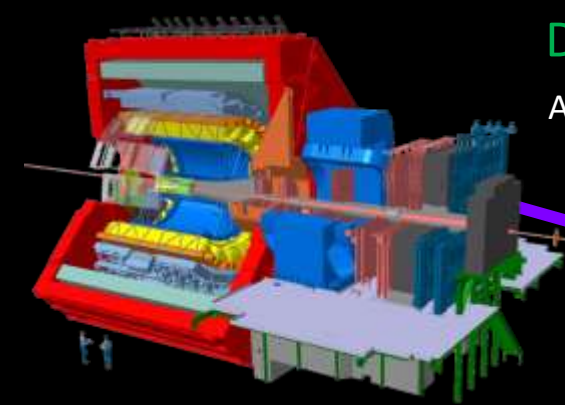
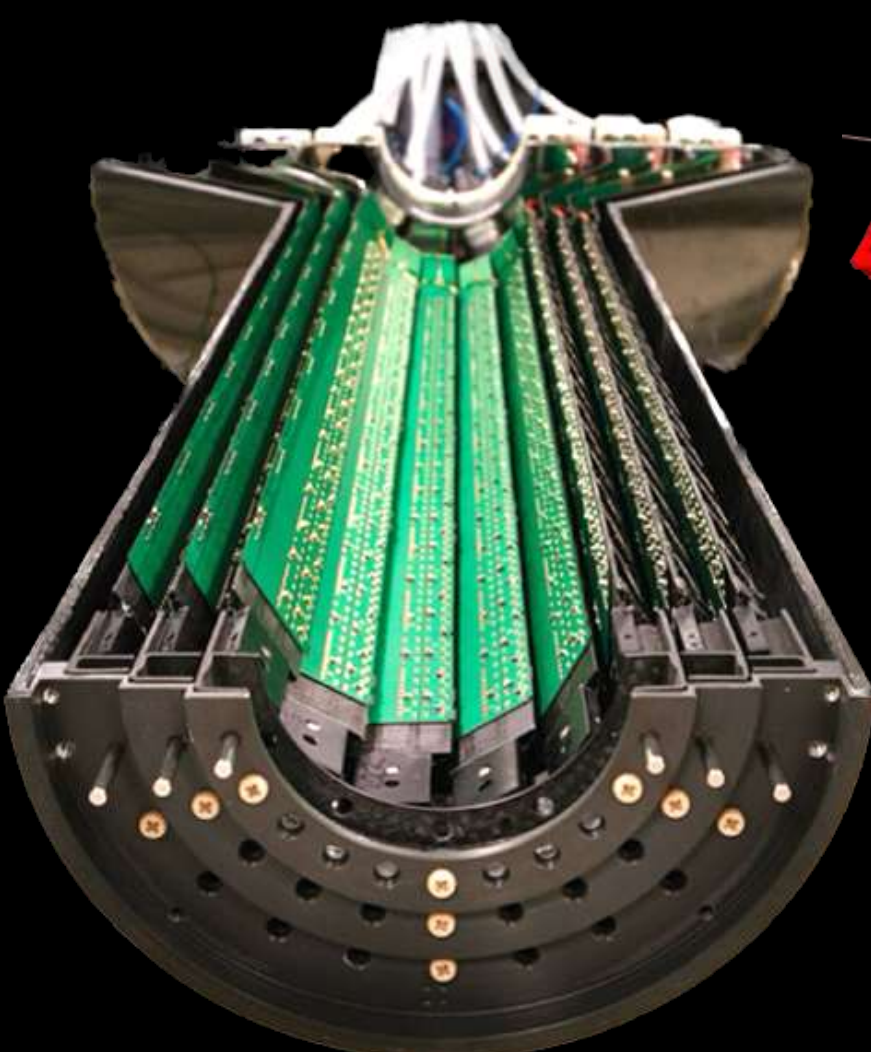


Dynamic characterization



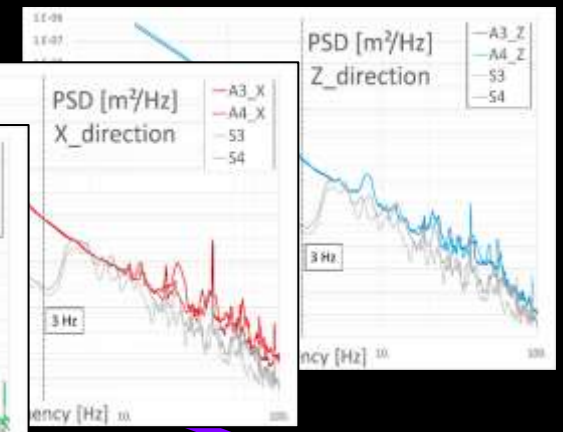
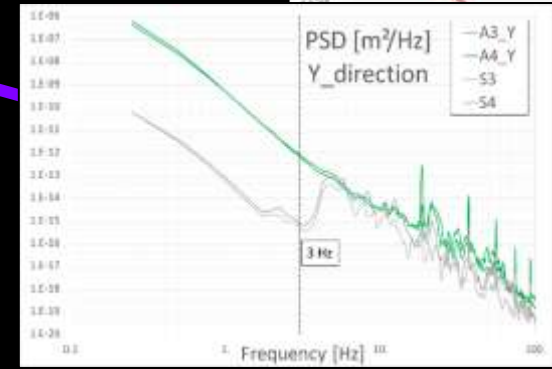
Non-conventional use of Carbon Fibre Reinforced Plastic (CFRP) materials for Vertex Detectors to match the requirements of minimum material budget, high rigidity, thermal management.

Dynamic stability (HC RUN3)



Detector input $R_x(f)$

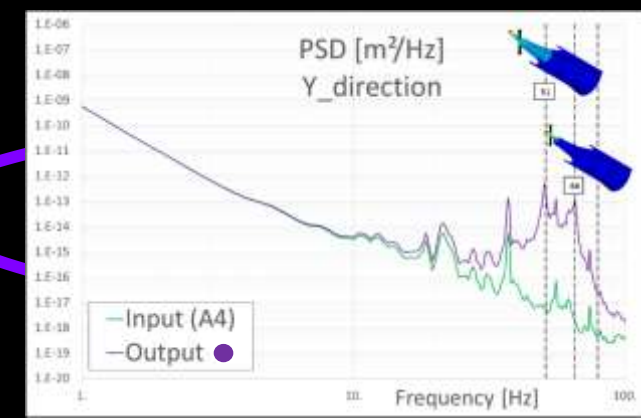
At ITS2 Interface



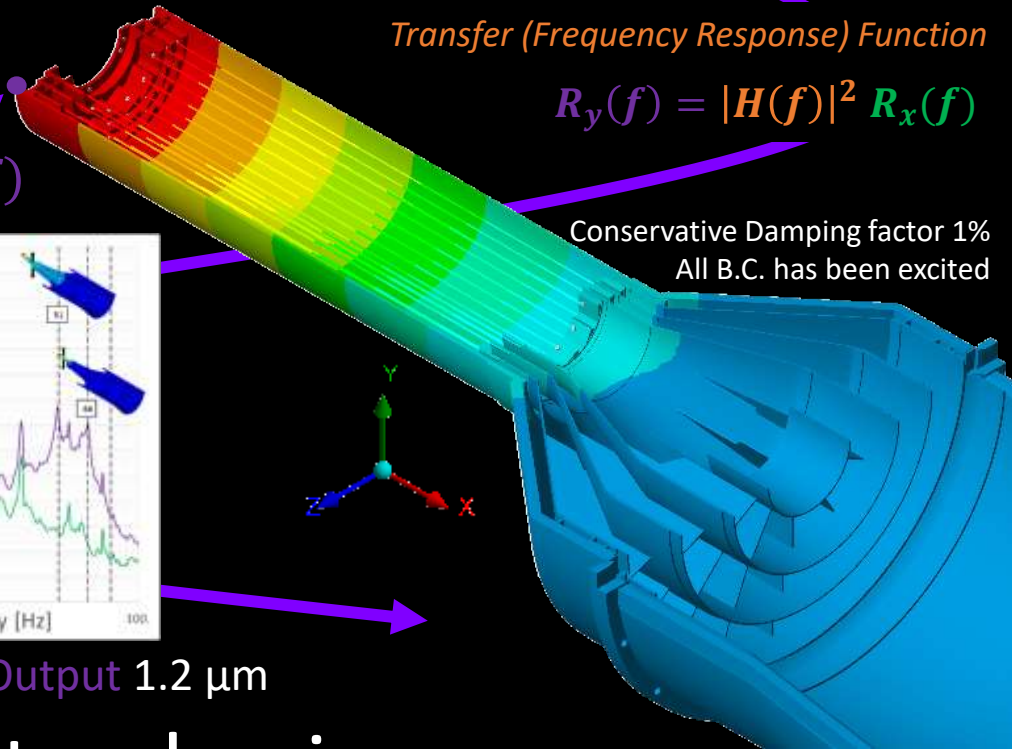
Transfer (Frequency Response) Function

$$R_y(f) = |H(f)|^2 R_x(f)$$

Detector output $R_y(f)$



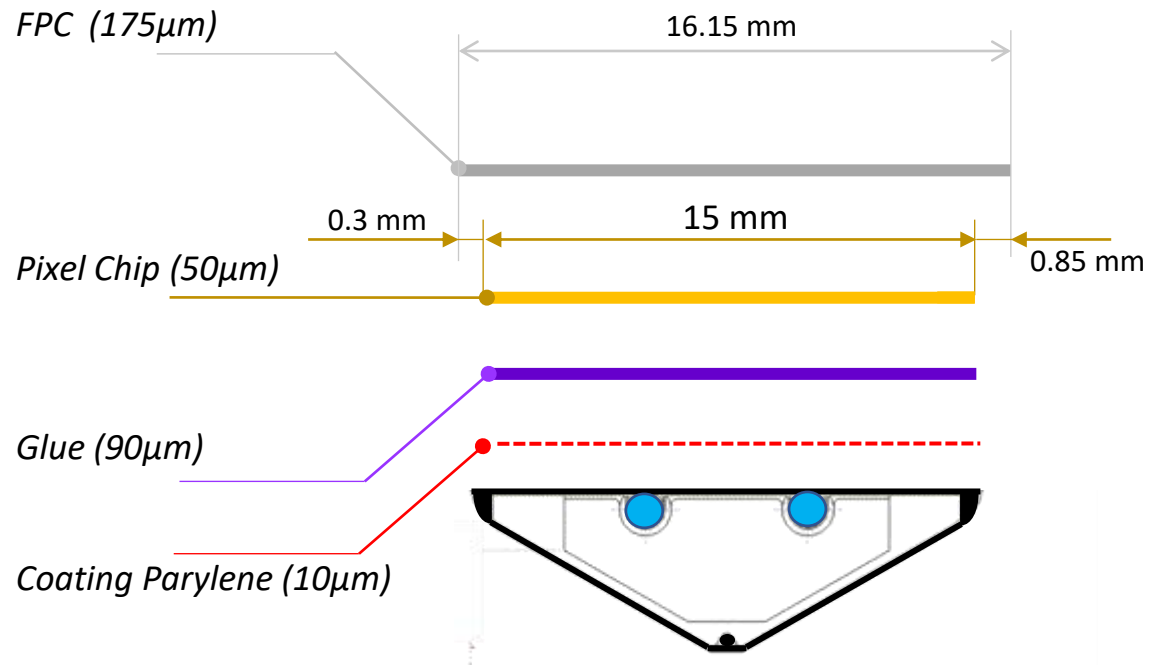
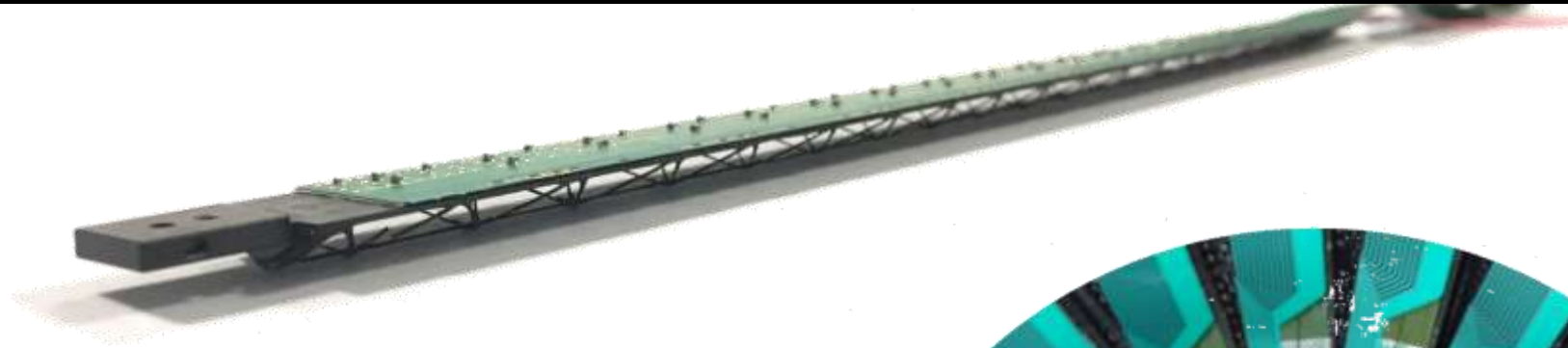
Conservative Damping factor 1%
All B.C. has been excited



