

Emergent 5-branes in the BMN Matrix Model

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Matrix Quantum Mechanics for M-theory Revisited
@CERN

Introduction

Matrix Models can be
non-perturbative formulation of string/M theory

c=1 matrix model, BFSS model, IKKT model,...



BMN matrix model (a.k.a. plane-wave matrix model)

... the **mass**-deformation of BFSS
w/ **maximal supersymmetry**

[Berenstein, Maldacena, Nastase '02]

Non-perturbative physics

D-/M-branes — how do they emerge?

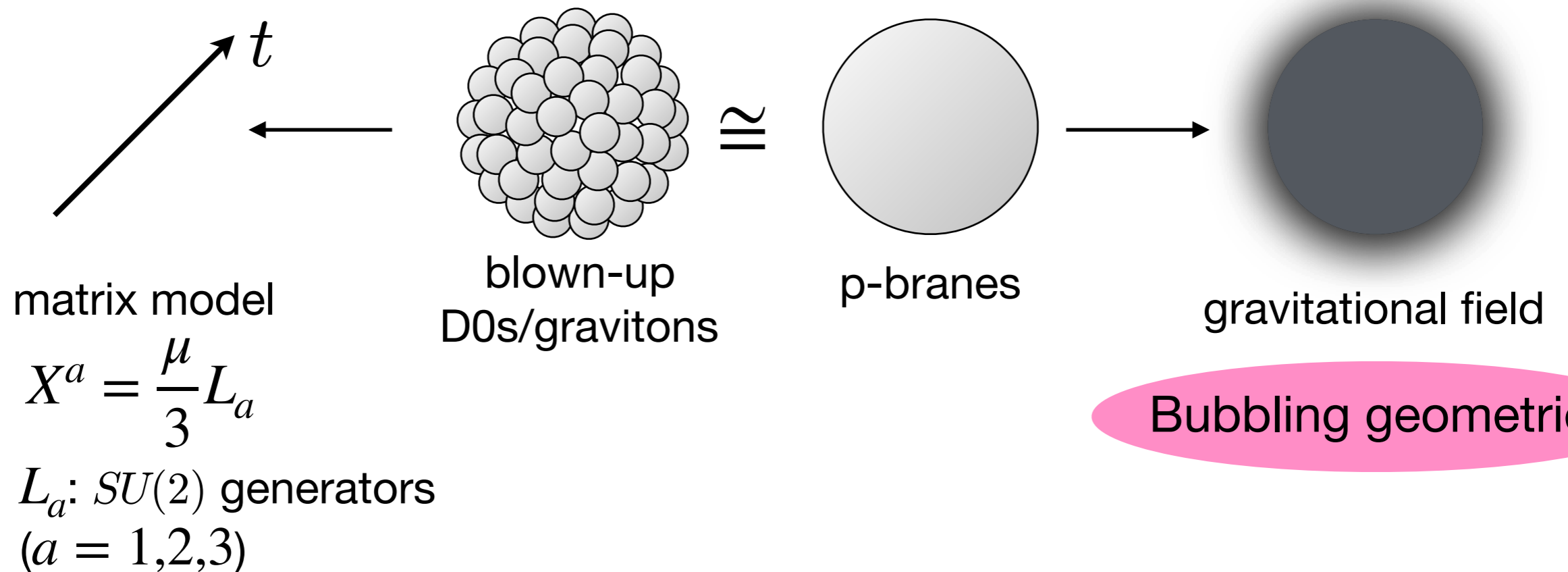
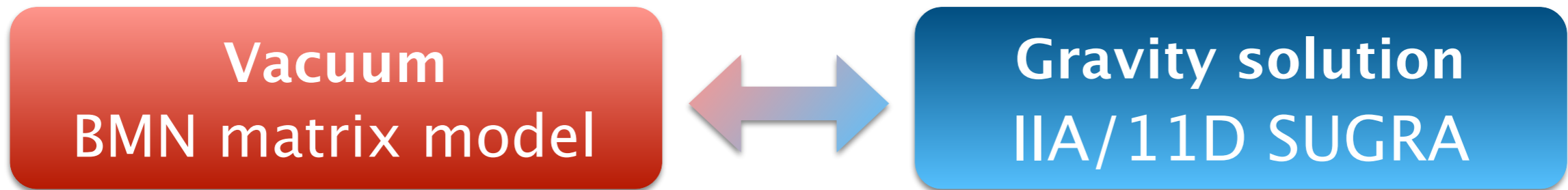
Target space metric — how is it determined?

... **Emergent geometry**

Introduction

Gauge/gravity duality

[Lin, Lunin, Maldacena '04; Lin, Maldacena '05]



Bubbling geometries

Many degenerate vacua

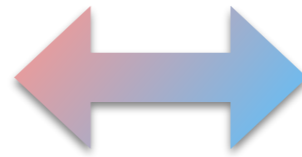
Each matrix-model vacuum should describe the corresponding brane config. and its gravitational field.

