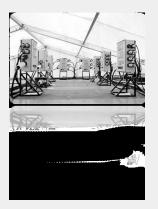


Designing Charge Pump Based Converters



Designing Charge Pump Based Converters



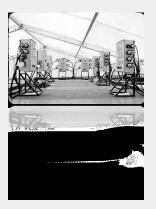
Advantages

No coils! Low EMI (if well designed) Fully integrated (if you only need a few luA) Digital control (when regulation is needed)

Disadvantages

Lower efficiency (if you need to regulate the output voltage) More switches and more silicon area Large inrush currents (if badly designed)





When to use?

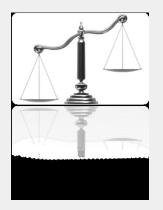
When you cannot use coils Extra silicon area is not a problem System has long standby periods Pins are available Output current range is medium 10 mA – 1 A*

Or

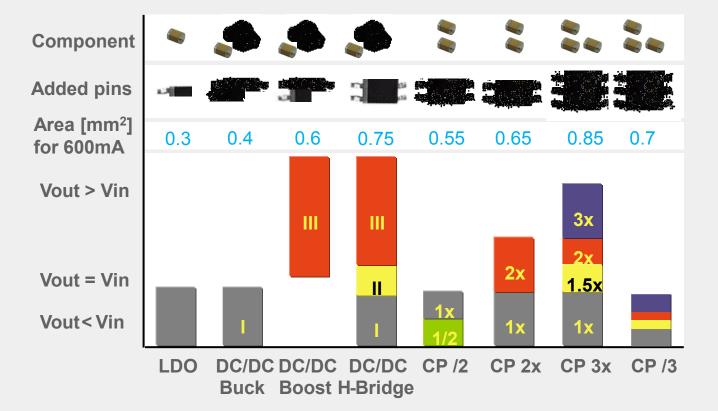
Fully integrated Small currents <100 uA

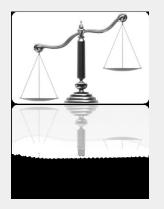
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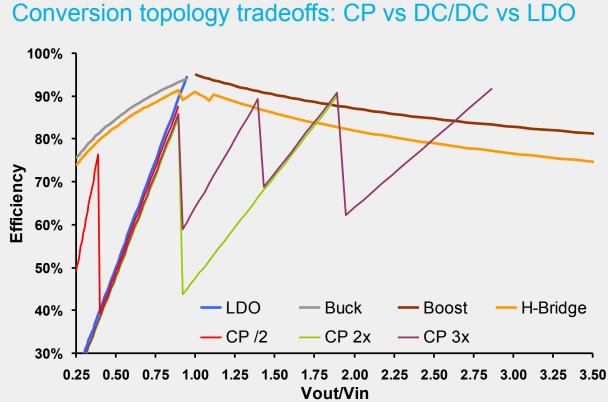




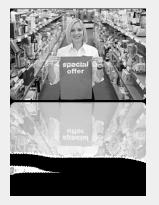






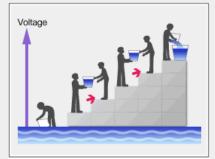


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In principle

Easy to understand Simple to design Very quick to develop



Working image of charge pump circuit (www.sii.co.jp)

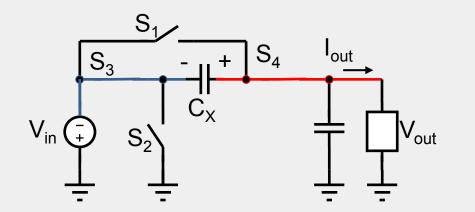
At the end

As complex as any engineer might like \bigcirc





In principle S_1 $V_{in} \xrightarrow{S_2}$ $V_{in} \xrightarrow{S_2}$ S_2 $V_{in} \xrightarrow{S_2}$ $V_{in} \xrightarrow{S_2}$ $V_{in} \xrightarrow{S_2}$



