

# Removing negative weights in Monte Carlo event samples

Andreas Maier



14 November 2023

J. R. Andersen, A. Maier, D. Maître [Eur.Phys.J.C 83 \(2023\) 9, 835](#)

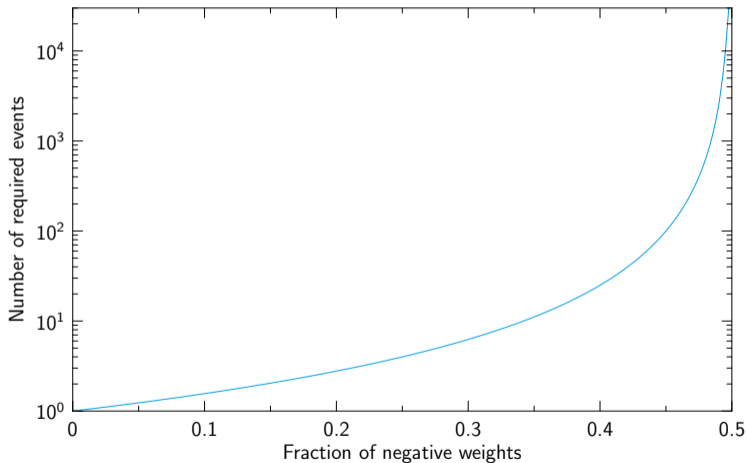
J. R. Andersen, A. Maier [Eur.Phys.J.C 82 \(2022\) 5, 433](#)

J. R. Andersen, C. Gütschow, A. Maier, S. Prestel [Eur.Phys.J.C 80 \(2020\) 11, 1007](#)

+ ongoing work with Ana Cueto, Stephen Jones

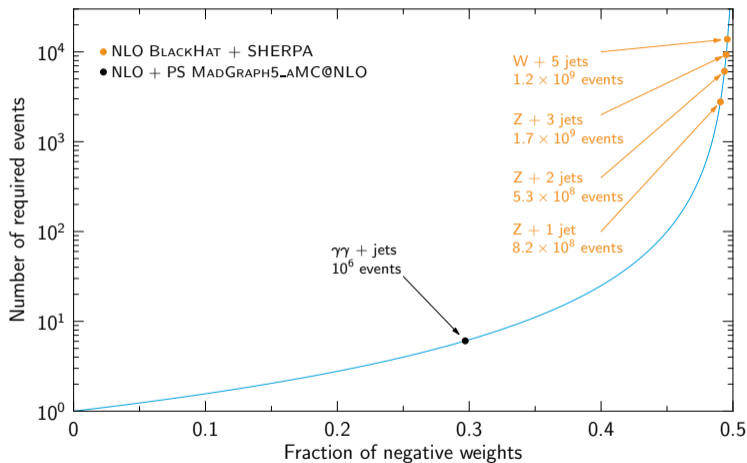
## Why are negative event weights a problem?

Number of unweighted events to reach given accuracy:



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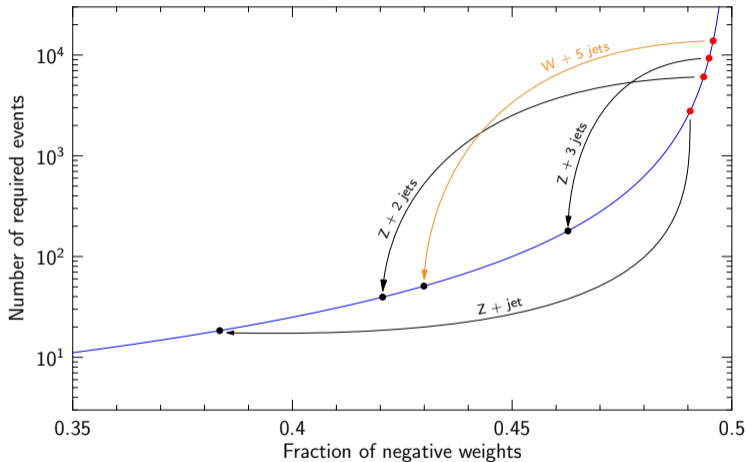