Introduction

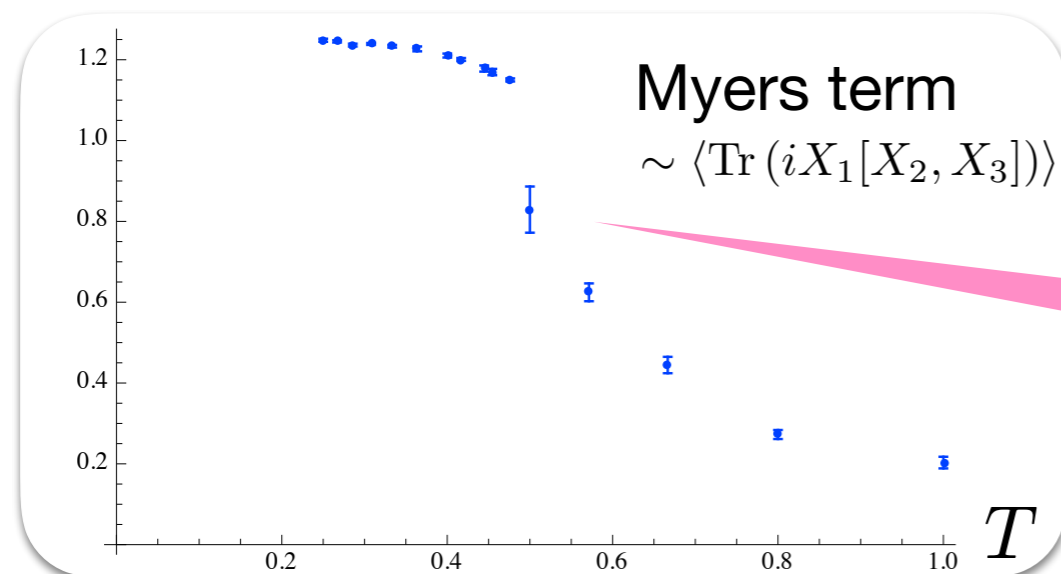
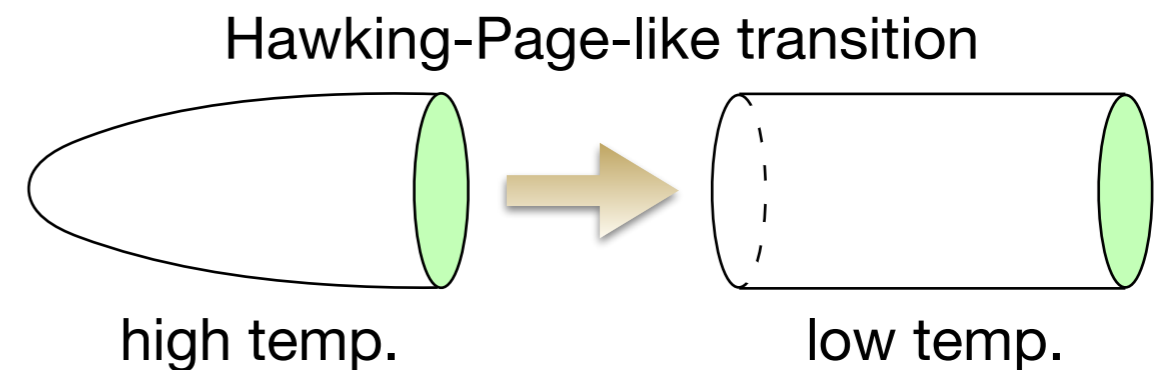
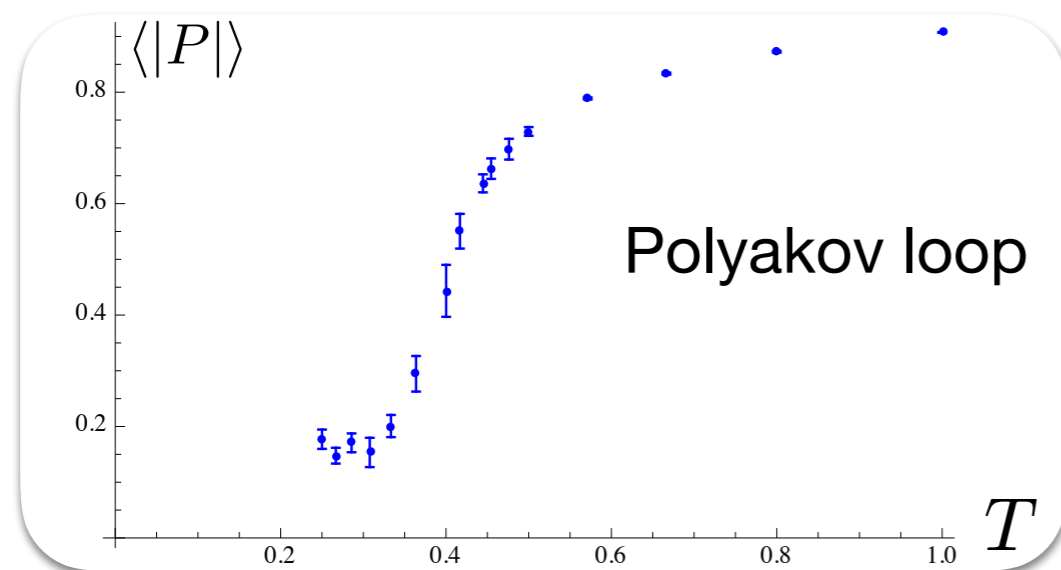
Gauge/gravity duality at finite T

[Costa, Greenspan, Penedones, Santos '14]

Thermal state
BMN matrix model



Thermal geometry
IIA/11D SUGRA



The agreement is numerically checked.

[Y.A., Filev, Kovacik, O'Connor '18;
Bergner, Bodendorfer, Hanada, Pateloudis,
Rinaldi, Schäfer, Vranas, Watanabe '21;...]

Transitions between different brane
configs have been observed.

$(\mu=5, L=24, N=11)$ [Y.A., Filev, Kovacik, O'Connor '18]

Introduction

The vacua of the BMN model

The BMN model has many degenerate vacua, protected by susy.

[Dasgupta, Sheikh-Jabbari, Raamsdonk '02]

$$X^a = \frac{\mu}{3} \begin{pmatrix} \mathbf{1}_{N_2^1} \otimes L_a^{[N_5^1]} \\ \mathbf{1}_{N_2^2} \otimes L_a^{[N_5^2]} \\ \vdots \end{pmatrix}$$

$(a = 1, 2, 3)$

$L_a^{[N_5^s]}$: N_5^s dimensional irrep. matrix
 N_2^s : multiplicity of this irrep.

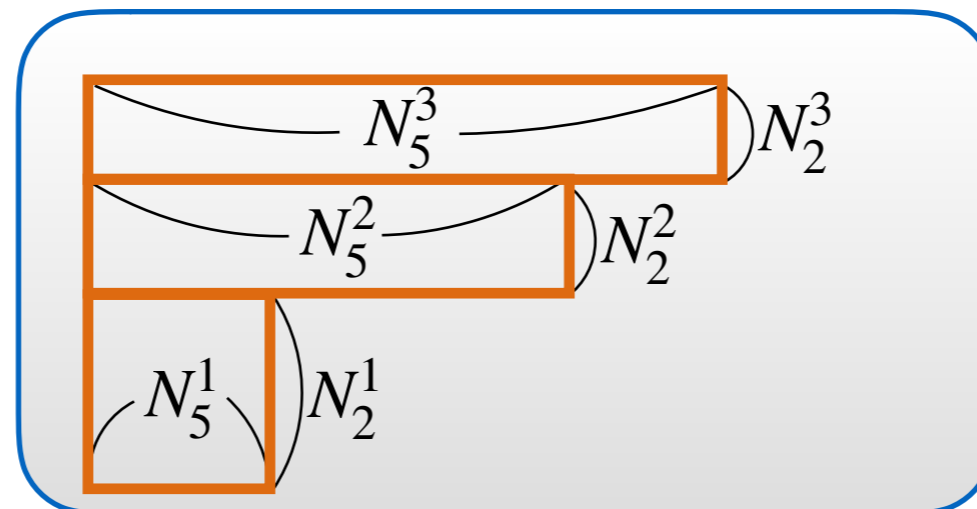
$$X^m = 0$$

$(m = 4, \dots, 9)$

The vacuum is parameterised by $\{N_2^s, N_5^s\}_{s=1,2,\dots}$

Partition of N

$$N = \sum_s N_2^s N_5^s$$



[Maldacena, Sheikh-Jabbari, Raamsdonk '02]