 $V_{out} = V_{cx} + V_{in} =$ =2. V_{in}

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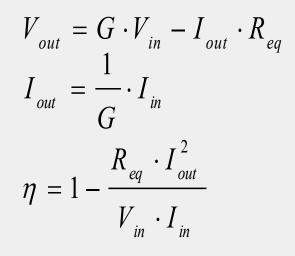
Ideally

Fixed voltage gain (G= 1/3, $\frac{1}{2}$, 2/3, 1x, 2x, 3x)

$$V_{out} = G \cdot V_{in}$$
$$I_{out} = \frac{1}{G} \cdot I_{in}$$
$$\eta = 100 \%$$

In reality

Looses so output voltage drops with load







Ideally

No voltage control

In reality

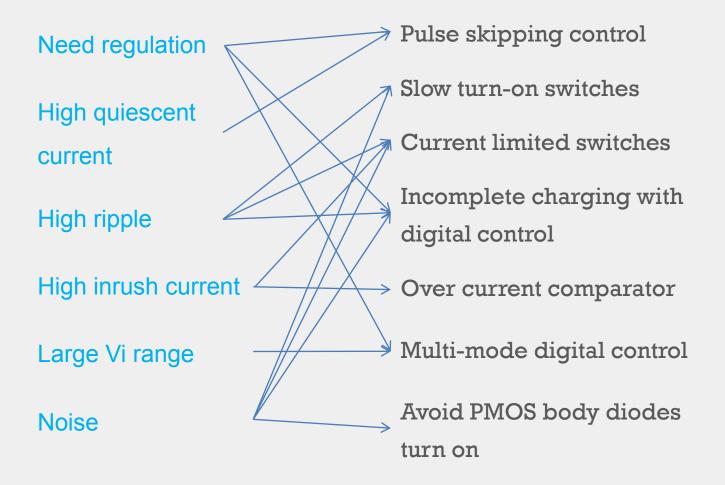
Voltage control is required (usually a system requirement and also pulse skipping reduces switching losses at light loads)

$$\begin{split} V_{out} &= G \cdot V_{in} - I_{out} \cdot R_{eq} \\ I_{out} &= \frac{1}{G} \cdot I_{in} \\ \eta &= 1 - \frac{R_{eq} \cdot I_{out}^2}{V_{in} \cdot I_{in}} \end{split}$$

$$\begin{split} V_{out} &= V_{prog} < G \cdot V_{in} - I_{out} \cdot R_{eq} \\ I_{out} &= \frac{1}{G} \cdot I_{in} \\ \eta &= \frac{V_{out}}{G \cdot V_{in}} \end{split}$$

CP PROB & SOL

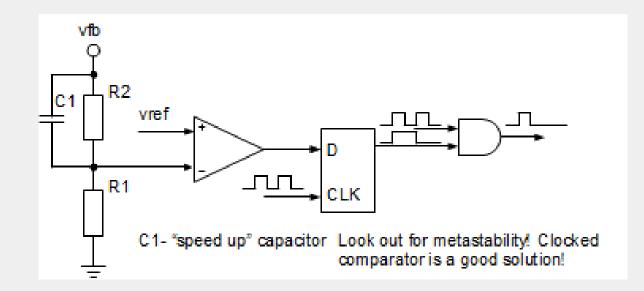




NEED REGULATION



Pulse skipping as simple as it gets ③

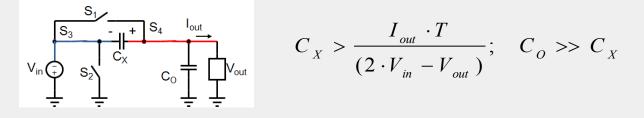


If you use this simple version you will probably get large ripple output!!

