

# Computer Algebra Challenges for Precision Calculations

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## Anatomy of precision calculations

#### • Perturbation theory expansion

- scattering amplitudes for real and virtual corrections
- subtraction scheme to extract and cancel singular configurations
- universal anomalous dimensions for resummation
	- DGLAP evolution of parton distributions
	- soft-gluon resummation
	- resummation of large logarithms:  $p_T$ , N-jettiness, R, ....

#### • Require (ideally analytic) computation of loop and phase space integrals

#### • Calculation of loop or phase space integrals

- phase space: cut loop integral
- expressed in generic loop integrals (here: two-loop)

$$
I_{t,r,s}(p_1,\ldots,p_n) = \int \frac{d^dk}{(2\pi)^d} \frac{d^dl}{(2\pi)^d} \frac{1}{D_1^{m_1} \ldots D_t^{m_t}} S_1^{n_1} \ldots S_q^{n_q}
$$

- Two challenges
	- algebraic complexity
		- reduce large number of loop integrals to smaller set of master integrals
	- analytic complexity
		- evaluate master integrals (analytically or numerically)

• Reduction to master integrals: integration-by-part (IBP) equations

 $\int d^d k$  $(2\pi)^d$  $d^d l$  $(2\pi)^d$  $\partial$  $\frac{\partial}{\partial a^{\mu}} [b^{\mu} f(k, l, p_i)] = 0$  with  $a^{\mu} = k^{\mu}, l^{\mu}; b^{\mu} = k^{\mu}, l^{\mu}, p_i^{\mu}$ *i*

- yield large system of linear relations among integrals (up to millions of equations)
- Method of solution
	- closed form
	- iterative with lexicographic ordering (Laporta algorithm: Reduze, FIRE, Kira, LiteRed,...)
- Result
	- generic integrals as linear combinations of a small number of master integrals

- Evaluation of master integrals
	- integrals are typically IR and/or UV divergent
- Direct numerical evaluation: sector decomposition (T.Binoth, G.Heinrich)
	- Partition of integration space into sectors of non-overlapping singularities
	- Laurent expansion of integrand

$$
(1-z)^{-1-\epsilon} = -\frac{1}{\epsilon}\delta(1-z) + \sum_{n} \frac{(-\epsilon)^n}{n!} \left(\frac{\ln^n(1-z)}{1-z}\right)_+
$$

- Numerical sector integrals: pySecDec, FIESTA
- Direct analytical evaluation: Mellin-Barnes, Feynman parameters
- Indirect analytical evaluation: differential equations

#### Multi-loop integrals  $\overline{\phantom{a}}$ *<sup>p</sup>*123⇠*p*<sup>12</sup> *p*3  $\Box$ Z d*<sup>d</sup>k*

- Differential equations for master integrals (A.Kotikov; E. Remiddi, TG) ⇠⇡*<sup>p</sup>*<sup>3</sup> *p*<sup>12</sup> (2⇡)*<sup>d</sup>* (2⇡)*<sup>d</sup> <sup>k</sup>*<sup>2</sup>*l*<sup>2</sup>(*<sup>l</sup> <sup>p</sup>*12)<sup>2</sup>(*<sup>k</sup> <sup>l</sup> <sup>p</sup>*3)<sup>2</sup> *.* (5.10)
	- differentiate integrand with respect to masses or momenta
	- apply IBP identities for the di↵erential equations are *s*<sup>123</sup> and *s*12. To illustrate the structure of the di↵erential equations, we



• integrate differential equations and match boundary conditions  $\epsilon$ <sub>o</sub> ace amerential equations and

- Systematic solution of DE
	- d-log form (J. Henn)
	- alphabet of process (letters = denominators)
	- iterated integrals
	- solutions: generalized polylogarithms (GPL)



$$
G(w_1,\ldots,w_n;z)=\int_0^z\frac{dt}{t-w_1}G(w_2,\ldots,w_n;t)
$$

- Requires
	- derivation of differential equations: IBPs
	- analytic expression for NxN matrix of differential equations for N masters  $T_{\rm t}$  second master integral can be obtained from this by analytic continuation of the hypergeometric continuation of the hypergeometric continuation of the hypergeometric continuation of the hypergeometric continuatio f diffe
	- optimized choice of master integrals: decoupling, diagonalization<br> *CERN code acceleration workshop* 16,11,2023

