

Machine Learning Methods

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Ultra-High Energy Cosmic Rays

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Wien, 14.12.2023



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Focus of the talk

- **Infer** the composition of Ultra High-Energy Cosmic Rays
- Solve **unfolding** problem in an unbiased way
(work in progress)
- Remove bias in **classification** problems
- Use results from **regression** in an unbiased way

Why Cosmic Rays?

Ultra High-Energy Cosmic Rays (UHECR)

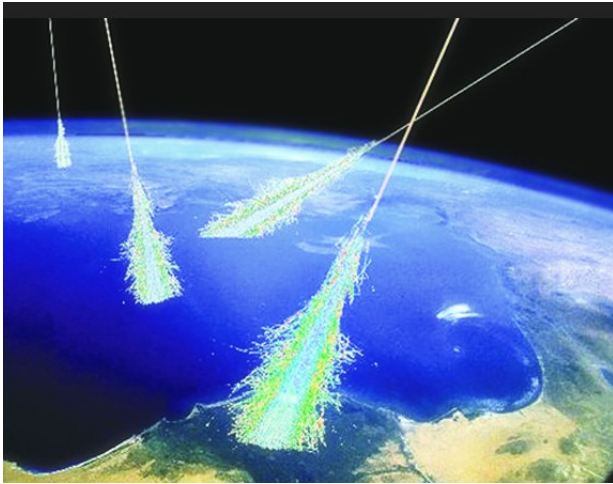
- atomic nuclei (H, He,..., Fe)
- $E \geq 10^9 \text{ GeV}$ (proton mass: 1 GeV)

Unknowns:

- acceleration mechanisms
- sources

This Talk

- composition
(fractions of atomic nuclei)



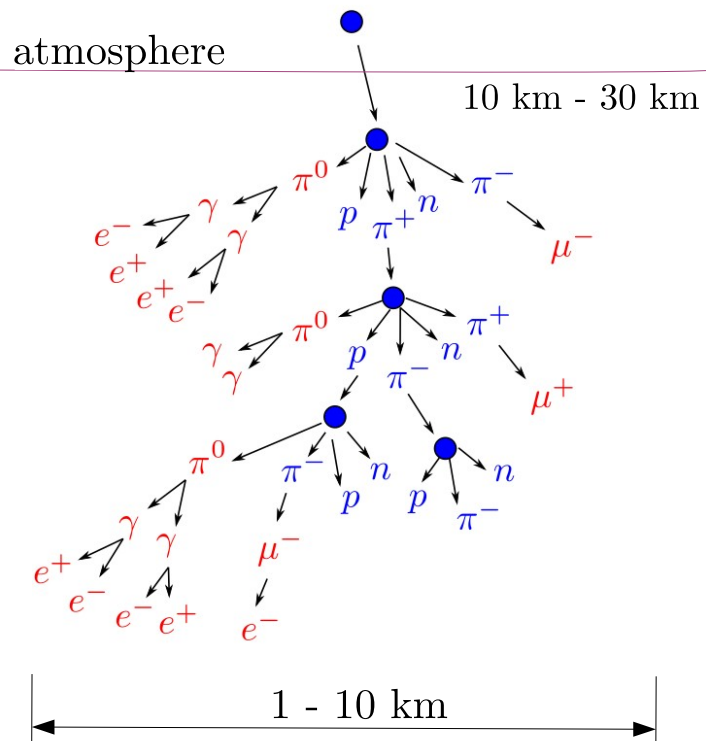
Motivation

- galactic & inter-galactic magnetic fields, propagation
- acceleration mechanisms (extreme events)
- hadron interactions at ultra high energies
 - $10^5 \times - 10^7 \times$ the energy at LHC
 - **undiscovered particles**

Artist's impression of cosmic rays striking Earth
(Simon Swordy/University of Chicago, NASA)

Extensive Air Showers

primary particle
(atomic nucleus)

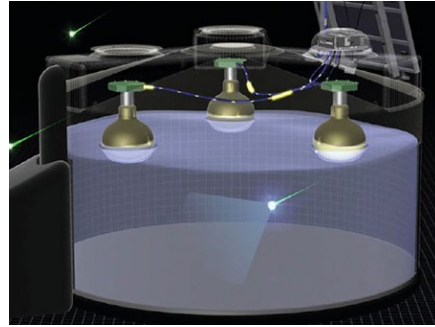


→ Most of the energy on the ground is carried by **muons**

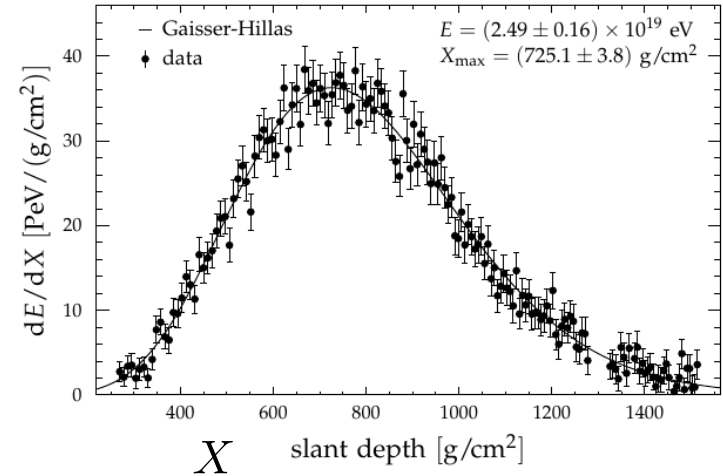
→ Charged particles ionize nearby particles in the air, fluorescence light is emitted

