

# EFTofLSS meets simulation-based inference: $\sigma_8$ from biased tracers



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Beatriz Tucci

In collaboration with: Fabian Schmidt  
Based on arXiv:2310.03741



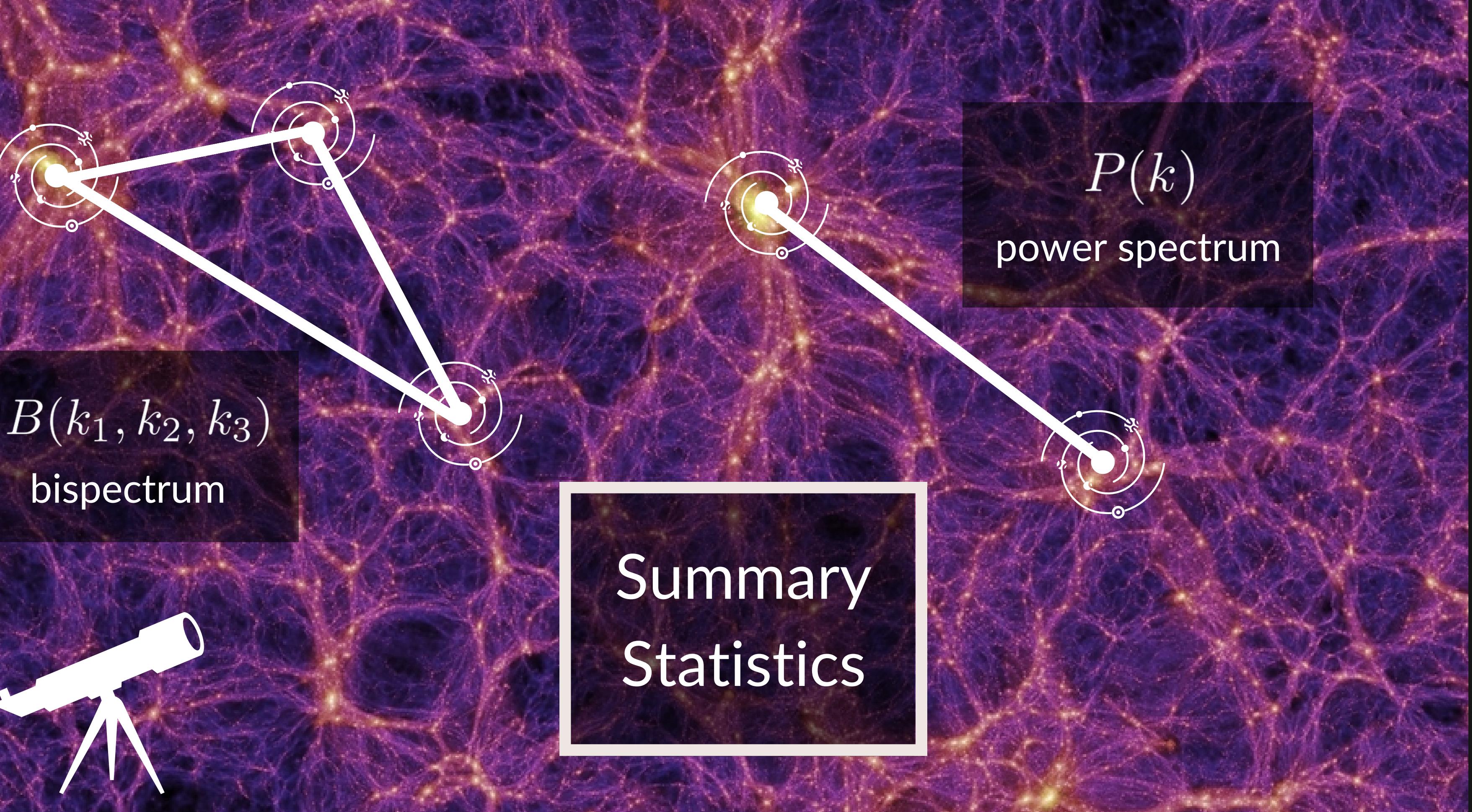


Ivana Babić talk today:  
*Field-level BAO inference*

Field level



Summary  
Statistics



$B(k_1, k_2, k_3)$   
bispectrum

$P(k)$   
power spectrum

Gaussian likelihood?



# Standard inference in cosmology

Parameters  
posterior

Likelihood

Prior over the  
parameters

$$p(\theta|x) \propto \mathcal{L}(x|\theta)\mathcal{P}(\theta)$$

# Standard inference in cosmology

Parameters  
posterior

$$p(\theta|x) \propto \boxed{\mathcal{L}(x|\theta)} \mathcal{P}(\theta)$$

Prior over the  
parameters

Likelihood

$$\mathcal{L}(x|\theta)$$

## Possible problems:

- Need of analytical approximations
- Cumbersome covariance estimations
- Binning effects

# Simulation-based inference

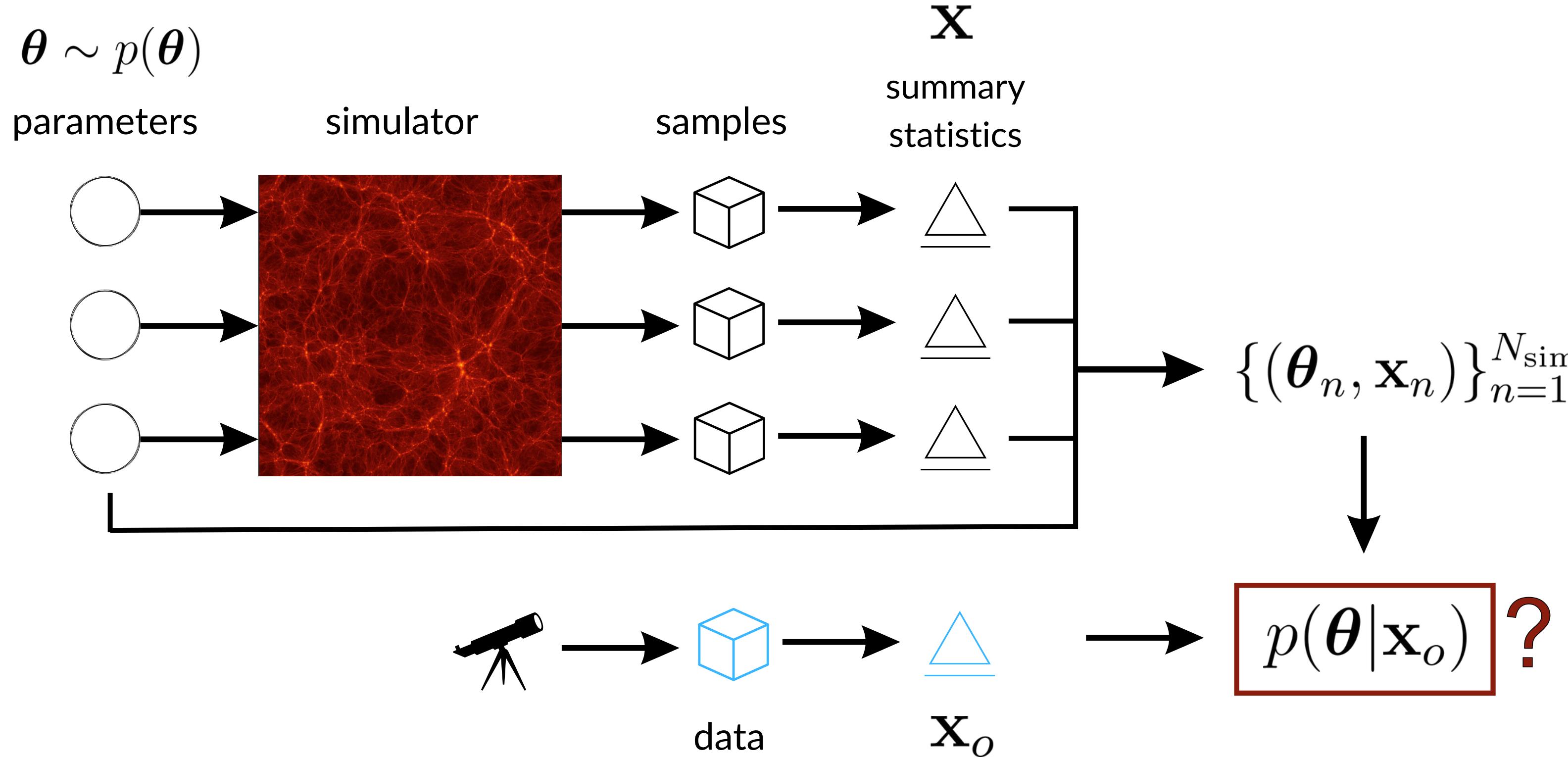
Parameters  
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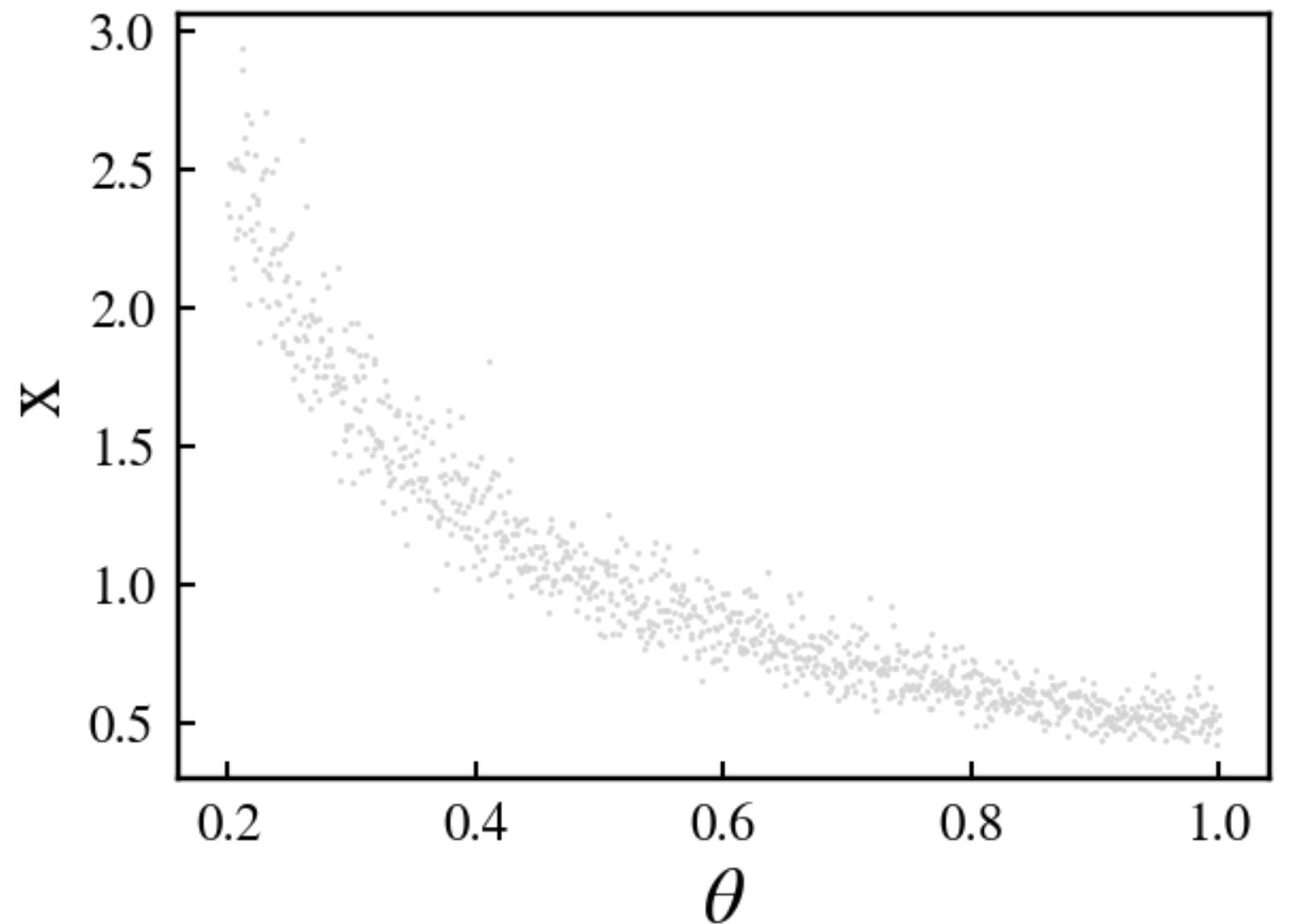