V + jets: [Phys. Rev. D 88 \(2013\) 014025](#), [Phys. Rev. D 97 \(2018\) 096010](#)

$\gamma\gamma$  + jets: parameters from background modelling for ATLAS  $H \rightarrow \gamma\gamma$  measurement [arXiv:2306.11379](#)

# Cell resampling for V + jets at NLO

## Negative weights

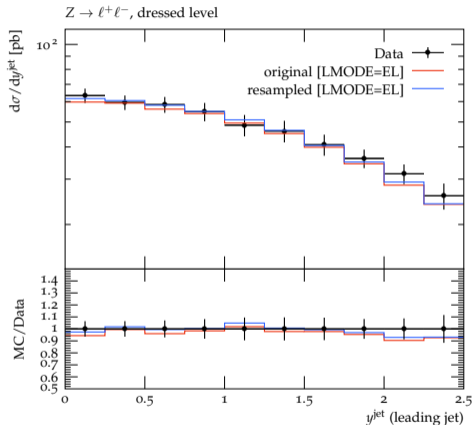
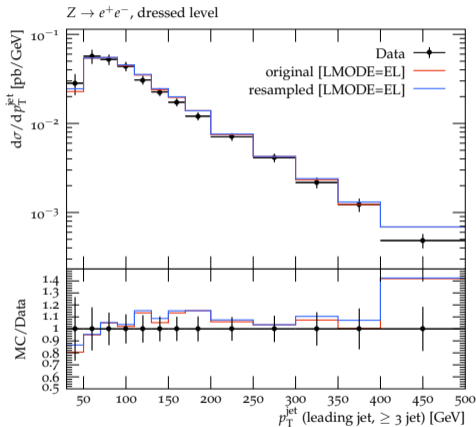


Cell resampling drastically reduces the number of required events

# Cell resampling for V + jets at NLO

## Predictions

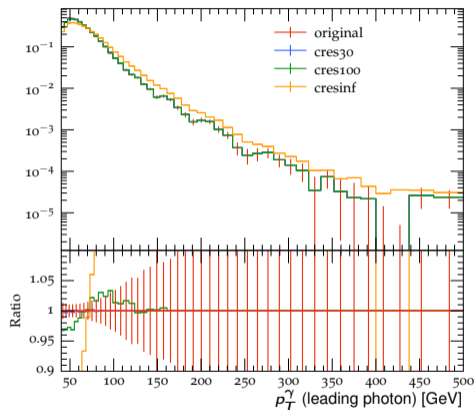
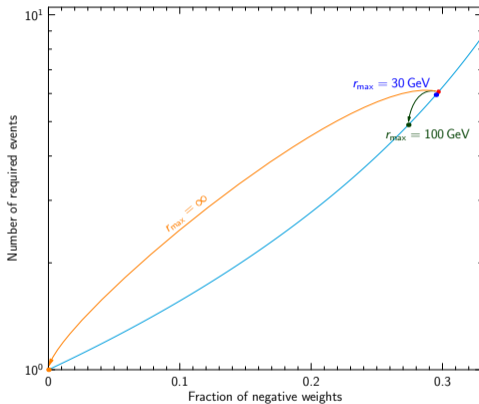
Analysis from *ATLAS*, *Eur. Phys. J. C77* (2017) 361:



Cell resampling preserves predictions within a few per cent

# Work in progress: showered samples

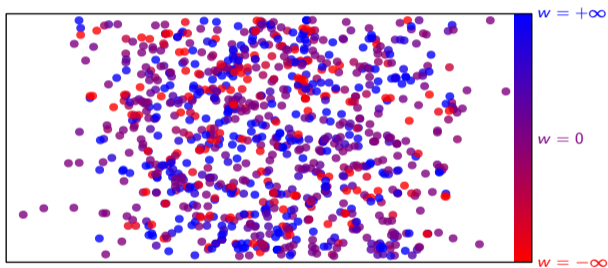
$pp \rightarrow \gamma\gamma + \text{jets}$ ,  $10^6$  events:



Expect more efficient negative-weight reduction for larger sample

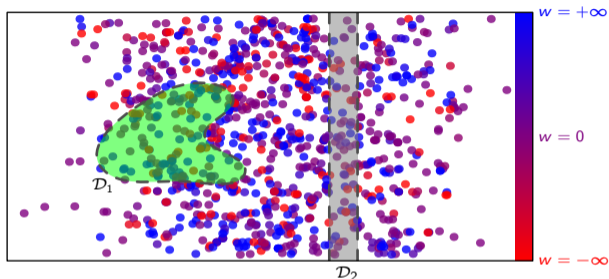
# Observables

Weighted events in 2D projection of phase space:



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Observables  $\mathcal{O}$ :

- Select region  $\mathcal{D}$  in phase space  $\geq$  experimental resolution
- $\mathcal{O} = \sum_{i \in \mathcal{D}} w_i \geq 0$  with sufficient statistics

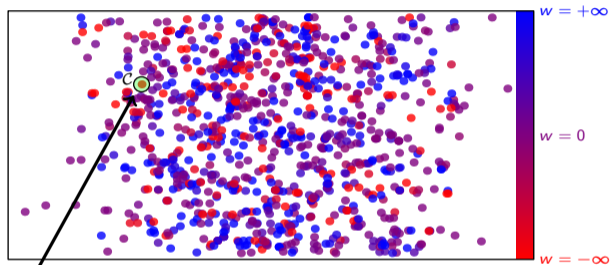
e.g. histogram bins

Redistribute weights without affecting any observable



# Cell resampling

[Andersen, Maier 2021]

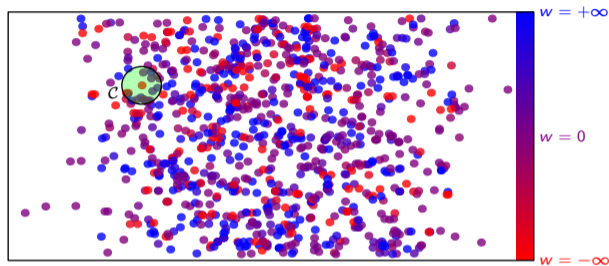


Cell resampling:

- 1 Choose seed event with negative weight for cell  $C$

# Cell resampling

[Andersen, Maier 2021]



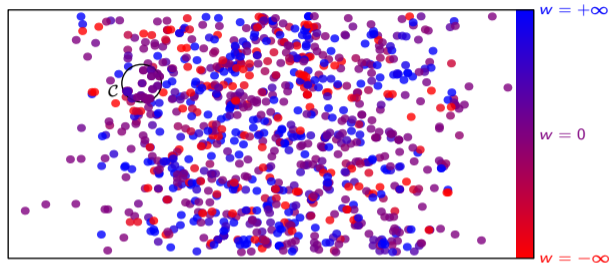
Cell resampling:

- 1 Choose seed event with negative weight for cell  $\mathcal{C}$
- 2 Iteratively add nearest event to cell until  $\sum_{i \in \mathcal{C}} w_i \geq 0$  or radius exceeds  $r_{\max}$

Cells get systematically smaller with increasing statistics

# Cell resampling

[Andersen, Maier 2021]

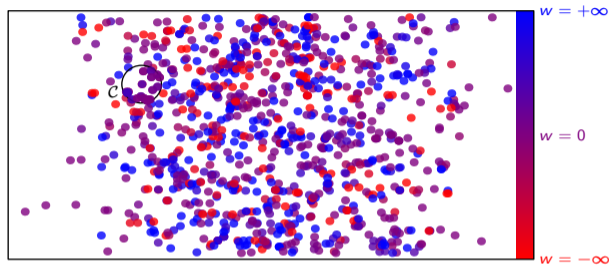


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- 4 Repeat

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[Andersen, Maier 2021]



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What does “nearest” mean?