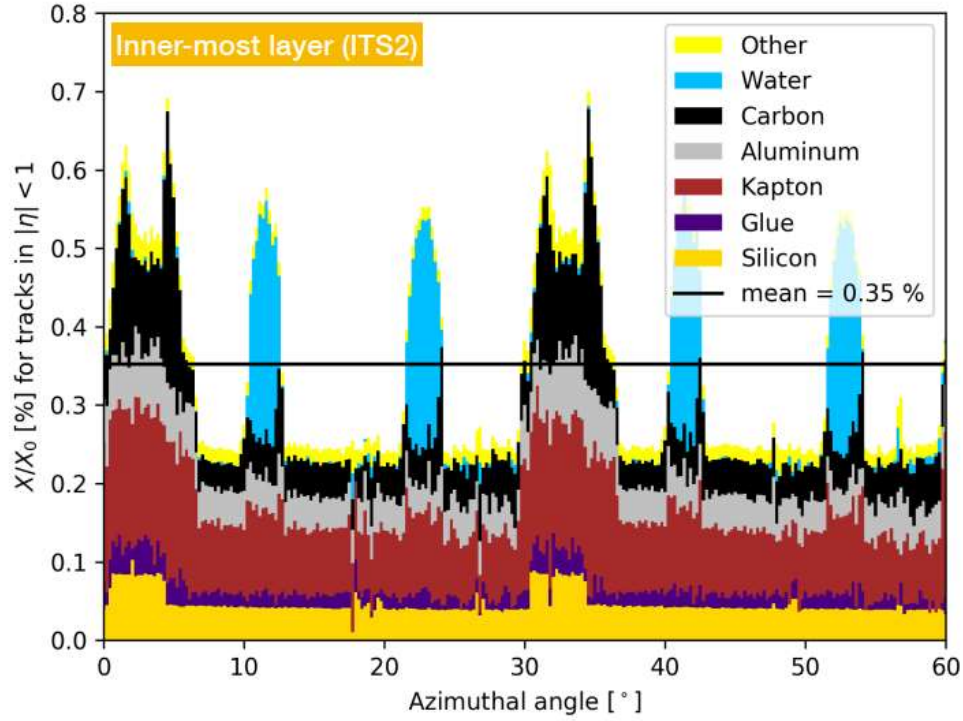
Y-RMS Input $0.72 \mu\text{m}$ \rightarrow Output $1.2 \mu\text{m}$

Stability seismic and cultural noise

Material budget (LHC RUN3)



Material budget (LHC RUN3)



Si only 1/7 of total material

Non uniformity due to overlaps+ support/cooling

Remove water cooling

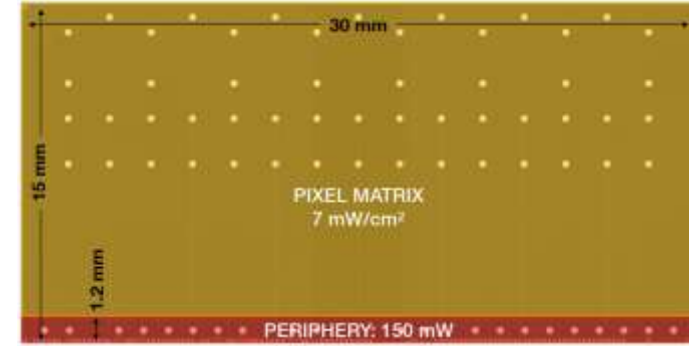
Possible by reducing power consumption in fiducial volume to ~230mW/cm²

Remove external data lines+ power distribution

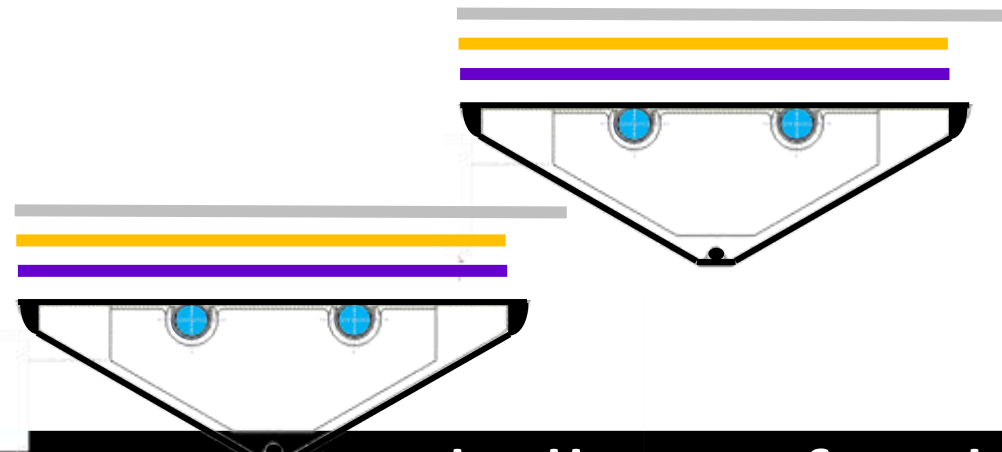
Possible to make a single large chip and use that for distribution

Remove mechanical support inside acceptance

Benefits from increased stiffness by rolling Si wafer

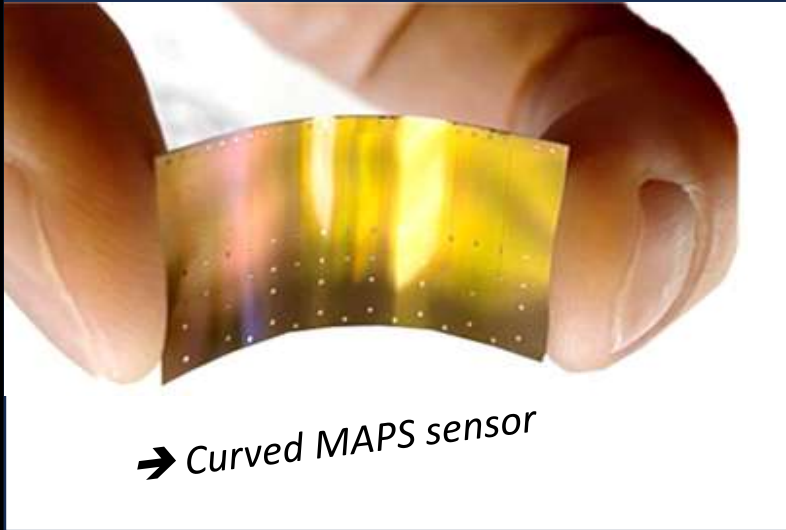


ALPIDE already close: ~40 mW/cm²

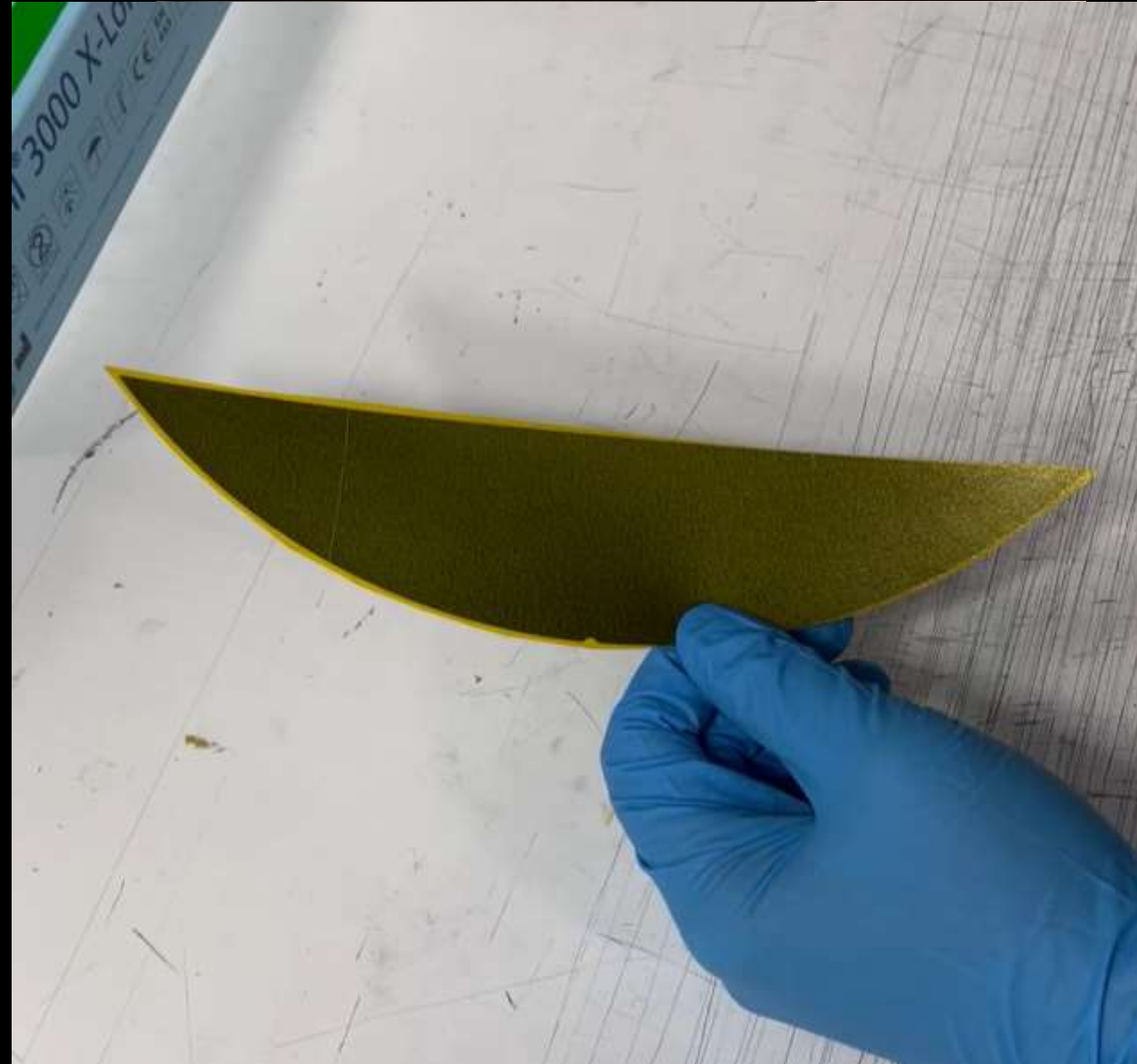


Main challenge for the mechanics is to disappear

Material budget (LHC RUN4)

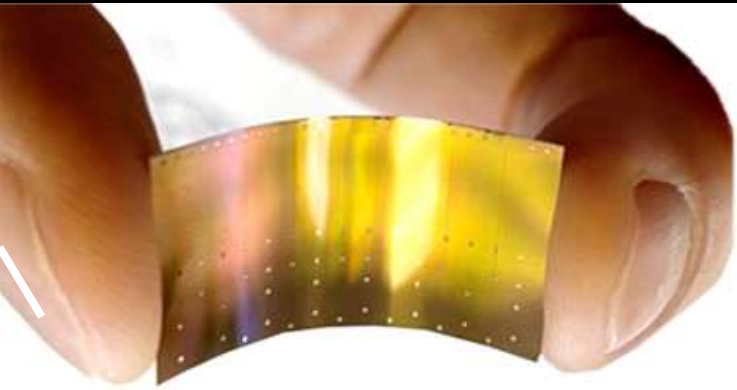


*Alpide, MLR1
bent down to 7 mm radius*



50 um Silicon bending

Material budget (LHC RUN4)