$$x \sim \text{simulator}(\theta)$$

# Simulation-based inference



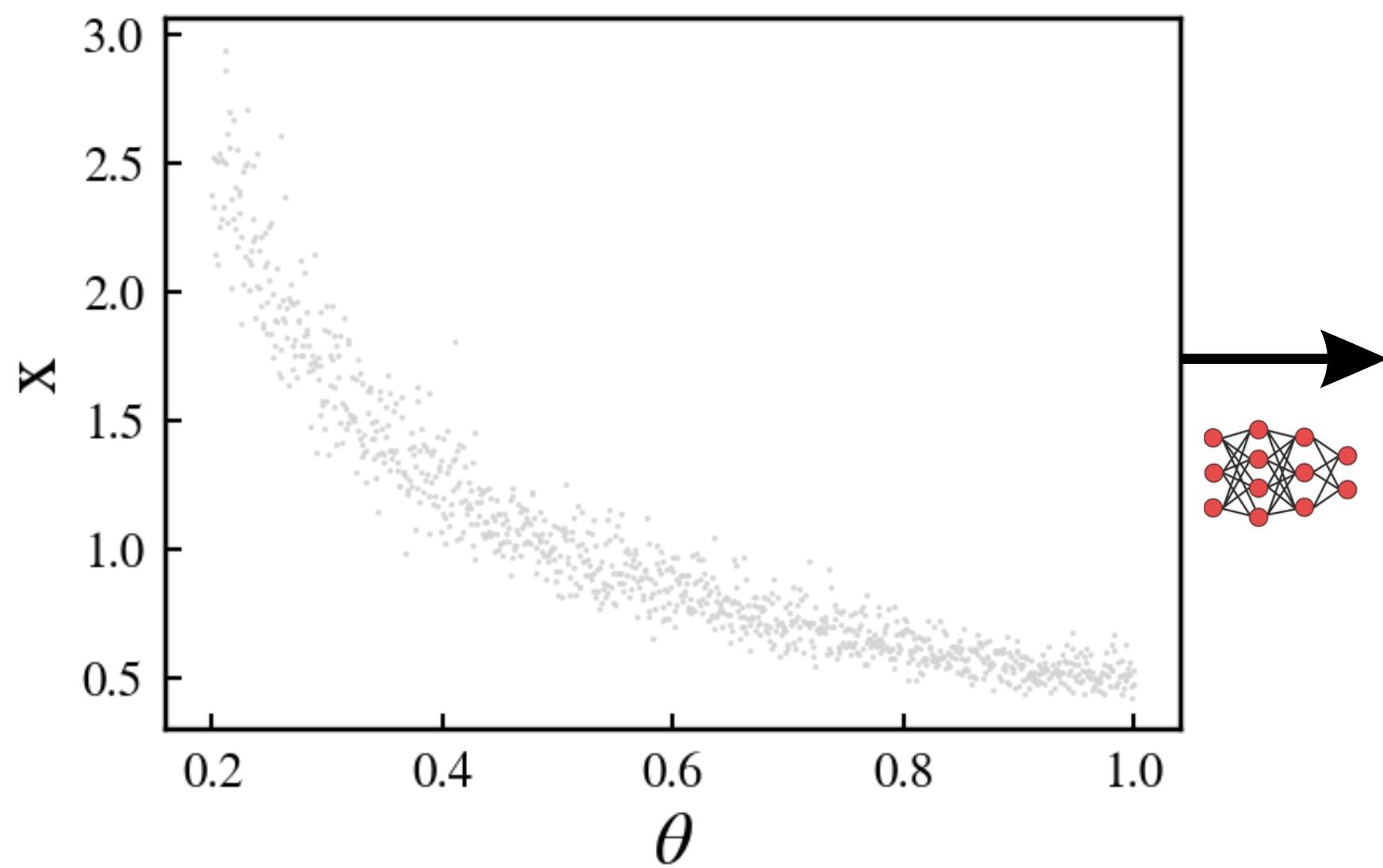
# Simulation-based inference

$$\{(\theta_n, \mathbf{x}_n)\}_{n=1}^{N_{\text{sim}}}$$

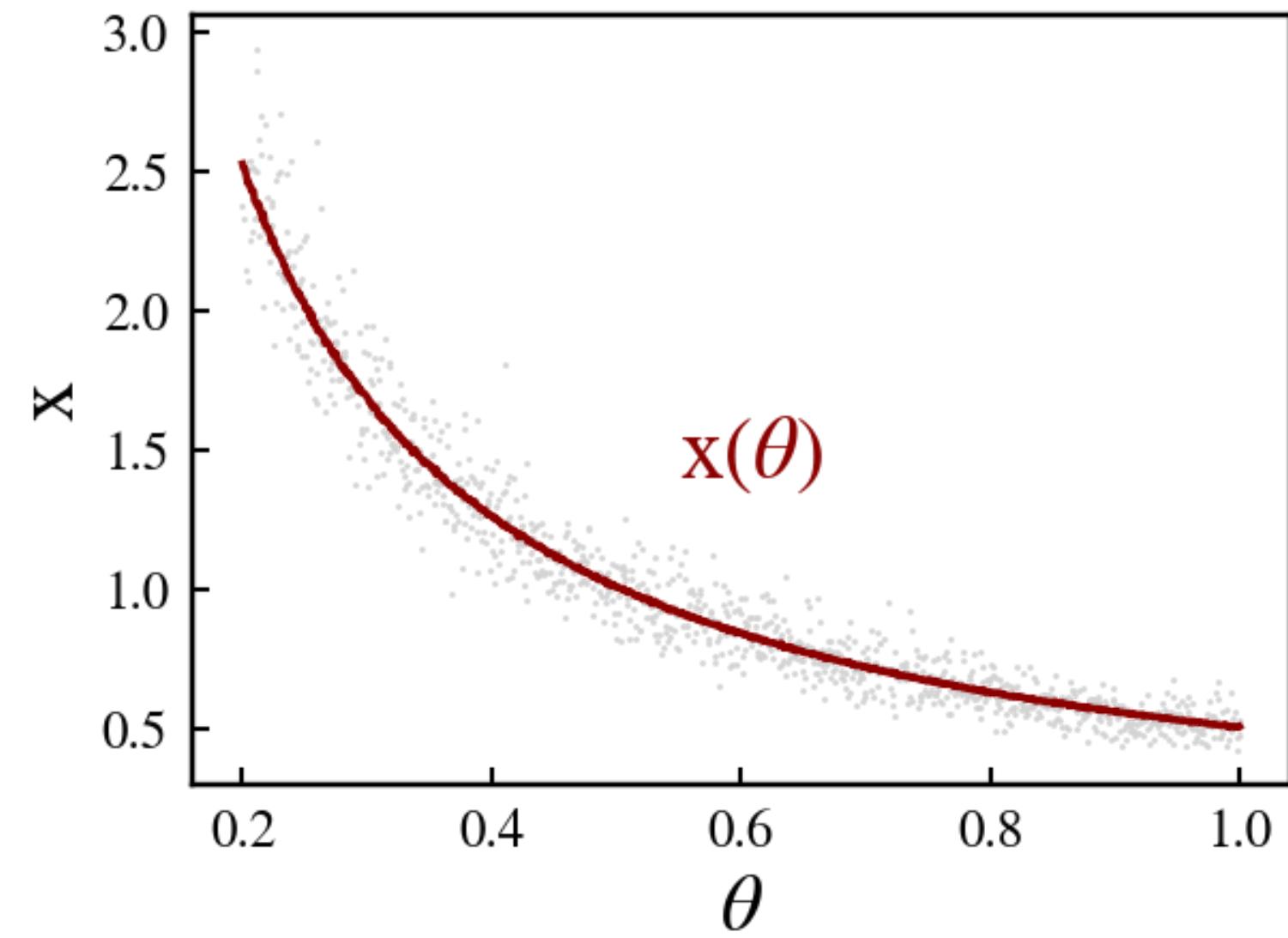


# Simulation-based inference

$$\{(\theta_n, \mathbf{x}_n)\}_{n=1}^{N_{\text{sim}}}$$



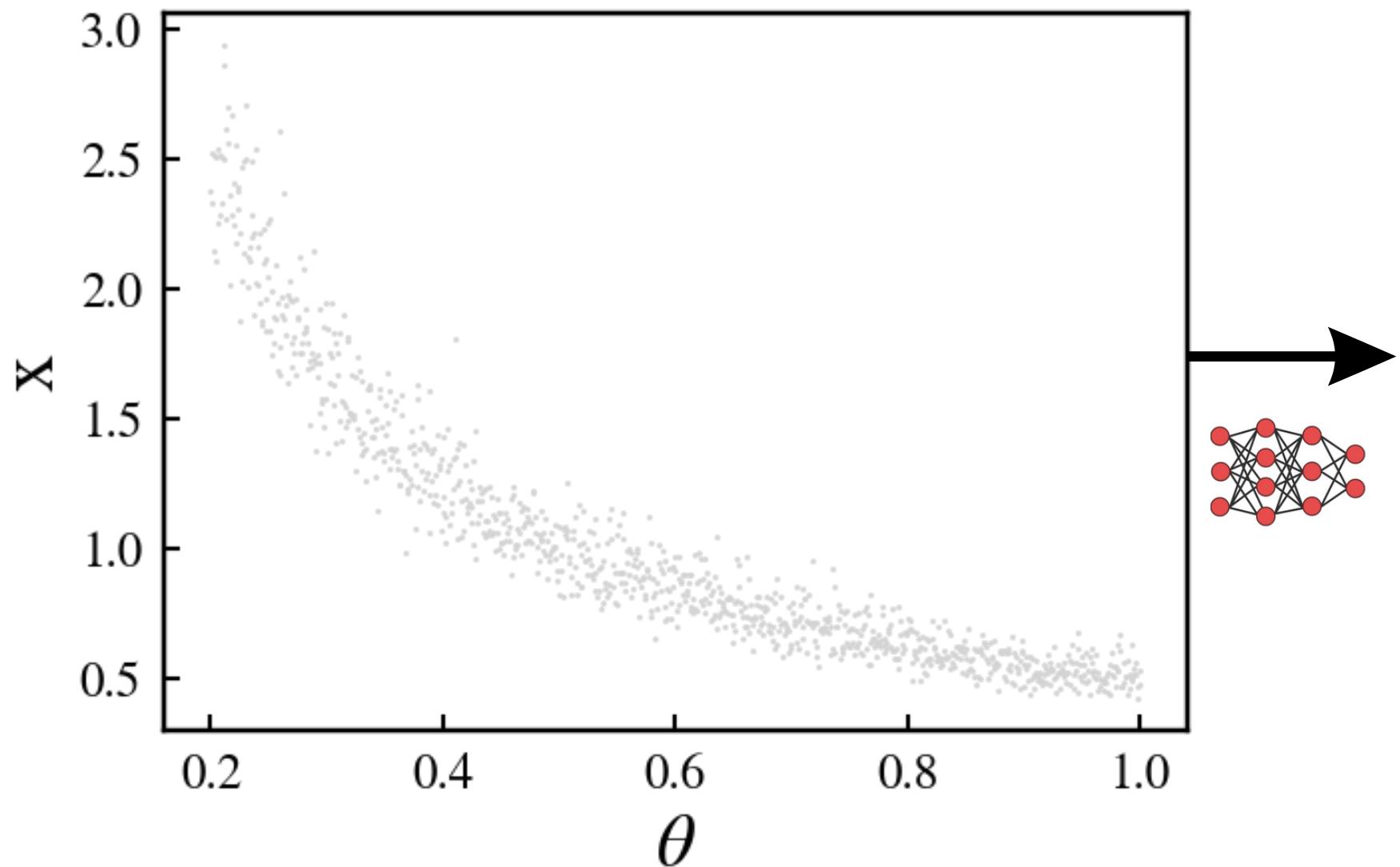
Summary statistics  
emulators



