

# EFT Measurements at the LHC

Markus Luty  
UC Davis/QMAP

S. Chang, M. Chen, D. Liu, ML, arXiv:2212.06215  
+ work in progress with S. Chang, T. Ma, A. Wulzer

# Big Picture

- The Standard Model is the most general UV complete theory with the observed elementary particle content
- All parameters of the SM have been determined at the percent level or better
- Any observed deviation from the SM
  - $\Rightarrow$   $\left\{ \begin{array}{l} \text{new light particles} \\ \text{new physics at high scales} \end{array} \right.$   $\leftarrow$  direct searches
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This talk:

- What are the observables that we want to measure?
- How should we measure/report them?

# Effective Field Theory

- Effects of high scale new physics can be parameterized by adding new effective interactions to the SM

# Effective Field Theory

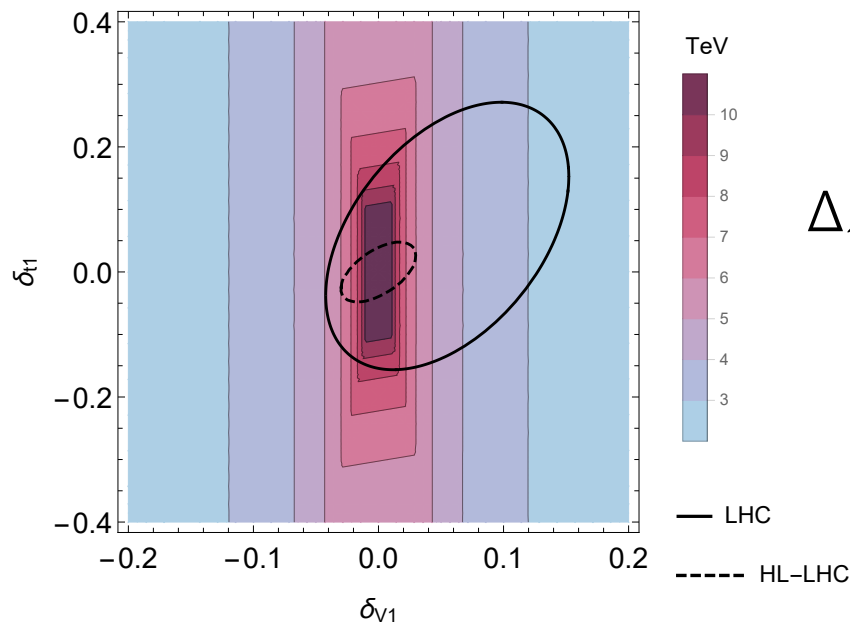
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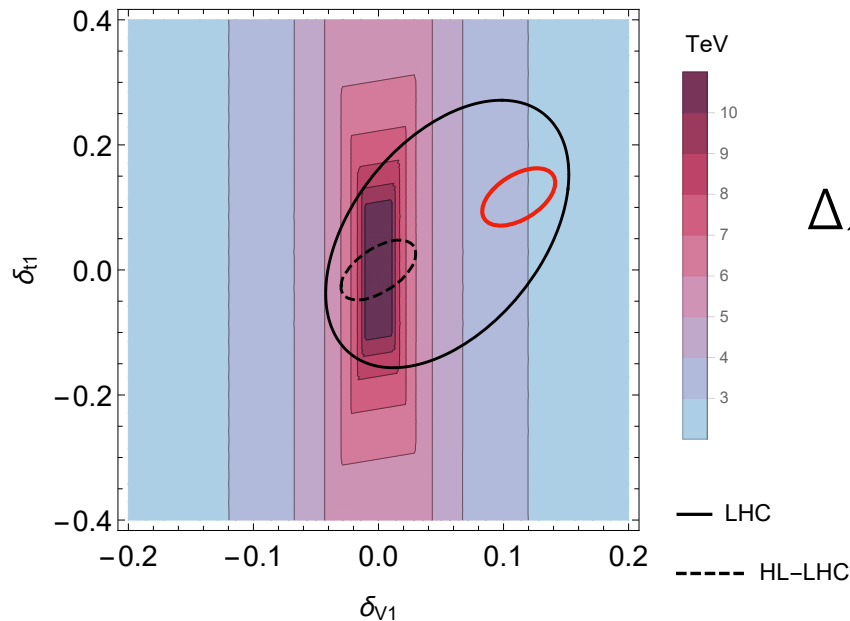


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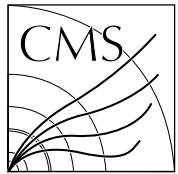
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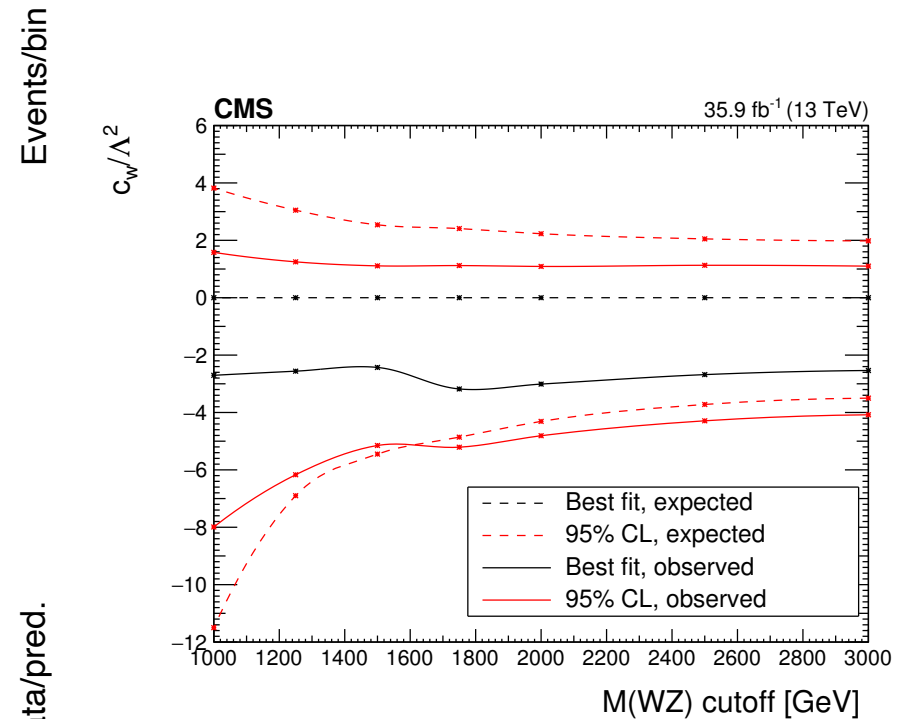
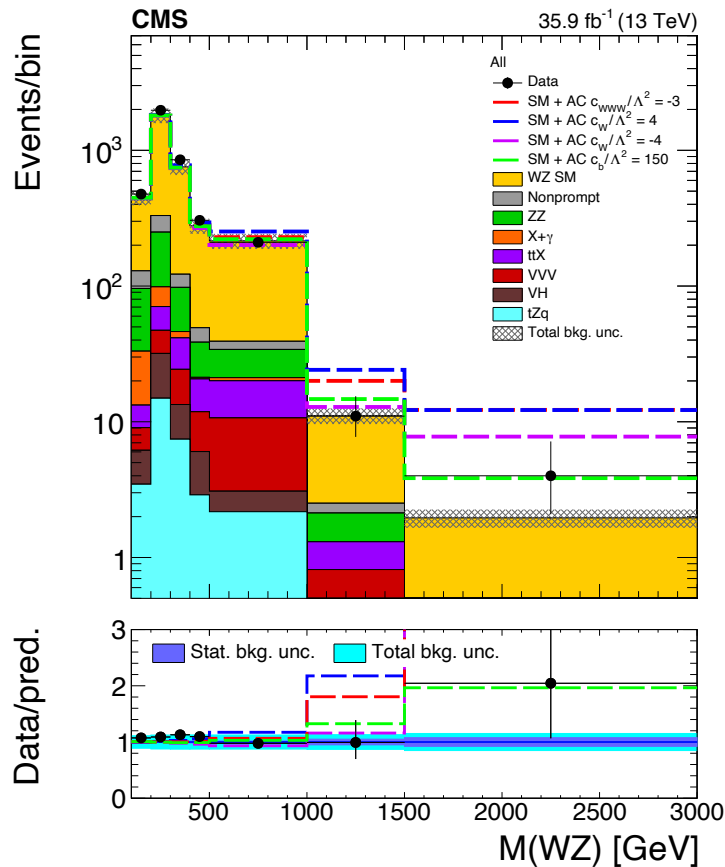
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# High Energy Signals