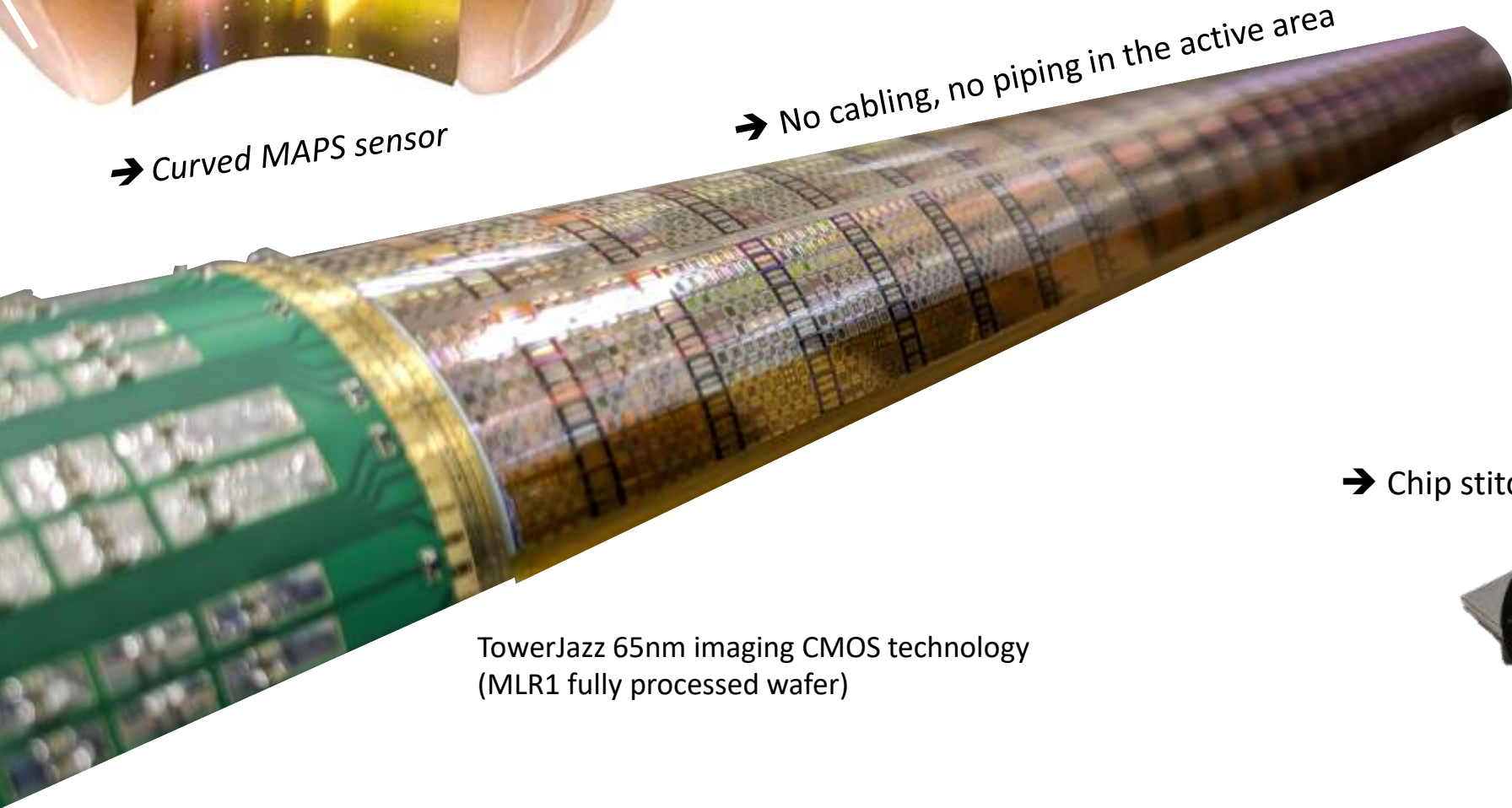


→ Curved MAPS sensor



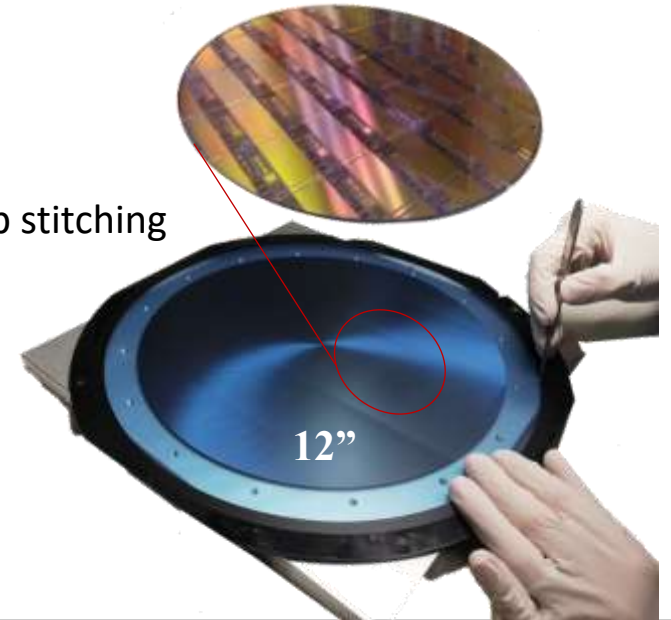
ALICE

→ No cabling, no piping in the active area



TowerJazz 65nm imaging CMOS technology
(MLR1 fully processed wafer)

→ Chip stitching

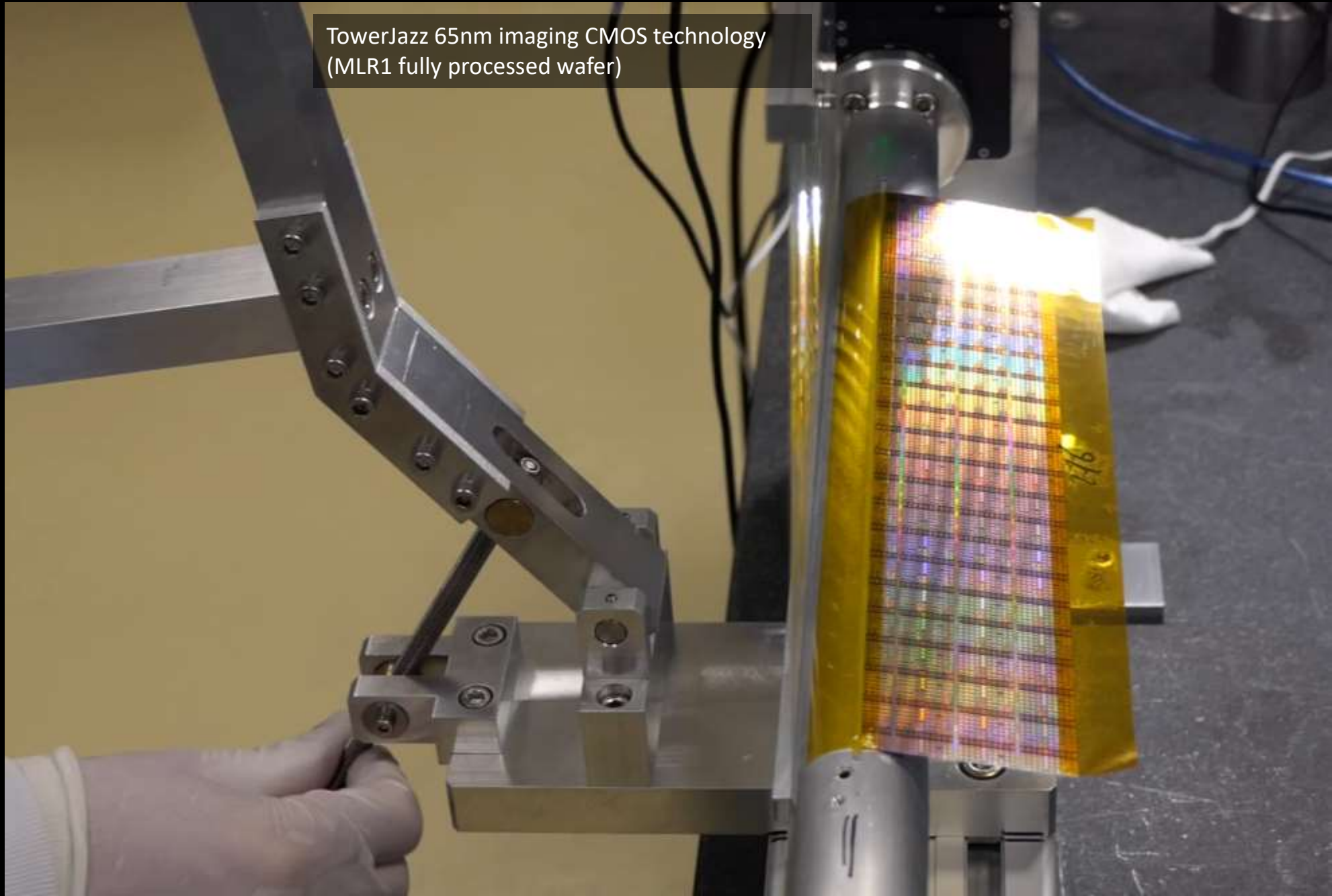


12"

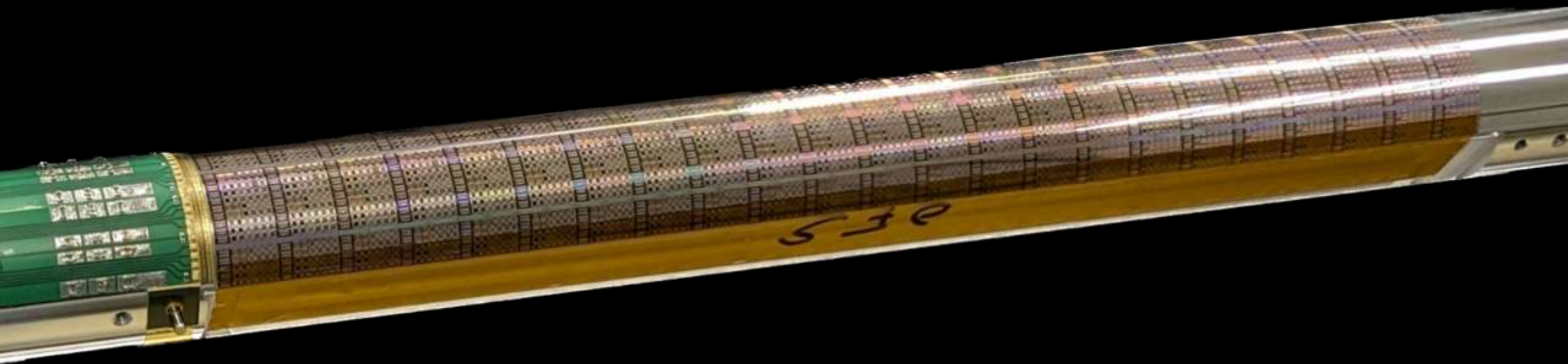
Only the sensor contribution to the active area

BENDING

TowerJazz 65nm imaging CMOS technology
(MLR1 fully processed wafer)

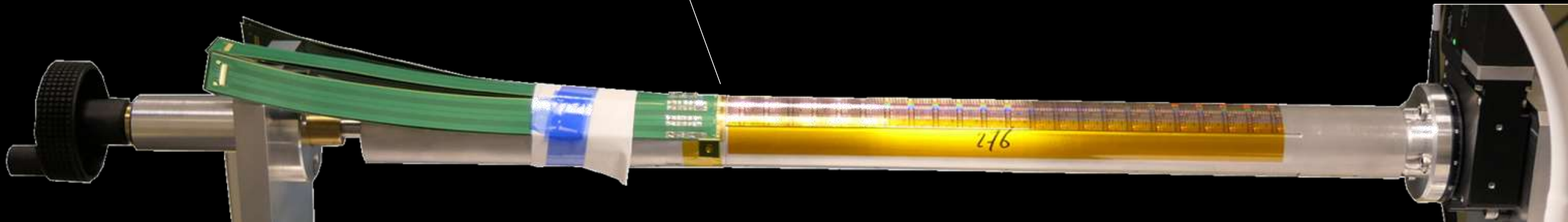


Flex Printed Circuit

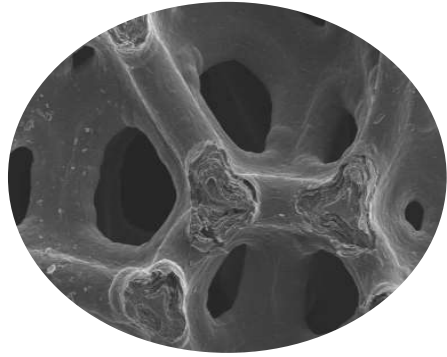




WIRE BONDING



CARBON FOAM



act as mechanical support and air cooling radiator

Half-Rings

Support & cooling: Half ring radiators

Allcomp K9 standard density

$\rho = 0.2-0.26 \text{ kg/dm}^3$, $k = >17 \text{ W/m}\cdot\text{K}$

Radiation length= 164 cm



Step1



- Carbon foam
- Glue penetration $\langle \zeta_g \rangle$
- Carbon fleece

Longerons

Support: Longerons

ERG Carbon RVC @Duocel

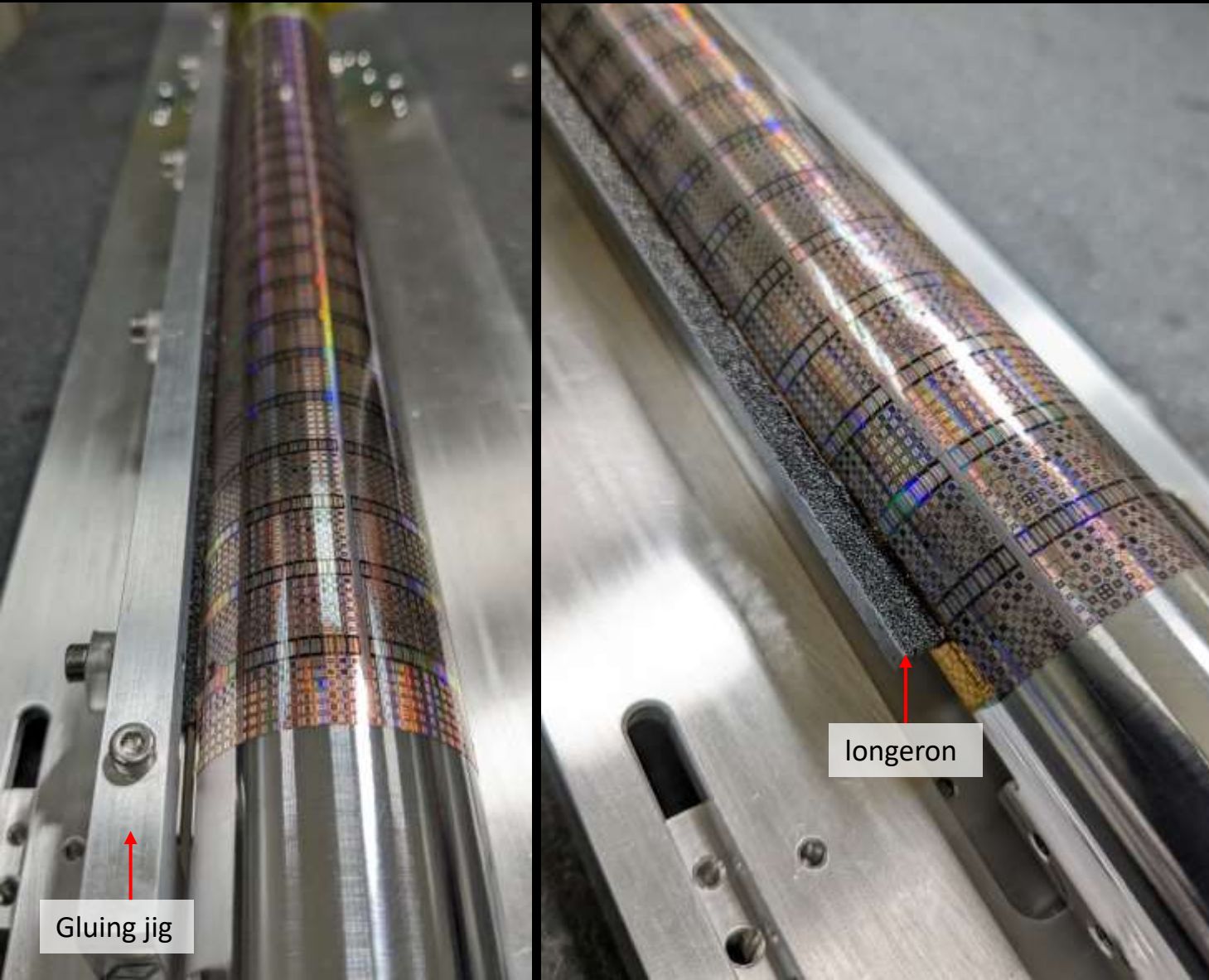
$\rho = 0.06 \text{ kg/dm}^3$, $k = 0.033 \text{ W/m}\cdot\text{K}$,