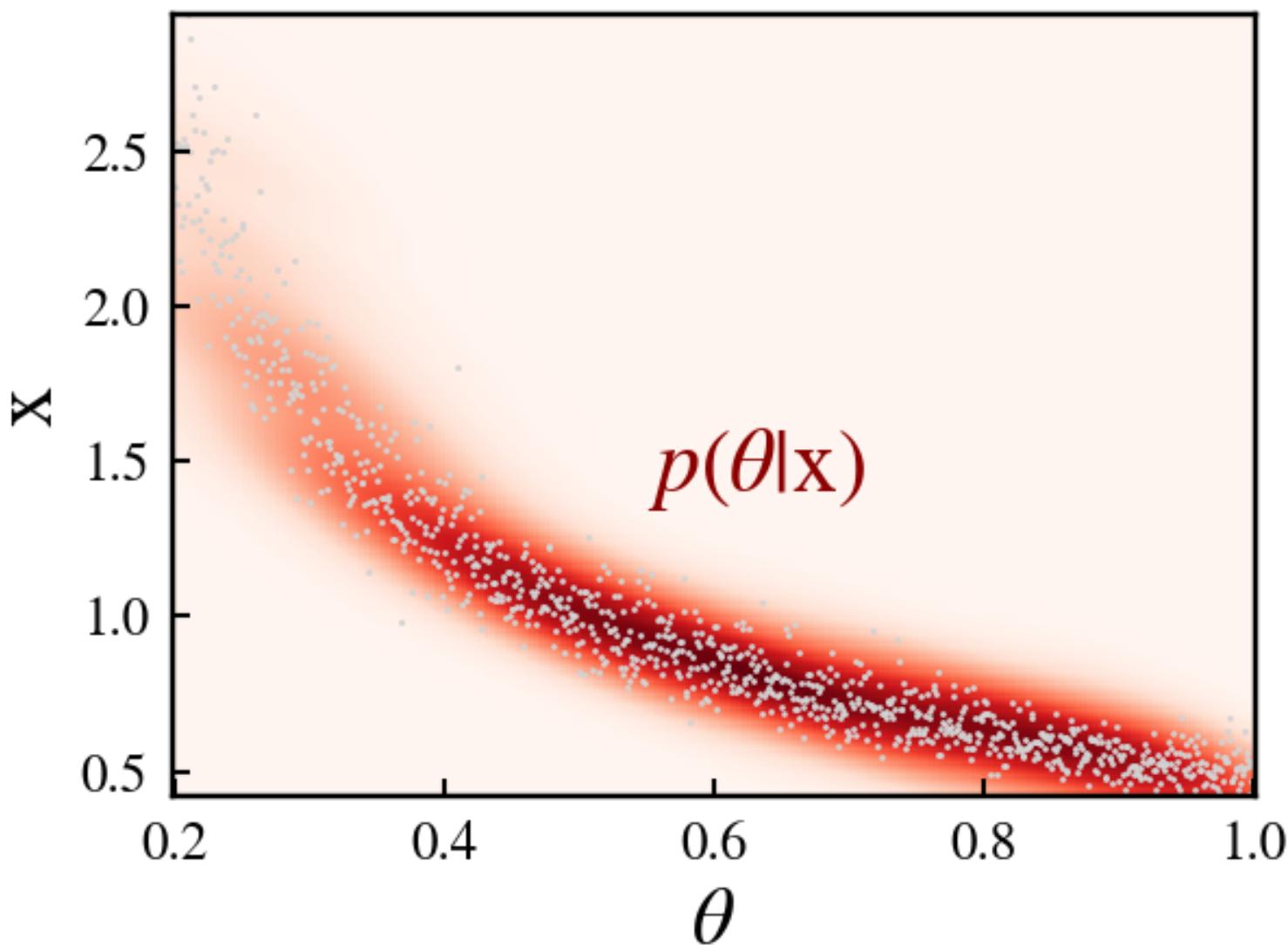
This is **not** what we are doing!

# Simulation-based inference

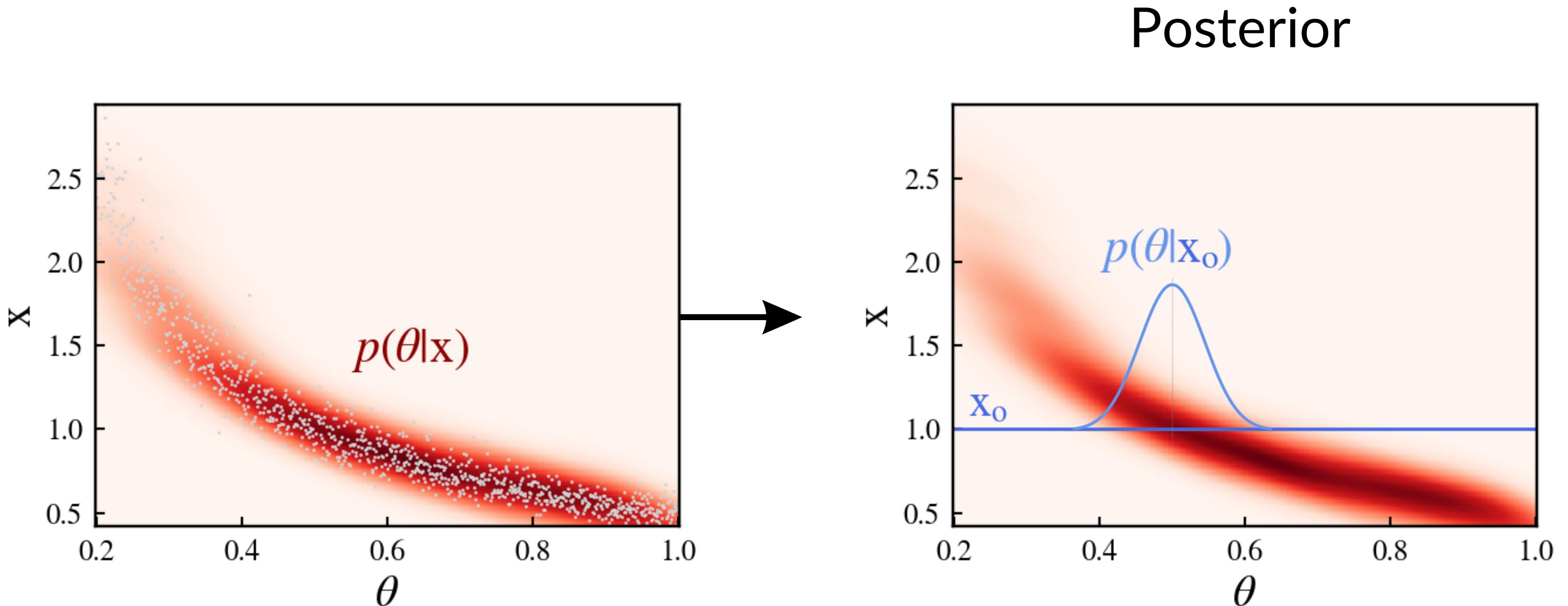
$$\{(\theta_n, \mathbf{x}_n)\}_{n=1}^{N_{\text{sim}}}$$



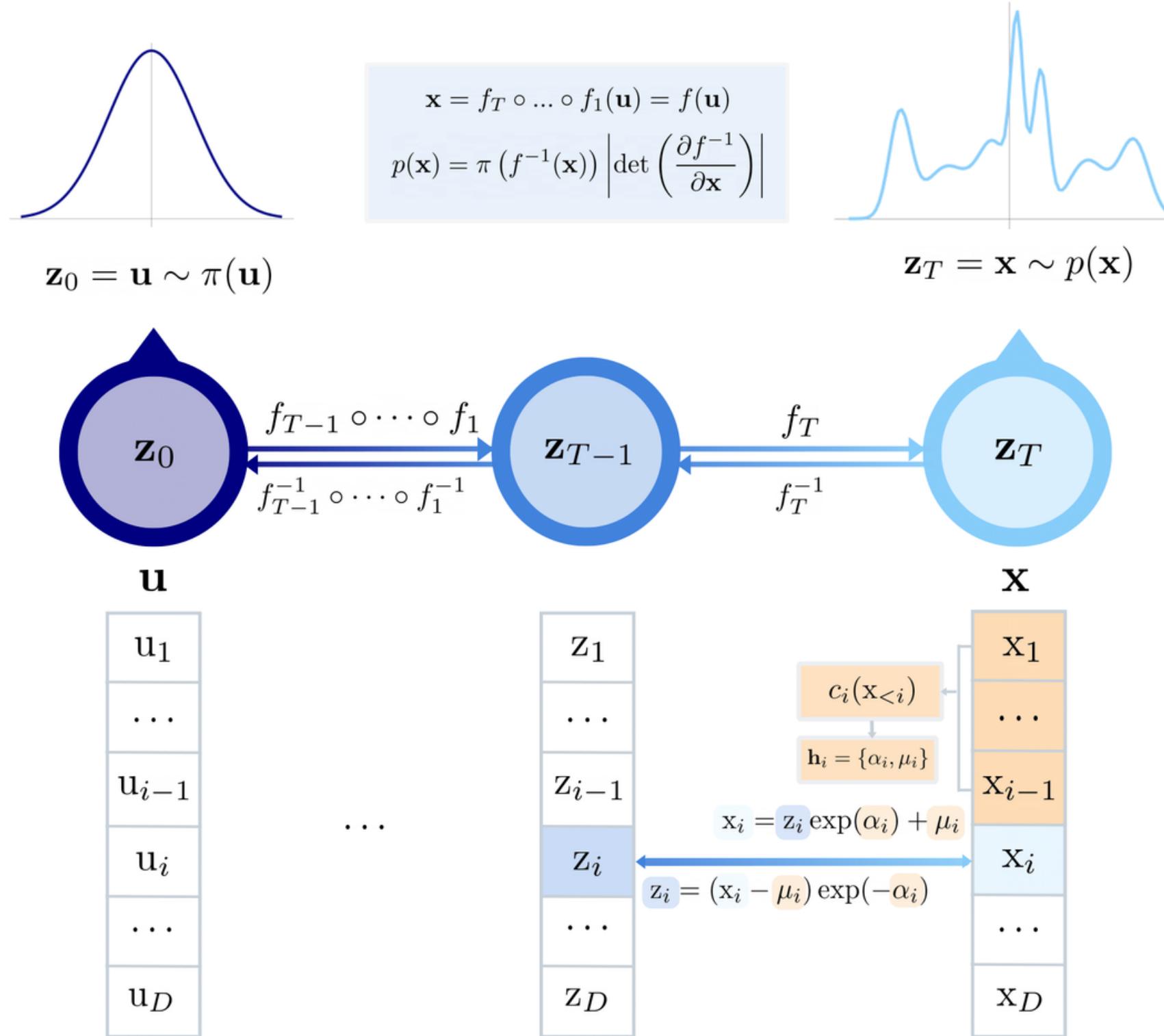
Neural Posterior  
Estimation (NPE)



# Simulation-based inference



# Normalizing Flows

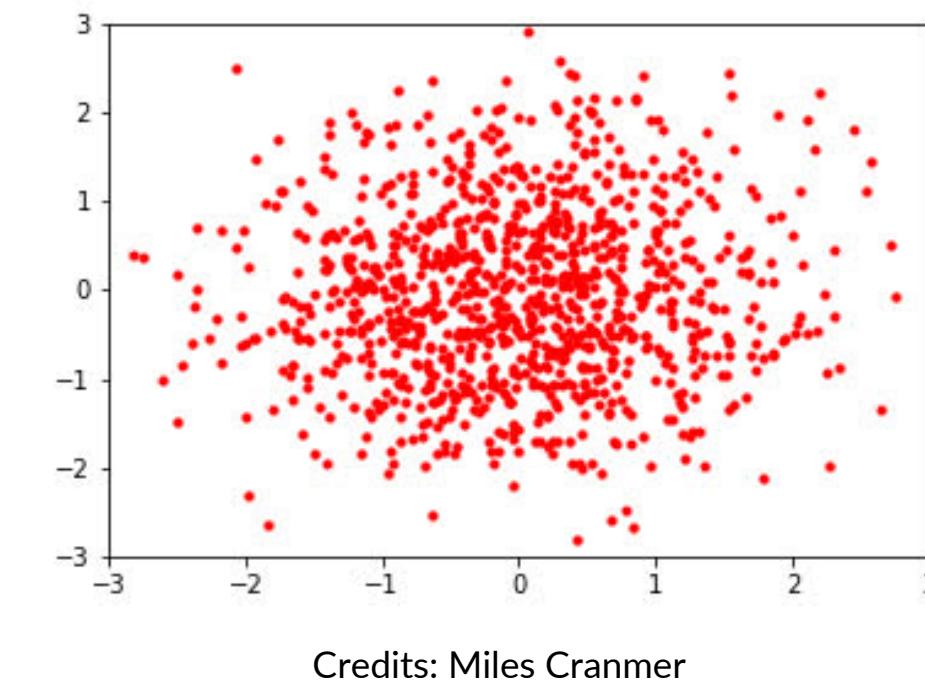


Tucci, Schmidt (2023)