Exploit hardness of BSM contribution...  
...but beware of breakdown of EFT

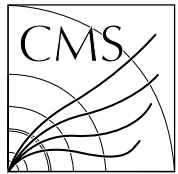


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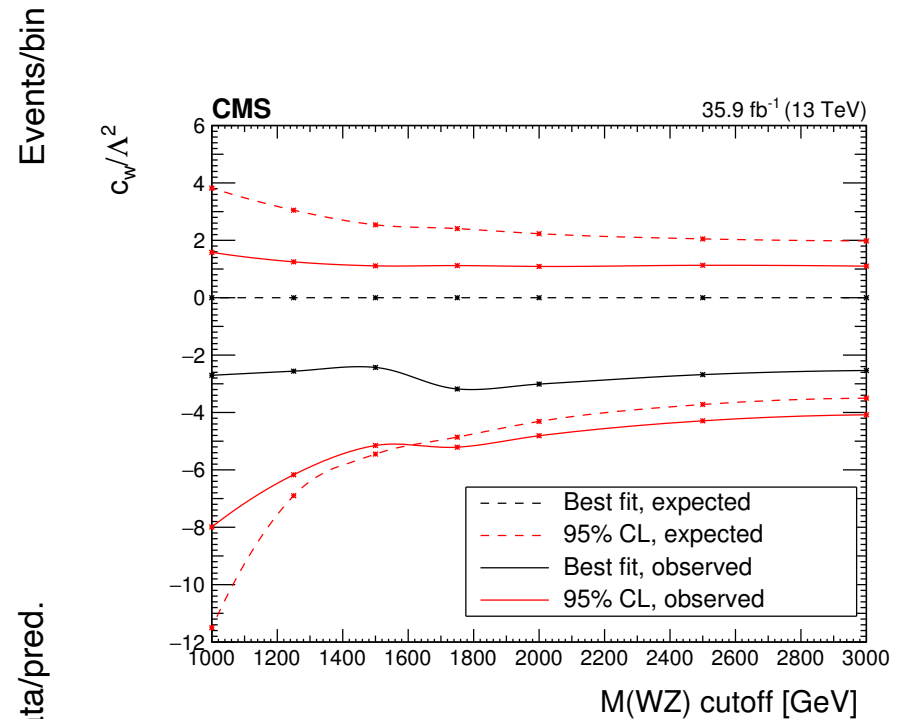
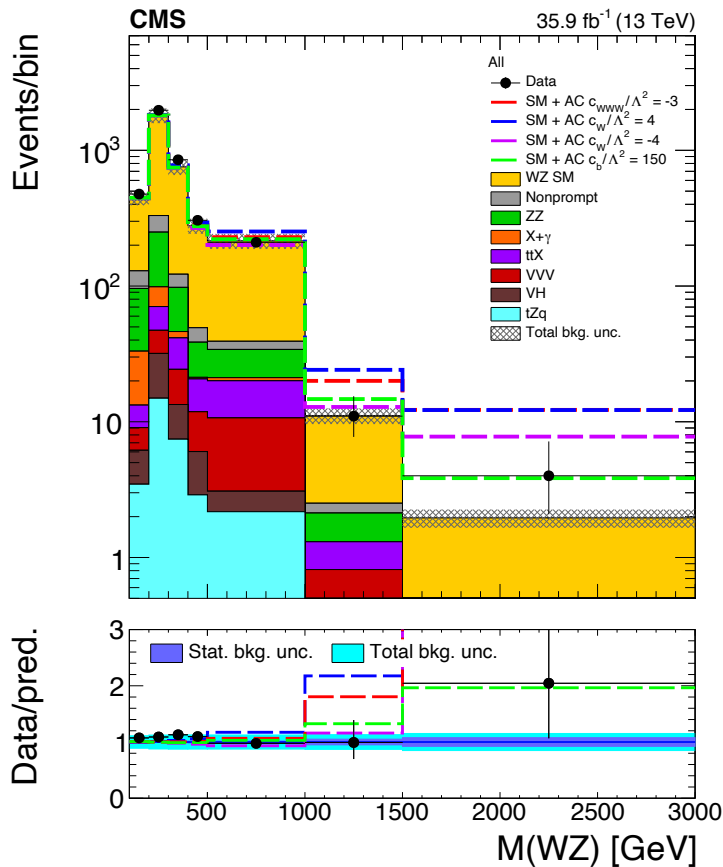