Introduction

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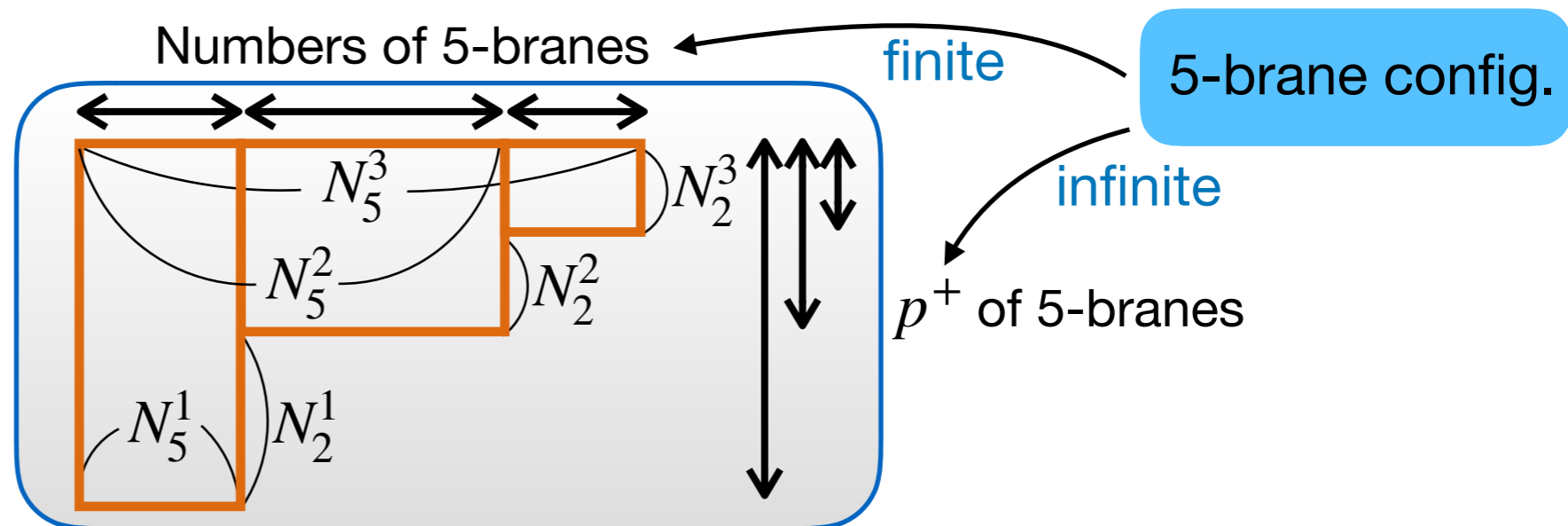
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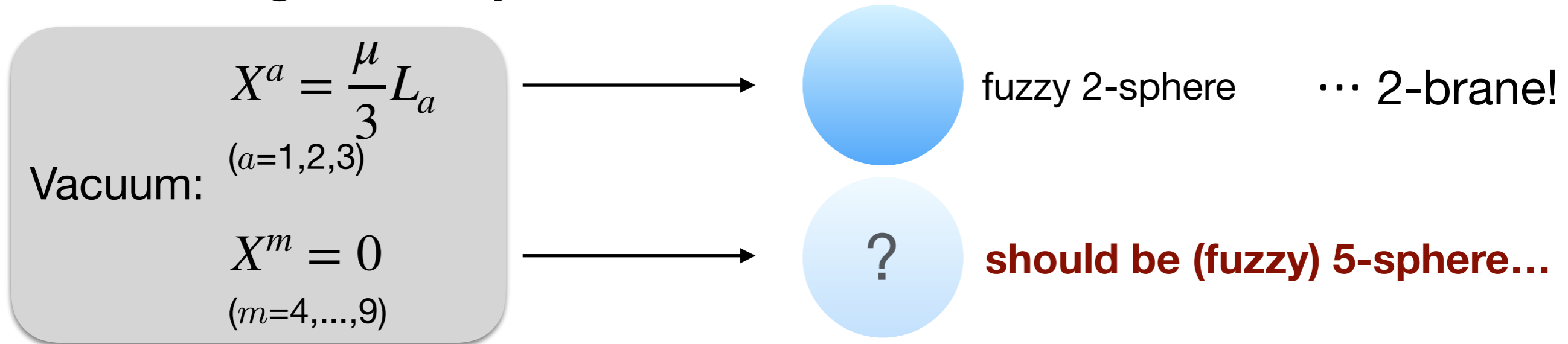
$$N = \sum_s N_2^s N_5^s$$



[Maldacena, Sheikh-Jabbari, Raamsdonk '02]

Introduction

5-brane geometry in the Matrix Model



5-branes have been a long-standing problem

To solve this problem, we ought to notice that geometrical features should be seen at **strong coupling**

Localisation

Localisation

Supersymmetric localisation computation

[Pestun '07;...]

Symmetry tends to make difficult computation possible.

The (new) SUSY localisation technique is a very powerful tool!

- applicable to a **large class** of supersymmetric theories
 - not only topological field theories
 - but also gauge theories on curved space, supergravity theories, ...

- can make an infinite-dim. path integral to a **finite-dim. integral**

$$\int [dX(\tau)] \rightarrow \int \left[\prod_{i=1}^N dm_i \right]$$

- its result is exact and valid in the **strong-coupling** regime

Localisation

How the localisation works

[Pestun '07;...]

Let us consider a system with a fermionic trf. δ

$$Z_{\mathcal{O}} = \int [dX] \mathcal{O} e^{-S[X]} \quad \delta S = 0 \quad \delta \mathcal{O} = 0$$

Introduce a deformation δV whose bosonic part is positive-definite.

$$Z_{\mathcal{O}}(t) := \int [dX] \mathcal{O} e^{-S[X] - t\delta V[X]} \quad \delta^2 V = 0$$

Then $\frac{dZ_{\mathcal{O}}(t)}{dt} := - \int [dX] \delta(\mathcal{O} V e^{-S[X] - t\delta V[X]}) = 0$ if the surface term vanishes or $[dX]$ is SUSY inv.