## Neural Density Estimators (NDEs):

- Neural Posterior Estimation (NPE)
- Neural Likelihood Estimation (NLE)

*sbi: A toolkit for simulation-based inference*  
Tejero-Cantero et al. (2020)

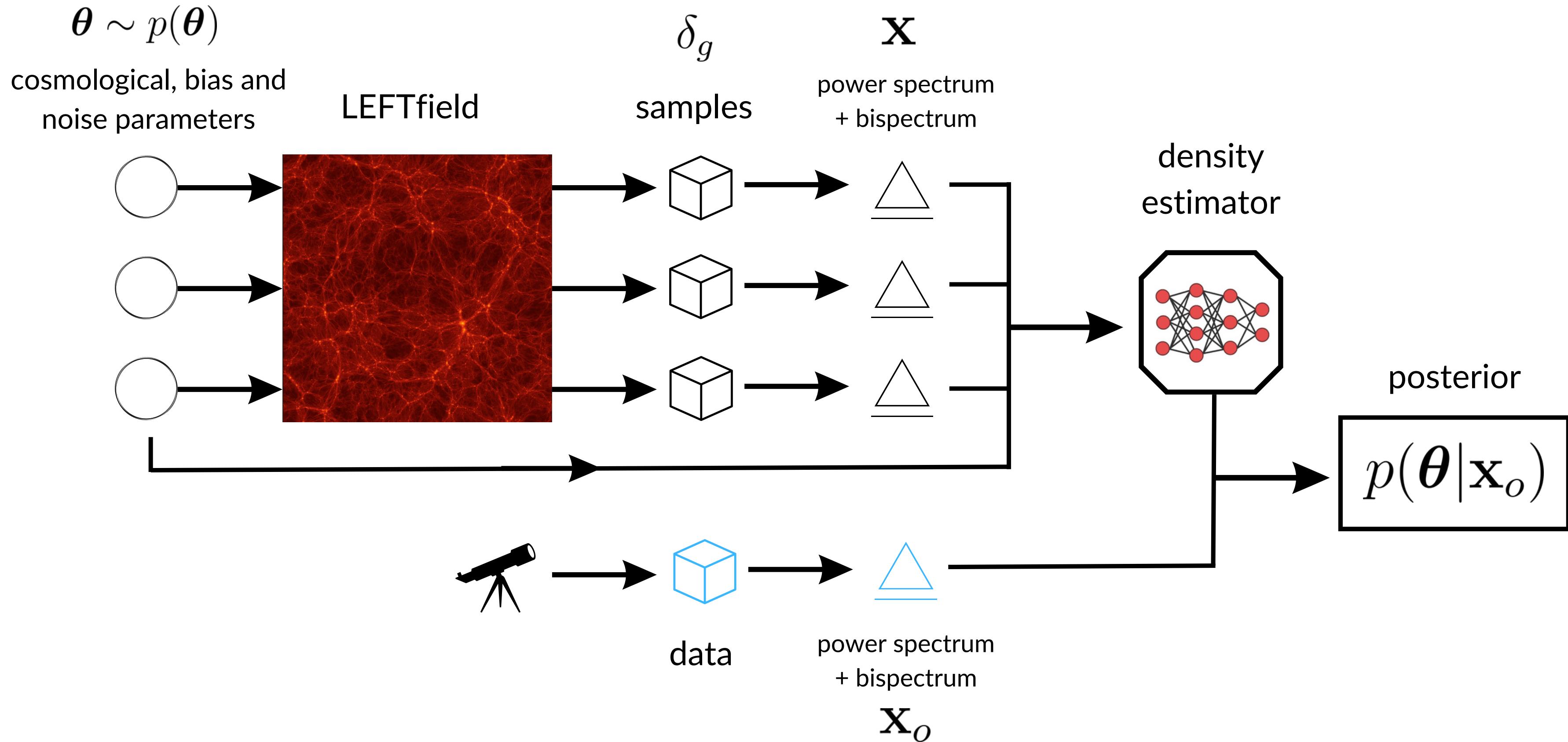


Learns an **invertible dynamical model**  
for samples of the distribution

# Simulation-based inference

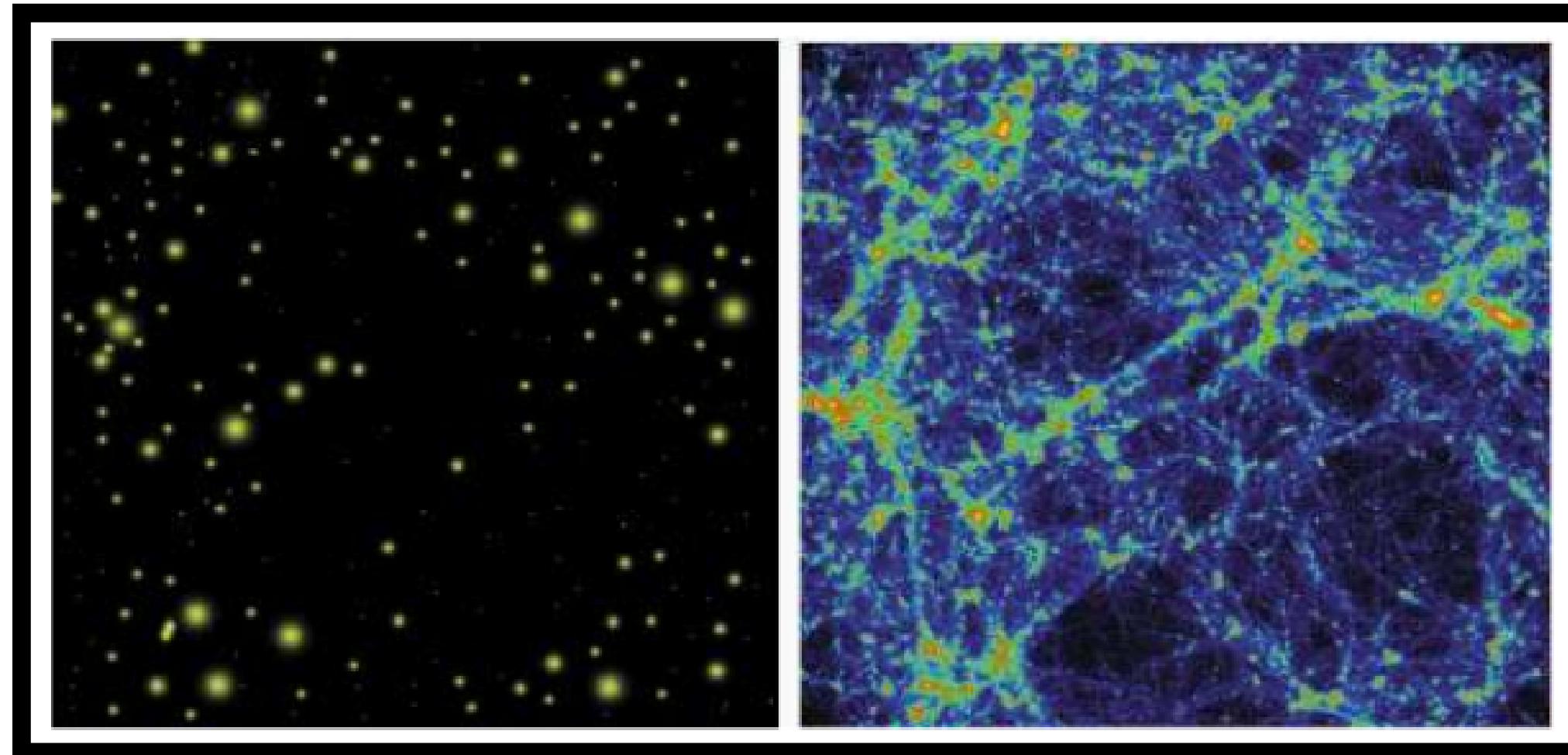
$$\theta \sim p(\theta)$$

# cosmological, bias and noise parameters



# The bias expansion

Cosmological  
tracers



Matter  
distribution

$$\delta_g(\mathbf{x}, \tau) = \sum_{\mathcal{O}} b_{\mathcal{O}}(\tau) \mathcal{O}(\mathbf{x}, \tau) + \varepsilon(\mathbf{x}, \tau) + \sum_{\mathcal{O}} \varepsilon_{\mathcal{O}}(\mathbf{x}, \tau) \mathcal{O}(\mathbf{x}, \tau)$$

For a review, see:  
Desjacques, Jeong  
& Schmidt (2016)

# Forward model



$$\alpha \equiv \sigma_8 / \sigma_8^{\text{fid}} \quad \hat{s}(\boldsymbol{x}) \sim \mathcal{N}(0, 1)$$

$$\delta_{\Lambda}^{(1)}(\boldsymbol{k}, z) = W_{\Lambda}(k) \sqrt{\alpha^2 P_L(k, z)} \hat{s}(\boldsymbol{k})$$

# Forward model

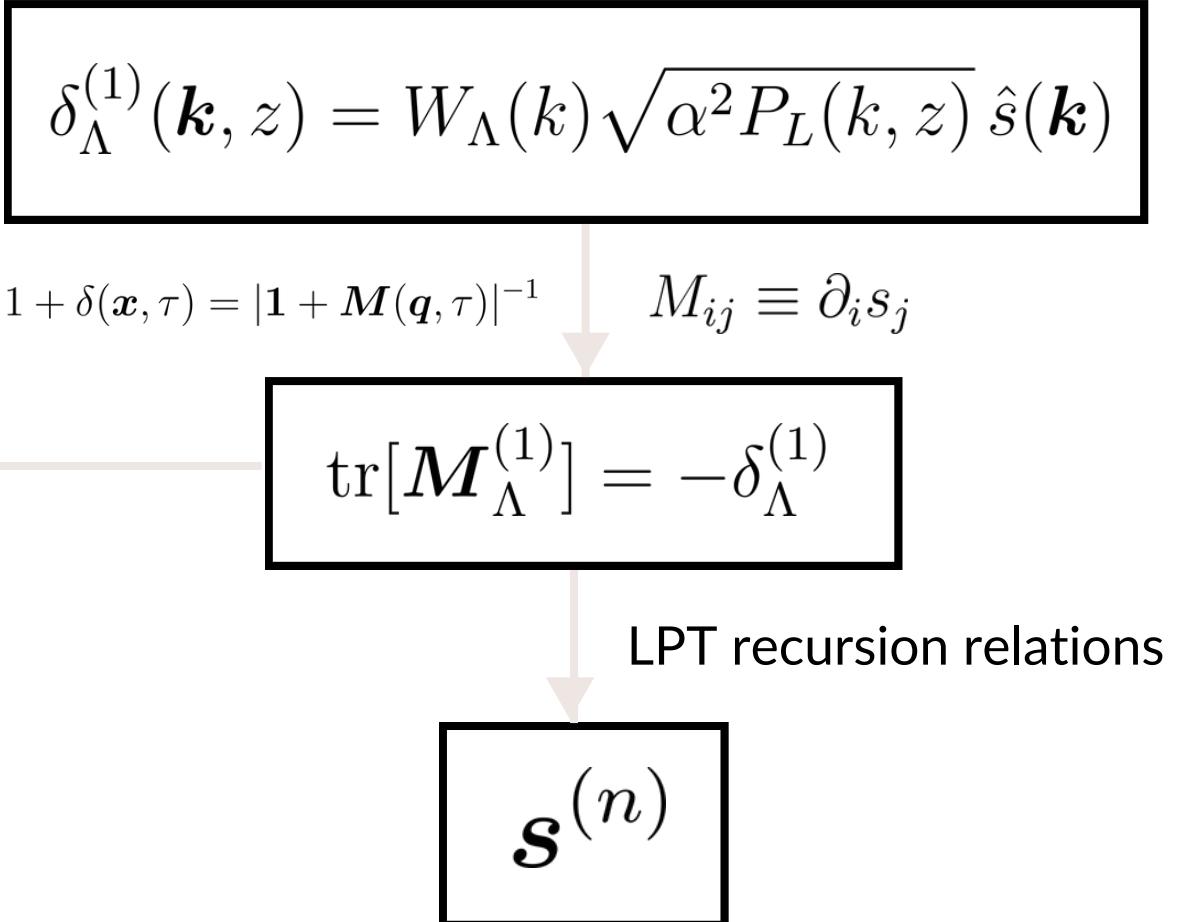


$$\alpha \equiv \sigma_8 / \sigma_8^{\text{fid}} \quad \hat{s}(\mathbf{x}) \sim \mathcal{N}(0, 1)$$