Radiation length= 854 cm



Assembly of a half-layer

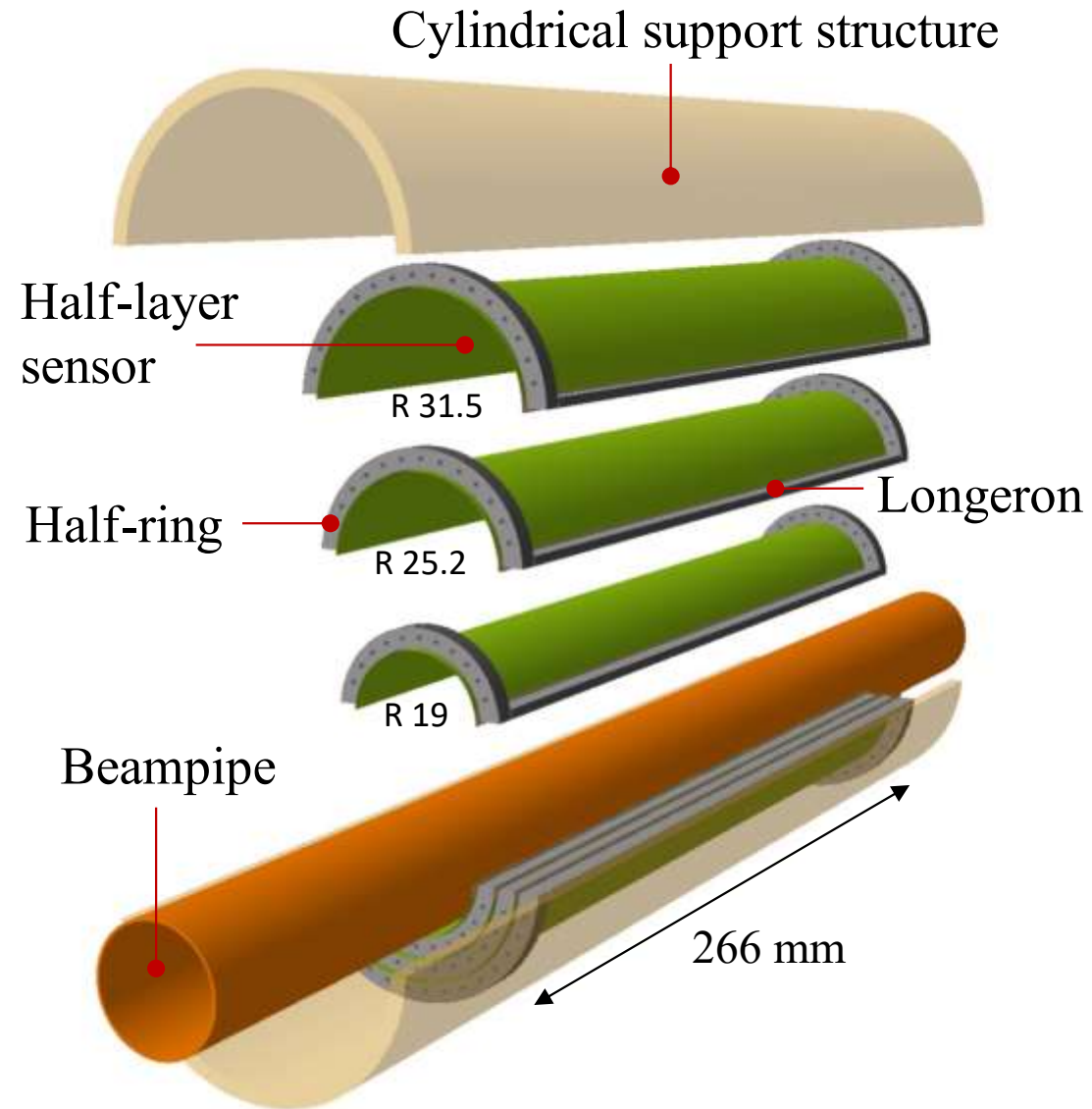
Gluing of the longerons



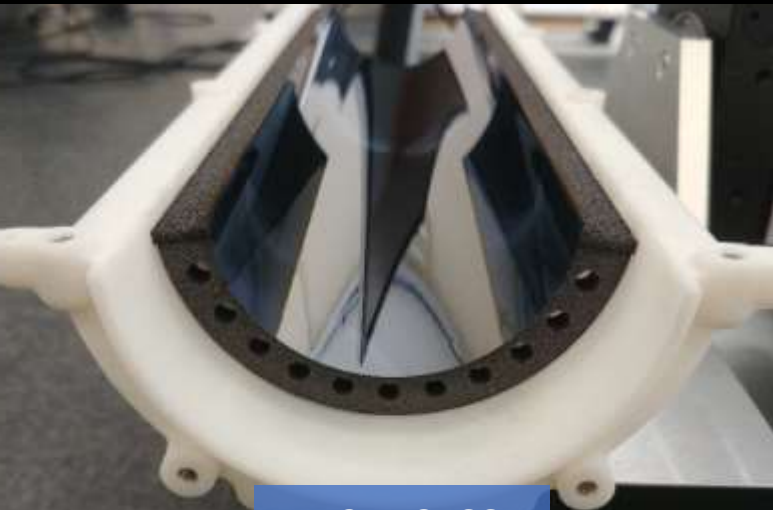
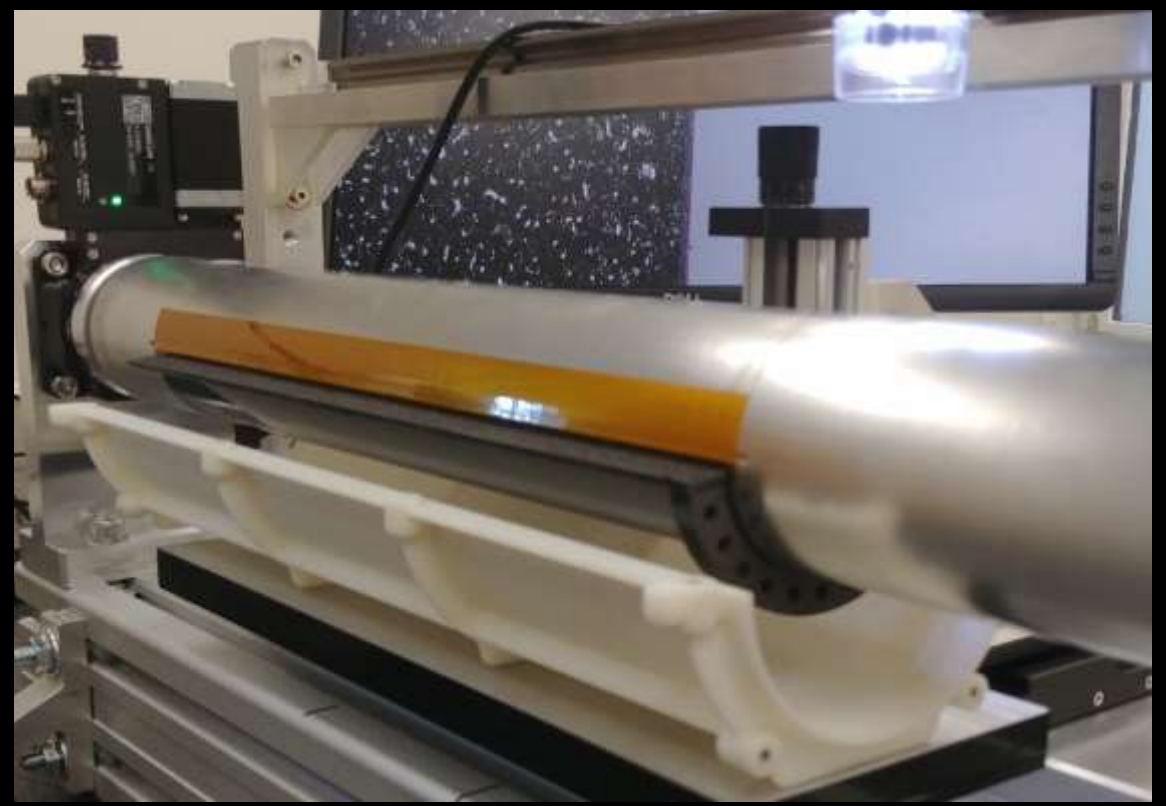
Gluing of the H-rings



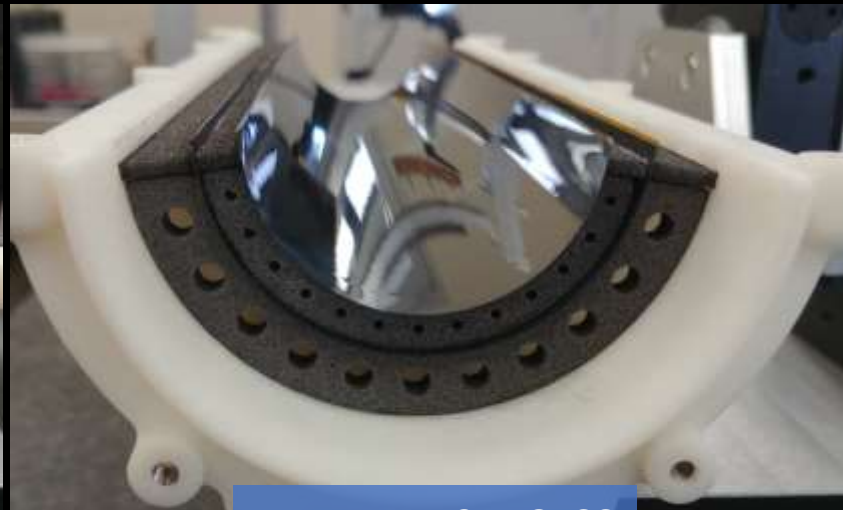
Assembly of a half-barrel



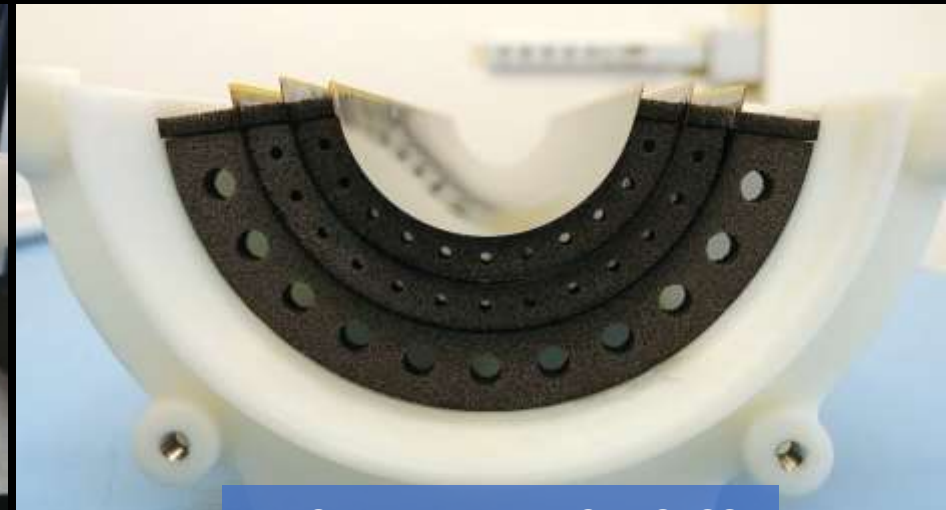
The silicon sensor itself is responsible for 0.07% X_0 and the material budget for tracks with $|\eta| < 1$ on average is set at 0.09% X_0 for the half-layer 0 reaching 0.13% X_0 for $|\eta| = 1$