HIGH RIPPLE



As bad as it gets at full charge/discharge with regulation 😕



SILICONGATE

$$V_{ripple \ 1} \approx (2 \cdot V_{in} - V_{out \ n^{-1}}) \frac{C_X}{C_X + C_O}$$

$$V_{ripple} \approx (2 \cdot V_{in} - V_{out}) \frac{ESL_{CO}}{ESL_{CX} + ESL_{CO} + L_{bond}} >> V_{ripple \ 1}$$

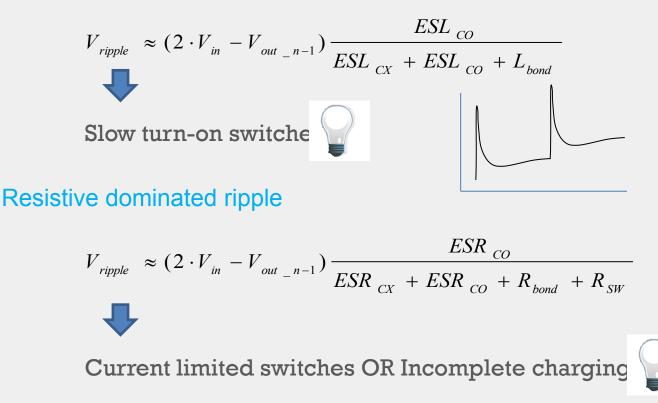
or

$$V_{ripple} \approx (2 \cdot V_{in} - V_{out}) \frac{ESR_{CO}}{ESR_{CX} + ESR_{CO} + R_{bond}} + R_{SW} \rightarrow> V_{ripple \ 1}$$

HIGH RIPPLE



Inductive dominated ripple

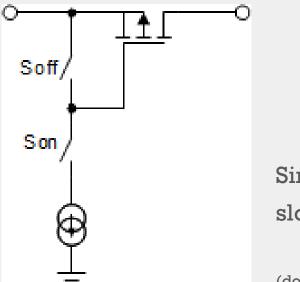


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SLOW TURN-ON SW



Good solution for inductive dominated ripple and EMI reduction



Simple but effective slow turn-on switch

(do not use ideal current sources)



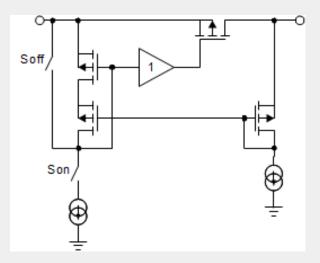




CURRENT LIMITED SW



Good solution for resistive dominated ripple and current limitation



Stability needs to be checked with bond wire and capacitor parasitic

Improves incomplete charging digital control (better solution than using Rdson or additional resistors to limit charging current)



With digital control

Simple

Effective

Lower ripple

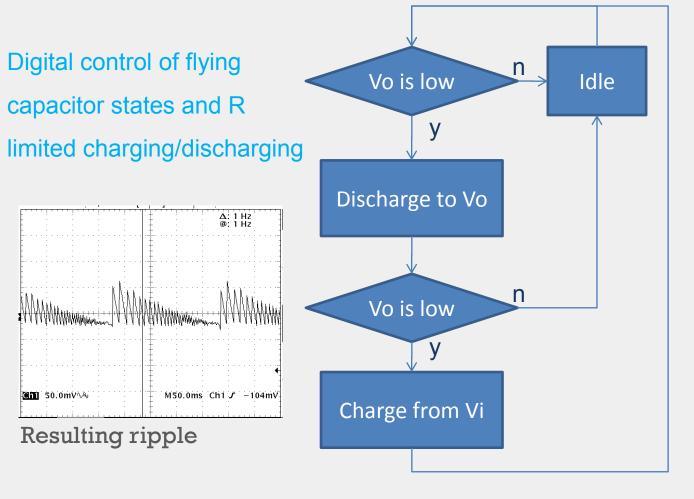
Maintains fast response to load transients

Requires larger flying capacitor

Requires some type of current limitation:

Rdson; additional R; current limited switches

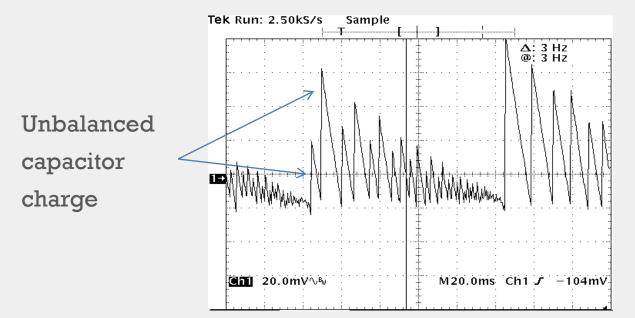




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Bad load balancing (CP with two flying capacitors)