Pierre Auger Observatory

Surface Detectors (SD) are
water Cherenkov detectors



Fluorescence detectors (FDs) operate
only in clear, moonless nights



$$X = \int \rho(\vec{r}) dr$$

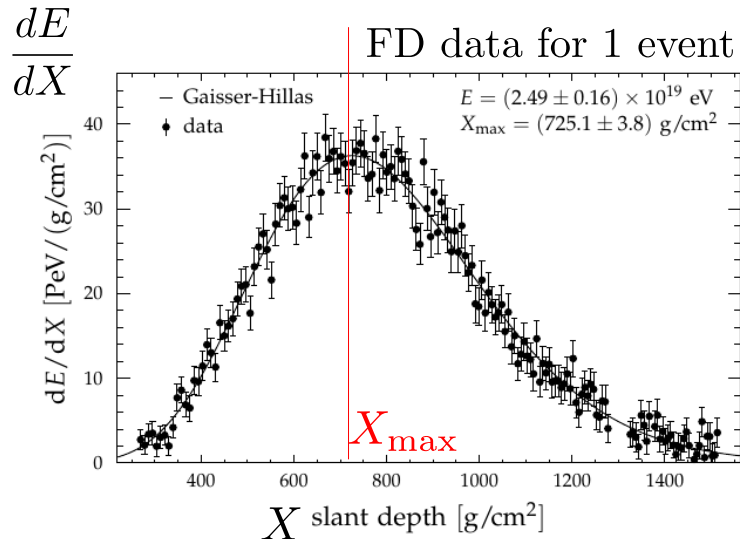
→ 1600 Surface detectors, 1.5 km apart, cover 3000 km²

→ 4 × 6 Fluorescence detectors, 330–380 nm

Data

Pierre Auger Observatory Open Data 2021

- 10% of all observed events
- ~ 1600 events with SD and FD data
- ~ 22000 events with only SD data

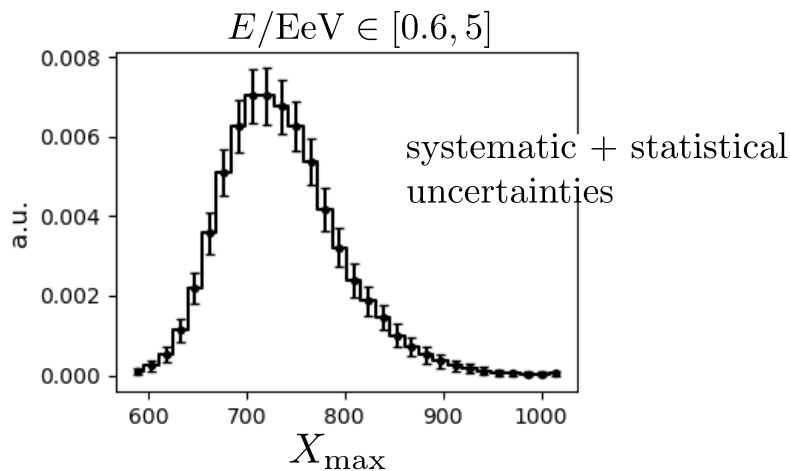


Composition is obtained by comparing simulations to measurements

- data from SD detectors cannot be reproduced by simulations
- X distribution can be well simulated
- X_{max} depends on mass of the primary particle

Measured values
(Pierre Auger Observatory)

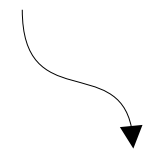
What we propose



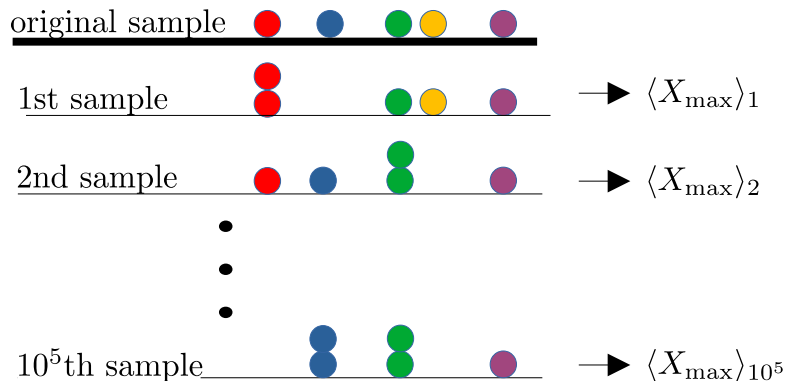
Most of the information: $\mathbf{z} = (z_1, z_2, z_3, z_4)$

$$z_1 = \frac{1}{N} \sum_{i=1}^N X_{\text{max},i} \quad n = 1, 2, 3, 4$$

$$z_n = \frac{1}{N} \sum_{i=1}^N (X_{\text{max},i} - z_1)^n$$



Bootstrap method



Distribution of observables

$$P(\mathbf{z}) = \mathcal{N}(\mathbf{z}|\mu, \Sigma)$$

*This trick lowers computational costs, but it is not required

What we propose

Simulations

- 0.6 EeV - 5 EeV
- 4 hadronic models
- 26 primaries: p, He, Li,..., Fe
- 6000 events/model/primary

$$P(\mathbf{z}|\mathbf{w}) = \mathcal{N}(\mathbf{z}|\mu(\mathbf{w}), \Sigma(\mathbf{w}))$$