Lagrangian Bias Operators

1 <sup>st</sup>	$\text{tr}[\mathbf{M}_\Lambda^{(1)}]$
2 <sup>nd</sup>	$\text{tr}[\mathbf{M}_\Lambda^{(1)} \mathbf{M}_\Lambda^{(1)}], (\text{tr}[\mathbf{M}_\Lambda^{(1)}])^2$

$$\delta_{g,\det}^L(\mathbf{q}, \tau) = \sum_{\mathcal{O}^L} b_{\mathcal{O}^L}(\tau) \mathcal{O}^L(\mathbf{q}, \tau)$$



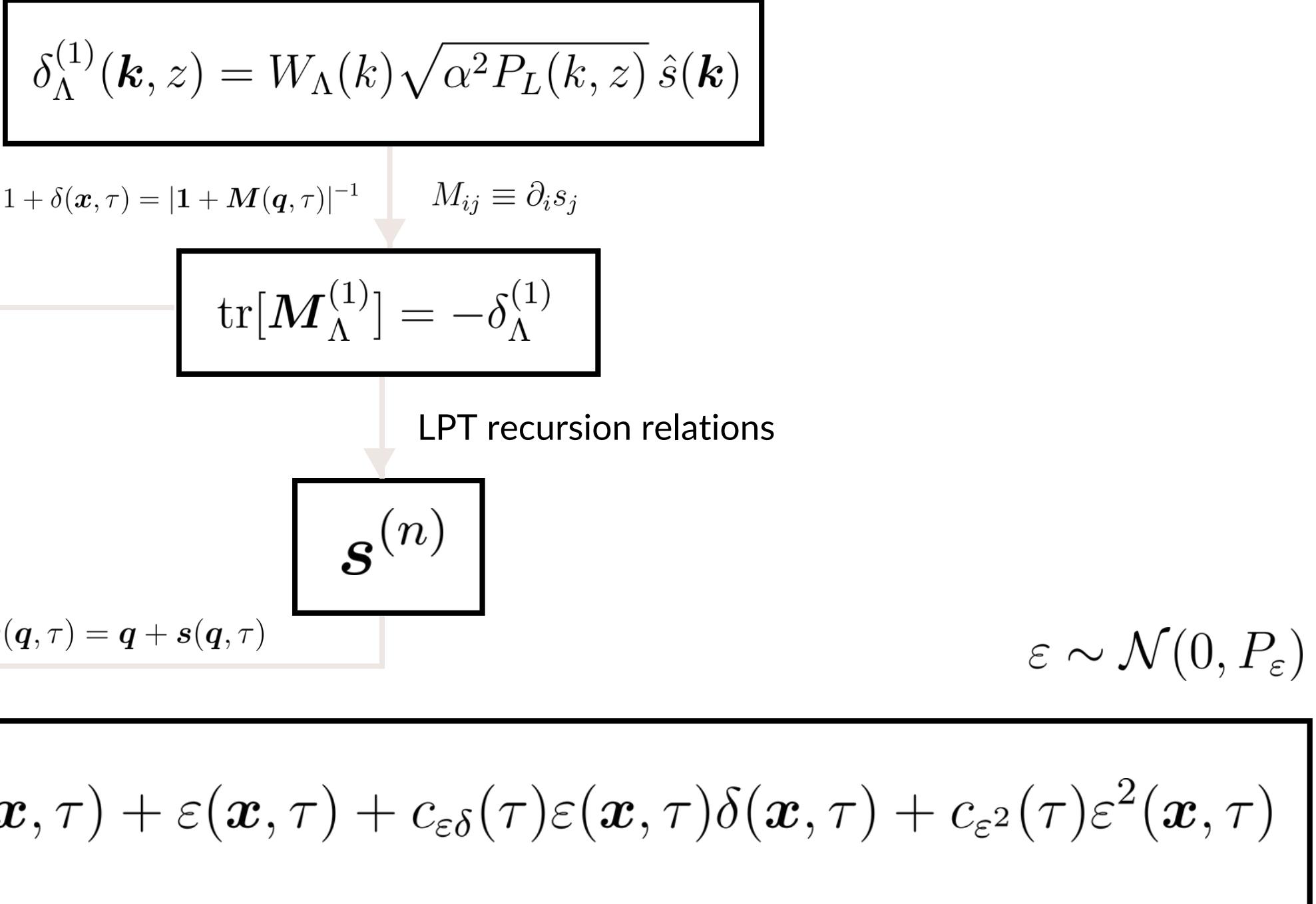
# Forward model



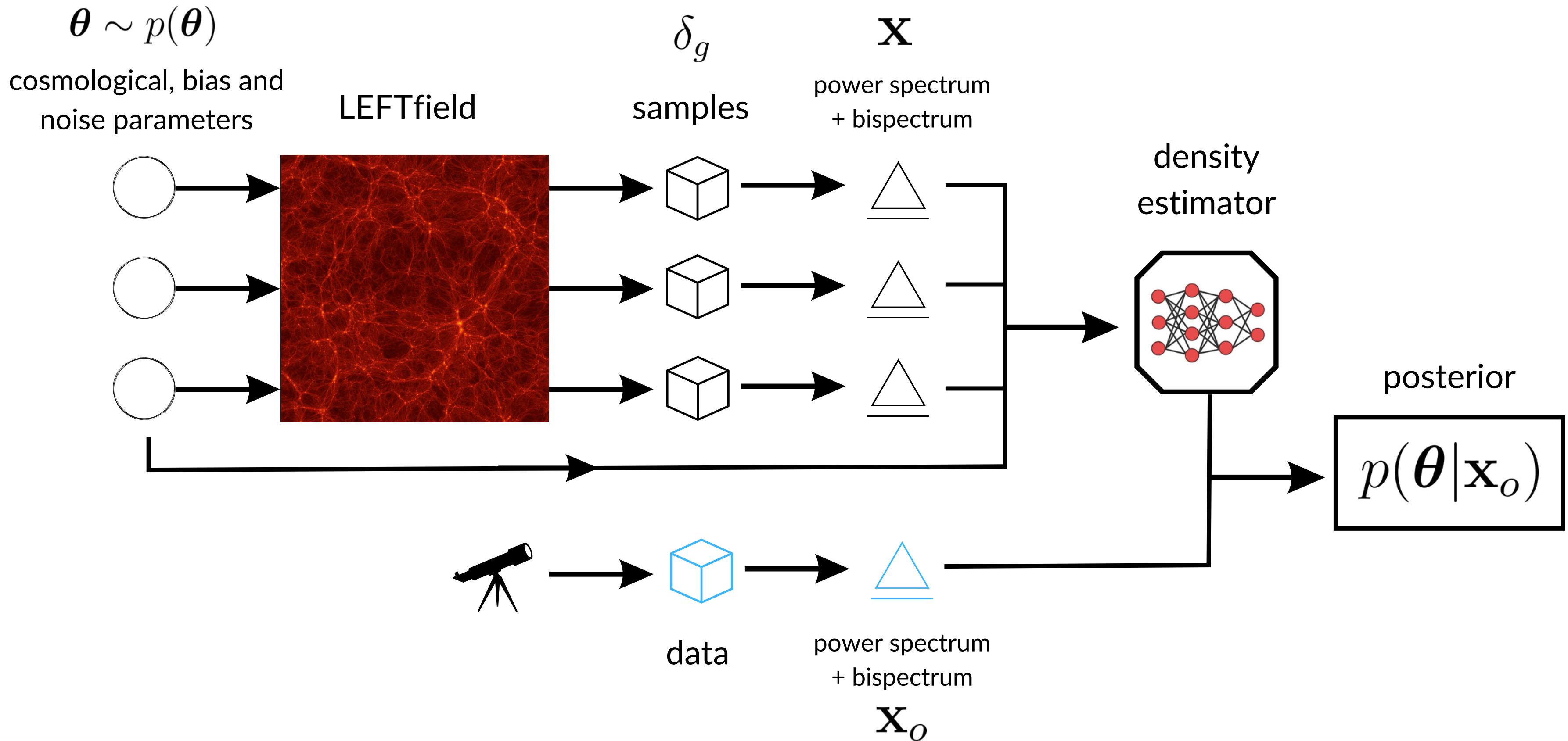
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## Lagrangian Bias Operators

1 <sup>st</sup>	$\text{tr}[\mathbf{M}_\Lambda^{(1)}]$
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# Simulation-based inference



# Our main goals

Considering an Euclid-like mock survey, we want to answer:

- Does the *non-Gaussianity* of the power-spectrum and bispectrum distributions at *low-k* affect cosmological inference?
- *How many simulations* are needed for posterior estimation?

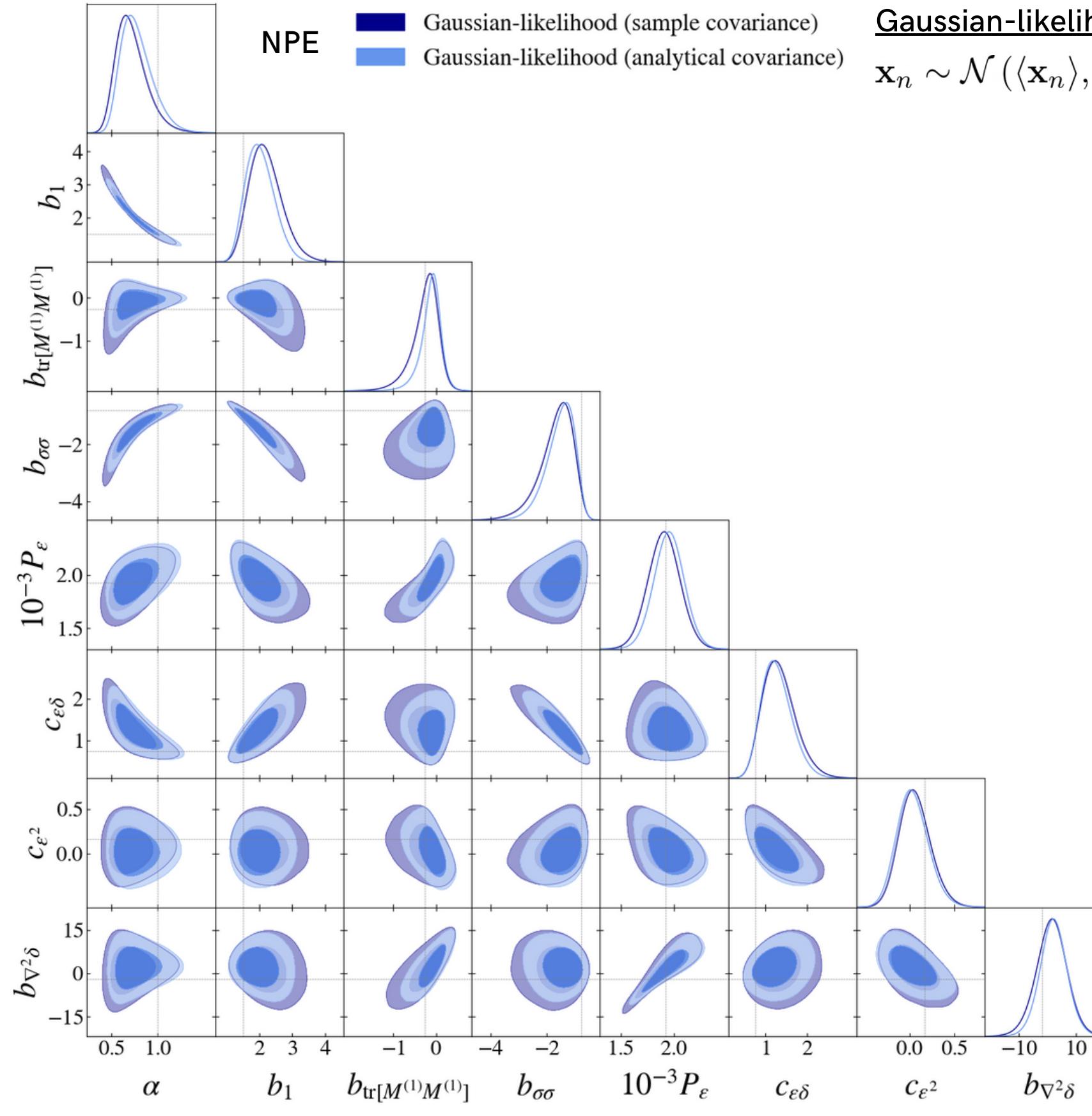
# Cosmological inference | Euclid configuration

$$N_{\text{sim}} = 10^5$$

$$k_{\max} = \Lambda = 0.1 h \text{Mpc}^{-1}$$

$$D = N_{\text{bin}} + N_{\text{tri}} = 33$$

$$\alpha \equiv \sigma_8 / \sigma_8^{\text{fid}}$$



Gaussian-likelihood

$$\mathbf{x}_n \sim \mathcal{N}(\langle \mathbf{x}_n \rangle, \text{Cov}[\mathbf{x}_o])$$