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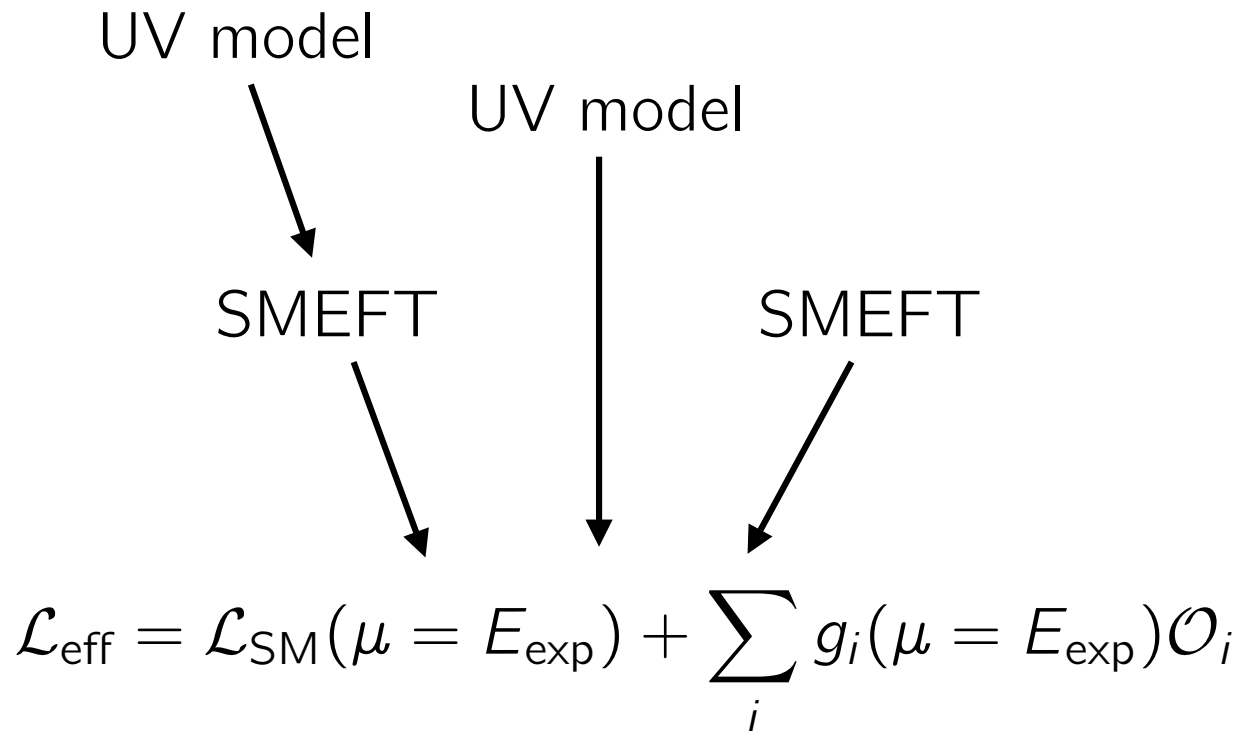


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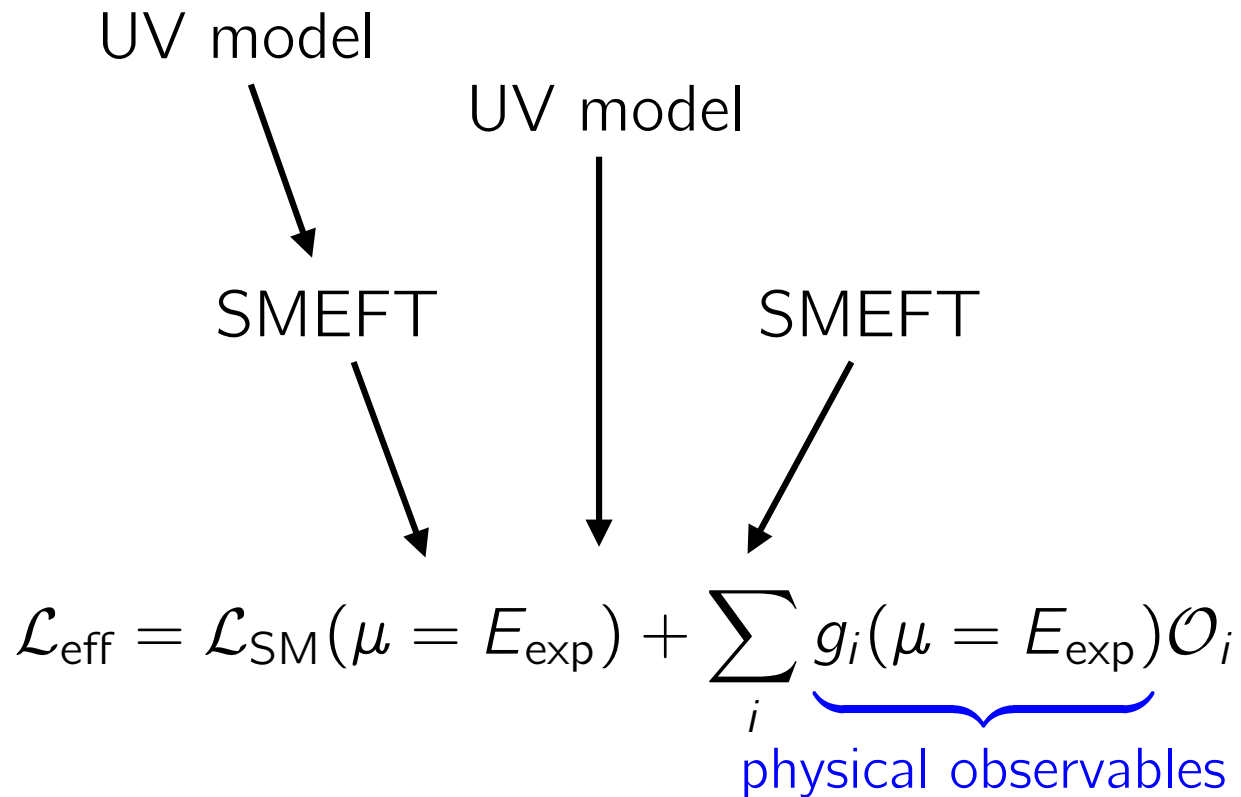
Can we be more systematic?