H-L2 + CYSS

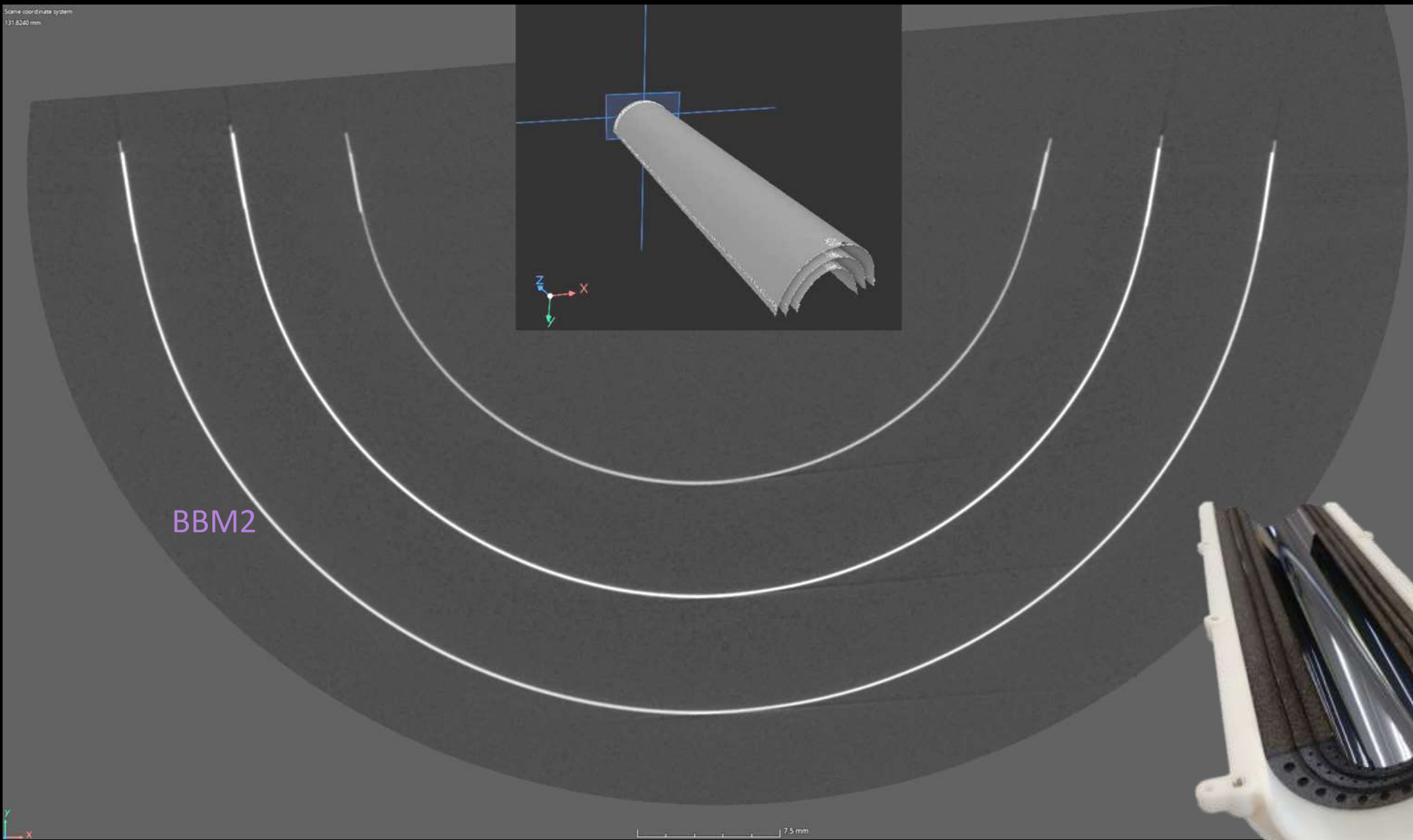


H-L1 + H-L2 + CYSS



H-L0 + H-L1 + H-L2 + CYSS

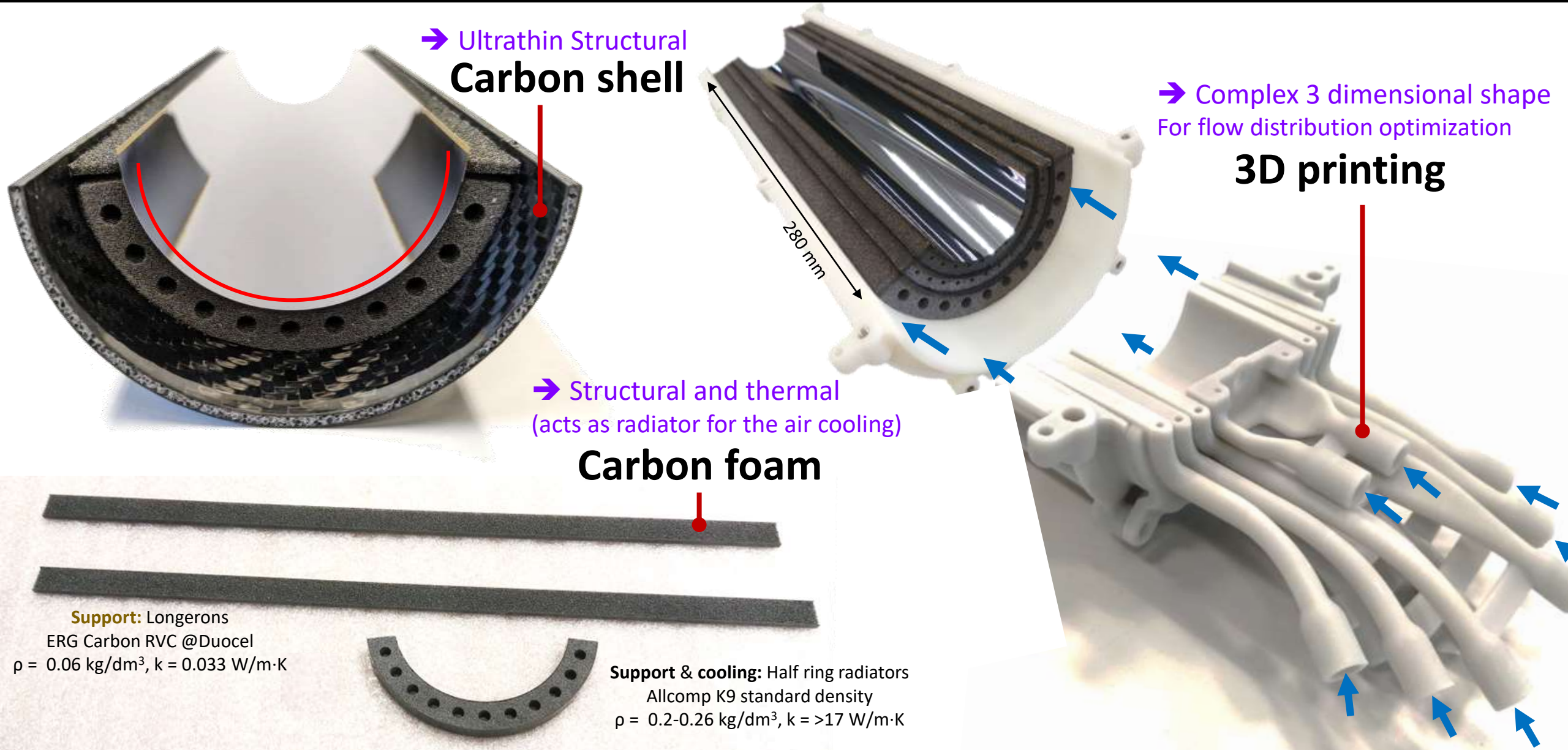
Scene coordinate system
131.8240 mm



BBM2



Thermal management AIR COOLING (LHC RUN 4)



Carbon foam as heat exchanger and mechanical support.... 19

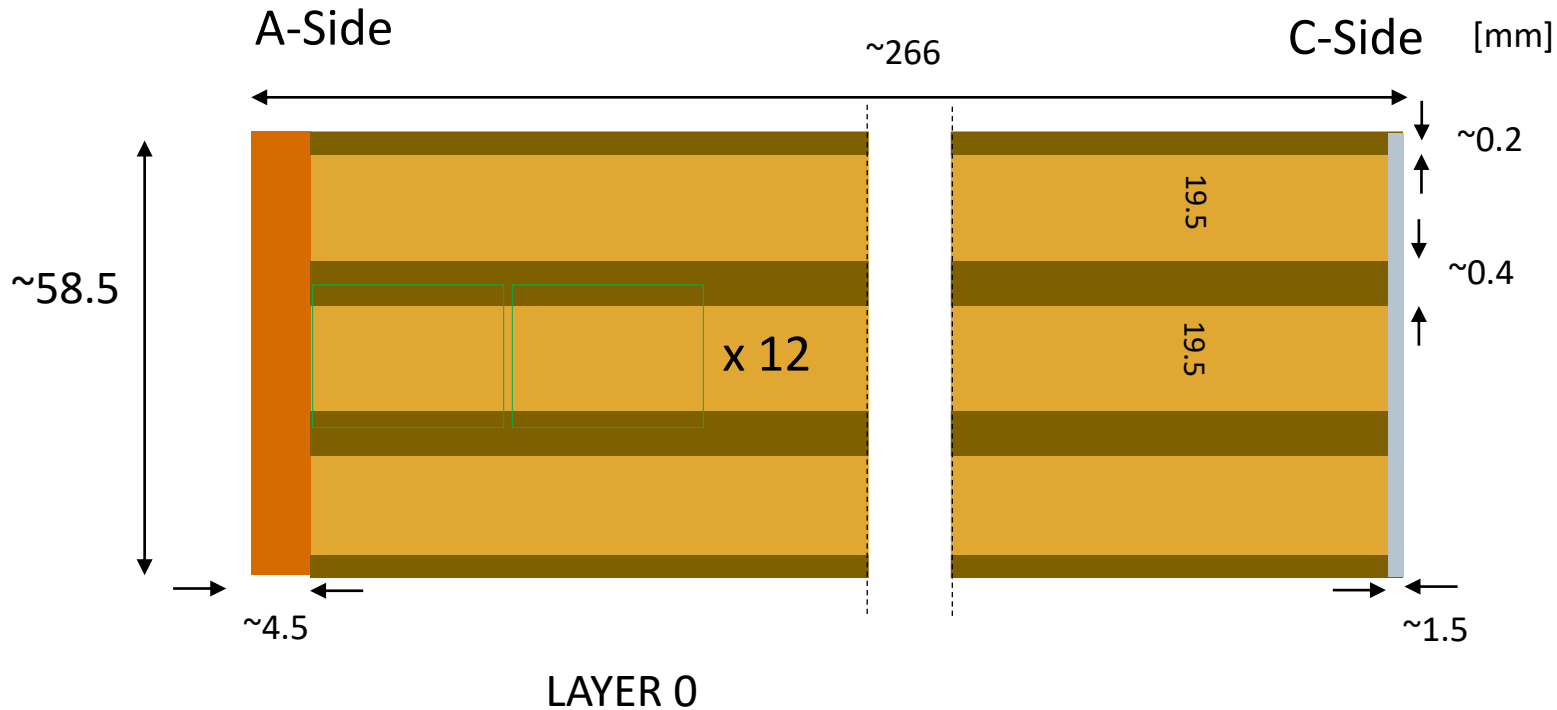
Thermal management AIR COOLING

(LHC RUN 4)

- Two zones of different power dissipation: endcap and matrix
- Same freestream velocity v_∞ in all layers, $v_\infty = 8$ m/s
- Temperature of the inlet air $T_\infty \approx 20$ °C

	Half detector
	Expected
Layer	Total power consumption estimate [W]
0	6.4
1	8.5
2	10.6

Totale 25
 Totale (2 half) 51



□ Repeated Sensor Unit (RSU)

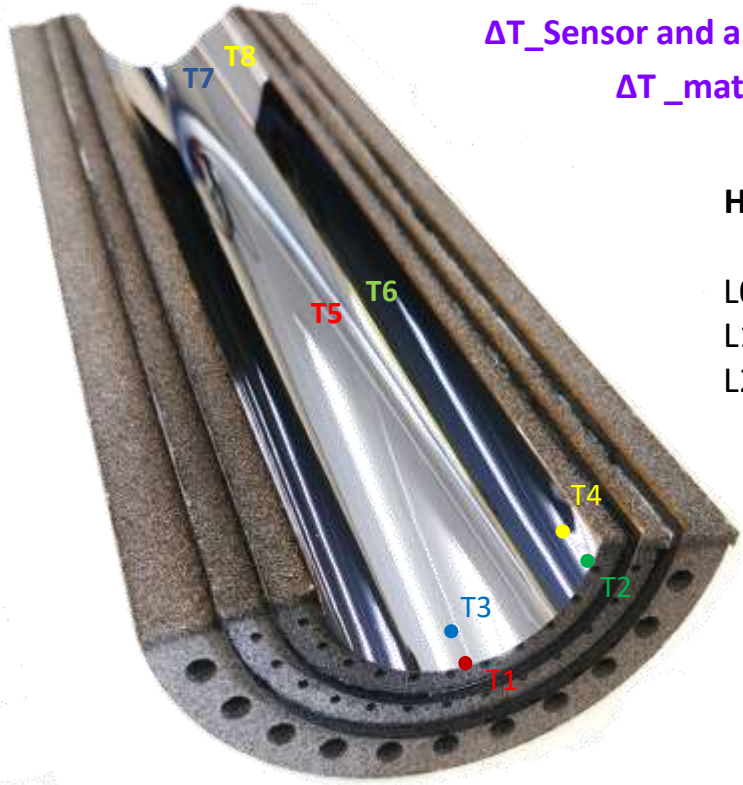
Half-layer Power distribution:

Endcap (791 mW/cm ²)
Matrix (15 mW/cm ²)
Periphery (432 mW/cm ²)

Beam pipe Power dissipation:

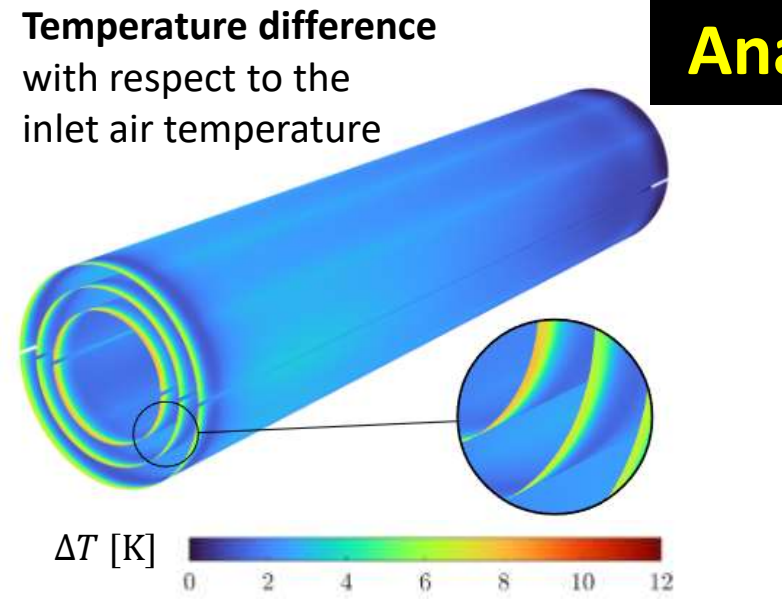
~10 mW/cm² → ~3 W

Thermal management (LHC RUN 4)