The original path integral can be computed by config.

localised around $\delta V = 0$: $Z_{\mathcal{O}} = Z_{\mathcal{O}}(0) = \lim_{t \rightarrow +\infty} Z_{\mathcal{O}}(t)$

 1-loop computation becomes **exact**

Localisation

BMN-model action

Let us consider a double-Wick-rotated theory $(\tau = it, X^0 = -iX^9)$
 (to construct susy)

$$S = \frac{1}{g^2} \int d\tau \operatorname{tr} \left(\frac{1}{2} (D_\tau X^i)^2 + \frac{1}{4} \left(-\frac{\mu}{3} \varepsilon^{abc} X_c - i[X^a, X^b] \right)^2 - \frac{1}{2} [X^a, X^m]^2 \right. \\ \left. - \frac{1}{4} [X^m, X^n]^2 + \frac{1}{2} \left(\frac{\mu}{6} \right)^2 X_m X^m + \sum_{I=1}^7 K_I K_I + \text{fermions} \right)$$

Off-shell SUSY (9 supercharges)

$(i=1, \dots, 8, 0, a=1, 2, 3, m=4, \dots, 8, 0)$

$$\delta_s X^i = i\epsilon \gamma^i \Psi, \quad \delta_s A = i\epsilon \gamma_\tau \Psi,$$

$$\delta_s \Psi = \left(D_\tau X_i \gamma^{\tau i} - \frac{i}{2} [X_i, X_j] \gamma^{ij} - \frac{\mu}{3} X_a \gamma^a \gamma^{123} + \frac{\mu}{6} X_m \gamma^m \gamma^{123} \right) \epsilon + K_I \nu^I$$

$$\delta_s K_I = i\nu_I \left(\gamma^\tau D_\tau \Psi - i\gamma^i [X_i, \Psi] - \frac{\mu}{24} \varepsilon_{abc} \gamma^{abc} \Psi \right) \quad [\text{Berkovits '93}]$$

Killing spinor eq.: $\partial_\tau \epsilon = -\frac{\mu}{12} \gamma_\tau \gamma^{123} \epsilon$

ϵ & ν_I 's satisfy conditions that make the SUSY closes off-shell

Localisation

Quarter-BPS sector (4 supercharges)

[Y.A., Ishiki, Okada, Shimasaki '12]

- $SO(5,1) \rightarrow SO(4) \times SO(1,1):$ $\gamma^{4567} \epsilon = \epsilon$

$$\left(\begin{array}{l} \mathcal{N} = 4 \text{ vector multiplet} \\ \rightarrow \mathcal{N} = 2 \text{ vector} + \mathcal{N} = 2 \text{ hyper} \end{array} \right)$$

- BPS Wilson loop : $\gamma^{03} \epsilon(\tau) = \epsilon(-\tau)$

$$\left(\begin{array}{l} \text{dim. reduction of} \\ \text{the half-BPS Wilson loop} \\ \text{in } \mathcal{N}=4 \text{ SYM on } R \times S^3 \end{array} \right)$$

$$\partial_\tau \epsilon = -\frac{\mu}{12} \gamma_\tau \gamma^{123} \epsilon$$

→ $\phi = X^3 + \sinh \frac{\mu\tau}{6} X^8 + \cosh \frac{\mu\tau}{6} X^0$ is invariant
 ($\propto \epsilon_1 \gamma^\mu \epsilon_2 X_\mu$)

Localisation

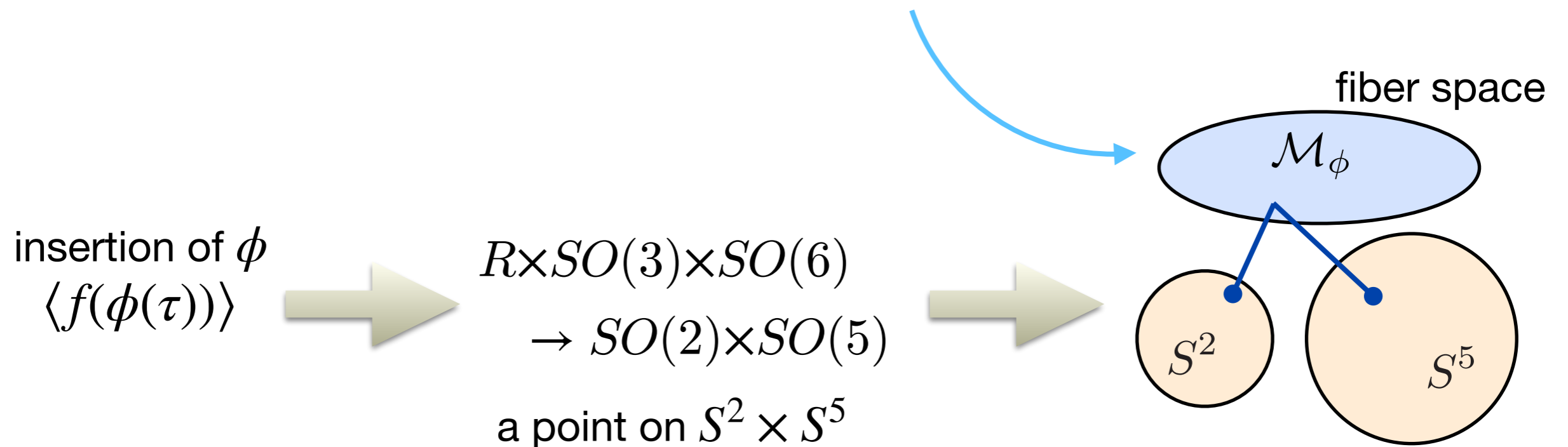
What will this 1/4-BPS mean?

[Y.A., Ishiki, Okada, Shimasaki '12]

In the original BMN model,

$$\phi = X^3 + i \left(\sin \frac{\mu t}{6} X^8 - \cos \frac{\mu t}{6} X^9 \right)$$

This would describe the radial directions of $S^2 \times S^5$



We expect it describes low-energy d.o.f. In fact, ϕ turns out to be time-independent, meaning that it only has a “0-energy mode.”

Localisation

Localisation for the BMN model

[Y.A., Ishiki, Okada, Shimasaki '12]

- Wick rotation to the Euclidean theory (but not compactified)
- B.C.: All fields approach the same vac. config. at $\tau \rightarrow \pm \infty$.
- Fermionic sym.: off-shell SUSY + BRST sym. $\delta = \delta_s + \delta_B$

(the 1/4-BPS)

- Deformation δV :
$$\delta V = \delta \left(\int d\tau \operatorname{tr}[\Psi \underline{\delta \Psi}] + V_{\text{gh}} \right)$$

Hermitian conjugate after the Wick rot.