# On-Shell Approach



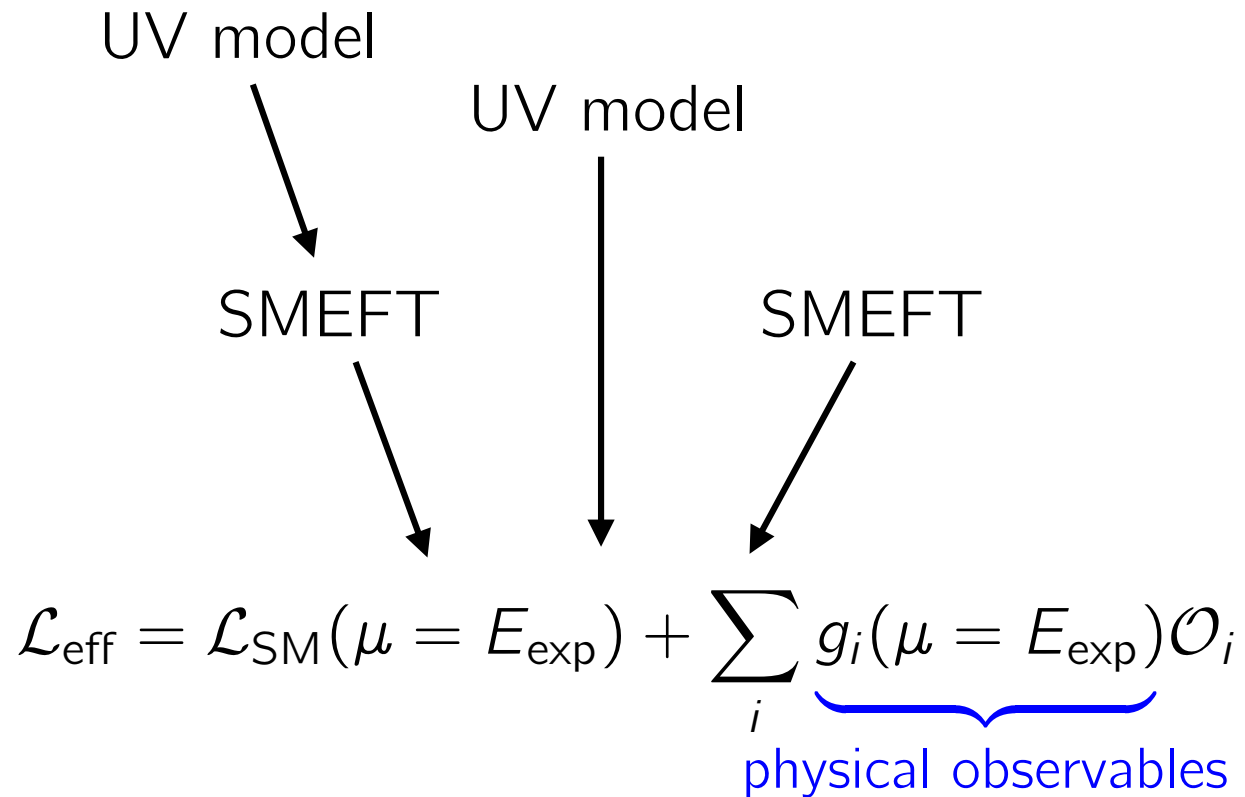
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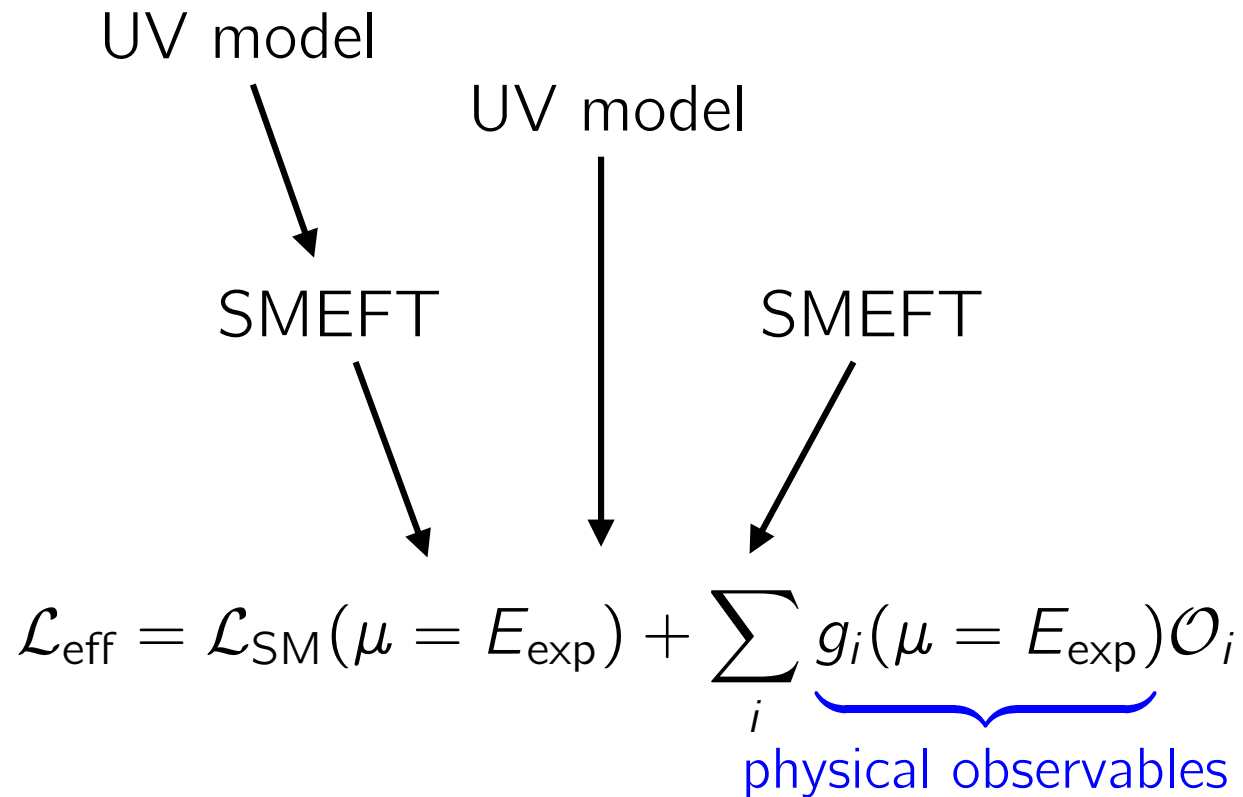
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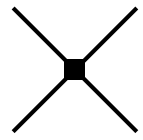
Classify:  $\mathcal{O}_i \leftrightarrow$  Feynman rules for on-shell particles

# Primary Observables

$$\times \quad \sum_i g_i \mathcal{O}_i^{(4)} = \sum_\alpha g_\alpha \mathcal{O}_\alpha^{(4)} \left[ 1 + \frac{c_1}{M^2} s + \frac{c_2}{M^2} t + \frac{c_3}{M^4} st + \dots \right]$$



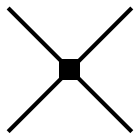
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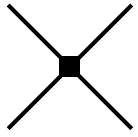
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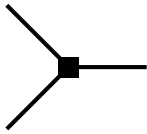


