Performance of the CMS Tracker during LHC Run 3





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In this talk

- CMS Tracker
 - Silicon Pixel detector
 - Silicon Strip detector
- Data taking conditions during Run 3
- Detector performance
 - Pixel tracker performance
 - Strip tracker performance
 - Tracker alignment performance





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CMS Tracker

- Largest silicon tracker in the world!
 - ≁ ~200 m² area, ~135M electronic channels
- Innermost subdetector of CMS
- Crucial for particle identification, track and vertex reconstruction
- Comprised of
 - Pixel sub-detector
 - 4 layers in the barrel (BPIX) and 3 disks (FPIX) in the forward regions
 - Strip sub-detector
 - 10 layers in the barrel (TIB, TOB) and 12 forward disks (TID, TEC)









CMS Silicon Pixel detector







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_1.8 _2.0 -2.2-2.4 -2.6-2.8-3.0 MHz/cm^2 4.0 n z [mm] 2017 Improved ROCs to cope with higher rates

_1.6

Reverse bias up to 800V (compared to 600V before)

4-hit coverage in $|\eta| < 3.0$

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collision point

BPIX Layer 1 only ~3 cm from beam pipe! \rightarrow Particle-hit rate up to 600

Detector component **closest to the**

- Phase-1 Pixel tracker in place since early
- **Pixel refurbished** during LS2
 - Layer 1 fully replaced in 2022







CMS Silicon Strip detector







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Data taking conditions during Run 3





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CMS data taking so far



- CMS instantaneous luminosity $\sim 2 \times 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$
- Mean number of interactions per bunch \bullet crossing (25ns) in 2024 ~ 63!
- Highly irradiated environment, challenging conditions for the tracker!





Luminosity delivered to CMS

- $Run1+Run2+Run3 \sim 318 \text{ fb}^{-1}$
- Just in Run3 ~ 154.6 fb⁻¹

Data-taking still ongoing!



Data included from 2015-06-03 08:41 to 2024-08-19 04:16 UTC

Source: CMS Luminosity Results

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Pixel Performance





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<u>Source</u>

Pixel Performance - Cluster Charge

Clusters formed of adjacent pixels with a charge above a certain threshold

Radiation damage \rightarrow Loss in charge collection efficiency

Solution: Increase operational bias voltage (e.g. Layer 1 gradually from 150 \rightarrow 500 V)



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Pixel Performance - Hit Efficiency

- cluster quality)
- $p_T > 2 \text{ GeV}$

Pixel Performance - Hit Efficiency

- cluster quality)
- FPIX hit efficiency stable across years

Definition: Probability to find any cluster within 1 mm around an expected hit (independent of the

Degradation in hit efficiency mostly for BPIX L1 due to radiation damage \rightarrow Solution: Raise HV

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Strip Performance

<u>CMS-DP-2023-030</u>, <u>CMS-DP-2023-040</u>

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- Drop in bad module fraction around 205 fb⁻¹ due to the recovery of a cooling loop in TEC+
- Fraction seen to increase for a handful of runs due to some (promptly recovered) issues in either data-taking or in powering

Strip Performance - Signal-to-noise Ratio

- Signal-to-noise ratio measured regularly throughout the year
 - Measured separately for 320 μ m and 500 μ m sensors in tracker endcaps
 - **High S/N ratio** \rightarrow **better** zero suppression and cluster building
 - Decreasing ratio with time (as expected from irradiation studies)
 - Expected S/N at the end of Run 3 (~500/fb)
 - Thin sensor 14.5
 - Thick sensor 18.5

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Strip Performance - Hit Efficiency

- Definition: Fraction of traversing tracks with a hit anywhere within a range of 15 strips
- Measured using high purity tracks; modules flagged as bad not used in measurement
- Data used from normal/very high lumi fills to compute hit efficiency

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Tracker Alignment Performance

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CMS-DP-2024-071

Track-based Alignment of the CMS Tracker

Goal: Determine corrections to the position and orientation of all modules of the tracker such that $\sigma_{align} \lesssim \sigma_{hit}$ $(\sigma_{hit} \rightarrow intrinsic hit resolution ~10 \mu m)$

Minimisation of sum of squares of normalised track-hit residuals

$$\chi^{2}(p,q) = \sum_{j}^{tracks} \sum_{i}^{hits} \left(\frac{m_{ij} - f_{ij}(p,q_{j})}{\sigma_{ij}^{m}} \right)^{2}$$

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5)	parameters
to	align!

Alignment is time dependent due to:

- + Cooling cycle $\mathcal{O}(10\mu m)$
- + Magnet cycle $\mathcal{O}(1mm)$
- + Irradiation $\mathcal{O}(1\mu m)$

Strategy:

- + Alignment during data taking → mainly consists of an automated alignment performed in a Prompt calibration loop (PCL)
- + Alignment for reprocessing \rightarrow At the end of 2022 and 2023 data taking, a full modular alignment of both pixel and strip

track-hit residual

Tracker Alignment Performance - Distribution of median residuals

- Tracks first refitted removing the hit under scrutiny to avoid any bias
- For a perfectly aligned detector, distributions expected to be centred at zero
- Width of distribution indicates local alignment precision

Distribution of median of track-hit residuals $x'_{pred} - x'_{hit}$ (DMRs) determined for a given no. of tracks

- + Alignment for reprocessing \rightarrow Smaller mean deviation away from zero and better width
 - Indicating less misalignment due to changing conditions and a higher precision of the calibration