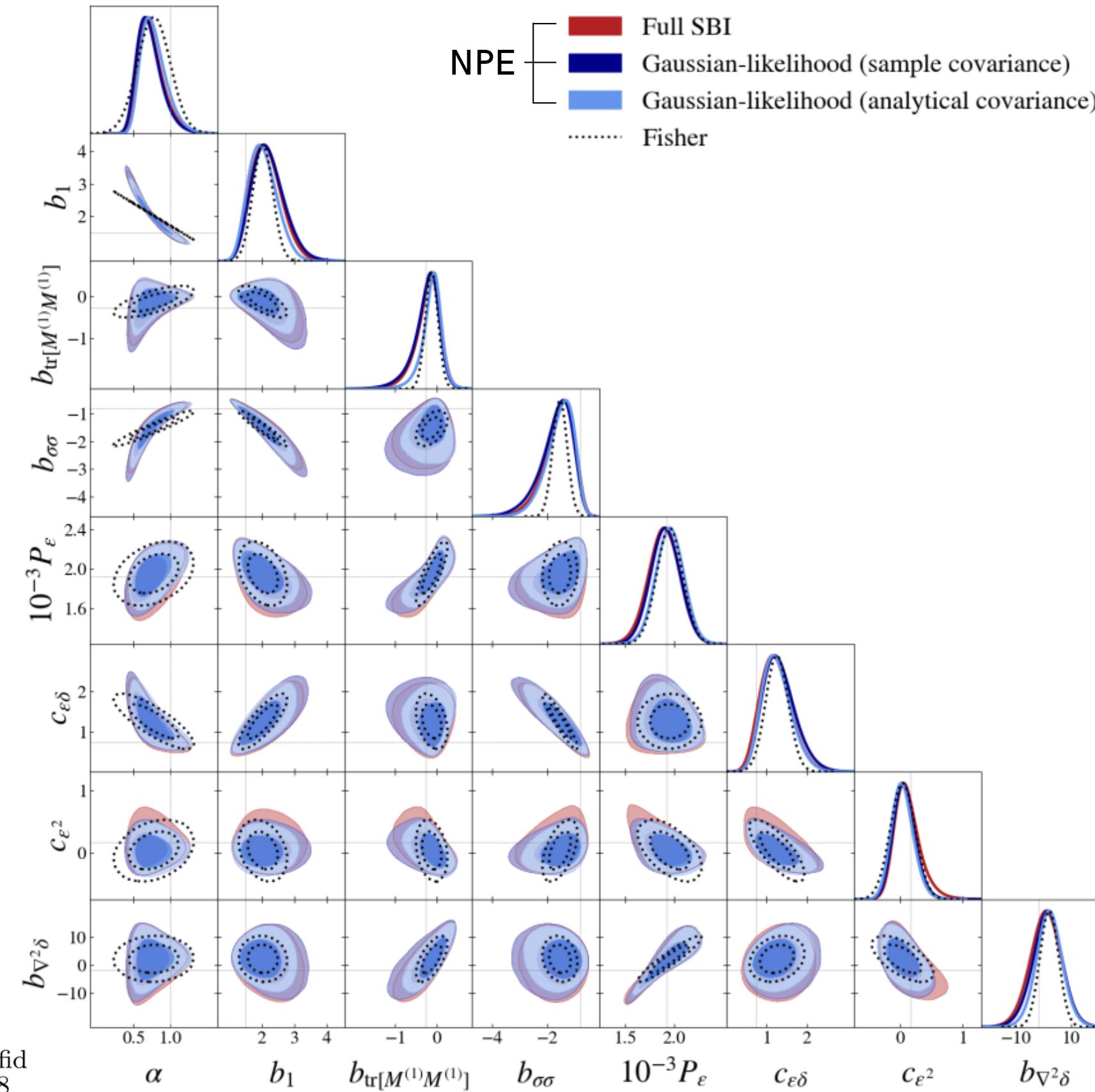
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NPE

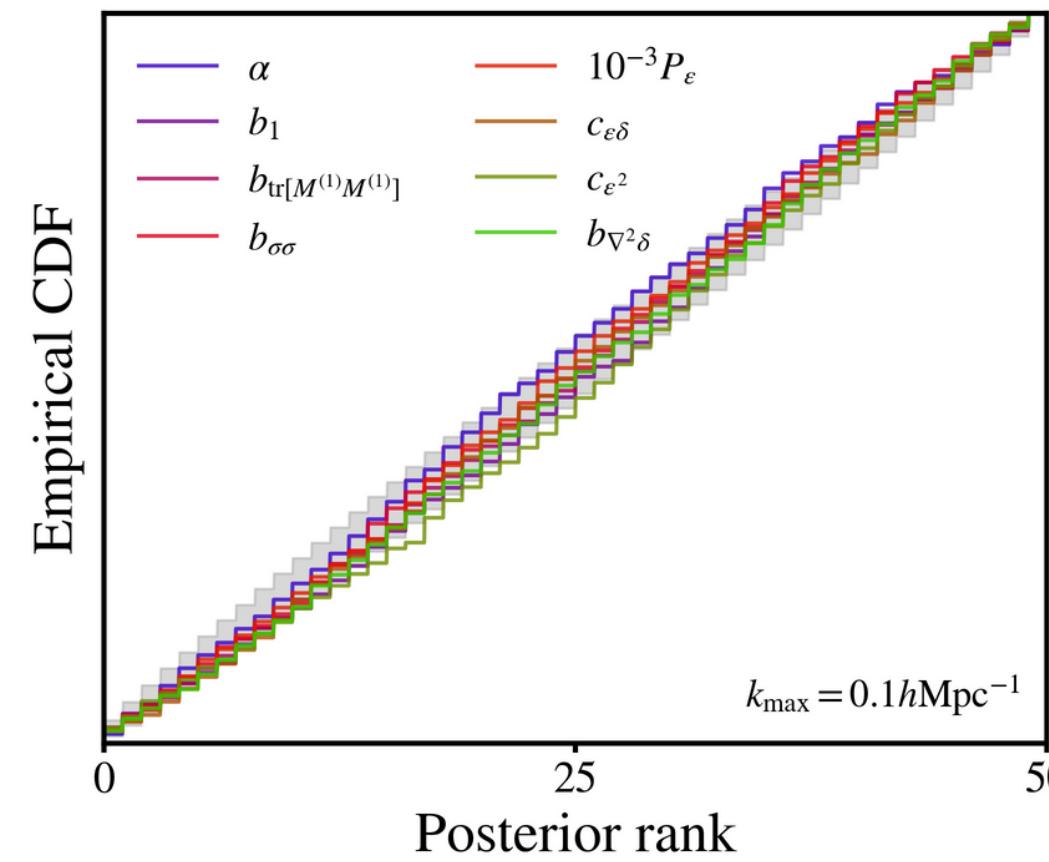
- Full SBI
- Gaussian-likelihood (sample covariance)
- Gaussian-likelihood (analytical covariance)
- Fisher

Gaussian-likelihood

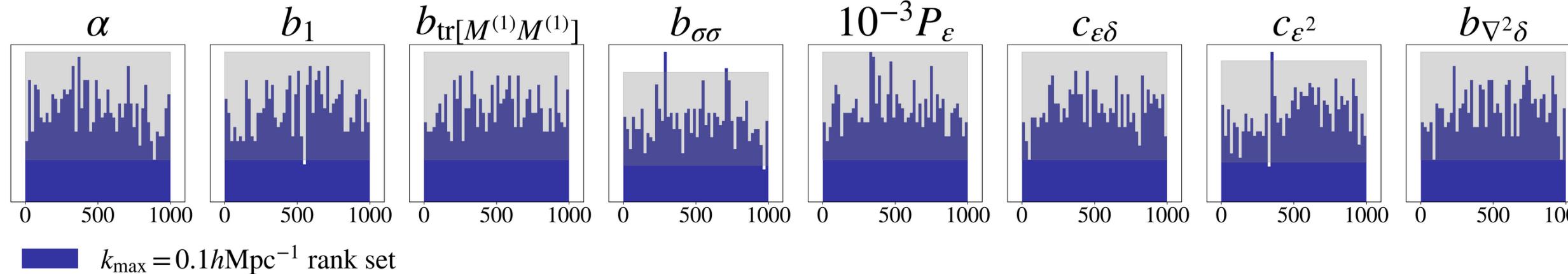
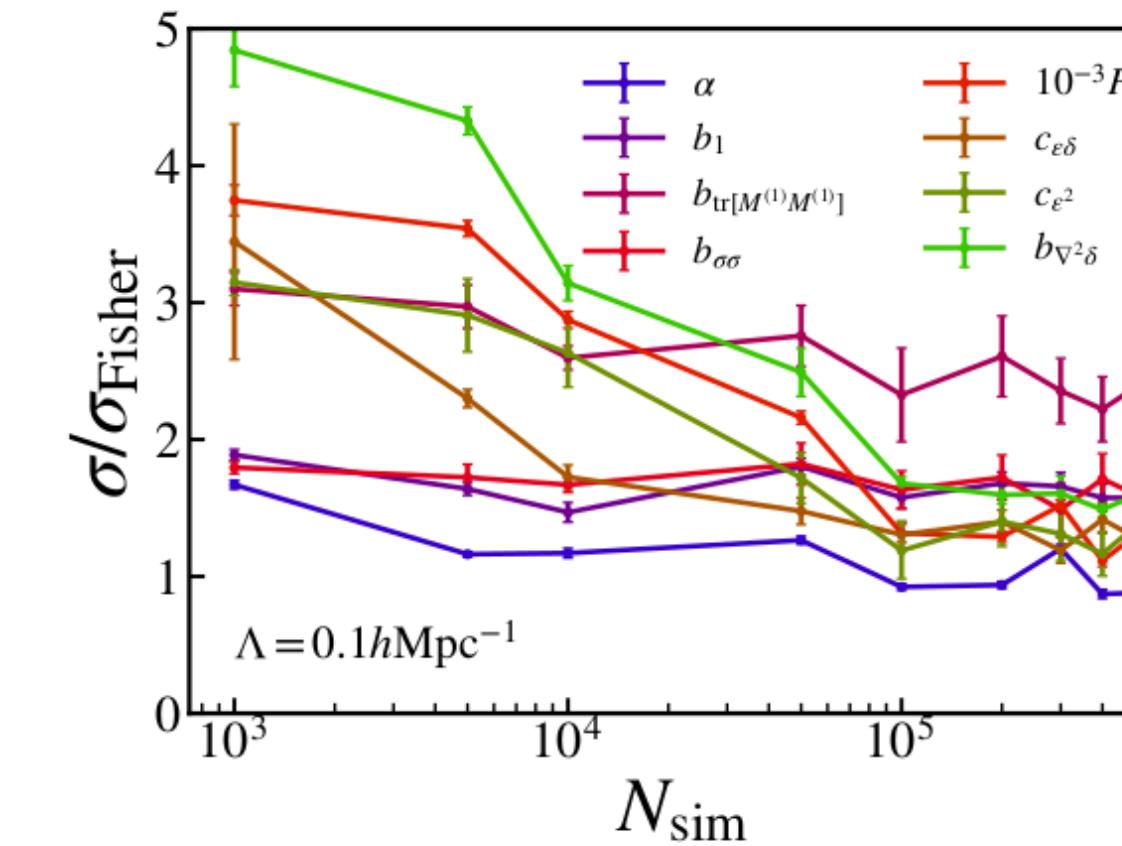
$$\mathbf{x}_n \sim \mathcal{N}(\langle \mathbf{x}_n \rangle, \text{Cov}[\mathbf{x}_o])$$

# Posterior diagnostics

Simulation-based calibration



Convergence

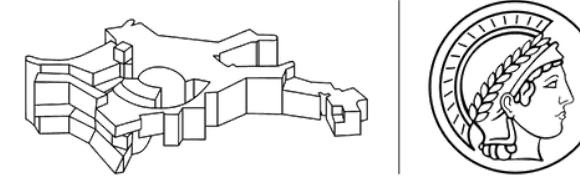


# Conclusion & Next Steps

- Simulation-based inference has proven to be a powerful tool for galaxy clustering analysis and offers several advantages over the likelihood-based approach;
- In the future, we plan to sample more cosmological parameters, add more summary statistics and improve observational aspects of the forward model (masks, systematic effects, etc);
- Comparison of field-level inference with HMC and SBI with summary statistics (P+B).