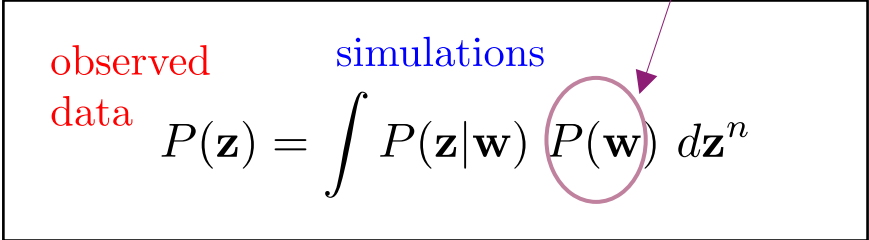
$$\mathbf{w} = (w_p, \dots, w_{Fe})$$

Measurements

$$P(\mathbf{z}) = \mathcal{N}(\mathbf{z}|\mu, \Sigma)$$

Problem

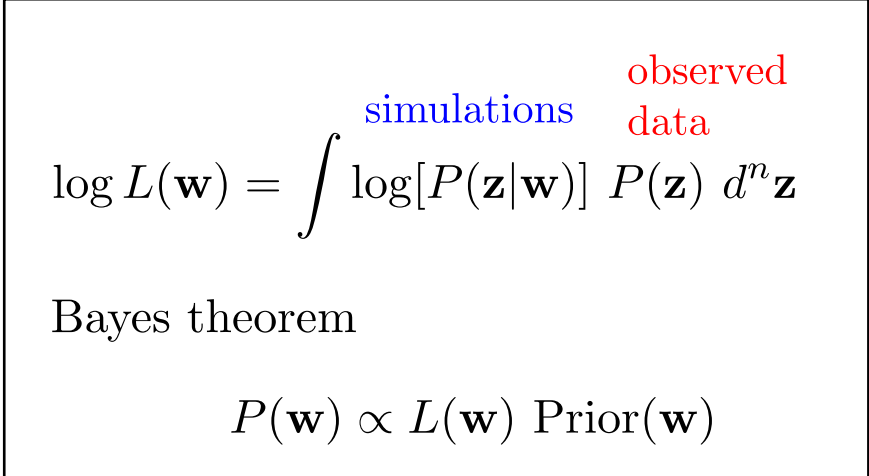
Distribution of compositions



The diagram shows the equation $P(\mathbf{z}) = \int P(\mathbf{z}|\mathbf{w}) P(\mathbf{w}) d\mathbf{z}^n$ inside a black-bordered box. The word "observed data" is written in red to the left of the equation. The word "simulations" is written in blue above the integral sign. The term $P(\mathbf{w})$ is circled in pink, and a pink arrow points from the text "Distribution of compositions" above to this circled term.

$$\text{observed data} \quad P(\mathbf{z}) = \int \text{simulations} \quad P(\mathbf{z}|\mathbf{w}) \quad P(\mathbf{w}) \quad d\mathbf{z}^n$$

Solution



The diagram shows the equation $\log L(\mathbf{w}) = \int \log[P(\mathbf{z}|\mathbf{w})] P(\mathbf{z}) d^n \mathbf{z}$ inside a black-bordered box. The word "simulations" is written in blue above the integral sign. The words "observed data" are written in red to the right of the equation.

$$\log L(\mathbf{w}) = \int \text{simulations} \quad \log[P(\mathbf{z}|\mathbf{w})] \quad \text{observed data} \quad P(\mathbf{z}) \quad d^n \mathbf{z}$$

Bayes theorem

$$P(\mathbf{w}) \propto L(\mathbf{w}) \text{Prior}(\mathbf{w})$$

What we propose

Log-Likelihood

$$\log L(\mathbf{w}) = \int \log[P(\mathbf{z}|\mathbf{w})] P(\mathbf{z}) d^m \mathbf{z}$$

simulations observed
data

→ analytical solution if $P(\mathbf{z}|\mathbf{w})$ and $P(\mathbf{z})$ are normal

Bayes theorem

$$P(\mathbf{w}) \propto L(\mathbf{w}) \text{ Prior}(\mathbf{w})$$

→ 25 dimensional distribution

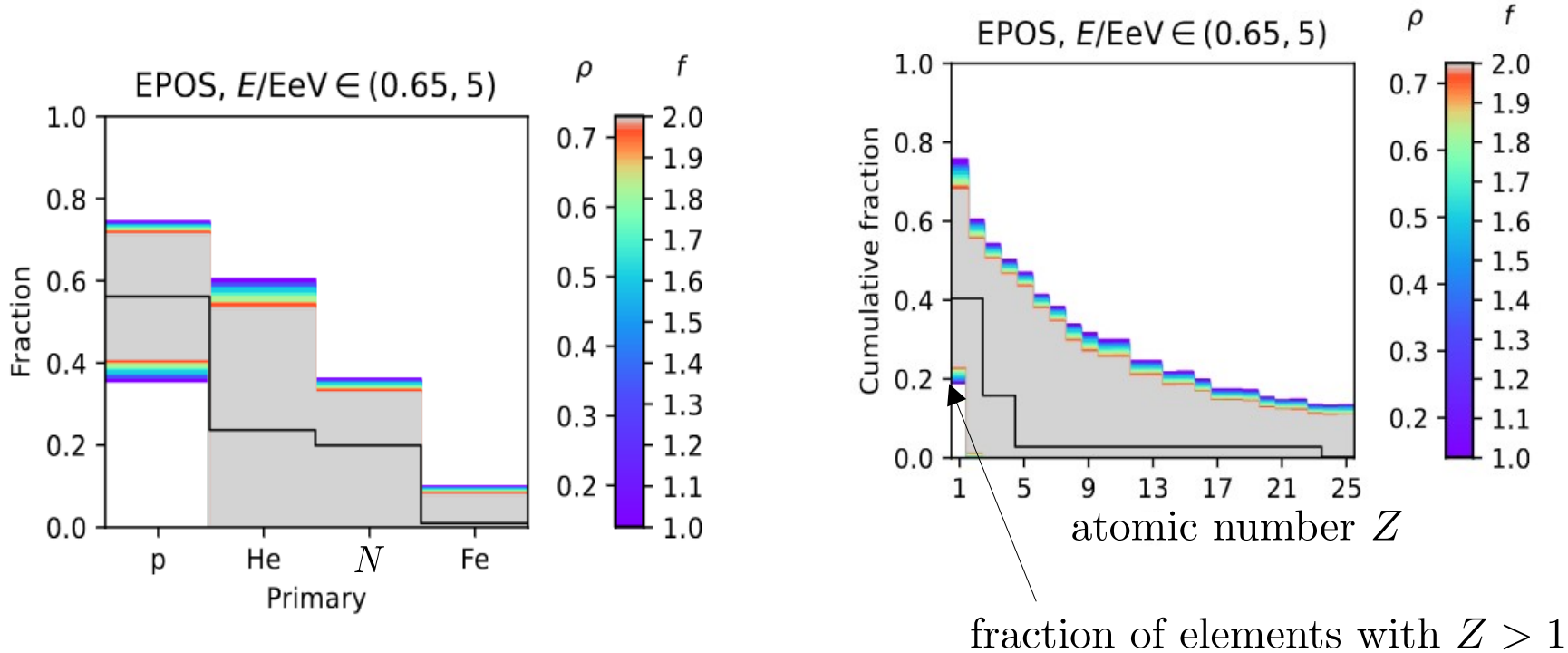
→ sample from $P(\mathbf{w})$ with **Nested Sampling (NS)**