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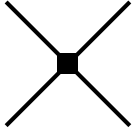


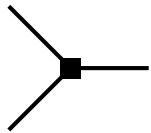
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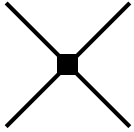
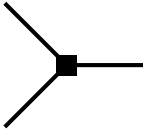
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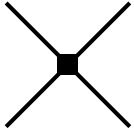
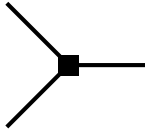
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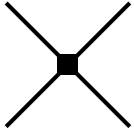
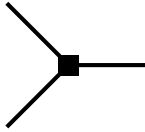
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In such cases, define “physical primary” to be leading operator

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$$M \lesssim E_{\max}(g_\alpha)$$

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$i$	$\mathcal{O}_i^{hZ\bar{f}f}$	CP	$d_{\mathcal{O}_i}$	SMEFT Operator	$c$ Unitarity Bound
1	$hZ^\mu\bar{\psi}_L\gamma_\mu\psi_L$	+	5	$i(H^\dagger\overleftrightarrow{D}_\mu H)\bar{Q}_L\gamma^\mu Q_L$	$\frac{0.6}{E_{\text{TeV}}^2}, \frac{5}{E_{\text{TeV}}^4}$
2	$hZ^\mu\bar{\psi}_R\gamma_\mu\psi_R$	+		$i(H^\dagger\overleftrightarrow{D}_\mu H)\bar{u}_R\gamma^\mu u_R$	
3	$hZ^{\mu\nu}\bar{\psi}_L\sigma_{\mu\nu}\psi_R + \text{h.c.}$	+	6	$\bar{Q}_L\sigma^{\mu\nu}u_R\sigma^a\tilde{H}W_{\mu\nu}^a + \text{h.c.}$	$\frac{2}{E_{\text{TeV}}^2}, \frac{10}{E_{\text{TeV}}^4}$
4	$ih\tilde{Z}_{\mu\nu}\bar{\psi}_L\sigma^{\mu\nu}\psi_R + \text{h.c.}$	-		$i\bar{Q}_L\sigma^{\mu\nu}u_R\sigma^a\tilde{H}\tilde{W}_{\mu\nu}^a + \text{h.c.}$	
5	$ihZ^\mu(\bar{\psi}_L\overleftrightarrow{\partial}_\mu\psi_R) + \text{h.c.}$	+	6	$(H^\dagger\overleftrightarrow{D}_\mu H)(\bar{Q}_L\overleftrightarrow{D}^\mu u_R)\tilde{H} + \text{h.c.}$	$\frac{0.1}{E_{\text{TeV}}^3}, \frac{4}{E_{\text{TeV}}^6}$
6	$hZ^\mu\partial_\mu(\bar{\psi}_L\psi_R) + \text{h.c.}$	-		$i(H^\dagger\overleftrightarrow{D}_\mu H)D^\mu(\bar{Q}_L u_R)\tilde{H} + \text{h.c.}$	
7	$ihZ^\mu\partial_\mu(\bar{\psi}_L\psi_R) + \text{h.c.}$	+		$(H^\dagger\overleftrightarrow{D}_\mu H)D^\mu(\bar{Q}_L u_R)\tilde{H} + \text{h.c.}$	
8	$hZ^\mu(\bar{\psi}_L\overleftrightarrow{\partial}_\mu\psi_R) + \text{h.c.}$	-		$i(H^\dagger\overleftrightarrow{D}_\mu H)(\bar{Q}_L\overleftrightarrow{D}^\mu u_R)\tilde{H} + \text{h.c.}$	
9	$ih\tilde{Z}_{\mu\nu}(\bar{\psi}_L\gamma^\mu\overleftrightarrow{\partial}^\nu\psi_L)$	+	7	$i H ^2\tilde{W}^{a\mu\nu}(\bar{Q}_L\gamma_\mu\sigma^a\overleftrightarrow{D}_\nu Q_L)$	$\frac{0.4}{E_{\text{TeV}}^3}, \frac{1}{E_{\text{TeV}}^4}$
10	$h\tilde{Z}_{\mu\nu}\partial^\mu(\bar{\psi}_L\gamma^\nu\psi_L)$	-		$ H ^2\tilde{W}^{a\mu\nu}D_\mu(\bar{Q}_L\gamma_\nu\sigma^a Q_L)$	
11	$ih\tilde{Z}_{\mu\nu}(\bar{\psi}_R\gamma^\mu\overleftrightarrow{\partial}^\nu\psi_R)$	+		$i H ^2\tilde{B}^{\mu\nu}(\bar{u}_R\gamma_\mu\overleftrightarrow{D}_\nu u_R)$	
12	$h\tilde{Z}_{\mu\nu}\partial^\mu(\bar{\psi}_R\gamma^\nu\psi_R)$	-		$ H ^2\tilde{B}^{\mu\nu}D_\mu(\bar{u}_R\gamma_\nu u_R)$	

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$$f_{\alpha}(x, y) \xrightarrow{|x|, |y| \ll 1} A_{\alpha}x + B_{\alpha}y + O(x^2, y^2, xy) \quad A_{\alpha}, B_{\alpha} \sim 1$$

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- Statistical error model

$$f_{\alpha}(x, y) = \sum_{i=1}^N c_{\alpha i} e_i(x, y)$$

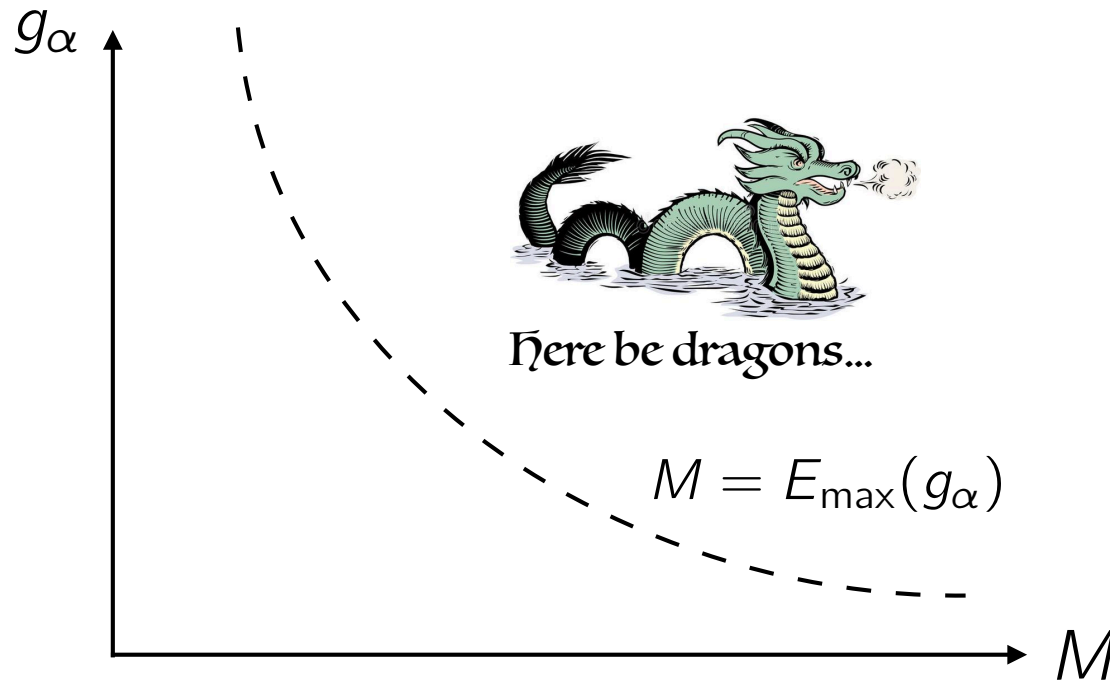
$c_{\alpha i}$  = nuisance parameters  $\langle c_{\alpha i} \rangle = 0, \delta c_{\alpha i} = 1$