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**MAX-PLANCK-INSTITUT**  
FÜR ASTROPHYSIK



A large, semi-transparent white text "Thank you!" is centered over a background image of a cosmic web, showing filaments of galaxies and luminous points of stars in shades of purple, blue, and yellow.

Thank you!

Beatrix Tucci

[tucci@mpa-garching.mpg.de](mailto:tucci@mpa-garching.mpg.de)

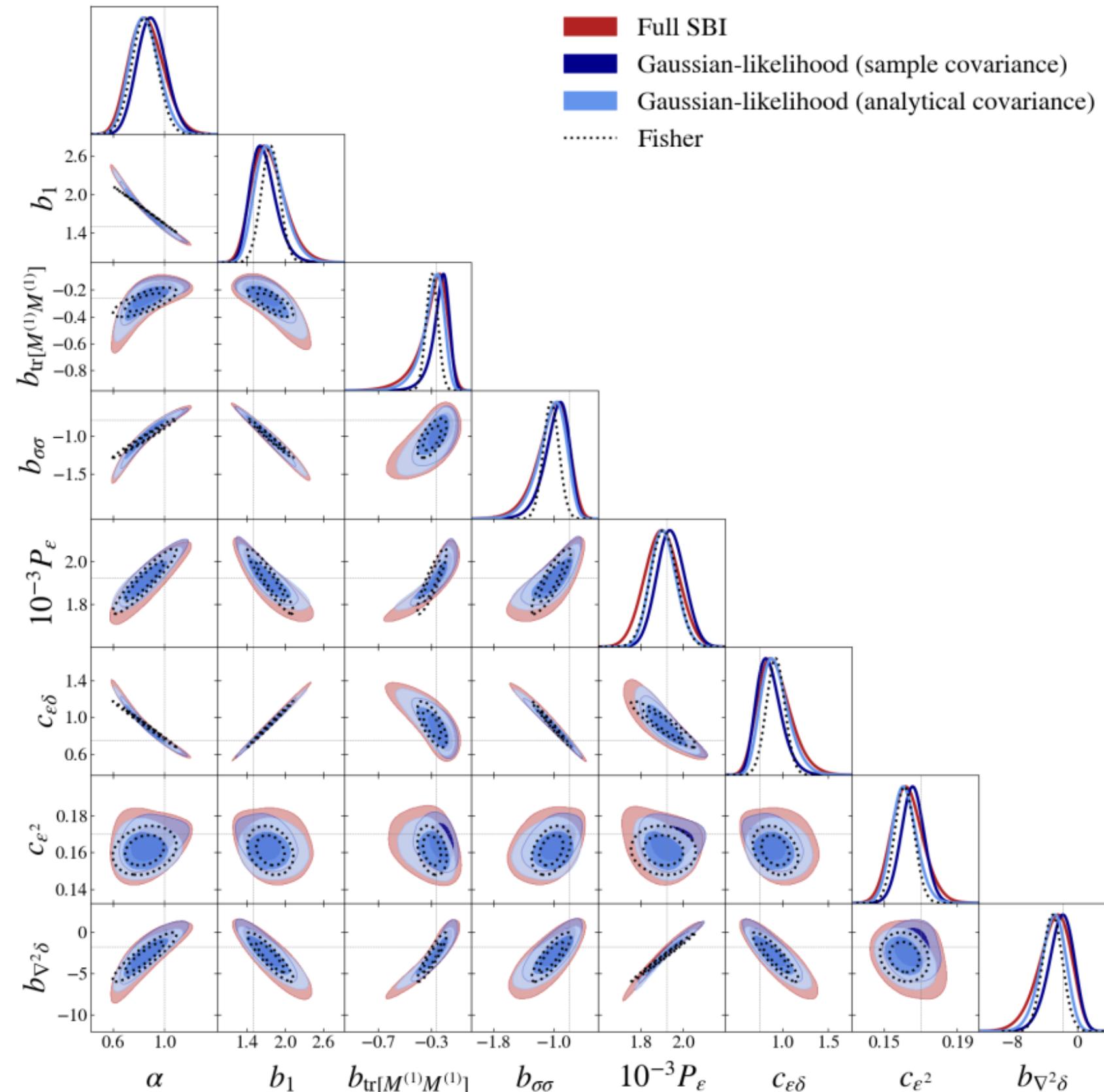
# Cosmological inference | Euclid configuration

Tucci, Schmidt (in prep.)