→ NS estimates the volume of $P(\mathbf{w})$ as a function of $\log L$

Most probable composition \mathbf{w}^* :

$$\log L(\mathbf{w}^*) = \max$$

Results

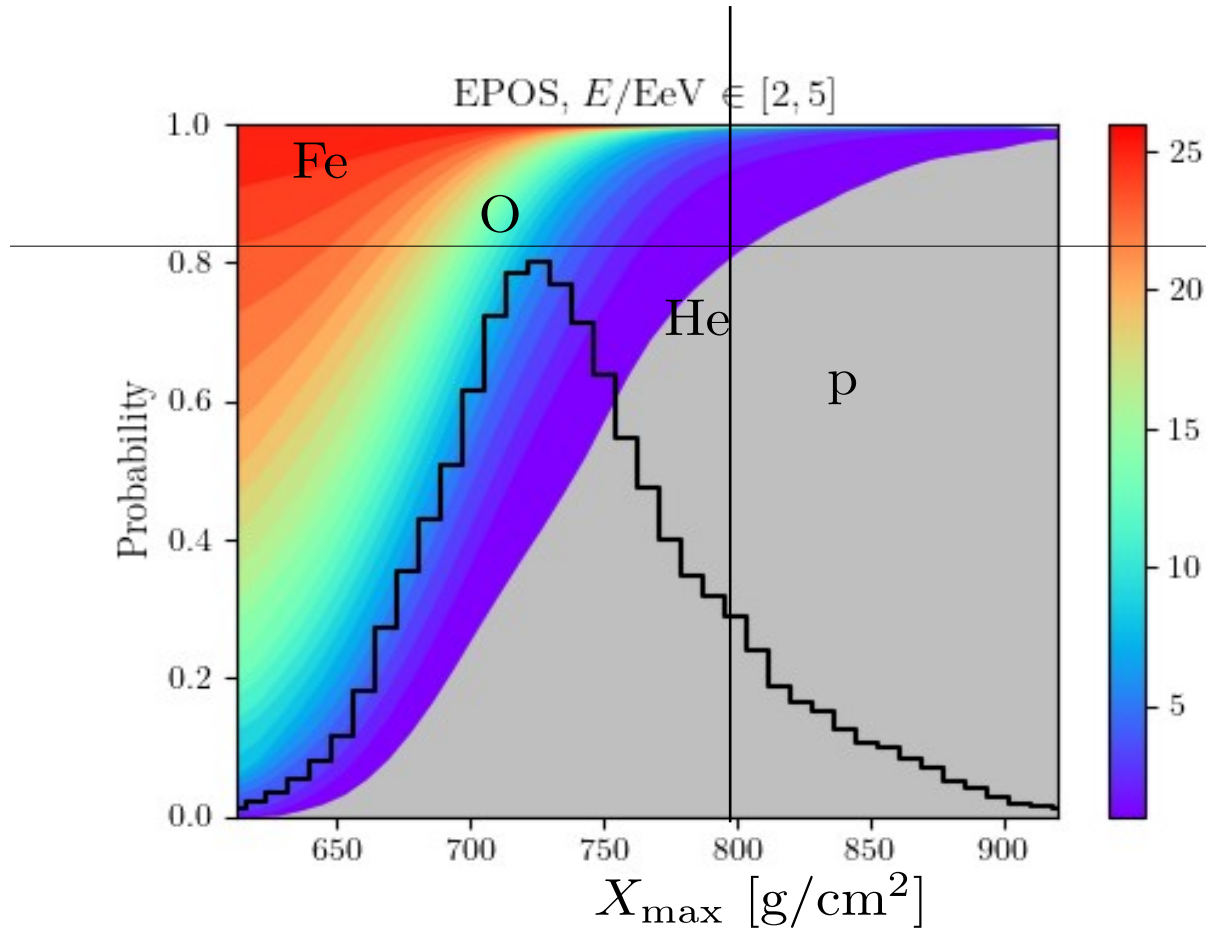


→ 95% CL

→ 1600 events

20% – 80% of primaries are not protons (95% CL)

Results



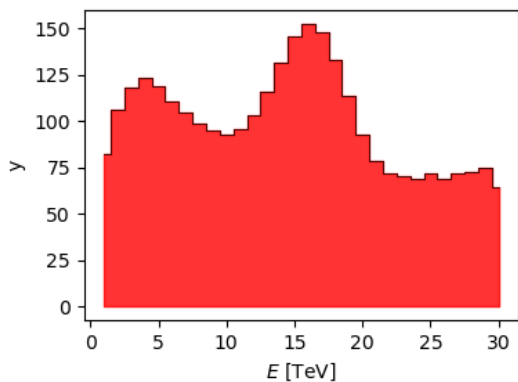
”Expected
Classification”

Applications

Unfolding problem

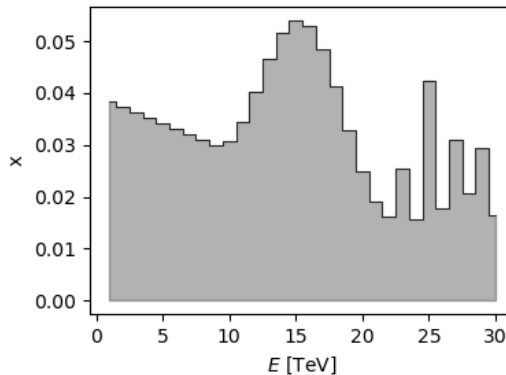
$$P(\mathbf{y}) = \int P(\mathbf{y}|\mathbf{x}) P(\mathbf{x}) d\mathbf{x}^n$$

observed
distribution



detector
response

actual
distribution



Unfolding

Unbiased solution

$$\log L(\mathbf{w}) = \int \log[P(\mathbf{z}|\mathbf{w})] P(\mathbf{z}) d^n \mathbf{z}$$