*s*<sup>123</sup>

• Main bottleneck: IBP equations

$$
I_{t,r,s}(p_1,\ldots,p_n) = \int \frac{d^dk}{(2\pi)^d} \frac{d^dl}{(2\pi)^d} \frac{1}{D_1^{m_1} \ldots D_t^{m_t}} S_1^{n_1} \ldots S_q^{n_q}
$$

- t: number of different propagators
- r: mass dimension of denominator ( $r \ge t$ )
- s: mass dimension of numerator
- Examples at current frontier:  $10^{6.7}$  integrals to  $10^{2.3}$  master integrals
	- three-loop  $2 \rightarrow 2$  amplitudes:  $4 \le t \le 10$ ,  $t \le r \le 10$ ,  $s \le 6$
	- four-loop OME for splitting functions:  $5 \le t \le 15$ ,  $t \le r \le 15$ ,  $s \le 6$
	- differential equations for master integrals: same  $(t,r)$ , typically  $s \leq 2$
- Combinatorial explosion of IBP system size

- Classical approach to IBP solutions: Laporta algorithm
	- IBP codes (Reduze, FIRE, Kira, LiteRed,...) use MPI for parallelization
	- run typically on multi-core machines with ~TB of RAM
	- distribute subsystems on different threads
	- limitations: memory usage per thread, interconnection of subsystems

#### • Algebraic complexity

- critically depends on number of scales (space-time dimension *d*, masses, invariants)
- large-scale algebraic simplifications at intermediate stages or as final step (polynomial arithmetic, using external tools: Fermat, Ginac, Symbolica)
- size of results (reduction tables, after simplification): can be TBs, insertion time-consuming

- Improvement to IBP reduction: syzygy equations (J.Gluza, D.Kosower, K.Larsen)
	- taming combinatorial growth: select IBP seed equations to always have  $r = t$
	- must derive syzygy equations for each integral topology: poor automation
- Finite field methods (A. von Manteuffel, R.Schabinger; T. Peraro)
	- solve IBP system for multiple integer values of *d*, masses and invariants (or subset)
	- perform integer arithmetic modulo some large number
	- full workflow can be done on finite field
	- reconstruct all rational coefficients in solution (FiniteFlow, Kira, FinRed)
- Challenges with finite field methods
	- point of reconstruction: IBP tables, integral coefficients, GPL coefficients
	- number of evaluations required for reconstruction and validation
	- inversion of rational matrices as task: could profit from novel computer architectures

- Limitation of algebraic approaches: number of mass scales (internal masses)
	- Complexity of IBPs and DEs (size of alphabet  $\sim$  number of possible kinematical cuts)
	- IBP reduction often not feasible, neither for amplitude nor for differential equation
- Numerical approach to IBP
	- IBP reduction and derivation of DE for each set of fixed numerical masses and kinematics
	- repeated for each phase space point (timing)
	- for symbolic *d*, truncated to finite terms in  $\varepsilon = (4-d)/2$
	- integer arithmetic
- Numerical approach to high-precision solutions to DE
	- solution by asymptotic series: DiffExp, SeaSyde (M.Hidding; T.Armadillo, R. Bonciani, S. Devoto, N. Rana, A. Vicini)
	- differential equations in complex mass parameter (Feynman +i $\delta$ ): AMFlow (x. Lui, Y.Q. Ma)

## Summary

#### Main bottleneck in calculation of loop amplitudes: solution of IBPs

- express loop amplitudes as linear combination of master integrals
- prerequisite for computation of master integrals from differential equations
- Task: solve large systems of linear equations with rational coefficients

#### Approaches

- symbolic solution: Laporta algorithm (+ syzygy) (+ finite field reconstruction)
- numerical solution: IBP and DE solution for each phase space point

#### Computing challenges

- problem size often memory and storage limited
- hardware solutions for large linear systems
- parallelization at different stages