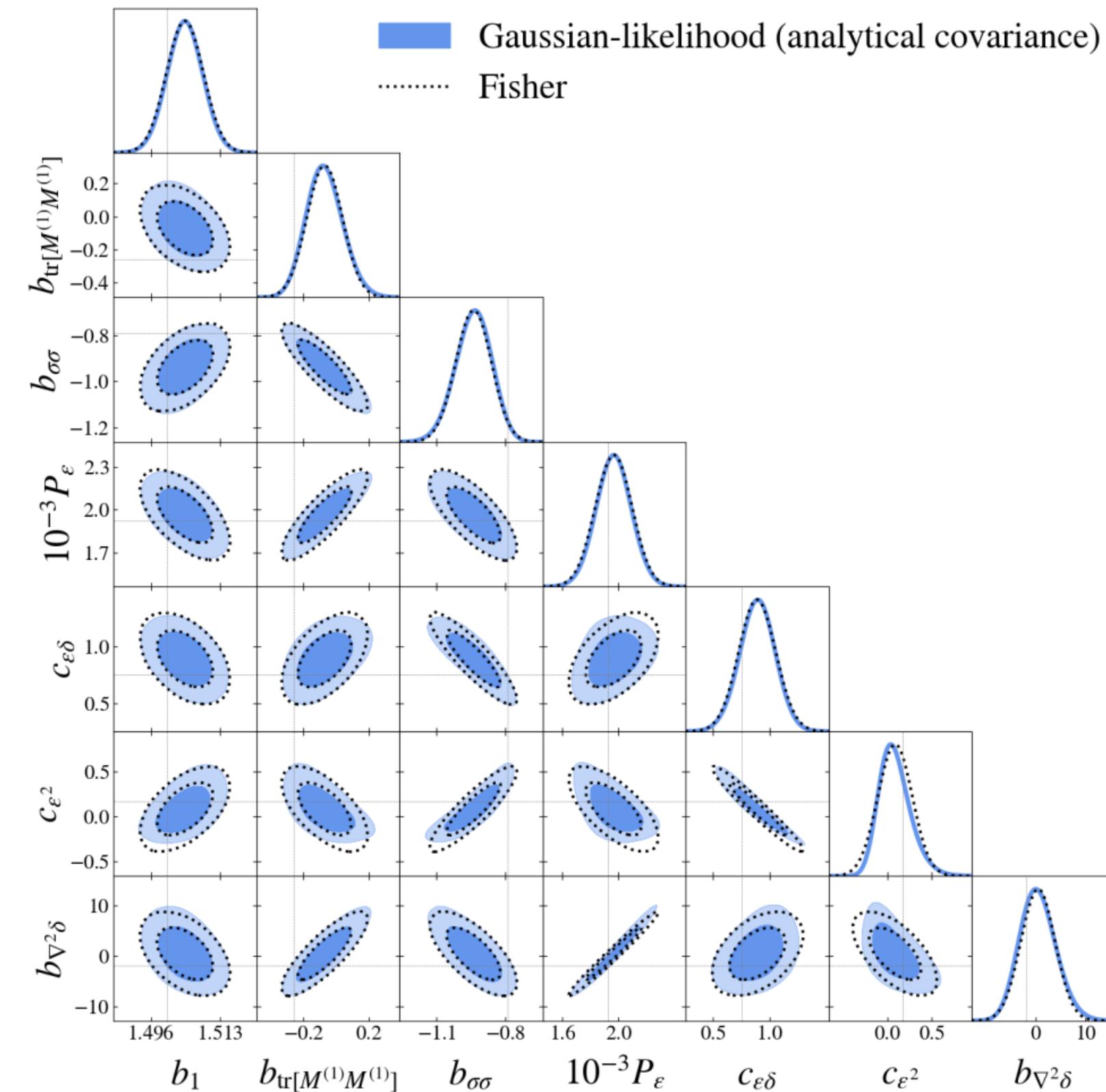
$$N_{\text{sim}} = 10^5$$

$$k_{\text{max}} = \Lambda = 0.2 h \text{Mpc}^{-1}$$

$$D = 49$$



# Euclid | Gaussian-likelihood

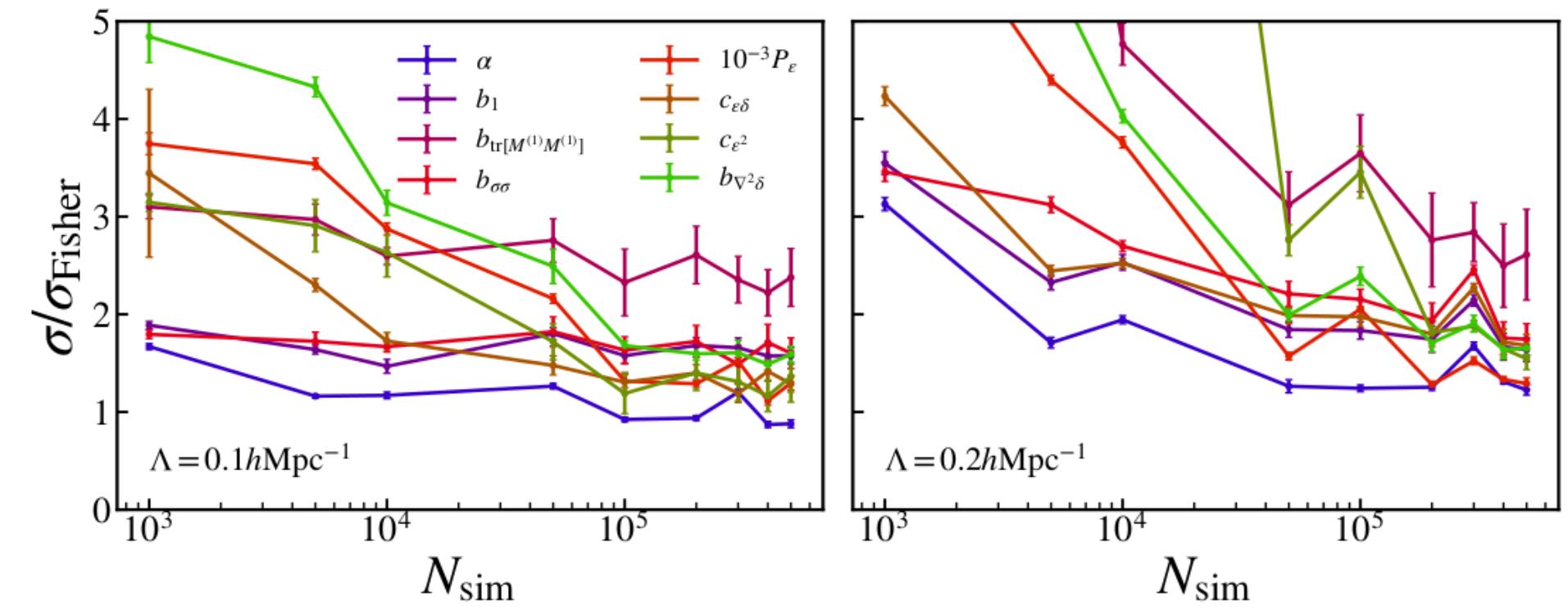
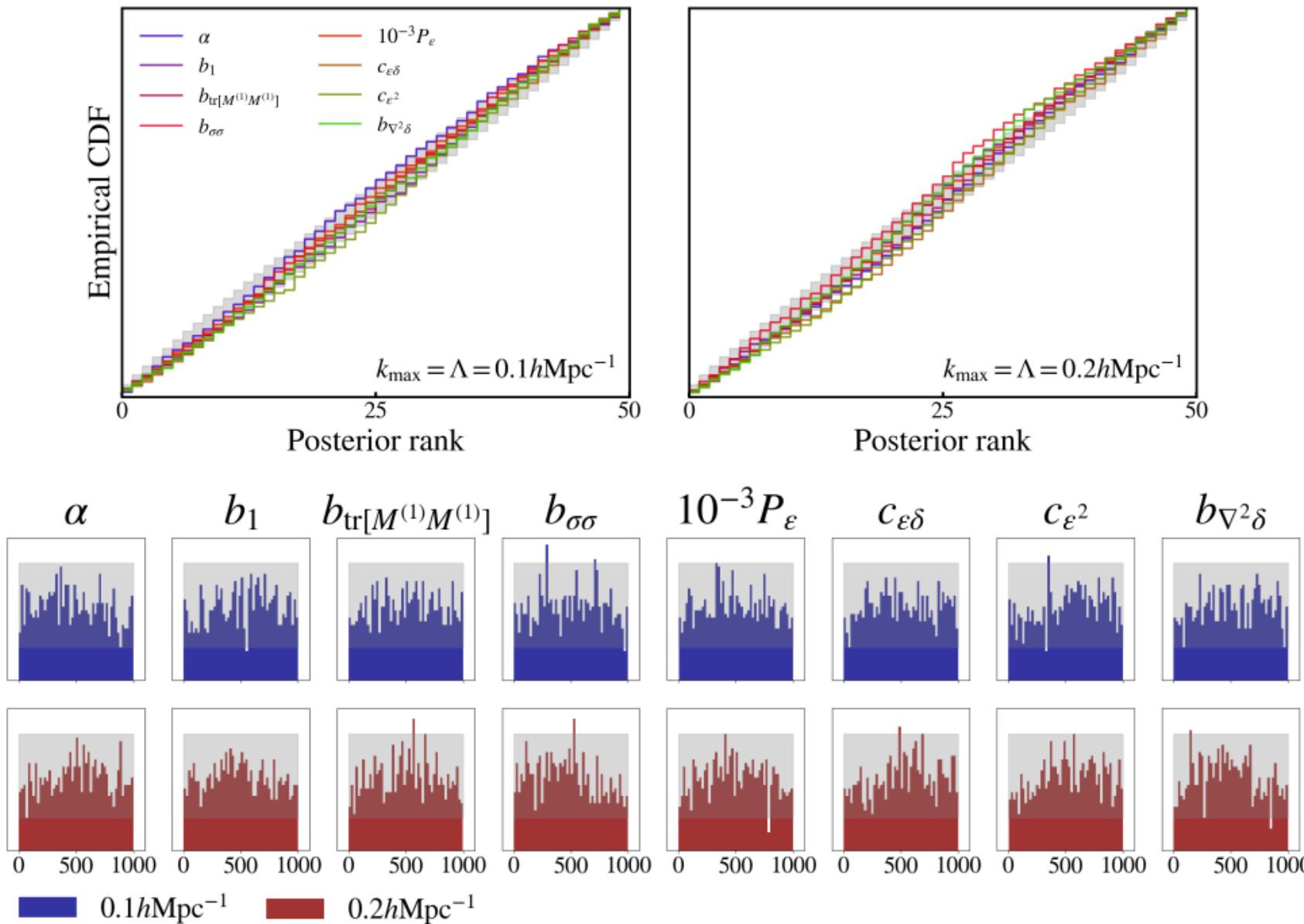


$$\mathbf{x}_n \sim \mathcal{N}(\langle \mathbf{x}_n \rangle, \text{Cov}[\mathbf{x}_o])$$

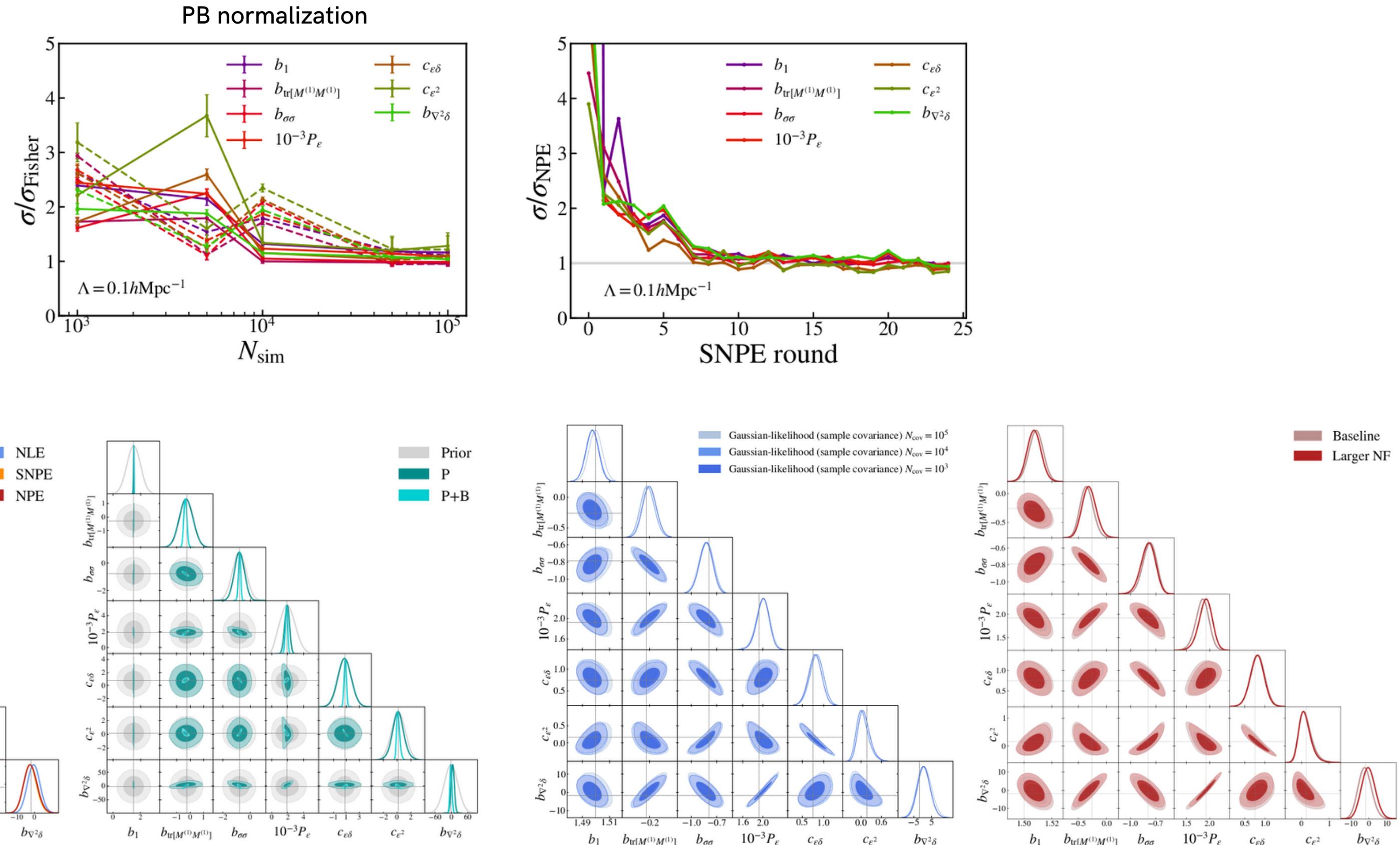
$$N_{\text{sim}} = 10^5$$

$$k_{\text{max}} = \Lambda = 0.1 h \text{Mpc}^{-1}$$

# Posterior diagnostics



# Inference tests

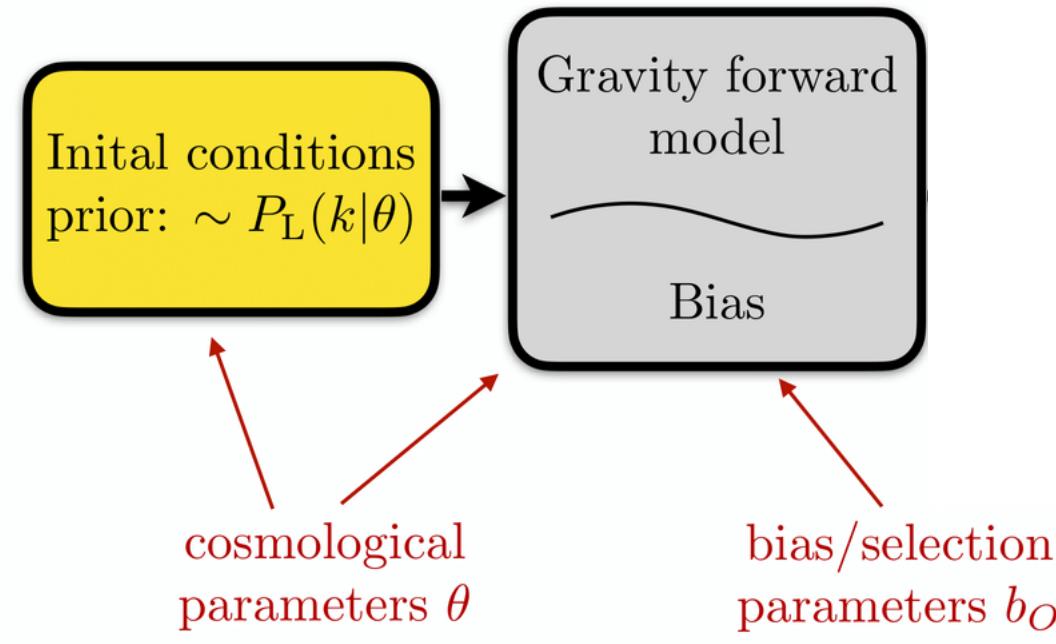


# LEFTfield | forward model



EFTofLSS based approach

$$\varepsilon \sim \mathcal{N}(0, \sigma_\varepsilon)$$



Perturbation Theory

$$\langle \delta_g(k_1) \delta_g(k_2) \delta_g(k_3) \rangle_{\text{stoch}}^{\prime \text{LO}} = B_\varepsilon + 2b_1 P_{\varepsilon \varepsilon \delta} (P_m(k_1) + 2 \text{ perm.})$$

Forward Model

$$\langle \delta_g(k_1) \delta_g(k_2) \delta_g(k_3) \rangle_{\text{stoch}}^{\prime \text{LO}} = 6c_\varepsilon^{\text{NG}} P_\varepsilon^2 + 2b_1 P_\varepsilon \sigma_{\varepsilon \delta} (P_m(k_1) + 2 \text{ perm.})$$

An  $n$ -th order Lagrangian Forward Model for Large-Scale Structure  
Fabian Schmidt (2021)

$$\delta_g(\mathbf{x}, \tau) = \delta_{g,\text{det}}(\mathbf{x}, \tau) + \varepsilon(\mathbf{x}, \tau) + \sigma_{\varepsilon \delta}(\tau) \varepsilon(\mathbf{x}, \tau) \delta(\mathbf{x}, \tau) + c_\varepsilon^{\text{NG}}(\tau) \varepsilon^2(\mathbf{x}, \tau)$$