$e_i(x, y)$  = basis of shape functions

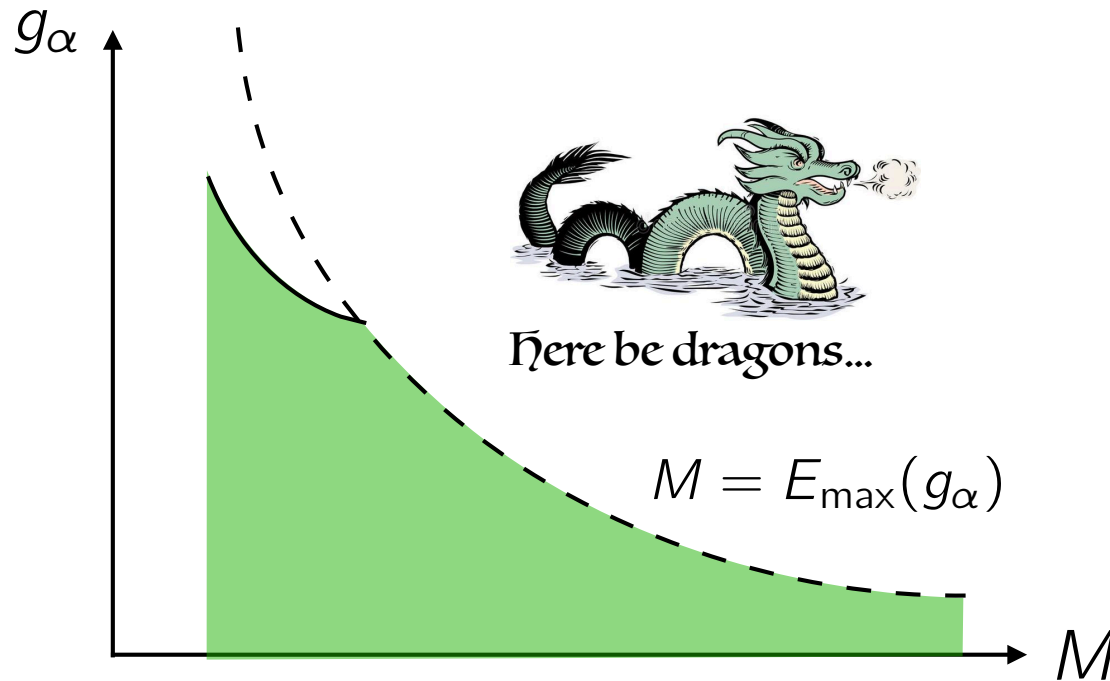
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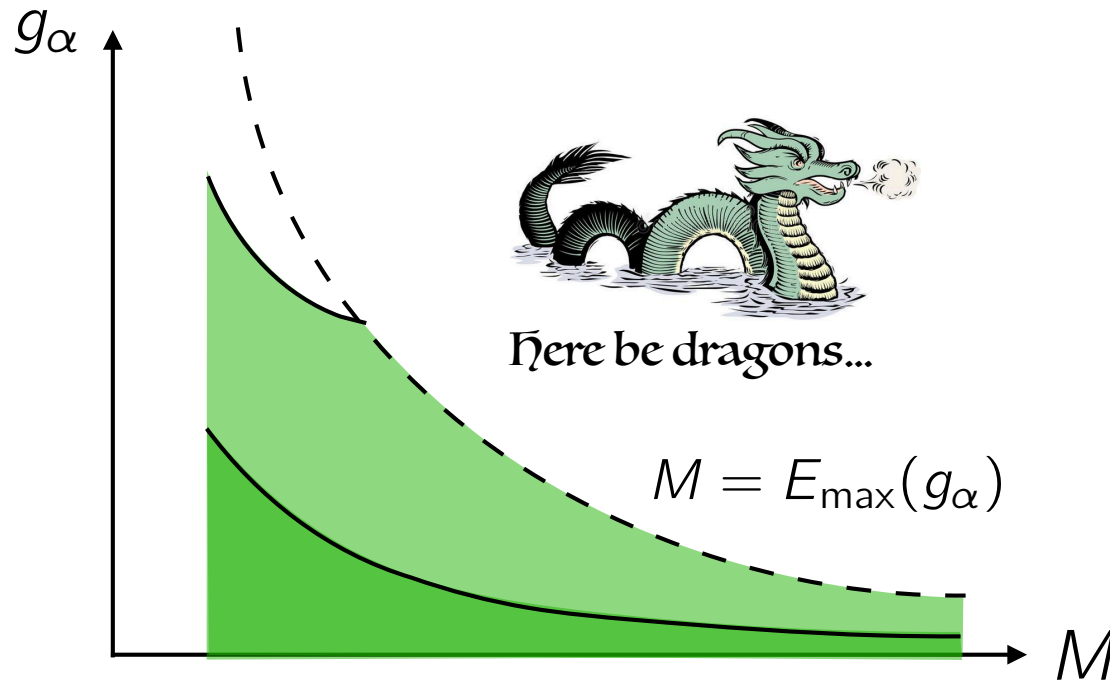
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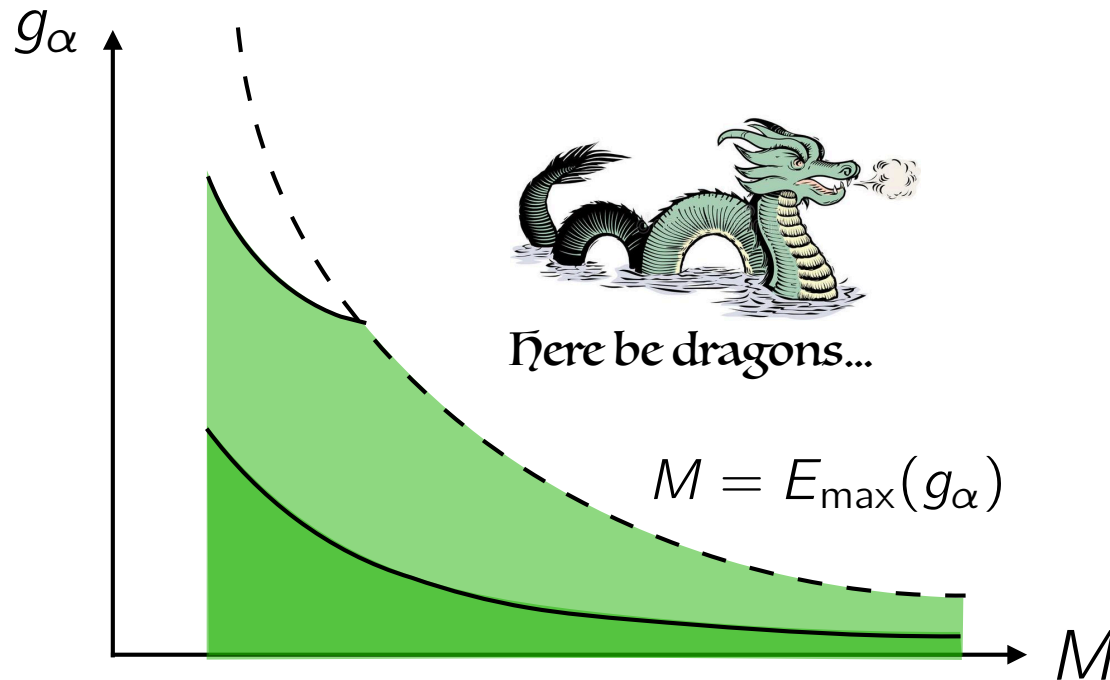
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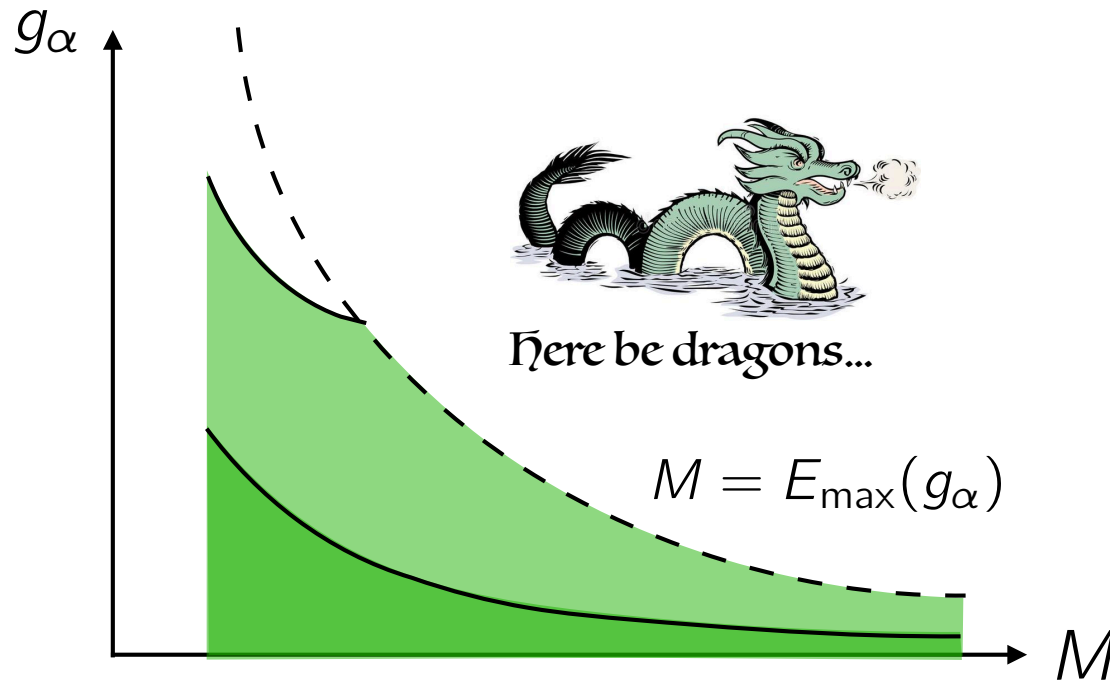
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- Allows analyses to be optimized for sensitivity to EFTs