Localising locus:

(basically, a solution to $\delta_s \Psi = 0$)

$$\hat{X}^a(\tau) = \frac{\mu}{3} L_a \quad \hat{X}^9(\tau) = -\frac{\mu M}{6 \cosh \frac{\mu\tau}{6}} \quad ([L_a, M] = 0)$$

same as the vacuum

“moduli”

other X 's are zero


$$\hat{\phi} = \frac{\mu}{6} (2L_3 + iM) \quad (\mu = 6 \text{ from now on, set by rescaling})$$

Localisation

Partition fn. in the 1/4-BPS sector

[Y.A., Ishiki, Okada, Shimasaki '12]

$$Z_1 = \int [dX] e^{-S[X] - t\delta V[X]}$$

$$= \lim_{t \rightarrow \infty} \int [dM][d\tilde{X}] e^{-S[\hat{X}] - t\delta V[\hat{X} + \frac{1}{\sqrt{t}}\tilde{X}]} = \int [dM] Z_{1\text{-loop}} e^{-S[\hat{X}]}$$

Exact result
(up to instanton effect)

$$S[\hat{X}] = \frac{2}{g^2} \text{tr} M^2 = \frac{2}{g^2} \sum_{s=1}^{\Lambda} \sum_{i=1}^{N_2^s} N_5^s m_{si}^2$$

contribution from superpartners of
 X^0, X^1, X^2, X^3, X^8

$$Z_{1\text{-loop}} = \prod_{s,t=1}^{\Lambda} \prod_{J=\frac{|N_5^s - N_5^t|}{2}}^{\frac{N_5^s + N_5^t}{2} - 1} \prod_{i=1}^{N_2^s} \prod_{j=1}^{N_2^t} \left[\frac{\{(2J+2)^2 + (m_{si} - m_{tj})^2\} \{(2J)^2 + (m_{si} - m_{tj})^2\}}{\{(2J+1)^2 + (m_{si} - m_{tj})^2\}^2} \right]^{\frac{1}{2}}$$

contribution from X^4, \dots, X^7

$$\hat{X}^a = 2 \begin{pmatrix} \mathbf{1}_{N_2^1} \otimes L_a^{[N_5^1]} & & & \\ & \ddots & & \\ & & & \mathbf{1}_{N_2^\Lambda} \otimes L_a^{[N_5^\Lambda]} \end{pmatrix} \quad (\Lambda \text{ blocks})$$

$$M = \begin{pmatrix} M_1 \otimes \mathbf{1}_{N_5^1} & & & \\ & \ddots & & \\ & & & M_\Lambda \otimes \mathbf{1}_{N_5^\Lambda} \end{pmatrix}$$

$(m_{si}$ are eigenvalues of M_s)

Localisation

The VEV of any 1/4-BPS operators can be computed by a **simple matrix integral**

τ -independent

$$\langle f_1(\phi(\tau_1)) f_2(\phi(\tau_2)) \cdots \rangle = \langle f_1((2L_3 + iM)) f_2((2L_3 + iM)) \cdots \rangle_{MM}$$

$$\left(\langle \mathcal{O} \rangle_{MM} = \frac{1}{Z_1} \int [dM] \mathcal{O} Z_{1\text{-loop}} e^{-S[\hat{X}]} \right)$$

The eigenvalue distribution for the s th block:

$$\rho^{(s)}(q) = \left\langle \sum_{i=1}^{N_2^s} \delta(q - m_{si}) \right\rangle_{MM}$$

(support: $[-q_m^{(s)}, q_m^{(s)}]$)

Localisation

Eigenvalue distribution

[Y.A., Ishiki, Okada, Shimasaki '14]

The saddle point eq. for $S_{\text{eff}}[M] = S[\hat{X}] - \ln Z_{1\text{-loop}}$
at large $q_m^{(s)}$ for the s th block is a Fredholm-type integral eq.

$$\rho^{(s)}(q) - \frac{1}{\pi} \sum_{t=1}^{\Lambda} \int_{-q_m^{(t)}}^{q_m^{(t)}} dq' \left[\frac{N_5^s + N_5^t}{(N_5^s + N_5^t)^2 + (q - q')^2} - \frac{|N_5^s - N_5^t|}{(N_5^s - N_5^t)^2 + (q - q')^2} \right] \rho^{(t)}(q') = \frac{\beta_s}{\pi} - \frac{2N_5^s}{\pi g^2} q^2$$

β_s : Lagrange multiplier

In the $\Lambda = 1$ case,

$$\rho(q) - \frac{1}{\pi} \int_{-q_m}^{q_m} dq' \frac{2N_5}{(2N_5)^2 + (q - q')^2} \rho(q') = \frac{\beta}{\pi} - \frac{2N_5}{\pi g^2} q^2$$

This can be solved in special limits.

$$(N_5/q_m \rightarrow 0 \text{ and } +\infty)$$

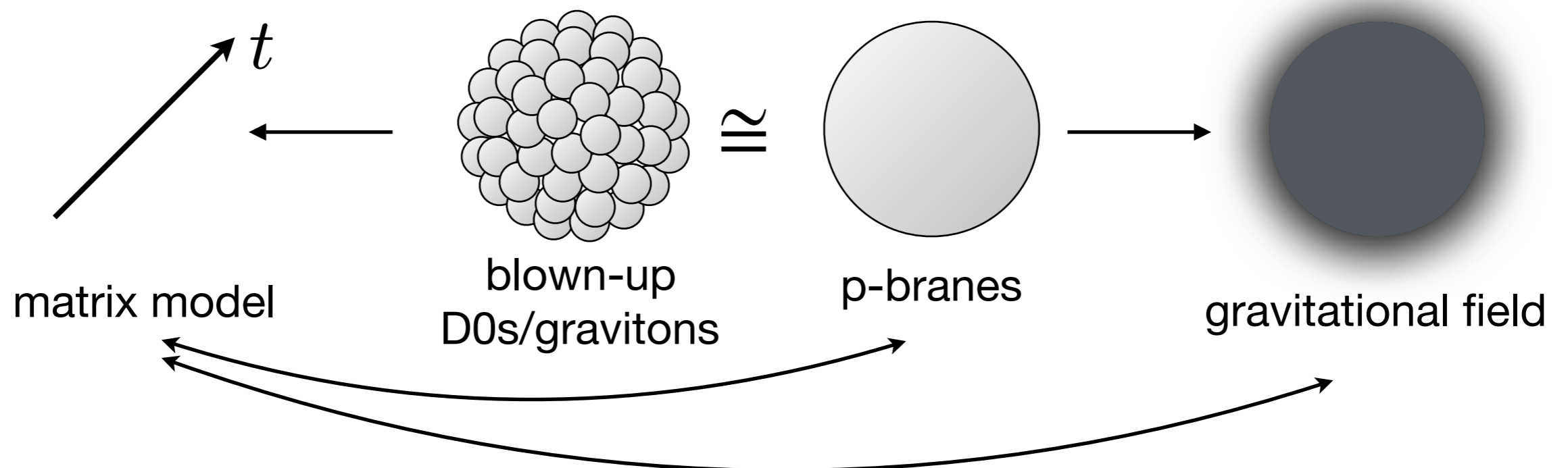
Localisation

Applications of the localisation result

- The eigenvalue dist. of ϕ reproduces **the spherical geometry of stacks of M5-branes.**