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# Distances in phase space

Criteria for distance function:

- **Small distance** between events that look **similar** in detector or differ only in properties the event generator can't predict
- **Large distance** between events that look **different** in detector

Define distance in terms of infrared & collinear safe objects, e.g. jets

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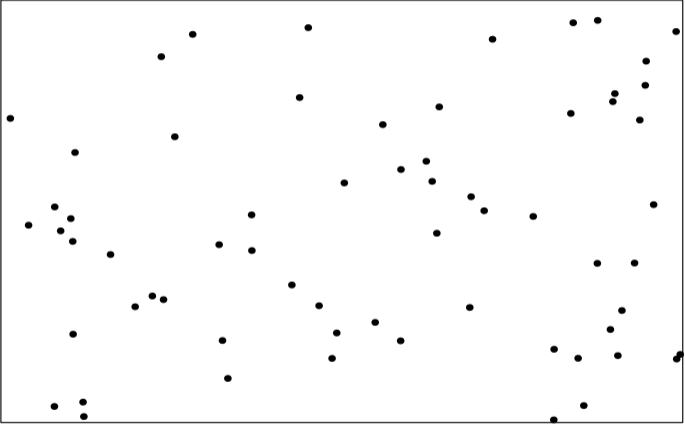
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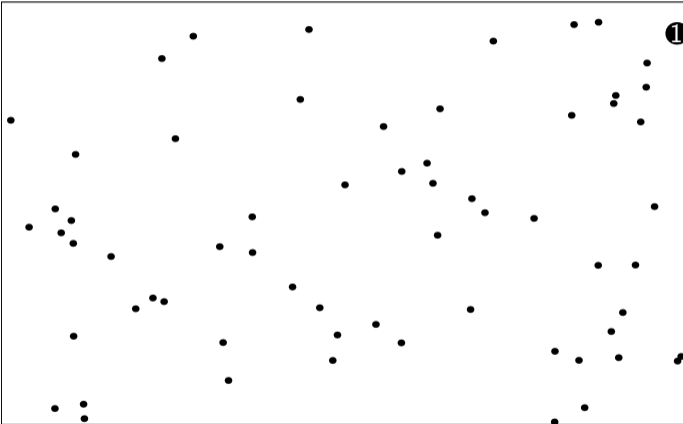
Current choice:

- 1 Find optimal pairing between observable objects in both events
- 2 Sum up spatial momentum differences

# Nearest-neighbour search



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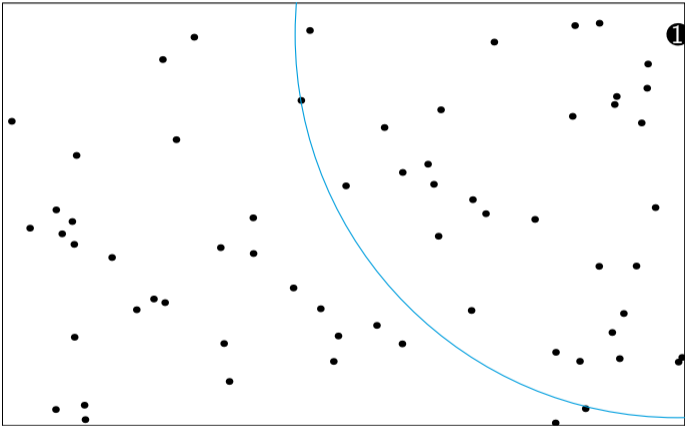


Vantage-point tree:





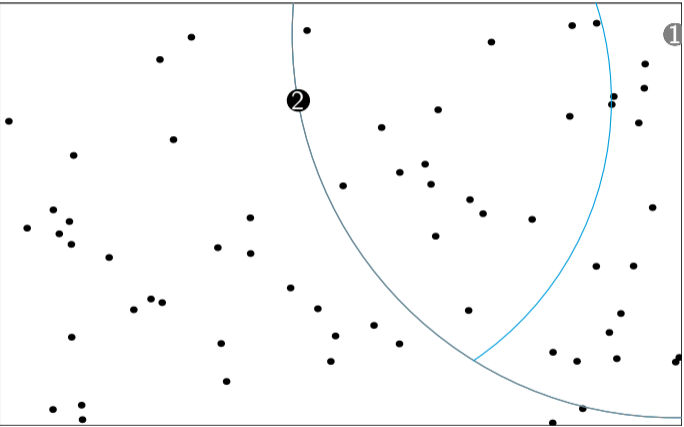
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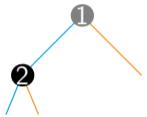
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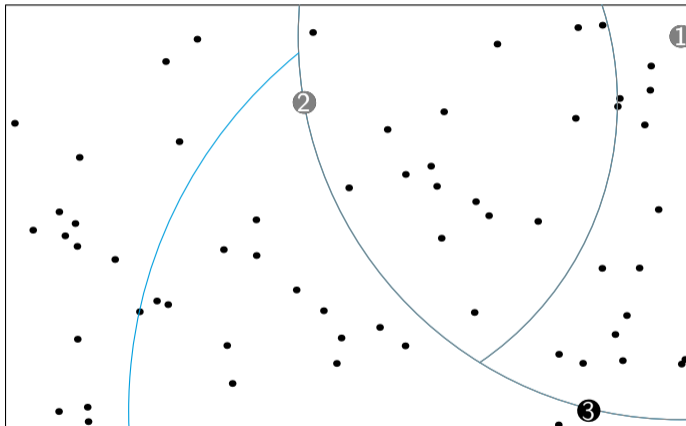
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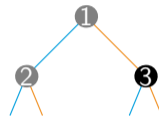
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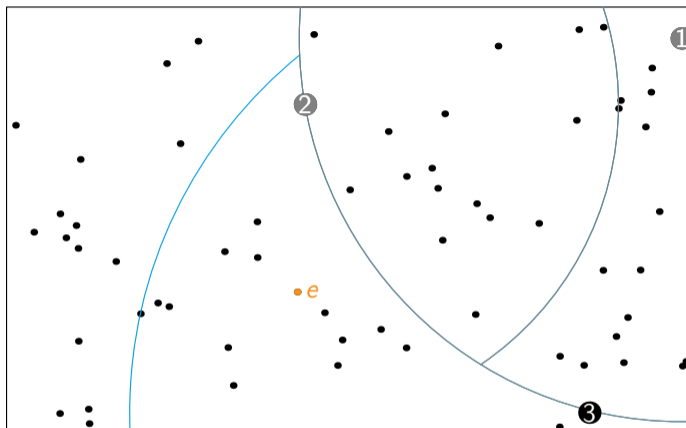
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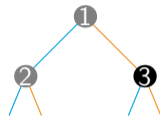
Vantage-point tree:



# Nearest-neighbour search



Vantage-point tree:



Search nearest neighbour for  $e$ :

- Find candidate in region containing  $e$
- Search neighbouring regions only if better candidate may be found

# Computing requirements

## Memory

Fast + exact nearest-neighbour search: keep all events in memory

Need  $\sim$  (byte size of event) GB for  $\sim 10^9$  events

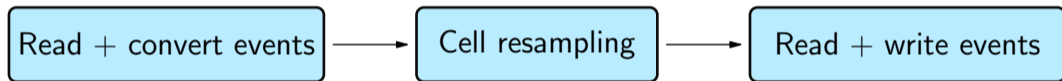
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Only store relevant event data: weights + momenta of outgoing analysis objects



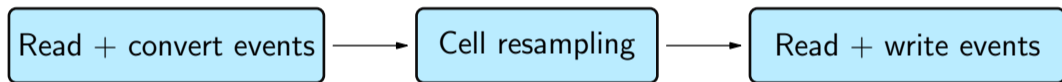
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Current requirements:

- Persistent event samples with reasonably fast sequential access
- 300 GB to 400 GB of memory per  $10^9$  events, no huge increase from showering expected