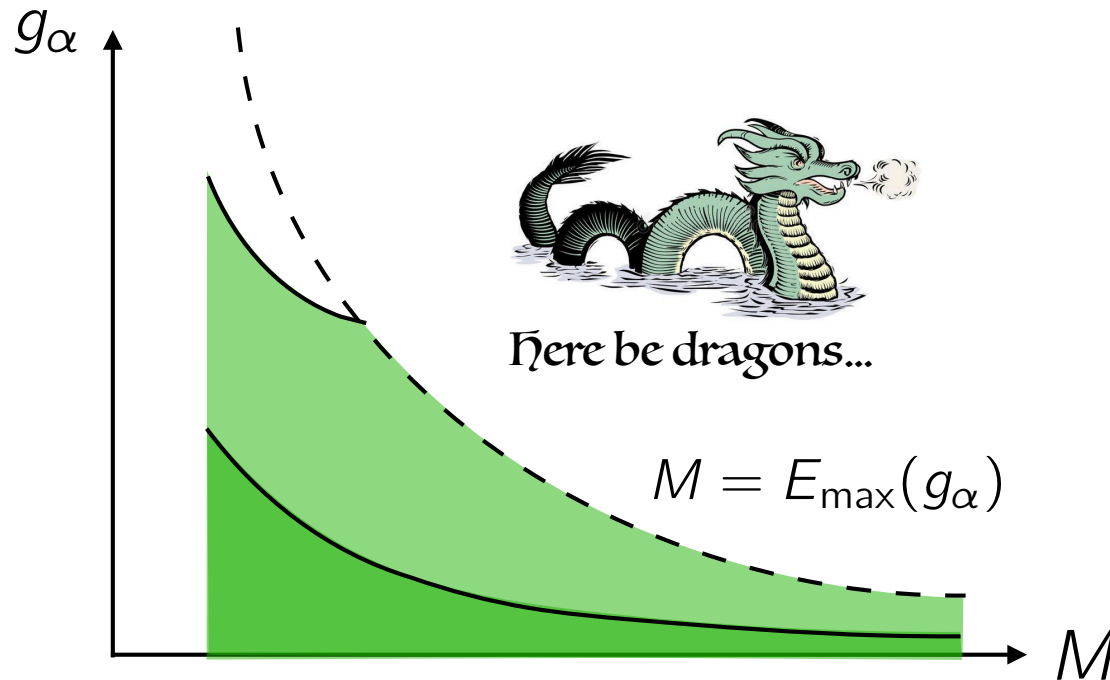


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- Constraints can be directly compared to UV models