Bayes theorem

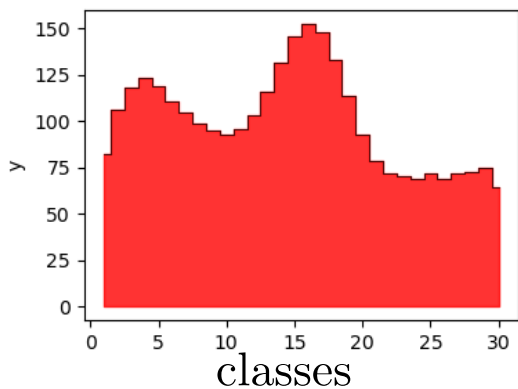
$$P(\mathbf{w}) \propto L(\mathbf{w}) \text{Prior}(\mathbf{w})$$

Applications

Removing bias in a classification problem

$$P(\mathbf{y}) = \int P(\mathbf{y}|\mathbf{x}) P(\mathbf{x}) d\mathbf{x}^n$$

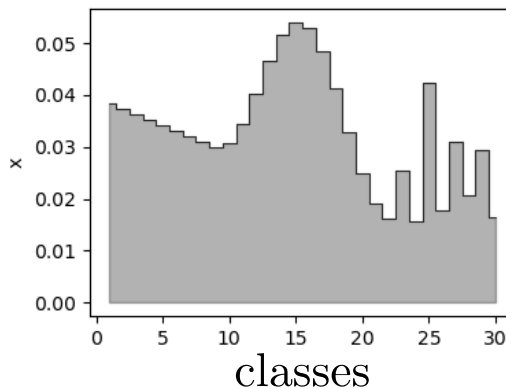
predicted probabilities



classifier response (confusion matrix)

Unfolding

actual labels



Unbiased solution

$$\log L(\mathbf{w}) = \int \log[P(\mathbf{z}|\mathbf{w})] P(\mathbf{z}) d^n \mathbf{z}$$

Bayes theorem

$$P(\mathbf{w}) \propto L(\mathbf{w}) \text{Prior}(\mathbf{w})$$

Applications

Removing bias in a classification problem (step by step)

→ train a classifier (on balanced dataset)

→ evaluate the confusion matrix, normalize rows (bootstrap method)
 $\{R_1, \dots, R_N\} \quad P(y|x) : \mathbf{x} \rightarrow \{R_1x, \dots, R_Nx\}$

→ predict distribution of classes on unlabelled dataset (bootstrap method)
 $\{y_1, \dots, y_N\} \rightarrow P(y)$

→ infer distribution $P(x)$ of actual distributions of classes x

$$\log L(\mathbf{x}) = \int \log[P(\mathbf{y}|\mathbf{x})] P(\mathbf{y}) d^n \mathbf{y}$$
$$P(\mathbf{x}) \propto L(\mathbf{x}) \text{Prior}(\mathbf{x})$$

→ reweight classifier outputs

**Classifier is treated as a black box →
predictions are statistically completely meaningful**

Applications

If $P(x)$ is parametrized with $P(x|\theta)$,
optimal parameters are given by maximizing:

$$\text{observed data } P(\mathbf{y}) = \int \text{detector/model } P(\mathbf{y}|\mathbf{x}) P(\mathbf{x}) d\mathbf{x}^n$$

$$\int \log \left\{ \int \text{detector/model } P(\mathbf{y}|\mathbf{x}) P(\mathbf{x}|\theta) d^n \mathbf{x} \right\} \text{observed data } P(\mathbf{y}) d^m \mathbf{y} = \max$$

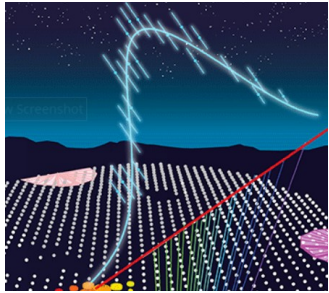
- NN
- normalizing flows
- ...

In practise...

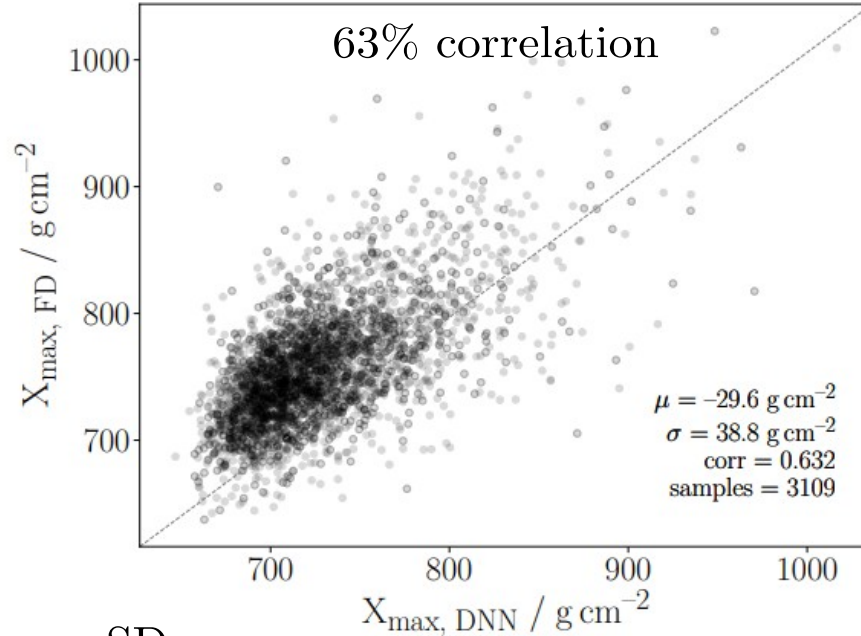
$$\left\langle \log \left\{ \left\langle \text{detector/model } P(\mathbf{y}|\mathbf{x}) \right\rangle_{\mathbf{x} \sim P(\mathbf{x}|\theta)} \right\} \right\rangle_{\mathbf{y} \sim P(\mathbf{y})} = \max \text{observed data}$$