It also reproduces the spherical geometry of stacks of M2-branes at large N_2 . [Y.A., Ishiki, Shimasaki, Terashima '17]

- The eigenvalue dist. of ϕ satisfies **exactly the same equations as the Lin-Maldacena geometry** does, i.e., ϕ constructs part of Einstein's eq. [Y.A., Ishiki, Okada, Shimasaki '14; Y.A., Ishiki, Shimasaki '14]



Localisation

- The **double scaling limit** for NS5-branes

(It was obtained with help of numerical computation)

[Y.A., Ishiki, Okada, Shimasaki '14;

Y.A., Ishiki, Matsumoto, Shimasaki, Watanabe '22]

(Purely analytic derivation of the DSL is work in progress)

[Y.A., Ishiki, Shimasaki]

What hasn't done yet

- Complete reconstruction of the Lin-Maldacena geometry in the matrix model, and the real meaning of ϕ
- $1/N$ correction and coupling expansion (α' correction)
- Reproducing the theory on M-branes in the 1/4-BPS sector
- Relationship to the ABJM/BLG model, in the limit for M2-branes
- Using the exact result as an input for the bootstrapping
- Application of the localisation technique to other BPS sectors, and other matrix models

M-brane geometry

M-brane geometry

The vacuum corresponding to a single-stack M5 ($\Lambda = 1$):

$$\hat{X}^a = \frac{\mu}{3} \mathbf{1}_{N_2} \otimes L_a^{[N_5]} \quad \text{with } N_2 \rightarrow \infty \text{ and } \lambda = g^2 N_2 \rightarrow \infty$$

... corresponds to $N_5/q_m \rightarrow 0$

$$\rho(q) - \frac{1}{\pi} \int_{-q_m}^{q_m} dq' \frac{2N_5}{(2N_5)^2 + (q - q')^2} \rho(q') = \frac{\beta}{\pi} - \frac{2N_5}{\pi g^2} q^2$$

$$= \frac{1}{2\pi i} (\omega(q - 2N_5 i) - \omega(q + 2N_5 i))$$

$$\omega(z) = \int dq \frac{\rho(q)}{z - q}$$

$$\implies N_5 (\omega'(q - i0) + \omega'(q + i0)) = \beta - \frac{2N_5}{g^2} q^2$$

~ one-matrix model with quartic interaction

q_m is determined by the least action:

$$\rho(q) = \frac{8}{3\pi q_m} \left[1 - \left(\frac{q}{q_m} \right)^2 \right]^{3/2} \quad q_m = (8g^2 N_2)^{1/4}$$

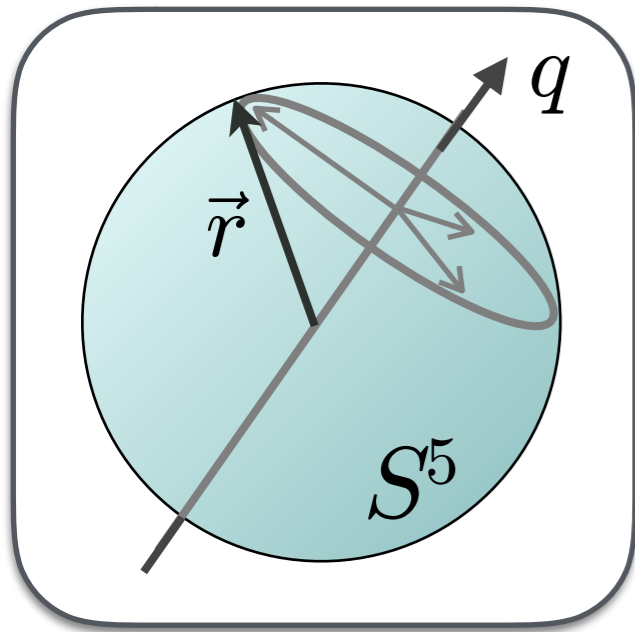
M-brane geometry

We now have the eigenvalue distribution in the M5 limit.

$$\rho(q) = \frac{8}{3\pi q_m} \left[1 - \left(\frac{q}{q_m} \right)^2 \right]^{3/2} \longrightarrow \hat{\rho}(\vec{r}) = \frac{1}{\pi^3 q_m^5} \delta(|\vec{r}| - q_m)$$

uplift to 6D

S^5 radius



$$\int_{-q_m}^{q_m} dq \rho(q) q^{2n} = \int d^6 \vec{r} \hat{\rho}(\vec{r}) x_9^{2n} \quad \vec{r} = \begin{pmatrix} x_4 \\ \vdots \\ x_9 \end{pmatrix}$$

[Filev, O'Connor '14;
Y.A., Ishiki, Shimasaki, Terashima '17]

$$q_m = (8g^2 N_2)^{1/4}$$

... exactly the same as the radius computed by the light-cone Hamiltonian for a 5-brane after the appropriate rescaling

$$H = \text{tr} \left(\frac{N}{2p^+} P^i P^i - \frac{\pi^2 T_{M2}^2 N}{p^+} [X^i, X^j][X_i, X_j] + \dots \right) \rightarrow \text{tr} \left(\frac{g^2}{2} P^i P^i - \frac{1}{4g^2} [X^i, X^j][X_i, X_j] + \dots \right)$$

[Y.A., Ishiki, Shimasaki, Terashima '17]

M-brane geometry

[Y.A., Ishiki, Shimasaki, Terashima '17]

- M5-brane realisation:

locus: $\phi \sim iM$ at large N_2 and $g^2 N_2 \gg 1$

$SO(6)$ symmetric uplift $\longrightarrow \hat{\rho}(\vec{r}) = \frac{1}{\pi^3 q_m^5} \delta(|\vec{r}| - q_m)$
 S^5 radius

- M2-brane realisation (at large N_2):

locus: $\phi \sim 2L_3$ at large N_5 and $g^2/N_5 \gg 1$

$SO(3)$ symmetric uplift $\longrightarrow \hat{\rho}(\vec{r}) = \frac{1}{4\pi \left(\frac{3\pi g^2 N_2}{8N_5}\right)^{\frac{2}{3}}} \delta\left(|\vec{r}| - \left(\frac{3\pi g^2 N_2}{8N_5}\right)^{\frac{1}{3}}\right)$
 S^2 radius

We reproduce the spherical thin shell distribution with the correct radius

N.B. The same goes for multiple-stack M2- or M5-branes.