# A Simple Analysis

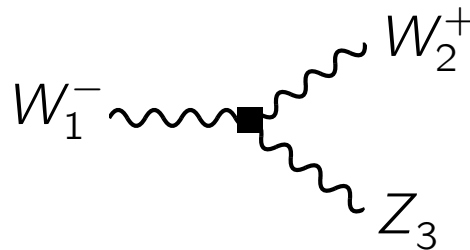
Work in progress...

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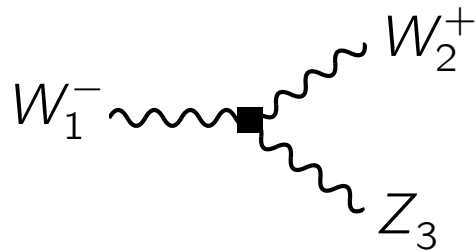
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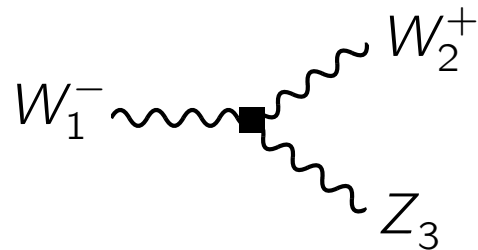
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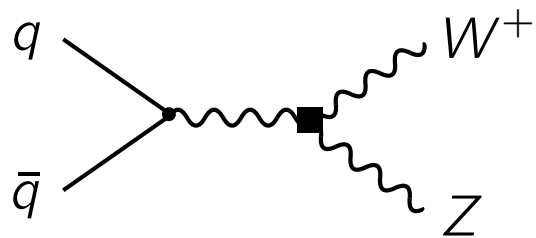
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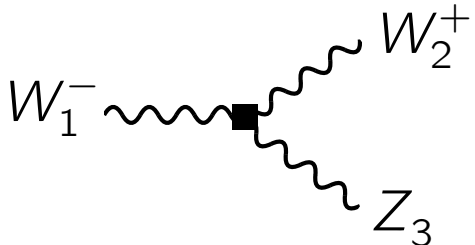
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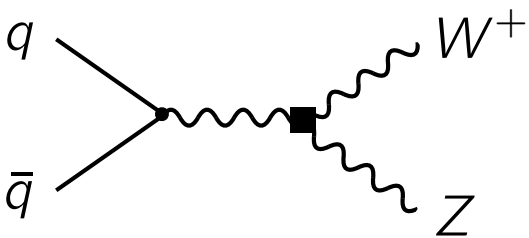
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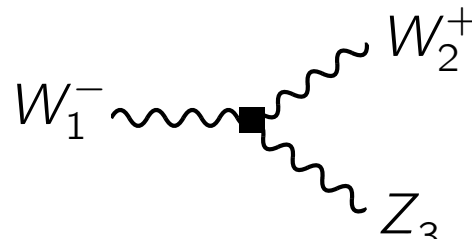
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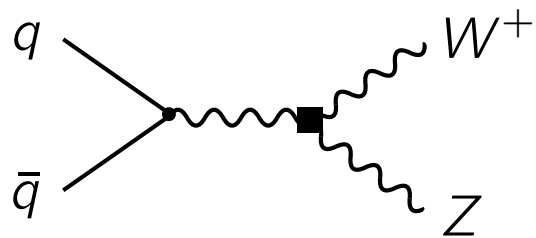
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Monte Carlo data can be generated by reweighting

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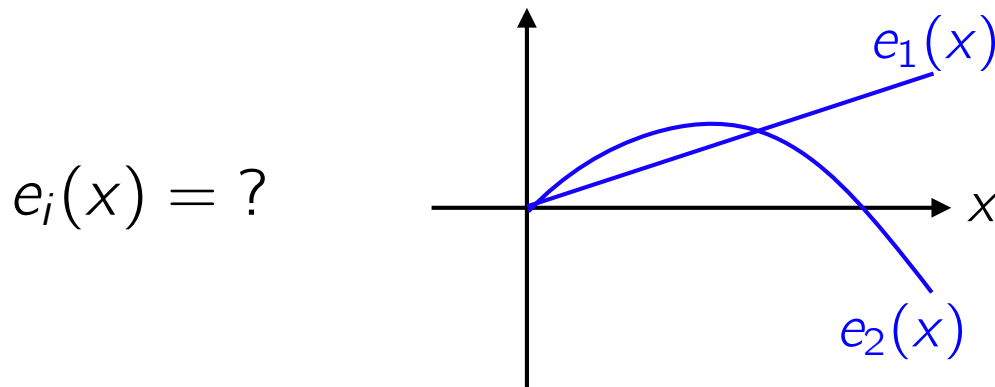
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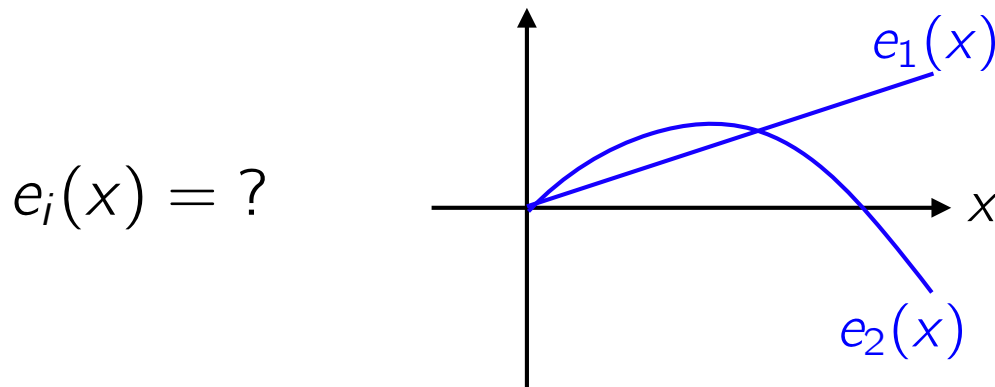
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$c_i =$  nuisance parameters

$$L(\delta g, c) = L_{\text{data}}(\delta g)L_{\text{prior}}(c)$$

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