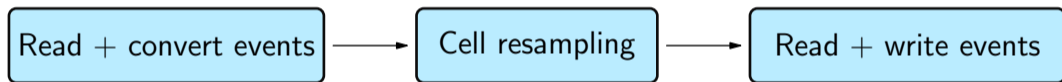
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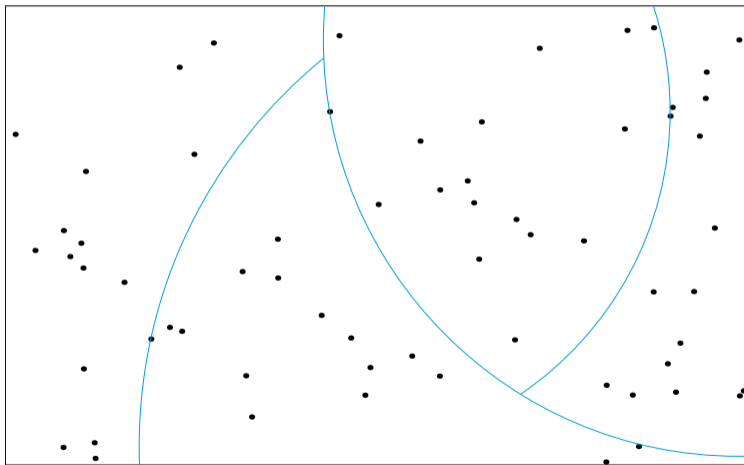
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Can we go beyond  $\sim 10^9$  events?



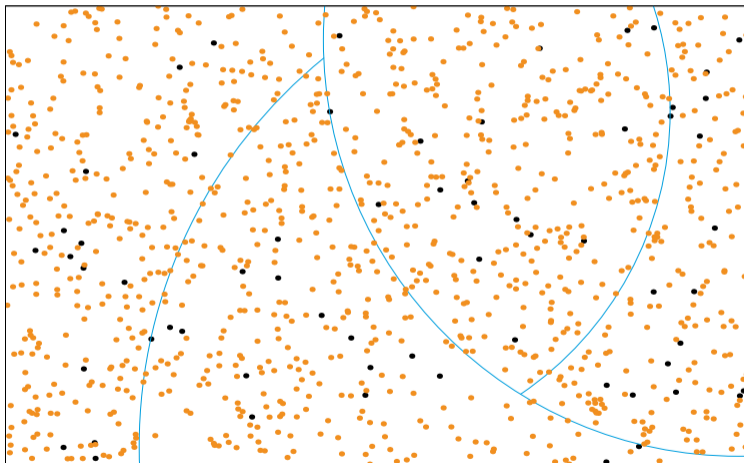
# Work in progress: memory efficiency

- 1 Partition phase space using vantage-point tree from [small event sample](#)



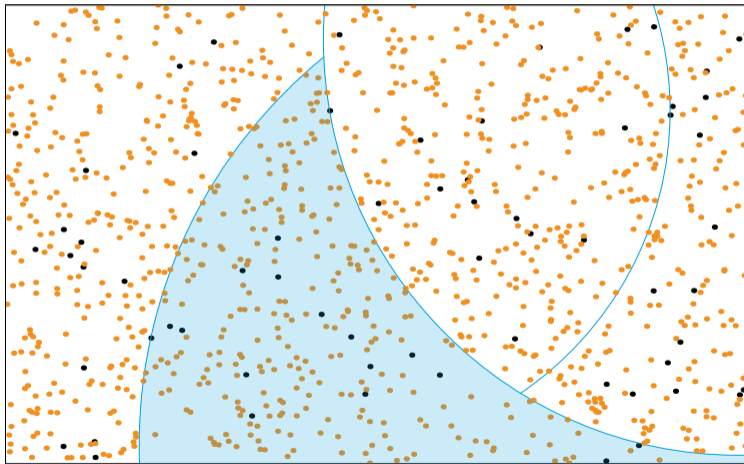
# Work in progress: memory efficiency

- 2 Identify region for each event in large sample



# Work in progress: memory efficiency

- 3 Independent cell resampling for each region



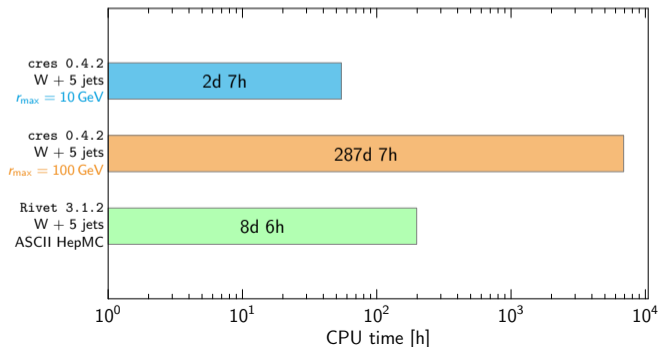
# Computing requirements

## CPU time

Benchmark machines:

# Cores	CPU model	Memory	Age
20	XEON E5-2640 @ 2.40GHz	400GB	~7 years
12	XEON E5-2643 @ 3.40GHz	800GB	~6 years

Local rotating disks, RAID 6



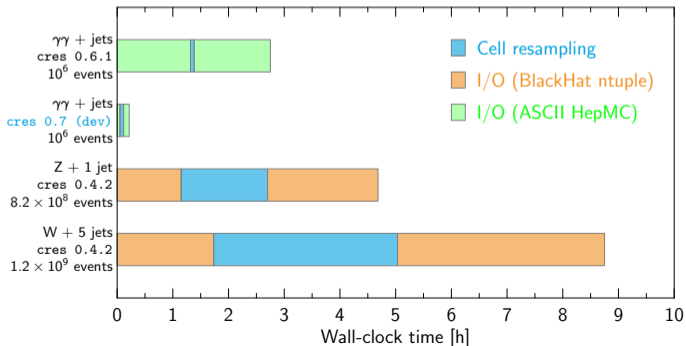
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## Wall-clock time

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# Summary

Current status:

- Remove event weights by smearing over small phase space regions
- Ready for large high-multiplicity samples
  - ▶ Computationally efficient:  $\sim 55$  CPU hours for one billion events ( $W + 5$  jets)
  - ▶ Significant memory requirements: 300 GB to 400 GB
  - ▶ Needs persistent event records
  - ▶ Work in progress: distribution over several nodes
- Proof of concept: showered samples

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## Wishlist:

- Adoption & integration into existing workflows
  - ▶ Support more event file formats?
  - ▶ Definitions of observable objects: flavoured jets, isolated photons, ...
  - ▶ Internal Monte Carlo optimisation  $\leftrightarrow$  MCMULE
  - ▶ ...
- Explore design space
  - ▶ Other distance measures, guided by detector sensitivities
  - ▶ Other prescriptions for redistributing weights
  - ▶ Further code optimisation?

# Backup

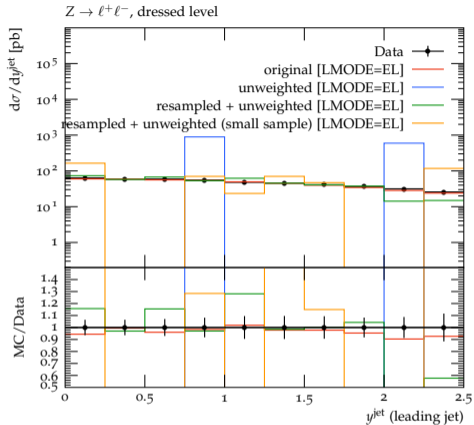
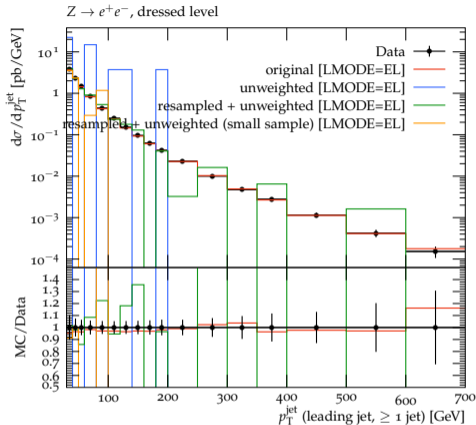


# Event samples

[BLACKHAT + SHERPA 2013 + 2017]