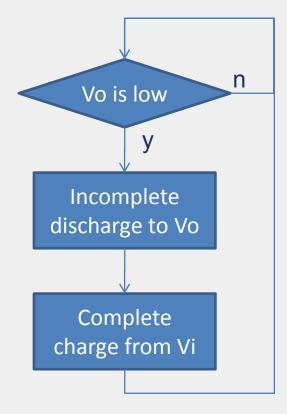


Simple solution: use complete charging on the flying capacitors and limit the discharge current for partial discharges



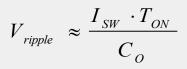
Improved control with limited discharge current ∆: 3 Hz @: 3 Hz 20.0mV M20.0ms Ch1 J -104mV

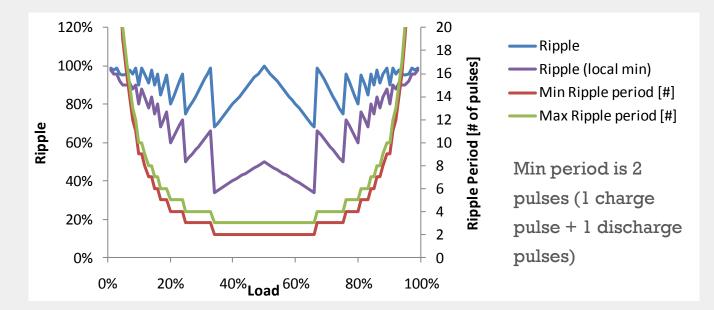
Resulting ripple





Improved control with limited discharge current

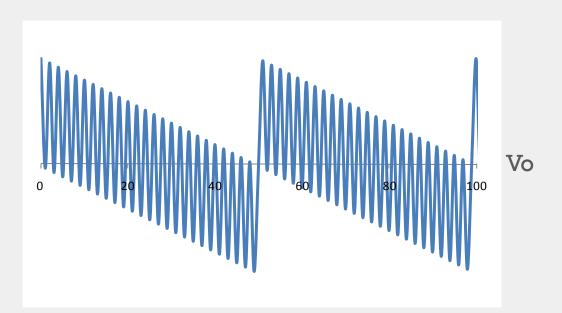




Plus the effects of Limit Cycle Oscillations



Limit Cycle Oscillations

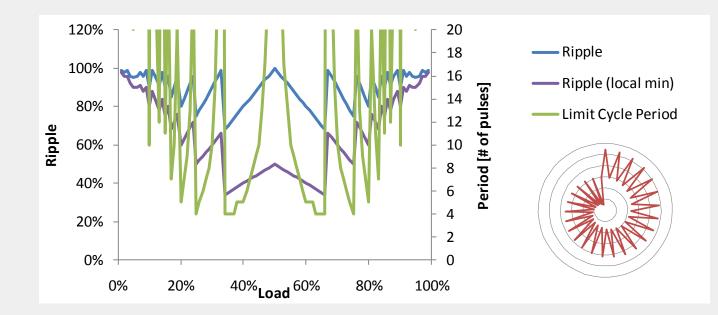


Same as for any other pulse skipping control...

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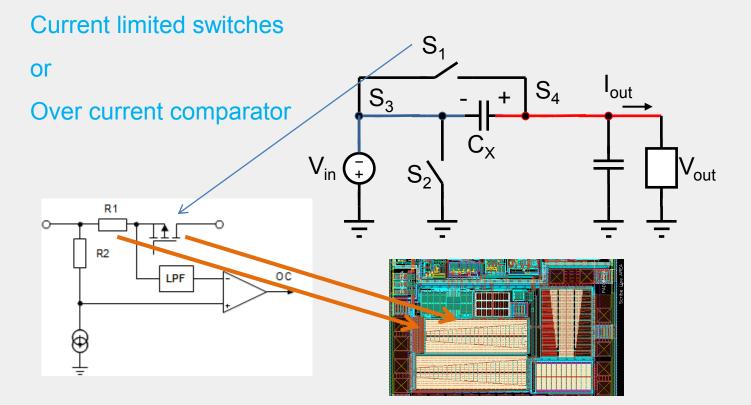