Regression

Measured X_{\max}



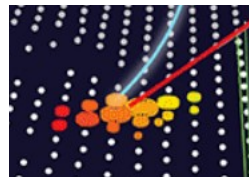
FD



Events with both
SD and FD data

Surface
detectors
data

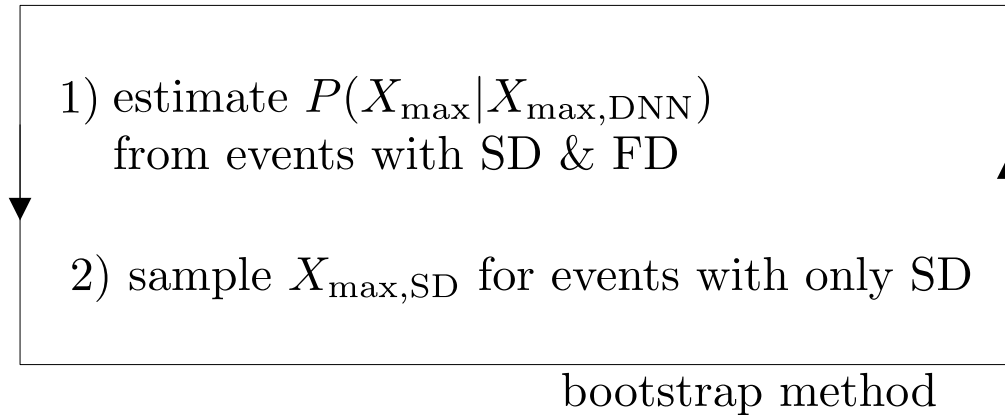
SD



\rightarrow DNN $\rightarrow X_{\max, \text{DNN}}$

Regression

How do we use predicted $X_{\max, \text{DNN}}$?

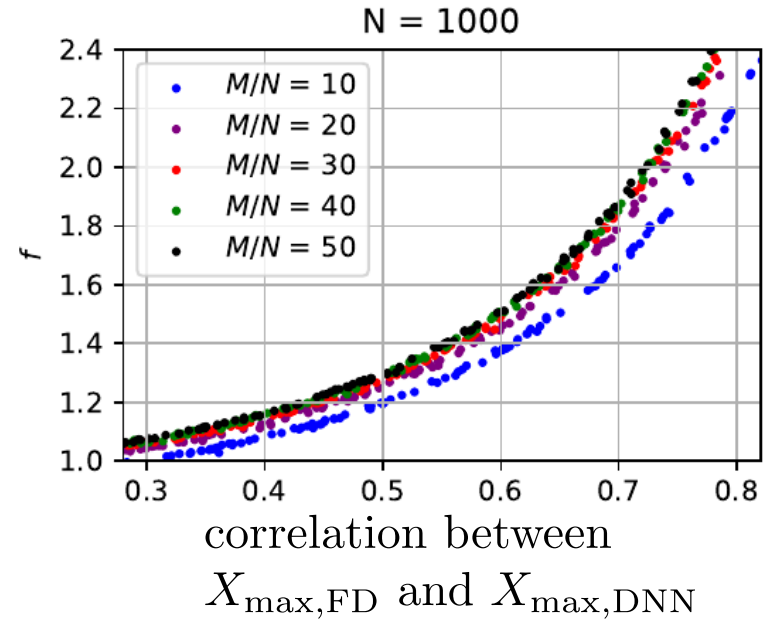


Measure of statistical power:

$$f = \frac{\text{Var}(\overline{X_{\max}^{\text{FD}}})}{\text{Var}(\overline{X_{\max}^{\text{FD+SD}}})}$$

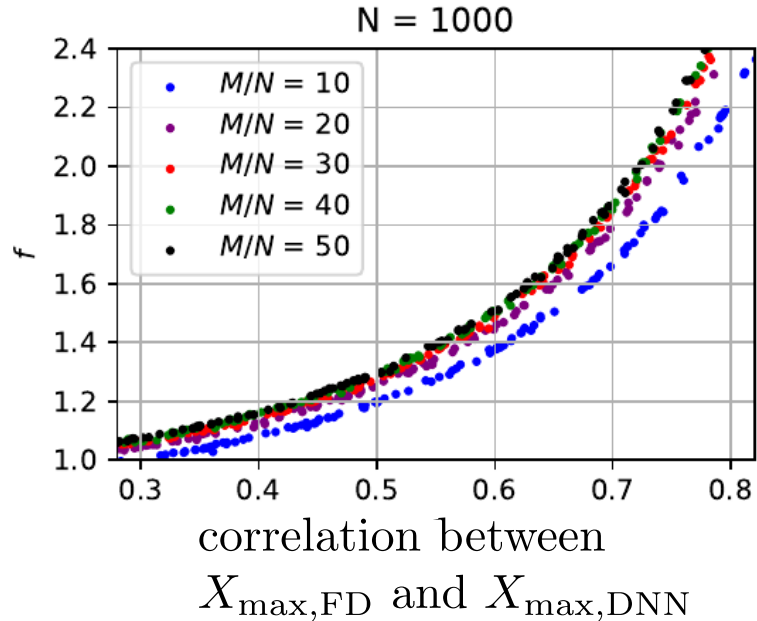
variance of the mean of $\{X_{\max, \text{FD}}\}$

variance of the mean of $\{X_{\max, \text{FD}}\} \cup \{X_{\max, \text{SD}}\}$



Regression

$$f = \frac{\text{Var}(\overline{X_{\max}^{\text{FD}}})}{\text{Var}(\overline{X_{\max}^{\text{FD}+\text{SD}}})}$$