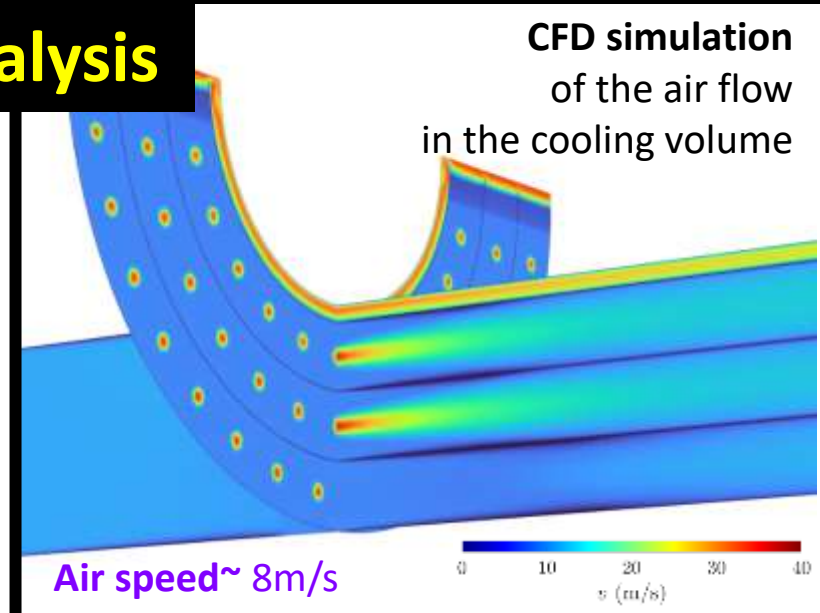


$\Delta T_{\text{Sensor and air}} < 10 \text{ } ^\circ\text{C}$
 $\Delta T_{\text{matrix}} < 5 \text{ } ^\circ\text{C}$

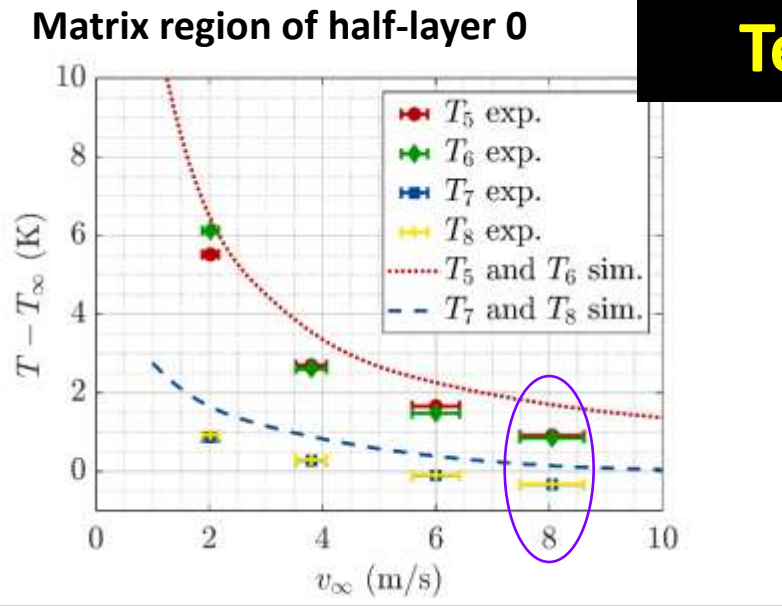
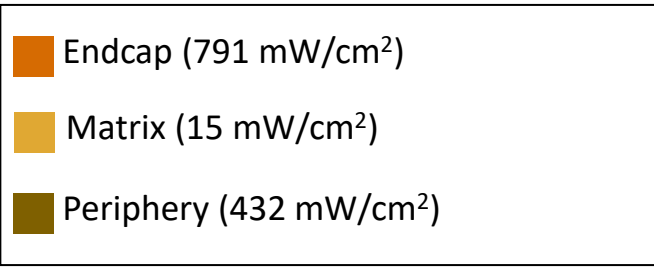
Half layer radius:
 L0 18 mm
 L1 24 mm
 L2 30 mm



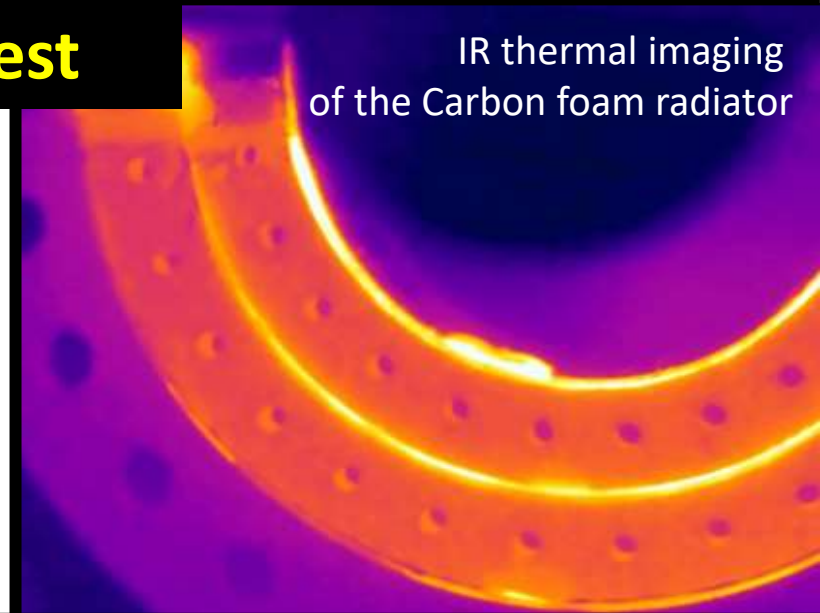
Analysis



Power-map of half-layer 0



Test



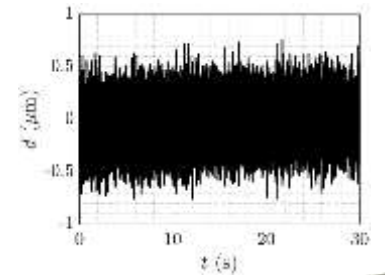
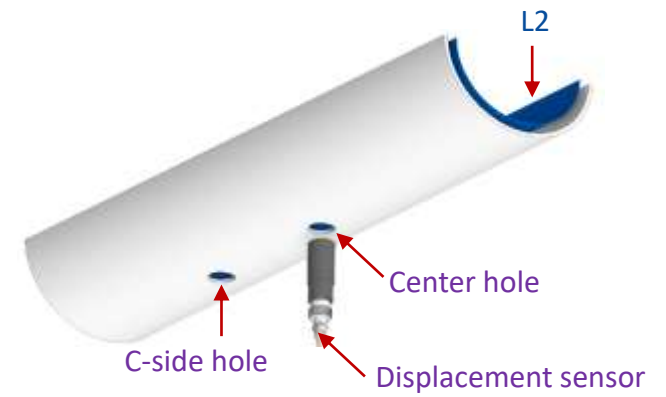
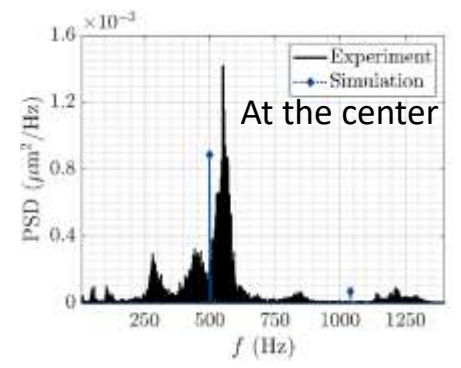
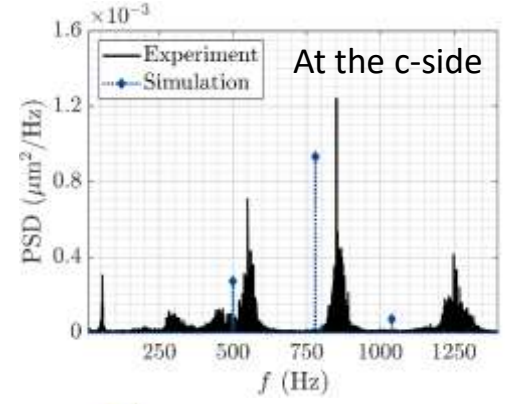
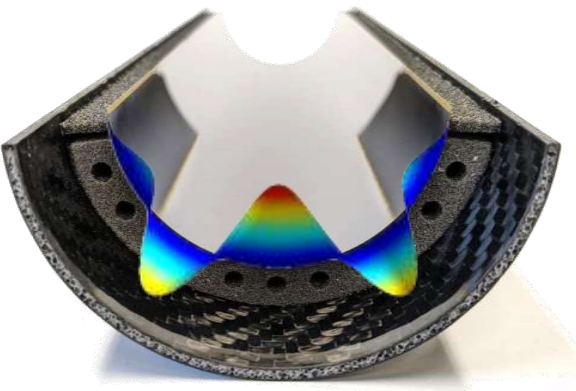
Aeroelastic stability (LHC RUN4)

Test ←

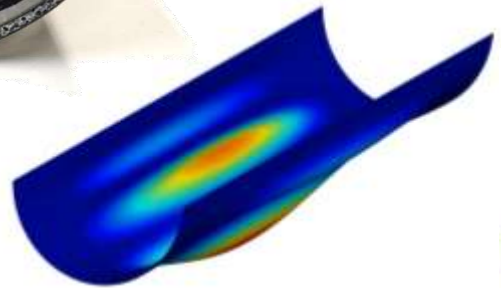
Simulation strategy

1. CFD simulations (8m/sec) → Aerodynamic forces (pressure fluctuations)
2. Forces → Transient mechanical simulations → L2 displacements

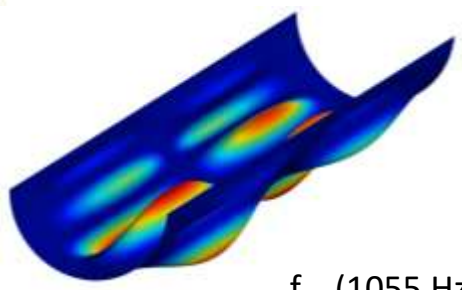
Peak-to-peak displacement $\sim 1.1 \mu\text{m}$
 Root Mean Square of the displacement $< 0.4 \mu\text{m}$
 Agreement experimental test and simulation



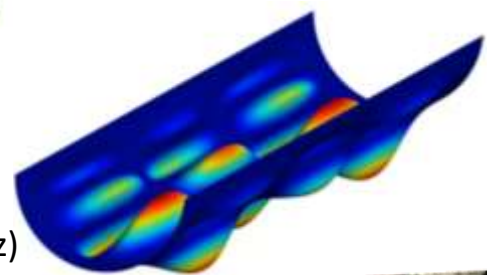
f_1 (492 Hz)
1st Natural freq



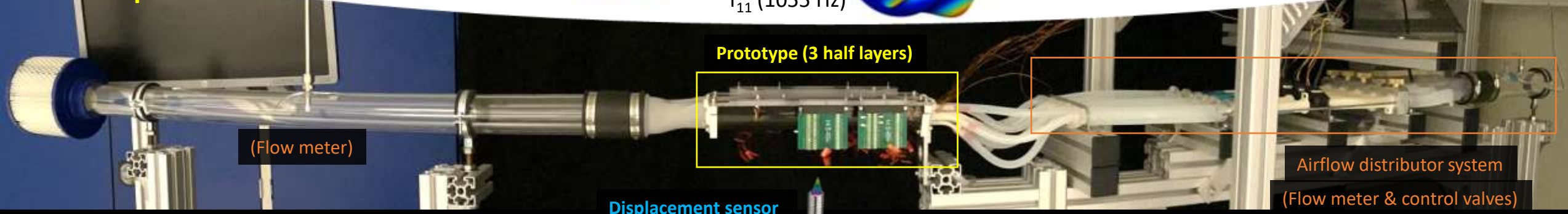
f_5 (775 Hz)



f_{11} (1055 Hz)