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Tracker Alignment Performance - Track-vertex Impact Parameters

- -5
- being studied from it and considering the impact parameter of this removed track

Impact parameters obtained by recalculating the primary vertex position after removing the track

Exploiting $Z \rightarrow \mu \mu$ events with mass and vertex constraints in alignment for reprocessing helps to reduce the bias in $d_z vs \eta$ significantly

Tracker Alignment - Weak Modes

- Weak modes \rightarrow Unphysical distortions of the detector that don't impact the track fit, but introduce biases in measurements
- Dataset variety of utmost importance for controlling various biases and weak modes
 - Cosmics and $Z \rightarrow \mu\mu$ events critical and therefore exploited in the alignment for reprocessing ◆

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Minimising the spatial dependence of the Z boson mass

- Reconstructed $Z \rightarrow \mu\mu$ mass as a function of
 - Difference in eta between the negatively and positively charged muons (left) lacksquare
 - Azimuthal angle phi of the positively charged muon (middle) and negatively charged muon (right)

Alignment for reprocessing shows an improvement in the uniformity of reconstructed $Z \rightarrow \mu\mu$ mass

Summary

- The CMS Tracker in good condition, successfully delivering high quality data in Run 3
 - The Pixel tracker after refurbishment with a new Layer 1 operating well +
 - The Strip tracker performing excellent, well after ~ 13 years of operation +
 - Ultimate physics precision achieved in the alignment of the tracker via reprocessing the data ◆
- Performance of the detector constantly monitored and frequent calibrations performed
 - + Ageing/irradiation effects visible \rightarrow Efforts made timely to mitigate them
- Studies ongoing with data collected (and to be collected during the remaining year). So many more interesting results expected. **Stay tuned!**

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Pixel Performance - Cluster Charge

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Pixel Performance - Cluster Size

- Cluster Size in X direction (global r– Φ)
 - \bullet
 - \bullet consequently different Lorentz charge
- Cluster Size in Y direction (global z on the barrel) lacksquare
 - tracks therefore longer clusters are expected

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Determined mostly by the Lorentz charge sharing and also the geometry of the detector The difference between layers in BPIX expected due to the different bias voltages and

Determined by the geometry of the detector: the layers closer to the beam see more shallow

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Pixel Performance - Hit Resolution

BPIX residual offset and resolution trends for L1

- **Increase** in offset and the degradation of resolution caused by radiation damage
 - Recovered by the increase in sensor high voltage bias and the update of the Lorentz angle
- Performance of template algorithm better than generic algorithm

Pixel Performance - Hit Resolution

Barrel hit residual calculation (Triplet method)

Fit residuals with Student-t function for offset (mean) and resolution

Select tracks with $p_T > 12$ GeV & 3 hits \rightarrow Refit using 2 hits \rightarrow Extrapolate to 3rd layer \rightarrow Calculate residuals with the actual hit

- Cluster position estimated with two reco algorithms
 - Generic: Simple; based on track ◆ position and angle; used in HLT
 - Template: Based on detailed cluster shape simulations; used in final track fitting offline.
 - Template algo performs better

Pixel Performance - High Voltage Bias Scans

- **Target:** To determine operational bias voltage for pixel sensors
- track cluster size
- Operating voltage 450 V in BPIX L1, 350 V in L2 and 250 V in L3 & 4

Monitored quantities: Hit efficiency, average normalized on-track cluster charge and average on-

- Trend change of the cluster size in xdirection comes from 2 competing effects:
 - Bias Volt. $\uparrow \rightarrow$ + Charge collection 1
 - Bias Volt. $\uparrow \rightarrow$ ◆ charge sharing ↓

Strip Performance - Hit Resolution

- Resolution computed using hits in overlapping modules of the same layer
- cluster)

Hit pairs selected requiring various quality conditions on strip-clusters (e.g. at most 4 strips per

Automated Tracker Alignment

- Automated alignment workflow that provides an update of the alignment parameters within 48 hours
- Alignment of the pixel while the strip is fixed
 - 2022: The pixel detector corrected at the **half-barrel** + half-cylinder level until the first technical stop (36. d.o.f). A new high granularity alignment (HG PCL) at the ladder+panel level active after the technical stop (~5k parameters)
 - 2023: The HG PCL predominantly active for the whole year

Tracker Alignment Performance - Distribution of median residuals

Sensitivity to Lorentz drift

- Sign of the Lorentz Angle (LA) shift depends on the orientation of the E field
- BPIX modules arranged in ladders (alternatively facing inward or outward w.r.t to the beamline)
 - Inward and outward facing tracker modules affected by Lorentz drift in opposite ways

• Ageing of modules due to high radiation environments causes changes in the Lorentz drift

Monitoring difference in DMR mean values ($\Delta\mu$) for inwards and outward facing modules allows to monitor the Lorentz drift

- + Deviation from zero \rightarrow Shift in $LA \rightarrow$ indication of radiation damage
- BPIX layer 1 most affected due ◆ to proximity to the interaction point

Tracker Alignment - Impact Parameter Bias in Z \rightarrow µµ events

- Mean correction to the measured transverse (top) and longitudinal (bottom) impact parameter estimated to satisfy on-averagezero difference between the impact parameters of the two muons originating from the Z boson is shown in bins of track and
 - Mean corrections are smaller and show an improved uniformity with the alignment for reprocessing
- The alignment during data taking (left) is shown in comparison to the alignment for reprocessing (right) for 2023 data