Theory on 5-branes

Theory on 5-branes

We should reproduce the theory on the spherical 5-branes.
But there's a subtlety for NS5-branes.

To reproduce the spherical brane geometry, we took

M5-brane limit: $N_2 \rightarrow \infty$ and $\lambda = g^2 N_2 \rightarrow \infty$... OK

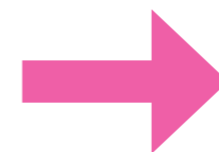
The theory on NS5-branes is considered to be Little String Theory.
LST should be reproduced in the BMN model by taking a limit.

NS5-brane limit: $N_2 \rightarrow \infty$ and $\lambda = g^2 N_2$: fixed (?)

NS5 coupling (?)

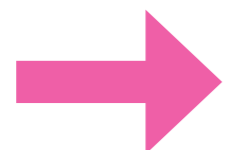


q_m doesn't approach ∞



The spherical NS5 geometry
is not reproduced

The above naive identification of the NS5 coupling may not be correct.



This would be answered by the gauge/gravity duality

Theory on 5-branes

Vacuum
BMN matrix model



Gravity solution
IIA/11D SUGRA

Type-IIA Lin-Maldacena geometry:

[Lin, Maldacena '05]

$$ds_{10}^2 = \left(\frac{\ddot{V} - 2\dot{V}}{-V''} \right)^{1/2} \left\{ -4 \frac{\ddot{V}}{\dot{V} - 2\dot{V}} dt^2 - 2 \frac{V''}{\dot{V}} (dr^2 + dz^2) + 4 \frac{d\Omega_5^2}{S^5} + 2 \frac{V'' \dot{V}}{\Delta} \frac{d\Omega_2^2}{S^2} \right\},$$

$$C_3 = -4 \frac{\dot{V}^2 V''}{\Delta} dt \wedge d\Omega_2, \quad B_2 = \left(\frac{(\dot{V}^2)'}{\Delta} + 2z \right) d\Omega_2, \dots$$

$(\Delta = (\dot{V} - 2\dot{V})V'' - (\dot{V}')^2)$
 (dot: $r\partial_r$, prime: ∂_z)

D2- and NS5-charges reside on (r, z) w/ $y = \dot{V} = 0$,
and each config. of the charges corresponds to a BMN vacuum.

It depends only on $V(r, z)$, which satisfies the Laplace eq.

$$\frac{1}{r^2} \ddot{V} + V'' = 0$$

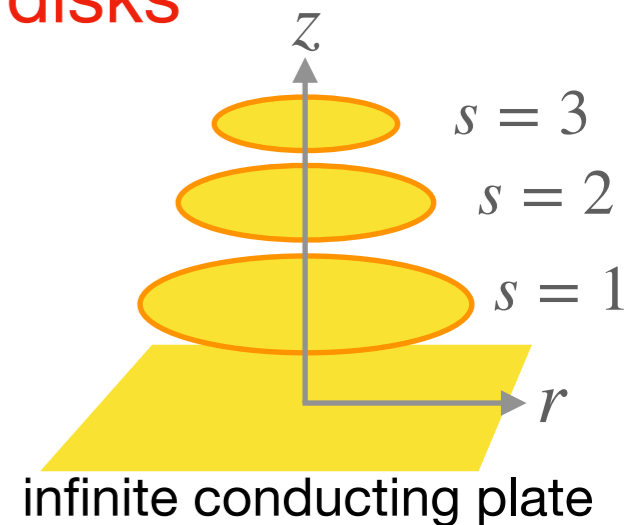
Theory on 5-branes

$V(r, z)$ can be regarded as an **axisymmetric electrostatic potential**.

- Laplace eq.: $\frac{1}{r^2} \dot{V} + V'' = 0$
- Positivity of the metric: background potential $V_{\text{b.g.}}(r, z) = V_0 \left(r^2 z - \frac{2}{3} z^3 \right)$
- Regularity at $y = \dot{V} = 0$: configuration of **conducting disks**

$$V(r, z) = V_{\text{b.g.}}(r, z) + \sum_{s=1}^{\Lambda} \phi_s [f_s(u); N_5^s, r, z]$$

“electric density” height of the disk



The Laplace eq. is rewritten as

$$f_s(u) - \frac{1}{\pi} \sum_{t=1}^{\Lambda} \int_{-R_t}^{R_t} du' \left[\frac{\frac{\pi}{2}(N_5^s + N_5^t)}{\frac{\pi^2}{4}(N_5^s + N_5^t)^2 + (u - u')^2} - \frac{\frac{\pi}{2} |N_5^s - N_5^t|}{\frac{\pi^2}{4}(N_5^s - N_5^t)^2 + (u - u')^2} \right] f_t(u') = C_s - V_0 N_5^s u^2$$

$$\int_{-R_s}^{R_s} du f_s(u) = \frac{\pi^2}{8} N_5^s$$

C_s : constant value of the potential on the s th disk

Theory on 5-branes

On the gauge theory side

$$\rho^{(s)}(q) - \frac{1}{\pi} \sum_{t=1}^{\Lambda} \int_{-q_m^{(t)}}^{q_m^{(t)}} dq' \left[\frac{N_5^s + N_5^t}{(N_5^s + N_5^t)^2 + (q - q')^2} - \frac{|N_5^s - N_5^t|}{(N_5^s - N_5^t)^2 + (q - q')^2} \right] \rho^{(t)}(q') = \frac{\beta_s}{\pi} - \frac{2N_5^s}{\pi g^2} q^2$$

On the gravity side

$$f_s(u) - \frac{1}{\pi} \sum_{t=1}^{\Lambda} \int_{-R_t}^{R_t} du' \left[\frac{\frac{\pi}{2}(N_5^s + N_5^t)}{\frac{\pi^2}{4}(N_5^s + N_5^t)^2 + (u - u')^2} - \frac{\frac{\pi}{2}|N_5^s - N_5^t|}{\frac{\pi^2}{4}(N_5^s - N_5^t)^2 + (u - u')^2} \right] f_t(u') = C_s - V_0 N_5^s u^2$$

They are completely the same equations!