Limit Cycle Oscillations



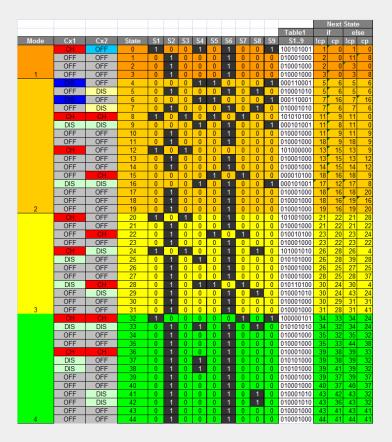
HIGH INRUSH CURRENT







LARGE VI RANGE

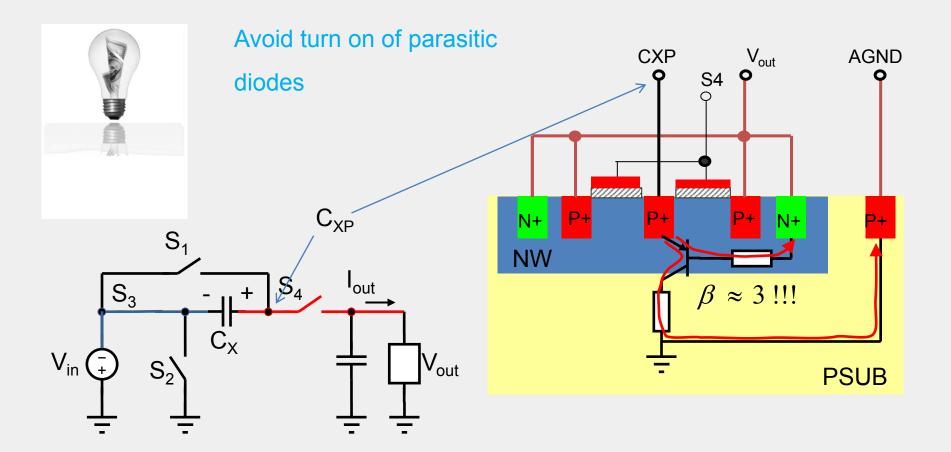


Multimode auto switching Lots of modes and conditions but simple digital implementation



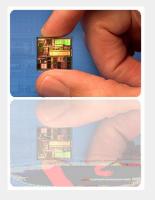


NOISE

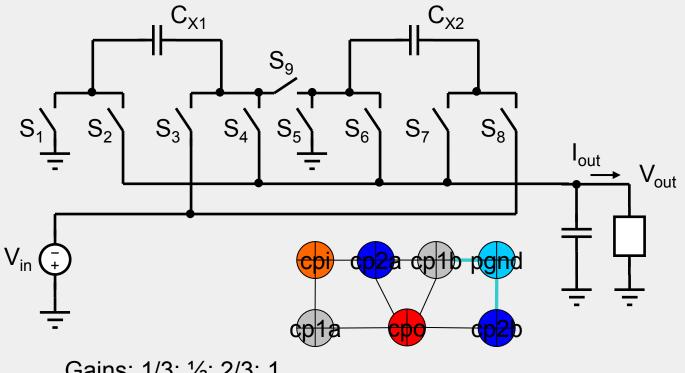




FRAC CP EXAMPLE

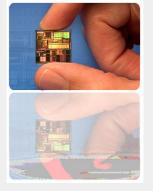


9 sw multimode topology

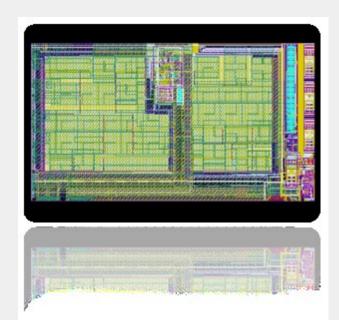


Gains: 1/3; 1/2; 2/3; 1

FRAC CP EXAMPLE



Layout



Fractionary CP

10 μ A consumption

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