Events with
FD and SD data
(~ 200 events)

Events with
ONLY SD data
(22000 events)

X_{\max}

$X_{\max} \sim P(X_{\max} | X_{\max,\text{DNN}})$
(large uncertainties)

Effectively > 200 events
with FD and SD

If correlation $|\rho(X_{\max}, X_{\max,\text{DNN}})| \sim 75\%$,
 2×200 events with FD and SD

Summary

- Progress on inferring the composition of UHECR
 - composition for 26 primaries with 95% confidence level
 - classification of primaries based on X_{\max}

→ Applications of the method

- unbiased solution to the unfolding problem
- removing bias on trained classifiers

(work in progress)

observed data $P(\mathbf{y}) = \int$ detector/model $P(\mathbf{y}|\mathbf{x})$ Goal $P(\mathbf{x}) d\mathbf{x}^n$

- Statistical power on predictions of a regression model



Thanks!

Cosmic Rays

What are made of?

e^+ , p^- , e^- , p^+ , stable atomic nuclei (H, He,..., Fe)

Typical sources

- gamma-ray bursts
- active galactic nuclei
- supernovae

	solar system	galactic sources	extra-galactic sources
Source			
Flux		$\lesssim \frac{1 \text{ event}}{m^2 \cdot \text{year}}$	$\frac{1 \text{ event}}{(km)^2 \cdot \text{year}}$
Energy [GeV]	$\lesssim 10^3$	$10^3 - 10^8$	$> 10^8$

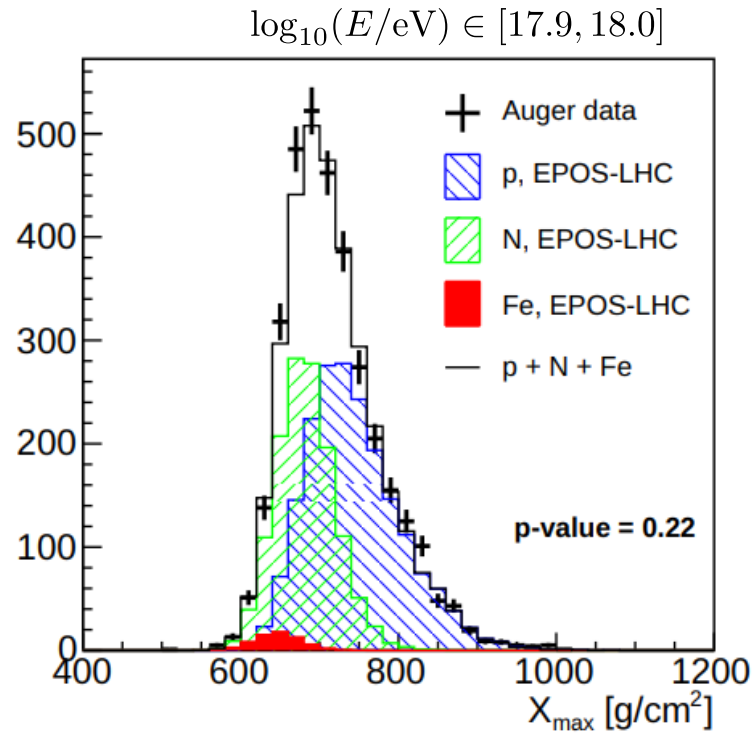
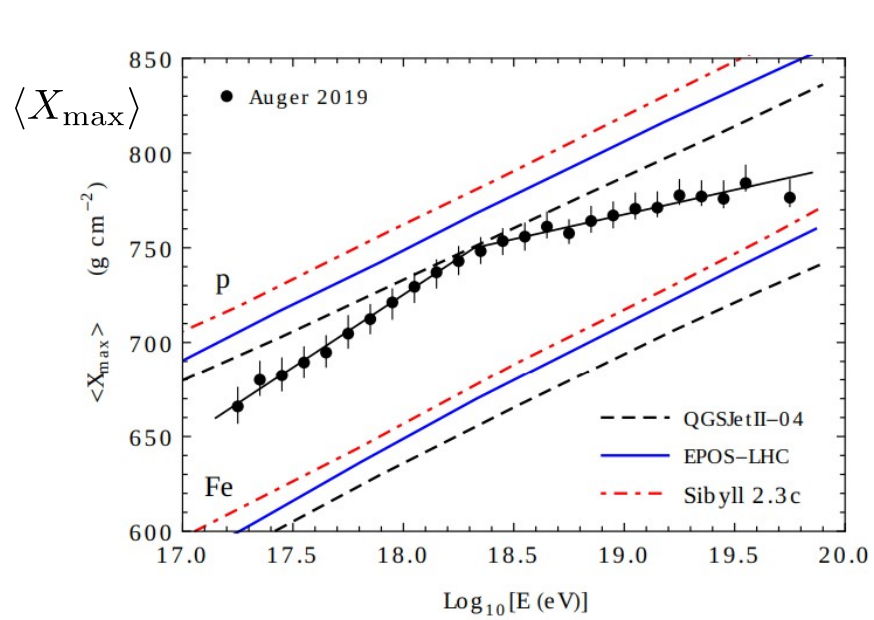
This talk

Ultra High-Energy
Cosmic Rays (UHECR)

$$E \sim 10^9 \text{ GeV}$$

$$E \sim 1 \text{ EeV}$$

Composition from literature

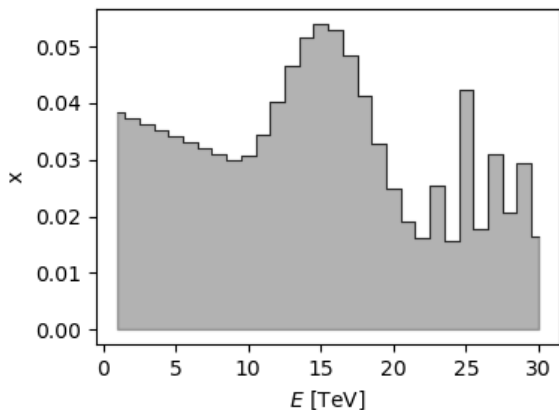


$w_p \sim 60\%$
 $w_{He} \sim 0$
 $w_N \sim 35\%$
 $w_{Fe} \sim 5\%$

Likelihood(w) $\sim \prod_{bin}$ Poisson distribution
 $w = \text{argmax}(\text{Likelihood})$