Identification:

$$f_s(u) = \frac{\pi}{4} \rho^{(s)}\left(\frac{2}{\pi}u\right)$$

$$R_s = \frac{\pi}{2} q_m^{(s)}$$

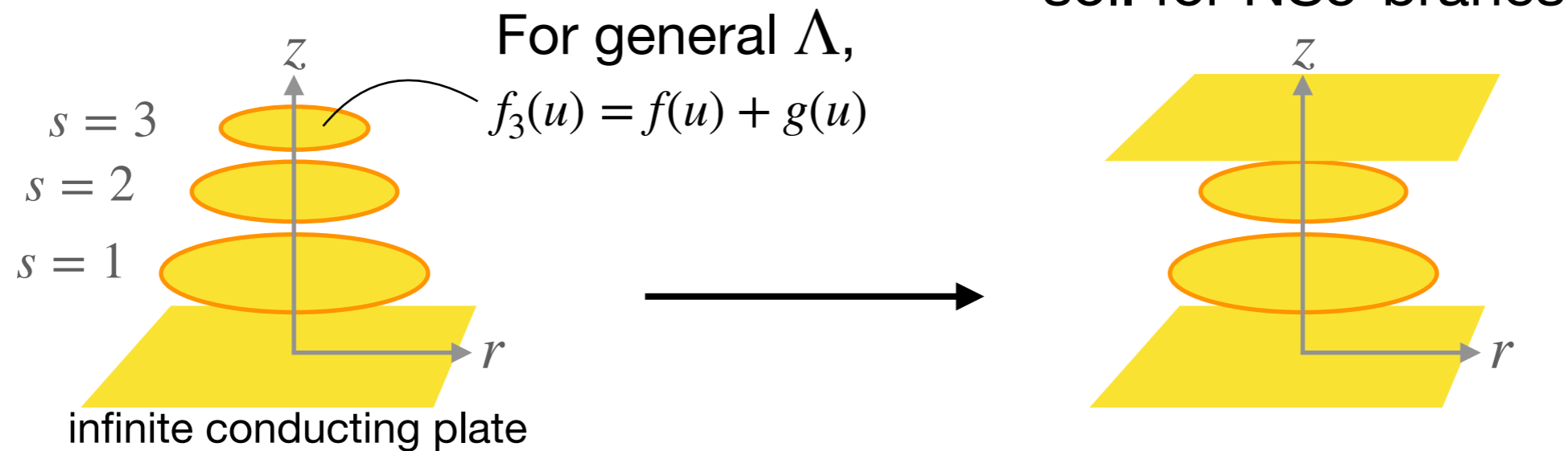
$$V_0 = \frac{2}{\pi^2 g^2}$$

[Y.A., Ishiki, Okada, Shimasaki '14,
Y.A., Ishiki, Shimasaki '14]

Eigenvalues construct a geometry.

Theory on 5-branes

There's a double scaling limit to obtain the gravity solution for NS5-branes on the gravity side:



For $\Lambda = 1$,

$$V = V_{\text{b.g.}} + \phi_1[f(u); N_5, r, z]$$

$$f(u) - \frac{1}{\pi} \int_{-R}^R du' \frac{\frac{\pi}{2}(2N_5)}{\frac{\pi^2}{4}(2N_5)^2 + (u - u')^2} f(u')$$

$$= C - V_0 N_5 u^2$$

$$V = \frac{1}{g_0} \sin \frac{2z}{N_5} I_0\left(\frac{2r}{N_5}\right) = V_{\text{NS5 b.g.}}$$

DSL: $R \rightarrow \infty, V_0 \rightarrow \infty$ with $g_0 \propto \frac{\exp[\frac{2R}{N_5}]}{V_0(RN_5)^{3/2}}$: fixed

Theory on 5-branes

According to the gauge/gravity duality,
the double scaling limit on the gauge theory side is

$$N_2 \rightarrow \infty, g^2 \rightarrow 0 \text{ with } \frac{(g^2 N_2)^{5/8}}{N_2} \exp \left[\pi \frac{(8g^2 N_2)^{1/4}}{N_5} \right] : \text{fixed}$$

coupling of the theory on NS5-branes

$$\longrightarrow \lambda = g^2 N_2 \sim N_5^4 (\ln N_2)^4 \rightarrow \infty$$

For general Λ , the DSL to obtain a theory on NS5-branes around a vacuum with D2 charges is to take the same limit only for the irrep. with the largest dim. N_5^Λ .

$$\rho^{(s)}(q) - \sum_{t=1}^{\Lambda} (\text{interactions with } \rho^{(t)}) = \frac{\beta_s}{\pi} - \frac{2N_5^s}{\pi g^2} q^2$$

$$\longrightarrow \rho^{(s)}(q) - \sum_{t=1}^{\Lambda-1} (\text{more interactions with } \rho^{(t)}) = \frac{\tilde{\beta}_s}{\pi} - \frac{1}{g_0} \sin \frac{2z}{N_5^s} \cosh \frac{2r}{N_5}$$

Theory on 5-branes

$$\tilde{g}_s := \frac{(g^2 N_2)^{5/8}}{N_2} \exp \left[\pi \frac{(8g^2 N_2)^{1/4}}{N_5} \right] : \text{fixed}$$

So far, the DSL was checked at the planar sector, but usually, a DSL is expected to keep all orders of $1/N$ expansion.

The expectation value of a function of ϕ is

$$\langle \mathcal{O}(\phi) \rangle = \sum_{h=0}^{\infty} d_h (g^2 N_2) N_2^{-h}$$

If \tilde{g}_s is the coupling of the theory on NS5-branes (LST),

$$\langle \mathcal{O}(\phi) \rangle = C(g^2 N_2) \sum_{h=0}^{\infty} c_h \tilde{g}_s^h \quad \longrightarrow \quad \frac{d_{h+1}}{d_h} = \frac{c_{h+1}}{c_h} (g^2 N_2)^{5/8} \exp \left[\pi \frac{(8g^2 N_2)^{1/4}}{N_5} \right]$$

Finiteness of c_1/c_0 was checked numerically

[Y.A., Ishiki, Matsumoto, Shimasaki, Watanabe '22]

DSL beyond the planar sector

Summary

- Branes in the matrix model get to be understood better. We see emergent geometry in the brane picture and the gauge/gravity picture; both pictures are consistent so far.
- Unfortunately, the emergence of the geometry we've seen is incomplete. We highly relied on symmetry of the geometry.
- The susy localisation technique is powerful. In this talk, the localisation technique was applied to a theory on the infinite real line. This type of localisation computation would be useful for a test of the matrix-model conjecture and the gauge/gravity conjecture.