Test set-up

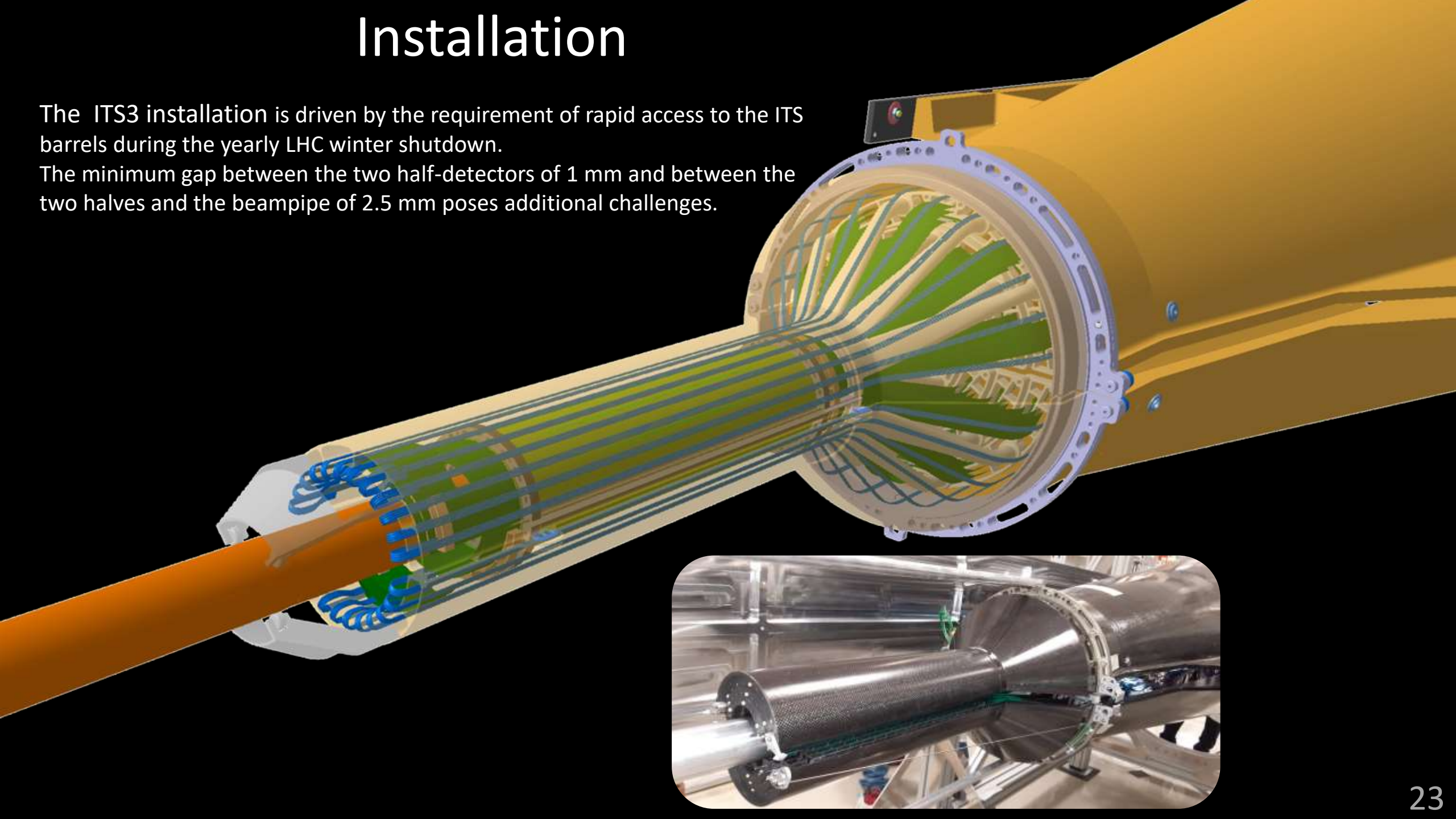


Displacement sensor (confocal chromatic)

Airflow distributor system (Flow meter & control valves)

Installation

The ITS3 installation is driven by the requirement of rapid access to the ITS barrels during the yearly LHC winter shutdown. The minimum gap between the two half-detectors of 1 mm and between the two halves and the beampipe of 2.5 mm poses additional challenges.

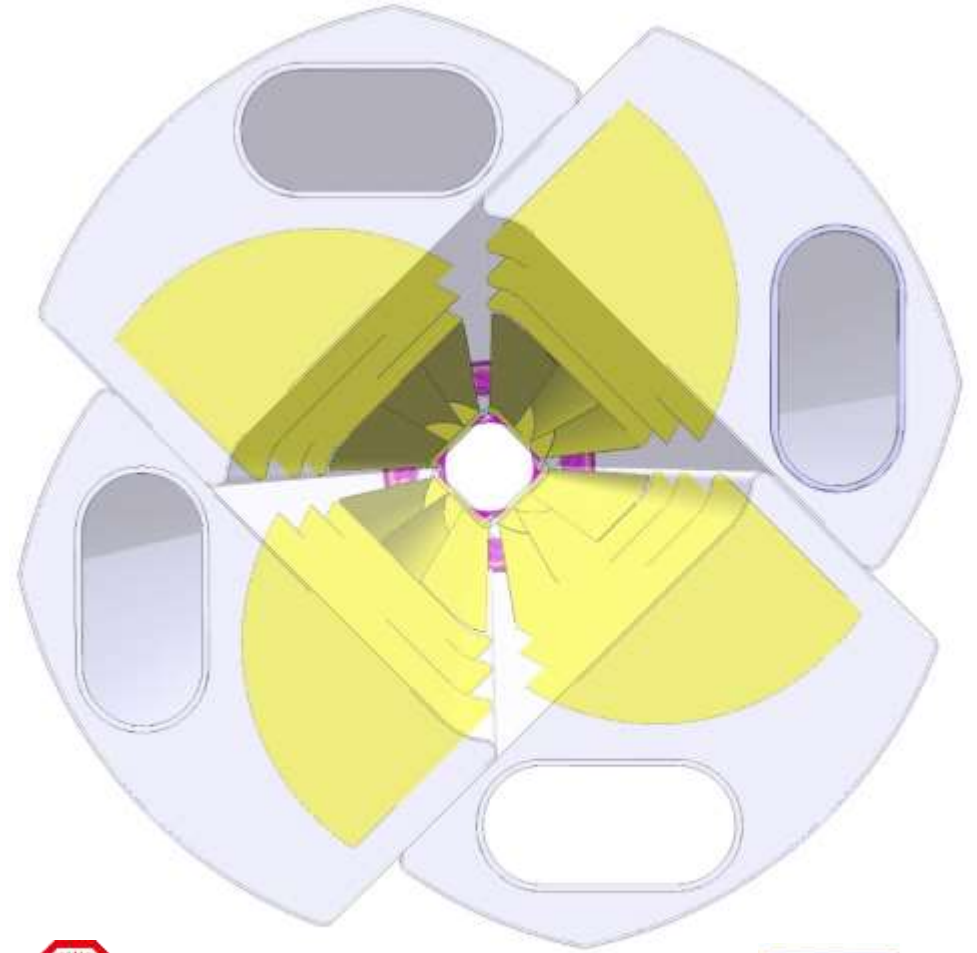
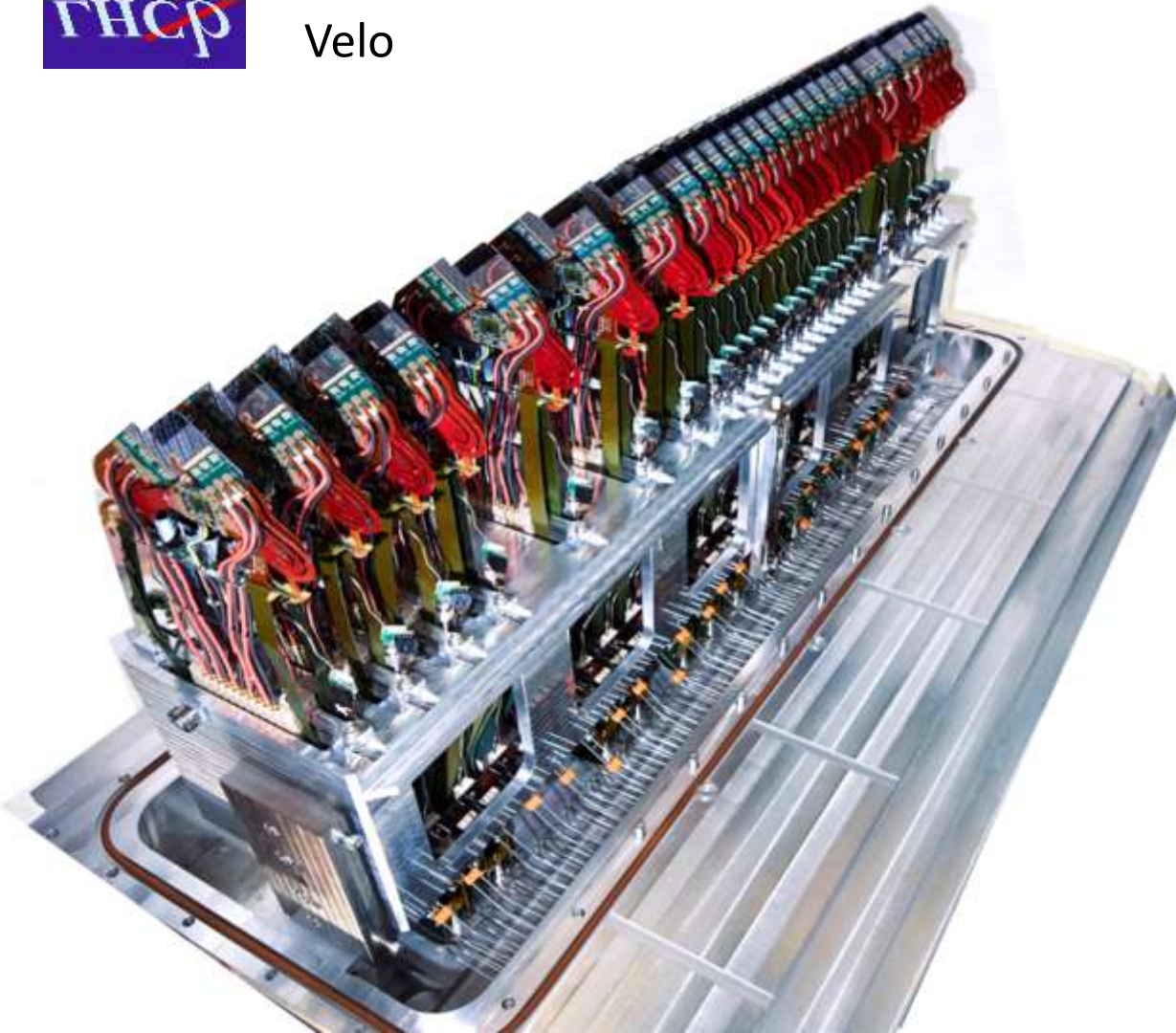


More challenges

Closer to IP



Velo



ALICE IRIS RUN4



EP R&D

Beampipe at LHC

	<i>Inner radius/thickness</i>			<i>[mm]</i>
	RUN1	RUN2	RUN3	Run 4
ALICE	29.2/ 0.8	29.2/ 0.8	18.2/ 0.8	16/ 0.5
CMS	29.2/ 0.8	21.7/ 0.8	21.7/ 0.8	
ATLAS	29.2/ 0.8	23.5/ 0.8	23.5/ 0.8	
LHCB	5/ 0.3	5/ 0.3	3.5/0.15	

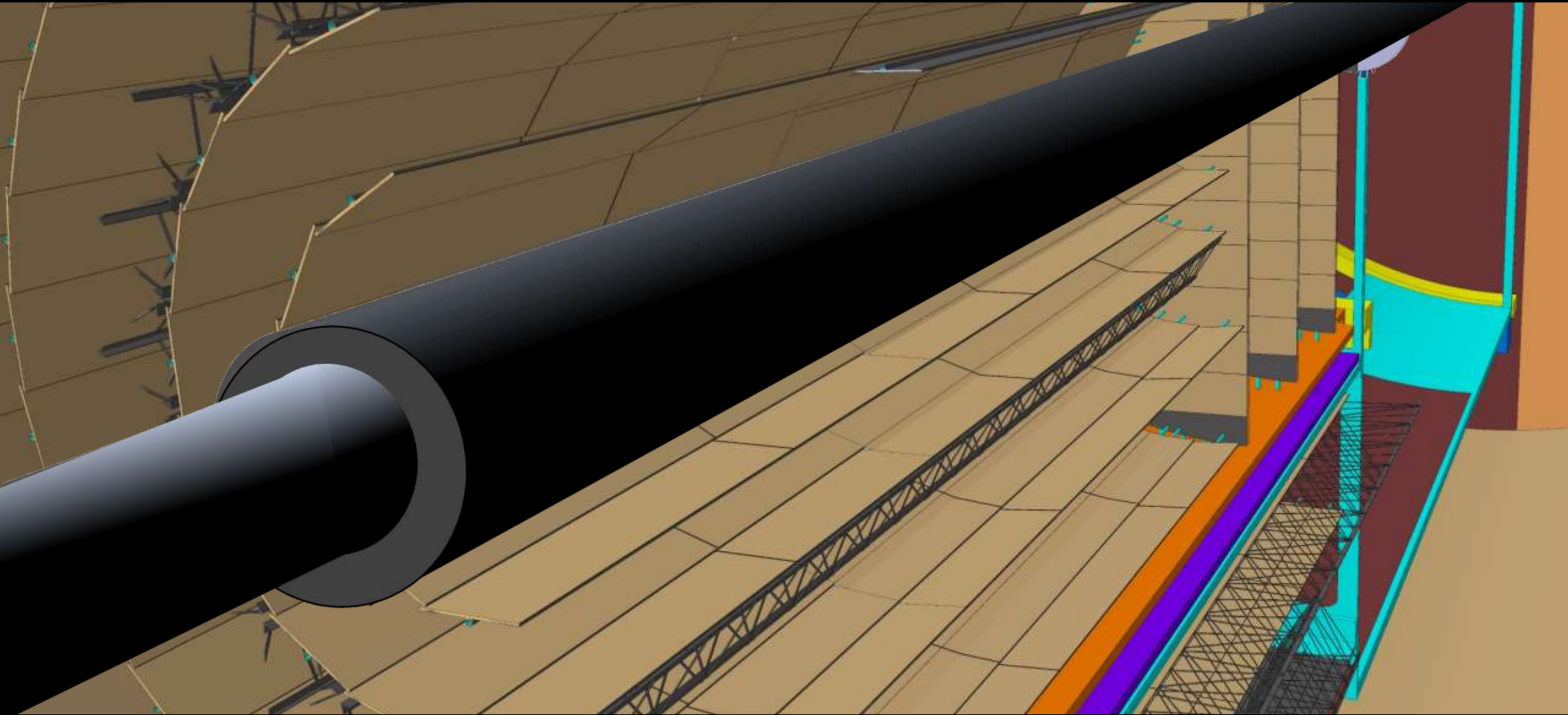
At LHC Apertures, impedance, vacuum stability for the vacuum chambers at the interaction points inside the LHC experiments are key parameters both to the safe operation of the LHC machine and to obtaining the best physics performance from the experiments.

Going closer to the beam with the Tracker layers, has a direct impact on these parameters

New designs for retractable trackers is being investigating, starting from Velo like concept and going to completely new concept like the Iris Tracker.