Unfolding problem 1/2

True distribution of events



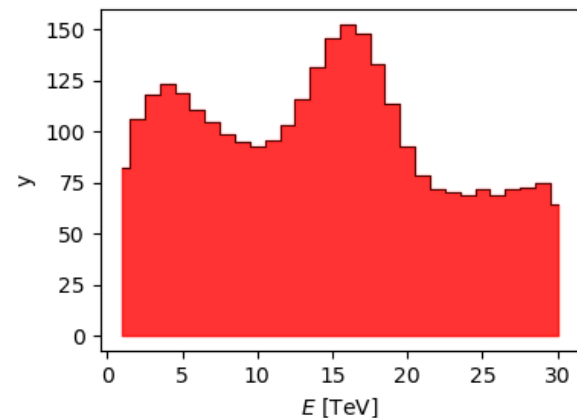
Detector measures

$$\mathbf{y} = (y_1, \dots, y_m)$$

given original values:

$$\mathbf{x} = (x_1, \dots, x_n)$$

Observed number of events



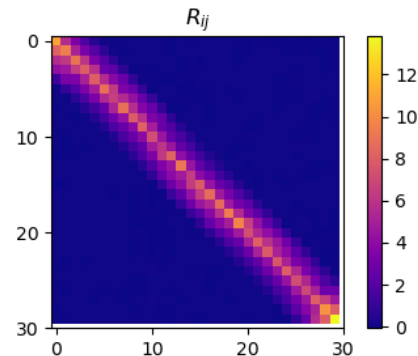
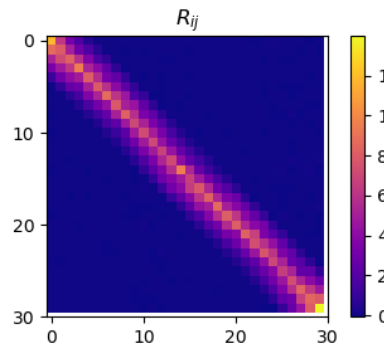
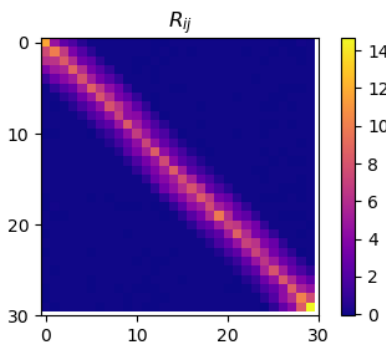
Assume detector response $P(\mathbf{y}|\mathbf{x})$ can be modeled as:

$$y_k = N_y \sum_j R_{kj} x_j$$

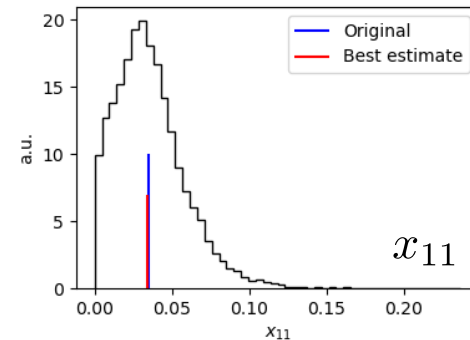
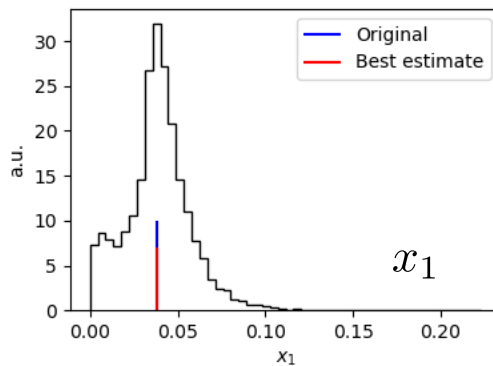
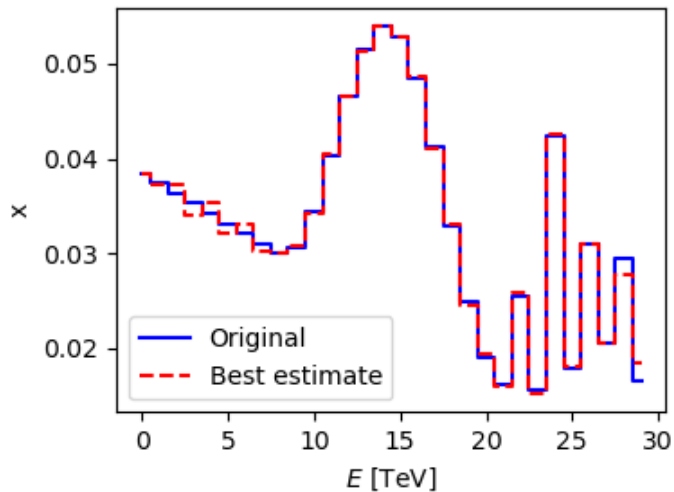
$$R_{kj} = \bar{R}_{kj} + \delta R_{kj} \epsilon$$

$$\epsilon \sim \mathcal{N}(0, 1)$$

R - response matrix



Unfolding problem 2/2



$$x^{\text{best estimate}} = \operatorname{argmax} \log L(x)$$

$$\log \left(\frac{L(\mathbf{x}^{\text{original}})}{L(\mathbf{x}^{\text{best estimate}})} \right) \approx 0.0047$$