Sample	Process	Centre-of-mass energy	# events
Z1	$pp \rightarrow (Z \rightarrow e^+ e^-) + \text{jet}$	13 TeV	$8.21 \times 10^8$
Z2	$pp \rightarrow (Z \rightarrow e^+ e^-) + 2 \text{ jets}$	13 TeV	$5.30 \times 10^8$
Z3	$pp \rightarrow (Z \rightarrow e^+ e^-) + 3 \text{ jets}$	13 TeV	$1.65 \times 10^9$
W5	$pp \rightarrow (W^- \rightarrow e^- \nu_e) + 5 \text{ jets}$	7 TeV	$1.17 \times 10^9$

# Unweighting for Z + jet



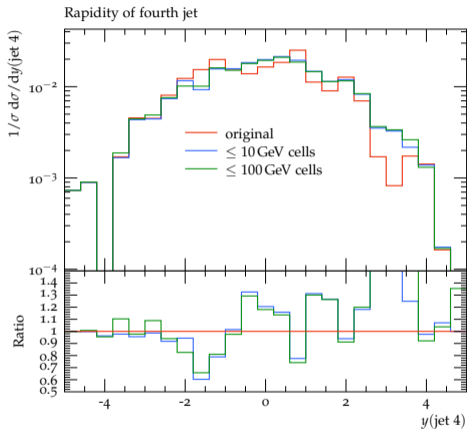
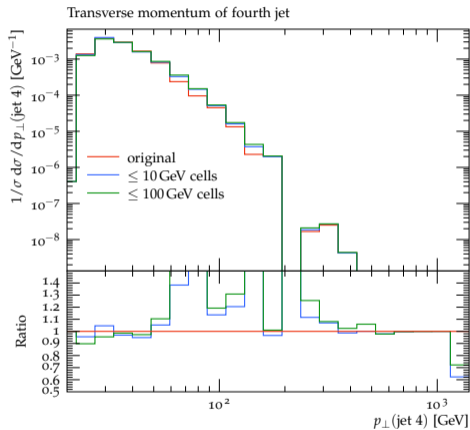
original:  $8.21 \times 10^8$  events

unweighted: 320 events

resampled + unweighted: 11574 events

resampled + unweighted (small sample): 320 events

# Resampling for W + 5 jets



## Distances in phase space

Need distance function  $d(e, e')$  between events  $e, e'$

- **Essential:**  $d(e, e')$  small  $\Rightarrow e, e'$  look similar in detector or differ only in properties the event generator can't predict
- **Desirable:**  $d(e, e')$  large  $\Rightarrow e, e'$  look different in detector

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Example: infrared safety

- $d(e, e')$  unaffected by collinear splittings with  $\Theta \rightarrow 0$
- $d(e, e')$  unaffected by soft particles with  $p \rightarrow 0$

$\Rightarrow$  define distance in terms of **infrared-safe physics objects**, e.g. jets

Here: Example for fixed-order (QCD) event generator

# Distances in phase space

## Concrete implementation

- ① Collect all infrared-safe objects in event  $e$  into sets  $\{s_1, s_2, \dots, s_T\}$

jets

electrons

$$d(e, e') = \sum_{t=1}^T d(s_t, s'_t)$$

# Distances in phase space

## Concrete implementation

jets                      electrons

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$$d(e, e') = \sum_{t=1}^T d(s_t, s'_t)$$

- 2 Objects in  $s_t$  have four-momenta  $(p_1, \dots, p_P)$

Objects in  $s'_t$  have four-momenta  $(q_1, \dots, q_Q, 0, \dots, 0)$



$$d(s_t, s'_t) = \min_{\sigma \in S_P} \sum_{i=1}^P d_t(p_i, q_{\sigma(i)})$$

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Efficient minimisation: [Hungarian algorithm](#) [Jacobi 1890]

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$$d(s_t, s'_t) = \min_{\sigma \in \mathcal{S}_P} \sum_{i=1}^P d_t(p_i, q_{\sigma(i)})$$

- 3 Choose distance function between particle momenta  
Here: independent of particle type  $t$ , do not consider internal structure

$$d_t(p, q) = \sqrt{(\vec{p} - \vec{q})^2 + \tau^2(p_{\perp} - q_{\perp})^2} \quad \tau: \text{tunable parameter}$$