Minimum aperture at injection ($n>7$) i.e. 16mm radius aperture

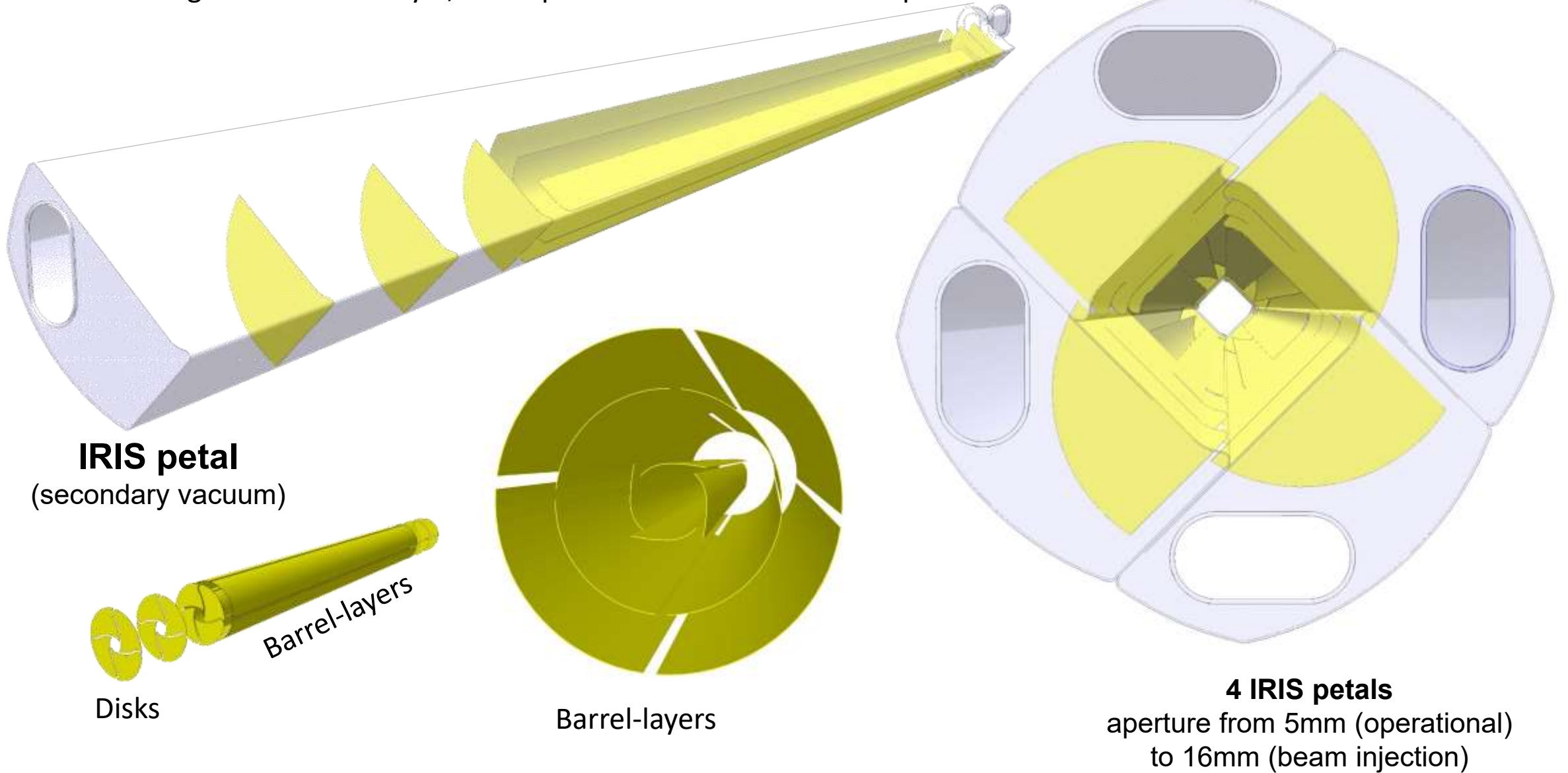
Closer to IB (ALICE IRIS RUN4)



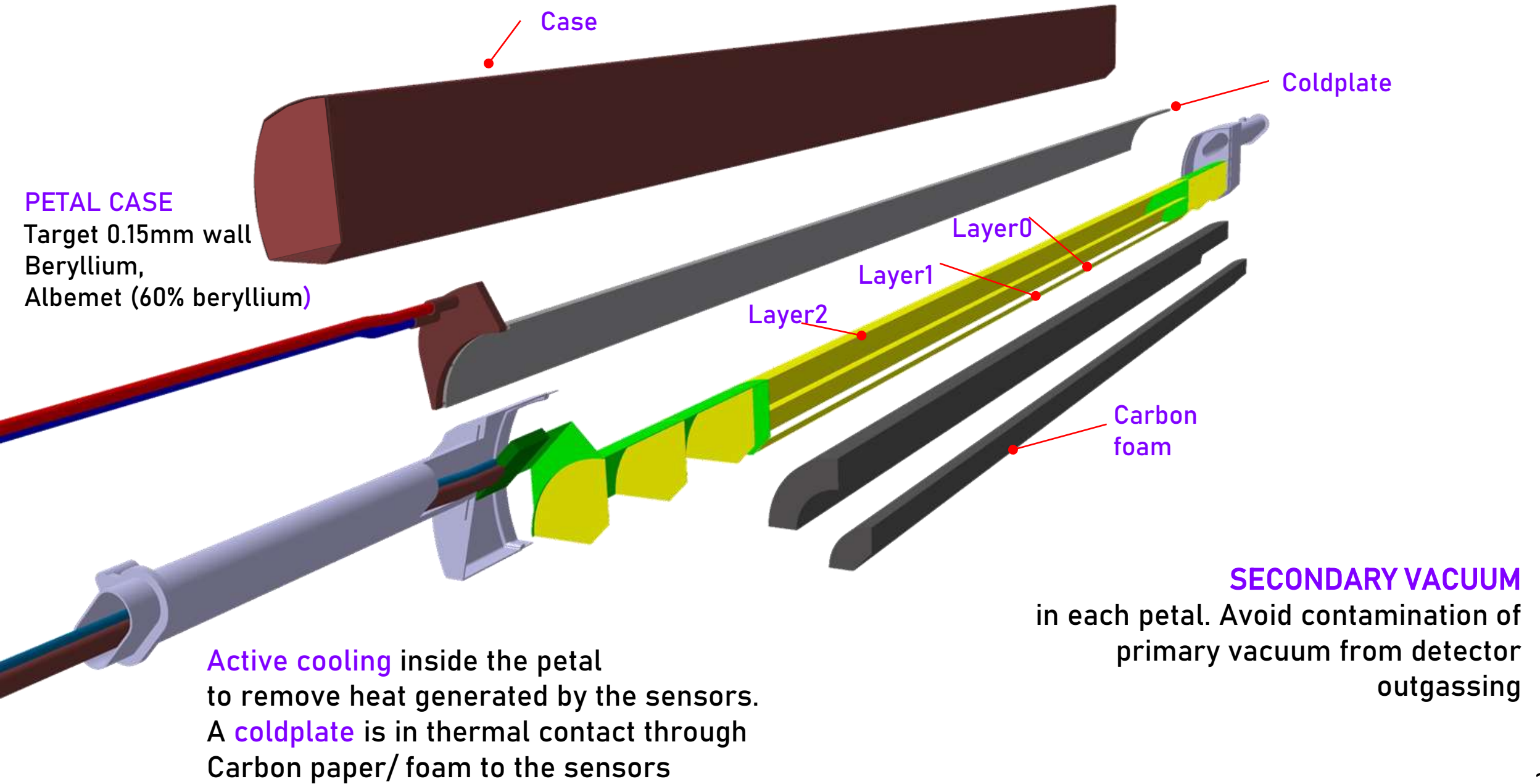
A retractable vertex detector inserted inside the beampipe

Closer to IB (ALICE IRIS RUN4)

The requirements on the pointing resolution are met by a vertex detector with an inner radius of 5 mm, about 0.1 % X0 of a radiation length for the first layer, and a position resolution of $\sim 2.5 \mu\text{m}$



Closer to IB (ALICE IRIS RUN4)



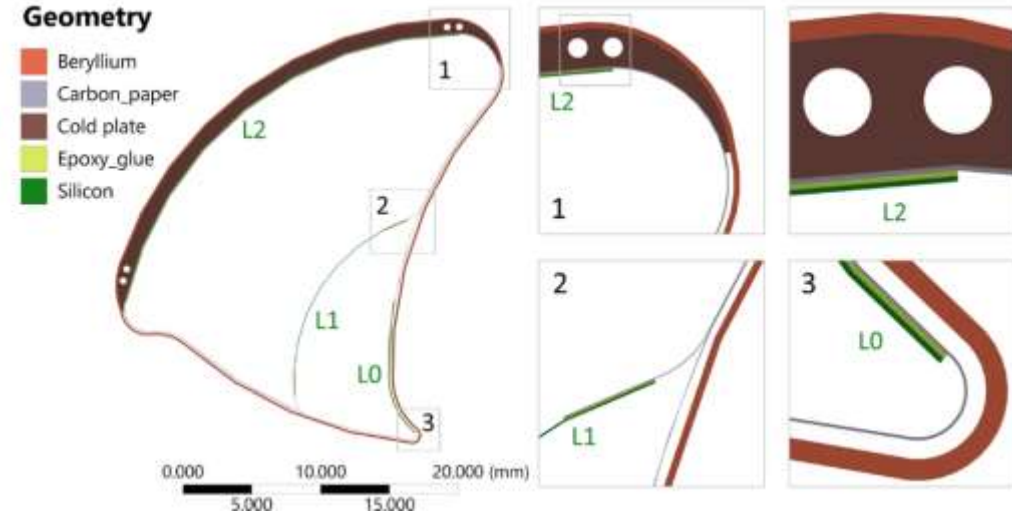


Iris tracker: Petals Cooling @ ~-25°C

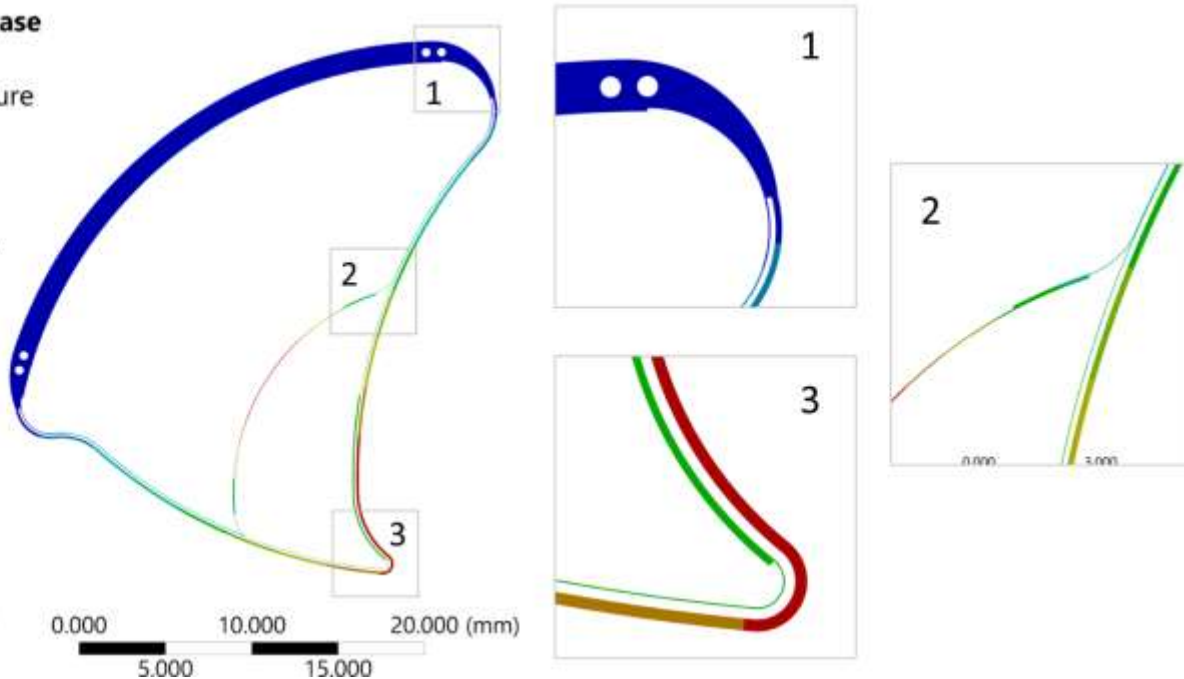
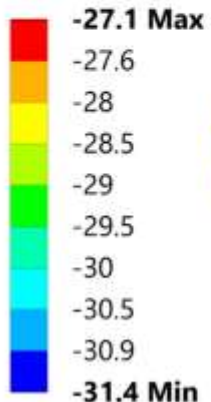
Expected 1×10^{16} 1 MeV n_{eq} of NIEL in 50 months of operation and 6 Mrad TID. Cooling will mitigate leakage current damages that will also depend on the process and the pixel geometry, not yet defined, in addition to the NIEL radiation level. The NIEL radiation load is about the same as for ATLAS and CMS.

Design assumption for preliminary assessment

1. Two-phase evaporative CO₂
(alternatives fluid will be considered)
2. Applied heat flux
70mW/cm² sensors heat flux
100mW/cm² beam pipe current flow (impedance)



AE: 2D Two-phase
All-70mW/cm²
Type: Temperature
Unit: °C
Time: 11



Temperature profile

Preliminary results show that the sensors can be cooled at ~ -29°C with an inlet CO₂ at -35°C.

Same analysis also shows a ΔT of 1-2 degrees within the single sensor and 5 degrees between the coldest (outermost) and hottest sensor (innermost).

Closer to IB (ALICE IRIS RUN4)

IRIS is constituted by 4 petals; each petal consists in a vacuum case that contains sensors and are independently connected to services.

4 x PETALS

SERVICES SIDE

All services from one side
Power, Data, Cooling, Rotation